Operations on matrices so far:

- addition/subtraction $A \pm B$
- scalar multiplication $c \cdot A$
- matrix multiplication $A \cdot B$
- matrix transpose A^T

Next: How to divide matrices?

Note: If a,b-numbers then:

i)
$$\frac{a}{b} = a \cdot b^1$$

2) b' is the number such that bb'=1

Definition

A matrix A is *invertible* if there exists a matrix B such that

$$A \cdot B = B \cdot A = I$$

(where I = the identity matrix). In such case we say that B is the *inverse* of A and we write $B = A^{-1}$.

Example.

$$A = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$$
 is invertible,
$$A^{-1} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

Check:
$$\begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$
$$\begin{bmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Note: Not every matrix is invertible.

Example:

$$A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

Assume that $B = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is a matrix such that AB = IThen:

$$I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a+c & b+d \\ a+c & b+d \end{bmatrix}$$

The first column gives:

$$1 = a+c$$
 $= a+c$ $= a+c$

Thus A is not invertible.

Matrix inverses and matrix equations

Proposition

If A is an invertible matrix then for any vector \mathbf{b} the equation $A\mathbf{x} = \mathbf{b}$ has exactly one solution.

Proof: If
$$Ax = b$$
 then:

$$A^{-1}Ax = A^{-1}b$$

$$Ix = A^{-1}b$$

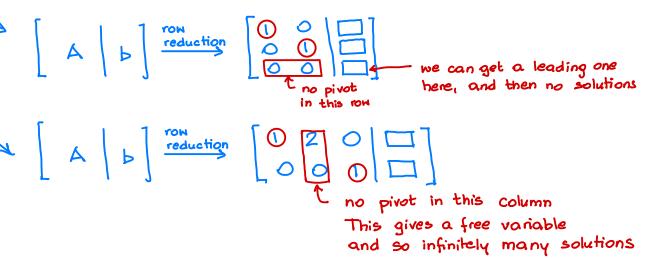
$$x = A^{-1}b$$
the unique solution of $Ax = b$

Example. Solve the following matrix equation:

$$\begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$
Recall: A is invertible, $A^{-1} = \begin{bmatrix} 1/2 & 1/2 \\ -1/2 & 1/2 \end{bmatrix}$
This gives:
$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = A^{-1} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1/2 & 1/2 \\ -1/2 & 1/2 \end{bmatrix} = \begin{bmatrix} 3/2 \\ 1/2 & 1/2 \end{bmatrix}$$

Recall: If *A* be is $m \times n$ matrix then:

- the matrix equation $A\mathbf{x} = \mathbf{b}$ has a solution for every \mathbf{b} if and only if A has a pivot position in every row;
- the matrix equation $A\mathbf{x} = \mathbf{b}$ has exactly one solution for $\mathbf{b} \in \operatorname{Col}(A)$ if and only if A has a pivot position in every column.



Theorem

If a matrix A is invertible then it must be a square matrix.

For a square matrix A the following conditions are equivalent:

- 1) A is an invertible matrix.
- 2) The matrix A has a pivot position in every row and column.
- 3) The reduced row echelon form of A is the identity matrix I_n .

Proposition

If A is an $n \times n$ invertible matrix then

$$A^{-1} = [\mathbf{w}_1 \ \mathbf{w}_2 \ \dots \ \mathbf{w}_n]$$

where \mathbf{w}_i is the solution of $A\mathbf{x} = \mathbf{e}_i$.

Proof: We have:
$$I_n = \begin{bmatrix} e_1 & e_2 & e_n \\ 0 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \end{bmatrix} = [e_1 & e_2 & \cdots & e_n]$$

This gives:

$$[\alpha_1, \alpha_2 \dots \alpha_n] = I_n = AA^{-1} = A[w_1, w_2, \dots w_n] = [Aw_1, Aw_2, \dots Aw_n]$$

We obtain:

$$Aw_1 = Q_1$$
, $Aw_2 = Q_2$, ..., $Aw_n = Q_n$

Example.

$$A = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \qquad \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \xrightarrow{\text{row reduction}} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \mathbf{I}_2, \text{ so } A \text{ is invertible}$$

We have:

$$A^{-1} = [W_1, W_2]$$
 where $W_1 = (solution of Ax = e_1)$
 $W_2 = (solution of Ax = e_2)$

Solve Ax = e1:

$$\begin{bmatrix} 1 & -1 & 1 \\ 1 & 1 & 0 \end{bmatrix} \xrightarrow{\text{row}} \begin{bmatrix} 1 & 0 & 1/2 \\ 0 & 1 & -1/2 \end{bmatrix} \qquad \text{So}: \quad W_1 = \begin{bmatrix} 1/2 \\ -1/2 \end{bmatrix}$$

Solve Ax = e2:

$$\begin{bmatrix} 1 & -1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \xrightarrow{\text{ron reduction}} \begin{bmatrix} 1 & 0 & \frac{1}{2} \\ 0 & 1 & \frac{1}{2} \end{bmatrix} \quad \text{So} : \quad W_2 = \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix}$$

This gives:

$$A^{-1} = \begin{bmatrix} W_1 & W_2 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

Simplification: How to solve several matrix equations with the same coefficient matrix at the same time

$$Ax = b_1, Ax = b_2, \dots, Ax = b_n$$
matrix of equations

$$\begin{bmatrix} A \mid b_1 \mid b_2 \mid \dots \mid b_n \end{bmatrix}$$
augmented matrix

$$\begin{bmatrix} row \\ reduction \end{bmatrix}$$
reduced matrix

$$\begin{bmatrix} read \ off \\ solutions \end{bmatrix}$$
solutions

Example. Solve the vector equations $A\mathbf{x} = \mathbf{e}_1$ and $A\mathbf{x} = \mathbf{e}_2$ where

$$A = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \qquad \mathbf{e}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \qquad \mathbf{e}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Solution:

Summary: How to invert a matrix

Example:
$$A = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$$

1) Augment A by the identity matrix.

2) Reduce the augmented matrix.

$$\begin{bmatrix} 1 & 1 & 1 & 0 \\ 1 & 2 & 0 & 1 \end{bmatrix} \xrightarrow{\text{reduction}} \begin{bmatrix} 1 & 0 & 2 & -1 \\ 0 & 1 & -1 & 1 \end{bmatrix}$$

2) If after the row reduction the matrix on the left is the identity matrix, then A is invertible and

$$A^{-1}$$
 = the matrix on the right

Otherwise *A* is not invertible.

In our example A is invertible and
$$A^{-1} = \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix}$$

Properties of matrix inverses

1) If A is invertible then A^{-1} is invertible and

$$(A^{-1})^{-1} = A$$

2) If A, B are invertible then AB is invertible and

$$(AB)^{-1} = B^{-1}A^{-1}$$

$$(AB)(B^{-1}A^{-1}) = A(BB^{-1})A^{-1} = AIA^{-1} = AA^{-1} = I$$

3) If A is invertible then A^T is invertible and

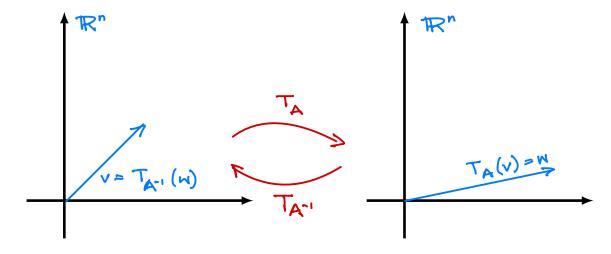
$$(A^T)^{-1} = (A^{-1})^T$$

Matrix inverses and matrix transformations

A - invertible nan matrix

$$T_A: \mathbb{R}^n \longrightarrow \mathbb{R}^n$$

$$T_{\overline{A'}} \colon \mathbb{R}^n \longrightarrow \mathbb{R}^n$$

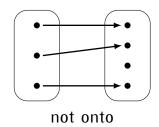


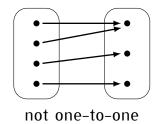
$$T_{A^{-1}}(T_{A}(v)) = T_{A^{-1}}(Av) = A^{-1}(Av) = (A^{-1}A)v = Iv = v$$

$$T_{A}(T_{A^{-1}}(w)) = \dots$$

Note

- If A is an $n \times n$ invertible matrix then the matrix transformation $T_A \colon \mathbb{R}^n \to \mathbb{R}^n$ has the inverse function $T_{A^{-1}} \colon \mathbb{R}^n \to \mathbb{R}^n$.
- ullet As a consequence the function T_A is both onto and one-to-one.



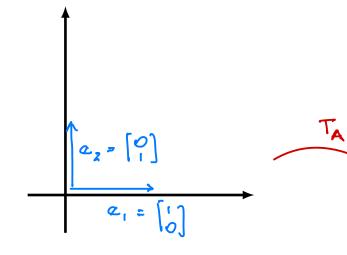


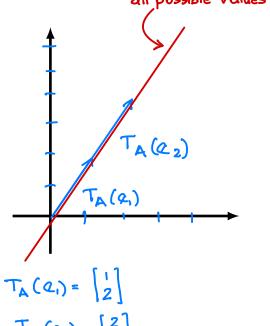
Example.

$$A = \left[\begin{array}{cc} 1 & 2 \\ 2 & 4 \end{array} \right]$$

$$A = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \qquad \begin{array}{c} T_{A} : \mathbb{R}^{2} \to \mathbb{R}^{2} \\ V \longmapsto A \end{array}$$

Col(A) = the space of all possible values of TA





$$T_{A}(Q_{1}) = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$T_{A}(Q_{2}) = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$

- · TA is not onto, so A is not invertible
- · TA is also not one-to-one since e.g.

$$T_{A}\left(\begin{bmatrix}2\\0\end{bmatrix}\right) = \begin{bmatrix}2\\4\end{bmatrix} = T_{A}\left(\begin{bmatrix}0\\1\end{bmatrix}\right)$$