view_frames Result Recorded at time: 1578489611.028 base Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1578489611.028 sec old) Most recent transform: 0.000 (1578489611.028 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec right_arm_base_link torso Broadcaster: /robot_state_publisher Average rate: 20.202 Hz Most recent transform: 1578489611.005 (0.023 sec old) Buffer length: 4.950 sec right_10 Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 20.202 Hz Average rate: 20.202 Hz Average rate: 10000.000 Hz Most recent transform: 1578489611.005 (0.023 sec old) Most recent transform: 1578489611.005 (0.023 sec old) Most recent transform: 0.000 (1578489611.028 sec old) Buffer length: 4.950 sec Buffer length: 0.000 sec Buffer length: 4.950 sec right_l1 right_torso_itb head Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 20.202 Hz Most recent transform: 0.000 (1578489611.028 sec old) Most recent transform: 0.000 (1578489611.028 sec old) Most recent transform: 0.000 (1578489611.028 sec old) Most recent transform: 1578489611.005 (0.023 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.950 sec right_11_2 right_12 head_camera screen Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 20.202 Hz Most recent transform: 1578489611.005 (0.023 sec old) Most recent transform: 0.000 (1578489611.028 sec old) Buffer length: 4.950 sec Buffer length: 0.000 sec right_13 right_12_2 Broadcaster: /robot_state_publisher Average rate: 20.202 Hz Most recent transform: 1578489611.005 (0.023 sec old) Buffer length: 4.950 sec right_l4 Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 20.202 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1578489611.028 sec old) Most recent transform: 1578489611.005 (0.023 sec old) Most recent transform: 0.000 (1578489611.028 sec old) Buffer length: 4.950 sec Buffer length: 0.000 sec Buffer length: 0.000 sec right_l4_2 right_arm_itb right_15 Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 20.202 Hz Average rate: 10000.000 Hz Most recent transform: 1578489611.005 (0.023 sec old) Most recent transform: 0.000 (1578489611.028 sec old) Most recent transform: 0.000 (1578489611.028 sec old) Buffer length: 0.000 sec Buffer length: 4.950 sec Buffer length: 0.000 sec right_l6 right_hand_camera right_wrist Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1578489611.028 sec old) Buffer length: 0.000 sec right_hand Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1578489611.028 sec old) Buffer length: 0.000 sec right_gripper_base Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1578489611.028 sec old) Most recent transform: 0.000 (1578489611.028 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec right_connector_plate_base right_gripper_tip Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1578489611.028 sec old) Buffer length: 0.000 sec right_connector_plate_mount Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1578489611.028 sec old) Buffer length: 0.000 sec right_electric_gripper_base Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 20.202 Hz Average rate: 20.202 Hz Most recent transform: 1578489611.005 (0.023 sec old) Most recent transform: 1578489611.005 (0.023 sec old) Buffer length: 4.950 sec Buffer length: 4.950 sec right_gripper_l_finger right_gripper_r_finger Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1578489611.028 sec old) Most recent transform: 0.000 (1578489611.028 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec right_gripper_l_finger_tip right_gripper_r_finger_tip