



MTH 309T LINEAR ALGEBRA

EXAM 1

October 3, 2019

Name:

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UB Person Number:

5	0	2	2	8	8	3	7
0	0	0	0	0	0	0	0
1	1	1	1	1	1	1	1
2	2	2	2	2	2	2	2
3	3	3	3	3	3	3	3
4	4	4	4	4	4	4	4
5	5	5	5	5	5	5	5
6	6	6	6	6	6	6	6
7	7	7	7	7	7	7	7
8	8	8	8	8	8	8	8
9	9	9	9	9	9	9	9

Instructions:

- Textbooks, calculators and any other electronic devices are not permitted. You may use one sheet of notes.
- For full credit solve each problem fully, showing all relevant work.

1	2	3	4	5	6	7	TOTAL	GRADE

18

10

10

20

20

7

2

2

10

98

A

1

2

3

4

5

6

7

PIAZZA

HILL

TOTAL

GRADE



1. (20 points) Consider the following vectors in \mathbb{R}^3 :

$$v_1 = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}, \quad v_2 = \begin{bmatrix} -1 \\ 1 \\ -3 \end{bmatrix}, \quad v_3 = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \quad w = \begin{bmatrix} -2 \\ 2 \\ b \end{bmatrix}$$

a) Find all values of b such that $w \in \text{Span}(v_1, v_2, v_3)$.

a) b) Is the set $\{v_1, v_2, v_3\}$ linearly independent? Justify your answer.

$$\left[\begin{array}{ccc|c} 1 & -1 & 1 & -2 \\ 0 & 1 & 2 & 2 \\ 2 & -3 & 0 & b \end{array} \right] \xrightarrow{R_3 - 2R_2} \left[\begin{array}{ccc|c} 1 & -1 & 1 & -2 \\ 0 & 1 & 2 & 2 \\ 0 & -1 & -2 & 4+b \end{array} \right] \xrightarrow{R_3 + R_2} \left[\begin{array}{ccc|c} 1 & 0 & 3 & 0 \\ 0 & 1 & 2 & 2 \\ 0 & 0 & 0 & 6+b \end{array} \right] \Rightarrow b = \cancel{6} \\ -6$$

b) The set $\{v_1, v_2, v_3\}$ is linearly dependent because

x_3 is a free variable meaning there are infinitely many solutions. ✓



2. (10 points) Consider the following matrix:

$$A = \begin{bmatrix} 1 & -1 & 2 \\ 1 & 0 & 1 \\ 0 & 2 & -1 \end{bmatrix}$$

Compute A^{-1} .

$$\cdot (-1) \left(\begin{array}{ccc|ccc} 1 & -1 & 2 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 2 & -1 & 0 & 0 & 1 \end{array} \right)$$

↓

$$\cdot 1 \left(\begin{array}{ccc|ccc} 1 & -1 & 2 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 2 & -1 & 0 & 0 & 1 \end{array} \right)$$

↓

$$\cdot (-2) \left(\begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 2 & -1 & 0 & 0 & 1 \end{array} \right)$$

↓

$$\cdot 1 \left(\begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 0 & 1 & 2 & -2 & 1 \end{array} \right)$$

↓

$$\cdot (-1) \left(\begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & -1 & 1 \\ 0 & 0 & 1 & 2 & -2 & 1 \end{array} \right)$$

↓

$$\begin{bmatrix} 1 & 0 & 0 & -2 & 3 & -1 \\ 0 & 1 & 0 & 1 & -1 & 1 \\ 0 & 0 & 1 & 2 & -2 & 1 \end{bmatrix}$$

$$\Rightarrow A^{-1} = \begin{bmatrix} -2 & 3 & -1 \\ 1 & -1 & 1 \\ 2 & -2 & 1 \end{bmatrix} \quad \checkmark$$

$$\text{check: } \begin{bmatrix} 1 & -1 & 2 \\ 1 & 0 & 1 \\ 0 & 2 & -1 \end{bmatrix} \cdot \begin{bmatrix} -2 & 3 & -1 \\ 1 & -1 & 1 \\ 2 & -2 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \checkmark$$



3. (10 points) Let A be the same matrix as in Problem 2, and let

$$B = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 4 \\ 3 & 2 & 1 \end{bmatrix} \quad A = \begin{bmatrix} 1 & -1 & 2 \\ 1 & 0 & 1 \\ 0 & 2 & -1 \end{bmatrix}$$

$$Ax = b \\ x = A^{-1} \cdot b$$

Find a matrix C such that $A^T C = B$ (where A^T is the transpose of A).

$$A^T C = B \Rightarrow C = (A^T)^{-1} \cdot B \quad (A^T)^{-1} = (A^{-1})^T \quad \checkmark$$

$$A^{-1} = \begin{bmatrix} -2 & 3 & -1 \\ 1 & -1 & 1 \\ 2 & -2 & 1 \end{bmatrix} \quad (A^{-1})^T = \begin{bmatrix} -2 & 1 & 2 \\ 3 & -1 & -2 \\ -1 & 1 & 1 \end{bmatrix}$$

$$(A^{-1})^T \cdot B = \begin{bmatrix} -2 & 1 & 2 \\ 3 & -1 & -2 \\ -1 & 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 4 \\ 3 & 2 & 1 \end{bmatrix} = \begin{bmatrix} -2+4+6 & -4+5+4 & -6+4+2 \\ 3-4-6 & 6-5-4 & 9-4-2 \\ -1+4+3 & -2+5+2 & -3+4+1 \end{bmatrix}$$

$$C = \begin{bmatrix} 8 & 5 & 0 \\ -7 & -3 & 3 \\ 6 & 5 & 2 \end{bmatrix} \quad \checkmark$$



4. (20 points) Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ be a linear transformation given by

$$T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} x_1 - 2x_2 \\ x_1 + x_2 \\ x_1 - 3x_2 \end{bmatrix}$$

a) Find the standard matrix of T .

b) Find all vectors u satisfying $T(u) = \begin{bmatrix} 1 \\ 10 \\ -2 \end{bmatrix}$.

a)

$$A = [T(e_1) \quad T(e_2)] \quad T(e_1) = T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 - 2(0) \\ 1 + 0 \\ 1 - 3(0) \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$T(e_2) = T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 0 - 2(1) \\ 0 + 1 \\ 0 - 3(1) \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \\ -3 \end{bmatrix}$$

$$\text{Standard matrix of } T = A = \begin{bmatrix} 1 & -2 \\ 1 & 1 \\ 1 & -3 \end{bmatrix} \checkmark$$

b) $A \cdot u = T(u)$

$$\begin{bmatrix} 1 & -2 \\ 1 & 1 \\ 1 & -3 \end{bmatrix} \cdot u = \begin{bmatrix} 1 \\ 10 \\ -2 \end{bmatrix}$$

$$\left[\begin{array}{cc|c} 1 & -2 & 1 \\ 1 & 1 & 10 \\ 1 & -3 & -2 \end{array} \right] \xrightarrow{R_2 - R_1} \left[\begin{array}{cc|c} 1 & -2 & 1 \\ 0 & 3 & 9 \\ 1 & -3 & -2 \end{array} \right] \xrightarrow{R_3 - R_1} \left[\begin{array}{cc|c} 1 & -2 & 1 \\ 0 & 3 & 9 \\ 0 & -1 & -3 \end{array} \right] \xrightarrow{R_2 \leftrightarrow R_3} \left[\begin{array}{cc|c} 1 & -2 & 1 \\ 0 & -1 & -3 \\ 0 & 3 & 9 \end{array} \right] \xrightarrow{R_2 \cdot (-1)} \left[\begin{array}{cc|c} 1 & -2 & 1 \\ 0 & 1 & 3 \\ 0 & 3 & 9 \end{array} \right] \xrightarrow{R_3 - 3R_2} \left[\begin{array}{cc|c} 1 & -2 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{array} \right]$$

$$\left[\begin{array}{cc|c} 1 & 0 & 7 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{array} \right] \xrightarrow{R_1 + 2R_2} \left[\begin{array}{cc|c} 1 & 0 & 7 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{array} \right]$$

$$x_1 = 7 \\ x_2 = 3$$

$$u = \begin{bmatrix} 7 \\ 3 \end{bmatrix} \checkmark$$

$$\text{check: } T\left(\begin{bmatrix} 7 \\ 3 \end{bmatrix}\right) = \begin{bmatrix} 7 - 2(3) \\ 7 + 3 \\ 7 - 3(3) \end{bmatrix} = \begin{bmatrix} 1 \\ 10 \\ -2 \end{bmatrix} \checkmark$$



5. (20 points) For each matrix A given below determine if the matrix transformation $T_A: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by $T_A(v) = Av$ is one-to-one or not. If T_A is not one-to-one, find two vectors v_1 and v_2 such that $T_A(v_1) = T_A(v_2)$.

a) $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 3 & 4 & 4 \end{bmatrix}$

b) $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 3 & 4 & 2 \end{bmatrix}$

a) $\begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 3 & 4 & 4 \end{bmatrix} \xrightarrow{R_3 - 3R_1} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 0 & 1 & 4 \end{bmatrix} \xrightarrow{R_2 \leftrightarrow R_3} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 2 & 4 \end{bmatrix} \xrightarrow{R_2 \cdot (-1)} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 2 \\ 0 & 1 & 4 \end{bmatrix} \xrightarrow{R_3 - R_2} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 2 \\ 0 & 0 & 2 \end{bmatrix} \xrightarrow{R_3 \cdot \frac{1}{2}} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_1 + 2R_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_2 \cdot (-2)} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

Since A has a pivot position in every column, $T_A(v)$ is one-to-one.

b) $\begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 3 & 4 & 2 \end{bmatrix} \xrightarrow{R_3 - 3R_1} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 4 \\ 0 & 1 & 2 \end{bmatrix} \xrightarrow{R_2 \cdot \frac{1}{2}} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 1 & 2 \end{bmatrix} \xrightarrow{R_2 \cdot (-1)} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 2 \\ 0 & 1 & 2 \end{bmatrix} \xrightarrow{R_3 - R_2} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$

Since A does not have a pivot position in every column, $T_A(v)$ is not one-to-one.

$T_A(v_1) = T_A(v_2)$

Let $T_A(v_1) = T_A(v_2) = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$

$\begin{bmatrix} x_1 & x_2 & x_3 \\ 1 & 0 & -2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$

$\begin{cases} x_1 = 1 + 2x_3 \\ x_2 = 2 - 2x_3 \\ x_3 = x_3 \end{cases}$

If $x_3 = 1$:

$\begin{aligned} x_1 &= 1 + 2(1) = 3 \\ x_2 &= 2 - 2(1) = 0 \\ x_3 &= 1 \end{aligned}$

If $x_3 = -1$:

$\begin{aligned} x_1 &= 1 + 2(-1) = -1 \\ x_2 &= 2 - 2(-1) = 4 \\ x_3 &= -1 \end{aligned}$

$v_1 = \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix}$

$v_2 = \begin{bmatrix} -1 \\ 4 \\ -1 \end{bmatrix}$





6. (10 points) For each of the statements given below decide if it is true or false. If it is true explain why. If it is false give a counterexample.

a) If u, v, w are vectors in \mathbb{R}^3 such that $w + u \in \text{Span}(u, v)$ then $w \in \text{Span}(u, v)$.

True. ✓ Vector u must be in the $\text{Span}(u, v)$, and given that $w + u \in \text{Span}(u, v)$ then $w + u$ must also be in the $\text{Span}(u, v)$.

↑
True, but this is not what this statement says.

b) If u, v, w are vectors in \mathbb{R}^3 such that the set $\{u, v, w\}$ is linearly independent then the set $\{u, v\}$ must be linearly independent.

True. ✓ In order for $\{u, v, w\}$ to be linearly independent, it must have a leading one in every column. This means $\{u, v\}$ also has a leading one in every column, so $\{u, v\}$ is linearly independent. ✓



7. (10 points) For each of the statements given below decide if it is true or false. If it is true explain why. If it is false give a counterexample.

a) If A is a 2×2 matrix and u, v are vectors in \mathbb{R}^2 such that Au, Av are linearly dependent then u, v also must be linearly dependent.

$\{Au, Av\}$ linearly dependent

False. [✓] Multiplying matrix A by vectors u and v does not necessarily preserve linear dependence.
 Why? example?

b) If $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is a linear transformation and $u, v, w \in \mathbb{R}^2$ are vectors such that u is in $\text{Span}(v, w)$ then $T(u)$ must be in $\text{Span}(T(v), T(w))$.

True. [✓] If vector $u \in \text{span}(v, w)$ and transformation T is applied to u, v, w then $T(u) \in \text{span}(T(v), T(w))$.
 why?