# Linear Algebra Notes

Basu Dev Karki

# Content

1	Line	ear Ma	aps	
	1.1	Vector	Spaces of Linear Maps	
		1.1.1	Definition and Examples of Linear Maps	
		1.1.2	Algebraic Operation on $\mathcal{L}(V,W)$	
		1.1.3	Exercises	
	1.2	Null S	paces and Ranges	
		1.2.1	Null Space and Injectivity	
		1.2.2	Range and Surjectivity	
		1.2.3	Fundamental Theorem of Linear Maps	
		1.2.4	Excercise	1
	1.3	Matrio	ces	1
		1.3.1	Representing a Linear Map by a Matrix	1
		1.3.2	Addition and Scalar Multiplication of Matrices	1
		1.3.3	Matrix Multiplication	1
		1.3.4	Column-Row Factorization and Rank of a Matrix	1
		1.3.5	Exercise	1

# 1 Linear Maps

# 1.1 Vector Spaces of Linear Maps

# 1.1.1 Definiton and Examples of Linear Maps

**Definition 1.1.** A linear map from V to W is a function  $T: V \to W$  with the following properties.

- 1. (Additivity) T(u+w) = T(u) + T(w) for all  $u, v \in V$
- 2. (Homogeneity)  $T(\lambda u) = \lambda T(u)$  for all  $\lambda \in \mathbf{F}$  and for all  $u \in V$

**Remark.** Some mathematicians use the phrase *linear transformation*, which means the same as linear map.

# **Definition 1.2.** (Notation)

- 1. The set of linear maps from  $V \to W$  is denoted by  $\mathcal{L}(V, W)$ .
- 2. The set of linear maps from  $V \to V$  is denoted by  $\mathcal{L}(V)$ . In other words,  $\mathcal{L}(V, V) = \mathcal{L}(V)$ .

# Examples:

#### zero

We will let the symbol 0 denote the liner map that takes every element of some vector space to additive identity of some another vector space. Thus,  $0 \in \mathcal{L}(V, W)$  is defined by

$$0(v) = 0$$

# identity operator

Let  $I \in \mathcal{L}(V)$  be defined by

$$I(v) = v$$

#### differentiation

Let  $D \in \mathcal{L}(\mathcal{P}(\mathbf{R}))$  be defined by

$$D(p) = p'$$

#### integration

Let  $T \in \mathcal{L}(\mathcal{P}(\mathbf{R}), \mathbf{R})$  be defined by

$$T(p) = \int_0^1 p$$

### composition

Fix a polynomial  $q \in \mathcal{P}(\mathbf{R})$ . Let  $T \in \mathcal{L}(\mathcal{P}(\mathbf{R}))$  be defined by

$$T(p) = (p \circ q)$$

**Remark.** We'll limit the Notation of T(v) to just Tv for convenience.

**Theorem 1.1.** Suppose  $v_1, \ldots, v_n$  is a basis of V and  $w_1, \ldots, w_n \in W$ . Then, there exists a unique linear map  $T: V \to W$  such that

$$Tv_k = w_k$$

for 
$$i = 1, 2, 3, \ldots, n$$
.

*Proof.* First we show the existence of such map. Define  $T: V \to W$  by

$$T(c_1v_1 + \dots + c_nv_n) = c_1w_1 + \dots + c_nw_n$$

where  $c_i \in \mathbf{F}$ . Since,  $v_1, \ldots, v_n$  is a basis of V, it maps every element of V to W, thus it is a function.

Now, set  $c_k = 1$  and all other c's to be 0 to show that  $Tv_k = w_k$ . From, here one can show that T is indeed a linear map. To show the uniqueness, suppose  $T' \in \mathcal{L}(V, W)$  and  $T'v_k = w_k$ . Using the properties of linear map,

$$T'(c_1v_1 + \dots + c_nv_n) = c_1w_1 + \dots + c_nw_n$$

Thus, T and T' agree on every input, thus T = T'.

# 1.1.2 Algebraic Operation on $\mathcal{L}(V, W)$

**Definition 1.3.** Suppose  $T, S \in \mathcal{L}(V, W)$  and  $\lambda \in \mathbf{F}$  then the *sum* and the *product* of the linear maps from V to W is defined by

$$(S+T)(v) = Sv + Tv$$
 and  $(\lambda T)(v) = \lambda (Tv)$ 

for all  $v \in V$ .

**Proposition 1.1.** With the operations defined above, the set  $\mathcal{L}(V, W)$  is a vector space.

*Proof.* The additive identity for  $\mathcal{L}(V, W)$  is the zero linear map 0(v) = 0. The inverse for T is ((-1)T)v = -(Tv). And the rest of the axioms are left for readers (future me) to verify.

**Definition 1.4.** Suppose  $T \in \mathcal{L}(U, V)$  and  $S \in \mathcal{L}(V, W)$  then the product  $ST \in \mathcal{L}(U, W)$  is defined by

$$(ST)(u) = S(Tu)$$

for all  $u \in U$ .

**Remark.** Be careful about the domains of S and T. Here, the domain of S must be the co-domain of T.

**Proposition 1.2.** For the product of linear maps, the following holds

- 1. (associativity)  $(T_1T_2)T_3 = T_1(T_2T_3)$  whenever the product makes sense(i.e  $T_3$  must map to domain of  $T_2$  and  $T_2$  must map to the domain of  $T_1$ ).
- 2. (**identity**)  $TI_{W,V} = I_{V,W}T$  whenever  $T \in \mathcal{L}(V,W)$ . Here  $I_{V,W}, I_{W,V}$  are the identity linear maps from V to W and W to V. We'll just limit he notation to TI = IT.
- 3. (distributivity)  $(S_1+S_2)T = S_1T+S_2T$  and  $S(T_1+T_2) = ST_1+ST_2$  for  $T, T_1, T_2 \in \mathcal{L}(U, V)$  and  $S, S_1, S_2 \in \mathcal{L}(V, W)$ .

**Proposition 1.3.** Suppose T is a linear map from V to W. Then, T(0) = 0.

*Proof.* From the definition of linear map we have,

$$T(0) = T(0+0) = T(0) + T(0) \implies T(0) = 0$$

#### 1.1.3 Exercises

**Problem :** Suppose  $b, c \in \mathbb{R}$ . Define  $T : \mathbb{R}^3 \to \mathbb{R}^2$  by

$$T(x, y, z) = (2x - 4y + 3z, 6x + cxyz)$$

Show that T is a linear map if and only if b = c = 0.

Solution: ( $\Leftarrow$ ) is pretty simple as you just have to verify the two axioms. For ( $\Rightarrow$ ), we know that if it is a linear map then  $T(0) = 0 \implies b = 0$ . Also, using the first axiom we get

$$T((x, y, z) + (1, 0, 0)) = T((x, y, z)) + T((1, 0, 0)) \implies c = 0$$

**Problem:** Suppose  $b, c \in \mathbb{R}$ . Define  $T : \mathcal{P}(\mathbb{R}) \to \mathbb{R}^2$  by

$$Tp = \left(3p(4) + 5p'(6) + bp(1)p(2), \int_{-1}^{2} x^{3}p(x)dx + c\sin(p(0))\right)$$

Show that T is a linear map if and only if b = c = 0.

Solution:  $(\Leftarrow)$  is pretty simple. For  $(\Rightarrow)$ , we can use the first axiom

$$T(p+q) = Tp + Tq$$

we'll just look at the first component first,

$$\implies 3(p+q)(4) + 5(p+q)'(6) + b(p+q)(1)(p+q)(2) = 3p(4) + 5p'(6) + bp(1)p(2) + 3q(4) + 5q'(6) + bq(1)q(2)$$

Since, (p+q)(4) = p(4) + q(4) and (p+q)'(6) = p'(6) + q'(6), we can simplify is down to,

$$b(p(1)q(2) + p(2)q(1)) = 0$$

Now, if you choose polynomials p,q>0 for x>0 then b=0. A similar argument works for c=0.

**Problem:** Suppose  $T \in \mathcal{L}(V, W)$  and  $v_1, \ldots, v_m$  is a list of vectors in V such that  $Tv_1, \ldots, Tv_m$  is a linearly independent list in W. Prove that  $v_1, \ldots, v_m$  is linearly independent.

Solution: Suppose on the contrary that  $v_1, \ldots, v_m$  are not linearly independent in V, then there exists  $\lambda_1, \ldots, \lambda_m$  not all zero such that

$$\lambda_1 v_1 + \dots + \lambda_m v_m = 0$$

But  $T(\lambda_1 v_1 + \cdots + \lambda_m v_m) = \lambda_1 T(v_1) + \cdots + \lambda_m T(v_m)$  which implies

$$\lambda_1 T(v_1) + \cdots + \lambda_m T(v_m) = 0 \implies \lambda_i = 0$$

a contradiction.

**Problem :** Show that every linear map from a one-dimensional vector space to itself is multiplication by some scalar. More precisely, prove that if dim V = 1 and  $T \in \mathcal{L}(V)$ , then there exists  $\lambda \in \mathbf{F}$  such that  $Tv = \lambda v$  for all  $v \in V$ .

Solution: Since dim V=1 there exists a  $v \in V$  s.t every  $v_i \in V$  can be written as  $\lambda_i v$  for some  $\lambda_i \in \mathbf{F}$ . Thus,  $v_i = \lambda_i v \implies T(v_i) = \lambda_i T(v)$ . Since,  $T(v) = v_j \in V$  for some j. Thus,  $T(v_i) = \lambda_i \lambda_j v = \lambda_j v_i$ .

**Problem:** Give an example of a function  $\varphi: \mathbf{R}^2 \to \mathbf{R}$  such that

$$\varphi(av) = a\varphi(v)$$

for all  $a \in \mathbf{R}$  and  $v \in \mathbf{R}^2$  but  $\varphi$  is not linear.

Solution : 
$$\varphi(x,y) = \begin{cases} \frac{x^3}{x^2 + y^2} & \text{if } (x,y) \neq (0,0) \\ 0 & \text{if } (x,y) = (0,0) \end{cases}$$

**Problem:** Give an example of a function  $\varphi: \mathbb{C} \to \mathbb{C}$  such that

$$\varphi(v+w) = \varphi(v) + \varphi(w)$$

for all  $v, w \in \mathbf{C}$  and but  $\varphi$  is not homogeneous.

Solution:  $\varphi(x) = \operatorname{Re}(x)$ .

**Problem :** Prove or give a counter example: Fix a polynomial  $q \in \mathcal{P}(\mathbf{R})$ . Let  $T : \mathcal{P}(\mathbf{R}) \to \mathcal{P}(\mathbf{R})$  be defined by  $Tp = q \circ p$  then T is a linear map.

Solution: Assume it was a linear map then T(0) = q(0) = 0. Just pick  $q(0) \neq 0$ . Example: q(x) = x + 1.

**Problem:** Suppose V is finite-dimensional and  $T \in \mathcal{L}(V)$ . Prove that T is a scalar multiple of identity if and only if ST = TS for every  $S \in \mathcal{L}(V)$ .

Solution: I really tried but it seems very hard to prove  $(\Rightarrow)$  but will come back later.

**Problem :** Suppose U is a subspace of V with  $U \neq V$ . Suppose  $S \in \mathcal{L}(U, W)$  and  $Su \neq 0$  for some  $u \in U$ . Define  $T: V \to W$  by

$$Tv = \begin{cases} Sv & \text{if } v \in U \\ 0 & \text{if } v \in V \text{ and } v \notin U \end{cases}$$

Prove that  $T \notin \mathcal{L}(V, W)$ .

Solution: Suppose it is a linear map, then T(u+v)=Tu+Tv where  $u\in U$  and  $v\in V$  and  $v\not\in U$ . One can check that  $v+u\in V$  but  $v+u\not\in U$ . Thus, 0=Tu=Su, but just take u s.t  $Su\neq 0$ .

**Problem:** Suppose V is finite-dimensional. Prove that every linear map on a subspace of U can be extended to a linear map on V. In other words, let U be a subspace of V and  $S \in \mathcal{L}(U, W)$ , then there exists a  $T \in \mathcal{L}(V, W)$  such that Tu = Su for all  $u \in U$ .

Solution: Let  $u_1, \ldots, u_m$  be the basis of U and let  $u_1, \ldots, u_m, v_1, \ldots, v_k$  be the extended basis of V. Let  $x = a_1u_1 + \cdots + a_mu_m + b_1v_1 + \cdots + b_kv_k$  and define

$$T(x) = a_1 S u_1 + \cdots + a_m S u_m + b_1 v_1 + \cdots + b_k v_k$$

From here its easy to see that Tu = Su for all  $u \in U$ . We just have to prove this is a linear map on V. Let  $y = x = c_1u_1 + \cdots + c_mu_m + d_1v_1 + \cdots + d_kv_k$  then

$$T(x+y) = (a_1 + c_1)Su_1 + \dots + (a_m + c_m) + (b_1 + d_1)v_1 + \dots + (b_k + d_k)v_k$$

$$\implies T(x+y) = a_1 S u_1 + \dots + a_m S u_m + b_1 v_1 + \dots + b_k v_k + c_1 S u_1 + \dots + c_m S u_m + d_1 v_1 + \dots + d_k v_k$$

$$\implies T(x+y) = Tx + Ty$$

Similarly one can prove  $T(\lambda x) = \lambda T(x)$ .

**Problem:** Suppose V is finite-dimensional with dim V > 0 and suppose W is infinite-dimensional. Prove that  $\mathcal{L}(V, W)$  is infinite-dimensional.

Solution: Let  $v_1, \ldots, v_m$  be basis of V. Suppose  $\mathcal{L}(V, W)$  is finite-dimensional then every  $T \in \mathcal{L}(V, W)$  can be written as

$$T(x) = \lambda_1 T_1(x) + \lambda_2 T_2(x) + \dots + \lambda_k T_k(x)$$

for some fixed  $T_1, T_2, \dots, T_k \in \mathcal{L}(V, W)$  and  $\lambda_i \in \mathbf{F}$ .

Since, W is infinite-dimensional,  $\exists w \in W \text{ s.t } w \notin \text{span}\{T_1(x), T_2(x), \dots, T_k(x)\}$  for some fixed  $x \in V$ .

Now, set  $x = v_i$  then  $w \neq \lambda_1 T_1(v_i) + \lambda_2 T_2(v_i) + \cdots + \lambda_k T_k(v_i)$ . One can find  $T \in \mathcal{L}(V, W)$  such that  $T(v_i) = w$  thus  $T(v_i) \neq \lambda_1 T_1(v_i) + \lambda_2 T_2(v_i) + \cdots + \lambda_k T_k(v_i)$  contradicting our assumption.

**Problem :** Let V be finite-dimensional and let  $\dim V > 1$ . Prove that there exists  $S, T \in \mathcal{L}(V)$  such that  $ST \neq TS$ .

Solution: Let  $v_1, \ldots, v_m$  be the basis of V and let  $x = a_1v_1 + \cdots + a_mv_m$ . Define  $S(x) = a_1v_1$  and  $T(x) = a_1v_2 + a_2v_3 + \cdots + a_{m-1}v_m + a_mv_1$ . So,  $T(S(x)) = a_1v_2$  and  $S(T(x)) = a_mv_1$ , thus

$$ST = TS \iff a_1 = a_m$$

but one can always choose x s.t  $a_1 \neq a_m$ .

**Problem :** Suppose V is finite-dimensional. Show that the only two-sided ideas of  $\mathcal{L}(V)$  are  $\{0\}$  and  $\mathcal{L}(V)$ . A subspace  $\mathcal{E}$  of  $\mathcal{L}(V)$  is called a two-sided ideal if for every  $E \in \mathcal{E}$  and  $T \in \mathcal{L}(V)$ ,  $TE \in \mathcal{E}$  and  $ET \in \mathcal{E}$ .

Solution: Let  $\mathcal{E}$  be a two-sided ideal of  $\mathcal{L}(V)$ . If  $\mathcal{E} = \{0\}$  we are done. Otherwise pick a nonzero operator  $A \in \mathcal{E}$ . Choose  $v \in V$  with  $Av \neq 0$ . Fix any  $y, z \in V$ . Choose  $R \in \mathcal{L}(V)$  with R(z) = v and choose  $S \in \mathcal{L}(V)$  with S(Av) = y. Then

$$T := SAR \in \mathcal{E}$$

(since  $\mathcal{E}$  is a two-sided ideal), and

$$T(z) = S(A(R(z))) = S(A(v)) = y.$$

Thus  $\mathcal{E}$  contains, for every pair y, z, an operator that sends z to y. Taking a basis  $u_1, \ldots, u_n$  of V and the operators  $E_{ij}$  defined by  $E_{ij}(u_j) = u_i$  and  $E_{ij}(u_k) = 0$  for  $k \neq j$ , we see each  $E_{ij}$  lies in  $\mathcal{E}$ . The set  $\{E_{ij}\}$  spans  $\mathcal{L}(V)$ , so  $\mathcal{E} = \mathcal{L}(V)$ . Hence the only two-sided ideals are  $\{0\}$  and  $\mathcal{L}(V)$ .  $\square$ 

# 1.2 Null Spaces and Ranges

# 1.2.1 Null Space and Injectivity

**Definition 1.5.** let  $T \in \mathcal{L}(V, W)$ , the null space of T, written as null T is the following set

$$\operatorname{null} T = \{ v \in V \mid Tv = 0 \}$$

# Examples

- 1. The zero map from V to W has a null space V as everything gets mapped to 0.
- 2. Let  $D \in \mathcal{L}(\mathcal{P}(\mathbf{R}))$  be the differentiation map defined by Dp = p'. The only functions whose derivative is equal to 0 are the constant function. Thus, null D is the set of constant functions.
- 3. Let  $D \in \mathcal{L}(\mathcal{P}(\mathbf{R}))$  be the multiplication by  $x^2$  map i.e  $Dp = x^2p$ . The only polynomial such that  $x^2p = 0$  is p = 0. Thus, null  $D = \{0\}$ .

**Proposition 1.4.** Suppose  $T \in \mathcal{L}(V, W)$ . Then, null T is a subspace of V.

**Proposition 1.5.** Let  $T \in \mathcal{T}(V, W)$ . Then T is injective  $\iff$  null  $T = \{0\}$ .

*Proof.* Suppose T is injective. Since it is a linear map T(0) = 0, thus by injectivity the only thing that gets map to 0 is 0. Thus, null  $T = \{0\}$ . Suppose T is such that null  $T = \{0\}$  then

$$T(v) = T(w) \implies T(v) + (-1)T(w) = 0$$
  
 $\implies T(v) + T(-w) = 0 \implies T(v - w) = 0 \implies v = w$ 

Thus, the map is injective.

#### 1.2.2 Range and Surjectivity

**Definition 1.6.** Let  $T \in \mathcal{L}(V, W)$ , the range of T is the following set,

$$range T = \{ Tv \mid v \in V \}$$

# Examples

- 1. If T is the zero map then the range of T is  $\{0\}$ .
- 2. Suppose  $D \in \mathcal{L}(\mathcal{P}(\mathbf{R}))$  be the differentiation map. Since, for every polynomial q there exists a polynomial p such that p' = q, the range is  $\mathcal{P}(\mathbf{R})$ .

**Proposition 1.6.** Let  $T \in \mathcal{L}(V, W)$  then range T is a subspace of W.

Proof. Since,  $0 \in V$  we know  $T(0) = 0 \in \operatorname{range} T$ . Now, suppose  $x, y \in \operatorname{range} T$  then x = Tv and y = Tw. Since,  $v + w \in V$ ,  $T(v + w) \in \operatorname{range} T \implies Tv + Tw \in \operatorname{range} T$  which mean  $x + y \in \operatorname{range} T$ . And  $x \in \operatorname{range} T \implies Tv \in \operatorname{range} T$  which means  $T(\lambda v) \in \operatorname{range} T$  as  $\lambda v \in V$ . Thus,  $\lambda x = \lambda T(v) = T(\lambda v) \in \operatorname{range} T$ .

#### 1.2.3 Fundamental Theorem of Linear Maps

**Theorem 1.2.** Suppose V is finite-dimensional and  $T \in \mathcal{L}(V, W)$ . Then range T is finite-dimensional and

$$\dim V = \dim \operatorname{null} T + \dim \operatorname{range} T$$

*Proof.* We know that null T is a subspace of V then since V is finite-dimensional it has a basis. Let  $u_1, \ldots, u_m$  be the basis of null T. Then we can extend this basis to a basis of V. Let  $u_1, \ldots, u_m, v_1, \ldots, v_n$  be the basis of V. Then,

$$x = a_1 u_1 + \dots + a_m u_m + b_1 v_1 + \dots + b_n v_n$$

$$\implies Tx = b_1 T v_1 + \dots + b_n T v_n$$

Thus, every Tv can be written as a linear combination of  $Tv_1, \ldots, Tv_n$ . Thus, range T is finite-dimensional. To prove our main result, we need to show that  $Tv_1, \ldots, Tv_n$  is a basis of range T. We already proved it spanned range T, now suppose

$$b_1 T v_1 + \dots + b_n T v_n = 0$$

$$\Longrightarrow T(b_1 v_1 + \dots + b_n v_n) = 0$$

Thus,  $b_1v_1+\cdots+b_nv_n \in \text{null } T$  and we can write it as  $b_1v_1+\cdots+b_nv_n = a_1u_1+\cdots+a_mu_m$ . Since,  $u_1,\ldots,u_m,v_1,\ldots,v_n$  is a basis vector we can say that  $b_i=a_i=0$ . Thus, we have proved that  $Tv_1,\ldots,Tv_n$  is a basis of range T and our theorem follows.

**Theorem 1.3.** Suppose V and W are both finite-dimensional vector spaces such that  $\dim V > \dim W$ . Then, there exists no **injective** linear map from V to W.

*Proof.* We know that, for a  $T \in \mathcal{L}(V, W)$ ,

$$\dim V = \dim \operatorname{null} T + \dim \operatorname{range} T$$

Since range T is a subspace of W,  $\dim W \geq \dim \operatorname{range} T$ . Thus,

$$\dim \operatorname{null} T = \dim V - \dim \operatorname{range} T$$

$$\geq \dim V - \dim W$$

$$> 0$$

Thus, null T has more than one vector, so T it's not injective by **Proposition 1.5**.  $\Box$ 

**Theorem 1.4.** Suppose V and W are both finite-dimensional vector spaces such that  $\dim V < \dim W$ . Then, there exists no **surjective** linear map from V to W.

*Proof.* Similar to the proof above.

**Definition 1.7.** Define  $T: \mathbf{F}^n \to \mathbf{F}^m$  as

$$T(x_1, \dots, x_n) = \left(\sum_{k=1}^n A_{1,k} x_k, \dots, \sum_{k=1}^n A_{m,k} x_k\right)$$

**Definition 1.8.** A homogeneous system of linear equations defined is as

$$\left(\sum_{k=1}^{n} A_{1,k} x_k, \dots, \sum_{k=1}^{n} A_{m,k} x_k\right) = (0, \dots, 0)$$

And a Inhomogeneous system of linear equation is defined as

$$\left(\sum_{k=1}^{n} A_{1,k} x_k, \dots, \sum_{k=1}^{n} A_{m,k} x_k\right) = (c_1, \dots, c_m)$$

where not all  $c_i$  are zero.

**Proposition 1.7.** A homogeneous system of linear equations with more variables than equations has nonzero solutions.

*Proof.* Use **Theorem 1.3** and **Theorem 1.4**.

**Proposition 1.8.** An inhomogeneous system of linear equations with more equations than variables has no solution for some choice of the constant terms.

*Proof.* Use **Theorem 1.3** and **Theorem 1.4**.

#### 1.2.4 Excercise

**Problem :** Give an example of a linear map T such that dim null T=3 and dim range T=2.

Solution:  $T(x_1, x_2, x_3, x_4, x_5) = (x_1, x_2).$ 

**Problem :** Suppose  $S, T \in \mathcal{L}(V, W)$  are such that range  $S \subseteq \text{null } T$ . Prove that  $(ST)^2 = 0$ .

Solution: Since range  $S \subseteq \text{null } T$ , T(Sv) = 0. Thus,

$$(ST)^2 = (ST)(ST) = S(T(S(Tv))) = S(0) = 0$$

**Problem:** Suppose  $v_1, \ldots, v_m$  is a list of vector in V. Define  $T \in \mathcal{L}(\mathbf{F}^m, V)$  by

$$T(z_1,\ldots,z_m)=z_1v_1+\ldots+z_mv_m$$

- a. What property of T corresponds to  $v_1, \ldots, v_m$  spanning V?
- b. What property of T corresponds to  $v_1, \ldots, v_m$  being linearly independent on V?

Solution: If  $v_1, \ldots, v_m$  spans V then range T = V thus T being surjective corresponds to  $v_1, \ldots, v_m$  spanning V.

If  $v_1, \ldots, v_m$  is linearly independent on V then null  $T = \{0\}$ , thus T being injective corresponds to  $v_1, \ldots, v_m$  being linearly independent on V.

**Problem:** Show that  $\{T \in \mathcal{L}(\mathbf{R}^5, \mathbf{R}^4) : \dim \operatorname{null} T > 2\}$  is not a subspace of  $\mathcal{L}(\mathbf{R}^5, \mathbf{R}^4)$ .

Solution: Let  $T(x_1, x_2, x_3, x_4, x_5) = (x_1, x_2, 0, 0)$  and  $T'(x_1, x_2, x_3, x_4, x_5) = (0, 0, x_3, 0)$ . Both of them are in  $\mathcal{L}(\mathbf{R}^5, \mathbf{R}^4)$ . Also dim null T = 3, dim null T' = 4 but  $T + T' = (x_1, x_2, x_3, 0) \implies \dim \text{null}(T + T') = 2 \not> 2$ .

**Problem:** Give an example of  $T \in \mathcal{L}(\mathbf{R}^4)$  such that range T = null T.

Solution:  $T(x_1, x_2, x_3, x_4) = (0, 0, x_1, x_2).$ 

**Problem:** Prove that there doesn't exists a  $T \in \mathcal{L}(\mathbf{R}^5)$  such that range T = null T.

Solution: Suppose there exists such T, then  $\dim \operatorname{range} T = \dim \operatorname{null} T$  but from the fundamental theorem of linear maps we have

$$\dim V = \dim \operatorname{range} T + \dim \operatorname{null} T$$

$$\implies$$
 dim range  $T = \dim \text{null } T = \frac{5}{2}$ 

which is impossible.

**Problem:** Suppose V and W are finite-dimensional with  $2 \leq \dim V \leq \dim W$ . Show that  $\{T \in \mathcal{L}(V, W) \mid T \text{ is not injective}\}$  is not a subspace of  $\mathcal{L}(V, W)$ .

Solution: Let  $v_1, \ldots, v_m$  be the basis of V and  $w_1, \ldots, w_n$  be the basis of W. Then, define  $T_i(a_1v_1 + \cdots + a_mv_m) = a_iw_i$ . One can check that this is not injective thus

$$T(a_1v_1 + \dots + a_mv_m) = \left(\sum_{i=1}^m T_i\right)(a_1v_1 + \dots + a_mv_m) = \sum_{i=1}^m a_iw_i$$

Now, suppose T(v) = T(v') then

$$a_1w_1 + \dots + a_mw_m = a'_1w_1 + \dots + a'_mw_m$$

$$\implies b_1 = b'_1 \quad (because \ of \ linear \ independence)$$

Thus, v = v'.

**Problem :** Suppose V is finite-dimensional and  $T \in \mathcal{L}(V, W)$ . Prove that there exists a subspace U and V such that

$$U \cap \text{null } T = \{0\} \text{ and } \text{range } T = \{Tu \mid u \in U\}$$

Solution: We know that null T is the subspace of V. Thus, there exists a U such that  $V = U \oplus \text{null } T$  and since it is a direct sum  $U \cap \text{null } T = \{0\}$ . Now, for the range of T

$$\operatorname{range} T = \{ Tv \mid v \in V \}$$
 
$$\implies \{ T(u+z) \mid u \in U, z \in \operatorname{null} T \} = \{ Tu \mid u \in U \}$$

**Problem:** Suppose T is a linear map from  $\mathbf{F}^4$  to  $\mathbf{F}^2$  such that

null 
$$T = \{(x_1, x_2, x_3, x_4) \in \mathbf{F}^4 \mid x_1 = 5x_2 \text{ and } x_3 = 7x_4\}$$

Prove that T is a surjective linear map.

Solution: We can write T as

$$\operatorname{null} T = \{ (5x_2, x_2, 7x_4, x_4) \mid x_2, x_4 \in \mathbf{F} \}$$

Now, since  $(5x_2, x_2, 7x_4, x_4) = x_2(5, 1, 0, 0) + x_4(0, 0, 7, 1) \implies \dim \text{null } T = 2$ . Thus,

$$\dim V = \dim \operatorname{null} T + \dim \operatorname{range} T$$

$$\implies 4 = 2 + \dim \operatorname{range} T$$

$$\implies$$
 dim range  $T=2$ 

Since, dim  $\mathbf{F}^2 = 2 = \dim \operatorname{range} T \implies \operatorname{range} T = \mathbf{F}^2$ . Thus, T is surjective.

**Problem:** Suppose U is three-dimensional subspace of  $\mathbb{R}^8$  and that T is a linear map from  $\mathbb{R}^8$  to  $\mathbb{R}^5$  such that null T = U. Prove that T is surjective.

Solution: Since, null  $T = U \implies \dim \text{null } T = 3$ . Thus,

$$\dim \mathbf{R}^8 = \dim \operatorname{null} T + \dim \operatorname{range} T$$

$$\implies$$
 dim range  $T=5$ 

Since, range T is a subspace of  $\mathbf{R}^5$  and dim range  $T=\dim \mathbf{R}^5$ ,  $\mathbf{R}^5=\mathrm{range}\,T$ . Thus, T is surjective.

**Problem:** Prove that there does not exist a linear map from  $\mathbf{F}^5$  to  $\mathbf{F}^2$  whose null space doesn't equals  $\{(x_1, x_2, x_3, x_4, x_5) \in \mathbf{F}^5 \mid x_1 = 3x_2 \text{ and } x_3 = x_4 = x_5\}.$ 

Solution: Suppose there does exist such a T. Then the null space can be written as

$$\operatorname{null} T = \{ (3x_2, x_2, k, k, k) \mid x_2, k \in \mathbf{F} \}$$

One can check that  $\dim \operatorname{null} T = 2$  but

$$\dim \mathbf{F}^5 = \dim \operatorname{null} T + \dim \operatorname{range} T$$

$$\implies$$
 dim range  $T=3$ 

But  $2 = \dim \mathbf{F}^2 \ge \dim \operatorname{range} T = 3$  which is false.

**Problem:** Suppose there exists a linear map on V such that the null space and range of T is finite dimensional. Prove that V is finite-dimensional.

Solution: Since, the range of T is finite-dimensional it must have a basis. Suppose  $Tv_1, \ldots, Tv_m$  is the basis then

$$T(x) = \lambda_1 T v_1 + \dots + \lambda_m T v_m$$

$$\implies T(x - \lambda_1 v_1 - \dots - \lambda_m v_m) = 0$$

Since, the null space is also finite-dimensional

$$x - \lambda_1 v_1 - \dots - \lambda_m v_m = \lambda_1' v_1' + \dots + \lambda_n' v_n'$$

where  $v'_1, \ldots, v'_n$  is the basis of the null space. Thus,

$$V = \operatorname{span}(v_1, \dots, v_m, v_1' \dots, v_n')$$

**Problem:** Suppose V and W are both finite-dimensional. Prove that there exists an injective linear map from V to W if and only if  $\dim V \leq \dim W$ .

Solution: Suppose  $T \in \mathcal{L}(V, W)$  is an injective map, then

$$\dim V = \dim \operatorname{null} T + \dim \operatorname{range} T$$

$$\implies$$
 dim  $V = \dim \operatorname{range} T \leq \dim W$ 

Now suppose dim  $V \leq \dim W$  then we can construct a injective map from V to W.

$$T(a_1v_1 + \dots + a_nv_n) = a_1w_1 + \dots + a_nw_n$$

where  $v_1, \ldots, v_n$  is the basis of V and  $w_1, \ldots, w_m$  is the basis of W. One can check this is a linear map and suppose T(x) = T(y) and let  $x = a_1v_1 + \cdots + a_nv_n$  and  $y = b_1v_1 + \cdots + b_nv_n$  then

$$T(x) = T(y)$$

$$\implies (a_1 - b_1)w_1 + \dots + (a_n - b_n)w_n = 0$$

$$\implies a_i = b_i$$

Thus, x = y.

**Problem:** Suppose V and W are finite-dimensional vector spaces and U is a subspace of V. Prove that there exists  $T \in \mathcal{L}(V, W)$  such that  $\operatorname{null} T = U$  if and only if  $\dim U \ge \dim V - \dim W$ .

Solution: Suppose  $\operatorname{null} T = U$  then

$$\dim V - \dim \operatorname{range} T = \dim U$$

$$\implies \dim V - \dim W \le \dim V - \dim \operatorname{range} T = \dim U$$

Now, suppose dim  $U \ge \dim V - \dim W$  then let  $u_1, \ldots, u_k$  be the basis of U and

$$u_1,\ldots,u_k,v_1,\ldots,v_m$$

be the extended basis of V. Let  $w_1, \ldots, w_j$  be the basis of W. From our condition, we know  $k \geq k + m - j \implies j \geq m$ . Thus we define

$$T(a_1u_1 + \cdots + a_ku_k + b_1v_1 + \cdots + b_mv_m) = b_1w_1 + \cdots + b_mw_m$$

Here,  $\operatorname{null} T = U$ .

**Problem :** Suppose V is finite-dimensional,  $T \in \mathcal{L}(V, W)$ , and U is a subspace of W. Prove that  $X = \{v \in V \mid Tv \in U\}$  is a subspace of V and

$$\dim X = \dim \operatorname{null} T + \dim(U \cap \operatorname{range} T)$$

Solution: The subspace part is pretty simple. Let  $S: X \to U$  be a map such that S(v) = T(v). Here, range  $S = U \cap \text{range } T$  and null S = null T.

**Problem :** Suppose U and V are finite-dimensional vector spaces and  $S \in \mathcal{L}(V, W)$  and  $T \in \mathcal{L}(U, V)$ . Prove that

 $\dim\operatorname{null} ST \leq \dim\operatorname{null} T + \dim\operatorname{null} S$ 

Solution : One can find that null  $ST = \operatorname{null} T \cup \{x \in U \mid S(T(x)) = 0, T(x) \neq 0\}.$ 

**Note:** It seems that these exercises are taking way too long to do. I'll however come back to it and finish

### 1.3 Matrices

# 1.3.1 Representing a Linear Map by a Matrix

**Definition 1.9.** Suppose m and n are two non-negative integers. A  $m \times n$  matrix is A is a rectangular array of elements in  $\mathbf{F}$  with m rows and n columns

$$A = \begin{pmatrix} A_{1,1} & \cdots & A_{1,n} \\ \vdots & & \vdots \\ A_{m,1} & \cdots & A_{m,n} \end{pmatrix}$$

The  $A_{i,j}$  represents the entry in *i*-th row and *j*-th column.

**Definition 1.10.** Suppose  $T \in \mathcal{L}(V, W)$  and  $v_1, \ldots, v_n$  is the basis of V and  $w_1, \ldots, w_m$  is a basis of W. The matrix of T with respect to these bases is the  $m \times n$  matrix  $\mathcal{M}(T)$  whose entries  $A_{i,j}$  are defined by

$$Tv_k = A_{1,k}w_1 + \cdots + A_{m,k}w_m$$

### Examples:

Suppose  $T \in \mathcal{L}(\mathbf{F}^2, \mathbf{F}^3)$  is defined by

$$T(x,y) = (x+3y, 2x+5y, 7x+9y)$$

Then,

$$\mathcal{M}(T) = \begin{pmatrix} 1 & 3 \\ 2 & 5 \\ 7 & 9 \end{pmatrix}$$

As T(1,0) = 1(1,0,0) + 2(0,1,0) + 7(0,0,1) and T(0,1) = 3(1,0,0) + 5(0,1,0) + 9(0,0,1).

### 1.3.2 Addition and Scalar Multiplication of Matrices

**Definition 1.11.** The sum of two matrices of same size is obtained by adding corresponding entries in the matrices i.e

$$\begin{pmatrix} A_{1,1} & \cdots & A_{1,n} \\ \vdots & & \vdots \\ A_{m,1} & \cdots & A_{m,n} \end{pmatrix} + \begin{pmatrix} B_{1,1} & \cdots & B_{1,n} \\ \vdots & & \vdots \\ B_{m,1} & \cdots & B_{m,n} \end{pmatrix}$$

$$= \begin{pmatrix} A_{1,1} + B_{1,1} & \cdots & A_{1,n} + B_{1,n} \\ \vdots & & \vdots \\ A_{m,1} + B_{1,1} & \cdots & A_{m,n} + B_{m,n} \end{pmatrix}$$

**Proposition 1.9.** Suppose  $S, T \in \mathcal{L}(V, W)$ . Then  $\mathcal{M}(S + T) = \mathcal{M}(S) + \mathcal{M}(T)$ .

*Proof.* Follows from the definition.

**Definition 1.12.** The product of a scalar and a matrix is obtained by multiplying each entry by the scalar i.e

$$\lambda \begin{pmatrix} A_{1,1} & \cdots & A_{1,n} \\ \vdots & & \vdots \\ A_{m,1} & \cdots & A_{m,n} \end{pmatrix} = \begin{pmatrix} \lambda A_{1,1} & \cdots & \lambda A_{1,n} \\ \vdots & & \vdots \\ \lambda A_{m,1} & \cdots & \lambda A_{m,n} \end{pmatrix}$$

**Proposition 1.10.** Suppose  $T \in \mathcal{L}(V, W)$  and  $\lambda \in \mathbf{F}$  then  $\lambda \mathcal{M}(T) = \mathcal{M}(\lambda T)$ .

*Proof.* Again, just use the definitions.

**Theorem 1.5.** Suppose  $\mathbf{F}^{m,n}$  be the set of all the matrices with entries in  $\mathbf{F}$ . Then, with addition and scalar multiplication defined above  $\mathbf{F}^{m,n}$  is a vector space and dim  $\mathbf{F}^{m,n} = mn$ .

*Proof.* Proving it is a vector space is pretty easy. To verify dim  $\mathbf{F}^{m,n} = mn$  define

$$X_{i,j} = \begin{pmatrix} 0 & \cdots & \cdots & \cdots \\ \vdots & \ddots & \vdots & \vdots \\ \vdots & \vdots & 1 & \vdots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

where every entry is 0 expect the  $A_{i,j}$  entry which is equal to 1. Now, its easy to see that every  $Z \in \mathbf{F}^{m,n}$  can be written as some linear combination of  $X_{i,j}$ 's. Thus,  $F^{m,n} = \operatorname{span}\{X_{i,j}\}$  where i,j vary with  $i = 1, \ldots, m$  and  $j = 1, \ldots, n$ . Also, every matrix with only 0 as its entry can only be written as linear combination of  $X_{i,j}$  with all of its scalars equal to 0. Since, there are mn entries the dimension of  $\mathbf{F}^{m,n}$  is equal to mn.  $\square$ 

# 1.3.3 Matrix Multiplication

**Definition 1.13.** Suppose A is a  $m \times n$  matrix and B is  $n \times p$  matrix. Then AB is defined as to be an  $m \times p$  matrix whose entry in row j and column k is given by

$$(AB)_{j,k} = \sum_{r=1}^{n} A_{j,r} B_{k,r}$$

**Remark.** The motivation for us to define the product like this comes from questioning, does  $\mathcal{M}(ST) = \mathcal{M}(S)\mathcal{M}(T)$ ? Suppose  $v_1, \dots, v_n$  is a basis of V and  $w_1, \dots, w_m$  is the basis of W. Suppose  $u_1, \dots, u_k$  is the basis of U then consider the map  $T: U \to V$  and  $S: V \to W$ . Suppose  $\mathcal{M}(S) = A$  and  $\mathcal{T} = B$ . Then

$$(ST)u_k = S\left(\sum_{r=1}^n B_{r,k}v_r\right)$$

$$= \sum_{r=1}^n B_{r,k}Sv_r$$

$$= \sum_{r=1}^n B_{r,k}\sum_{j=1}^m A_{j,r}w_j$$

$$= \sum_{i=1}^m \left(\sum_{r=1}^n A_{j,r}B_{r,k}\right)w_j$$

That is how we define M(ST) and that is why **Definition 1.13.** makes sense.

**Proposition 1.11.** Suppose  $T \in \mathcal{L}(U, V)$  and  $S \in \mathcal{L}(V, W)$ , then

$$\mathcal{M}(ST) = \mathcal{M}(S)\,\mathcal{M}(T)$$

*Proof.* It follows from our remark and how we defined the product of the matrix.

**Definition 1.14.** Suppose A is a  $m \times n$  matrix then

- 1. If  $1 \le j \le m$  then  $A_{j,}$  denotes the  $1 \times n$  matrix consisting of row j of A.
- 2. If  $1 \leq j \leq n$  then  $A_{\cdot,j}$  denotes  $m \times 1$  matrix consisting of column j of A.

# Example:

Suppose  $A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}$  then

$$A_{1,\cdot} = \begin{pmatrix} 1 & 2 & 3 \end{pmatrix}$$

$$A_{\cdot,3} = \begin{pmatrix} 3 \\ 6 \end{pmatrix}$$

**Theorem 1.6.** Suppose A is a  $m \times n$  matrix and B is a  $n \times p$  matrix. Then

$$(AB)_{j,k} = A_{j,\cdot}B_{\cdot,k}$$

where  $1 \le j \le m$  and  $1 \le k \le p$ .

*Proof.* The definition of matrix multiplication states that

$$(AB)_{j,k} = \sum_{r=1}^{n} A_{j,r} B_{r,k}$$
$$= A_{j,1} B_{1,k} + \dots + A_{j,n} B_{n,k}$$

Now, if you take  $A_{j,\cdot}$  and  $B_{\cdot,k}$  and multiply it out you'll get the same thing.

**Theorem 1.7.** Suppose A is a  $m \times n$  matrix and B is a  $n \times p$  matrix. Then

$$(AB)_{\cdot,k} = AB_{\cdot,k}$$

for  $1 \le k \le p$ .

*Proof.* Both of the matrix have size  $m \times 1$ . The *j*-th row of  $(AB)_{\cdot,k}$  has the element  $(AB)_{j,k}$  and the *j*-th row of  $AB_{\cdot,k}$  has element  $A_{j,1}B_{1,1} + A_{j,2}B_{2,1} + \cdots + A_{j,n}B_{n,1}$ . Thus, from our previous theorem they're equal.

**Theorem 1.8.** Suppose A is a  $m \times n$  matrix and  $b = \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$  is a  $n \times 1$  matrix. Then,

$$Ab = b_1 A_{\cdot,1} + \cdots + b_n A_{\cdot,n}$$

*Proof.* They both have same size and the entries of of Ab is the same as of the right side.

**Theorem 1.9.** Suppose C is an  $m \times c$  matrix and R is a  $c \times n$  matrix

- 1. The column k of CR is the linear combination of the columns of C, with coefficients of this linear combination coming from column k of R.
- 2. Then row j of CR is a linear combination of the rows of R, with the coefficients of this linear combination coming from row j of C.

*Proof.* Use **Theorem 1.7.** and **Theorem 1.8.** for 1. and we'll prove 2. in the exercise section.  $\Box$ 

#### 1.3.4 Column-Row Factorization and Rank of a Matrix

**Definition 1.15.** Suppose A is a  $m \times n$  matrix with entries in **F**.

- 1. The **column rank** of A is the dimension of the span of columns of A in  $\mathbf{F}^{1,m}$ .
- 2. The **row rank** of A is the dimension of the span of rows of A in  $\mathbf{F}^{n,1}$ .

Example: Suppose

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}$$

then the column rank is the dimension of

$$\operatorname{span}\left(\begin{pmatrix}1\\4\end{pmatrix},\begin{pmatrix}2\\5\end{pmatrix},\begin{pmatrix}3\\6\end{pmatrix}\right)$$

and the row rank is the dimension of

$$\operatorname{span}((1 \quad 2 \quad 3), (4 \quad 5 \quad 6))$$

**Definition 1.16.** The *transpose* of a  $m \times n$  matrix A, denoted by  $A^t$ , is the  $n \times m$  matrix whose entries are given by

$$(A^t)_{i,j} = A_{j,i}$$

**Theorem 1.10.** Suppose A is an  $m \times n$  matrix with entries in  $\mathbf{F}$  and column rank  $c \geq 1$ . Then there exists a  $m \times c$  matrix C and  $c \times n$  matrix R, both with entries in F, such that A = CR.

*Proof.* The list  $A_{\cdot,1}, \ldots, A_{\cdot,n}$  of columns of A can be reduced to a basis of the span of the columns of A. This basis has length c by definition of column rank. The c columns can be put together to form  $m \times c$ .

Now, each column k of A is a linear combination of columns of C. Make the coefficients of this linear combination column k of R. This matrix R has size  $c \times n$ . Thus, A = CR follows form **Theorem 1.9.**(a).

**Theorem 1.11.** Suppose  $A \in \mathbf{F}^{m,n}$  then the column rank of A equals row rank of A.

*Proof.* Let c be the column rank of A. Then A = CR by the previous theorem where C and R are the matrix whose size are  $m \times c$  and  $c \times n$  respectively. Now, from textbfTheorem 1.9. (b) each row of A is a linear combination of rows of R. Since, R has c columns this implies that

rowrank 
$$A \le c = \text{columnrank } A$$

Now applying the same thing to  $A^t$  we get

$$columnrank A = rowrank A^{t}$$

$$\leq columnrank A^{t}$$

$$= rowrank A$$

Thus, we're done.

**Remark.** From now on, we'll limit our use our terminology of "row rank" and "column rank" to just "rank".

#### 1.3.5 Exercise

**Problem :** Suppose  $T \in \mathcal{L}(V, W)$ . Show that with respect to each choice of basis of V and W, the matrix of T has at least dim range T nonzero entries.

Solution: Let  $v_1, \ldots, v_n$  be the basis of V and  $w_1, \ldots, w_m$  be the basis of W then suppose k of those vectors are 0 under T and let those vectors be  $v_1, \ldots, v_k$ . Thus,

range 
$$T = \operatorname{span}\{Tv_{k+1}, \dots, Tv_n\}$$

Thus, dim range  $T \leq n-k$ . But since  $T(v_j) \neq 0$  for each  $k+1 \leq j \leq n$ , there must be one entry thats not 0 for each  $T(v_j)$ . Since, the number of  $T(v_j) \neq 0$  are exactly n-k and  $n-k \geq \dim \operatorname{range} T$  this means there is at least dim range T nonzero entries in matrix of T.

**Problem:** Suppose V and W are finite-dimensional and  $T \in \mathcal{L}(V, W)$ . Prove that dim range T = 1 if and only if there exist a basis of V and a basis of W such that with respect to these bases, all the entries of  $\mathcal{M}(T)$  is 1.

Solution: Let us first prove  $(\Leftarrow)$ . Suppose  $A_{i,j} = 1$  for all i, j. That means,  $T(v_i) = \sum w_j$  where  $v_1, \ldots, v_n$  is the basis of V and  $w_1, \ldots, w_m$  is the basis of W. Thus,  $Tv_1 = Tv_2 = \cdots = Tv_n = k$  and range  $T = \text{span}\{Tv_1, \cdots, Tv_n\} = \text{span}\{k\} \implies \dim \text{range } T = 1$ . Now, for the  $(\Rightarrow)$  we use the Fundamental theorem of linear maps,

$$\dim V = \dim \operatorname{null} T + \dim \operatorname{range} T$$

$$\implies \dim V = \dim \operatorname{null} T + 1$$

Now, suppose  $v_2, \ldots, v_n$  be that basis of null T. Then extend this basis to V, suppose  $v_2, \ldots, v_n, v$  then

$$T(v_2) = T(v_3) = \dots = T(v_n) = 0$$
  
 $\implies T(v) = T(v_2 + v) = \dots = T(v_n + v)$ 

One can check that  $v_2 + v, \ldots, v$  is a basis of V (as its linearly independent and has length n). Now, since dim range T = 1 we have  $T(x) = \lambda T(v)$  and we choose  $T(v), w_2, \ldots, w_m$  as our basis for W. Now, we use a clever trick and set  $w_1 = T(v) - w_2 - w_3 - \cdots - w_m$  and notice that  $w_1, \cdots, w_m$  is a basis of W. Thus,

$$T(v_i) = T(v) = \sum w_j$$

Thus, we're done.

**Problem:** Suppose that  $D \in \mathcal{L}(\mathcal{P}_3(\mathbf{R}), \mathcal{P}_2(\mathbf{R}))$  is the differentiation map defined by Dp = p'. Find a basis of  $\mathcal{P}_3(\mathbf{R})$  and a basis of  $\mathcal{P}_2(\mathbf{R})$  such that the matrix of D with respect to these bases is

$$\left(\begin{array}{cccc}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & 1 & 0
\end{array}\right)$$

Solution: Take the basis of  $\mathcal{P}_3(\mathbf{R})$  to be  $z, \frac{z^2}{2}, \frac{z^3}{3}, 1$  and  $\mathcal{P}_2(\mathbf{R})$  to be  $1, z, z^2$ .

**Problem:** Suppose V and W are finite-dimensional and  $T \in \mathcal{L}(V, W)$ . Prove that there exist a basis of V and a basis of W such that with respect to these bases, all entries of  $\mathcal{M}(T)$  are 0 except that the entries in row k, column k, equal 1 if  $1 \le k \le \dim$  range T.

Solution: Let dim V = n and dim range T = m. Now, let  $v_{m+1}, \dots, v_n$  be the basis of dim null T. Now, extend these basis such in the following way

$$(v_1,\ldots,v_m,v_{m+1},\ldots,v_n)$$

Here,  $T(v_i) \neq 0$  for  $1 \leq i \leq m$ . Now, since  $(v_1, \dots, v_m, v_{m+1}, \dots, v_n)$  spans V the list  $(Tv_1, \dots, Tv_m)$  must span range T and in fact it is the basis of range T (one can check that its linearly independent). We can now extend this basis to the basis of W. Suppose  $(Tv_1, \dots, Tv_m, w_1, \dots, w_k)$  is the basis of W. Then,

$$T(v_i) = 0 \cdot T(v_1) + \dots + 1 \cdot T(v_i) + \dots + 0 \cdot w_k$$

for  $1 \le i \le m = \dim \operatorname{range} T$ . But for  $i > \dim \operatorname{range} T$  we have

$$0 = T(v_i) = 0 \cdot T(v_1) + 0 \cdot T(v_2) + \dots + 0 \cdot w_k$$

**Problem :** Suppose  $\sigma_1, ..., \sigma_m$  is a basis of V and W is finite-dimensional. Suppose  $T \in \mathcal{L}(V, W)$ . Prove that there exists a basis  $w_1, ..., w_n$  of W such that all entries in the first column of  $\mathcal{M}(T)$  [with respect to the bases  $\sigma_1, ..., \sigma_m$  and  $w_1, ..., w_n$ ] are 0 except for possibly a 1 in the first row, first column.

Solution: We know that range  $T = \text{span}\{T(\sigma_1), T(\sigma_2), \dots, T(\sigma_m)\}$ . Thus, we can make this span a basis. If  $T(\sigma_1) = 0$  then we're done but if not then the basis of range T would be

$$(T(\sigma_1), z_2, \ldots, z_k)$$

Now, we can extend this basis to the basis of W, suppose its

$$(T(\sigma_1), z_2, \ldots, z_k, s_{k+1}, \ldots, s_m)$$

then

$$T(\sigma_1) = 1 \cdot T(\sigma_1) + 0 \cdot z_2 + \dots + 0 \cdot s_m$$

**Problem :** Suppose  $w_1, ..., w_n$  is a basis of W and V is finite-dimensional. Suppose  $T \in \mathcal{L}(V, W)$ . Prove that there exists a basis  $\sigma_1, ..., \sigma_m$  of V such that all entries in the first row of  $\mathcal{M}(T)$  [with respect to the bases  $\sigma_1, ..., \sigma_m$  and  $w_1, ..., w_n$ ] are 0 except for possibly a 1 in the first row, first column.

Solution: