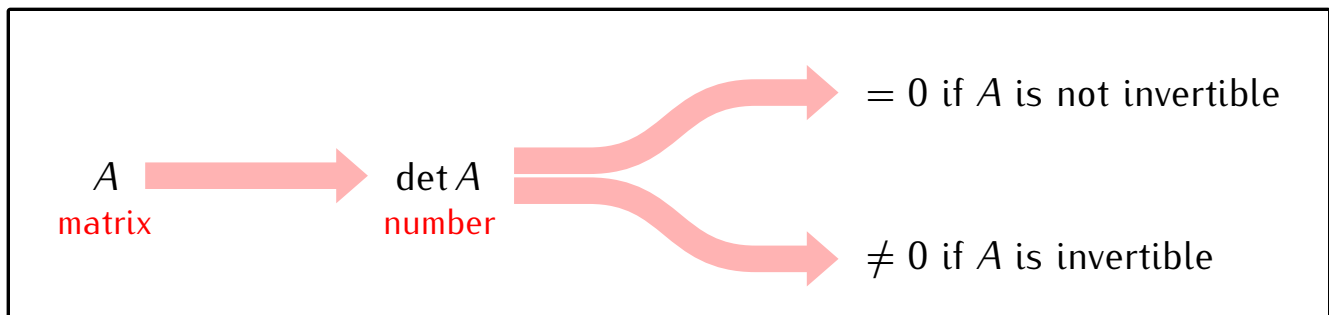


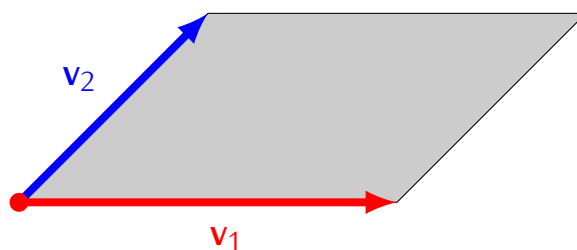
**Example.** Solve the equation

$$\begin{bmatrix} 1 & 1 & 2 \\ 4 & 0 & 0 \\ 1 & 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

Recall:



**Note.** Any two vectors in  $\mathbb{R}^2$  define a parallelogram:



**Notation**

$$\text{area}(v_1, v_2) = \left( \begin{array}{l} \text{area of the parallelogram} \\ \text{defined by } v_1 \text{ and } v_2 \end{array} \right)$$

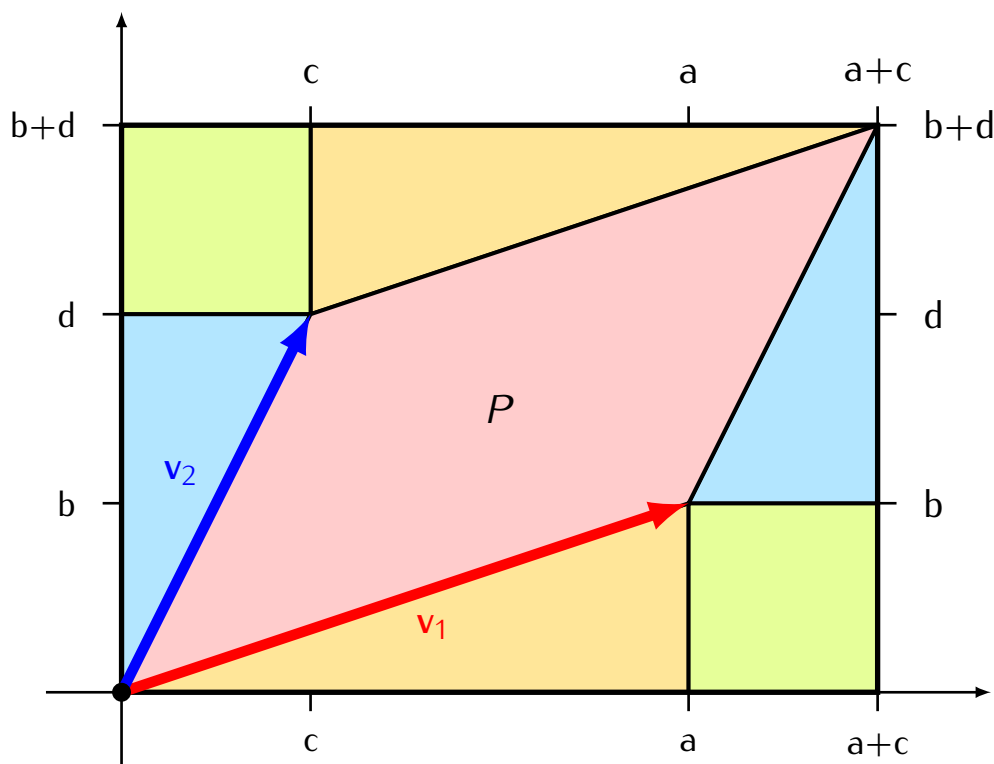
## Theorem

If  $\mathbf{v}_1, \mathbf{v}_2 \in \mathbb{R}^2$  then

$$\text{area}(\mathbf{v}_1, \mathbf{v}_2) = \left| \det \begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 \end{bmatrix} \right|$$

*Idea of the proof.*

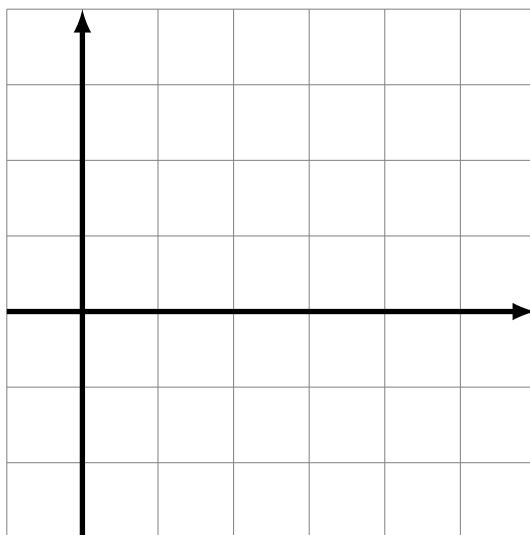
$$\mathbf{v}_1 = \begin{bmatrix} a \\ b \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} c \\ d \end{bmatrix}$$



$$\begin{aligned}
 & \text{area}(P) \\
 & + \frac{1}{2}ab \\
 & + \frac{1}{2}ab \\
 & + \frac{1}{2}cd \\
 & + \frac{1}{2}cd \\
 & + cb \\
 & + cb \\
 & \hline
 & (a+c)(b+d)
 \end{aligned}$$

**Example.**

$$\mathbf{v}_1 = \begin{bmatrix} 2 \\ 3 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 2 \\ -2 \end{bmatrix}$$

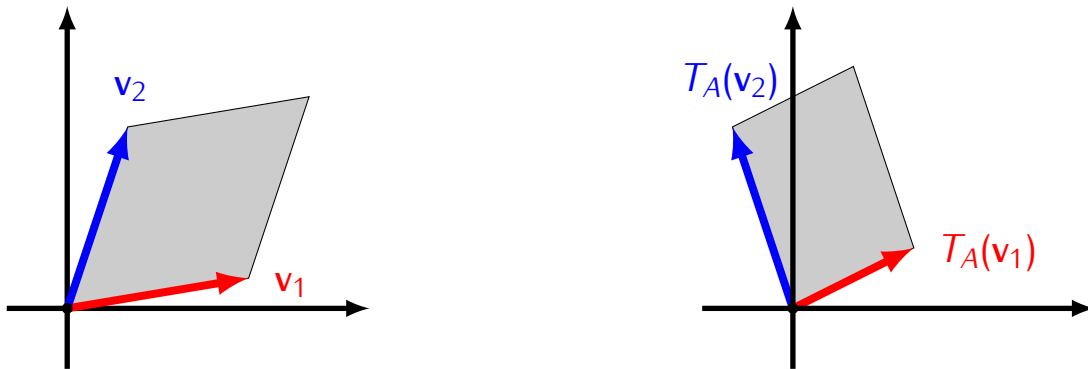


## Determinants and linear transformations

**Recall:** If  $A$  is a  $2 \times 2$  matrix then it defines a linear transformation

$$T_A: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \quad T_A(\mathbf{v}) = A\mathbf{v}$$

**Note.**  $T_A$  maps parallelograms to parallelograms:



### Theorem

If  $A$  is a  $2 \times 2$  matrix and  $\mathbf{v}_1, \mathbf{v}_2 \in \mathbb{R}^2$  then

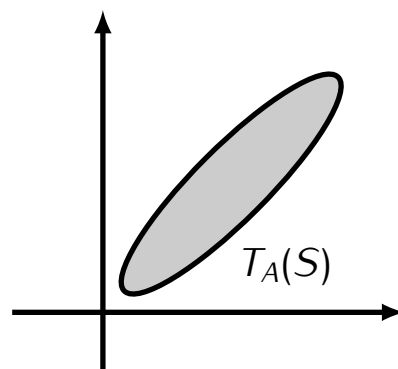
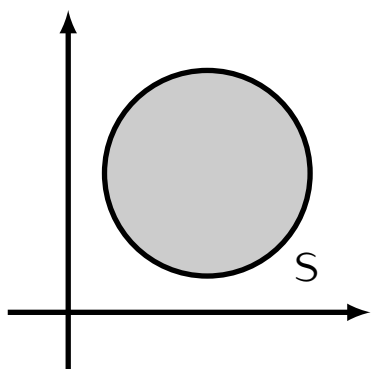
$$\text{area}(T_A(\mathbf{v}_1), T_A(\mathbf{v}_2)) = |\det A| \cdot \text{area}(\mathbf{v}_1, \mathbf{v}_2)$$

## Generalization:

### Theorem

If  $A$  is a  $2 \times 2$  matrix then for any region  $S$  of  $\mathbb{R}^2$  we have:

$$\text{area}(T_A(S)) = |\det A| \cdot \text{area}(S)$$



*Idea of the proof.*

The area of  $S$  can be approximated by the sum of small squares covering  $S$ .

