Linearization of Balanced and Unbalanced Optimal Transport

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July 26, 2021

Overview

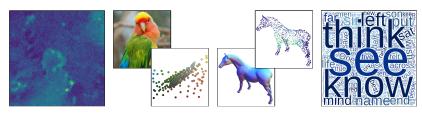
- 1. Introduction to optimal transport
- 2. Linearized optimal transport
- 3. Unbalanced transport and linearization
- 4. Conclusion and open questions

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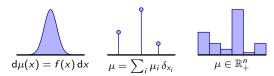
Metric measure spaces for data modelling

Comparing and understanding data



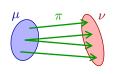
'Are two samples similar?'

Language: positive Radon measures $\mathcal{M}_+(X)$ on metric space (X,d)



■ similarity of samples \Leftrightarrow metric on $\mathcal{M}_+(X)$

Couplings and optimal transport







Couplings

- $\blacksquare \Pi(\mu, \nu) := \{ \pi \in \mathcal{M}_+(X \times X) : \mathsf{P}_{1\sharp}\pi = \mu, \, \mathsf{P}_{2\sharp}\pi = \nu \}$
- marginals: $P_{1\sharp}\pi(A) := \pi(A \times X), P_{2\sharp}\pi(B) := \pi(X \times B)$
- rearrangement of mass, generalization of map

Optimal transport [Kantorovich, 1942]

$$C(\mu, \nu) := \inf \left\{ \int_{X \times X} c(x, y) \, \mathrm{d}\pi(x, y) \bigg| \pi \in \Pi(\mu, \nu) \right\}$$

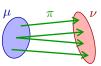
- **cost function** $c: X \times X \to \mathbb{R}$ for moving unit mass from x to y
- **convex problem**: linear program

Wasserstein distance on probability measures $\mathcal{P}(X)$

$$W_p(\mu, \nu) := (C(\mu, \nu))^{1/p} \text{ for } c(x, y) := d(x, y)^p, \quad p \in [1, \infty)$$

Wasserstein distances: basic properties

$$W_p(\mu,\nu) := \inf \left\{ \int_{X \times X} d(x,y)^p \, \mathrm{d}\pi(x,y) \middle| \pi \in \Pi(\mu,\nu) \right\}^{1/p}$$

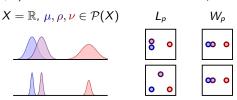


Properties

✓ **intuitive:** minimal π ⇒ optimal assignment **Thm:** $[X = \mathbb{R}^d, \, \mu \ll \text{Lebesgue}, \, c = d^p] \Rightarrow [\pi = (\text{id}, \, T)_{\sharp}\mu]$

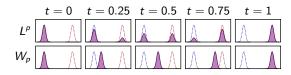
$$W_2(\mu, \nu) = \left(\int_X \|T(x) - x\|^2 d\mu(x)\right)^{1/2}$$

- √ metrizes weak* convergence
- \checkmark respects (X, d), **robust** to discretization errors, positional noise



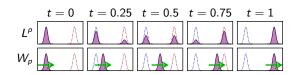
Wasserstein distances: displacement interpolation

- (X, d) length space $\Rightarrow (\mathcal{P}(X), W_p)$ is length space
- \bullet d(x,y) is **length of shortest continuous path** between x and y



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Dynamic formulation: Benamou–Brenier formula (on $X = \mathbb{R}^d$)

• (weak) **continuity equation**: mass ρ , velocity field v

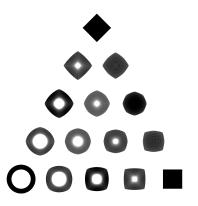
$$\mathcal{CE}(\mu, \nu) := \{ (\rho, \nu) : \partial_t \rho + \nabla(\nu \cdot \rho) = 0, \ \rho_0 = \mu, \ \rho_1 = \nu \}$$

■ least action principle: minimize Lagrangian / kinetic energy

$$W_2(\mu, \nu)^2 = \inf_{(\rho, \nu) \in \mathcal{CE}(\mu, \nu)} \int_{[0, 1] \times X} \|v_t\|^2 \, \mathrm{d}\rho_t \mathrm{d}t$$

Wasserstein distances: barycenter

[Agueh and Carlier, 2011]



W_2 barycenter: weighted center of mass

- \blacksquare measures $(\mu_i)_{i=1}^n$
- weights $(\lambda_i)_{i=1}^n$, $\lambda_i \geq 0$, $\sum_{i=1}^n \lambda_i = 1$
- **barycenter:** $\operatorname{argmin}_{\nu} \sum_{i=1}^{n} \lambda_{i} W_{2}^{2}(\nu, \mu_{i})$

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What now?

What we have

- √ OT induces meaningful, robust metric on samples
- X numerically more involved, √but good solvers exist
- √ can interpolate and average

But...

- X analyzing point clouds in non-linear metric space is tricky
 - √ approximate Euclidean embeddings
 - X interpretation not obvious
- X requires computation of all pairwise distances

Wasserstein-2: Local linearization

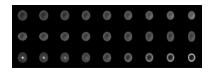
Recall Brenier Theorem

 $lacksquare [X=\mathbb{R}^d,\,\mu\ll ext{Lebesgue},\,c=d^2]\Rightarrow [\pi=(ext{id},\,T)_\sharp\mu]$

$$W_2(\mu, \nu) = \left(\int_X \|T(x) - x\|^2 d\mu(x)\right)^{1/2}$$

Idea [Wang et al., 2012]

- set of samples $\{\nu_i\}_{i=1}^N$, 'reference' measure μ
- represent ν_i by optimal T_i for $W_2(\mu, \nu_i)$, Lagrangian representation
- \checkmark approximate distance $\text{Lin }W_2(\nu_i,\nu_j) := ||T_i T_j||_{L^2(\mu,\mathbb{R}^d)}$
- $\{T_i\}_{i=1}^N$ lie in $L^2(\mu, \mathbb{R}^d) \Rightarrow$ vector space
- \checkmark only OT problems $W_2(\mu, \nu_i)$ need to be solved, not all $W_2(\nu_i, \nu_j)$
- ✓ simple post-processing, PCA, classifiers, . . .



Wasserstein-2: Local linearization, interpretation

Benamou–Brenier formula (for $X = \mathbb{R}^d$):

$$W_2(\mu, \mathbf{\nu})^2 = \inf_{(
ho, v) \in \mathcal{CE}(\mu, \mathbf{\nu})} \int_{[0,1] \times X} \left\| v_t \right\|^2 \mathrm{d}
ho_t \mathrm{d} t$$

• $(\mathcal{P}(X = \mathbb{R}^d), W_2)$ 'looks like' **Riemannian manifold** [Otto, 2001] where **tangent space** at ρ_t is $L^2(\rho_t, \mathbb{R}^d)$

Gradient flows via minimizing movements [Ambrosio et al., 2008]

- heat equation as gradient flow of entropy w.r.t. W_2 [Jordan et al., 1998] Logarithmic and exponential map
 - let $\pi = (id, T)_{\sharp} \mu$ optimal for $W_2^2(\mu, \nu)$

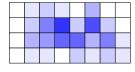
$$\mathsf{Log}_{\mu}(\nu) = v_0 = T - \mathsf{id}, \qquad \mathsf{Exp}_{\mu}(v_0) = (\mathsf{id} + v_0)_{\sharp} \mu$$

Interpretation of [Wang et al., 2012]

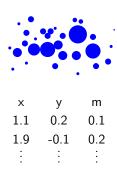
- lacksquare local approximation of manifold by tangent plane at μ
- simple analogy: sphere
- some insights:
 - μ needs to be chosen carefully, close to $\{\nu_i\}$ \Rightarrow diameter of samples should not be too high
 - approximation quality depends on curvature of manifold [Gigli, 2011; Mérigot et al., 2020; Delalande and Merigot, 2021]

Comparing Eulerian and Lagrangian representation

Eulerian



Lagrangian



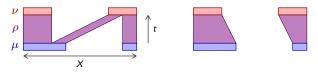
- better choice depends on problem / context
- Lagrangian representation order invariant
- but consistent order makes comparison easier
- LinOT provides canonical order, 'know which list items to compare'

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Hellinger-Kantorovich distance: motivation [Kondratyev et al., 2016;

Chizat et al., 2018c; Liero et al., 2018]



■ unbalanced continuity equation: mass ρ , velocity v, source α

$$\mathcal{CE}(\mu, \nu) := \{ (\rho, \nu, \alpha) : \partial_t \rho + \nabla(\nu \cdot \rho) = \alpha \cdot \rho, \ \rho_0 = \mu, \ \rho_1 = \nu \}$$

unbalanced Benamou-Brenier formula:

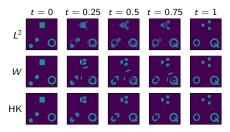
$$\mathsf{HK}(\mu,\nu)^2 := \inf_{(\rho,v,\alpha) \in \mathcal{CE}(\mu,\nu)} \int_{[0,1] \times X} \left[\|v_t\|^2 + \frac{1}{4} \frac{\alpha_t^2}{2} \right] \, \mathrm{d}\rho_t \mathrm{d}t$$

- other unbalanced models:
 - [Dolbeault et al., 2009]
 - [Piccoli and Rossi, 2016]: TV/L₁-type penalty (cf. [Caffarelli and McCann, 2010]: optimal partial transport)
 - [Maas et al., 2015, 2017]: L_2 and L_2 - L_1 -type penalty

Hellinger-Kantorovich distance: overview

$$\mathsf{HK}(\mu,\nu)^2 := \inf_{(\rho,v,\alpha) \in \mathcal{CE}(\mu,\nu)} \int_{[0,1] \times X} \left[\| \mathsf{v}_t \|^2 + \frac{\kappa}{4} \frac{\alpha_t^2}{4} \right] \, \mathrm{d}\rho_t \mathrm{d}t$$

- Thm: HK is geodesic distance on non-negative measures
 - geodesics well understood [Liero et al., 2018; Chizat et al., 2018a]
 - weak Riemannian structure [Kondratyev et al., 2016; Liero et al., 2016]
- transport up to $\frac{\kappa\pi}{2}$, pure Hellinger after that choose κ by physical intuition and cross-validation
- simple numerical approximation via entropic regularization and Sinkhorn-type algorithm [Chizat et al., 2018b]
- **barycenters** [Chung and Phung, 2020; Friesecke et al., 2021]

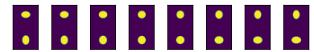


Hellinger-Kantorovich distance: local linearization

with Tianji Cai, Junyi Cheng, Matthew Thorpe [Cai et al., 2021]

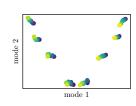
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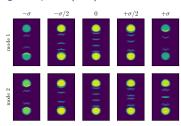
Samples: (varying ellipticities and radii)



$$\mathsf{Log}_{\mu}^{W_2}(\nu) = v_0 \qquad \qquad \mathsf{Log}_{\mu}^{\mathsf{HK}}(\nu) = (v_0, \alpha_0, \sqrt{\nu^{\perp}})$$

Principal component analysis in tangent space (W_2) :



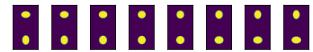


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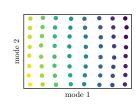
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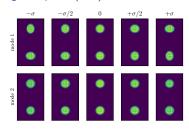
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Principal component analysis in tangent space (HK):



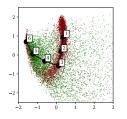


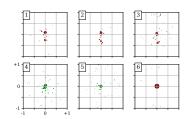
Hellinger–Kantorovich distance: local linearization, cont.

[Cai et al., 2021]

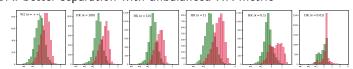
Example application: classification of particle jets

- mass represents energy absorbed in detector plane
- separate weak (red) vs strong (green) decay channels





■ LDA: better separation with unbalanced HK metric



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Conclusion

Optimal transport

- √ intuitive, robust, flexible metric for probability measures
- √ rich geometric structure (Riemannian flavour...)
- √ accessible by convex optimization

Local linearization of OT [Wang et al., 2012]

- √ Lagrangian representation: combine OT metric with linear structure
- √ intuitive interpretation of tangent vectors
- \checkmark useful representation for subsequent machine learning analysis

Unbalanced transport

- √ more robust to mass fluctuations
- √ carries over to linearization [Cai et al., 2021]
- \checkmark hyperparameter κ easy to tune
- √ formulas look scary, but numerics almost the same

Example code:

https://github.com/bernhard-schmitzer/UnbalancedLOT

Open questions

How well does the linear approximation work?

- tricky question! not my area of expertise, guess: can be arbitrarily bad without regularity assumptions on samples
- some preliminary related results for Wasserstein-2 case exist [Gigli, 2011; Mérigot et al., 2020; Delalande and Merigot, 2021], still open for HK

Riemannian structure of HK metric

- if we have the embedding of two samples, take their average and then apply the exponential map, do we get a valid data point?
- more mathematically: is [range of the logarithmic map] = [domain of the exponential map] convex?
- regularity of logarithmic map?

Beyond simple one-point-linearization

- 'local triangulation' of a sub-manifold?
- barycentric subspace analysis [Pennec, 2018; Bonneel et al., 2016]?

Statistical questions

- how robust is the analysis under sampling of the samples?
- what if samples are themselves only empirical measures?

Even better interpretation of tangent vectors

relevance for medical diagnosis

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