

Linear Algebra	Calculus
$\mathbb{R}^n = \left(\begin{array}{l} \text{set of all column vectors} \\ \text{with } n \text{ entries} \end{array} \right)$	$C^\infty(\mathbb{R}) = \left(\begin{array}{l} \text{set of all smooth} \\ \text{functions } f: \mathbb{R} \rightarrow \mathbb{R} \end{array} \right)$
Column vectors can be added and multiplied by real numbers.	Functions can be added and multiplied by real numbers.
Linear transformation is a function $T: \mathbb{R}^n \rightarrow \mathbb{R}^m, \quad T(\mathbf{v}) = A\mathbf{v}$	Differentiation is a function $D: C^\infty(\mathbb{R}) \rightarrow C^\infty(\mathbb{R}), \quad D(f) = f'$
It satisfies:	It satisfies:
<ul style="list-style-type: none"> • $T(\mathbf{u} + \mathbf{v}) = T(\mathbf{u}) + T(\mathbf{v})$ • $T(c\mathbf{v}) = cT(\mathbf{v})$ 	<ul style="list-style-type: none"> • $D(f + g) = D(f) + D(g)$ • $D(cf) = cD(f)$
Typical problem: given a vector \mathbf{b} find all vectors \mathbf{x} such that $T(\mathbf{x}) = \mathbf{b}$ (i.e solve the equation $A\mathbf{x} = \mathbf{b}$).	Typical problem: given a function g find all functions f such that $D(f) = g$ (i.e find antiderivatives of g).
Fact: Such vectors \mathbf{x} are of the form $\mathbf{x} = \mathbf{v}_0 + \mathbf{n}$ where: <ul style="list-style-type: none"> • \mathbf{v}_0 is some distinguished solution of $A\mathbf{x} = \mathbf{b}$; • $\mathbf{n} \in \text{Nul}(A)$ (i.e. \mathbf{n} is a solution of $A\mathbf{x} = \mathbf{0}$). 	Fact: Such functions f are of the form $f = F + C$ where: <ul style="list-style-type: none"> • F is some distinguished antiderivative of g; • C is a constant function (i.e. C is a solution of $D(f) = 0$).

Definition

A (real) vector space is a set V together with two operations:

- addition

$$\begin{aligned} V \times V &\longrightarrow V \\ (u, v) &\longmapsto u + v \end{aligned}$$

- multiplication by scalars

$$\begin{aligned} \mathbb{R} \times V &\longrightarrow V \\ (c, v) &\longmapsto c \cdot v \end{aligned}$$

Moreover the following conditions must be satisfied:

- 1) $u + v = v + u$
- 2) $(u + v) + w = u + (v + w)$
- 3) there is an element $0 \in V$ such that $0 + u = u$ for any $u \in V$
- 4) for any $u \in V$ there is an element $-u \in V$ such that $u + (-u) = 0$
- 5) $c(u + v) = cu + cv$
- 6) $(c + d)u = cu + du$
- 7) $(cd)u = c(du)$
- 8) $1u = u$

Elements of V are called *vectors*.

Theorem

If V is a vectors space then:

- 1) $c \cdot \mathbf{0} = \mathbf{0}$ where $c \in \mathbb{R}$ and $\mathbf{0} \in V$ is the zero vector;
- 2) $0 \cdot \mathbf{u} = \mathbf{0}$ where $0 \in \mathbb{R}$, $\mathbf{u} \in V$ and $\mathbf{0}$ is the zero vector;
- 3) $(-1) \cdot \mathbf{u} = -\mathbf{u}$

Proof of 2) :

We have:

$$0 \cdot \mathbf{u} = (0+0) \cdot \mathbf{u} \stackrel{\text{by (6)}}{=} 0 \cdot \mathbf{u} + 0 \cdot \mathbf{u}$$

This gives:

$$\begin{aligned} (0 \cdot \mathbf{u}) + (- (0 \cdot \mathbf{u})) &= \underbrace{(0 \cdot \mathbf{u} + 0 \cdot \mathbf{u})}_{\parallel \leftarrow \text{by (2)}} + (- (0 \cdot \mathbf{u})) \\ \parallel \leftarrow \text{by (4)} \quad & (0 \cdot \mathbf{u}) + (0 \cdot \mathbf{u} + (- (0 \cdot \mathbf{u}))) \\ \parallel \leftarrow \text{by (4)} \quad & (0 \cdot \mathbf{u}) + \mathbf{0} \\ \parallel \leftarrow \text{by (3) and (1)} \quad & 0 \cdot \mathbf{u} \end{aligned}$$

So: $\mathbf{0} = 0 \cdot \mathbf{u}$

Examples of vector spaces.

$$1) \mathbb{R}^n = \left\{ \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix} \mid a_1, \dots, a_n \in \mathbb{R} \right\}$$

$$2) \mathcal{F}(\mathbb{R}) = \{ \text{the set of all functions } f: \mathbb{R} \rightarrow \mathbb{R} \}$$

$$3) \mathbb{P} = \{ \text{the set of all polynomials of variable } t \} \\ = \{ a_0 + a_1 t + \dots + a_m t^m \mid a_i \in \mathbb{R}, m \geq 0 \}$$

$$4) M_{m,n}(\mathbb{R}) = \{ \text{the set of all } m \times n \text{ matrices} \} \\ = \left\{ \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} \mid a_{ij} \in \mathbb{R} \right\}$$

Definition

Let V be a vector space. A *subspace* of V is a subset $W \subseteq V$ such that

- 1) $0 \in W$
- 2) if $u, v \in W$ then $u + v \in W$
- 3) if $u \in W$ and $c \in \mathbb{R}$ then $cu \in W$.

Example.

Recall: \mathbb{P} = the vector space of all polynomials.

Take $\mathbb{P}_n = \{ \text{the set of polynomials of degree } \leq n \}$

\mathbb{P}_n is a subspace of \mathbb{P}

Note:

Let $S_3 = \{ \text{the set of polynomials of degree equal to 3} \}$

S_3 is not a subspace of \mathbb{P}

E.g:
$$\left. \begin{array}{l} p(t) = 7 + t - 2t^2 + 3t^3 \\ q(t) = 5 - 4t + 2t^2 - 3t^3 \end{array} \right\} \text{polynomials in } S_3$$

$$p(t) + q(t) = 12 - 3t \quad \left. \vphantom{\begin{array}{l} p(t) + q(t) = 12 - 3t \end{array}} \right\} \text{polynomial of degree 1, not in } S_3$$

Proposition: If V is a vector space, and $W \subseteq V$ is a subspace then W is itself a vector space.

Example.

Recall: $\mathcal{F}(\mathbb{R})$ = the vector space of all functions $f: \mathbb{R} \rightarrow \mathbb{R}$

Some interesting subspaces of $\mathcal{F}(\mathbb{R})$:

- 1) $C(\mathbb{R})$ = the subspace of all continuous functions $f: \mathbb{R} \rightarrow \mathbb{R}$
- 2) $C^n(\mathbb{R})$ = the subspace of all functions $f: \mathbb{R} \rightarrow \mathbb{R}$ that are differentiable n or more times.
- 3) $C^\infty(\mathbb{R})$ = the subspace of all smooth functions $f: \mathbb{R} \rightarrow \mathbb{R}$ (i.e. functions that have derivatives of all orders: f', f'', f''', \dots).

Note

Let $S = \left\{ \begin{array}{l} \text{the set of all functions } f: \mathbb{R} \rightarrow \mathbb{R} \\ \text{such that } f(t) \geq 0 \text{ for all } t \in \mathbb{R} \end{array} \right\}$

S is not a subspace of $\mathcal{F}(\mathbb{R})$

E.g. Take $f(t) = t^2$, then $f(t) \in S$

but $(-2) \cdot f(t) = -2 \cdot t^2$ is not in S .

Note. If V is a vector space then:

- 1) the biggest subspace of V is V itself;
- 2) the smallest subspace of V is the subspace $\{0\}$ consisting of the zero vector only;
- 3) if a subspace of V contains a non-zero vector, then it contains infinitely many vectors.

Indeed: if W is a subspace of V and $u \in W$, $u \neq 0$ then for any $c \in \mathbb{R}$ we have $cu \in W$ and $c_1 u \neq c_2 u$ for $c_1 \neq c_2$.