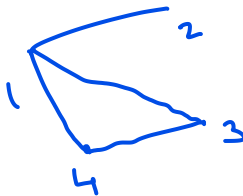


Graph theory

Definition

An undirected graph $G = (V, E)$ consists of V , a nonempty set of vertices (or nodes) and E , a set of edges (edge is an unordered pair of vertices).

eg. $G_1 = (\underbrace{\{1, 2, 3, 4\}}_V, \underbrace{\{\{1, 2\}, \{3, 4\}, \{1, 4\}, \{1, 3\}\}}_E)$



Definition

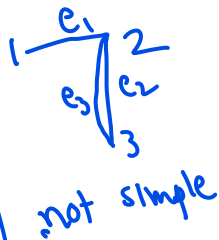
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Note: If either V or E is infinite then G is called **Infinite graph**, otherwise finite.

Definition

A graph in which each edge connects two different vertices and where no two edges connect the same pair of vertices is called a simple graph.

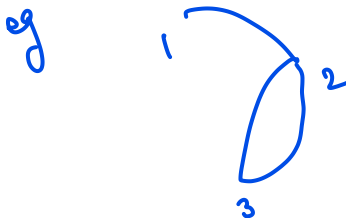
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Graphs that may include loops, and possibly multiple edges connecting the same pair of vertices or a vertex to itself, are sometimes called **pseudographs**.

Definition

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A graph with both directed and undirected edges is called a mixed graph.

Type	Edges	Multiple Edges Allowed?	Loops Allowed?
Simple graph	Undirected	No	No
Multigraph	Undirected	Yes	No
Pseudograph	Undirected	Yes	Yes
Simple directed graph	Directed	No	No
Directed multigraph	Directed	Yes	Yes
Mixed graph	Directed and undirected	Yes	Yes

Definition

Two vertices u and v in an undirected graph G are called adjacent (or neighbors) in G if u and v are endpoints of an edge e of G .

Such an edge e is called incident with the vertices u and v and e is said to connect u and v .

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Question: Construct a graph with 4 vertices of degree 2, 3, 4, 2.

Theorem (THE HANDSHAKING THEOREM)

Let $G = (V, E)$ be an undirected graph with m edges. Then

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Definition

When (u, v) is an edge of the graph G with directed edges, u is said to be **adjacent** to v and v is said to be adjacent from u . The vertex u is called the **initial vertex** of (u, v) , and v is called the **terminal or end vertex** of (u, v) . The initial vertex and terminal vertex of a loop are the same.

Definition

In a graph with directed edges the **in-degree** of a vertex v , denoted by $\deg^-(v)$, is the number of edges with v as their terminal vertex. The **out-degree** of v , denoted by $\deg^+(v)$, is the number of edges with v as their initial vertex.

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$$\sum_{v \in V} \deg^-(v) = \sum_{v \in V} \deg^+(v) = |E|$$

Some Special Simple Graphs

Complete Graph on n vertices: K_n , is a simple graph that contains exactly one edge between each pair of distinct vertices.

Draw complete graphs with 1, 2, 3, 4 vertices.

A **cycle** C_n , $n \geq 3$, consists of n vertices v_1, v_2, \dots, v_n and edges $\{v_1, v_2\}, \{v_2, v_3\}, \dots, \{v_{n-1}, v_n\}$, and $\{v_n, v_1\}$.

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Wheel W_n when we add an additional vertex to a cycle C_n , for $n \geq 3$, and connect this new vertex to each of the n vertices in C_n , by new edges.

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A simple graph G is called **bipartite** if its vertex set V can be partitioned into two disjoint sets V_1 and V_2 such that every edge in the graph connects a vertex in V_1 and a vertex in V_2 (so that no edge in G connects either two vertices in V_1 or two vertices in V_2).

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Theorem

A simple graph is bipartite if and only if it is possible to assign one of two different colors to each vertex of the graph so that no two adjacent vertices are assigned the same color.

Marriages on an Island: Suppose that there are m men and n women on an island. Each person has a list of members of the opposite gender acceptable as a spouse. We construct a bipartite graph $G = (V_1, V_2)$ where V_1 is the set of men and V_2 is the set of women so that there is an edge between a man and a woman if they find each other acceptable as a spouse.

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Theorem (HALL'S MARRIAGE THEOREM)

The bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) has a complete matching from V_1 to V_2 if and only if $|N(A)| \geq |A|$ for all subsets A of V_1 .

Generating New Graphs from Old

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A subgraph of a Graph $G = (V, E)$ is a graph $H = (W, F)$ such that $W \subseteq V$, $F \subseteq E$

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Adjacency lists: For a graph with no multiple edges.

Vertex	Adjacent vertices
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Isomorphism of Graphs

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The simple graphs $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ are isomorphic if there exists a bijective function f from V_1 to V_2 with the property that a and b are adjacent in G_1 if and only if $f(a)$ and $f(b)$ are adjacent in G_2 , for all a and b in V_1 .

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Still there is no polynomial time (worst case) algorithm for graph isomorphism.

Connectivity

For an undirected graph G , a **path** of length n is a sequence of edges e_1, e_2, \dots, e_n that begins at a vertex of a graph and travels from vertex to vertex along edges of the graph, where $e_i = \{x_i, x_{i+1}\}$.

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A directed graph is **weakly connected** if there is a path between every two vertices in the underlying undirected graph. An isomorphic invariant for simple graphs is the existence of a simple circuit of length k , where k is a positive integer greater than 2.

Euler Paths and Circuits

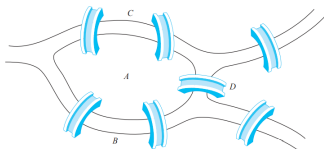


FIGURE 1 The Seven Bridges of Königsberg.

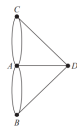


FIGURE 2 Multigraph Model of the Town of Königsberg.

Question: Is it possible to start at some location in the town, travel across all the bridges once without crossing any bridge twice, and return to the starting point?

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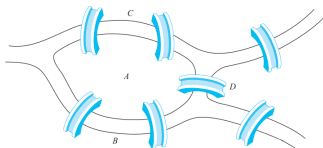


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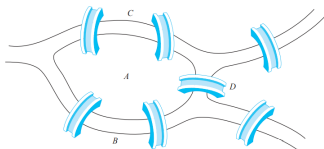


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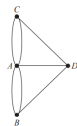


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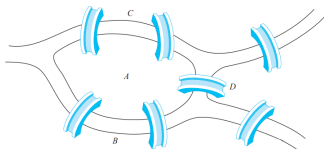


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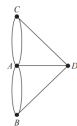


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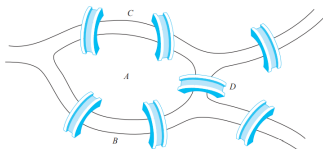


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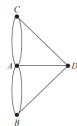


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NECESSARY AND SUFFICIENT CONDITIONS FOR EULER CIRCUITS AND PATHS

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A connected multigraph with at least two vertices has an Euler path if and only if each of its vertices has even degree except 2 vertices (i.e., exactly 2 vertices have odd degree).

ALGORITHM 1 Constructing Euler Circuits.

procedure *Euler*(G : connected multigraph with all vertices of even degree)
 circuit := a circuit in G beginning at an arbitrarily chosen vertex with edges successively added to form a path that returns to this vertex
 $H := G$ with the edges of this circuit removed
 while H has edges
 subcircuit := a circuit in H beginning at a vertex in H that also is an endpoint of an edge of *circuit*
 $H := H$ with edges of *subcircuit* and all isolated vertices removed
 circuit := *circuit* with *subcircuit* inserted at the appropriate vertex
 return *circuit* {*circuit* is an Euler circuit}

Hamilton Path and Circuit

A simple path in a graph $G=(V, E)$ that passes through every vertex exactly once is called a **Hamilton path**, i.e. x_0, x_1, \dots, x_n is a Hamilton path iff $V=\{x_0, x_1, \dots, x_n\}$ and $x_i \neq x_j$ for $i \neq j$

Hamilton Path and Circuit

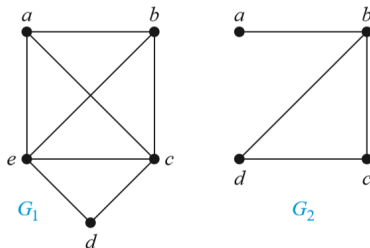
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Theorem (Dirac's Theorem)

If G is a simple graph with n vertices with $n \geq 3$ such that the degree of every vertex in G is at least $n/2$, then G has a Hamilton circuit.

Theorem (Ore's Theorem)

If G is a simple graph with n vertices with $n \geq 3$ such that $\deg(u) + \deg(v) \geq n$ for every pair of nonadjacent vertices u and v in G , then G has a Hamilton circuit.

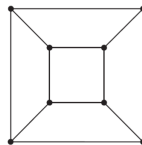
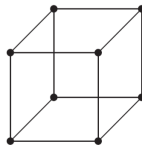
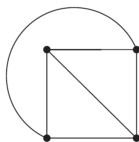
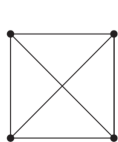
Hamilton Circuits has applications in traveling salesperson problem, coding theory.

Planar Graphs

A graph is called **planar** if it can be drawn in the plane without any edges crossing. Such a drawing is called a planar representation of the graph.

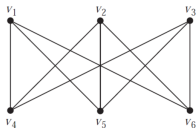
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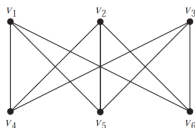


A graph may be planar even if it is usually drawn with crossings, because it may be possible to draw it in a different way without crossings.

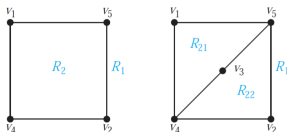
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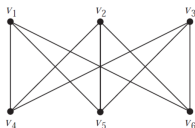


the vertices v_1 and v_2 must be connected to both v_4 and v_5 . These four edges form a closed curve that splits the plane into two regions, R_1 and R_2

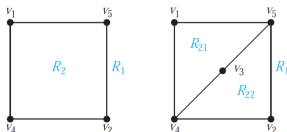


The vertex v_3 is in either R_1 or R_2 . When v_3 is in R_2 , the inside of the closed curve, the edges between v_3 and v_4 and between v_3 and v_5 separate R_2 into two subregions, R_{21} and R_{22} .

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There is no way to place the final vertex v_6 without forcing a crossing.

APPLICATIONS OF PLANAR GRAPHS Planarity of graphs plays an important role in the design of **electronic circuits**. We can model a circuit with a graph by representing components of the circuit by vertices and connections between them by edges. We can print a circuit on a single board with no connections crossing if the graph representing the circuit is planar.

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Corollary (2)

If G is a connected planar simple graph then G has a vertex of degree not exceeding five.

If a graph is planar, so will be any graph obtained by removing an edge $\{u, v\}$ and adding a new vertex w together with edges $\{u, w\}$ and $\{w, v\}$. Such an operation is called an **elementary subdivision**.

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Theorem (Kuratowski's Theorem)

A graph is nonplanar if and only if it contains a subgraph homeomorphic to $K_{3,3}$ or K_5 .

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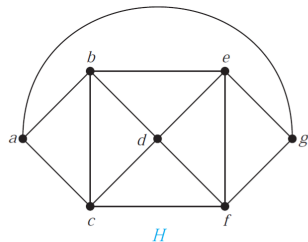
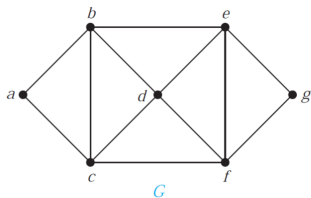
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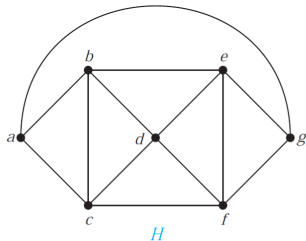
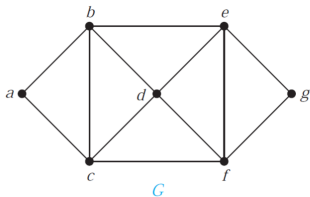
Theorem (THE FOUR COLOR THEOREM)

The chromatic number of a planar graph is no greater than four.

What are the chromatic numbers of the graphs G and H :

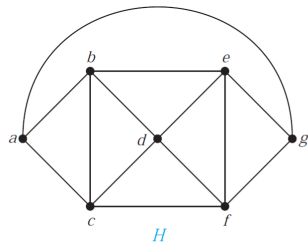
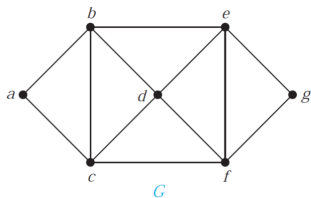


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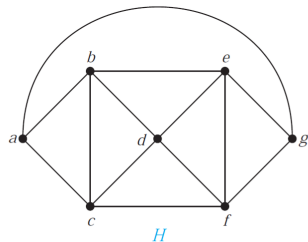
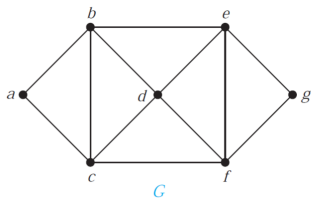
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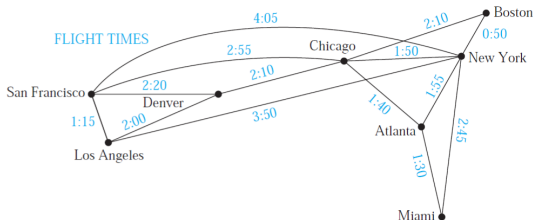
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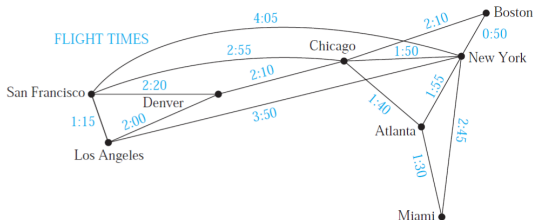
Shortest-Path Problems

Weighted Graph: Graphs that have a number assigned to each edge are called weighted graphs.



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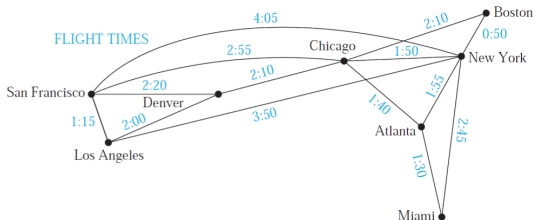
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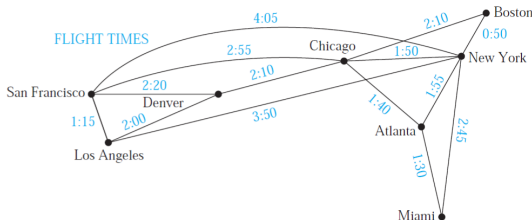


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Question: Find a shortest path from San Francisco to Boston.

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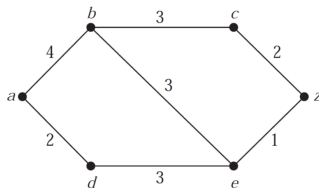
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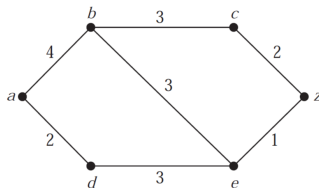
San Francisco, New York, Boston: $4:05 + 0:50 = 4:55$

San Francisco, Chicago, Boston: $2:55 + 2:10 = 5:05$

Shortest-Path Algorithm: Dijkstra

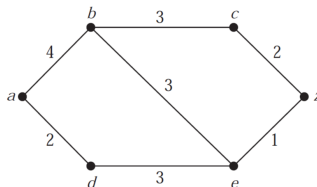


Shortest-Path Algorithm: Dijkstra



Question: Find a shortest path from a to z .

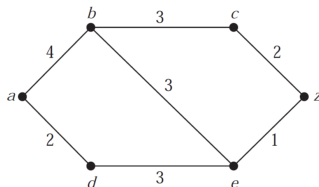
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Idea: find the length of a shortest path from a to successive vertices, until z is reached.

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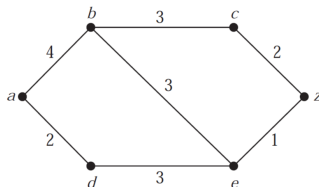


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The only paths starting at a that contain no vertex other than a are formed by adding an edge that has a as one endpoint: a, b of length 4 and a, d of length 2.

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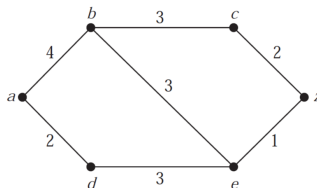
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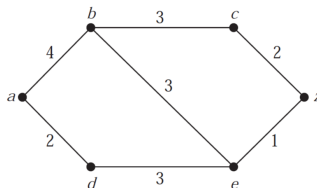
d is the **closest vertex** to a and the shortest path from a to d has length 2.

Ctd...



find the second closest vertex by examining all paths that begin with the shortest path from a to a vertex in the set $\{a, d\}$, followed by an edge that has one endpoint in $\{a, d\}$ and its other endpoint is not in this set.

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There are two such paths to consider, a, d, e of length 7 and a, b of length 4. Hence, the **second closest** vertex to a is b and the shortest path from a to b has length 4.

To find the third closest vertex to a , we need to examine only the paths that begin with the shortest path from a to a vertex in the set $\{a, d, b\}$, followed by an edge that has one endpoint in the set $\{a, d, b\}$ and its other endpoint not in this set.

To find the third closest vertex to a , we need to examine only the paths that begin with the shortest path from a to a vertex in the set $\{a, d, b\}$, followed by an edge that has one endpoint in the set $\{a, d, b\}$ and its other endpoint not in this set.

There are three such paths, a, b, c of length 7, a, b, e of length 7, and a, d, e of length 5. Because the shortest of these paths is a, d, e the **third closest** vertex to a is e .

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To find the fourth closest vertex to a , we need to examine only the paths that begin with the shortest path from a to a vertex in the set $\{a, d, b, e\}$, followed by an edge that has one endpoint in the set $\{a, d, b, e\}$ and its other endpoint not in this set.

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To find the fourth closest vertex to a , we need to examine only the paths that begin with the shortest path from a to a vertex in the set $\{a, d, b, e\}$, followed by an edge that has one endpoint in the set $\{a, d, b, e\}$ and its other endpoint not in this set. There are two such paths, a, b, c of length 7 and a, d, e, z of length 6. Because the shorter of these paths is a, d, e, z , the **fourth closest** vertex to a is z and the length of the shortest path from a to z is 6

ALGORITHM 1 Dijkstra's Algorithm.

procedure *Dijkstra*(G : weighted connected simple graph, with
all weights positive)

{ G has vertices $a = v_0, v_1, \dots, v_n = z$ and lengths $w(v_i, v_j)$
where $w(v_i, v_j) = \infty$ if $\{v_i, v_j\}$ is not an edge in G }

for $i := 1$ **to** n

$L(v_i) := \infty$

$L(a) := 0$

$S := \emptyset$

{the labels are now initialized so that the label of a is 0 and all
other labels are ∞ , and S is the empty set}

while $z \notin S$

$u :=$ a vertex not in S with $L(u)$ minimal

$S := S \cup \{u\}$

for all vertices v not in S

if $L(u) + w(u, v) < L(v)$ **then** $L(v) := L(u) + w(u, v)$

{this adds a vertex to S with minimal label and updates the
labels of vertices not in S }

return $L(z)$ { $L(z)$ = length of a shortest path from a to z }

The **traveling salesperson problem** asks for the circuit of minimum total weight in a weighted, complete, undirected graph that visits each vertex exactly once and returns to its starting point. This is equivalent to asking for a Hamilton circuit with minimum total weight in the complete graph, because each vertex is visited exactly once in the circuit.

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No algorithm with polynomial worst-case time complexity.