

Recall: If A is an $m \times n$ matrix then

$$A \cdot \underbrace{\begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}}_{\substack{\uparrow \\ \text{vector in } \mathbb{R}^n}} = \underbrace{\begin{bmatrix} c_1 \\ \vdots \\ c_m \end{bmatrix}}_{\substack{\uparrow \\ \text{vector in } \mathbb{R}^m}}$$

Example:

$$\underbrace{\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}}_{\substack{\text{2x3 matrix}}} \cdot \underbrace{\begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}}_{\substack{\text{vector in } \mathbb{R}^3}} = 2 \cdot \begin{bmatrix} 1 \\ 4 \end{bmatrix} + (-1) \begin{bmatrix} 2 \\ 5 \end{bmatrix} + 1 \cdot \begin{bmatrix} 3 \\ 6 \end{bmatrix} = \underbrace{\begin{bmatrix} 3 \\ 9 \end{bmatrix}}_{\substack{\text{vector in } \mathbb{R}^2}}$$

Definition

If A is an $m \times n$ matrix then the function

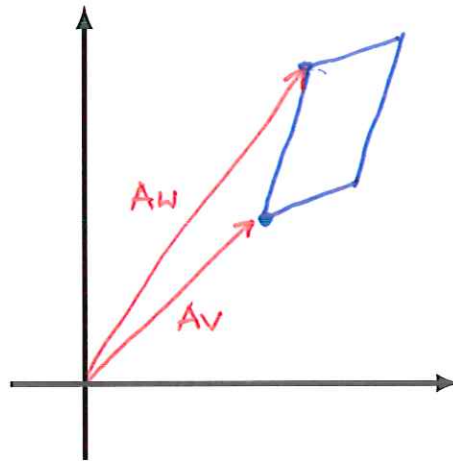
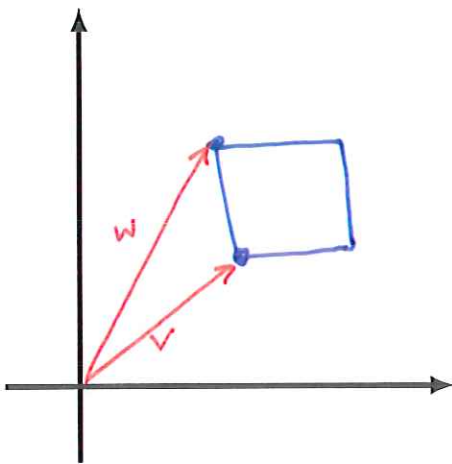
$$T_A: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

given by $T_A(v) = Av$ is called the *matrix transformation* associated to A .

Geometric interpretation of matrix transformations $\mathbb{R}^2 \rightarrow \mathbb{R}^2$

A - 2×2 matrix

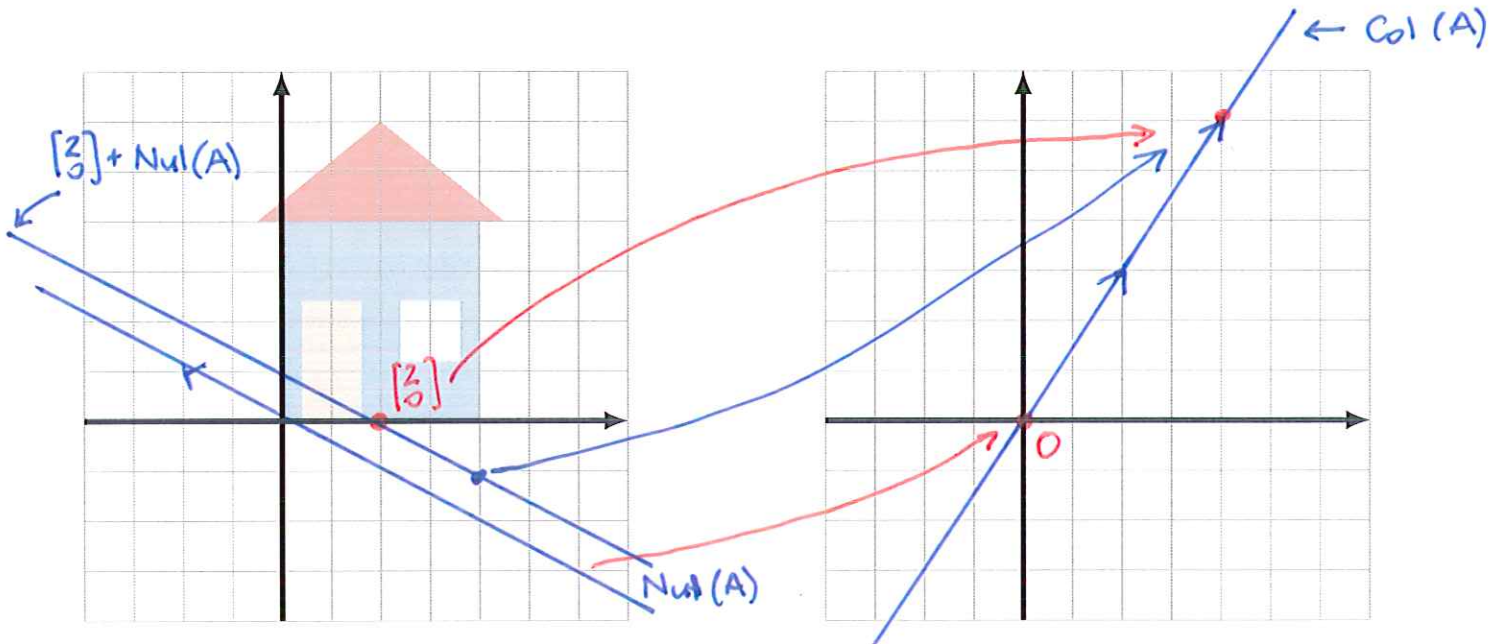
$$T_A : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$$
$$v \longmapsto Av$$



Null spaces, column spaces and matrix transformations

Example.

$$A = \begin{bmatrix} 2 & 4 \\ 3 & 6 \end{bmatrix} \quad T_A: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$



$$\begin{aligned} (\text{Possible values of } T_A) &= (\text{vectors of the form } Av) \\ &= (\text{vectors in } \text{Col}(A)) \\ &= \text{Span} \left(\begin{bmatrix} 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 6 \end{bmatrix} \right) \end{aligned}$$

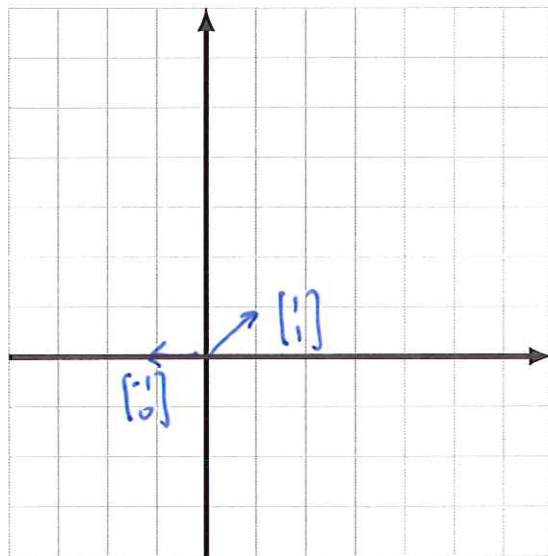
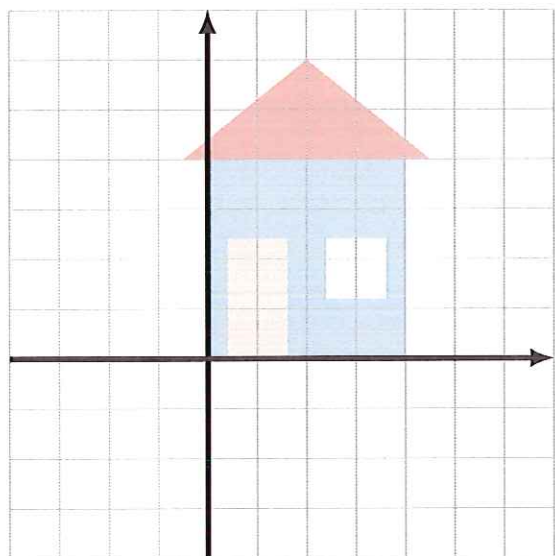
$$\begin{aligned} (\text{vectors } v \text{ s.t. } T_A(v) = 0) &= (\text{vectors } v \text{ s.t. } Av = 0) \\ &= \text{Nul}(A) \end{aligned}$$

$$\left[\begin{array}{cc|c} 2 & 4 & 0 \\ 3 & 6 & 0 \end{array} \right] \xrightarrow{\text{row red.}} \begin{array}{c} x_1 \quad x_2 \\ \left[\begin{array}{cc|c} 1 & 2 & 0 \\ 0 & 0 & 0 \end{array} \right] \end{array} \quad x = \begin{bmatrix} -2x_2 \\ x_2 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \end{bmatrix}$$

$$\underline{\text{so:}} \quad \text{Nul}(A) = \text{Span} \left(\begin{bmatrix} -2 \\ 1 \end{bmatrix} \right)$$

Example.

$$A = \begin{bmatrix} 1 & -1 \\ 1 & 0 \end{bmatrix} \quad T_A: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$



$$\begin{aligned} (\text{Possible values of } T_A) &= \text{Col}(A) \\ &= \text{Span} \left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right) \end{aligned}$$

Recall: If an $m \times n$ matrix A has a pivot position in every row then $\text{Col}(A) = \mathbb{R}^m$

In our case:

$$\begin{bmatrix} \textcircled{1} & -1 \\ 1 & \textcircled{0} \end{bmatrix} \xrightarrow{\text{row red.}} \begin{bmatrix} \textcircled{1} & 0 \\ 0 & \textcircled{1} \end{bmatrix} \quad \text{so: } \text{Col}(A) = \mathbb{R}^2$$

Upshot: Any vector in \mathbb{R}^2 is a value of T_A

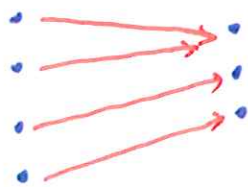
$$\text{Nul}(A): \quad \left[\begin{array}{cc|c} 1 & -1 & 0 \\ 1 & 0 & 0 \end{array} \right] \xrightarrow{\text{row red.}} \left[\begin{array}{cc|c} x_1 & x_2 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{array} \right] \quad \begin{cases} x_1 = 0 \\ x_2 = 0 \end{cases} \quad \text{so: } \text{Nul}(A) = \left\{ \begin{bmatrix} 0 \\ 0 \end{bmatrix} \right\}$$

This gives: if $v \neq w$ then $T_A(v) \neq T_A(w)$.

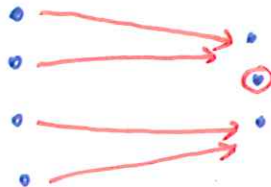
Recall:

A function $F: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is:

- *onto* if for each $\mathbf{b} \in \mathbb{R}^m$ there is $\mathbf{v} \in \mathbb{R}^n$ such that $F(\mathbf{v}) = \mathbf{b}$;

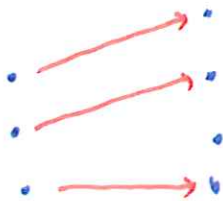


onto

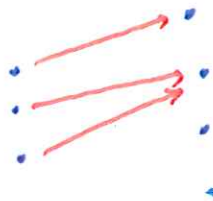


not onto

- *one-to-one* if for any $\mathbf{v}_1, \mathbf{v}_2$ such that $\mathbf{v}_1 \neq \mathbf{v}_2$ we have $F(\mathbf{v}_1) \neq F(\mathbf{v}_2)$.



one-to-one



not one-to-one

Proposition

Let A be an $m \times n$ matrix. The following conditions are equivalent:

- 1) The matrix transformation $T_A: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is onto.
- 2) $\text{Col}(A) = \mathbb{R}^m$.
- 3) The matrix A has a pivot position in every row.

Proposition

Let A be an $m \times n$ matrix. The following conditions are equivalent:

- 1) The matrix transformation $T_A: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is one-to-one.
- 2) $\text{Nul}(A) = \{0\}$.
- 3) The matrix A has a pivot position in every column.

Example. For the following 3×4 matrix A check if the matrix transformation $T_A: \mathbb{R}^4 \rightarrow \mathbb{R}^3$ is onto and if it is one-to-one.

$$A = \begin{bmatrix} 1 & 1 & 0 & 2 \\ -2 & -2 & 1 & -5 \\ 1 & 1 & -1 & 4 \end{bmatrix}$$

$$\begin{bmatrix} \textcircled{1} & 1 & 0 & 2 \\ -2 & -2 & \textcircled{1} & -5 \\ 1 & 1 & -1 & \textcircled{4} \end{bmatrix} \xrightarrow{\text{row red.}} \begin{bmatrix} \textcircled{1} & 1 & 0 & 0 \\ 0 & 0 & \textcircled{1} & 0 \\ 0 & 0 & 0 & \textcircled{1} \end{bmatrix}$$

pivot position in every row $\Rightarrow \text{Col}(A) = \mathbb{R}^3$
so: T_A is onto

no pivot position in the second column $\Rightarrow \text{Nul}(A) \neq \{0\}$
so: T_A is not one-to-one.

Example. For the following 3×3 matrix A check if the matrix transformation $T_A: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ is onto and if it is one-to-one.

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 1 & 2 & 5 \end{bmatrix}$$

$$\begin{bmatrix} \textcircled{1} & 2 & 3 \\ 2 & \textcircled{3} & 4 \\ 1 & 2 & \textcircled{5} \end{bmatrix} \xrightarrow{\text{row red.}} \begin{bmatrix} \textcircled{1} & 0 & 0 \\ 0 & \textcircled{1} & 0 \\ 0 & 0 & \textcircled{1} \end{bmatrix}$$

pivot position in every row $\Rightarrow \text{Col}(A) = \mathbb{R}^3$
so: T_A is onto

pivot position in every column $\Rightarrow \text{Nul}(A) = \{0\}$
so: T_A is one-to-one.

Proposition

Let A be an $m \times n$ matrix. If the matrix transformation $T_A: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is both onto and one-to-one then we must have $m = n$ (i.e. A must be a square matrix).