#### **Definition**

A set of vectors  $\{\mathbf{v}_1, \dots, \mathbf{v}_k\}$  in  $\mathbb{R}^n$  is an *orthogonal set* if each pair each pair of vectors in this set is orthogonal, i.e.

$$\mathbf{v}_i \cdot \mathbf{v}_j = 0$$

for all  $i \neq j$ .

## Example.

$$\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\} \text{ is an orthogonal set in } \mathbb{R}^3.$$

## Example.

$$\left\{ \begin{bmatrix} 1\\2\\3 \end{bmatrix}, \begin{bmatrix} -3\\0\\1 \end{bmatrix}, \begin{bmatrix} 1\\-5\\3 \end{bmatrix} \right\} \text{ is another orthogonal set in } \mathbb{R}^3.$$



If  $\{v_1, \ldots, v_k\}$  is an orthogonal set of non-zero vectors in  $\mathbb{R}^n$  then this set is linearly independent.

**Recall:** Any linearly independent set of n vectors in  $\mathbb{R}^n$  is a basis of  $\mathbb{R}^n$ .

# Corollary

If  $\{v_1, \ldots, v_n\}$  is an orthogonal set of n non-zero vectors in  $\mathbb{R}^n$  then this set is a basis of  $\mathbb{R}^n$ .

#### **Definition**

If V is a subspace of  $\mathbb{R}^n$  then we say that a set  $\{\mathbf{v}_1, \dots \mathbf{v}_k\}$  is an *orthogonal basis* of V if

- 1)  $\{v_1, \dots v_k\}$  is a basis of V and
- 2)  $\{v_1, \dots v_k\}$  is an orthogonal set.

**Recall.** If  $\mathcal{B} = \{\mathbf{v}_1, \dots \mathbf{v}_k\}$  is a basis of a vector space V and  $\mathbf{w} \in V$  then the coordinate vector of  $\mathbf{w}$  relative to  $\mathcal{B}$  is the vector

$$\left[\begin{array}{c}\mathbf{w}\end{array}\right]_{\mathcal{B}} = \left[\begin{array}{c}c_1\\ \vdots\\ c_k\end{array}\right]$$

where  $c_1, \ldots, c_k$  are scalars such that  $c_1 \mathbf{v}_1 + \ldots + c_k \mathbf{v}_k = \mathbf{w}$ .

## **Propostion**

If  $\mathcal{B} = \{\mathbf{v}_1, \dots \mathbf{v}_k\}$  is an orthogonal basis of V and  $\mathbf{w} \in V$  then

$$\left[\begin{array}{c}\mathbf{w}\end{array}\right]_{\mathcal{B}} = \left[\begin{array}{c}c_1\\\vdots\\c_k\end{array}\right]$$

where 
$$c_i = \frac{\mathbf{w} \cdot \mathbf{v}_i}{\mathbf{v}_i \cdot \mathbf{v}_i} = \frac{\mathbf{w} \cdot \mathbf{v}_i}{\left|\left|\mathbf{v}_i\right|\right|^2}$$

Example. Let

$$\mathcal{B} = \left\{ \begin{bmatrix} 1\\2\\3 \end{bmatrix}, \begin{bmatrix} -3\\0\\1 \end{bmatrix}, \begin{bmatrix} 1\\-5\\3 \end{bmatrix} \right\}, \quad \mathbf{w} = \begin{bmatrix} 3\\2\\1 \end{bmatrix}$$

The set  $\mathcal B$  is an orthogonal basis of  $\mathbb R^3$ . Compute  $[\mathbf w]_{\mathcal B}$ .

## Theorem (Gram-Schmidt Process)

Let  $\{v_1, \ldots, v_k\}$  be a basis of V. Define vectors  $\{w_1, \ldots, w_k\}$  as follows:

$$\mathbf{w}_1 = \mathbf{v}_1$$

$$\mathbf{w}_2 = \mathbf{v}_2 - \left(\frac{\mathbf{w}_1 \cdot \mathbf{v}_2}{\mathbf{w}_1 \cdot \mathbf{w}_1}\right) \mathbf{w}_1$$

$$\mathbf{w}_3 = \mathbf{v}_3 - \left(\frac{\mathbf{w}_1 \cdot \mathbf{v}_3}{\mathbf{w}_1 \cdot \mathbf{w}_1}\right) \mathbf{w}_1 - \left(\frac{\mathbf{w}_2 \cdot \mathbf{v}_3}{\mathbf{w}_2 \cdot \mathbf{w}_2}\right) \mathbf{w}_2$$

... ... ... ... ... ...

$$\mathbf{w}_k = \mathbf{v}_k - \left(\frac{\mathbf{w}_1 \cdot \mathbf{v}_k}{\mathbf{w}_1 \cdot \mathbf{w}_1}\right) \mathbf{w}_1 - \left(\frac{\mathbf{w}_2 \cdot \mathbf{v}_k}{\mathbf{w}_2 \cdot \mathbf{w}_2}\right) \mathbf{w}_2 - \ldots - \left(\frac{\mathbf{w}_{k-1} \cdot \mathbf{v}_k}{\mathbf{w}_{k-1} \cdot \mathbf{w}_{k-1}}\right) \mathbf{w}_{k-1}$$

Then the set  $\{\mathbf{w}_1, \ldots, \mathbf{w}_k\}$  is an orthogonal basis of V.

**Example.** In  $\mathbb{R}^4$  take

$$\mathbf{v}_1 = \begin{bmatrix} 2\\1\\3\\-1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 7\\4\\3\\-3 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 5\\7\\7\\8 \end{bmatrix}$$

The set  $\mathcal{B} = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  is a basis of some subspace  $V \subseteq \mathbb{R}^4$ . Find an orthogonal basis of V.

### **Definition**

An orthogonal basis  $\mathcal{B} = \{\mathbf{w}_1, \dots, \mathbf{w}_k\}$  of V is called an *orthonormal basis* if  $||\mathbf{w}_i|| = 1$  for  $i = 1, \dots, k$ .

## **Propostion**

If  $\mathcal{B} = \{v_1, \dots v_k\}$  is an orthonormal basis of V and  $\mathbf{w} \in V$  then

$$\left[\begin{array}{c}\mathbf{w}\end{array}\right]_{\mathcal{B}} = \left[\begin{array}{c}c_1\\\vdots\\c_k\end{array}\right]$$

where  $c_i = \mathbf{w} \cdot \mathbf{v}_i$ .

**Note.** If  $\mathcal{B} = \{v_1, \dots v_k\}$  is an orthogonal basis of V then

$$C = \left\{ \frac{\mathbf{v}_1}{\|\mathbf{v}_1\|}, \dots, \frac{\mathbf{v}_k}{\|\mathbf{v}_k\|} \right\}$$

is an orthonormal basis of V.