```
when started
set drive velocity to
                           %
                  100
set turn velocity to
                           %
                   100
      ForkMotorGroup
                           velocity to
                                              %
                                       100
set
               for (15
                         degrees ▶
      right
turn
       forward
                        410
drive
                   for
                               mm
      ForkMotorGroup
                                            1050
                             down
                                       for
                                                     degrees
spin
                        250
drive
       reverse
                   for
                               mm
                                                     degrees
      ForkMotorGroup
                                            1500
                             down
                                       for
spin
                        degrees >
      left
                   25
turn
              for
                        400
       forward
drive
                   for
                               mm
                                          250
      ForkMotorGroup
                                     for
                                                 degrees
                             up
spin
                   for
                        250
drive
                               mm
       reverse
               for (100
                          degrees >
      right
turn
                       175
       forward
drive
                   for
                               mm
      ForkMotorGroup
                                            250
                                                    degrees
                                       for
                             down
spin
                      (400)
                  for
      reverse
                  150 degrees ▶
              for
      left
turn
       forward
                   for (900)
drive
                               mm
                                     for (250)
      ForkMotorGroup
                                                 degrees
spin
                             up
                   for (850)
drive
       reverse
                               mm
                                         ▶
                         degrees ▶
      right
               for (60)
turn
                                            250
      ForkMotorGroup
                                                    degrees
                             down
                                       for
spin
                       250
drive
                   for
                                         ▶
       reverse
                               mm
                  90
              for
                        degrees ▶
turn
      left
                   for (1500)
       forward
drive
                                mm
               for (180) degrees ▶
turn
      right
                   for (1500)
       forward
                                mm
drive
                                            250
      ForkMotorGroup
                                       for
                                                    degrees
                             down
spin
                   for
                       250
drive
                                         ▶
                               mm
       reverse
                         degrees ▶
                   135
turn
      left
              for
```