Recall:

1) The least square solutions of a matrix equation $A\mathbf{x} = \mathbf{b}$ are the solutions of the equation

$$A\mathbf{x} = \operatorname{proj}_{\operatorname{Col}(A)}\mathbf{b}$$

- 2) If $A\mathbf{x} = \mathbf{b}$ is a consistent equation, then $\mathbf{b} \in \operatorname{Col}(A)$, and $\operatorname{proj}_{\operatorname{Col}(A)}\mathbf{b} = \mathbf{b}$. In such case the least square solutions of $A\mathbf{x} = \mathbf{b}$ are just the ordinary solutions.
- 3) If $A\mathbf{x} = \mathbf{b}$ is inconsistent, then the least square solutions are the best substitute for the (nonexistent) ordinary solutions.
- 4) If $\{v_1, \ldots, v_k\}$ is an orthogonal basis of a subspace V of \mathbb{R}^n then

$$\operatorname{proj}_{V} \mathbf{w} = \left(\frac{\mathbf{w} \cdot \mathbf{v}_{1}}{\mathbf{v}_{1} \cdot \mathbf{v}_{1}}\right) \mathbf{v}_{1} + \ldots + \left(\frac{\mathbf{w} \cdot \mathbf{v}_{k}}{\mathbf{v}_{k} \cdot \mathbf{v}_{k}}\right) \mathbf{v}_{k}$$

5) If $\{v_1, \ldots, v_k\}$ is an arbitrary basis of V then we can use the Gram-Schmidt process to obtain an orthogonal basis of V.

How to compute least square solutions of Ax = b (version 1.0)

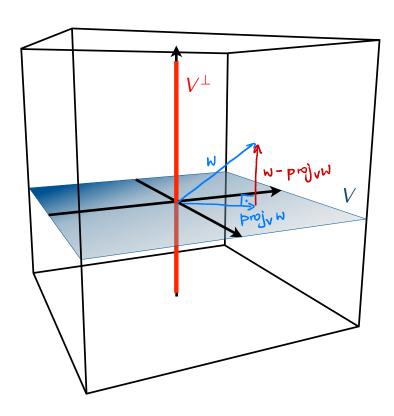
- 1) Compute a basis of Col(A).
- 2) Use the Gram-Schmidt process to get an orthogonal basis of Col(A).
- 3) Use the orthogonal basis to compute $proj_{Col(A)}\mathbf{b}$.
- 4) Compute solutions of the equation $A\mathbf{x} = \operatorname{proj}_{\operatorname{Col}(A)} \mathbf{b}$.

Next goal: Simplify this.

Definition

If V is a subspace of \mathbb{R}^n then the *orthogonal complement* of V is the set V^{\perp} of all vectors orthogonal to V:

$$V^{\perp} = \{ \mathbf{w} \in \mathbb{R}^n \mid \mathbf{w} \cdot \mathbf{v} = 0 \}$$



Note: If V=R" WER" then (W-projvW) e V1

Proposition

If V is a subspace of \mathbb{R}^n then:

- 1) V^{\perp} is also a subspace of \mathbb{R}^n .
- 2) For each vector $\mathbf{w} \in \mathbb{R}^n$ there exist unique vectors $\mathbf{v} \in V$ and $\mathbf{z} \in V^{\perp}$ such that $\mathbf{w} = \mathbf{v} + \mathbf{z}$.

Definition

If A is an $m \times n$ matrix then the *row space* of A is the subspace Row(A) of \mathbb{R}^n spanned by rows of A.

Example

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$$

$$\Re(A) = \operatorname{Span}\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \end{bmatrix}\right)$$

Proposition

If A is a matrix then

$$Row(A)^{\perp} = Nul(A)$$

Note:

If
$$A = \begin{bmatrix} r_1 & r_2 & r_3 \\ r_2 & r_4 \end{bmatrix}$$
 rous of A

then: $A \cdot V = \begin{bmatrix} r_1 \cdot V \\ r_2 \cdot V \\ r_m \cdot V \end{bmatrix}$

E.q:

$$\begin{bmatrix} r_1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \cdot \begin{bmatrix} 7 \\ 8 \\ q \end{bmatrix} = \begin{bmatrix} 1 \cdot 7 + 2 \cdot 8 + 3 \cdot q \\ 4 \cdot 7 & 5 \cdot 8 + 6 \cdot q \end{bmatrix} = \begin{bmatrix} r_1 \cdot V \\ r_2 \cdot V \end{bmatrix}$$

Proof of Proposition:

Let $A = \begin{bmatrix} r_1 \\ r_2 \\ r_m \end{bmatrix}$. We have: $V \in \text{Nul}(A)$

$$AV = O$$

$$T_1 \cdot V = O_1 T_2 \cdot V = O_1, \dots, r_m \cdot V = O_1$$

$$V \in \text{Row}(A) + O_1$$

Corollary

If A is a matrix then

$$Col(A)^{\perp} = Nul(A^{T})$$

Note:
$$Col(A) = Rou(A^T)$$
 $Col(A) = Rou(A^T)$
 $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$
 $A^T = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$
 $Col(A) = Span(\begin{bmatrix} 1 \\ 4 \end{bmatrix}, \begin{bmatrix} 2 \\ 5 \end{bmatrix}, \begin{bmatrix} 3 \\ 6 \end{bmatrix})$
 $Rou(A^T) = Span(\begin{bmatrix} 1 \\ 4 \end{bmatrix}, \begin{bmatrix} 2 \\ 5 \end{bmatrix}, \begin{bmatrix} 3 \\ 6 \end{bmatrix})$
 $Proof o(Corollary)$
 $Col(A)^{\perp} = Rou(A^T)^{\perp} = Nul(A^T)$

Back to least square solutions

Theorem

A vector $\hat{\mathbf{x}}$ is a least square solution of a matrix equation

$$Ax = b$$

if and only if $\hat{\mathbf{x}}$ is an ordinary solution of the equation

$$(A^T A)\mathbf{x} = A^T \mathbf{b}$$

Proof: If \hat{x} is a least square solution of Ax = b then:

This gives:

$$(b-A\hat{x}) = (b-proj_{Col(A)}b) \in Col(A)^{\perp} = Nul(A^{\top})$$

We obtain:

$$A^{T}(b-A\hat{x})=0$$

This shows that & is a solution of the equation

Theorem

The equation

$$(A^T A)\mathbf{x} = A^T \mathbf{b}$$

is called the *normal equation* of Ax = b.

How to compute least square solutions of Ax = b(version 2.0)

- 1) Compute A^TA , A^T **b**.
- 2) Solve the normal equation $(A^T A)\mathbf{x} = A^T \mathbf{b}$.

Example. Compute least square solutions of the following equation:

$$\begin{bmatrix} 1 & 1 \\ 0 & 2 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$
Note:
$$\begin{cases} x_1 + x_2 = 1 \\ 2x_2 = 2 \\ 0 = 3 \end{cases}$$
no solutions

Solution:

$$A^{T} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 2 & 0 \end{bmatrix}$$
 $A^{T}A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 2 & 0 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 5 \end{bmatrix}$
 $A^{T}b = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 2 & 0 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 5 \end{bmatrix}$

The normal equation:

The normal equation:

$$A^{T}A \times = A^{T}b$$

$$\begin{bmatrix} 1 & 1 \\ 1 & 5 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 5 \end{bmatrix}$$
and metrix
$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 5 & 5 \end{bmatrix} \xrightarrow{red} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \end{bmatrix} \qquad \frac{\text{least sq. solutions}}{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$