

An Efficient Video Desnowing and Deraining Method with a Novel Variant Dataset

Arezoo Sadeghzadeh, Md Baharul Islam, Reza Zaker

2021. 09. 23

ICVS-2021, Vienna University of Technology



Contents



Introduction

- The importance of snow/rain removal
- Challenges
- The main goal of the paper



The Problems of Current Studies

- Image-based approaches
- Video-based approaches



Dataset Development

- Videos with Synthetic snow and Synthetic rain
- Videos with Quasi-snow
- Videos with Real Snow and Rain



The Proposed Method

Pixel-wise Video Desnowing/Deraining



Experimental Results and Comparison

- Qualitative Results
- Quantitative Results
- Computational Cost



Conclusion

- Cons/Pros
- Future Direction

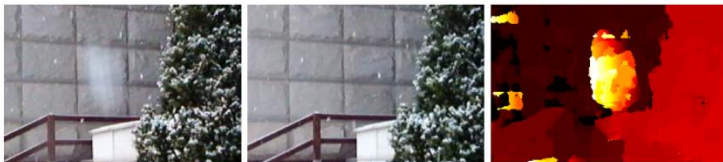
Introduction

The Importance of Snow/Rain Removal

Example For Its Importance



Object detection in presence of snow Object detection from the scene without snow



Left image

Right image

Disparity map

Why Snow/Rain Removal?

Weather conditions such as rain, snow, fog, and haze have a negative effect on the perceptual quality of the videos/ images captured from outdoor video/ image processing or vision systems

Application

Video/movie editing, vision-based navigation, autonomous driving, and video surveillance

Introduction

Challenges and Limitations of Video-based Snow/Rain Removal Approaches

Performance of Video-based Approaches

Performance degradation of the video rain removal techniques applied to the snowy videos

Causing severe blurring artifacts even for static backgrounds when the camera slightly shakes or moves while capturing the videos

Performance

Dataset

Lack of Appropriate Dataset

Lack of ground-truth information for real snowy/rainy scenes from videos or YouTube

Limited variations of the snowflakes, rain streaks, camera setting, and environmental conditions in synthetic snow and rain

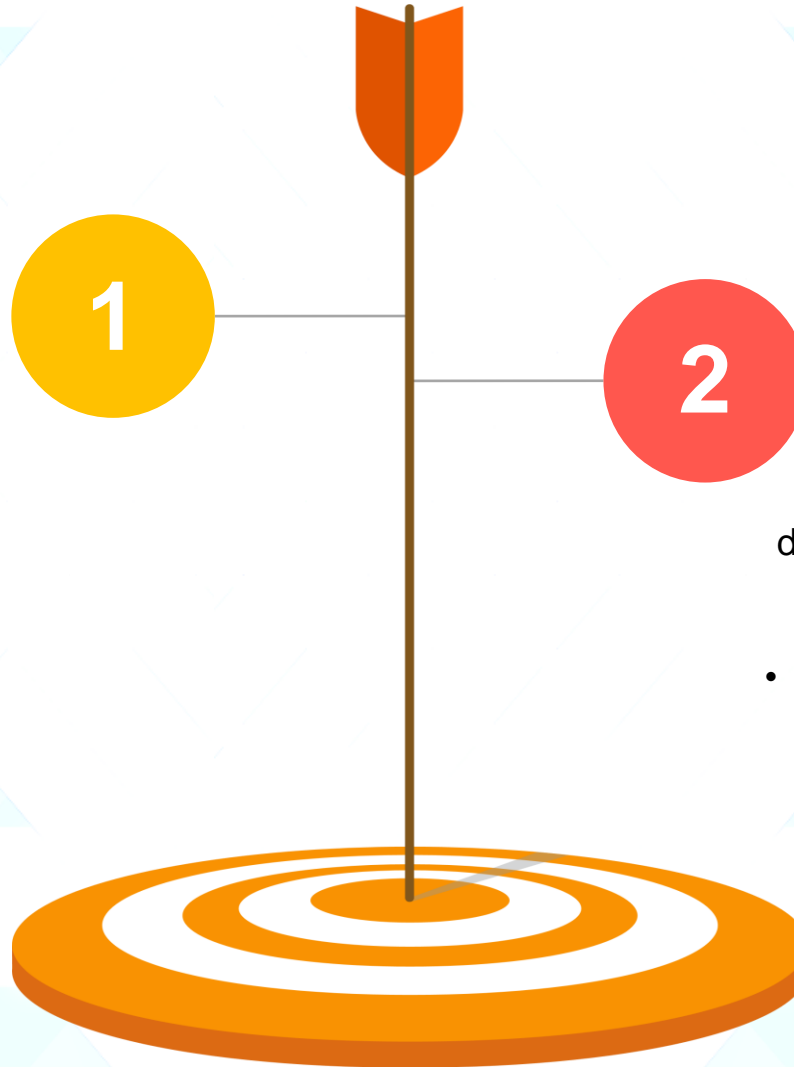


Introduction

The Main Goal of the Paper

Novel Dataset Development

- Providing a new snow and rain videos dataset
- Considering all variations of background (static and dynamic) and the camera (static and dynamic, e.g. translation, zooming, illumination changes, and rotation)
- Providing the ground-truth information in the synthetic snow and rain videos allows the



Pixel-wise Video Snow/Rain Removal Method

- A simple but very efficient video desnowing/deraining method based on the temporal information and the color of the pixels
- Removing the snow and rain for static background and camera even for heavy snow
- Low computational cost and high robust to illumination changes and camera shaking

Introduction

The Problems of Current Studies

Snow/Rain Removal

Image-based Approaches

Suffering from the limited generalization ability ← Sparsity prior, patch-rank prior



Time-consuming and a very large size ← CNNs and handcrafted priors

A physics-based backbone and GAN
single-image desnowing model based on a pyramidal hierarchical design

Video-based Approaches

High correlation between the corresponding pixels in consecutive frames

Stereo videos desnowing/deraining



Include more information and details than the monocular videos



CNNs and RCNNs

Online multi-scale convolutional sparse coding



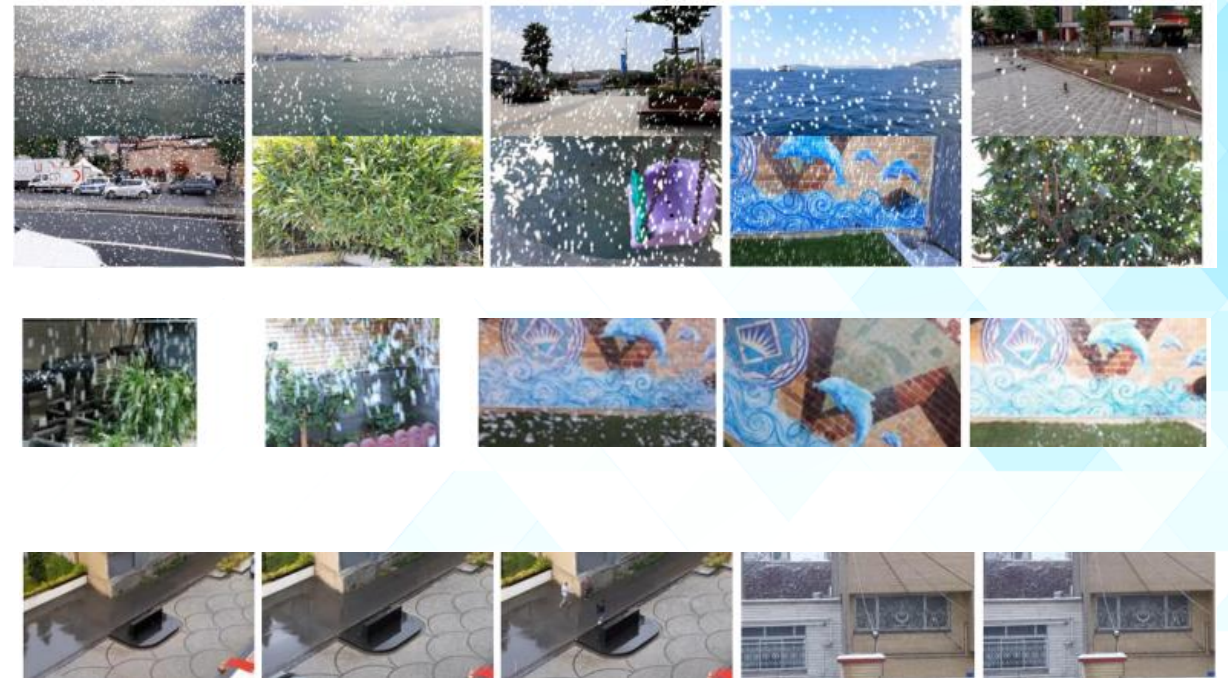
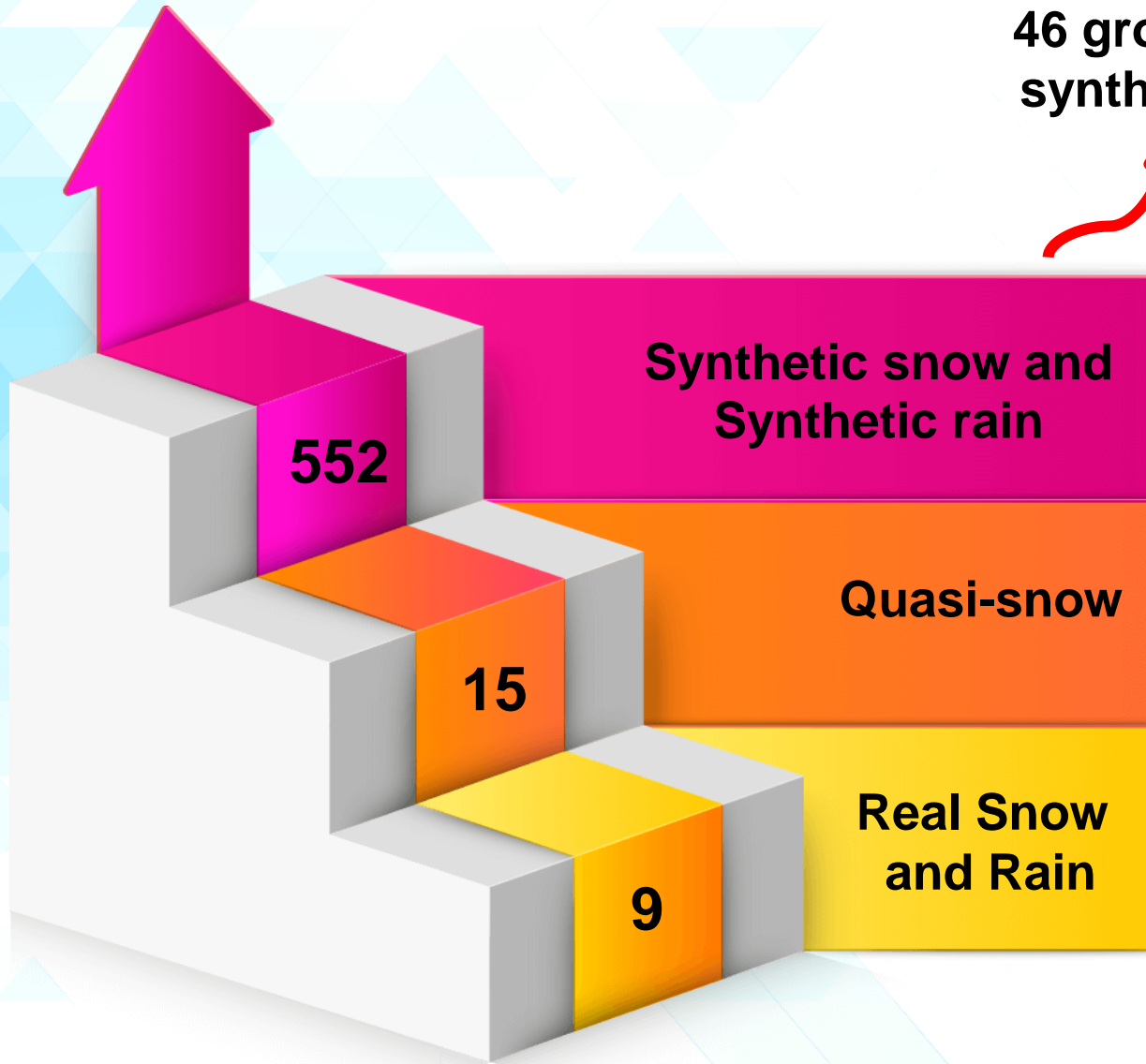
Limitations on non-surveillance videos, moving objects, fast illumination changes, and fast moving cameras

Dataset Development

Variants in Snow&Rain Videos

46 ground-truth videos and 506
synthetic snow/rain created by
augmentation

Totally 577 Videos



Dataset Development

Variants in Snow&Rain Videos

Ground-truth videos for synthetic snow and rain

Camera resolution	Camera variations	Background	Number of videos	Video length
25MP 1080 × 1920 pixels fps = 30	Static	Dynamic (slow)	3	35 s, 14 s, 13 s
		Dynamic (fast)	4	8 s, 8 s, 10 s, 8 s
	Dynamic (shaking and translation)	Dynamic (slow)	1	14 s
	Static and Dynamic (slow and fast translation, zooming, rotation, illumination changes, small and large shaking, both rotation and zooming)	Dynamic (fast)	13	11 s, 11 s, 14 s, 18 s, 11 s, 10 s, 13 s, 29 s, 9 s, 12 s, 11 s, 13 s, 11s
		Dynamic (slow)	13	14 s, 21 s, 14 s, 13 s, 18 s, 10 s, 10 s, 20 s, 10 s, 34 s, 11 s, 9 s, 13 s
		Static	12	22 s, 11 s, 18 s, 11 s, 25 s, 12 s, 37 s, 11 s, 10 s, 14 s, 18 s, 11 s

Videos based on quasi-snow

8Mp 480 × 460 fps = 30	Static	Static	2	59 s, 23 s
	Dynamic (translation)		1	74 s
25MP 1080 × 1920 fps = 30	Static and Dynamic (slow and fast translation, zooming, rotation, illumination changes, small and large shaking, both rotation and zooming)		13	25 s, 19 s, 12 s, 10 s, 26 s, 16 s, 16 s, 10 s, 19 s, 28 s, 11 s, 26 s, 13 s

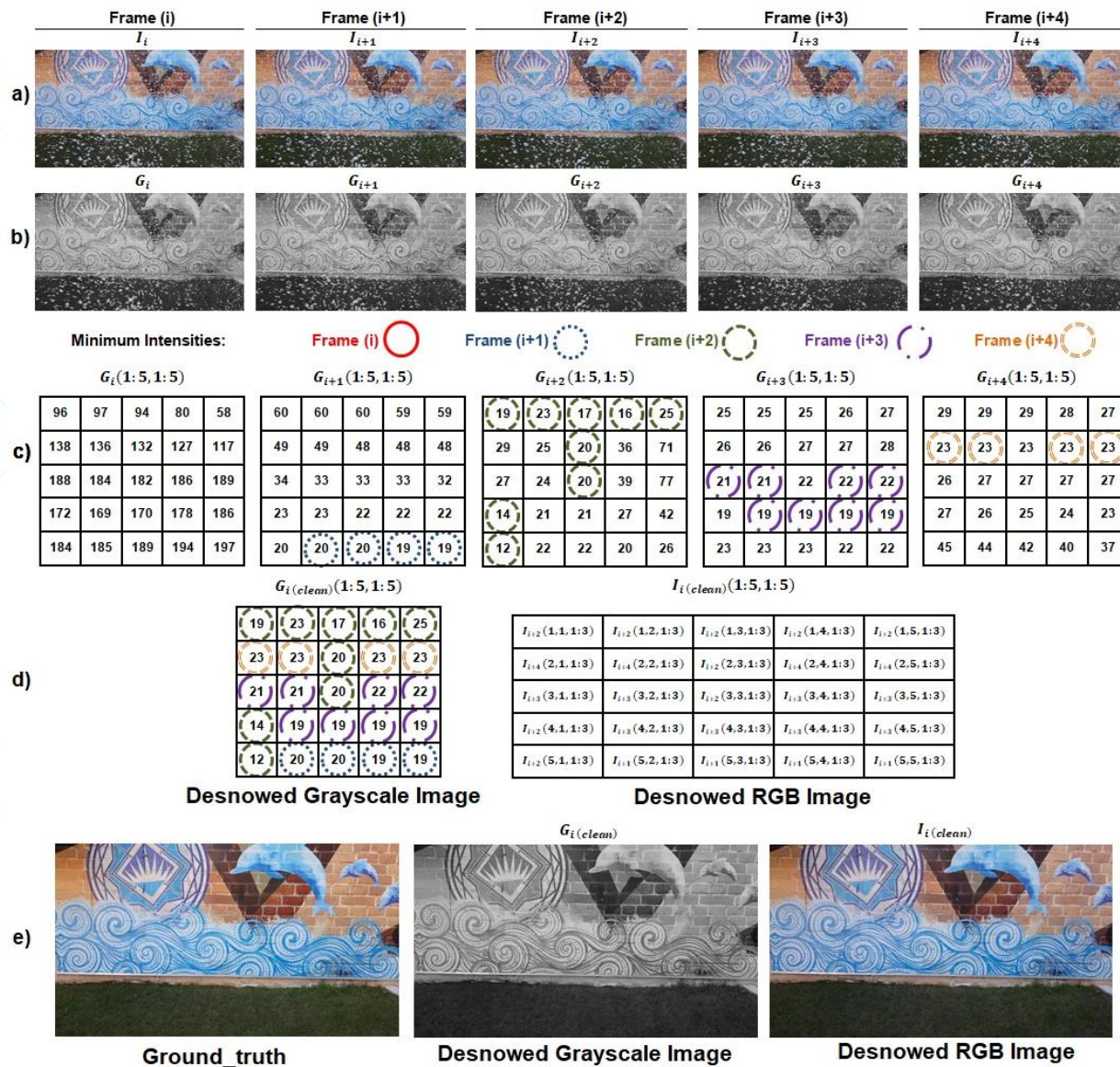
Videos with real snow and rain

13MP 1080 × 1920 fps = 30	Static	Static	1 (snow)	8 s
25MP 1080 × 1920 fps = 30	Static	Static and Dynamic	8 (light and heavy rain)	21 s, 7 s, 21 s, 11 s, 12 s, 42 s, 11 s, 18 s

Total characteristics of the videos and the considered scenarios in the developed dataset.

Proposed Method

The Overall Flowchart



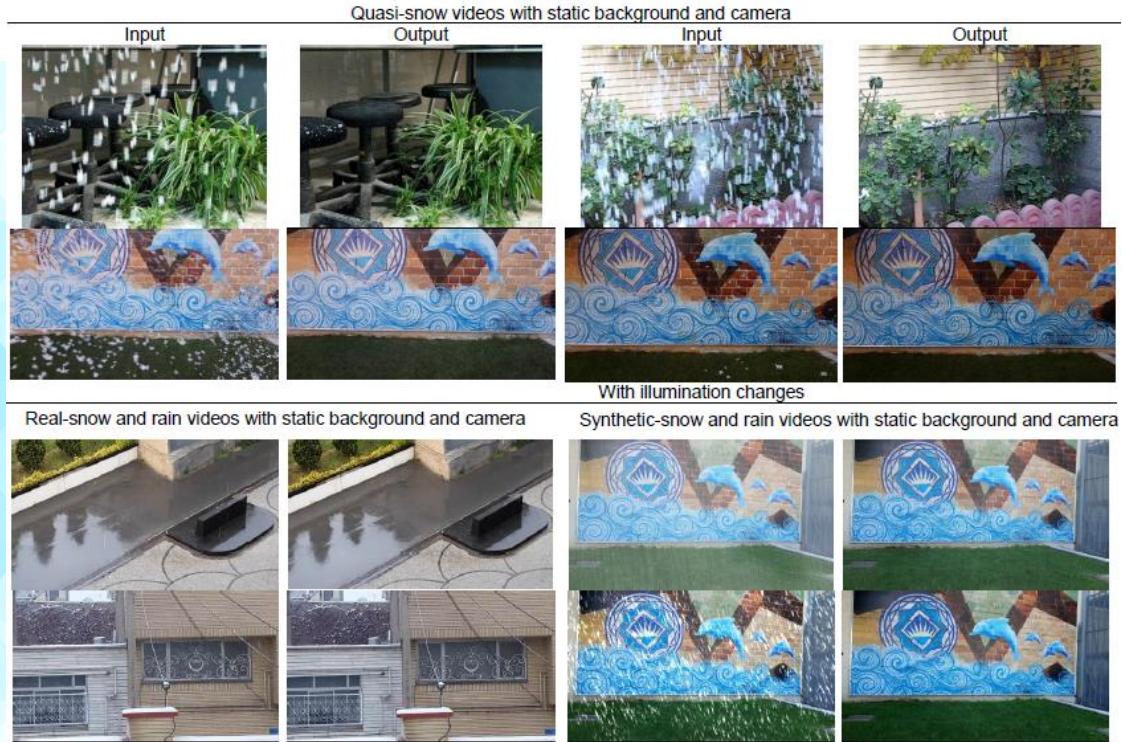
Proposed Method

	A single pixel in five consecutive frames	The selected background												
a)	<p>Given single pixel is background in all frames</p> <table><tr><td>F1</td><td>F2</td><td>F3</td><td>F4</td><td>F5</td></tr><tr><td>76</td><td>77</td><td>80</td><td>70</td><td>85</td></tr></table>	F1	F2	F3	F4	F5	76	77	80	70	85	<table><tr><td>F4</td></tr><tr><td>70</td></tr></table>	F4	70
F1	F2	F3	F4	F5										
76	77	80	70	85										
F4														
70														
b)	<p>Given single pixel is background in some frames</p> <table><tr><td>F1</td><td>F2</td><td>F3</td><td>F4</td><td>F5</td></tr><tr><td>100</td><td>210</td><td>105</td><td>204</td><td>108</td></tr></table>	F1	F2	F3	F4	F5	100	210	105	204	108	<table><tr><td>F1</td></tr><tr><td>100</td></tr></table>	F1	100
F1	F2	F3	F4	F5										
100	210	105	204	108										
F1														
100														
c)	<p>Given single pixel is background in only one frame</p> <table><tr><td>F1</td><td>F2</td><td>F3</td><td>F4</td><td>F5</td></tr><tr><td>220</td><td>215</td><td>217</td><td>210</td><td>50</td></tr></table>	F1	F2	F3	F4	F5	220	215	217	210	50	<table><tr><td>F5</td></tr><tr><td>50</td></tr></table>	F5	50
F1	F2	F3	F4	F5										
220	215	217	210	50										
F5														
50														
d)	<p>Given single pixel is white background in some frames and snow in the others</p> <table><tr><td>F1</td><td>F2</td><td>F3</td><td>F4</td><td>F5</td></tr><tr><td>210</td><td>225</td><td>210</td><td>200</td><td>215</td></tr></table>	F1	F2	F3	F4	F5	210	225	210	200	215	<table><tr><td>F4</td></tr><tr><td>200</td></tr></table>	F4	200
F1	F2	F3	F4	F5										
210	225	210	200	215										
F4														
200														

The possible conditions for a single pixel in five consecutive frames.

Experimental Results

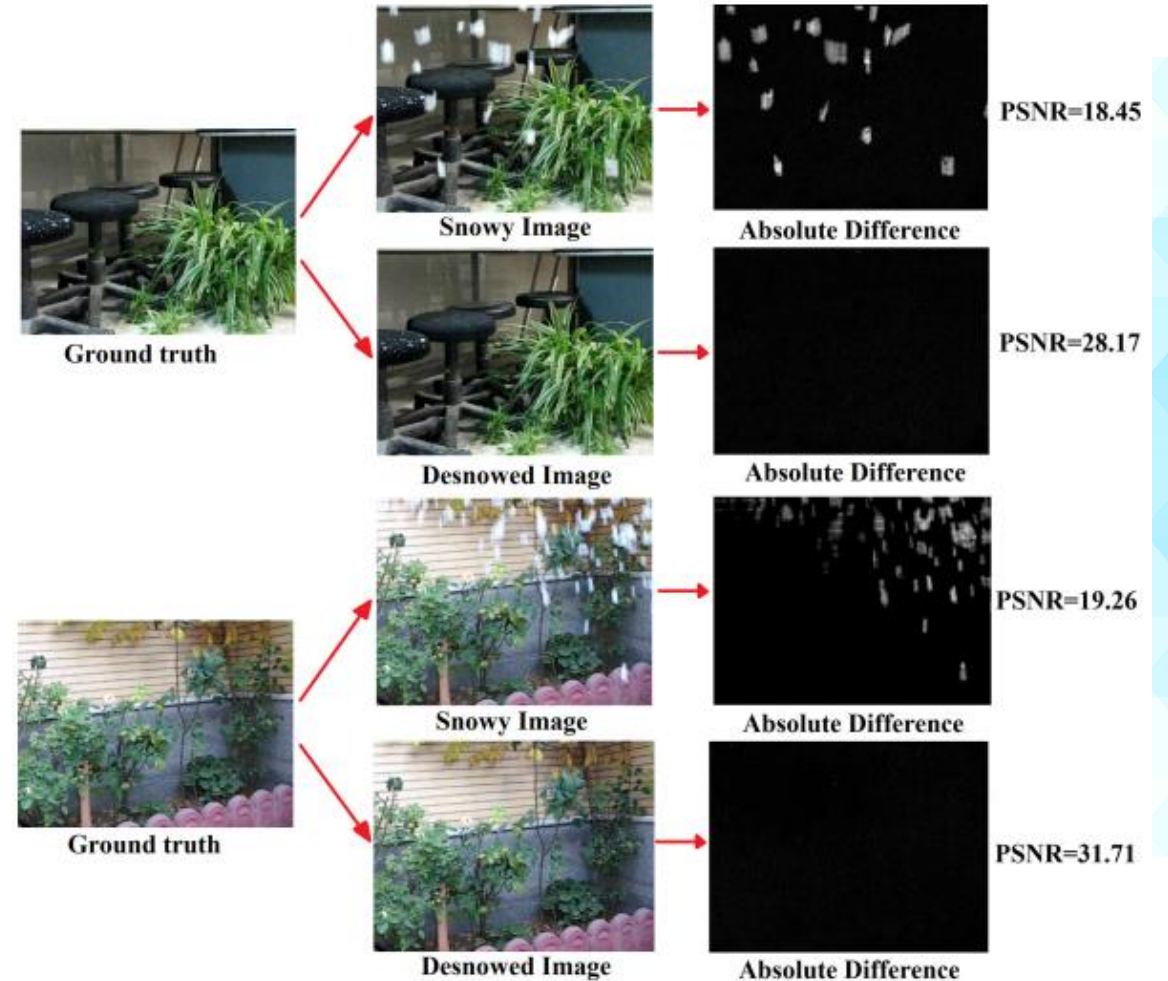
Qualitative and Quantitative Results and Computational time



Qualitative Results

Image size	3 consecutive frames	7 consecutive frames	10 consecutive frames
480 × 640	0.61 s	0.65 s	0.75 s
1080 × 1920	3.82 s	4.10 s	4.40 s

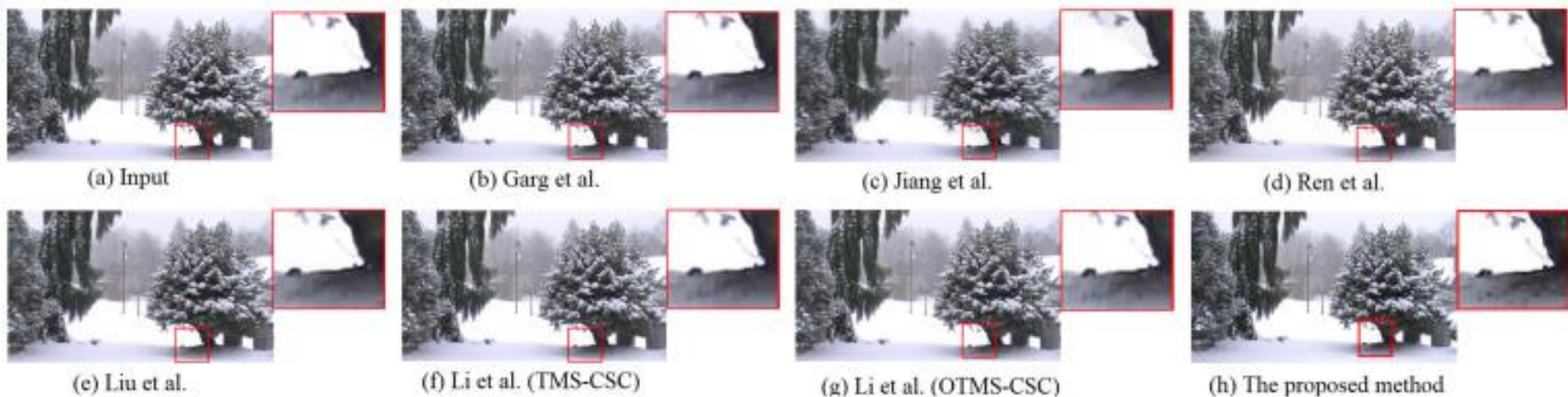
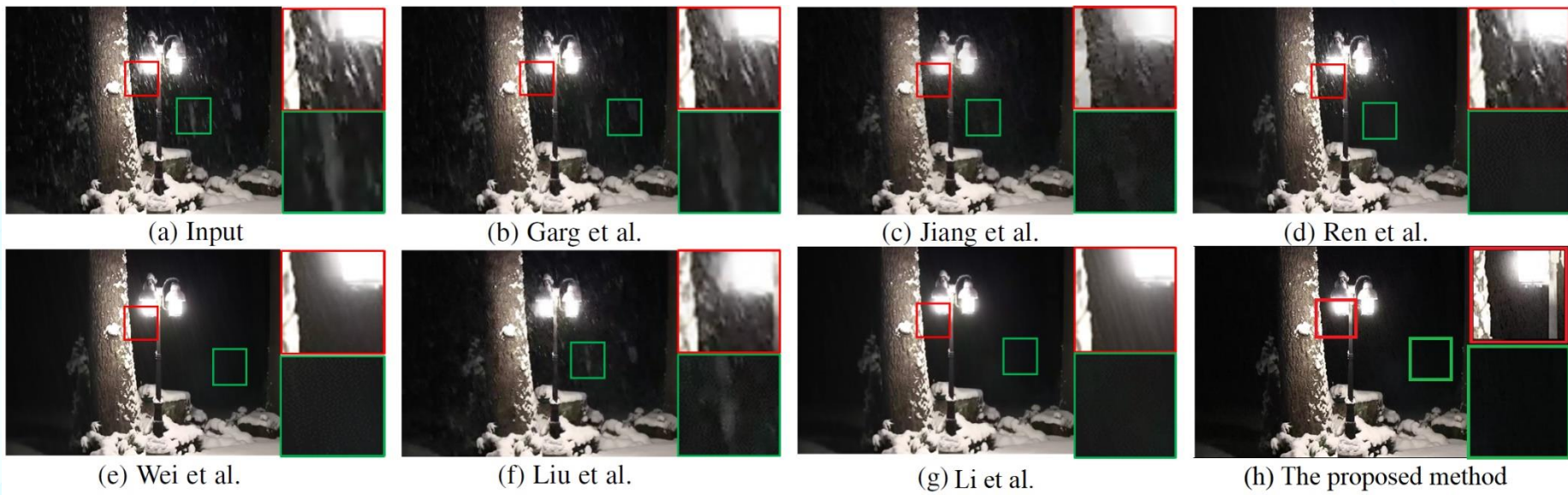
Computational time



Quantitative Results

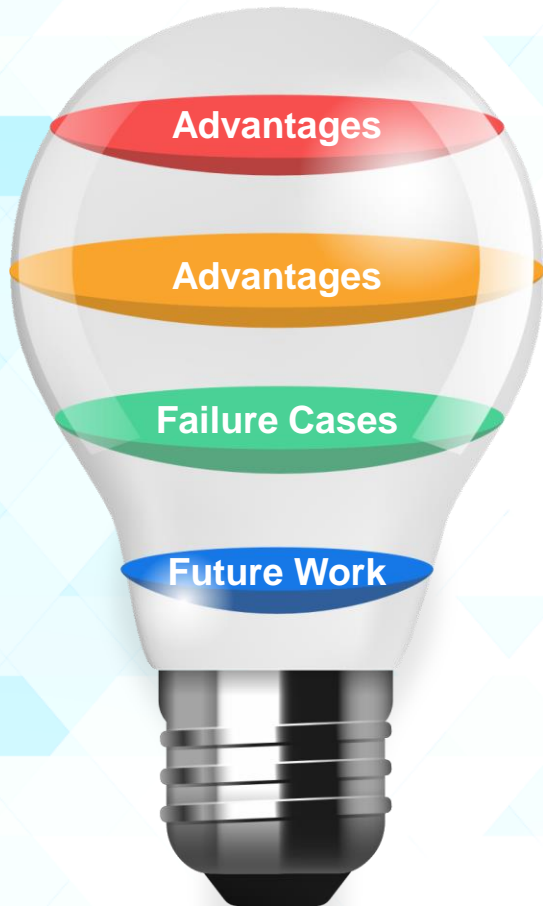
Experimental Results

Comparison



Conclusion

Cons/Pros and Future Direction



Building a snow and rain dataset for the first time by considering all possible background and camera scenarios



Our desnowing/deraining method could efficiently remove the snow/rain without causing any blurriness even for heavy snow scenarios and illumination changes with low computational cost and time.



Suffering from limitations in dealing with extensive background movements and camera translation, rotation, and zooming in the presence of heavy snow/rain



Improving the method to deal with the dynamic background and moving cameras



**Thank you for
your attention!**