Linear Programs

Initializing The Simplex Algorithm

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Where We Stand, What We Face?

We now have an algorithm SIMPLEX (*Restricted*), which is conjectured to solve linear programs. For the time being we've shown that it terminates either by specifying that we have an unbounded linear program, or by returning a finite value *expected* to be the maximum we are looking for.

Uptill now, we've been working under the following two assumptions:

- Our linear program is *feasible*; meaning that it has at least one feasible solution
- The basic solution of the initial slack form is feasible.

During this lecture, we are going to build a function INITSIMPLEX taking in a linear program (A, b, c) and either returning back the fact it is **not** feasible or a linear program $(N, B, \underline{A}, \underline{b}, \underline{c}, v)$ in slack form and that has feasible basic solution.



Let *L* be the linear program, given in standard form :

maximize
$$z = v + \sum_{j=1}^{n} c_{j} x_{j}$$
 subject to
$$\forall i \in B, \quad \sum_{j=1}^{n} a_{ij} x_{j} \leq b_{i}$$
 with
$$\forall j \in N, \quad x_{i} \geq 0$$

Out of L we build the following auxiliary linear program L_{marker} :

maximize
$$z=-x_0$$
 subject to
$$\forall i \in B, \quad \sum_{j=1}^n a_{ij}x_j - x_0 \leq b_i$$
 with $\forall j \in N \cup \{0\}, \quad x_j \geq 0$

Proposition

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Proof: Notice first that the optimal objective value of L_{marker} is 0. Therefore, if we show that 0 is an objective value of L_{marker} it is necessarily the optimal one. If L is feasible then there is a tuple (t_1, \ldots, t_n) of non-negative real numbers satisfying all linear constraints of L. The tuple $(0, t_1, \ldots, t_n)$ does thus satisfy L_{marker}

and 0 is then a objective value of L_{marker} , i.e. the optimal one.

Conversely, if L_{marker} has objective value 0 (thus optimal) it is of the form $(0, t_1, ..., t_n)$. Plugging this tuple in the linear constraints of L_{marker} it implies $(t_1, ..., t_n)$ is a solution of L_{marker}

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The difference between L and L_{marker} is that L_{marker} is always feasible :

If *E* is the set of indices of *B* such that b_i is negative then the tuple $(-\min_i\{b_i\}, 0, ..., 0)$ is a feasible solution of L_{marker} .

Thus, temporarily admitting validity of the *restricted* simplex algorithm, if we're able to find a linear program equivalent to L_{marker} which has feasible basic solution then we can decide on feasibilty of L.

Consider the following slack form of L_{marker}

maximize
$$z=-x_0$$
 subject to
$$\forall\,i\in B,\quad x_i=b_i-\sum_{j=1}^n a_{ij}x_j+x_0$$
 with
$$\forall\,j\in N\cup B\cup\{0\},\quad x_j\geq 0$$

Basic solution of L_{marker} is not feasible as soon as L is not, i.e. as soon as one of the b_i is negative. We assume this is the case.

Let k be the index of a minimum b_k among all b_i coefficients. We already know that $(-b_k, 0, ..., 0)$ is a feasible solution of L_{marker} .

Let's now use PIVOT with entering variable 0 and leaving one k. The **same** previous feasible solution of L_{marker} is now the basic solution of the linear program we got after pivotting.

We got an equivalent linear program to L_{marker} having feasible basic solution!

Testing Feasibility

- **Input:** L = (A, b, c) a linear program in standard form having infeasible initial basic solution
- **Output:** An auxiliary linear program having feasible basic solution if L is feasible, raises an exception *infeasible* otherwise.
 - 1: **function** IsFeasible(A, b, c)
- 2: form L_{marker} by adding a column of -1s at the beginning of A and change c to $(-1,0,\ldots,0)$.
- 3: \triangleright corresponds to adding $-x_0$ on the left hand of each linear constraint and to putting objective function to $-x_0$

- 4: let (*N*, *B*, **A**, **b**, **c**, 0) be the resulting slack form of *L*_{marker}
- 5: $k \leftarrow \text{index ofmin}_i\{b_i\}$
- 6: (N, B, A, b, c, 0, k, 0) = PIVOT(N, B, A, b, c, 0, k, 0)
- 7: ightharpoonup The basic solution for L_{marker} is now feasible
- 8: **if** SIMPLEX(N, B, A, b, c, 0) = 0 **then**
- 9: **return** (*N*, *B*, **A**, **b**, **c**, 0)
- 10: **else**
- 11: **raise exception** *infeasible*
 - 12: **end if**
- 13: end function



Getting a Feasible Basic Solution

Assumption

We assume ${\tt IsFeasible}(L)$ didn't raise any exception.

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Under the previous assumption IsFeasible returns an equivalent linear program L' to L_{marker} which has feasible basic solution with objective value 0.

Getting a Feasible Basic Solution

Assumption

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Let's replace the objective value of L' with the one of L we started with. To get a linear program L'' out of this we also need to replace the possible basic variables of the objective value with their expressions in terms of non-basic variables of L'. Let's also make sure that x_0 is not a basic variable of L'' by pivoting L'' with leaving variable x_0 and any other entering variable having non-zero coefficient in the corresponding line.

Fact

Putting x_0 to 0 in L'' gives back a linear program whose equivalent to L and has feasible basic solution.

The InitSimplex Function

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Input: L = (A, b, c) a linear program in standard form
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Output: An equivalent program having feasible basic solution if *L* is feasible.

- 1: **function** InitSimplex(A, b, c)
- 2: **if** IsFEASIBLE(A, b, c) raises an exception **then**
- 3: **raise exception** *infeasible*
- 4: else
- 5: (N, B, A', b', c', v) = ISFEASIBLE(A, b, c)
- 6: **if** 0 is basic **then**
- 7: Choose *e* such that $a'_{0e} \neq 0$
- 8: (N, B, A', b', c', v) = PIVOT(N, B, A', b', c', v, 0, e)
- 9: end if
- 10: Update (c, v) to express objective value in terms non-basic indices
- 11: Remove column corresponding to index 0 from A'
- 12: **return** (N, B, A', b', c, v)
 - 13: **end if**
 - 14: end function

Where We Stand?

We are now able to

- know whether a linear program is feasible or not using ISFEASIBLE
- if it is feasible we can build up an equivalent linear program which has feasible basic solution using INITSIMPLEX
- once we get a linear program having feasible basic solution we can check whether our linear program is unbounded or has a hopefully optimal finite solution using the *restricted* SIMPLEX.

We are left with showing validity of *restricted* SIMPLEX in order to show we indeed got what we hope for in the previous last point.

We call $\ensuremath{\mathsf{SIMPLEX}}$ the algorithm globally going through all previous steps.

