
DETECTION AND CLASSIFICATION OF INCIPIENT FAULTS IN AUTOMOTIVE USING MACHINE LEARNING APPROACH

Machine Learning Course Project



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Abstract:

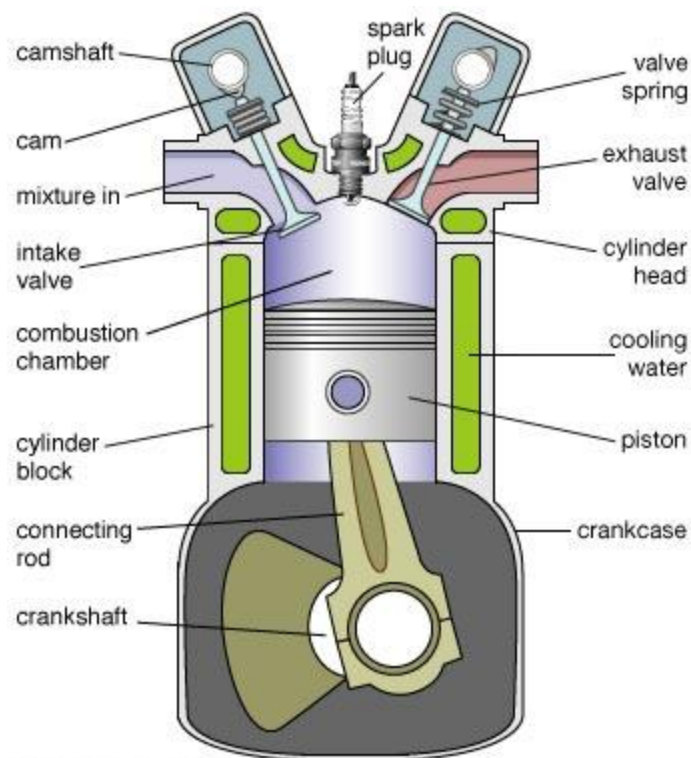
Integrated vehicle health management (IVHM) or integrated system health management (ISHM) is the unified capability of systems to assess the current or future state of the member system health and integrate that picture of system health within a framework of available resources and operational demand. IVHM helps in better management of vehicle and vehicle fleet health. This is achieved through correct use of reliable sensing and prognosis systems to monitor part health and also using usage data to assist in understanding the load experienced and likely future vehicle load. Detection of early and low magnitude faults in automotive engines requires dynamic engine models which can capture within-cycle continuous switching dynamics of engine under different input and state conditions. In this project we tried to predict the state of engine error using machine learning concepts. We are targeting here the training of data and interpretation of faults on the earlier work done and trying to explore the machine learning opportunities in the context of fault detection.

Problem Statement:

Online fault diagnosis of automotive engines is a crucial part of integrated vehicle health management (IVHM) and associated prognosis strategies, which are being employed in increasingly many automotive vehicles at present times. Detection of early and low magnitude faults in automotive engines requires dynamic engine models which can capture within-cycle continuous switching dynamics of engine under different input and state conditions. However, because implementations of such accurate model based diagnosis schemes require huge computational capacity usually not found on engine electronic control units (ECUs), a trade-off is sought between model complexity and performance of diagnosis schemes. We are targeting here the training of data and interpretation of faults on the earlier work done and trying to explore the machine learning opportunities in the context of fault detection.

Methodology:

Understanding the existing model.



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Figure: Spark Ignition 4-stroke Engine Components

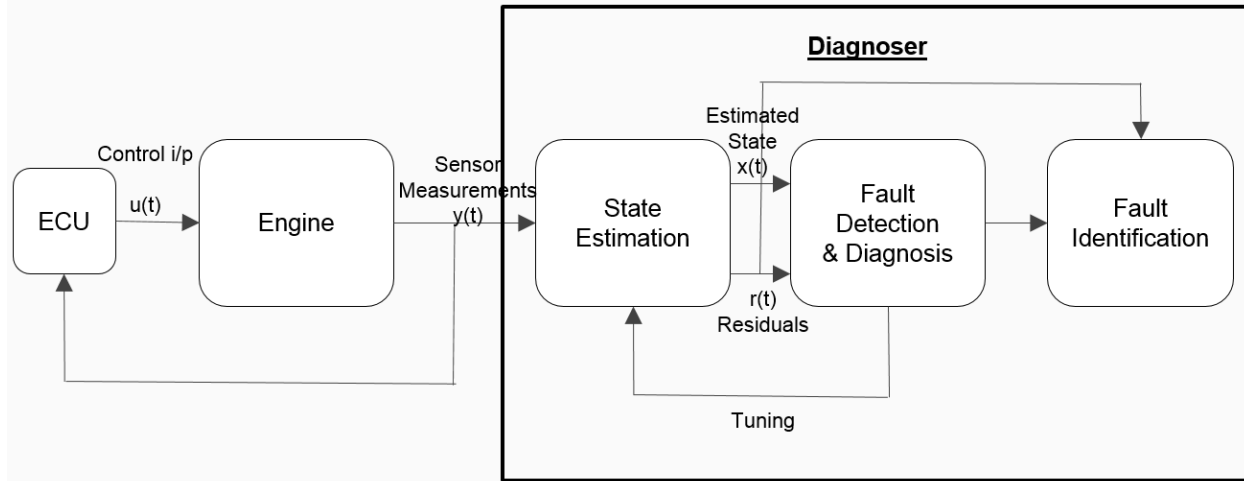


Figure: Introduction to the work, block diagram

Figure shows an online fault diagnosis scheme in which WCCM could be employed. It could be used inside nonlinear estimators/observers for accurate estimation of engine variables that are usually not measured, such as the pressures, temperatures and masses of individual gas species in cylinders. These variables contain fault signatures needed for fault detection and isolation. Being a diagnosis-oriented model, the WCCM has the advantage of accessing control signals coming out of ECU, and can improve the diagnosis functionality. Further, such a model when implemented online could help the ECU in implementing fault tolerant control schemes and integrated vehicle health management (IVHM). Note that even for fault tolerant control, unlike control-oriented models, diagnosis models need not have to be hard real time, allowing for more complexity to be added to the model for better diagnosability.

Identifying our contribution:

Existing work of the NP-MASS lab takes the measurement residuals as an input and computes likelihood function for each non faulty and faulty states; and identifies the state of the system. We try to enhance the work, by replacing identification logic with Machine learning algorithm. The input is measurement residual for ML algorithm and the output is classification of state. We trained the system using naïve Bayes classifier, Random Forest and J48.

Since number of features were much more than the observations available we used random forest algorithm for the classification task.

Results:

Results of training data using Random Forest, Naïve Bayes, J48 algorithm:

Random Forest:

Instances: 1400

Attributes: 8524

=== Classifier model (full training set) ===

=== Summary ===

Correctly Classified Instances	581	96.8333 %
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Incorrectly Classified Instances	19	3.1667 %
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=== Detailed Accuracy By Class ===

	TP Rate	FP Rate	Precision	Recall	F-Measure	MCC	ROC Area	PRC Area	Class
	0.980	0.013	0.961	0.980	0.970	0.960	0.999	0.998	0
	0.967	0.013	0.960	0.967	0.963	0.951	0.995	0.989	1
	0.947	0.013	0.959	0.947	0.953	0.938	0.995	0.988	2
	0.980	0.002	0.993	0.980	0.987	0.982	1.000	0.999	3
Weighted Avg.	0.968	0.011	0.968	0.968	0.968	0.958	0.997	0.993	

Naive Bayes Classifier:

=== Summary ===

Correctly Classified Instances	1608	80.4 %
Incorrectly Classified Instances	392	19.6 %

=== Detailed Accuracy By Class ===

	TP Rate	FP Rate	Precision	Recall	F-Measure	MCC	ROC Area	PRC Area	Class
	0.834	0.063	0.814	0.834	0.824	0.765	0.903	0.744	0
	0.816	0.083	0.767	0.816	0.791	0.719	0.896	0.709	1
	0.738	0.086	0.741	0.738	0.739	0.653	0.849	0.652	2
	0.828	0.029	0.904	0.828	0.864	0.823	0.907	0.806	3
Weighted Avg.	0.804	0.065	0.807	0.804	0.805	0.740	0.889	0.727	

J48 TREE:

=== Summary ===

Correctly Classified Instances	523	87.1667 %
Incorrectly Classified Instances	77	12.8333 %

=== Detailed Accuracy By Class ===

	TP Rate	FP Rate	Precision	Recall	F-Measure	MCC	ROC Area	PRC Area	Class
	0.940	0.018	0.946	0.940	0.943	0.924	0.965	0.908	0
	0.720	0.027	0.900	0.720	0.800	0.751	0.929	0.810	1
	0.927	0.113	0.732	0.927	0.818	0.757	0.926	0.718	2
	0.900	0.013	0.957	0.900	0.928	0.906	0.955	0.917	3
Weighted Avg.	0.872	0.043	0.884	0.872	0.872	0.834	0.944	0.838	

Sample Dataset

Inlet Manifold Temperature	Inlet Manifold Pressure	Outlet Manifold Pressure
-6.03E-02	2.36E+03	-2.39E+04
-1.24E-02	2.35E+03	-2.38E+04
-1.07E-02	2.06E+03	-2.41E+04
-6.89E-02	1.72E+03	-2.28E+04
-3.63E-02	2.09E+03	-2.17E+04

Conclusions:

We are able to apply various algorithm to train our system that predicts and classifies faults with very high accuracy. In this project we have used residual data to train the system, this work can further be extended to use raw data directly from the various sensors.

References:

[1] Nadeer E P, Amit Patra, and Siddhartha Mukhopadhyay, Hybrid State Space Modelling of an SI Engine for Online Fault Diagnosis.