# Jonathan Bayless

A well-rounded software developer focusing on embedded software and mobile app development with a background in electronics and controls systems.

## **Employment**

#### **Carrier Corporation**

Graduate Hire Program - Firmware Developer, Scrum Master

May 2019-Present

- Led Sprint Planning Meetings, Daily Standups, and Retrospectives as Scrum Master to maximize team productivity
- Ensured on-time and successful product launch as a subject matter expert in System Control and Diagnostics domains
- Led team of 20 in a transition to a version control process that improved dev productivity and aligned better with business goals
- Supported recruiting efforts by interviewing candidates and acting as Ambassador for Grad Hire Program in Indy office
- Resolved defects and new feature tickets at highest velocity in team

#### The Boeing Company

F15 Mission Processing Software Infrastructure Intern

May 2018-August 2018

- Added support for new systems and communication protocols to improve coverage of existing logging systems
- Revamped RTOS frame analysis tool to aid in threading use and prevent mission-affecting overframing
- Rewrote Ada parser for flight test messages in Python to support new message spec and cut technical debt
- Fixed bugs in build scripts and test environments

### **Rolls-Royce Corporation**

Electrical Test Engineering Intern

May-August 2016, May-August 2017

- Designed and implemented new controls algorithm that improves performance over PID
- Created VBA tool for parsing .ini config files into Excel sheet that became standard for collaboration with mechanical teams
- Validated signal configuration for European test stands in QNX based HMI software

### **Education**

Purdue University Graduated May 2019

Bachelor of Science in Electrical Engineering, Minor in Organizational Leadership

# **Ancillary Projects**

### auToDo

Co-Founder, CEO June 2019–Present

- Created a cross-platform mobile application with Flutter for tracking routine car maintenance tasks
- $\boldsymbol{\mathsf{-}}\ \mathsf{Led}\ \mathsf{marketing}\ \mathsf{campaigns},\ \mathsf{SEO}\ \mathsf{efforts},\ \mathsf{and}\ \mathsf{customer}\ \mathsf{engagement}\ \mathsf{to}\ \mathsf{grow}\ \mathsf{user}\ \mathsf{base}$
- Used Firebase authentication and NoSQL database technologies with BLoC state management methodology

### **Purdue ACM SIGBots**

President, Vice President

April 2016-April 2018, April 2018-April 2019

- Developed a variety of Kalman Filters, PID controls, path planning, and odometry for mobile robots
- Placed 1st in World Competition Rankings and 4th in the World Programming Skills
- Increased users of team's RTOS/Dev Environment from 200 to 2000+ as kernel developer and UX/API designer

### **Association for Computing Machinery**

President

April 2018-April 2019

- Coordinated team meetings and events, handled team finances and maintained relationships with sponsors
- Led four Special Interest Groups (SIGs) in areas of App Development, AI, Robotics, and Game Development

### **Technical Skills**

Programming Languages (Proficient): C, C++, Python, MATLAB, Dart

Programming Languages (Knowledgeable): C#, Ada, Arm Assembly, (S)CSS, Javascript/Typescript/NodeJS, Kotlin, Swift

Programming Skills: QNX/Unix/Linux environments, Git, CI/CD, IBM Rational Jazz Suite (DOORS), GDB, SQL, Bash

Other Software Skills: LTSpice/NGSpice, KiCad, CATIA, Autodesk Inventor/Fusion, Adobe Illustrator

 $\textbf{Controls Skills:} \ \ \text{Kalman filtering (EKF/UKF)}, \ \text{State Space control}, \ \text{Al autotuning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Spline path planning for PID}, \ \text{Pure Pursuit}, \ \text{Pure Purs$ 

Other: Soldering, MIG welding, plasma cutting, 3D printing, Wood shop equipment, CNC