



# MTH 309T LINEAR ALGEBRA

## EXAM 1

October 3, 2019

Name:

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UB Person Number:

5	0	2	6	4	8	1	0
0	0	0	0	0	0	0	0
1	1	1	1	1	1	1	1
2	2	2	2	2	2	2	2
3	3	3	3	3	3	3	3
4	4	4	4	4	4	4	4
5	5	5	5	5	5	5	5
6	6	6	6	6	6	6	6
7	7	7	7	7	7	7	7
8	8	8	8	8	8	8	8
9	9	9	9	9	9	9	9

Instructions:

- Textbooks, calculators and any other electronic devices are not permitted. You may use one sheet of notes.
- For full credit solve each problem fully, showing all relevant work.

1	2	3	4	5	6	7	TOTAL	GRADE

20

8

8

20

14

7

10

2

10

98

A

1

2

3

4

5

6

7

PIAZZA

HILL

TOTAL

GRADE



1. (20 points) Consider the following vectors in  $\mathbb{R}^3$ :

$$v_1 = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}, \quad v_2 = \begin{bmatrix} -1 \\ 1 \\ -3 \end{bmatrix}, \quad v_3 = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \quad w = \begin{bmatrix} -2 \\ 2 \\ \textcircled{b} \end{bmatrix}$$

a) Find all values of  $b$  such that  $w \in \text{Span}(v_1, v_2, v_3)$ .

b) Is the set  $\{v_1, v_2, v_3\}$  linearly independent? Justify your answer.

A)  $c_1 v_1 + c_2 v_2 + c_3 v_3 = w$   $\begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & 2 \\ 2 & -3 & 0 \end{bmatrix} = A$

$$c_1 \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} + c_2 \begin{bmatrix} -1 \\ 1 \\ -3 \end{bmatrix} + c_3 \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} = \begin{bmatrix} -2 \\ 2 \\ b \end{bmatrix}$$

Aug.

$$\left[ \begin{array}{ccc|c} 1 & -1 & 1 & -2 \\ 0 & 1 & 2 & 2 \\ 2 & -3 & 0 & b \end{array} \right] \xrightarrow{R_3 \rightarrow 2R_1 - R_3} \left[ \begin{array}{ccc|c} 1 & -1 & 1 & -2 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & -4-b \end{array} \right] \xrightarrow{R_1 \rightarrow R_2 + R_1}$$

$$\left[ \begin{array}{ccc|c} 1 & 0 & 3 & 0 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & -4-b \end{array} \right] \xrightarrow{R_3 \rightarrow R_3 - R_2} \left[ \begin{array}{ccc|c} 1 & 0 & 3 & 0 \\ 0 & 1 & 2 & 2 \\ 0 & 0 & 0 & -6-b \end{array} \right]$$

For  $w$  to be in the  $\text{Span}(v_1, v_2, v_3)$   $b$  must equal  $-6$ . ✓

B) The solution to  $Ax = 0$  is  $A$  is  $\begin{bmatrix} x_1 & x_2 & x_3 \\ 1 & 0 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$

$$x_1 = -3x_3$$

$$x_2 = -2x_3$$

$$x_3 = x_3$$

The presence of a free variable suggests infinitely many solutions to  $Ax = 0$ . Since the homogeneous equation does not have one trivial solution it is Linearly Dependent ✓



2. (10 points) Consider the following matrix:

$$A = \begin{bmatrix} 1 & -1 & 2 \\ 1 & 0 & 1 \\ 0 & 2 & -1 \end{bmatrix}$$

Compute  $A^{-1}$ .

$$A \cdot A^{-1} = I_3$$

$$\left[ \begin{array}{ccc|ccc} 1 & -1 & 2 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 2 & -1 & 0 & 0 & 1 \end{array} \right] \xrightarrow{R_2 \rightarrow R_2 - R_1} \left[ \begin{array}{ccc|ccc} 1 & -1 & 2 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 2 & -1 & 0 & 0 & 1 \end{array} \right] \xrightarrow{R_1 \rightarrow R_2 + R_1} \left[ \begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 2 & -1 & 0 & 0 & 1 \end{array} \right]$$

$$\left[ \begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 2 & -1 & 0 & 0 & 1 \end{array} \right] \xrightarrow{R_3 \rightarrow R_3 - 2R_2} \left[ \begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 0 & 1 & 2 & -2 & 1 \end{array} \right] \xrightarrow{R_3 \rightarrow \frac{1}{3}R_3} \left[ \begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 0 & 1 & \frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \end{array} \right]$$

$$\left[ \begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 0 & 1 & \frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \end{array} \right] \xrightarrow{R_2 \rightarrow R_2 + R_3} \left[ \begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & -\frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ 0 & 0 & 1 & \frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \end{array} \right] \xrightarrow{R_1 \rightarrow R_1 - R_3} \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & -\frac{2}{3} & \frac{5}{3} & -\frac{1}{3} \\ 0 & 1 & 0 & -\frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ 0 & 0 & 1 & \frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \end{array} \right]$$

$$\left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & -\frac{2}{3} & \frac{5}{3} & -\frac{1}{3} \\ 0 & 1 & 0 & -\frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ 0 & 0 & 1 & \frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \end{array} \right]$$

$$A^{-1} = \begin{bmatrix} -\frac{2}{3} & \frac{5}{3} & -\frac{1}{3} \\ -\frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ \frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \end{bmatrix}$$



Simpler:  $(A^T)^{-1} = (A^{-1})^T$

Then use problem 2.

3. (10 points) Let  $A$  be the same matrix as in Problem 2, and let

$$B = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 4 \\ 3 & 2 & 1 \end{bmatrix}$$

Find a matrix  $C$  such that  $A^T C = B$  (where  $A^T$  is the transpose of  $A$ ).

$$A = \begin{bmatrix} 1 & -1 & 2 \\ 1 & 0 & 1 \\ 0 & 2 & -1 \end{bmatrix} \quad A^T = \begin{bmatrix} 1 & 1 & 0 \\ -1 & 0 & 2 \\ 2 & 1 & -1 \end{bmatrix}$$

Inverse of  $A^T$   $\left[ \begin{array}{ccc|ccc} 1 & 1 & 0 & 1 & 0 & 0 \\ -1 & 0 & 2 & 0 & 1 & 0 \\ 2 & 1 & -1 & 0 & 0 & 1 \end{array} \right] \xrightarrow{R_2 \rightarrow R_1 + R_2} \left[ \begin{array}{ccc|ccc} 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 2 & 1 & 1 & 0 \\ 2 & 1 & -1 & 0 & 0 & 1 \end{array} \right] \xrightarrow{R_3 \rightarrow R_3 - 2R_2}$

$$\left[ \begin{array}{ccc|ccc} 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 2 & 1 & 1 & 0 \\ 0 & -1 & -1 & -1 & 0 & 1 \end{array} \right] \xrightarrow{R_2 \rightarrow R_3 + R_2} \left[ \begin{array}{ccc|ccc} 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 0 & -1 & -1 & -1 & 0 & 1 \end{array} \right] \xrightarrow{R_1 \rightarrow R_3 + R_1}$$

$$\left[ \begin{array}{ccc|ccc} 1 & 0 & -1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 0 & -1 & -1 & -1 & 0 & 1 \end{array} \right] \xrightarrow{R_1 \rightarrow R_1 + R_2} \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 0 & -1 & -1 & -1 & 0 & 1 \end{array} \right] \xrightarrow{R_3 \rightarrow R_2 + R_3}$$

$$\left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 0 & -1 & 0 & -1 & 1 & 2 \end{array} \right] \xrightarrow{R_2 \leftrightarrow R_3} \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 0 & 1 & 2 \\ 0 & -1 & 0 & -1 & 1 & 2 \\ 0 & 0 & 1 & 0 & 1 & 1 \end{array} \right] \xrightarrow{R_2 \rightarrow -R_2}$$

$$\left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 0 & 1 & 2 \\ 0 & 1 & 0 & 1 & -1 & -2 \\ 0 & 0 & 1 & 0 & 1 & 1 \end{array} \right]$$

Inverse  $A^T = \begin{bmatrix} \times & 1 & 2 \\ \times & -1 & -2 \\ \times & 1 & 1 \end{bmatrix}$

$(A^T)^{-1} \cdot B = C$  ✓

$$\begin{bmatrix} 0 & 1 & 2 \\ 1 & -1 & -2 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 4 \\ 3 & 2 & 1 \end{bmatrix} = \begin{bmatrix} 0+4+6 & 0+5+4 & 0+4+2 \\ 1-4-6 & 2-5+1 & 3-4-2 \\ 0+4+3 & 0+5+2 & 0+4+1 \end{bmatrix}$$

$$= \begin{bmatrix} 10 & 9 & 6 \\ -9 & 7 & -9 \\ 7 & 7 & 5 \end{bmatrix}$$



4. (20 points) Let  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$  be a linear transformation given by

$$T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} x_1 - 2x_2 \\ x_1 + x_2 \\ x_1 - 3x_2 \end{bmatrix}$$

a) Find the standard matrix of  $T$ .

b) Find all vectors  $u$  satisfying  $T(u) = \begin{bmatrix} 1 \\ 10 \\ -2 \end{bmatrix}$ .

$$A) T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} x_1 - 2x_2 \\ x_1 + x_2 \\ x_1 - 3x_2 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + x_2 \begin{bmatrix} -2 \\ 1 \\ -3 \end{bmatrix}$$

$$\text{Standard Matrix} = \begin{bmatrix} 1 & -2 \\ 1 & 1 \\ 1 & -3 \end{bmatrix} \quad \checkmark$$

$$B) x_1 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + x_2 \begin{bmatrix} -2 \\ 1 \\ -3 \end{bmatrix} = \begin{bmatrix} 1 \\ 10 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -2 & 1 \\ 1 & 1 & 10 \\ 1 & -3 & -2 \end{bmatrix} \xrightarrow{R_2 \rightarrow R_1 - R_2} \begin{bmatrix} 1 & -2 & 1 \\ 0 & -3 & -9 \\ 1 & -3 & -2 \end{bmatrix} \xrightarrow{R_3 \rightarrow R_1 - R_3}$$

$$\begin{bmatrix} 1 & -2 & 1 \\ 0 & -3 & -9 \\ 0 & 1 & 3 \end{bmatrix} \xrightarrow{R_2 \rightarrow 3R_3 + R_2} \begin{bmatrix} 1 & -2 & 1 \\ 0 & 0 & 0 \\ 0 & 1 & 3 \end{bmatrix} \xrightarrow{R_1 \rightarrow 2R_3 + R_1}$$

$$\begin{bmatrix} 1 & 0 & 7 \\ 0 & 0 & 0 \\ 0 & 1 & 3 \end{bmatrix} \xrightarrow{R_3 \leftrightarrow R_2} \begin{bmatrix} x_1 & x_2 & \\ 1 & 0 & 7 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{bmatrix}$$

$$x_1 = 7 \\ x_2 = 3$$

$$u = \begin{bmatrix} 7 \\ 3 \end{bmatrix} \quad \checkmark$$





5. (20 points) For each matrix  $A$  given below determine if the matrix transformation  $T_A: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  given by  $T_A(v) = Av$  is one-to-one or not. If  $T_A$  is not one-to-one, find two vectors  $v_1$  and  $v_2$  such that  $T_A(v_1) = T_A(v_2)$ .

a)  $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 3 & 4 & 4 \end{bmatrix}$

b)  $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 3 & 4 & 2 \end{bmatrix}$

$$A \cdot v = b$$

$$T_A(v_1) = T_A(v_2)$$

$$T_A(v_1) - T_A(v_2) = 0$$

$$T_A(v_1 - v_2) = 0$$

one-to-one pivot position in every column

A)  $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 3 & 4 & 4 \end{bmatrix} \xrightarrow{R_3 \rightarrow R_3 - 3R_1} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 0 & 1 & 4 \end{bmatrix} \xrightarrow{R_2 \leftrightarrow \frac{1}{2}R_2} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 1 & 4 \end{bmatrix} \xrightarrow{R_1 \rightarrow R_1 - R_2}$

$$\begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 2 \\ 0 & 1 & 4 \end{bmatrix} \xrightarrow{R_3 \rightarrow R_3 - R_2} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 2 \\ 0 & 0 & -2 \end{bmatrix} \xrightarrow{R_3 \rightarrow -\frac{1}{2}R_3} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_2 \rightarrow 2R_2 + R_3}$$

$$\begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_1 \rightarrow 2R_3 + R_1} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

This is one-to-one ✓

$$\text{So } T_A(v_1) - T_A(v_2) = 0$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{matrix} x_1 = 0 \\ x_2 = 0 \\ x_3 = 0 \end{matrix}$$

$$\text{Nul } A = \text{Span}\{0\}$$

$$v_1 \text{ can be } \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad v_2 \text{ can be } \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix}$$

If  $T_A$  is one-to-one then there are no such vectors. These two vectors do not work in part b) either.

B)  $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 3 & 4 & 2 \end{bmatrix} \xrightarrow{R_3 \rightarrow R_3 - 3R_1} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 0 & 1 & 2 \end{bmatrix} \xrightarrow{R_1 \rightarrow R_1 - R_3} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 2 & 4 \\ 0 & 1 & 2 \end{bmatrix} \xrightarrow{R_2 \rightarrow \frac{1}{2}R_2}$

$$\begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 2 \\ 0 & 1 & 2 \end{bmatrix} \xrightarrow{R_3 \rightarrow R_3 - R_2} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

We can see not every column will be a pivot so  $T_A(v) = Av$

is not one-to-one. ✓

↑  
 $v_1, v_2$  ?



6. (10 points) For each of the statements given below decide if it is true or false. If it is true explain why. If it is false give a counterexample.

a) If  $u, v, w$  are vectors in  $\mathbb{R}^3$  such that  $w + u \in \text{Span}(u, v)$  then  $w \in \text{Span}(u, v)$ .

$$u = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad v = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad w = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

True ✓

$$w + u \in \text{Span}(u, v)$$

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \in \text{Span}\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) \text{ True}$$

$$w \in \text{Span}(u, v)$$

$$\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \in \text{Span}\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) \text{ True}$$

One example is not a proof.

?

Since  $w + u$  is in the span of  $u, v$  their combination of  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$  can be made from  $c_1 u + c_2 v = w + u$ . If you let  $c_1 = 1$  and  $c_2 = 1$

$$u + v = w + u$$

$$v = w$$

Since  $v = w$   $w$  is in span of  $v$  which makes  $w \in \text{Span}(u, v)$  True

b) If  $u, v, w$  are vectors in  $\mathbb{R}^3$  such that the set  $\{u, v, w\}$  is linearly independent then the set  $\{u, v\}$  must be linearly independent.

$$u = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad v = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad w = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

Lin independent means one trivial solution  
To  $AX = b$

TRUE ✓

Since  $u, v, w$  are linearly independent that means all columns on  $A$  are pivot columns. So if you were to remove a vector  $w$  for example and solve for independence with  $u$  and  $v$  you are left with a  $3 \times 2$  matrix with pivot positions in every column so they are independent. ✓



7. (10 points) For each of the statements given below decide if it is true or false. If it is true explain why. If it is false give a counterexample.

a) If  $A$  is a  $2 \times 2$  matrix and  $u, v$  are vectors in  $\mathbb{R}^2$  such that  $Au, Av$  are linearly dependent then  $u, v$  also must be linearly dependent.

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

$$u = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad v = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

FALSE

$$Au = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$Av = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\text{If } A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \text{ and } u = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \text{ and } v = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\text{then } Av = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \text{ and } Au = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Since these two vectors are NOT scalar multiples of each other this statement is false.



b) If  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is a linear transformation and  $u, v, w \in \mathbb{R}^2$  are vectors such that  $u$  is in  $\text{Span}(v, w)$  then  $T(u)$  must be in  $\text{Span}(T(v), T(w))$ .

TRUE If  $u$  is in  $\text{Span}$  of  $v, w$  this means

$$c_1 v + c_2 w = u$$

$$\text{A linear transformation } T_A(c_1 v + c_2 w) = T_A(u)$$

is applied to both sides

$$c_1 T_A(v) + c_2 T_A(w) = T_A(u)$$

Any linear combination of  $T(v)$  and  $T(w)$

will get you  $T_A(u)$

