Data communication and networking Hw-II

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Q1) a) Given frame Payload:-

DDEEDDD F DOED

=) now we will see when a flag byte occurs

in the data thun we will add ESC byte
before it, also in this way it we see

that an Esc byte is Present then we will
add an additional ESC before it too.

byte-Stuffed frame Payload:

DDEEEEDDDDEFD

b) Given flag bits = 01111110 Given Frame:

000 1111111000111110 1000 1111111111110000111

Ans//: => now for bit staff we will see that whenever five consecutive 1's are Present in the data, then we will insert a o after it to avoid confusion with the flag Sequence given = 01111110

So the frame will be:

Q2) a) Show the generation of the CRC-32 codeword at the Sender Site lusing binary division) when the dataword is "ARC" in ASCII.

Ans/:- first of all converting ARC in Binary:

> C= 0 | 000011 A = 01 000001 B = 010000 10

=> combining: 010000010100001000011 => Since this Ps cRc-32, -> 80 we will have to add 32 zeros to the D. = doing division here i'n textual format because of space constraint 011 199999 Vol 0000 1001000011 0000000000 11100100000010001101101110000000000 10000010011000010001110110110111 110011001010000101010101010110 \_ /00000100110000010001110110110111 10011101011000000100100011011001

11 0 110 10 10 110 111 11 100 110 100 100 100 10 100000010011000001000111011011011 1011110011101101101000010100101 100000 100 1100 000 1000 11 101 10 1101 1 69/11000001011001011110011111101 \$00001001100000100011101101101 11/01/00/00/10000/1000/00/00/100/00 100000100110000010001110110110110 V/0101/010100000000011001 00000110 /1000001001100000000011011011011 910100110000000000000100101100010 16000010011000001000111011011011 ro101111100000100010100110101010 100000 100 1100000 1000111011011011 0101101111000 101010011101 11000 =) this approach was time consuming got errors in between this So wrote a basic Python code for calculating the remainder

```
def remainder(dataword, divisor):
    data=list(map(int, dataword))
    divisor=list(map(int, divisor))
   #adding zeroes in last
   data.extend([0]*(len(divisor)-1)) #this will end zeroes (in our case will append 32 0's)
   for i in range(len(dataword)): #running the loop for xor of every bit with divisor
       #since we only need to peform xor if the current bit in dataword is 1:
       if data[i]==1:
           for j in range(len(divisor)):
               data[i+j]= data[i+j] ^ divisor[j]
    #remainder will be the last bits after the division
    remainder=data[-(len(divisor)-1):]
   return ''.join(map(str, remainder))
dataword = '010000010100001001000011' #we got this dataword for ABC in asci-II
divisor = '100000100110000010001110110110111' #divisor which was given
remainder=remainder(dataword, divisor)
print("remainder is:", remainder)
```

Sheve I used Simple level code for the Purpose of calculating semainder.

# Outfut remainders-

PS C:\Users\Dell> & C:/Python311/python.exe "e:/fall 24/DCN/remainder.py" remainder is: 10101111100000100010100110101010
PS C:\Users\Dell>

Remain Ler 8-

10101111110000001000101010101010

=) Since final codeword:

Original dataword + remain

b) for checking the Syndrome we will

check that it we divide the

codeword reviewed by divisor then

we get all o's or not in remainder

if all o's -> codeword accepted

if not -> codeword not accepted by

reciever

```
fall 24 > DCN > ♥ remainder.py > ...
    def check_codeword(codeword, divisor):
        data=list(map(int, codeword))
        divisor=list(map(int, divisor))
       for i in range(len(codeword)-len(divisor)+1):
           if data[i]==1:
               for j in range(len(divisor)):
                   data[i + j]= data[i + j]^divisor[j]
        syndrome=data[-(len(divisor)-1):]
        return ''.join(map(str, syndrome))
    #codeword which we got after combining the original dataword and the remainder
    divisor = '1000001001100000100011101101101111'
    syndrome=check_codeword(codeword, divisor)
    print("syndrome is:",syndrome)
    #checking whether we are getting all 0's as remainder or not
    if syndrome == '0' * (len(divisor) - 1):
       print("codeword is accepted")
    else:
20
       print("codeword is rejected")
```

Used the code which I already wrote in the Part (a), just removed the O's Padding Part from the function definition Since now we avent dealing with the dataward which needed 32 o's to be added.

The Nemainder as all O's.

calculated Syndrome:

the recieved codeword is accepted by the reciever because the calculated Syndrome is all zeros which Shows us that no errors were detected during the transmission. Also, this zero Syndrome implies that the transmitted data word when appended with the remainder has not changed the Pattern and the data hence the codeword is accepted.

c) I inserted the given codeword Pn my Python code which will do the division Process and tell whether we have O syndrome or not:

```
fall 24 > DCN > @ remainder.py >
    def check_codeword(codeword, divisor):
       data=list(map(int, codeword))
       divisor=list(map(int, divisor))
       for i in range(len(codeword)-len(divisor)+1):
           if data[i]==1:
               for j in range(len(divisor)):
                   data[i + j]= data[i + j]^divisor[j]
       syndrome=data[-(len(divisor)-1):]
       return ''.join(map(str, syndrome))
    #codeword which we got after combining the original dataword and the remainder
    divisor = '1000001001100000100011101101101111'
14
    syndrome=check_codeword(codeword, divisor)
    print("syndrome is:",syndrome)
    #checking whether we are getting all 0's as remainder or not
    if syndrome == '0' * (len(divisor) - 1):
       print("codeword is accepted")
    else:
       print("codeword is rejected")
```

PS C:\Users\Dell> & <u>C:/Python311/python.exe</u> "e:/fall 24/DCN/remainder.py" syndrome is: 001100011001111011100101011110100 codeword is rejected

es Since we can see that the Syndrome
is not zero hence the codeword will
be rejected by the reciever

$$\frac{ds}{d\alpha} = 1 \cdot e^{-2\alpha} + \alpha \cdot (-2) \cdot e^{-2\alpha}$$

$$\frac{ds}{d\alpha} = e^{-2\alpha} \cdot (1-2\alpha)$$

$$e^{-2\alpha} \cdot (1-2\alpha) = 0$$

$$1-2\alpha = 0$$

$$(\alpha = 1/2) \rightarrow (\text{oudition})$$

$$4 \text{ or max}$$

$$4 \text{ or max}$$

$$4 \text{ through Rut}$$

$$2) \text{ Slotted aloha } % -$$

$$S = \alpha \cdot e^{-\alpha}$$

$$\frac{ds}{d\alpha} = \frac{d}{d\alpha} (\alpha \cdot e^{-\alpha})$$

$$u = \alpha \quad \text{of } \alpha = -\alpha$$

$$u = \alpha \quad \text{of } \alpha = -\alpha$$

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$$\frac{ds}{ds} = 1 \cdot e^{-c} + c \cdot (-1) \cdot e^{-c}$$

$$\frac{ds}{ds} = e^{-c} \cdot (1-c) = 0$$

1-G=0
[G=1]

(ondition for max throughput

Protocol where the device transmits data whenever it has information to Send and it doen't writs for a specific time Slot, if for example lets Say two devices transmit at the Same time a collision will occur and both nessages will be lost and then each device will retransmit after the random delay. While the Slotted aloha infrores on the Pove aloha by dividing time into

Slots, the devices are only allowed to transmit the data at the beginning of each time Slot.

Pure albha -> max throughput -> 18.4%

Slotted aloha -> 4 -> 36.8%

In a CSMA/CD network, devices begin transmitting as soon as they sense that the channel is clear. However, if two devices start transmitting nearly simultaneously, a collision can occur. For effective collision detection, the transmitting device must remain active on the network long enough to detect any collisions that might occur as the signal propagates to the farthest point on the network and back, known as the round-trip time requirement. If the frame is too short, a device could finish transmitting before the collision signal has time to return, resulting in undetected collisions and errors on the network. Ensuring a sufficient frame length allows each station to detect collisions before completing its transmission, thereby maintaining network reliability.

- **Propagation Delay**: In a CSMA/CD network, it takes time Tp for the signal to propagate from one end of the network to the other. If a collision occurs at the far end, it will take another Tp for the collision signal to propagate back to the transmitting station.
- Frame Transmission Time: If Tfr is shorter than 2·TP a station could finish sending its frame before it even realizes that a collision occurred. This would defeat the purpose of collision detection.
- **Ensuring Collision Detection**: By ensuring Tfr≥2·TP the rule guarantees that:
  - The transmitting station will still be actively sending data when the collision signal reaches it.
  - This enables the station to detect the collision and retransmit the frame later, following the CSMA/CD protocol.

Given:

Tfr=40us

Tp=25us

- Station A starts sending a frame at t=0 μs
- Station B starts sending a frame at t=20 μs

#### **Does Station A Detect Collision?**

Station A starts transmitting a frame at  $t=0~\mu s$  and will complete its transmission by  $t=40~\mu s$ . If a collision occurs, the collision signal takes Tp=25  $\mu s$  to reach Station A. By the time this signal arrives at  $t=25~\mu s$ , Station A is still transmitting. Since A continues to transmit until  $t=40~\mu s$  it will ultimately detect the collision. Therefore, Station A will detect the collision.

#### Does station B detect collision?

Station B starts sending its frame at  $t=20~\mu s$ . If a collision happens, it means both Station A and Station B are trying to send data at the same time. Since Station B has already begun sending its data when the collision occurs, it will be able to notice that something went wrong. When a collision happens, the signals from both stations interfere with each other. This interference creates a collision signal that travels back through the network. Because Station B started sending its frame at  $t=20~\mu s$  and the collision occurs shortly after that, the collision signal will reach Station B while it is still transmitting. As a result, Station B can detect the collision during its transmission. It will recognize

that its data did not go through correctly, prompting it to stop transmitting and try again later. Therefore, Station B will detect the collision.

# c) For the given network $Tp = 25 \mu s$ and data rate of 10Mbps, suggest the appropriate value of Tfr and minimum frame size so that both station can detect collision.

Using the rule;

Tfr >= 2.Tp

Tfr>=2x25us (given Tp=25us)

#### Tfr > = 50us

Minimum frame size=Tfr x Data rate

Data rate=10mbps (given);

Minimum frame size= 50us (found earlier) x 10mbps

Minimum frame size= $50x10^{(-6)}s x 10 x 10^{(6)}$ 

Minimum frame size= 500bits

# Q5) Contrast different types of MAC addresses and state one use case for each type of MAC address in different LAN settings.

#### 1. Unicast MAC Address

- A unicast MAC address is a unique identifier assigned to a network interface card (NIC) that
  allows for one-to-one communication. This address is used to send data to a specific device
  on a network.
- uses:
  - o **File Sharing**: Transmitting files directly between two computers in a local network.
  - o **VoIP Calls**: Establishing a one-on-one voice call between two IP phones, ensuring that audio packets are sent to the intended recipient.
  - o **Secure Connections**: Creating a direct encrypted connection between a user's device and a secure server for data transfer, such as in VPN connections.

## 2. Broadcast MAC Address

- A broadcast MAC address allows data packets to be sent to all devices on a network segment. The standard broadcast address in Ethernet networks is FF:FF:FF:FF:FF.
- Uses:
  - ARP Requests: Address Resolution Protocol (ARP) requests use the broadcast MAC address to map IP addresses to MAC addresses within a local network, allowing devices to discover each other's addresses.
  - **Network Time Protocol (NTP)**: NTP servers may use broadcast messages to synchronize time across all devices in a network simultaneously.
  - o **Software Updates**: Sending broadcast messages to notify all devices on a network about available software updates or maintenance tasks.

### 3. Multicast MAC Address

• A multicast MAC address is used to send data packets to a specific group of devices rather than all devices (as with broadcast) or a single device (as with unicast). Multicast addresses are typically in the range of 01:00:5E:00:00:00 to 01:00:5E:7F:FF:FF.

#### Uses:

- **Video Conferencing**: Sending video and audio streams to multiple participants in a video conference using multicast addresses to optimize bandwidth.
- Online Gaming: Multiplayer online games often use multicast to send game state updates to multiple players connected in the same local network.
- Sensor Networks: In IoT applications, multicast can be used to send sensor data to multiple applications or devices that need to receive updates simultaneously.

# Difference between the Different Types of MAC Addresses

- Unicast: One-to-one communication, where data is sent to a specific device only.
- o **Broadcast**: One-to-all communication, where data is sent to every device on the network.
- Multicast: One-to-many communication, where data is sent to a specific group of devices that have joined a multicast group.

# • In terms of efficiency;

- o **Unicast**: Efficient for direct communication but can lead to high traffic if many devices are sending data to a single device simultaneously.
- **Broadcast**: Efficient for sending the same message to multiple devices, but can lead to network congestion if overused, as all devices must process the broadcast frame.
- Multicast: More efficient than broadcast when sending data to multiple specific devices, as only those devices in the multicast group process the data, reducing overall network load.

# **Q6**)

# A)

The IEEE 802.3 standard for 40Gbps and 100Gbps Ethernet introduces several advancements that differentiate these high-speed Ethernet technologies from earlier standards, such as 10Gbps Ethernet.

# 1. Physical Layer Specifications

- Cabling: 40GbE and 100GbE support similar cabling options, including multimode fiber (MMF) using QSFP+ SR4 optics. 100GBASE-SR10 uses 10 lanes over multimode fiber, and, in contrast, the single-mode version of this module achieves a distance of up to two miles while employing four wavelengths.
- Transceivers & Connectors: Your information will allow any connection, the standards
  defines different types of transceiver mostly CFP (C Form-factor Pluggable) for 100Gbps
  connections that operates at various implementations such as 100GBASE-SR10 and
  100GBASE-LR4.

# 2. Modulation Techniques and Encoding Schemes

• Encoding Schemes: Different encoding schemes are crucial to an effective application of data over communication steams. This includes, for instance, the definition of a 40GbE **that can** 

- take advantage of a 64b/66b encoding scheme instead of the 8b/10 used in legacy Ethernet implementations to provide lower overhead and increased efficiency than its older sibling at >100 Gbps data rates.
- Baseband Modulation Techniques: Progress in modulation techniques allows for faster data rates on the same cabling. Wavelength division multiplexing (WDM) is used in 100GBASE-LR4 for example to have signals on different wavelengths over the same fiber.

## 3. Maximum Transmission Distances

• Transmission Distances: 40GbE can achieve a maximum distance of 150 meters over OM3 multimode fiber and up to 400 meters over OM4 fiber. In contrast, 100GbE can reach up to 100 meters on OM3 and 150 meters on OM4 fiber. For single-mode fiber, both standards support longer distances, with 100GBASE-LR4 achieving distances of up to 10 kilometers.

#### 4. Data Rate

• **Data Rates**: The main distinguishing feature is the significant increase in data rates. While 10Gbps Ethernet allows for speeds of up to 10 Gbps, 40GbE operates at 40 Gbps, and 100GbE operates at 100 Gbps. This increase allows for faster data transmission and the ability to handle larger amounts of network traffic

# 5. Signal Types

- **Signal Types**: 40GbE and 100GbE utilize multiple signal types, including:
  - o **10GBASE-R** for 10 Gbps links,
  - o 40GBASE-SR4 for short-range multimode applications,
  - o 100GBASE-SR10 for short-range multimode applications,
  - o 100GBASE-LR4 for long-range single-mode applications

These signal types allow for flexibility in deployment and compatibility with existing infrastructure while providing options for both short-range and long-range connectivity. The IEEE 802.3 standard for 40Gbps and 100Gbps Ethernet introduces critical advancements in physical layer specifications, modulation techniques, maximum transmission distances, data rates, and signal types, significantly enhancing network performance compared to earlier standards like 10Gbps Ethernet. These improvements cater to the growing demand for higher bandwidth and faster data transmission in modern network environments.

Q7) a) Sun	of all words
	= 4500 + 0073 + 0000
	+ 4000
4500	
+ 0073	
4573	() One's complement:
	(8573)16
4573	1,
1	1000 0101 0111 0011
4573	
$\downarrow$	(7A8c) ← 0111 1010 1000 1100
4573	16
+ 4000	
8573	CheckSum= (7ABC)16
	7 (8