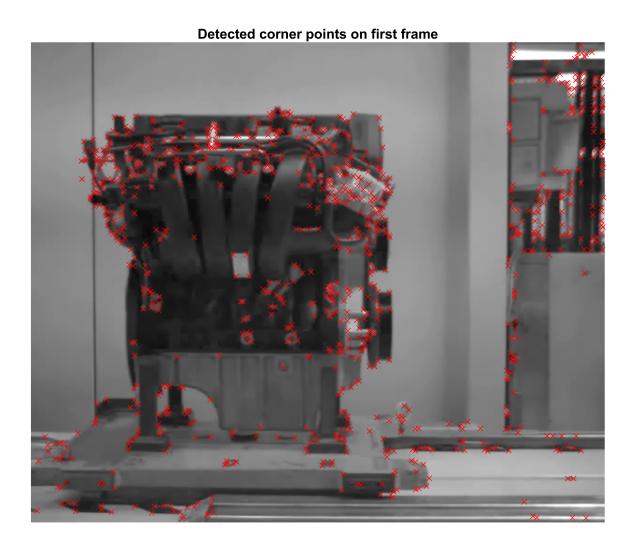
# Image and Video Processing - Task 4

## Motion tracking of feature points and dense optical flow

Daniel Kuknyo [Y80L35]

#### Read and setup

```
clear all; close all; clc;
% Read input
max_displacement = 2;
vname = 'motor.avi';
video = VideoReader(vname);
videoFrame = readFrame(video);
% Detect points on the video to track
points = detectMinEigenFeatures(rgb2gray(videoFrame));
points = points.Location;
% Visualize points
imshow(videoFrame);
hold on;
for i = 1:size(points, 1)
    px = points(i, 1);
    py = points(i, 2);
    plot(px, py, 'x', 'Color', 'red');
title('Detected corner points on first frame');
hold off;
```



#### Initialize tracker, player and writer

```
videoPlayer = vision.VideoPlayer('Position', [100 100 [size(videoFrame, 2), size(videoFrame, 1),
pointTracker = vision.PointTracker('MaxBidirectionalError', max_displacement);
initialize(pointTracker, points, videoFrame);

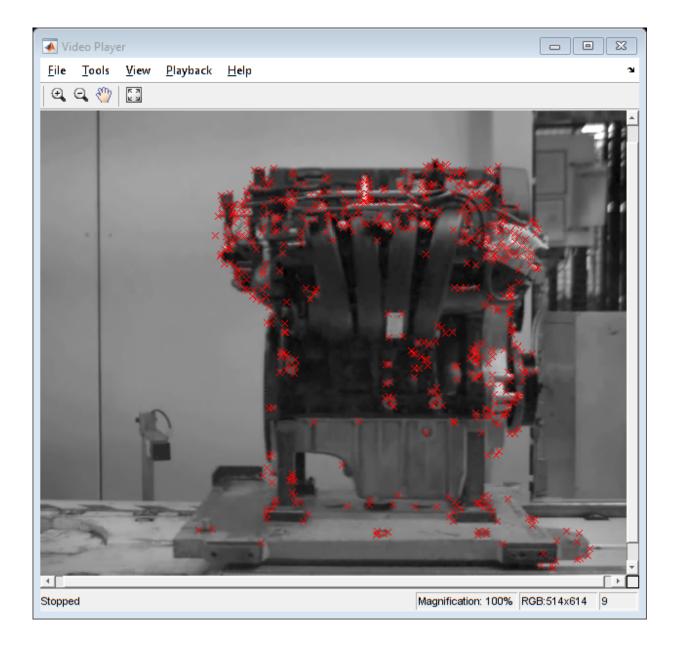
oldPoints = points;

writer = VideoWriter(strcat('output_', vname), 'Uncompressed AVI');
writer.FrameRate = 1;
open(writer);
```

### **Tracking the points**

```
i = 1;
while hasFrame(video)
  vframe = readFrame(video); % Next frame
```

```
[points, isFound] = step(pointTracker, vframe);
    visiblePoints = points(isFound, :);
    oldInliers = oldPoints(isFound, :);
    if size(visiblePoints, 1) >= 2 % need at least 2 points
       % Estimate the geometric transformation
        [xform, inlierIdx] = estimateGeometricTransform2D(...
            oldInliers, visiblePoints, 'similarity', 'MaxDistance', 4);
        oldInliers = oldInliers(inlierIdx, :);
       visiblePoints = visiblePoints(inlierIdx, :);
       % Create frame with markers
       vframe = insertMarker(vframe, visiblePoints, 'x-mark', 'Color', 'red');
       writeVideo(writer, vframe);
        oldPoints = visiblePoints;
       setPoints(pointTracker, oldPoints);
    end
    % Display the annotated video frame using the video player object
    step(videoPlayer, vframe);
end
close(writer);
release(pointTracker);
release(videoPlayer);
```



### Setting up for optical flow

```
video = VideoReader(vname);
optical_writer = VideoWriter(strcat('output_opticFlow_', vname), 'Uncompressed AVI');
optical_writer.FrameRate = 1;
open(optical_writer);

opticFlow = opticalFlowHS();

h = figure;
movegui(h);
hViewPanel = uipanel(h,'Position', [0 0 1 1], 'Title','Plot of Optical Flow Vectors');
hPlot = axes(hViewPanel);
i = 1;
while hasFrame(video)
if(mod(i,4) == 0 || i == 1)
```

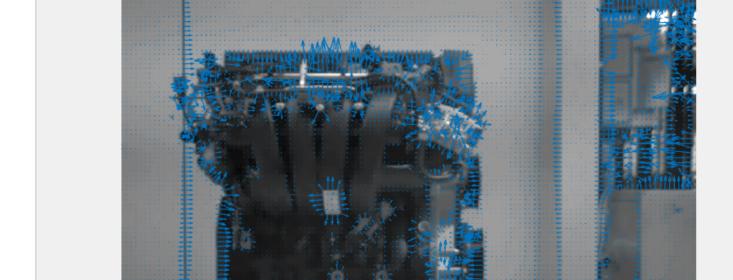
```
vframe = readFrame(video);
    gframe = im2gray(vframe);
    flow = estimateFlow(opticFlow, gframe);
    imshow(vframe)

    hold on
    plot(flow, 'DecimationFactor', [5 5], 'ScaleFactor', 60, 'Parent', hPlot);
    hold off

    F = getframe(hPlot);
    iframe = frame2im(F);
    writeVideo(optical_writer, iframe);
    end

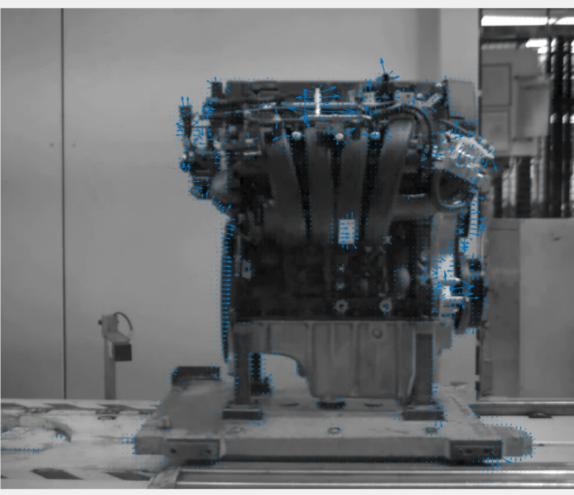
    pause(10^-3)
    i = i + 1;
end
```

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Plot of Optical Flow Vectors

Plot of Optical Flow Vectors



close(optical\_writer);