

Discussion of Optimal bandwidth choice for robust bias-corrected inference in regression discontinuity designs

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Introduction

Introduction

- ▶ The regression discontinuity (RD) design is widely used in program evaluation, causal inference, and treatment effect settings.
- ▶ In the past, empirical work in RD designs often employs a mean square error (MSE) optimal bandwidth for local polynomial estimation of and inference on treatment effects.
- ▶ This MSE-optimal bandwidth choice yields an MSE-optimal RD point estimator, but is by construction invalid for inference.
- ▶ Robust bias-corrected (RBC) inference methods provide a natural solution to this problem: RBC confidence intervals and related inference procedures remain valid even when the MSE-optimal bandwidth is used.
- ▶ This paper: the authors establish Coverage Error-optimal RBC confidence interval estimators
 - ▶ Analogously, minimizing the error in rejection probability of the associated hypothesis testing procedures for RD treatment effects

RBC Optimal Inference vs. CE Optimal Inference

- ▶ Robust bias-corrected (RBC) inference methods are valid when using the MSE-optimal bandwidth
 - ▶ Paper shows that they yield suboptimal confidence intervals in terms of coverage error.
 - ▶ Establishes coverage error expansions for RBC confidence interval estimators and uses these results to propose new inference-optimal bandwidth choices for forming these intervals.
- ▶ Authors derive a CE-optimal bandwidth choice designed to minimize coverage error of the interval estimator, which is a fundamentally different goal than minimizing the MSE of the point estimator.
 - ▶ The MSE- and CE-optimal bandwidths are complementary, as both can be used in empirical work to construct, respectively, optimal point estimators and optimal inference procedures for RD treatment effects.

Set-Up

- ▶ Estimand:

$$\tau_\nu = \tau_\nu(c) = \frac{\partial^\nu}{\partial x^\nu} E[Y_i(1) - Y_i(0) | X_i = x] \Big|_{x=c}$$

- ▶ A generalized set of treatment effects (regression discontinuity corresponding to $\nu = 0$, kink to $\nu = 1$, etc.)
- ▶ Restrict attention to $\nu = 0$ case in presentation.

Set-Up [2]

► Point Estimate:

The idea is to first choose a neighbourhood around the cutoff c via a positive bandwidth choice h , and then employ (local) weighted polynomial regression using only observations with score X_i lying within the selected neighbourhood.

► Estimator that follows from this idea:

$$\hat{\tau}(h) = \nu! e' \hat{\beta}_{+,p}(h) - \nu! e' \hat{\beta}_{-,p}, \quad \nu = 0, 1, \dots, p$$

where (e.g.):

$$\hat{\beta}_{-,p} = \operatorname{argmin}_{\beta \in R^{p+1}} \sum_{i=1}^N 1(c > X_i) (Y_i - r_p(X_i - c)' \beta)^2 K_h(X_i - c)$$

with $r_p(x) = (1, x, \dots, x^p)$.

Optimal Bandwidth

- ▶ With this estimator, the MSE can be approximated as follows:

$$E \left[(\hat{\tau}_\nu(h) - \tau_\nu)^2 \mid X_1, \dots, X_n \right] \approx_p h^{2p+2-2\nu} \mathcal{B}^2 + \frac{\mathcal{V}}{nh^{1+2\nu}}$$

- ▶ Which by the first order condition yields:

$$h_{\text{MSE}} = \left[\frac{(1+2\nu)\mathcal{V}}{2(1+p-\nu)\mathcal{B}^2} \right]^{\frac{1}{2p+3}} n^{-\frac{1}{2p+3}}$$

Plug-in Estimators

- ▶ The authors also derived closed form expressions of \mathcal{V} and \mathcal{B}
- ▶ Since we don't know them, rely on plug-in estimators to pick the h_{MSE}
 - ▶ The resulting estimator is “feasible” since a preliminary bandwidth, e.g. Imbens and Kalyanaraman (2012), is used to arrive at a plug-in estimate of \mathcal{B} and \mathcal{V} respectively.

Robust Bias-corrected Inference

- ▶ The infeasible estimator $\hat{\tau}_\nu(h_{\text{MSE}})$ and its data-driven counterpart $\hat{\tau}_\nu(\hat{h}_{\text{MSE}})$ are MSE-optimal point estimators of τ_ν in large samples.
- ▶ These point estimators are used not only to construct the “best guess” of the unknown RD treatment effect τ_ν , but also to conduct statistical inference, in particular for forming confidence intervals for τ_ν .
- ▶ The standard approach employs a Wald test statistic under the null hypothesis, and inverts it to form the confidence intervals. Specifically, for some choice of bandwidth h , the t -test statistic takes the form

$$T(h) = \frac{\hat{\tau}_\nu(h) - \tau_\nu}{\sqrt{\hat{V}(h)/(nh^{1+2\nu})}},$$

where it is assumed that $T(h) \sim \mathcal{N}(0, 1)$, at least in large samples.

Confidence Interval Based on RBC Estimate

- ▶ Hence the corresponding confidence interval estimator for τ_ν is

$$l_{\text{US}}(h) = \left[\hat{\tau}_\nu(h) - z_{1-\alpha/2} \cdot \sqrt{\frac{\hat{V}(h)}{nh^{1+2\nu}}}, \hat{\tau}_\nu(h) + z_{1-\alpha/2} \cdot \sqrt{\frac{\hat{V}(h)}{nh^{1+2\nu}}} \right],$$

where z_α denotes the (100α) -percentile of the standard normal distribution.

The Problem This Paper Solves

- ▶ The confidence interval $l_{US}(h)$ will only have correct asymptotic coverage, in the sense of $P[\tau_\nu \in l_{us}(h)] = 1 - \alpha + o(1)$, if h obeys $nh^{2p+3} \rightarrow 0$, that is, the bandwidth is “small enough”.
 - ▶ In particular, the MSE-optimal bandwidth is too large: the CI does not approach $(1 - \alpha)$, rendering inference and confidence intervals based on the naive t -test invalid.

Why is the naive t test invalid?

In a nutshell:

- ▶ **MSE-Optimal Bandwidth (h_{MSE}):** This bandwidth is chosen to make the **squared bias** of the same order of magnitude as the **variance**. It balances them perfectly to minimize the total error of the *point estimate*.
- ▶ **Valid Naive Inference:** This requires the t-statistic $T(h)$ to be centered around zero. For this to happen, the **bias** must be of a *smaller order of magnitude* than the **standard error**.
- ▶ h_{MSE} creates a bias that is “too big” relative to the standard error, so the t-statistic is not centered at zero, and the confidence interval is systematically off-center.

Asymptotic distribution of the raw estimator $\hat{\tau}_\nu(h)$.

Standard results in local polynomial regression (which form the basis for the MSE formula) show that the estimator $\hat{\tau}_\nu(h)$ is asymptotically normal, but with a bias term. For a large sample size n , its distribution is:

$$\hat{\tau}_\nu(h) \approx \mathcal{N} \left(\tau_\nu + \underbrace{h^{p+1-\nu}\mathcal{B}}_{\text{Bias}}, \underbrace{\frac{\mathcal{V}}{nh^{1+2\nu}}}_{\text{Variance}} \right)$$

Where \mathcal{B} and \mathcal{V} are the bias and variance constants from the MSE formula.

Asymptotic Distribution of t Stat

The naive t -statistic is defined as:

$$T(h) = \frac{\hat{\tau}_\nu(h) - \tau_\nu}{\sqrt{\hat{V}(h)/(nh^{1+2\nu})}}$$

Let's analyze the numerator and denominator:

- ▶ The denominator is the estimated **standard error**. Since $\hat{V}(h)$ is a consistent estimator for V , the denominator converges to $\sqrt{V/(nh^{1+2\nu})}$.
- ▶ The numerator is the centered estimator: $\hat{\tau}_\nu(h) - \tau_\nu$. From Step 1, this part is distributed as $\mathcal{N}(\text{Bias}, \text{Variance})$.

Distribution of t stat.

Now, let's divide the numerator by the (true) standard error to see the distribution of the t-statistic:

$$T(h) \approx \frac{\mathcal{N}\left(h^{p+1-\nu}\mathcal{B}, \frac{\mathcal{V}}{nh^{1+2\nu}}\right)}{\sqrt{\frac{\mathcal{V}}{nh^{1+2\nu}}}} = \mathcal{N}\left(\frac{h^{p+1-\nu}\mathcal{B}}{\sqrt{\frac{\mathcal{V}}{nh^{1+2\nu}}}}, 1\right)$$

► Simplify the mean term:

$$\text{Mean of } T(h) = \frac{h^{p+1-\nu}\mathcal{B} \cdot \sqrt{nh^{(1+2\nu)/2}}}{\sqrt{\mathcal{V}}} = \frac{\mathcal{B}}{\sqrt{\mathcal{V}}} \sqrt{nh^{2p+3}}$$

So, the asymptotic distribution of the naive t-statistic is:

$$T(h) \xrightarrow{d} \mathcal{N}\left(\frac{\mathcal{B}}{\sqrt{\mathcal{V}}} \sqrt{nh^{2p+3}}, 1\right)$$

Convergence result

- Check the condition $nh^{2p+3} \rightarrow 0$.

From the result before, $T(h)$ will only converge to a *standard* normal $N(0, 1)$ if its mean converges to zero. This happens if and only if:

$$nh^{2p+3} \rightarrow 0$$

This is the condition for a “small enough” bandwidth, often called an **“undersmoothed” bandwidth**.

Plug-in h_{MSE}

Now we plug in the MSE-optimal bandwidth h_{MSE} . The MSE-optimal bandwidth is defined by its rate:

$$h_{MSE} = C \cdot n^{-1/(2p+3)}$$

where C is the constant $[(1 + 2\nu)V/(2(1 + p - \nu)B^2)]^{1/(2p + 3)}$.

Let's substitute this specific h into the term nh^{2p+3} :

$$\begin{aligned} n(h_{MSE})^{2p+3} &= n \left(C \cdot n^{-1/(2p+3)} \right)^{2p+3} \\ &= n \cdot C^{2p+3} \cdot \left(n^{-1/(2p+3)} \right)^{2p+3} \\ &= n \cdot C^{2p+3} \cdot n^{-1} \\ &= C^{2p+3} \end{aligned}$$

Conclusion

This is a **non-zero constant**. It does **not** converge to 0. Because $n(h_{MSE})^{2p+3}$ converges to a non-zero constant, the mean of the t-statistic $T(h_{MSE})$ also converges to a non-zero constant:

$$T(h_{MSE}) \xrightarrow{d} \mathcal{N}(\mu, 1) \quad \text{where } \mu = \frac{\mathcal{B}}{\sqrt{\mathcal{V}}} \sqrt{C^{2p+3}} \neq 0$$

The confidence interval $I_{US}(h_{MSE})$ is constructed assuming the test statistic follows a $\mathcal{N}(0, 1)$ distribution. But in reality, it follows a normal distribution shifted by μ .

Therefore, the probability of coverage is:

$$P[\tau_\nu \in I_{US}(h_{MSE})] = P[-z_{1-\alpha/2} \leq T(h_{MSE}) \leq z_{1-\alpha/2}] \rightarrow P[-z_{1-\alpha/2} \leq \mathcal{N}(\mu, 1) \leq z_{1-\alpha/2}]$$

This probability is the area under a normal curve centered at μ . Because μ is not zero, this area is **not** equal to $1 - \alpha$. The inference is invalid.

Solution

- Bias correction is an alternative to undersmoothing. Calonico et al. (2014) introduced a robust bias-correction method:

$$T_{\text{RBC}}(h) = \frac{\hat{\tau}_{\nu, \text{BC}}(h) - \tau_{\nu}}{\sqrt{\hat{V}_{\text{BC}}(h)/(nh^{1+2\nu})}}, \quad \text{where} \quad \hat{\tau}_{\nu, \text{BC}}(h) = \hat{\tau}_{\nu}(h) - h^{1+p-\nu} \hat{B}(b),$$

and

$$I_{\text{RBC}}(h) = \left[\hat{\tau}_{\nu, \text{BC}}(h) - z_{1-\alpha/2} \cdot \sqrt{\frac{\hat{V}_{\text{BC}}(h)}{nh^{1+2\nu}}}, \hat{\tau}_{\nu, \text{BC}}(h) + z_{1-\alpha/2} \cdot \sqrt{\frac{\hat{V}_{\text{BC}}(h)}{nh^{1+2\nu}}} \right],$$

For inference, a key feature is that $\hat{V}_{\text{BC}}(h)$ is an estimator of the variance of $\hat{\tau}_{\nu, \text{BC}}(h)$, not of the variance of $\hat{\tau}_{\nu}(h)$.

Stepwise

- ▶ The Main Task (using bandwidth h):
 - ▶ Running a local polynomial regression of order p using a bandwidth h . This gives us our initial, biased estimate $\hat{\tau}_\nu(h)$.
- ▶ The Source of the Bias:
 - ▶ The bias in $\hat{\tau}_\nu(h)$ comes from the fact that our polynomial of order p fails to perfectly capture the true shape of the CE-function. The dominant part of this approximation error is related to the next highest-order term we omitted, which is the $(p + 1)$ -th derivative. The bias constant B is a function of this $(p + 1)$ -th derivative.
- ▶ Estimating the Bias (using bandwidth b):
 - ▶ To correct for the bias, we can't use the true bias B because it depends on an unknown derivative. We must estimate it. The text explicitly states that estimating \hat{B} requires a local polynomial regression of order $p + 1$.
 - ▶ We need to use a regression of order $p + 1$ because that's the order required to estimate the $(p + 1)$ -th derivative.
 - ▶ Like any local polynomial regression, this procedure requires its own bandwidth. We call this the auxiliary bandwidth, b .

Three claims

Paper shows that:

- ▶ $I_{RBC}(h)$ has asymptotic coverage error $(P(\tau \in CI(X)) - (1 - \alpha))$ that is no larger than $I_{US}(h)$, and is strictly smaller in most practically relevant cases, even when the corresponding best possible bandwidth is used to construct each confidence interval.
- ▶ Employing the MSE-optimal bandwidth h_{MSE} to construct $I_{RBC}(h)$ is valid but suboptimal in terms of coverage error.
- ▶ Paper drives new optimal bandwidth choices that minimize the coverage error of the RBC confidence intervals.

Three Proof Sketches: Claim 1

Claim: $I_{RBC}(h)$ has an asymptotic coverage error that is no larger than that of $I_{US}(h)$, and is strictly smaller in most cases, even when using the best possible bandwidth for each.

Proof Sketch: The proof rests on comparing the rates at which the coverage errors of the two intervals vanish as the sample size n grows. A faster rate means a better interval. The key tool is the Edgeworth expansion of the coverage error from the paper's Theorem 3.1.

- Coverage Error for Undersmoothing (I_{US}): The naive t-statistic $T(h)$ has a non-zero asymptotic mean (bias) unless h is chosen to be “small enough.” The coverage error of $I_{US}(h)$ is dominated by two terms: one from variance and one from this uncorrected bias.

$$\text{Coverage Error}(I_{US}(h)) \approx \underbrace{C_1 \cdot n^{-1} h^{-1}}_{\text{Variance Term}} + \underbrace{C_2 \cdot (nh^{p+1-\nu})^2}_{\text{Squared Bias Term}} + \dots$$

- To get the best possible US interval, we must choose h to balance these two terms. This leads to the optimal undersmoothing bandwidth, h_{US} , which has a rate of $h_{US} \propto n^{-1/(p+2)}$. Plugging this optimal rate back into the error formula shows that the fastest possible coverage error for I_{US} vanishes at a rate of $O(n^{-(p+1)/(p+2)})$.

Proof Sketch: Claim 1 - Why is that the Coverage Error?

Given the earlier derived expression for the shift of our t-statistic from zero:

$$\mu_T \approx \frac{\mathcal{B}}{\sqrt{\mathcal{V}}} \cdot \sqrt{nh^{2p+3}}$$

A confidence interval $[-z, z]$ for a standard normal variable covers $1 - \alpha$ of the probability mass. If our variable is actually a normal variable with mean μ_T instead of 0, the coverage probability is $P(-z \leq \mathcal{N}(\mu_T, 1) \leq z)$.

Using a Taylor expansion of this probability around $\mu_T = 0$, ([► Derivation](#)), we find that the first-order effect of the shift cancels out due to symmetry, and the dominant error term is proportional to the **square of the mean shift**:

$$\text{Coverage Error from Bias} \approx \text{Constant} \times (\mu_T)^2$$

Now, substitute our expression for μ_T :

$$\text{Error from Bias} \approx \text{Constant} \times \left(\frac{\mathcal{B}}{\sqrt{\mathcal{V}}} \cdot \sqrt{nh^{2p+3}} \right)^2 = \underbrace{\left(\frac{\mathcal{B}^2}{\mathcal{V}} \cdot \text{Const} \right)}_{C_2} \cdot (nh^{2p+3})$$

Claim 1: Origin of the Variance Term: $C_1 \cdot n^{-1}h^{-1}$

This term captures all other deviations from a perfect $N(0, 1)$ distribution. It is not about the *center* of the distribution, but about its *shape* and *randomness*.

- ▶ The numerator has its own **kurtosis** (i.e., fatter or thinner tails than a normal distribution).
- ▶ The denominator $\hat{V}(h)$ is a **random variable** itself. It has its own variance. Dividing by a random variable, instead of a constant, induces extra variability and non-normality in the ratio.

Claim 1: Origin of the Variance Term: $C_1 \cdot n^{-1}h^{-1}$ [2]

- ▶ Formal analysis using Edgeworth expansions, but use heuristic: **the effective sample size**.
- ▶ The estimator $\hat{\tau}_\nu(h)$ is a local average. The number of data points it effectively uses is roughly proportional to nh .
 - ▶ Higher-order approximation errors (related to skewness, kurtosis, etc.) decrease as the sample size increases.
 - ▶ The leading error term in an Edgeworth expansion for a symmetric statistic (after accounting for bias) is typically of the order $1/(\text{sample size})$.
 - ▶ In our case, the relevant sample size is nh . Therefore, the leading error term that captures all these shape distortions is proportional to:

$$\text{Error from Shape/Variance} \approx \frac{C_1}{nh} = C_1 \cdot n^{-1}h^{-1}$$

This term represents how much the coverage probability is distorted because our t-statistic isn't a perfect bell curve, primarily due to the randomness in the standard error estimate and the kurtosis of the point estimate.

Proof Sketch: Claim 1 [2]

- **Coverage Error for RBC (I_{RBC}):** By construction, the RBC procedure removes the first-order bias term C_2 . Its coverage error (similar argument) is therefore dominated by a variance term and a higher-order bias term.

$$\text{Coverage Error}(I_{RBC}(h)) \approx \underbrace{C'_1 \cdot n^{-1} h^{-1}}_{\text{Variance Term}} + \underbrace{C'_2 \cdot (nh^{p+2-\nu})^2}_{\text{Higher-Order Bias}} + \dots$$

- To get the best possible RBC interval, we choose h to balance these different terms.
 - This leads to the new CE-optimal bandwidth, h_{RBC} , which has a rate of $h_{RBC} \propto n^{-1/(p+3)}$. Plugging this optimal rate back in shows that the fastest possible coverage error for I_{RBC} vanishes at a rate of $O(n^{-(p+2)/(p+3)})$.

Proof Sketch: Claim 1 [3]

- ▶ Compare the two best-case error rates: $n^{-(p+1)/(p+2)}$ for US versus $n^{-(p+2)/(p+3)}$ for RBC.
 - ▶ For any $p \geq 0$, the exponent for RBC is larger in magnitude (e.g., for $p = 1$, we compare $n^{-2/3}$ vs $n^{-3/4}$).
 - ▶ This means the coverage error for the best RBC interval vanishes strictly faster than the coverage error for the best US interval.
 - ▶ This establishes the “strictly smaller” claim.
 - ▶ The “no larger than” part holds even under minimal smoothness assumptions where the first-order bias is still removed by RBC, making it at least as good as US.

Proof Sketch: Claim 2 [1]

Claim: Using the MSE-optimal bandwidth h_{MSE} to construct $I_{RBC}(h)$ is valid for inference, but the resulting interval is suboptimal in terms of coverage error.

Proof Sketch:

- ▶ Validity:
 - ▶ The RBC t-statistic is $T_{RBC}(h) = (\hat{\tau}_\nu(h) - \text{BiasEstimate} - \tau_\nu)/SE$.
 - ▶ The entire point of the BiasEstimate is to cancel the asymptotic bias of $\hat{\tau}_\nu(h)$.
 - ▶ This cancellation works regardless of the specific (valid) bandwidth h used.
 - ▶ Therefore, even when $h = h_{MSE}$, the numerator of $T_{RBC}(h_{MSE})$ is asymptotically centered at zero, and the whole statistic converges to a standard $N(0, 1)$.
- ▶ This means hypothesis tests have the correct size and confidence intervals have the correct coverage in the limit, so inference is valid.

Proof Sketch: Claim 2 [2]

- ▶ Suboptimality comes from a mismatch in optimization goals.
 - ▶ h_{MSE} is derived by minimizing the Mean Squared Error of the point estimate: $MSE(h) = \text{Bias}^2 + \text{Variance}$. This involves balancing a variance term with the first-order bias term, which yields the rate $h_{MSE} \propto n^{-1/(2p+3)}$.
 - ▶ The Coverage Error of the RBC interval, as shown in sketch (a), is determined by a balance between the variance term and a higher-order bias term. Minimizing this error yields the optimal rate $h_{RBC} \propto n^{-1/(p+3)}$.
 - ▶ Since $1/(2p+3) \neq 1/(p+3)$ (for $p \geq 1$), the h_{MSE} rate is not the rate that optimally minimizes the coverage error of the RBC interval.
 - ▶ Plugging h_{MSE} into the RBC coverage error formula creates an imbalance between the error components. This leads to a coverage error that vanishes more slowly than the error achieved by using the purpose-built h_{RBC} . Therefore, while valid, it's not the best one can do.

Proof Sketch: Claim 3 [1]

Claim: We can derive a new optimal bandwidth h_{RBC} that minimizes the RBC coverage error, and this choice has positive consequences for interval length.

Proof Sketch (Theorem 3.2): The optimal bandwidth h_{RBC} is found by explicitly minimizing the Edgeworth expansion of the RBC coverage error with respect to h . This involves taking the derivative of the coverage error formula (from sketch 1) with respect to h , setting it to zero, and solving.

- ▶ This defines both the optimal rate $h_{RBC} \propto n^{-1/(p+3)}$ and the associated constant \mathcal{H} . In practice, this requires estimating the unknown quantities in the error formula and numerically solving for the optimal bandwidth (a “direct plug-in” approach).
- ▶ Consequences for Interval Length: The length of a confidence interval is directly proportional to its standard error. A larger bandwidth h leads to a shorter interval.
- ▶ We found the optimal rates: $h_{RBC} \propto n^{-1/(p+3)}$ and $h_{US} \propto n^{-1/(p+2)}$.
- ▶ Since $1/(p+3) < 1/(p+2)$, the h_{RBC} bandwidth vanishes more slowly, meaning for any large n , h_{RBC} will be larger than h_{US} .
- ▶ Because I_{RBC} optimally employs a larger bandwidth, its standard error is smaller, and its length is therefore asymptotically shorter than the best possible undersmoothed interval I_{US} .

The End

Appendix

- ▶ In an ideal world, our t-statistic T follows a standard normal distribution, $T \sim N(0, 1)$. A two-sided $(1 - \alpha)$ confidence interval corresponds to finding the region $[-z_c, z_c]$ where $P(-z_c \leq T \leq z_c) = 1 - \alpha$. Here, z_c is the critical value (e.g., 1.96 for $\alpha = 0.05$).
 - ▶ In the undersmoothing case with a “too large” bandwidth, our t-statistic $T(h)$ is *not* centered at zero. It is approximately normal, but with a non-zero mean μ_T .

$$T(h) \approx N(\mu_T, 1)$$

- ▶ We still use the same interval $[-z_c, z_c]$ because we are *assuming* it's a standard normal. The actual coverage probability is now $P(-z_c \leq N(\mu_T, 1) \leq z_c)$.
- ▶ We want to understand the difference between the actual and nominal coverage, which is the coverage error:

$$\text{Coverage Error} = P(-z_c \leq N(\mu_T, 1) \leq z_c) - (1 - \alpha)$$

- ▶ We will analyze this by defining a function for the coverage probability and expanding it with a Taylor series.

The Taylor Expansion Derivation

Let $g(\mu)$ be the probability that a normal random variable with mean μ and variance 1 falls within the interval $[-z_c, z_c]$.

$$g(\mu) = P(-z_c \leq N(\mu, 1) \leq z_c)$$

Let $\Phi(x)$ be the CDF and $\phi(x)$ be the PDF of a standard normal $N(0, 1)$. We can write $g(\mu)$ using the standard normal CDF:

$$g(\mu) = \Phi(z_c - \mu) - \Phi(-z_c - \mu)$$

Our goal is to approximate $g(\mu_T)$ when μ_T is small. We use a second-order Taylor expansion of $g(\mu)$ around the point $\mu = 0$:

$$g(\mu) \approx g(0) + g'(0)\mu + \frac{g''(0)}{2}\mu^2$$

The coverage error is $g(\mu) - g(0)$. So, we need to find the first and second derivatives of $g(\mu)$ and evaluate them at $\mu = 0$.

Step 1: Calculate the First Derivative $g'(\mu)$

We use the chain rule and the fact that $d/dx\Phi(x) = \phi(x)$:

$$\begin{aligned}g'(\mu) &= \frac{d}{d\mu} [\Phi(z_c - \mu) - \Phi(-z_c - \mu)] \\&= \phi(z_c - \mu) \cdot (-1) - \phi(-z_c - \mu) \cdot (-1) \\&= -\phi(z_c - \mu) + \phi(-z_c - \mu)\end{aligned}$$

Now, evaluate at $\mu = 0$:

$$g'(0) = -\phi(z_c) + \phi(-z_c)$$

A key property of the standard normal PDF is that it is symmetric: $\phi(x) = \phi(-x)$. Therefore:

$$g'(0) = -\phi(z_c) + \phi(z_c) = 0$$

This is a crucial result. It means that for very small shifts in the mean, the coverage error is *not* proportional to μ . The leading error term must come from the second derivative.

Step 2: Calculate the Second Derivative $g''(\mu)$

We differentiate $g'(\mu)$ with respect to μ . We need the rule for the derivative of the PDF:
 $d/dx\phi(x) = -x\phi(x)$.

$$\begin{aligned}g''(\mu) &= \frac{d}{d\mu} [-\phi(z_c - \mu) + \phi(-z_c - \mu)] \\&= -(\phi'(z_c - \mu) \cdot (-1)) + (\phi'(-z_c - \mu) \cdot (-1)) \\&= \phi'(z_c - \mu) - \phi'(-z_c - \mu) \\&= (-(z_c - \mu)\phi(z_c - \mu)) - (-(-z_c - \mu)\phi(-z_c - \mu)) \\&= -(z_c - \mu)\phi(z_c - \mu) - (z_c + \mu)\phi(-z_c - \mu)\end{aligned}$$

Now, evaluate at $\mu = 0$:

$$g''(0) = -(z_c)\phi(z_c) - (z_c)\phi(-z_c)$$

Using the symmetry $\phi(z_c) = \phi(-z_c)$ again:

$$g''(0) = -z_c\phi(z_c) - z_c\phi(z_c) = -2z_c\phi(z_c)$$

This is a non-zero negative constant.

Step 3: Assemble the Result

Now we plug our derivatives back into the Taylor expansion for the coverage error, $g(\mu) - g(0)$:

$$\begin{aligned}\text{Coverage Error} &\approx g'(0)\mu + \frac{g''(0)}{2}\mu^2 \\ &\approx (0)\mu + \frac{-2z_c\phi(z_c)}{2}\mu^2 \\ &= -z_c\phi(z_c)\mu^2\end{aligned}$$

Finally, we substitute our specific mean shift, $\mu = \mu_T$:

$$\text{Coverage Error from Bias} \approx \underbrace{(-z_c\phi(z_c))}_{\text{A negative constant}} \cdot (\mu_T)^2$$

This explicitly shows that the dominant component of the coverage error arising from a bias in the test statistic is proportional to the **square of that bias**. This is the mathematical origin of the “Squared Bias Term” in the proof sketch.

Appendix II: Edgeworth Expansions (Example)

- ▶ Imagine you have a statistic, like the sample mean. The Central Limit Theorem (CLT) tells us that for a large sample size, the distribution of this statistic is *approximately* a normal distribution.
- ▶ An **Edgeworth expansion** is a way to make that approximation much more precise.
 - ▶ It takes the normal distribution from the CLT as a starting point and then adds a series of correction terms to it.
 - ▶ These correction terms account for the ways the true distribution deviates from a perfect normal curve, primarily due to **skewness** and **kurtosis** in the original data.
- ▶ Think of it like a Taylor series for probability distributions.
 - ▶ A Taylor series approximates a complex function with a simple polynomial.
 - ▶ The more terms you add, the better the approximation.
 - ▶ An Edgeworth expansion approximates a complex probability distribution with a simple normal distribution plus polynomial correction terms.
 - ▶ The more terms you add, the more accurately you capture the true shape of the distribution.

Formal Definition

Let Z_n be a standardized statistic based on a sample of size n . For example, $Z_n = \sqrt{n}(\bar{X}_n - \mu)/\sigma$. Let $F_n(z)$ be the true cumulative distribution function (CDF) of Z_n , so $F_n(z) = P(Z_n \leq z)$. The Central Limit Theorem states:

$$F_n(z) \approx \Phi(z)$$

where $\Phi(z)$ is the CDF of a standard normal distribution. This approximation has an error that shrinks as n gets larger.

An **Edgeworth expansion** provides an asymptotic expansion for $F_n(z)$ in powers of $n^{-1/2}$. It gives a more detailed approximation:

$$F_n(z) \approx \Phi(z) - \phi(z) \left[\frac{p_1(z)}{\sqrt{n}} + \frac{p_2(z)}{n} + \frac{p_3(z)}{n^{3/2}} + \dots \right]$$

Where:

- ▶ $\Phi(z)$ is the standard normal CDF (the CLT part).
- ▶ $\phi(z)$ is the standard normal probability density function (PDF).
- ▶ $p_1(z), p_2(z), \dots$ are polynomials in z . The crucial part is that the **coefficients of these polynomials depend on the moments (like skewness and kurtosis) of the underlying data distribution.**

The first correction term, governed by $p_1(z)$, accounts for skewness. The second term, governed by $p_2(z)$, accounts for kurtosis and other higher-order features.

Simple Example: The Sample Mean

Let's look at the first-order Edgeworth expansion for the standardized sample mean $Z_n = \sqrt{n}(\bar{X}_n - \mu)/\sigma$.

The first polynomial, $p_1(z)$, is given by:

$$p_1(z) = \frac{\gamma}{6}(z^2 - 1)$$

where $\gamma = E[(X - \mu)^3]/\sigma^3$ is the **skewness** of the original data distribution.

Plugging this in, the first-order Edgeworth expansion is:

$$P(Z_n \leq z) \approx \Phi(z) - \phi(z) \frac{\gamma}{6\sqrt{n}}(z^2 - 1)$$

What does this tell us?

1. **The Role of Skewness:** The first and most important correction to the normal approximation comes from the skewness (γ) of the original data. If the original data is perfectly symmetric (like a t-distribution or the normal distribution itself), then $\gamma = 0$, and this entire first correction term vanishes. In that case, the normal approximation is much more accurate.
2. **The Role of Sample Size:** The correction term is divided by \sqrt{n} . This shows that as the sample size n gets very large, the correction term goes to zero, and we are left with the simple CLT result, as expected.
3. **Improving Approximations:** If you have data from a skewed distribution, and a finite sample size, this formula will give you a much more accurate p-value or critical value than relying on the simple normal approximation alone.

In the context of the Calonico, Cattaneo, and Farrell paper, they use Edgeworth expansions on their complex RD t-statistic to get a highly accurate formula for its true distribution. This allows them to precisely characterize the coverage error of confidence intervals and then find the bandwidth that minimizes this error.