



# SPADE♠

## A SEMI-SUPERVISED PROBABILISTIC APPROACH FOR DETECTING ERRORS IN TABLES

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# Tables are rich sources of structured knowledge

- Millions of tables on the Web
- Providing data for many applications

# Beers

	Country (or territory) ⇅	Capital
1	China ( <a href="#">more</a> )	<a href="#">Beijing</a>
2	Japan ( <a href="#">more</a> )	<a href="#">Tokyo</a>
3	DR Congo	<a href="#">Kinshasa</a>
4	Russia ( <a href="#">more</a> )	<a href="#">Moscow</a>
5	Indonesia ( <a href="#">more</a> )	<a href="#">Jakarta</a>
6	South Korea ( <a href="#">more</a> )	
7	Egypt ( <a href="#">more</a> )	
8	Mexico	

	index ▲ ▼	beer_name ▼	style ▼	ounces ▼	abv ▼
	1	Pub Beer	American Pale Lager	12.0 oz	0.05
	2	Devil's Cup	American Pale Ale (APA)	12.0 oz.	0.07
	3	Rise of the Phoenix	American IPA	12.0 ounce	0.07
	4	Sinister	American Double / Impe	12.0 oz	0.09%
	5	Sex and Candy	American IPA	12.0 OZ.	0.08
	6	Black Exodus	Oatmeal Stout	12.0 oz	0.08

	GDP per capita	Voluntary expenditure	Household income	Passenger transport
	41 450	2.3	-0.5	138 643
	43 746	2.3	1.1	132 125
	44 720	2.3	0.4	134 954 e

Country	Economics
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# Tables can contain errors

- Errors can be detrimental for data applications

	index ▲ ▼	beer_name ▼	style ▼	ounces ▼	abv ▼
	1	Pub Beer	American Pale Lager	12.0 oz	0.05
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# Supervised approach: Need of extensive labeling data

1000  
normal rows

GDP per capita	Voluntary expenditure	Household income	Passenger transport
41 450	2.3	-0.5	138 643
...	...	...	...
...	...	...	...
43 746	2.3	1.1	132 125
44 720	2.3	0.4	134 954 e



How many labeled examples  
before reaching the error ?



# Supervised approach: Imbalanced dataset

1000  
normal rows

GDP per capita	Voluntary expenditure	Household income	Passenger transport
41 450	2.3	-0.5	138 643
...	...	...	...
...	...	...	...
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44 720	2.3	0.4	134 954 e



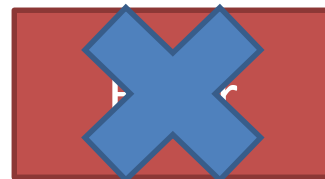
Why only a few errors ?



# Unsupervised approach: Inductive bias in method design

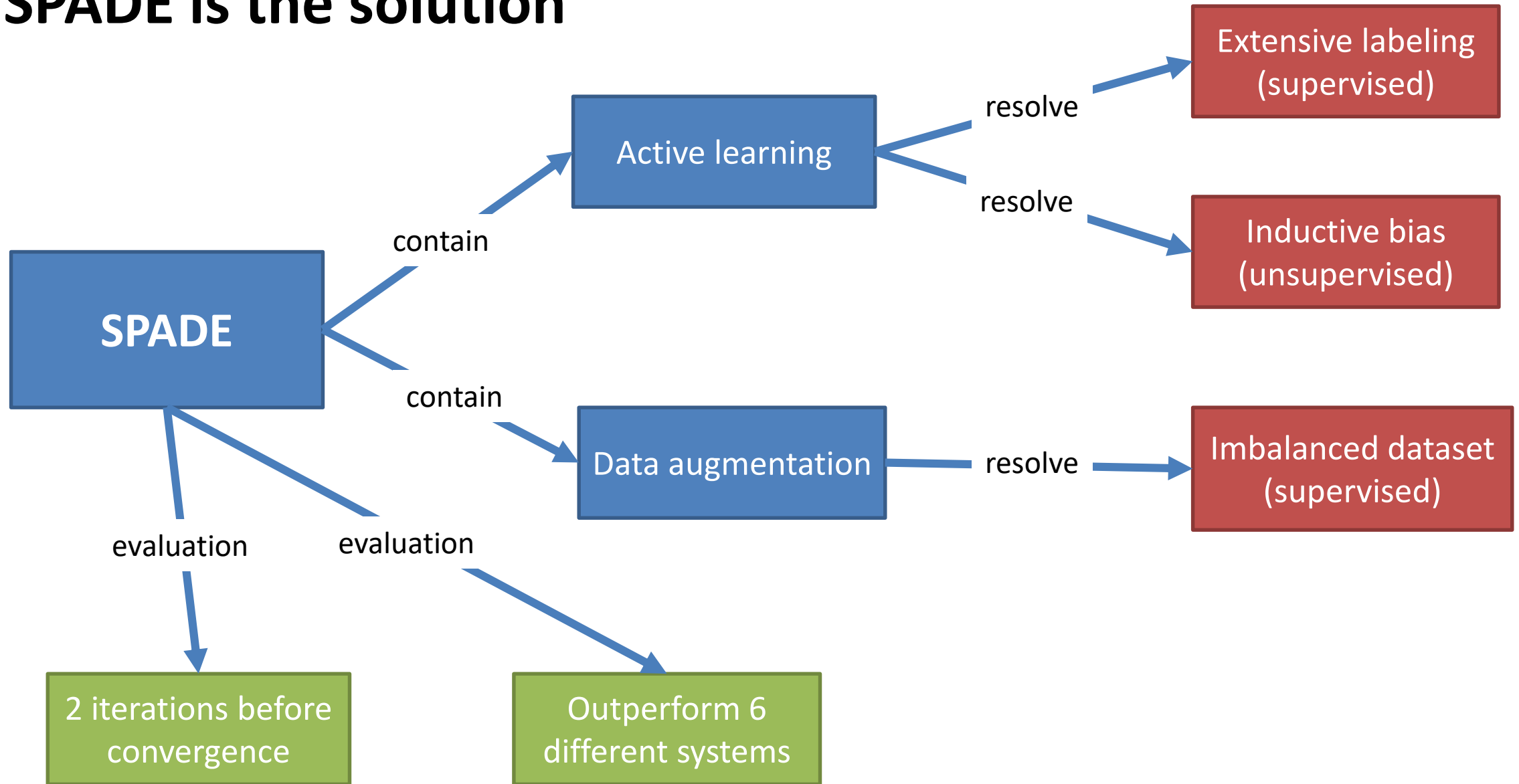
GDP per capita	Voluntary expenditure	Household income	Passenger transport
41 450	2.3	-0.5	138 643
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Inductive bias: only negative value in the column

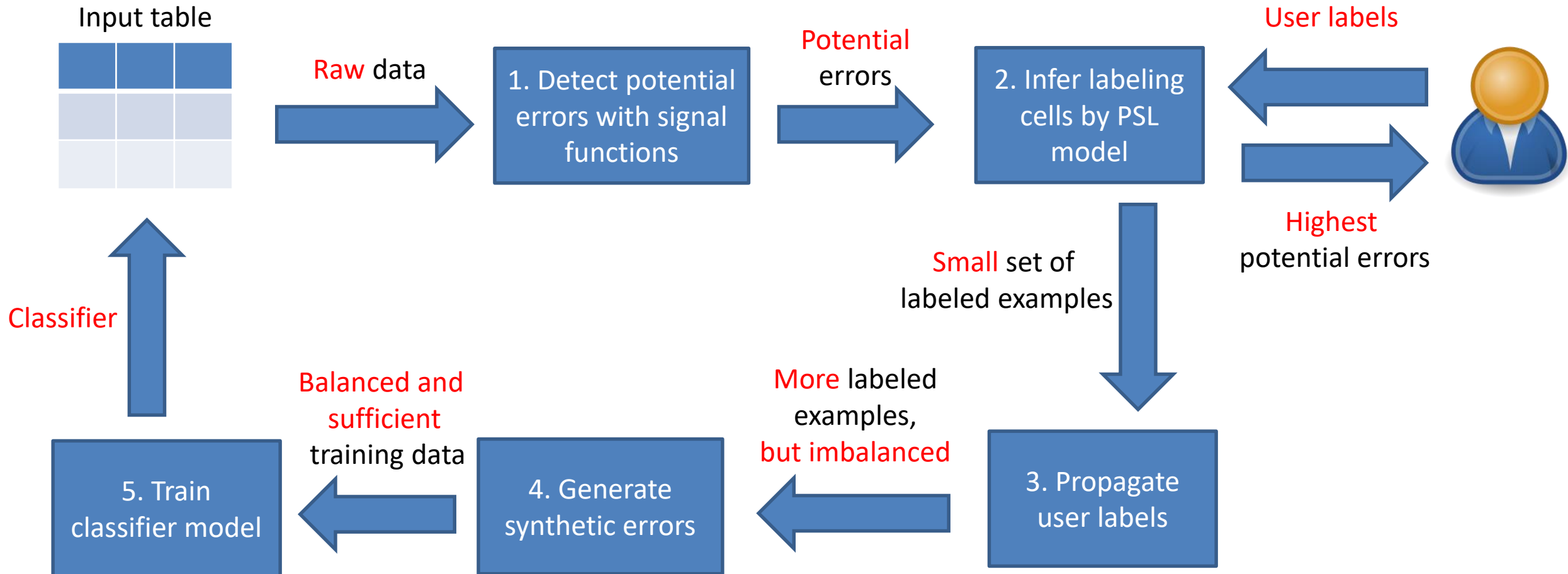


Normal  
Value

# SPADE is the solution

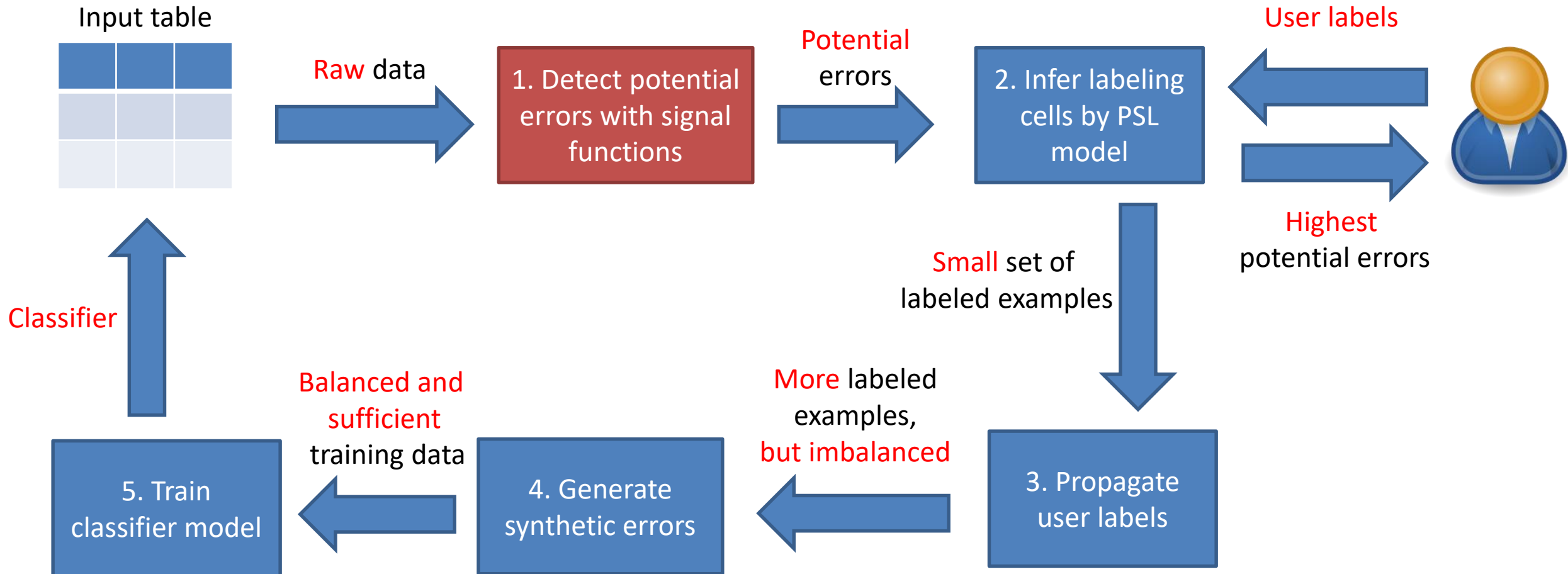


# Overall approach





# Detect potential errors with signal functions



# How to detect potential errors ?

GDP per capita	Voluntary expenditure	Household income	Passenger transport
41 450	2.3	-0.5	138 643
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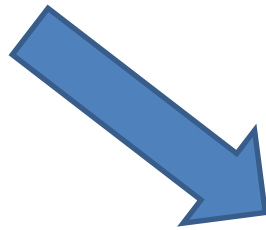


Different from other values – **Internal signal**

Potential  
Errors

# How to detect potential errors ?

GDP per capita	Voluntary expenditure	Household income	Passenger transport
41 450	2.3	-0.5	138 643
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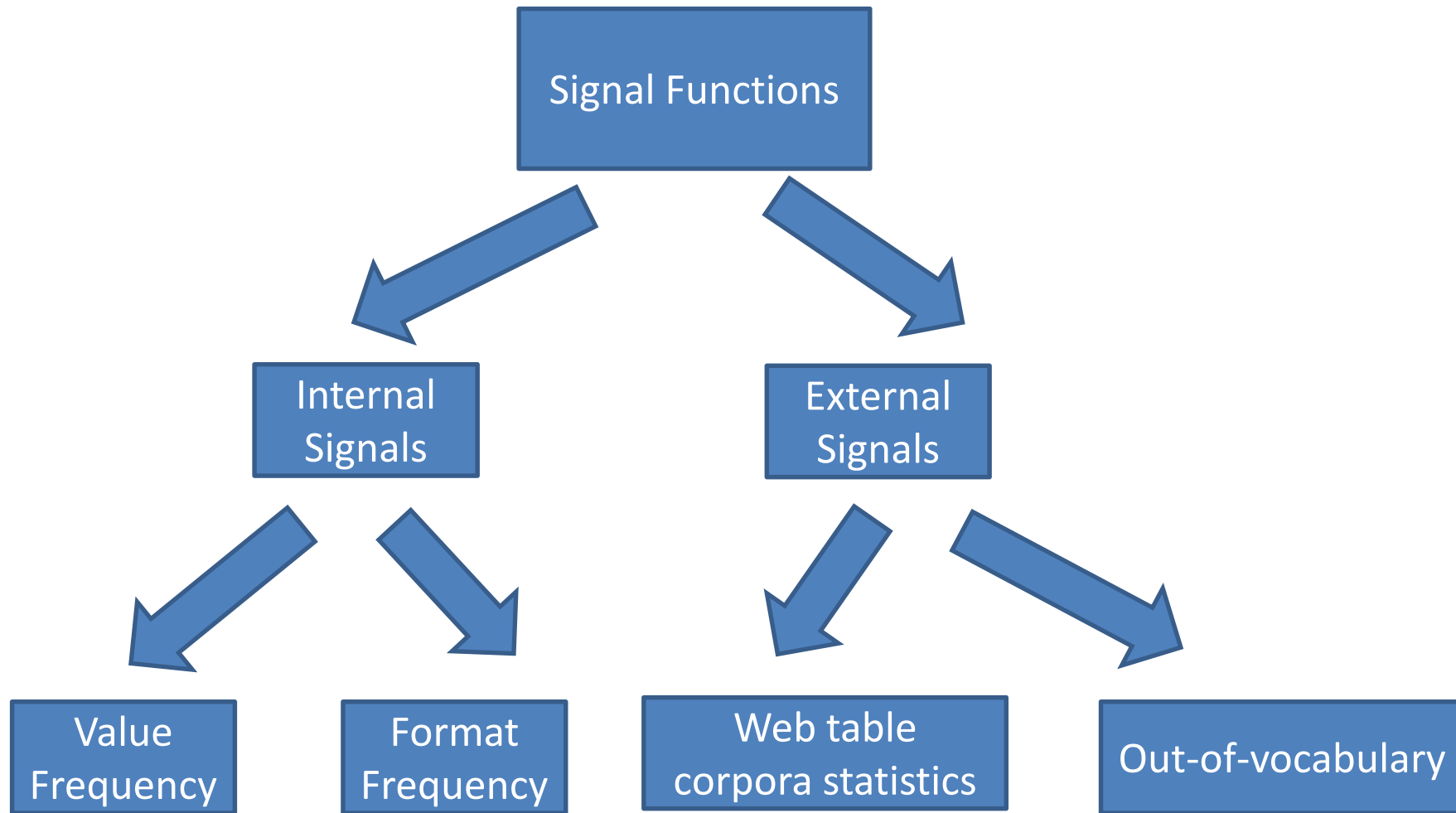


Uncommon formats – **External signal**

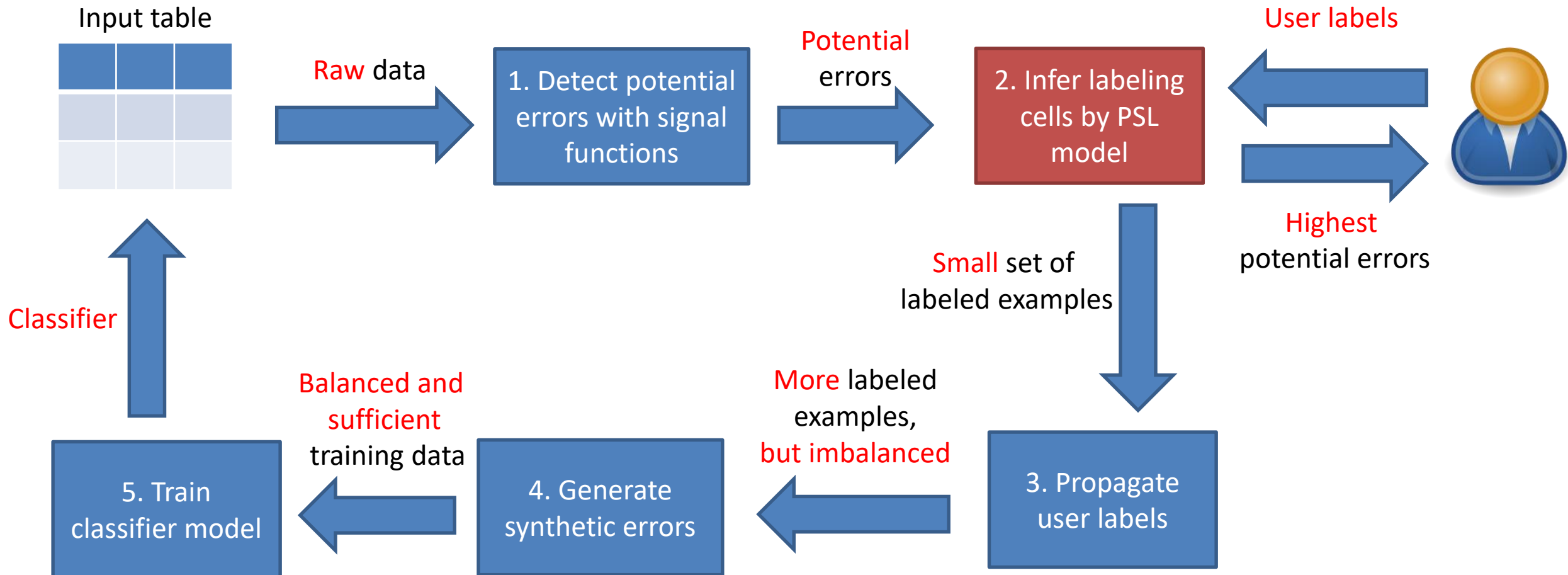
Potential  
Errors



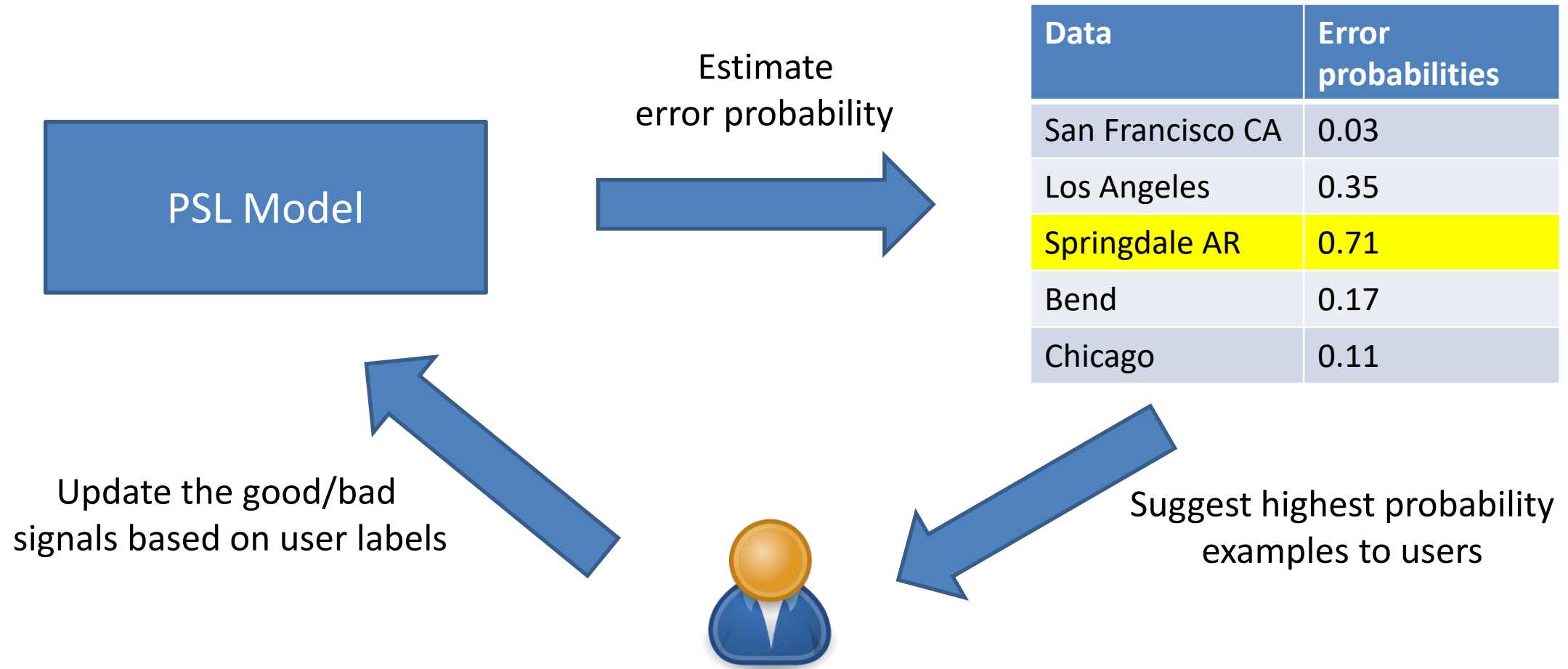
# External and internal signals



# Overall approach



# PSL model: Active learning iteration



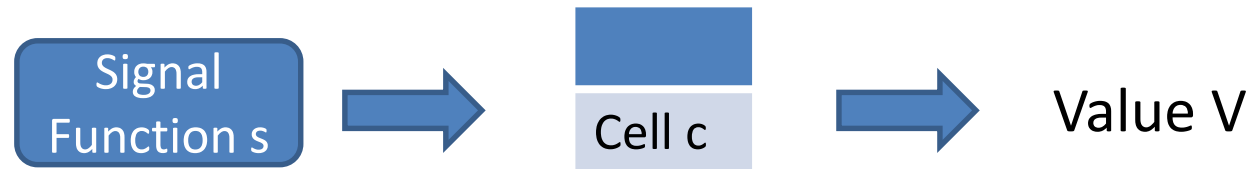
# Probabilistic Soft Logic (PSL) model

- A probabilistic graphical model framework using first-order logic
- Two main elements: predicates and rules
- Predicates can have “soft” values  $[0,1]$

# PSL model: Predicates

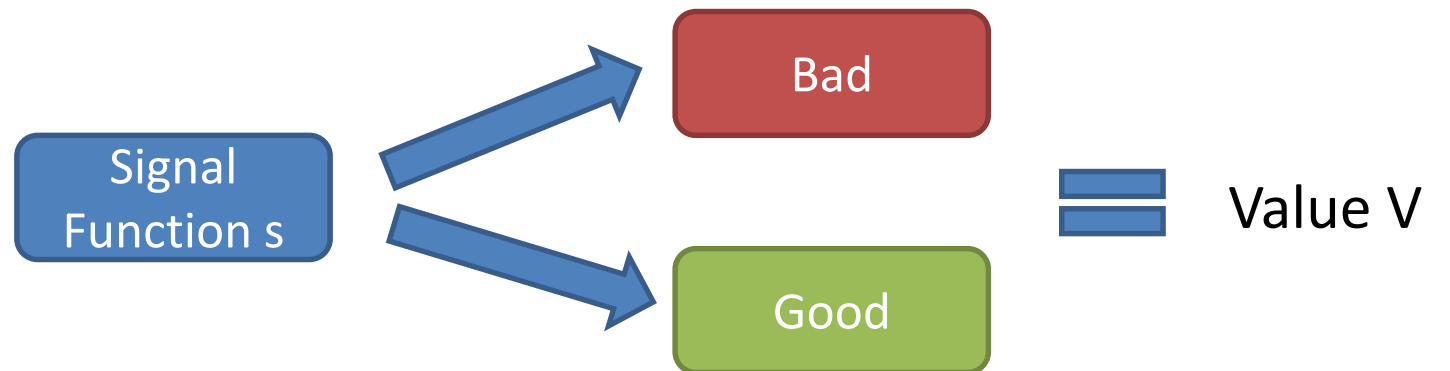
$$\textit{HasSignal}(c, s) = V$$

Indicate value of signal function  $s$  when applying on cell  $c$



$$\textit{BadSignal}(s) = V$$

Indicate if a signal is bad or good





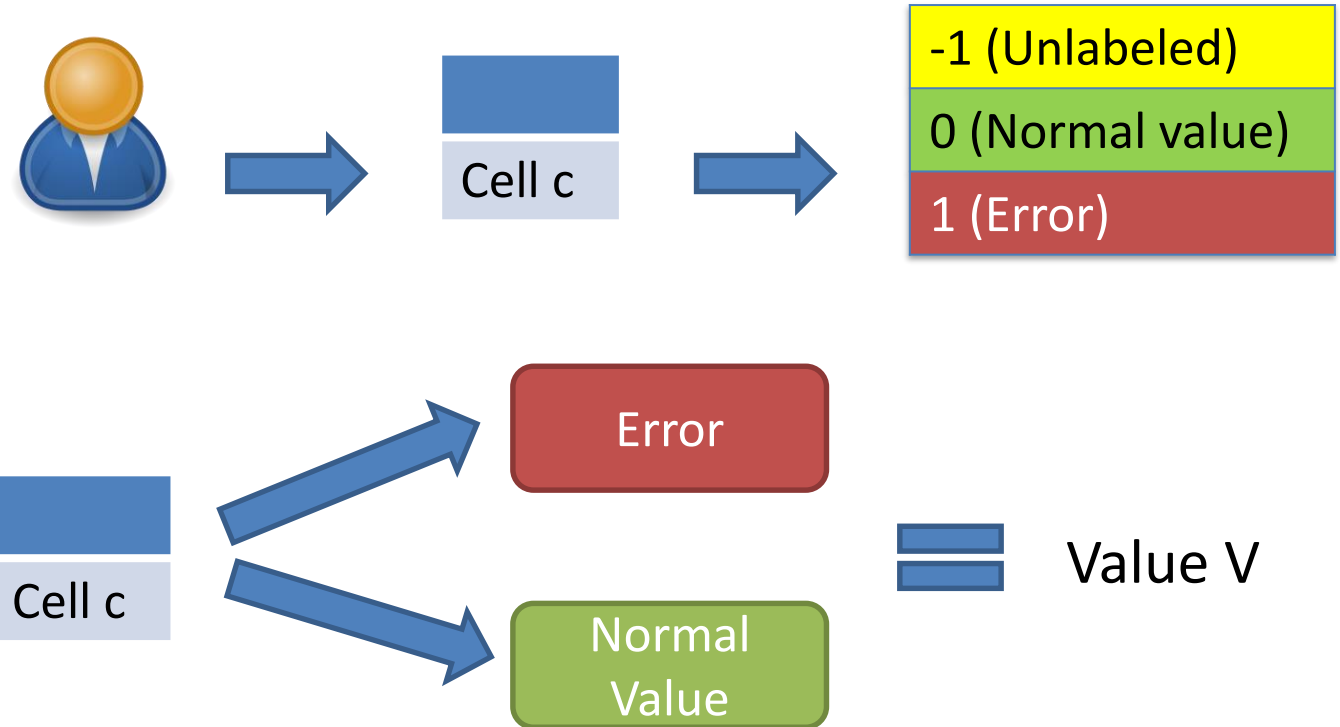
# PSL model: Predicates

$$\text{Label}(c, \{-1, 0, 1\}) = \{0, 1\}$$

Indicate user label of cell c

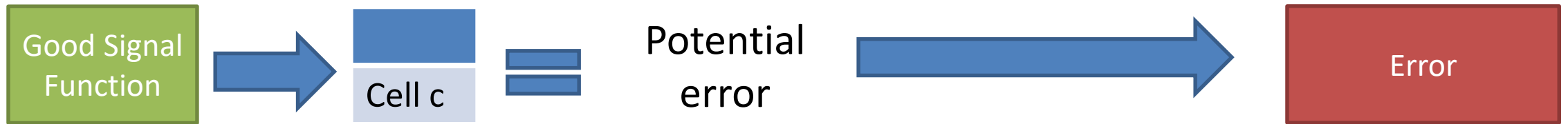
$$\text{Error}(c) = V$$

Indicate error probability of cell c

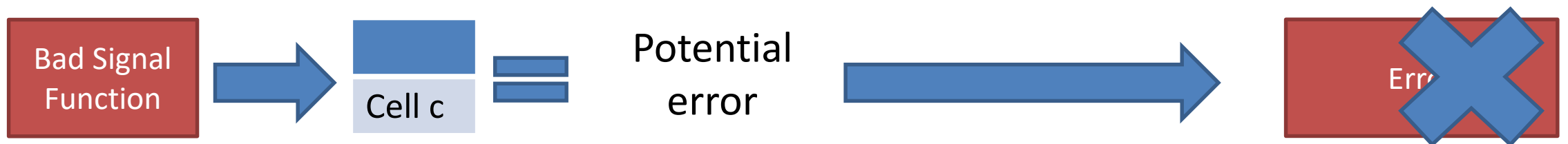


# PSL rules: Error probabilities

$$\neg \text{BadSignal}(s) \wedge \text{HasSignal}(c, s) \Rightarrow \text{Error}(c)$$



$$\text{BadSignal}(s) \wedge \text{HasSignal}(c, s) \Rightarrow \neg \text{Error}(c)$$

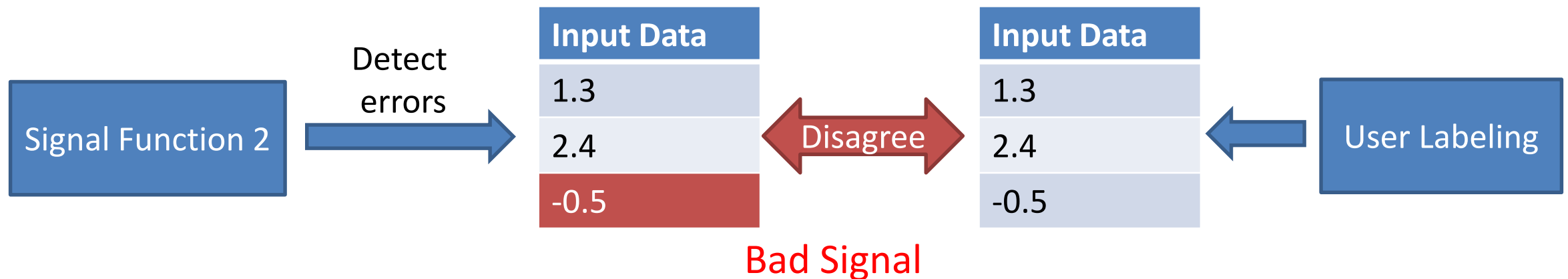


# PSL rules: Signal function and user labeling

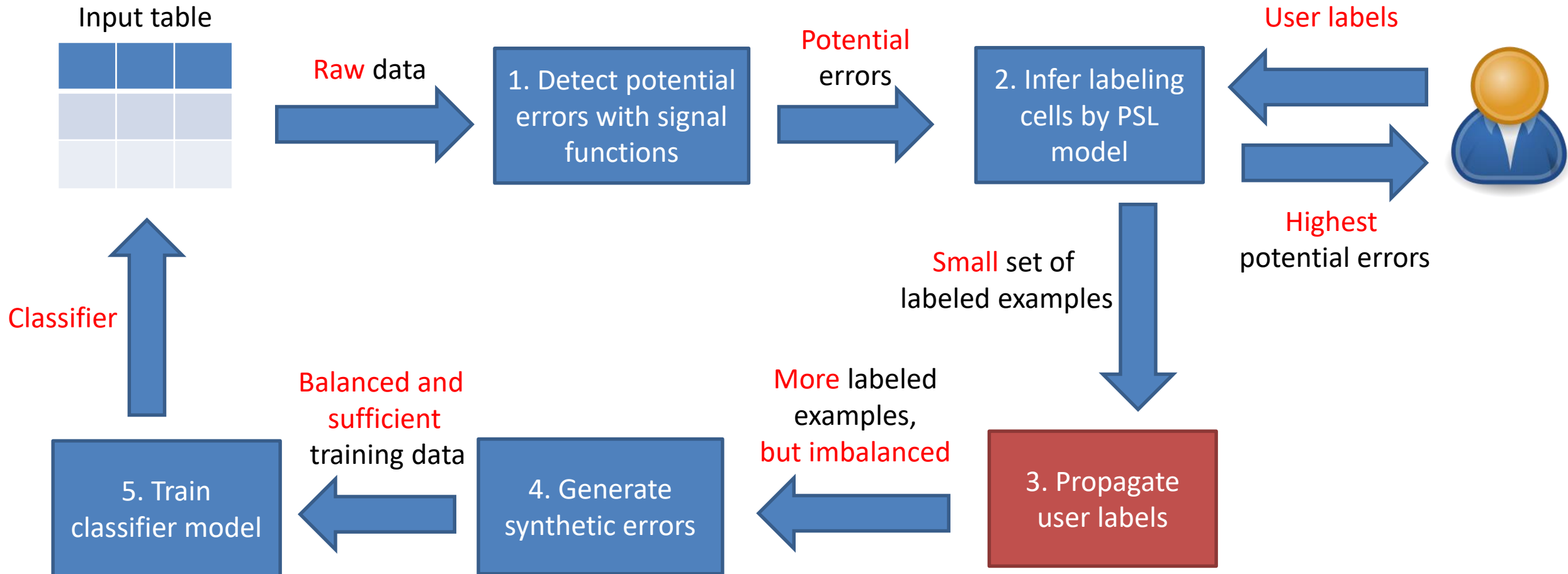
$$Label(c, 1) \wedge HasSignal(c, s) \Rightarrow \neg BadSignal(s)$$



$$Label(c, 0) \wedge HasSignal(c, s) \Rightarrow BadSignal(s)$$



# Overall approach



# Label propagation

Data	Error probability
San Francisco CA	0.7
Los Angeles	0.35
Springdale AR	0.71
Bend	0.17
Chicago	0.11

User labeling



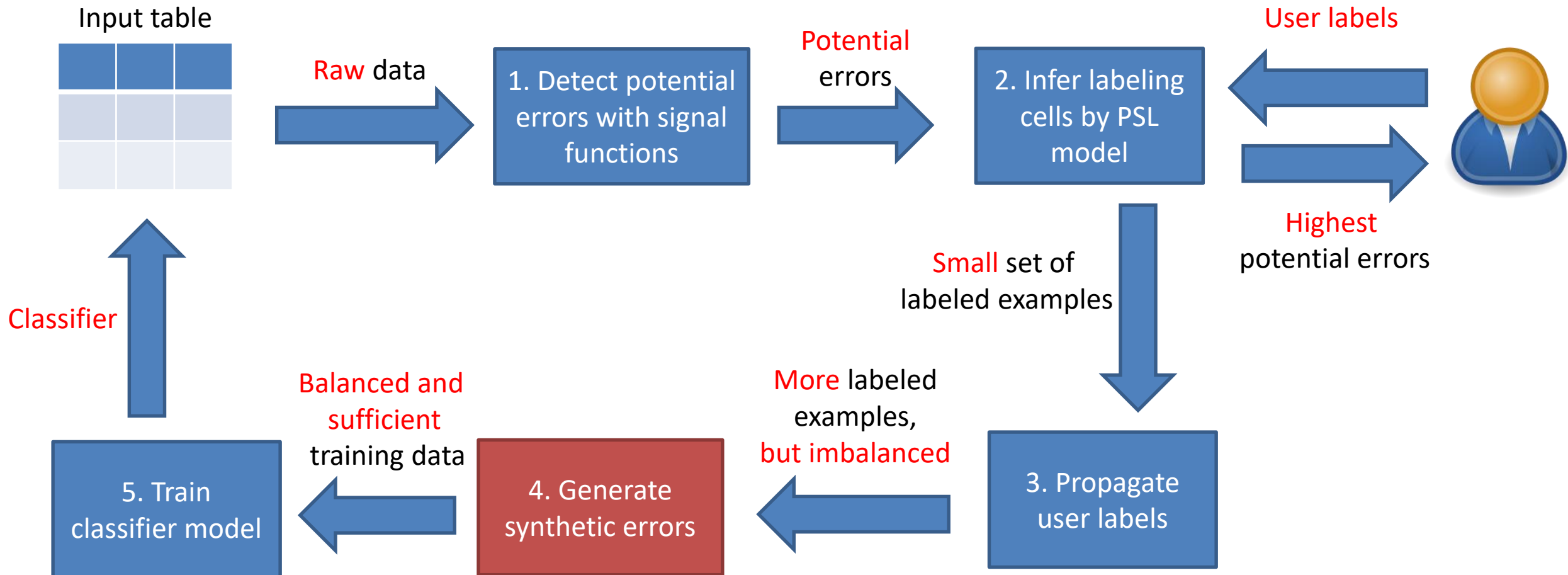
Data	Error probability
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San Francisco CA	0.7
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Chicago	0.11

Label propagation

$$d(\mathbf{e}) = |\mathbf{e}_1 - \mathbf{e}_2| \leq \epsilon$$
$$\epsilon = 0.1$$

# Overall approach



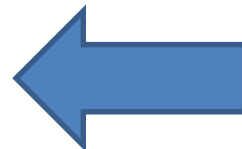
# Synthetic error generation

Data	Error Score
San Francisco CA	0.55
Los Angeles	0.35
Springdale AR	0.59
Bend	0.17
Chicago	0.11

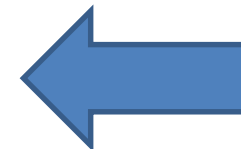


Data	Cleaned data
San Francisco CA	San Francisco
Los Angeles	
Springdale AR	Springdale
Bend	
Chicago	

Generated Errors
San Francisco CA CA
Los Angeles CA
Springdale AR AR
Bend CA
Chicago AR



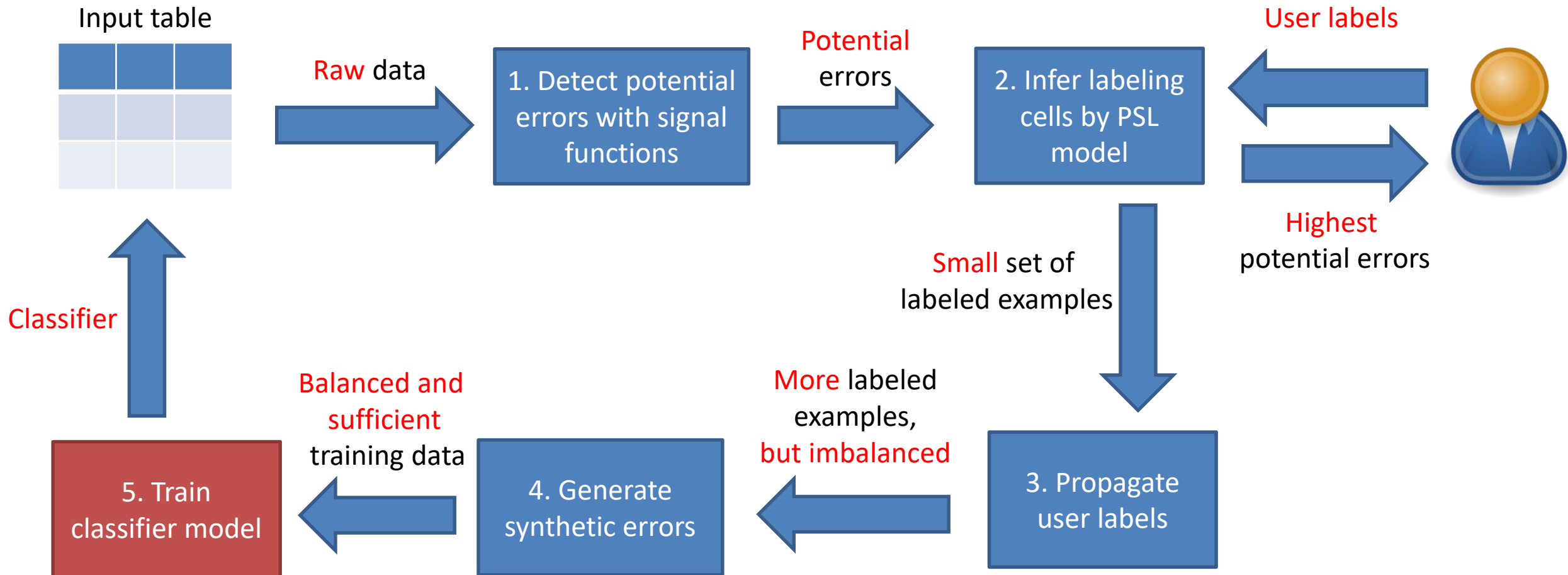
Data
San Francisco CA
Los Angeles
Springdale AR
Bend
Chicago



Learn transformations  
to convert cleaned data  
to erroneous data

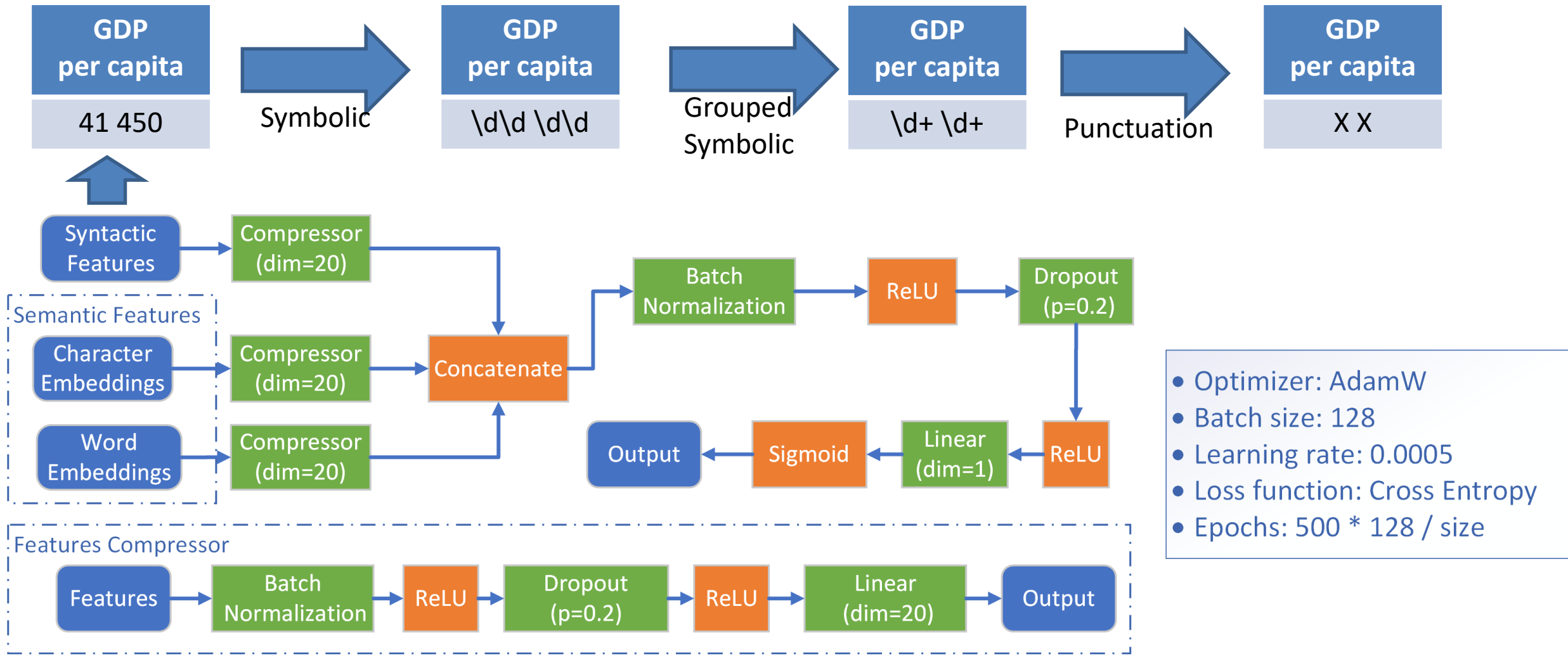
```
INSERT_END("CA")  
INSERT_END("AR")
```

# Overall approach

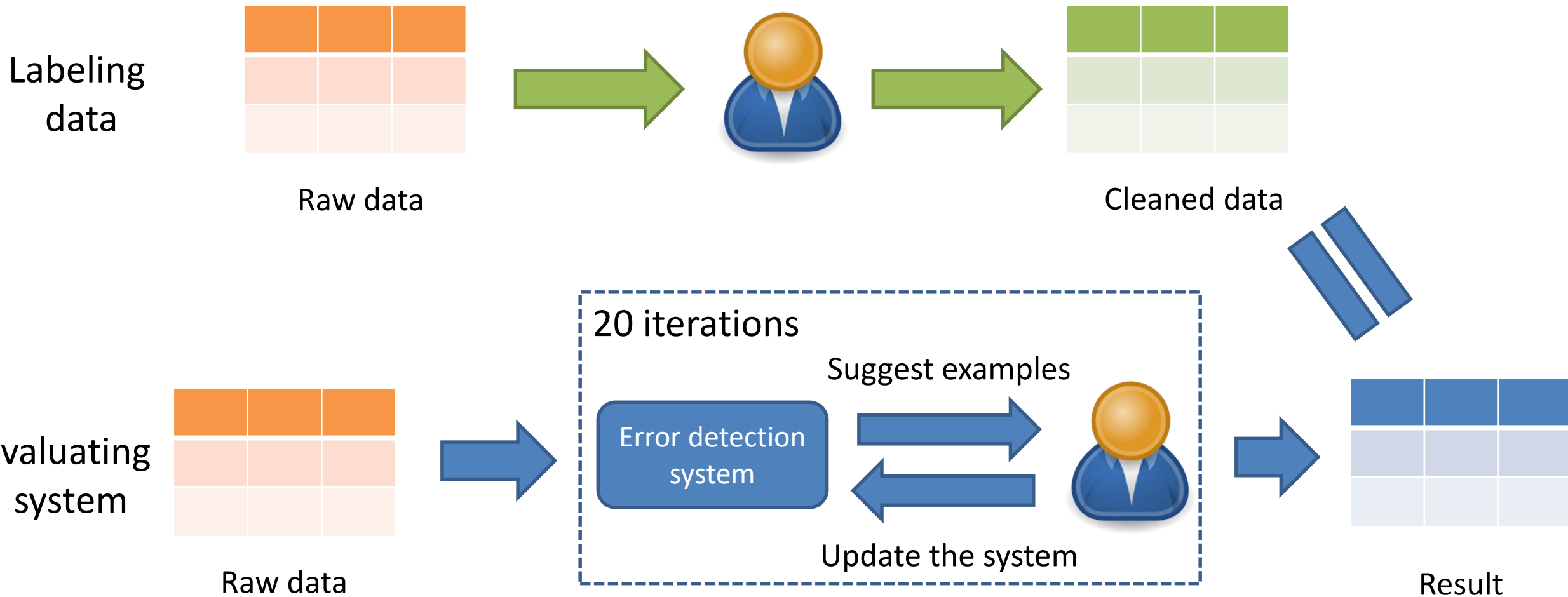




# Training classifier model



# Evaluation process



# Evaluation result

- SPADE outperforms 6 different systems: Raha [Mahdavi et al., 2019], ED2 [Neutatz et al., 2019], dBoost [Mariet et al., 2016], NADEEF [Dallachiesa et al., 2013], KATARA [Chu et al., 2015], ActiveClean [Krishman et al., 2016]
  - Experiment on 5 datasets from Raha
  - Average of ten runs with  $SD = \pm 0.01$ , \*:  $SD = \pm 0.02$ , \*\*:  $SD = \pm 0.03$

Approach	Hospital			Beers			Rayyan			Flights			Movies		
	P	R	F	P	R	F	P	R	F	P	R	F	P	R	F
<i>dBoost</i>	0.07	0.37	0.11	0.34	1.00	0.50	0.05	0.18	0.08	0.25	0.34	0.29	0.25	0.79	0.38
<i>NADEEF</i>	0.05	0.37	0.09	0.13	0.06	0.08	0.30	0.85	0.44	0.42	0.93	0.58	<b>1.00</b>	0.08	0.16
<i>KATARA</i>	0.44	0.11	0.18	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
<i>ActiveClean</i>	0.02	0.15	0.04	0.16	1.00	0.28	0.09	<b>1.00</b>	0.16	0.30	<b>0.99</b>	0.46	0.06	<b>1.00</b>	0.12
<i>ED2</i>	0.45	0.29	0.33	<b>1.00</b>	0.96	0.98	0.80	0.69	0.74	0.79	0.63	0.68	0.93	0.05	0.13
<i>Raha</i>	<b>0.94</b>	0.59	0.72	0.99	0.99	0.99	<b>0.81</b>	0.78	0.79	<b>0.82</b>	0.81	<b>0.81</b>	0.85	0.88	0.86
SPADE	0.93	<b>1.00</b>	<b>0.96</b>	<b>1.00</b>	<b>1.00</b>	<b>1.00</b>	0.80*	0.92*	<b>0.85</b>	0.81**	0.81**	<b>0.81*</b>	<b>0.99</b>	0.83	<b>0.90</b>

# Conclusion

- Novel probabilistic active learning model for minimal user labeling
  - capture signals for both internal and external information
  - iteratively update model to recommend the most informative example
- Data augmentation process where we enrich our training datasets with synthetic data
  - propagate labeled data and generates additional errors
  - generalize better to unseen errors
- Semi-supervised approach for error detection with excellent performance