**Creating a VM using Ubuntu 22.04 jammy:**

A screenshot of a computer

Description automatically generated

A screenshot of a computer

Description automatically generated

A screenshot of a computer

Description automatically generated

A screenshot of a computer

Description automatically generated

A computer screen shot of a jellyfish

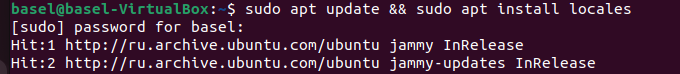
Description automatically generated

**Installing ROS 2:**

**Set locale:**

A screenshot of a computer program

Description automatically generated



A computer screen shot

Description automatically generated

A screenshot of a computer program

Description automatically generated

**Setup Sources:**

A screenshot of a computer program

Description automatically generated

A computer screen with white text

Description automatically generated





**Install ROS 2 packages:**

A computer screen shot of a program

Description automatically generated

A screenshot of a computer

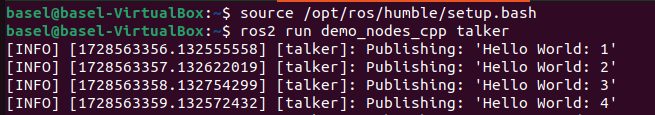
Description automatically generated A screenshot of a computer program

Description automatically generated

**Environment setup:**

**Try some examples:**

**Talker-listener:**

 A screenshot of a computer program

Description automatically generated

**Pyperplan:**

git clone https://github.com/aibasel/pyperplan

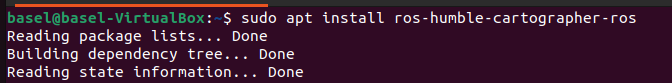
**turtlebot3:**

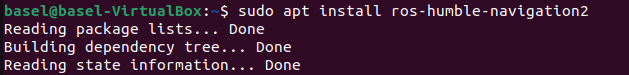
A black background with white text

Description automatically generated

A screenshot of a computer

Description automatically generated





A screenshot of a computer

Description automatically generated





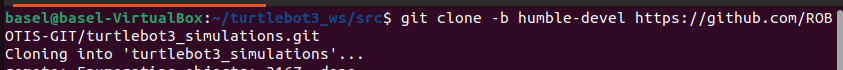


A computer screen shot of a computer code

Description automatically generated with medium confidence

A screenshot of a computer screen

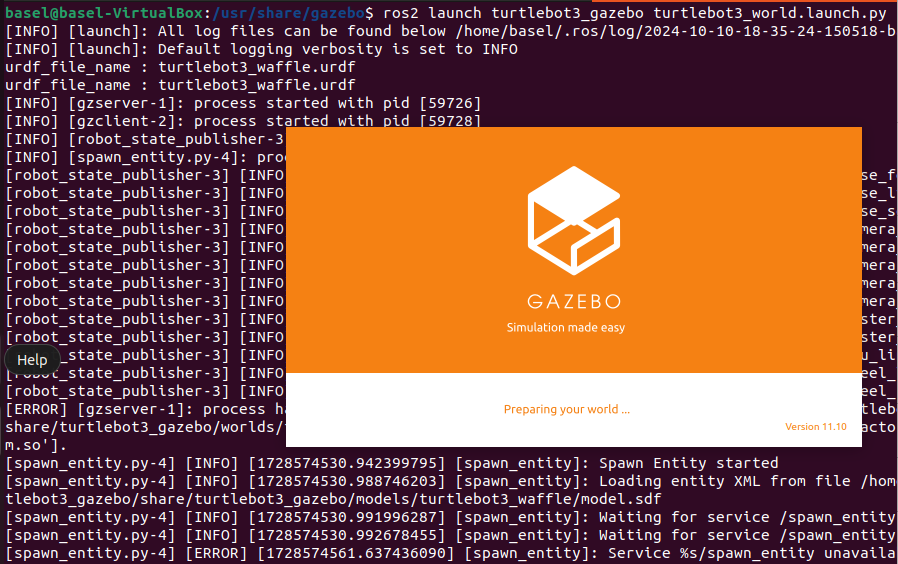
Description automatically generated





A computer screen with white text

Description automatically generated



**Turtlebot3 with manipulator:**

