

Theorem

Any A an $m \times n$ matrix can be written as a product

$$A = U\Sigma V^T$$

where:

- $U = [\mathbf{u}_1 \ \dots \ \mathbf{u}_m]$ is an $m \times m$ orthogonal matrix.
- $V = [\mathbf{v}_1 \ \dots \ \mathbf{v}_n]$ is an $n \times n$ orthogonal matrix.
- Σ is an $m \times n$ matrix of the following form:

$$\begin{bmatrix} \sigma_1 & 0 & \dots & 0 \\ 0 & \sigma_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_n \\ 0 & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & 0 \end{bmatrix} \quad \text{or} \quad \begin{bmatrix} \sigma_1 & 0 & \dots & 0 & 0 & \dots & 0 \\ 0 & \sigma_2 & \dots & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & 0 & 0 & \dots & 0 \\ 0 & 0 & \dots & \sigma_m & 0 & \dots & 0 \end{bmatrix}$$

(if $n \leq m$) (if $n \geq m$)

where $\sigma_1 \geq \sigma_2 \geq \dots \geq 0$.

Note.

- The numbers $\sigma_1, \sigma_2, \dots$ are called *singular values* of A .
- The vectors $\mathbf{u}_1, \dots, \mathbf{u}_m$ are called *left singular vectors* of A .
- Then the vectors $\mathbf{v}_1, \dots, \mathbf{v}_n$ are called *right singular vectors* of A .
- The formula $A = U\Sigma V^T$ is called a *singular value decomposition (SVD)* of A .
- The matrix Σ is uniquely determined, but U and V depend on some choices.

Theorem

Let A be a matrix with a singular value decomposition

$$A = U\Sigma V^T$$

If

$$U = [u_1 \ \dots \ u_m] \quad V = [v_1 \ \dots \ v_n]$$

and $\sigma_1, \dots, \sigma_r$ are singular values of A then then

$$A = \sigma_1(u_1 v_1^T) + \sigma_2(u_2 v_2^T) + \dots + \sigma_r(u_r v_r^T)$$

e.g.:

$$A = \underset{3 \times 2}{U} \cdot \underset{3 \times 3}{\Sigma} \cdot \underset{3 \times 2}{V}^T$$

$$U = [u_1 \ u_2 \ u_3]$$

$$\Sigma = \begin{bmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \\ 0 & 0 \end{bmatrix}$$

$$V = [v_1 \ v_2]$$

$$A = [u_1 \ u_2 \ u_3] \cdot \begin{bmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} v_1^T \\ v_2^T \end{bmatrix}$$

$$= [\sigma_1 u_1 \ \sigma_2 u_2] \cdot \begin{bmatrix} v_1^T \\ v_2^T \end{bmatrix}$$

$$= \sigma_1(u_1 v_1^T) + \sigma_2(u_2 v_2^T)$$

Application: Image compression



- The size of this image is 700×800 pixels.
- The color of each pixel is represented by an integer between 0 (black) and 255 (white).
- The whole image is described by a (symmetric) matrix A consisting of $700 \times 800 = 560,000$ numbers
- Each number is stored in 1 byte, so the image file size is 560,000 bytes (≈ 0.53 MB).

How to make the image file smaller:

1) Compute SVD of the matrix A :

$$A = U\Sigma V^T$$

where

$$U = [u_1 \ \dots \ u_m] \quad V = [v_1 \ \dots \ v_n]$$

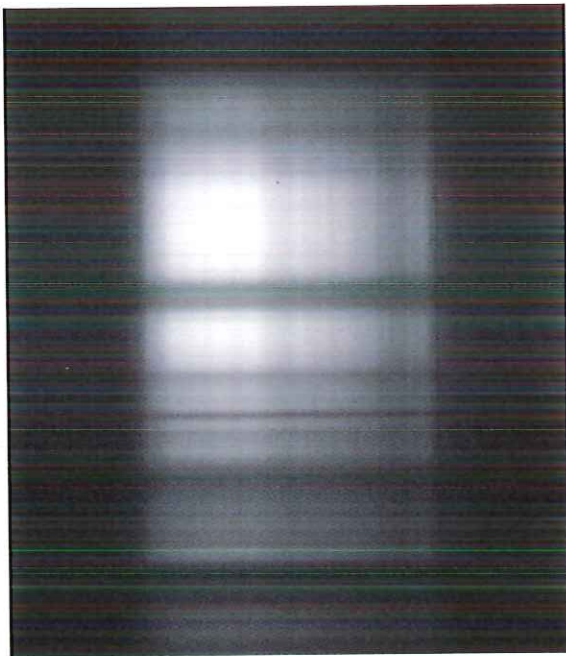
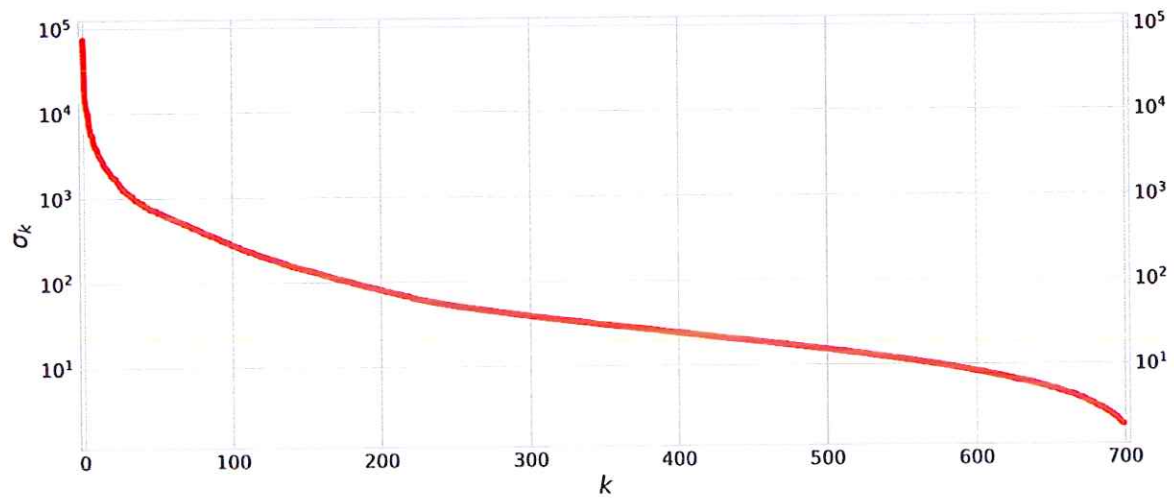
and $\sigma_1, \dots, \sigma_r$ are singular values of A .

2) Replace A by the matrix

$$B_k = \sigma_1(u_1 v_1^T) + \dots + \sigma_k(u_k v_k^T)$$

for some $1 \leq k \leq 700$. This matrix can be stored using $k \cdot (700 + 800 + 1)$ numbers.

Singular values of the matrix A



matrix B_1
1501 bytes
compression 374:1



matrix B_5
7905 bytes
compression 75:1



matrix B_{10}
15,010 bytes
compression 37:1



matrix B_{20}
30,020 bytes
compression 18:1



matrix B_{50}
75,050 bytes
compression 7:1



matrix B_{100}
150,100 bytes
compression 4:1

How to compute SVD of a matrix A

Assume: $A = U \cdot \Sigma \cdot V^T$

\uparrow \uparrow \uparrow
 orthogonal diagonal orthogonal

Then: $A^T A = (U \Sigma V^T)^T (U \Sigma V^T) = (V^T)^T \Sigma^T U^T U \Sigma V = V (\Sigma^T \Sigma) V^T$

Note: $\Sigma^T \Sigma$ is a diagonal matrix with squares of singular values on the diagonal.

e.g.: $\Sigma = \begin{bmatrix} \sigma_1 & 0 & 0 \\ 0 & \sigma_2 & 0 \end{bmatrix}$

$$\Sigma^T \cdot \Sigma = \begin{bmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{bmatrix} \cdot \begin{bmatrix} \sigma_1 & 0 & 0 \\ 0 & \sigma_2 & 0 \end{bmatrix} = \begin{bmatrix} \sigma_1^2 & 0 & 0 \\ 0 & \sigma_2^2 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

We obtain: $\underbrace{A^T A}_{\text{symmetric}} = V \underbrace{(\Sigma^T \Sigma)}_{\text{diagonal}} V^T$

\leftarrow This is an orthogonal diagonalization of $A^T A$.
 We know how to compute.

This gives matrices V and Σ :

(columns of V) = (orthogonal eigenvectors of $A^T A$)

(diagonal entries of Σ)
 (i.e. singular values of A) = $\sqrt{\text{eigenvalues of } A^T A}$

It remains to compute the matrix U

$A = U \Sigma V^T$ gives: $AV = U \Sigma$

Note: If $U = [u_1 \dots u_m]$ $V = [v_1 \dots v_n]$ $\sigma_1, \dots, \sigma_r$ - non-zero singular values of A

then: $AV = [Av_1 \ Av_2 \ \dots \ Av_n]$

$U \Sigma = [\sigma_1 u_1 \ \sigma_2 u_2 \ \dots \ \sigma_r u_r \ 0 \ \dots \ 0]$

So: $u_1 = \frac{1}{\sigma_1} (Av_1)$ $u_2 = \frac{1}{\sigma_2} (Av_2)$ \dots $u_r = \frac{1}{\sigma_r} (Av_r)$

Vectors u_{r+1}, \dots, u_m can be chosen in an arbitrary way so that $\{u_1, \dots, u_r, u_{r+1}, \dots, u_m\}$ is an orthonormal basis of \mathbb{R}^m .

How to compute SVD of a matrix A

1) Compute an orthogonal diagonalization of the symmetric $n \times n$ matrix $A^T A$:

$$A^T A = Q D Q^T$$

such that eigenvalues on the diagonal of the matrix D are arranged from the largest to the smallest. We set $V = Q$.

2) If

$$D = \begin{bmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_n \end{bmatrix}$$

then $\sigma_i = \sqrt{\lambda_i}$. This gives the matrix Σ .

Note: if $n > m$ then we use only $\lambda_1, \dots, \lambda_m$. The remaining eigenvalues $\lambda_{m+1}, \dots, \lambda_n$ of D will be equal to 0 in this case.

3) Let $V = [v_1 \dots v_n]$, and let $\sigma_1, \dots, \sigma_r$ be non-zero singular values of A . The first r columns of the matrix $U = [u_1 \dots u_m]$ are given by

$$u_i = \frac{1}{\sigma_i} A v_i$$

The remaining columns u_{r+1}, \dots, u_m can be added arbitrarily so that U is an orthogonal matrix (i.e. $\{u_1, \dots, u_m\}$ is an orthonormal basis of \mathbb{R}^m).

Example. Find SVD of the following matrix:

$$A = \begin{bmatrix} -1 & 0 \\ 1 & -1 \\ 0 & 1 \end{bmatrix} \quad A = U \Sigma V^T$$

$\begin{matrix} 3 \times 2 \\ U \end{matrix}$
 $\begin{matrix} \Sigma = \begin{bmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \\ 0 & 0 \end{bmatrix}$
 $\begin{matrix} 3 \times 2 \\ V \end{matrix}$
 $\begin{matrix} 2 \times 2 \end{matrix}$

① Compute an orthogonal diagonalization of $A^T A$:

$$A^T A = \begin{bmatrix} -1 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} \cdot \begin{bmatrix} -1 & 0 \\ 1 & -1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$$

$$P(\lambda) = \det(A^T A - \lambda I) = \lambda^2 - 4\lambda + 3 \quad \text{eigenvalues of } A^T A: \lambda_1 = 3, \lambda_2 = 1$$

$$(\text{basis of eigensp. for } \lambda_1 = 3) = \left\{ \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \right\} \quad \|w_1\| = \sqrt{2}$$

$$(\text{basis of eigensp. for } \lambda_2 = 1) = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\} \quad \|w_2\| = \sqrt{2}$$

We get: $A^T A = V D V^T$ where $V = \begin{bmatrix} \frac{w_1}{\|w_1\|} & \frac{w_2}{\|w_2\|} \end{bmatrix} = \begin{bmatrix} -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$

$$D = \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix} \quad \begin{matrix} \sigma_1^2 \\ \sigma_2^2 \end{matrix}$$

② We obtain:

$$V = \begin{bmatrix} -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}, \quad \Sigma = \begin{bmatrix} \sqrt{3} & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$$

③ Compute U :

$$\text{Let } U = [u_1, u_2, u_3]$$

$$\begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ -\frac{2}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 1 & -1 \\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} = [u_1, u_2, u_3] \cdot \begin{bmatrix} \sqrt{3} & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} = [\sqrt{3}u_1, 1 \cdot u_2]$$

$A \cdot V$

$$\text{So: } u_1 = \frac{1}{\sqrt{3}} \begin{bmatrix} \frac{1}{\sqrt{2}} \\ -\frac{2}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{6}} \\ -\frac{2}{\sqrt{6}} \\ \frac{1}{\sqrt{6}} \end{bmatrix} \quad u_2 = \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

$u_3 = ?$

- Start with a vector z_3 lin. indep. of u_1, u_2 .

In this example we can use e.g. $z_3 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

- $\{u_1, u_2, z_3\}$ is an basis of \mathbb{R}^3 . Use Gram-Schmidt process to make it into an orthogonal basis.

Since u_1, u_2 are already orthogonal it suffices to modify z_3 :

$$w_3 = z_3 - \left(\frac{z_3 \cdot u_1}{u_1 \cdot u_1} \right) u_1 - \left(\frac{z_3 \cdot u_2}{u_2 \cdot u_2} \right) u_2$$

$$z_3 \cdot u_1 = 1/\sqrt{6}, \quad u_1 \cdot u_1 = 1, \quad z_3 \cdot u_2 = -1/\sqrt{2}, \quad u_2 \cdot u_2 = 1$$

so:

$$w_3 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} - \frac{1}{\sqrt{6}} \begin{bmatrix} 1/\sqrt{6} \\ 2/\sqrt{6} \\ 1/\sqrt{6} \end{bmatrix} - \left(-\frac{1}{\sqrt{2}} \right) \begin{bmatrix} -1/\sqrt{2} \\ 0 \\ 1/\sqrt{2} \end{bmatrix} = \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix}$$

Take $u_3 = \frac{w_3}{\|w_3\|}$

$$\|w_3\| = \frac{1}{\sqrt{3}} \quad \text{so:} \quad u_3 = \sqrt{3} \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix} = \begin{bmatrix} 1/\sqrt{3} \\ 1/\sqrt{3} \\ 1/\sqrt{3} \end{bmatrix}$$

We obtain:

$$A = \begin{matrix} & \begin{matrix} u_1 & u_2 & u_3 \end{matrix} \\ \begin{bmatrix} 1/\sqrt{6} & -1/\sqrt{2} & 1/\sqrt{3} \\ 2/\sqrt{6} & 0 & 1/\sqrt{3} \\ 1/\sqrt{6} & 1/\sqrt{2} & 1/\sqrt{3} \end{bmatrix} & \cdot & \begin{bmatrix} \sqrt{3} & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} & \cdot & \begin{bmatrix} -1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix} \\ & \begin{matrix} U & \Sigma & V^T \end{matrix} \end{matrix}$$