Packages Wed Date: _ sobot-localization package. state et noder a) ext-localization mode b) UKf-localization node Leyos proflouring node. c) navasat-transform-node. This nade allows To Houspoins Reognaghic Co DIN (lot & Cong) into Robots would frame (map or for Generating frajectory? Pockage odom to tajectory a) path-odom-platter -> to plot nodes. unfeltend path b) path-followed-plotty-9 **Ontinental**

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	Visualison used to plot multiplot
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About launch files
- Thouse stanto picos
* It suns 3 nodes
1) An *Kf Instance that fuses
1) An *Kf "instance that fuses Odometery (only if provided) and IMU data of outputs State
IMU data & outputs State
estimate.
Descond *Kf instance that fuses same data, but also fuses
fuses same data, but also fuses
4PI data
3) An instance navsat-flansform-node; which takes eigs dota and produce
while takes eight dota and produce
Pose-data.
This is or sobot-localization
package.

	Et sur 2 nodes.
11/	path-odom-plottey -> Let publisher lodompath topi which is unfiltered path
-	e) path_folter_plotter -> Vet publishes /folteredpath lop which is foltered path.
-	168 & for odom-to-Kajeite
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