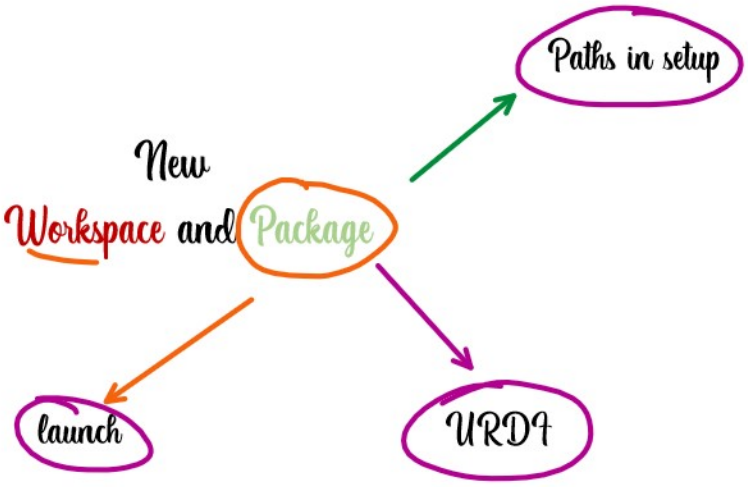
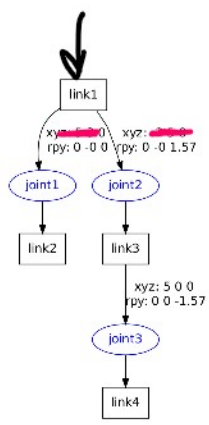
S#1 :: Universal Robot Description File

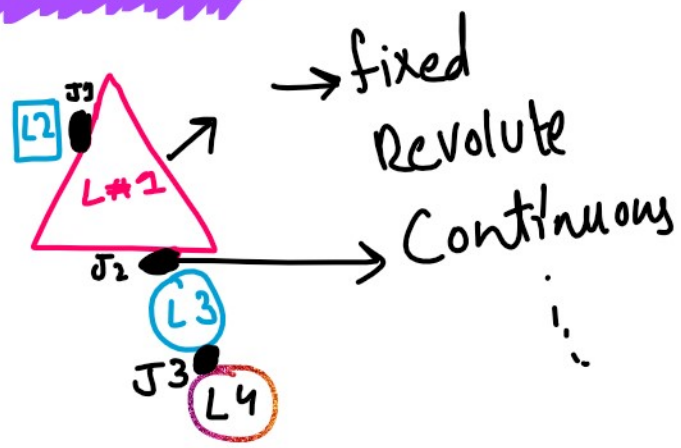
Monday, 12 July 2021 10:30 AM



Tree Structure of URDF



http://library.isr.ist.utl.pt/docs/roswiki/urdf(2f)Tutorials(2f)Create(20)your(20)own(20)urdf(20)file.html

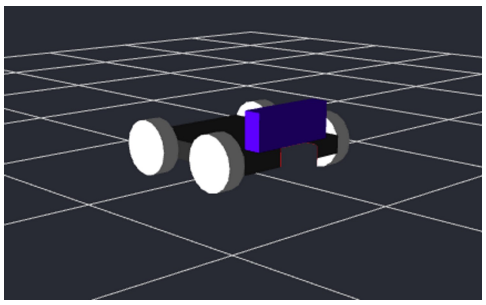


Tree Structure of Rover

Links and joints of our robot

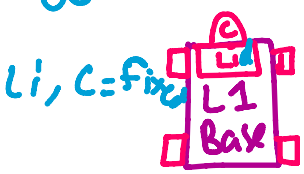
Creating our robot tree which makes sense.

Links and joints of our robot

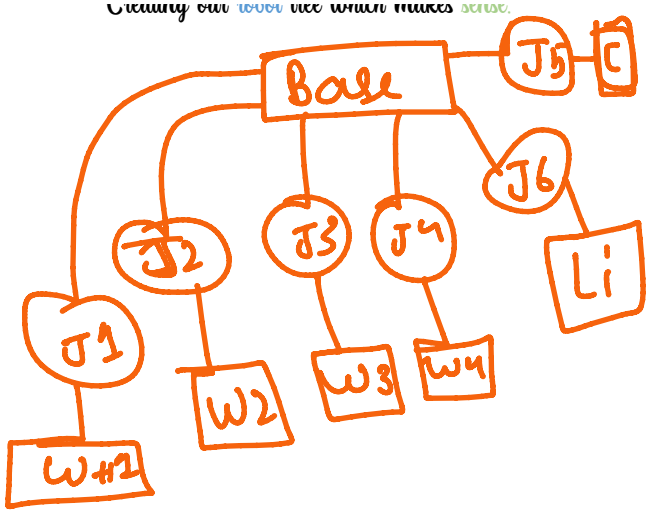


W = Revolute

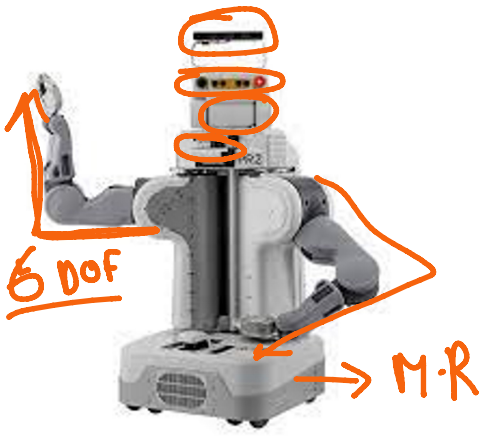
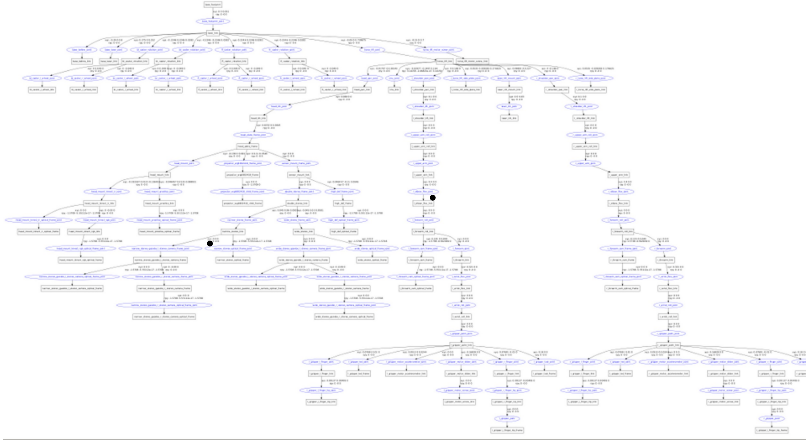
Li, C = fixed



Creating our robot tree which makes sense.



Now lets take a look at pr2's tree



Tree.