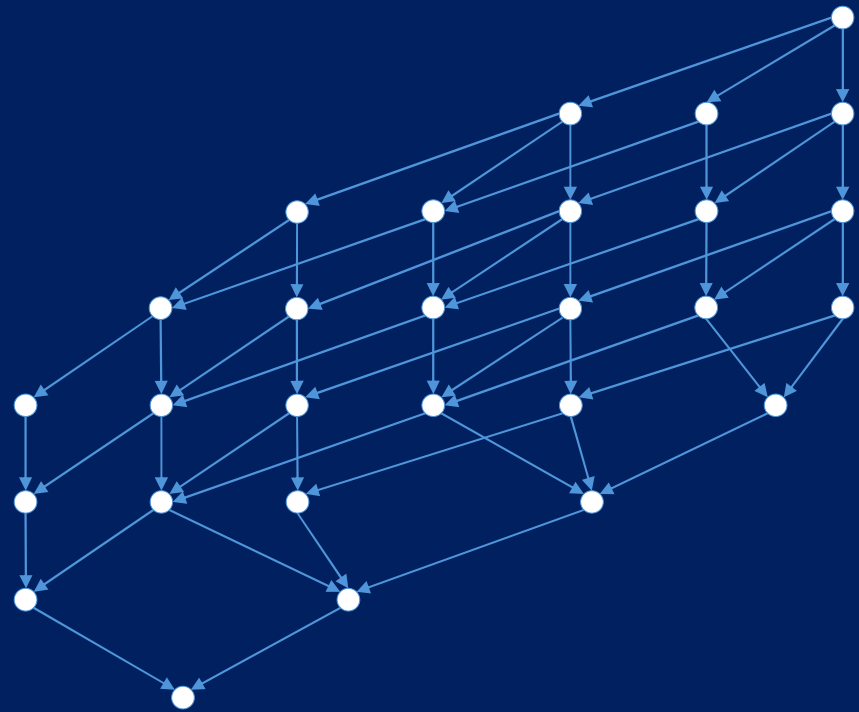


Graph Signal Processing

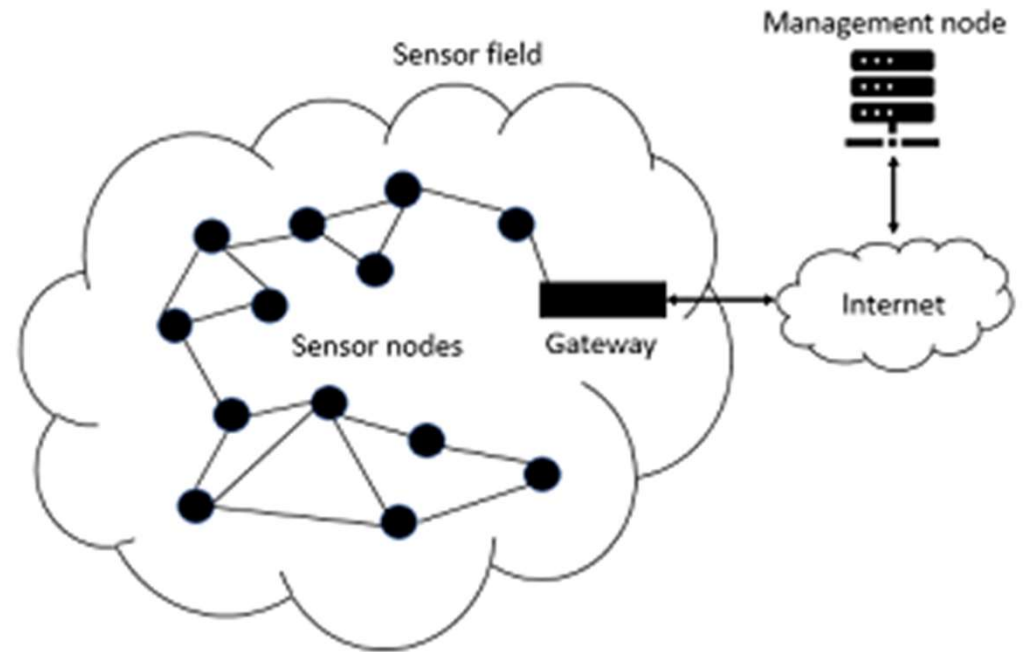
Bastian Seifert

Sommersemester 2025



Problem statement

- Sensors might be expensive to operate
- Sensor/battery lifetime might be increased when used less often
- System might be more efficient with less data transmitted



https://study.com/cimages/multimages/16/c701edbb-2f75-4518-a658-60a5743f66a5_sensor_networ.png

Sampling problem: How to infer values of nodes not observed?

Sampling

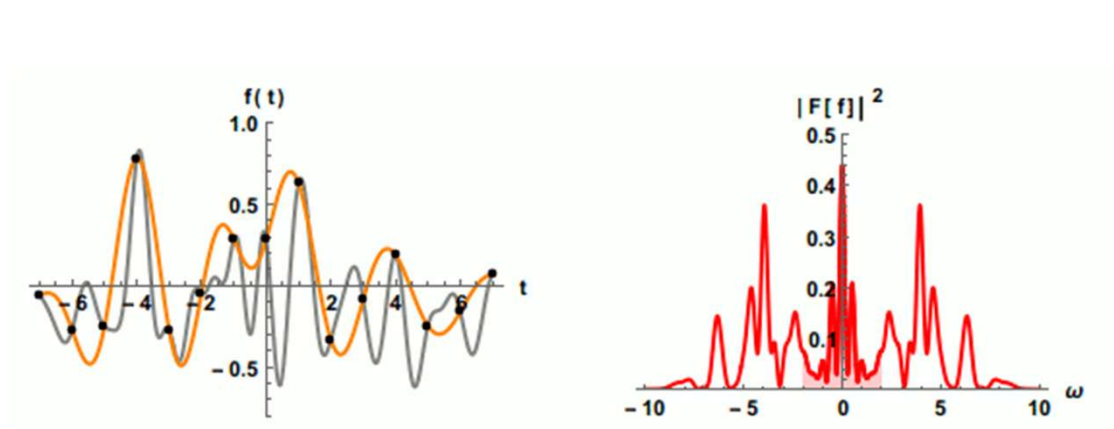
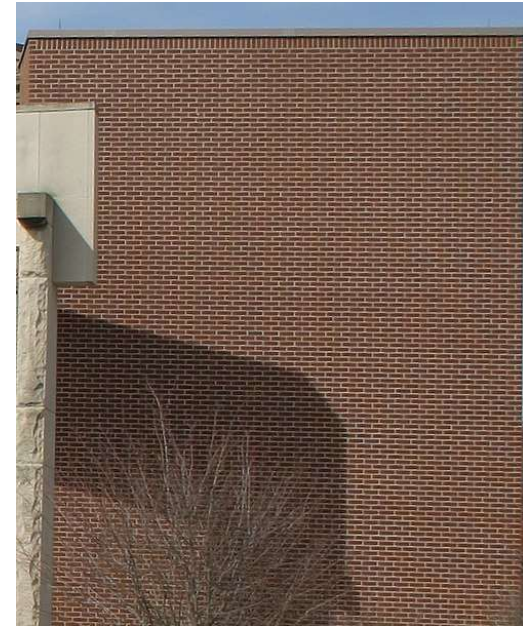
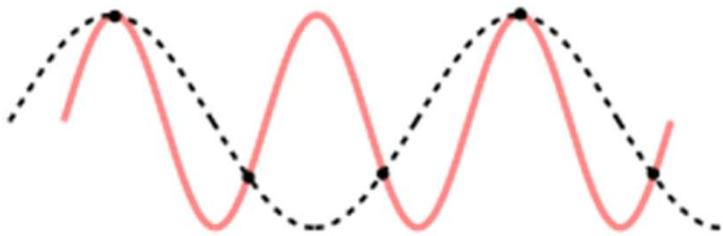


Figure: https://en.wikipedia.org/wiki/Nyquist%E2%80%93Shannon_sampling_theorem

Down-Sampling (gone wrong)



Figures: https://en.wikipedia.org/wiki/Nyquist%E2%80%93Shannon_sampling_theorem

Sampling

$$x \in \mathbb{C}^N$$

$$x_M = \Psi x \in \mathbb{C}^M, \quad M < N$$

↑ Measured signal

Sampling takes (a linear combination of) samples at chosen measurement points to produce a lower dimensional signal.

Interpolation

$$\tilde{x} = \Phi x_M = \Phi \Psi x \in \mathbb{C}^N$$

Interpolation approximates the original signal based on the sampled signal.

$$\tilde{x} \approx x$$

Example

$$\Psi = \begin{bmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 \end{bmatrix}$$

$$\Psi x = \begin{bmatrix} x_2 + x_4 \\ x_1 + x_3 \end{bmatrix}$$

$$\Phi = \begin{bmatrix} 0 & \frac{1}{2} \\ \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \\ \frac{1}{2} & 0 \end{bmatrix}$$

$$\Phi \Psi x = \frac{1}{2} \begin{bmatrix} x_1 + x_3 \\ x_2 + x_4 \\ x_1 + x_3 \\ x_2 + x_4 \end{bmatrix}$$

$$x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix}$$

Perfekte Rekonstruktion für
Signale mit $x_1 = x_3$ und $x_2 = x_4$

Sampling and Interpolation are pseudo-inverse operations to each other

Bandlimited Graph Signals

Graph signals are called k -bandlimited if they can be expressed as a linear combination of k eigenvectors of the graph shift operator

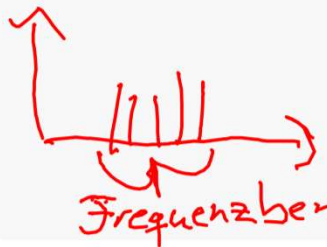
$$\mathbf{x} = U_k \alpha, \quad \text{with } \alpha \in \mathbb{R}^k$$

k Eigenvektoren von T , also graph Frequenzen
Die k Frequenzen können beliebig gewählt werden
 Note that this is equivalent to k -sparsity in the graph Fourier domain

$$\|\mathcal{F}\mathbf{x}\|_0 = k$$

(Hint: Sparse Fourier transformation)

Frequenzbereich der $\neq 0$ ist definiert



Perfect Reconstruction Condition

k -bandlimited

A graph signal can be perfectly recovered if

$$\text{rank}(\Psi U_k) = k$$

The interpolation operator which achieves perfect recovery is

$$\Phi = U_k V$$

where

$$V \Psi U_k = \mathbb{I}_k$$

is an identity matrix (i.e., a pseudo-inverse)

$$\Phi \Psi \mathbf{x} = \Phi \Psi U_k \alpha = U_k \underbrace{V \Psi U_k}_{\mathbb{I}_k} \alpha = U_k \alpha = \mathbf{x}$$

Perfect reconstruction is possible for bandlimited signals

Sampling strategies

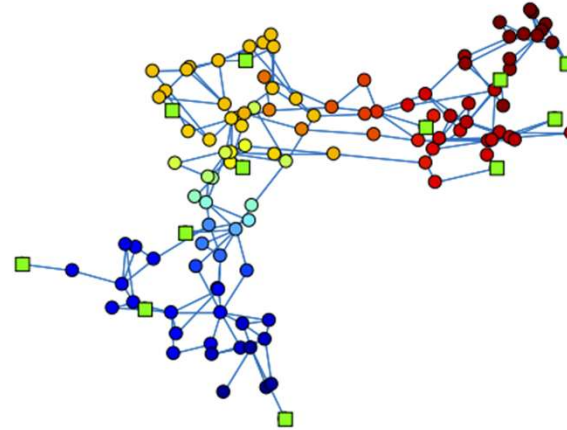
- **D-optimal design:** Minimizes the log-determinant of the interpolation error covariance to achieve maximum overall confidence in parameter estimation
- **A-optimal design:** Minimizes the mean squared error across all estimated coefficients to give the best average estimation accuracy
- **E-optimal design:** Minimize the maximum (worst-case) variance in any direction, ensuring robust reconstruction under the least favorable scenario

Algorithm 1 : Greedy selection of graph samples

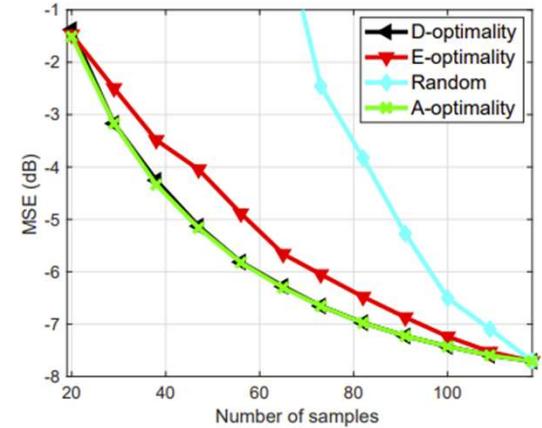
Input Data : $\mathbf{U}_{\mathcal{F}}$, M ;

Output Data : \mathcal{S} , the sampling set.

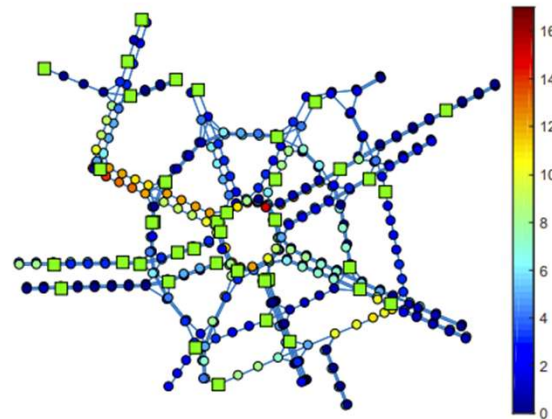
Function : initialize $\mathcal{S} \equiv \emptyset$
 while $|\mathcal{S}| < M$
 $s = \arg \max_j f(\mathcal{S} \cup \{j\})$;
 $\mathcal{S} \leftarrow \mathcal{S} \cup \{s\}$;
 end



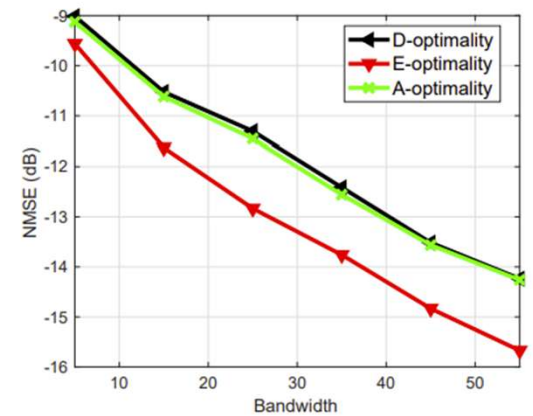
(a) Graph topology and sampling set



(b) MSE versus number of samples



(a) Graph topology and sampling set



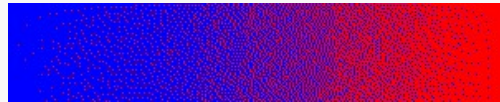
(b) NMSE versus bandwidth

Figures: Sampling and Recovery of Graph Signals, Lorenzo et al.

Dithering and Blue noise



dithering approximates higher colour depth



- Human perception prefers **even but non-uniform** sample distributions
- Blue noise = no low-frequency components → avoids clustering, redundancy

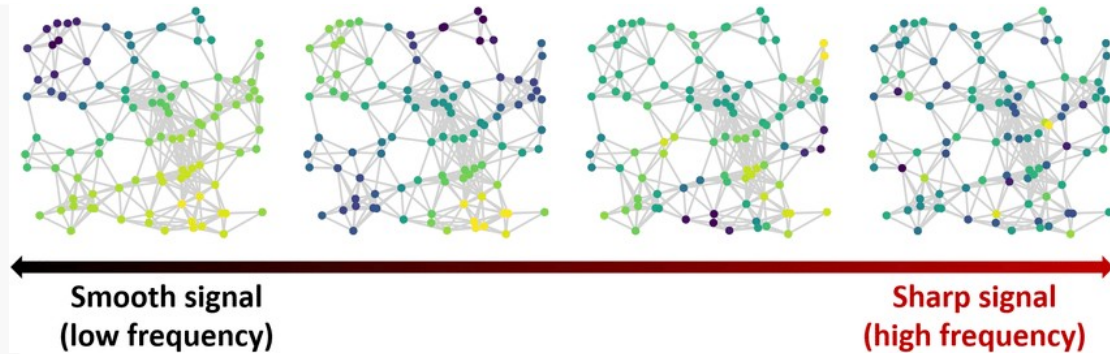


Figure: <https://www.researchgate.net/publication/355901199/figure/fig1/AS:1086260500275200@1635996093701>
graph-signal-becomes-sharper-going-from-left-to-right-Smooth-graph-signals-assign.ppm

Blue noise sampling

- Blue noise sampling patterns have energy concentrated in high frequencies
- Select nodes so that the frequency spectrum of the sampling pattern avoids low frequencies, preserving signal diversity and reducing aliasing

Blue noise sampling spreads samples to avoid low-frequency redundancy and clustering

Energy Penalization Method

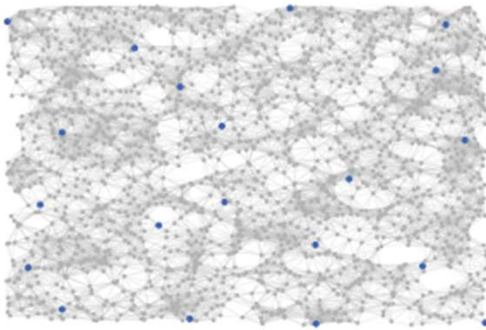
Blue-noise sampling can be framed as minimizing overlap with low-frequency eigenspaces:

$$\min_{s \in \{0,1\}^n} \|U_{low}^\top s\|^2$$

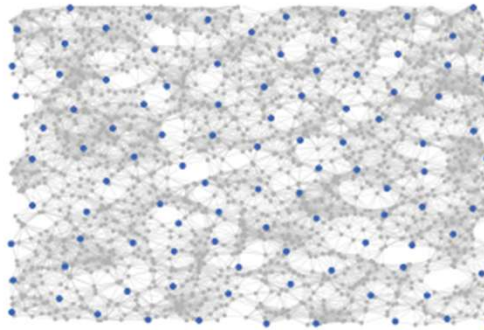
Spectral Spreading Principle

- Maximize energy outside the low-frequency subspace by choosing sampling sets that "look like noise" in the spectral domain
- Ensure samples are well-distributed across the graph topology

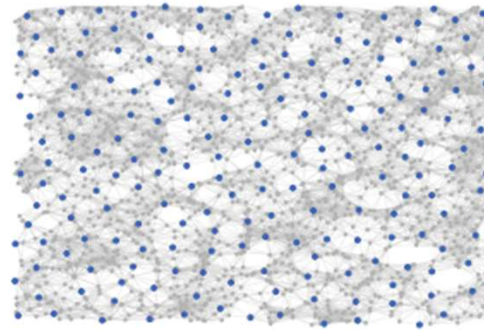
$d = 0.01$



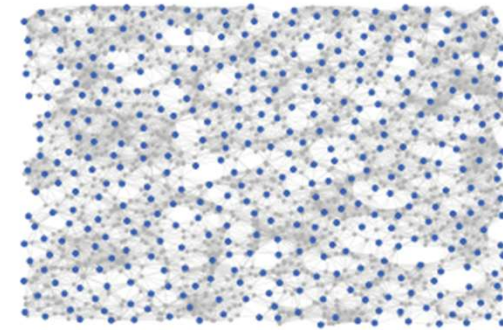
$d = 0.05$



$d = 0.1$



$d = 0.2$



Figures: Blue-Noise Sampling on Graphs, Parada-Mayorga et al.

Blue-noise sampling penalizes low-frequency concentration in sampling vector.

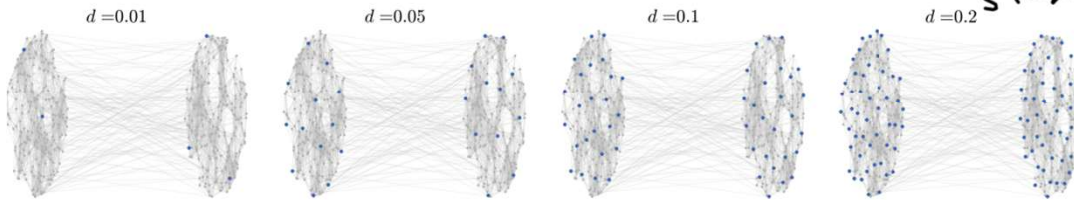
Algorithm

Idea: Sequential computation of distances between sampling points and relocation of points with short geodesic distance to put them far from each other.

Indiziert
ob Element
in Sampling set

Berechnet, wie
nah Sampling
punkte liegen

Wie nah Punkte
außerhalb
Sampling set
sind



Figures: Blue-Noise Sampling on Graphs, Parada-Mayorga et al.

Algorithm 1: Void and Cluster Algorithm for Graphs.

Input: m : number of samples, σ , NumIter.

Output: s : sampling pattern

Initialisation: $s = \mathbf{0}$, IndA = -1, IndB = -1.

Calculate $K(i, j) = e^{-\frac{r(i, j)^2}{\sigma}}$ for all $1 \leq i, j \leq N$.

2: $c = K \mathbf{1}_{N \times 1}$.

Get \mathcal{M} as m nodes selected at random.

4: $s(\mathcal{M}) = 1$.

for $r = 1 : 1 : \text{NumIter}$ **do**

6: $c(\text{supp}(s)) = \sum K(\text{supp}(s), \text{supp}(s))$.

8: $c(\text{supp}(s)^c) = \sum K(\text{supp}(s), \text{supp}(s)^c) - \tau$.

$s(\arg \max_i \{c(i)\}) = 0$.

$s(\arg \min_i \{c(i)\}) = 1$.

10: **if** IndA = $\arg \max_i \{c(i)\}$ and IndB = $\arg \min_i$

$\{c(i)\}$

then

break

12: **else**

IndA = $\arg \min_i \{c(i)\}$.

14: IndB = $\arg \max_i \{c(i)\}$.

end if

16: **end for**

return s

Sampling
point
Schlechter
Kandidat
für
Sampling
point

Algorithm is computationally more efficient than greedy sampling