

$$g_\lambda(\lambda) = \frac{\mu g_\nu(\nu) - \nu g_\mu(\mu)}{\mu - \nu} + \lambda \frac{g_\mu(\mu) - g_\nu(\nu)}{\mu - \nu}$$

this must
be a const.
in λ !

$-\frac{B}{4}$

$$\left. \begin{aligned} g_\lambda(\lambda) &= -\frac{A}{4} - \frac{B}{4} \lambda \\ g_\mu(\mu) &= -\frac{A}{4} - \frac{B}{4} \mu \\ g_\nu(\nu) &= -\frac{A}{4} - \frac{B}{4} \nu \end{aligned} \right\}$$

A, B are non-trivial separation constants.

\downarrow

due to cyclic symmetry of the variables.

$$g_s(s) = \frac{1}{\phi_s(s)} [\dots] \quad \phi_s(s) = -\frac{A}{4} - \frac{B}{4} s$$

3 separation const.

$$\left. \begin{aligned} \hat{F}_s \phi_s(s) &= \left(a^2 b^2 c^2 \frac{a^2}{c^2} + A s + B s^2 \right) \phi_s(s) \\ \text{and } \hat{F}_s &= 4 \left[s F(s) \frac{\partial^2}{\partial s^2} + \left(F(s) + \frac{1}{2} s F'(s) \right) \frac{\partial}{\partial s} \right] \end{aligned} \right\}$$

these are 3 eq.-s: λ, μ, ν

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\leadsto 1 vált. Schr. lket a sajátvált. szerint.

\downarrow
már nem pars. diff.

$\leadsto A, B$ m, l.-vel megfelelő separációs konstansok.

\leadsto megmaradó operátorok megkonstruálhatóak belőlük.

$$\hat{G} = -\vec{\nabla} \left(1 - \frac{x^2}{a^2} - \frac{y^2}{b^2} - \frac{z^2}{c^2} \right) \vec{\nabla} \leadsto \frac{\omega^2}{c_0^2} \varphi = \hat{G} \varphi$$

általánosanított
nulla-megyenlet

$$\hat{F}_\lambda \varphi_1(\lambda) = \left(a^2 b^2 c^2 \frac{\omega^2}{c_0^2} + A\lambda + B\lambda^2 \right) \varphi_2(\lambda) \quad / \cdot \varphi_\mu \varphi_\nu$$

$$\left. \begin{aligned} \hat{F}_\lambda \varphi(\lambda, \mu, \nu) &= (\dots) \varphi(\lambda, \mu, \nu) \\ \hat{F}_\mu \varphi(\mu, \nu, \lambda) &= (\dots) \varphi(\mu, \nu, \lambda) \\ \hat{F}_\nu \varphi(\nu, \lambda, \mu) &= (\dots) \varphi(\nu, \lambda, \mu) \end{aligned} \right\} \text{let a teljes } \varphi\text{-re}$$

$$\begin{pmatrix} \hat{F}_\lambda \varphi \\ \hat{F}_\mu \varphi \\ \hat{F}_\nu \varphi \end{pmatrix} = \begin{pmatrix} 1 & \lambda & \lambda^2 \\ 1 & \mu & \mu^2 \\ 1 & \nu & \nu^2 \end{pmatrix} \begin{pmatrix} a^2 b^2 c^2 \frac{\omega^2}{c_0^2} \varphi \\ A\varphi \\ B\varphi \end{pmatrix}$$

$$\begin{pmatrix} a^2 b^2 c^2 \frac{\omega^2}{c_0^2} \varphi \\ A\varphi \\ B\varphi \end{pmatrix} = \begin{pmatrix} 1 & \lambda & \lambda^2 \\ 1 & \mu & \mu^2 \\ 1 & \nu & \nu^2 \end{pmatrix}^{-1} \begin{pmatrix} \hat{F}_\lambda \varphi \\ \hat{F}_\mu \varphi \\ \hat{F}_\nu \varphi \end{pmatrix}$$

$$\leadsto \text{elso let a szorzás után: } \frac{\omega^2}{c_0^2} \varphi = \hat{G} \varphi$$

$$\leadsto \text{második -ra-: } A\varphi = \hat{A} \varphi$$

$$\leadsto \text{harmadik -ra-: } B\varphi = \hat{B} \varphi$$

$$\Rightarrow \varphi \hat{A}, \hat{B}, \hat{G} \text{ -nek szimultán sajátfv. } \leadsto \text{kommutálók (?)}$$

$$\hat{B} = \frac{1}{(\lambda - \mu)(\mu - \nu)(\nu - \lambda)} \left((\mu - \nu) \hat{F}_\lambda + (\nu - \lambda) \hat{F}_\mu + (\lambda - \mu) \hat{F}_\nu \right)$$

$$\hat{A} = \frac{1}{(1-\mu)(\mu-\nu)(\nu-1)} \left((\mu^2 - \nu^2) \hat{F}_\lambda + (\nu^2 - 1^2) \hat{F}_\mu + (1^2 - \mu^2) \hat{F}_\nu \right) \quad (15)$$

→ vissza tudsz fordítani Descartes-ba

$$\hat{B} = (\vec{r} \cdot \vec{v})(\vec{r} \cdot \vec{v} + 3) - a^2 \frac{\partial^2}{\partial x_1^2} - b^2 \frac{\partial^2}{\partial x_2^2} - c^2 \frac{\partial^2}{\partial x_3^2}$$

$$\hat{A} = \left\{ \left[(b^2 + c^2)(x_1 - a^2) + a^2(x_2^2 + x_3^2) \right] \frac{\partial^2}{\partial x_1^2} + \right.$$

$$+ 2a^2 x_2 x_3 \frac{\partial^2}{\partial x_2 \partial x_3} +$$

$$+ 3(b^2 + c^2) x_1 \frac{\partial}{\partial x_1} +$$

+ ciklikus tagok

$$(a \rightarrow b \rightarrow c; x_1 \rightarrow x_2 \rightarrow x_3)$$

→ ezzel az op.-l nem a "normál" skalárszorzat mellett lesznek önadjungáltak (sajátért. valós.)

$$\langle \psi | \varphi \rangle = \int_{V_{TF}} \psi^*(x) \varphi(x) d^3x$$

csak a T_F ellipszoid belsejében végezni el!

→ itt az op. önadjungáltak lesznek.

$$\left. \begin{aligned} \hat{G} &= \hat{G}^* \\ \hat{A} &= \hat{A}^* \\ \hat{B} &= \hat{B}^* \end{aligned} \right\}$$

$$\langle \psi | \hat{G} | \varphi \rangle = \int_{V_{TF}} d^3x \psi^* \vec{\nabla} \left(1 - \frac{x_1^2}{a^2} - \frac{x_2^2}{b^2} - \frac{x_3^2}{c^2} \right) \vec{\nabla} \varphi =$$

$$= \int_{V_{TF}} d^3x \left\{ \vec{\nabla} \left[\psi^* \left(1 - \dots \right) (\vec{\nabla} \varphi) \right] + \right. \\ \left. + (\vec{\nabla} \psi^*) \left(1 - \dots \right) (\vec{\nabla} \varphi) \right\} =$$

→ teljes divergencia → 0

$$= \int_{V_{TF}} d^3x (\vec{\nabla} \psi^*) (1 - \dots) (\vec{\nabla} \varphi)$$

→ láthatóan önadjungált
(A, B hasonlóan viselkednek)

$$[\hat{G}, \hat{A}] = [\hat{G}, \hat{B}] = [\hat{A}, \hat{B}] = 0$$

→ \hat{B} sajátértékei: $n \cdot (n+3)$

→ \hat{A} — 4 — : ???

$x_1^\alpha x_2^\beta x_3^\gamma (\dots) \Rightarrow$ így is átírható szorzatra

$\left. \begin{array}{l} \alpha = 0, 1 \\ \beta = 0, 1 \\ \gamma = 0, 1 \end{array} \right\}$ szimmetria permutációk különböző térfüggvények.

↓
polinom elliptikus koordinátákban.

$$Q_p(s) = (s - \theta_1)(s - \theta_2) \dots (s - \theta_n)$$

↙
n gyöke a polinomnak.

$$Q(\lambda, \mu, \nu) = \underbrace{(\lambda - \mathcal{O}_1)(\mu - \mathcal{O}_1)(\nu - \mathcal{O}_1) \dots (\lambda - \mathcal{O}_n)(\mu - \mathcal{O}_n)(\nu - \mathcal{O}_n)}_{\text{...}}$$

$$\left(1 - \frac{x_1^2}{a^2 - \mathcal{O}_1} - \frac{x_2^2}{b^2 - \mathcal{O}_1} - \frac{x_3^2}{c^2 - \mathcal{O}_1} \right)$$

ez teljesen szimmetrikus x_1, x_2, x_3 -ban.

→ leírható az n -ed fős polinomok alábját.

• állítás:

$$Q(x_1, x_2, x_3) = x_1^\alpha x_2^\beta x_3^\gamma \prod_{i=1}^n \left(1 - \frac{x_i^2}{a^2 - \mathcal{O}_i} - \frac{x_i^2}{b^2 - \mathcal{O}_i} - \frac{x_i^2}{c^2 - \mathcal{O}_i} \right)$$

a generációs fv.-t ilyen alakban kell keresni.

→ \mathcal{O}_i -k és ω -k ismeretlenei

> innen kell vizsgálnia < - - - - -

$$Q(x_1, x_2, x_3) = x_1^\alpha x_2^\beta x_3^\gamma \cdot \tilde{Q}$$

$$\frac{\omega^2}{c_0^2} x_1^\alpha x_2^\beta x_3^\gamma \tilde{Q} = \hat{G} x_1^\alpha x_2^\beta x_3^\gamma \tilde{Q}$$

$$\frac{\omega^2}{c_0^2} \tilde{Q} = \underbrace{x_1^{-\alpha} x_2^{-\beta} x_3^{-\gamma} \hat{G} x_1^\alpha x_2^\beta x_3^\gamma}_{\tilde{G}} \tilde{Q}$$

\tilde{G} hasonlósági transzformált.

$$\hat{G} = - \underbrace{\vec{\nabla} \left(1 - \frac{x_1^2}{a^2} - \frac{x_2^2}{b^2} - \frac{x_3^2}{c^2} \right) \vec{\nabla}}_{=: Q_0}$$

$$\varphi_i := \left(1 - \frac{x_1^2}{a^2 - \varphi_i} - \frac{x_2^2}{b^2 - \varphi_i} - \frac{x_3^2}{c^2 - \varphi_i} \right)$$

$$\hat{\varphi} = \prod_{i=1}^n \varphi_i$$

$$\hat{G} = -\varphi_0 \Delta + \left(\frac{2x_1}{a^2} \frac{\partial}{\partial x_1} + \frac{2x_2}{b^2} \frac{\partial}{\partial x_2} + \frac{2x_3}{c^2} \frac{\partial}{\partial x_3} \right)$$

• hasonlósági transzformáció:

$$\begin{aligned} x_1^{-\alpha} x_2^{-\beta} x_3^{-\gamma} \Delta x_1^{\alpha} x_2^{\beta} x_3^{\gamma} &= x_1^{-\alpha} \frac{\partial^2}{\partial x_1^2} x_1^{\alpha} + \\ &+ x_2^{-\beta} \frac{\partial^2}{\partial x_2^2} x_2^{\beta} + \\ &+ x_3^{-\gamma} \frac{\partial^2}{\partial x_3^2} x_3^{\gamma} \end{aligned}$$

$$\begin{aligned} &\leadsto \underbrace{\left(x_1^{-\alpha} \frac{\partial}{\partial x_1} x_1^{\alpha} \right) \left(x_1^{-\alpha} \frac{\partial}{\partial x_1} x_1^{\alpha} \right)}_{\substack{x_1^{-\alpha} \cancel{x_1^{\alpha}} \left(\frac{\partial}{\partial x_1} + \alpha x_1^{\alpha-1} \right) \\ x_1^{\alpha}}} = \left(\frac{\partial}{\partial x_1} + \frac{\alpha}{x_1} \right) \end{aligned} \quad /ab = ba + [a, b]/$$

$$\begin{aligned} &\leadsto \left(\frac{\partial}{\partial x_1} + \frac{\alpha}{x_1} \right)^2 = \frac{\partial^2}{\partial x_1^2} + \frac{\alpha}{x_1} \frac{\partial}{\partial x_1} + \left(\frac{\alpha}{x_1} \frac{\partial}{\partial x_1} - \frac{\alpha}{x_1^2} \right) + \frac{\alpha^2}{x_1^2} \\ &= \frac{\partial^2}{\partial x_1^2} + \frac{2\alpha}{x_1} \frac{\partial}{\partial x_1} + \underbrace{\frac{\alpha(\alpha-1)}{x_1^2}}_{\substack{\alpha=0,1 \\ \downarrow \\ \emptyset}} \end{aligned}$$

$$x_1^{-\alpha} x_2^{-\beta} x_3^{-\gamma} \Delta x_1^{\alpha} x_2^{\beta} x_3^{\gamma} = \Delta + \left(\frac{2\alpha}{x_1} \frac{\partial}{\partial x_1} + \frac{2\beta}{x_2} \frac{\partial}{\partial x_2} + \frac{2\gamma}{x_3} \frac{\partial}{\partial x_3} \right) \quad (23)$$

$$x_1^{-\alpha} x_2^{-\beta} x_3^{-\gamma} \frac{2x_1}{a^2} \frac{\partial}{\partial x_1} x_1^{\alpha} x_2^{\beta} x_3^{\gamma} = \frac{2x_1}{a^2} \underbrace{\left(x_1^{-\alpha} \frac{\partial}{\partial x_1} x_1^{\alpha} \right)}_{\left(\frac{\partial}{\partial x_1} + \frac{\alpha}{x_1} \right)} =$$

$$= \frac{2x_1}{a^2} \frac{\partial}{\partial x_1} + \frac{2\alpha}{a^2}$$

$$\tilde{G} = G + \left(\frac{2\alpha}{x_1} \frac{\partial}{\partial x_1} + \frac{2\beta}{x_2} \frac{\partial}{\partial x_2} + \frac{2\gamma}{x_3} \frac{\partial}{\partial x_3} \right) + 2 \left(\frac{\alpha}{a^2} + \frac{\beta}{b^2} + \frac{\gamma}{c^2} \right)$$

$$\begin{aligned} \tilde{G} &= 2 \left(\frac{\alpha}{a^2} + \frac{\beta}{b^2} + \frac{\gamma}{c^2} \right) - \mathcal{Q}_0 \left(\Delta + \left(\frac{2\alpha}{x_1} \frac{\partial}{\partial x_1} + \frac{2\beta}{x_2} \frac{\partial}{\partial x_2} + \frac{2\gamma}{x_3} \frac{\partial}{\partial x_3} \right) \right) + \\ &+ \left(\frac{2x_1}{a^2} \frac{\partial}{\partial x_1} + \frac{2x_2}{b^2} \frac{\partial}{\partial x_2} + \frac{2x_3}{c^2} \frac{\partial}{\partial x_3} \right) \end{aligned}$$

$$\left[\frac{\omega^2}{c_0^2} \tilde{\varphi} = \tilde{G} \tilde{\varphi} \right]$$

$$\bullet \text{ Ma } \tilde{Q} = 1 \leadsto \frac{\omega^2}{c_0^2} = 2 \left(\frac{\alpha}{a^2} + \frac{\beta}{b^2} + \frac{\gamma}{c^2} \right)$$

$$\bullet \text{ Ma } \tilde{Q} \neq 1:$$

$$\frac{\partial \tilde{\varphi}}{\partial \varphi_i} = \frac{\tilde{\varphi}}{\varphi_i}$$

$$\Delta \tilde{\varphi} = \frac{\partial}{\partial x_1} \left(\sum_{i=1}^3 \frac{\partial \tilde{\varphi}}{\partial \varphi_i} \frac{(-2)x_1}{a^2 - \varphi_i} \right) + \frac{\partial}{\partial x_2} \left(\sum_{i=1}^3 \frac{\partial \tilde{\varphi}}{\partial \varphi_i} \frac{(-2)x_2}{b^2 - \varphi_i} \right) +$$

$$+ \frac{\partial}{\partial x_3} \left(\sum_{i=1}^3 \frac{\partial \tilde{\varphi}}{\partial \varphi_i} \frac{(-2)x_3}{c^2 - \varphi_i} \right) =$$

$$= \sum_{i=1}^{\tilde{n}} \sum_{\substack{j=1 \\ i \neq j}}^{\tilde{n}} \frac{\partial^2 \tilde{\varphi}}{\partial \varphi_i \partial \varphi_j} \left(\frac{4x_i^2}{(a^2 - \varphi_i)(a^2 - \varphi_j)} + \frac{4x_2^2}{(b^2 - \varphi_i)(b^2 - \varphi_j)} + \frac{4x_3^2}{(c^2 - \varphi_i)(c^2 - \varphi_j)} \right) +$$

$$+ (-2) \sum_{i=1}^{\tilde{n}} \frac{\partial \tilde{\varphi}}{\partial \varphi_i} \left(\frac{2}{a^2 - \varphi_i} + \frac{2}{b^2 - \varphi_i} + \frac{2}{c^2 - \varphi_i} \right) =$$

$$\frac{1}{a^2 + \varphi_i} - \frac{1}{a^2 + \varphi_j} = \frac{\varphi_j - \varphi_i}{(a^2 + \varphi_i)(a^2 + \varphi_j)} \quad / \quad \frac{1}{\varphi_j - \varphi_i} x_i$$

$$\frac{x_i^2}{(a^2 + \varphi_i)(a^2 + \varphi_j)} = \frac{1}{\varphi_j - \varphi_i} \left(\frac{x_i^2}{a^2 + \varphi_i} - \frac{x_i^2}{a^2 + \varphi_j} \right)$$

azonos átalakítás

$$= 4 \sum_{i \neq j} \frac{\partial^2 \tilde{\varphi}}{\partial \varphi_i \partial \varphi_j} \frac{1}{\varphi_j - \varphi_i} \left[\underbrace{\left(1 - \frac{x_i^2}{a^2 + \varphi_j} - \frac{x_2^2}{b^2 + \varphi_j} - \frac{x_3^2}{c^2 + \varphi_j} \right)}_{\varphi_j} - \underbrace{\left(1 - \frac{x_i^2}{a^2 + \varphi_i} - \frac{x_2^2}{b^2 + \varphi_i} - \frac{x_3^2}{c^2 + \varphi_i} \right)}_{\varphi_i} \right] -$$

$$- \sum_{i=1}^{\tilde{n}} \frac{\partial \tilde{\varphi}}{\partial \varphi_i} \left(\frac{2}{a^2 + \varphi_i} + \frac{2}{b^2 + \varphi_i} + \frac{2}{c^2 + \varphi_i} \right) =$$

~ azonosítással: $\frac{\partial \tilde{\varphi}}{\partial \varphi_i} \varphi_i = \tilde{\varphi} \quad \forall i$ $\frac{\partial \tilde{\varphi}}{\partial \varphi_i \partial \varphi_j} \varphi_i = \frac{\partial \tilde{\varphi}}{\partial \varphi_j}$

$$= 4 \sum_{i \neq j} \frac{\partial \tilde{\varphi}}{\partial \varphi_i} \frac{1}{\varphi_j - \varphi_i} - 4 \sum_{i \neq j} \frac{\partial \tilde{\varphi}}{\partial \varphi_j} \frac{1}{\varphi_j - \varphi_i} - \sum_i \frac{\partial \tilde{\varphi}}{\partial \varphi_i} \left(\frac{2}{a^2 + \varphi_i} + \frac{2}{b^2 + \varphi_i} + \frac{2}{c^2 + \varphi_i} \right)$$

$$= -4 \sum_i \frac{\partial \tilde{\varphi}}{\partial \varphi_i} \sum_{\substack{j=1 \\ j \neq i}}^{\tilde{n}} \frac{1}{\varphi_i - \varphi_j} - 4 \sum_i \frac{\partial \tilde{\varphi}}{\partial \varphi_i} \sum_{\substack{j=1 \\ j \neq i}}^{\tilde{n}} \frac{1}{\varphi_i - \varphi_j} - (\dots)$$

$$\Delta \tilde{\varphi} = - \sum_{i=1}^4 \frac{\partial \tilde{\varphi}}{\partial \varphi_i} \left(\frac{2}{a^2 + d_i} + \frac{2}{b^2 + d_i} + \frac{2}{c^2 + d_i} + \sum_{j \neq i} \frac{f}{d_i - d_j} \right) \quad (25)$$
