

## MTH 309T LINEAR ALGEBRA EXAM 1

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Name: Ricky Chen		
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1 2	3 4	5 6 7 TOTAL GRADE



1. (20 points) Consider the following vectors in  $\mathbb{R}^3$ :

$$\mathbf{v}_1 = \left[ \begin{array}{c} 1 \\ 0 \\ 2 \end{array} \right], \quad \mathbf{v}_2 = \left[ \begin{array}{c} -1 \\ 1 \\ -3 \end{array} \right], \quad \mathbf{v}_3 = \left[ \begin{array}{c} 1 \\ 2 \\ 0 \end{array} \right], \quad \mathbf{w} = \left[ \begin{array}{c} -2 \\ 2 \\ b \end{array} \right]$$

- a) Find all values of b such that  $w \in \text{Span}(v_1, v_2, v_3)$ .
- b) Is the set  $\{v_1, v_2, v_3\}$  linearly independent? Justify your answer.

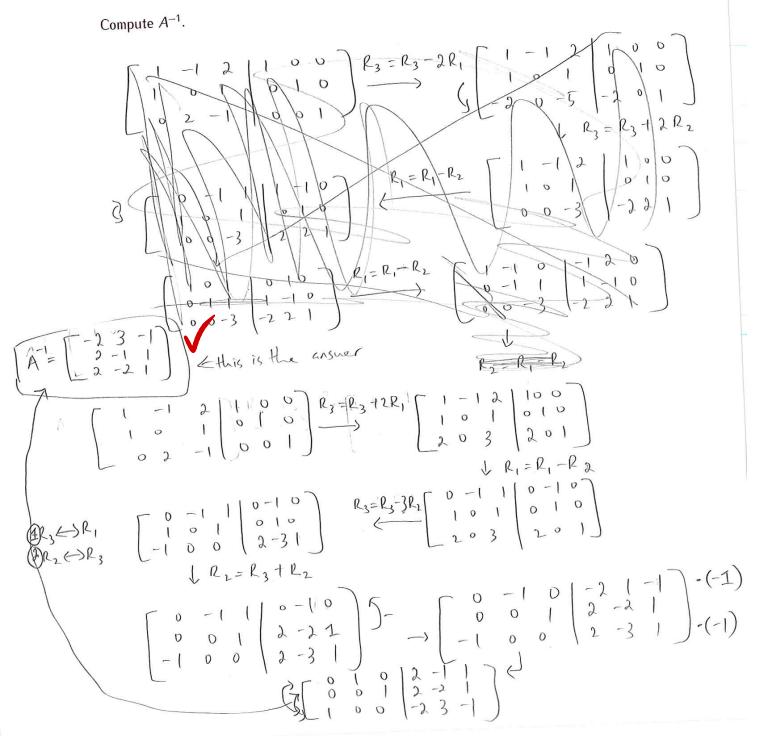
a) 
$$\begin{bmatrix} 1 & -1 & 1 & -2 \\ 0 & 1 & 2 & 2 \\ 2 & -3 & 0 & b \end{bmatrix}$$
  $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & -1 & 1 & -2 \\ 0 & 1 & 2 & 2 \\ 0 & -1 & 0 & b + 4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 0 & 2 & b & +b \\ 0 & -1 & 0 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 0 & 2 & b & +b \\ 0 & -1 & 0 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 0 & 2 & b & +b \\ 0 & -1 & 0 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 0 & 2 & b & +b \\ 0 & -1 & 0 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 0 & 2 & b & +b \\ 0 & -1 & 0 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 0 & 2 & b & +b \\ 0 & -1 & 0 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 0 & 2 & b & +b \\ 0 & -1 & 0 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 0 & 2 & b & +b \\ 0 & -1 & 0 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 0 & 2 & b & +b \\ 0 & -1 & 0 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 0 & 2 & b & +b \\ 0 & -1 & 0 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 0 & 2 & b & +b \\ 0 & -1 & 0 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 0 & 2 & b & +b \\ 0 & -1 & 0 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 0 & 2 & b & +b \\ 0 & 0 & 1 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 1 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 1 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 1 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 1 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 1 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 1 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 1 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 1 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 1 & b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\begin{bmatrix} 1 & 0 & -2 & -b & -6 \\ 0 & 1 & 0 & -b & -4 \\ 0 & 0 & 1 & -b & +4 \end{bmatrix}$   $\rightarrow R_3 = R_3 - 2R_1$   $\rightarrow R_3 = R_3 - 2R_1$   $\rightarrow R_3$ 

Correct conclusion, but it comes from an incorrect roul reduction.



## 2. (10 points) Consider the following matrix:

$$A = \begin{bmatrix} 1 & -1 & 2 \\ 1 & 0 & 1 \\ 0 & 2 & -1 \end{bmatrix}$$





3. (10 points) Let A be the same matrix as in Problem 2, and let

$$A = \begin{bmatrix} 1 & -1 & 2 \\ 1 & 0 & 1 \\ 0 & 2 & -1 \end{bmatrix} \qquad B = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 4 \\ 3 & 2 & 1 \end{bmatrix}$$

Find a matrix C such that  $A^TC = B$  (where  $A^T$  is the transpose of A).

Find a matrix C such that 
$$A^{2}C = B$$
 (where A is the standard of the standa



4. (20 points) Let  $T: \mathbb{R}^2 \to \mathbb{R}^3$  be a linear transformation given by

$$T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} x_1 - 2x_2 \\ x_1 + x_2 \\ x_1 - 3x_2 \end{bmatrix}$$

a) Find the standard matrix of  $\mathcal{T}$ .

b) Find all vectors u satisfying 
$$T(u) = \begin{bmatrix} 1 \\ 10 \\ -2 \end{bmatrix}$$
.

a) 
$$V = \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}$$
  $V = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$   $\begin{bmatrix} -2 \\ 0 \end{bmatrix}$   $\begin{cases} e_1 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \end{cases}$ 

$$T(u) = \begin{bmatrix} a_1 - 2a_2 \\ a_1 + a_2 \\ a_1 - 3a_2 \end{bmatrix}$$
  $T(v) = \begin{bmatrix} b_1 - 2b_2 \\ b_1 + b_2 \\ b_2 \end{bmatrix}$ 

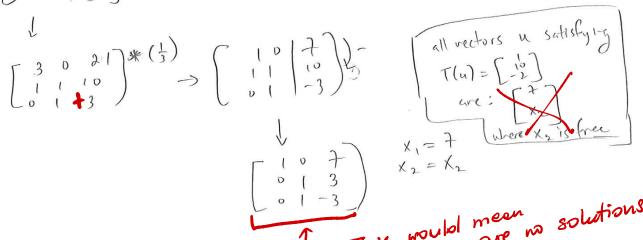
$$T(e_1) = \begin{bmatrix} 1 \\ 1 \end{bmatrix} T(e_2) = \begin{bmatrix} -2 \\ 1 \\ -3 \end{bmatrix}$$

$$T(e_1) = \begin{bmatrix} 1 \\ -3 \end{bmatrix}$$
  $Standard matrix of  $T = \begin{bmatrix} 1 & -2 \\ 1 & -3 \end{bmatrix}$$ 

$$R_3 = R_3 - R_1$$
  $\left( \begin{array}{c|c} 1 & -2 & 1 \\ 1 & 1 & 1 \\ 1 & -3 & -2 \end{array} \right)$ 

$$\begin{bmatrix} 3 & 0 & 21 \\ 1 & 1 & 10 \\ 0 & 1 & 43 \end{bmatrix} * \begin{pmatrix} \frac{1}{3} \\ 0 & 1 & -3 \end{pmatrix} \rightarrow \begin{bmatrix} 1 & 0 & | & 7 \\ 0 & 1 & | & -3 \\ 0 & 1 & | & -3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 \\ 0 & 3 \\ 0 & 1 & -3 \end{bmatrix}$$





5. (20 points) For each matrix A given below determine if the matrix transformation  $T_A \colon \mathbb{R}^3 \to \mathbb{R}^3$  given by  $T_A(\mathbf{v}) = A\mathbf{v}$  is one-to one or not. If  $T_A$  is not one-to-one, find two vectors  $v_1$  and  $v_2$  such that  $T_A(v_1) = T_A(v_2)$ .

a) 
$$A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 3 & 4 & 4 \end{bmatrix}$$
 b)  $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 3 & 4 & 2 \end{bmatrix}$ 

$$\mathbf{b}) \ A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 3 & 4 & 2 \end{bmatrix}$$



- 6. (10 points) For each of the statements given below decide if it is true or false. If it is true explain why. If it is false give a counterexample.
- a) If u, v, w are vectors in  $\mathbb{R}^3$  such that  $w + u \in Span(u, v)$  then  $w \in Span(u, v)$ .

True, because since with wis in the spon (u,v) then it must be true that we spon(u,v) be cause? The sum of the two vectors are in the spon (u,v).

b) If u,v,w are vectors in  $\mathbb{R}^3$  such that the set  $\{u,v,w\}$  is linearly independent then the set  $\{u,v\}$  must be linearly independent.

True V

$$U = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \qquad V = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \qquad W = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

the set {4,v3 ([0], [0]) is also linearly independent

because it has only one solution and phot col in every column. If u,v,w are independent then it has pirot col. in every column that mems with I we vectors it still holds true.



- 7. (10 points) For each of the statements given below decide if it is true or false. If it is true explain why. If it is false give a counterexample.
- a) If A is a  $2 \times 2$  matrix and u, v are vectors in  $\mathbb{R}^2$  such that Au, Av are linearly dependent then u, v also must be linearly dependent.

False,

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \qquad u = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \qquad v = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

u and v could still be independent and be multiplied with A to make it Inearly dependent. < example?

This matrix preserves independence

b) If  $T: \mathbb{R}^2 \to \mathbb{R}^2$  is a linear transformation and  $u, v, w \in \mathbb{R}^2$  are vectors such that u is in  $\mathrm{Span}(v, w)$  then T(u) must be in  $\mathrm{Span}(T(v), T(w))$ .

Yes, true because if u is in the Span of (v, w) then
the transformation could just be the scalar of u vector
and it would still let T(u) be in the span of T(v), T(w)