

PROGRAMMING EMBEDDED SYSTEMS

Assignment one Intro to FreeRTOS and Scheduling

Bassem Farag Personal number: 199110167153 November 3, 2016

1 Programming with FreeRTOS tasks

- 1. a) As "xTimeincrement" defines the amount of time that the task will be idle (roughly the period of the task) so the data type of that variable can have limitations on the calculations.
 - b) While trying to test the accuracy of the delay until using different xTimeincrement values, the minimum value was one millisecond, even when i try to delay with a value less than 1 millisecond by inceasing the value of the "TickRate" in the FReeRTOSConfig.h file it suffers from anomalies.
 - c) The resolution can affect the performance of the system as it can limit the delay between tasks which can affect the performance.

2 RATE-MONOTONIC SCHEDULING

- 1. As the Rate monotonic scheduling is used with periodic tasks with (T=D), so for the "Planning module" task the RMS can not deal with it, so as a task set it can not be scheduled by the RMS.
- 2. For the rest four tasks and by calculating the *Utilization factor* which was less than the *Utilization Bound* so the rest of the task set is schedulable.

Lab.1 1



- 3. The $\it WCET$ can be calculated by simulation as follows:
 - a) Create a timer.
 - b) Start the timer when the task is released.
 - c) Save the value of the timer when the tasks finishes execution.