Machine Learning and Data Science

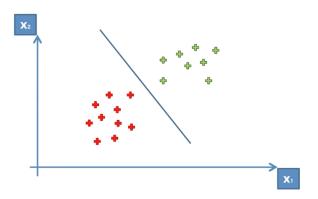
Machine à vecteurs de support, astuce du noyau (kernel SVM)

Bassem Ben Hamed

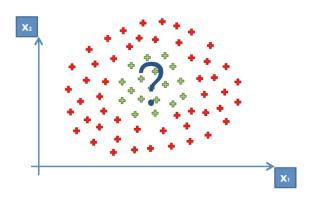
Juillet 2018

Kernel SVM Intuition

SVM sépare bien ces points



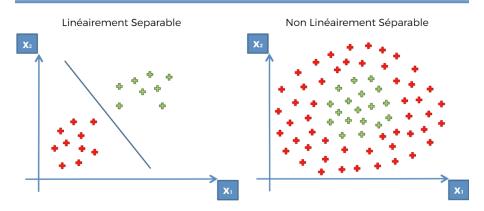
Et ces points?



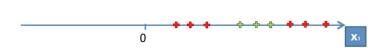
Pourquoi?

Parce que les points d'observation ne sont pas LINÉAIREMENT SEPARABLES

Linéairement Séparable



Espace de plus grande dimension

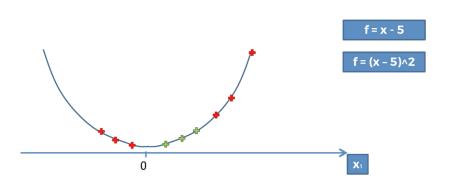


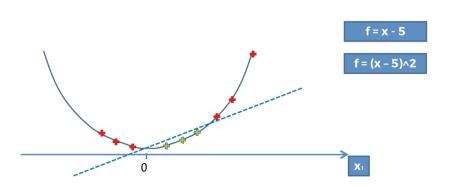
f=x-5

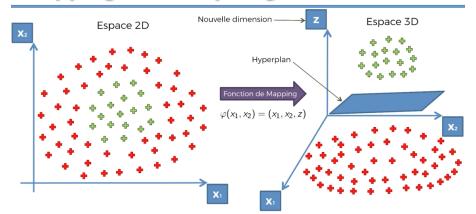


f=x-5

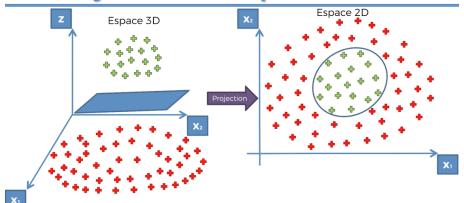








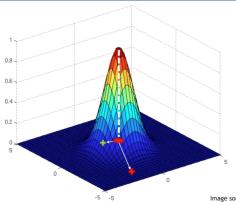
Re-Projection vers Espace 2D



Mais il y a un petit problème...

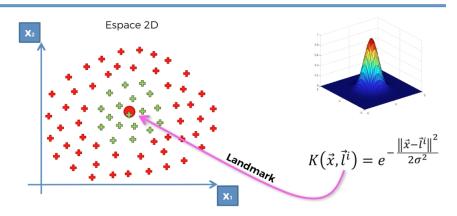
Le Mapping vers un espace de plus grande dimension peut demander trop de calculs

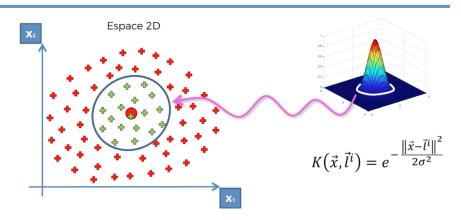
La solution Kernel

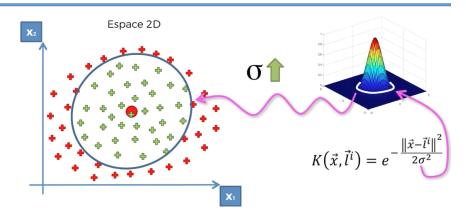


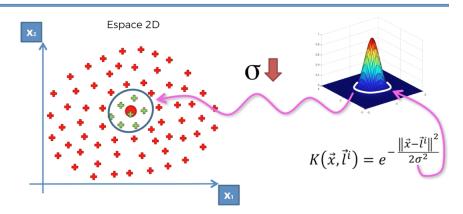
$$K(\vec{x}, \vec{l}^i) = e^{-\frac{\|\vec{x} - \vec{l}^i\|^2}{2\sigma^2}}$$

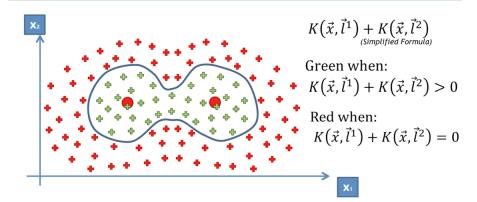
Image source: http://www.cs.toronto.edu/~duvenaud/cookbook/index.html





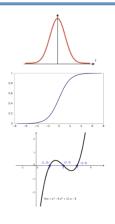






D'autres Kernels

D'autres Kernels



Gaussian RBF Kernel

$$K(\vec{x}, \vec{l}^i) = e^{-\frac{\left\|\vec{x} - \vec{l}^i\right\|^2}{2\sigma^2}}$$

Sigmoid Kernel

$$K(X,Y) = \tanh(\gamma \cdot X^T Y + r)$$

Polynomial Kernel

$$K(X,Y) = (\gamma \cdot X^T Y + r)^d, \gamma > 0$$