



$$x = \gamma \sin \theta \cos \phi$$

$$y = \gamma \sin \theta \sin \phi$$

$$z = \gamma \cos \theta$$

$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k} = \gamma\hat{r}$$

$$= \gamma \sin \theta \cos \phi \hat{i} + \gamma \sin \theta \sin \phi \hat{j} + \gamma \cos \theta \hat{k}$$

$$\hat{r} = \frac{\vec{r}}{|\vec{r}|}$$

$$= \sin \theta \cos \phi \hat{i} + \sin \theta \sin \phi \hat{j} + \cos \theta \hat{k}$$

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$$\nabla = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right)$$

$$\nabla \cdot \vec{F} =$$

$$\nabla \times \vec{F} =$$

$\hat{r}, \hat{\theta}, \hat{\phi}$

$$\hat{\theta} = \frac{\frac{\partial \vec{r}}{\partial \theta}}{\left| \frac{\partial \vec{r}}{\partial \theta} \right|} = \frac{\gamma \cos \theta \cos \phi \hat{i} + \gamma \cos \theta \sin \phi \hat{j} - \gamma \sin \theta \hat{k}}{\gamma}$$

$\boxed{\hat{\theta} = \cos \theta \cos \phi \hat{i} + \cos \theta \sin \phi \hat{j} - \sin \theta \hat{k}}$

$$\vec{r} = \underline{\gamma \sin \theta \cos \phi \hat{i} + \gamma \sin \theta \sin \phi \hat{j} + \gamma \cos \theta \hat{k}}$$

$$\hat{\beta} = \frac{\frac{\partial \vec{r}}{\partial \phi}}{\left| \frac{\partial \vec{r}}{\partial \phi} \right|} = \frac{-\gamma \sin \theta \sin \phi \hat{i} + \gamma \sin \theta \cos \phi \hat{j}}{\gamma \sin \theta} \quad \boxed{\hat{\beta} = -\sin \phi \hat{i} + \cos \phi \hat{j}}$$

$\hat{i}, \hat{j}, \hat{k}$

$$\left\{ \begin{array}{l} \hat{\gamma} = \sin \theta \cos \phi \hat{i} + \sin \theta \sin \phi \hat{j} + \cos \theta \hat{k} \\ \hat{\theta} = \cos \theta \cos \phi \hat{i} + \cos \theta \sin \phi \hat{j} - \sin \theta \hat{k} \\ \hat{\rho} = -\sin \phi \hat{i} + \cos \phi \hat{j} \end{array} \right.$$

$$\begin{aligned} \hat{i} \cdot \hat{i} &= 1 \\ \hat{i} \cdot \hat{\theta} &> 0 \end{aligned}$$

∇ ? in spherical polar coordinates

$$\vec{dl} = dx \hat{i} + dy \hat{j} + dz \hat{k}$$

$$\left\{ \begin{array}{l} T(x_1, y_1, z_1) \\ T(x_2, y_2, z_2) \end{array} \right.$$

$$dT = \frac{\partial T}{\partial x} dx + \frac{\partial T}{\partial y} dy + \frac{\partial T}{\partial z} dz$$

$$dT = (\vec{\nabla} T) \cdot \vec{dl}$$

$$\nabla = i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z}$$

$$d u(r, \theta, \phi) = \frac{\partial u}{\partial r} dr + \frac{\partial u}{\partial \theta} d\theta + \frac{\partial u}{\partial \phi} d\phi = \vec{\nabla} u \cdot \vec{dl} \quad | \quad dT = \vec{\nabla} T \cdot \vec{dl}$$

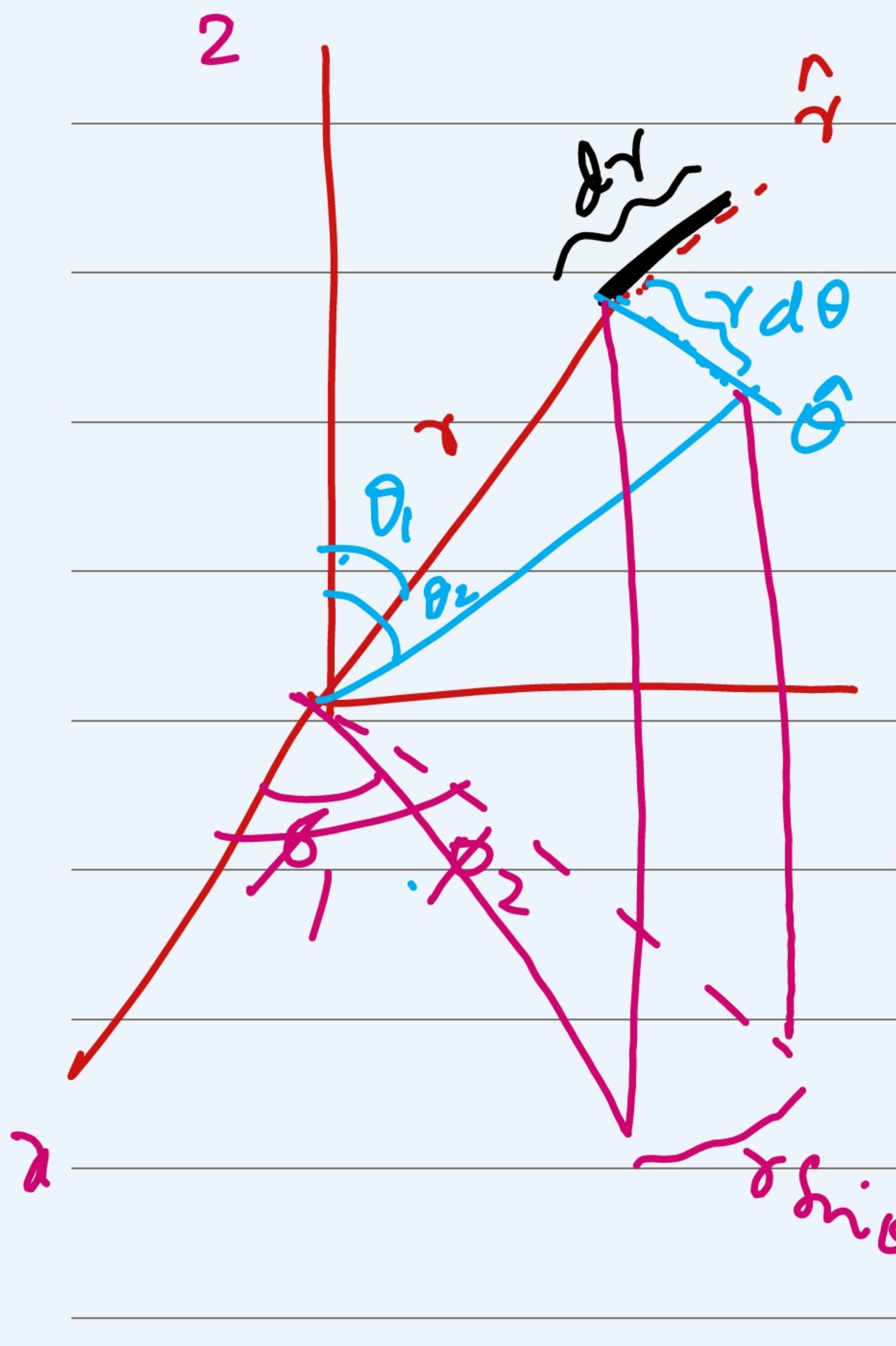
$$= \underbrace{[(\nabla u)_r \hat{r} + (\nabla u)_\theta \hat{\theta} + (\nabla u)_\phi \hat{\phi}]}_{\text{red bracket}}$$

$$\begin{aligned} \vec{dl} &= dr \hat{r} \\ &+ r d\theta \hat{\theta} \\ &+ r \sin \theta d\phi \hat{\phi} \end{aligned}$$

$$= (\nabla u)_r dr + (\nabla u)_\theta d\theta + (\nabla u)_\phi d\phi$$

$\hat{r} \hat{\theta} \hat{\phi}$

$$\boxed{\nabla u = \frac{\partial u}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial u}{\partial \theta} \hat{\theta} + \frac{1}{r \sin \theta} \frac{\partial u}{\partial \phi} \hat{\phi}}$$



$$d\vec{r} = \underline{dr} \hat{r} + \underline{r d\theta} \hat{\theta} + \underline{r \sin\theta d\phi} \hat{\phi}$$

$$dT = dl_r dl_\theta dl_\phi$$

$$= r^2 \sin\theta dr d\theta d\phi$$

Spherical polar $\nabla = \underline{\frac{\partial}{\partial r}} \hat{r} + \underline{\frac{1}{r} \frac{\partial}{\partial \theta}} \hat{\theta} + \underline{\frac{1}{r \sin\theta} \frac{\partial}{\partial \phi}} \hat{\phi}$

Cartesian $\nabla = \underline{i} \frac{\partial}{\partial x} + \underline{j} \frac{\partial}{\partial y} + \underline{k} \frac{\partial}{\partial z}$.

$$\vec{r} \times \vec{A}$$

$$\vec{A} = A_r \hat{r} + A_\theta \hat{\theta} + A_\phi \hat{\phi}$$

$$\vec{\nabla} \cdot \vec{A} = \left[\hat{r} \frac{\partial}{\partial r} + \frac{\hat{\theta}}{r} \frac{\partial}{\partial \theta} + \frac{\hat{\phi}}{r \sin \theta} \frac{\partial}{\partial \phi} \right] \cdot [A_r \hat{r} + A_\theta \hat{\theta} + A_\phi \hat{\phi}]$$

$$\frac{\hat{r}}{r^2} = 0$$

$$= \hat{r} \cdot \underline{\frac{\partial}{\partial r} [A_r \hat{r}]}$$

$$= \hat{r} \cdot \left[\frac{\partial A_r}{\partial r} \hat{r} + A_r \frac{\partial \hat{r}}{\partial r} \right]$$

$$\vec{A} = \vec{F} = \frac{1}{r^2} \hat{r}$$

$$\boxed{\nabla \cdot \vec{A} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (A_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial A_\phi}{\partial \phi}.}$$

$$\iiint (\nabla \cdot \vec{F}) d\tau = \iint \vec{F} \cdot d\vec{a}$$

$\hat{r} da = d\theta d\phi \hat{r}$

1. $\vec{F} = r^2 \hat{r}$

$$\iint \vec{F} \cdot \hat{r} da = r^2 \sin\theta d\theta d\phi$$

$$= 4\pi R^4$$

$\vec{\nabla} \cdot \vec{F} = \frac{1}{r^2} \frac{\partial}{\partial r} [r^2 \vec{r}] = 4$

$$\iiint (\nabla \cdot F) d\tau = \iint_R r^2 \sin\theta dr d\theta d\phi$$

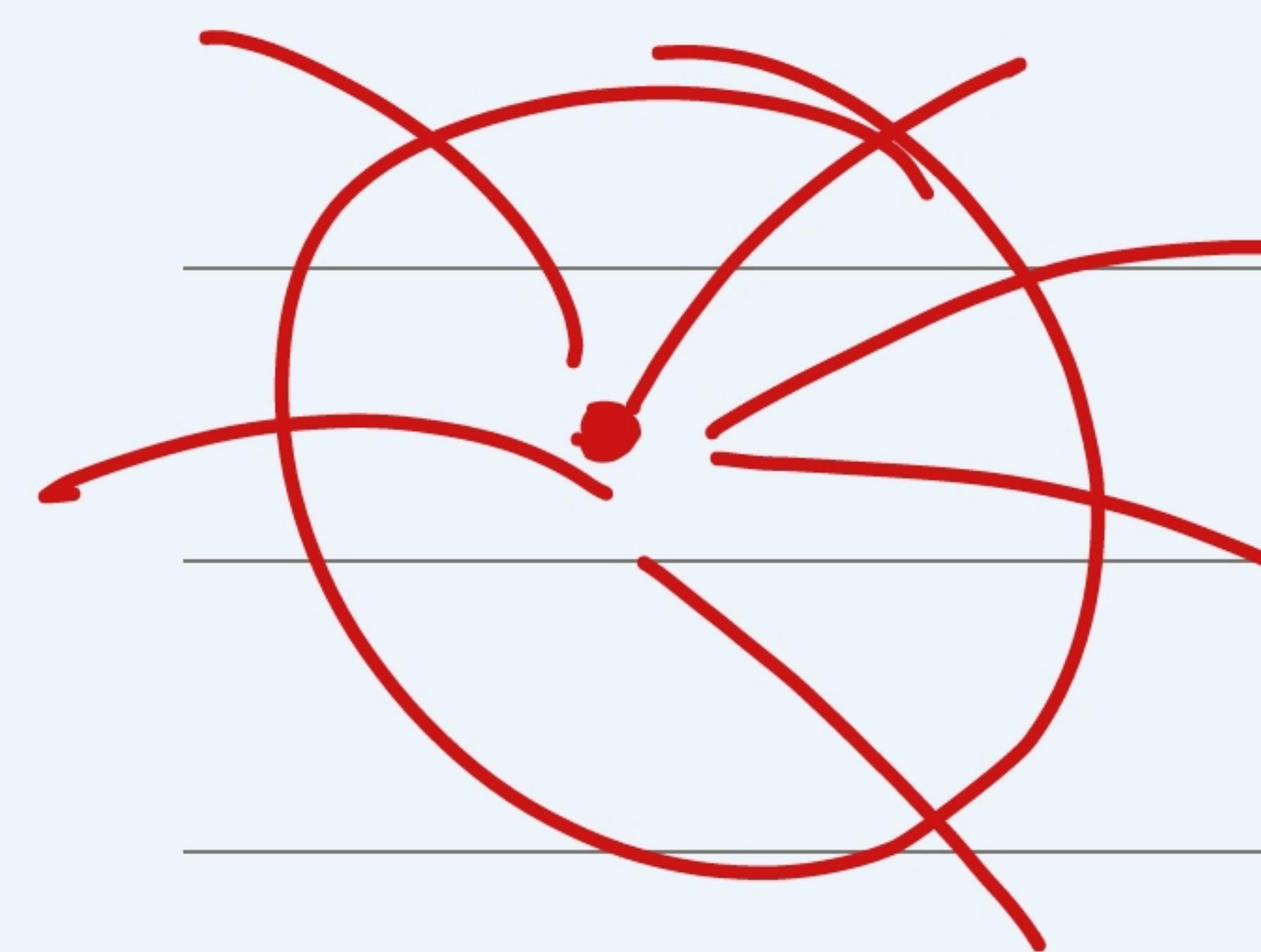
$$\iiint (\nabla \cdot F) d\tau = 4 \int_0^R r^3 dr \int_0^\pi \sin\theta d\theta \int_0^{2\pi} d\phi = 4\pi R^4$$

$$\vec{F}_2 = \frac{\gamma \hat{r}}{r^2}$$

$$\iiint_V (\nabla \cdot \vec{F}_2) d\tau = \iint_A \vec{F}_2 \cdot d\vec{a}$$

$\rightarrow 4\pi$

$$\nabla \cdot \vec{F}_2 = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{1}{r^2} \right) = 0$$



$$\int_0^{2\pi} \int_0^\pi \vec{F}_2 \cdot d\vec{a} \hat{r} = r^2 \sin\theta d\theta d\phi \hat{r}$$

$$\int_0^{2\pi} \int_0^\pi \vec{F}_2 \cdot d\vec{a} = \frac{\sin\theta d\theta d\phi}{2} \frac{1}{2\pi}$$

$= 4\pi$

Dirac-Delta function.

$$\exp \left[-\frac{(x-a)^2}{2s^2} \right]$$

$$\exp[-x^2]$$

