

Tuto_2.5_Parameter_estimation_for_compact_object_mergers

November 21, 2020

1 Gravitational Wave Open Data Workshop #3

Tutorial 2.5: Parameter estimation for compact object mergers – Using and interpreting posterior samples This is a simple demonstration to loading and viewing data released in association with the publication titled **GWTC-1: A Gravitational-Wave Transient Catalog of Compact Binary Mergers Observed by LIGO and Virgo during the First and Second Observing Runs** available through [DCC](#) and [arXiv](#). This should lead to discussion and interpretation.

The data used in these tutorials will be downloaded from the public DCC page [LIGO-P1800370](#).

[Click this link to view this tutorial in Google Colaboratory](#)

1.1 Installation (execute only if running on a cloud platform!)

```
[1]: # -- Use the following line for google colab
     #! pip install -q 'corner==2.0.1'
```

Important: With Google Colab, you may need to restart the runtime after running the cell above.

1.2 Initialization

```
[2]: from __future__ import division, print_function
     import numpy as np
     import matplotlib.pyplot as plt
     import h5py
     import pandas as pd
     import corner
```

1.3 Get the data

Selecting the event, let's pick GW150914.

```
[3]: label = 'GW150914'
```

```
# if you do not have wget installed, simply download manually
# https://dcc.ligo.org/LIGO-P1800370/public/GW150914_GWTC-1.hdf5
# from your browser
! wget https://dcc.ligo.org/LIGO-P1800370/public/{label}_GWTC-1.hdf5
```

```
--2020-11-21 19:28:28--
https://dcc.ligo.org/LIGO-P1800370/public/GW150914_GWTC-1.hdf5
Resolving dcc.ligo.org (dcc.ligo.org)... 131.215.125.144
Connecting to dcc.ligo.org (dcc.ligo.org)|131.215.125.144|:443... connected.
HTTP request sent, awaiting response... 302 Found
Location: https://dcc.ligo.org/public/0157/P1800370/005/GW150914_GWTC-1.hdf5
[following]
--2020-11-21 19:28:30--
https://dcc.ligo.org/public/0157/P1800370/005/GW150914_GWTC-1.hdf5
Reusing existing connection to dcc.ligo.org:443.
HTTP request sent, awaiting response... 200 OK
Length: 7026464 (6.7M)
Saving to: 'GW150914_GWTC-1.hdf5'

GW150914_GWTC-1.hdf 100%[=====>] 6.70M 2.60MB/s in 2.6s

2020-11-21 19:28:32 (2.60 MB/s) - 'GW150914_GWTC-1.hdf5' saved [7026464/7026464]
```

```
[4]: posterior_file = './'+label+'_GWTC-1.hdf5'
posterior = h5py.File(posterior_file, 'r')
```

1.3.1 Looking into the file structure

```
[5]: print('This file contains four datasets: ',posterior.keys())
```

This file contains four datasets: <KeysViewHDF5 ['IMRPhenomPv2_posterior', 'Overall_posterior', 'SEOBNRv3_posterior', 'prior']>

This data file contains several datasets, two using separate models for the gravitational waveform (IMRPhenomPv2 and SEOBNRv3 respectively, see the [paper](#) for more details).

It also contains a joint dataset, combining equal numbers of samples from each individual model, these datasets are what is shown in the [paper](#).

Finally, there is a dataset containing samples drawn from the prior used for the analyses.

```
[6]: print(posterior['Overall_posterior'].dtype.names)
```

```
('costheta_jn', 'luminosity_distance_Mpc', 'right_ascension', 'declination',
'm1_detector_frame_Msun', 'm2_detector_frame_Msun', 'spin1', 'spin2',
'costilt1', 'costilt2')
```

Here are some brief descriptions of these parameters and their uses:

- `luminosity_distance_Mpc`: luminosity distance [Mpc]
- `m1_detector_frame_Msun`: primary (larger) black hole mass (detector frame) [solar mass]
- `m2_detector_frame_Msun`: secondary (smaller) black hole mass (detector frame) [solar mass]
- `right_ascension, declination`: right ascension and declination of the source [rad].
- `costheta_jn`: cosine of the angle between line of sight and total angular momentum vector of system.
- `spin1, costilt1`: primary (larger) black hole spin magnitude (dimensionless) and cosine of the zenith angle between the spin and the orbital angular momentum vector of system.
- `spin2, costilt2`: secondary (smaller) black hole spin magnitude (dimensionless) and cosine of the zenith angle between the spin and the orbital angular momentum vector of system.

A convenient (and pretty) way to load up this array of samples is to use [pandas](#):

```
[7]: samples=pd.DataFrame.from_records(np.array(posterior['Overall_posterior']))
```

```
[8]: samples
```

```
[8]:      costheta_jn  luminosity_distance_Mpc  right_ascension  declination  \
0      -0.976633          517.176717          1.456176      -1.257815
1      -0.700404          401.626864          2.658802      -0.874661
2      -0.840752          369.579071          1.106548      -1.136396
3      -0.583657          386.935268          2.077180      -1.246351
4      -0.928271          345.104345          0.993604      -1.069243
5      -0.861517          312.266527          0.884342      -0.875526
6      -0.993057          482.702041          1.254024      -1.220087
7      -0.951662          473.665172          1.419747      -1.271510
8      -0.896320          469.099680          2.236555      -1.234226
9      -0.963932          556.990637          1.700747      -1.262282
10     -0.820570          500.368921          2.276248      -1.202984
11     -0.674318          393.492394          2.341810      -1.190604
12     -0.650114          420.066518          2.509839      -1.105781
13     -0.933496          468.648499          1.637059      -1.261151
14     -0.906077          507.140697          1.434600      -1.239394
15     -0.884868          377.765909          1.158292      -1.171804
16     -0.767135          394.088489          1.830805      -1.287126
17     -0.963054          545.922299          1.163536      -1.148894
18     -0.956892          420.316660          1.192301      -1.186619
19     -0.903831          550.460213          2.082583      -1.262594
20     -0.911840          501.145664          2.086447      -1.261614
21     -0.946788          588.954034          2.416206      -1.192111
22     -0.977904          513.966913          1.831148      -1.262297
23     -0.935906          433.154879          1.479955      -1.253897
24     -0.905283          341.298103          0.998063      -1.072230
```

| | | | | |
|------|-----------|------------|----------|-----------|
| 25 | -0.988916 | 331.863993 | 0.896731 | -0.893949 |
| 26 | -0.734077 | 329.644247 | 2.422131 | -1.157909 |
| 27 | -0.968690 | 407.794381 | 1.430451 | -1.247261 |
| 28 | -0.901933 | 466.915429 | 1.635602 | -1.277849 |
| 29 | -0.911420 | 520.304212 | 1.898219 | -1.255650 |
| ... | ... | ... | ... | ... |
| 8320 | -0.963754 | 479.627679 | 1.421226 | -1.237403 |
| 8321 | -0.797818 | 291.640379 | 0.921329 | -1.037707 |
| 8322 | -0.903869 | 302.571288 | 0.894647 | -0.926900 |
| 8323 | -0.995566 | 535.871423 | 2.426527 | -1.161662 |
| 8324 | -0.128536 | 251.468407 | 1.351458 | -1.186373 |
| 8325 | -0.916900 | 481.455085 | 1.402443 | -1.226163 |
| 8326 | -0.750079 | 398.735004 | 1.256436 | -1.252159 |
| 8327 | -0.952350 | 362.100941 | 1.094760 | -1.108855 |
| 8328 | -0.863589 | 409.387362 | 1.266844 | -1.216554 |
| 8329 | -0.867119 | 584.992707 | 2.544252 | -1.071247 |
| 8330 | -0.916898 | 396.680219 | 1.293819 | -1.225568 |
| 8331 | -0.964043 | 556.990459 | 1.609491 | -1.258841 |
| 8332 | -0.936385 | 550.553176 | 2.260506 | -1.191693 |
| 8333 | -0.991132 | 589.459904 | 2.267003 | -1.215404 |
| 8334 | -0.980707 | 515.160072 | 1.755466 | -1.274265 |
| 8335 | -0.951436 | 406.233345 | 1.080483 | -1.137830 |
| 8336 | -0.543811 | 382.763475 | 2.350371 | -1.165626 |
| 8337 | -0.314194 | 273.768244 | 1.907840 | -1.238437 |
| 8338 | -0.792538 | 484.979160 | 2.563289 | -1.019216 |
| 8339 | -0.868087 | 339.484613 | 0.955686 | -1.021462 |
| 8340 | -0.924296 | 495.492685 | 1.701333 | -1.279951 |
| 8341 | -0.781792 | 440.172496 | 1.538598 | -1.270290 |
| 8342 | -0.890317 | 569.832475 | 2.387177 | -1.112518 |
| 8343 | -0.906677 | 497.608021 | 1.878699 | -1.267034 |
| 8344 | -0.975888 | 513.885473 | 2.012550 | -1.287542 |
| 8345 | -0.691637 | 306.985025 | 1.485646 | -1.269228 |
| 8346 | -0.834615 | 462.649414 | 2.065362 | -1.265618 |
| 8347 | -0.911463 | 448.930876 | 1.536913 | -1.257956 |
| 8348 | -0.856914 | 561.020036 | 2.367289 | -1.211824 |
| 8349 | -0.919556 | 519.641782 | 1.916675 | -1.250801 |

| | m1_detector_frame_Msun | m2_detector_frame_Msun | spin1 | spin2 | \ |
|---|------------------------|------------------------|----------|----------|---|
| 0 | 39.037380 | 37.044563 | 0.417147 | 0.867740 | |
| 1 | 34.620096 | 34.184416 | 0.125709 | 0.260679 | |
| 2 | 37.894343 | 33.970520 | 0.581047 | 0.926893 | |
| 3 | 36.412973 | 35.684463 | 0.235808 | 0.094391 | |
| 4 | 39.477251 | 31.645008 | 0.511521 | 0.868009 | |
| 5 | 40.053864 | 31.991598 | 0.270972 | 0.248762 | |
| 6 | 41.302817 | 32.510163 | 0.296694 | 0.073529 | |
| 7 | 38.622335 | 36.758122 | 0.568455 | 0.548404 | |
| 8 | 41.520437 | 28.397390 | 0.538265 | 0.712628 | |

| | | | | |
|------|-----------|-----------|----------|----------|
| 9 | 38.005237 | 36.227526 | 0.422409 | 0.185092 |
| 10 | 37.122250 | 36.083515 | 0.257545 | 0.332633 |
| 11 | 38.459260 | 31.799995 | 0.022493 | 0.364121 |
| 12 | 44.076230 | 29.201757 | 0.070059 | 0.241866 |
| 13 | 38.645475 | 32.398512 | 0.005890 | 0.119546 |
| 14 | 37.874577 | 36.509048 | 0.494393 | 0.636374 |
| 15 | 36.357493 | 33.687949 | 0.488504 | 0.254615 |
| 16 | 35.965565 | 34.205400 | 0.078071 | 0.234350 |
| 17 | 38.542505 | 35.798820 | 0.288123 | 0.559945 |
| 18 | 42.288312 | 33.486999 | 0.814305 | 0.373396 |
| 19 | 36.773857 | 36.210384 | 0.539052 | 0.563486 |
| 20 | 36.842878 | 35.179096 | 0.759660 | 0.827230 |
| 21 | 39.068531 | 36.506772 | 0.206433 | 0.108762 |
| 22 | 40.953668 | 33.062135 | 0.377102 | 0.178347 |
| 23 | 39.059075 | 34.346471 | 0.038759 | 0.469905 |
| 24 | 36.178895 | 33.058884 | 0.269331 | 0.046139 |
| 25 | 40.408669 | 30.338095 | 0.274004 | 0.457297 |
| 26 | 37.791702 | 35.097534 | 0.099933 | 0.120829 |
| 27 | 44.392623 | 27.101020 | 0.248231 | 0.152856 |
| 28 | 40.804260 | 34.357069 | 0.481804 | 0.262667 |
| 29 | 38.468793 | 38.112555 | 0.780451 | 0.456891 |
| ... | ... | ... | ... | ... |
| 8320 | 37.418872 | 33.040471 | 0.213178 | 0.106581 |
| 8321 | 37.963982 | 36.136089 | 0.529649 | 0.409030 |
| 8322 | 39.094267 | 33.338767 | 0.559142 | 0.418611 |
| 8323 | 42.714378 | 30.441516 | 0.922040 | 0.989441 |
| 8324 | 36.806506 | 36.472964 | 0.928667 | 0.316016 |
| 8325 | 37.287401 | 36.838470 | 0.511637 | 0.173961 |
| 8326 | 41.601842 | 33.599982 | 0.018344 | 0.171433 |
| 8327 | 41.690405 | 30.406117 | 0.424441 | 0.358483 |
| 8328 | 37.583397 | 33.914142 | 0.229000 | 0.254653 |
| 8329 | 39.350488 | 33.336474 | 0.014724 | 0.014333 |
| 8330 | 36.265841 | 33.210403 | 0.491009 | 0.051018 |
| 8331 | 40.152133 | 33.299200 | 0.276635 | 0.282308 |
| 8332 | 40.094982 | 32.925201 | 0.361812 | 0.664824 |
| 8333 | 36.951265 | 36.662160 | 0.980342 | 0.814305 |
| 8334 | 38.136783 | 35.955693 | 0.184186 | 0.310562 |
| 8335 | 36.627502 | 36.258330 | 0.234235 | 0.082137 |
| 8336 | 38.205089 | 33.141560 | 0.173946 | 0.427770 |
| 8337 | 38.056001 | 33.102631 | 0.393329 | 0.455752 |
| 8338 | 36.365292 | 34.805373 | 0.234390 | 0.112930 |
| 8339 | 38.351915 | 33.147393 | 0.263137 | 0.024049 |
| 8340 | 43.020937 | 28.566935 | 0.023839 | 0.301614 |
| 8341 | 38.802564 | 34.771638 | 0.187242 | 0.128243 |
| 8342 | 39.873922 | 35.808303 | 0.556795 | 0.564091 |
| 8343 | 38.359023 | 35.279562 | 0.449313 | 0.311660 |
| 8344 | 41.548878 | 28.998181 | 0.280597 | 0.954617 |

| | | | | |
|------|-----------|-----------|----------|----------|
| 8345 | 37.561962 | 33.355792 | 0.484003 | 0.627191 |
| 8346 | 37.824298 | 36.674075 | 0.589654 | 0.650758 |
| 8347 | 38.063291 | 35.757913 | 0.708407 | 0.714805 |
| 8348 | 44.884396 | 31.592433 | 0.389284 | 0.521304 |
| 8349 | 37.275183 | 35.445032 | 0.391824 | 0.516908 |

| | costilt1 | costilt2 |
|------|-----------|-----------|
| 0 | -0.280624 | 0.403853 |
| 1 | -0.757349 | -0.312285 |
| 2 | 0.649781 | -0.510843 |
| 3 | 0.116578 | -0.720505 |
| 4 | -0.438237 | 0.269333 |
| 5 | -0.349028 | 0.545518 |
| 6 | 0.137425 | -0.083697 |
| 7 | -0.594185 | 0.877344 |
| 8 | -0.045699 | -0.426311 |
| 9 | 0.681972 | -0.847753 |
| 10 | -0.951930 | 0.814314 |
| 11 | -0.049694 | -0.468250 |
| 12 | 0.990392 | -0.460822 |
| 13 | -0.022517 | -0.642337 |
| 14 | 0.590248 | -0.352235 |
| 15 | -0.534439 | 0.618918 |
| 16 | -0.617526 | -0.395582 |
| 17 | 0.267301 | 0.041915 |
| 18 | 0.438368 | -0.855349 |
| 19 | 0.174670 | -0.012382 |
| 20 | -0.579448 | 0.395875 |
| 21 | 0.534922 | 0.544726 |
| 22 | 0.128910 | 0.550940 |
| 23 | -0.219874 | 0.053649 |
| 24 | -0.606615 | 0.512709 |
| 25 | -0.881741 | 0.277930 |
| 26 | 0.336268 | 0.149600 |
| 27 | -0.254594 | 0.346958 |
| 28 | 0.542702 | -0.567035 |
| 29 | -0.255877 | 0.806603 |
| ... | ... | ... |
| 8320 | -0.206470 | -0.841896 |
| 8321 | 0.749740 | -0.718774 |
| 8322 | 0.258864 | -0.649596 |
| 8323 | 0.569637 | -0.896173 |
| 8324 | 0.129004 | -0.504672 |
| 8325 | 0.531790 | -0.986684 |
| 8326 | 0.176509 | 0.850630 |
| 8327 | -0.089335 | 0.007443 |
| 8328 | 0.470166 | -0.730604 |

```

8329 -0.203959 -0.831735
8330 -0.411079  0.952778
8331  0.397194 -0.102864
8332 -0.296723  0.156690
8333  0.018503 -0.030134
8334  0.187724  0.264574
8335 -0.081511  0.262844
8336  0.969616 -0.554059
8337  0.492497 -0.758070
8338 -0.007013 -0.919706
8339 -0.410763  0.038883
8340  0.235901 -0.382719
8341 -0.124488  0.932231
8342  0.821992 -0.662277
8343 -0.029597  0.195098
8344  0.613993 -0.547786
8345  0.194507 -0.408345
8346 -0.737792  0.875384
8347  0.852085 -0.797475
8348 -0.251461  0.830526
8349 -0.705305  0.600727

```

[8350 rows x 10 columns]

Those are all the samples stored in the Overall dataset.

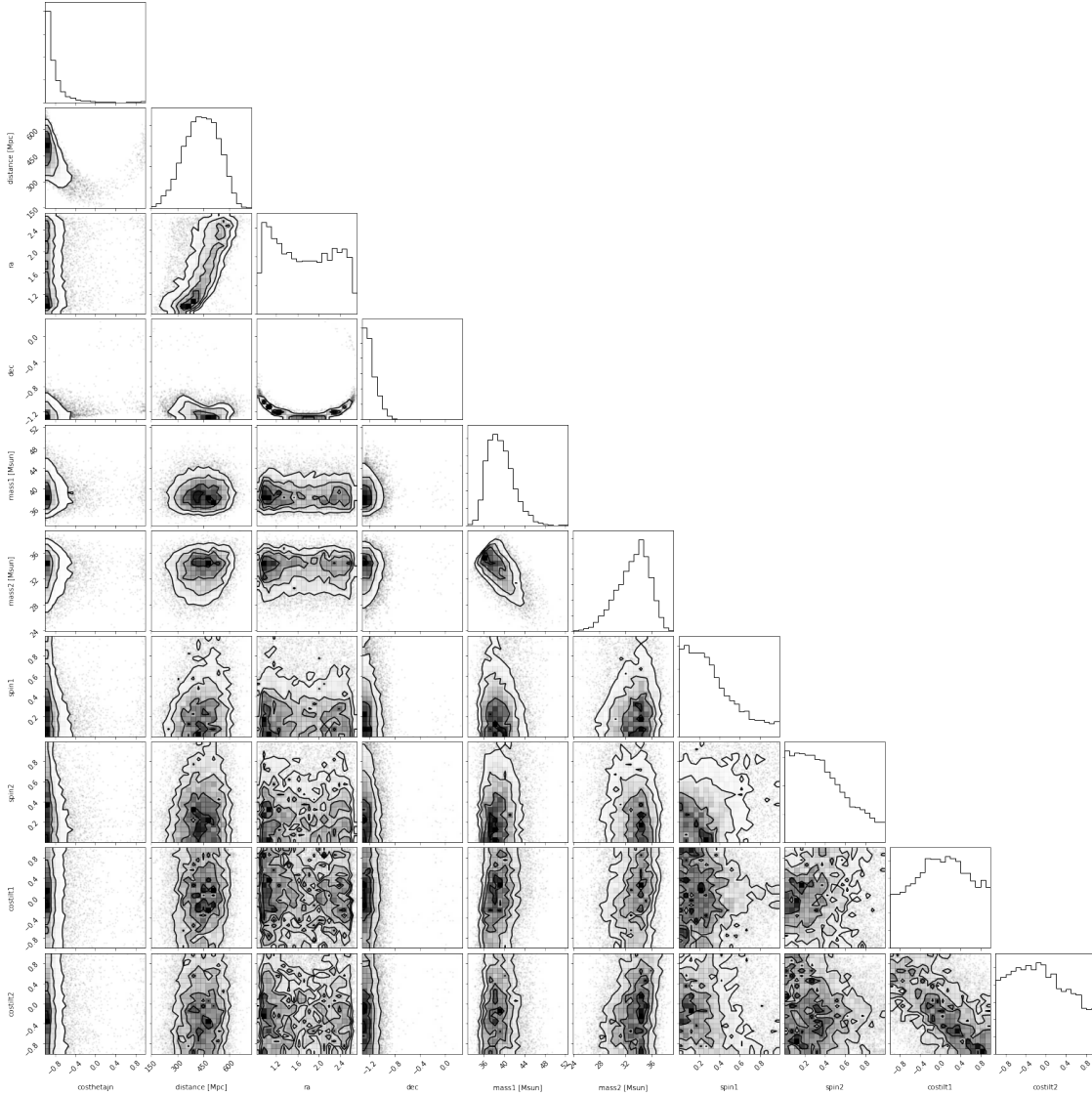
1.3.2 Plotting

We can plot all of them with, for instance, the [corner](#) package:

```

[9]: corner.corner(samples, labels=['costhetajn',
                                   'distance [Mpc]',
                                   'ra',
                                   'dec',
                                   'mass1 [Msun]',
                                   'mass2 [Msun]',
                                   'spin1',
                                   'spin2',
                                   'costilt1',
                                   'costilt2']);

```

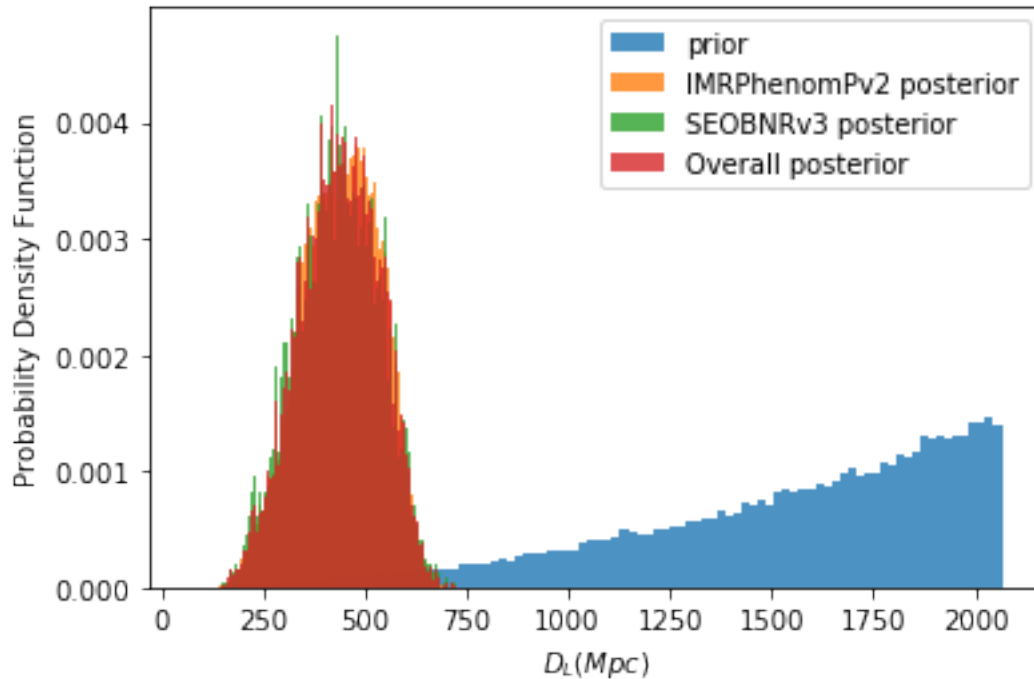


Each one and two dimensional histogram are *marginalised* probabilby density functions. We can manually select one parameter, say luminosity distance, and plot the four different marginalised distributions:

```
[10]: plt.hist(posterior['prior']['luminosity_distance_Mpc'], bins = 100,
→label='prior', alpha=0.8, density=True)
plt.hist(posterior['IMRPhenomPv2_posterior']['luminosity_distance_Mpc'], bins =
→100, label='IMRPhenomPv2 posterior', alpha=0.8, density=True)
plt.hist(posterior['SEOBNRv3_posterior']['luminosity_distance_Mpc'], bins = 100,
→label='SEOBNRv3 posterior', alpha=0.8, density=True)
plt.hist(posterior['Overall_posterior']['luminosity_distance_Mpc'], bins = 100,
→label='Overall posterior', alpha=0.8, density=True)
plt.xlabel(r'$D_L$ (Mpc)$')
```



```
plt.ylabel('Probability Density Function')
plt.legend()
plt.show()
```



1.3.3 Computing new quantities

The masses given are the ones seen by the detector, in the “detector frame”. To get the masses of the source black holes, we need to correct for the gravitational-wave redshifting. This forces us to assume a cosmology:

```
[11]: import astropy.units as u
      from astropy.cosmology import Planck15, z_at_value
```

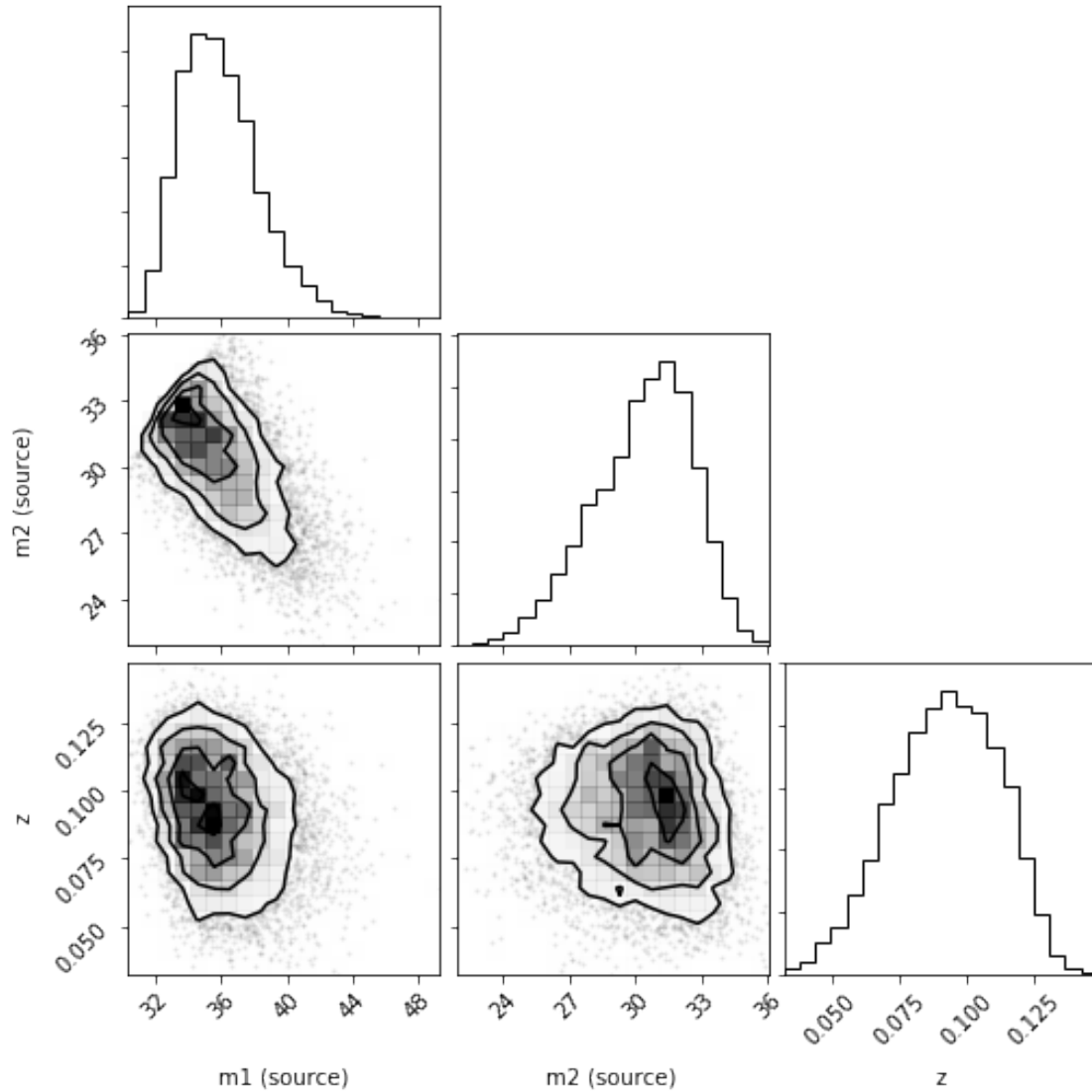
We now compute the redshift value for all the samples (using only their distance value). See [astropy.cosmology](#) for implementation details, in particular how to make the following more efficient:

```
[12]: z = np.array([z_at_value(Planck15.luminosity_distance, dist * u.Mpc) for dist in
    → samples['luminosity_distance_Mpc']])
```

```
[13]: samples['m1_source_frame_Msun']=samples['m1_detector_frame_Msun']/(1.0+z)
      samples['m2_source_frame_Msun']=samples['m2_detector_frame_Msun']/(1.0+z)
      samples['redshift']=z
```

And we can plot the marginalised probability density functions:

```
[14]: corner.  
      ↪corner(samples[['m1_source_frame_Msun','m2_source_frame_Msun','redshift']],labels=['m1_↪  
      ↪(source)',  
      ↪  
      ↪      'm2 (source)',  
      ↪  
      ↪      'z']]);
```



1.4 Calculating credible intervals

Let's see how we can use bilby to calculate summary statistics for the posterior like the median and 90% credible level.

```
[15]: import bilby
# calculate the detector frame chirp mass
mchirp = ((samples['m1_detector_frame_Msun'] *
→samples['m2_detector_frame_Msun'])**(3./5))/\
        (samples['m1_detector_frame_Msun'] +
→samples['m2_detector_frame_Msun'])**(1./5)
# initialize a SampleSummary object to describe the chirp mass posterior samples
chirp_mass_samples_summary = bilby.core.utils.SamplesSummary(samples=mchirp,
→average='median')
print('The median chirp mass = {} Msun'.format(chirp_mass_samples_summary.
→median))
print('The 90% confidence interval for the chirp mass is {} - {} Msun'.
→format(chirp_mass_samples_summary.lower_absolute_credible_interval,
→chirp_mass_samples_summary.upper_absolute_credible_interval))
```

The median chirp mass = 31.23055308109465 Msun

The 90% confidence interval for the chirp mass is 29.655877108464615 -
32.97324559242388 Msun

1.5 Challenge question

Calculate the posterior for the effective spin, which is the mass-weighted component of the binary spin aligned to the orbital angular momentum. It is given by Eqn. 3 of <https://journals.aps.org/prx/pdf/10.1103/PhysRevX.9.011001>. The z-component of each component spin is defined as $\chi_{1z} = \chi_1 \cos \theta_1$. Then initialize a `SamplesSummary` object for the `chi_eff` posterior and calculate the mean and the lower and upper absolute credible interval.

$$1.5.1 \quad \chi_{eff} = \frac{m_1 \chi_{1z} + m_2 \chi_{2z}}{m_1 + m_2}$$

$$\chi_{eff} = \frac{m_1 \chi_1 \cos \theta_1 + m_2 \chi_2 \cos \theta_2}{m_1 + m_2}$$

```
[26]: X_det = ((samples['m1_detector_frame_Msun'] * samples['spin1'] *
→samples['costilt1']) + (samples['m2_detector_frame_Msun'] * samples['spin2'] *
→samples['costilt2']))/(samples['m1_detector_frame_Msun'] +
→samples['m2_detector_frame_Msun'])
```

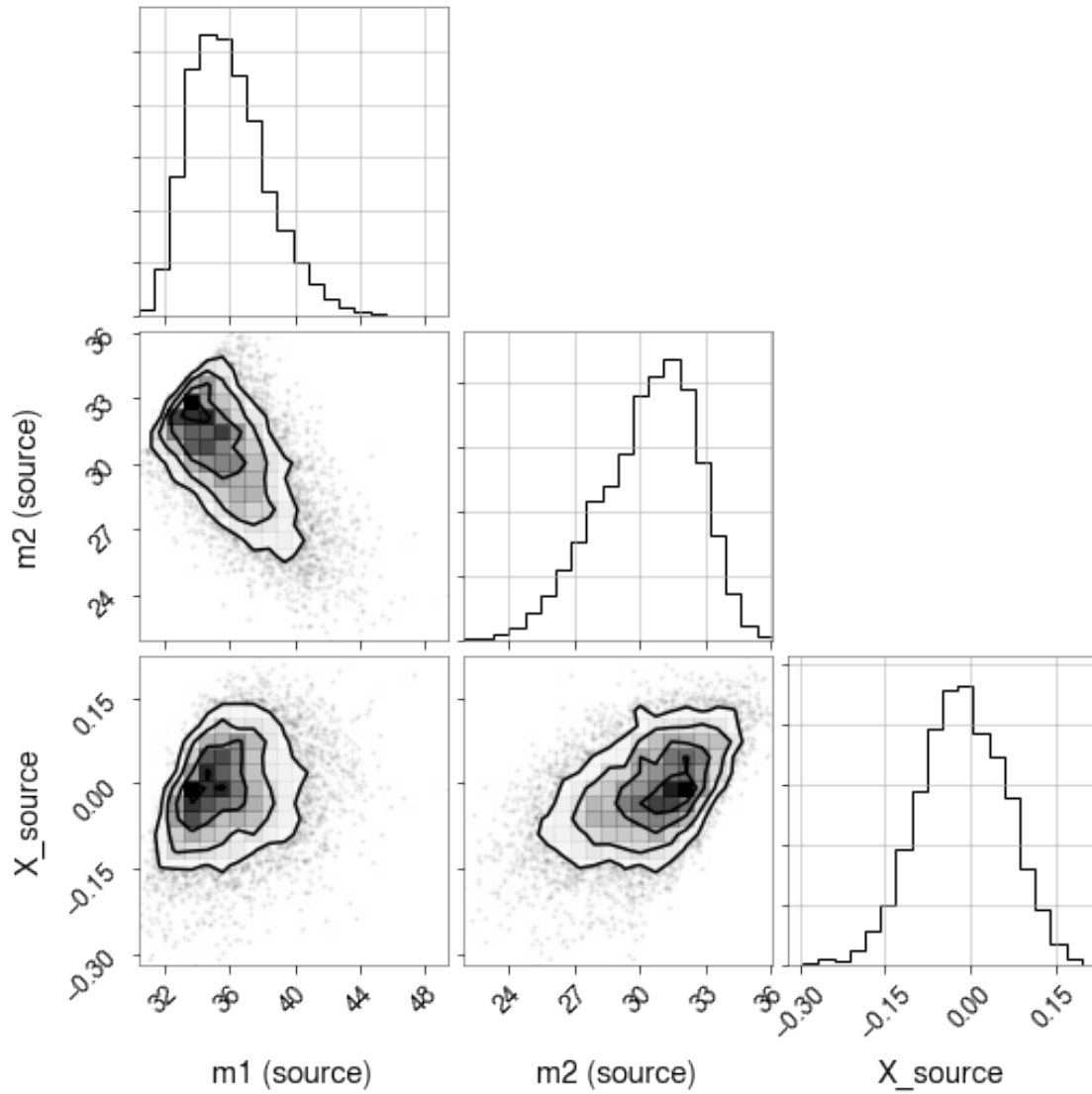
```
[28]:
```

```
X_source = ((samples['m1_source_frame_Msun'] * samples['spin1'] *
→samples['costilt1']) + (samples['m2_source_frame_Msun'] * samples['spin2'] *
→samples['costilt2']))/(samples['m1_source_frame_Msun'] +
→samples['m2_source_frame_Msun'])
```

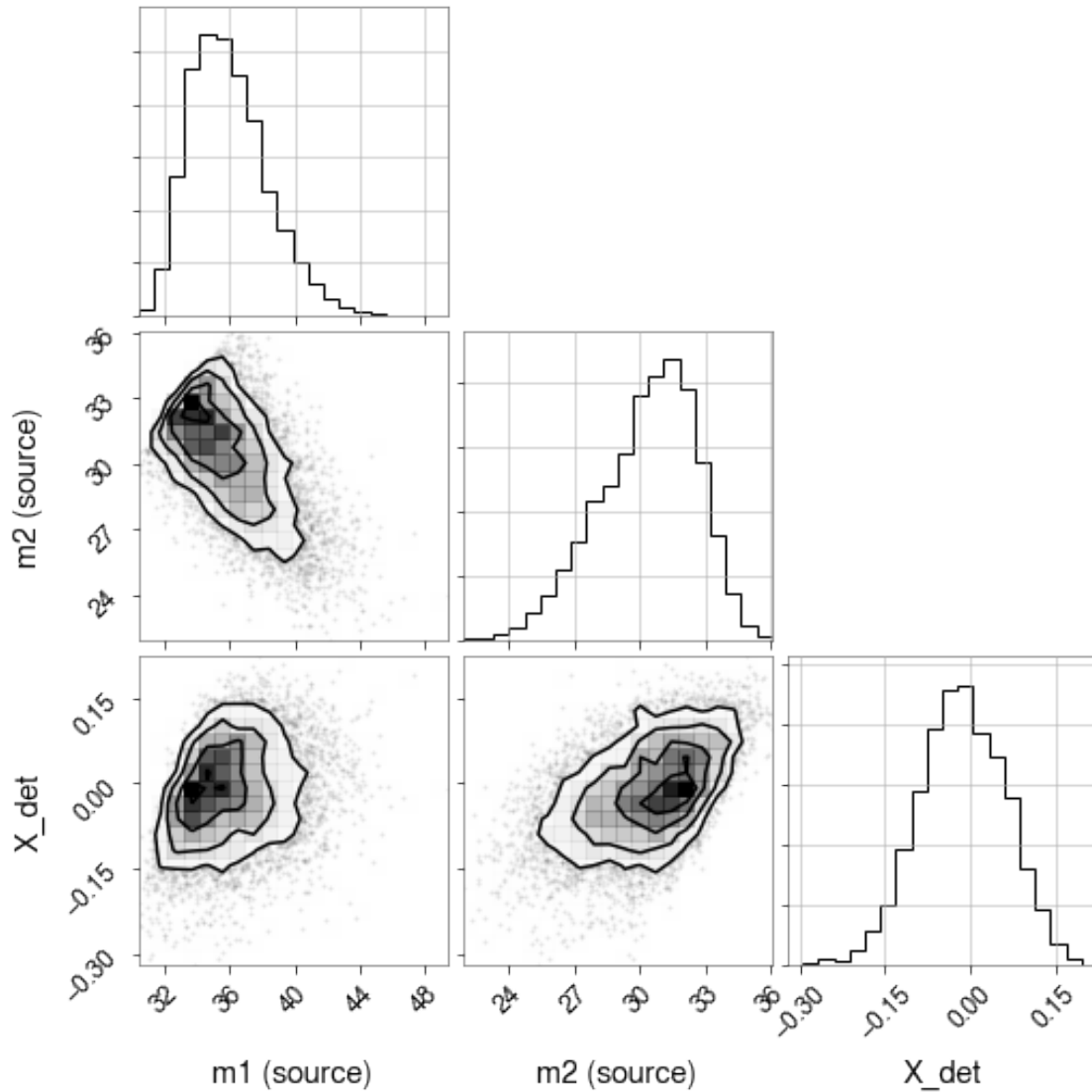
```
[31]: samples['chi_eff_det']=X_det
```

```
[32]: samples['chi_eff_source']=X_source
```

```
[33]: corner.  
      ↪corner(samples[['m1_source_frame_Msun', 'm2_source_frame_Msun', 'chi_eff_source']], labels=['m1_u  
      ↪(source)',  
  
      ↪      'm2 (source)',  
  
      ↪      'X_source']]);
```



```
[34]: corner.  
      →corner(samples[['m1_source_frame_Msun','m2_source_frame_Msun','chi_eff_det']],labels=['m1_  
      →(source) ',  
  
      →      'm2 (source)',  
  
      →      'X_det']]);
```



```
[38]: chi_eff_det_samples_summary = bilby.core.utils.SamplesSummary(samples=X_det,
    ↳ average='median')
print('The median chi_eff_det = {}'.format(chi_eff_det_samples_summary.median))
print('The 90% confidence interval for the chi_eff_det is {} - {}'.format(
    ↳ chi_eff_det_samples_summary.lower_absolute_credible_interval,
    ↳ chi_eff_det_samples_summary.upper_absolute_credible_interval))
```

The median chi_eff_det = -0.014932627380503358

The 90% confidence interval for the chi_eff_det is -0.14138898362283844 - 0.10932272798368625

```
[39]: chi_eff_source_samples_summary = bilby.core.utils.  
      ↳SamplesSummary(samples=X_source, average='median')  
      print('The median chi_eff_source = {}'.format(chi_eff_source_samples_summary.  
      ↳median))  
      print('The 90% confidence interval for the chi_eff_source is {} - {}'.  
      ↳format(chi_eff_source_samples_summary.lower_absolute_credible_interval,  
      ↳chi_eff_source_samples_summary.upper_absolute_credible_interval))
```

The median chi_eff_source = -0.014932627380503357

The 90% confidence interval for the chi_eff_source is -0.14138898362283844 -
0.10932272798368625

```
[ ]:
```