

# Atharva Bhosale

## Indian Institute of Technology Tirupati

Undergraduate, **Mechanical Engineering**  
e-mail: atharva1936bh@gmail.com  
Mobile: +91 8080-670-192

LinkedIn: [linkedin.com/in/iathxvab](https://www.linkedin.com/in/iathxvab)

### Education

BTech, Mechanical Engineering: Indian Institute of Technology Tirupati	CGPA: 7.7/10	2024 - 2028
Class 12, HSC (MH) : Vidya Valley International School, Chinchwad	Aggregate: 86.33 %	2022 - 2024
Podar International School Chinchwad (CBSE)	Aggregate: 95.80%	2009 - 2022

### Experience

#### E-Yantra 2025 (Holo Battalion), IIT Bombay: [Aug. 2025 - Jan. 2026]

- Worked on image processing and numpy for pose estimation of bot using a overhead camera.
- Developed and tested **ROS2-based holonomic mobile robot** involving inverse kinematics and motion control.
- Designed and developed an entire bot body CAD Model and PCB design.

#### Core member at Techmaniacs (Tech Club) , Robotics Team: [July. 2024 - Jan. 2026]

- Hands-on experience with Ridgetel Labs TourtiseBot, implemented SLAM, writing custom teleoperation and hardware interface node using Python ROS2 (Humble).
- Hands-on experience with drone building, calibration of software, hardware, and wrote a program for geofencing a particular region in ArduPilot.
- Conducted workshops for students to teach them the basics required for robotics.

### Projects

#### Simple Mobile Robotic Arm (2D) [Github Link:](#) [Dec. 2024]

- Building a robotic arm simulation capable of linear motion and pick-and-place tasks using ROS2 (Humble).
- Implemented ROS2 publishers/subscribers for motion control and feedback in a custom simulation environment.
- Demonstrated basic automation and teleoperation using Python scripting and ROS2 topics.

#### Catch Nearest Turtle [Github Link:](#) [Dec. 2024]

- This ROS 2 package simulates a turtle in the turtlesim environment that automatically catches the nearest turtle.
- It uses ROS 2 nodes to detect the closest turtle and move toward it until it's caught.
- Parameters can be change in the yaml file which is present in my\_robot\_bringup/config/\*\*\*. and play around with it.

### Skills

Computer Skills:	C++, Python, Data Structures and Algorithms, HTML, MS Word, MS Excel, MS PowerPoint
Software Skills:	Robot Operating System, Fusion 360
Relevant Coursework:	Introduction to Programming (IIT TP), Introduction to Data Science and Machine Learning (IIT TP), Numerical Analysis(IIT TP), Mechatronics System Design (IIT TP)

### Positions of Responsibilities

**Team Captain E-Yantra 25:** Led a team of 3 students to participate in the E-Yantra Robotics Competition 2025. (Aug. 2025 - Jan. 2026)

**Core member Techmaniacs:** Conducted various workshops and events for the technical club of IITTirupati. (2024 - 2026)

### Achievements

1. **TechHeist (Tirutsava-25, IIT Tirupati):** 2<sup>nd</sup> Runner up

### Extracurriculars and Hobbies

- Hosted several events in college (Cultural Fests, Technical Workshops, Sports Events, etc).
- Love lawn tennis, solving puzzles, and personal finance.