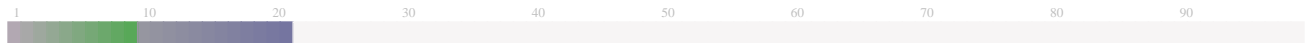


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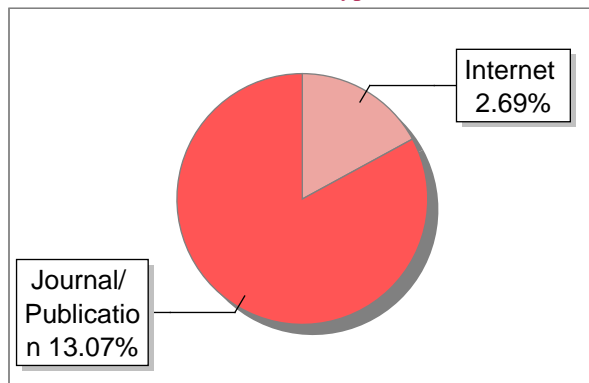
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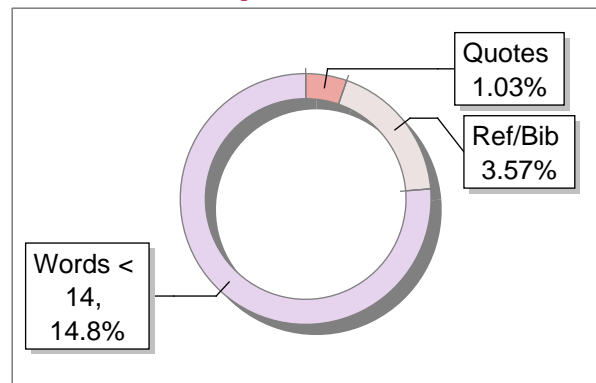
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## ABSTRACT

Traffic sign is the <sup>36</sup>important part of the traffic system. It is mandatory to follow traffic sign and obey traffic rules to ensure surety. Road safety is important for both pedestrian <sup>22</sup>and drivers. <sup>45</sup>There are many factors affecting road safety like road conditions, traffic signs, weather conditions, conjected roads <sup>22</sup>and the most important thing is <sup>26</sup>people who are not following the traffic signs. The traffic sign recognition system plays a vital function and it provides timely road information to the driver, and may ensure the safety of life on the road. Here, selected signs was taken and worked for traffic sign detection, <sup>4</sup>we used a convolutional neural network (CNN) individually to detect and recognize the traffic signs. Driver will recognize the traffic sign and get alert so unwanted accidents might be avoided.

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## Chapter 1

### INTRODUCTION

#### 1.1 INTRODUCTION ON ROAD SAFETY SIGNS

The trafficking framework is incomplete without a traffic sign.. <sup>20</sup> It is basic to follow the traffic signs and comply with traffic rules to guarantee security. Street wellbeing is a significant worry for the two people on foot and drivers. Plenty <sup>13</sup> of factors are there which influence the well-being of the street like street conditions, traffic signs, weather patterns, blocked streets, and so on. Among them, the most crucial one is traffic signs. At times drivers misread these traffic signs <sup>33</sup> which is one of the contributing variables to mishaps. With the blast of the auto business, they are zeroing in on executing independent vehicles. <sup>15</sup> It is expected to be more secure and more effective. Traffic sign grouping is a significant part of independent vehicles. <sup>32</sup> It ought to be done effectively to control street mishaps and to encourage the believability of independent vehicles. In any case, this could imperil the trafficking framework. Characterizing traffic signs is as yet a difficult example acknowledgment issue for PC frameworks. Ordinary Methods like AI Algorithms have been utilized in rush hour gridlock sign characterization. AI is a field that had outgrown the field of man-made consciousness, is of most extreme significance since it empowers the machines to acquire human-like insight without express programming. Because of the misfortune in handmade elements, a heap of profound learning calculations have been advanced to naturally <sup>42</sup> become familiar with the elements through the various secret layers in a profound brain organization. Profound learning is the investigation of fake brain organizations and related AI calculations that contain multiple secret layers. Profound learning permits computational <sup>23</sup> models that are made out of different handling layers to learn portrayals of information with different

degrees of deliberation Deep learning has reliably worked in its capacity to give precise acknowledgment and forecast. So <sup>5</sup> Deep learning outperforms Machine Learning calculations. This paper proposes a CNN model of profound nature CNN Model by adding four thick layers or completely associated layers. Since a completely associated layer learns highlights from every one of the mixes of the elements of the past layers, it advances profoundly.

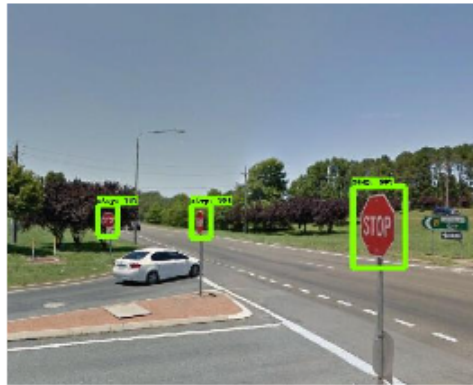


Figure 1.1.1 Diagram <sup>14</sup> of Traffic sign classification.

## 1.2 <sup>6</sup> PROJECT OBJECTIVE:

- The ultimate aim of the project is to alert the driver by the automatically recognizing the traffic signs which is present along the road using deep learning. This project is <sup>2</sup> to detect the traffic sign and help the driver to drive carefully and also to avoid accidents
- As per available literature, very little body of research is attempted to detect the traffic sign automatically.

### 1.3 PROJECT SCOPE:

- The Scope of this task is to make things simple for the individual who is driving the vehicle, which offers the data about the traffic hints he will cross.
- The traffic signs improve traffic security by illuminating the driver regarding speed cut-off points or potential perils, for example, cold streets, approaching street works or passer-by intersections.

## Chapter 2

### LITERATURE SURVEY

V.abdulRahimanet al[4] proposed about The detection and identification of traffic signs is handled by a vision-based vehicle guiding system. The system collects data from the road ahead and supports the driver in making quick decisions, making driving safer and easier.

Arturo de la Escaleraet al [5] recommendabout traffic signs give drivers with extremely useful road information in order to make driving safer and easier. Traffic signs, we believe, should serve the same purpose for autonomous cars. They are meant to be quickly identified by human drivers due to their distinct colour and form from the surrounding surroundings.

KedkarnChaiyakhan et al [1]recommended about A traffic sign categorization system is a feature of a driving assistance system that warns and advises the driver on the meaning of traffic signs. We proposed the idea of automatically classifying each type of data in this study of directional signs A publicly available dataset was used to test the proposed approach.The main contribution offered in this research is traffic sign categorization using support vector machines and image segmentation. For classification, the image segmentation algorithm region of interest (ROI) with normal direction feature utilising SVM linear kernel function is effective.

Min Shi,Haifeng,et al [2] proposed about One of the key tasks of many traffic sign identification systems is to classify the shapes of traffic signs. They used support vector machines to create a shape-based classification model. The major

<sup>18</sup>goal of this project was to recognise seven <sup>17</sup>different types of traffic sign shapes and five different types of speed restriction signs. The data was represented to <sup>27</sup>the SVM for training and testing using two types of features: binary image and Zernike moments.

Min Shiet al [3] suggested about The Intelligent Transportation System (ITS) is a system that uses sophisticated technology to create a safe, efficient, and integrated transportation environment. <sup>3</sup>The detection and recognition of road signs is a key aspect of ITS, which provides ways to collect real-time traffic data for processing at a central location. This project will create <sup>2</sup>a road sign recognition model based on AI and image analysis technologies that uses the Support Vector Machines machine learning method to recognise road signs.

## **Chapter 3**

### **PROBLEM STATEMENT**

A good answer to this problem would be to create machines that are environmentally conscious. As a result, safe vehicle driving is becoming a hot concern in a variety of areas, from tiny ventures to huge automobile manufacturing. However, this subject presents several concerns and issues. It is necessary to determine the width of the road's margins, recognise road signs, traffic signals, pedestrians, and other items that contribute to safe driving. There are several approaches to solve these problems.

## Chapter 4

### SYSTEM ANALYSIS

#### 4.1 EXISTING SYSTEM

The past exploration was a picture classifier in view of an AI calculation (KNN). AI (ML) is the specialized investigation of calculations and measurable models that PC frameworks use to do an undertaking effectively without using unequivocal directions, rather depending on models and derivation.

##### Disadvantages:

- Less accuracy
- It's not work well with image data

#### 4.2 PROPOSED SYSTEM

This research implemented a CNN model to enhance the accuracy of traffic sign classification. Initially, Data pre-processing was done, which consists of Gray Scale conversion, Histogram Equalization, and Normalization on the GTSRB dataset. Data pre-processing is followed by Data augmentation. Data augmentation increased the number of training data to prevent overfitting. After that, the TS CNN model was implemented and trained with the GTSRB dataset

##### Data Pre-processing:

- Gray Scale Conversion
- Histogram Equalization
- Normalization

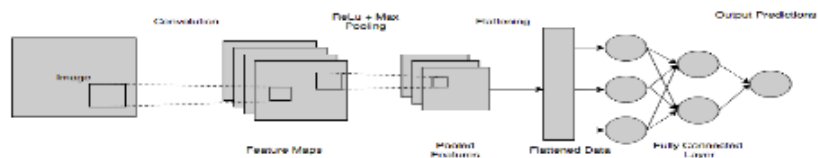


Figure 4.1.1 CNN algorithm layers



## **Chapter 5**

### **SYSTEM REQUIREMENTS**

#### **5.1 HARDWARE REQUIREMENTS**

- Laptop/System
- Minimum 4GB RAM.
- i5/i7 Processors
- Stable Internet connection
- 1GB free of Hard disk space / 500mb free of SSD

#### **5.2 SOFTWARE REQUIREMENTS**

- Operating System: Windows (Any version)
- Python Idle version 3.7
- Python packages
- Web browser: Microsoft Edge/Firefox/Google Chrome.

## Chapter 6

### METHODOLOGY

#### 6.1 STEPS

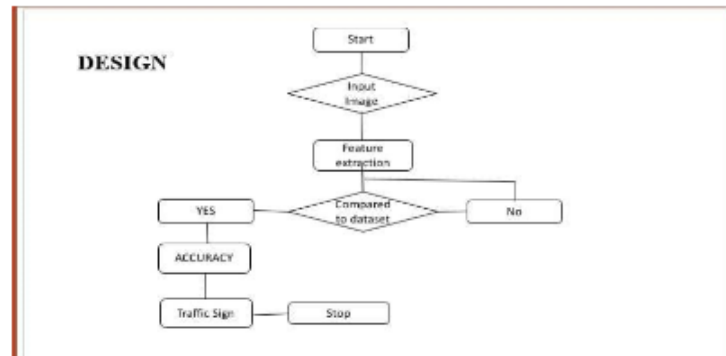


Figure 6.1.1 Design for Traffic sign classification

- Gather the information needed for training. After identifying some of the traffic signs, and gathered the datasets of traffic signs.
- After collecting the data pre-processing is done, it is nothing but image resizing. Removing the missing or irrelevant information
- After that, data is trained in order to anticipate the outcome. They have trained the data that was acquired after using the pre-processing approach.
- After training is completed, all the trained data will be stored in a file called pickle file. once this file is created, A file can be used for testing purpose how many times they want and it is also need not to be trained again
- Then it will predict what kind of traffic sign the input image is and also it will predict the accuracy, that is how much percentage the input image matches to the dataset image and then the accuracy will be calculated.

#### 6.2MODULES

##### 6.2.1DATA COLLECTION

In data collection process to collect a different types of traffic sign images for Kaggle training purpose.

### 6.2.2 DATA PRE-PROCESSING

The adjustments we do to our data before passing it to the algorithm are referred to as pre-processing. Data The raw data is converted into an understandable data set using a pre-processing approach. In other words, anytime data is received from numerous sources, it is collected in a raw format that makes analysis impossible.

### 6.2.3 DATA TRAIN

The data used to train an algorithm or deep learning model to anticipate the outcome you want it to predict is referred to as training data. The performance of the algorithm you're applying to train the machine is measured using test data.

### 6.2.4 MODEL CREATE

A neural network is a simplified model of how the human brain processes information. It models a large number of interconnected processing units that resemble abstract representations of neurons. The processing elements are organised into layers.

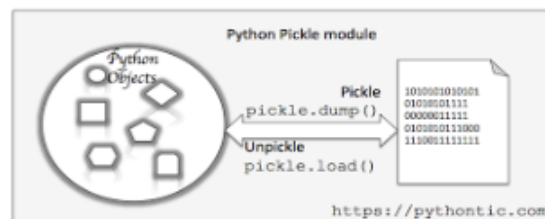
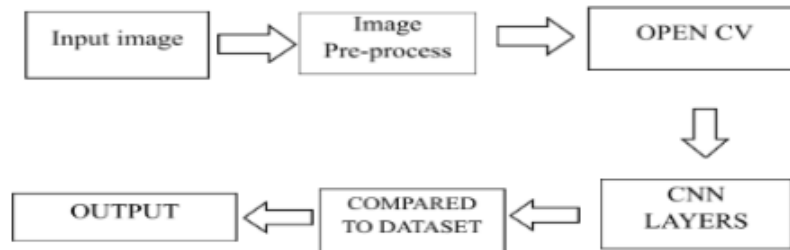


Figure 6.2.1 Creating the model

### 6.2.5 MODEL PREDICTION

Predictive analysis is a mathematical procedure that analyses patterns in a collection of input data to predict future events or outcomes. It's an important part of predictive analytics, a sort of data analytics that forecasts activity, behaviour, and trends using based on prior data.



**Figure 6.2.2 Block Diagram**

## Chapter 7

### MODEL & TRAINING

#### 7.1 DATA COLLECTION

Collecting Datasets of traffic sign symbols from a particular platform like Kaggle(<https://www.kaggle.com/datasets/shanmukh05/traffic-sign-cropped>)



Figure 7.1.1 Traffic sign dataset

Name	Date modified	Type	Size
DANGERTURN	5/3/2022 6:18 PM	File folder	
HOSPITAL	5/3/2022 6:18 PM	File folder	
NOPARKING	5/3/2022 6:21 PM	File folder	
SCHOOLZONE	5/3/2022 6:23 PM	File folder	
STOP	5/3/2022 6:24 PM	File folder	
TURNRIGHT	5/3/2022 6:21 PM	File folder	

Figure 7.1.2 Important traffic

## **Chapter 8**

### **IMPLEMENTATION**

#### **8.1 LIBRAIES USED**

- Open CV
- TensorFlow
- Keras
- NumPy

##### **8.1.1 OPEN CV**

OpenCV is an open-source computer vision, machine learning, and image processing toolkit. Python, C++, Java, and more programming languages are supported by OpenCV. It can analyse photos and movies to recognise items, people, and even human handwriting.

In the categorization of brain strokes, an open CV is employed to interpret the images. The imread syntax <sup>31</sup> is used in the image reading process in CV2.

##### **8.1.2 TENSORFLOW**

TensorFlow is an open-source AI application improvement system. It's an emblematic math tool compartment that performs many errands including profound brain network preparing and deduction utilizing dataflow and differentiable programming. Designers can utilize different instruments, systems, and local area assets to develop AI applications. Google TensorFlow is presently the most notable profound learning library in the world. AI is utilized by Google in each of its items to improve search, interpretation, picture subtitling, and suggestions.

### 8.1.3 KERAS

Keras is a high-level neural network API that may be used with Tensor Flow, Theano, and CNTK. It has a high-level, user-friendly, modular, and extendable API that allows for quick experimentation. Keras may be used on both the CPU and the GPU. Francois Chollet created and maintains Keras, which is part of the Tensor Flow core and is Tensor Flow's preferred high-level API.

Keras includes the two most popular Keras models (Sequential and Functional), as well as the core layers and certain Pre-Processing features.

### 8.1.4 NUMPY

NumPy, or Numerical Python, is a library that contains multidimensional array objects and a collection of functions for manipulating them. NumPy allows you to conduct mathematical and logical operations on arrays.

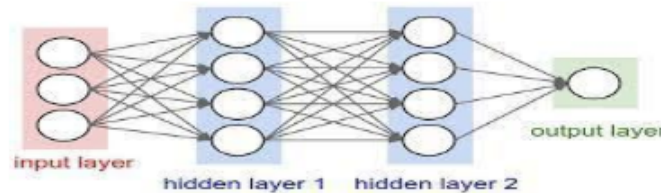
## 8.2 ALGORITHM USED

**CNN:** The info picture is changed utilizing a convolution layer to extricate highlights from it. The image is convolved with a bit in this change. A bit is a little grid that is more modest in level and width than the image to be convolved. A convolution lattice or convolution veil is one more name for it.

It requires input information, a channel, and a component map, in addition to other things.

Expect the info is a variety picture made out of a 3D grid of pixels. This suggests the information will have three aspects, which relate to RGB in an image.

A component identifier, otherwise called a bit or a channel, will navigate over the picture's responsive fields, checking for the presence of the element. Convolution is the term for this system.



### 8.2.1 Convolution neural network algorithm

## 8.3 LAYERS IN CNN

- Pooling layer
- Flatten layer
- Fully connected layer

### 8.3.1 POOLING LAYER

Downsampling, also known as pooling layers, is a dimensionality <sup>12</sup>reduction technique that reduces the number of factors in the input. The pooling process sweeps a filter across the whole input, similar to the convolutional layer, however this <sup>37</sup>filter does not contain any weights. Instead, the kernel uses an aggregation function to populate the output array from the values in the receptive field.

### 8.3.2 FLATTEN LAYER

The flatten function reduces multi-dimensional input tensors to a single dimension, allowing you to model your input layer and create your neural network model, then effectively transfer those inputs to each and every neuron in the model.

### 8.3.3 FULLY CONNECTED LAYER



- The full-connected layer's name is self-explanatory. In partly linked layers, the pixel values of the input picture are not directly connected to the output layer, as previously stated.
- Each node in the output layer, on the other hand, links directly to a node in the preceding layer in the fully-connected layer.
- This layer performs classification tasks based on the characteristics retrieved by the preceding layers and their various filters.

## Chapter 9

### RESULTS

Traffic sign characterization is utilized to perceive traffic signs which is available along the road. Some guidelines are additionally shown for not many traffic signs. If the result picture is peril sign, then an alarm sound will be produced. If the result picture is school zone or medical clinic zone, then, at that point, a voice message like "go sluggish school is close" and "Kindly don't horn" will be produced. So, it will order the traffic signs and caution the driver so the gamble of mishaps can be diminished.



**Figure 9.1.1 Result Analysis**



**Figure 9.1.2 Traffic Sign detection**

## **Chapter 10**

### **CONCLUSION**

The <sup>30</sup> Traffic Sign Classification using the TS CNN Model was developed using the GTSRB dataset. To improve contrast and resolution, data pre-processing processes were done to the dataset. Data Augmentation is used after Data Pre-processing to increase the amount of photos in the training samples to reduce overfitting. Our model obtained a substantially higher accuracy of 98.44 percent on the test data. Current state-of-the-art algorithms are outperformed by this strategy. The goal in the future is to use CNN variants to increase the accuracy of traffic sign categorization.

## Chapter 11

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