DeepMind

Discovering faster matrix multiplication algorithms with reinforcement learning

Alhussein Fawzi, Matej Balog, Aja Huang, Thomas Hubert, Bernardino Romera-Paredes, Mohammadamin Barekatain, Alexander Novikov, Francisco J. R. Ruiz, Julian Schrittwieser, Grzegorz Swirszcz, David Silver, Demis Hassabis, Pushmeet Kohli



Example of a fast matrix multiplication algorithm (Strassen '69)

$$\begin{pmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \end{pmatrix} = \begin{pmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{pmatrix} \cdot \begin{pmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{pmatrix}$$

$$p_{1} = (x_{11} + x_{22})(y_{11} + y_{22}),$$

$$p_{2} = (x_{11} + x_{22})y_{11},$$

$$p_{3} = x_{11}(y_{12} - y_{22}),$$

$$p_{4} = x_{22}(-y_{11} + y_{12}),$$

$$p_{5} = (x_{11} + x_{12})y_{22},$$

$$p_{6} = (-x_{11} + x_{21})(y_{11} + y_{12}),$$

$$p_{7} = (x_{12} - x_{22})(y_{21} + y_{22}).$$

$$\left(\begin{array}{c|c} \cdot & \cdot \\ \hline \cdot & \cdot \end{array}\right) \cdot \left(\begin{array}{c|c} \cdot & \cdot \\ \hline \cdot & \cdot \end{array}\right) = \left(\begin{array}{c|c} \cdot & \cdot \\ \hline \cdot & \cdot \end{array}\right)$$

$$\rightarrow C(n) \le 7C(n/2) + O(n^2), \quad C(1) = 1$$

Theorem (Strassen)

We can multiply $n \times n$ matrices with $O(n^{\log_2(7)}) = O(n^{2.81})$ arithmetic operations.

$$\begin{pmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \end{pmatrix} = \begin{pmatrix} p_1 + p_4 - p_5 + p_7 & p_3 + p_5 \\ p_2 + p_4 & p_1 + p_3 - p_2 + p_6 \end{pmatrix}.$$



Main idea

Fix matrix size (e.g. 2x2), use Reinforcement Learning to generate this algorithm line by line

At the end of every episode, give non-zero reward if the algorithm is incorrect (we can check symbolically)

RL TLDR: do random things many times, $\begin{pmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \end{pmatrix} = \begin{pmatrix} p_1 + p_4 - p_5 + p_7 & p_3 + p_5 \\ p_2 + p_4 & p_1 + p_3 - p_2 + p_6 \end{pmatrix}$ choose best trajectories (according to reward), reinforce (learn to do more of those actions in similar situations)

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Matrix Multiplication Tensor

Lets learn to find many different algorithms, from simple to complex, providing a curriculum for the agent



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Matrix multiplication is a bilinear operation.

Lets find algorithms for many bilinear operations.



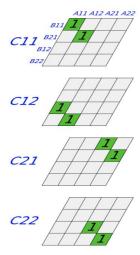
Matrix Multiplication Tensor

The matrix multiplication operator can be represented by a tensor.

The operator representing the multiplication of two NxN matrices, is a tensor of dimension N²xN²xN².

For 2x2 Matrix multiplications:

$$\begin{pmatrix} c_1 & c_2 \\ c_3 & c_4 \end{pmatrix} = \begin{pmatrix} a_1 & a_2 \\ a_3 & a_4 \end{pmatrix} \cdot \begin{pmatrix} b_1 & b_2 \\ b_3 & b_4 \end{pmatrix}$$





Decompose this tensor into a factor decompositions.

$$T = \sum_{q \le R} u_q \otimes v_q \otimes w_q$$



Decompose this tensor (cube) into a factor (vectors) decompositions.

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$$C = AB = \sum_{q=1}^{R} \langle u_q, A \rangle \langle v_q, B \rangle w_q$$



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Strassen's algorithm

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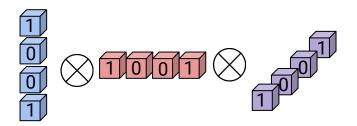
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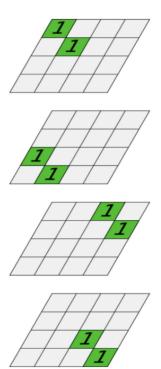
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 Rank-7 factorization





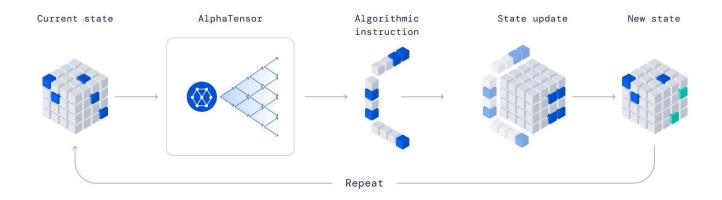
Modeling as a ML problem

Maths problem

Find low-rank decompositions of the matrix multiplication tensor

Modeling

Find shortest path to all-zero tensor





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Maths problem

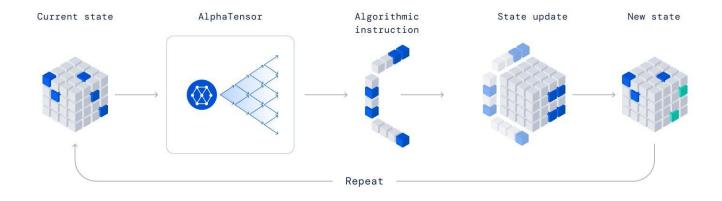
Find low-rank decompositions of the matrix multiplication tensor

Modeling

Find shortest path to all-zero tensor

Difficulties:

- Only one tensor to decompose
- No training data
- Huge action space
- Symmetries (e.g., permutation invariance)





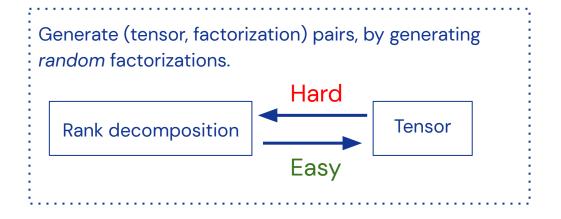
Ingredient #1: Synthetic data

- We generally require lots of data to train powerful ML models.
- In maths, abundant data is rarely available ⇒ rely instead on synthetic data.



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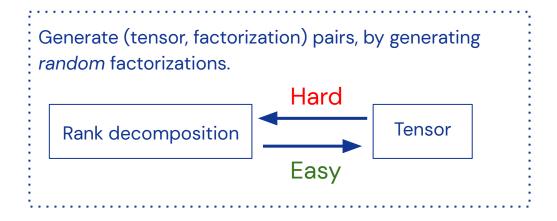
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- Training the network on data coming from actors in addition to synthetic data

Potential difficulty: The distribution of synthetic data can be far from that of the target.



Ingredient #2: Diversifying the target

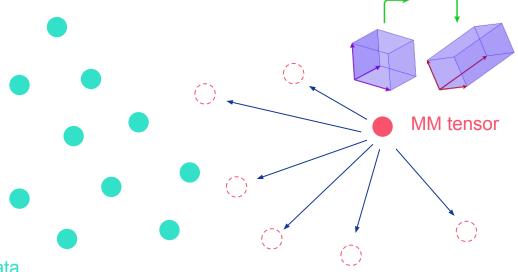
- In ML, we generally care about the average performance across many datapoints (test data).
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- In ML, we generally care about the average performance across many datapoints (test data).
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Express the target in mathematically equivalent ways – change the basis.



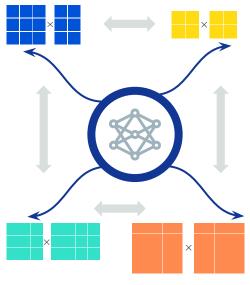


Ingredient #3: Train a generalist agent rather than several experts

 $h_1 = a_6 (b_1 - b_7 + b_9)$ $h_2 = (a_1 + a_4)(b_1 - b_2 + b_5)$ $h_3 = a_5 (-b_3 - b_4 + b_6)$ $h_4 = -(a_3 + a_6)(b_4 + b_7 - b_8)$ $h_5 = b_8 (a_1 + a_3)$ $h_6 = b_3 (a_4 + a_5)$ $h_7 = a_2 (b_5 + b_6 + b_9)$ $h_8 = -b_5 (a_1 + a_2 + a_4 + a_5)$ $h_9 = (b_3 + b_5)(a_1 + a_4 + a_5)$ $h_{10} = a_1 (b_2 + b_3 - b_8)$ $h_{11} = (a_1 - a_6)(b_1 - b_8)$ $h_{12} = b_9 (a_2 - a_3)$ $h_{13} = b_4 (a_2 - a_3 + a_5 - a_6)$ $h_{14} = (b_4 + b_9)(-a_2 + a_3 + a_6)$ $h_{15} = b_1 (a_4 + a_6)$ $y_1 = h_1 + h_{11} - h_{12} - h_{14} - h_4 + h_5$ $y_2 = -h_1 + h_{12} + h_{13} + h_{14} + h_{15}$ $y_3 = h_{10} + h_5 + h_6 - h_8 - h_9$ $y_4 = -h_{10} + h_{11} + h_{15} - h_2 - h_6 + h_9$ $y_5 = -h_{12} - h_6 + h_7 + h_8 + h_9$ $y_6 = h_{12} + h_{13} + h_{14} + h_3 + h_6$

 $\begin{array}{l} h_1 = -\left(a_4 + a_5 + a_8\right)\left(b_2 - b_3 + b_4 - b_8\right) \\ h_2 = \left(a_1 + a_2 + a_7\right)\left(b_1 - b_5 - b_6 + b_7\right) \\ h_3 = \left(b_1 - b_2\right)\left(-a_1 + a_3 + a_4\right) \\ h_4 = -\left(b_6 - b_9\right)\left(a_2 - a_5 + a_6\right) \\ h_5 = -\left(b_1 + b_2\right)\left(a_1 - a_3 + a_7\right) \\ h_6 = \left(b_{11} + b_2\right)\left(a_1 - a_3 + a_7\right) \\ h_7 = b_{11}\left(-a_1 + a_3 - a_5 + a_6 - a_7 - a_8 + a_9\right) \\ h_8 = b_2\left(-a_1 + a_3\right) \\ h_9 = b_6\left(-a_5 + a_6\right) \\ h_{10} = \left(a_5 + a_8\right)\left(b_{11} + b_2 - b_3 + b_4 + b_7 - b_8\right) \\ h_{11} = \left(b_5 + b_6 - b_7\right)\left(a_1 + a_2 + a_7 + a_8\right) \\ h_{12} = \left(b_2 - b_3 + b_4\right)\left(a_4 + a_5 + a_7 + a_8\right) \end{array}$

 $\begin{array}{l} y_1 = h_{14} + h_{18} + h_{23} + h_4 + h_9 \\ y_2 = h_{14} + h_{16} + h_{20} + h_{21} + h_4 + h_9 \\ y_3 = h_{11} + h_2 + h_{22} - h_{23} + h_{28} \\ y_4 = -h_{18} - h_{25} - h_4 - h_8 - h_9 \\ y_5 = h_{17} + h_{26} - h_3 - h_8 - h_9 \\ y_6 = h_{27} - h_5 + h_6 + h_7 + h_8 + h_9 \\ y_7 = h_{13} + h_{14} + h_{19} + h_9 + h_8 - h_9 \end{array}$



```
\begin{split} h_1 &= (a_1 + a_4) \left( b_1 + b_4 \right) \\ h_2 &= a_1 \left( b_2 - b_4 \right) \\ h_3 &= (a_2 - a_4) \left( b_3 + b_4 \right) \\ h_4 &= b_1 \left( a_3 + a_4 \right) \\ h_5 &= a_4 \left( -b_1 + b_3 \right) \\ h_6 &= - \left( a_1 - a_3 \right) \left( b_1 + b_2 \right) \\ y_1 &= b_4 \left( a_1 + a_2 \right) \\ y_1 &= h_1 + h_3 + h_5 - h_7 \\ y_2 &= h_4 + h_5 \\ y_3 &= h_2 + h_7 \\ y_4 &= h_1 + h_2 - h_4 + h_6 \end{split}
```

```
\begin{array}{l} h_1 = -a_{16}b_4 \\ h_2 = a_1 \left(-b_{23} + b_3\right) \\ h_3 = \left(a_1 + a_3\right) \left(b_1 + b_2 + b_{23} - b_5\right) \\ h_4 = \left(a_1 - a_{20} + a_5\right) \left(-b_{23} + b_3 + b_4\right) \\ h_5 = \left(c_{20} + a_3 - a_5\right) \left(b_{14} - b_2 + b_{22}\right) \\ h_6 = \left(a_3 - a_3\right) \left(b_{11} + b_{15} + b_2 - b_{22}\right) \\ h_7 = -\left(b_{14} + b_{17} - b_7\right) \left(a_{18} - a_{20} - a_3 + a_5\right) \\ h_8 = b_5 \left(-a_{16} + a_{17} - a_{20}\right) \\ h_9 = \left(-c_{20} + a_4 + a_5\right) \left(-b_1 + b_{11} - b_{17} + b_{19} + b_{20} + b_{21}\right) \\ h_{10} = \left(a_2 - a_2 + a_5\right) \left(b_{15} + b_{15} - b_5 + b_6 - b_7 + b_9\right) \\ h_{11} = a_{18} \left(b_{12} - b_{14} + b_2\right) \\ h_{12} = \left(a_1 - a_{16} - a_{20} + a_5\right) \left(b_{13} + b_{18} + b_3 + b_4 + b_8\right) \\ \vdots \\ y_1 = h_{15} + h_{18} - h_{10} - h_{21} - h_{22} - h_{24} + h_{25} - h_{27} - h_{28} + h_{31} - h_{32} \end{array}
```

 $\begin{aligned} & y_0 = -h_{40} + h_{71} - h_{73} - h_{78} + h_{80} - h_{82} + h_{84} + h_{84} + h_{87} - h_{91} + h_{92} \\ & y_3 = -h_{40} - h_{40} + h_{53} + h_{63} + h_{77} + h_{80} - h_{84} + h_{94} \\ & y_4 = -h_{10} + h_{25} - h_{27} - h_{28} - h_{22} + h_{33} - h_{60} + h_{84} + h_{87} - h_{92} \\ & y_5 = h_{43} - h_{40} - h_{64} - h_{67} + h_{70} + h_{72} + h_{80} + h_{84} + h_{87} - h_{92} \\ & y_6 = h_{13} - h_{18} - h_{20} + h_{21} + h_{29} + h_{22} + h_{34} - h_{34} - h_{35} + h_{38} - h_{40} + h_{6} \\ & y_7 = h_{44} - h_{45} - h_{40} - h_{54} + h_{55} - h_{60} - h_{64} + h_{88} + h_{80} + h_{67} \\ & y_8 = h_{41} - h_{42} + h_{43} - h_{42} - h_{45} - h_{66} - h_{84} + h_{88} + h_{89} + h_{89} \\ & y_9 = h_{11} + h_{13} - h_{18} + h_{29} + h_{22} - h_{30} + h_{8} + h_{6} - h_{7} \\ & y_{10} = h_{41} - h_{24} + h_{43} + h_{48} - h_{46} - h_{66} + h_{88} + h_{66} - h_{66} + h_{88} - h_{66} - h_{66} \end{aligned}$



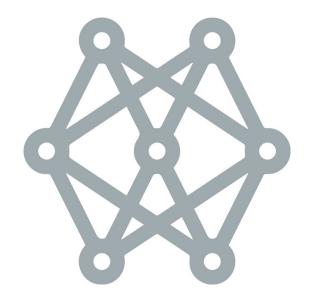
Generalist agent vs expert

 Better performance through transfer: Generalist agent getting better results (more efficient algorithms) compared to individual "experts".

 More efficient: Can generate efficient algorithms tailored for each matrix size (with just one experiment!)



Ingredient #4: Training large and deep models adapted to the task

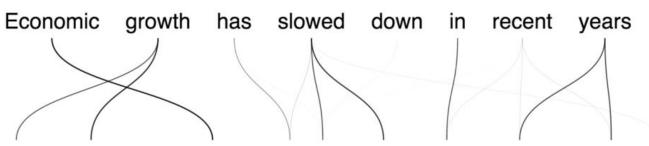


Beyond shallow fully-connected layers



Ingredient #4: Training large and deep models adapted to the task: attention

Attention and transformers have now become ubiquitous in ML models

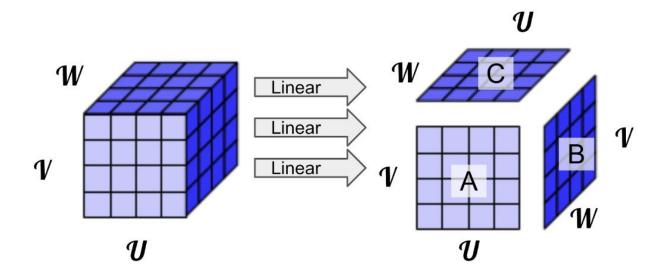


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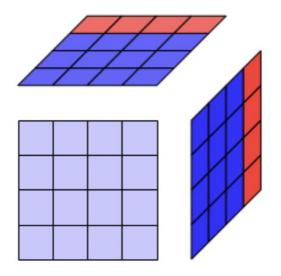
Adapt the architecture to the task at hand by incorporating symmetries and prior knowledge about the problem





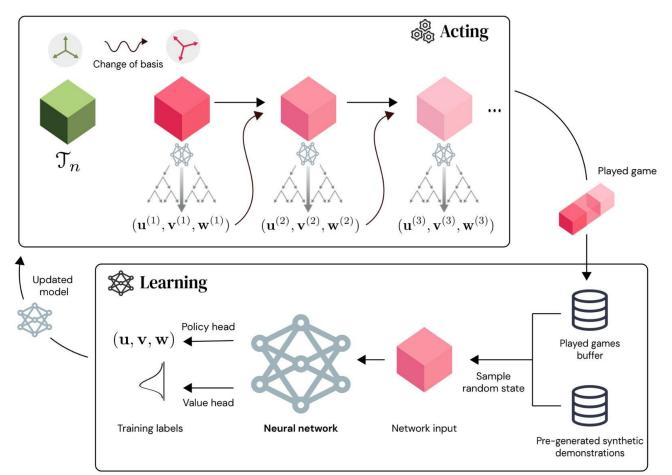
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Overall system





Results on matrix multiplication tensors

| Size (n, m, p) | Best method known | Best rank known | • | nsor rank Standard |
|------------------|--|--------------------|----|-----------------------|
| (2, 2, 2) | (Strassen, 1969) | 7 | 7 | 7 |
| (3, 3, 3) | (Laderman, 1976) | 23 | 23 | 23 |
| (4, 4, 4) | (Strassen, 1969) $(2, 2, 2) \otimes (2, 2, 2)$ | 49 | 47 | 49 |
| (5, 5, 5) | (3,5,5) + (2,5,5) | 98 | 96 | 98 |
| (2,2,3) | (2,2,2) + (2,2,1) | 11 | 11 | 11 |
| (2, 2, 4) | (2,2,2)+(2,2,2) | 14 | 14 | 14 |
| (2, 2, 5) | (2,2,2) + (2,2,3) | 18 | 18 | 18 |
| (2, 3, 3) | (Hopcroft and Kerr, 1971) | 15 | 15 | 15 |
| (2, 3, 4) | (Hopcroft and Kerr, 1971) | 20 | 20 | 20 |
| (2, 3, 5) | (Hopcroft and Kerr, 1971) | 25 | 25 | 25 |
| (2, 4, 4) | (Hopcroft and Kerr, 1971) | 26 | 26 | 26 |
| (2, 4, 5) | (Hopcroft and Kerr, 1971) | 33 | 33 | 33 |
| (2, 5, 5) | (Hopcroft and Kerr, 1971) | 40 | 40 | 40 |
| (3, 3, 4) | (Smirnov, 2013) | 29 | 29 | 29 |
| (3, 3, 5) | (Smirnov, 2013) | 36 | 36 | 36 |
| (3, 4, 4) | (Smirnov, 2013) | 38 | 38 | 38 |
| (3, 4, 5) | (Smirnov, 2013) | 48 | 47 | 47 |
| (3, 5, 5) | (Sedoglavic and Smirnov, 2021) | 58 | 58 | 58 |
| (4, 4, 5) | (4,4,2) + (4,4,3) | 64 | 63 | 63 |
| (4, 5, 5) | $(2,5,5)\otimes(2,1,1)$ | 80 | 76 | 76 |

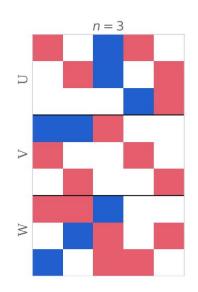


Our procedure can be applied to find algorithms for arbitrary bilinear maps



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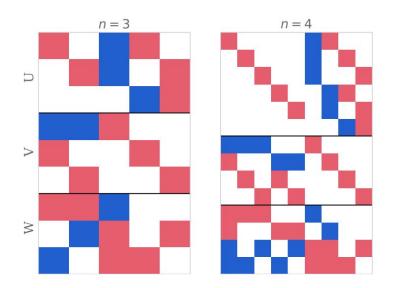
Example: skew-symmetric matrix-vector product





Our procedure can be applied to find algorithms for arbitrary bilinear maps

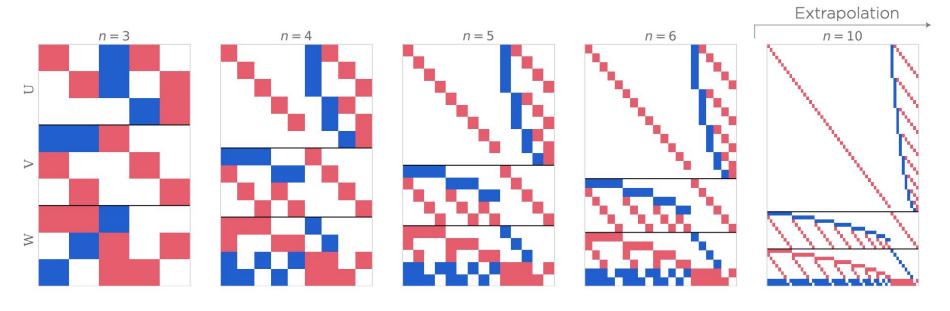
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Example: skew-symmetric matrix-vector product

```
Input: n \times n skew-symmetric matrix A, vector b.
```

Output: The resulting vector $\mathbf{c} = \mathbf{Ab}$ computed in $\frac{(n-1)(n+2)}{2}$ multiplications.

1: **for**
$$i = 1, ..., n-2$$
 do

2: **for**
$$j = i + 1, ..., n$$
 do

$$w_{ij} = a_{ij}(b_j - b_i)$$

 \triangleright Computing the first (n-2)(n+1)/2 intermediate products

4: **for**
$$i = 1, ..., n$$
 do

5:
$$q_i = b_i \sum_{j=1}^n a_{ji}$$

 \triangleright Computing the final n intermediate products

6: **for**
$$i = 1, ..., n-2$$
 do

6: **for**
$$i=1,\ldots,n-2$$
 do
7: $c_i = \sum_{j=1}^{i-1} w_{ji} + \sum_{j=i+1}^n w_{ij} - q_i$

8:
$$c_{n-1} = -\sum_{i=1}^{n-2} \sum_{j=i+1}^{n-2} w_{ij} - \sum_{j=1}^{n-2} w_{jn} + \sum_{i=1, i \neq n-1}^{n} q_i$$

9: $c_n = -\sum_{i=1}^{n-1} \sum_{j=i+1}^{n} w_{ij} + \sum_{i=1}^{n-1} q_i$

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Our procedure can be applied to find algorithms for arbitrary bilinear maps

Example: skew-symmetric matrix-vector product

Input: $n \times n$ skew-symmetric matrix **A**, vector **b**.

Output: The resulting vector $\mathbf{c} = \mathbf{Ab}$ computed in $\frac{(n-1)(n+2)}{2}$ multiplications.

Improves over previous best know result [Ye, Lim, 2018]

1: **for**
$$i = 1, ..., n-2$$
 do

2: **for**
$$j = i + 1, ..., n$$
 do

$$w_{ij} = a_{ij}(b_j - b_i)$$

 \triangleright Computing the first (n-2)(n+1)/2 intermediate products

4: **for**
$$i = 1, ..., n$$
 do

5:
$$q_i = b_i \sum_{j=1}^n a_{ji}$$

 \triangleright Computing the final n intermediate products

6: **for**
$$i = 1, \ldots, n-2$$
 do

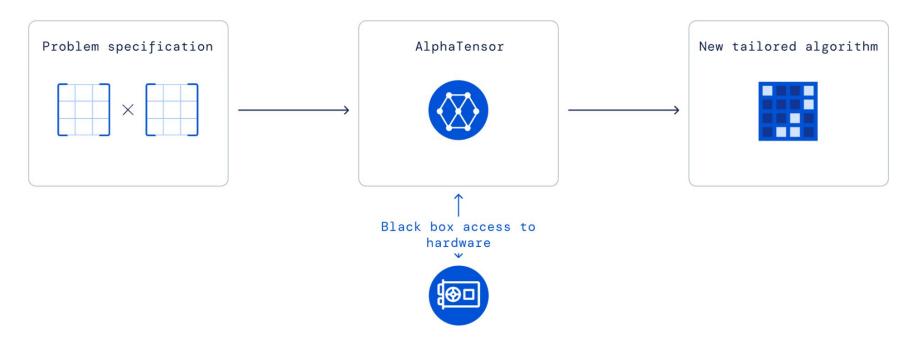
6: **for**
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 do
7: $c_i = \sum_{j=1}^{i-1} w_{ji} + \sum_{j=i+1}^n w_{ij} - q_i$

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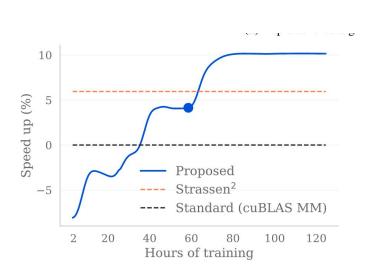
Beyond rank optimization

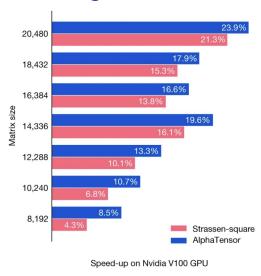




Runtime on real-world hardware

Reward proportional to the execution time of the algorithm





Algorithm tailored to the target hardware (e.g., algorithm optimized on CPU would not perform well on GPU)



Conclusions

- Transformed a maths/algorithmic problem into a game, and used 4 ingredients to make ML actually work
 - 1. If there is no data, generate synthetic data
 - 2. Diversifying the target
 - 3. Generalist agent, rather than expert
 - 4. Use large deep models, and embed prior knowledge into the architecture

- The resulting discovered algorithms outperform state-of-the-art algorithms in terms of rank
- Obtained system is very flexible and customizable (e.g., supporting finite fields, arbitrary tensors, reward, ...)



Extra slides



Decompose this tensor (cube) into a factor (vectors) decompositions.

$$T = \sum_{q \leq R} u_q \otimes v_q \otimes w_q$$

Algorithm 1: Meta-algorithm parameterized by $\{\mathbf{u}^{(r)}, \mathbf{v}^{(r)}, \mathbf{w}^{(r)}\}_{r=1}^{R}$ for computing the matrix product $\mathbf{C} = \mathbf{AB}$. Note that R controls the number of multiplications between input matrix entries.

Parameters: $\{\mathbf{u}^{(r)}, \mathbf{v}^{(r)}, \mathbf{w}^{(r)}\}_{r=1}^R$: length- n^2 vectors such that $\mathbf{T}_n = \sum_{r=1}^R \mathbf{u}^{(r)} \otimes \mathbf{v}^{(r)} \otimes \mathbf{w}^{(r)}$

Input: A, B: matrices of size $n \times n$

Output: C = AB

1: **for**
$$r = 1, \dots, R$$
 do

2:
$$m_r \leftarrow \left(u_1^{(r)}a_1 + \dots + u_{n^2}^{(r)}a_{n^2}\right) \left(v_1^{(r)}b_1 + \dots + v_{n^2}^{(r)}b_{n^2}\right)$$

3: **for**
$$i = 1, ..., n^2$$
 do

4:
$$c_i \leftarrow w_i^{(1)} m_1 + \dots + w_i^{(R)} m_R$$

5: return C



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