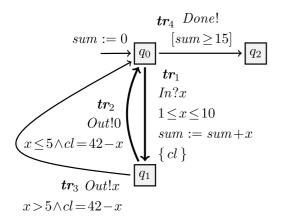
Timed symbolic transition system - Reference system model

SPTG automata models, called **timed symbolic transition systems**, will be introduced in the following using a small dummy one, \mathbb{G} sufficient to illustrate the main components:



Channels are $C = \{In, Out, Done\}$, data variables are $A = \{x, sum\}$, and clocks are $K = \{cl\}$. Clock cl ranges over positive rationals, providing a dense time domain, and measures elapsed time. Variable x stores incoming values, while variable sum accumulates them (initialized to 0).

Channels are typed and declared as input or output:

- In?x binds x to a value of the type of In (here, positive rationals),
- Out!t emits a value t of the type of Out,
- channels without data, like *Done*, have undefined type.

A transition is a tuple

 $(q,act,\phi,\mathbb{K},
ho,q')$, where:

- q,q' are states,
- act is an input/output action,
- ϕ is a guard,
- $\mathbb{K} \subseteq K$ is the set of clocks to reset,
- ρ is an update $x_1! := !t_1, \ldots, x_n! := !t_n$ on data variables (where terms t_i may involve clocks).

When ho=id, variables remain unchanged; only relevant updates are shown.

The system \mathbb{G} has three states q_0, q_1, q_2 and four transitions:

- $\mathbf{tr}_1 = (q_0, In?x, 1 \leq x \leq 10, cl, sum! := !sum + x, q_1)$ \rightarrow processes inputs;
- $\mathbf{tr}_2 = (q_1, Out!0, x \leq 5 \land cl = 42 x, \emptyset, id, q_0)$ \rightarrow emits 0 for small inputs;
- $\mathbf{tr}_3 = (q_1, Out!x, x > 5 \land cl = 42 x, \emptyset, id, q_0)$ \rightarrow emits the received value otherwise;
- $\mathbf{tr}_4 = (q_0, Done!, sum \ge 15, \emptyset, id, q_2)$ \rightarrow may signal termination when the accumulated sum reaches 15.

Encoding of the timed symbolic transition system in XLIA

The SPTG framework, being an extension of the DIVERSITY symbolic execution platform, uses its entry language to express models of timed symbolic transition systems. This language, called **XLIA** (**eXecutable Language for Interaction and Architecture**), is designed for specifying the behavior of component-based systems.

In XLIA, components are referred to as machines. These machines are communicating, hierarchical, and heterogeneous, and their evaluation semantics can be customized to support different analysis or execution contexts.

The complete XLIA specification is available in the XLIA documentation.

For timed symbolic transition systems, a single machine is typically used to represent the system under study, which interacts with its environment through well-defined communication interfaces.

The automaton \mathbb{G} is encoded in the **XLIA** input language of the **DIVERSITY** symbolic execution platform as follows:

```
timed system Example01 Dummy {
@composite:
    statemachine Example01 Dummy {
    @public:
        port input In( urational );
        port output Out( urational );
        port output Done;
    @private:
        var urational
                            sum;
        var urational
        var clock urational cl;
    @region:
        state<start> q0 {
            @init{
                sum := 0;
            transition tr1 --> q1 {
                input In( x );
```

```
guard ( 1 <= x <= 10 );
                 sum := sum + x;
                c1 := 0;
            }
            transition tr4 --> q2 {
                 guard ( sum >= 15 );
                 output Done;
            }
        }
        state q1 {
            transition tr2 --> q0 {
                 guard ( x <= 5 \&\& c1 == 42-x );
                 output Out( 0 );
            }
            transition tr3 --> q0 {
                 guard ( x > 5 \&\& cl == 42-x );
                 output Out( x );
            }
        }
        state q2;
    @com:
        connect< env >{
            input In;
            output Out;
            output Done;
     }
}
```

1. General Structure

The **XLIA model** (entry language of the **DIVERSITY** symbolic execution platform) encodes the automaton by explicitly separating the **static part** (declarations of variables, clocks, and communication ports) from the **behavioral part** (states, transitions, and synchronization).

The timed system construct defines the **whole system**, while the nested statemachine block defines the actual automaton.

2. Static Part

The static part declares:

- **Ports** (inputs/outputs), which correspond to the external interactions of the automaton.
- Variables (data and clocks), which capture internal state and timing information.

From the XLIA model:

```
@public:
   port input In( urational );
```

```
port output Out( urational );
  port output Done;
@private:
  var urational         sum;
  var urational         x;
  var clock urational cl;
```

Mapping to the automaton

XLIA element	Meaning	Automaton equivalent
port input In(urational)	Input port for receiving a rational value \boldsymbol{x}	Transition input action $In?x$
<pre>port output Out(urational)</pre>	Output port for sending a rational value	Transition output action $Out!0$ or $Out!x$
port output Done	Output signal without data	Transition output action $Done$
var urational sum	Data variable tracking accumulated input	Automaton variable (used in guards/actions)
var urational x	Data variable holding the latest input	Variable bound by input message
var clock urational	Clock variable (measures elapsed time since last reset)	Automaton clock for timed constraints

Thus, the static part declares the **interface** and **internal state space** of the automaton.

3. Behavioral Part

The behavioral description is under @region, where states and transitions are defined.

```
@region:
    state<start> q0 { ... }
    state q1 { ... }
    state q2;
```

States

- q0: Initial state (<start>), where sum is initialized.
- q1: Intermediate state reached after an input.
- q2: Final or terminal state when the condition sum >= 15 holds.

Initialisation

```
@init {
    sum := 0;
}
```

Transitions from q0

```
transition tr1 --> q1 {
    input In( x );
    guard ( 1 <= x <= 10 );
    sum := sum+x;
    cl := 0;
}
transition tr4 --> q2 {
    guard ( sum >= 15 );
    output Done;
}
```

Transition Mapping

Transition	Automaton equivalent	Description
tr1	$(q_0,\mathit{In}?x,1 \leq x \leq 10,\mathit{cl},\mathit{sum}! := !\mathit{sum} + x,q_1)$	Receives input x , adds to sum , resets the clock cl .
tr4	$(q_0, Done!, sum \geq 15, \emptyset, id, q_2)$	Produces $ m Done$ output when accumulated $ m sum \geq 15$.

Transitions form q1

```
transition tr2 --> q0 {
    guard ( x <= 5 && cl == 42-x );
    output Out( 0 );
}
transition tr3 --> q0 {
    guard ( x > 5 && cl == 42-x );
    output Out( x );
}
```

Transition	Automaton equivalent	Description
tr2	$(q_0,\mathit{In}?x,1 \leq x \leq 10,\mathit{cl},\mathit{sum}! := !\mathit{sum} + x,q_1)$	Emits value 0 , for small inputs.
tr3	$(q_1, \mathit{Out}!0, x \leq 5 \wedge cl = 42 - x, \emptyset, id, q_0)$	Emits received input x , otherwise.

4. Communication Interface

The @com section defines how this state machine interacts with the environment:

```
@com:
    connect< env >{
        input In;
        output Out;
        output Done;
}
```

This binds the declared input/output ports to the environment.

5. Summary: Automaton -- XLIA Correspondence

Automaton Concept	XLIA Encoding
Locations q_0,q_1,q_2	state q0, state q1, state q2
Initial location	state <start></start>
Transitions	transition trX> qY { }
Guards	guard() expressions
Clocks	Declared with var clock
Clock resets	Assignments like c1 := 0
Input actions	input In(x)
Output actions	output Out() or output Done
Variable updates	Direct assignments inside transition body
Terminal state	state q2; (no outgoing transitions)

More on XLIA subset to encode timed symbolic transition system

```
// Composite Part: State Machine Definition
@composite:
statemachine SM {
  @public:
    // -----
    // Declaration of Ports
    // -----
    port input In;
    port output Done;
    port input In1( urational );
    port input In2( integer );
    port output Out( urational );
    // Declaration of N-ary Ports
    port input In3( bool, integer, rational );
    port output Out2( integer, bool );
    // -----
    // Declaration of Constants
    // -----
    const integer N = 42;
  @private:
    // Declaration of Variables
    // -----
    var urational sum;
    var urational x;
    var urational y;
    var integer z;
    var bool
            flag;
    var integer fee;
    // -----
    // Declaration of Clocks
    // -----
    var clock urational cl;
    var clock urational cl2;
  // Behavioral Description: States and Transitions
  @region:
    // -----
    // Initial State
    // -----
    state<start> q0 {
       @init {
         sum := 0;
         flag := false;
```

```
guard( fee > 0 );
      }
      transition tr1 --> q1 {
         input In1( x );
         guard ( 1 <= x <= 10 );
         sum := sum + x;
         y := sum;
         c1 := 0;
      }
      transition tr2 --> q1 {
         input In( x );
         guard ( 10 < x \&\& x < N );
         {|,|
            sum := sum + x;
           y := sum; // y receives the pre-increment sum value
         c12 := 0;
      }
  }
   // -----
   // Secondary State
   // -----
  state q1 {
      transition tr3 --> q0 {
         guard( x <= 10 \&\& cl == N - x );
         output Out( sum - 1 );
      }
      transition tr4 --> q0 {
         guard(x > 10);
         guard( cl <= 5 );
         output Out2( fee, flag );
         flag := true;
         c12 := 0;
      }
     transition tr5 --> q2 {
         guard( sum >= 15 && cl2 <= 1 );
         output Done;
         c12 := 0;
      }
   }
   // Terminal State
   // -----
   state q2;
// Communication Part: Port Connections
```

```
@com:
    connect< env > {
        input In;
        input In1;
        input In2;
        input In3;
        output Done;
        output Out;
        output Out2;
    }
}
```