58 05 5050

$$* \|A\|_{+}^{2} = \sum_{i=1}^{d} \delta_{i}^{2}$$

$$a_{j} = \sum_{i=1}^{d} (a_{j} v_{i} | v_{i}^{T}) A = \sum_{i=1}^{d} (A v_{i}) v_{i}^{T}$$

$$fow$$

$$\|A\|_{F}^{2} = \sum_{j=1}^{n} |a_{j}|^{2} = \sum_{j=1}^{n} |a_{j} u_{j}|^{2} = \sum_{j=1}^{n} |X v_{j}|^{2} = \sum_{j=1}^{n} |S_{j}|^{2}$$

A_k =
$$\sum_{i=1}^{k} s_i u_i v_i^T ||A - A_k||_F^2 = \sum_{i=k+1}^{d} s_i^2$$

* || A - A | | \le || A - B || + The rows of A | are the projections of the rows of A onto the Vie.

Rank Nullity Thm:

$$||A - A_k|| \le ||A - B||$$

best fit V_k

$$A = \sum_{i=1}^{d} S_i u_i v_i^T \qquad A_k = \sum_{i=1}^{d} S_i u_i^* v_i^T$$

11 X - AL112 = 11 A - 13112

0+ Z € Ker(B) 1 span { Vi, ···, bk+1}

max by defi-

$$|Az|^2 = |\sum_{i=1}^{d} c_i u_i u_i^T z_i|^2 = \sum_{i=1}^{k+1} \delta_i^2 (u_i^T z_i)^2 > \delta_{k+1}^2 \sum_{i=1}^{k+1} |u_i^T z_i|^2$$

Let
$$\{v_1, \ldots, v_k, u_1, \ldots, u_k\} \xrightarrow{span} span (A_k, B)$$

 $p \leq 2k$

) extended variables

$$||A_{k}-B||_{F}^{2} = \sum_{i=1}^{k} |(A_{k}-B)u_{i}|^{2} + \sum_{i=k+1}^{p} |(A_{k}-B)u_{i}|^{2}$$

$$= \sum_{i=1}^{k} |(A_{k}-B)u_{i}|^{2} + \sum_{i=k+1}^{p} |Bu_{i}|^{2}$$

$$\leq k \|A - B\|_{2}^{2} + 2 \sum_{i=k+1}^{P} |Au_{i}|^{2} + 2 \sum_{i=k+1}^{T} |(B-A)u_{i}|^{2}$$

 $\leq k \|A - B\|_{2}^{2} + 2 k \sigma_{k+1}^{2} (x) + 2 k \|A - B\|_{2}^{2}$

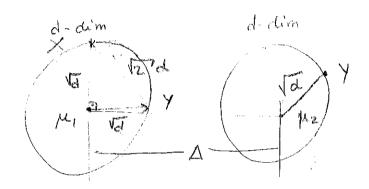
$$\leq k \|A-B\|_{2}^{2} + 2k \int_{k+1}^{2} (x) + 2k \|A-B\|_{2}^{2}$$

- Clustering is useful when the points are separable (in terms of wean, Joriana).
- When the distributions are overlapped the machine tearner will classify wrong.

We can cluster when the ments are for apart and variances do not overlop much.

$$\frac{f = \omega_1 + \frac{1}{1} + \frac{1}{1} + \frac{1}{1} + \frac{1}{1} + \frac{1}{1} = \frac{1}{1} + \frac{1}{1} + \frac{1}{1} = \frac{1}{1} + \frac{1}{1} = \frac{$$

What's the structure of dollar to make us use ML?



where will Y most likely be? Since the mass is localed in equator, it's likely to be on the civil which is orthogonal to X's direction.

$$X = (\sqrt{d} + O(1), O(1), O(1))$$

$$\gamma = (0(1), ..., \sqrt{d} + 0(1), 0(1))$$

$$|X-Y|^2 \approx 2d \pm O(\sqrt{d})$$

$$|X-Y|^2 \approx \Delta^2 + 2d \pm O(\sqrt{d})$$

$$|X-Y|^2 \approx \Delta^2 + 2d \pm O(\sqrt{d})$$

$$(*)$$

The max of LHS 5 the min of RHS of (*) $2A + O(TA) < \Delta^2 + 2A - O(TA)$ $2O(TA) < \Delta^2$ $\Delta D O(d^{3/4})$

Why not random proj? Not only the clata points will be randomly projected but also the distances will be randomly projected.