```
when started

set drive velocity to ( 100 ) %

set turn velocity to ( 100 ) %

set   ForkMotorGroup   velocity to ( 100 ) %

turn   right   for ( 15 ) degrees ▶

drive   forward   for ( 410 ) mm   ▶

spin   ForkMotorGroup   down   for ( 1050 ) degrees   ▶

drive   reverse   for ( 250 ) mm   ▶

spin   ForkMotorGroup   down   for ( 1500 ) degrees   ▶

turn   left   for ( 25 ) degrees ▶

drive   forward   for ( 400 ) mm   ▶

spin   ForkMotorGroup   up   for ( 250 ) degrees   ▶

drive   reverse   for ( 250 ) mm   ▶

turn   right   for ( 100 ) degrees ▶

drive   forward   for ( 175 ) mm   ▶

spin   ForkMotorGroup   down   for ( 250 ) degrees   ▶

drive   reverse   for ( 400 ) mm   ▶

turn   left   for ( 150 ) degrees ▶

drive   forward   for ( 900 ) mm   ▶

spin   ForkMotorGroup   up   for ( 250 ) degrees   ▶

drive   reverse   for ( 850 ) mm   ▶

turn   right   for ( 60 ) degrees ▶

spin   ForkMotorGroup   down   for ( 250 ) degrees   ▶

drive   reverse   for ( 250 ) mm   ▶

turn   left   for ( 90 ) degrees ▶

drive   forward   for ( 1500 ) mm   ▶

turn   right   for ( 180 ) degrees ▶

drive   forward   for ( 1500 ) mm   ▶

spin   ForkMotorGroup   down   for ( 250 ) degrees   ▶

drive   reverse   for ( 250 ) mm   ▶

turn   left   for ( 135 ) degrees ▶
```