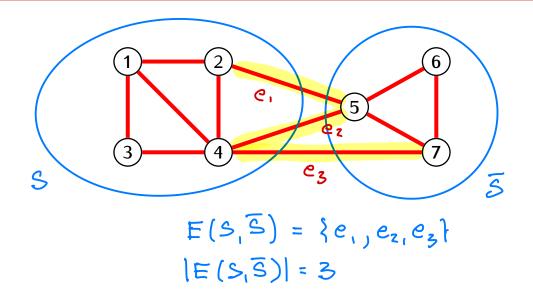
**Notation.** If *S* is a finite set then

|S| :=(the number of elements of S)

#### **Definition**

Let G be a graph with the set of vertices V. Let  $S\subseteq V$  and let  $\overline{S}=V\setminus S$ . Then

$$E(S, \overline{S}) = \begin{pmatrix} \text{the set of edges of } G \\ \text{with one end in } S \\ \text{and the other end is } \overline{S} \end{pmatrix}$$



**Partitioning problem.** For a given connected graph with the set of vertices  $V=1,\ldots,N$  and a given number  $1\leq k\leq N$  find  $S\subseteq V$  such that |S|=k and that  $E(S,\overline{S})$  is as small as possible.

#### **Definition**

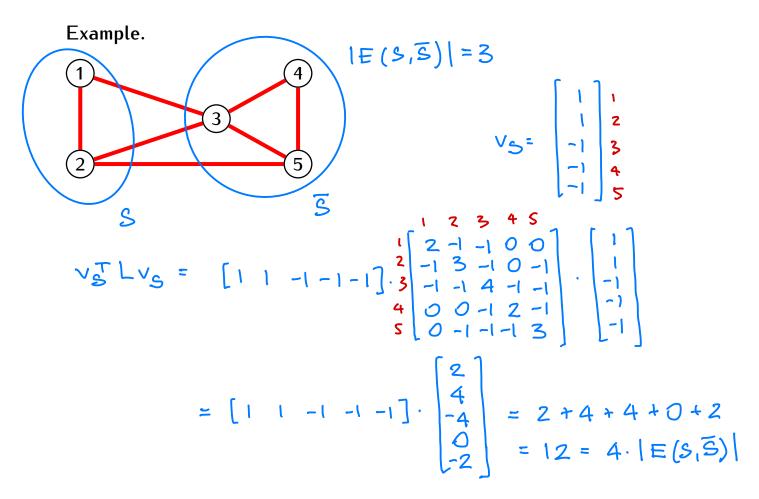
Let G be a graph with vertices  $V = \{1, ..., N\}$ , and let  $S \subseteq V$ . The selector vector of S is the vector  $\mathbf{v}_S \in \mathbb{R}^N$  given by

$$\mathbf{v}_S = \begin{bmatrix} x_1 \\ \vdots \\ x_N \end{bmatrix} \quad \text{where} \quad x_i = \begin{cases} 1 & \text{if } i \in S \\ -1 & \text{if } i \in \overline{S} \end{cases}$$

## **Proposition**

Let G be a graph with vertices  $V = \{1, ..., N\}$ , and let L be the Laplacian of G. For  $S \subseteq V$  we have:

$$|E(S, \overline{S})| = \frac{1}{4} \cdot \mathbf{v}_S^T L \mathbf{v}_S$$



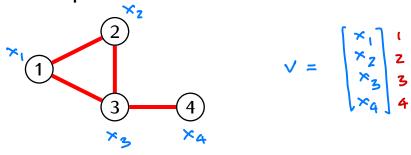
**Notation.** If i, j are vertices in a graph then we will write  $i \sim j$  if there is an edge joining i and j.

#### Lemma

Let G be a graph with vertices  $V = \{1, ..., N\}$ , and let L be the Laplacian of G. For any vector  $\mathbf{v} = \begin{bmatrix} x_1 \\ \vdots \\ x_N \end{bmatrix}$  we have

$$\mathbf{v}^T L \mathbf{v} = \sum_{\substack{i < j \\ i \sim j}} (x_i - x_j)^2$$

Example.



$$V^{T} L V = (x_1 - x_2)^2 + (x_1 - x_3)^2 + (x_2 - x_3)^2 + (x_3 - x_4)^2$$

Proof of Lemma. 
$$\bot = D - A$$

$$\Lambda = \begin{bmatrix} x^{N} \\ \vdots \\ x^{2} \end{bmatrix}$$

$$V^T L_V = V^T (D-A)_V = V^T D_V - V^T A_V$$

$$\sqrt{T} D v = \sum_{i} deg(i) \times_{i}^{2} = \sum_{i < j} \times_{i}^{2} + \times_{j}^{2}$$
check



$$\nabla^{T} A V = \sum_{i \neq j} x_{i} x_{j} = \sum_{i \neq j} x_{i} x_{j} + \sum_{j \neq i} x_{j} x_{j} = 2 \sum_{i \neq j} x_{i} x_{j}$$

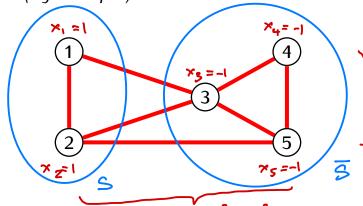
$$\uparrow i \neq j \qquad i \neq j \qquad i \neq j$$

$$\uparrow i \neq j \qquad i \neq j \qquad i \neq j$$

## This gives:

$$\nabla^{T} \sqsubseteq \nabla = \sum_{\substack{i < j \\ i \sim j}} \left( \times_{i}^{2} + \times_{j}^{2} - 2 \times_{i} \times_{j}^{2} \right) = \sum_{\substack{i < j \\ i \sim j}} \left( \times_{i} - \times_{j}^{2} \right)$$





 $(x_i - x_j)^2 = 0$ if i and j are both
in S or in  $\overline{S}$ 

$$(x_i - x_j)^2 = 2^2 = 4$$
  
if ies and jes  
or ies and jes

By Lemma:

$$V_{s}^{T} \cdot L \cdot V_{s} = \sum_{\substack{i < j \\ i \sim j}} (x_{i} - x_{j})^{2} = \sum_{\substack{i < j \\ i \sim j \\ i,j \text{ are in different groups}}} 4 \cdot |E(s_{i}\overline{s})|$$

# Partitioning problem restated:

Given a connected graph with vertices  $\{1,2,...,N\}$  and Laplacian L find a vector  $v = \begin{bmatrix} x_1 \\ \vdots \\ x_N \end{bmatrix} \in \mathbb{R}^N$  such that:

hard 
$$\rightarrow [(1) \times_{i} = \pm 1 \text{ for } i = 1, 2, ..., N]$$

$$(2) \sum_{i} \times_{i} = k - (N - k) \quad (\text{equivalently: } V = \begin{bmatrix} 1 \\ 1 \end{bmatrix} = k - (N - k)$$

$$(3) \quad V^{T} L V \quad \text{is the the smallest possible.}$$

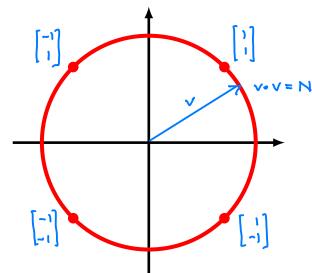
#### Relaxation:

Find a vector  $V = \begin{bmatrix} x_1 \\ \vdots \\ x_N \end{bmatrix} \in \mathbb{R}^N$  such that:

$$(1)$$
  $\vee \cdot \vee = N$ 

(2) 
$$V \cdot \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} = k - (N-k)$$

(3) VTLV is the smallest possible.



# Note:

Let  $v_p = a$  solution of the partitioning problem  $v_R = a$  solution of the relaxed problem

Then

2) we can use  $V_R$  to get an approximated solution of the partitioning problem

# Preparation: Eigenvectors of the Laplacian of a graph

Let G be a connected graph with N vertices and L be the Laplacian of G.

1) Since L is a symmetric matrix, it has N orthonormal eigenvectors  $\mathbf{u}_1, \dots, \mathbf{u}_N$ .

orthonormal: 
$$u_i \cdot u_j = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$$

Let

$$\lambda_1 = \text{eigenvalue corresponding to } \mathbf{u}_1$$
  
 $\lambda_2 = \text{eigenvalue corresponding to } \mathbf{u}_2$   
... ... ... ... ...  
 $\lambda_N = \text{eigenvalue corresponding to } \mathbf{u}_N$ 

We can assume that  $\lambda_1 \leq \lambda_2 \leq \cdots \leq \lambda_N$ .

- 2)  $\lambda_i \geq 0$  for i = 1, ..., N (since L can be written in the form  $BB^T$  for some matrix B).
- 3) Since G connected, we have  $\lambda_1 = 0$  and  $\lambda_i > 0$  for i = 2, ..., N.
- 4) We can take

$$\mathbf{u}_1 = \frac{1}{\sqrt{N}} \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}$$

# Solution of the relaxed problem

Let 
$$O = \lambda_1 < \lambda_2 \le ... \le \lambda_N$$
 - eigenvalues of L  

$$\frac{1}{|IN|} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = u_1 \quad u_2 \quad ... \quad u_N \quad - \quad \text{corresponding orthonormal eigenvectors}$$

Take 
$$v \in \mathbb{R}^N$$
 that satisfies the conditions (1), (2), (3)   
since  $\{u_1,...,u_N\}$  is a basis of  $\mathbb{R}^N$  we have:  
$$v = \sum_i c_i u_i \qquad \text{for some } c_i \in \mathbb{R}$$

Condition (11) gives:

$$N = v \cdot v = \left(\sum_{i} c_{i} u_{i}\right) \left(\sum_{i} c_{i} u_{i}\right) = \sum_{ij} c_{i} c_{j} \left(u_{i} \cdot u_{j}\right) = \sum_{i} c_{i}^{2}$$

$$\sum_{i} c_{i}^{2}$$

Condition (2) gives:  

$$k - (N-k) = v \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \left( \sum_{i} c_{i} u_{i} \right) \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \sum_{i} c_{i} \left( u_{i} \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right) = c_{1} \cdot \frac{N}{\sqrt{N}} = c_{1} \sqrt{N}$$
Thus:  $c_{1} = \frac{k - (N-k)}{\sqrt{N}}$ 

Condition (3):

$$v^{T} \perp v = \left(\sum_{i} c_{i} u_{i}\right)^{T} \perp \left(\sum_{i} c_{i} u_{i}\right) = \left(\sum_{i} c_{i} u_{i}\right)^{T} \left(\sum_{i} c_{i}$$

solution of the relaxed problem continued...

<u>Upshot</u>: To get a vector  $v \in \mathbb{R}^N$  that satisfies (11), (2), (3) we need to take:

$$v = cu_1 + du_2$$

where :

$$c = \frac{k - (N - k)}{\sqrt{N}}$$
,  $c^2 + d^2 = N$   
(or  $d^2 = N - c^2$ )

This gives:

$$d^{2} = N - c^{2} = N - \frac{(k - (N - k))^{2}}{N} = \frac{Ak(N - k)}{N}$$

$$d = \pm \sqrt{\frac{Ak(N - k)}{N}}$$

$$check$$

#### We obtain:

1) The solution of the relaxed partitioning problem is given by the vector

$$V_{R} = \frac{k - (N - k)}{\sqrt{N}} \cdot \underbrace{\frac{1}{\sqrt{N}} \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix}}_{N} \underbrace{\pm \sqrt{\frac{4k(N - k)}{N}}}_{N} \cdot u_{z}$$

2) For this vector we have:

$$V_R^T L V_R = c \cdot O + d^2 \cdot \lambda_2 = \frac{4k(N-k)}{N} \cdot \lambda_2$$

#### **Theorem**

Let G be a graph with N vertices, and let  $\lambda_2$  be the second smallest eigenvalue of the Laplacian of G. Then for any set S of vertices of G we have

$$|E(S, \overline{S})| \ge \frac{|S| \cdot |\overline{S}|}{N} \cdot \lambda_2$$

Proof: Assume that 
$$|S| = k$$
.

Let  $v_g =$  the selector vector for the set  $S$ 
 $v_R =$  the solution of the relaxed partitioning problem

We have:

 $|E(S_1S)| = \frac{1}{4} v_S^T L v_S \geqslant \frac{1}{4} v_R^T L v_R = \frac{1}{4} \frac{4k(N-k)}{N} \cdot \lambda_2$ 
 $= \frac{|S| \cdot |S|}{N} \cdot \lambda_2$ 

## **Definition**

Let G be a graph. The second smallest eigenvalue  $\lambda_2$  of the Laplacian of G is called the *algebraic connectivity* of G.

# Back to the partitioning problem

**Recall:** Given a connected graph with the set of vertices  $V = \{1, 2, ..., N\}$  and 0 < k < N we want to find  $S \subseteq V$  such that |S| = k and  $|E(S, \overline{S})|$  is as small as possible (equivalently:  $\mathbf{v}_S^T L \mathbf{v}_S$  is as small as possible).

## Approximated solution:

- i) Compute  $V_R$  = the solution of the relaxed problem
- 2) Take the set SSV such that the selector vector vs is the closest to VR.

Recall: dist 
$$(v_R, v_S)$$
 =  $\|v_R - v_S\| = \sqrt{(v_R - v_S) \cdot (v_R - v_S)}$   
distance between vectors =  $\sqrt{v_R \cdot v_R} - 2v_R \cdot v_S + v_S \cdot v_S$   
 $= \sqrt{2N - v_R^2 v_S}$ 

Thus dist (VRIVS) is the smallest when VRIVS is the largest.

Recall: 
$$V_R = cu_1 + du_2$$
  $u_1 = \frac{1}{I_N} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ ,  $u_2 - eigenvector of L corresponding to  $\lambda_2$ 
 $V_R \cdot V_3 = c \cdot \frac{1}{I_N} \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} \cdot V_S + d \cdot u_2 \cdot V_S$   $d = \pm \sqrt{\frac{4k(N-k)}{N}}$ 
 $\frac{c}{I_N} \cdot (k - (N-k))$  (does not depend on S)$ 

Thus we want duz. vs to be as large as possible Note:

- i) if d>0 then d·uz·vs is the biggest if entires of vs equal to 1 correspond to the k largest entries of uz.
- 2) if d<0 then  $d\cdot u_z \cdot v_s$  is the biggest if entries of  $v_s$  equal to  $1^{82}$  correspond to the k smallest entries of  $u_z$ .

## The spectral partitioning algorithm

**Recall:** Given a connected graph with the set of vertices  $V = \{1, 2, ..., N\}$  and 0 < k < N we want to find  $S \subseteq V$  such that  $|E(S, \overline{S})|$  is as small as possible.

#### Approximated solution:

- 1. Compute the Laplacian *L* of the graph.
- 2. Compute the eigenvector of L corresponding to the second smallest eigenvalue  $\lambda_2$ :

$$\mathbf{u}_2 = \left[ \begin{array}{c} x_1 \\ \vdots \\ x_N \end{array} \right]$$

3. Let

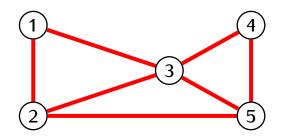
$$S_{+} = \{i_{1}, \dots, i_{k}\} \subseteq V$$
  
$$S_{-} = \{j_{1}, \dots, j_{k}\} \subseteq V$$

such that

- $x_{i_1}, \ldots, x_{i_k}$  are the largest entries of  $\mathbf{u}_2$
- $x_{j_1}, \ldots, x_{j_k}$  are the smallest entries of  $\mathbf{u}_2$ .

If  $x_{i_1} + \cdots + x_{i_k} \ge -(x_{j_1} + \cdots + x_{j_k})$  take  $S = S_+$ . Otherwise take  $S = S_-$ .

# Example.



$$L = \begin{bmatrix} 2 & -1 & -1 & 0 & 0 \\ -1 & 3 & -1 & 0 & -1 \\ -1 & -1 & 4 & -1 & -1 \\ 0 & 0 & -1 & 2 & -1 \\ 0 & -1 & -1 & -1 & 3 \end{bmatrix}$$

# Eigenvalues of L:

$$\lambda_{1} = 0$$
,  $\lambda_{1} = 1.586$ ,  $\lambda_{3} = 4.14$ ,  $\lambda_{2} = 5$ 

$$\lambda_{1} = 0$$

$$\lambda_{1} = 0.653$$

$$0.271$$

$$0$$

$$-0.653$$

$$-0.271$$

$$5$$

#### **Definition**

Let G be a graph with the set of vertices V. The *Cheeger constant* of G is the number

$$h(G) = \min \left\{ \frac{|E(S,\overline{S})|}{|S|} \mid S \subseteq V, \ 1 \le |S| \le \frac{|V|}{2} \right\}$$

#### Corollary

If  $\lambda_2$  is the algebraic connectivity a graph G then

$$h(G) \geq \frac{1}{2}\lambda_2$$

Proof: We had: if 
$$S \in V$$
 then
$$|E(S_1\overline{S})| \geqslant \frac{|S| \cdot |S|}{|V|} \cdot \lambda_2$$

$$\stackrel{SO:}{|E(S_1\overline{S})|} \geqslant \frac{|S|}{|V|} \cdot \lambda_2$$

$$|SI| \leq \frac{|V|}{2} \quad \text{then} \quad |S| \geqslant \frac{|V|}{2} \leq 0:$$

$$|E(S_1\overline{S})| \geqslant \frac{|S|}{|V|} \cdot \lambda_2 \geqslant \frac{|V|}{2|V|} \cdot \lambda_2 = \frac{1}{2} \lambda_2$$
for all  $S$  such that  $|S| \leq \frac{|V|}{2}$ 

$$|S| \leq \frac{|V|}{2} \cdot \lambda_2 \Rightarrow \frac{|V|}{2|V|} \cdot \lambda_2 = \frac{1}{2} \lambda_2$$

$$|S| \leq \frac{|V|}{2} \cdot \lambda_2 \Rightarrow \frac{|V|}{2|V|} \cdot \lambda_2 \Rightarrow \frac{|V|} \cdot \lambda_2 \Rightarrow \frac{|V|}{2|V|} \cdot \lambda_2 \Rightarrow \frac{|V|}{2|V|} \cdot \lambda_2 \Rightarrow \frac{|V|}{2|V$$

# Theorem (Cheeger inequality)

If  $\lambda_2$  is the algebraic connectivity of a graph G then

$$\sqrt{2\lambda_2 d_{\max}} \ge h(G)$$

where  $d_{\text{max}}$  is the maximal degree of a vertex of G.