Next: From systems of linear equations to vector equations.

$$\begin{cases} x_1 + 2x_2 = 4 \\ 2x_1 + 7x_2 = 9 \\ 4x_1 + x_2 = 0 \end{cases} \qquad x_1 \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 7 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 9 \\ 0 \end{bmatrix}$$

Why vectors and vector equations are useful:

- They show up in many applications (velocity vectors, force vectors etc.)
- They give a better geometric picture of systems of linear equations.

Definition

A column vector is a matrix with one column.

Example

$$u : \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \qquad V = \begin{bmatrix} 5 \\ -1 \\ 0 \\ 7 \end{bmatrix}$$

Note. Columns of a matrix are column vectors.

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} = \begin{bmatrix} V_1 & V_2 & V_3 \end{bmatrix}$$

$$V_1 = \begin{bmatrix} 1 \\ 4 \end{bmatrix} \quad V_2 = \begin{bmatrix} 2 \\ 5 \end{bmatrix} \quad V_3 = \begin{bmatrix} 3 \\ 6 \end{bmatrix}$$

Notation

 \mathbb{R}^n is the set of all column vectors with n entries.

$$\mathbb{R}^2 = \left\{ \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} \middle| a_1, a_2 \in \mathbb{R} \right\} = \text{the set of all vectors with } 2 \text{ entries}$$

$$\mathbb{R}^3 = \left\{ \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} \middle| a_1, a_2, a_3 \in \mathbb{R} \right\} = \text{the set of all vectors with } 3 \text{ entries}$$

Operations on vectors in \mathbb{R}^n

1) Addition of vectors:

$$\begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} + \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix} = \begin{bmatrix} a_1 + b_1 \\ \vdots \\ a_n + b_n \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + \begin{bmatrix} 5 \\ -1 \\ 7 \end{bmatrix} = \begin{bmatrix} 6 \\ 1 \\ 10 \end{bmatrix}$$

Note: We can add two vectors only if they have the same number of entries.

2) Multiplication by scalars:

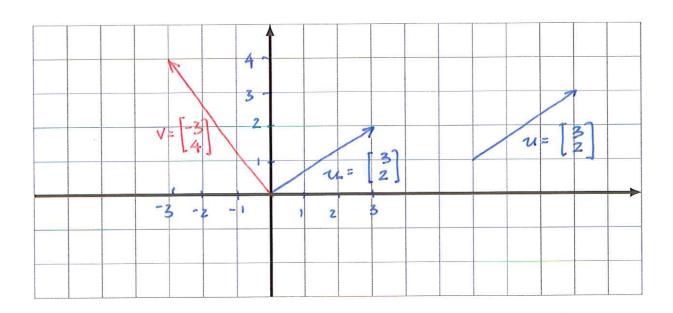
scalars = real numbers

$$c \cdot \left[\begin{array}{c} a_1 \\ \vdots \\ a_n \end{array} \right] = \left[\begin{array}{c} ca_1 \\ \vdots \\ ca_n \end{array} \right]$$

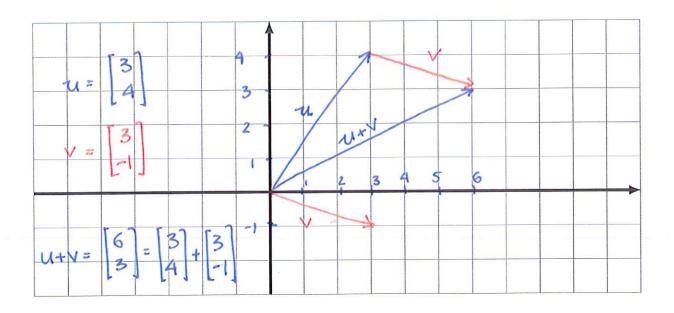
$$\underbrace{2.9:}_{3. \begin{bmatrix} 2 \\ -1 \\ 5 \end{bmatrix}} = \begin{bmatrix} 6 \\ -3 \\ 15 \end{bmatrix}$$

Geometric interpretation of vectors in $\mathbb{R}^2\,$

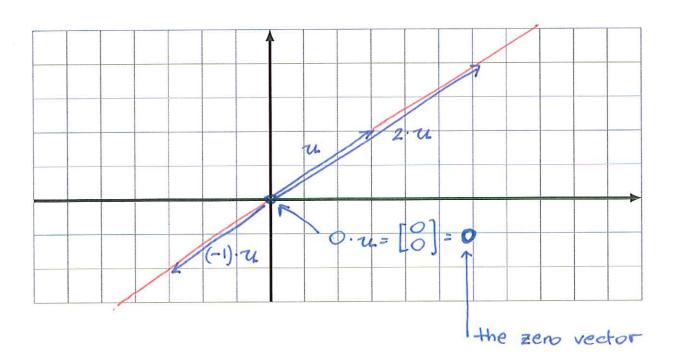
Vector coordinates:



Vector addition:



Scalar multiplication:



Vector equations

$$x_1v_1 + x_2v_2 + \ldots + x_pv_p = w$$
vectors in \mathbb{R}^n

Example. Solve the following vector equation:

$$x_{1}\begin{bmatrix} 2\\3 \end{bmatrix} + x_{2}\begin{bmatrix} 4\\-2 \end{bmatrix} = \begin{bmatrix} 10\\3 \end{bmatrix}$$

$$\begin{bmatrix} 2\times_{1}\\3\times_{1} \end{bmatrix} + \begin{bmatrix} 4\times_{2}\\-2\times_{2} \end{bmatrix} = \begin{bmatrix} 10\\3 \end{bmatrix}$$

$$\begin{bmatrix} 2\times_{1}+4\times_{2}\\3\times_{1}-2\times_{2} \end{bmatrix} = \begin{bmatrix} 10\\3 \end{bmatrix}$$

$$\begin{bmatrix} 2\times_{1}+4\times_{2}\\3\times_{1}-2\times_{2} \end{bmatrix} = \begin{bmatrix} 10\\3 \end{bmatrix}$$

$$\begin{cases} 2\times_{1}+4\times_{2}=10\\3\times_{1}-2\times_{2}=3\\ \text{ system of linear equations} \end{cases}$$

ouigmented metrix;

$$\begin{bmatrix} 2 & 4 & 10 \\ 3 & -2 & 3 \end{bmatrix} \xrightarrow{\text{now red.}} \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 3/2 \end{bmatrix} \xrightarrow{\text{solutions}} \begin{cases} x_1 = 2 \\ x_2 = 3/2 \end{cases}$$

How to solve a vector equation

$$x_1v_1 + \ldots + x_pv_p = w$$

vector of equation

make a matrix

 $\begin{bmatrix} v_1 & \dots & v_p & w \end{bmatrix}$ augmented matrix

row reduction

[reduced matrix]

read off solutions

$$\begin{cases} x_1 = \dots \\ \dots & \dots \\ x_p = \dots \\ \text{solutions} \end{cases}$$

Example: Target shooting.

At time t=0 a target is observed at the position (x_0, y_0) moving in the direction of the vector v_t . The target is moving at such speed, that it travels the length of v_t in one second. Find t_0 such that a missile positioned at the point (0,0) will intercept the target if it is fired at the time t_0 . The missile travels the length of the vector v_m in one second.

