

Lecture 3: Regression analysis with time series data II

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- Consequences of spurious regression & stationarity
- Dickey-Fuller test
- Application of Dickey-Fuller test
- Co-integration
- Error-correction models
- Forecasting
- Vector autoregressive (VAR) model

Material:

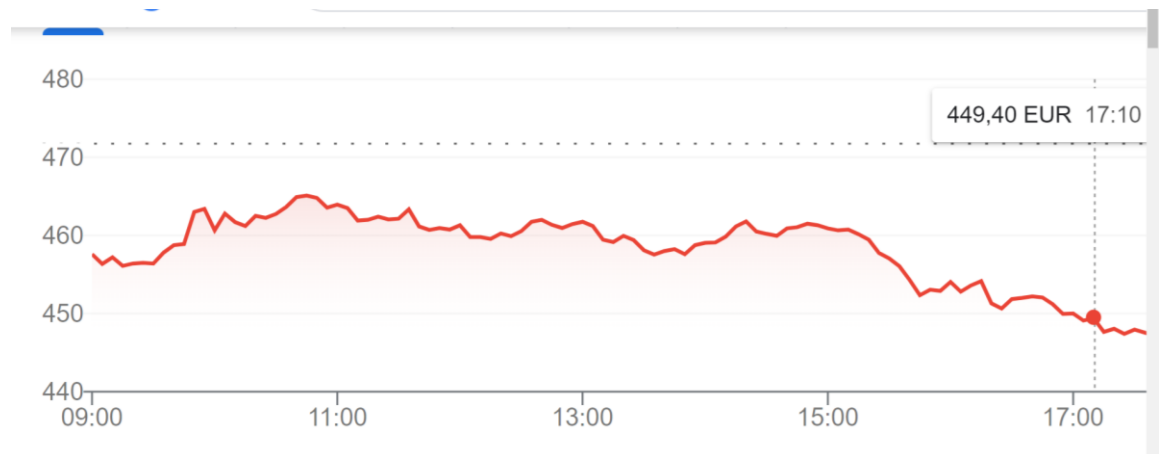
Chapter 18: 11.3, 18.2, 18.3, 18.4, 18.5

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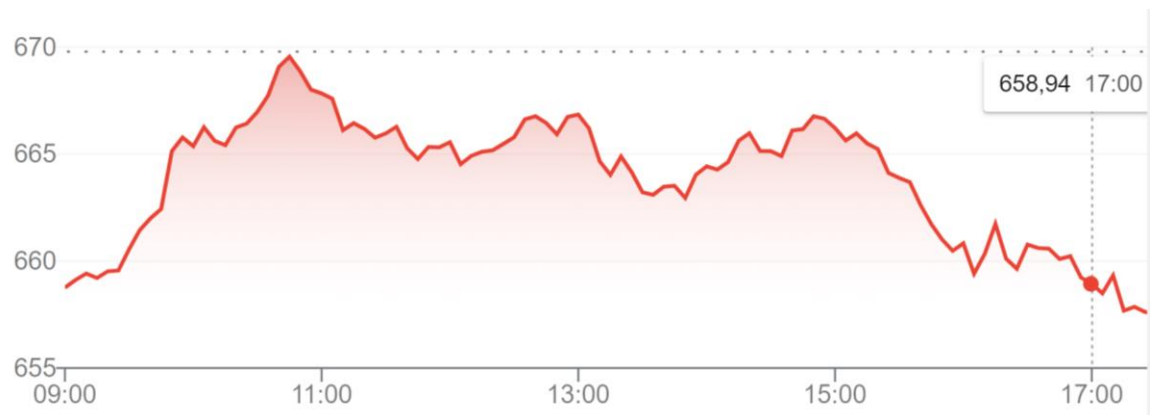
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Motivation

- For instance the stockprice of ASML. Development of ASML on Thursday 22 September 2023



- There is also information on the development of the AEX index on the same day



FORECASTING THE STOCKPRICE OF ASML – WAY OF THINKING

- Construct a forecasting model. Make a sample split into the observations to estimate the parameters of a forecasting model
- The remainder of the observations are used to make predictions (forecasts) with the forecasting model
- Make use of the model that has the smallest forecast error for the testing dataset (= running a horse race)
- Options:

1. simple time trend: $AS\hat{M}L_t = \hat{\alpha}_0 + \hat{\alpha}_1 t$

2. Lagged values: $AS\hat{M}L_t = \hat{\beta}_0 + \hat{\beta}_1 ASML_{t-1}$ with $|\hat{\beta}_1| < 1$

3. Other variables: $AS\hat{M}L_t = \hat{\gamma}_0 + \hat{\gamma} AEX_{t-1}$

4. Unit root/Random walk/I(1):

$$AS\hat{M}L_t = \hat{\lambda}_0 + ASML_{t-1}$$

5. Co-integration: $AS\hat{M}L_t = \hat{\delta}_0 + \hat{\delta}_1 AEX_t$

6. Some combination of these five options

7. Vector Autoregressive (VAR) model

- Previous week: options 1, 2 and 3
- THIS WEEK: options 4 and 5 and 7
- THIS WEEK: shall we analyse $ASML_t$ or

$$\Delta ASML_t \quad (= ASML_t - ASML_{t-1})$$

We will apply the Dickey-Fuller test

Spurious regression

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Motivation: spurious regression

Aim: to introduce spurious regression and co-integration.

- Consider a regression of y_t on x_t where both variables are non-stationary (they are integrated of order one – I(1)). A good example is the relation between AEXindex and the stockprice of ASML.
- In that case, there is the possibility of spurious regression. CONSEQUENCE: Estimation by OLS gives inconsistent coefficients and the t -values are misleading.
- Spurious regression does not occur if the two variables are co-integrated, that is, a linear combination of the two variables is stationary (I(0)).

Example - Spurious regression

- Let y_t (= stock price ASML) and x_t (=AEX index) be two independent random walks:
 - $y_t = y_{t-1} + e_t$
 - $x_t = x_{t-1} + a_t$

Where the error terms e_t and a_t are mutually independent.

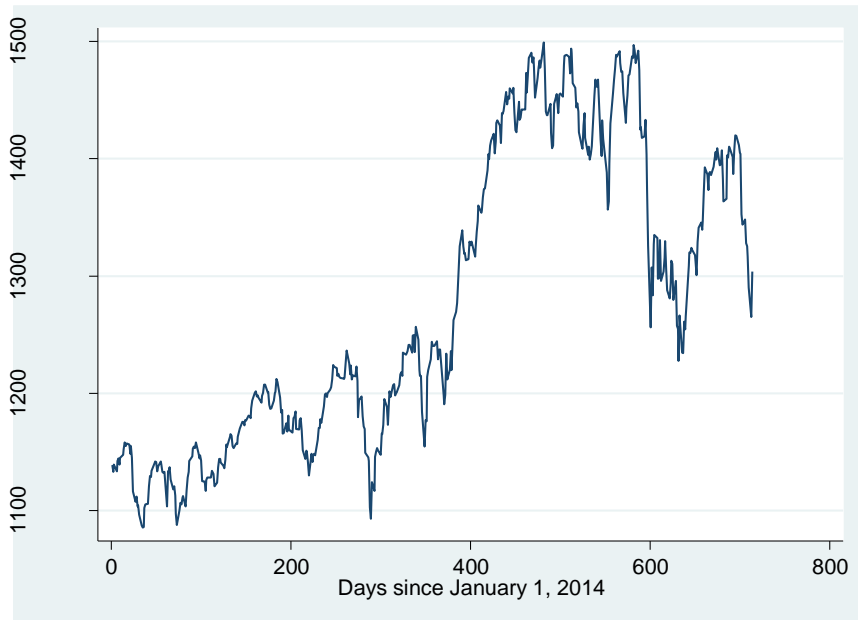
- Let's assume that y_t and x_t are independent, so that there is no relationship between both variables.
- However, a regression of the level of y (not a growth variable) on the level of x yields a high R^2 and a very low Durbin Watson statistic:

$$\text{○ } y_t = \beta_0 + \beta_1 x_t + u_t \quad (18.30)$$

- Adding a time trend to the regression equation does not change the result, and the results cannot be trusted.
 - $y_t = \beta_0 + \beta_1 x_t + \gamma t + u_t$
- However, a regression in first differences delivers the expected results: $\Delta y_t = \alpha_2 + \beta_2 \Delta x_t + \Delta u_t$

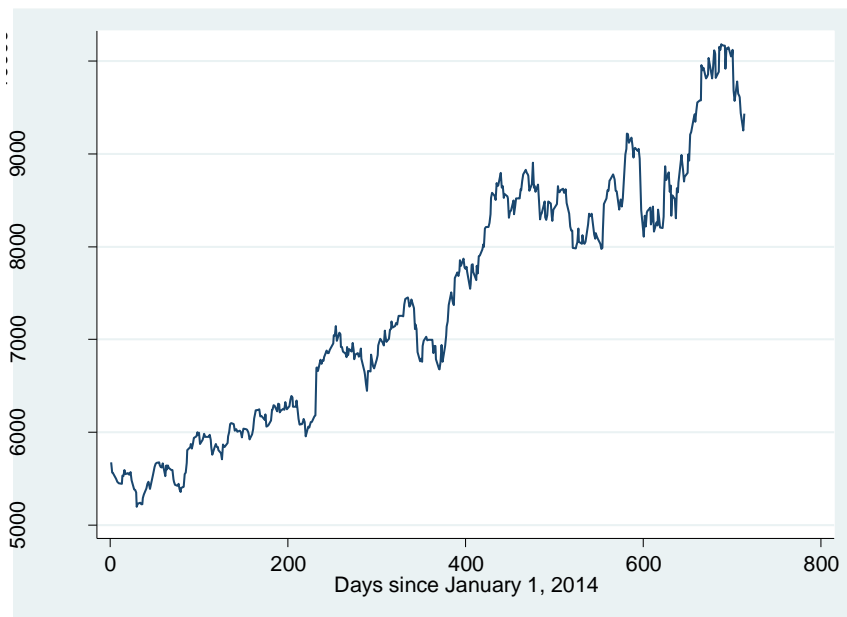
Level: *AEXindex*

```
. keep if stock == 14  
. tsset time  
. graph twoway line AEXindex time
```



Level: *Stockprice*

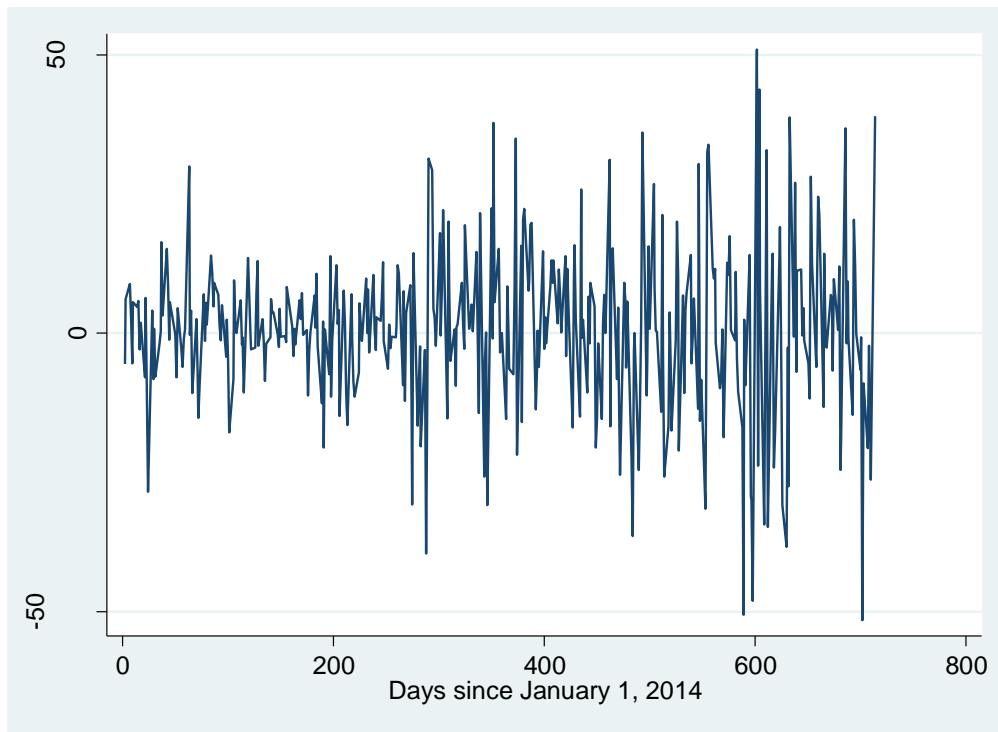
```
. graph twoway line stockprice time
```



The purpose of those graphs is to recognize the development of the level stockprice and to check whether any time trend is needed. Graphs below: the development in the first difference of the stock price is not completely irregular. This is what will be usually checked first.

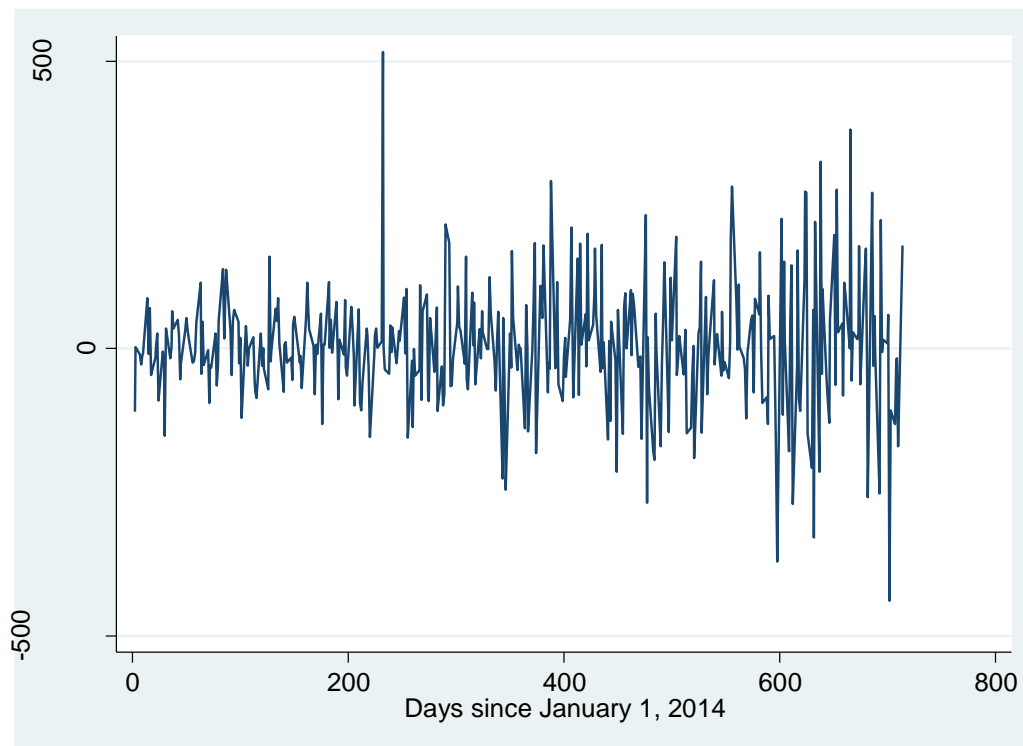
First difference: $\Delta AEXindex$

```
. graph twoway line d.AEXindex time
```



First difference: $\Delta stockprice$

```
. graph twoway line d.stockprice time
```



Consequences of spurious regression & stationarity

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Time series: consistency of OLS

Consider a time-series model with a finite lag.

$$y_t = \alpha + \delta_0 z_t + \delta_1 z_{t-1} + u_t \quad t = 1, 2, \dots$$

- The regression parameters $\alpha, \delta_0, \delta_1$ can be estimated consistently with OLS if the following assumptions hold (in addition to the assumptions of linearity and no perfect collinearity):

TS.1' y_t, z_t, z_{t-1}, u_t must be:

- Stationary
- Weakly dependent.

TS.3' z_t, z_{t-1} are contemporaneously exogenous: $Cov(z_t, u_t) = 0$ and $Cov(z_{t-1}, u_t) = 0$.

Week 2: weak dependence

- Moving average (MA) and autoregressive (AR) models are weakly dependent, in contrast to unit root models.

Correlation between x_t and x_{t+1} :

$$\text{Corr}(x_t, x_{t+1}) = \frac{\text{Cov}(x_t, x_{t+1})}{\sqrt{\text{Var}(x_t)}\sqrt{\text{Var}(x_{t+1})}}$$

Correlation between x_t and x_{t+2} :

$$\text{Corr}(x_t, x_{t+2}) = \frac{\text{Cov}(x_t, x_{t+2})}{\sqrt{\text{Var}(x_t)}\sqrt{\text{Var}(x_{t+2})}}$$

.....

Correlation between x_t and x_{t+h} :

$$\text{Corr}(x_t, x_{t+h}) = \frac{\text{Cov}(x_t, x_{t+h})}{\sqrt{\text{Var}(x_t)}\sqrt{\text{Var}(x_{t+h})}}$$

The definition of **weakly-dependent time series**:

A stationary time series $\{x_t : t = 1, 2, \dots\}$ is weakly dependent if x_t and x_{t+h} are “almost independent” as $h \rightarrow \infty$. Thus $\text{Corr}(x_t, x_{t+h}) \rightarrow 0$ as $h \rightarrow \infty$.

Stationarity

Formal definition of stationary stochastic process (see Wooldridge, Section 11.1):

The stochastic process $\{x_t : t = 1, 2, \dots\}$ is stationary if for every collection of time indices $1 \leq t_1 < t_2 < \dots < t_m$, the joint distribution of $x_{t_1} < x_{t_2} < \dots < x_{t_m}$ is the same as the joint distribution of $x_{t_1+h} < x_{t_2+h} < \dots < x_{t_m+h}$ for all integers $h \geq 1$.

- A stochastic process that is not stationary, is said to be a nonstationary process.
- Stationarity implies that the sequence $\{x_t : t = 1, 2, \dots\}$ is *identically distributed*.
- A process with a time trend is nonstationary

Weaker requirement: covariance stationarity

The stochastic process $\{x_t : t = 1, 2, \dots\}$ is covariance stationary if

- 1) $E(x_t)$ is constant
- 2) $Var(x_t)$ is constant
- 3) For any t , $h \geq 1$, $Cov(x_t, x_{t+h})$ depends only on h and not on t .

Examples of stationary and non-stationary models

Three classes of models are considered:

1) Moving Average (MA) models. E.g. MA(1) (maximum of one period lag):

$$y_t = e_t + \alpha_1 e_{t-1} \quad t = 1, 2, \dots$$

where the error term e_t is i.i.d. with $Ee_t = 0$ and $Var(e_t) = \sigma_e^2$

Features: y_t is stationary and weakly dependent.

2) Autoregressive models. E.g. AR(1) (maximum of one period lag):

$$y_t = \rho_1 y_{t-1} + e_t \quad t = 1, 2, \dots$$

where e_t is i.i.d. with $Ee_t = 0$ and $Var(e_t) = \sigma_e^2$. The error term e_t is independent of y_{t-1} .

Features: y_t is stationary and weakly dependent if the stability condition is met: $|\rho_1| < 1$.

3) Unit root model:

$$y_t = y_{t-1} + e_t \quad t = 1, 2, \dots$$

where e_t is i.i.d. with $Ee_t = 0$ and $Var(e_t) = \sigma_e^2$. The error term e_t is independent of y_{t-1} . Features: y_t is a highly persistent time series.

It is nonstationary and not weakly dependent.

We would like to know how to respond to models containing unit root.

Response:

- 1) Do not need to apply any transformation to the time series if a time series does not have a unit root.
- 2) Take the first differences if a time series has a unit root.

- $\{y_t\}$: Integrated of order one (or $I(1)$).

$$\{y_t\}: I(1) \text{ or } y_t = y_{t-1} + e_t$$

- Note that the first difference of $\{y_t\}$ is $\{e_t\}$.

$$y_t - y_{t-1} = e_t$$

Since e_t is assumed to be i.i.d., it is stationary and weakly dependent.

Dickey-Fuller test

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How do we check for a unit root? Dickey-Fuller test

Aim: to describe the Dickey-Fuller(DF) test.

- Start with an AR(1) model:

$$y_t = \alpha + \rho y_{t-1} + e_t \quad t = 1, 2, \dots, n \quad (18.17)$$

- Assume that e_t is i.i.d. with zero mean and constant variance.

e_t is independent of $y_{t-1}, y_{t-2}, \dots, y_0 \therefore$

$$E(e_t | y_{t-1}, y_{t-2}, \dots, y_0) = 0$$

- $\rho = 1$ gives a random walk
 - $\alpha = 0$ without drift
 - $\alpha \neq 0$ with drift
- The hypotheses:
 - $H_0 : \rho = 1$ (unit root)
 - $H_1 : \rho < 1$ (no unit root)
- Note:
 - Under the null hypothesis the time series $\{y_t\}$ follows random walk/ $\{y_t\}$ has a unit root/ $\{y_t\}$ is I(1) (integrated of order one). These three terms are synonyms. The time series does not follow a t -distribution if the null hypothesis is not rejected. Not even asymptotically.
 - The alternative hypothesis is one sided. If the null hypothesis is rejected, the time series follows a stable AR(1) model.

- Define: $\theta = \rho - 1$ (18.19)

- $y_t = \alpha + \rho y_{t-1} + e_t$ becomes

$$\begin{aligned}
y_t - y_{t-1} &= \alpha + \rho y_{t-1} - y_{t-1} + e_t \\
\Delta y_t &= \alpha + (\rho - 1) y_{t-1} + e_t
\end{aligned}
\tag{18.21}$$

- which is a regression of Δy_t on y_{t-1} :
- The hypotheses become:
 - $H_0 : \theta = 0; (\rho = 1)$ (unit root)
 - $H_1 : \theta < 0; (\rho < 1)$ (no unit root)
- Note:
 - The left-hand side is the first difference variable Δy_t (which is I(0) if H_0 is true); the right-hand side is a level variable (I(1) if H_0 is true).
 - Problem: the t -statistic for $\hat{\theta}$ does not follow t -distribution under H_0 as y_{t-1} is I(1).
 - Dickey-Fuller uses different critical values for the t -statistic of $\hat{\theta}$ (estimated parameter on lagged level variable)

Table 18.2

Signif. level	1%	2.5%	5%	10%
Critical value	-3.43	-3.12	-2.86	-2.57

- E.g. reject H_0 if t -value < -2.86 . Compared with the standard t -test critical values (e.g. -1.645 with $\alpha=0.05$), it is more difficult to reject H_0 with the DF-critical values.
- Apply DF-test on all variables of the regression equation.

Augmented Dickey-Fuller test

Aim: to introduce the augmented DF-test, which corrects for autocorrelation in the residuals.

- Consider a model with additional lags

$$\Delta y_t = \alpha + \theta y_{t-1} + \gamma_1 \Delta y_{t-1} + e_t \quad \text{with } \gamma_1 < 1 \quad (18.23)$$
$$t = 2, 3, \dots, n$$

- DF-test: $H_0: \theta = 0$; $H_1: \theta < 0$ using DF-critical values of t -statistic $\hat{\theta}$
- The critical values of t -statistic for $\hat{\gamma}_1$ (lagged dependent variable) approximately follow a t -distribution. Standard t -tests and F -tests can be applied to determine the appropriate number of (p) lags, Δy_{t-j} to include. $j = 1, 2, \dots, p$
- Rule of thumb:
 - Annual data: one or two lags suffice
 - Monthly data: 12 lags might be needed
 - Quarterly data: four or five lags.

Dickey-Fuller test with time trend

Aim: to introduce a time trend in the DF-test.

- A time trend is added to the basic equation:

$$\Delta y_t = \alpha + \delta t + \theta y_{t-1} + e_t \quad t = 2, 3, \dots, n \quad (18.25)$$

- The same testing procedure as above is applied. Problem: t -value of the estimated parameter on time trend $\hat{\delta}$ does not follow t -distribution under H_0 .
- Dickey-Fuller: the critical values for the t -statistic of $\hat{\theta}$ (estimated parameter on lagged level variable) are:

Table 18.3

Signif. level	1%	2.5%	5%	10%
Critical value	-3.96	-3.66	-3.41	-3.12

- E.g. reject H_0 if t -value < -3.41 at the 5% level. The critical value (5% significance level) of Table 18.2 was 2.86.
- The problem with the DF-test is that it lacks power (large type II-error). There is a high tendency to “accept” the null hypothesis of a unit root, while H_1 (stationarity) is true. This is especially true in the case of small samples.

Application of Dickey-Fuller test

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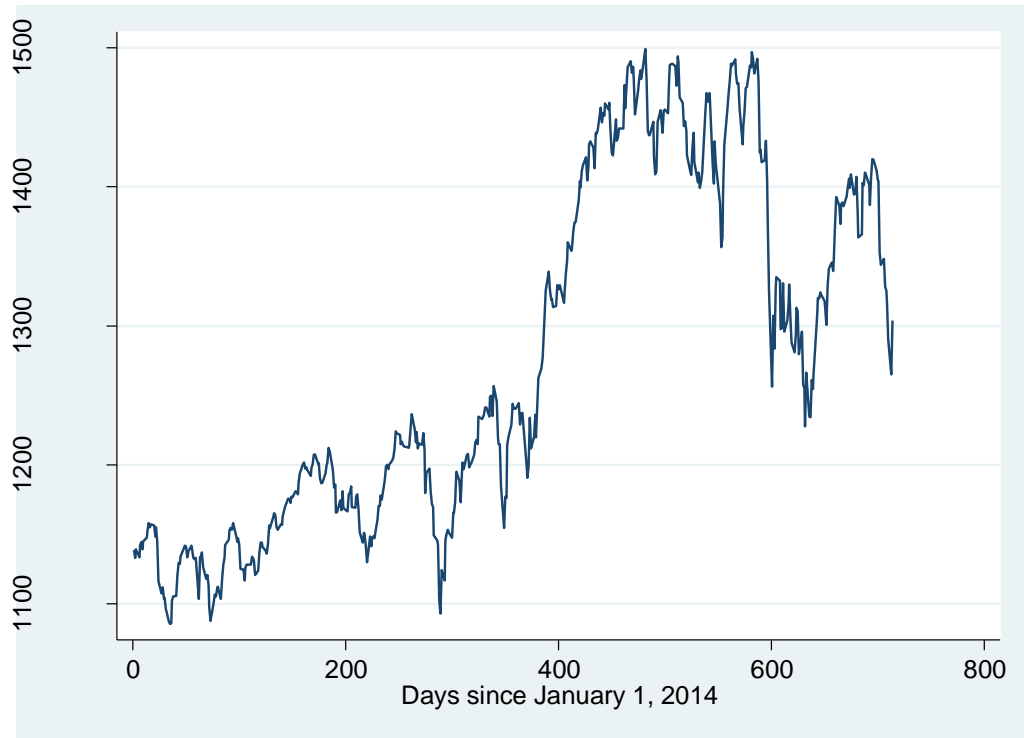
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Example 1: stockdata.dta

Structure:

- Visually inspect to determine whether a time trend is needed in the test.
- Test for unit root in both *AEXindex* and *stockprice*.
- Start with augmented Dickey-Fuller test and determine the appropriate number of lags to include.
- Check whether the time trend is needed in the DF-test.

graph twoway line AEXindex time



1. Test for *stockprice* (no time trend)

- First investigate how many lags of the dependent variable should be included (augmented Dickey-Fuller test).

```
. reg d.AEXindex l.d.AEXindex l2.d.AEXindex l3.d.AEXindex l.AEXindex
```

Source	SS	df	MS	Number of obs = 506		
Model	962.017589	4	240.504397	F(4, 501)	=	1.13
Residual	106309.236	501	212.194083	Prob > F	=	0.3399
Total	107271.253	505	212.418323	R-squared	=	0.0090
				Adj R-squared	=	0.0011
				Root MSE	=	14.567

D.AEXindex	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
AEXindex						
LD.	.0386363	.0448846	0.86	0.390	-.0495491	.1268216
L2D.	-.0332562	.0450354	-0.74	0.461	-.1217377	.0552252
L3D.	.0445622	.0451556	0.99	0.324	-.0441554	.1332798
L1.	-.0083304	.0052092	-1.60	0.110	-.018565	.0019042
_cons	10.95294	6.677218	1.64	0.102	-2.165858	24.07174


```
. test l.d.AEXindex l2.d.AEXindex l3.d.AEXindex
```

```
( 1) LD.AEXindex = 0
( 2) L2D.AEXindex = 0
( 3) L3D.AEXindex = 0
```

```
F( 3, 501) = 0.71
Prob > F = 0.5479
```

$$H_0 : \beta_1 = 0, \beta_2 = 0, \beta_3 = 0$$

$$H_1 : H_0 \text{ not true}$$

The F-statistic > critical value then reject H_0

Since $0.71 < 2.60$ we cannot reject H_0

This can also be observed from the p-value: $0.5479 > 0.05$

```
. reg d.AEXindex l.d.AEXindex l.AEXindex
```

Source	SS	df	MS	Number of obs = 508		
Model	641.309471	2	320.654735	F(2, 505) = 1.52		
Residual	106703.314	505	211.293691	Prob > F = 0.2202		
Total	107344.624	507	211.725096	R-squared = 0.0060		
				Adj R-squared = 0.0020		
				Root MSE = 14.536		

D.AEXindex	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
AEXindex						
LD.	.0354617	.0447228	0.79	0.428	-.052404	.1233274
L1.	-.0082106	.0051726	-1.59	0.113	-.0183732	.0019519
_cons	10.80051	6.629097	1.63	0.104	-2.223492	23.82452

- Estimated parameter on $D.AEX_{t-1}$: a one unit increase in the previous period's change in the AEX index is associated with a 0.0355 unit increase in the current period's change in the AEX index (the t-statistic of 0.79 indicates the effect is zero)
- Estimated parameter on AEX_{t-1} : a one unit increase in AEX in the previous period is associated with a -0.0082 unit decrease in the change in AEX in the current period. (the t-statistic of -1.59 indicates the effect is zero)

```
. reg d.AEXindex l.AEXindex
```

Source	SS	df	MS	Number of obs = 509		
Model	494.45124	1	494.45124	F(1, 507) = 2.35		
Residual	106884.985	507	210.81851	Prob > F = 0.1263		
Total	107379.436	508	211.376842	R-squared = 0.0046		
				Adj R-squared = 0.0026		
				Root MSE = 14.52		

D.AEXindex	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
AEXindex						
L1.	-.0078945	.0051549	-1.53	0.126	-.018022	.002233
_cons	10.39236	6.605534	1.57	0.116	-2.585224	23.36995

$H_0: \theta = 0$ (thus: $\rho = 1$)

$H_1: \theta < 0$ (thus: $\rho < 1$)

If $t_{stat} < cv$, we decide to reject H_0

$-1.53 > -2.86$, H_0 cannot be rejected.

Thus: There is a unit root

- Conclusion 1: no lags on Δy is needed.
- Conclusion 2: the t -statistic of the parameter on y_{t-1} is -1.53 , which is above the critical value of -2.86 in the DF-table.
Conclusion: H_0 cannot be rejected. *AEXindex* has a unit root.

2. Test for *stockprice* (time trend)

```
. reg d.AEXindex l.d.AEXindex l2.d.AEXindex l3.d.AEXindex l.AEXindex day
```

Source	SS	df	MS	Number of obs = 506		
Model	1304.99105	5	260.99821	F(5, 500)	=	1.23
Residual	105966.262	500	211.932524	Prob > F	=	0.2930
				R-squared	=	0.0122
				Adj R-squared	=	0.0023
Total	107271.253	505	212.418323	Root MSE	=	14.558

D.AEXindex	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
AEXindex						
LD.	.0459267	.0452216	1.02	0.310	-.042921	.1347745
L2D.	-.0264859	.0453212	-0.58	0.559	-.1155293	.0625576
L3D.	.0508838	.0454005	1.12	0.263	-.0383155	.1400831
L1.	-.0178597	.0091222	-1.96	0.051	-.0357822	.0000629
day	.009889	.0077735	1.27	0.204	-.0053839	.0251618
_cons	20.56107	10.07844	2.04	0.042	.7597643	40.36237

```
. test l.d.AEXindex l2.d.AEXindex l3.d.AEXindex
```

```
( 1) LD.AEXindex = 0
( 2) L2D.AEXindex = 0
( 3) L3D.AEXindex = 0
      F( 3, 500) = 0.83
      Prob > F = 0.4782
```

Estimated parameter on day: The current period's change in the AEXindex increases by 0.0099 per day, holding 3 periods lagged differences constant.

```
. reg d.AEXindex l.d.AEXindex l.AEXindex day
```

Source	SS	df	MS	Number of obs = 508		
Model	966.988196	3	322.329399	F(3, 504)	=	1.53
Residual	106377.635	504	211.066737	Prob > F	=	0.2065
				R-squared	=	0.0090
				Adj R-squared	=	0.0031
Total	107344.624	507	211.725096	Root MSE	=	14.528

D.AEXindex	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
AEXindex						
LD.	.0425579	.0450624	0.94	0.345	-.0459753	.1310911
L1.	-.0173047	.0089625	-1.93	0.054	-.0349132	.0003037
day	.0094712	.0076246	1.24	0.215	-.0055088	.0244511
_cons	19.96979	9.918958	2.01	0.045	.4821953	39.45739

. reg d.AEXindex l.AEXindex day						
Source	SS	df	MS	Number of obs = 509		
Model	778.508723	2	389.254362	F(2, 506) = 1.85		
Residual	106600.927	506	210.673769	Prob > F = 0.1587		
Total	107379.436	508	211.376842	R-squared = 0.0073		
				Adj R-squared = 0.0033		
				Root MSE = 14.515		
D.AEXindex	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
AEXindex						
L1.	-.0162843	.0088746	-1.83	0.067	-.0337199	.0011513
day	.0087559	.0075405	1.16	0.246	-.0060587	.0235704
_cons	18.85052	9.831666	1.92	0.056	-.4653963	38.16643

Conclusion of unit root does not change.

3. Test for *stockprice* (no time trend)

. reg d.stockprice l.d.stockprice l2.d.stockprice l3.d.stockprice l.stockprice						
Source	SS	df	MS	Number of obs = 506		
Model	21268.5588	4	5317.13969	F(4, 501) = 0.47		
Residual	5686521.35	501	11350.342	Prob > F = 0.7589		
Total	5707789.91	505	11302.5543	R-squared = 0.0037		
				Adj R-squared = -0.0042		
				Root MSE = 106.54		
D.stockprice	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
stockprice						
LD.	-.0354153	.0447523	-0.79	0.429	-.1233407	.05251
L2D.	-.0016895	.0449451	-0.04	0.970	-.0899935	.0866146
L3D.	.034884	.0450086	0.78	0.439	-.053545	.1233129
L1.	-.0028721	.0035604	-0.81	0.420	-.0098673	.0041231
_cons	28.99591	26.70869	1.09	0.278	-23.47893	81.47075

. test l.d.stockprice l2.d.stockprice l3.d.stockprice

- (1) LD.stockprice = 0
- (2) L2D.stockprice = 0
- (3) L3D.stockprice = 0

F(3, 501) = 0.41
 Prob > F = 0.7462

```

. reg d.stockprice l.d.stockprice l.stockprice

```

Source	SS	df	MS			
Model	13523.8227	2	6761.91134	Number of obs = 508		
Residual	5698814.53	505	11284.7813	F(2, 505) = 0.60		
				Prob > F = 0.5496		
				R-squared = 0.0024		
				Adj R-squared = -0.0016		
Total	5712338.36	507	11266.9396	Root MSE = 106.23		

```

-----+-----
D.stockprice |      Coef.   Std. Err.      t    P>|t|     [95% Conf. Interval]
-----+-----
stockprice |
  LD. |   -.0350543   .0445508    -0.79   0.432    - .122582    .0524734
  L1. |   -.0025621   .0035289    -0.73   0.468    - .0094953    .004371
  _cons |    26.78994   26.47965     1.01   0.312    -25.2339    78.81378
-----+-----

```

```

. reg d.stockprice l.stockprice

```

Source	SS	df	MS			
Model	5486.72812	1	5486.72812	Number of obs = 509		
Residual	5720620.49	507	11283.2751	F(1, 507) = 0.49		
				Prob > F = 0.4859		
				R-squared = 0.0010		
				Adj R-squared = -0.0010		
Total	5726107.22	508	11271.8646	Root MSE = 106.22		

```

-----+-----
D.stockprice |      Coef.   Std. Err.      t    P>|t|     [95% Conf. Interval]
-----+-----
stockprice |
  L1. |   -.0024544   .0035196    -0.70   0.486    - .0093692    .0044605
  _cons |    25.50761   26.41139     0.97   0.335    -26.38164    77.39687
-----+-----

```

- Conclusion 1: no lags on Δy is needed.
- Conclusion 2: the t -statistic of the parameter on y_{t-1} is -0.70 , which is above the critical value of -2.86 in the DF-table.
Conclusion: H_0 cannot be rejected. *Stockprice* has a unit root.

4. Test for *stockprice* (time trend)

```
. reg d.stockprice l.d.stockprice l2.d.stockprice l3.d.stockprice l.stockprice
day
```

Source	SS	df	MS	Number of obs =	506
Model	155454.684	5	31090.9367	F(5, 500) =	2.80
Residual	5552335.23	500	11104.6705	Prob > F =	0.0166
				R-squared =	0.0272
				Adj R-squared =	0.0175
Total	5707789.91	505	11302.5543	Root MSE =	105.38

D.stockprice	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]
stockprice					
LD.	-.0116868	.0447886	-0.26	0.794	-.0996838 .0763101
L2D.	.0207671	.0449229	0.46	0.644	-.0674939 .1090281
L3D.	.0555125	.0449127	1.24	0.217	-.0327283 .1437533
L1.	-.0494445	.0138527	-3.57	0.000	-.0766613 -.0222277
day	.4386184	.1261787	3.48	0.001	.1907127 .6865241
_cons	259.9198	71.49079	3.64	0.000	119.4604 400.3792

```
. test l.d.stockprice l2.d.stockprice l3.d.stockprice
```

- ```
(1) LD.stockprice = 0
(2) L2D.stockprice = 0
(3) L3D.stockprice = 0
```

```
F(3, 500) = 0.59
Prob > F = 0.6206
```

```
. reg d.stockprice l.d.stockprice l.stockprice day
```

| Source   | SS         | df  | MS         | Number of obs | = | 508    |
|----------|------------|-----|------------|---------------|---|--------|
| Model    | 138911.355 | 3   | 46303.7848 | F( 3, 504)    | = | 4.19   |
| Residual | 5573427    | 504 | 11058.3869 | Prob > F      | = | 0.0061 |
| Total    | 5712338.36 | 507 | 11266.9396 | R-squared     | = | 0.0243 |
|          |            |     |            | Adj R-squared | = | 0.0185 |
|          |            |     |            | Root MSE      | = | 105.16 |

| D.stockprice | Coef.     | Std. Err. | t     | P> t  | [95% Conf. Interval] |
|--------------|-----------|-----------|-------|-------|----------------------|
| stockprice   |           |           |       |       |                      |
| LD.          | -.0138589 | .0445486  | -0.31 | 0.756 | -.1013827 .0736648   |
| L1.          | -.0464675 | .0134986  | -3.44 | 0.001 | -.072988 -.019947    |
| day          | .4139798  | .1229413  | 3.37  | 0.001 | .1724392 .6555203    |
| _cons        | 244.7914  | 69.84611  | 3.50  | 0.000 | 107.566 382.0168     |

```
. reg d.stockprice l.stockprice day
```

| Source   | SS         | df  | MS         | Number of obs | = | 509    |
|----------|------------|-----|------------|---------------|---|--------|
| Model    | 143367.438 | 2   | 71683.7191 | F( 2, 506)    | = | 6.50   |
| Residual | 5582739.78 | 506 | 11033.0826 | Prob > F      | = | 0.0016 |
| Total    | 5726107.22 | 508 | 11271.8646 | R-squared     | = | 0.0250 |
|          |            |     |            | Adj R-squared | = | 0.0212 |
|          |            |     |            | Root MSE      | = | 105.04 |

| D.stockprice | Coef.     | Std. Err. | t     | P> t  | [95% Conf. Interval] |
|--------------|-----------|-----------|-------|-------|----------------------|
| stockprice   |           |           |       |       |                      |
| L1.          | -.0478543 | .0133058  | -3.60 | 0.000 | -.0739958 -.0217129  |
| day          | .4282322  | .1211368  | 3.54  | 0.000 | .1902392 .6662252    |
| _cons        | 251.1049  | 68.95356  | 3.64  | 0.000 | 115.6343 386.5754    |

- Conclusion 1: no lags on  $\Delta y$  is needed.
- Conclusion 2: the  $t$ -statistic of the parameter on  $y_{t-1}$  is -3.60, which is below the critical value of -3.41 in the DF-table, but it is above the critical value of -3.96.  
Conclusion:  $H_0$  can be rejected. *Stockprice* has no unit root for significance level of 0.05 and *Stockprice* has a unit root for significance level of 0.01.  
In what follows, we assume that *Stockprice* has a unit root.

# Co-integration

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## Co-integration and error-correction models

*Aim: to introduce a co-integrating regression*

- Co-integration theory was developed by Engle and Granger (1987)
- Starting point: two variables that are both  $I(1)$ :  $y_t$  and  $x_t$ .
  - A Dickey Fuller test indicates whether the variables are  $I(0)$  or  $I(1)$ .
- One would expect that linear combinations of  $y_t$  and  $x_t$  are non-stationary also.
- Both variables are co-integrated if there is a  $\beta$ , for which the linear combination of  $y_t$  and  $x_t$  is stationary ( $I(0)$ ). The linear combination is  $y_t - \beta x_t$
- Economic interpretation of co-integration: the difference between  $y_t$  and  $\beta x_t$  is on average constant. There is a tendency to move back to this constant. Also, the variance of  $y_t - \beta x_t$  is constant. Thus,  $y_t = \alpha + \beta x_t$  is a long-run relationship.
- There are two cases where co-integration occurs.
- Case 1:  $\beta$  is known. Compute  $s_t = y_t - \beta x_t$  and test whether there is a unit root in  $s_t$  using a Dickey Fuller test.
  - If the null hypothesis is rejected (of a unit root in  $s_t$ ) then  $y_t$  and  $x_t$  will be co-integrated.
- Case 2:  $\beta$  is unknown and must be estimated. If  $y_t$  and  $x_t$  are co-integrated the OLS estimator  $\hat{\beta}$  from the co-integrating regression:
$$\hat{y}_t = \hat{\alpha} + \hat{\beta} x_t \tag{18.31}$$
is consistent for  $\beta$ .
  - Determine the residual:  $\hat{u}_t = y_t - \hat{\alpha} - \hat{\beta} x_t$



- Since  $\hat{\beta}$  is estimated, the critical values of Tables 18.2 and 18.3 cannot be used.

**Testing for co-integration (after co-integrating regression  
(18.31) (Engle-Granger test):**

**Table 18.4**

|                |       |       |       |       |
|----------------|-------|-------|-------|-------|
| Signif. level  | 1%    | 2.5%  | 5%    | 10%   |
| Critical value | -3.90 | -3.59 | -3.34 | -3.04 |

- The model:  $y_t = \alpha + \beta x_t$
- Dickey Fuller test on co-integration of  $y_t$  and  $x_t$ . We run a regression of  $\Delta \hat{u}_t$  on  $\hat{u}_{t-1}$ , and we may compare the  $t$ -statistic on  $\hat{u}_{t-1}$  with the critical value in table 18.3.
  - If fail to reject  $H_0$ : regression of  $y_t$  on  $x_t$  is spurious.
  - If reject  $H_0$ : regression of  $y_t$  on  $x_t$  is a co-integrating regression.
- There may be a time-trend in the co-integrating regression:
 
$$y_t = \hat{\alpha} + \hat{\eta}t + \hat{\beta}x_t \quad (18.32)$$

**Table 18.5**

|                |       |       |       |       |
|----------------|-------|-------|-------|-------|
| Signif. level  | 1%    | 2.5%  | 5%    | 10%   |
| Critical value | -4.32 | -4.03 | -3.78 | -3.50 |

## Example 2: test on co-integration

```
. reg AEXindex stockprice
```

| Source   | SS         | df  | MS         | Number of obs = | 510     |
|----------|------------|-----|------------|-----------------|---------|
| Model    | 6031609.59 | 1   | 6031609.59 | F( 1, 508) =    | 1610.23 |
| Residual | 1902875.37 | 508 | 3745.81766 | Prob > F =      | 0.0000  |
|          |            |     |            | R-squared =     | 0.7602  |
|          |            |     |            | Adj R-squared = | 0.7597  |
| Total    | 7934484.96 | 509 | 15588.3791 | Root MSE =      | 61.203  |

| AEXindex   | Coef.    | Std. Err. | t     | P> t  | [95% Conf. Interval] |
|------------|----------|-----------|-------|-------|----------------------|
| stockprice | .0811894 | .0020233  | 40.13 | 0.000 | .0772144 .0851645    |
| _cons      | 675.5636 | 15.19135  | 44.47 | 0.000 | 645.718 705.4092     |

```
. predict uhat, resid
```

```
. reg d.uhat l.uhat
```

| Source   | SS         | df  | MS         | Number of obs = | 509    |
|----------|------------|-----|------------|-----------------|--------|
| Model    | 195.994111 | 1   | 195.994111 | F( 1, 507) =    | 1.74   |
| Residual | 57211.1212 | 507 | 112.842448 | Prob > F =      | 0.1881 |
|          |            |     |            | R-squared =     | 0.0034 |
|          |            |     |            | Adj R-squared = | 0.0014 |
| Total    | 57407.1153 | 508 | 113.006133 | Root MSE =      | 10.623 |

| D.uhat | Coef.     | Std. Err. | t     | P> t  | [95% Conf. Interval] |
|--------|-----------|-----------|-------|-------|----------------------|
| uhat   |           |           |       |       |                      |
| L1.    | -.0101998 | .0077394  | -1.32 | 0.188 | -.0254051 .0050054   |
| _cons  | -.2724943 | .470849   | -0.58 | 0.563 | -1.19755 .6525611    |

- The above output indicates that *AEXindex* and *stockprice* are not co-integrated, as the  $t$ -statistic on  $\hat{u}_{t-1}$  (-1.32) is above the critical value (Table 18.4; -3.34 at the 5%-level).

```
. reg d.uhat l.uhat day
```

| Source   | SS         | df  | MS         | Number of obs = 509    |  |  |
|----------|------------|-----|------------|------------------------|--|--|
| Model    | 320.225932 | 2   | 160.112966 | F( 2, 506) = 1.42      |  |  |
| Residual | 57086.8894 | 506 | 112.81994  | Prob > F = 0.2429      |  |  |
| Total    | 57407.1153 | 508 | 113.006133 | R-squared = 0.0056     |  |  |
|          |            |     |            | Adj R-squared = 0.0016 |  |  |
|          |            |     |            | Root MSE = 10.622      |  |  |

| D.uhat | Coef.     | Std. Err. | t     | P> t  | [95% Conf. Interval] |          |
|--------|-----------|-----------|-------|-------|----------------------|----------|
| uhat   |           |           |       |       |                      |          |
| L1.    | -.0106252 | .0077493  | -1.37 | 0.171 | -.0258499            | .0045995 |
| day    | -.0033669 | .0032085  | -1.05 | 0.295 | -.0096705            | .0029368 |
| _cons  | .5895392  | .9468343  | 0.62  | 0.534 | -1.270671            | 2.44975  |

- The above output indicates that *AEXindex* and *stockprice* are not co-integrated, as the  $t$ -statistic on  $\hat{u}_{t-1}$  (-1.37) is above the critical value (Table 18.5; -3.78 at the 5%-level).

# Error-correction models

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## Error-correction models

*Aim: to consider the economic implications of error-correction models.*

**Case 1 (no error correction):**  $y_t$  and  $x_t$  are both  $I(1)$ , and there is no co-integration between  $y_t$  and  $x_t$  (no rejection of  $H_0$  after DF-test on residuals of (18.31). The model becomes:

$$\Delta y_t = \alpha_0 + \alpha_1 \Delta y_{t-1} + \gamma_0 \Delta x_t + \gamma_1 \Delta x_{t-1} + u_t \quad (18.36)$$

All variables are in first differences.

**Case 2 (error-correction model):**  $y_t$  and  $x_t$  are both  $I(1)$ , and there is co-integration between  $y_t$  and  $x_t$  (rejection of  $H_0$  after DF-test on residuals of (18.31)).

$$\begin{aligned} \Delta y_t &= \alpha_0 + \alpha_1 \Delta y_{t-1} + \gamma_0 \Delta x_t + \gamma_1 \Delta x_{t-1} + \delta s_{t-1} + u_t = \\ &= \alpha_0 + \alpha_1 \Delta y_{t-1} + \gamma_0 \Delta x_t + \gamma_1 \Delta x_{t-1} + \delta(y_{t-1} - \beta x_{t-1}) + u_t \end{aligned} \quad (18.37)$$

- $s_{t-1} = y_{t-1} - \beta x_{t-1}$  is called the error-correction term. Note that the lag  $t-1$  of  $s$  is included in the equation.

### Economic interpretation:

$$\Delta y_t = \alpha_0 + \gamma_0 \Delta x_t + \delta(y_{t-1} - \beta x_{t-1}) + u_t \quad (18.38)$$

where  $\delta < 0$ .

- $\Delta y_t$  will return to equilibrium if  $y_{t-1} > \beta x_{t-1}$  or  $y_{t-1} < \beta x_{t-1}$  as  $\delta < 0$ . If  $y_{t-1} > \beta x_{t-1}$  the return to equilibrium will involve a decrease in  $\Delta y_t$ , and if  $y_{t-1} < \beta x_{t-1}$  it will lead to increase in  $\Delta y_t$ . The adjustments are because the parameter  $\delta < 0$
- In equation (18.38) a lag of  $\Delta y_t$  was excluded to keep it simple.

### **How is an error-correction model estimated?**

*Aim: to demonstrate the estimation procedure.*

#### **Case 1: $\beta$ is known.**

Regress  $\Delta y_t$  on  $\Delta x_t$  and  $s_{t-1}$ , where  $s_{t-1} = y_{t-1} - \beta x_{t-1}$   
 $s_{t-1}$  is the error correction term.

Note that the lag  $t-1$  of  $s$  is included in the equation.

#### **Case 2: $\beta$ is unknown - two-stage procedure**

Regress  $\Delta y_t$  on  $\Delta x_t$  and  $\hat{s}_{t-1}$ , where  $\hat{s}_{t-1} = y_{t-1} - \hat{\beta} x_{t-1}$

## Summary

- The model:  $y_t = \alpha + \beta x_t$ 
  - Step 1: Dickey Fuller tests for unit root in  $y_t$  and  $x_t$ 
    - This determines whether to include a time trend and how many lags of  $\Delta y_t$  are appropriate.
  - If both  $y_t$  and  $x_t$  are I(1) continue with the following:
  - Step 2: co-integrating regression
  - Step 3: Dickey-Fuller test (for unit root), to the residuals
$$\hat{u}_t = y_t - \hat{\alpha} - \hat{\beta}x_t$$
  - Step 4a: If the model contains unit root (H0 of step 3 cannot be rejected), estimate the model in first differences.
  - Step 4b: If the model contains no unit root (H0 of step 3 can be rejected) use the error-correction model.
  - Step 5 (after 4b). Estimate the error-correction model using the two-stage procedure.



# Forecasting

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## Section 18.5: Forecasting

*Aim: to introduce forecasting procedures*

- Next we consider forecasting with time series, and we apply it to dynamic models.
- At time  $t$  we would like to make a forecast of  $y$  at  $t+1$ .
- Notation:
  - $I_t$ : all information available at time  $t$ .
  - $f_t$  is the one-period ahead forecast.
  - $e_{t+1} = y_{t+1} - f_t$ : forecast error
- We consider the squared error (as a loss function)
  - $E(e_{t+1}^2 | I_t) = E[(y_{t+1} - f_t)^2 | I_t]$  (18.40)
  - The squared error is minimal at  $f_t = E(y_{t+1} | I_t)$
  - Best forecast:  $E(y_{t+1} | I_t)$
- Example 3: Forecast based on a martingale (it means that adding more lagged variables does not provide more information to the equation):
  - $E(y_{t+1} | y_t, y_{t-1}, \dots, y_0) = y_t$
- Example 4: Forecast based on **exponential smoothing**:
  - $f_t = \alpha y_t + (1 - \alpha)f_{t-1}$  (with  $f_0 = y_0$  and  $0 < \alpha < 1$ ) so that the forecast of  $y_{t+1}$  is a weighted average of the previous forecast (at  $t-1$ ) and the current realization of  $y$ .
  - $E(y_{t+1} | I_t) = \alpha y_t + \alpha(1 - \alpha)y_{t-1} + \dots + \alpha(1 - \alpha)^t y_0$
- The application of smoothing (in addition to forecasting) can be used to extract an overall trend from a time-series. This is because a time series may contain a trend component as well as an irregular component. The researcher might only be interested in the trend component.

## Example 5: stockdata.dta

- Example 1 showed that *stockprice* is  $I(1)$ . It contains a unit root, so the level of *stockprice* is uninformative.

```
. tssmooth exponential lev_stockprice = stockprice

computing optimal exponential coefficient (0,1)

optimal exponential coefficient = 0.9998
sum-of-squared residuals = 36603.576
root mean squared error = 8.651817

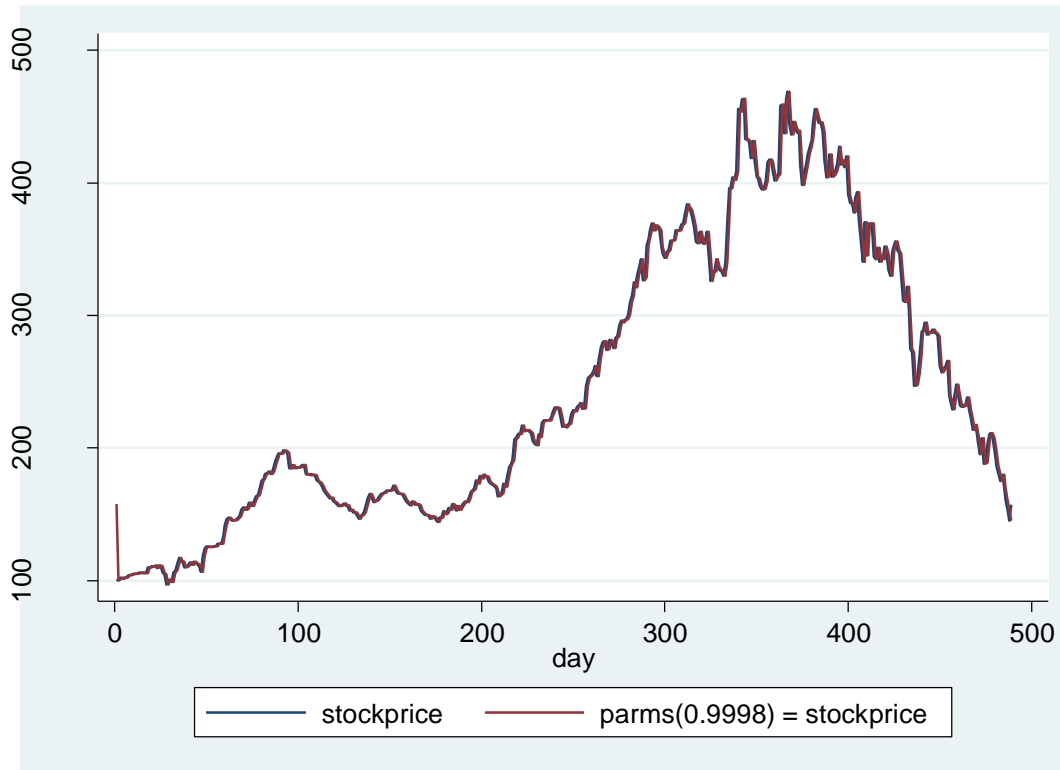
. tssmooth exponential dif_stockprice = d.stockprice

computing optimal exponential coefficient (0,1)

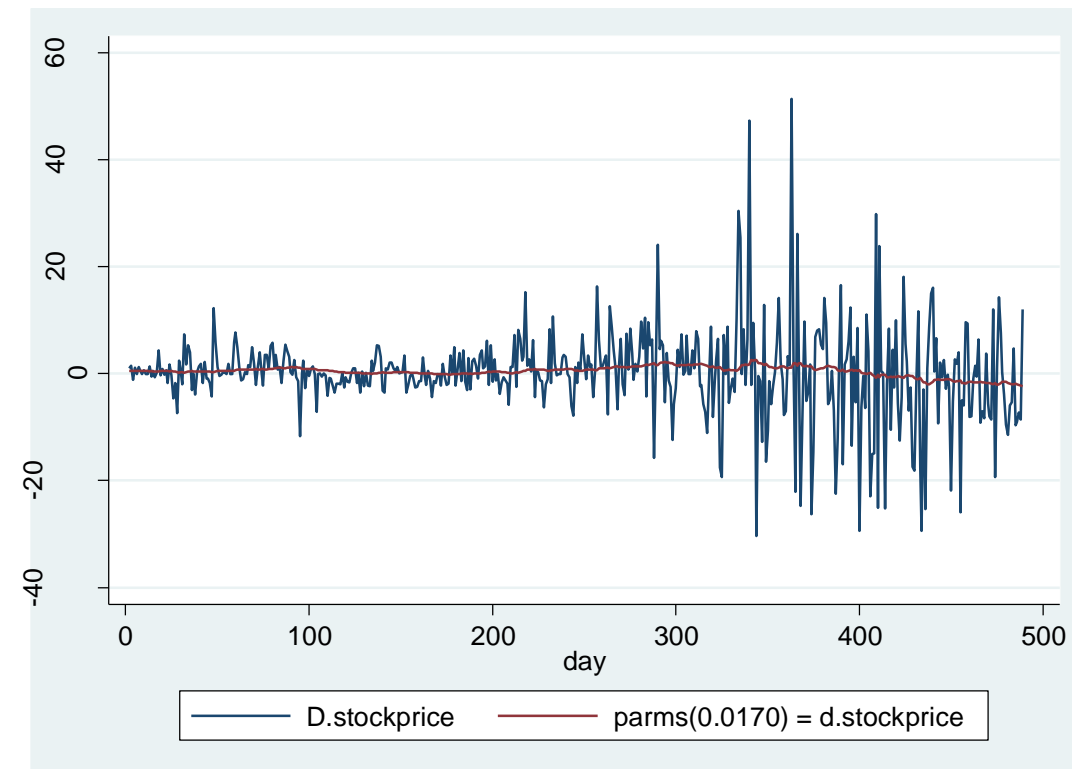
optimal exponential coefficient = 0.0170
sum-of-squared residuals = 33045.423
root mean squared error = 8.2289751
. tsline gfr gfr_smooth_level
. tsline d.gfr gfr_smooth_dif

(see graphs below)
```

tsline stockprice lev\_stockprice



. tsline d.stockprice dif\_stockprice (on first-differenced data)



## Using regression models for forecasting

*Aim: to show that regressions can be used for forecasts and forecast intervals.*

- Below is a dynamic regression equation, in which the forecast depends on lagged values of  $y$  and  $z$ :

$$y_t = \delta_0 + \alpha_1 y_{t-1} + \gamma_1 z_{t-1} + u_t$$

$$E(u_t | I_{t-1}) = 0$$

- The forecast of  $y_{t+1}$  is  $\delta_0 + \alpha_1 y_t + \gamma_1 z_t$

- Thus:  $\hat{f}_t = \hat{\delta}_0 + \hat{\alpha}_1 y_t + \hat{\gamma}_1 z_t$

- The forecast error is  $e_{t+1} = y_{t+1} - \hat{f}_t$

- The variance of the forecast error is:

$$Var(e_{t+1}) = Var(u_t) + Var(\hat{f}_t) = \hat{\sigma}_u^2 + Var(\hat{f}_t)$$

- A 95% forecast interval:  $\hat{f}_t \pm 2 * \sqrt{\hat{\sigma}_u^2 + Var(\hat{f}_t)}$  (18.47)

# Vector autoregressive (VAR) model

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## Vector autoregressive (VAR) model: Sims (Nobel prize, 2011)

*Aim: to introduce VAR-models for forecasting.*

- Model:

$$y_t = \delta_0 + \alpha_1 y_{t-1} + \gamma_1 z_{t-1} + \alpha_2 y_{t-2} + \gamma_2 z_{t-2} + \dots \quad (18.50)$$

$$z_t = \eta_0 + \beta_1 y_{t-1} + \rho_1 z_{t-1} + \beta_2 y_{t-2} + \rho_2 z_{t-2} + \dots$$

- A VAR model may be applied for forecasting

e.g.

$$y_t = \delta_0 + \alpha_1 y_{t-1} + \gamma_1 z_{t-1} + u_{1t}$$

$$z_t = \eta_0 + \beta_1 y_{t-1} + \rho_1 z_{t-1} + u_{2t}$$

$u_{1t}$  and  $u_{2t}$  are i.i.d. (with different variances and they are mutually independent). They are independent of all previous observations of  $y$  and  $z$ .

- Three advantages of VAR models are that:
  - a) The components can be considered simultaneously
  - b) The model can be more parsimonious
  - c) The model may include fewer lags

This allows more accurate forecasting, because the information set (the right-hand side variables of the regression equation) is extended and also includes the history of other variables.

- Impulse Response Functions (IRF) is also used to produce forecasts. (no part of this course)
- The error terms are assumed to be stationary (no unit root).
- (18.50) is not a structural equation model because:
  - The exclusion constraints (see forthcoming lecture 7) are not necessary to identify the structural model.
  - There is no a priori distinction between endogenous and exogenous variables.
- OLS on equations of equation (18.50) separately will yield consistent estimates.
- It is not easy to select the optimal lag length. Estimate the model and then apply the Akaike Information Criterion (AIC, not part of this course). Choose the model with the lowest AIC. The AIC is a selection criterion that is comparable to the adjusted  $R$ -

squared (remember that the selected model is often the one with the highest  $R$ -squared).



## Example 6: VAR

The command for VAR (we apply 2 lags)

```
. var d.AEXindex d.stockprice, lags(1/2)
```

Vector autoregression

|                |             |            |   |          |
|----------------|-------------|------------|---|----------|
| Sample:        | 4 - 510     | No. of obs | = | 507      |
| Log likelihood | = -4994.471 | AIC        | = | 19.7415  |
| FPE            | = 1284333   | HQIC       | = | 19.77421 |
| Det(Sigma_ml)  | = 1234654   | SBIC       | = | 19.82491 |

| Equation     | Parms | RMSE    | R-sq   | chi2     | P>chi2 |
|--------------|-------|---------|--------|----------|--------|
| D_AEXindex   | 5     | 14.5954 | 0.0035 | 1.766256 | 0.7786 |
| D_stockprice | 5     | 106.408 | 0.0050 | 2.529515 | 0.6394 |

|              | Coef.     | Std. Err. | z     | P> z  | [95% Conf. Interval] |
|--------------|-----------|-----------|-------|-------|----------------------|
| D_AEXindex   |           |           |       |       |                      |
| AEXindex     |           |           |       |       |                      |
| LD.          | .0145237  | .0617081  | 0.24  | 0.814 | -.106422 .1354694    |
| L2D.         | -.0643886 | .0615668  | -1.05 | 0.296 | -.1850573 .05628     |
| stockprice   |           |           |       |       |                      |
| LD.          | .0037053  | .0084287  | 0.44  | 0.660 | -.0128147 .0202353   |
| L2D.         | .0059473  | .0084252  | 0.71  | 0.480 | -.0105657 .0224604   |
| _cons        | .2688697  | .6495078  | 0.41  | 0.679 | -1.004142 1.541882   |
| D_stockprice |           |           |       |       |                      |
| AEXindex     |           |           |       |       |                      |
| LD.          | .5195352  | .4498833  | 1.15  | 0.248 | -.36222 1.40129      |
| L2D.         | -.3051594 | .4488529  | -0.68 | 0.497 | -1.184895 .5745761   |
| stockprice   |           |           |       |       |                      |
| LD.          | -.0839891 | .0614497  | -1.37 | 0.172 | -.2044284 .0364502   |
| L2D.         | .0207528  | .0614238  | 0.34  | 0.735 | -.0996357 .1411413   |
| _cons        | 8.039581  | 4.735239  | 1.70  | 0.090 | -1.241318 17.32048   |

## **Wrapping up**

We have considered:

- Testing for unit roots
- Co-integration and error correction models
- A test for co-integration: Engle and Granger test.
- Error-correction
- Prediction and smoothing
- Vector Autoregressive (VAR) models