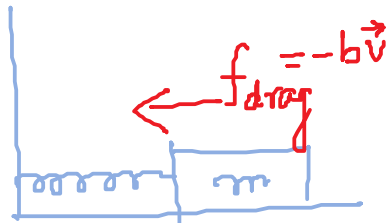


Harmonic Oscillations



Undamped

$$\vec{F} = -\vec{f}_s$$

$$\ddot{x} + \frac{k}{m}x = 0$$

$$x(t) = C \cos(\omega_0 t + \phi)$$

$$\omega_0 = \sqrt{\frac{k}{m}}$$

Damped

$$\vec{F} = -\vec{f}_s - \vec{f}_{\text{drag}}$$

Lightly
critically
Heavily

Forced
oscillation

$$\ddot{x} + \frac{b}{m}\dot{x} + \frac{k}{m}x = 0$$

$$\gamma = \frac{b}{m}, \quad \omega_0 = \sqrt{\frac{k}{m}}$$

Damped Ho:

$$\ddot{z} + \gamma \dot{z} + \omega_0^2 z = 0$$

$$z = a + iy$$

$$x(t) = \text{Re}[z]$$

$$z = z_0 e^{i\alpha t}$$

↓

$$[(i\alpha)^2 + i\gamma\alpha + \omega_0^2] z_0 e^{i\alpha t} = 0$$

$$\alpha^2 - i\gamma\alpha - \omega_0^2 = 0$$

$$\alpha = \frac{i\gamma \pm \sqrt{4\omega_0^2 - \gamma^2}}{2} = \frac{i\gamma}{2} \pm \sqrt{\omega_0^2 - \frac{\gamma^2}{4}}$$

$$\omega_0^2 < \frac{\gamma^2}{4}$$

$$\omega_0^2 = \frac{\gamma^2}{4}$$

$$\omega_0^2 = \frac{k}{m}, \quad \gamma^2 = \frac{b^2}{m^2}$$

1. Lightly: $\omega_0^2 > \frac{\gamma^2}{4}$, $\sqrt{\omega_0^2 - \frac{\gamma^2}{4}} > 0$, $\left. \begin{matrix} z_+ \\ z_- \end{matrix} \right\} \rightarrow$

$$x(t) = C e^{-\frac{\gamma}{2}t} [\cos(\omega t + \phi)]$$

$$Z_{initial} = C \cos \phi, \quad \tan \phi = \frac{-\gamma}{2\omega}$$

2. Critically damped: $\omega_0^2 = \frac{\gamma^2}{4}$, $\alpha = \frac{i\gamma}{2}$

$$Z_1(t) = c e^{-\frac{\gamma}{2}t} \cos \omega t = \underbrace{c e^{-\frac{\gamma}{2}t}}_{\text{critically damped}} \cos \omega t$$

$$\lim_{\omega \rightarrow 0} Z_2(t) = \lim_{\omega \rightarrow 0} c_1 e^{-\frac{\gamma}{2}t} \sin \omega t = 0$$

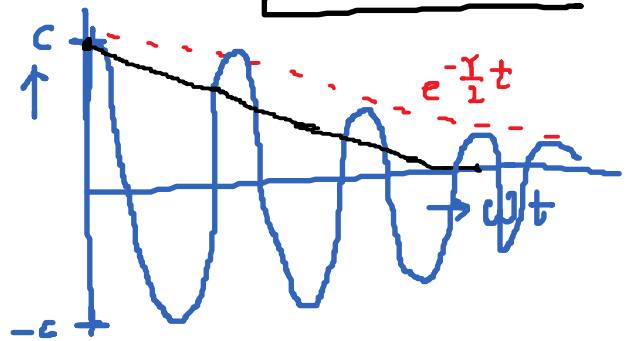
$$\omega = \sqrt{\omega_0^2 - \frac{\gamma^2}{4}}$$

$$\omega \rightarrow 0$$

$$\omega > 0$$

$$\lim_{\omega \rightarrow 0} \frac{Z_2(t)}{\omega} = \lim_{\omega \rightarrow 0} c e^{-\frac{\gamma}{2}t} \cdot \frac{\sin \omega t}{\omega}$$

$$= c_2 t e^{-\frac{\gamma}{2}t}$$



$$Z(t) = (c_1 + c_2 t) e^{-\frac{\gamma}{2}t}$$

Critically damped

2. Heavily damped:-

$$\alpha = \frac{i\gamma}{2} \pm \sqrt{\omega_0^2 - \frac{\gamma^2}{4}}, \quad \omega_0^2 < \frac{\gamma^2}{4}$$

Imaginary

$$\Gamma = \sqrt{\frac{\gamma^2}{4} - \omega_0^2}$$

$$\alpha_{\pm} = \frac{i\gamma}{2} \pm i\Gamma$$

$$Z(t) = Z_0 e^{i\alpha t} = Z_0 e^{i(\frac{i\gamma}{2} \pm i\Gamma)t}$$

$$Z(t) = Z_0 e^{-\left(\frac{\gamma}{2} \pm \Gamma\right)t}$$

$$Zcy = Z_0 e$$

$$1. \omega_0^2 > \frac{\gamma^2}{4} \Rightarrow x(t) = C e^{-\frac{\gamma}{2}t} \cos(\omega t + \phi), \quad \omega = \sqrt{\omega_0^2 - \frac{\gamma^2}{4}}$$

$$2. \omega_0^2 = \frac{\gamma^2}{4} \Rightarrow x(t) = (A + Bt) e^{-\frac{\gamma}{2}t}$$

$$3. \omega_0^2 < \frac{\gamma^2}{4} \Rightarrow x(t) = C_1 e^{-\left(\frac{\gamma}{2} \pm r\right)t}$$

Energy of Lightly Damped No: $\omega_0^2 > \frac{\gamma^2}{4}$

$$x(t) = C e^{-\frac{\gamma}{2}t} \cos(\omega t + \phi)$$

$$E(t) = K \cdot E(t) + P \cdot E(t) = \frac{1}{2} m \dot{\vartheta}^2 + \frac{1}{2} K x^2$$

$$\dot{\vartheta} = -\frac{\gamma}{2} C e^{-\frac{\gamma}{2}t} \cos(\omega t + \phi) - C e^{-\frac{\gamma}{2}t} \omega \sin(\omega t + \phi)$$

$$= -\omega C e^{-\frac{\gamma}{2}t} \left[\sin(\omega t + \phi) + \left(\frac{\gamma}{2\omega} \right) \cos(\omega t + \phi) \right]$$

Small and negligible

$$\dot{\vartheta} = -\omega C e^{-\frac{\gamma}{2}t} \sin(\omega t + \phi)$$

$$E(t) = \frac{1}{2} m \omega^2 C^2 e^{-\gamma t} \sin^2(\omega t + \phi)$$

$$+ \frac{1}{2} K C^2 e^{-\gamma t} \cos^2(\omega t + \phi)$$

Underdamped

$$x(t) = C \cos(\omega_0 t + \phi)$$

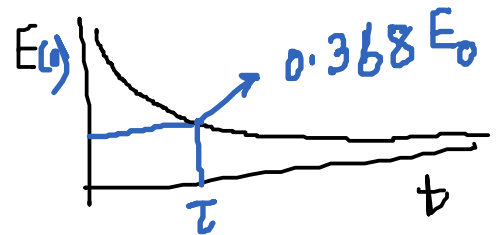
$$\dot{\vartheta}(t) = -C \omega_0 \sin(\omega_0 t + \phi)$$

$$K E(t) = \frac{1}{2} m C^2 \omega_0^2 \sin^2(\omega_0 t + \phi)$$

$$+ \frac{1}{2} K \epsilon^2 e^{-\gamma t} \cos^2(\omega t + \phi)$$

$$\Rightarrow \boxed{E(t) = \frac{1}{2} K \epsilon^2 e^{-\gamma t}} \Rightarrow E(0) = \frac{1}{2} K \epsilon^2$$

$$E(t) = E(0) e^{-\gamma t}$$



$$\underline{\gamma \tau = 1},$$

$$E(t) = 0.368 E_0$$

$$\frac{b}{m} = 1 \Rightarrow \boxed{\tau = \frac{m}{b}}$$

$$\underline{E(t) = E_0 e^{-\gamma t}} \Rightarrow \frac{dE}{dt} = -\gamma E_0 e^{-\gamma t} = -\gamma E$$

Q-factor of the oscillator \Rightarrow

$$Q = \frac{\text{Energy stored in the oscillator}}{\text{Energy dissipated per radian}} = \frac{E}{\gamma E / \omega} = \frac{\omega}{\gamma} \approx \frac{\omega_0}{\gamma}$$

$$\boxed{\frac{dE}{dt} = -\gamma E}$$

$$\Rightarrow \Delta E \approx \left| \frac{dE}{dt} \right| \Delta t \approx \gamma E \Delta t \approx \frac{\gamma E}{\omega}$$

$$\omega \Delta t = 1 \Rightarrow \boxed{\Delta t = \frac{1}{\omega}}$$

$$\omega = \sqrt{\omega_0^2 - \frac{\gamma^2}{4}}$$

$$\omega \approx \omega_0$$

very small

$$\gamma = b/m$$

$$\omega = \sqrt{\omega_0^2 - \frac{\gamma^2}{4}}$$

lightly

$$Q = \frac{\omega}{\gamma} \approx \frac{\omega_0}{\gamma} \gg 1$$

Liquidity

$$M = \frac{M^*}{2} = \frac{M^*}{2} > \frac{M^*}{2} \quad \omega = \sqrt{\omega_0^2 - \frac{1}{4}}$$