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Idea:\mathbf{w}^T\mathbf{x} + w_0 = \tilde{\mathbf{w}}^T\tilde{\mathbf{x}}, where
\tilde{\mathbf{w}} := [w_1, ..., w_d, w_0]^T; \ \tilde{\mathbf{x}} = [x_1, ..., x_d, 1]^T
Def: Residual: r_i = y_i - f(y_i); Loss function l;
l^p-loss: l(r) = |r|^p; Emp. risk: \hat{R}(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^n l(r_i) SGD:b)\mathbf{w}_{t+1} = (1 - \frac{2\lambda}{n} \eta_t) \mathbf{w} + 1[y_t \mathbf{w}^T \mathbf{x}_t < 1] \eta_t y_t \mathbf{x}_t Alt: Thresh \tau in \operatorname{sgn}(\mathbf{w}^T \mathbf{x} - \tau). Acc. = \frac{TP + TN}{n};
LSR problem: \hat{\mathbf{w}} = \arg\min_{\mathbf{w}} \sum_{i=1}^{n} (y_i - \mathbf{w}^T \mathbf{x}_i)^2
LSR expl. sol.: \hat{\mathbf{w}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}; O(nd^2 + d^3) feat. selection S \subseteq V, CV-Loss \hat{L}(S):
Gradient Descent (G.D.) \nabla \hat{R} \Rightarrow O(nd) \log(\frac{1}{n}): 1. Start with S = \emptyset and E_0 = \infty
1. Start at an arbitrary \mathbf{w}_0 \in \mathbb{R},
2. For t=0,1,2,... do: \mathbf{w}_{t+1} = \mathbf{w} - \eta_t \nabla \hat{R}(\mathbf{w}_t).
\cdot R \text{ convex} \Rightarrow \text{G.S. converges}; l = l^2, \eta_t = \frac{1}{2} \Rightarrow O(t) b) Compute error: E_i = \hat{L}(S \cup \{s_i\})
Adaptive step size: (Add step 3. in G.D. above)
1.Line search: 3. \eta_t^* = \arg\min_{n \in [0,\infty)} \hat{R}(\mathbf{w}_t - \eta g_t). Greedy backward selection (-slower, +dep. feats) \cdot_{\text{reduces } c \text{ or } c(c-1)/2 \text{ req. bin. clas.rs to } O(\log_2 c)
2.Bold driver: 3.If \hat{R}(\mathbf{w}_t) < \hat{R}(\mathbf{w}_t) : \eta_t := c_{acc}\eta_{t-1}, 1. Start with S = V and E_{d+1} = \infty
else \eta_t := c_{dec} \eta_{t-1}.
Non-lin. reg.: f(x) = \sum_{i=1}^d w_i \phi_i(\mathbf{x}), \, \mathcal{B}_H = (\phi_i)_i
ERM: LoLN \Rightarrow \hat{R}(\mathbf{w}) \xrightarrow{|D| \to \infty} R(\mathbf{w}) a.s..
l = l^2, supp(D) < \infty \Rightarrow ||R - \hat{R}|| \to 0 (in C^0)
+\mathbb{E}_D[\hat{R}_D(\hat{\mathbf{w}}_D)] \leq \mathbb{E}_D[R(\hat{\mathbf{w}}_D)] (Pf. Jensen's (swap))
Idea: Use train/val./test sets, reduce general. error ||\mathbf{w}||_0 = |\{i : w_i \neq 0\}|; "Sparsity trick": use ||\mathbf{w}||_1
·Optimize \hat{\mathbf{w}}_{D_{train}} = \arg\min \hat{R}_{train}(\mathbf{w}), but
evaluate \hat{R}_{test}(\hat{\mathbf{w}}) = \frac{1}{|D_{test}|} \sum_{(\mathbf{x}, u) \in D_{test}} (y - \hat{\mathbf{w}}^T \mathbf{x})^2. L1-5 VIVI: \min_{\mathbf{w}} \frac{1}{n} \sum_{i:H(\mathbf{w}, \mathbf{x}_i, y_i) + |A||\mathbf{w}||1} \sum_{i:H(\mathbf{w}, \mathbf{x}_i, y_i) + |A||\mathbf{w}||1} \sum_{(\mathbf{x}, u) \in D_{test}} (y - \hat{\mathbf{w}}^T \mathbf{x})^2. Greedy: +any method, -slower (train many models); 1. For j \in \text{Layer}_1, set v_j = x_j. For each layer l = 1:L-1
\mathbb{E}_{D_{tr.},D_{test}}[\ddot{R}_{D_{test}}(\hat{\mathbf{w}}_{D_{tr.}})] = \mathbb{E}_{D_{tr.}}[R(\hat{\mathbf{w}}_{D_{tr.}})](iid)
MC/k-fold cross validation (only when D idd):
1. For candidate model m and i=1,...,k:
  a) Split (train) data: D = D_{train}^{(i)} \sqcup D_{val}^{(i)}
  b) Train model: \hat{\mathbf{w}}_{i,m} = \arg\min_{\mathbf{w}} \hat{R}_{train}^{(i)}(\mathbf{w})
  c) Estimate error: \hat{R}_m^{(i)} = \hat{R}_{mal}^{(i)}(\mathbf{\hat{w}}_i)
2. Select model: \hat{m} = \arg\min_{m} \frac{1}{k} \sum_{i=1}^{k} \hat{R}_{m}^{(i)}
k large: Risk overfitting to D_{val}, underfitting to
 D_{train} and having too little data for training
k small: Higher O(\cdot) but better performance
k=n: LOOCV; in practice often k=5 or k=10
RR prob.: \min_{\mathbf{w}} \frac{1}{n} \sum_{i=1}^{n} (y_i - \mathbf{w}^T \mathbf{x}_i)^2 + \lambda ||\mathbf{w}||_2^2
RR expl. sol.: \hat{\mathbf{w}} = (\mathbf{X}^T \mathbf{X} + \lambda \mathbf{I})^{-1} \mathbf{X}^T \mathbf{y} (std \mathbf{X}!), k((x,y),(x',y')) := k_1(x,y) \overline{k_2}(x',y') kernel
x_{ij} = \frac{x_{ij} - \hat{\mu}_j}{\hat{\sigma}_i} | \hat{\mu}_j = \frac{1}{n} \sum_{i=1}^n x_{ij} | \hat{\sigma}_j = \frac{1}{n} \sum_{i=1}^n (x_{ij} - \hat{\mu}_j)^2 \cdot \frac{k((x,y),(x',y')) - k_1(x,y) + k_2(x',y')}{k((x,y),(x',y'))} = k_1(x,y) + k_2(x',y') \text{ kernel}
RRGD:2. For t: \mathbf{w}_{t+1} = (1 - 2\lambda \eta_t) \mathbf{w}_t - \eta_t \nabla \hat{R}(\mathbf{w}_t) P: \hat{\alpha} = \arg\min_{\alpha} \frac{1}{n} \sum_i \max(0, -y_i \alpha^T \mathbf{k_i})
General regularizatoin: \min_{\mathbf{w}} \hat{R}(\mathbf{w}) + \lambda C(\mathbf{w})
· Tradeoff: g.o.f. vs. simplicity (\lambda \gg 0 \text{ higher } O(\cdot)) \lambda \alpha^T \mathbf{D}_{\boldsymbol{y}} \mathbf{K} \mathbf{D}_{\boldsymbol{y}} \alpha, \ \mathbf{k}_i = [y_1 k(\mathbf{x}_i, \mathbf{x}_1), ..., k(\mathbf{x}_i, \mathbf{x}_n)]
\lambda choice: CV w. e.g. m(\lambda), \lambda \in \{10^{-6}, 10^{-5}, ..., 10^{6}\} RR: \hat{\alpha} = \arg\min_{\alpha} \frac{1}{n} ||\alpha^{T} \mathbf{K} - y||_{2}^{2} + \lambda \alpha^{T} \mathbf{K} \alpha =
Bin. lin. classifiers: f(\mathbf{x}) = f_{\mathbf{w}}(\mathbf{x}) = \operatorname{sgn}(\mathbf{w}^T\mathbf{x}), (\mathbf{K} + n\lambda\mathbf{I})^{-1}\mathbf{y} (closed form sol) Kernel reg.
l = l_{0/1}(\mathbf{w}; \mathbf{x}_i, y_i) := 1[y_i \neq f_{\mathbf{w}}(\mathbf{x}_i)] \text{ (a.e. } \nabla_{\mathbf{w}} = 0!) \text{ pred.: } \hat{y} = \sum_{j=1}^n \alpha_j k(x_j, x)
Surrogate losses: l_P(\mathbf{w}; \mathbf{x}, y) = max(0, -y\mathbf{w}^T\mathbf{x}), Kernel bin. cl. pred.: \hat{y} = \text{sgn}\left(\sum \alpha_i y_i k(x_i, x)\right)
l_H(\mathbf{w}; \mathbf{x}, y) = max(0, 1 - y\mathbf{w}^T\mathbf{x})
GD: 2.For t: \mathbf{w}_{t+1} = \mathbf{w}_t - \eta_t \sum_{i \in \mathcal{I}_{\mathbf{w}_t}} y_i \mathbf{x_i}, where +No training necessary, -depends on all data/ineff. Backpropagation (Matrix version):
\mathcal{I}_{\mathbf{w}} = \{i : (\mathbf{x}_i, y_i) \text{ incorrectly classified by } \mathbf{w}\} \text{ (inef.!) } \mathbf{k} - \mathbf{P} : + \text{Optim. weights improve perf., } + \text{Some k}
Idea: Evaluate only a k pts in \mathcal{I}_{\mathbf{w}} (k = 1 \Rightarrow \text{SGD}) capture "global trends", +Depends only on wrongly
SGD:1.Start with arbitrary \mathbf{w}_0 \in \mathbb{R}^d
2. For t=0,1,2,... do:
  a) Pick (\mathbf{x}', y') \in D_{train} U-randomly
  b) Set \mathbf{w}_{t+1} = \mathbf{w}_t - \eta_t \nabla l(\mathbf{w}_t; \mathbf{x}', y')
Conv. Guar. if \sum_t \eta_t = \infty and \sum_t \eta_t^2 < \infty
Minibatch SGD: a) k > 1 and in b) take \nabla l avg
 "Mini-batches exploit parallelism, reduce variance"
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Greedy forward selection: Feat.s V = \{1, ..., d\}, \text{Prec.} = \frac{TP}{TP + FP}; \mathbb{E}[TPR] = p = \mathbb{E}[TPR];
 2. For i=1,..,d, do:
a) Find best feature: s_i = \arg\min_{j \in V \setminus S} \hat{L}(S \cup \{j\})
  c) If E_i > E_{i-1} break, else set S = S \cup \{s_i\}
 2. For i=d,..,1, do:
 a) Find best feature: s_i = \arg\min_{j \in S} \hat{L}(S \setminus \{j\})
  b)Compute error: E_i = \hat{L}(S \setminus \{s_i\})
  c)If E_i > E_{i+1} break, else set S = S \setminus \{s_i\}
 Alt: \hat{\mathbf{w}} = \arg\min \sum l(\mathbf{w}; \mathbf{x}_i, y_i) + \lambda ||\mathbf{w}||_0, where
L1-SVM: \min_{\mathbf{w}} \frac{1}{n} \sum l_H(\mathbf{w}; \mathbf{x}_i, y_i) + \lambda ||\mathbf{w}||_1
L0/L1-regul.: +faster, -only lin models
 Reprsnt.r Thm: \hat{\mathbf{w}} = \sum_i \alpha_i(y_i) \mathbf{x}_i \in \langle \mathbf{x}_1, .., \mathbf{x}_n \rangle
 \RightarrowPerc: \min_{\alpha} \sum_{i} max(0, -y_i \sum_{j} \alpha_j y_j(\mathbf{x}_i^T \mathbf{x}_i))
 \alpha; 2. k(\mathbf{x}, \mathbf{x}') = \mathbf{x}^T \mathbf{x}' \mapsto \phi(\mathbf{x})^T \phi(\mathbf{x}') =: k_{\phi}(\mathbf{x}, \mathbf{x}')
 PA:1.\alpha := 0. 2.t = 1, 2, ... : a)Pick (x_i, y_i) \sim D
b) \alpha_i := \alpha_i + \eta_t \max(0, -\operatorname{sgn}(y_i \sum_i \alpha_j y_j k(\mathbf{x}_j, \mathbf{x}_i))) 3. \mathbf{f} := \mathbf{W}^{(L)} \mathbf{v}^{(L-1)}
Def: k kernel iff K sym. & pos. semi-def. iff SP/IP 4. Predict \mathbf{y} = \mathbf{f} / \mathbf{y} = \mathrm{sgn}(\mathbf{f}) / \mathbf{y} = \mathrm{arg\,max}, \mathbf{f}
 Laplacian: e^{-||\mathbf{x}-\mathbf{x}'||_1/h}
 k_1 + k_2, k_1 k_2, c k_1 \text{ for } c > 0 \text{ and } f(k_1) \text{ for } f \text{ poly}
 with pos. coeffs or exponential are also kernels
 k(k_i)_i^d \text{ kernels} \Rightarrow k(\mathbf{x}, \mathbf{x}') = \sum_{j=1}^d k_j(x_j, x_j') \text{ kernel} SGD for ANNs: 1. Initialize weights W
 SVM: \hat{\alpha} = \arg\min_{\alpha} \frac{1}{n} \sum_{i} \max(0, 1 - y_i \alpha^T \mathbf{k_i}) +
 \mathbf{k}-NN: \hat{y}(\mathbf{x}) = \operatorname{sgn}(\sum y_i 1[\mathbf{x}_i \ kNN \ of \ \mathbf{x}]) \ (k?\text{CV!})
 classified ex.s, -Training requires optimization
 Sum: Can derive non-para. m.s from para. w. k's
 Prob: Paramatric models "rigid", non-param. fail
 to extrapolate: Sol: (Semi-param. m.) Add. comb.
 of lin. & non-lin. kernels
\cdot E.g. k(\mathbf{x}, \mathbf{x}') = c_1 \exp(-||\mathbf{x} - \mathbf{x}'||_2^2/h^2) + c_2 \mathbf{x}^T \mathbf{x}'
   \Rightarrow f(\mathbf{x}) = \sum \alpha_i k(\mathbf{x}_i, \mathbf{x}) = f_{\alpha}(\mathbf{x}) + \mathbf{w}_{\alpha}^T \mathbf{x}
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Perceptron alg (PA): SGD with l = l_P and \eta_t = 1 Downsmplng:+Smaller/faster,-Wasteful/info-loss; He (ReLU): w_{i,j} \sim \mathcal{N}(0, \frac{2}{n_i}); LR: start fixed/small
 Thm: If data lin. separable, PA finds lin. separator Upsmplng:+Uses \forall (x,y),-slow,-adds artificial info; then decrease, e.g. \eta_t = \min_{t=0}^{\infty} (0.1, 100/t) or
 SVM: \min_{\mathbf{w}} \frac{1}{2} \sum l_H(\mathbf{w}; \mathbf{x}_i, y_i) + \lambda ||\mathbf{w}||_2^2; ip \eta_t = \frac{1}{M} Cost-sens. loss: l_{CS}(\mathbf{w}; \mathbf{x}, y) = c_y l(\mathbf{w}; \mathbf{x}, y), c_y > 0. decreasing step function; Momentum: (Escape loc.
                                                                                                                                                                                                        min.) \mathbf{W} := \mathbf{W} - m \cdot a - \eta_t \nabla_{\mathbf{W}} l(\mathbf{W}; \mathbf{y}, \mathbf{x})
                                                                                                                                                                                                        Regul.:*Early stop. (when Err.(D_{val}) \uparrow),*Train
                                                                                                   Rec.=TPR+FPF, FPR=\frac{TP}{TP+FN}; FPR=\frac{TP}{TN+FP}; F1-Score=\frac{2TP}{2TP+FP+FN} = \frac{2}{Prec^{-1}+TPR^{-1}}
Thm: A1 \ge A2 \ ROC = \frac{TPR}{FPR} \ \text{iff} \ A1 \ge A2 \ \frac{Prec}{Rec}.
                                                                                                                                                                                                        dropout unit p/\text{test } \mathbf{w} := p\mathbf{w}, *L(\mathbf{W}) + \lambda ||\mathbf{W}||_F^2
                                                                                                                                                                                                        Batch norm.:(mini-batch \mathcal{B} = (x_i)_i^m) Learn \gamma, \beta.
                                                                                                                                                                                                        For each layer: (\varphi(wx) = \varphi(wBN_{\gamma,\beta}(x)))
                                                                                                                                                                                                           a) Normalize: \hat{x_i} = \frac{1}{m} \sum (x_i - \mu_B)^2
                                                                                                   Multi lin. class.: \hat{y} = \arg\max_{i} \mathbf{w}_{i}^{T} \mathbf{x}, ||\mathbf{w}_{i}|| = 1.
                                                                                                                                                                                                           b) Scale & shift: y = \gamma \hat{x}_i + \beta = :BN_{\gamma,\beta}(x_i)
                                                                                                    Alt (1v1): \hat{y} = \arg\max_{i \le c} |\{j : 0 < \operatorname{sgn}(\mathbf{w}_{i,i}^T \mathbf{x})\}|
                                                                                                                                                                                                        CNNs: Apply m diff. f \times f filters to an n \times n im.
                                                                                                    Encode: 1 \mapsto [0, ..., 1], 2 \mapsto [0, ..., 1, 0], c \mapsto [1, ..., 1, 1]
                                                                                                                                                                                                       yields an m \times l \times l to get, s.t. l = \frac{n+2 \cdot \text{padding} - f}{\text{stride}} + 1
                                                                                                                                                                                                        \mathbf{Past}: \mathbf{sigmoid}/\mathbf{tanh}(\mathbf{difbl}), \mathbf{Now}: \mathbf{ReLu}(\mathbf{fast}, \mathbf{stable} \nabla \mathbf{s})
                                                                                                    MCSVM: \nabla l = x(1 - 2 \cdot 1[\neg(*) \land i = y])1[(*) > 0]
                                                                                                                                                                                                        Kernels:+Convex,+noise robust,\pm O(D),-1 layer;
                                                                                                    l_{MC-H}(\mathbf{W}; \mathbf{x}, y) = \max(0, 1 + \max_{j \in [c] \setminus y} \mathbf{w}_j^T - \mathbf{w}_y^T \mathbf{x})
                                                                                                                                                                                                        ANNs:+flexible,nonlin,+layers(abstr),-may params
                                                                                                    Idea: Instead of cust. feats min \sum l(y_i; \sum w_j \phi_j(\mathbf{x}_i)) and choices,-noise sensitive
                                                                                                    learn feat param.s: \min_{\mathbf{w},\theta} \sum l(y_i; \sum w_i \phi(\mathbf{x}_i, \theta_i))
                                                                                                                                                                                                        k-Means: Pick centers of k clusters \hat{\mu} = \arg\min \hat{R},
                                                                                                    \phi(\mathbf{x},\theta) = \varphi(\theta^T\mathbf{x}); \varphi = \text{act. fun. e.g. } Sigm(z) = 0
                                                                                                                                                                                                       where \hat{R}(\mu) = \hat{R}(\mu_1, ..., \mu_k) = \sum_i \min_i ||\mathbf{x}_i - \mu_i||_2^2.
||\mathbf{w}||_0 = |\{i : w_i \neq 0\}|; \text{ "Sparsity trick": use } ||\mathbf{w}||_1 = \frac{e^z - e^{-z}}{1 + \exp(-z)}, \\ \text{tasso:min } \frac{1}{n} \sum_{i=1}^n (y_i - \mathbf{w}^T \mathbf{x}_i)^2 + \lambda ||\mathbf{w}||_1 (\text{inclds FS})}{1 + \exp(-z)}, \\ \text{ANN:nest.d comp (var) lin f.s comp w (fxd) nonlins 1. Init. cluster centers: } \mu^{(0)} = [\mu_1^{(0)}, ..., \mu_k^{(0)}]
                                                                                                                                                                                                        \negconv.\RightarrowNP-h.But:Lloyd's (local) heuristic O(knd):
                                                                                                    Forward propagation/ANN prediction:
                                                                                                                                                                                                        2. While not converged:
                                                                                                                                                                                                         a) For \mathbf{x}_i \in D: z_i^{(t)} = \arg\min_i ||\mathbf{x}_i - \mu_i^{(t-1)}||_2^2
                                                                                                                                                                                                         b) Update center as mean of assigned data pts
                                                                                                    2. For each layer l=1:L-1
                                                                                                          For j \in \text{Layer}_l, \text{set:} v_j = \varphi(\sum_{i \in \text{Layer}_{l-1}} w_{j,i} v_i)
                                                                                                                                                                                                                \mu_j^{(t)} = \frac{1}{n_j} \sum_{i:z^{(t)}=j} \mathbf{x}_i, where n_j = |\{i: z_i^{(t)} = j\}|
                                                                                                   3.For j \in \text{Layer}_L: f_j = \sum_{i \in \text{Layer}_{L-1}} w_{j,i} v_i
\textbf{KT: 1. Use w in Thm as ansatz, replacing w with} \quad \textbf{4.Predict} \quad y_j = f_j \ / \ y_i = \operatorname{sgn}(f_j) \ / \ y_j = \operatorname{arg max}_i f_i \ \mathbf{kMs} + + \ \operatorname{seeding:}(\mathbb{E}[\hat{R}(\mu^{(0)})] \le O(\log k) \min_{\mu} \hat{R}(\mu))
                                                                                                                                                                                                        1. Start w. rand. pt. \mathbf{x}_{i_1} as centr \mu_1^{(0)} = \mathbf{x}_{i_1},
                                                                                                    Or Alt: 1.For \mathbf{v}^{(0)} := \mathbf{x}
                                                                                                                                                                                                       2. For j = 2:k: Pick i_j with prob.:
                                                                                                    2.For l = 1 : L - 1 : \mathbf{v}^{(l)} := \varphi(\mathbf{W}^{(l)}\mathbf{v}^{(l-1)})
                                                                                                                                                                                                       \frac{1}{C} \cdot \min_{1 \leq l \leq j-1} d(\mathbf{x}_{i_j}, \mu_l^{(0)}) \text{ and set } \mu_j^{(0)} = x_{i_j}.
MS:Regul.,heuristic qu.m.s (elbow),info. theo. basis
 Poly: (\mathbf{x}^T\mathbf{x}+1)^d, Gaussian/RBF: e^{1||\mathbf{x}-\mathbf{x}'||_2^2/h^2}, Thm (UAT): Let \sigma be a contin. sigm. func.. Then \mathbf{PCA}(k=1):arg min \{\sum_{i=1}^n ||z_i\mathbf{w}-\mathbf{x}_i||_2^2, z_i^* = \mathbf{w}^T\mathbf{x}_i\} = \mathbf{w}^T\mathbf{x}_i
                                                                                                    \{G(x) = \sum_{j=1}^{N} \alpha_j \sigma(y_j^T x + \theta_j)\} \subset^{dense} C^0([0,1]^n).
                                                                                                                                                                                                       \arg\max_{\|\mathbf{x}\|=1} \sum (\mathbf{w}^T \mathbf{x}_i)^2 = \arg\max_{\hat{\mu}=0} \arg\max_{\|\mathbf{v}\|=1} \mathbf{w}^T \Sigma \mathbf{w} = \mathbf{v}_1 \text{ princ.}
                                                                                                    Prob: \mathbf{W}^* = \arg\min_{\mathbf{W}} \sum l(\mathbf{W}; \mathbf{y}_i, \mathbf{x}_i) not convex.
                                                                                                    Multi-loss: l(\mathbf{W}; \mathbf{y}, \mathbf{x}) = \sum l_i(\mathbf{W}, y_i, \mathbf{x})
                                                                                                                                                                                                       EV of \Sigma = \sum_{i=1}^{d} \lambda_i \mathbf{v}_i \mathbf{v}_i^T, \lambda_i \geq \lambda_{i+1} \geq 0
                                                                                                                                                                                                        (f: d \to k > 1): Sol: \mathbf{z}_i = \mathbf{W}^T \mathbf{x}_i = f(\mathbf{x}_i), \Sigma = "
                                                                                                    2. For t = 1, 2, ...:

\operatorname{arg\,min}_{\mathbf{W}\in\mathcal{O}^{||}(d\times k),\mathbf{Z}\in\mathbb{R}^{k\times n}}\sum||\mathbf{W}\mathbf{z}_i-\mathbf{x}_i||_2^2

                                                                                                        Pick (\mathbf{x}, \mathbf{y}) \in D U-randomly
                                                                                                                                                                                                        \mathbf{W} := (\mathbf{v}_1 | \cdot | \mathbf{v}_d) \in \mathbb{R}^{d \times k} \text{ orth} \equiv \mathbf{W}^T \mathbf{W} = \mathbf{I} \neq \mathbf{W} \mathbf{W}^T
                                                                                                        Take step: \mathbf{W} := \mathbf{W} - \eta_t \nabla_{\mathbf{W}} l(\mathbf{W}; \mathbf{y}, \mathbf{x})
                                                                                                                                                                                                        SVD:X = USV^T \Rightarrow 1st \ k \text{ p.c.} are 1st k \text{ cols of } V
                                                                                                    Backpropagation:
                                                                                                                                                                                                        ((Pf: n\Sigma = \mathbf{X}^T\mathbf{X} = \mathbf{V}\mathbf{S}^T\mathbf{U}^T\mathbf{U}\mathbf{S}\mathbf{V}^T = \mathbf{V}\mathbf{S}^T\mathbf{S}\mathbf{V}^T))
                                                                                                    1. For j \in \text{Layer}_{L+1}:
                                                                                                                                                                                                        \mathbf{K}\text{-PCA}(k=1): \arg\max_{\alpha} \{\alpha^T \mathbf{K}^T \mathbf{K} \alpha : \alpha^T \mathbf{K} \alpha = 1\}
                                                                                                        a) Compute error signal \delta_j = l_j'(f_j)
                                                                                                                                                                                                       Sol: \alpha^* = \frac{\mathbf{v}_1}{\sqrt{\lambda_1}}, \mathbf{K} = \sum \lambda_i \mathbf{v}_i \mathbf{v}_i^T, \lambda_1 \geq \cdots \lambda_d \geq 0
                                                                                                       b) For each unit i \in \operatorname{Layer}_L : \frac{\partial}{\partial w_{i,i}} = \delta_j v_i
                                                                                                                                                                                                       (k \ge 1): \alpha^{(i)} = \frac{\mathbf{v}_i}{\sqrt{\lambda_1}} \in \mathbb{R}^n \text{ for } 1 \le i \le k, \mathbf{K} = ",
                                                                                                    2.For l = L - 1:1 and j \in Layer_l:
                                                                                                        a) Error signal: \delta_j = \varphi'(z_j) \sum_{i \in \text{Layer}_{l+1}} w_{i,j} \delta_i \ f(\mathbf{x}) = \mathbf{z} = (z_i)_i^k = (\sum_j \alpha_j^{(i)} k(\mathbf{x}_j, \mathbf{x}))_i^k
                                                                                                                                                                                                        Center: \mathbf{K}' = \mathbf{K} - \mathbf{K}\mathbf{E} - \mathbf{E}\mathbf{K} + \mathbf{E}\mathbf{K}\mathbf{E}, \mathbf{E} = \frac{1}{2}\mathbf{1} \cdot \mathbf{1}^T
                                                                                                        b) For i \in \mathrm{Layer}_{l-1}: \frac{\partial}{\partial w_{i,i}} = \delta_j v_i
                                                                                                                                                                                                        Autoenc.s:Learn Id_d: f(\mathbf{x}; \theta) = f_2(f_1(\mathbf{x}; \theta_1); \theta_2),
                                                                                                                                                                                                       s.t. f_1: \mathbb{R}^d \to \mathbb{R}^k. NNA: take hidden layer as f_1(\mathbf{x})
                                                                                                    1. For j \in \text{Layer}_{L+1}:
                                                                                                                                                                                                       train \min_{\mathbf{W}} \sum ||\mathbf{x}_i - \mathbf{f}(\mathbf{x}_i; \mathbf{W})||_2^2 via bekprop SGD
                                                                                                        a) Compute error \delta^{(L)} = \mathbf{l}'(\mathbf{f}) := [l'(f_1), ..., l'(f_p)]
                                                                                                                                                                                                        \varphi = Id \ (\varphi \text{ act. func}) \Rightarrow f = PCA \text{ solution}
                                                                                                        b) Gradient \nabla_{\mathbf{W}(\mathbf{L})} l(\mathbf{W}; \mathbf{y}, \mathbf{x}) = \delta^{(L)} \mathbf{v}^{(L-1)T}
                                                                                                                                                                                                        Probmod: (\mathbf{x}_i, y_i) \sim P(\mathbf{X}, Y), h : \mathcal{X} \to \mathcal{Y}, risk:
                                                                                                    2.For l = L - 1:1:
                                                                                                                                                                                                        R(h) = \mathbb{E}_{\mathbf{X},Y}[l(y;h(\mathbf{x}))]; \text{Reg.:}
                                                                                                        a) Error: \delta^{(l)} = \varphi'(\mathbf{z}^{(l)}) \cdot_{pw} (\mathbf{W}^{(l+1)T} \delta^{(l+1)})
                                                                                                                                                                                                        R(h) = \int P(\mathbf{x}, y) l(y; h(\mathbf{x})) d\mathbf{x} dy;
                                                                                                       b) Gradient 
abla_{\mathbf{W}^{(l)}} l(\mathbf{W}; \mathbf{y}, \mathbf{x}) = \delta^{(l)} \mathbf{v}^{(l-1)T}
                                                                                                                                                                                                       Class.:R(h) = \mathbb{E}[1[Y \neq h(\mathbf{X})]];
                                                                                                    Init.:Keep \text{Var}[W] c<br/>nst acr. layers, avoid \exp/\text{van} \nabla
                                                                                                                                                                                                        h^*(x) = \arg\min_{\hat{y}} \mathbb{E}_Y[1[Y \neq \hat{y} | \mathbf{X} = \mathbf{x}]] =
                                                                                                   Glorot (tanh): w_{i,j} \sim \mathcal{N}(0, \frac{1}{n_{in}}) / \mathcal{N}(0, \frac{2}{n_{in} + n_{out}})
                                                                                                                                                                                                        \arg\max_{\hat{y}} P(Y = \hat{y} | \mathbf{X} = \mathbf{x})
```

```
E.g. LSR:
   R(h) = \mathbb{E}_{X,Y}[(Y - h(\mathbf{X}))^2] = \mathbb{E}[\min_h \mathbb{E}[(Y - h(\mathbf{X}))^2]]
h(\mathbf{X})^2 |\mathbf{X} = \mathbf{x}| \frac{dl}{dy} = 0 \mathbb{E}[(\mathbb{E}[Y|\mathbf{X} = \mathbf{x}] - h(\mathbf{X}))^2], \text{ i.e.}
 h^*(\mathbf{x}) = \mathbb{E}[Y|\mathbf{X} = \mathbf{x}] (Baves' opt. pred. for l^2)
 Practice: \hat{y} = \hat{\mathbb{E}}[Y|\mathbf{X}] = \int y \hat{P}(Y|\mathbf{X}) dy
MLE: \theta^* = \arg \max_{\theta} \hat{P}(y_1, ..., y_n | \mathbf{x}_1, ..., \mathbf{x}_n, \theta) \stackrel{iid}{=}
 \arg\min - \sum \log \hat{P}(y_i, \mathbf{x}_i, \theta). Easy to show ...
  Thm: f(y|\mathbf{x}) = \mathcal{N}(h^*(\mathbf{x}), \sigma^2)(y) \iff h^* = \hat{h} = LSE
 e.g. y_i \sim \mathcal{N}(\mathbf{w}^T \mathbf{x}_i, \sigma^2) \Rightarrow \hat{\mathbf{w}} = \arg\min \sum (y_i - \mathbf{x}_i)^2
 BV-T.o.:Pred.Err.=Bias<sup>2</sup>+Var+Noise=Exp.risk=
\mathbb{E}_D\mathbb{E}_{\mathbf{X},Y}[(Y-\hat{h}_D(\mathbf{X}))^2]; \mathbf{Noise}: \mathbb{E}_{\mathbf{X},Y}[(Y-h^*(\mathbf{X}))^2]; \mathbf{LS}: \hat{P}(y|\mathbf{x}) = \mathcal{N}(y; \hat{\mathbf{w}}^T\mathbf{x}, \sigma^2), \mathcal{A} = \mathbb{R}, C(y,a) = (y-1)
 Bias:\beta = \mathbb{E}_X[\mathbb{E}_D \hat{h}_D(\mathbf{X}) - h^*(\mathbf{X})]; Variance:
\mathbb{E}_{\mathbf{X}} \operatorname{Var}_{D}[\hat{h}_{D}(\mathbf{X})]^{2} = \mathbb{E}_{\mathbf{X}} \mathbb{E}_{D}[\hat{h}_{D}(\mathbf{X}) - \mathbb{E}_{D'}\hat{h}_{D'}(\mathbf{X})]^{2}; \ a)^{2} \Rightarrow a^{*} = \arg\min_{a \in \mathcal{A}} \mathbb{E}_{y}[C(y, a) | \mathbf{x}] \overset{\partial=0, \int}{=} \hat{\mathbf{w}}^{T} \mathbf{x},
  \beta(mle/lse)=0,use regul. trade bit of \beta for much Var.
\mathbf{MAP: \hat{w}} = \arg\max_{\mathbf{w}} P(\mathbf{w}|\mathbf{x}_{1:n}, y_{1:n}) \stackrel{Bayes'}{=} \arg\max_{\mathbf{w}} \frac{P(\mathbf{w})P(y_{1:n}|\mathbf{x}_{1:n}, \mathbf{w})}{P(y_{1}, \dots, y_{n}|\mathbf{x}_{1:n}, \dots, \mathbf{x}_{n})} = \arg\max_{\mathbf{w}} \log(\cdots)
 Thm:arg min<sub>w</sub> \sum l(\mathbf{w}^T \mathbf{x}_i; \mathbf{x}_i, y_i) + C(\mathbf{w}) =
 \arg \max_{\mathbf{w}} \Pi_i P(y_i | \mathbf{x}_i, \mathbf{w}) P(\mathbf{w}) = \arg \max_{\mathbf{w}} P(\mathbf{w} | D),
 C(\mathbf{w}) = -\log P(\mathbf{w}), l(\mathbf{w}^T \mathbf{x}_i; y_i) = -\log P(y_i | \mathbf{x}_i, \mathbf{w})
·MAP w. (y|\mathbf{x},\mathbf{w}) \sim \mathcal{N}(\mathbf{w}^T\mathbf{x},\sigma^2) + w_i \sim \mathcal{N}(0,\beta^2) is For t=1,2,3... | improve: red uncert of D
 \hat{w} = \arg\min_{\mathbf{w}} \frac{\sigma^2}{\beta^2} ||\mathbf{w}||_2^2 + \sum_i (y_i - \mathbf{w}^T \mathbf{x}_i)^2 = \operatorname{RR}(\frac{\sigma^2}{\beta^2})
 · " w.Lapl.prior(y|\mathbf{x}, \mathbf{w}) \sim \mathcal{L}(\mathbf{w}^T \mathbf{x}, b) \Rightarrow \mathbf{w} = \text{L1-RR}
 · Now come up w. new methods (improving
 robustness) by changing prior/l.f. e.g. Student's s-t Gen. models: predict P(\mathbf{x}, y) instead of P(y|\mathbf{x})
 Log. reg.: (y|\mathbf{x},\mathbf{w}) \sim \text{Ber}(\sigma(\mathbf{w}^T\mathbf{x})) (i.e. Bernoulli 1.Estimate prior on labels P(y)
noise) with \sigma(z) := \frac{1}{1 + \exp(-\mathbf{w}^T \mathbf{x})}. Now using MLE, 2.Estimate P(\mathbf{x}|y) \ \forall y \le c \Leftrightarrow P(\mathbf{x},y) = P(\mathbf{x}|y)P(y))
we find: \hat{\mathbf{w}} = \arg\min_{\mathbf{w}} \sum \log(1 + \exp(-y_i \mathbf{w}^T \mathbf{x}_i)) = 3. Obtain P(y|\mathbf{x}) = \frac{P(y)P(\mathbf{x}|y)}{Z}, Z = P(x) (Bayes)
(u^* \sum_{i=1}^{n} w_i^*) = \arg\min_{\mathbf{w}} \sum_{i=1}^{n} \log\sum_{i=1}^{n} w_i P(\mathbf{x}|\Sigma_i,\mu_i)
 \arg\min_{\mathbf{w}} \sum l_{logistic}(\mathbf{w}; \mathbf{x}_i, y_i) = \arg\min_{\mathbf{w}} \hat{R}(\mathbf{w})
Logistic SGD: (l_{\log} \approx l_P \text{ is convex & smooth! :-}) ) . Model feats: P(X_1,..,X_d|Y) \stackrel{iid}{=} \prod_{i=1}^d P(X_i|Y),
 1. Init w:
 2. For t=1,2,...:
          a) Pick (x, y) U-randomly
          b) Compute prob of misclass. with current
                       model \hat{P}(Y = -y|\mathbf{w}, \mathbf{x})) = (1 + \exp(y\mathbf{w}^T\mathbf{x}))
          c) Take step: \mathbf{w} = \mathbf{w} + \eta_t y \mathbf{x} \hat{P}(Y = -y | \mathbf{w}, \mathbf{x})
 Again, use MAP to get, regularized methods:
12 (Gauss. prior): \min_{\mathbf{w}} \sum l_{\log}(\mathbf{w}; y_i, \mathbf{x}_i) + \lambda ||\mathbf{w}||_2^2
   \mathbf{v} = \mathbf{v} \cdot 
c) Step: \mathbf{w} = \mathbf{w}(1 - 2\lambda \eta_t) + \eta_t y \mathbf{x} \Gamma(1 - -y_{\parallel} \mathbf{w}, \mathbf{x}_j) - \gamma_t \Gamma(1 - y_{\parallel} \mathbf{w}, \mathbf{x}_j)

11 (Laplace prior): \min_{\mathbf{w}} \sum l_{\log}(\mathbf{w}; y_i, \mathbf{x}_i) + \lambda ||\mathbf{w}||_1 \quad w_0 = \log \frac{\hat{p}_+}{1 - \hat{p}_+} + \sum_j d_j \frac{\hat{\mu}_{-,j}^2 - \hat{\mu}_{+,j}^2}{2\hat{\sigma}_+^2}, \quad w_j = \frac{\hat{\mu}_{+,j} - \hat{\mu}_{-,j}}{\hat{\sigma}_j^2}
 Classify: \hat{P}(y|\mathbf{x}, \hat{\mathbf{w}}) = (1 + \exp(-y\hat{\mathbf{w}}^T\mathbf{x}))
 K-LogR: \hat{\alpha} = \arg\min_{\alpha} \sum \log (1 + \alpha)
 \exp(-y_i \alpha^T \mathbf{K}_i) + \lambda \alpha^T \mathbf{K} \alpha, \mathbf{K} = (\mathbf{K}_1 | \cdots | \mathbf{K}_n)
Classify: \hat{P}(y|\mathbf{x},\hat{\alpha}) = (1 + \exp(-y \sum \alpha k(\mathbf{x}_i,\mathbf{x}))^{-1})
MC LogR:P(Y = i | \mathbf{x}, \mathbf{w}_{1:c}) = \frac{\exp(\mathbf{w}_i^T \mathbf{x})}{\sum \exp(\mathbf{w}^T \mathbf{x})} (w.l.o.g. MLE 4 \hat{p}_y and \hat{\mu}_y = (\hat{\mu}_{y,j})_j^d same as 4 NB
  \mathbf{w} = 0 for uniqueness). Cross-entropy loss:
 l_{CE}(y; \mathbf{x}, \mathbf{w}_{1:c}) = -\log P(Y = y | \mathbf{x}, \mathbf{w}_1, ..., \mathbf{w}_c)
In ANN: l_{CE}(Y = i, f_1, ..., f_c) = -\log \frac{\exp(f_i)}{\sum_{i=1}^{c} \exp(f_i)}
 SVM/Perc:+sometimes higher accuracy,+sparse
 sol's;-MC class difficult; LogR:+Class probs;-Dense
sols
 Decision Theory: C: \mathcal{Y} \times \mathcal{A} \to \mathbb{R}, \mathcal{A}=Action set
 Bayesian D.T.: Do a^* = \arg\min_{a \in A} \mathbb{E}_y[C(y, a)|\mathbf{x}]
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E.g.s: Ass. \hat{P}(y|\mathbf{x}) = \text{Ber}(y; \sigma(\hat{\mathbf{w}}^T\mathbf{x})), \mathcal{A} = \{\pm 1\},
                                                                                                                                                                                    C(y, a) = 1[y \neq a] \Rightarrow a^* = \arg\min \mathbb{E}[C(y, a)|\mathbf{x}] \stackrel{\text{...}}{=}
                                                                                                                                                                                   \operatorname{sgn}(\mathbf{w}^T\mathbf{x}) = \operatorname{arg\,max}_y \hat{P}(y|\mathbf{x}) \text{ Asym. Cs: } \hat{P}, \mathcal{A} = \text{"}, \text{ Categ.NB:} P(X_j = x|Y = y) = \theta_{x|y}^{(j)}, \sum_x \theta_{x|y}^{(j)} = 1
                                                                                                                                                                                    C(y,a) = c_{FP}1[y=-1,a=1] + c_{FN}1[y=1,a=-1] \cdot \text{MLE 4 cl. label dstr. } \hat{P}(Y=y) = \hat{p}_y = \frac{n_y}{n_y}
                                                                                                                                                                                     \iff p := P(y = +1|\mathbf{x}) > \frac{c_{FP}}{c_{FP} + c_{FN}}
                                                                                                                                                                                    "Doubtful" LR: \hat{P} = ", A = \{\pm 1, D\},
                                                                                                                                                                                    C(y, a) = 1[y \neq a, a \in \{\pm 1\}] + c1[a = D] \Rightarrow a^* =
                                                                                                                                                                                    \arg\min_{a\in A} \mathbb{E}_{y}[C(y,a)|\mathbf{x}] = y1_A + D1_{A^c},
                                                                                                                                                                                    Asym. Cs: \hat{P}, \mathcal{A} = ", C(y, a) =
                                                                                                                                                                                   c_1 \max(y-a,0) + c_2 \max(a-y,0) = \text{underest+overest } \hat{\theta} = \underset{\alpha_+ + n_+ - 1}{\arg \max_{\theta} P(\theta|y_1,...,y_n;\alpha_+,\alpha_-)} = \\ \Rightarrow a^* = \underset{\alpha_+ + n_+ + \alpha_- + n_- - 2}{\arg \min_{a \in \mathcal{A}} \mathbb{E}_y[C(y,a)|\mathbf{x}]} = \frac{\alpha_+ + n_+ - 1}{\alpha_+ + n_+ + \alpha_- + n_- - 2}; \text{ more e.g. } (\beta,\text{Ber}), (\text{Dir},\text{Cat}/\alpha_+) = \frac{\alpha_+ + n_+ - 1}{\alpha_+ + n_+ + \alpha_- + n_- - 2}; \text{ more e.g. } (\beta,\text{Ber}), (\text{Dir},\text{Cat}/\alpha_+) = \frac{\alpha_+ + n_+ - 1}{\alpha_+ + n_+ + \alpha_- + n_- - 2}; \text{ more e.g. } (\beta,\text{Ber}), (\text{Dir},\text{Cat}/\alpha_+) = \frac{\alpha_+ + n_+ - 1}{\alpha_+ + n_+ + \alpha_- + n_- - 2}; \text{ more e.g. } (\beta,\text{Ber}), (\text{Dir},\text{Cat}/\alpha_+) = \frac{\alpha_+ + n_+ - 1}{\alpha_+ + n_+ + \alpha_- + n_- - 2}; \text{ more e.g. } (\beta,\text{Ber}), (\text{Dir},\text{Cat}/\alpha_+) = \frac{\alpha_+ + n_+ - 1}{\alpha_+ + n_+ + \alpha_- + n_- - 2}; \text{ more e.g. } (\beta,\text{Ber}), (\text{Dir},\text{Cat}/\alpha_+) = \frac{\alpha_+ + n_+ - 1}{\alpha_+ + n_+ + \alpha_- + n_- - 2}; \text{ more e.g. } (\beta,\text{Ber}), (\text{Dir},\text{Cat}/\alpha_+) = \frac{\alpha_+ + n_+ - 1}{\alpha_+ + n_+ + \alpha_- + n_- - 2}; \text{ more e.g. } (\beta,\text{Ber}), (\text{Dir},\text{Cat}/\alpha_+) = \frac{\alpha_+ + n_+ - 1}{\alpha_+ + n_+ + \alpha_- + n_- - 2}; \text{ more e.g. } (\beta,\text{Ber}), (\text{Dir},\text{Cat}/\alpha_+) = \frac{\alpha_+ + n_+ - 1}{\alpha_+ + n_+ + \alpha_- + n_- - 2}; \text{ more e.g. } (\beta,\text{Ber}), (\text{Dir},\text{Cat}/\alpha_+) = \frac{\alpha_+ + n_+ - 1}{\alpha_+ + n_+ + \alpha_- + n_- - 2}; \text{ more e.g. } (\beta,\text{Ber}), (\text{Dir},\text{Cat}/\alpha_+) = \frac{\alpha_+ + n_+ - 1}{\alpha_+ + n_+ + \alpha_- + n_- - 2}; \text{ more e.g. } (\beta,\text{Ber}), (\text{Dir},\text{Cat}/\alpha_+) = \frac{\alpha_+ + n_+ - 1}{\alpha_+ + \alpha_+ + \alpha_- + n_- - 2}; \text{ more e.g. } (\beta,\text{Ber}), (\text{Dir},\text{Cat}/\alpha_+) = \frac{\alpha_+ + n_+ - 1}{\alpha_+ + \alpha_+ +
                                                                                                                                                                                   \hat{\mathbf{w}}^T \mathbf{x} + \sigma \Phi^{-1} (\frac{c_1}{c_1 + c_2})
                                                                                                                                                                                    Uncert. sampling: Pick ex. we r most uncert.
                                                                                                                                                                                  bout, maintain uncert. D_X = \{\mathbf{x}_1, ..., \mathbf{x}_n\}
                                                                                                                                                                                   Init D = \emptyset | viol. iid, can get stuck w bad models Prob: Non-convex, \Sigma_j's must stay sym-pos-def,
                                                                                                                                                                                        Est. \hat{P}(Y_i|\mathbf{x}_i) given D
                                                                                                                                                                                           Query label y_{i_t} and set D := D \cup \{(\mathbf{x}_{i_t}, y_{i_t})\}
                                                                                                                                                                                   Naive Bayes:O(cd), \sum_{y}^{z} P(Y=y) = \sum_{y \in \mathcal{Y}} p_y = 1 (\mu^*, \Sigma^*, w^*) = \arg\min - \sum_{i}^{n} \log \sum_{j}^{k} w_j \mathcal{N}(\mathbf{x}_i | \mu_j, \sigma_j)
                                                                                                                                                                                    with P(x_j|y) = \mathcal{N}(x_j|\mu_{y,j}, \sigma_{y,j}^2, j, j \leq d \text{ (indep feats)} \Sigma_j^* = \frac{\sum \gamma_j(\mathbf{x}_i)(\mathbf{x}_i - \mu_j^*)(\mathbf{x}_i - \mu_j^*)^T}{\sum \gamma_j(\mathbf{x}_i)}, w_j^* = \frac{1}{n} \sum \gamma_j(\mathbf{x}_i)
                                                                                                                                                                                   · Determine P(Y), \mu_{j,y}, \sigma_{j,y} by MLE (given D)
· MLE 4 class prior: \hat{p}_y = \frac{\{\{i: y_i = y\}| \ n = : \frac{n_y}{n}\}}{n}
                                                                                                                                                                                 - MLE 4 feat distr.: \hat{\mu}_{y,j} = \frac{1}{n_y} \sum_{i:y_i=y}^n x_{i,j}, (\mathbf{x}_i, y_i) E:Calculate \gamma_j^{(t)}(\mathbf{x}_i) given \mu^{(t)}, \Sigma^{(t)}, \mathbf{w}^{(t)}(\text{SSL:+y})
                                                                                                                                                                                  \hat{\sigma}_{y,j}^2 = \frac{1}{n_y} \sum_{i:y_i=y} (x_{i,j} - \hat{\mu}_{y,j})^2 · Prediction: y =
                                                                                                                                                                                    \arg\max_{y'} \hat{P}(y'|\mathbf{x}) = \arg\max_{y'} \hat{P}(y') \prod_{i}^{d} \hat{P}(x_i|y')
                                                                                                                                                                                  \text{Bin. cl.}/c = 2 \Rightarrow y = \operatorname{sgn} \log \frac{P(Y=1|\mathbf{x})}{P(Y=-1|\mathbf{x})} = \operatorname{sgn} f(\mathbf{x}) \ w_j^{(t)} = \frac{1}{n} \sum \gamma_j^{(t)}(\mathbf{x}_i), \ \mu_j^{(t)} = \frac{\sum \gamma_j^{(t)}(\mathbf{x}_i)\mathbf{x}_i}{\sum \gamma_j^{(t)}(\mathbf{x}_i)}, 
                                                                                                                                                                                    Prob: overconfidence, so dont use (contin) probs
                                                                                                                                                                                    \mathbf{Gn.GB:}O(cd^2), P(\mathbf{x}|y) \sim \mathcal{N}(\mu_y, \Sigma_y)(\mathrm{NB:}\Sigma_y = \mathrm{diag})
                                                                                                                                                                                 · MLE 4 distr. \hat{P}(\mathbf{x}|y) = \mathcal{N}(\mathbf{x}; \hat{\mu}_y, \hat{\Sigma}_y) with
                                                                                                                                                                                  \hat{\Sigma}_y = \frac{1}{n_y} \sum_{i:y_i = y} (\mathbf{x}_i - \hat{\mu}_y) (\mathbf{x}_i - \hat{\mu}_y)^T and
                                                                                                                                                                                    · Prediction: same as with NB
                                                                                                                                                                                   c = 2 \Rightarrow f(\mathbf{x}) = \log \frac{p}{1-p} + \frac{1}{2} [\log \frac{|\hat{\Sigma}_-|}{|\hat{\Sigma}_+|} + (\mathbf{x} - \mathbf{x})]
                                                                                                                                                                                    (\hat{\mu}_{-})^T \hat{\Sigma}_{-}^{-1} (\mathbf{x} - \hat{\mu}_{-}) - (\mathbf{x} - \hat{\mu}_{+})^T \hat{\Sigma}_{+}^{-1} (\mathbf{x} - \hat{\mu}_{+})
                                                                                                                                                                                    F's LDAO(d):GB w. c=2, p=.5, \hat{\Sigma}_{-}=\hat{\Sigma}_{+}=:\hat{\Sigma} Thm: EM equiv to following procedure:
                                                                                                                                                                                    · Predict y = \operatorname{sgn}(f(\mathbf{x})) = \operatorname{sgn}(\mathbf{w}^T\mathbf{x} + w_0) with
                                                                                                                                                                                    \mathbf{w} = \hat{\Sigma}^{-1}(\hat{\mu}_{+} - \hat{\mu}_{-}), w_0 = \frac{1}{2}(\hat{\mu}_{-}^T \hat{\Sigma}^{-1} \hat{\mu}_{-} - \hat{\mu}_{+}^T \hat{\Sigma}^{-1} \hat{\mu}_{+})
                                                                                                                                                                                    f(\mathbf{x}) = \log \frac{p(\mathbf{x})}{1 - p(\mathbf{x})} \equiv p(x) = \sigma(f(\mathbf{x})) so this is LR!
                                                                                                                                                                                    vs LR:+outliers/P(x), -norm. X else not robust
Bayesian optm. dec.: dec. taken if P(y|\mathbf{x}) known
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vs PCA: LDA proj. 1-d subsp. 2 max.
                                                                                               Var(between class) Var(within class), PCA(k=1) only max. (all) var.
c(y,u) = c_F p_1[y=-1,u-1] + c_F N_1[y=1,u-1]
c_+ = \mathbb{E}[C(y,1)|\mathbf{x}] < c_- = \mathbb{E}[C(y,-1)|\mathbf{x}] \quad \text{MLE 4 dstr.feat.s } \theta_{x|y}^{(j)} = \frac{|\{X_j=x,Y=y\}|}{n_y}, O(exp(d))! \text{ flexible nonlin func (e.g. NN) } \mathbf{GANs}: \text{ Train } G \text{ w.}
                                                                                              y = \arg\max_{\eta'} \hat{P}(y'|\mathbf{x}) = \arg\max_{\eta'} \hat{P}(y') \prod \hat{P}(x_{\bar{\eta}}|y) noise Z while training D discriminator 2 distg.
                                                                                              Mixed distr: NB doesn't require feat.s have i.d.; e.g.; between X from G and raw real X
                                                                                             P(x_{1:20}|y) = \prod_{i=1}^{10} \text{Cat}(x_{i}|y,\theta) \prod_{i=1}^{10} \mathcal{N}(x_{i};\mu_{i|y},\sigma_{i|y}^{2})
                                                                                              Prior over param.s:
A = [\hat{P}(y|\mathbf{x}) \geq 1 - c], \text{i.e.only pick likely class if sure } P(\theta|y_{1:n}) = \frac{1}{Z}P(\theta)P(y_{1:n}|\theta), Z = \int P(\theta)P(y_{1:n})d\theta \quad D : \mathbb{R}^d \to [0,1] \text{ wants: } D(x) = 1[x \text{ is real}];
                                                                                              Prior dstr. and l.h.f. conjugate if post. dstr. stays G: \mathbb{R}^m \to \mathbb{R}^d wants: D(G(z)) = 1
                                                                                              as prior; e.g. l.h.f.:Bin., Prior:\beta(\theta; \alpha_+, \alpha_-), Obs:
                                                                                              D_{n_{+},n_{-}}, Post:\beta(\theta; \alpha_{+} + n_{+}, \alpha_{-} + n_{-}); MAP:
                                                                                              MultiNom),(G.s,G.s);Use pairs as regul.s
                                                                                             GMMs:P(\mathbf{x}|\mu, \Sigma, \mathbf{w}) = \sum_{i}^{c} w_{i} \mathcal{N}(\mathbf{x}; \mu_{i}, \Sigma_{i}) \text{ (convex) } \mathbf{w}_{D}^{(t+1)} = \mathbf{w}_{D}^{(t)} + \eta_{t} \nabla_{\mathbf{w}_{D}} M(\mathbf{w}_{G}^{(t)or(t+1)}, \mathbf{w}_{D})
                                                                                              L(w_{1:k}, \mu_{1:k}, \Sigma_{w:k}) = -\sum_{i}^{n} \log \sum_{j}^{k} w_{j} \mathcal{N}(\mathbf{x}_{i} | \mu_{j}, \Sigma_{j})
                                                                                              unlike GBCs z in P(z, \mathbf{x}) = w_z \mathcal{N}(\mathbf{x} | \mu_z, \Sigma_z) is unobs. feat.s), "cannot compute l.h. on holdout set
                                                                                              Hard EM: * Init params \theta, * For t=1,2...:
  Pick most uncer.: i_t = \arg\min_i |0.5 - \hat{P}(Y_i|\mathbf{x}_i)| E: Pred.cl.: \forall i : z_i^{(t)} = \arg\max_z P(z|\mathbf{x}_i, \theta^{(t-1)}) = \mathbf{PSt}: X_i \sim f(\cdot|\theta_0) w. unknown \theta_0 \in \Theta the likelihood
                                                                                              \arg\max_{z} P(z|\theta^{(t-1)})P(\mathbf{x}_{i}|z,\theta^{(t-1)}).
                                                                                            M: Compute MLE as for GBC:
                                                                                              \theta^{(t)} = \arg\max_{\theta} P(D^{(t)}|\theta) \text{ w. } D = ((\mathbf{x}_i, z_i^{(t)}))_i.
                                                                                             s.t. \mu_j^* = \frac{\sum \gamma_j(\mathbf{x}_i)\mathbf{x}_i}{\sum \gamma_j(\mathbf{x}_i)}
                                                                                              (For SSL add. require \gamma_i(\mathbf{x}_i) = 1[j = y_i] if y known)
                                                                                              \textbf{Soft-EM:} \\ \textbf{While not converged:} \quad |E=exp.suff.st.
                                                                                            \begin{array}{l} \gamma_j^{(t)}(\mathbf{x}_i) = \frac{w_j P(\mathbf{x}_i | \Sigma_j, \mu_j)}{\sum w_l P(\mathbf{x}_i | \Sigma_l, \mu_l)} (/1\{j = y_i\} \text{ if } y_i \text{ known}) \\ \text{M:Fit clusters to weighted data } |\text{M} = \text{Max.l.h.sol} \end{array}
                                                                                            \Sigma_{j}^{(t)} = \frac{\sum \gamma_{j}^{(t)}(\mathbf{x}_{i})(\mathbf{x}_{i} - \mu_{j}^{(t)})(\mathbf{x}_{i} - \mu_{j}^{(t)})^{T}}{\sum \gamma_{i}^{(t)}(\mathbf{x}_{i})} (\text{Optn.add.on}\Sigma)
                                                                                              We can avoid degeneracy/ovrftng by \Sigma_i^{(t)} + = \nu^2 \mathbf{I}
                                                                                             Initing?w^{(0)} \sim U, \mu^{(0)} = \text{rand/k-M} + +, \sigma = \text{sph./}\hat{\sigma}^2 I
                                                                                              (CV 4 k works i.C.2 kMs, try max log-l.h. on D_{val})
                                                                                              Soft(asgn)EM: higher l.h.s cuz better w cltr ovrlps
                                                                                              \lim_{\sigma \to 0} SEM(\sigma^2 I) \sim \text{k-M;L's h} \sim HEM(\text{sph.}\Sigma = \sigma^2 I)
                                                                                              Alg Props:Mon.incr. l.h.;GMM guar. 2 conv. loc.
                                                                                             GMBC: P(\mathbf{x}|y) = \sum_{j=1}^{n_y} w_j^{(y)} \mathcal{N}(\mathbf{x}; \mu_j^{(y)}, \Sigma_j^{(y)})
                                                                                              Dens.est.: Model P(\mathbf{x}) w. GMM but P(y|\mathbf{x}) discr.ly \mu = \mathbb{E}[\mathbf{X}]; Var(\mathbf{a}^T\mathbf{X}) = \mathbf{a}^T \Sigma \mathbf{a}, \mathbf{a} \in \mathbb{R}
                                                                                               ·E-step: Q(\Theta; \Theta^{(t-1)}) =
                                                                                                              \mathbb{E}_{z_{1:n}}[\log P(x_{1:n}, z_{1:n}|\Theta)|x_{1:n}, \Theta^{(t-1)}]
                                                                                                              = \sum_{i=1}^{n} \sum_{z_i}^{k} \gamma_{z_i}(x_i) \log P(x_i, z_i | \Theta)
                                                                                               ·M-step: \Theta^{(t)} = \arg \max_{\theta} Q(\Theta; \Theta^{(t-1)})
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Thm: EM monot.ly incr. l.h. (=P(x_{1:n}, z_{1:n}|\Theta)).
Cor: For Gauss mixt. this means EM guar. loc.
 Impl. gen. mod.s: Learn \mathbf{X} = G(\mathbf{Z}; \mathbf{w}) w. Z
 "simple" distr data (e.g. P(Z) = \mathcal{N}(0, \Sigma)), G
"Use discriminative learning to train generative
 Objective: \min_{\mathbf{w}_G} \max_{\mathbf{w}_D} M(\mathbf{w}_G, \mathbf{w}_D) =
 \min_{\mathbf{w}_C} \max_{\mathbf{w}_D} \mathbb{E}_{\mathbf{x} \sim \text{Data}} \log D(\mathbf{x}; \mathbf{w}_D) +
 \mathbb{E}_{\mathbf{z} \sim \mathcal{N}} \log(1 - D(G(\mathbf{z}; \mathbf{w}_G); \mathbf{w}_D)) (Saddle pt./GT)
 Simul. (mini batch) GD:
\mathbf{w}_G^{(t+1)} = \mathbf{w}_G^{(t)} - \eta_t \nabla_{\mathbf{w}_G} M(\mathbf{w}_G, \mathbf{w}_D^{(t)}),
Probs: Data mem.⇒degen. sols,
 oscillations/divergence, mode collapse (special, on
 func. (l.h.(f.)) is L(\theta) = f(x_1, ..., x_n | \theta) \stackrel{iid}{=} \prod_{i=1}^n f(x_i | \theta)
 The MLE is then \hat{\theta} = \arg \max_{\theta \in \Theta}
 \cdot \varphi(\cdot) < t\varphi(x_1) + (1-t)\varphi(x_2) \Rightarrow \varphi(\mathbb{E}[X]) < \mathbb{E}[\varphi(X)]
 k(x,y) := (x^T y)^m, x, y \in \mathbb{R}^d impl. repr. mon.s of
 degree = m, there are \binom{d+m-1}{d}, O(d^m) \to O(d)
 k(x,y) := (1+x^Ty)^m impl. repr. mon.s of degree
 \leq m there are \binom{d+m}{m}
 Eigen.: A \in \mathbb{R}^{n \times n}, \exists EV basis \Rightarrow A = QDQ^{-1}
LU: Gauss. Elim., A \in \mathbb{R}^{m \times n} \Rightarrow A = LU
 \mathbf{QR}/\mathbf{QU}: Gr.-Schm., A \in \mathbb{R}^{n \times n} \Rightarrow A = QU
SVD: A \in \mathbb{R}^{m \times n}, U \in \mathbb{R}^{m \times m}, V \in \mathbb{R}^{n \times n}, \Sigma \in \mathbb{R}^{n \times n}
  \mathbb{R}^{m \times n} : A = U \Sigma V^T
Cholesky: A \in \mathbb{R}^{n \times n}, sym-pos-def \Rightarrow A = LL^T
 Pos-def: \forall x \in \mathbb{R}^n \setminus 0 : x^T A x > 0 \iff \sigma(A) \subset \mathbb{R}_{>0}
 \exists x : Ax = b \iff \det A \neq 0 \iff [Ax = 0 \equiv x = 0]
 \cdot \det(\mathbf{X}^T \mathbf{X}) \neq 0 \iff \exists ! \mathbf{w} = \arg\min \sum (y_i - \mathbf{w}^T \mathbf{x}_i)^2
Counter-example: \mathcal{D} = \{(0,0)\} has \infty sols
 \cdot \frac{\partial \mathbf{x}^T \mathbf{a}}{\partial \mathbf{x}} = \mathbf{a}; \ \frac{\partial \mathbf{a}^T \mathbf{X} \mathbf{b}}{\partial \mathbf{X}} = \mathbf{a} \mathbf{b}^T; \ \frac{\partial \mathbf{x}^T \mathbf{A} \mathbf{x}}{\partial \mathbf{x}} = (\mathbf{A} + \mathbf{A}^T) \mathbf{x}
LTP: \bigsqcup_{\mathbb{N}} A = \overset{\circ}{\Omega} \Longrightarrow P(B) = \overset{\circ}{\Sigma} P(B|A_i) P(A_i)
Bayes' rule: P(A|B) = P(B|A) \frac{P(A)}{P(B)}
P(A_1,..,A_n) = P(A_1)P(A_2|A_1) \cdot P(A_n|A_1,..,A_{n-1})
Norm Distr.: p(x|\mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp(-\frac{(x-\mu)^2}{2\sigma^2});
f(\mathbf{x}) = \frac{1}{(2\pi)^{n/2} \sqrt{|\det(\Sigma)|}} \exp\left(-\frac{1}{2} (\mathbf{x} - \mu)^T \Sigma^{-1} (\mathbf{x} - \mu)\right)
 C.M.: \Sigma = \mathbb{E}[(\mathbf{X} - \mu)(\mathbf{X} - \mu)^T] = (\text{Cov}(X_i, X_i))_{i,i}
Beta: f(x) = \frac{\Gamma(\alpha_1 + \alpha_2)}{\Gamma(\alpha_1)\Gamma(\alpha_2)} x^{\alpha_1 - 1} (1 - x)^{\alpha_2 - 1} 1_{(0, 1)},
\Gamma(a) \int_0^\infty t^{a-1} e^{-t} dt; Lapl Distr: \frac{1}{2h} \exp(-\frac{|x-\mu|}{h})
St.'s-t:\Gamma(\frac{\nu+1}{2})/(\sqrt{\nu\pi}\Gamma(\frac{\nu}{2}))(1+\frac{x^2}{\nu})^{-\frac{\nu+1}{2}}
\mathbf{MN}(\mathbf{w}.\ \mathbf{repl.}): \frac{N!}{n_1!\cdots n_{r!}!} p_1^{n_1}\cdots p_k^{n_k!}
\mathbf{MvHG}(\text{wo. repl.}):(\prod_{i=1}^{c} {K_i \choose k_i})/{N \choose n}
```