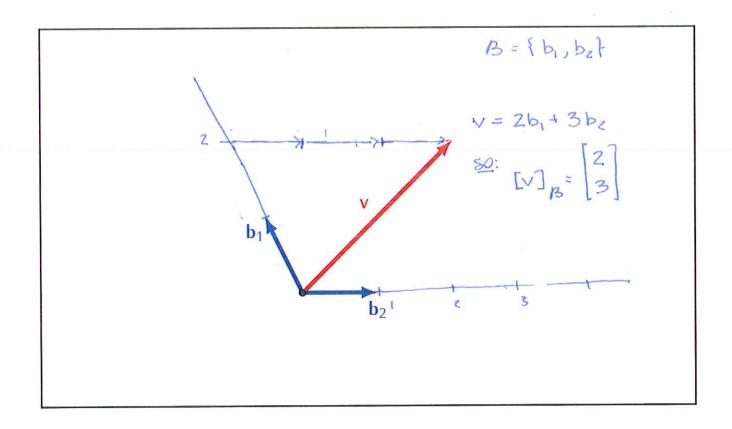
<u>Recall:</u> Any basis $\mathcal{B} = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$ of a vector space V defines a coordinate system:

$$\mathbf{v} = c_1 \mathbf{b}_1 + \ldots + c_n \mathbf{b}_n = \mathbf{v}$$

$$\begin{bmatrix} \mathbf{v} \end{bmatrix}_{\mathcal{B}} = \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix}$$



Note. Choosing a convenient basis can simplify computations.

Example. Graphene lattice.

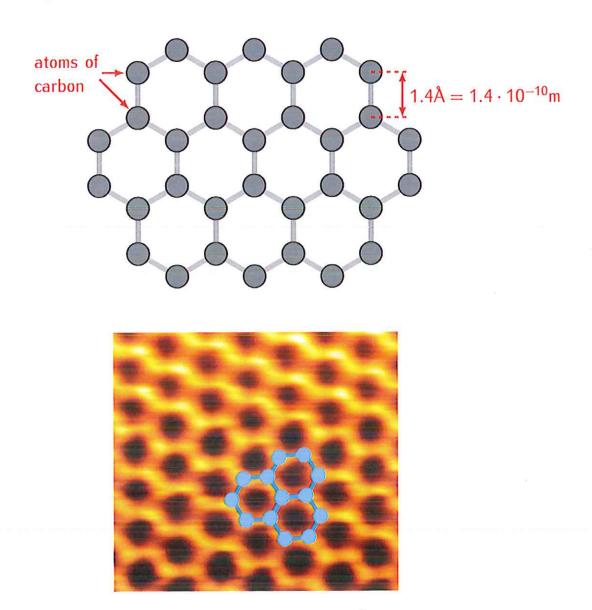
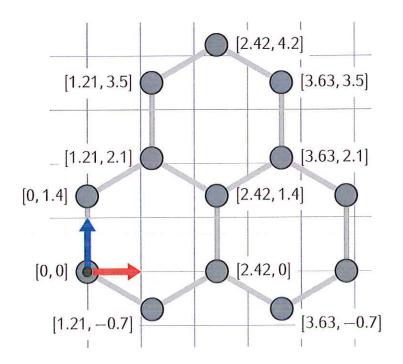


Image of graphene taken with an atomic force microscope. © University of Augsburg, Experimental Physics IV.

Coordinates of atoms in the graphene lattice

In the standard basis $\mathcal{E} = \{\mathbf{e}_1, \mathbf{e}_2\}$:

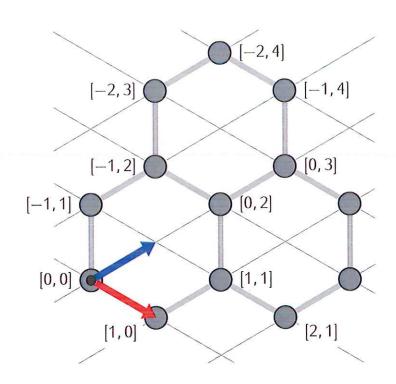
$$\mathbf{e}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$
$$\mathbf{e}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$



In a more convenient basis $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}$:

$$\mathbf{b}_1 = \begin{bmatrix} 1.21 \\ -0.7 \end{bmatrix}$$

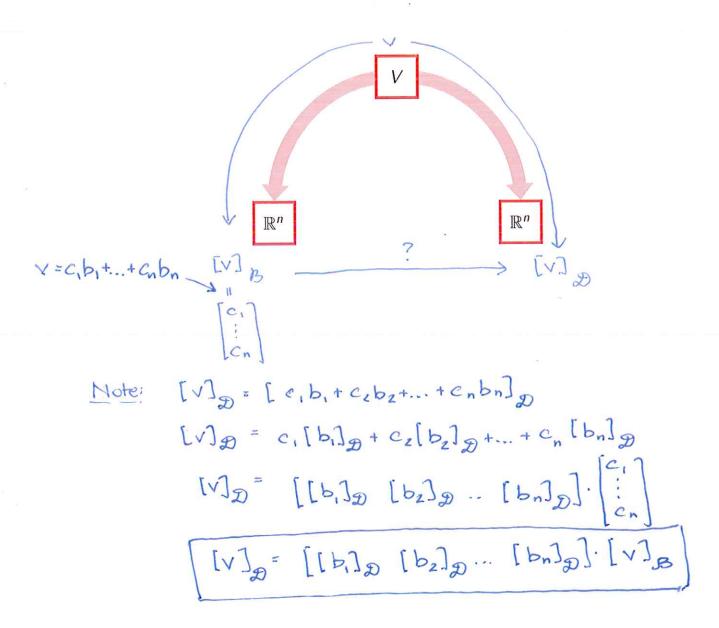
$$\mathbf{b}_2 = \begin{bmatrix} 1.21 \\ 0.7 \end{bmatrix}$$



Problem Let

$$\mathcal{B} = \{b_1, \ldots, b_n\}, \quad \mathcal{D} = \{d_1, \ldots, d_1\}$$

be two bases of a vector space V, and let $v \in V$. Assume that we know $[v]_{\mathcal{B}}$. What is $[v]_{\mathcal{D}}$?



Definition

Let $\mathcal{B} = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$ and $\mathcal{D} = \{\mathbf{d}_1, \dots, \mathbf{d}_1\}$ be two bases of a vector space V. The matrix

$$P_{\mathcal{D} \leftarrow \mathcal{B}} = \left[\begin{array}{ccc} \left[\mathbf{b}_1 \right]_{\mathcal{D}} & \left[\mathbf{b}_2 \right]_{\mathcal{D}} & \dots & \left[\mathbf{b}_n \right]_{\mathcal{D}} \end{array} \right]$$

is called the *change of coordinates matrix* from the basis $\mathcal B$ to the basis $\mathcal D$.

Propostion

Let $\mathcal{B} = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$ and $\mathcal{D} = \{\mathbf{d}_1, \dots, \mathbf{d}_1\}$ be two bases of a vector space V. For any vector $\mathbf{v} \in V$ we have

$$\left[\mathbf{v}\right]_{\mathcal{D}} = P_{\mathcal{D} \leftarrow \mathcal{B}} \cdot \left[\mathbf{v}\right]_{\mathcal{B}}$$

Example. Let \mathbb{P}_2 be the vector space of polynomials of degree ≤ 2 . Consider two bases of \mathbb{P}_2 :

$$\mathcal{B} = \{1, 1+t, 1+t+t^2\}$$

$$\mathcal{D} = \{1+t, 1-5t, 2+t^2\}$$

- 1) Compute the change of coordinates matrix $P_{\mathcal{D}\leftarrow\mathcal{B}}$.
- 2) Let $p \in \mathbb{P}_2$ be a polynomial such that

$$[p]_{\mathcal{B}} = \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix}$$

Compute $[p]_{\mathcal{D}}$.

Solution:

1)
$$\mathcal{P}_{\mathcal{D}\leftarrow\mathcal{B}} = [[1]_{\mathcal{D}} [1+\epsilon]_{\mathcal{D}} [1+\epsilon+\epsilon^{2}]_{\mathcal{D}}]$$

We have:
$$1 = \frac{5}{6} (1+\epsilon) + \frac{1}{6} (1-5\epsilon) + 0 \cdot (2+\epsilon^{2}) \quad \text{so: } [1+\epsilon]_{\mathcal{D}} = \begin{bmatrix} 5/6 \\ 1/6 \\ 0 \end{bmatrix}$$

$$1+\epsilon = 1 \cdot (1+\epsilon) + 0 \cdot (1-5\epsilon) + 0 \cdot (2+\epsilon^{2}) \quad \text{so: } [1+\epsilon]_{\mathcal{D}} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$1+\epsilon+\epsilon^{2} = -\frac{2}{3} (1+\epsilon) - \frac{1}{3} (1-5\epsilon) + 1 \cdot (2+\epsilon^{2}) \quad \text{so: } [1+\epsilon+\epsilon^{2}] = \begin{bmatrix} -2/3 \\ -1/3 \\ 1 \end{bmatrix}$$

This gives:
$$\mathcal{P}_{\mathcal{D}\leftarrow\mathcal{B}} = \mathcal{P}_{\mathcal{D}\leftarrow\mathcal{B}} \cdot [\mathcal{P}]_{\mathcal{B}} = \begin{bmatrix} 5/6 & 1 & -2/3 \\ 1/6 & 0 & -1/3 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix} = \begin{bmatrix} 19/6 \\ -7/6 \\ 5 \end{bmatrix}$$

2)
$$[\mathcal{P}_{\mathcal{D}} = \mathcal{P}_{\mathcal{D}\leftarrow\mathcal{B}} \cdot [\mathcal{P}]_{\mathcal{B}} = \begin{bmatrix} 5/6 & 1 & -2/3 \\ 1/6 & 0 & -1/3 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix} = \begin{bmatrix} 19/6 \\ -7/6 \\ 5 \end{bmatrix}$$

Proposition

If $\mathcal{B}, \mathcal{D}, \mathcal{E}$ are three bases of a vector space V then:

1)
$$P_{\mathcal{B}\leftarrow\mathcal{D}}=(P_{\mathcal{D}\leftarrow\mathcal{B}})^{-1}$$

2)
$$P_{\mathcal{E} \leftarrow \mathcal{B}} = P_{\mathcal{E} \leftarrow \mathcal{D}} \cdot P_{\mathcal{D} \leftarrow \mathcal{B}}$$