

Python NIRSPEC Pipeline Cheat Sheet

Initial setup

1. On hobbes the source code is located in the directory `/opt/python/2.7.5/lib/python2.7/site-packages/`
 - A. `pynirspec/` — The actual pipeline. Converts raw FITS images into reduced 1-D spectra
 - B. `atmopt/` — Contains code that computes atmospheric models using the RFM line-by-line code (`rfm_tools.py`) used for the wavelength calibration.
 - C. `pyspec/` — Tools for dealing with fully reduced 1D spectra (I haven't used this)
 2. Within your working directory create the following directories: `CAL1D/`, `L1FILES/`, `SA1D/`, `SPEC1D/`, `SPEC2D/`, and `WAVE/`.
 3. If you plan to edit the code you should get a bitbucket account and follow `pontoppi/pynirspec`, `pontoppi/atmopt`, and `pontoppi/pyspec`.
 - A. It's a mercurial repository. Email Klaus Pontoppidan (pontoppi@stsci.edu) for access.
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Reduction

1. Inputs

1. `nirspec.ini` file — contains spectral setups (echelle/cross disperser angles), number of orders, location of orders, and initial guesses for wavelength calibration, *initial guess for resolving power (~25000)*
→ must match fits headers
Wrange in um, Yrange in pixels
2. Driver script — see example

2. Level 1 - Each step is performed on a science and standard target

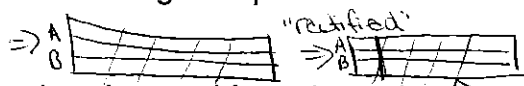
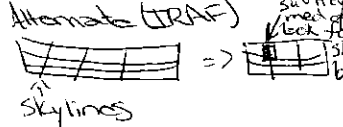
- A. `FDark` and `ODark` — median combined dark frames for the flats and science frames, respectively. Also creates a bad pixel mask.
not used once calculated

- B. `OFlat` — Median combined, normalized flat field.

- C. `Nod` — Stack of A-B images

- i. Based on coordinates from the headers, images are assigned as A or B (Errors occur at this step sometimes). *For long observations, detector may drift. A,B positions become inconsistent. Crash.*
- ii. A-B subtraction, flat field and bad pixel corrections are applied. *Solution: Line 468 of `pynirspec.py`, 'problem: True', specify A,B nodes *or if header incomplete*
- iii. An image of just the sky is also created.
- iv. Uncertainties are propagated as a separate image

D. Order — Average combined A-B image

- Offsets along the spatial axis are computed independently for A and B nodes
- Shifts are applied and the images are averaged together.
- The combined image is rectified along the spatial axis so that the centroid of the PSF follows a single row. 
- The median of each column is subtracted from that column. 
- Final image is printed to the SPEC2D/ directory which includes the target image with uncertainties and the sky image with uncertainties.

E. SPEC1D — 1D spectrum with a rough wavelength calibration

- 1-D spectrum is extracted based on an optimal extraction method.
- An initial wavelength calibration is applied based on the initial guesses from the nirspec.ini file.
- The final spectrum is printed to the SPEC1D/ directory. Includes arrays for: wavelength, source flux, uncertainty in source flux, sky flux, and uncertainty in sky flux for both the A and B positions.

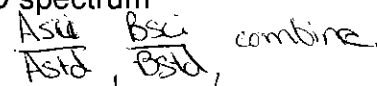
F. WaveCal — Wavelength calibrated 1-D spectra for A and B nodes

- Atmospheric model is computed by RFM (atmopt) based on wavelength regions given in nirspec.ini
- Cross-correlation between model and observed sky yields the wavelength calibration which is a 4th order polynomial. The optimization happens in rf_m_tools.py (atmopt) within the Optimize() class.
- The final spectrum is printed to WAVE/. The format is the same as SPEC1D/ except the wavelength calibration is updated.

*λ is not regularly spaced
Flux evenly spaced over 1024 pixels.*

3. Level 2

A. CalSpec — A/B averaged, telluric corrected (from standard) 1-D spectrum

- A and B nod spectra are normalized to median 
- Optional Beers law correction is applied to the standard
- Science spectra are divided by the telluric standard
- The final spectrum is printed to CAL1D/. Includes arrays for: wavelength, telluric divided flux, and uncertainty in flux.