



# MTH 309T LINEAR ALGEBRA

## EXAM 1

October 3, 2019

Name:

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UB Person Number:

5	0	1	9	9	6	6	8
0	0	0	0	0	0	0	0
1	1	1	1	1	1	1	1
2	2	2	2	2	2	2	2
3	3	3	3	3	3	3	3
4	4	4	4	4	4	4	4
5	5	5	5	5	5	5	5
6	6	6	6	6	6	6	6
7	7	7	7	7	7	7	7
8	8	8	8	8	8	8	8
9	9	9	9	9	9	9	9

Instructions:

- Textbooks, calculators and any other electronic devices are not permitted. You may use one sheet of notes.
- For full credit solve each problem fully, showing all relevant work.

1 2 3 4 5 6 7 TOTAL GRADE

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20

5

7

8

5

10

0

55

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2

3

4

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6

7

TOTAL

GRADE



1. (20 points) Consider the following vectors in  $\mathbb{R}^3$ :

$$v_1 = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}, \quad v_2 = \begin{bmatrix} -1 \\ 1 \\ -3 \end{bmatrix}, \quad v_3 = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \quad w = \begin{bmatrix} -2 \\ 2 \\ b \end{bmatrix}$$

a) Find all values of  $b$  such that  $w \in \text{Span}(v_1, v_2, v_3)$ .

b) Is the set  $\{v_1, v_2, v_3\}$  linearly independent? Justify your answer.

$$\begin{array}{c} \left[ \begin{array}{ccc|c} 1 & -1 & 1 & -2 \\ 0 & 1 & 2 & 2 \\ 2 & -3 & 0 & b \end{array} \right] \quad R_3 = -2(R_1) + R_3 \\ \hline \left[ \begin{array}{ccc|c} 1 & -1 & 1 & -2 \\ 0 & 1 & 2 & 2 \\ 0 & -1 & -2 & 4+b \end{array} \right] \quad R_3 + R_2 + R_3 \\ \hline \left[ \begin{array}{ccc|c} 1 & -1 & 1 & -2 \\ 0 & 1 & 2 & 2 \\ 0 & 0 & 0 & 6+b \end{array} \right] \quad R_1 = R_2 + R_1 \\ \hline \begin{array}{ccc|c} v_1 & v_2 & v_3 & \\ \left[ \begin{array}{ccc|c} 1 & 0 & 3 & 0 \\ 0 & 1 & 2 & 2 \\ 0 & 0 & 0 & 6+b \end{array} \right] & R_2 = R_1 - R_2 & & \end{array} \\ \hline \left[ \begin{array}{ccc|c} 1 & 0 & 3 & 0 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & 0 & 6+b \end{array} \right] \end{array}$$

b) The solution is linear independent. The last row is 0 and because of that there are multiple solutions. Also, it can't be dependent because every column must be a pivot.

b) before ~~it~~ in order for it be



$$\begin{aligned} (-1)(-2) &= 2 & 2(-1)+1 &= -2 \\ -2(1) &= -2 & & \end{aligned}$$

2. (10 points) Consider the following matrix:

$$A = \begin{bmatrix} 1 & -1 & 2 \\ 1 & 0 & 1 \\ 0 & 2 & -1 \end{bmatrix}$$

Compute  $A^{-1}$ .

$$(-1)(-2) = 2 - 1 = 1$$

$$\begin{array}{l} \begin{array}{ccc|ccc} 1 & -1 & 2 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 2 & -1 & 0 & 0 & 1 \end{array} \rightarrow \begin{array}{ccc|ccc} 1 & -1 & 2 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 2 & -1 & 0 & 0 & 1 \end{array} \quad R_3 = -2(R_2) + R_3 \\ \\ \begin{array}{ccc|ccc} 1 & -1 & 2 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 0 & 1 & 2 & 0 & 1 \end{array} \quad R_2 = -R_1 + R_2 \quad R_1 = 2R_2 + R_1 \\ \\ \begin{array}{ccc|ccc} 1 & 1 & 0 & -1 & 2 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 0 & 1 & 2 & 0 & 1 \end{array} \rightarrow \begin{array}{ccc|ccc} 1 & 1 & 0 & -1 & 2 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 0 & 1 & 2 & 0 & 1 \end{array} \quad R_2 = R_3 + R_2 \\ \\ \begin{array}{ccc|ccc} 1 & 1 & 0 & -1 & 2 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 0 & 1 & 2 & 0 & 1 \end{array} \rightarrow \begin{array}{ccc|ccc} 1 & 0 & 0 & 0 & 1 & -1 \\ 0 & 1 & 0 & -1 & 1 & 1 \\ 0 & 0 & 1 & 2 & 0 & 1 \end{array} \quad R_1 = 2 - R_2 + R_1 \\ \\ \boxed{A^{-1} = \begin{bmatrix} 0 & 1 & -1 \\ -1 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}} \end{array}$$



3. (10 points) Let  $A$  be the same matrix as in Problem 2, and let

$$B = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 4 \\ 3 & 2 & 1 \end{bmatrix}$$

Find a matrix  $C$  such that  $A^T C = B$  (where  $A^T$  is the transpose of  $A$ ).

$$A^T = \begin{bmatrix} 1 & 1 & 0 \\ -1 & 0 & 2 \\ 2 & 1 & -1 \end{bmatrix} \cdot C = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 4 \\ 3 & 2 & 1 \end{bmatrix}$$

$$(AB)^T = B^T A^T$$

$$2 \times 4 = 8$$

$$A^T \cdot C = B$$

$$\frac{B}{A^T} = C = B \cdot (A^T)^{-1}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 4 \\ 3 & 2 & 1 \end{bmatrix} \begin{bmatrix} 0 & -1 & 0 \\ 1 & 1 & 0 \\ -1 & 1 & 1 \end{bmatrix}$$

$$\begin{aligned} -1 + 2 + 3 &= 4 \\ -4 + 5 + 4 &= 5 \\ -3 + 2 + 1 &= 0 \end{aligned}$$

$$\begin{bmatrix} -1 & 4 & 3 \\ 1 & 5 & 4 \\ 1 & 0 & 1 \end{bmatrix} = C$$

$$= 0 \begin{bmatrix} 1 \\ 4 \\ 3 \end{bmatrix} + 1 \begin{bmatrix} 2 \\ 5 \\ 2 \end{bmatrix} - 1 \begin{bmatrix} 3 \\ 4 \\ 1 \end{bmatrix}$$

$$= 0 \begin{bmatrix} 1 \\ 4 \\ 3 \end{bmatrix} + 1 \begin{bmatrix} 2 \\ 5 \\ 2 \end{bmatrix} - 1 \begin{bmatrix} 3 \\ 4 \\ 1 \end{bmatrix}$$

$$= 0 \begin{bmatrix} 1 \\ 4 \\ 3 \end{bmatrix} + 0 \begin{bmatrix} 2 \\ 5 \\ 2 \end{bmatrix} + 1 \begin{bmatrix} 3 \\ 4 \\ 1 \end{bmatrix}$$



4. (20 points) Let  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$  be a linear transformation given by

$$T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} x_1 - 2x_2 \\ x_1 + x_2 \\ x_1 - 3x_2 \end{bmatrix}$$

a) Find the standard matrix of  $T$ .

b) Find all vectors  $u$  satisfying  $T(u) = \begin{bmatrix} 1 \\ 10 \\ -2 \end{bmatrix}$ .

$$\begin{bmatrix} 1 & -2 \\ 1 & 1 \\ 1 & -3 \end{bmatrix} \cdot (u) = \begin{bmatrix} 1 \\ 10 \\ -2 \end{bmatrix} \quad T = \begin{bmatrix} 1 & -2 \\ 1 & 1 \\ 1 & 3 \end{bmatrix}$$

$$\begin{bmatrix} x_1 & x_2 \\ 1 & -2 & | & 1 \\ 1 & 1 & | & 10 \\ 1 & -3 & | & -2 \end{bmatrix} \quad \begin{array}{l} R_2 = R_2 - R_1 \\ R_3 = -R_1 + R_3 \end{array}$$

$$\begin{array}{ccc|c} 1 & -2 & 1 & \\ (0 & 3 & 9) \cdot \frac{1}{3} & \\ 0 & -1 & -3 & \end{array} \quad \begin{array}{ccc|c} 1 & -2 & 1 & \\ 0 & 1 & 3 & \\ 0 & -1 & -3 & = -R_2 + R_3 \end{array} \quad = \begin{array}{ccc|c} 1 & -2 & 1 & \\ 0 & 1 & 3 & \\ 0 & 0 & 0 & \end{array}$$

$$R_1 = 2(R_2) + R_1 = \begin{array}{ccc|c} 1 & 0 & 1 & \\ 0 & 1 & 3 & \\ 0 & 0 & 0 & \end{array}$$

$$\begin{array}{l} x_1 = 1 \\ x_2 = 3 \end{array}$$





5. (20 points) For each matrix  $A$  given below determine if the matrix transformation  $T_A: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  given by  $T_A(v) = Av$  is one-to-one or not. If  $T_A$  is not one-to-one, find two vectors  $v_1$  and  $v_2$  such that  $T_A(v_1) = T_A(v_2)$ .

a)  $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 3 & 4 & 4 \end{bmatrix}$

b)  $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 3 & 4 & 2 \end{bmatrix}$

$A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 3 & 4 & 4 \end{bmatrix}$   $R_2 = R_2 \cdot \frac{1}{2}$   
 $R_3 = -3R_1 + R_3$

$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & -1 & -4 \end{bmatrix}$

$R_3 = R_3 + R_2$

$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & -2 \end{bmatrix}$   $R_3 = R_2 - R_3$

a)  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$

Onto pivot column

$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 2 \\ 3 & 4 & 2 \end{bmatrix}$

$R_3 = -3R_1 + R_3$

$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & -1 & -4 \end{bmatrix}$

b)  $\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & -2 \end{bmatrix}$

$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$

One to one



6. (10 points) For each of the statements given below decide if it is true or false. If it is true explain why. If it is false give a counterexample.

a) If  $u, v, w$  are vectors in  $\mathbb{R}^3$  such that  $w + u \in \text{Span}(u, v)$  then  $w \in \text{Span}(u, v)$ .

It is ~~true~~ <sup>false</sup>. No matter how much you ~~can~~ change it the rule only applies for multiplication.

b) If  $u, v, w$  are vectors in  $\mathbb{R}^3$  such that the set  $\{u, v, w\}$  is linearly independent then the set  $\{u, v\}$  must be linearly independent.

False - linearly independent means: that there ~~is only one~~ <sup>must be</sup> infinite solutions. We do not know which vector has a free variable. so we don't know 100 percent of the time.

Example

Free variable

$u, v, w$

$u$  and  $v$  can be dependent



7. (10 points) For each of the statements given below decide if it is true or false. If it is true explain why. If it is false give a counterexample.

a) If  $A$  is a  $2 \times 2$  matrix and  $u, v$  are vectors in  $\mathbb{R}^2$  such that  $Au, Av$  are linearly dependent then  $u, v$  also must be linearly dependent.



True, if they have a unique solution, it doesn't matter

whether they are ~~separated or not~~ represented in a matrix or not

b) If  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is a linear transformation and  $u, v, w \in \mathbb{R}^2$  are vectors such that  $u$  is in  $\text{Span}(v, w)$  then  $T(u)$  must be in  $\text{Span}(T(v), T(w))$ .

True,  $\text{Span}(v, \dots, v_p) =$  set of all linear combination

$$c_1 v_1 + c_2 v_2.$$

thus it holds ~~every~~

than  $T(u)$  must be in  $\text{Span}(T(v), T(w))$