

# Computer Architecture Lab 2

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## Abstract

Here we trying to document our Lab2 Homework of Computer Architecture lesson in Hochschule Esslingen.

## 1 Task 2.1

### 1.1 Fixing ticker.asm

In our defines we need to give TIMER\_ON value \$80 instead of \$70 , aslo we need to give **TSCR2** value #\$07 so our instructions should look something like

```
TIMER_ON    equ $80                ; tscr1 value to turn ECT on

MOVB #$07, TSCR2                    ; initiliaze TSCR2
```

### 1.2 Testing ticker.asm

Since we are working on simulator, we need to use CPU's Cycles to test our ticker.asm

So we can put a breakpoint in the **isrECT4** method like shown in Figure 1

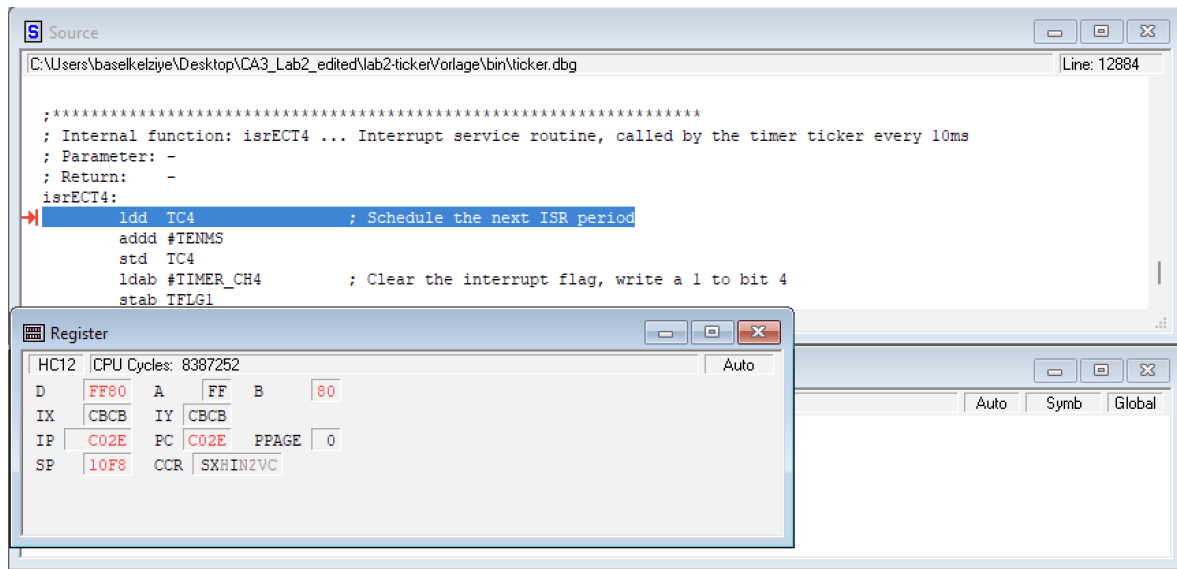


Figure 1: CPU Cycle After First Call

Here we can see that at the moment our cycle amount is **8387252**.

Now lets start our program and let see the cpu cycle amount when we hit the breakpoint again.

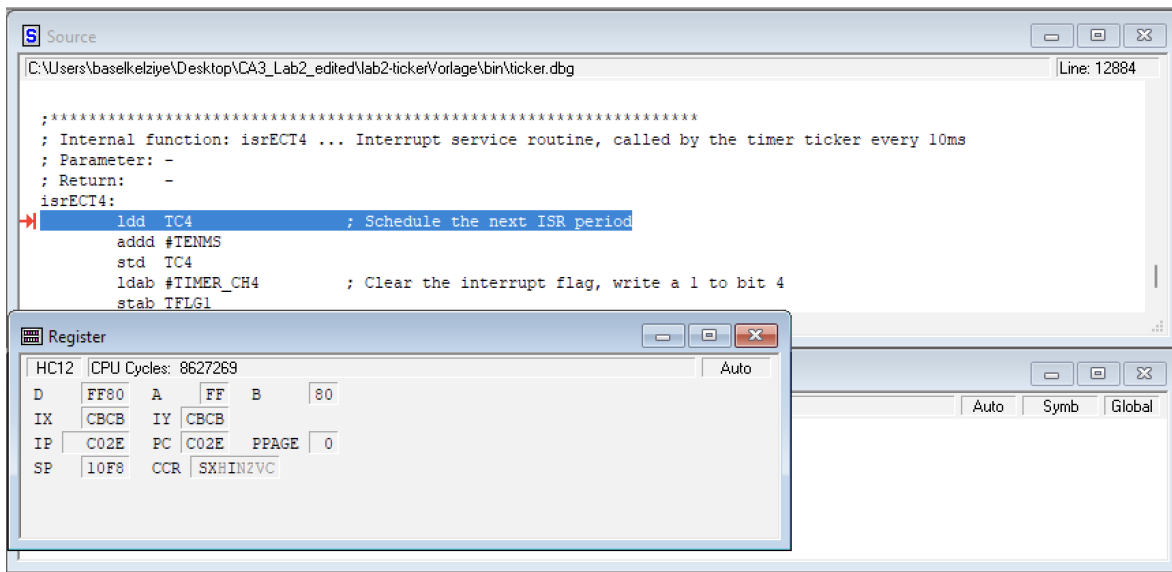


Figure 2: CPU Cycle After Second Call

as shown in Figure 2 our cpu cycle has increased to **8627269**  
to calculate the cycles between the 2 isrECT4 calls we do  $CYCLE2 - CYCLE1 = 8627269 - 8387252$   
= **240017**

To calculate the elapsed time we can use the following formula:

$$ElapsedTime = \frac{NumberOfcycles * 1000(ms)}{ClockFrequency}$$

And since our Dragon12 Board has a clock of 24MHz our equation look like:

$$ElapsedTime = \frac{240017 * 1000(ms)}{24 * 10^6} \approx 10ms$$

## 2 Uhr-voltage

### 2.1 buttons.c Module

Buttons are read using Polling, and only SW2-5 buttons are getting read. But while reading the buttons we need to **Debounce** so we don't trigger a function more than the intended amount [read more](#).

Initilize buttons:

```
DDRH = 0x00; //PORTH all input
```

So the method used to debounce is to read the button, save the state. Wait for a specified time and then re-read the button. If it matches the last state we can say that the button's signal is safe to read.

```

// registers: unchanged
void check_button(){

    unsigned char temp = PTH & PB_MASK; // only look at 2-5 switches only

    if(temp == (PTH & PB_MASK)){
        if(lastButton != temp){
            lastButton = temp;
            debounce = DEBOUNCE_DELAY; // wait before processing
            repeat = -1; // signify initial depression
            repeatDelay = INITIAL_REPEAT_DELAY;
            return;
        }

        if (debounce != 0){ // we are debouncing
            debounce--;
            return;
        }

        if(temp == 4){ //SW2
            if(repeat > 0){
                repeat--;
            } else{
                repeat = repeatDelay;
                repeatDelay = REPEAT_DELAY;
                clockMode = ~clockMode;
            }
        }
    }
}

```

Figure 3: Debouncing Buttons

in Figure 3 a part of the reading button function is given.  
Corresponding on the clicked button a function is triggered.

## 2.2 Adding Time

To handle the overflows an intuitive way is to call the other adding function when overflows happen.

```

// registers: unchanged
void add_second(void){
    seconds_passed++;
    seconds = (seconds + 1)%60;
    if(seconds == 0){
        add_minute();
    }
}

// Public interface function: add_minute -> add 1 minutes
//called only from add_second, calls add_hour
// Parameter: -
// Return: -
// Registers: Unchanged
void add_minute(void){
    minutes = (minutes + 1)%60;
    if(minutes == 0){
        add_hour();
    }
}

```

Figure 4: Time Adding Functions

As an example if we have 60 seconds passed and we need to increment the minutes, instead of adding the minutes like `minutes++` we call `add_minute()` function shown in Figure 4. And if we have an overflow in minutes now the `add_minute()` function will call `add_hour()` function and increments the hours. Using this strategy we get a clean and easy way to handle the overflows. **Note:** `add_hour()` function is implemented in the "Assembly-directive" Section to achieve the 12-Hours mode. (Will be covered later in the report).

## 2.3 clock.c Module

### 2.3.1 Print Names Periodically

Our `print_names_periodically()` function uses a global variable `my_semaphore` to decide which name to print. The value gets complemented when a change occurs.

```
// Public interface function: print_names_periodically -> prints the name. called every 10 seconds
// global variable my_semaphore changes state for the names
// Parameter: -
// Return: -
// Registers: Unchanged

void print_names_periodically(void){
    if(my_semaphore)
    {
        my_semaphore = 0;
        WriteLine_Wrapper("Basel@ITW2021/22",0);
    }
    else
    {
        my_semaphore = 1;
        WriteLine_Wrapper("Elias@ITW2021/22",0);
    }
}
```

Figure 5: Function to print the names periodically

### 2.3.2 Assembly Directives

Here `add_hour` and `adjust_clock_string` methods are generated recording to the `SELECT12HOURS` macro value.

#### 2.3.2.1 add\_hour

If 12 Hours mode is selected our hours are getting modulus by 13 and a new global variable `isPM` is introduced to determine the "AM/PM" Time Zone.

```
//Macro SELECT12HOURS if its set to 1
//add_hour function modulus on 13
//if hours = 12 isPM switches(from AM to PM vice-versa)
//if hours = 0 increment hours
#if SELECT12HOURS == 1
void add_hour(void){
    hours = (hours + 1)%13;
    if(hours == 12){
        isPM = !isPM;
    }
    if(hours == 0){
        hours++;
    }
}
#else
//its important to have the same name for the fu
//they function for 24H system (SELECT12HOURS =
void add_hour(void){
    hours = (hours + 1)%24;
}
#endif
```

Figure 6: Comparison of add\_hour functions

In Figure 6. We can see the difference between the 2 compiled functions. If we use the 12Hour system(on the left) PM variable is used and we module by 13 and not 24.

#### 2.3.2.2 adjust\_clock\_string

in Our adjust string functions the difference is that if we are in `SELECT12HOURS` mode (on the left) depending on `isPM` variable a "AM/PM" is added.

<pre> void adjust_clock_string(void){     result_char[0] = hour_char[4];     result_char[1] = hour_char[5];     result_char[2] = ':';     result_char[3] = minutes_char[4];     result_char[4] = minutes_char[5];     result_char[5] = ':';     result_char[6] = seconds_char[4];     result_char[7] = seconds_char[5];     result_char[9] = 'M';     if(isPM){         result_char[8] = 'P';     } else{         result_char[8] = 'A';     } } </pre>	<pre> void adjust_clock_string(void){     result_char[0] = hour_char[4];     result_char[1] = hour_char[5];     result_char[2] = ':';     result_char[3] = minutes_char[4];     result_char[4] = minutes_char[5];     result_char[5] = ':';     result_char[6] = seconds_char[4];     result_char[7] = seconds_char[5]; }  #endif </pre>
--	--

Figure 7: Comparison of adjust\_clock\_string

### 2.3.3 Clock Pulse

This function is the heart of our program. It gets executed every second.

```

void clock_pulse(void){
    add_second();
    decToASCII_Wrapper(hour_char, hours);
    decToASCII_Wrapper(minutes_char, minutes);
    decToASCII_Wrapper(seconds_char, seconds);
    adjust_clock_string();
    display_LED_C();
    if(seconds_passed%10 == 0){
        print_names_periodically();
        seconds_passed = 0; //prevent overflow
    }

    WriteLine_Wrapper(result_char, 1);
}

```

Figure 8: clock\_pulse function

as shown in Figure 8, first of all add.second() method is called, then we convert the hours, minutes and seconds to string using decToASCII function from LAB1. and then we create final string from the hours, minutes, seconds string. and we check if 10s is already passed to print names.

seconds\_passed variable is incremented in add.seconds() method.

## 2.4 Thermometer.c

This module is written in C and provides methods to convert measured temperature values in a desired string format that is ready to be displayed on the LCD display. The two assembler routines initADC(void) and convertADC(void) from the adc.asm module are referenced and used here to control the data acquisition through the ADC. The integer variable always holds the latest temperature value in Degrees celsius ranging from -30°C to 70°C. The character Array holds the formatted textual representation that is fetched from other module with the getTemperatureText(void) function

### 2.4.1 initThermometer

is called once for initializing the the temperature variable with zero and to cofigure the ADC properly before measurements are taken.

### 2.4.2 updateThermometer

is called periodically in sync with the LCD display refresh that happens every second. It instructs the ADC module to convert and store the latest measurement.

## 2.5 Adc.asm

The module is written in Assembler and provides basic functionality to periodically read from the Analog-Digital-Converter using an interrupt.

### 2.5.1 initADC

routine enables the 10 bit ATD0 Analog-Digital-Converter of the dragon board and configures it to take 4 independent measurements before triggering the interrupt to signal a `ready for conversion` state.

### 2.5.2 adcISR

The interrupt service routine `adcISR` is invoked as soon as the next 4 measurements have been taken. We sum them up and perform two logic right shifts to divide the sum by 4. This way we always have the average of 4 measurements which makes the system more robust. The average is stored and the interrupt flag resetted, so that the next measurements can be taken.

### 2.5.3 convertADC

The `convertADC` routine performs mapping of the raw value on to the degree celsius scale. It goes by the following formula:

$$\text{temperature} = \left( \frac{\text{adcVal} \times 100}{1023} \right) - 30$$

This routine is always called from the thermometer module right before the next temperature value is fetched.

## 2.6 main.c

in main i have `display_led_C` function which toggles the first LED0 every time it gets called, and if `clockMode` is in set mode it turn on the LED7.

```
void display_LED_C(void){ //displays the led corresponding to the clock's state
    PORTB = (PORTB ^ (1<<0));
    if(clockMode)
    {
        PORTB = PORTB & 0x7F;
    } else{
        PORTB = PORTB | 0xFE;
    }
}
```

Figure 9: `display_led()` function

### 2.6.1 main function

in main function we only initialize the hardware peripherals and call an endless loop. if clockEvent is truly value (non-zero) clock\_pulse() method is called, and check\_button() is called. the clockEvent value is changed every second in ticker.asm (Figure 10)

```
; --- Add user code here: Add whatever you want to do every second ---
    PSHE
    LDAB #1
    STAB clockEvent
    PULB
|

; --- End of user code -----
...

```

Figure 10: Changing clockMode in assembler





### 3 Flowcharts



