

A LIGHTBULB WORM?

Details of the Philips Hue Smart Lighting Design

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(Black Hat USA 2016 White Paper)

ABSTRACT

This whitepaper is designed to show some details of the Philips Hue system. It is not designed to demonstrate any specific attack, but instead a chance to “poke around” to see what security features are present. It is designed to serve as a reference for those designing similar systems, to give an idea what attack surfaces might be exploited.

This analysis focuses on the embedded hardware itself. In particular, I look at the Bridge 1.0 (round), the Bridge 2.0 (square), the low-cost white light bulbs, and the BR30 color bulb.

The newer Bridge 2.0 makes an interesting target for hardware hackers to use, as it's possible to obtain a root console (as discussed herein) allowing you to take control of this device.

Having access to the root console also allows more detailed analysis of the binaries present on the bridge, which could lead to the discovery of other vulnerabilities. In particular, there are some ‘interesting’ files including what appears to be a master process for running the Bridge 2.0 (webserver, certain aspects of ZigBee, talking to Hue app, etc.).

Overall, we still find a number of security features present on the various systems that make it more difficult to attack than typical consumer electronics. Firmware updates appear always to be encrypted to protect them from analysis, and are signed to protect devices from being reprogrammed by another actor.

Despite this, certain engineering trade-offs may cause problems in the future. Bulbs of the same type use the same encryption key for the firmware files, which means that a leak of that encryption key could allow someone to *permanently reprogram lightbulbs over the air*. This could cause a variety of problems, in the extreme case allowing a reflashed bulb to then reflash nearby bulbs (i.e., a worm).

This work came about due to attempting to answer someone's question about the possibility of a lightbulb worm (hence the title, with the question mark).

1 INTRODUCTION

The Philips Hue is one of the most popular “smart lighting” products on the market. If you haven’t used these devices, the idea of a “smart lightbulb” might seem like another dumb internet of things example, there are many practical uses that have driven its adoption.

For example, using these smart light bulbs allows you to “rewire” switch layouts. A simple wall-mount switch (which requires no batteries, as it is powered by a minute amount of mechanical energy you generate by hitting the switch) means you are not constrained by how your house is currently wired, or even placement of the switch. Anyone who has struggled with a switch that is half-hidden behind a piece of furniture will appreciate such abilities!

Of course many more advanced uses are possible, such as automatically adjusting lighting based on other devices turning on, remotely controlling lights, linking light settings to motion detection, etc.

The Philips Hue is built on top of the ZigBee Light Link (ZLL) protocol; you can see more about this from the ZigBee Alliance website at <http://www.zigbee.org/zigbee-for-developers/applicationstandards/zigbee-light-link/>. You can also download details from some of the silicon manufacturers that make devices for ZLL networks – for example, NXP has a PDF at http://www.nxp.com/documents/user_manual/JN-UG-3091.pdf, which goes through details of the ZLL.

ZigBee itself is built on top of a low-power radio network called IEEE 802.15.4. This standard is designed for very low-power, low data rate devices. The maximum packet size is 127 bytes and maximum transfer rate is 250 kbit/s. Range varies somewhat based on conditions & specifics of the radios – about 25-100m is typical for IEEE 802.15.4 devices in practical scenarios.

It is possible to achieve ranges of over a 1000m line-of-sight with some IEEE 802.15.4 devices using the standard antennas (i.e., NOT Yagi or high-gain antennas).

ZigBee is commonly run at the 2.4 GHz band (in the same band as Wi-Fi), although there is a lower-frequency version that can occupy a band around 700-900 MHz (specific band depends on region of the world). The ZLL runs entirely on the 2.4 GHz band, thus range may also depend on how much traffic the ZLL network needs to conflict with.

The central node in these networks is called the “bridge” by Philips, as it controls all the light-bulbs. This bridge device contains the IP link as well, typically via an Ethernet jack. The bridge devices powers up and makes a network, which the various lightbulbs can then join.

ZLL SECURITY TRADE-OFFS

One of the most difficult problems for these types of devices is how to securely “join” an authorized network.

If you bring home a smart light, how does it know what network to join, and how does it do so securely? The IEEE 802.15.4 radio chips (these chips form the basis of any ZigBee device, be ZLL or otherwise) almost always have support for AES-128 which is used to encrypt network traffic. In ZLL there is a network-wide key used for all traffic.

Such a network-wide key is very common in these types of networks; few protocols use different link keys between devices. But how you give the new device that network key is critical – we obviously cannot send it in cleartext, in case an attacker is listening.

And some devices (such as the wall-switches) may be so power-constrained they cannot perform much processing beyond simply sending messages. Anything that uses asymmetric cryptography or a D-H key exchange is infeasible.

ZLL solves the problem through the use of a master (symmetric) key. This master key is used to encrypt a network key, which can then be securely sent to a device joining the network. Anyone making a ZLL device knows this master key, and promises to store it securely.

This ZLL master key would also be programmed into every ZLL device – if even one customer had one insecure product that revealed the key, it is no longer considered a secret.

However – all may not be lost. Even if an attacker has the key, they cannot automatically determine the network key for a given random network. They would have to join that network or observe the traffic of another device joining.

An attacker *may*, however, be able to perform a “Light Stealing” attack. There is a provision within the ZLL to remotely request that a device is “reset to factory new” state. If an attacker was in possession of the ZLL master key, they could send such legitimate requests.

To help combat this, devices perform verification based on the received signal strength indicator (RSSI) of such requests. Devices are only supposed to respond if the signal is sufficiently strong to indicate it comes from a nearby device – in the case of Philips Hue, it appears to only work if approximately 30 cm away.

In legitimate requests, the transmit power is also lowered. As an attacker we would have no such issues, and can use excessive transmit power for sending these requests. Such a request format may allow nearby attackers to temporarily “take over” lights by forcing them to join a new network. More detail on this will be published in a forthcoming paper by another author (with some details/demos at Blackhat USA 2016).

Ultimately, while you may be surprised by the use of a fixed symmetric master key, given the various constraints it provides a reasonable trade-off between a secure implementation

and good “out of box” experience, which is supposed to allow different manufacturers even to work together.

There are a number of assumptions underlying this of course (mainly about the correctness of certain implementations), and we’ll explore some of these here.

2 PREVIOUS & FUTURE WORK

I’m far from the first person to look at ZigBee, ZLL, or even the Philips Hue system. I thought I’d provide a few links for information that will be of interest to you.

Travis Goodspeed has done considerable work in ZigBee hacking:

- See one of his Blackhat presentations: <https://www.blackhat.com/presentations/bh-usa-09/GOODSPEED/BHUSA09-Goodspeed-ZigbeeChips-SLIDES.pdf>
- Other older work published on his blog too, see for example: <http://travisgoodspeed.blogspot.ca/2009/03/breaking-802154-aes128-by-syringe.html>
- Which references some associated interesting

Tobias Zillner’s ZigBee Exploited talk & white-paper also is a good quick introduction:

- Slides link: <https://www.blackhat.com/docs/us-15/materials/us-15-Zillner-ZigBee-Exploited-The-Good-The-Bad-And-The-Ugly.pdf>
- Whitepaper link: <https://www.blackhat.com/docs/us-15/materials/us-15-Zillner-ZigBee-Exploited-The-Good-The-Bad-And-The-Ugly-wp.pdf>

There are many more people working on hacking ZigBee/IEEE 802.15.4 networks. For example the KillerBee framework (published by <http://www.riverloopsecurity.com/projects.html>) is a good example of how advanced tools can be!

Nitesh Dhanjani has specifically done work on the Philips Hue system:

- A 46-page paper is available at <http://www.dhanjani.com/docs/Hacking%20Lightbulbs%20Hue%20Dhanjani%202013.pdf>

The last referenced paper (Nitesh Dhanjani) goes into considerable detail on protocol-layer flaws in the Philips Hue system looking at traffic to/from the bridge device. My work has concentrated only at attacks starting at the bridge and beyond (i.e., no work was done by me on the network traffic).

While I don’t know the source, the ZLL master key I mentioned earlier appears to be leaked, showing up in various online sources. It’s thus possible an attacker could either (a) perform attacks that require talking to ZLL devices, or (b) impersonate a ZLL device by being able to decrypt and determine a ZLL link key. This was reported by Tobias Zillner in his “Zigbee Exploited” talk as well.

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Also, during my preparation for this work I met another researcher, Eyal Ronen, who has been working hard on similar security analysis, but going much more in-depth on the actual firmware update process along with what is required to reflash arbitrary bulbs over the air (OTA).

Eyal previously published a paper demonstrating what could happen should an attacker take control of your bulbs – in particular using them to leak data by bulb brightness changes (see <http://www.wisdom.weizmann.ac.il/~eyalro/EyalShamirLed.pdf> for this paper).

While at the time I'm writing this whitepaper for Black Hat 2016 his newer research is not yet released, I highly recommend checking his website at <http://www.wisdom.weizmann.ac.il/~eyalro/> for updates. His work looks to (a) release specific attacks again some of these devices, and (b) push these attacks to be useful in complex and realistic scenarios. It's also ongoing, so he'll likely have more attacks in the future too!

3 USEFUL TOOLS

The objective of this work is to show what type of hacks are possible. The specifics of tools required depends on what you wish to accomplish. To accomplish the rooting requires the minimal amounts of tools:

- USB to Serial adapter.
- A few paperclips (or some bits of wire).

But for more advanced hacks, you'll start to need additional tools such as:

- Bus pirate (SPI flash dumping).
- Volt meter.
- Oscilloscope.
- Fine-tipped soldering iron (I love the Metcal ones).
- Stereo microscope for inspecting/soldering.

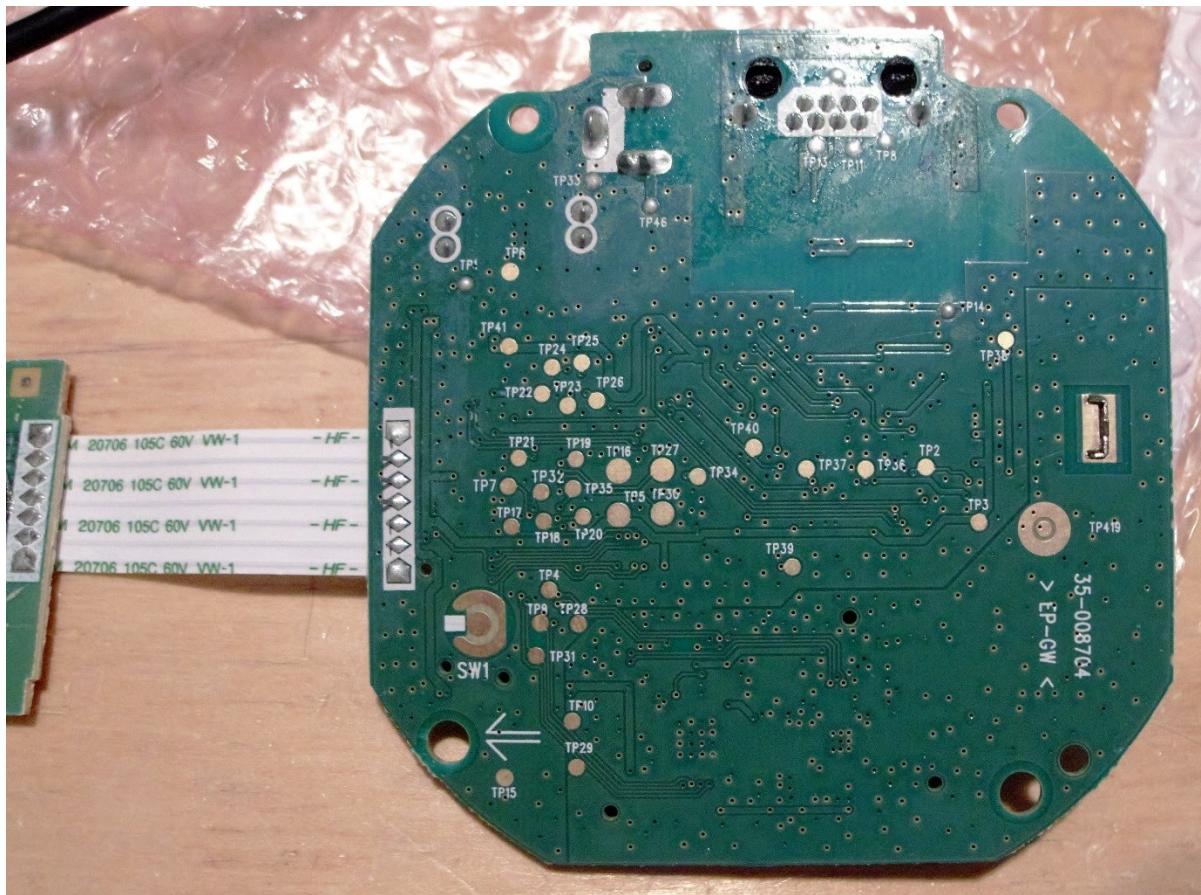
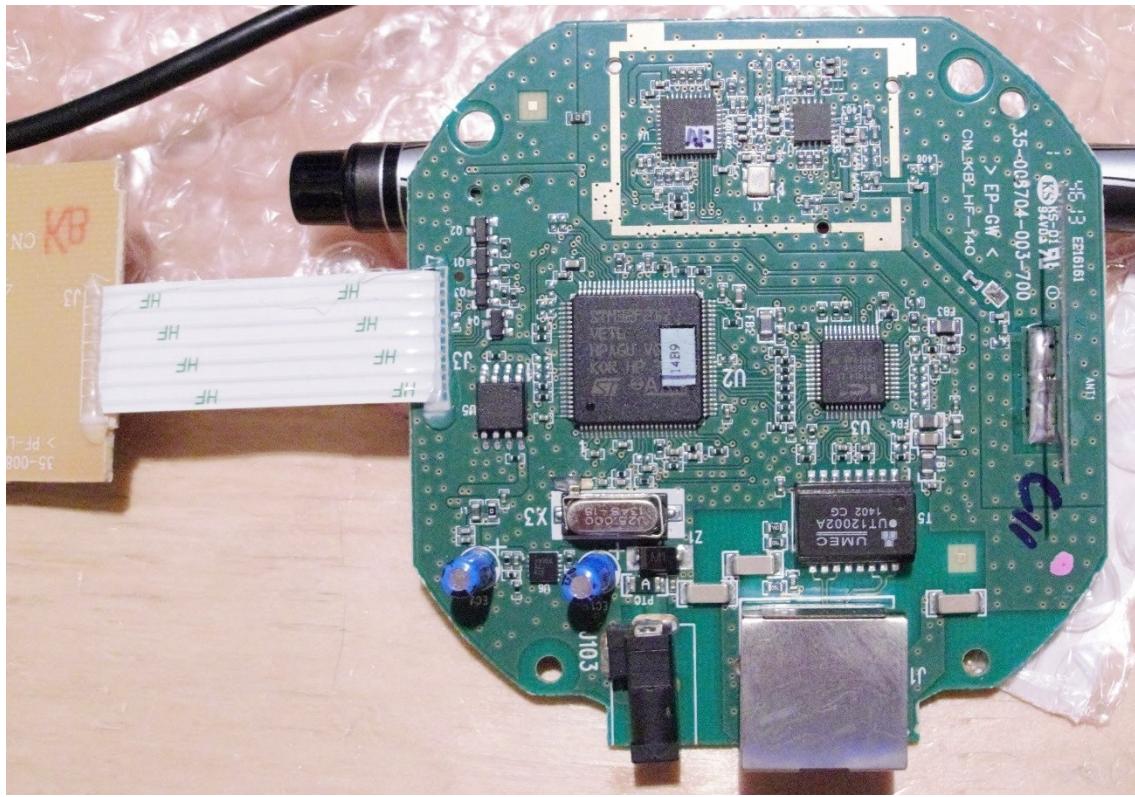
To do the power analysis & glitching attacks, I also used:

- ChipWhisperer Capture hardware (ChipWhisperer-Pro was used here, but most of the attacks possible with ChipWhisperer-Lite + some external logic for triggering).

With that background, let's dive right into some specific examples of the hardware. I'll start with the older version of the bridge device.

4 BRIDGE V 1.0

The "bridge v1.0" are the original version of the Hue bridge, which are round in appearance. The internals of the bridge are shown below:



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These bridges contain two sections: the main ARM processor, and the Zigbee ZLL solution (referred to as the ‘Zigbee SoC’. The use of a separate chip for holding the entire ZigBee stack is something we’ll see repeated in the second-generation bridge as well.

The main ARM processor is a STM32F217VET6 by ST (direct link to datasheet: <http://www.st.com/content/ccc/resource/technical/document/datasheet/51/9b/66/ba/d4/a8/49/4a/CD00263874.pdf/files/CD00263874.pdf/jcr:content/translations/en.CD00263874.pdf>).

This is a Cortex M3 device, with 512 Kbyte FLASH memory (internal) + 128Kbytes of SRAM (internal). It contains a number of cryptographic hardware accelerators (AES + 3DES + MD5 + SHA-1).

There is an external SPI flash chip (Winbond 25Q16BVS) connected to the ARM processor. On a virgin bridge this appears to hold simple strings indicating the ZLL groups and similar information, but is almost entirely filled with “FF” bytes (i.e., empty):

Once a bridge has been running, it holds additional configuration information. It does not appear to ever hold an unencrypted firmware update, even during the update process itself (more details later on that).

The ZigBee section is of most interest to us. It contains a CC2530F256 IEEE 802.15.4 SoC device, alongside a CC2590 “range extender” (i.e., amplifier). There are a number of test points on the PCB, so I can briefly talk about their purpose in our “first look” at the bridge device.

BRIDGE DEVICE – FINDING SERIAL PORTS

To get an idea of the boot process, we can find 3 serial ports on the PCB which spit data out at a standard 115,200 baud rate. One is connected to the ARM (status information), and two are the link between the CC2530 and the ARM. These test points are marked on the bottom as:

- TP30 is the ARM serial log output

- TP9/TP10 is the CC2530 to ARM serial port test points

An example of the communication between the ARM and the CC2530 is given below.

Data to ARM from CC2530:

```
[Log,Info,S_DeviceInfo,Booting into normal mode...]
[Log,Info,S_DeviceInfo,DeviceId: IpBridge]
[Log,Info,N_Security,LIB4.4.52]
[Log,Info,N_Security,KeyBitMask,0x0012]
[Log,Info,A_Bridge,Platform version 0.25.0,package_ZigBee
8720,package_Z_Stack 8720,built by LouvreZLL]
[Log,Info,A_Bridge,Product version 5.7.1,SmartBridge 11393,built by
LouvreZLL]
[Bridge,Version,5.7.1,SmartBridge 11393,built by LouvreZLL]
[Bridge,GroupRange,0x5357,0x5367]
[Log,Info,D_Led,dc 16]
[Bridge,NetworkSettings,False,0xB163,26DF52A183D85889,11,0,S=0x0001]
[Log,Info,A_Bridge,NwkAddr: 0x0001, Ch: 11, Pan: 0xB163, NwkUpdId: 0,
ExtPanID:26:DF:52:A1:83:D8:58:89]
[Log,Info,D_Led,dc 16]
[TH,Ready,0]
[Connection,A]
[Connection,GetAddress,L=00:17:88:01:01:07:BF:FC,S=0x0001.0]
[Bridge,StoreGroupRange,0]
[Log,Info,N_ConnectionRouter,Startup network discovery...]
```

Data to CC2530 from ARM:

```
[Link,A]
[Link,GetAddress,L=00:17:88:01:01:07:BF:FC,S=0x0001.0]
```

We can see the general format of requests being sent as [Module, Request1<, Request 2>] and responses being [Module, Response1 <,Response2>]. Specifics of the number of arguments seems to vary between parameters.

BRIDGE DEVICE – TAKING OVER SERIAL

The Zigbee SoC contains the secret ZLL encryption key. An interesting attack is that we never actually need to determine this key, but can instead use the provided Zigbee SoC to send and receive messages that will be encrypted with the correct key. This attack would be made more powerful by looking at the Bridge 2.0 device, where we can find more details of the communications protocol encoded inside a control application.

I'll demonstrate the data format later when looking at the over-the-air update for the BR30 bulb.

FIRMWARE UPDATE: NETWORK PERSPECTIVE

It's relatively easy to monitor the network traffic while performing a firmware update. This details there is a server which simply provides a file that is downloaded, this file has a name like

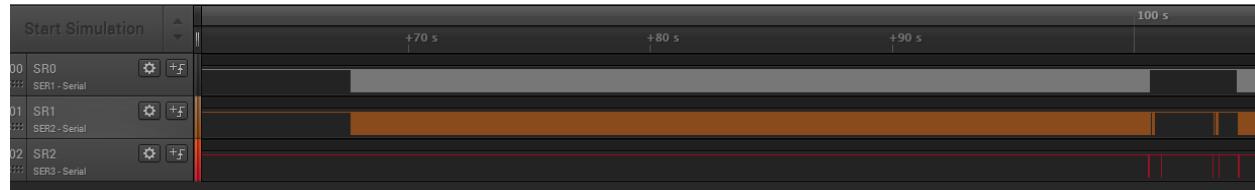
`firmware_rel_cc2530_encrypted_stm32_encrypted_01030262_0012.fw`. As suggested by the name, it includes both the firmware for the CC2530 and for the STM32 processor.

Both appear to be encrypted (no noticeable strings, etc). It's easy to get different releases of this file, and comparing them shows the encryption does not appear to be something like a stream cipher using the same key, as we would expect runs of the same encrypted sequences where code aligned between them (such as the value of strings, init code, etc.).

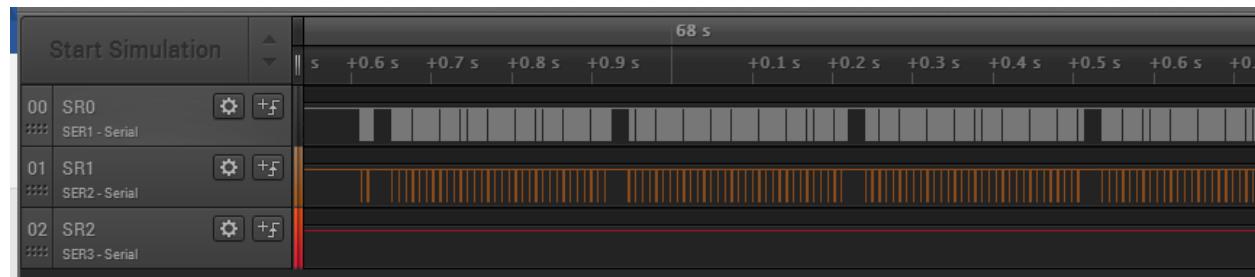
Our primary interest at this point is the ZigBee side, so will concentrate on how the CC2530 firmware update works. I'll discuss that next.

FIRMWARE UPDATE: CC2530

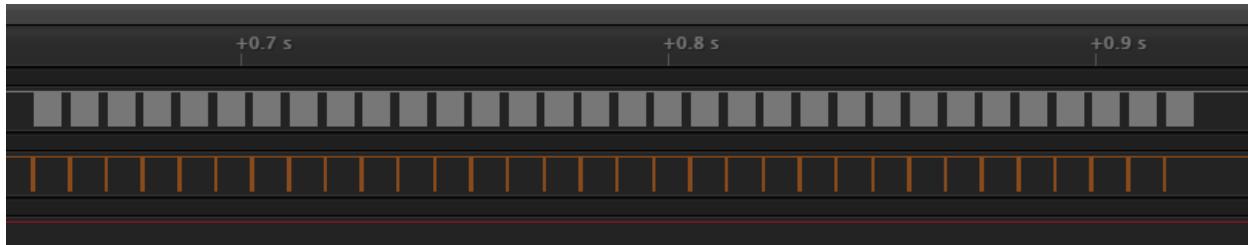
Using a Logic Pro 16, I could log the entire serial protocol during the update process to see what happens during this process. It took a little while to perform the complete update, as can be seen here:



We can look closer, and see “gaps” between groups of packets:



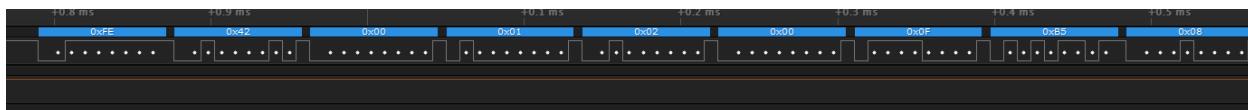
Each of those “Gaps” represents the delay of a page erase. Zooming in closer you can see there is 32 packets, each packet containing 64 bytes of data between page erases:



This 2048 byte spacing aligns with the actual page size of the CC2530. Looking at the bootloader protocol, we can determine it appears to be an implementation of the “SerialBootLoader” (see <http://processors.wiki.ti.com/index.php/SerialBootLoader> for command list).

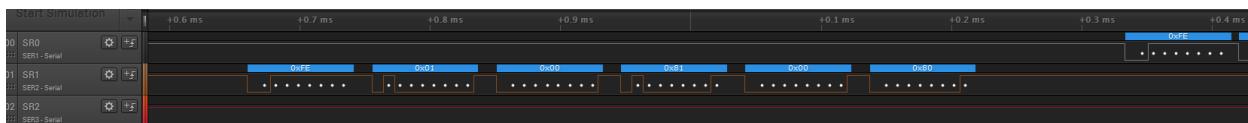
An example SBL implementation with encryption is available at <https://github.com/lee-wei/CC2540/tree/master/Projects/ble/util/EBL/app>, which is a version for the CC2540. The file format appears to differ from this project, but it provides a useful starting point to understand a possible code flow.

The frame format is fairly simple, with 6 bytes of header:

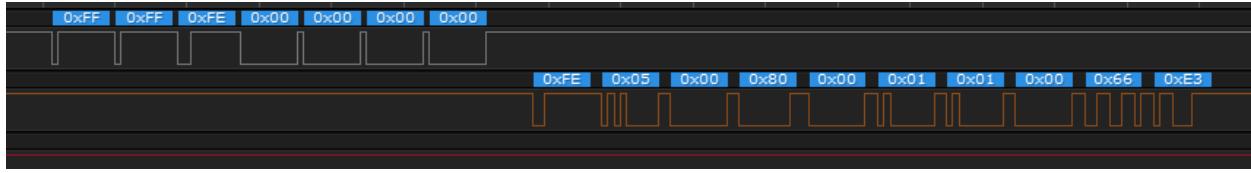


- FE is the “start of frame” header.
 - 42 is the length (66 bytes, payload + addr)
 - 00 01 is a fixed sequence
 - 02 00 is the page to write (in LSB, MSB format, so this equates to 0x0002)
 - Next follows 64 bytes of (encrypted) data.
 - Finally a FCS byte is calculated as the XOR of the previous bytes (see the SBL documentation for details).

If the message is OK (FCS passes + the expected address was sent), the bootloader response with an OK command. At this point the next frame can be sent:



To enter bootloader mode, pin P0.1 was determined to be responsible for entering bootloader mode. If this pin is pulled HIGH after a reset, the bootloader will be entered. If the pin is LOW, the regular code will run. Assuming we entered the bootloader, we can send the “sign-on” command, FF FF FE 00 00 00 00. The bootloader will respond with FE 05 00 80 00 01 01 00 66 E3:



We can then shovel groups of packets to the bootloader. The actual encrypted firmware data is part of the single update file as mentioned. The firmware that is passed over the serial port is directly found in the downloaded firmware file – that is the data sent over the serial port is not modified by the STM32 itself.

Thus any encryption happened *before* the file was uploaded to the Philips servers. This makes our attack more difficult, as we will require to focus on the CC2530 decryption process. Possible attack scenarios include:

- Using the SRAM dump attack to see if keys are in memory.
- Using side-channel power analysis.
- Using glitching attacks.
- Breaking the fuse bits to allow reading the memory out.
- Trying to load a program which allows reading the memory out.

I explored the first three of these options here.

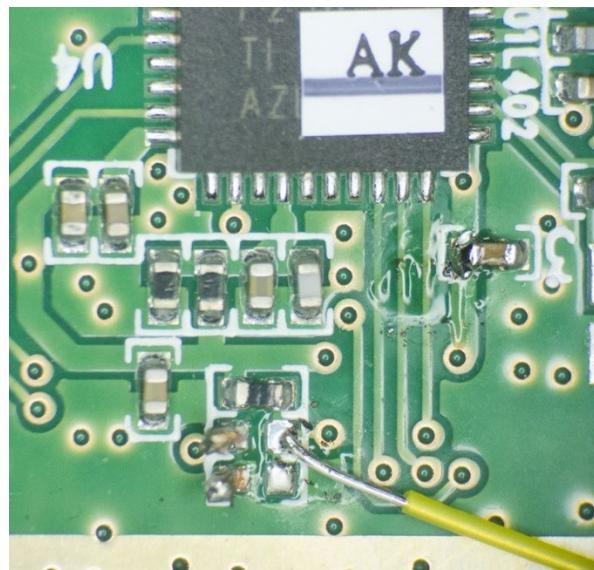
SRAM DUMPING

In order to get an idea what exactly is happening, I used Travis Goodspeed's CC "SRAM dump" attack (see <http://www.blackhat.com/presentations/bh-usa-09/GOODSPEED/BHUSA09-Goodspeed-ZigbeeChips-PAPER.pdf>).

This allows me to dump the SRAM contents of a device, BUT it requires erasing the device to do so. Luckily the bridge 1.0 devices are available cheaply in bulk due to the release of the Bridge 2.0, so many people were upgrading. I had a good boneyard of dead devices from erasing them at various stages:



The debug pins are at TP29/TP31 for DD/DC respectively. You also need the reset pin at TP28. Note the reset pin is driven by the STM32 by default – you can either try holding the STM32 in reset itself to float the pin, or cut the reset by lifting a resistor and instead driving the reset pin from there, as I have done:



I erased several devices at various stages, such as:

- When running normally (not in the bootloader).
- At various stages of the bootloader – before receiving any data, after receiving the first valid frame, second valid frame, and a “much later” frame.

The following shows a dump comparing two such locations – here is the difference between the first valid frame, and after the second valid frame:

Note the messages from address 0xA1 to 0xA6 is the TX buffer (that was the FE 01 00 81 00 80 that was sent in response to an accepted packet). The part after that is the received data, suggesting this is the RX buffer.

I was hoping the data was decrypted in-place and left in SRAM, but it appears that the bootloader is overwriting memory once done with it. This is suggested by the block of FF in place of the RX buffer – it's assumed that perhaps the first frame didn't include any encrypted data, but was instead setup information, the expected signature, etc.

In addition, I didn't find any keys that appeared to decrypt the firmware file. This required some guesses on my part – for example I didn't try AES-CTR mode decryption, I was only using AES-CBC with various key sizes & byte orders.

The known ZLL master key also did not appear in any of the SRAM dumps (including dumps when the device was running normally, not in bootloader mode).

This suggests Philips was aware of this attack vector, and rather actively worked to avoid leaving sensitive data in memory. This attack was published in 2009, so we would hope the designers were aware of it, and avoided keeping sensitive data in SRAM when not needed.

While the data is presumably still in memory at some point, it would require very precise timing to recover this data. In addition, it would come at a large cost in terms of number of bridge devices killed.

For the bootloader at least, we can avoid needing so many bridges by taking advantage of glitch attacks.

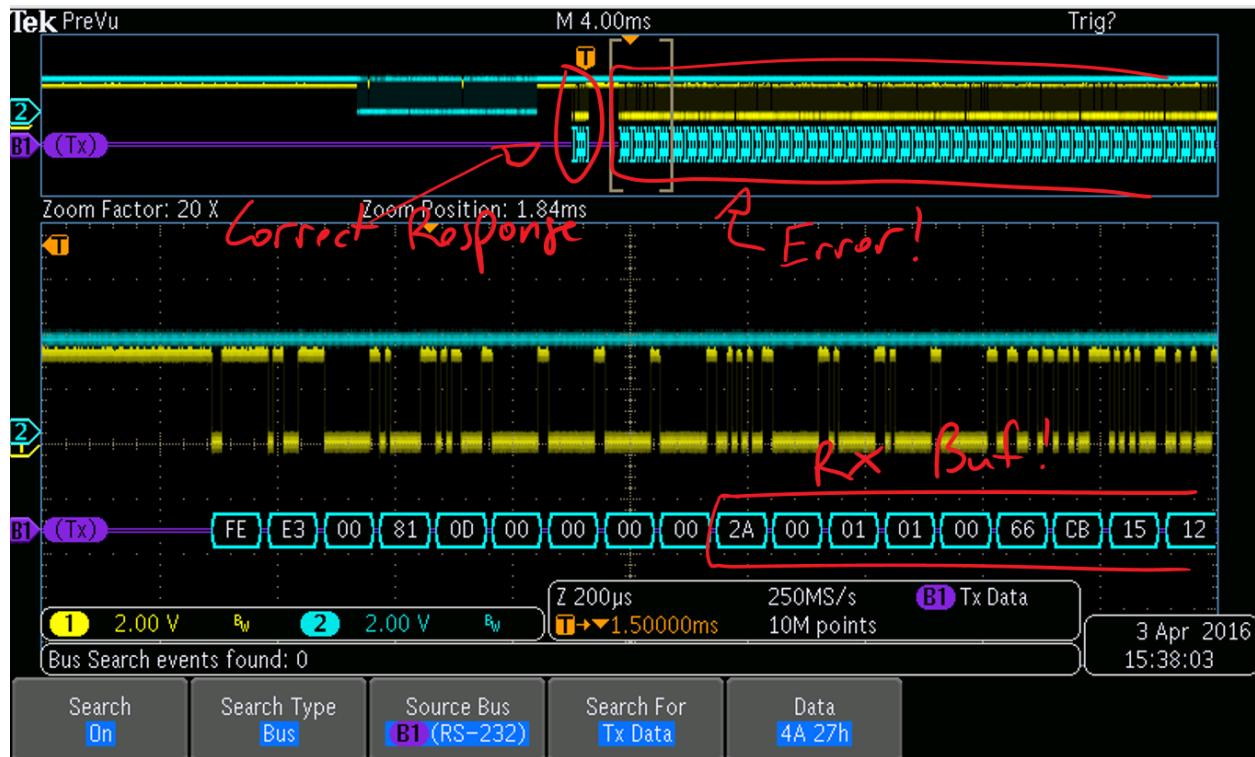
GLITCH ATTACKS

Rather than erasing the device, we can use clock glitching to dump the buffer (see http://wiki.newae.com/Tutorial_A7_Glitch_Buffer_Attacks for a tutorial). This is possible because there is likely some transmit code like the following:

```
for(uint8 i = 0; i < data_to_send; i++) {  
    uart_write(tx_buf[i]);  
}
```

We can use a glitch attack to cause this loop to send more data than expected, which will send the RX buffer back to us. This works because the RX buffer is located in memory after the TX buffer. Causing the above transmit loop to execute additional iterations will simply transmit the memory beyond the TX buffer.

If this RX buffer now contains decrypted data, it would also be sent to us. This was successful in that it allowed reading out the RX buffer, as the following shows:



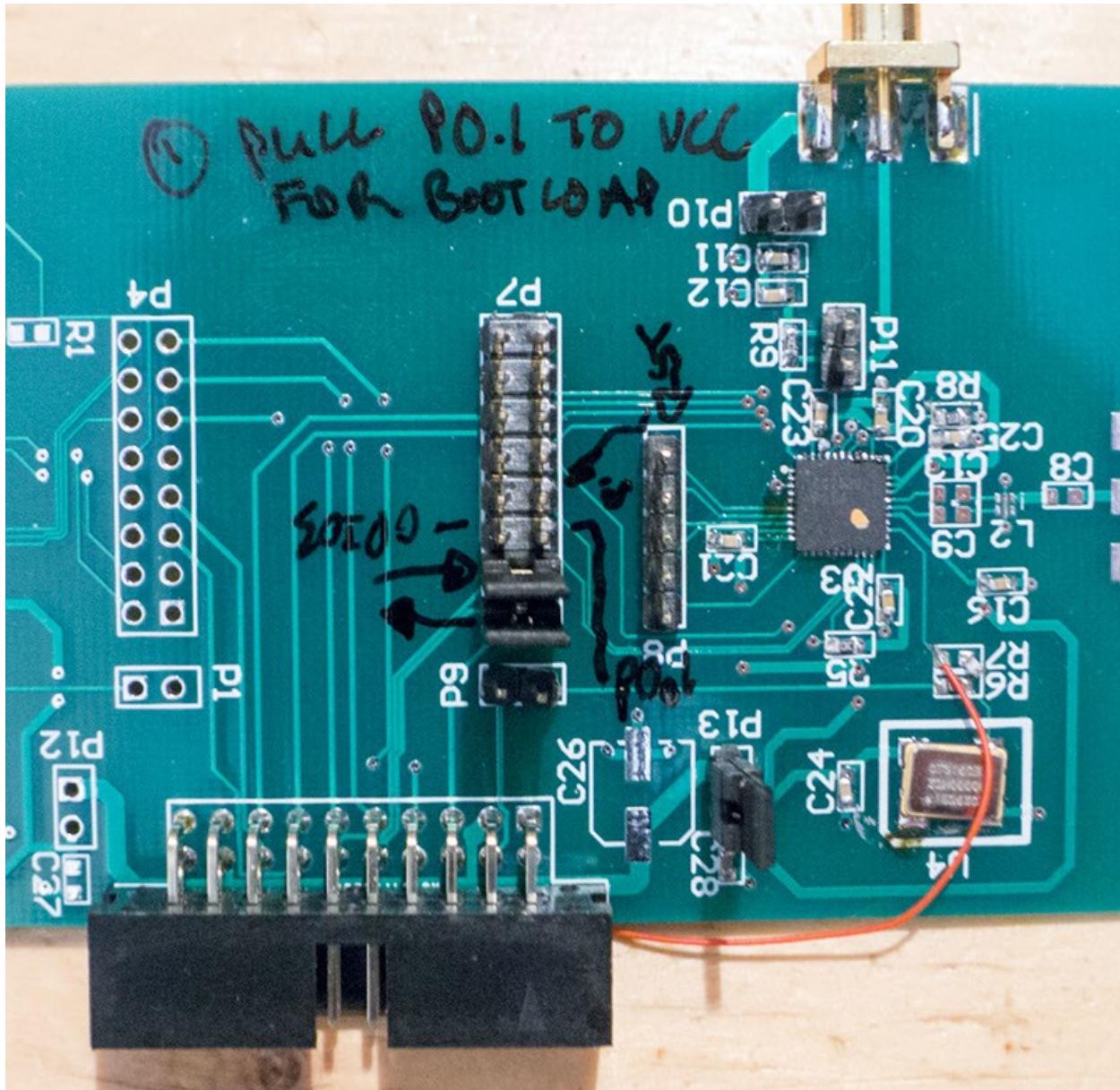
This used a clock glitch inserted after receiving the correct response. This caused the system to continue sending data back to me, and allowed recovery of the complete RX buffer (along with some memory beyond that buffer).

At this point I haven't determined the timing for reading the decrypted data – the data appears to have been wiped by the time the glitches cause the data to be read back. Further work is required, such as inserting glitches to avoid wiping the memory.

Because the ZLL master key is already known, getting the decrypted bridge firmware may not be of great value. It's still possible there could be bugs in the bridge interface we wish to exploit, but I haven't pushed further in this area.

SIDE-CHANNEL POWER ANALYSIS

Side-channel power analysis is another potential method of retrieving the encryption key. I designed a custom board for both side-channel power analysis and the glitching attacks, on which I mounted a CC2530 extracted from a bridge device:



Using the known protocol, I could cause this device to perform the bootloading process (and thus perform the decryption operation).

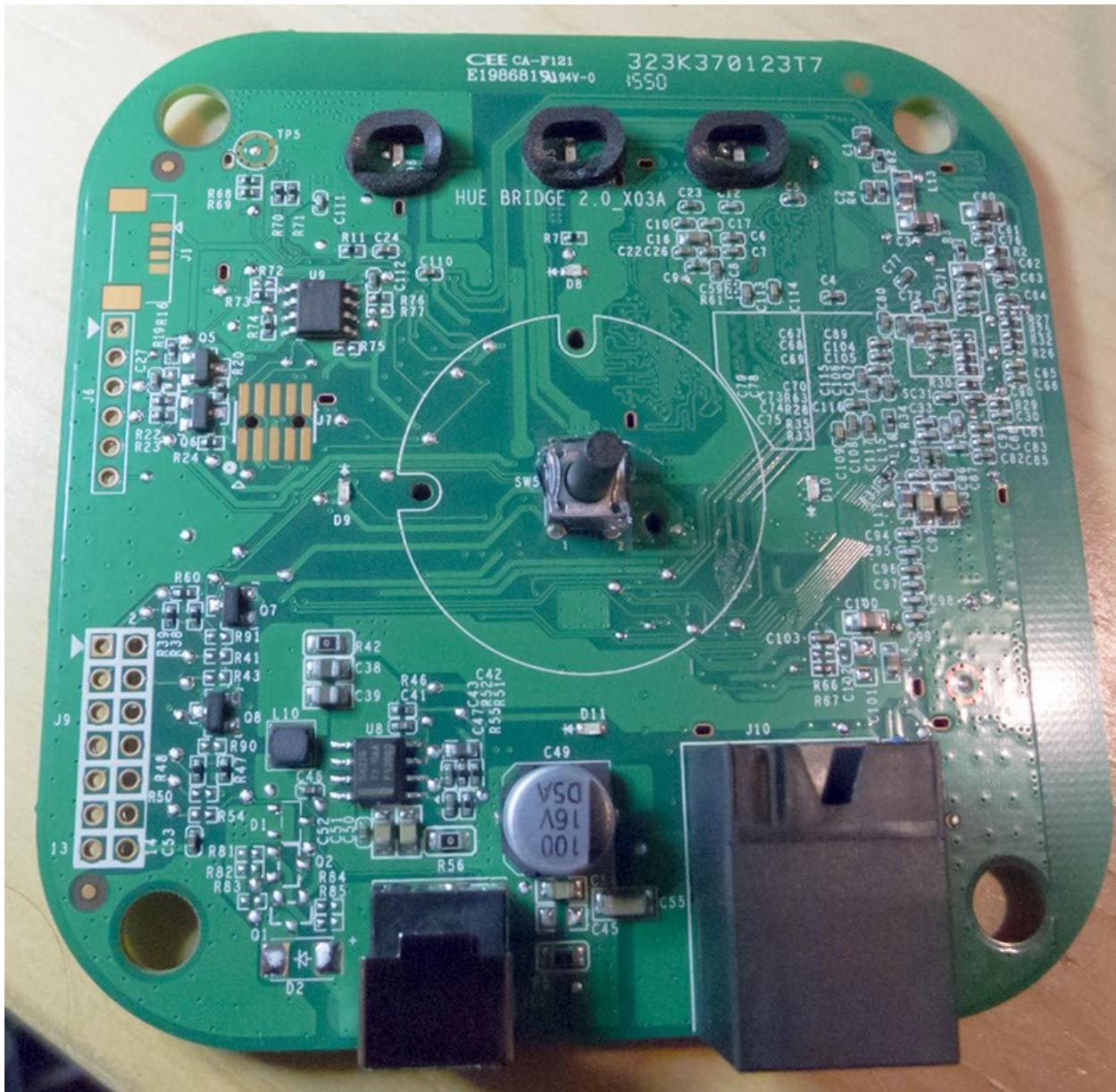
Based on the timing, it seemed likely the AES hardware accelerator in the CC2530 is used. At this point the CC2530 hardware accelerator has not been broken, so performing side-channel power analysis would first require breaking the hardware accelerator in the ideal case.

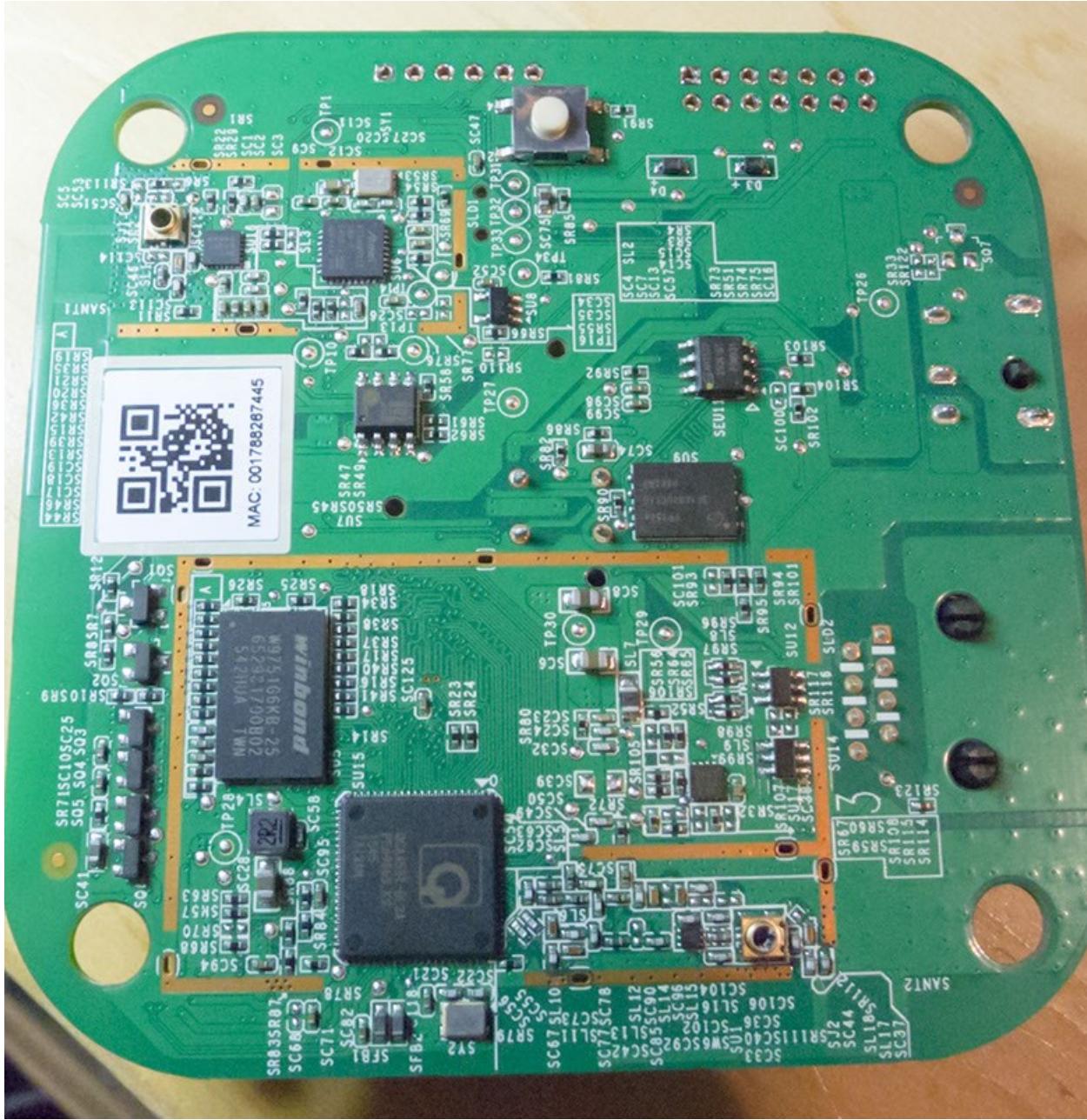
This would entail a time commitment beyond what would be required to move my work (and answer the question in the general case) forward.

Given enough time I think one of the above attacks looks likely to succeed, but they are not trivial to get either the timing or the measurements working. Instead I'll move onto the newer bridge devices, which have a more interesting architecture.

5 BRIDGE V 2.0

The top and bottom side of the bridge is shown below:





The bridge itself has a QCA4531 main SoC, which is a MIPS processor by Qualcomm. It's designed for these "internet of things" type environments.

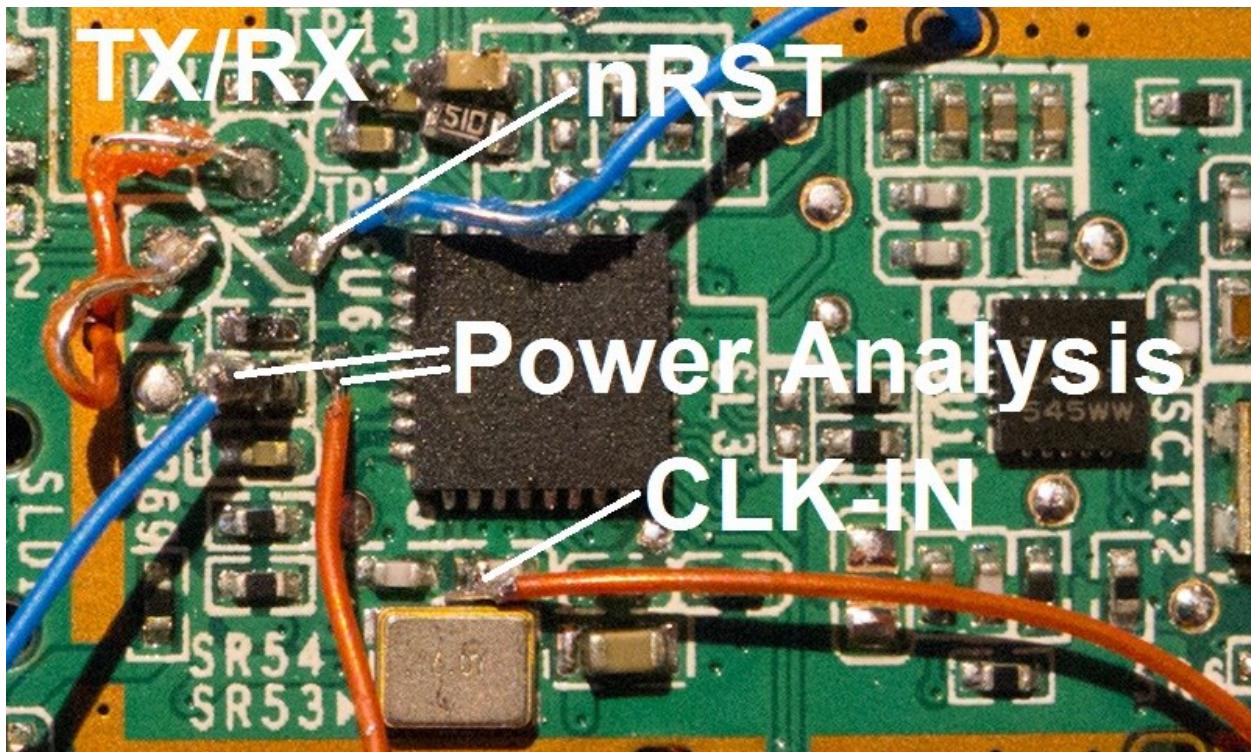
There is DDR memory associated with it, alongside a 1GBit SPI-connected NAND flash P/N GigaDevice GD5F1GQ4UC (datasheet: <http://gigadevice.com/product/download/242.html>), and a smaller SPI-connected NOR flash (this is the standard type of SPI flash), P/N 25Q41BT.

The two flash memories are present because the smaller SPI flash contains the bootloader. This is loaded first, and then the larger flash memory is used to load the kernel & filesystem.

For the ZigBee connection, an Atmel SAMR21E18A is provided. This is a very low-power Cortex-M0+ ARM processor that also has an IEEE 802.15.4 radio built in. Once again it has a small SPI flash memory connected, presumably for the purpose of storing various ZigBee information.

The connection between the SAMR21E18A and the QCA4531 is mostly done through a USB to Serial chip, a PL2303SA mounted at SU7. In addition, there is a buffer at SU8 which holds the SAMR21 in reset until the QCA4531 is ready. This buffer is assumed present because the input appears to be 2.5V logic, and the output a 3.3V logic. The test pad at TP34 allows an override of this logic, to avoid waiting for the QCA4531 to boot. You can also lift the pad of SU8 that connects to the reset pin of the SAMR21 (this is what I did).

The SAMR21 reset is not a labeled test point. The TX/RX pair is at TP14 and a nearby unnamed test point. All of these are shown below:



The additional connections labeled “power analysis” and “CLK-IN” are used for performing side-channel power analysis (more on this later).

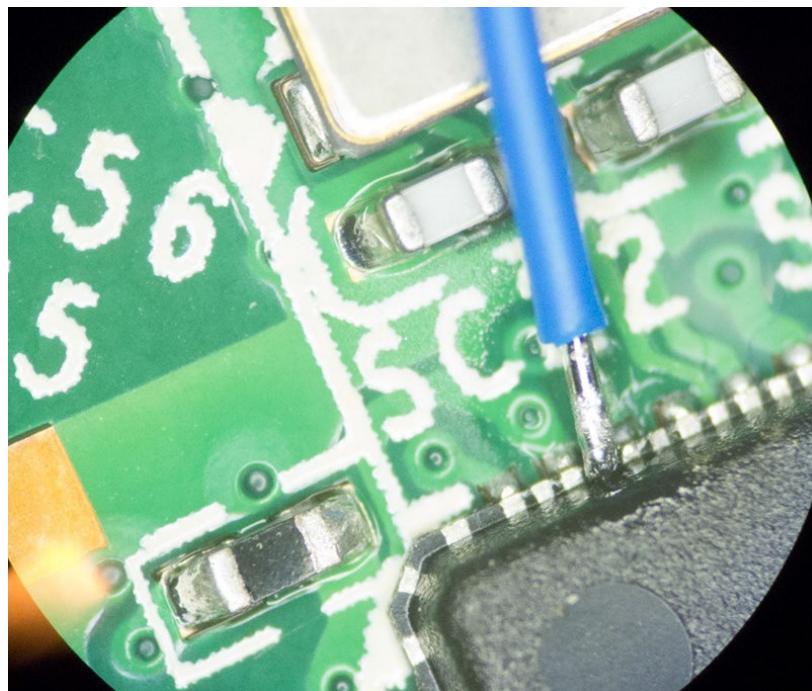
The SAMR21 has a programming heading at J7, which can be mounted as it uses a standard Atmel 0.05” spacing 10-pin header. Even with this header mounted the chip did not respond to programming commands. The reset pin was wired to the header for this test (by default only the SWDIO and SWCLK pins were wired to the header), and the pin from SU8 was lifted to avoid driving the reset pin during these attempts.

For the QCA4531 I didn't find a test point with an easy “reset” pin. This is useful as holding the main QCA4531 chip in reset was needed during analysis of the SAMR21 without

removing it from the board. As the SAMR21 reset pin is driven by a buffer, it still required lifting the reset pin, as mentioned previously.

Instead, I determined there appeared to be a pin that when pulled low caused a reset to happen. This was found by probing with a 1K resistor to ground – this should be sufficiently strong to pull down a logic pin, but without shorting out other pins.

I don't know if the pin is actually reset or something else (a test pin, shutdown pin, etc) but it "did the trick". In particular, power consumption was much lower when this pin was held down, indicating processing was not occurring. This pin connection is shown below, the top part of this photo is near the edge of the PCB:



Considerable mechanical support is required here – the “pin” is actually a small amount of exposed metal, as the actual connection is underneath the chip. I couldn't find anywhere this pin connects to on the board which would have been an easier test point. Not shown in the photo is a large blob of glue placed over this connection, and the wire is wrapped around a hole in the PCB to give it more mechanical support.

BRIDGE DEVICE – FINDING SERIAL PORTS

Finding serial ports is again done with probing around using an oscilloscope to look for interesting traffic after a boot.

The serial port for the ZigBee SoC was discussed above, and the serial port for the main QCA4531 will be discussed below. Note the traffic on the ZigBee SoC took some time to happen after a reboot (~30 – 60 seconds), as the ZigBee SoC is held in reset by the QCA4531 until it fully boots up.

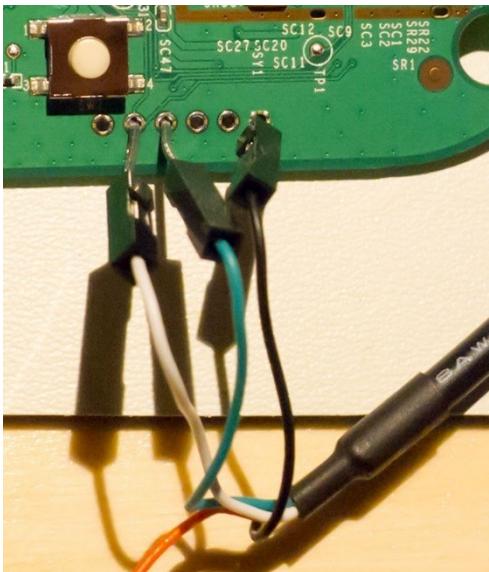
GETTING ROOT ON LINUX

Getting root on these devices can be accomplished with little effort, and I'll briefly describe the process. This allows you the capability of performing further hardware hacking attacks, as well as analyzing some of the binaries on the system.

First, we'll connect a serial console. For the serial cable (a standard 3.3V type one, DO NOT use a 5V cable), there is a 6-pin header along the bottom. Pin '1' has a square footprint, and counting from pin 1 the connections are:

- Pin 1 = GND
- Pin 4 = RX In (connect to TX Out of your serial cable)
- Pin 5 = TX Out (connect to RX in of your serial cable).

The following shows an example of using paper-clips to connect these cables up (to avoid soldering):



Next, confirm you see some boot output like the following:

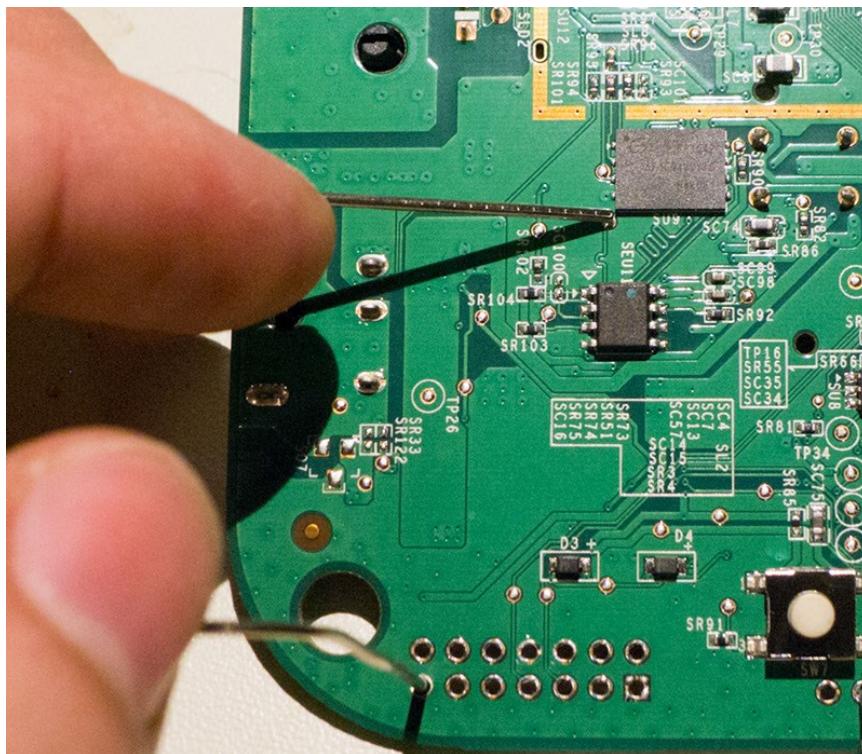
```
U-Boot 1.1.4 (Sep 8 2015 - 04:08:21)

bsb002 - Honey Bee 2.0DRAM:
sri
Honey Bee 2.0
ath_ddr_initial_config(195): (16bit) ddr2 init
tap = 0x00000003
Tap (low, high) = (0x8, 0x22)
Tap values = (0x15, 0x15, 0x15, 0x15)
64 MB
Top of RAM usable for U-Boot at: 84000000
Reserving 214k for U-Boot at: 83fc8000
...
```

What we need to do is short a test-point on the NAND SPI flash during the boot process. This must occur right after the following is printed to the serial port (roughly):

```
Net: ath_gmac_enet_initialize...
Fetching MAC Address from 0x83febe80
Fetching MAC Address from 0x83febe80
ath_gmac_enet_initialize: reset mask:c02200
Scorpion ---->S27 PHY*
S27 reg init
: cfg1 0x800c0000 cfg2 0x7114
eth0: 00:03:7f:11:20:ce
athrs27_phy_setup ATHR_PHY_CONTROL 4 :1000
athrs27_phy setup ATHR PHY SPEC STAUS 4 :10
```

Which occurs 1-3 seconds after power-on. The short is simply to use a paperclip or wire between the GND pin and the following test-point near the NAND FLASH chip:



This will cause the NAND chip to no longer be detected by u-boot, which should fall out to the console. At this point you can set a few environmental variables, and save them to the non-volatile memory:

```
ath> setenv bootdelay 3
ath> printenv security
***COPY THE DEFAULT VALUE THAT WAS PRINTED & SAVE THIS SOMEWHERE**
ath> setenv security '$5$wbgtEC1iF$ugIfQUoE7SNg4mplDI/7xdfLC7jXoMAkupeMsm10hY9'
ath> printenv security
security=$5$wbgtEC1iF$ugIfQUoE7SNg4mplDI/7xdfLC7jXoMAkupeMsm10hY9
ath> saveenv
ath> reset
```

The first one is simply making it possible to hit “enter” on the serial port during boot to fall into the bootloader menu. This means you only need to perform the NAND flash trick once, then not worry about doing it again, even if you want to modify other strings in the u-boot menu.

The second is writing a new root password. Before doing that you should save the old password. These are in the shadow-file format, and you can use ‘mkpasswd’ to generate your own.

The given example results in a root password of ‘toor’. Once the device resets, you should be able to log in with root/toor and receive a prompt. This will happen after the device fully boots, and you can press “enter” to receive the log-in prompt. You can see a video of this being performed at <https://www.youtube.com/watch?v=hi2D2MnwiGM> .

At this point, you’ll want to edit the file /etc/rc.local and add the following to enable telnet:

```
iptables -I INPUT -p tcp --dport 23 --syn -j ACCEPT  
telnetd
```

You may also want to add the /etc/rc.local to the /etc/sysupgrade.conf file to avoid it being overwritten in the future.

Before powering off the system, use the ‘halt’ command. This will cause data to be written to the flash memory (otherwise it may be lost). Use the halt command and then power-cycle the device to reset it. If you fail to do this the changes to rc.local might not be written to flash and the daemon won’t come up.

Once the system comes up again, you should be able to telnet in! You’ll need to know the IP address, which you can either get via the Hue App, or using ‘ifconfig’ on the serial console, or by checking your DHCP tables in your router.

You can also try pinging Philips-hue.local which should resolve to the IP address of your bridge (this won’t work on Windows 7 by default, but will on Linux / Mac OSX and perhaps Windows 10).

GETTING A MASTER SHELL

While the above trick is the best option for getting a useful root shell, I originally used u-boot to modify the ‘init’ argument of the kernel. This was done with the following:

```
setenv std_bootargs 'board=BSB002 console=ttyS0,115200 ubi.mtd=overlay  
rootfs=/dev/mtdblock:rootfs rootfstype=squashfs noinitrd  
init=/bin/sh';
```

Where the default would be:

```
setenv std_bootargs 'board=BSB002 console=ttyS0,115200 ubi.mtd=overlay  
rootfs=/dev/mtdblock:rootfs rootfstype=squashfs noinitrd  
init=/sbin/init';
```

By calling `/bin/sh`, the system falls into a root shell on boot. However it does not run the ‘init’ binary, which causes a lot of problems. In particular the filesystem remains read-only, and a number of entries are not populated (such as the `/proc` filesystem).

However the `/bin/sh` shell is powerful as it did not require me to know anything about how the ‘security’ envvar was used. Instead I determined later that it was being copied into the shadow file, and thus was the root password.

INTERESTING FILES AND NOTES

There are many interesting files available which can be further studied:

- The main function of the router seems to be held in a binary called ‘ipbridge’ at `/usr/sbin`. This seems to be the most likely location to find flaws. This binary appears to be everything from the webserver (including having the HTML pages encoded inside it) to handling ZigBee events to parsing requests.
- The ‘ipbridge_io’ in particular talks with the Zigbee SoC, meaning this binary in combination with ‘ipbridge’ could tell us:
 - What commands are used by the SoC (so we can use the SoC ourselves).
 - Are there any bugs allowing the SoC to send messages which cause problems, potentially allowing an attacker that was able to send some messages to the Linux system over the zigbee link to cause problems for the bridge?
- There is a file at `/home/swupdate/certs/enc.k`, which you can use “hexdump” to see contains 32-bytes of data. This file is referenced from `/usr/sbin/swupdate` as being the AES-256-CBC key used in decrypting certain binary blobs during the SW update process.

This key is constant across the two different Hue Bridges I looked at. This key, however, only decrypts some data store, that data store itself still has an encrypted firmware image for the Zigbee SoC inside it.

- The binary ‘zigbee_soc_updater’ at `/usr/sbin` which appears to handle the bootloading process for the SoC. This may have additional information about the blob format, as it seems to reference both a HwId and a KeyId being encoded in the binary blob.

```
root@Philips-hue:/usr/sbin# ./zigbee_soc_updater -f /lib/firmware/zigbee.sbl
ipbridge: [serial_linux.c,120,Console handle: 0]
ipbridge: [serial_linux.c,152,Pipe In handle: 4]
ipbridge: [serial_linux.c,160,Pipe In /tmp/ipbridgeio_in already exists]
ipbridge: [serial_linux.c,174,Pipe Out handle: 5]
ipbridge: [serial_linux.c,182,Pipe Out /tmp/ipbridgeio_out: 17 File exists]
ipbridge: [serial_linux.c,196,Pipe Out handle: 6]
ipbridge: [led_openwrt.c,145,No ledName for LED:1]
ipbridge: [main.c,290>Welcome to the ZigBee Soc Updater!]
ipbridge: [main.c,293,ZigBee Soc Update file: /lib/firmware/zigbee.sbl]
ipbridge: [main.c,125,Mode of operation: MODE_OF_OPERATION_UPDATE]
ipbridge: [zigbee_updater.c,113,Update ZigBee SoC]
ipbridge: [zigbee_updater.c,481,ZIGBEE_UPDATER_EnableBootloader]
ipbridge: [zigbee_updater.c,397,Trying to sync ZigBee SoC]
ipbridge: [zigbee_updater.c,144,Unable to read Hwid]
ipbridge: [zigbee_updater.c,481,ZIGBEE_UPDATER_EnableBootloader]
ipbridge: [zigbee_updater.c,397,Trying to sync ZigBee SoC]
ipbridge: [zigbee_updater.c,144,Unable to read Hwid]
ipbridge: [zigbee_updater.c,481,ZIGBEE_UPDATER_EnableBootloader]
ipbridge: [zigbee_updater.c,397,Trying to sync ZigBee SoC]
ipbridge: [zigbee_updater.c,144,Unable to read Hwid]
ipbridge: [zigbee_updater.c,481,ZIGBEE_UPDATER_EnableBootloader]
ipbridge: [zigbee_updater.c,397,Trying to sync ZigBee SoC]
ipbridge: [zigbee_updater.c,144,Unable to read Hwid]
ipbridge: [zigbee_updater.c,481,ZIGBEE_UPDATER_EnableBootloader]
ipbridge: [zigbee_updater.c,397,Trying to sync ZigBee SoC]
ipbridge: [zigbee_updater.c,144,Unable to read Hwid]
ipbridge: [main.c,339,ZigBee SOC update failed!]
root@Philips-hue:/usr/sbin#
```

- The zigbee SoC firmware files themselves seem to be placed at /lib/firmware – again these are the encrypted SBL files, so this isn't a huge attack.
- Looking at two different devices, they appeared to have different root passwords. I've been told devices have unique root passwords per device, which is a **definite win** security-wise.

FIRMWARE UPDATE – NETWORK PERSPECTIVE

One of the first things I did was sniff the network traffic while performing a firmware update. This revealed a single binary blob was downloaded, called `bsb002_image_01032318.fw2`. This file once again appears to be encrypted, and unlike last time was not simply split into two files, where one is sent to the Zigbee SoC directly. None of the sequences sent to the SoC over the serial port appeared in this binary file at all.

Having now looked at the `swupdate` binary, it's clear this is because the encrypted Zigbee SoC firmware file is further encrypted inside the update image. The update image does have a signature present, and presumably, this is checked by the Bridge itself to avoid loading unsigned binaries. The combination of encryption & signing should stop an attacker from forcing someone to load a malicious binary.

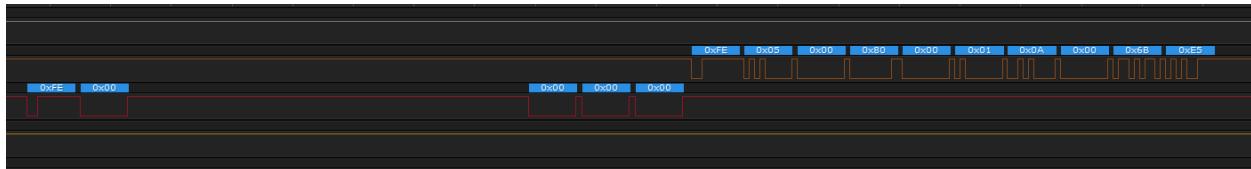
Unfortunately, as the encryption key used for the binary blob can be discovered easily, and appears to be consistent across bridge devices, the encryption adds little to the data security. This shouldn't affect the signing operation, however, as the security of the signing operation is dependent on the private key held by Philips in a secure location.

FIRMWARE UPDATE - SAMR21E18A BOOTLOADER

Interestingly, the SAMR21E18A appears to use the same bootloader as the CC2530 device. Presumably Philips is trying to keep a minimum amount of variation between versions. In the following figures data sent TO the SAMR21E18A is on the lower line.

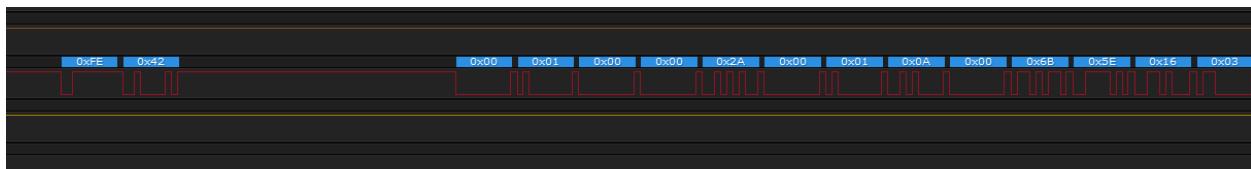
We can see the sign-on command of `FE 00 00 00 00` is answered with `FE 05 00 80 00 01 0A 00 6B E5`. You'll notice the spacing of the sent commands is "odd" – my assumption is this is related to the fact traffic is passing down the USB stack and through a USB-serial

converter. So for example on the Linux side they are calling a send() command with first 2 bytes, and then 3 bytes. This gets split into separate USB transactions which adds some delay:



There appears to be no pin bootstrap required, as was for the CC2530. Sending the sign-on command seems to result in the response without any pin changes after reset.

Data is sent using the same format – FE 42 00 01 is a header, followed by two bytes of LSB, MSB packet number information, followed by 64 bytes of data, and a final FCS:

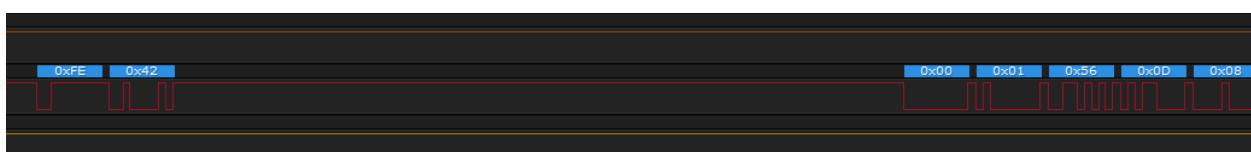


The FCS is an XOR of all bytes starting at the length (i.e., NOT including the FE byte) until the last byte of the payload.

If the package is accepted, the SAMR21E18A will respond with FE 01 00 81 00 80.



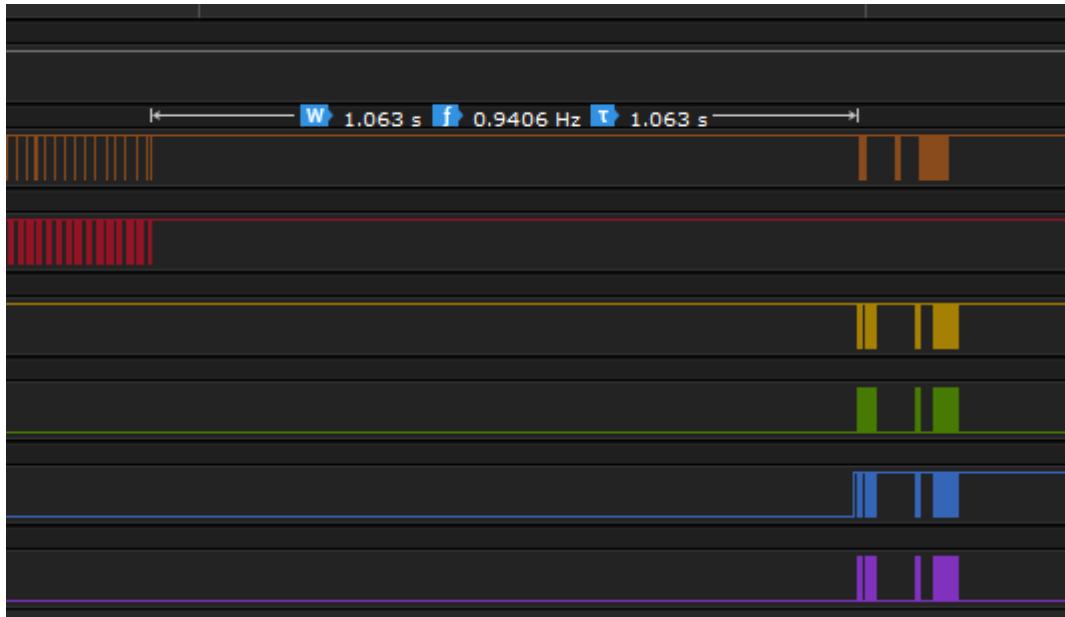
Once the final packet is written (number D56, shown here):



We can write FE 00 00 03 03 which starts the programmed image:



After sending the start command, there is almost a 1-second delay before anything happens, shown below.:



This suggests that further processing may be occurring – the 18A has 256K of FLASH memory, which would be insufficient to be using half of it for temporarily storing the image (the image has approx. a 218 496 byte size, assuming that the encrypted image is the same size as the decrypted image).

Instead, this delay may be verification of a signature, or it's possible the decryption doesn't happen until this time. Some possible answers can be found using power analysis of the bootloader.

The lower 4 lines in the image showing the delay after receiving the go command are SPI pins. This traffic is consistent with a standard start-up, and an insignificant amount of data is read/written from SPI. I assume the SPI flash is completely unused for boot loading purposes.

In my analysis, sending valid but unexpected data (i.e., random payloads but with correct FCS and address) sometimes resulted in the bootloader giving an invalid response (i.e., responded with something other than FE 01 00 81 00 80).

There is assumed to be some underlying structure in the Zigbee SoC file. Further analysis of the zigbee_soc_updater file is needed to see if this can easily be discovered. For example, there are numerous references to a “HwId” being encoded in the file (as the zigbee_soc_updated checks the update file matches the version the hardware reports), and there is a reference to a KeyID as well.

Looking back at the response to the sign-on command, we see it has a reported payload length of 5. This suggests the payload is then 00 01 0A 00 6B. We find these same bytes as part of the header of the encrypted file:

00000000	2A 00 01 0A 00 6B 5E 16 03 20 16 24 43 03 55 80	*
00000010	E1 10 48 0E C5 AE 15 EF 1E 84 5C 7F 71 00 71 27	á
00000020	23 4D F6 4C 09 38 6D F6 3A F7 6B 1D 6F 14 7D 66	#
00000030	E5 0A 97 0A 9B 41 AD 3D 6B 00 58 E2 C6 5D 92 20	à
00000040	00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00	=

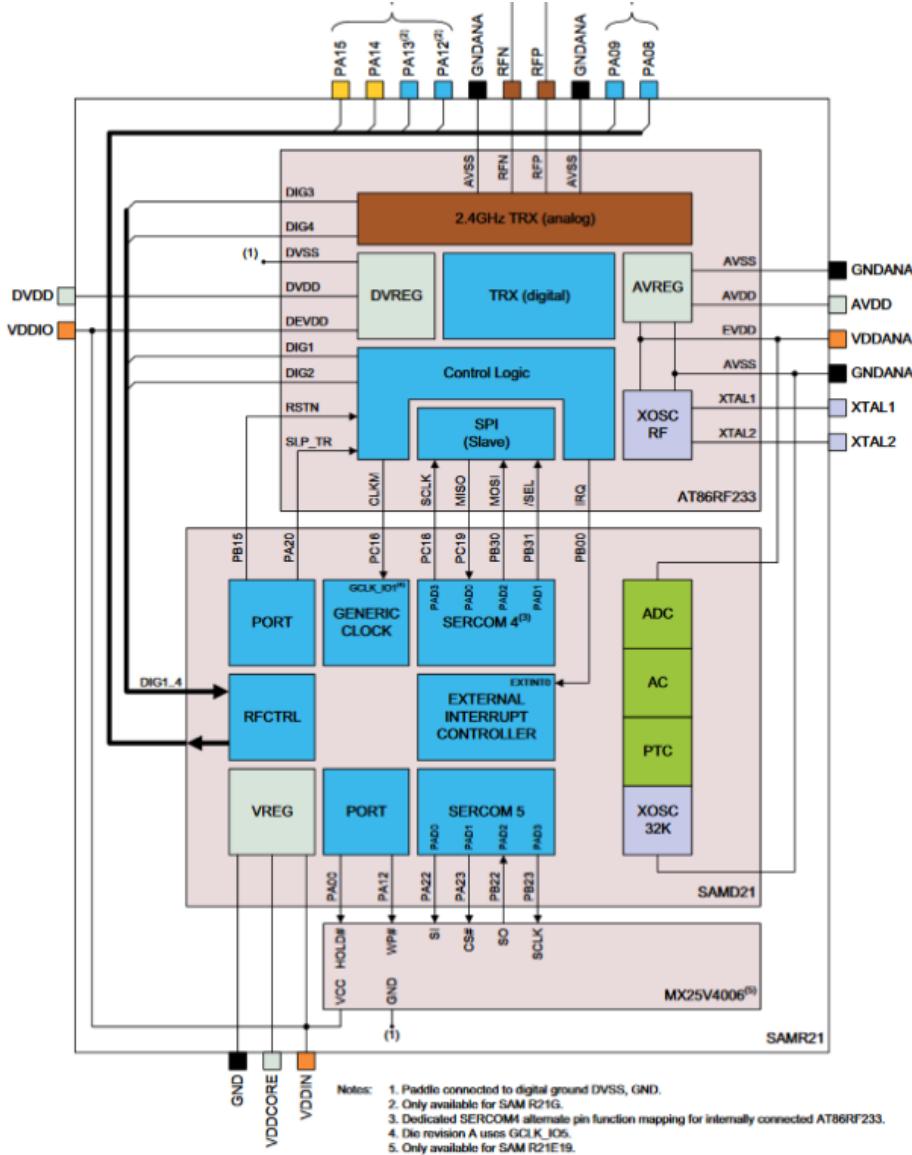
This suggests that the sign-on command is providing information which is matched to the SoC firmware file. Unraveling the firmware update file is useful to determine where exactly the encryption is happening, as it then allows us to inject more useful packets (which forms the basis of an attack such as at http://wiki.newae.com/Tutorial_A5_Breaking_AES-256_Bootloader).

The AES accelerator on the SAMR21E18A is much simpler, and in fact the AES hardware accelerator (which is part of the AT86RF233) I suspect to be breakable, since it's likely the same peripheral used in the ATMega128RFA1 (which can be attacked, as I showed at <https://eprint.iacr.org/2015/529.pdf>). This means that side-channel power analysis on the SAMR21E18A may be more successful than on the CC2530.

These measurements were taken from the VDDCORE power supply, by inserting a resistor in-line with the VDDCORE pin and adding an external ~1.95V power supply. This power supply is designed to cause the internal 1.8V regulator to shut down, as it reduces the noise on the measurement using an external supply.

Of interest I also took measurements of the VDD power supply, which is internally used by the RF233 core which has the AES peripheral. There appeared to be no unique power signatures beyond some spikes due to USART traffic. This would suggest that either (a) software encryption is being used, or (b) the power signature is much different than expected.

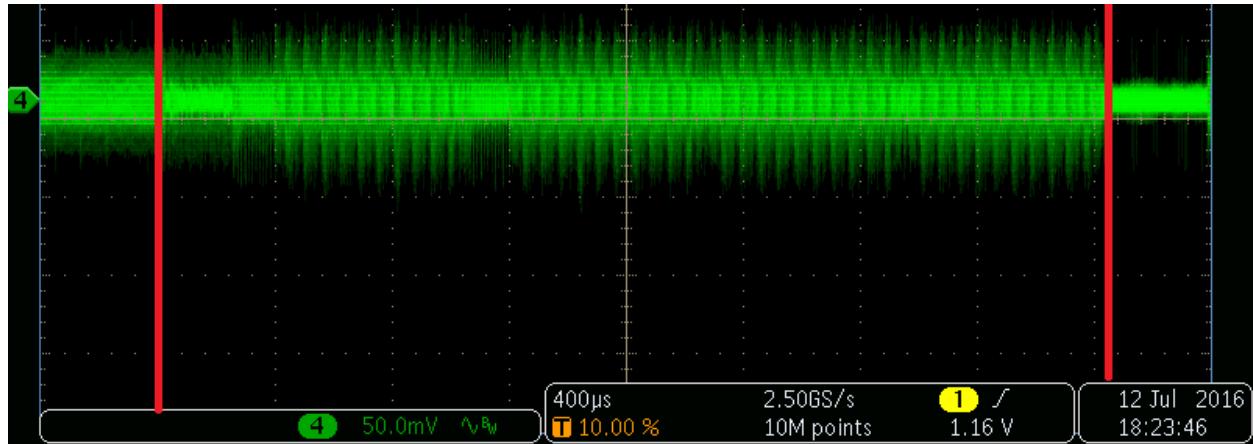
The setup of the SAMR21E18A is slightly odd, that makes a software implementation more likely, even though it contains an AES hardware accelerator. The SAMR21E18A chip internally has a separate microcontroller + an AR86RF233 die connected via SPI:



This means using the AES accelerator has performance limits, since you need to transfer data to/from it via SPI first. In addition, the AES accelerator only supports a limited number of modes (AES-ECB, and AES-CBC encryption) since they are the only ones required by IEEE 802.15.4. It may have been easier to use a software implementation to support the mode required by the bootloader.

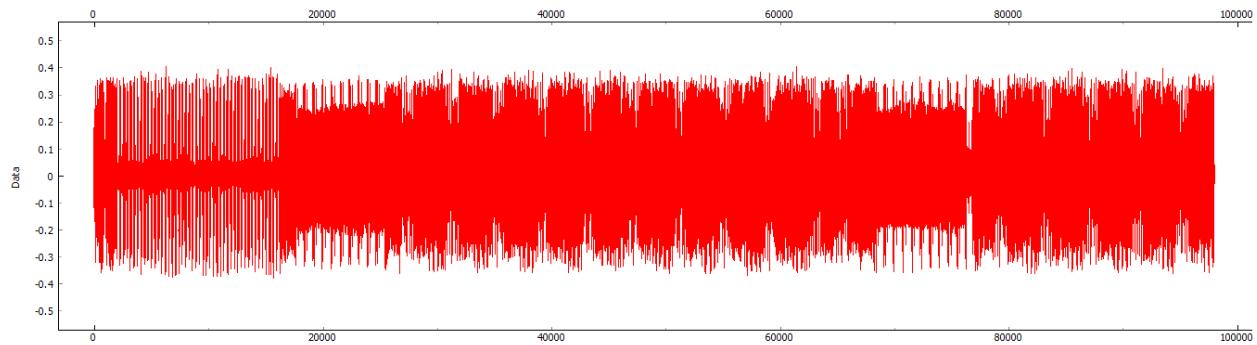
It's also possible that (a) the algorithm is not AES-128, or (b) the actual decryption occurs during that 1-second delay. The latter seems somewhat unlikely as the page write time alone is 2.5 mS, and with 64-byte pages this means the firmware update spans 3400 pages. This would take much longer than 1s to write if so – I think instead it's verifying the complete firmware image, and only if a signature matches does it flag the image as valid.

Looking at the power signature after the first 64-byte packet is sent is as follows, where the red bar on the left indicates the end of the TX serial data, and the red bar on the right indicates the start of the RX serial data:



Several interesting features are allowed. There is various processing that appears to occur, as well as around 4 “groups” of 10 peaks. This 10-peak group may be some form of encryption (i.e., AES-128 which has ten rounds?).

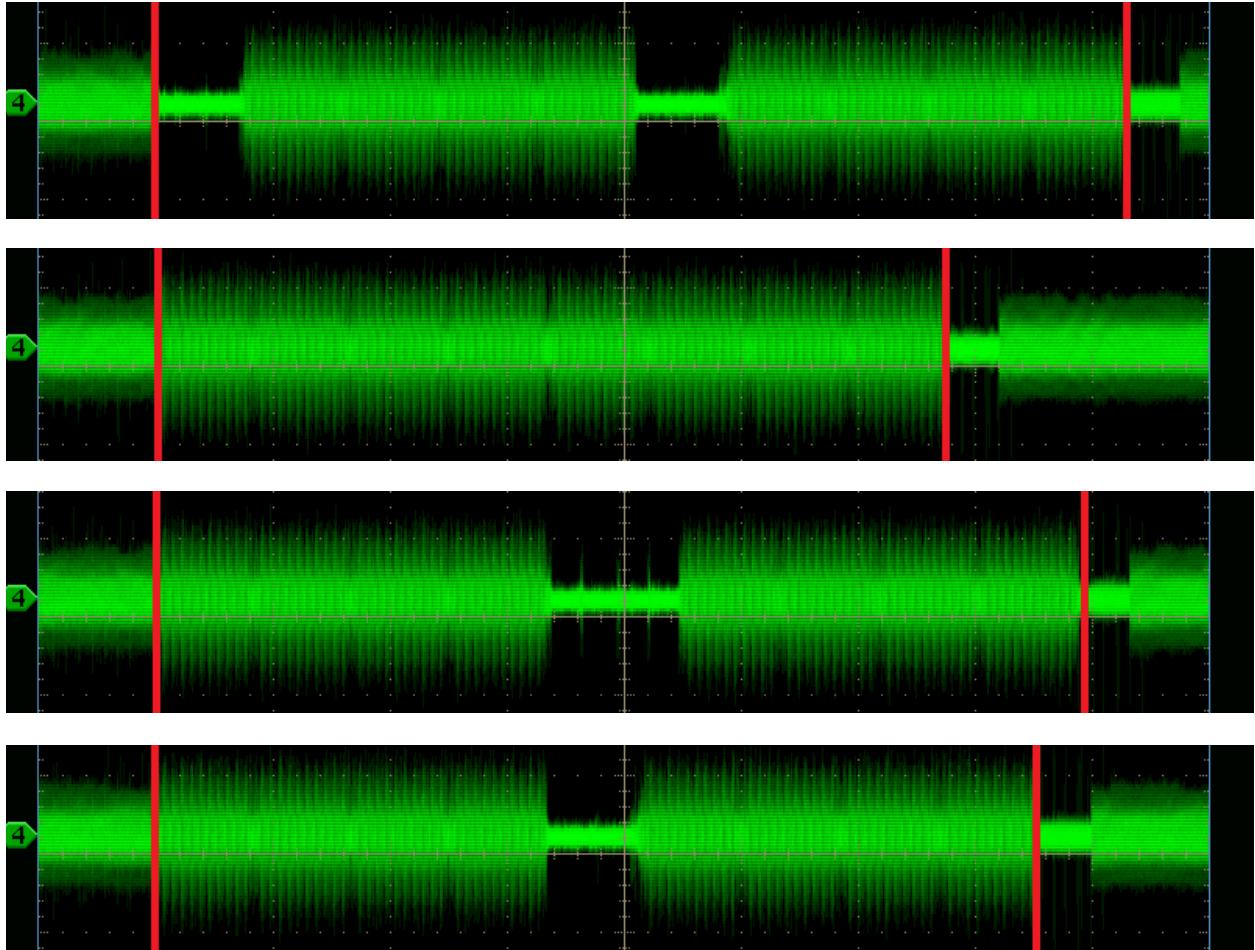
We can get a slightly more reliable signal using the ChipWhisperer capture instead – this concentrates on the first 3.5 divisions in the above image. We can see the 10-round sequence at sample points approximately 2800 to 6500, and starting to repeat again around 78000:



Again the processing is very clear here, although the specific algorithm is still unknown.

The following figures have a time scale of 800uS/div (note this covers 2x as much time as the above scale).

After Packet #2, #3, #4, #5 respectively:



The processing seems to be done in two groups (each group is assumed to be 64) bytes. It's possible the variable delay between them is due to a page write and/or part of a row erase finishing.

A brief test for AES-128 leakage was unsuccessful, but more time may be needed to determine this. In addition this test would only work for AES-128 decryption in CBC mode. Knowing more about the type of the firmware encryption would be useful in concentrating this attack.

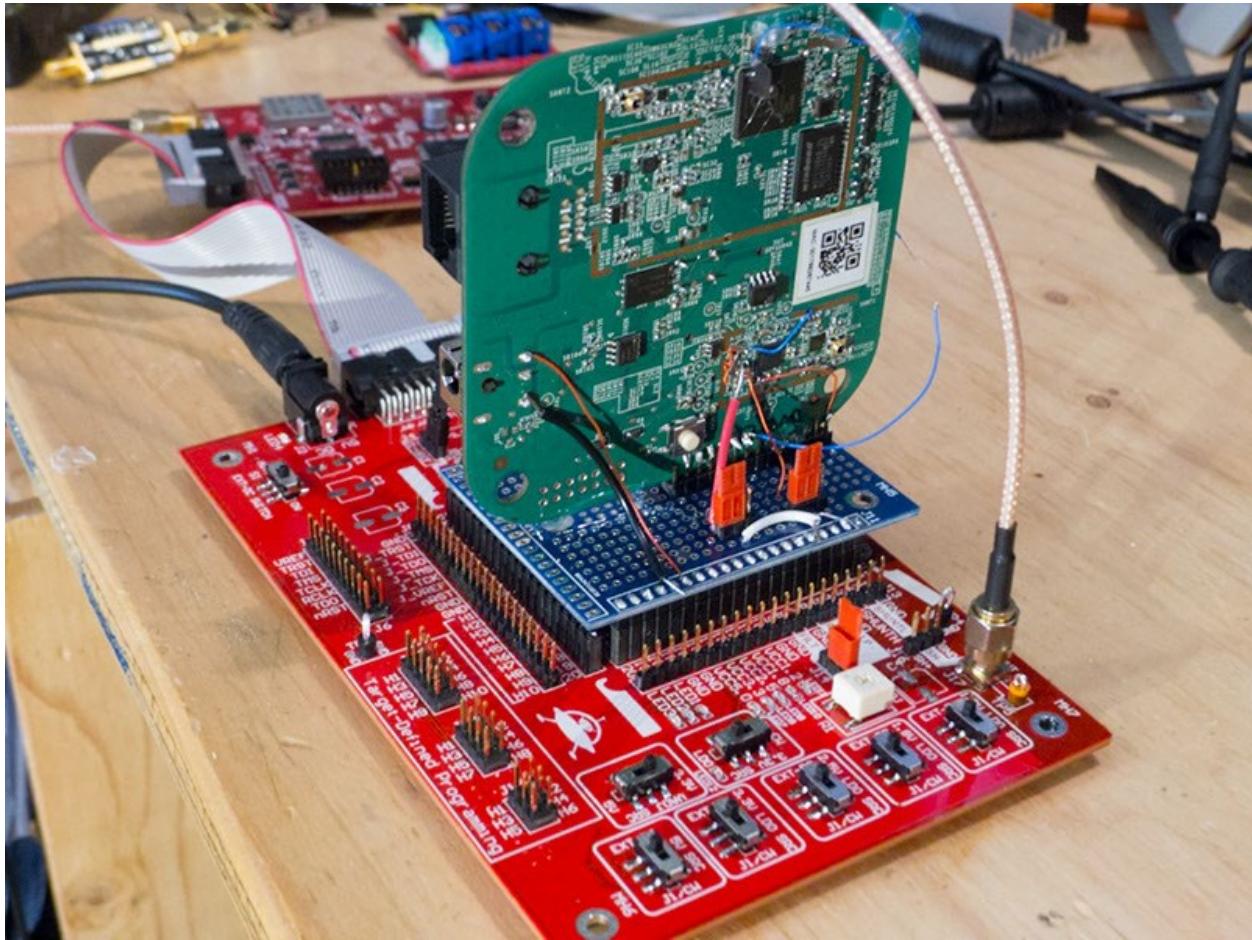
It's possible the first group is decrypting the firmware, and the next group is calculating some signature using the same algorithm (but with a different key).

It would also be useful to characterize the leakage on the SAMR21E18A device, for example loading a test program that performs a row erase & page write to see if this provide unique

signatures. If these could be matched to the above images, it would give a better idea about the bootloader process.

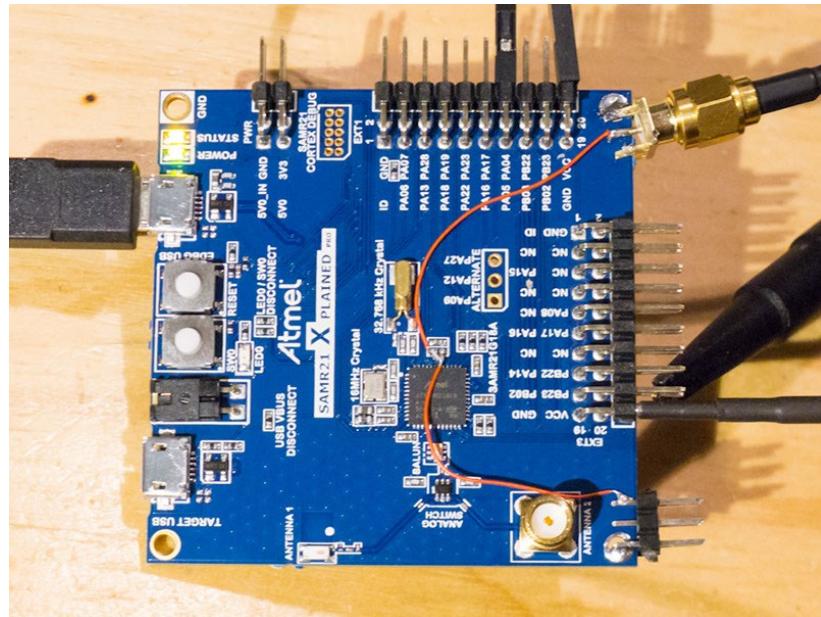
But it can be seen that a suitable power signature can be recorded from the bootloader on the SAMR21E18A device. More work is required to determine what protection against power analysis might be built into this bootloader.

For these examples, a generic target board was used which had the main bridge board mounted onto it:



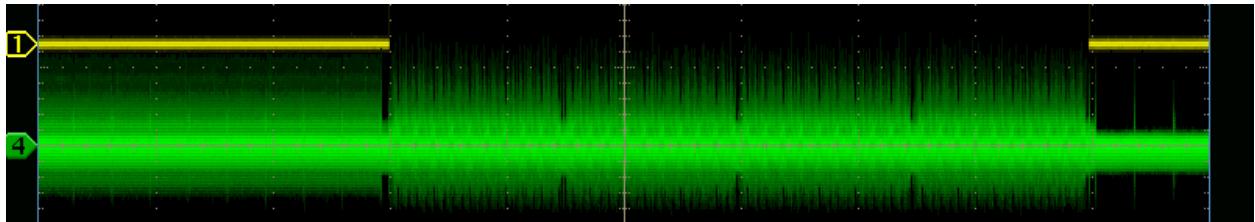
The CLK-IN point shown earlier was driven via a 1K resistor. This resistor caused the crystal on the board to become phase-locked with an external clock. If performing clock glitching, the crystal on the board would be removed and the clock input would be driven with a stronger source.

For testing the above waveforms with expected programs on a SAMR21E18A, an Atmel SAMR21 Xplained Pro board was used, which was instrumented in a similar fashion to allow measurements on the VDDCORE supply:

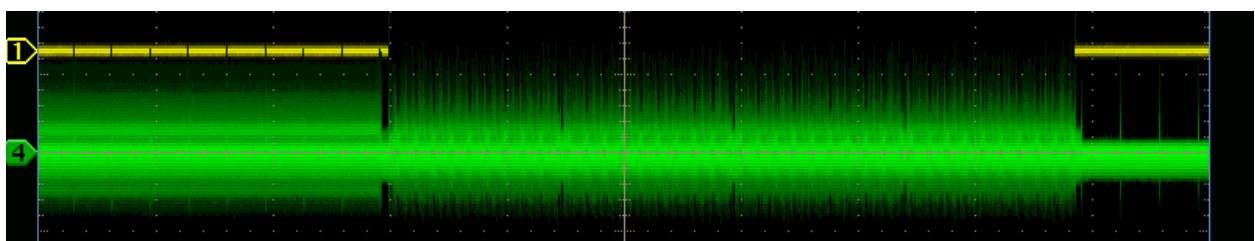


Running the Atmel-provided AES examples (which are included in the examples under the SAMD21 Xplained Pro board, and can be copied over to this board easily) gives some idea of the expected power signatures when decrypting 64-bytes of data using different AES modes:

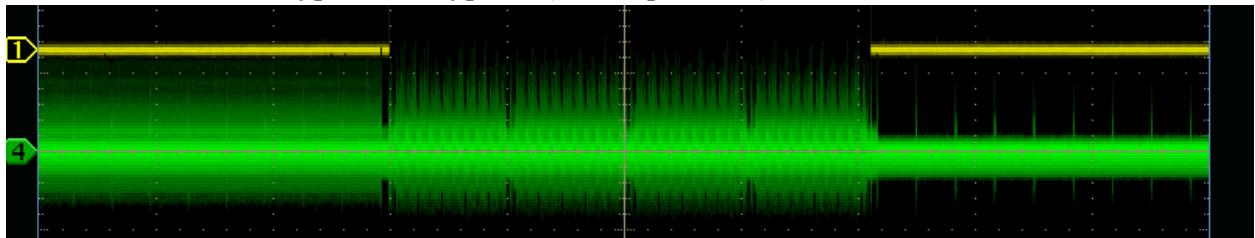
AES-128 in ECB Decryption:



AES-128 in CBC Decryption:



AES-128 in CTR encryption/decryption (same operation):



Visual inspection reveals a very close match to the observed waveforms, in particular for the AES-CTR mode. Using AES-CTR mode is another good security practice that complicates a basic side-channel analysis attack.

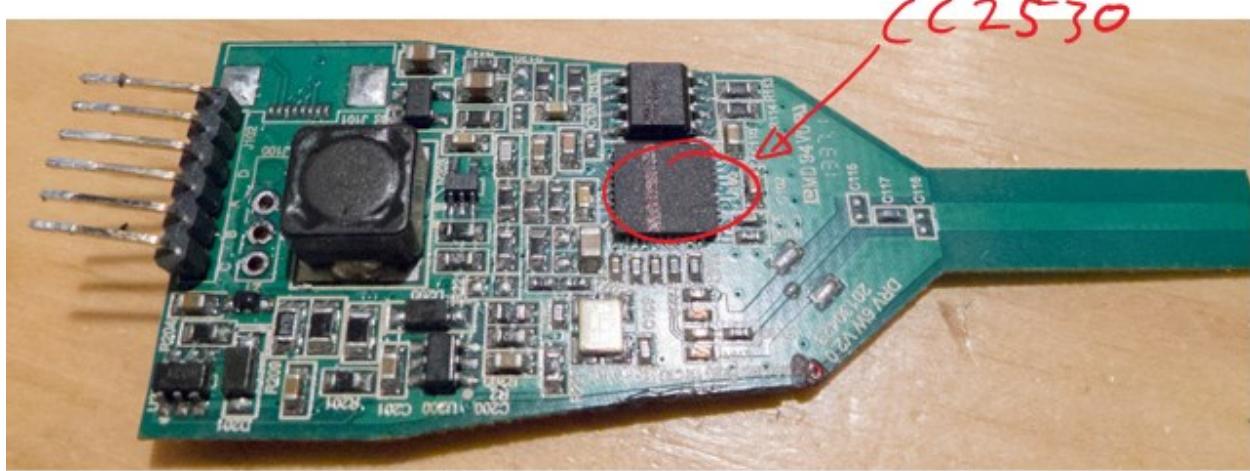
Performing an attack against AES-CTR mode requires some additional work (detailed in <https://www.iacr.org/archive/ches2007/47270001/47270001.pdf>) but still remains possible, and as can be seen here further work may reveal the keying material used for the ZigBee SoC firmware update.

6 COLOR BR30 BULBS

The color BR30 bulbs are an older design, and of particular interest as they are the only ones as of this whitepaper that have an over-the-air (OTA) firmware update. This means it is possible to learn a little about the bootloading process here. A photo of the light (being cut open) is shown below:

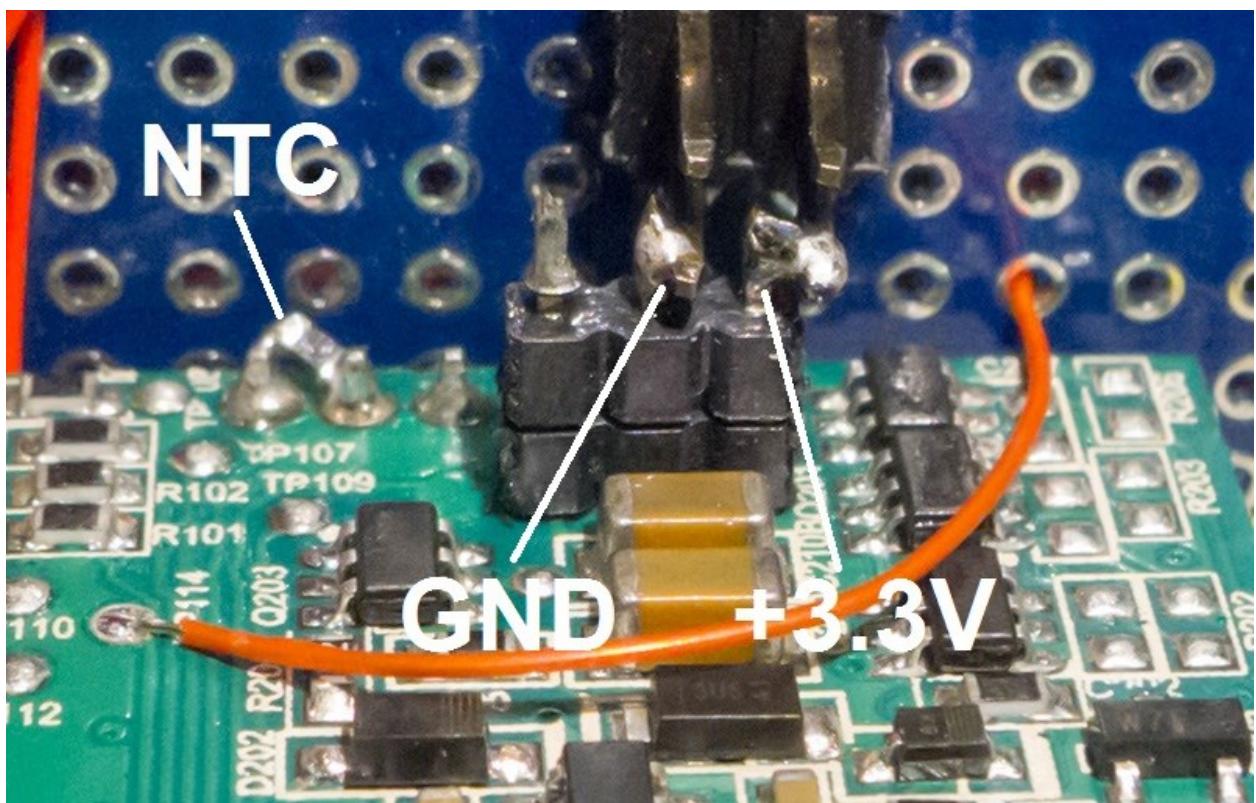


Inside this device, there is a CC2530 (same as on the Bridge V1.0) as shown below:



Using the bulb board outside of the bulb requires two small PCB modifications:

- 1) There is a temperature sensor (small surface-mount part) on the LED board, which is soldered onto the 6-pin header. If this sensor is not soldered, the board will shut down as it believes it is in an over-temperature situation (referred to as NTC in the below figure).
- 2) Power is applied (+3.3V) via the 3-pin header. Both of these are shown below:



There is again a serial port accessible at TP114. This allows monitoring of messages from the CC2530 device, and uses the same basic protocol as previously discussed.

FIRMWARE UPDATE INFORMATION

The firmware updates are downloaded Over The Air (OTA). The firmware file itself can be downloaded from a fixed URL, and contains an encrypted firmware file (similar to the firmware update for the CC2530 device).

The firmware update has the filename `ConnectedLamp-Target_0012_13452_8D.sbl-ota`. This data is transmitted over the air, and written into the SPI flash on the BR30 bulb.

On start-up, the CC2530 checks this SPI flash. It appears that byte at address 0x0004 acts as a flag – if programmed to value 0xFF it causes the device to bootload. This is useful as it can be used in trying to load new firmware files without needing to perform an OTA update (which takes a fair amount of time to download the new file).

The start of the SPI flash in the BR30 is shown here. Note it starts “SBL1”, again finding reference to the ‘Serial Boot Loader’ from TI.

File Disk Edit View Structures Crypto Macro Help									
00000000	53	42	4C	31	FF	FF	FF	FF	FF
00000010	FF								
00000020	FF								
00000030	FF								
00000040	FF								
00000050	FF								
00000060	FF								
00000070	FF								
00000080	FF								
00000090	FF								

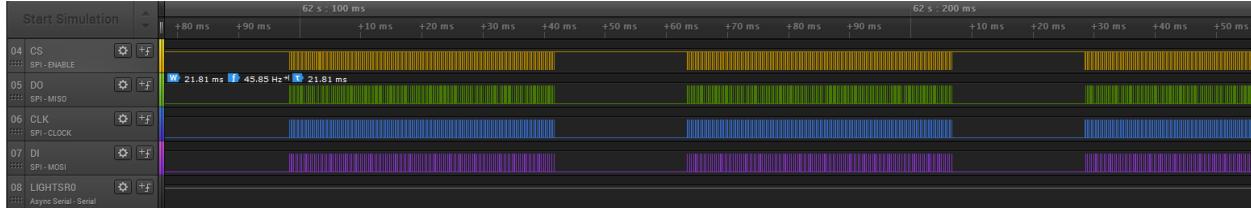
The bootloader reads through the flash twice. The first time is verifying the signature (to confirm a valid file is available), the second time it actually does the programming.

This is done to avoid discovering *after* programming that the signature is invalid, which would leave the light bricked. The bulb is assumed to also verify the signature of the data once written into the internal flash memory before becoming active.

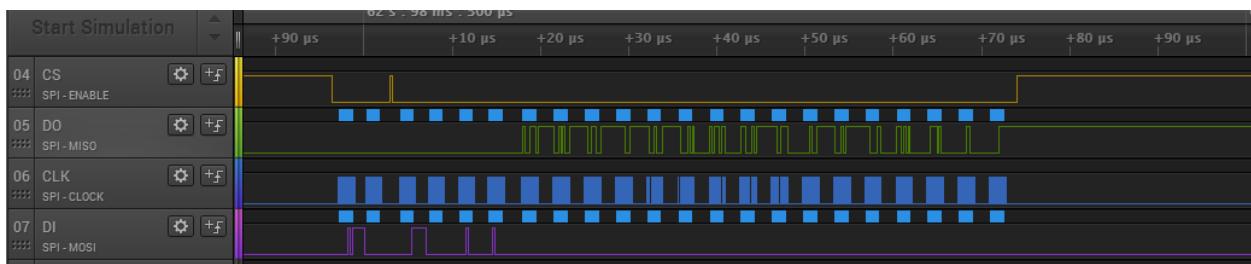
We can see the first run-through is done as a straight pass:



Notice the second pass (starting around 62s) has some “gaps.” These gaps are highlighted here:



These gaps are the page erase being performed. This is how we know the actual write is occurring at this time. Zooming in within one block, we see that 16 bytes are read from the SPI flash at a time:



This would again suggest that perhaps AES-128 is being used to encrypt the firmware file. This would agree with the existence of an AES-128 hardware module inside the CC2530.

We can use the previous “erase flash but read SRAM” bug to dig a little more. To do this, we need a more fine-grained control of the erase process. To start with, we consider what is in the SPI flash, as shown here:

First block sent

000780:	FF														
000790:	FF														
0007A0:	FF														
0007B0:	FF														
0007C0:	2A	00	01	00	00	66	52	14	10	02	17	30	39	03	EF	40 *....FR...09..@
0007D0:	2E	37	00	25	EC	C0	47	65	CB	E1	1E	0E	74	F7	A1	14 .7.%..Ge....t...
0007E0:	EE	6B	58	85	2F	F3	00	83	68	12	67	71	4C	7A	75	20 .kX.../...h.gqLzu
0007F0:	4D	00	E0	74	95	54	CE	AB	23	72	2B	80	AB	46	46	CD M..t.T..#r+..FF.
000800:	77	CF	AC	2E	8C	58	9E	75	8C	1D	77	43	D5	A2	28	5c w....X.u..wC..(\`
000810:	4E	94	CC	F9	C8	C5	5B	62	E7	09	88	E3	6A	3A	0C	07 N.....[b...j:..
000820:	86	27	80	7A	76	91	90	AA	1E	8F	40	FD	35	96	CC	C0 ..'..zu....@.5...
000830:	BF	53	2D	F0	88	7E	28	ED	F3	B7	96	AF	65	8C	8A	1D .S-..~(..e....
000840:	D6	8B	07	49	EE	8C	B7	49	54	D9	D9	62	94	62	65	0C ...I...IT..b.be..
000850:	99	E4	BB	4A	CE	17	26	28	A8	FF	F3	4C	48	45	B0	A0 ...J...&(...LHE..
000860:	2E	29	30	2A	4E	1D	40	42	C3	8A	9D	E0	D6	6E	47	98 .)=*N@B....nG.
000870:	D3	42	47	CF	29	EC	BC	88	CB	FB	35	15	CD	DB	8A	FE .BG.).....5.....

The “2A”... is the actual OTA firmware file, the same as downloaded from the URL.

SIDE-TRACK: BRIDGE 1.0 SERIAL PORT

In addition we can look back to the Bridge 1.0 serial port, and see where the encrypted firmware file is sent over the serial port to the Zigbee SoC.

The following is part of the log of data sent from the STM32 to the Zigbee SoC:

Colin O'Flynn

```
[Zcl,S,S=0x0004.11,768,0071000100004002400300040007000800,64]  
[Zcl,S,S=0x0004.11,25,1902059700000000000000000000009001,64]  
[Zcl,S,S=0x0004.11,25,190305000b1000018c340042000000002b1ef1ee0b000138  
0000000b1000018c340042020000000000000000000000000000000000000000000000  
00,64]  
[Zcl,S,S=0x0004.11,25,190405000b1000018c3400422b0000002b00000000000000000000  
0000b8ef03002a00010000665214100217303903ef402e370b25ecc04765cbe11e0e74  
f7,64]  
[Zcl,S,S=0x0002.11,6,0072000000,64]  
[Zcl,S,S=0x0004.11,25,190505000b1000018c340042560000002ba114ee6b58b52f  
f30d83681267714c7a75204d08e0749554ceab23722b80ab4646cd77cfac2e8c589e75  
8c,64]
```

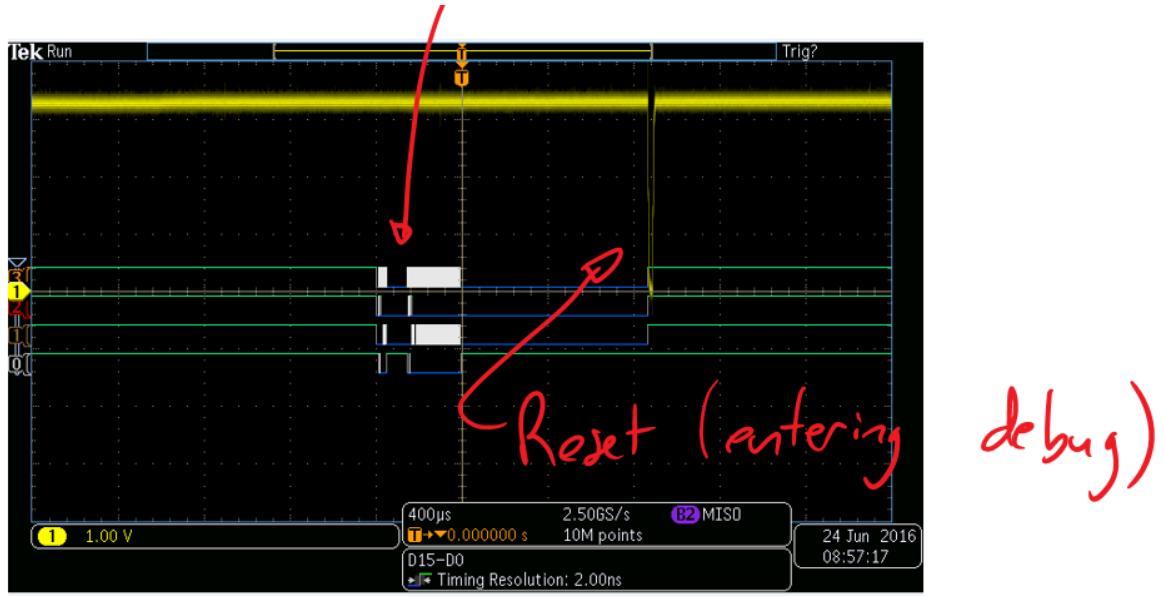
The data in red (starting 2a...) can be seen to lie at SPI flash hex address 7C0 to 7DD. The next group in green can be seen to be the data from 7DE to 808. The encrypted firmware data is sent as-is over the serial port, which transmits them as ZLL messages. The ZLL messages if inspected in wireshark will be encrypted by the (unknown) link key.

We now return back to the SRAM dump attack.

DUMPING SRAM

To perform the SRAM dump, it requires a special firmware which enters debug based on an external trigger. In this case an oscilloscope was used to generate a trigger based on SPI data, which corresponds to a certain part of the SPI flash being read.

Once this data is read out, the debug mode is entered. Debug mode halts the CPU, and allows us to perform the chip erase and then read the SRAM out. The following shows the timing of the SPI data with the reset pulse:



A delay has been added from the SPI data to the debug mode to allow time for processing to occur. The following shows some annotations on the dumped SRAM memory after the first 16 bytes were read from the SPI flash:

00000000	A7 7B 8B 33 11 A4 C9 33 84 A2 DE 32 5C DA E4 B0
00000010	EA 67 DE CF DF 6B 06 5E EF 41 2F 9E BE 7F 66 AE
00000020	A7 FA CB BB F6 FA B0 3C 17 FB 34 F9 9B F4 90 FB
00000030	EE FF FD 77 8F F3 7B 76 DF 9E 79 63 84 EB FA B3
00000040	F9 6D C5 F6 F0 5B EF 00 00 FF 00 00 7D 01 B9 EF
00000050	66 00 D9 E7 00 00 0E 0E 00 78 03 FF FA E6 00 30
00000060	F0 0E C4 1C 00 4C F8 07 E6 00 30 F0 0E C4 1C 46
00000070	F8 DE FA 9B BE 00 8C FA 00 6E EF C2 EF A5 00 E6
00000080	07 2A 00 01 00 00 66 52 14 10 02 17 30 39 03 FF
00000090	40 3C 49 A6 E7 2D 6E 2D B8 D4 48 DD 37 B3 10 1F
000000A0	9C 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
000000B0	00 00 00 00 00 00 2A B0 01 00 00 66 52
000000C0	14 10 02 17 30 39 03 EF 40 2E 37 0B 25 EC C0 47
000000D0	65 CB E1 1E 0E 74 F7 A1 14 EE 6B 58 B5 2F F3 0D
000000E0	33 68 12 67 71 4C 7A 75 20 40 00 E0 74 95 54 CE
000000F0	AB 23 72 2B 80 AB 46 46 CD F4 3E 66 00 53 42 4C
00000100	11 FF 00 00 00 00 E8 FB 01 02 03 01 09 5E B5
00000110	A9 00 FE F8 BF 6B FB 79 F5 1F 89 8F B5 F9 E2 7E
00000120	F3 CD 44 5D 3B B9 FB 1B FA 60 DD FF DF 1F 72 FE
00000130	17 99 3A 97 DE FF 4E 33 78 7D 06 DE C7 71 AD DF
00000140	CE BE B2 EB 4C D4 CE 05 0E BD BB 6C BD 23 D4 BF
00000150	1D 75 BE F5 E6 FF 95 BB DD C3 BD 11 DF F0 DF 88
00000160	8E 89 7F FD 51 11 E7 DA 7E 7C AC 4B D4 AF 7D 5C
00000170	74 CD A9 EE DF 29 C7 BB 8D B8 EF BB FE D1 BD F3
00000180	A5 F9 5C 57 A6 B4 96 FF B0 7F BD 7E D1 7F AA 4F
00000190	F6 FF FE 3D 6F FB A9 F7 F4 0F 6E 7D 66 E2 FB C5
000001A0	EB 9E FF TF F6 B1 3D 0F BA 3C 5E 6F CA 65 4D CB
000001B0	B1 8F FD F8 FB 4F F7 A3 F9 0F ED 38 FD 55 D1 ED
000001C0	53 1B 87 9D 92 AE DF 95 F2 BB 54 1E DB 28 7B 5D
000001D0	FB EC EB AF D6 2E E1 63 BD B3 37 D3 AE 83 FB B2
000001E0	76 3D 3D CB 31 BF DA 15 67 E7 6E DF EB 7F 4D 5C
000001F0	4C 7F 28 F7 4F DE 25 91 FF 2A E5 03 7E ED D7 77
00000200	01 C7 B8 DC DA B7 AF 7C 2F 6A B5 F9 31 62 14 FC

We can easily see where the RX buffer is located. There is not a clear TX buffer however, making the glitch attack more difficult. This is likely due to the fact the SPI bootloader may use "hard-coded" calls to the transmit function per byte.

Performing this attack erases the bulb, making it useless. Thus it's desired to avoid performing this attack often due to the cost of the BR30 bulbs.

A write/erase second attack should be performed during the “decryption” phase of the algorithm. While the SRAM dump above has clear information of interest, we may find more by looking at a SRAM dump during the decryption phase and not the signature verification phase.

At this stage I've run out of working BR30 bulbs, and due to the relatively high cost of them decided to look into other areas.

7 LOW-COST WHITE BULBS

The newer white bulbs are available at very low cost (\$15 CAD!). They make an interesting development platform due to the very low cost.

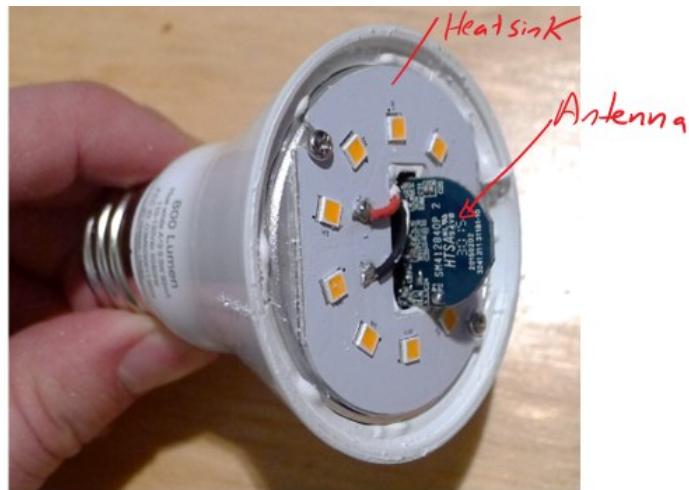
The low-cost white bulbs are shown here:



The top part can be taken off by cutting around the seal:

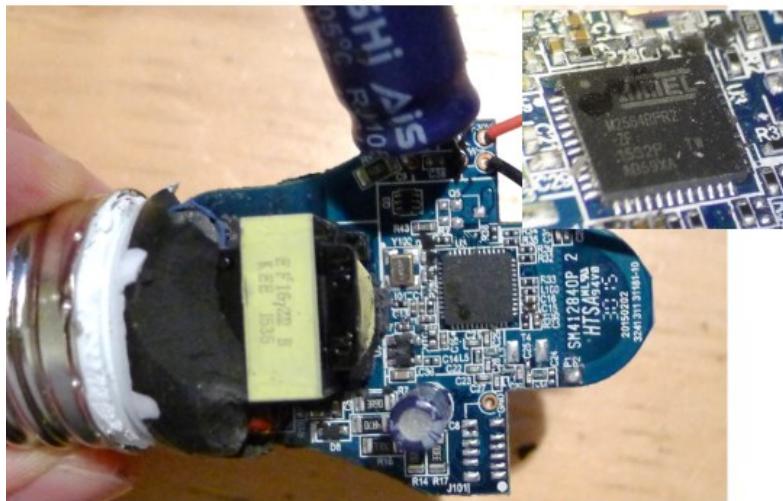
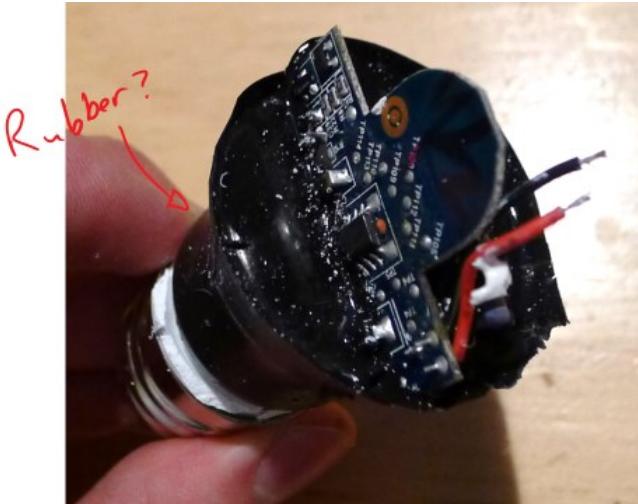


The bulb being taken apart is shown in the following photos:



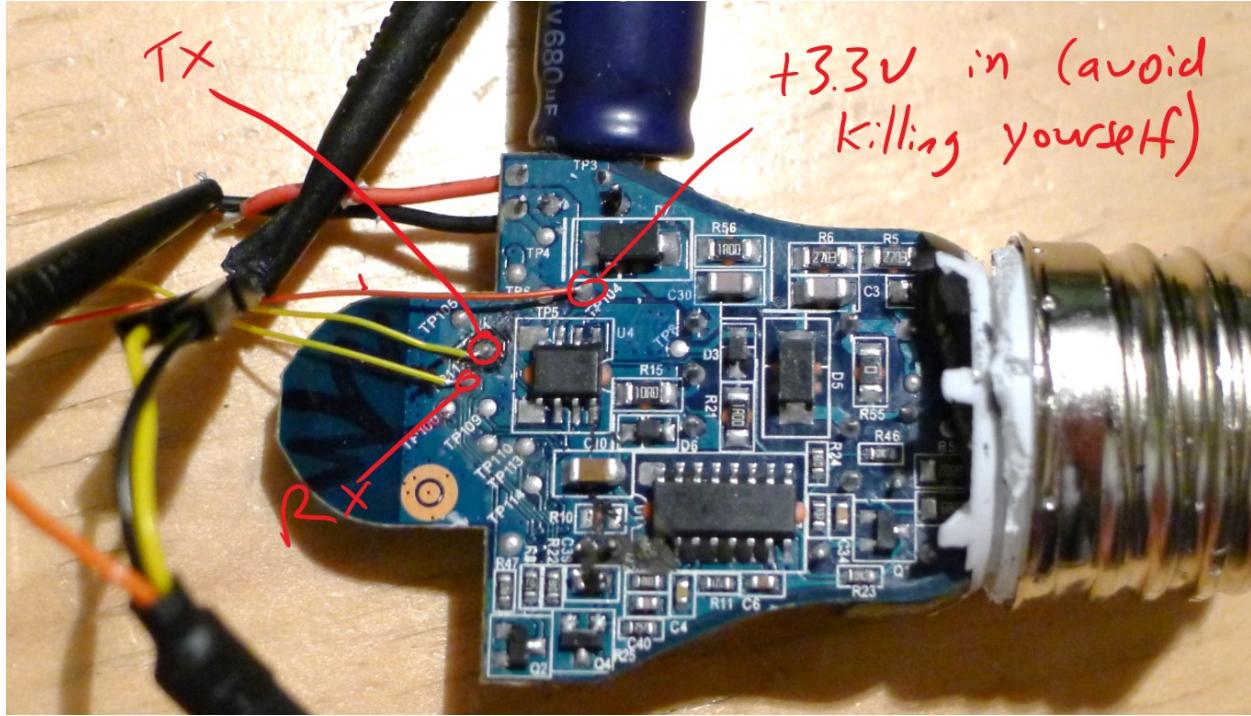
Removing the top heatsink requires careful scrapping of the silicon sealant, along with removing the very tight fit of the top metal plate. Unfortunately, the test points cannot be easily accessed without removing this plate.

Further taking apart the device by stripping the outside case shows a potting compound of some sort:



The core processor is an Atmel ATmega2564RFR2. The test points present allow JTAG programming of this device (detailed later).

The bulb can again be powered up using an external 3.3V supply. There is both a TX and RX available – this uses the same sort of format as the rest of the serial ports within the Hue system(s). The RX is pin TP112, and TX is TP111.



Looking at the strings printed on start-up, we can see the lock bits are set correctly. The following shows the start-up message printed over the serial port (my emphasis added):

```
[Log, Info, ConnectedLamp, MCUCR=0x00, LockBits=0xFC, LowFuse=0xF6, HighFuse=0x9A, ExtFuse=0xFE]
[Log, Info, ConnectedLamp, devsig=0x1EA803]
[Log, Info, S_DeviceInfo, Booting into normal mode...]
[Log, Info, S_DeviceInfo, DeviceId: Bulb_A19_DimmableWhite_v2]
[Log, Info, N_Security, LIB4.5.75]
[Log, Info, N_Security, KeyBitMask, 0x0012]
[Log, Info, ConnectedLamp, Platform version 0.41.0.1, package_ZigBee117, package_BC_Stack 104, svn 26632]
[Log, Info, ConnectedLamp, Product version WhiteLamp-Atmel5.38.1.15095, built by LouvreZLL]
[Log, Info, A_Commissioning, Factory New at Ch: 11]
[TH, Ready, 0]
```

We can send other messages over the serial port. For example to get the software version we can send the GetSwVersion command (which was found by looking at strings in the ipbridge binary):

```
[TH, GetSwVersion]
[TH, GetSwVersion, 0, WhiteLamp-Atmel-Target, 0x0012, 5.38.1.15095]
```

Messages must be followed with a ‘\r’, the serial port can be changed to use this setting normally. Sending a newline alone or newline+carriage return ('\n\r') will result in an error.

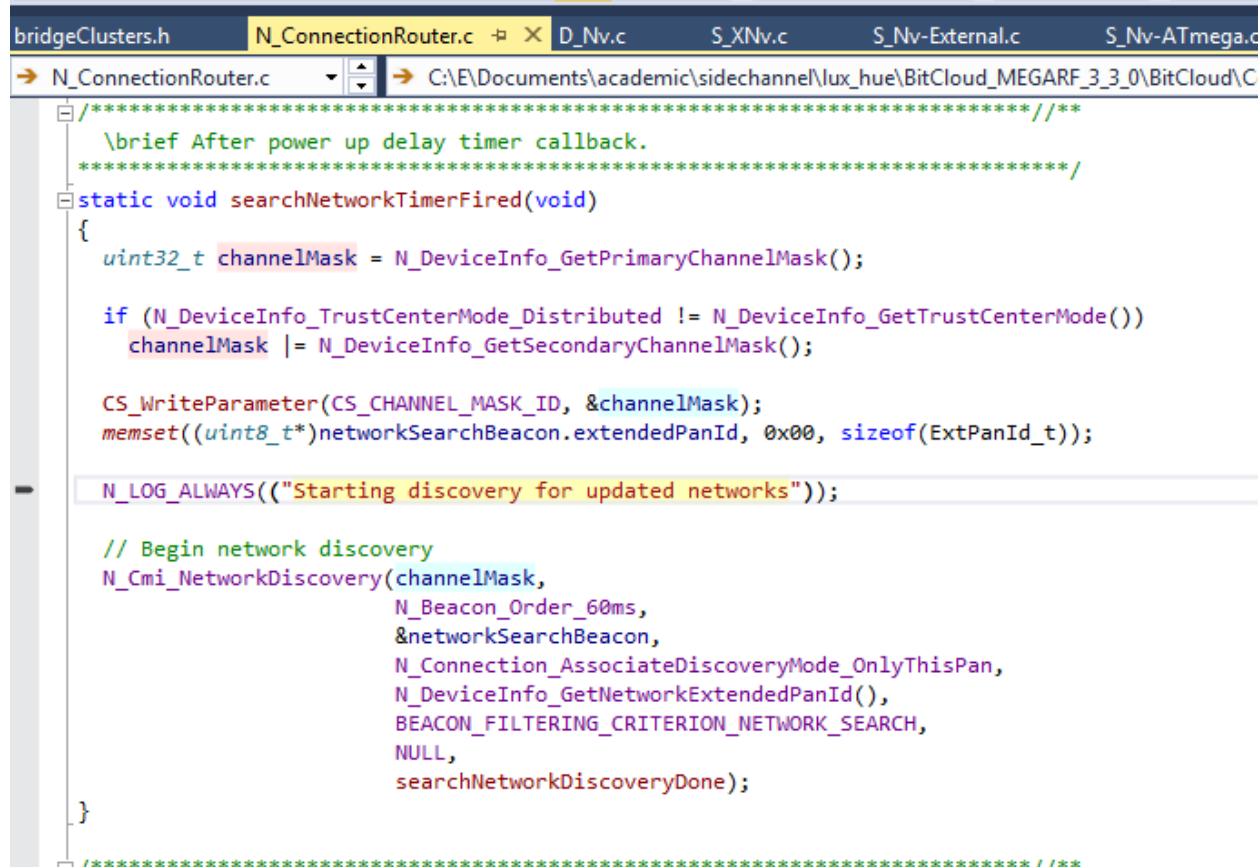
The availability of an active serial port is potentially of great interest – this could give rise to being susceptible to glitch attacks, or potential buffer overflows.

Using the printed data, we can also guess what the underlying stack might be. For example here are two lines in the log message:

```
[Log, Info, N_Connection, Starting discovery for updated networks]
```

```
[Log, Info, N_Connection, Discovery for updated networks completed]
```

This is the same message as printed by Atmel's ZLL BitCloud stack:



```
bridgeClusters.h      N_ConnectionRouter.c  D_Nv.c      S_XNv.c      S_Nv-External.c  S_Nv-ATmega.c
→ N_ConnectionRouter.c  ➔ C:\E\Documents\academic\sidechannel\lux_hue\BitCloud_MEGARF_3_3_0\BitCloud\O
  /**
   * \brief After power up delay timer callback.
   */
  static void searchNetworkTimerFired(void)
  {
    uint32_t channelMask = N_DeviceInfo_GetPrimaryChannelMask();

    if (N_DeviceInfo_TrustCenterMode_Distributed != N_DeviceInfo_GetTrustCenterMode())
      channelMask |= N_DeviceInfo_GetSecondaryChannelMask();

    CS_WriteParameter(CS_CHANNEL_MASK_ID, &channelMask);
    memset((uint8_t*)networkSearchBeacon.extendedPanId, 0x00, sizeof(ExtPanId_t));

    N_LOG_ALWAYS(("Starting discovery for updated networks"));

    // Begin network discovery
    N_Cmi_NetworkDiscovery(channelMask,
                           N_Beacon_Order_60ms,
                           &networkSearchBeacon,
                           N_Connection_AssociateDiscoveryMode_OnlyThisPan,
                           N_DeviceInfo_GetNetworkExtendedPanId(),
                           BEACON_FILTERING_CRITERION_NETWORK_SEARCH,
                           NULL,
                           searchNetworkDiscoveryDone);
  }
  /**
  */
```

We can also do things like short the SPI lines low – this results in error messages which are very consistent with those expected to be printed by the BitCloud stack.

This would suggest there is multiple underlying stacks present – this adds additional chances for bugs to enter, as there may be errors in the Atmel stack not present in the TI stack.

Also, knowing the stack allows us to understand the external SPI flash memory. For example looking at the source code we expect the string “S_XNv2” as described in the comments:

```
/** 16 byte sector header used in flash located at the start of the active sector. */
typedef struct SectorHeader_t
{
    /** Is this sector active. Written with 0x0000 at the end of the compact operation. */
    uint16_t isActive;
    /** Signature to detect valid sectors. Must have the value "S_XNv2". */
    uint8_t signature[6];
    /** Counter, decreased each time a new sector becomes the active sector. */
    uint32_t sequenceNumber;
    /** Parity bits for the sequenceNumber field = sequenceNumber ^ 0xFFFFFFFFuL. */
    uint32_t sequenceParity;
} SectorHeader_t;
```

A dump of the SPI flash shows this exact string being present:

FF FF FF FF	yyyyyyyyyyyyyyyy				
00 00 53 5F	58 4E 76 32	EA FF FF FF	15 00 00 00	S_XNv2	ÿÿÿÿÿÿÿÿÿÿÿÿÿÿ
00 00 FE FF	00 00 80 00	80 00 00 00	00 00 D4 2A	bÿ	€ € 0*
A0 00 D0 09	80 0A E0 OC	D0 12 30 14	E0 18 80 1C	þþþþþþþþþþþþþþ	þþþþþþþþþþþþþþ
40 20 D0 24	90 28 D0 2D	E0 30 D0 36	30 38 A0 3C	@ E\$	(ðà0 E\$08 <
30 41 40 44	A0 48 40 4C	B0 50 B0 56	10 58 A0 5C	0A@D	H@L°P°V+X
40 60 10 64	D0 68 60 6C	20 70 B0 74	80 78 20 7D	@`+d Eh` l p°t ex }	0
30 80 FF FF	FF FF FF FF	FF FF FF FF	FF FF FF FF	ÿÿÿÿÿÿÿÿÿÿÿÿÿÿÿÿ	ÿÿÿÿÿÿÿÿÿÿÿÿÿÿÿÿ
FF FF FF FF	ÿÿÿÿÿÿÿÿÿÿÿÿÿÿÿÿ	ÿÿÿÿÿÿÿÿÿÿÿÿÿÿÿÿ			
FF FF FF FF	ÿÿÿÿÿÿÿÿÿÿÿÿÿÿÿÿ	ÿÿÿÿÿÿÿÿÿÿÿÿÿÿÿÿ			
00 00 00 00	00 00 7C 00	7C 00 00 00	00 00 3D 6B	=k	500 r; oPr. op r+o r
35 09 30 01	3B 09 50 01	2C 09 70 01	2B 09 90 01	1°° r6° ðr L°O77 P7	1°° r6° ðr L°O77 P7
31 09 B0 01	36 09 F0 01	03 09 30 02	02 08 50 02	o n- o - o - o - + L	o n- o - o - o - + L
00 00 20 02	2F 00 90 02	01 00 B0 02	02 00 10 03		

The SPI flash, however, seems to contain only information on the ZigBee network configuration, and nothing of great interest such as keys or firmware.

Until an OTA update is released for the Atmel-based bulbs, it's hard to know exactly how the update process works. I assume it's similar to the CC2530 device (copies data to SPI flash, then bootloads from SPI flash).

TEST POINT CONNECTIONS

The test points on this board allow reprogramming of the ATMega2564RFR2 using a JTAG programmer. The location of test points is as such:

- TP104 = 3.3V IN
- TP105 = GND
- TP100 = RSTN

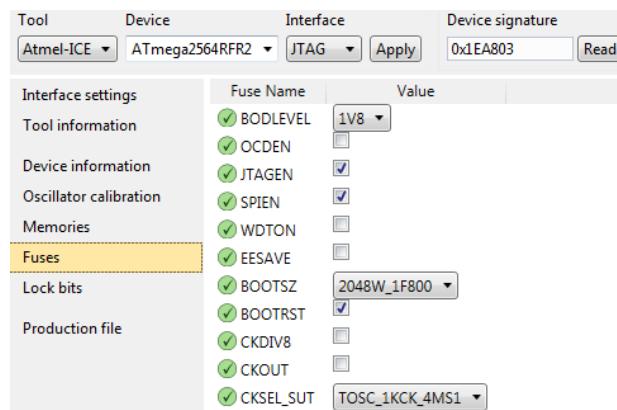
- TP109 = TCK
- TP110 = TMS
- TP113 = TDO
- TP114 = TDI

While soldering wires to these test-points requires removal of the LED board / heat-sink assembly, it should be possible to design a small PCB-jig that can press against these test points, and is inserted from the top without removing the LED board / heat-sink assembly.

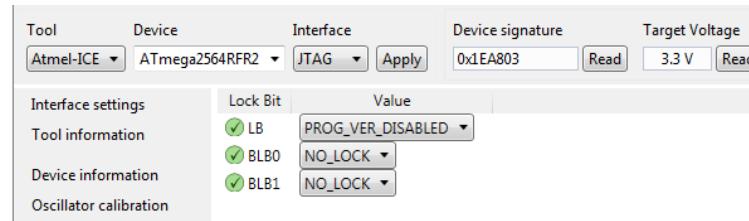
This would make it possible to re-use the low-cost white Hue LEDs as a generic development platform for those doing wireless sensor network (WSN) research.

FUSE INFORMATION

I also verified the fuse/lock-bits were set correctly by reading them with JTAG, beyond what was printed on the console at boot (in case that was incorrect). This confirms the system jumps to a fairly small bootloader – 2K words [4K bytes] of FLASH is reserved for the bootloader, the chip allows reserving up to 4K words of FLASH:



The security fuses do prevent program read-out. Interestingly, as first pointed out to me by Eyal Ronen, there are no locks on the bootloader section to prevent read-out by application code. The AVR has lock bits that can be set to prevent such read-out, but they are not used here:



Leaving the bootloader unlocked was likely done as another engineering trade-off, as by leaving the bootloader unlocked Philips can update the bootloader itself in a future firmware upgrade.

The disadvantage from a security perspective is that if an alternate method of loading code is found (for example – the bootloader has a flag to allow unencrypted binaries to be loaded, etc.), we could then load a program to read the bootloader out and determine the secret encryption keys.

Note the AVR's architecture prevents a basic glitch attack from working to read the bootloader section out. As the AVR is a Harvard architecture, the data and code memory is separate. Loading data from code memory requires special instructions, thus glitching some arbitrary transmit loop cannot result in code memory dumps.

8 CONCLUSIONS

A lightbulb worm doesn't exist today, but the "makings" of such a worm seem to exist in the architecture of any smart-lighting system. These systems involved wireless connections, where the very simple devices have limited ability to know what network they should join. An attacker can thus find ways to cause devices to switch networks, and if the device can be reflashed once under their control, a worm is trivial to generate from this arrangement.

The specific ZigBee Light Link (ZLL) implementation in Philips Hue takes a number of precautions to reduce the risk of this happening – using encrypted firmware updates for example to stop arbitrary code from being flashed, and using unique root passwords to hopefully stop someone from logging into the Bridge devices en-masse to attack the network from the Ethernet side.

Some engineering trade-offs were made that have the potential to cause serious problems. It appears all bulbs of the same type use the same encryption key for the firmware image, and if that key leaks it may be difficult to securely change the key. Realistically, such trade-offs are simply part of any product design and it's difficult to call them "good" or bad" design.

This paper has outlined various methods that might be used in further analysis of the system. Examples of glitch attacks to dump SRAM, alongside power analysis to determine where data processing occurred within the bootloader was demonstrated. Finally, an example of how to get a root console on the newer Bridge 2.0 devices was presented, which will be useful in performing further analysis of the binaries on these devices.

Readers interested in learning more about what sort of leakage can happen with a lightbulb attack, and then looking at how they can be applied, are encouraged to see Eyal Ronen's current and future publications (<http://www.wisdom.weizmann.ac.il/~eyalro/>).

ABOUT THE AUTHOR

Colin O'Flynn has developed the world's first open-source platform for side-channel power analysis and glitching attacks, and has spoken around the world about the application of this platform to various targets. You can read more about this platform (called ChipWhisperer), including seeing examples of how to perform these attacks at <http://www.chipwhisperer.com>.

Colin is currently finishing a PhD, and alongside that started NewAE Technology Inc. to sell the open-source hardware that resulted from the ChipWhisperer project, and also offers training and consulting services through this company. See www.newae.com for more information.

Before working in embedded security, he developed solutions for low-power wireless embedded systems, and continues some embedded design work as part of NewAE, as well as writing about FPGA design for Circuit Cellar magazine. He lives in Halifax, NS, Canada. He maintains a blog at www.oflynn.com, which contains various ongoing electronics projects (and some security work too).