Forecasting at Scale

Christian Barz

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2 Prophet model

3 Stan model and fitting

4 Future Talk's

5 Further reading

Prophet's goals and alternative

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The Prophet library is a model and a framework, that targets

non-experts with background business knowledge

¹Taylor, Letham, Forecasting at scale, 2017, The American Statistician

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- non-experts with background business knowledge
- less knowledge about time series is required

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Prophet library

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- easy to configure (analyst in the loop)

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- easily interpretable parameters

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Prophet library

- non-experts with background business knowledge
- less knowledge about time series is required
- easy to configure (analyst in the loop)
- easily interpretable parameters
- flexible for a wide range of business problems

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Prophet's goals and alternative

The forecast R-package contains some alternative for automated times series models.

auto.arima², fits mutliple ARIMA models and take the best fit

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- auto.arima², fits mutliple ARIMA models and take the best fit
- ets³, fits mutliple exponential smoothing models and take the best fit
- snaive⁴, random walk model with seasonality

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Stan model and fitting

Future Talk's 000 urther reading O

Prophet model

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y(t) target

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- \bullet s(t) seasonal model
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- \bullet ϵ_t error term (not accomodated by the model)

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The trend model

Trend can be modeled by

saturated growth model

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Trend can be modeled by

- saturated growth model
- piecewise linear model

A basic logistic growth model is given by

$$g(t) = \frac{C}{1 + exp(-k(t-m))}$$

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Nonlinear Saturating growth (time dependent parameters)

- ullet C (carrying capacity) and k (growth rate) are usually not constant
- incoporate trend changes by explicite defined change points
- change point can be set by analyst (e.g. product launches) or automatically selected

TBA

this is not explained in the paper

Nonlinear Saturating growth (time dependent carrying capacity)

TBA

- this is not explained in the paper
- In the documentation of the prophet library the carrying capacity is a parameter (vector of same length as the data/ future time frame)

let s_1,\ldots,s_n be change points (time stamps). define $\delta\in\mathbb{R}^n$ (vector of growth rate adjustments) define growth rate at time t by

$$k(t) := k + \sum_{j:s_j < t} \delta_j$$

where k is the base growth rate

Nonlinear Saturating growth (non constant growth rate - mathematically correct)

define $a(t) \in \{0,1\}^n$ by

$$a_j(t) := egin{cases} 1, & ext{for } t \leq s_j \ 0, & ext{otherwise} \end{cases}$$

then rate at time t is given by

$$k(t) := k + a(t)^T \delta$$

Nonlinear Saturating growth (non constant growth rate - mathematically correct 2)

The offset parameter m is than adjusted according to the change points by:

$$\gamma_i := \left(s_j - m - \sum_{l < j} \gamma_j \right) \left(1 - \frac{k + \sum_{l < j} \delta_l}{k + \sum_{l \le j} \delta_l} \right)$$

Nonlinear Saturating growth (non constant growth rate - mathematically correct 3)

Putting all together we recieve :

$$g(t) = \frac{C(t)}{1 + exp(-k(t)(t - m(t)))}$$
$$= \frac{C(t)}{1 + exp(-(k + a(t)^T \delta)(t - (m + a(t)^T \gamma)))}$$

using the change points from above a piecewise linear model is given by

$$g(t) = k(t) \cdot t + m(t)$$

:= $(k + a(t)^T \delta) * t + (m + a(t)^T \gamma)$

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where

- $P(\delta|Data)$ is the conditional probability to observe δ given Data
- $P(Data|\delta)$ is the likelihood, which can be interpreted as the probability to observe Data given δ

Change points are automatically detected by putting a sparse prior on δ , i.e.

$$\delta_j \sim Laplace(0, au)$$

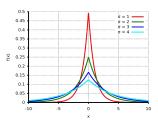


Figure 1: LaPlace density function taken from wikipedia, here $\sigma = \tau$

The seasonality is approximated by a (truncated) Fourier serie:

$$s(t) = \sum_{i=1}^{N} \left(a_n \cos\left(\frac{2\pi i t}{P}\right) + b_n \sin\left(\frac{2\pi i t}{P}\right)\right)$$

where

 \blacksquare P is the period in days, for example P =7 for weekly seasonality

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where

- \blacksquare P is the period in days, for example P =7 for weekly seasonality
- N truncates the series and is a model parameter for the user to adjust the fitting

Fitting requires to estimate 2N parameters $\beta = (a_1, b_1, \dots, a_N, b_N)$.

This is done by constructing a matrix of seasonality vectors for each t in our historical and future data, e.g. for weekly seasonality and ${\cal N}=3$

$$X(t):=(\cos(\frac{2\pi(1)t}{7}),\ldots,\sin(\frac{2\pi(3)t}{7}))$$

Hence the seasonal component is

$$s(t) = X(t) \cdot \beta$$

where the prior on β is normaly distributed: $\beta \sim \text{Normal}(0, \sigma^2)$.

Fourier series

TBF

 recall how is an element in an vector space is represented in a basis

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- the functions $e_k(x) := \exp(\frac{2\pi i k x}{P})$ is a basis of a (dense) subspace in the vector space of P periodic functions
- the basis functions e_k can be expressed as a function in sin and cos
- convergence of Fourier series

"Holidays and Events"

Stan model and fitting

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Stan model and fitting

Stan is a platform for Bayesian inference using MCMC sampling and more.

```
model {
// Priors
k \sim normal(0, 5);
m ~ normal(0, 5):
epsilon \sim normal(0, 0.5);
delta ~ double_exponential(0, tau);
beta ~ normal(0, sigma);
// Logistic likelihood
y \sim normal(C . / (1 + exp(-(k + A * delta))))
                           * (t - (m + A * gamma)))) +
              X * beta, epsilon);
}
```

Prophet uses the L-BFGS algorithm from Stan to fit the GAM

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- BFGS = Broyden-Fletcher-Goldfarb-Shanno algorithm, quasi Newton method

Future Talk's •00

Future Talk's

regarding Prophet

• how the time dependet carrying capacity is determined?

- how the time dependet carrying capacity is determined ?
- how additional regressors are included ?

regarding Prophet

- how the time dependet carrying capacity is determined ?
- how additional regressors are included ?
- how outliers are handeled ?

Stan models

- Stan models
- GAMS

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- Baysian models

- Stan models
- GAMS
- Baysian models
- L-BFGS

- Stan models
- GAMS
- Baysian models
- L-BFGS
- Marcov chain Monte Carlo

Further reading

Further reading

■ The textbook for forecast R-package, but with a lot of theory and practice