

# Forecasting at Scale

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## Prophet's goals and alternative

# Prophet library

The Prophet library<sup>1</sup> is a model and a framework, that targets

- non-experts with background business knowledge

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- less knowledge about time series is required
- easy to configure (analyst in the loop)
- easily interpretable parameters
- flexible for a wide range of business problems

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# Alternative

The forecast R-package contains some alternative for automated times series models.

- `auto.arima`<sup>2</sup>, fits multiple ARIMA models and take the best fit

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- `snaive`<sup>4</sup>, random walk model with seasonality

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# Prophet model

# Generalized additive models

Prophet uses a generalized additive model (GAM)<sup>5</sup>

$$y(t) = g(t) + s(t) + h(t) + \epsilon_t$$

- $y(t)$  target

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- $\epsilon_t$  error term (not accomodated by the model)

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# The trend model

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- piecewise linear model

# Nonlinear Saturating growth (basic)

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- $C$  (carrying capacity) and  $k$  (growth rate) are usually not constant
- incorporate trend changes by explicit defined change points
- change point can be set by analyst (e.g. product launches) or automatically selected

# Nonlinear Saturating growth (time dependent carrying capacity)

TBA - this is not explained in the non reviewed paper

# Nonlinear Saturating growth (non constant growth rate - idea)

let  $s_1, \dots, s_n$  be change points (time stamps).

define  $\delta \in \mathbb{R}^n$  (vector of growth rate adjustments)

define growth rate at time  $t$  by

$$k(t) := k + \sum_{j:s_j < t} \delta_j$$

where  $k$  is the base growth rate

# Nonlinear Saturating growth (non constant growth rate - mathematically correct)

define  $a(t) \in \{0, 1\}^n$  by

$$a_j(t) := \begin{cases} 1, & \text{for } t \leq s_j \\ 0, & \text{otherwise} \end{cases}$$

then rate at time  $t$  is given by

$$k(t) := k + a(t)^T \delta$$

# Nonlinear Saturating growth (non constant growth rate - mathematically correct 2)

The offset parameter  $m$  is then adjusted according to the change points by:

$$\gamma_i := \left( s_j - m - \sum_{l < j} \gamma_l \right) \left( 1 - \frac{k + \sum_{l < j} \delta_l}{k + \sum_{l \leq j} \delta_l} \right)$$

# Nonlinear Saturating growth (non constant growth rate - mathematically correct 3)

Putting all together we recieve :

$$\begin{aligned} g(t) &= \frac{C(t)}{1 + \exp(-k(t)(t - m(t)))} \\ &= \frac{C(t)}{1 + \exp(-(k + a(t)^T \delta)(t - (m + a(t)^T \gamma)))} \end{aligned}$$

# Linear trend with Changepoints

using the change points from above a piecewise linear model is given by

$$\begin{aligned} g(t) &= k(t) \cdot t + m(t) \\ &:= (k + a(t)^T \delta) * t + (m + a(t)^T \gamma) \end{aligned}$$

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- recall Bayes theorem

$$P(\delta|Data) = \frac{P(Data|\delta) \cdot P(\delta)}{P(Data)}$$

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where

- $P(\delta|Data)$  is the conditional probability to observe  $\delta$  given  $Data$
- $P(Data|\delta)$  is the likelihood, which can be interpreted as the probability to observe  $Data$  given  $\delta$

# Automatic changepoint selection

Change points are automatically detected by putting a sparse prior on  $\delta$ , i.e.

$$\delta_j \sim \text{Laplace}(0, \tau)$$

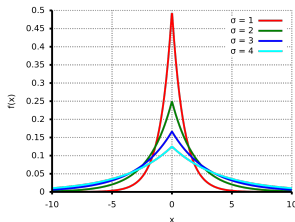


Figure 1: LaPlace density function from wikipedia, here  $\sigma = \tau$

# The seasonal model

The seasonality is approximated by a (truncated) Fourier serie:

$$s(t) = \sum_{i=1}^N (a_n \cos(\frac{2\pi it}{P}) + b_n \sin(\frac{2\pi it}{P}))$$

where

- P is the period in days, for example  $P = 7$  for weekly seasonality

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- P is the period in days, for example  $P = 7$  for weekly seasonality
- N truncates the series and is a model parameter for the user to adjust the fitting

# The seasonal model (fitting)

Fitting requires to estimate  $2N$  parameters  $\beta = (a_1, b_1, \dots, a_N, b_N)$ .

This is done by constructing a matrix of seasonality vectors for each  $t$  in our historical and future data, e.g. for weekly seasonality and  $N = 3$

$$X(t) := (\cos(\frac{2\pi(1)t}{7}), \dots, \sin(\frac{2\pi(3)t}{7}))$$

Hence the seasonal component is

$$s(t) = X(t) \cdot \beta$$

where the prior on  $\beta$  is normally distributed:  $\beta \sim \text{Normal}(0, \sigma^2)$ .

# Fourier series

TBF

- recall how is an element in an vector space is represented in a basis



# Fourier series

## TBF

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- the functions  $e_k(x) := \exp(\frac{2\pi i k x}{P})$  is a basis of a (dense) subspace in the vector space of  $P$  periodic functions

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- the basis functions  $e_k$  can be expressed as a function in sin and cos

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- the basis functions  $e_k$  can be expressed as a function in sin and cos
- convergence of Fourier series

# “Holidays and Events”

TBF

## Stan model and fitting

# Stan model and fitting

Stan is a platform for Bayesian inference using MCMC sampling and more.

# Stan model with logistic growth trend model

```
model {  
  // Priors  
  k ~ normal(0, 5);  
  m ~ normal(0, 5);  
  epsilon ~ normal(0, 0.5);  
  delta ~ double_exponential(0, tau);  
  beta ~ normal(0, sigma);  
  // Logistic likelihood  
  y ~ normal(C ./ (1 + exp(-(k + A * delta  
                                .* (t - (m + A * gamma)))) +  
            X * beta, epsilon);  
}
```

# Stan fitting for prophet

- Prophet uses the L-BFGS algorithm from Stan to fit the GAM



# Stan fitting for prophet

- Prophet uses the L-BFGS algorithm from Stan to fit the GAM
- BFGS = Broyden–Fletcher–Goldfarb–Shanno algorithm, quasi Newton method

## Future Talk's

# regarding Prophet

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- how outliers are handled ?

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- Stan models

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- GAMS
- Bayesian models
- L-BFGS
- Markov chain Monte Carlo

## Further reading

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- The textbook for forecast R-package, but with a lot of theory and practice