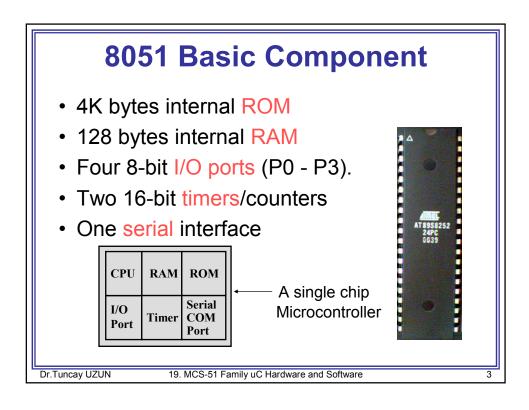
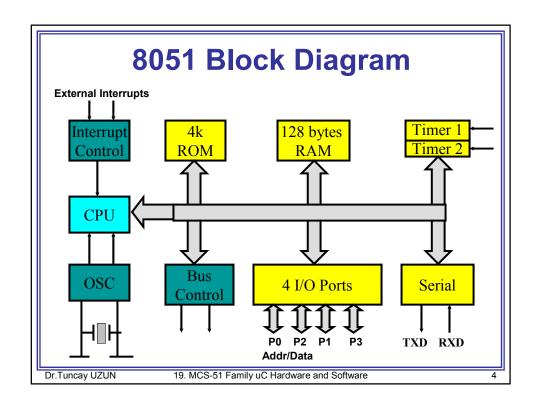
# **Microcontroller**

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# MCS-51 Family uC Hardware

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#### **Other 8051 Features**

- only 1 On chip oscillator (external crystal)
- 6 interrupt sources (2 external, 3 internal, Reset)
- 64K external code (program) memory (only read) PSEN
- 64K external data memory (can be read and write) by RD,WR
- Code memory is selectable by EA (internal or external)
- We may have External memory as data and code

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# **Embedded System**

ENVIRONMENT

MAIN SYSTEM

Embedded System

- · What is Embedded System?
  - An embedded system is closely integrated with the main system
  - It may not interact directly with the environment
  - For example A microcomputer in a car ignition control
  - ❖ An embedded product uses a microprocessor or microcontroller to do one task only
  - There is only one application software that is typically burned into ROM

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#### **Examples of Embedded Systems**

- Keyboard
- Printer
- video game player
- MP3 music players
- Embedded memories to keep configuration information
- Mobile phone units
- Domestic (home) appliances
- · Data switches
- Automotive controls

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# Three criteria in Choosing a Microcontroller

- meeting the computing needs of the task efficiently and cost effectively
  - speed, the amount of ROM and RAM, the number of I/O ports and timers, size, packaging, power consumption
  - easy to upgrade
  - cost per unit
- availability of software development tools
  - assemblers, debuggers, C compilers, emulator, simulator, technical support
- wide availability and reliable sources of the microcontrollers

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#### Comparison of the 8051 Family Members

- ROM type
  - 8031 no ROM
  - 80xx mask ROM
  - 87xx EPROM
  - 89xx Flash EEPROM
- 89xx
  - 8951
  - 8952
  - 8953
  - 8955
  - 898252
  - 891051
  - 892051
- Example (AT89C51,AT89LV51,AT89S51)
  - AT= ATMEL(Manufacture)
  - C = CMOS technology
  - LV= Low Power(3.0v)

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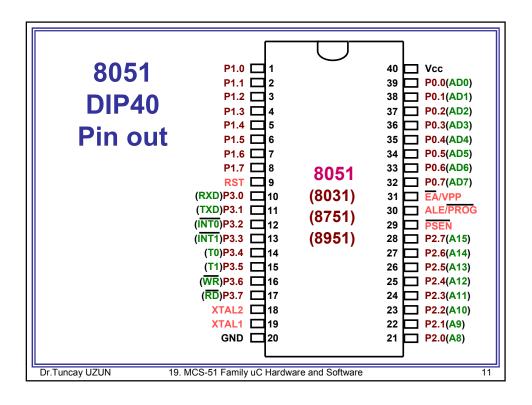
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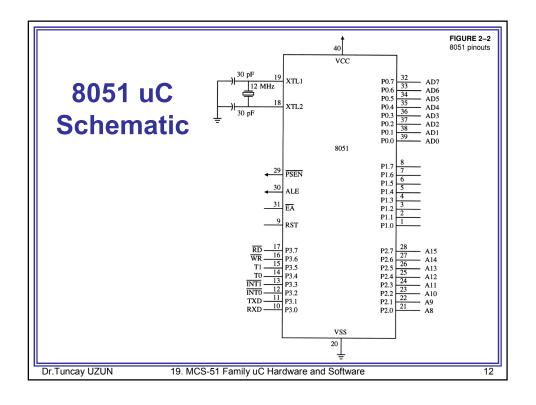
# **Comparison of the 8051 Family Members**

89XX	ROM	RAM	Timer	Int Source	IO pin	Other
8951	4k	128	2	6	32	-
8952	8k	256	3	8	32	-
8953	12k	256	3	9	32	WD
8955	20k	256	3	8	32	WD
898252	8k	256	3	9	32	ISP
891051	1k	64	1	3	16	AC
892051	2k	128	2	6	16	AC

WD: Watch Dog Timer AC: Analog Comparator ISP: In System Programable

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#### **IMPORTANT PINS (I/O Ports)**

- One of the most useful features of the 8051 is that it contains four I/O ports (P0 - P3)
- Port 0 pins 32-39 P0 P0.0 P0.7
  - 8-bit R/W General Purpose I/O
  - Or acts as a multiplexed low byte address and data bus for external memory design
- - Only 8-bit R/W General Purpose I/O
- Port 2 pins 21-28 P2 P2.0 P2.7
  - 8-bit R/W General Purpose I/O
  - Or high byte of the address bus for external memory design
- Port 3 pins 10-17 P3 P3.0 P3.7
  - General Purpose I/O
  - if not using any of the internal peripherals (timers) or external interrupts.
- Each port can be used as input or output (bi-direction)

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#### **Port 3 Alternate Functions**

Port Pin	Alternate Function
P3.0	RXD (serial input port)
P3.1	TXD (serial output port)
P3.2	INTO (external interrupt 0)
P3.3	INT1 (external interrupt 1)
P3.4	T0 (Timer 0 external input)
P3.5	T1 (Timer 1 external input)
P3.6	WR (external data memory write strobe)
P3.7	RD (external data memory read strobe)

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#### **IMPORTANT PINS**

- PSEN (out): Program Store Enable, the read signal for external program memory (active low).
- ALE (out): Address Latch Enable, to latch address outputs at Port0 and Port2
- EA (in): External Access Enable, active low to access external program memory locations 0 to 4K
- RXD,TXD: UART pins for serial I/O on Port 3
- XTAL1 & XTAL2: Crystal inputs for internal oscillator.

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#### Machine cycle

#### Find the machine cycle for:

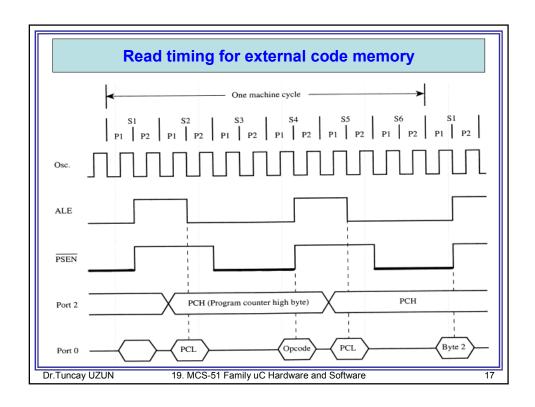
- (a) XTAL = 11.0592 MHz
- (b) XTAL = 12 MHz.
- (c) XTAL = 16 MHz.

#### Solution:

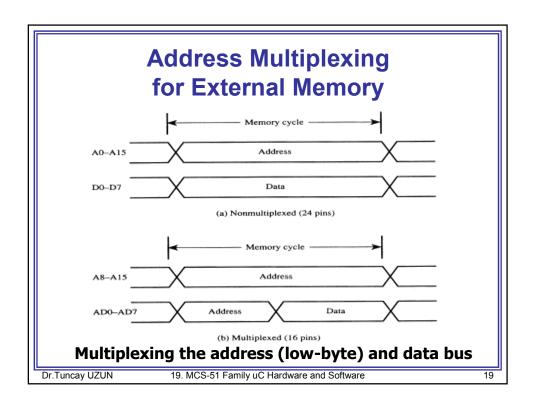
- (a) 11.0592 MHz / 12 = 921.6 kHz;
- machine cycle = 1 / 921.6 kHz = 1.085 μs
- (b) 12 MHz / 12 = 1 MHz;
- machine cycle = 1 / 1 MHz = 1  $\mu$ s
- (b) 16 MHz / 12 = 1.333 MHz;
- machine cycle = 1 / 1.333 MHz = 0.75 μs

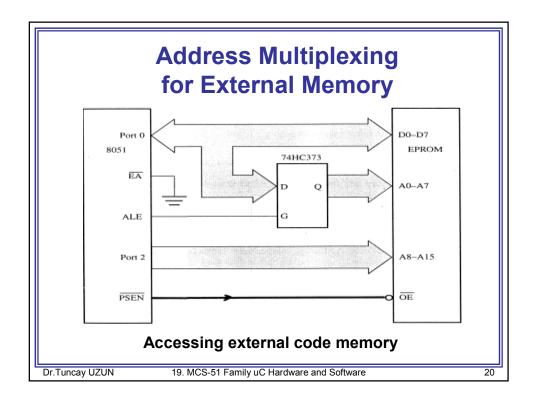
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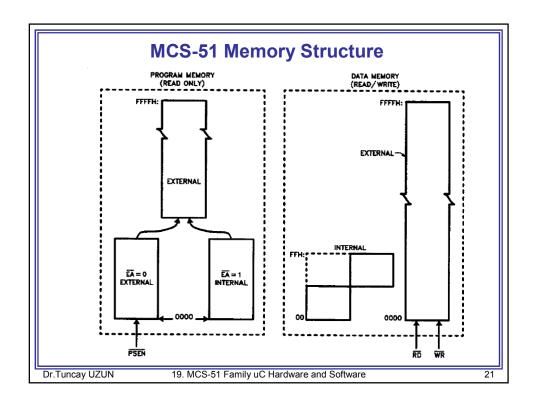
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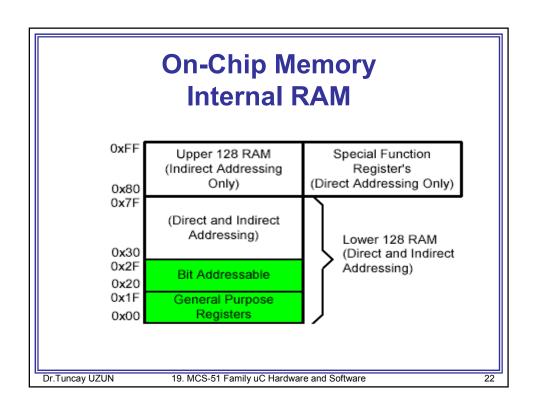


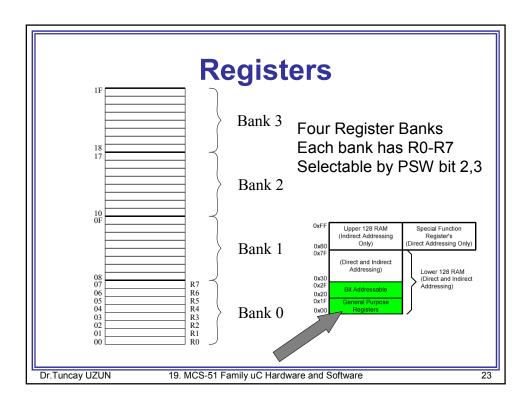
Register         Reset Value           PC         0000           ACC         0000           B         0000           PSW         0000
ACC 0000 B 0000
В 0000
PSW 0000
SP 0007
DPTR 0000
RAM are all zero

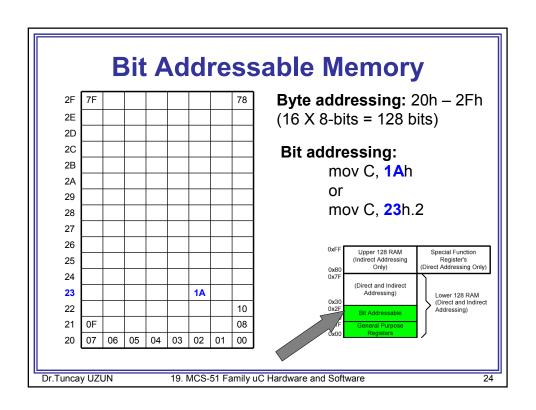


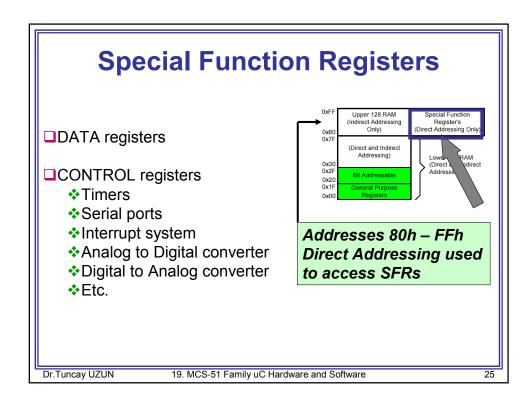


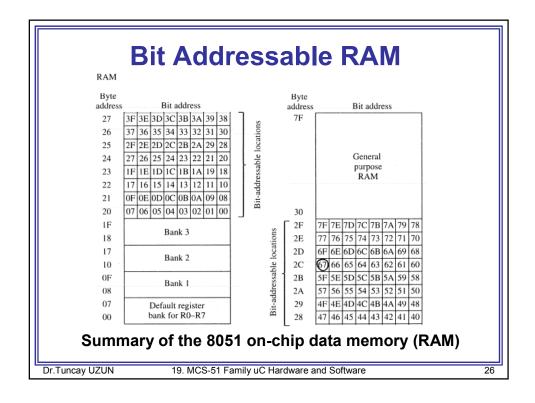


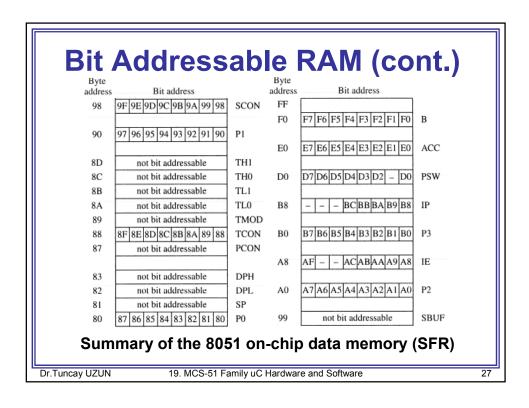


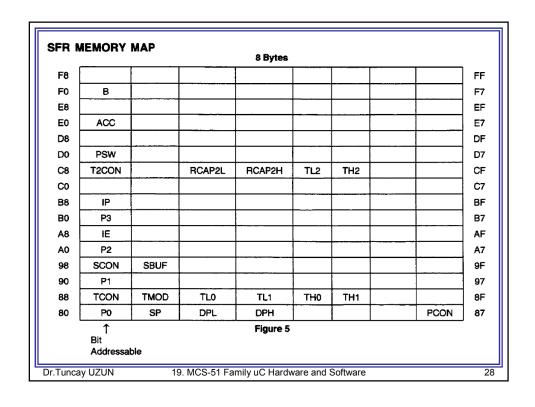








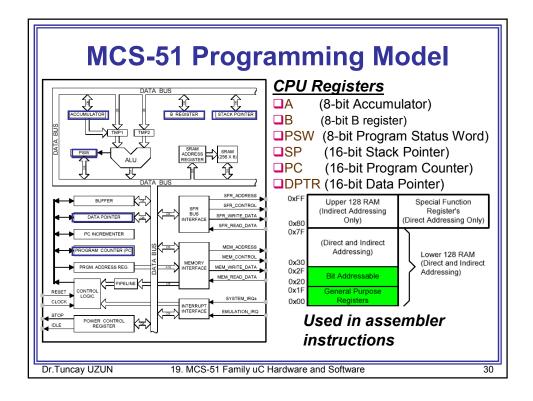


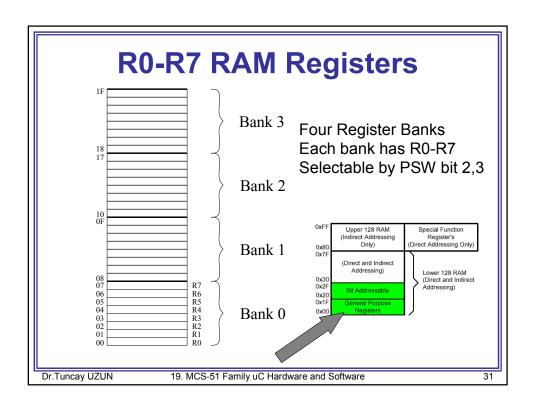


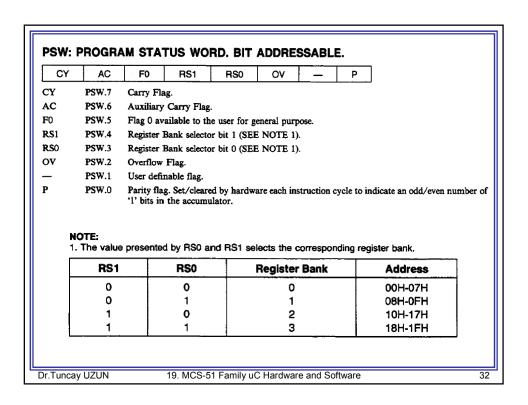
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#### MCS-51 Assembly Language

MCS-51 Instruction Structure

MOV destination, source ; dest. ← source

6802 uP 8051 uC

LDAA #40H MOV A,#40H LDAA 40H MOV A,40H

STAA 41H MOV 40H,A

LDAA 0,X MOVC A,@A+DPTR

BCS L1 JC L1

JSR 1200H LCALL 1200H

CLC CLR C

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# **Addressing Modes**

Immediate Mode - specify data by its value

MOV A,#0 ;put 0 in the accumulator

;A = 00000000

MOV R4,#11h ; put 11hex in the R4 register

;R4 = 00010001

MOV B, #11 ;put 11 decimal in b register

;B = 00001011

MOV DPTR, #7521h ; put 7521 hex in DPTR

;DPTR = 0111010100100001

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## **Addressing Modes**

Register Addressing – either source or destination is one of CPU register

MOV RO, A

MOV A,R7

ADD A,R4

ADD A,R7

MOV DPTR, #25F5H

MOV R5, DPL

MOV R, DPH

Note: that MOV R4,R7 is incorrect

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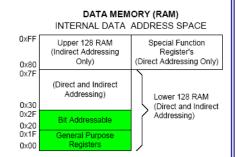
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# Addressing Modes e – specify data by its 8-bit addressing Modes

<u>Direct Mode</u> – specify data by its 8-bit address usually for 30h-7Fh of RAM

MOV A,70h ; copy contents of RAM at 70h to a MOV R0,40h ; copy contents of RAM at 70h to a MOV 56h,A ; put contents of a at 56h to a MOV 0D0h,A ; put contents of a into PSW



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#### **Addressing Modes**

Register Indirect – the address of the source or destination is specified in registers

Uses registers R0 or R1 for 8-bit address:

```
MOV PSW,#0 ; use register bank 0 MOV R0,#0x3C MOV @R0,#3 ; memory at 3C gets #3 ; M[3C] \leftarrow 3
```

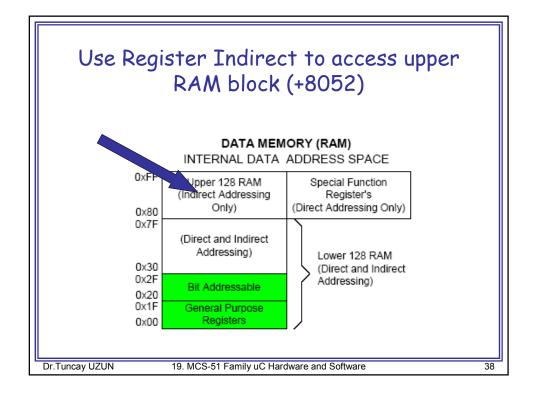
Uses DPTR register for 16-bit addresses:

```
MOV DPTR, #0x9000 ; DPTR ← 9000h
MOVX A, @DPTR ; A ← M[9000]
```

Note that 9000 is an address in external memory

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## **Addressing Modes**

<u>Register Indexed Mode</u> – source or destination address is the sum of the <u>base address</u> and the accumulator (Index)

Base address can be <u>DPTR</u> or PC

MOV DPTR, #4000h

MOV A, #5

**MOV A, @A+DPTR** ;a ← M[4005]

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## **Addressing Modes**

Register Indexed Mode continue
Base address can be DPTR or PC

ORG 1000h

1000 MOV A, #5

 $PC \rightarrow 1002 \text{ MOVC A, @A+PC}$  ;a  $\leftarrow M[1008]$ 

1003 NOP

- Table Lookup
- MOVC only can <u>read</u> <u>internal</u> code memory

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#### MCS-51 Instruction Set

- Arithmetic Operation Instructions
- Logic Operation Instructions
- Data Transfer Instructions
- Boolean Variable Manipulation Instructions
- Program Branching Instructions

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#### **Data Transfer Instructions**

- MOV dest , source ; dest ← source
- Stack instructions

Exchange instructions

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#### **Acc Register**

- A register can be accessed by direct and register mode
- This 3 instruction has same function with different code

0703 E500 mov a,00h 0705 8500E0 mov acc,00h 0708 8500E0 mov 0e0h,00h

Also this 3 instruction

070B E9 mov a,r1 070C 89E0 mov acc,r1 070E 89E0 mov 0e0h,r1

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#### **SFRs Address**

B – always direct mode - except in MUL & DIV

0703 8500F0 mov b,00h 0706 8500F0 mov 0f0h,00h

0709 8CF0 mov b,r4 070B 8CF0 mov 0f0h,r4

P0~P3 – are direct address

0704 F580 mov p0,a 0706 F580 mov 80h,a 0708 859080 mov p0,p1

Also other SFRs (pcon, tmod, psw,....)

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#### **8051 Instruction Format**

· immediate addressing

Op code | Immediate data

add a,#3dh ;machine code=243d

· Direct addressing

Op code | Direct address

mov r3,0E8h ;machine code=ABE8

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#### **8051 Instruction Format**

Register addressing

```
Op code | n| n| n|
070D E8
                          ;E8 = 1110 \ 1000
070E E9
                          ;E9 = 1110 1001
           mov a,r1
070F EA
                          ;EA = 1110 \ 1010
           mov a,r2
0710 ED
           mov a,r5
                         ; ED = 1110 1101
0711 EF
           mov a,r7
                          ; Ef = 1110 1111
0712 2F
           add a,r7
         mov r0,a
0713 F8
0714 F9
         mov r1,a
0715 FA
           mov r2,a
0716 FD
           mov r5,a
```

mov r5,a

0717 FD

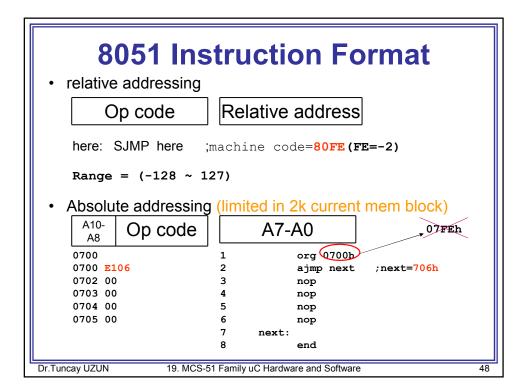
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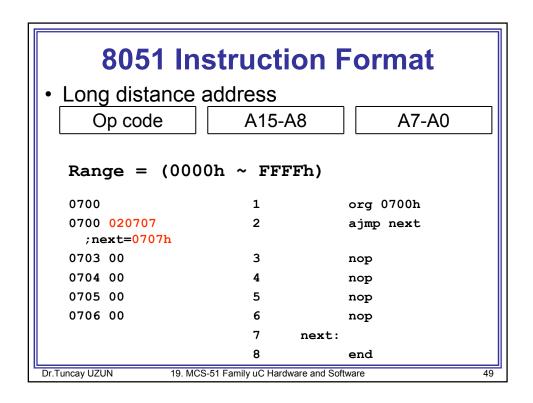
#### **8051 Instruction Format**

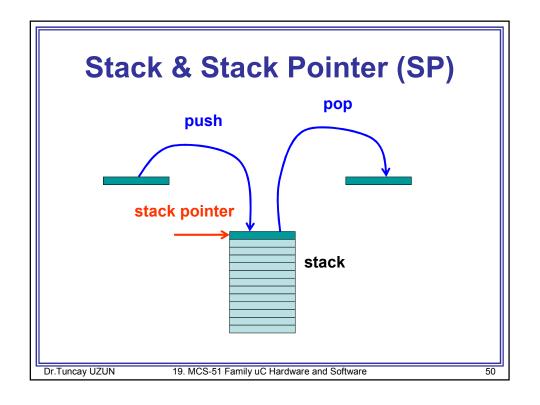
· Register indirect addressing

```
Op code
             ; i = 0 or 1
mov a, @Ri
070D E7
             mov
                  a,@r1
070D 93
             movc a,@a+dptr
070E 83
             movc a,@a+pc
070F E0
             movx a,@dptr
0710 F0
             movx @dptr,a
0711 F2
             movx @r0,a
0712 E3
             movx a,@r1
```

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#### **Stack**

- Stack-oriented data transfer
  - –Only one operand (direct addressing)
  - -SP is other operand register indirect implied
- •Direct addressing mode must be used in PUSH and POP

MOV SP,#0x40 ; Initialize SP

PUSH 0x55; SP $\leftarrow$ SP+1,M[SP] $\leftarrow$ M[55]

 $;M[41] \leftarrow M[55]$ 

POP B ; B←M[55]

Note: can only specify RAM or SFRs (direct mode) to push or pop. Therefore, to push/pop the accumulator,

must use acc, not a

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### **Multiply**

When multiplying two 8-bit numbers, the size of the maximum product is 16-bits

 $FF \times FF = FE01$ (255 x 255 = 65025)

MUL AB ; BA  $\leftarrow$  A \* B

Note: B gets the High byte A gets the Low byte

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#### Division

Integer Division

```
DIV AB ; divide A by B
```

```
A ← Quotient(A/B)
B ← Remainder(A/B)
```

OV - used to indicate a divide by zero condition. C – set to zero

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# Decimal Adjust Accum. for Add.

DA A

; decimal adjust a

Used to facilitate BCD addition.

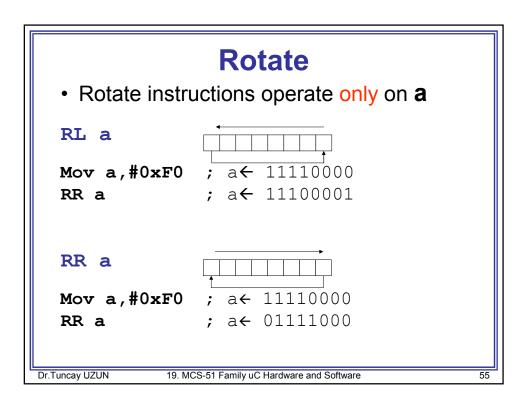
Adds "6" to either high or low nibble after an addition to create a valid BCD number.

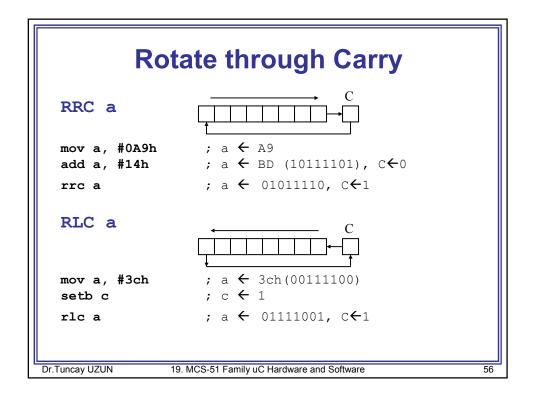
#### Example:

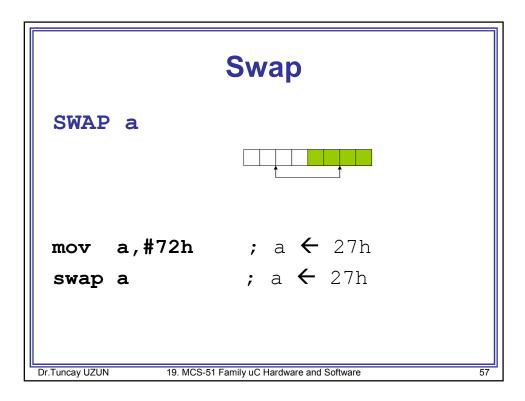
```
mov a,#23h
mov b,#29h
add a,b ; a ← 23h + 29h = 4Ch (wanted 52)
DA a ; a ← a + 6 = 52
```

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### **Conditional Jump**

 These instructions cause a jump to occur only if a condition is true. Otherwise, program execution continues with the next instruction.

- There is no zero flag (z)
- · Content of A checked for zero on time

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JNZ <rel addr=""> Jum  JC <rel addr=""> Jum  JNC <rel addr=""> Jum  JB <bit>,<rel addr=""> Jum  JNB <bit>,<rel addr=""> Jum  JNB <bit>,<rel addr=""> Jum  ABC <bir>,<rel addr=""> Jum  &amp;cl</rel></bir></rel></bit></rel></bit></rel></bit></rel></rel></rel>	Description
JNZ <rel addr=""> Jum  JC <rel addr=""> Jum  JNC <rel addr=""> Jum  JB <bit>,<rel addr=""> Jum  JNB <bit>,<rel addr=""> Jum  JNB <bit>,<rel addr=""> Jum  ABC <bir>,<rel addr=""> Jum  &amp;cl</rel></bir></rel></bit></rel></bit></rel></bit></rel></rel></rel>	
<pre>JC <rel addr=""> Jum JNC <rel addr=""> Jum JB <bit>,<rel addr=""> Jum JNB <bit>,<rel addr=""> Jum JBC <bir>,<rel addr=""> Jum &amp;cl</rel></bir></rel></bit></rel></bit></rel></rel></pre>	o if a = 0
<pre>JNC <rel addr=""> Jum JB <bit>,<rel addr=""> Jum JNB <bit>,<rel addr=""> Jum JBC <bir>,<rel addr=""> Jum &amp;cl</rel></bir></rel></bit></rel></bit></rel></pre>	o if a != 0
<pre>JB <bit>,<rel addr=""> Jum JNB <bit>,<rel addr=""> Jum JBC <bir>,<rel addr=""> Jum &amp;cl</rel></bir></rel></bit></rel></bit></pre>	o if C = 1
<pre>JNB <bit>,<rel addr=""> Jum JBC <bir>,<rel addr=""> Jum &amp;cl</rel></bir></rel></bit></pre>	o if C != 1
JBC // JBC // Jum // &cl	o if bit = 1
&cl	o if bit != 1
	o if bit =1, ear bit
CJNE A, direct, < rel addr > Commem equ	

### **Example: Conditional Jumps**

if (a = 0) is true
 send a 0 to LED
else

send a 1 to LED

jz led\_off
Setb P1.6
sjmp skipover

led\_off: clr P1.6

mov A, PO

skipover:

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### **Iterative Loops**

```
For A = 0 to 4 do
{...}

clr a
loop: ...

inc a

cjne a, #4,
loop
```

```
For A = 4 to 0 do
{...}

mov R0, #4

loop: ...

djnz R0, loop
```

#### Call and Return

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- · Call is similar to a jump, but
  - Call pushes PC on stack before branching

- •Return is also similar to a jump, but
  - Return instruction pops PC from stack to get address to jump to

ret ; PC ← stack

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### **Interrupt Vectors**

Each interrupt has a specific place in code memory where program execution (interrupt service routine) begins.

**External Interrupt 0** : 0003h Timer 0 overflow : 000Bh **External Interrupt 1** : 0013h Timer 1 overflow : 001Bh

Serial : 0023h

Timer 2 overflow(8052+): 002bh

Note: that there are only 8 memory locations between

vectors.

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## **Interrupt Vectors**

To avoid overlapping Interrupt Service routines, it is common to put JUMP instructions at the vector address. This is similar to the reset vector.

```
009BH
                     ; at EX7 vector
       ljmp EX7ISR
       cseg at 0x100; at Main program
Main:
                     ; Main program
EX7ISR: ...
                 ; Interrupt service routine
                  ; Can go after main program
                  ; and subroutines.
       reti
```

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