

Exponential Smoothing

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Exponential Smoothing

- Exponential smoothing is a standard way to produce forecasts
- We will focus on linear specification
- Large range specifications including multiplicative models
- Linear with logs is a simple way to have a multiplicative model
- Observed data are $\{X_1, X_2, \dots, X_T\}$

References

1. Hyndman, R.J., & Athanasopoulos, G. (2018) Forecasting: principles and practice, 2nd edition, OTexts: Melbourne, Australia. OTexts.com/fpp2. Accessed on April 15, 2020.

Simple Exponential Smoothing

Random Walk

- The basic EWMA, which is known as Simple Exponential Smoothing (SES)
- Defined using the recursion

$$\hat{X}_{T+1|T} = \alpha X_T + (1 - \alpha) \hat{X}_{T|T-1}$$

- The first forecast is

$$\hat{X}_{2|1} = \alpha X_1 + (1 - \alpha) \hat{X}_{1|0}$$

- $\hat{X}_{1|0}$ is an initial value that is not from the data.
 - ▶ Often set to X_1
- α (and $X_{1|0}$) is commonly estimated using least squares

Underlying Model

- Optimal forecast for an Integrated MA(1)

$$X_{T+1} = X_T - (1 - \alpha) \epsilon_T + \epsilon_{T+1}$$

$$\mathbb{E}_T [X_{T+1}] = X_T - (1 - \alpha) \epsilon_T$$

$$\epsilon_T = X_T - X_{T-1} + (1 - \alpha) \epsilon_{T-1}$$

$$\begin{aligned}\Rightarrow \mathbb{E}_T [X_{T+1}] &= X_T - (1 - \alpha) X_T + (1 - \alpha) X_{T-1} - (1 - \alpha)^2 \epsilon_{T-1} \\&= \alpha X_T + (1 - \alpha) X_{T-1} - (1 - \alpha)^2 \epsilon_{T-1} \\&= \alpha X_T + (1 - \alpha) X_{T-1} - (1 - \alpha)^2 X_{T-1} + (1 - \alpha)^2 X_{T-2} - (1 - \alpha)^3 \epsilon_{T-2} \\&= \alpha X_T + \alpha (1 - \alpha) X_{T-1} + (1 - \alpha)^2 X_{T-2} + (1 - \alpha)^3 \epsilon_{T-2}\end{aligned}$$

- If we assume $\epsilon_0 = 0$

$$\mathbb{E}_T [X_{T+1}] = \alpha \sum_{i=0}^T (1 - \alpha)^i X_{T-i}$$

Forecasts and Prediction Intervals

- Forecasts are always a random walk

$$\hat{X}_{T+h|T} = \hat{X}_{T+1|T}$$

- Prediction Intervals are simple using the IMA analogy

$$PI = \left[\hat{X}_{T+h|T} - 1.96\sigma\sqrt{1 + (h - 1)\alpha^2}, \hat{X}_{T+h|T} + 1.96\sigma\sqrt{1 + (h - 1)\alpha^2} \right]$$

Understanding Prediction Errors

- Note that 2-step forecast error is

$$\begin{aligned} X_{T+2} - \text{E}_T [X_{T+2}] &= X_{T+2} - \text{E}_T [X_{T+1}] \\ &= X_{T+2} - (X_T - (1 - \alpha) \epsilon_T) \\ &= X_{T+1} - (1 - \alpha) \epsilon_{T+1} + \epsilon_{T+2} - (X_T - (1 - \alpha) \epsilon_T) \\ &= (X_T - (1 - \alpha) \epsilon_T + \epsilon_{T+1}) \\ &\quad - (1 - \alpha) \epsilon_{T+1} + \epsilon_{T+2} - (X_T - (1 - \alpha) \epsilon_T) \\ &= \epsilon_{T+1} - (1 - \alpha) \epsilon_{T+1} + \epsilon_{T+2} \\ &= \alpha \epsilon_{T+1} + \epsilon_{T+2} \end{aligned}$$

- Same structure continues for any horizon, so

$$X_{T+h} - \text{E}_T [X_{T+h}] = \epsilon_{T+h} + \sum_{i=1}^{h-1} \alpha \epsilon_{T+i}$$

Conclusions

- Simple Exponential Smoothing is an EWMA
- Forecasts are identical for all horizons
- Depends on two parameters
 - ▶ α : the smoothing parameter
 - ▶ $X_{1|0}$: the initial value
 - ▶ Estimate one or both using LS
- Optimal forecast for an Integrated MA(1)

Exponential Smoothing: Trends and Seasonality

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Holt's Model

Random Walk with Drift

- EWMA extent to include trends using a two-equation system

$$\hat{X}_{T+h|T} = L_T + hB_T$$

$$L_T = \alpha X_T + (1 - \alpha) (L_{T-1} + B_{T-1})$$

$$B_T = \beta (L_T - L_{T-1}) + (1 - \beta) B_{T-1}$$

- Can recursively substitute to gain some insights

$$\begin{aligned} X_{T+1|T} &= L_T + B_T \\ &= \alpha X_T + (1 - \alpha) (L_{T-1} + B_{T-1}) + B_T \\ &= \alpha X_T + (1 - \alpha) (\alpha X_{T-1} + (1 - \alpha) (L_{T-2} + B_{T-2})) + B_T + (1 - \alpha) B_{T-1} \\ &= \alpha X_T + \alpha (1 - \alpha) X_{T-1} + (1 - \alpha)^2 L_{T-2} + B_T + (1 - \alpha) B_{T-1} + (1 - \alpha)^2 B_{T-2} \\ &\vdots \\ &= \alpha \sum_{i=0}^{T-1} (1 - \alpha)^i X_{T-i} + \sum_{j=0}^{T-1} (1 - \alpha)^j B_{T-j} \end{aligned}$$

Trend Smoother

- Holt's model contains two exponential smoothers
- Each of the B_T terms are exponential smoothers

$$B_T = \beta \underbrace{(L_T - L_{T-1})}_{\text{Innovation to levels}} + (1 - \beta) B_{T-1}$$

- Known as double exponential smoothing
- Parameters are α and β
- Initial values L_0 and B_0 can be estimated
- Typical fixed values are $L_0 = X_1$ and B_1 are $(X_n - X_1) / (n - 1)$ for some $n \leq T$
 - ▶ Common to choose $n = 2$

Damped Trends

Limiting Trend Effects

- Dampening adds another option
- Local trend growth but ultimately finite

$$\begin{aligned}\hat{X}_{T+h|T} &= L_T + (\phi + \phi^2 + \dots + \phi^h) B_T \\ L_T &= \alpha X_T + (1 - \alpha) (L_{T-1} + \phi B_{T-1}) \\ B_T &= \beta (L_T - L_{T-1}) + (1 - \beta) \phi B_{T-1}\end{aligned}$$

- Long-run forecast converges to

$$\lim_{h \rightarrow \infty} X_{T+h|T} = L_T + \frac{\phi}{1 - \phi} B_T$$

- ϕ is usually forced to be large
 - ▶ Damped trend forecast is not too far from the trend over short horizons
- If $\phi \approx 1$ then difficult to distinguish from undamped model
- Usually restricted to $0.8 \leq \phi \leq 0.98$
- In practice, damping helps

Holt-Winters

Random walk with drift and Seasonality

- Seasonality is added to produce the Holt-Winters model
- Four equation system

$$\hat{X}_{T+h|T} = L_T + hB_T + S_{T+h-m(k+1)}$$
$$L_T = \underbrace{\alpha(X_T - S_{T-m})}_{\text{Deseasonalized}} + (1 - \alpha)(L_{T-1} + B_{T-1})$$
$$B_T = \beta(L_T - L_{T-1}) + (1 - \beta)B_{T-1}$$
$$S_T = \underbrace{\gamma(X_T - L_{T-1} - B_{T-1})}_{\text{Surprise rel Level and Trend}} + (1 - \gamma)S_{T-m}$$

- System of $2 + m$ smoothers
- Each seasonality is as its own EWMA/SES using a modified shock
- $k = \lfloor (h - 1) / m \rfloor$

Damped Trend

Limiting Trend Effects

- Can be damped to reduce trend effects

$$\hat{X}_{T+h|T} = L_T + (\phi + \phi^2 + \dots + \phi^h) B_T + S_{T+h-m(k+1)}$$

$$L_T = \alpha (X_T - S_{T-m}) + (1 - \alpha) (L_{T-1} + \phi B_{T-1})$$

$$B_T = \beta (L_T - L_{T-1}) + (1 - \beta) \phi B_{T-1}$$

$$S_T = \gamma (X_T - L_{T-1} - \phi B_{T-1}) + (1 - \gamma) S_{T-m}$$

- Damping parameter $0.8 \leq \phi \leq 0.98$

Prediction Intervals

- 95% prediction intervals are complicated in the larger models

$$PI = \left[\hat{X}_{T+h|T} \pm 1.96\sigma\psi_h \right]$$

- Trend

$$\psi_h^2 = 1 + (h - 1) \left[\alpha^2 + \alpha^2\beta h + \frac{1}{6}\alpha^2\beta^2 h (2h - 1) \right]$$

- Damped Trend

$$\begin{aligned} \psi_h^2 = & 1 + \alpha^2 (h - 1) + \frac{\alpha\beta\phi h}{(1 - \phi)^2} [2\alpha(1 - \phi) + \alpha\beta\phi] \\ & - \frac{\alpha\beta\phi(1 - \phi^h)}{(1 - \phi)^2(1 - \phi^2)} [2\alpha(1 - \phi^2) + \alpha\beta\phi(1 + 2\phi - \phi^h)] \end{aligned}$$

- Holt-Winters

$$\psi^2 = 1 + (h - 1) \left[\alpha^2 + \alpha^2\beta h + \frac{1}{6}\alpha^2\beta^2 h (2h - 1) \right] + \gamma k \{2\alpha + \gamma + \alpha\beta m(k + 1)\}$$

- Damped Holt-Winters: Too long to type!

Conclusions

- Holt's Models includes two exponential smoothers
 - ▶ Level and Trend
- The Holt-Winters Model uses $2 + m$ exponential smoothers
 - ▶ Level, Trend, and Seasonal (m)
- Damping the trend adds additional flexibility
 - ▶ Limits the long-run effect of the trend on the forecast
 - ▶ Generally improves performance
- Prediction intervals are available for all four specifications