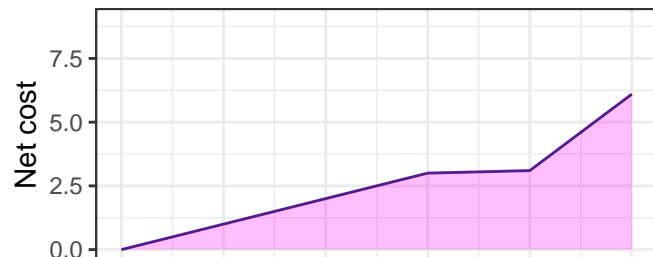
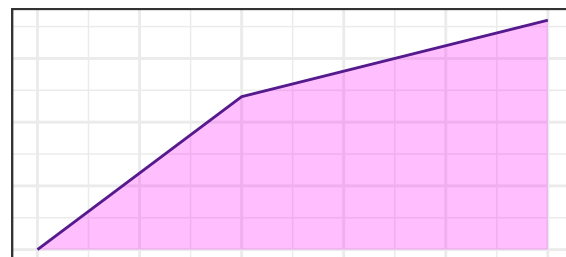


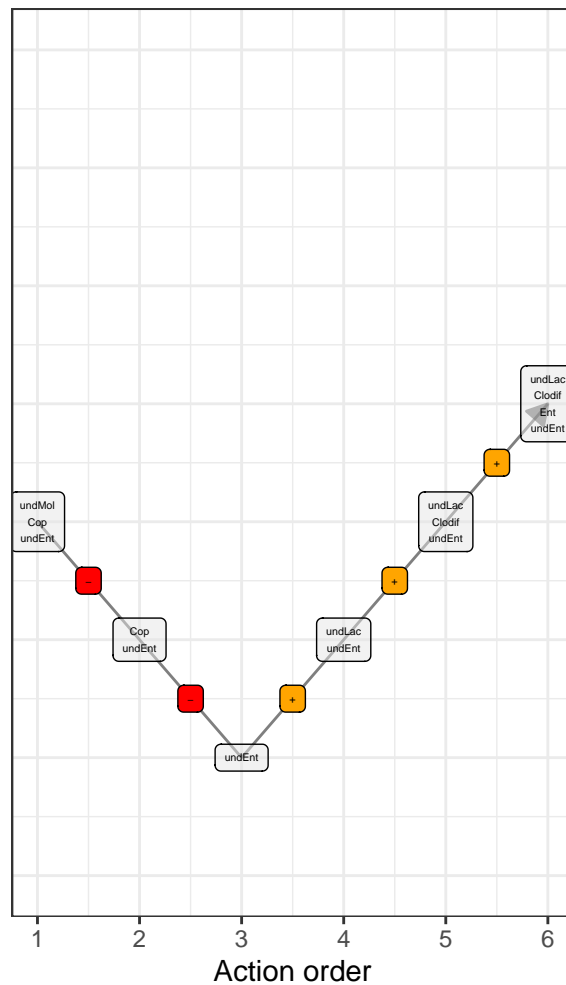
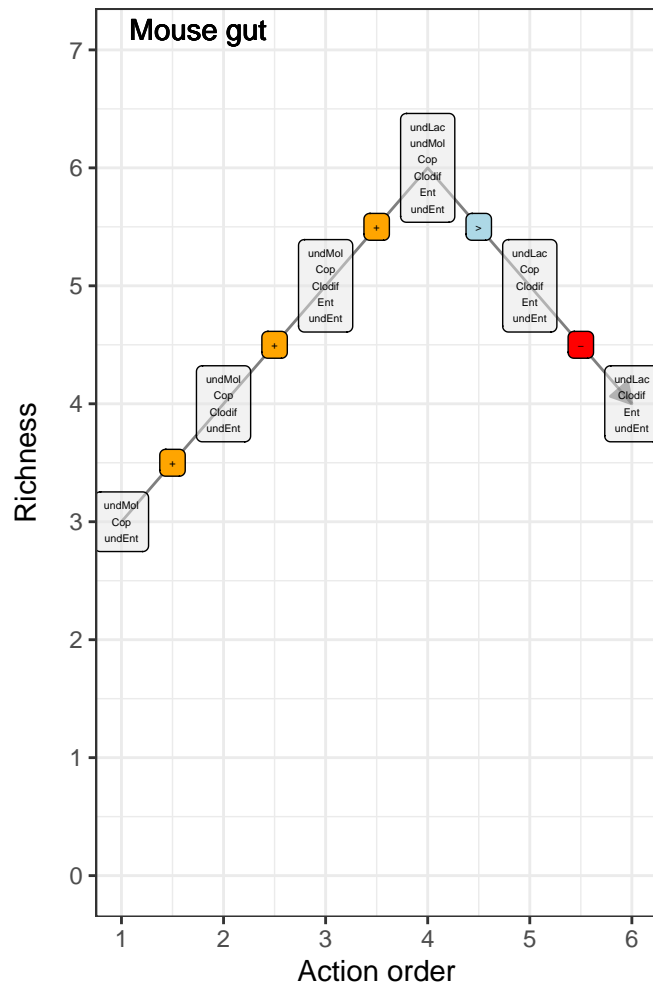
Optimal path



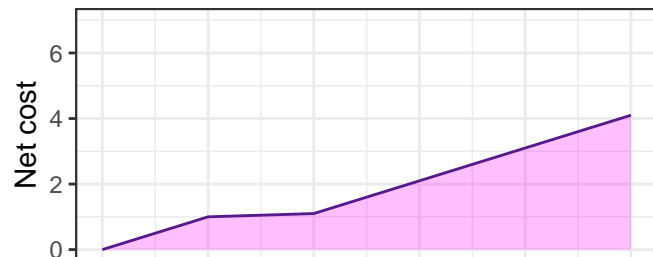
Nominal path



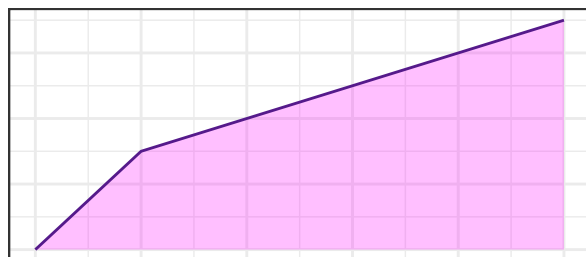
Mouse gut



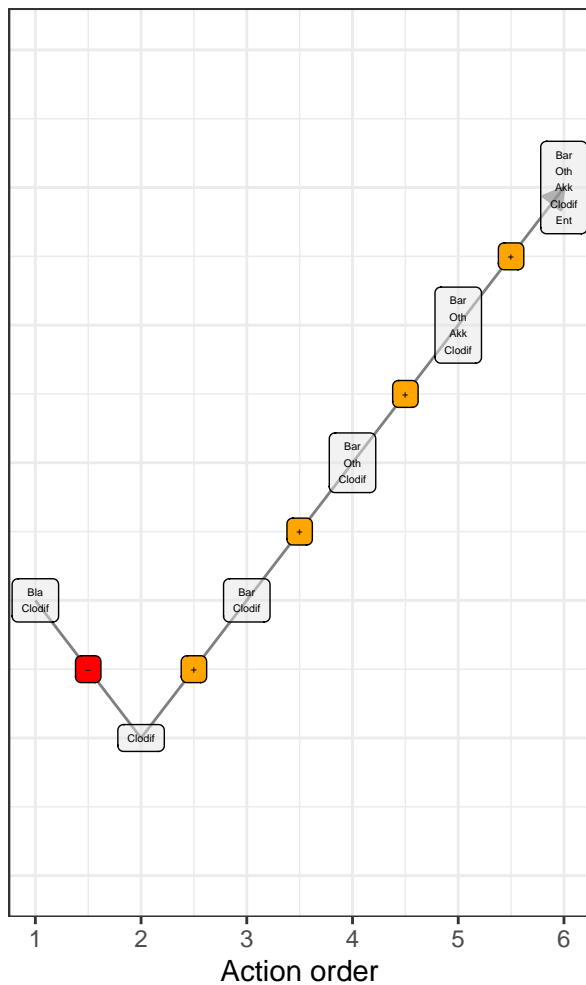
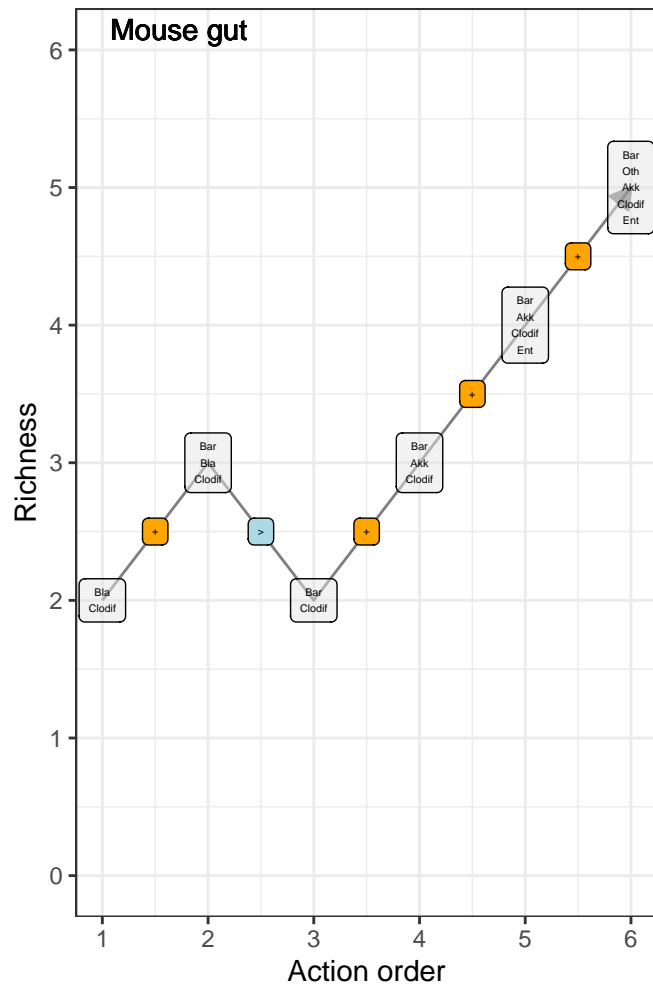
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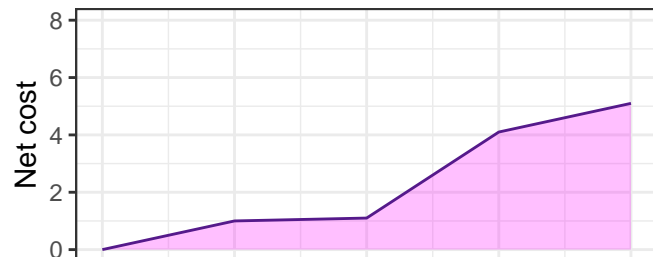
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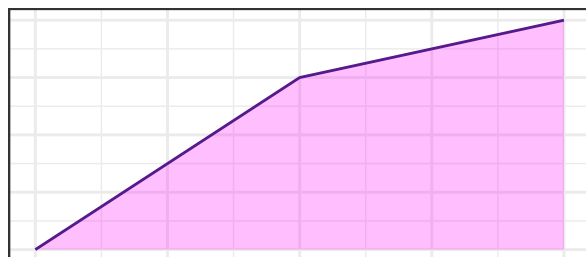
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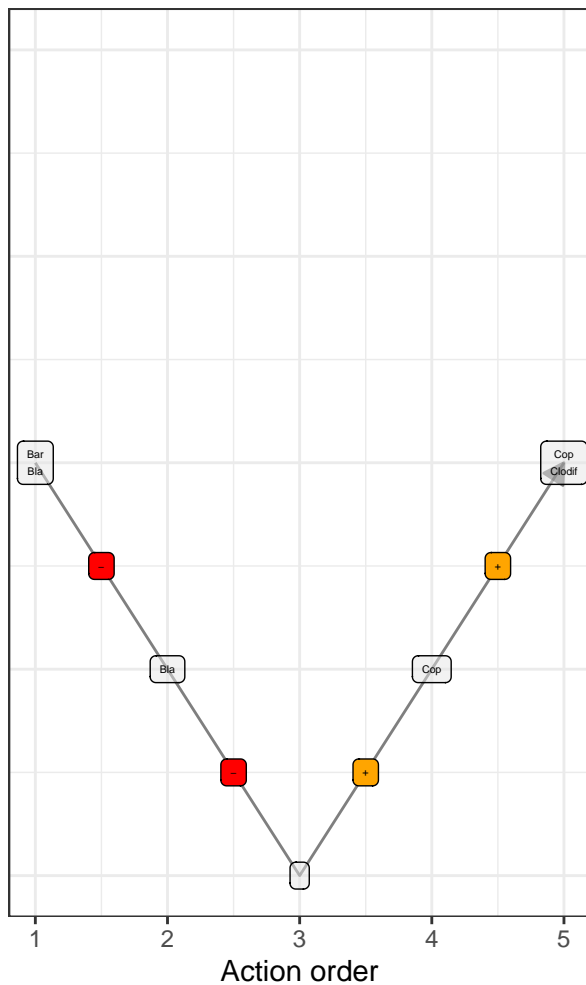
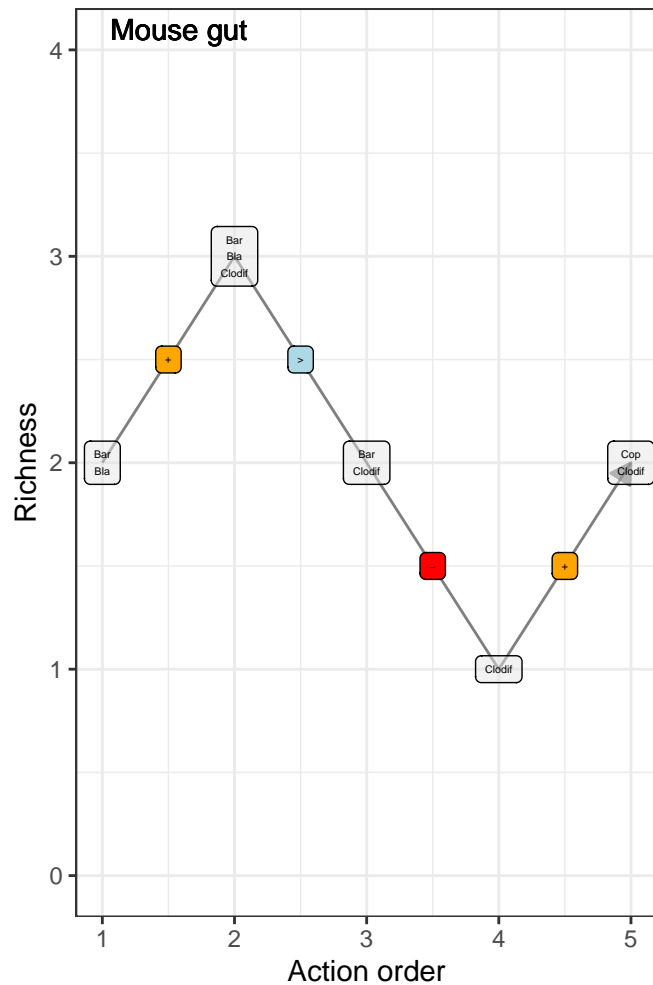
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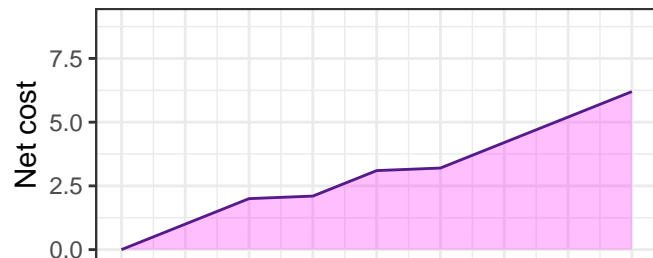
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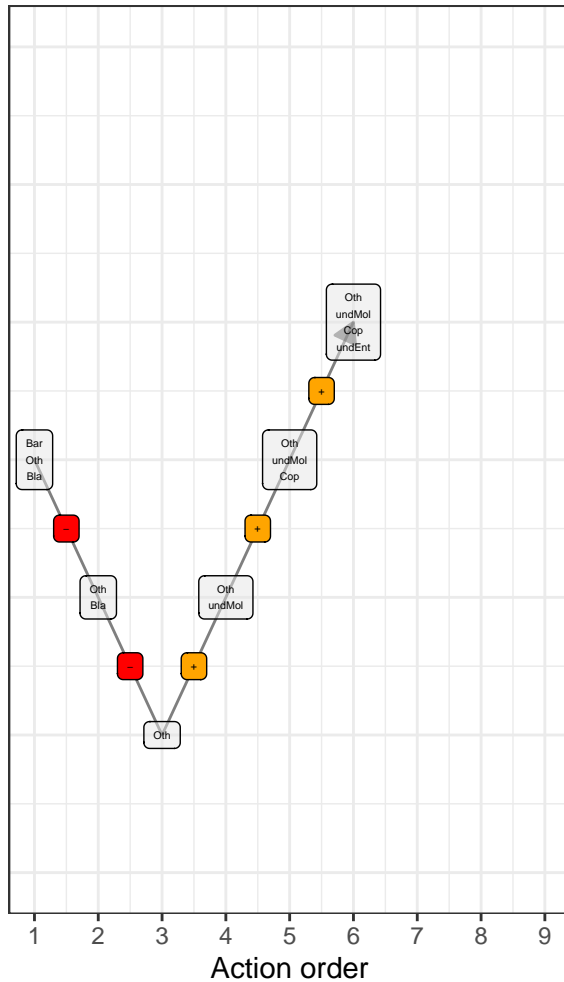
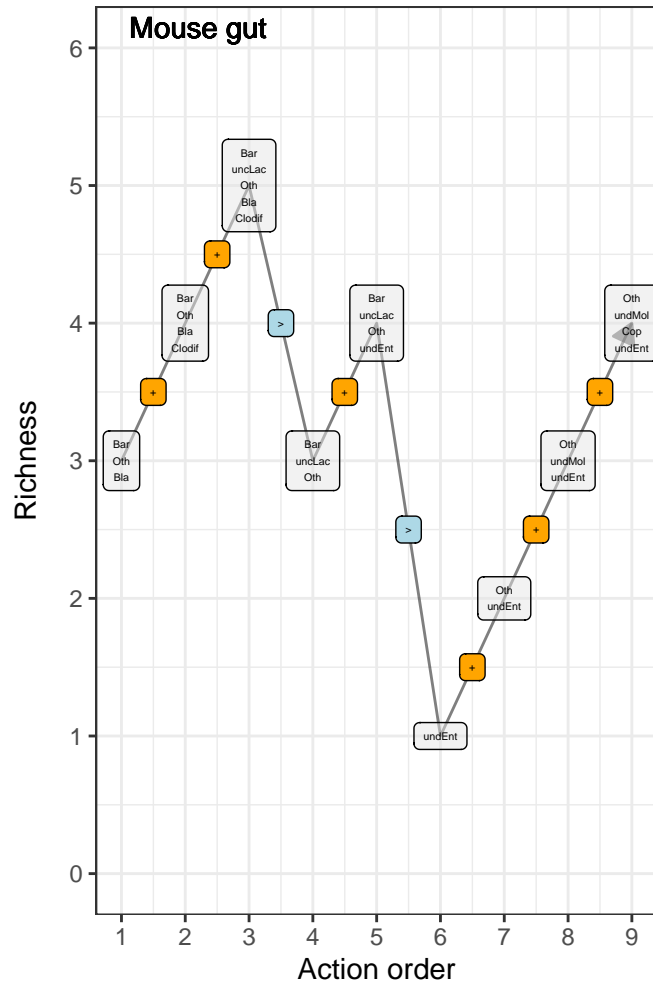
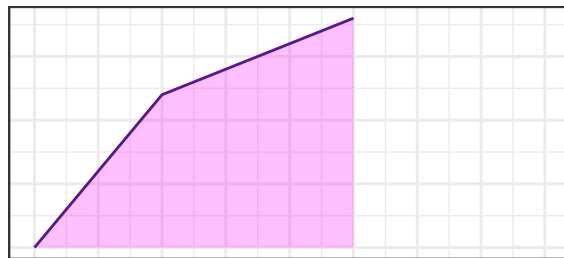
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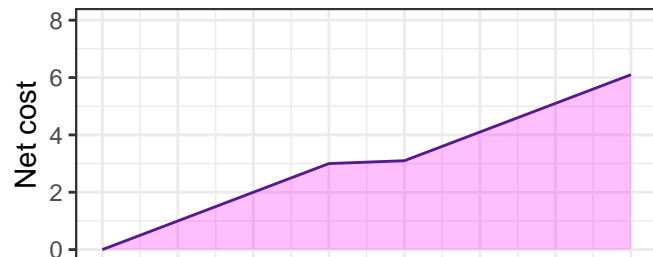
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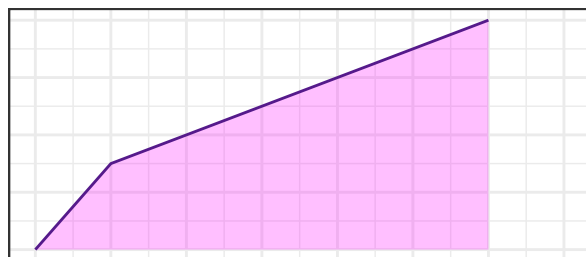
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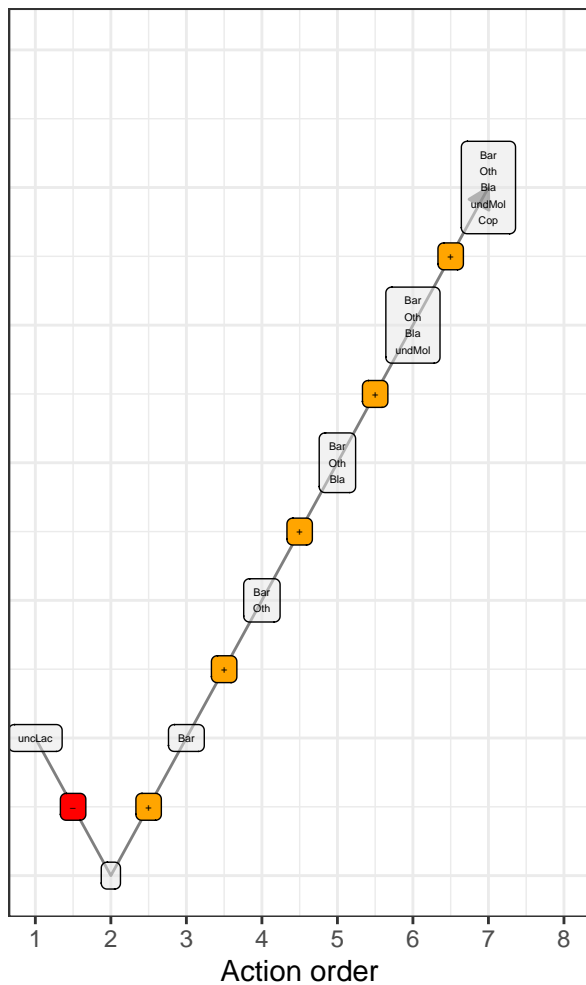
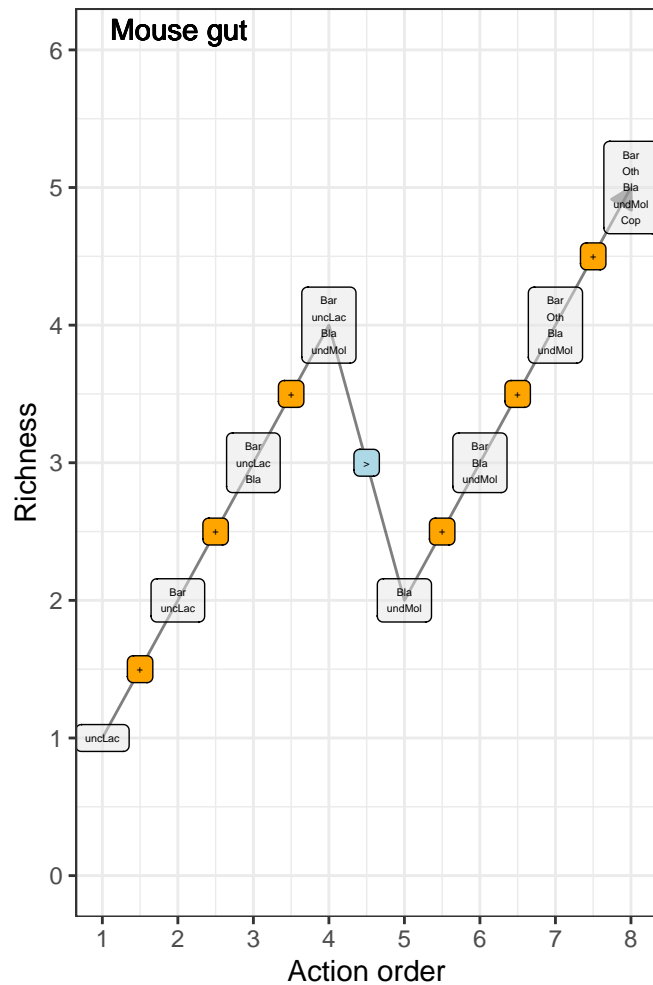
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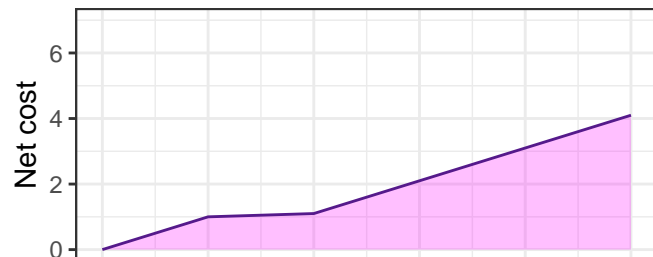
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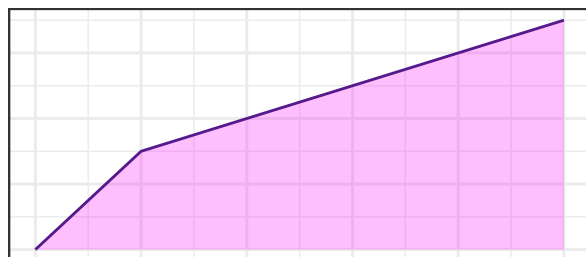
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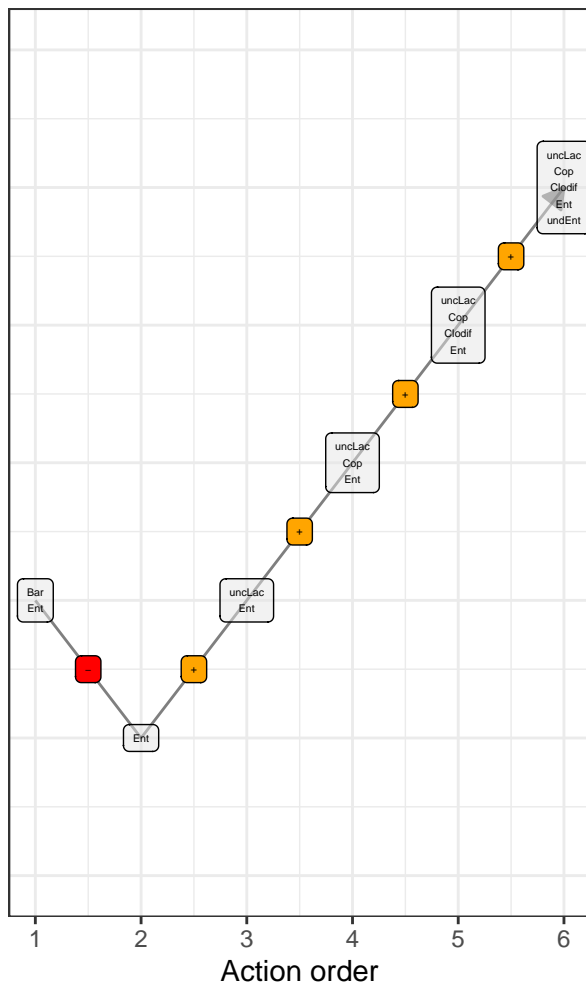
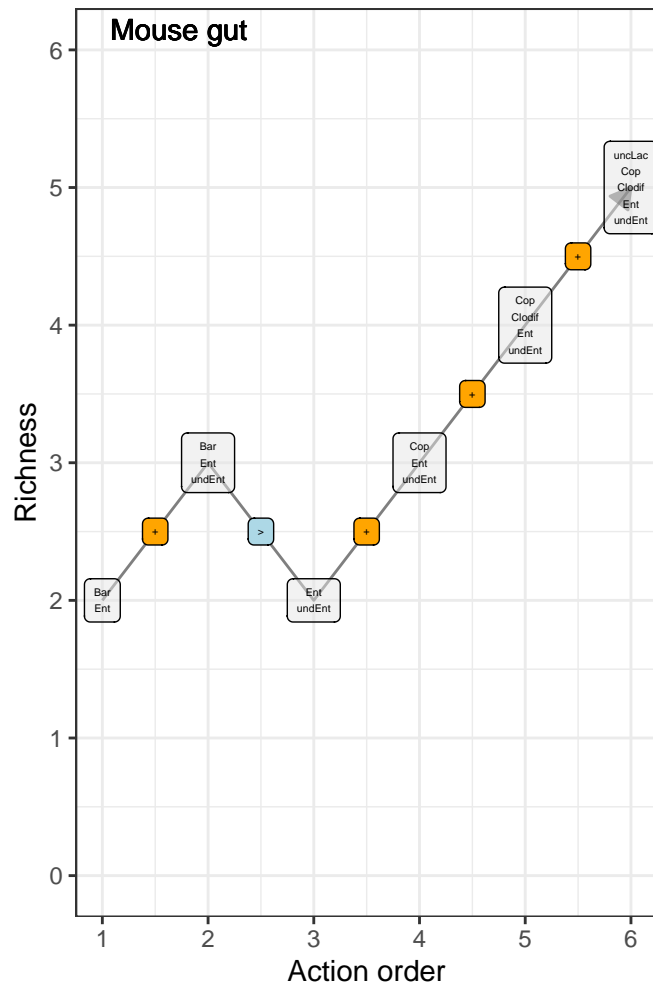
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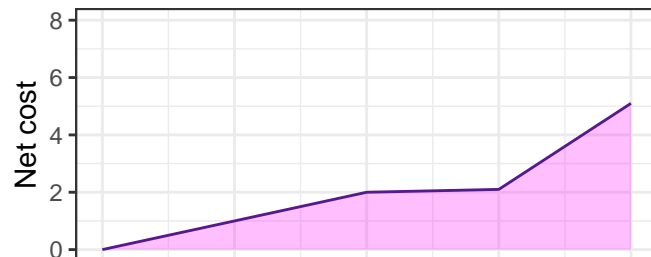
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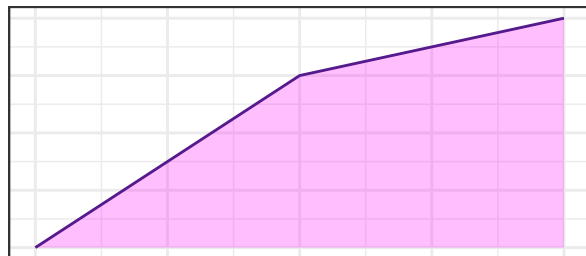
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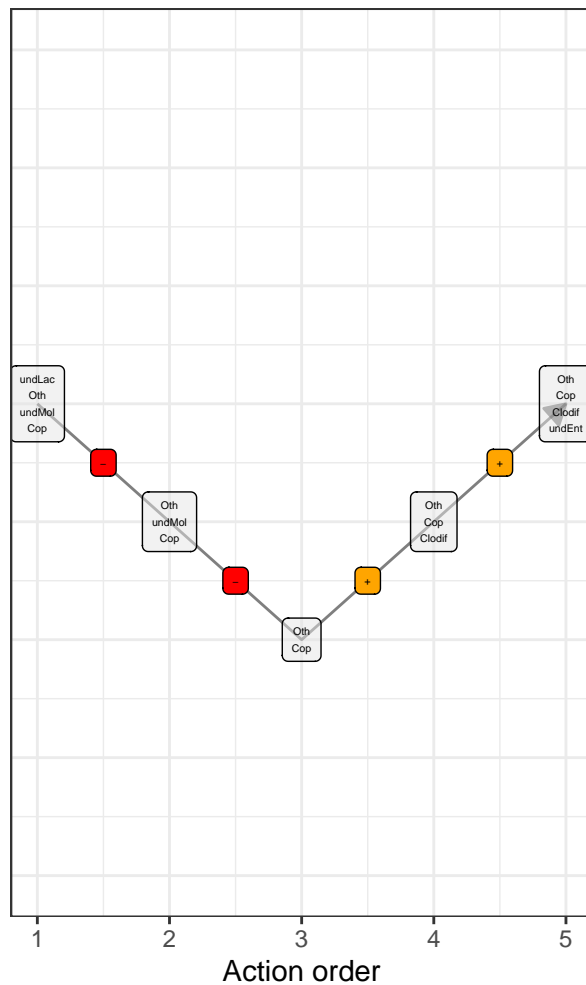
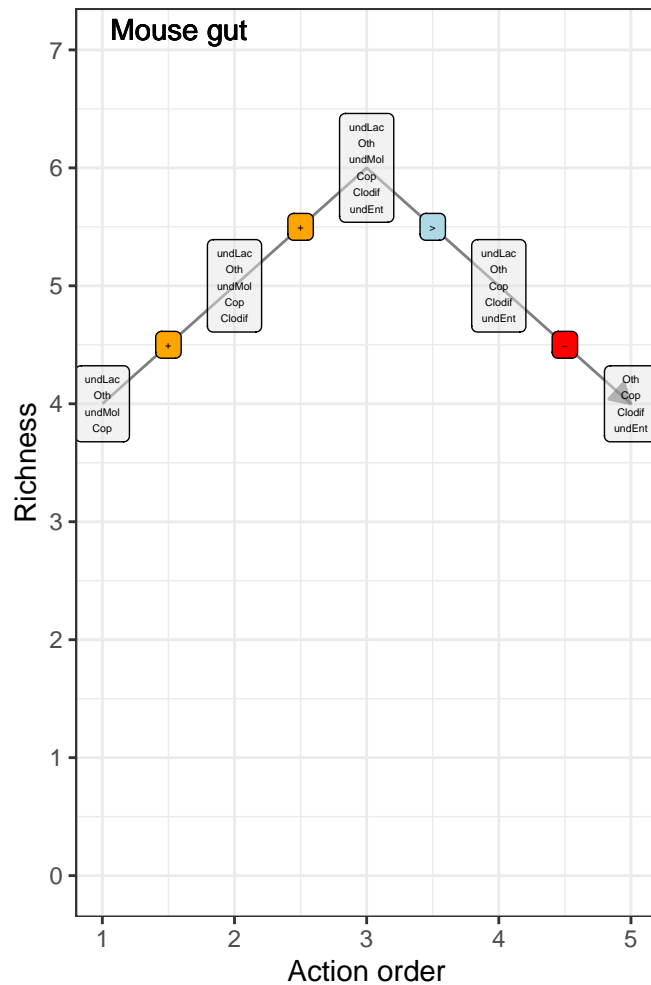
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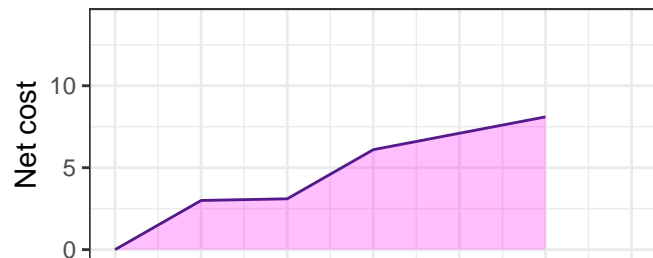
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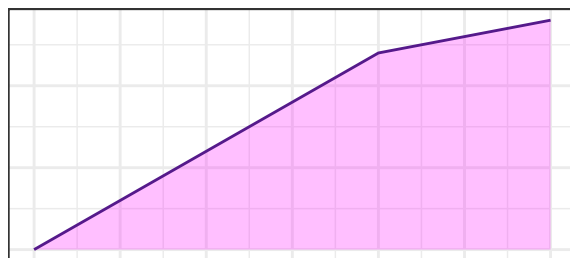
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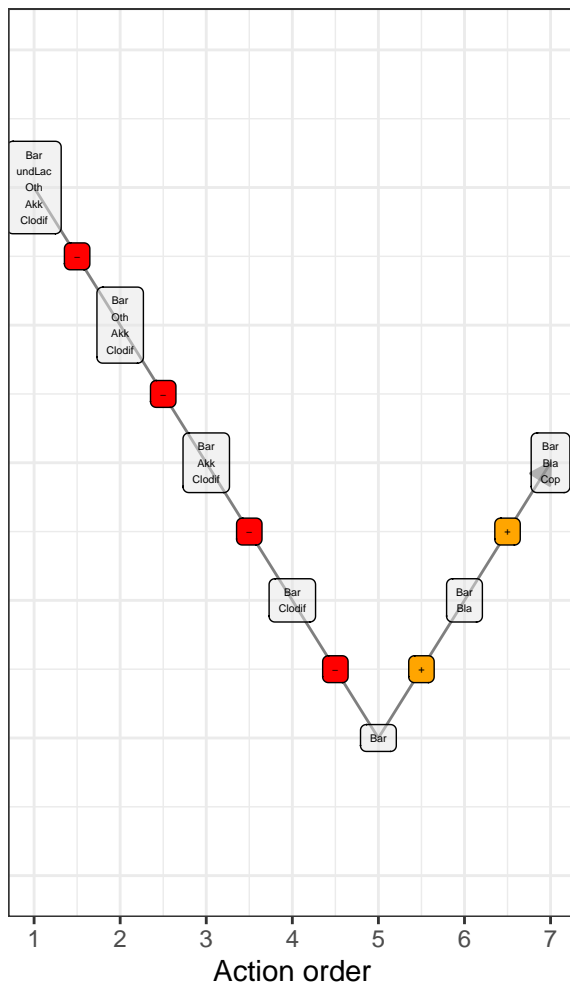
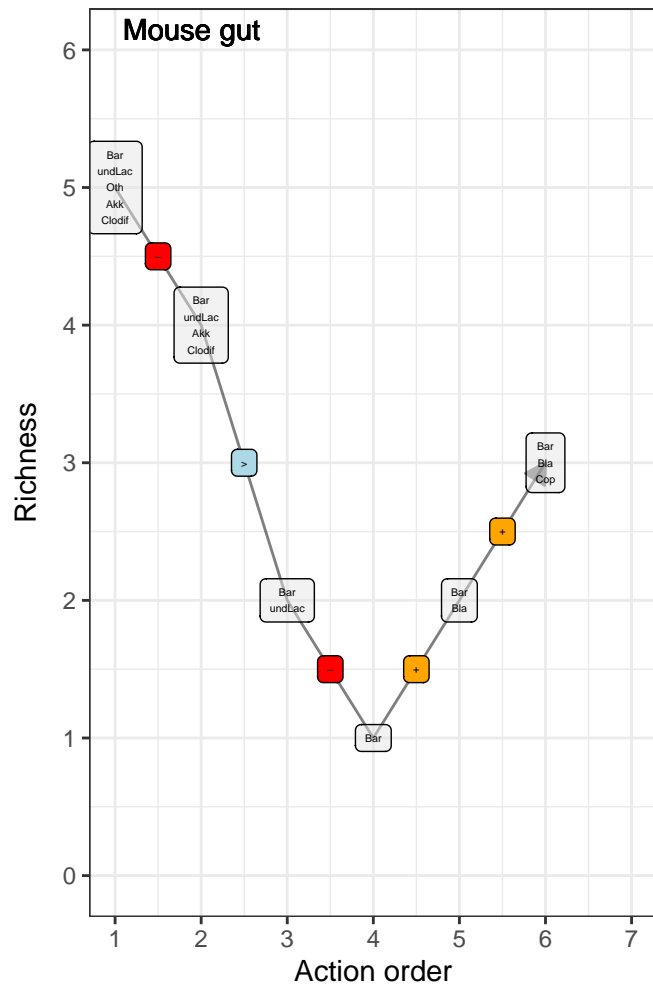
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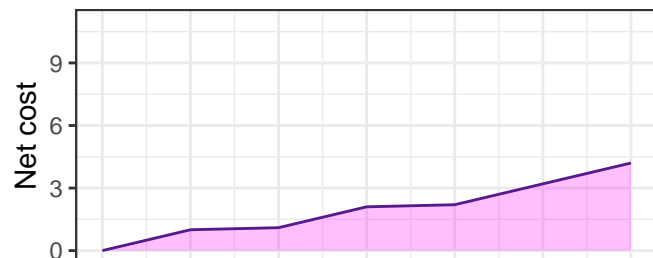
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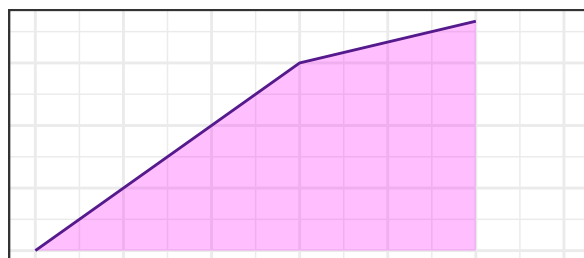
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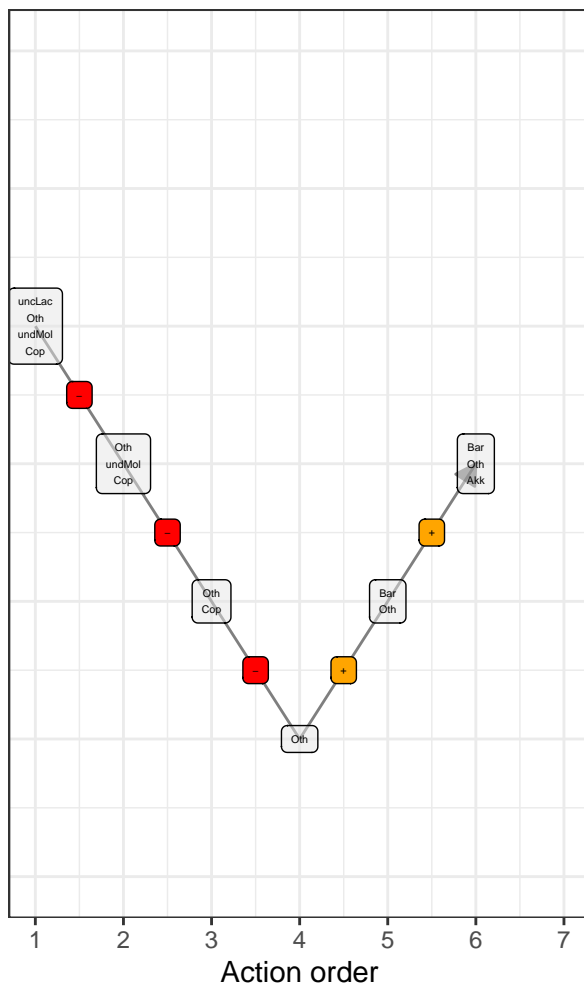
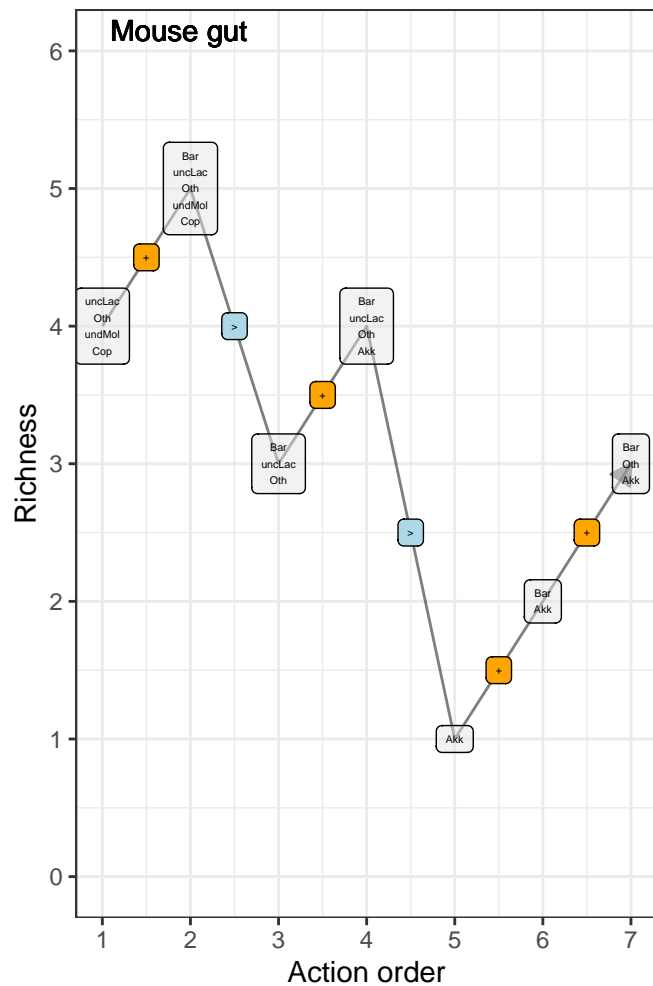
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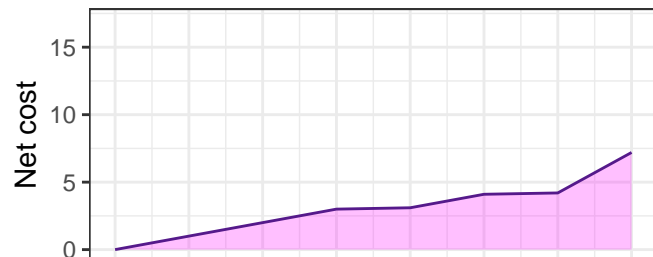
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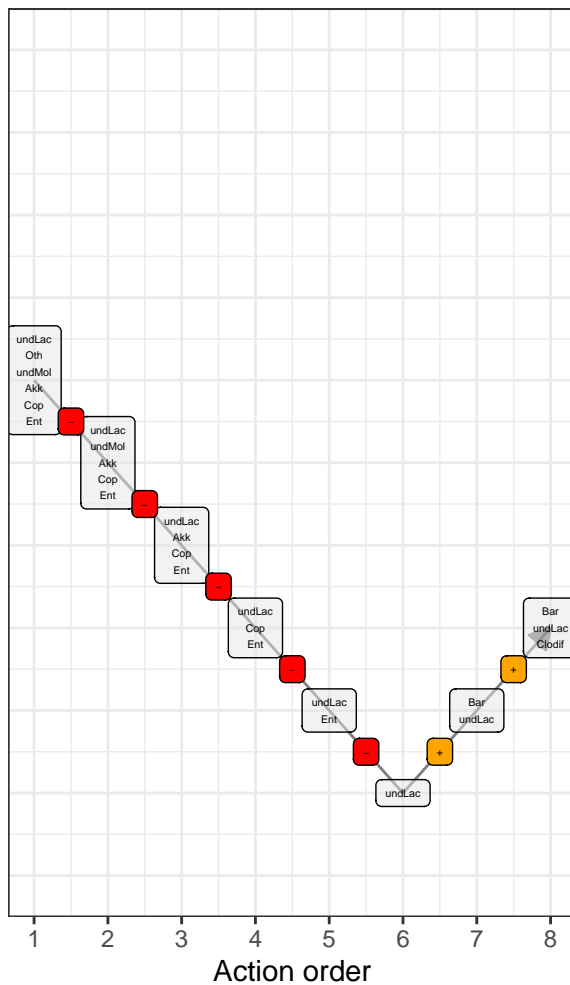
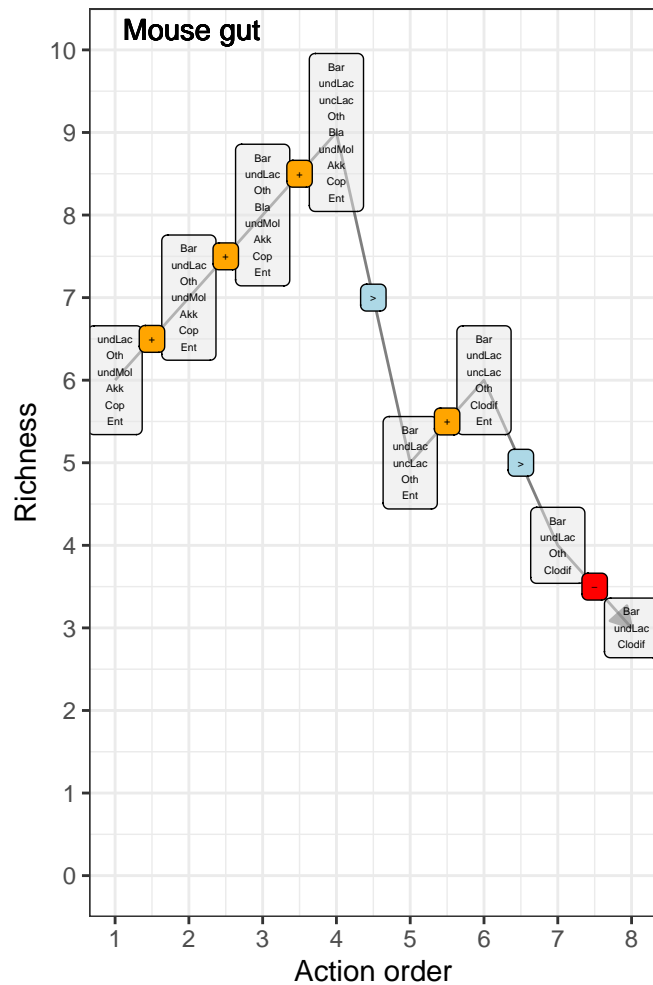
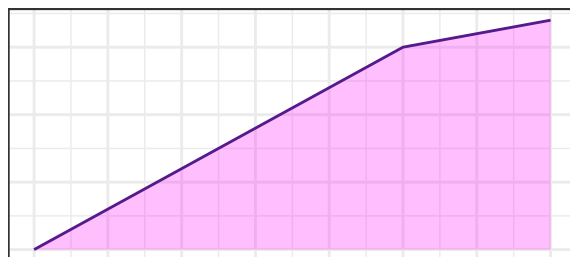
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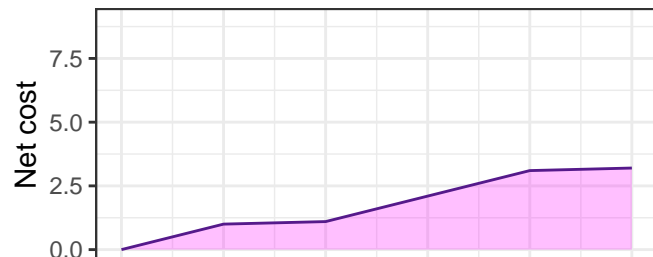
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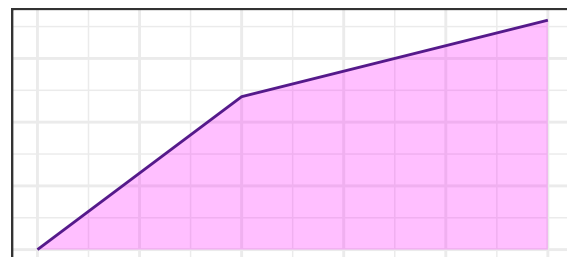
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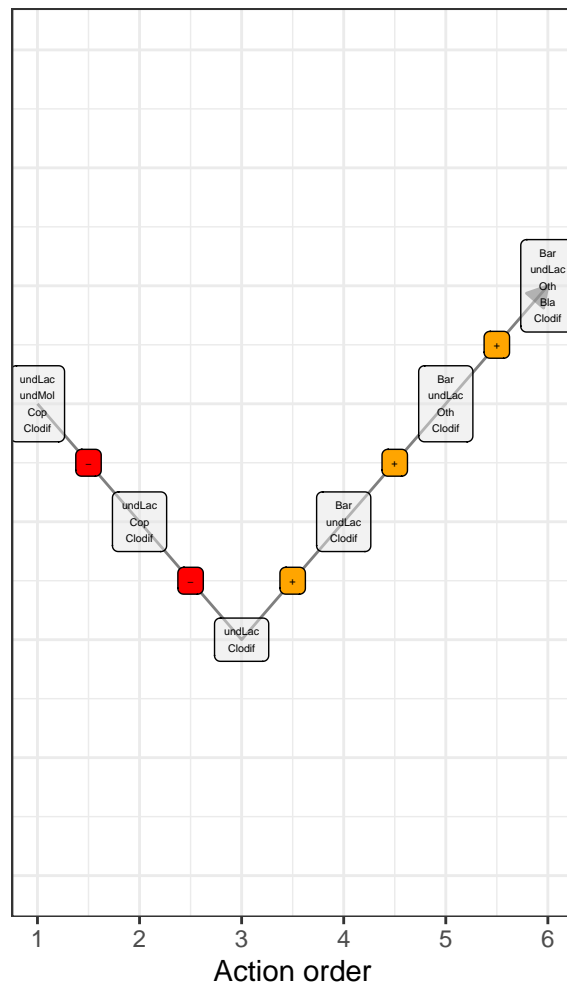
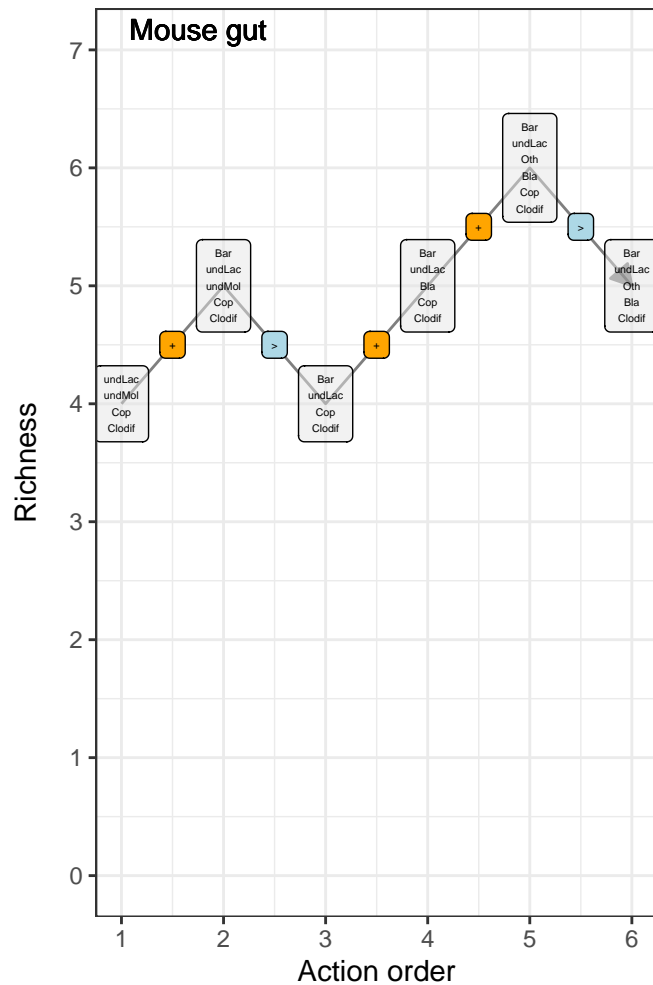
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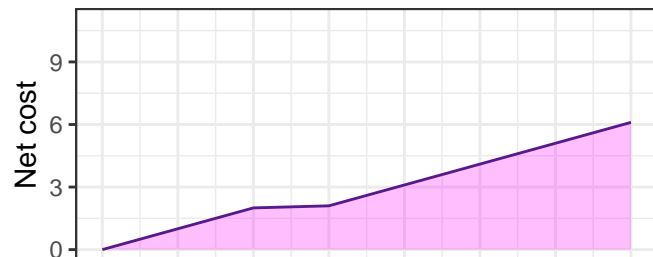
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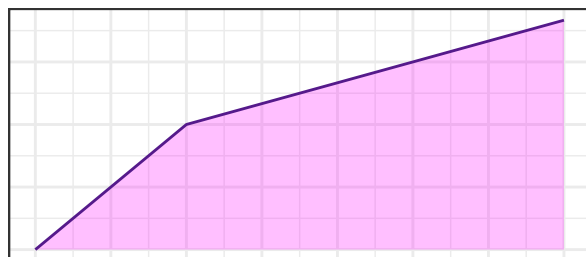
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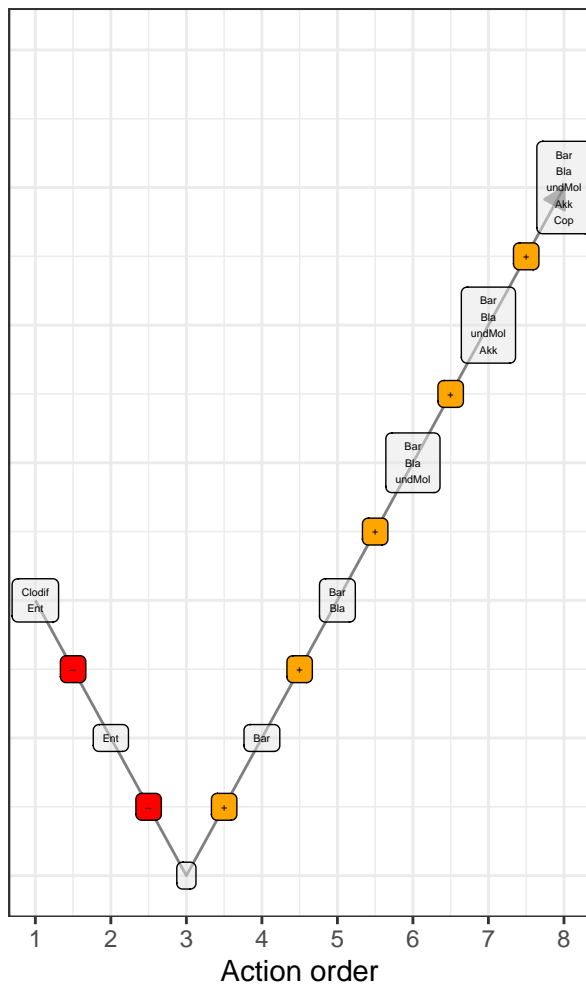
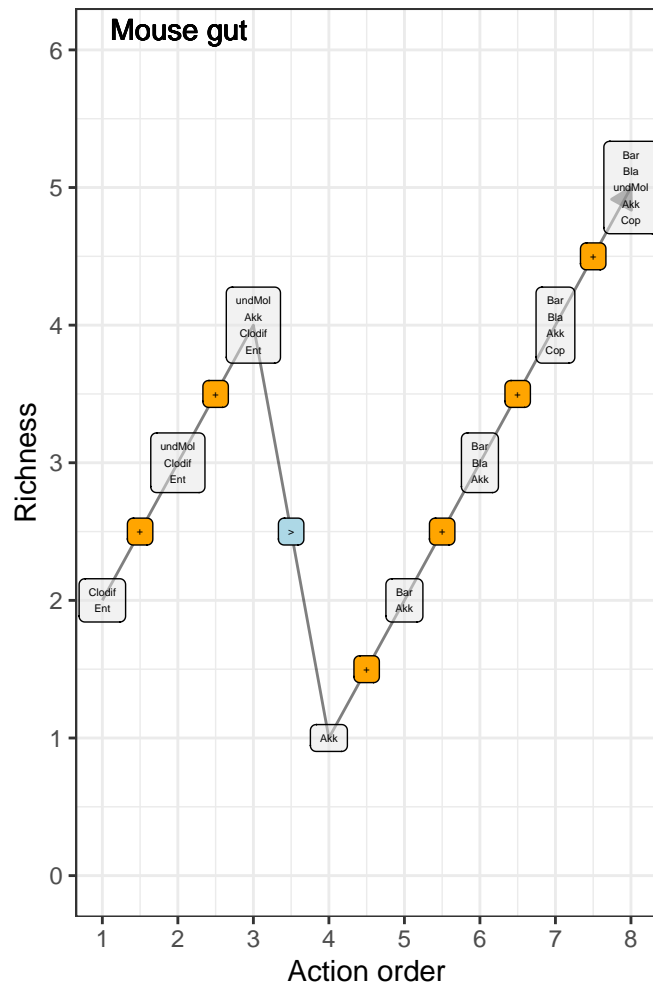
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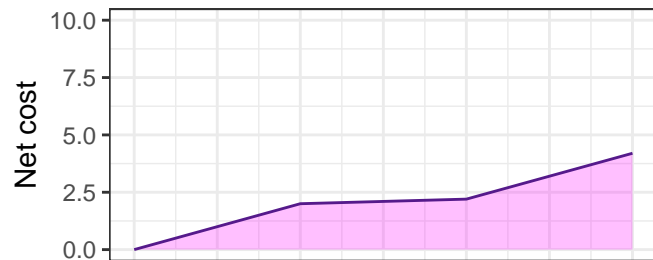
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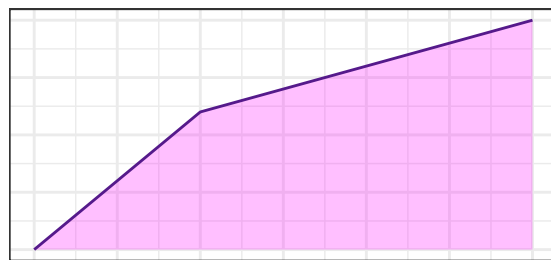
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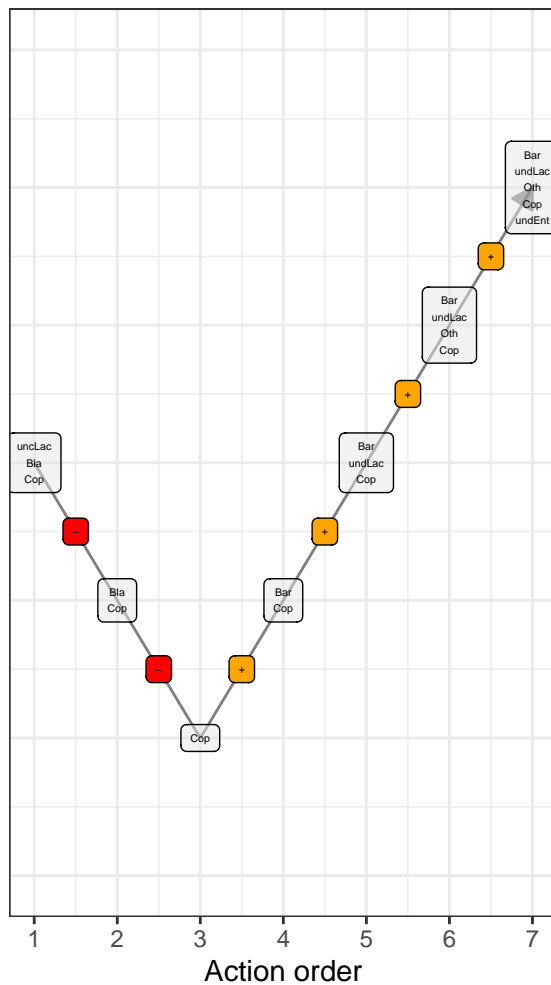
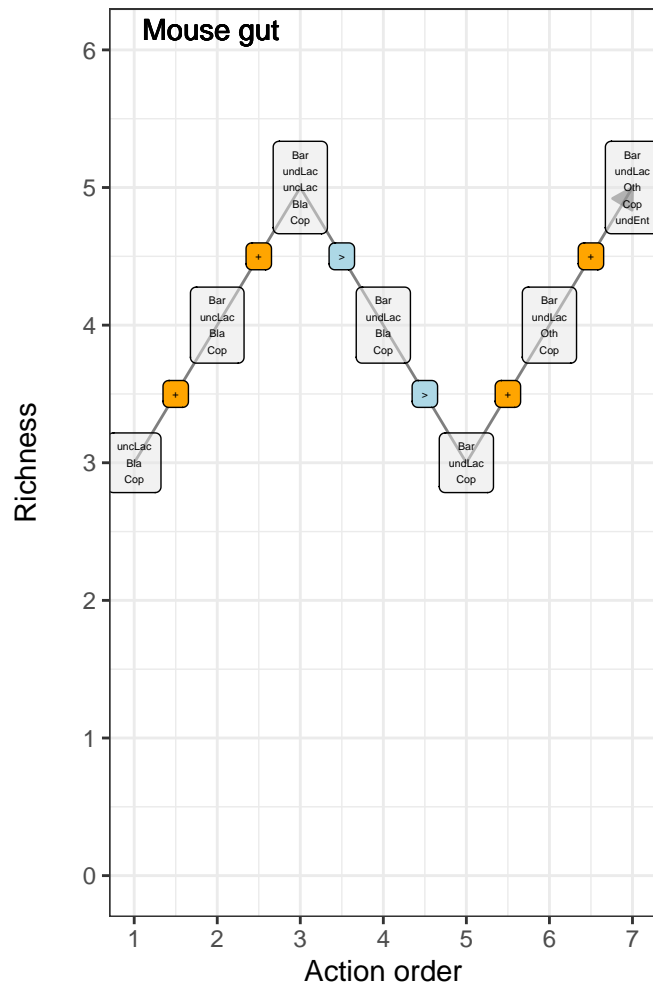
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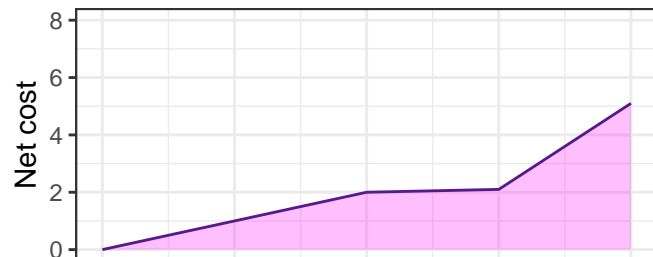
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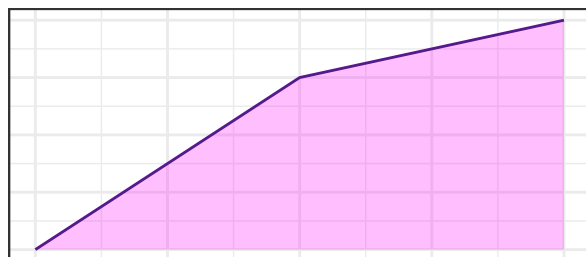
Mouse gut



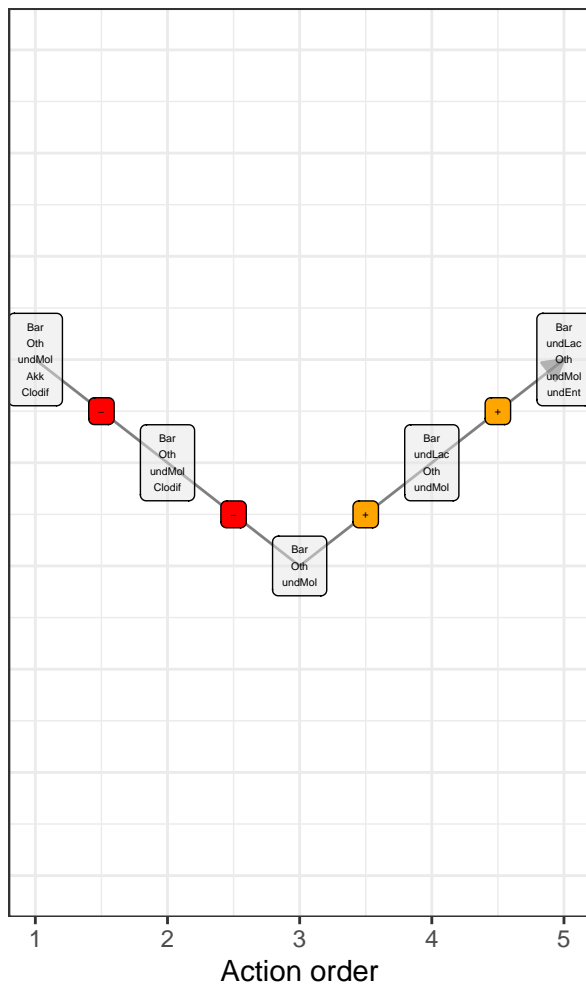
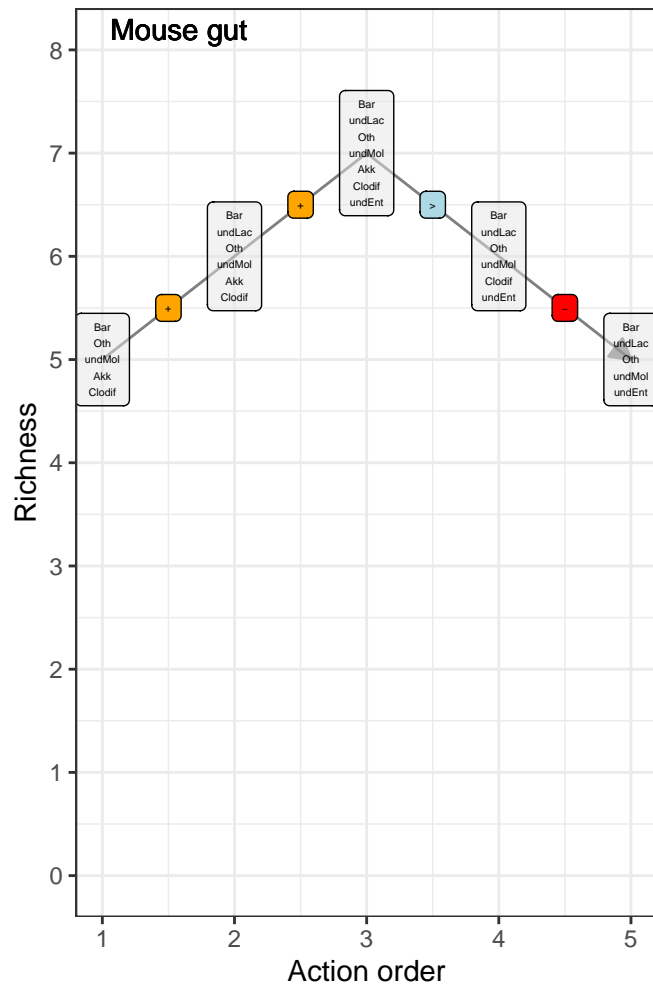
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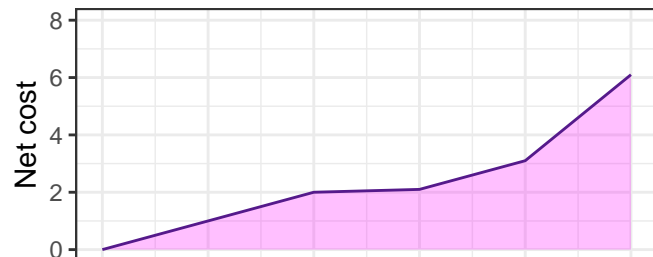
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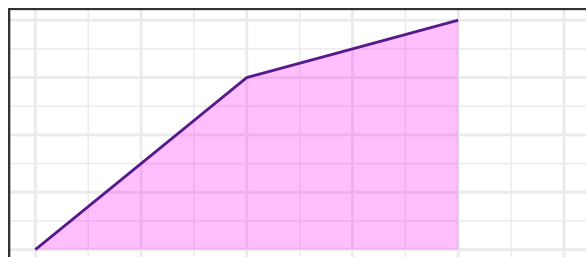
Mouse gut



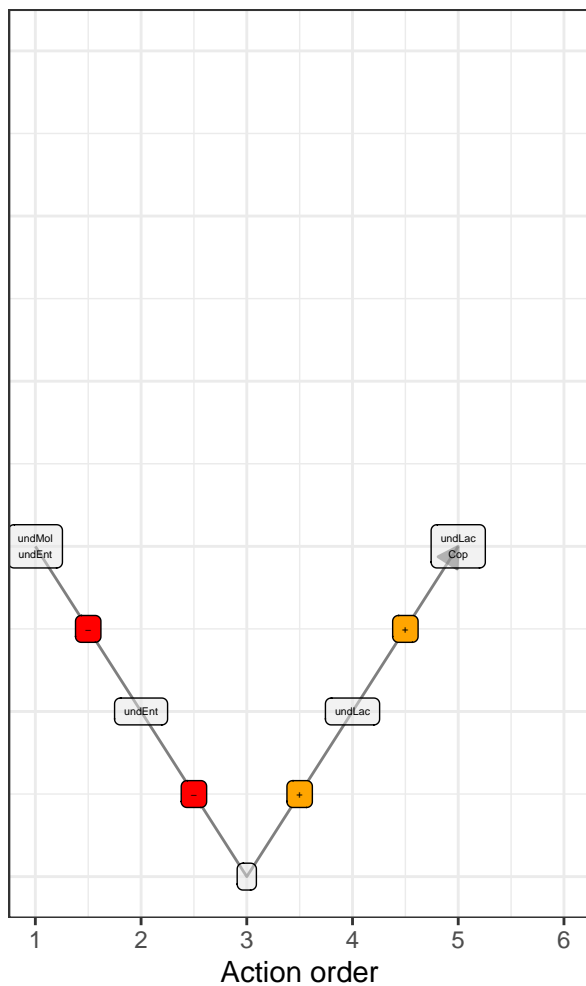
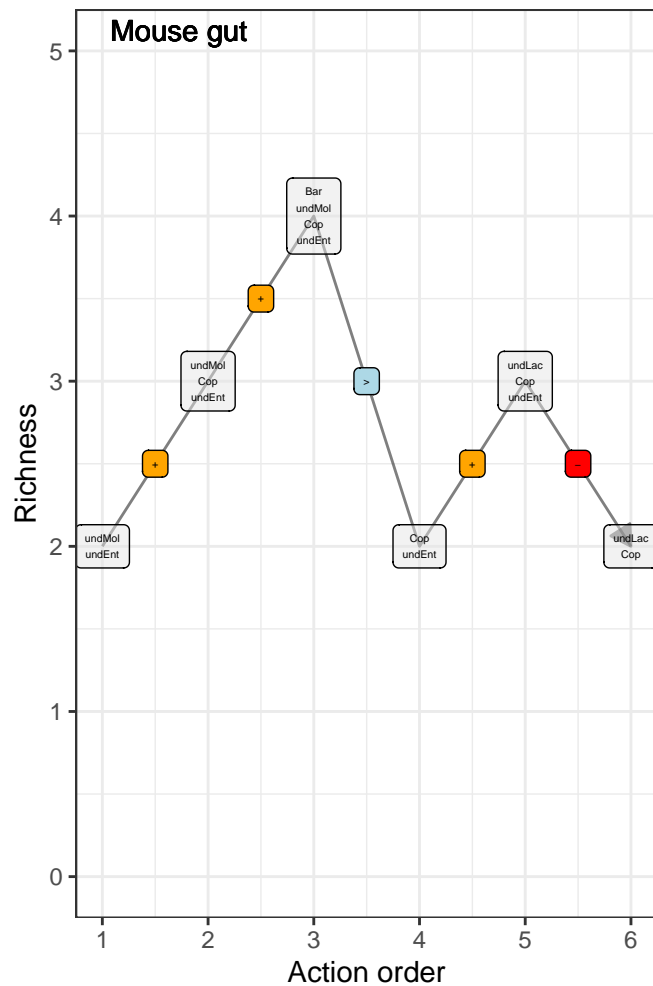
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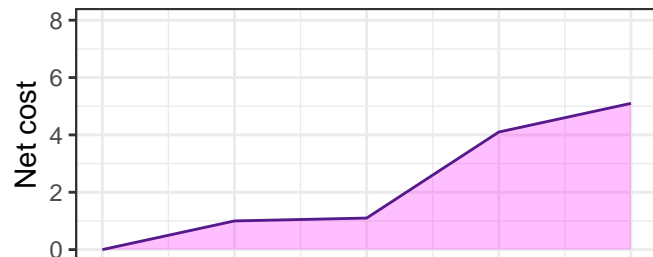
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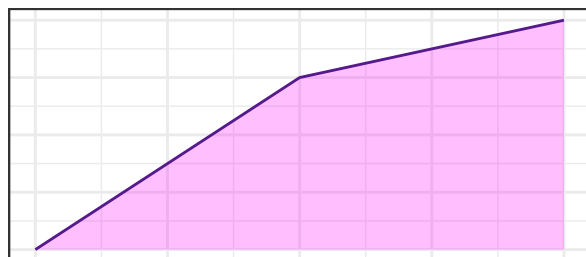
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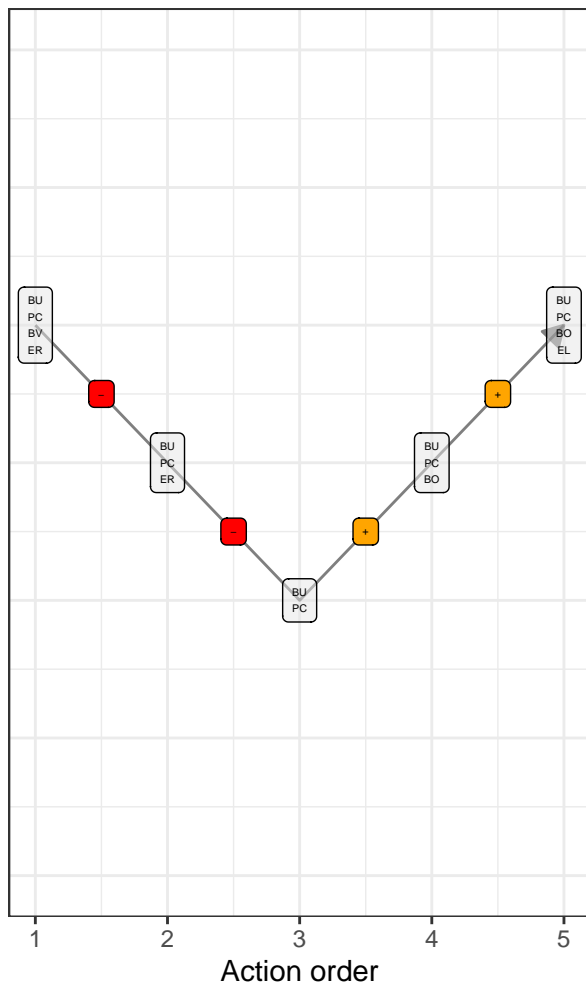
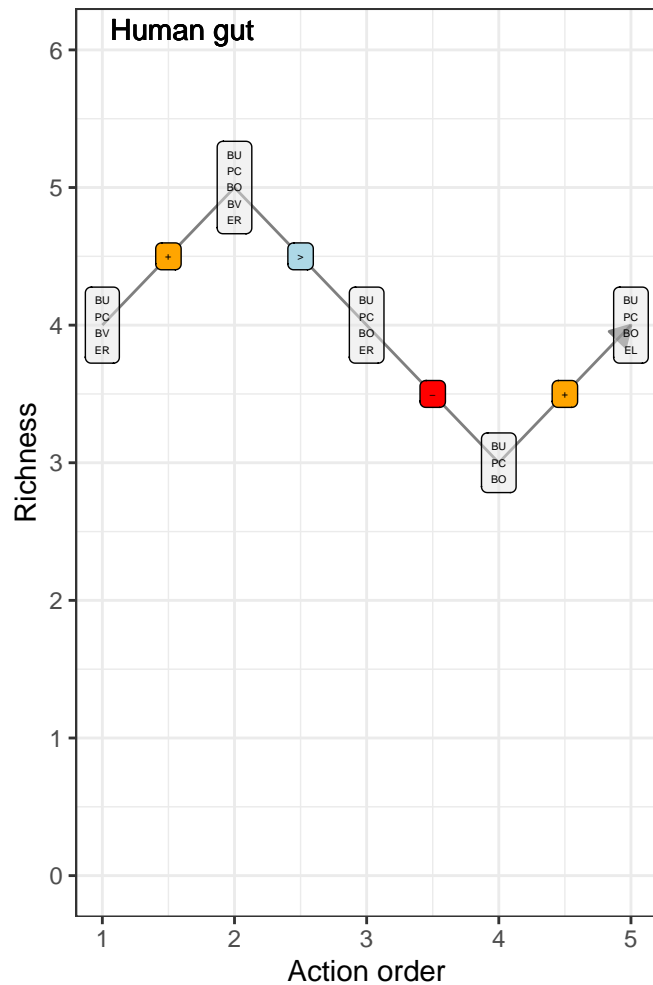
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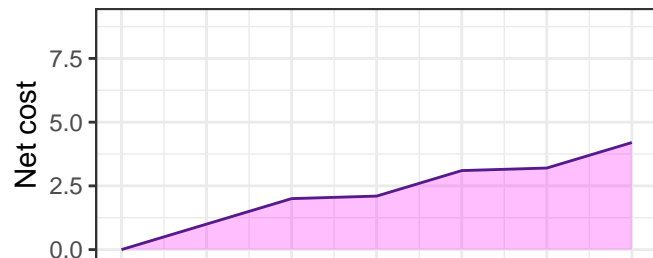
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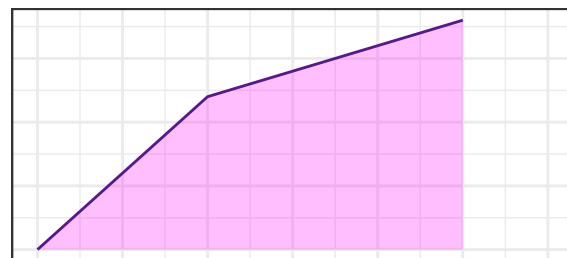
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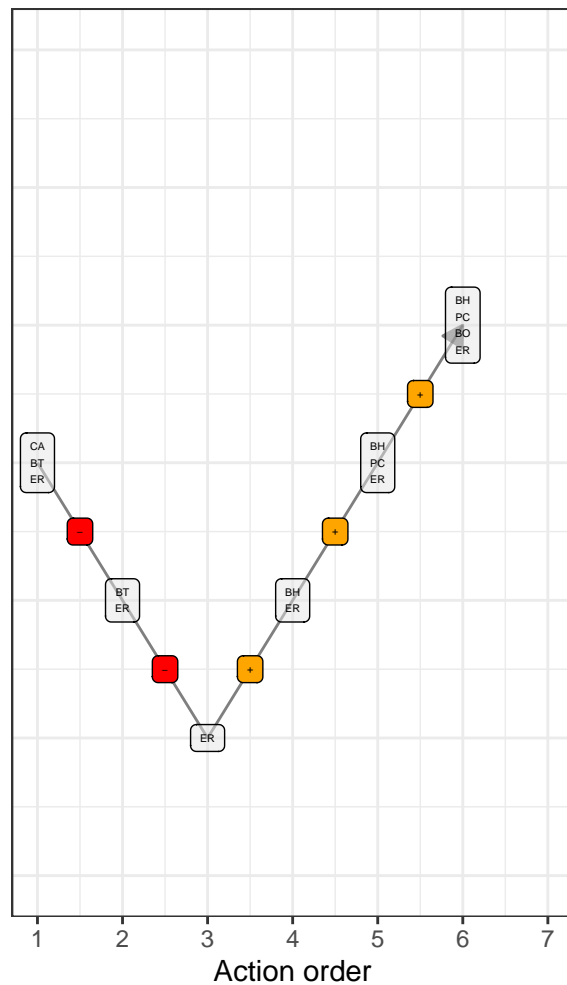
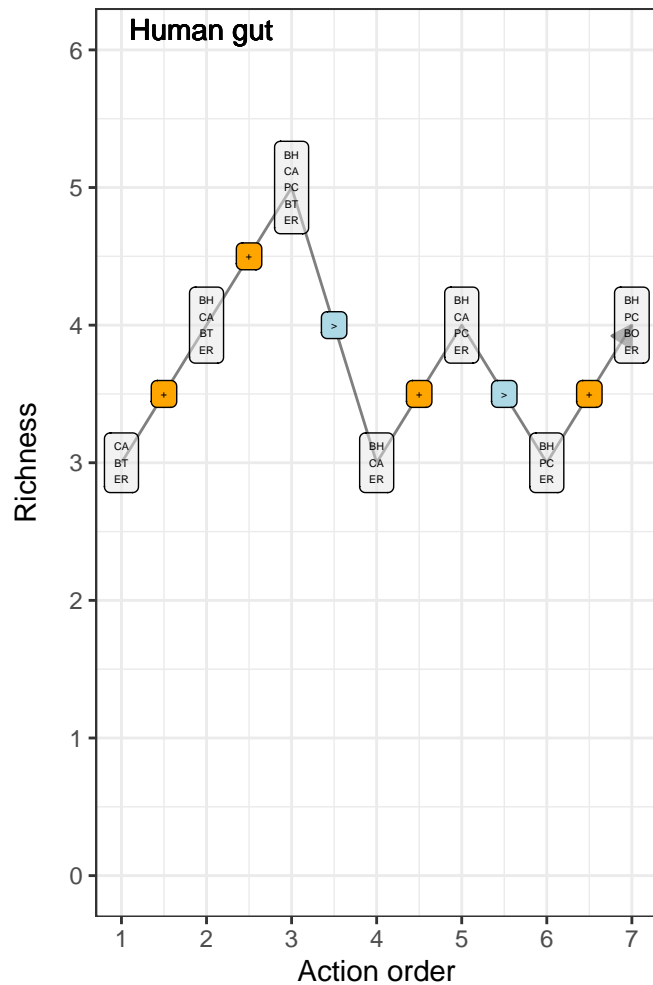
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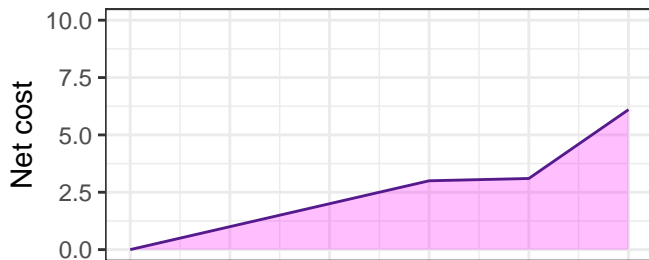
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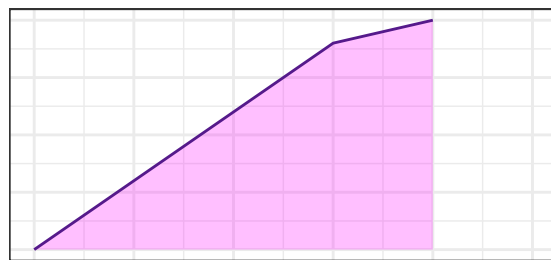
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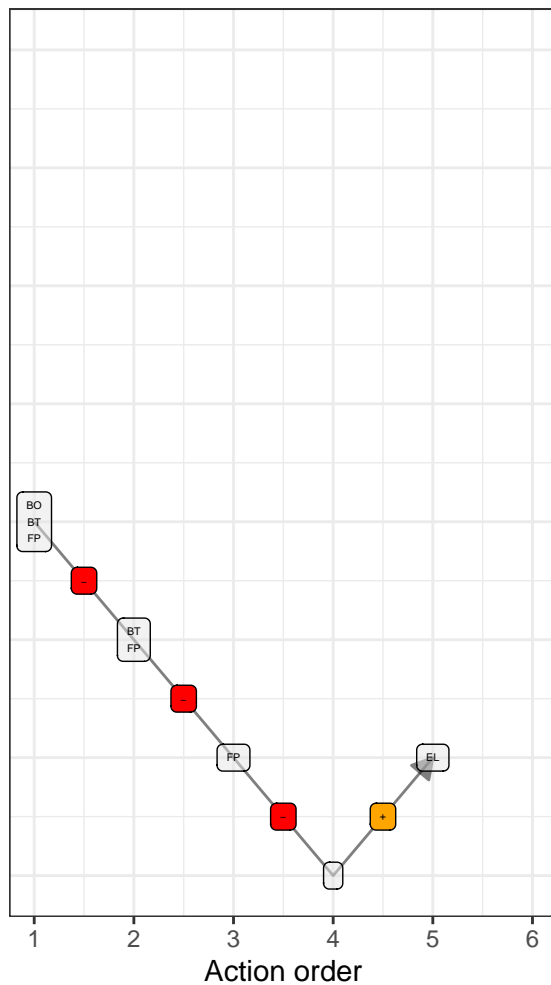
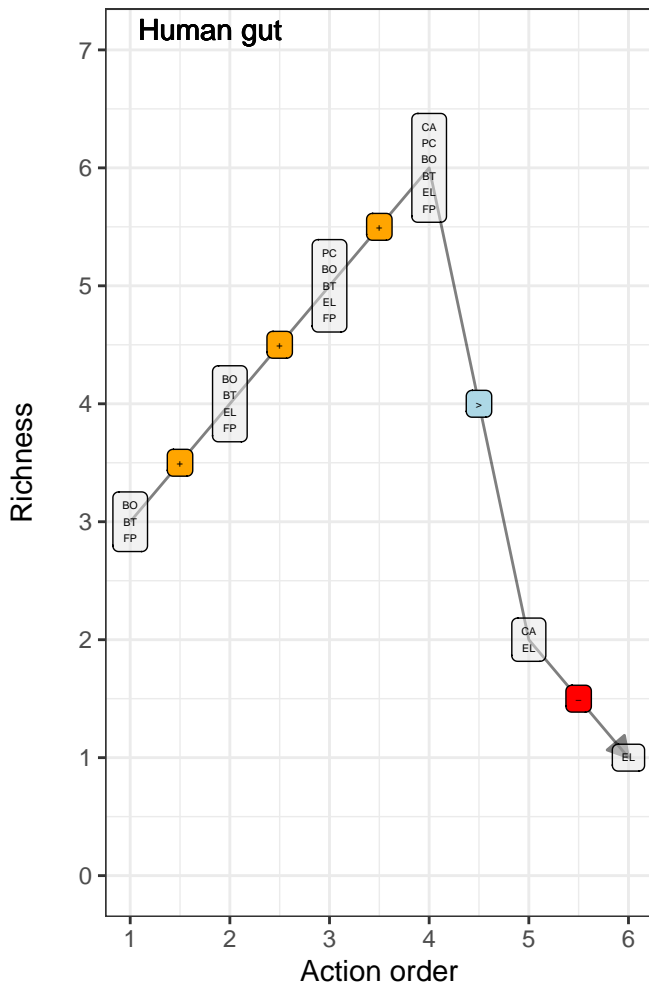
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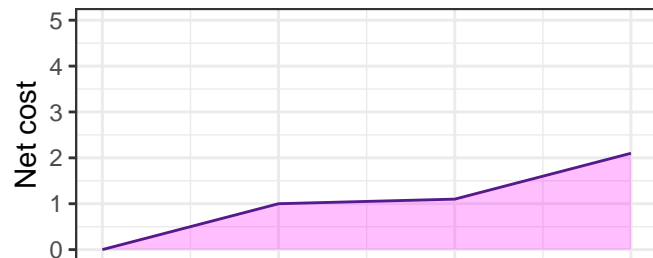
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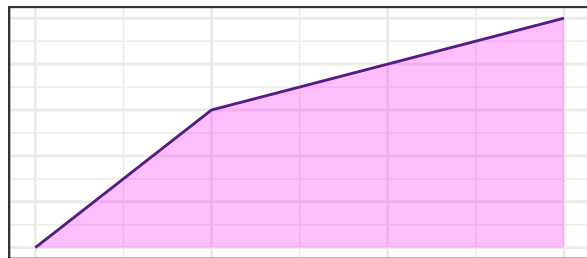
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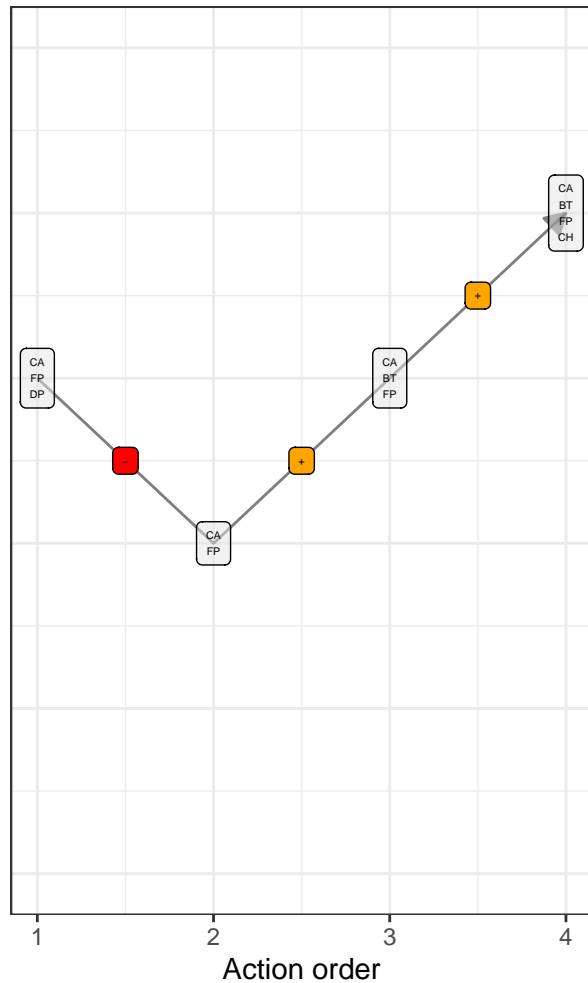
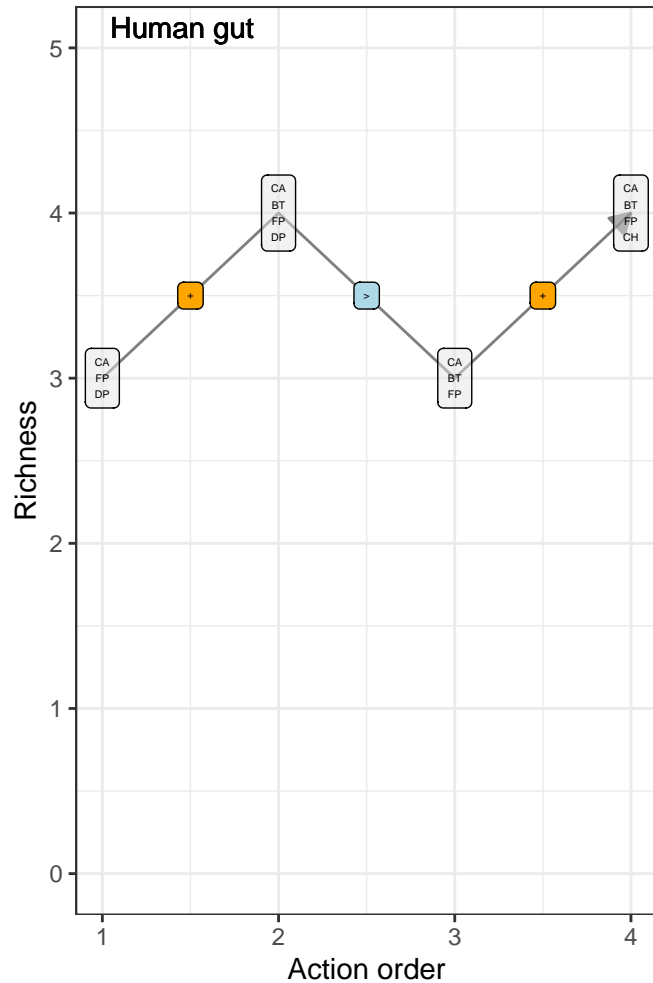
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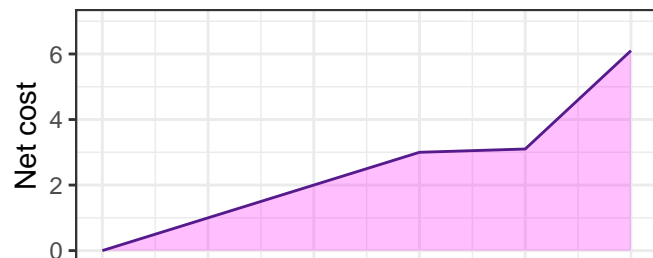
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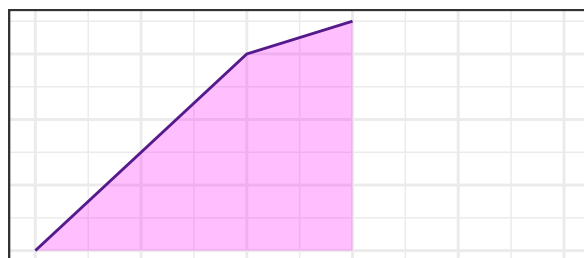
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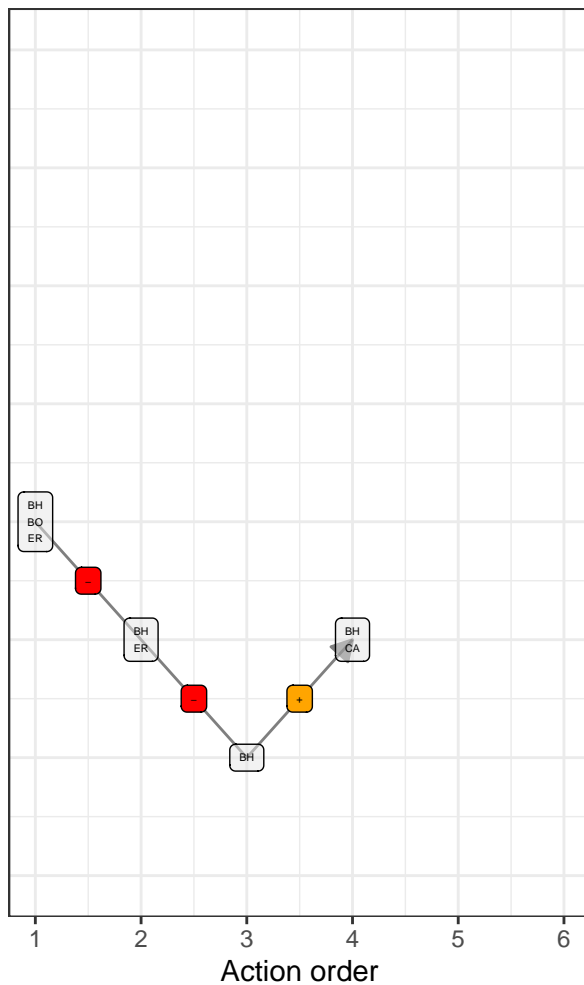
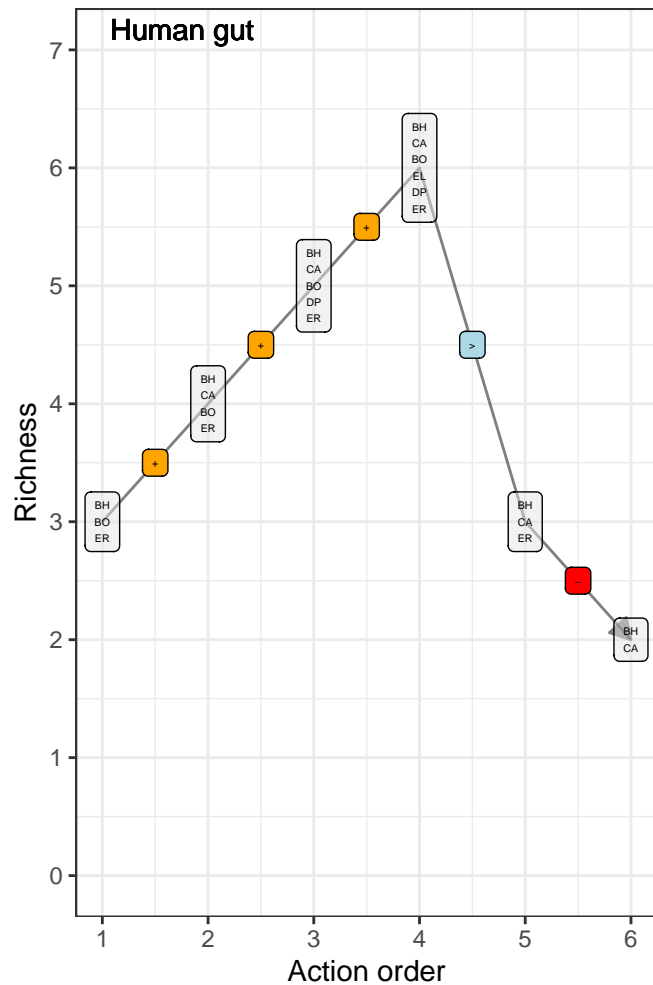
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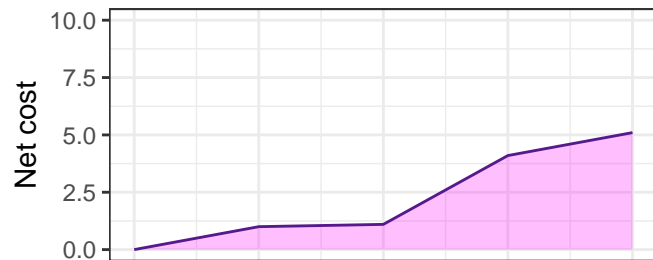
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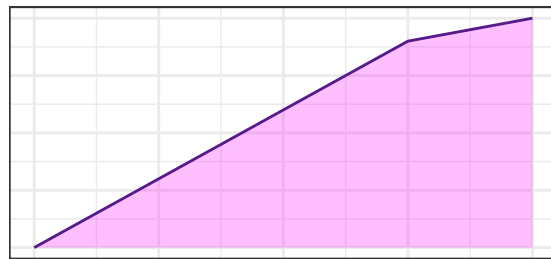
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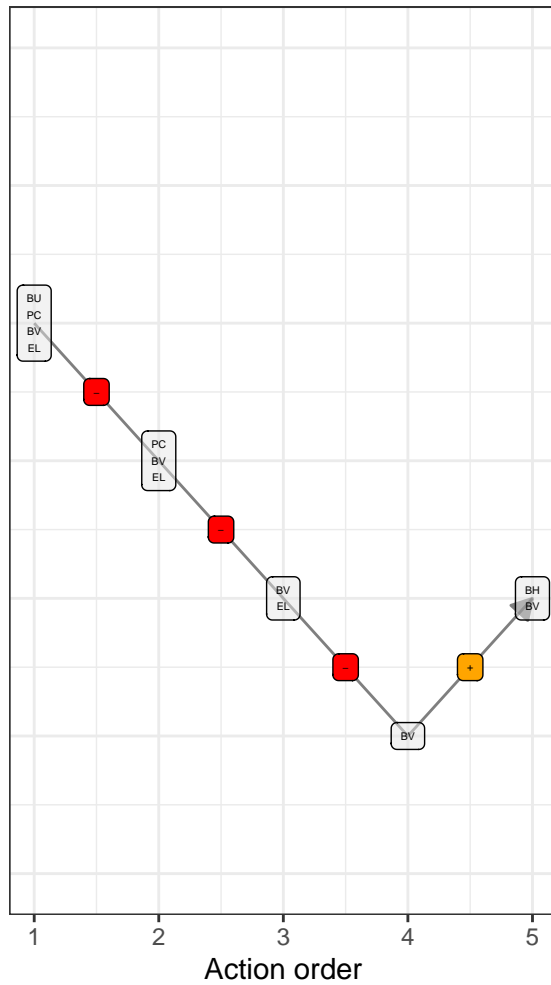
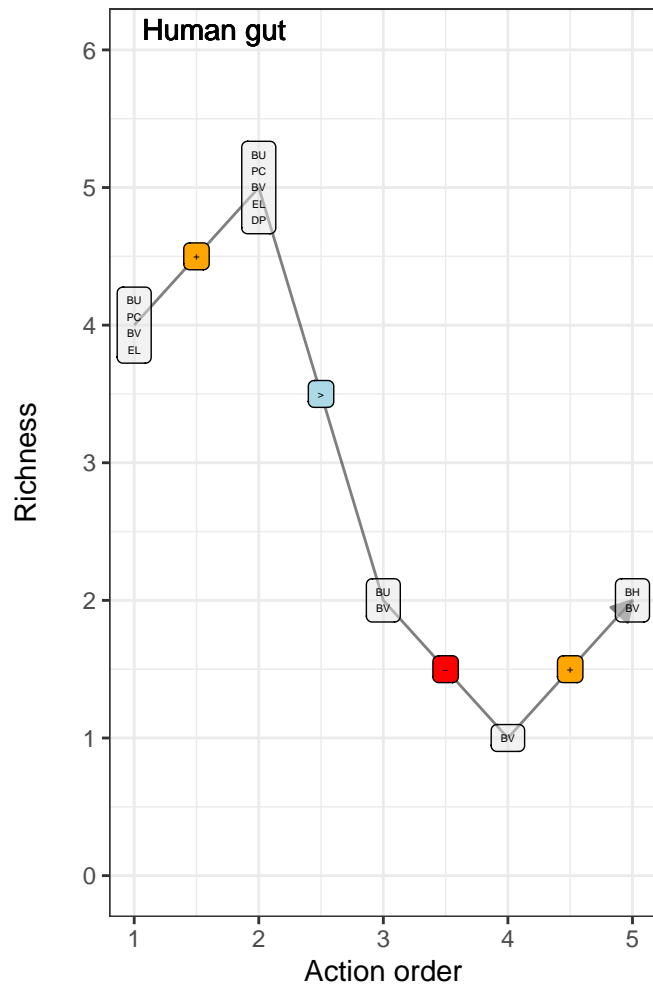
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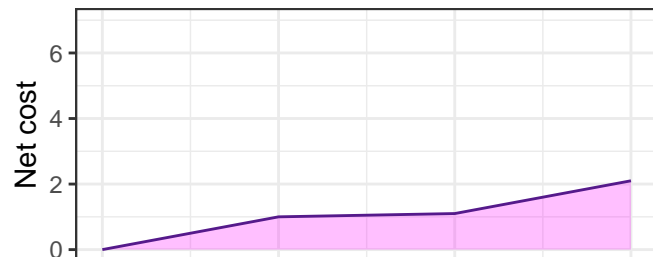
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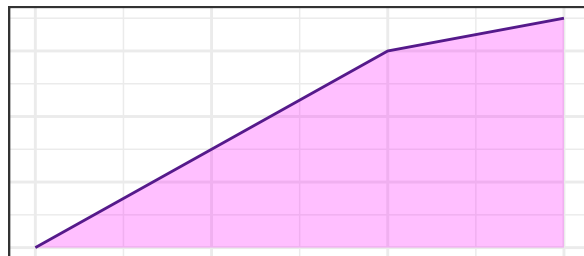
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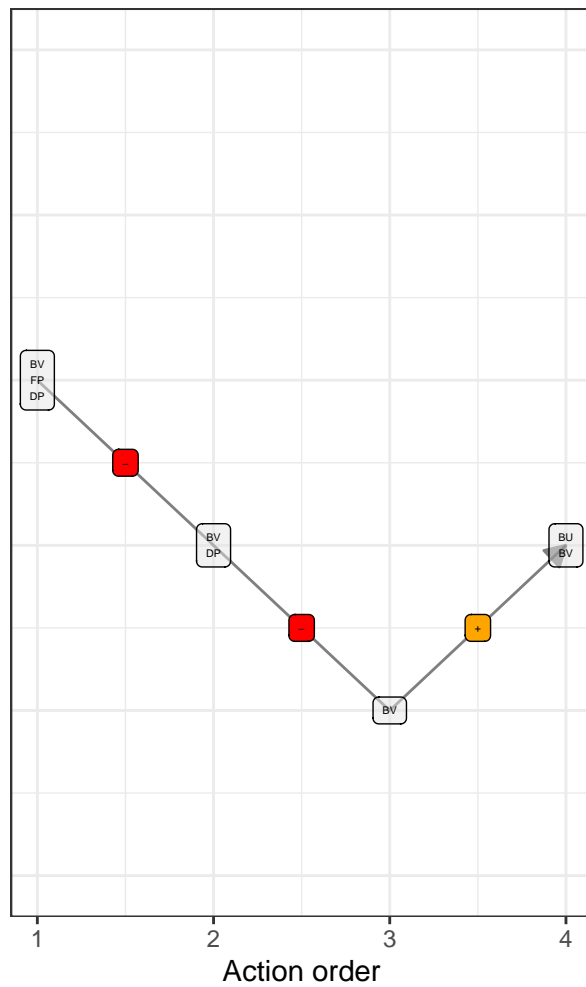
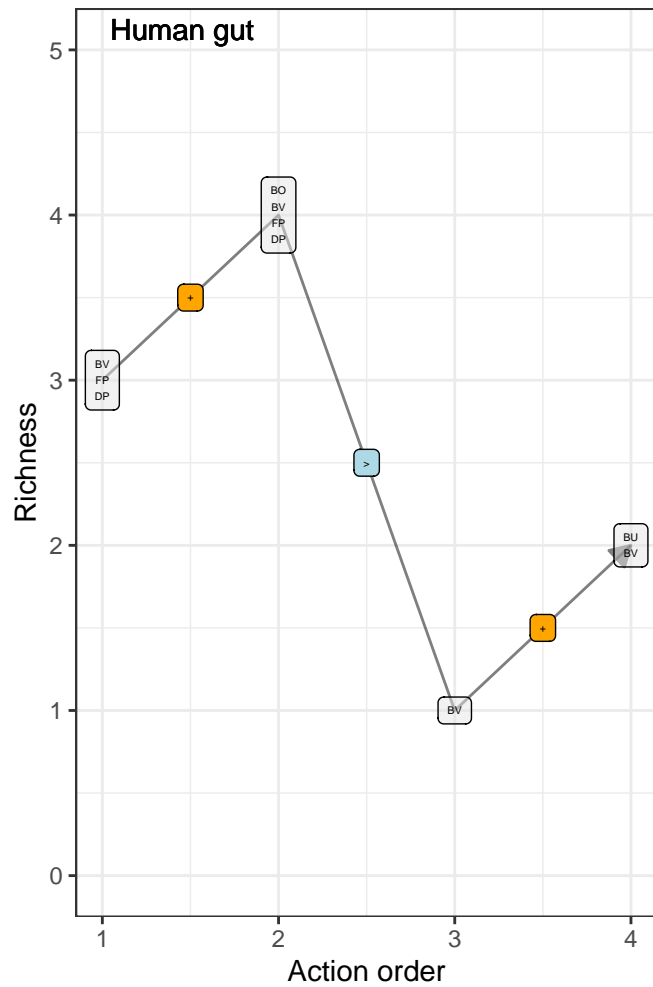
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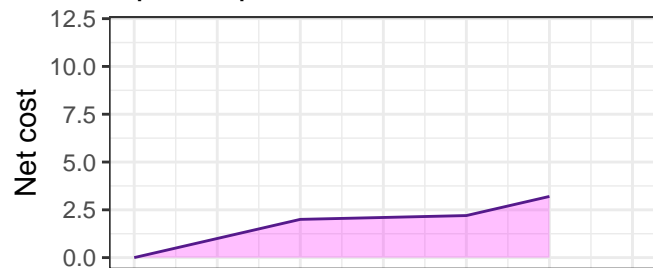
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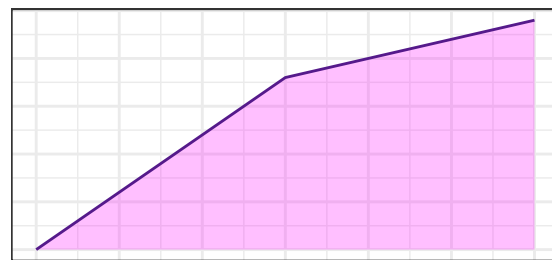
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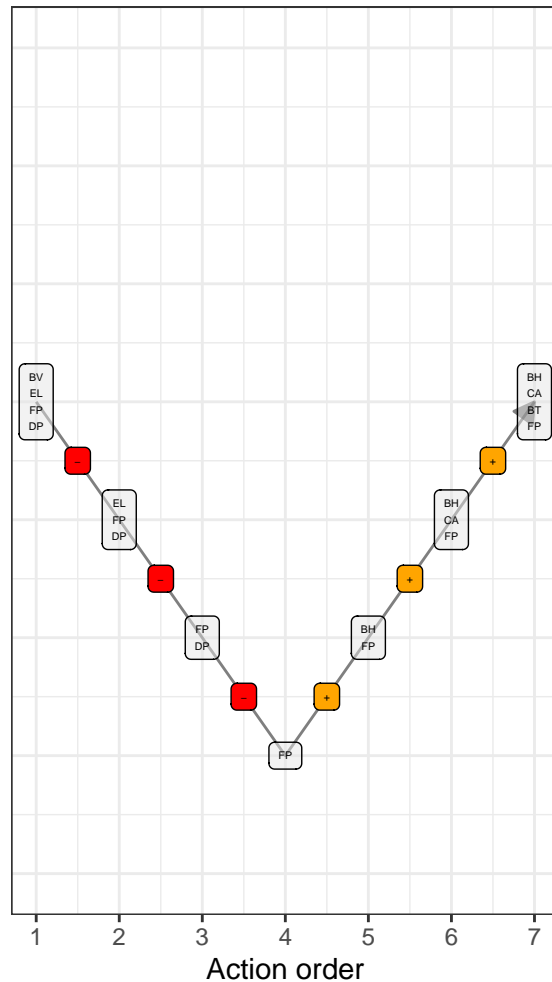
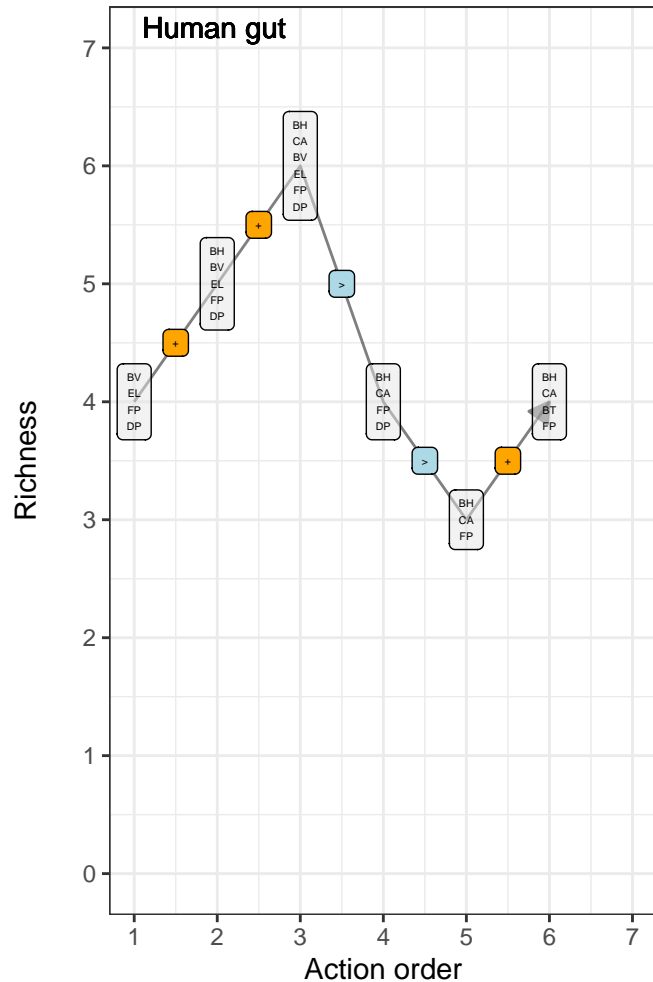
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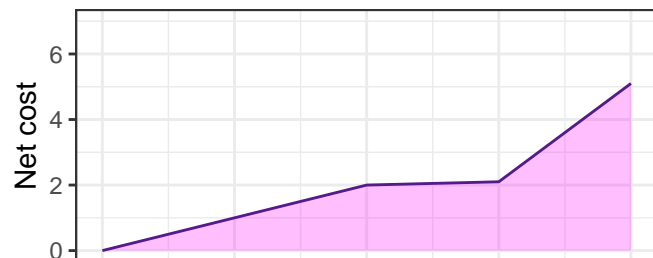
Nominal path



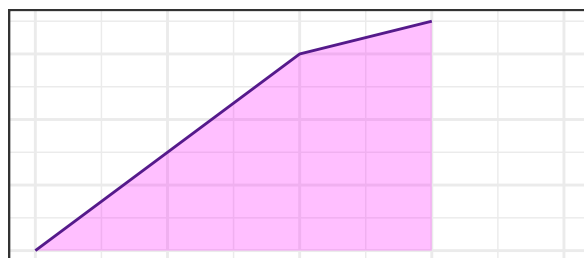
Human gut



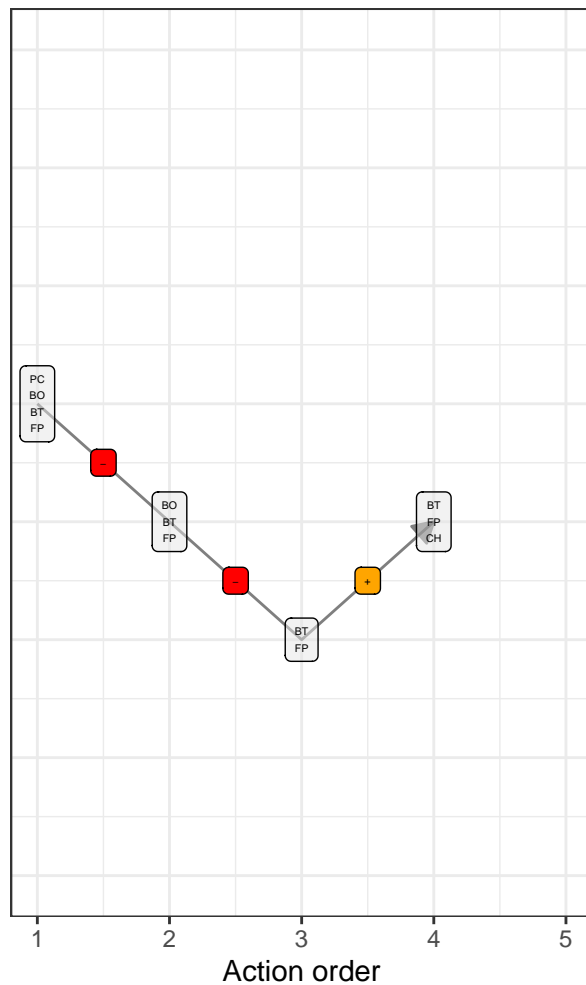
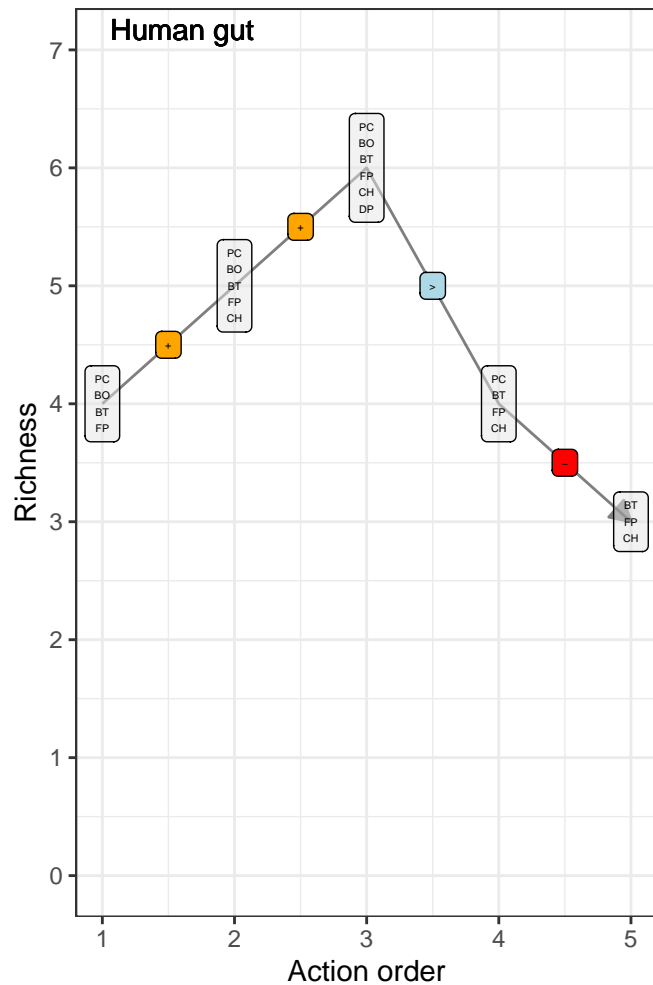
Optimal path



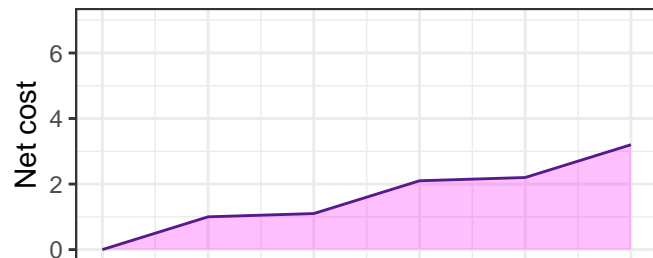
Nominal path



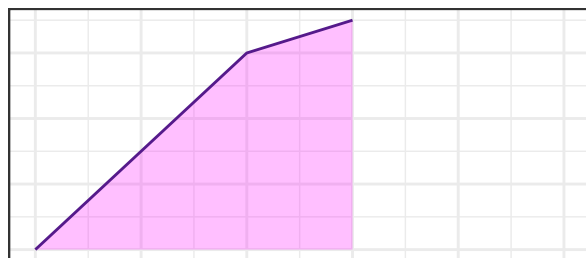
Human gut



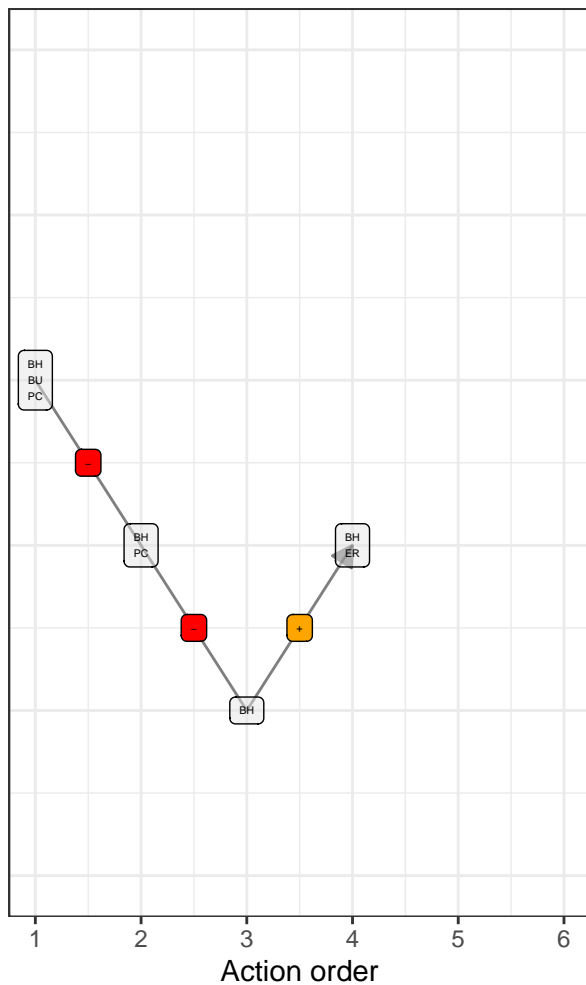
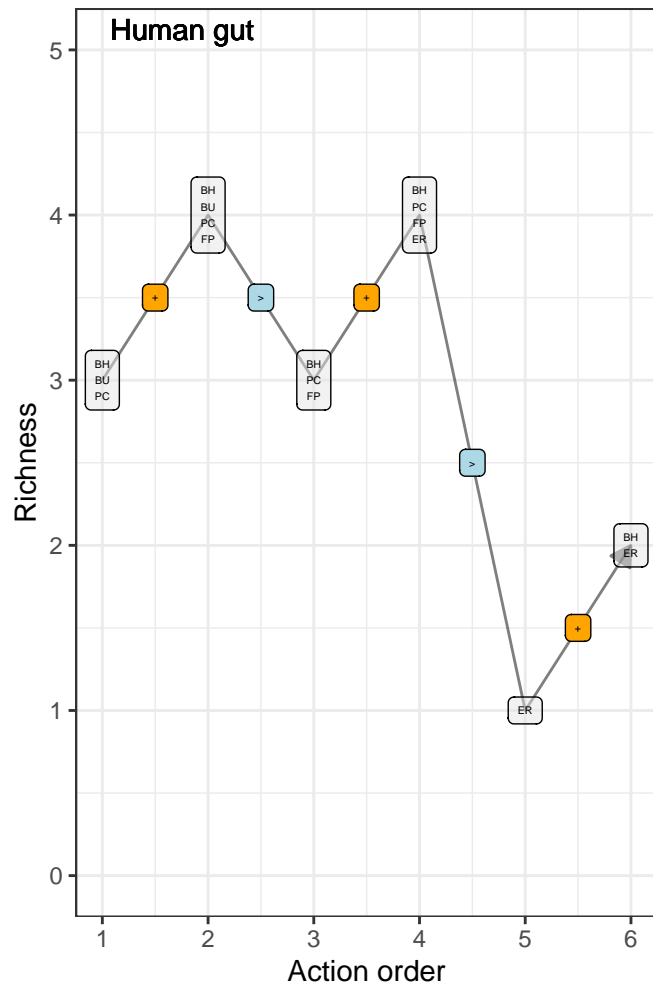
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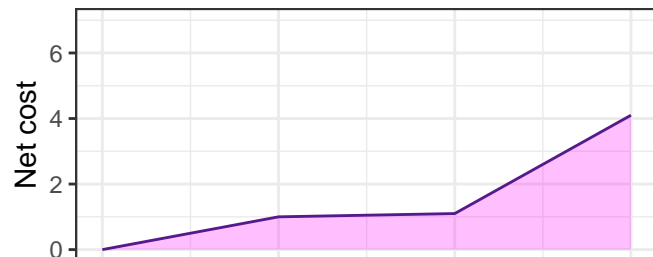
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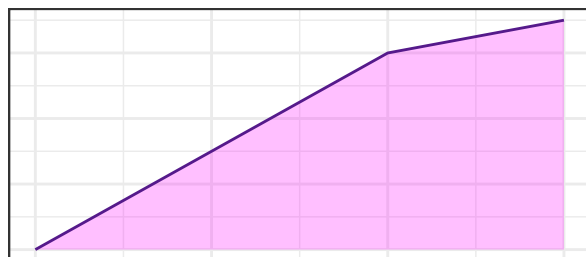
Human gut



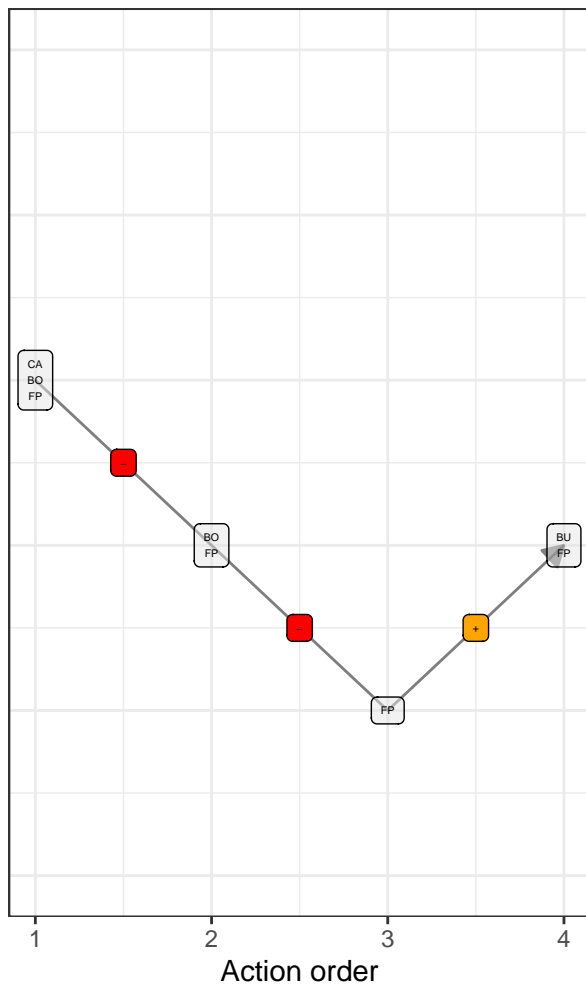
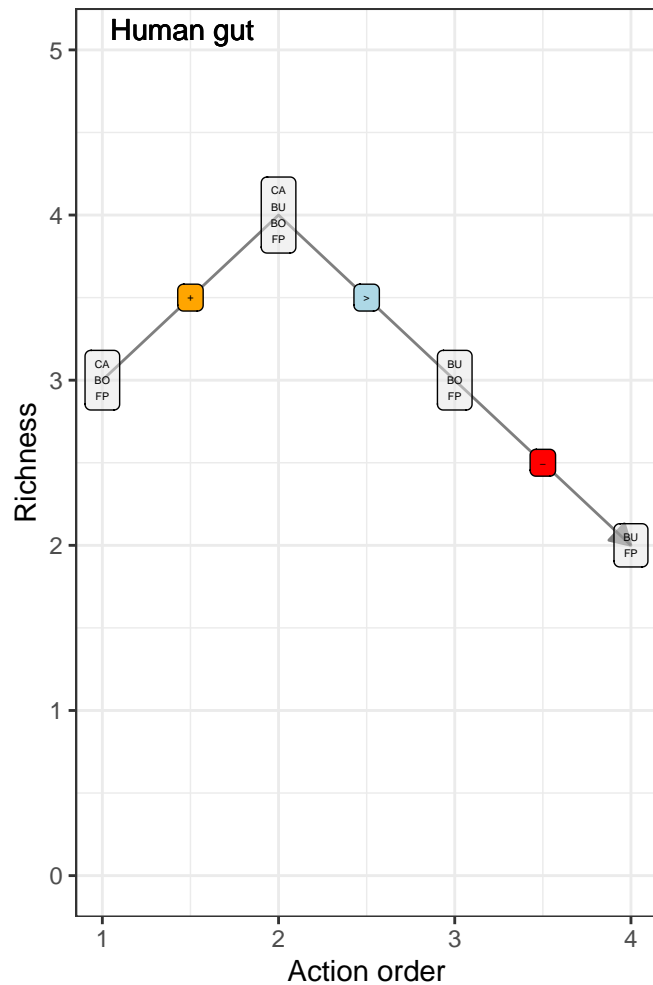
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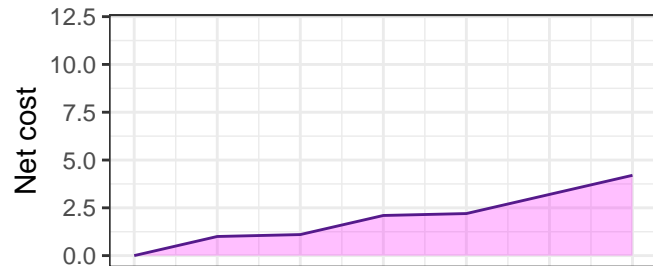
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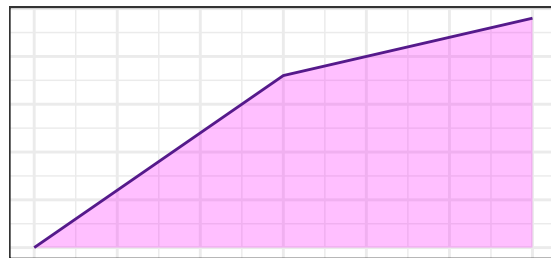
Human gut



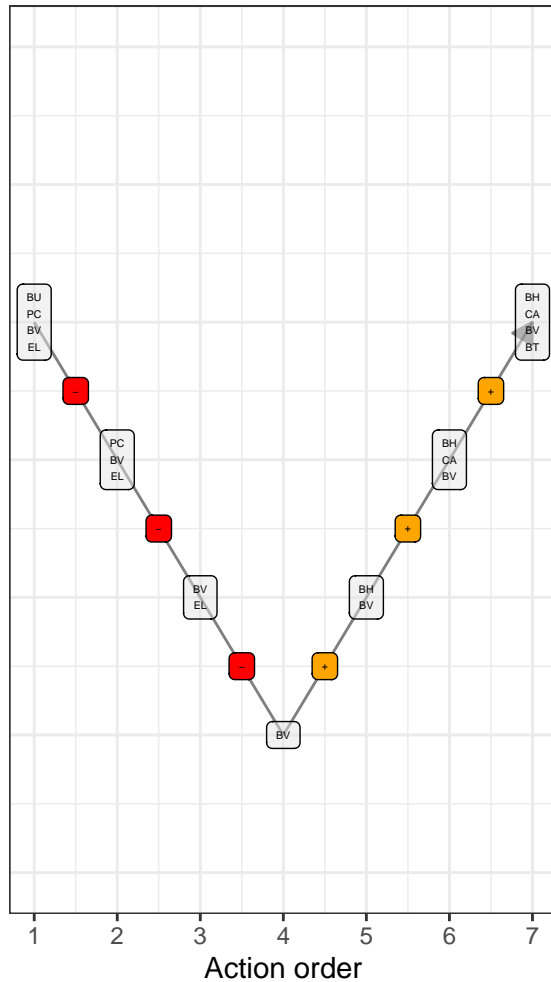
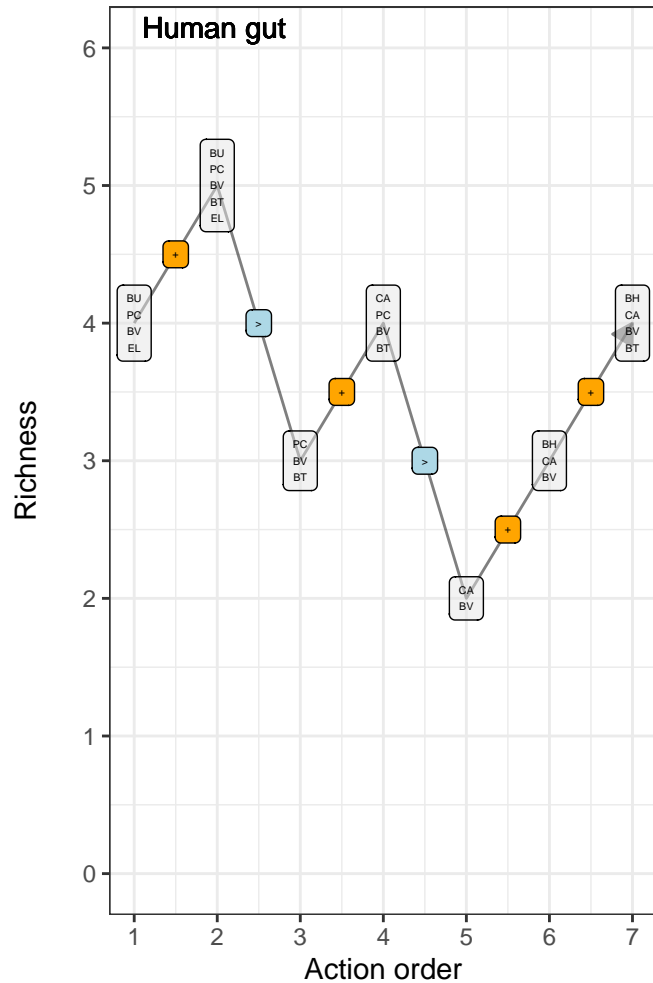
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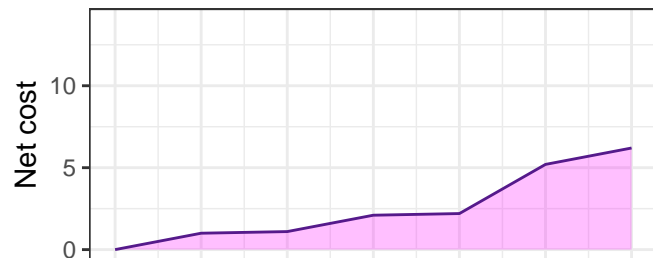
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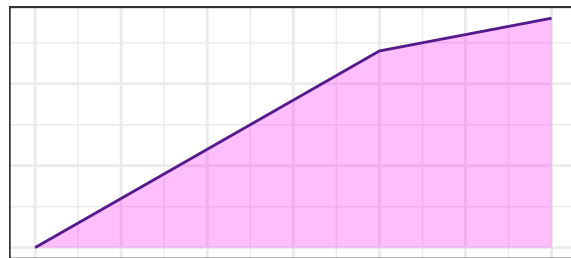
Human gut



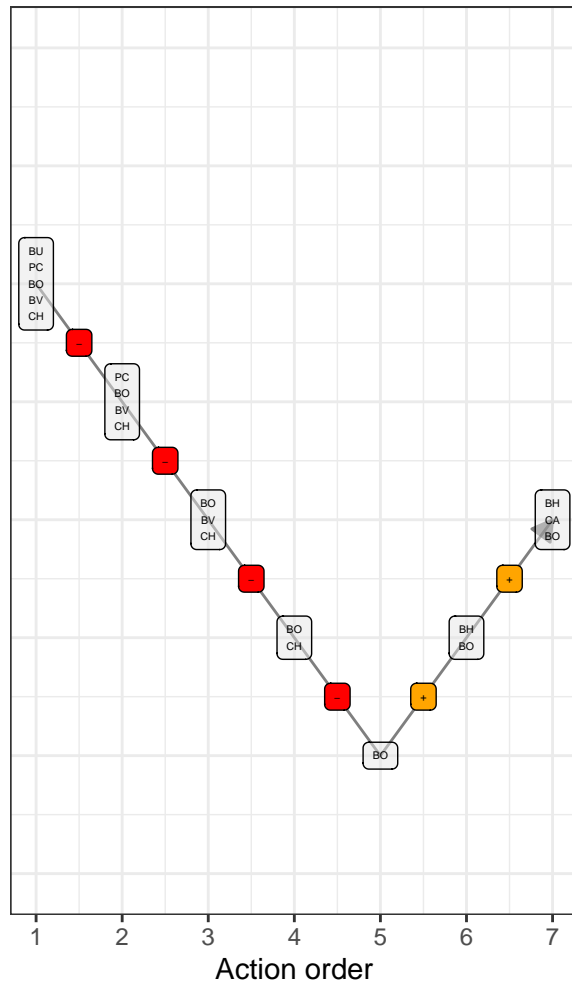
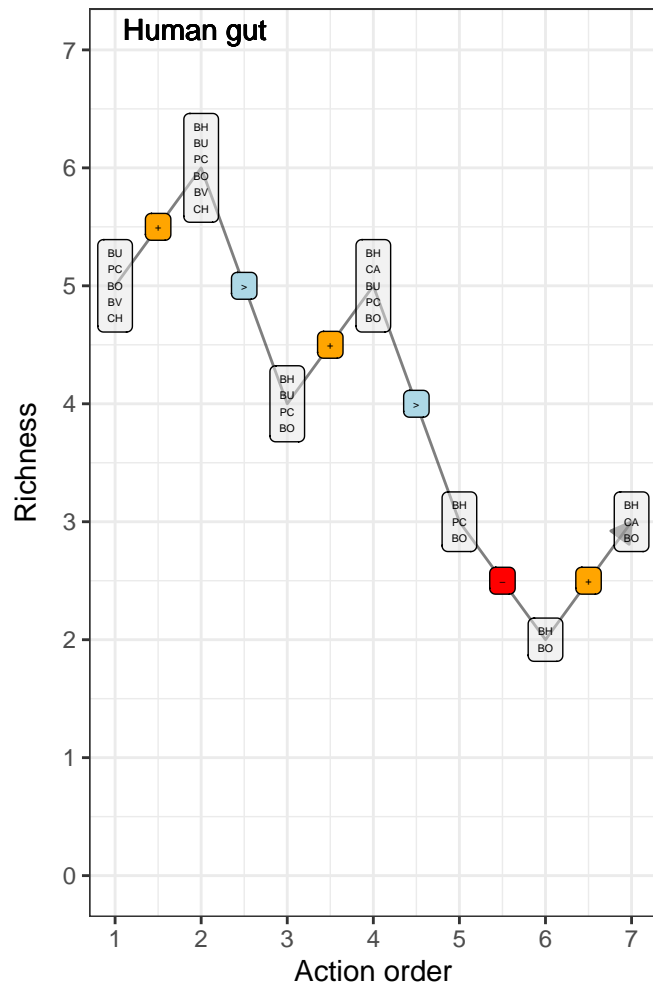
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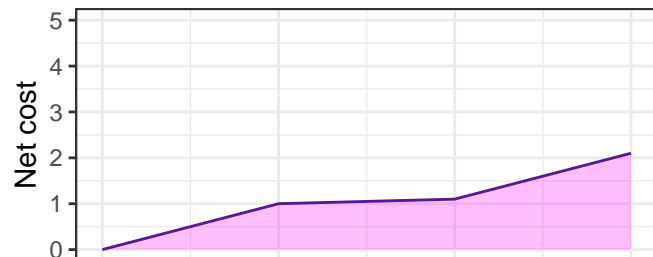
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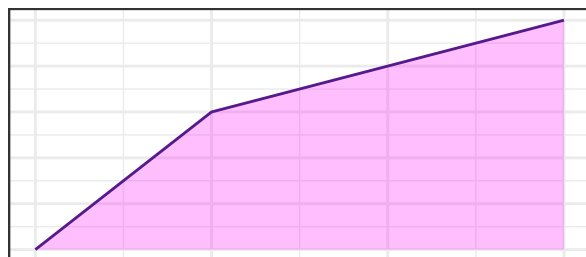
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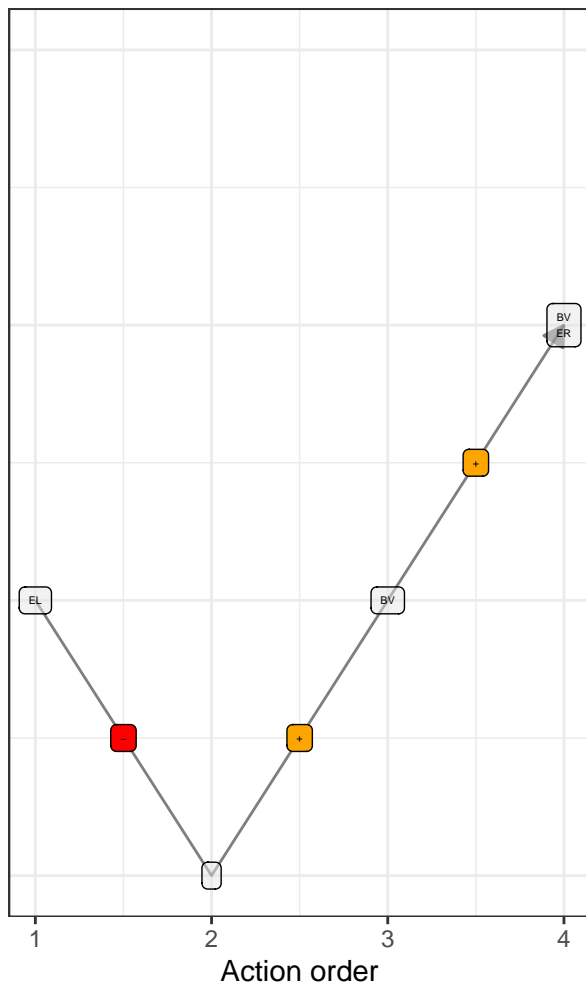
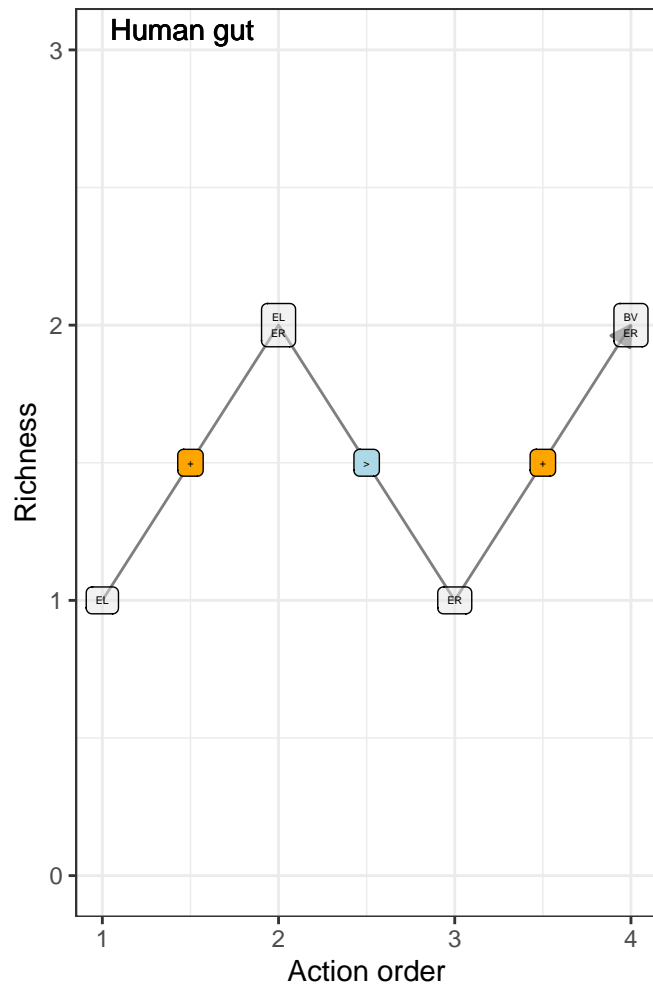
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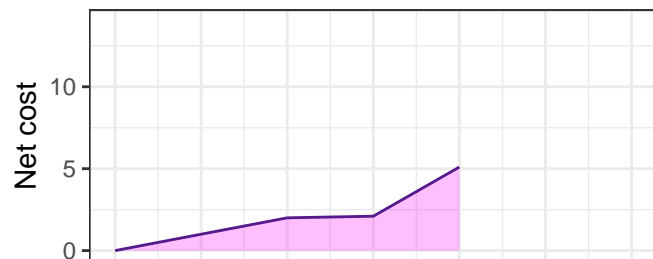
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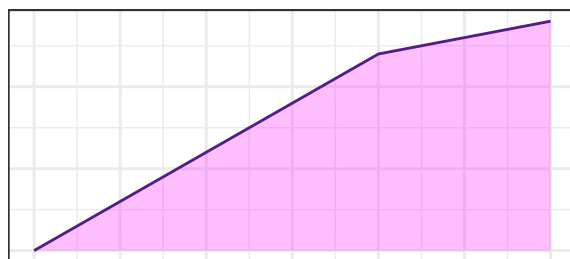
Human gut



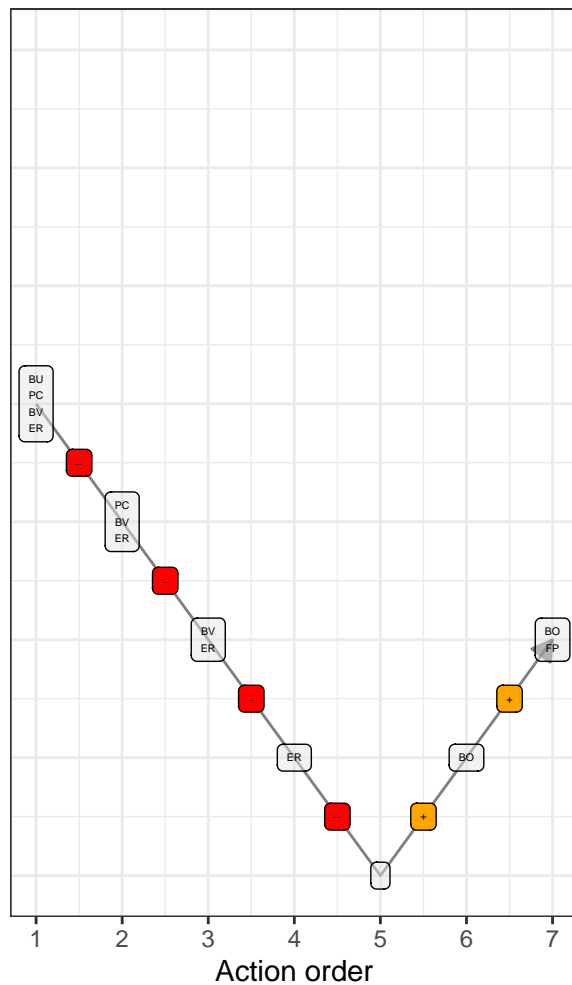
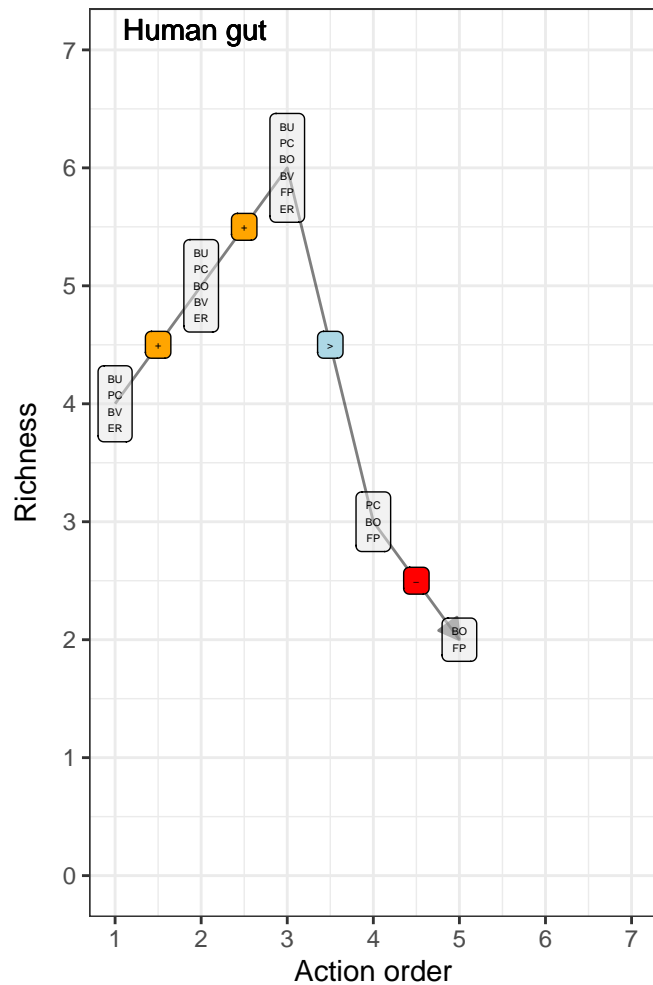
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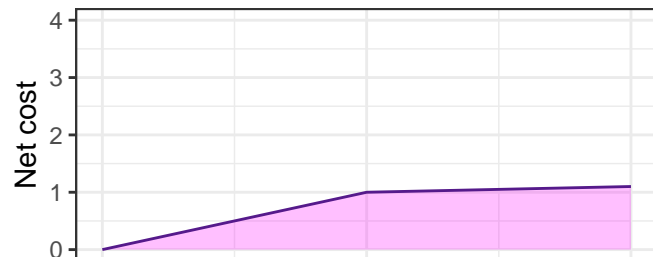
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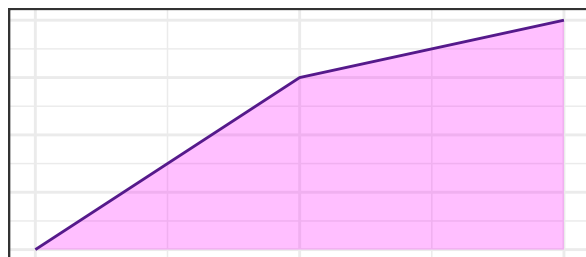
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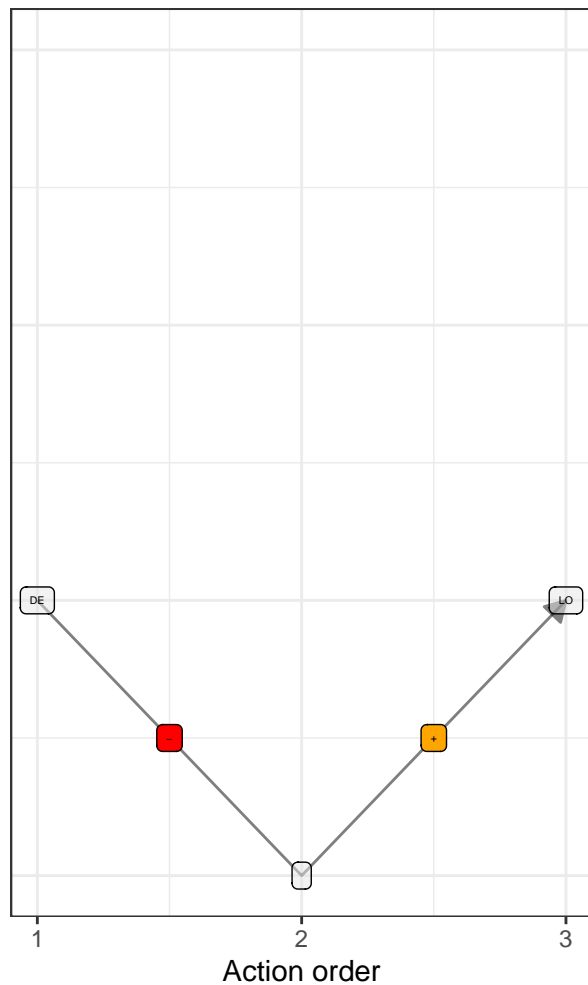
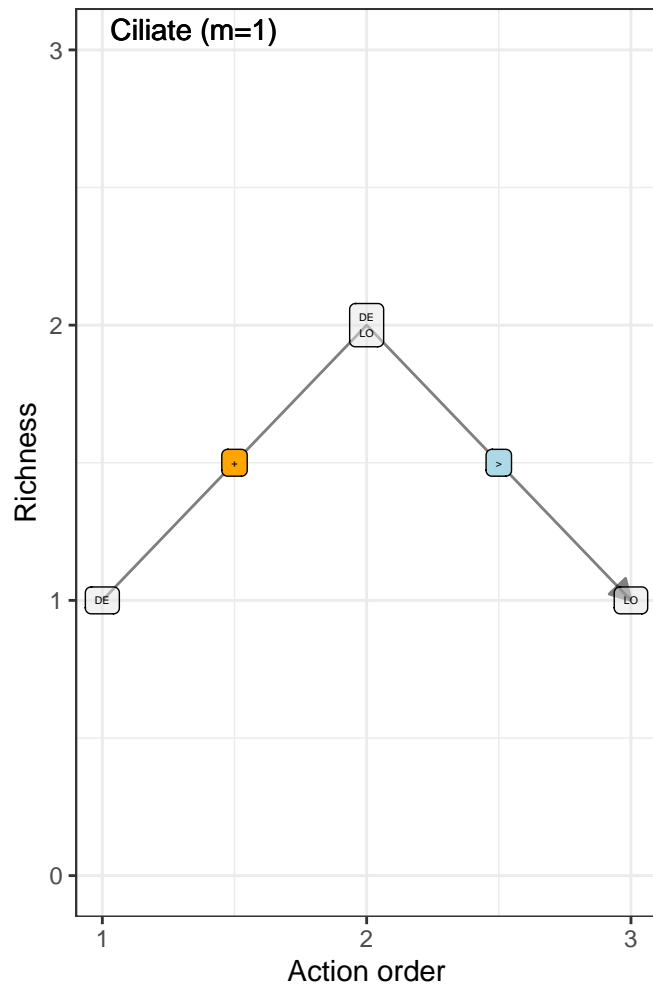
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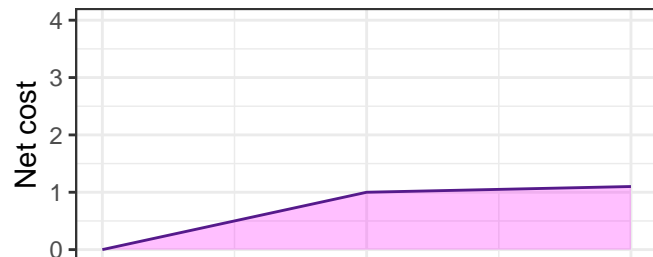
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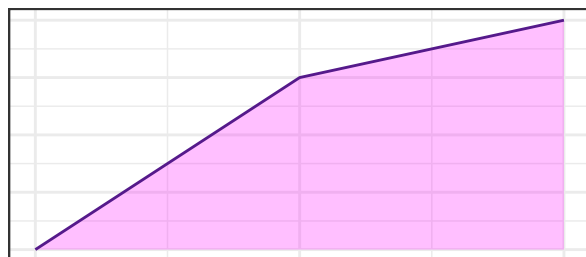
Ciliate (m=1)



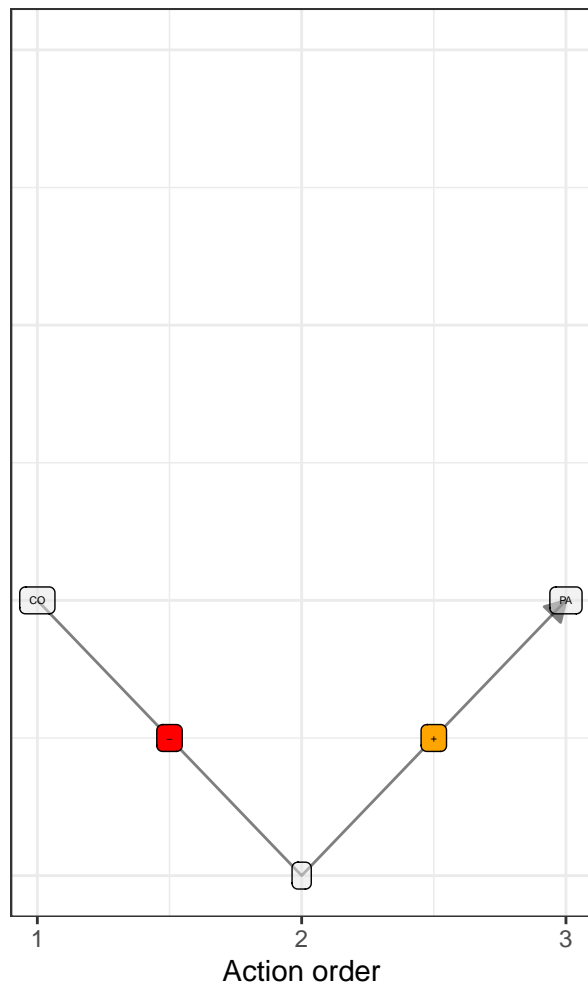
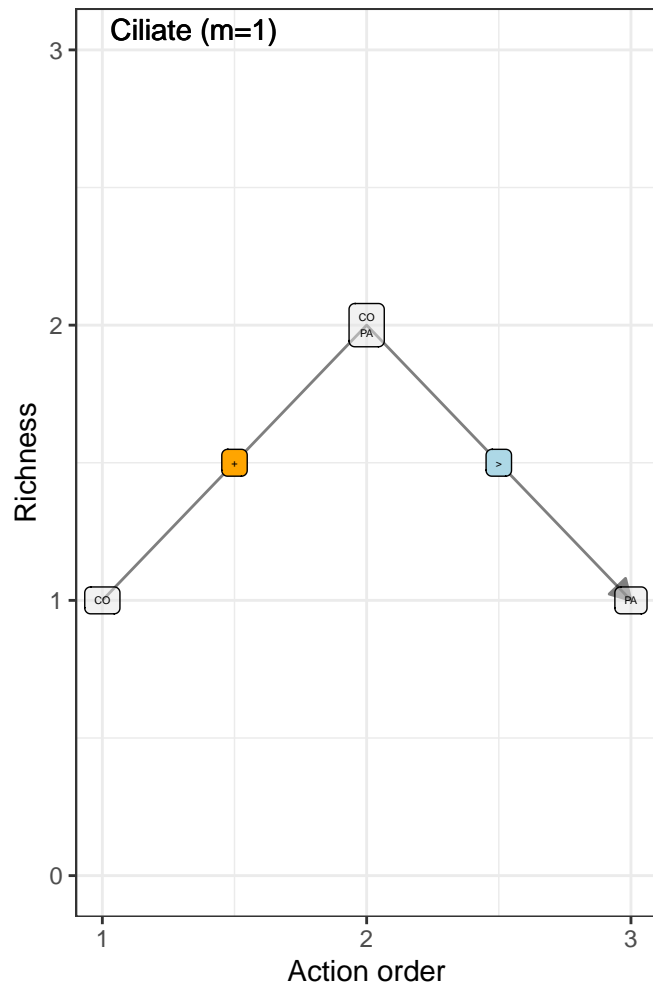
Optimal path



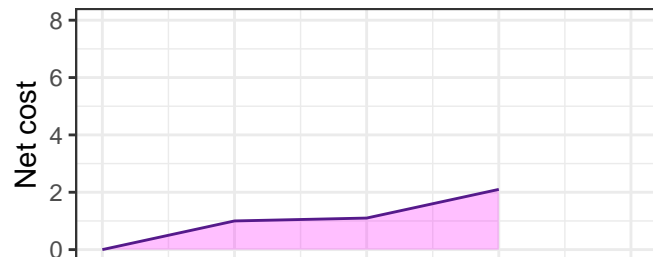
Nominal path



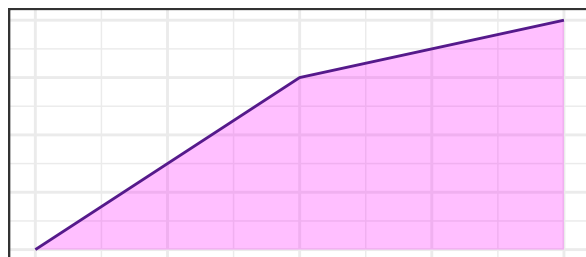
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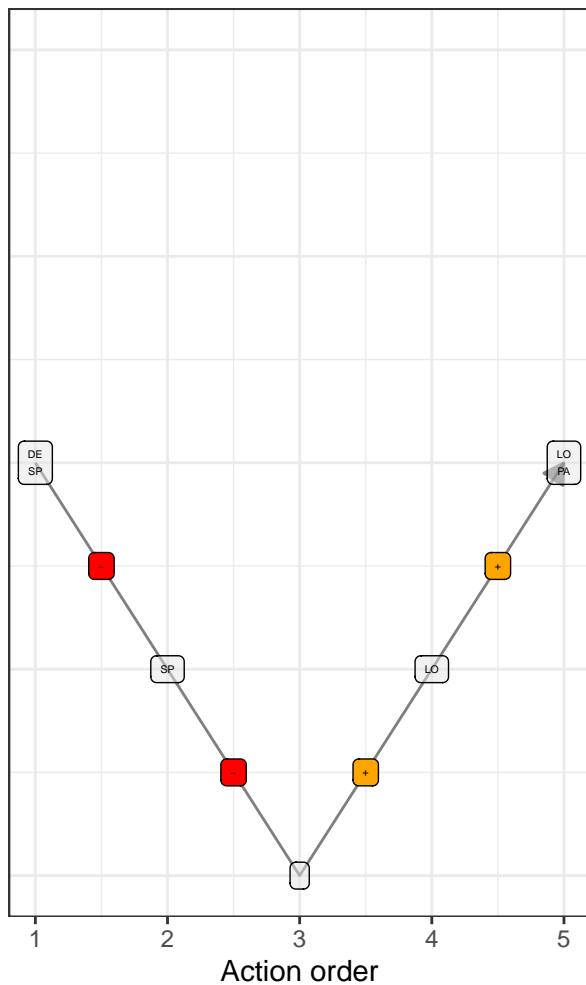
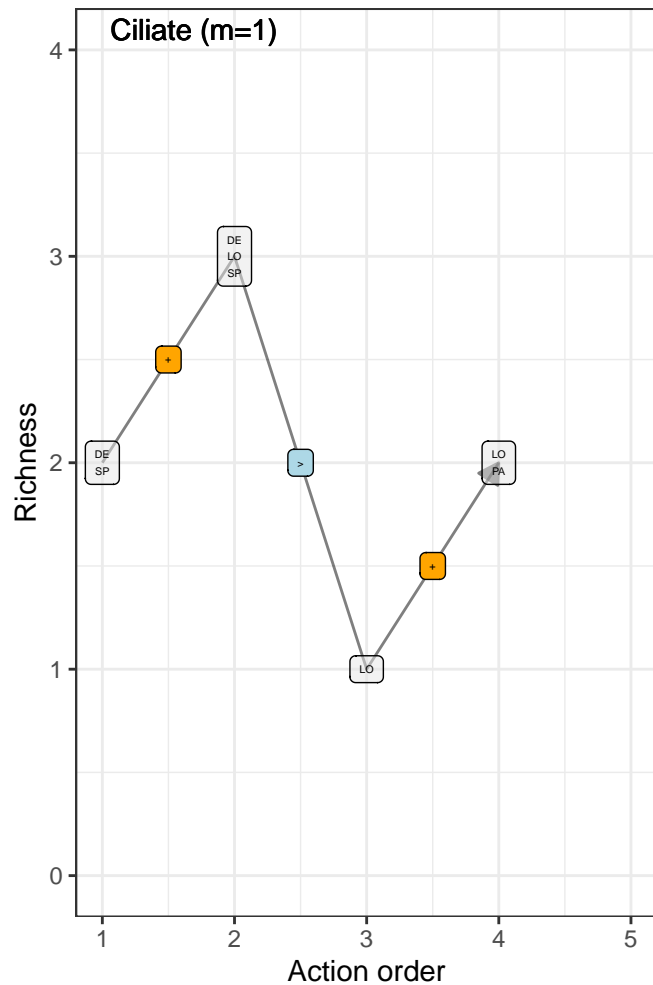
Optimal path



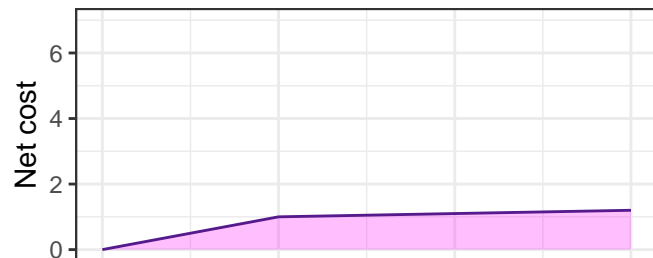
Nominal path



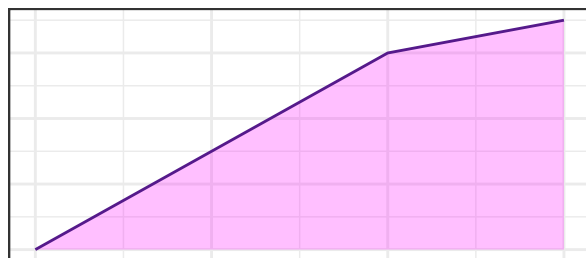
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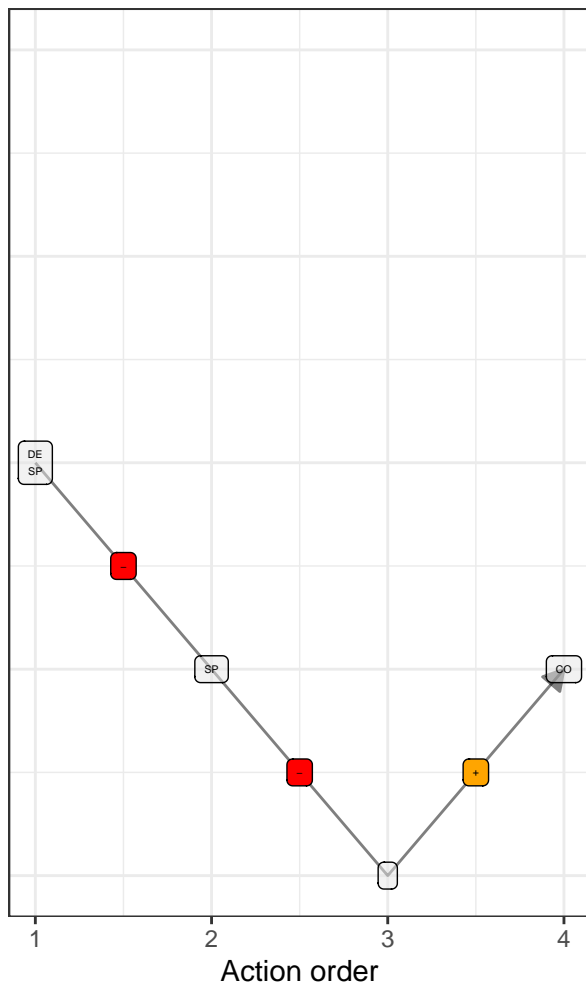
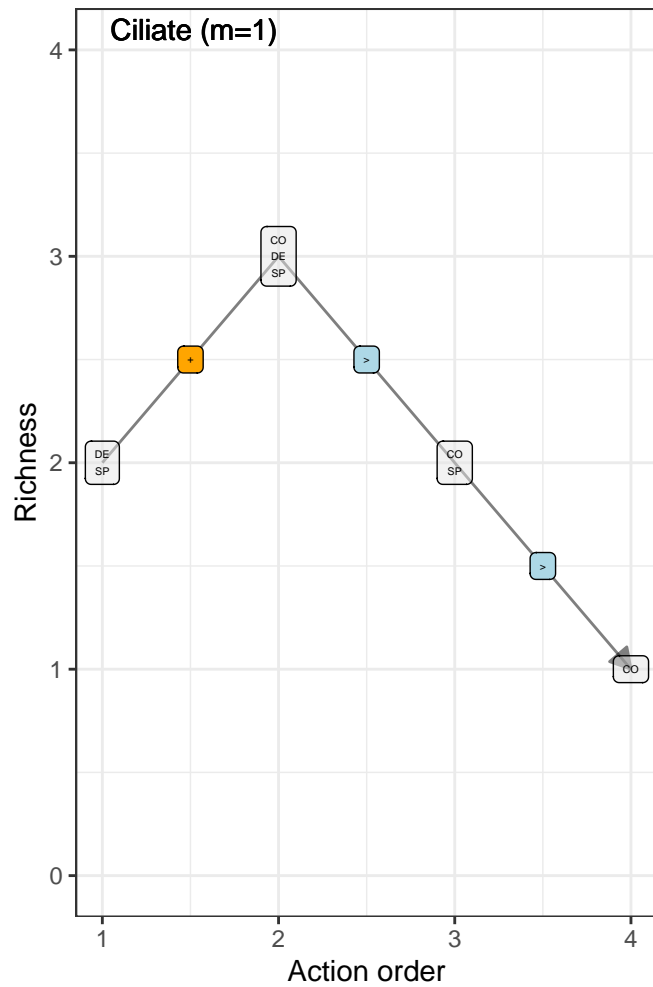
Optimal path



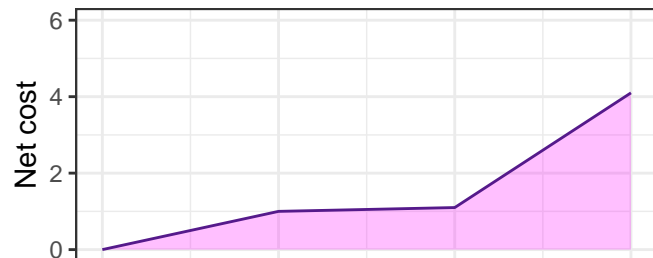
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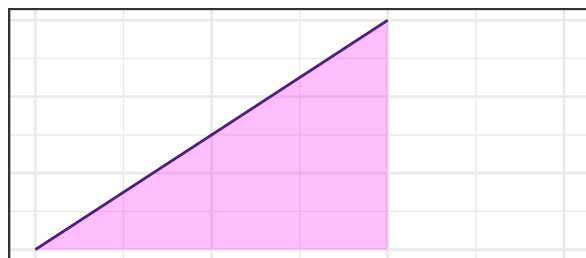
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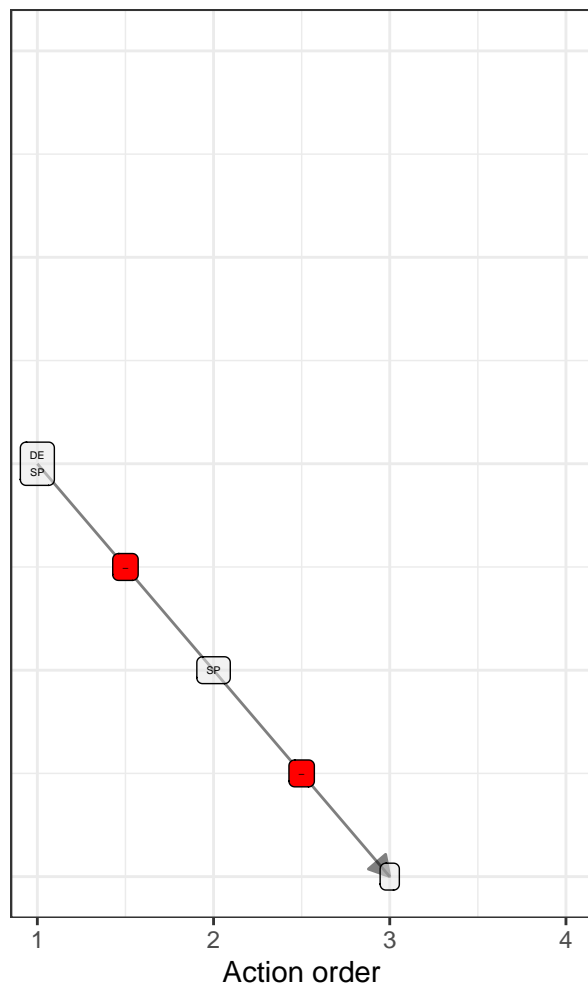
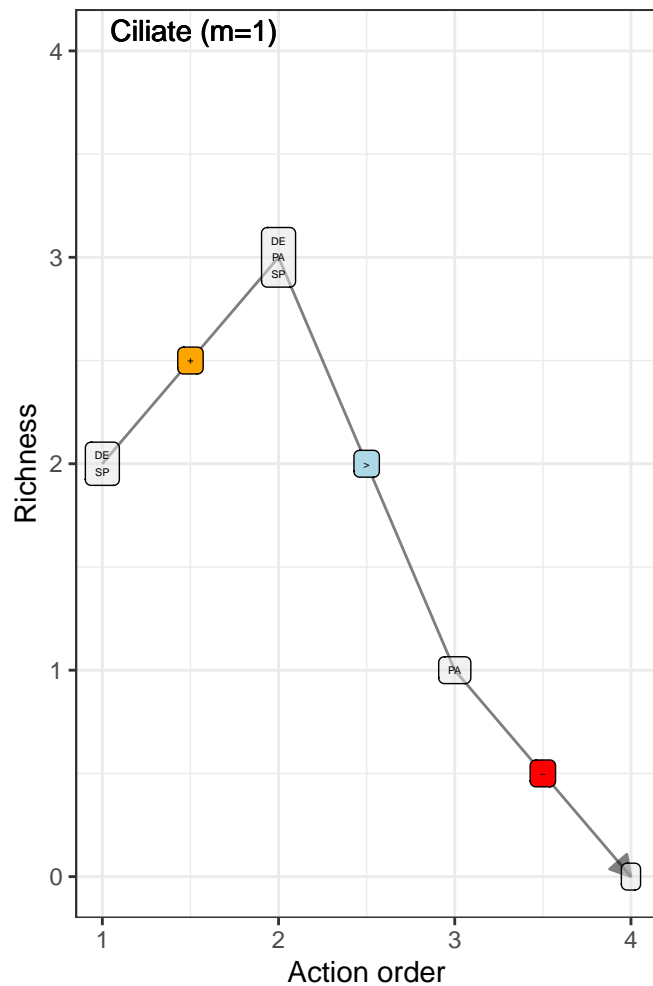
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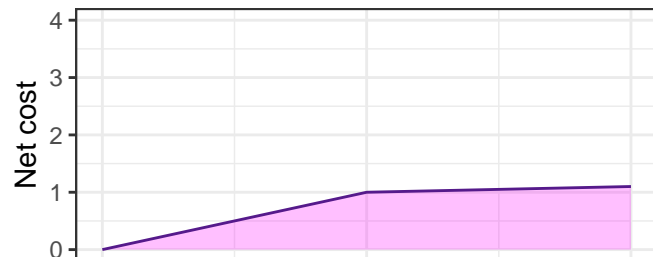
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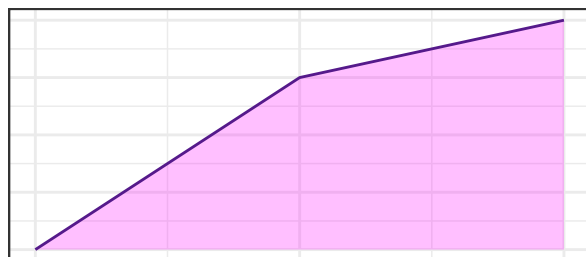
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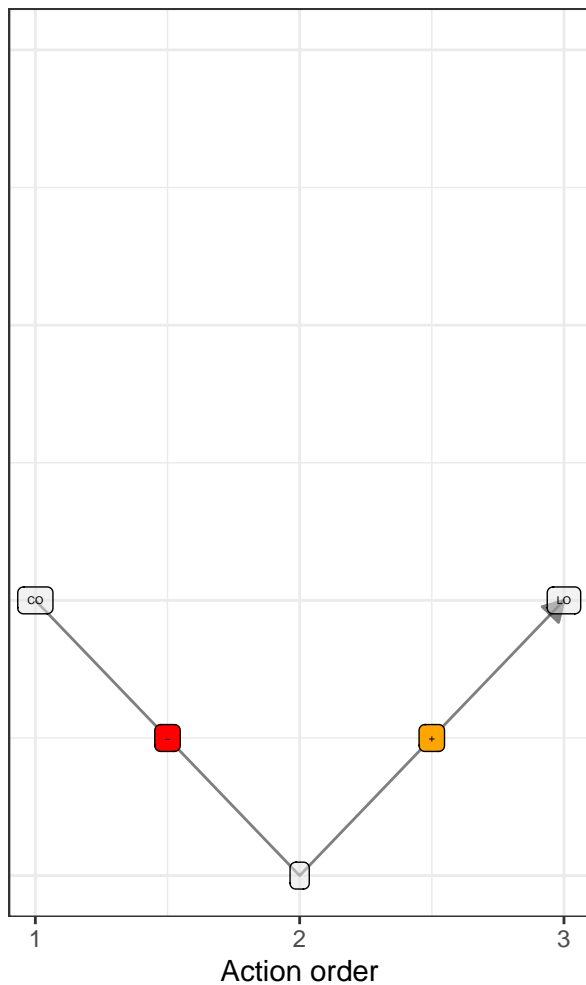
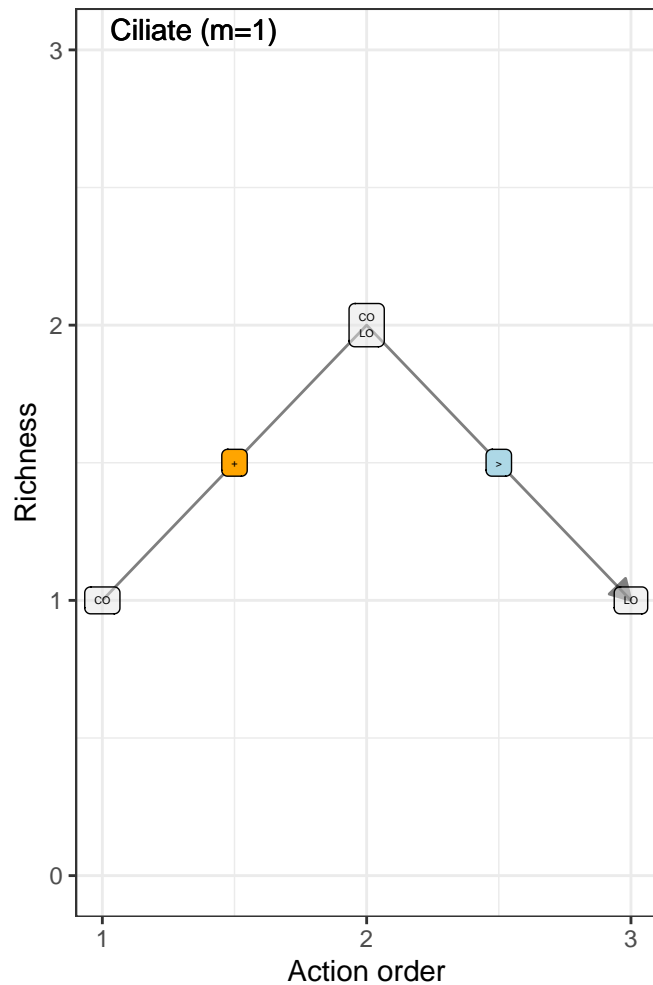
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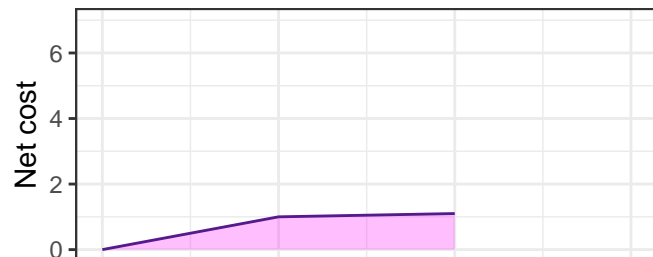
Nominal path



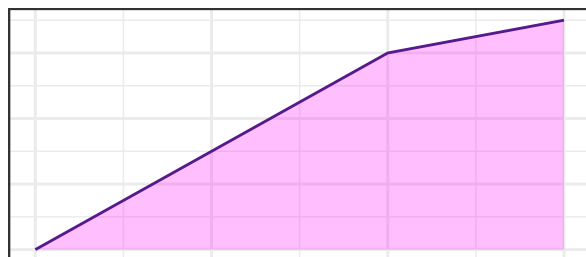
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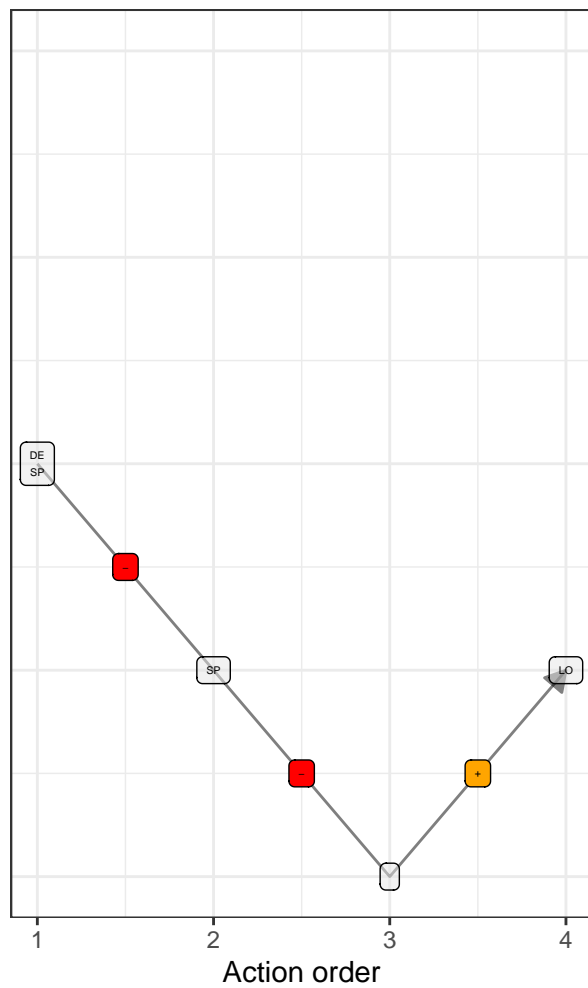
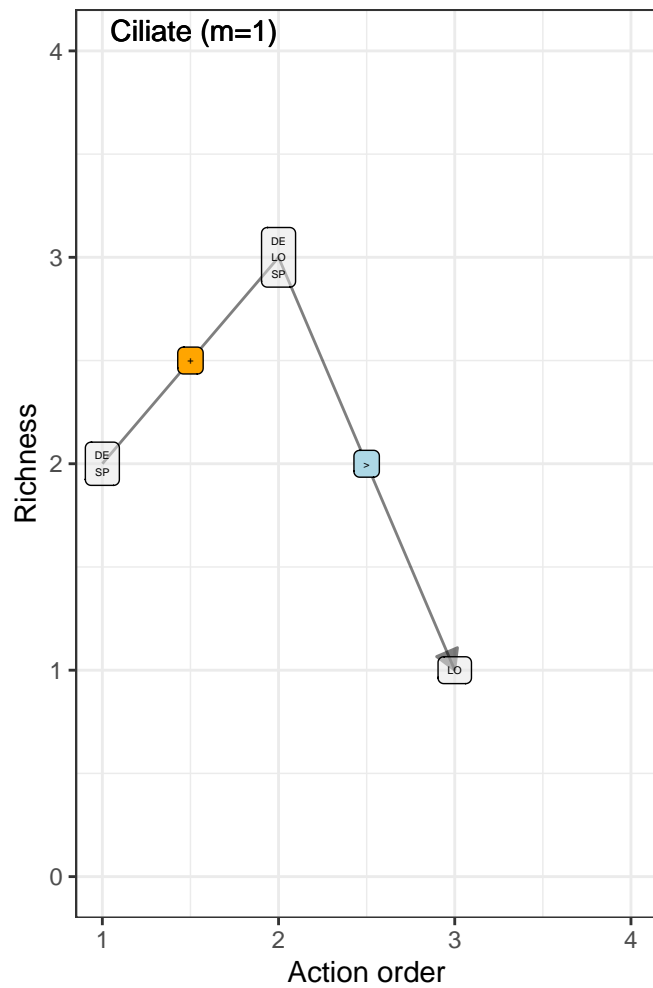
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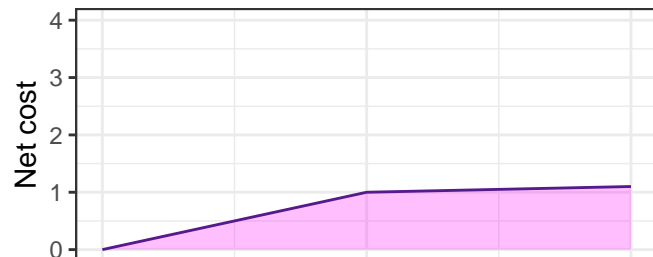
Nominal path



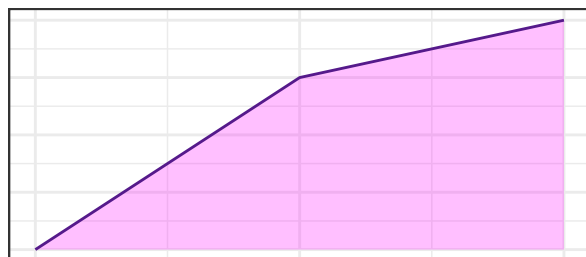
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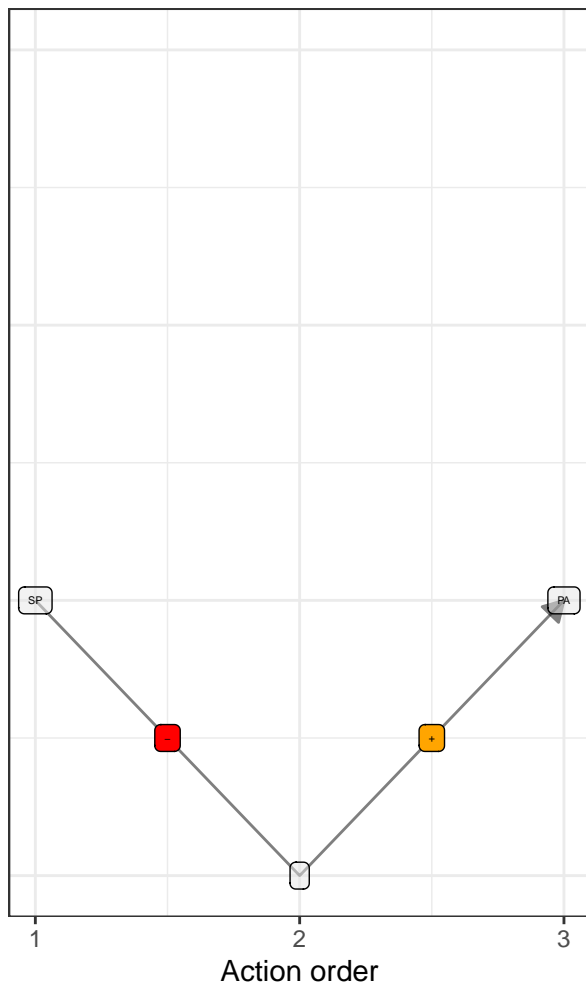
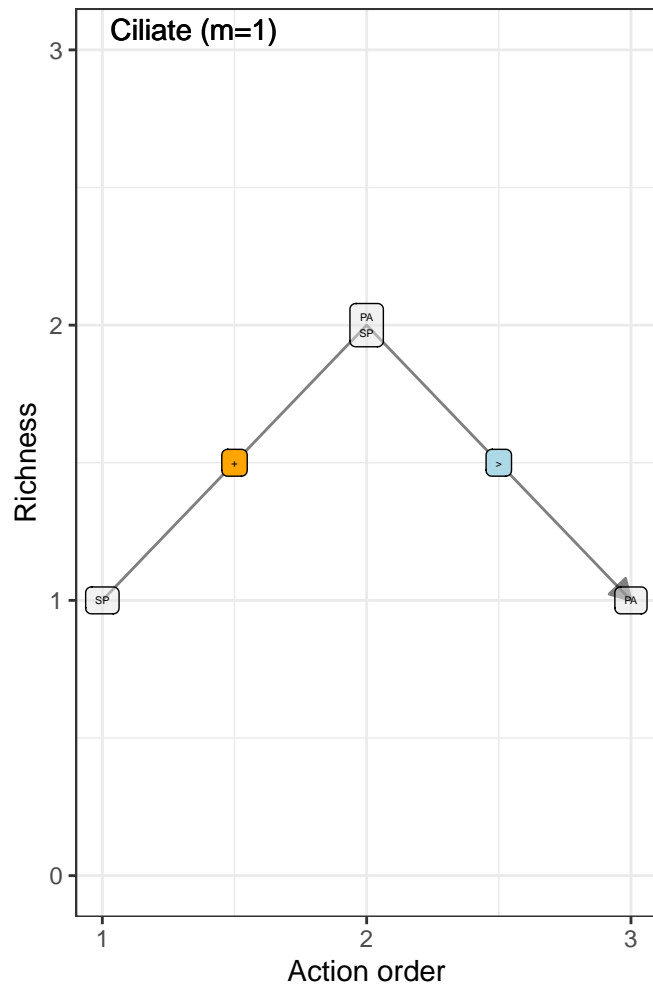
Optimal path



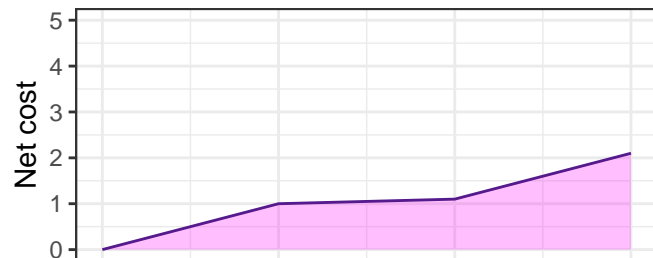
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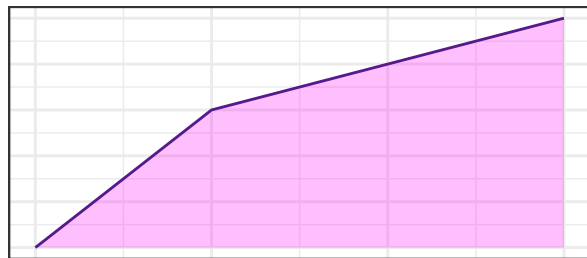
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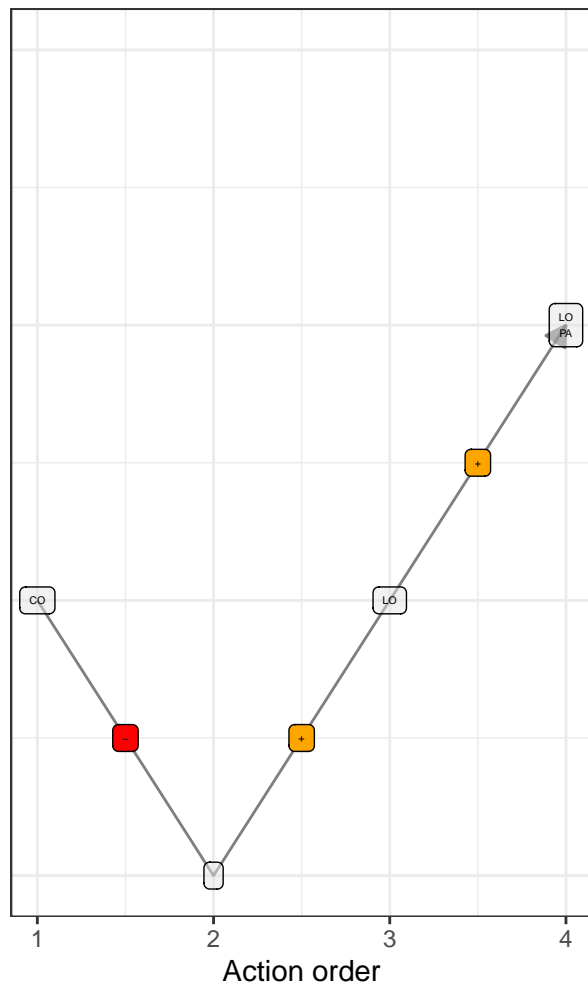
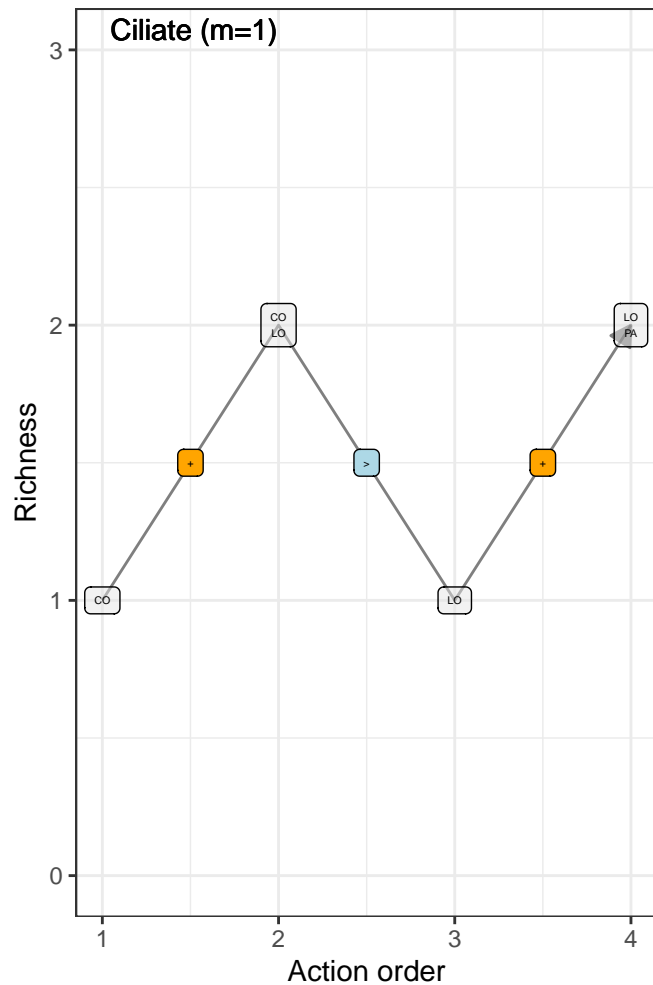
Optimal path



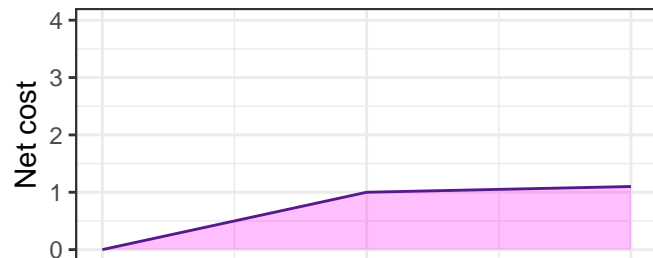
Nominal path



Ciliate (m=1)



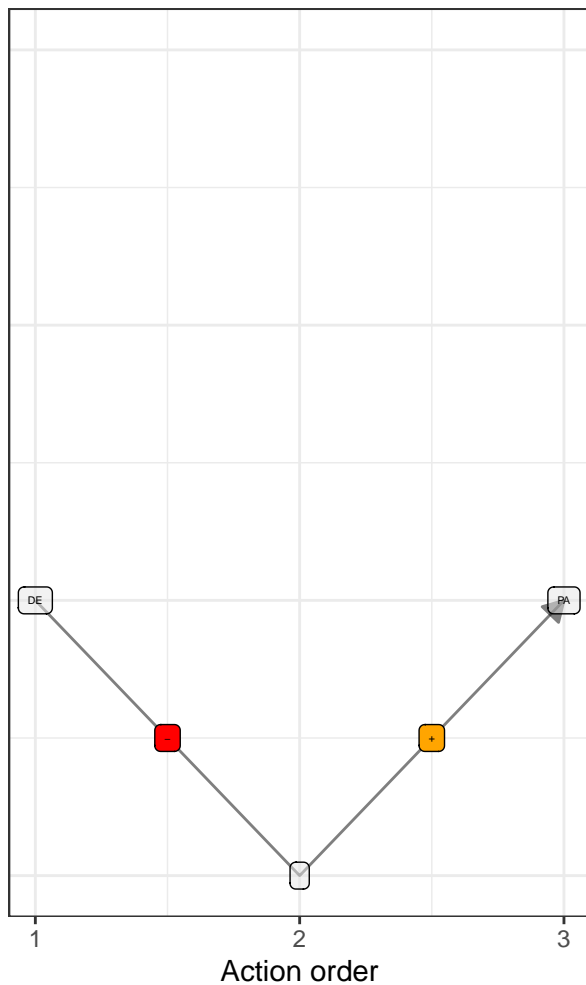
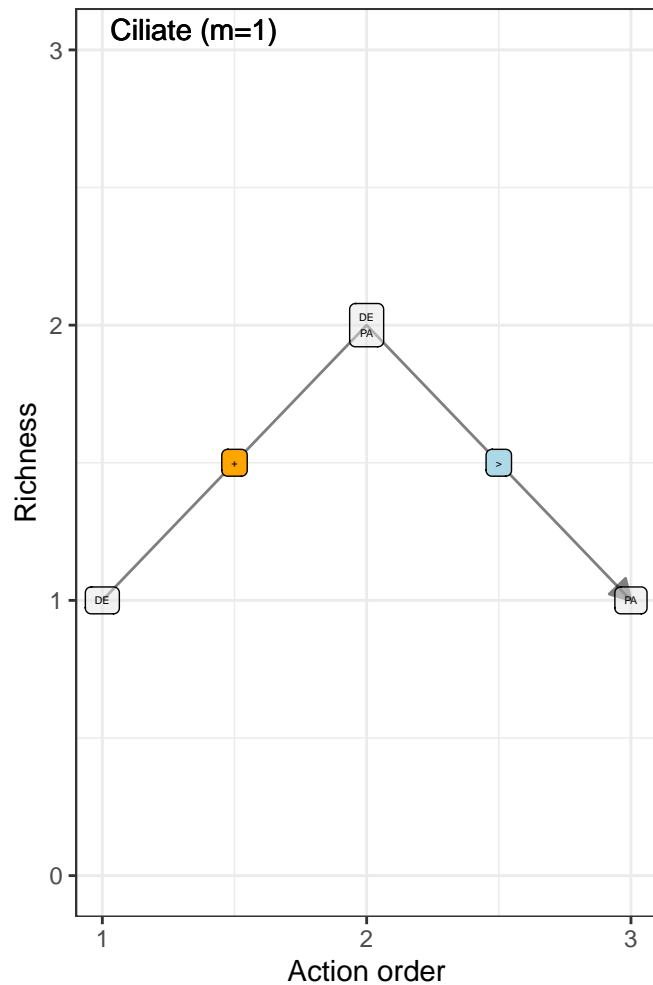
Optimal path



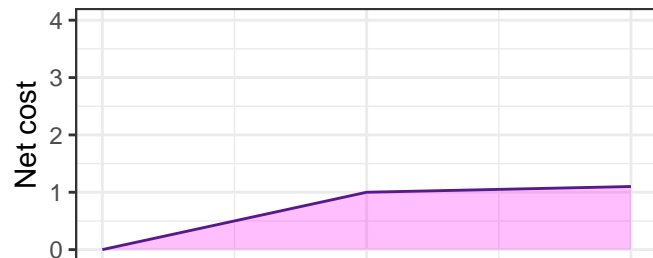
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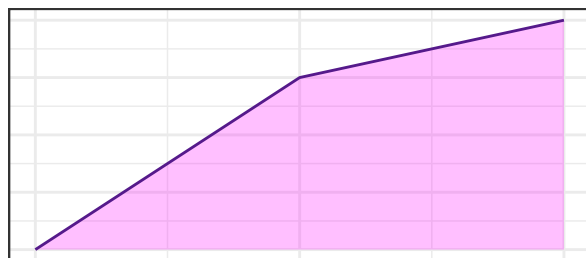
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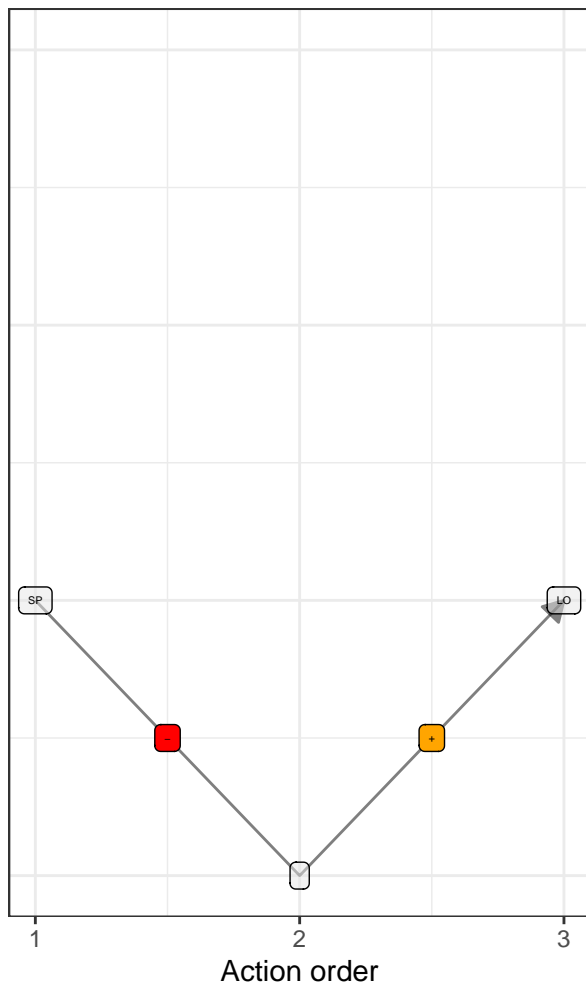
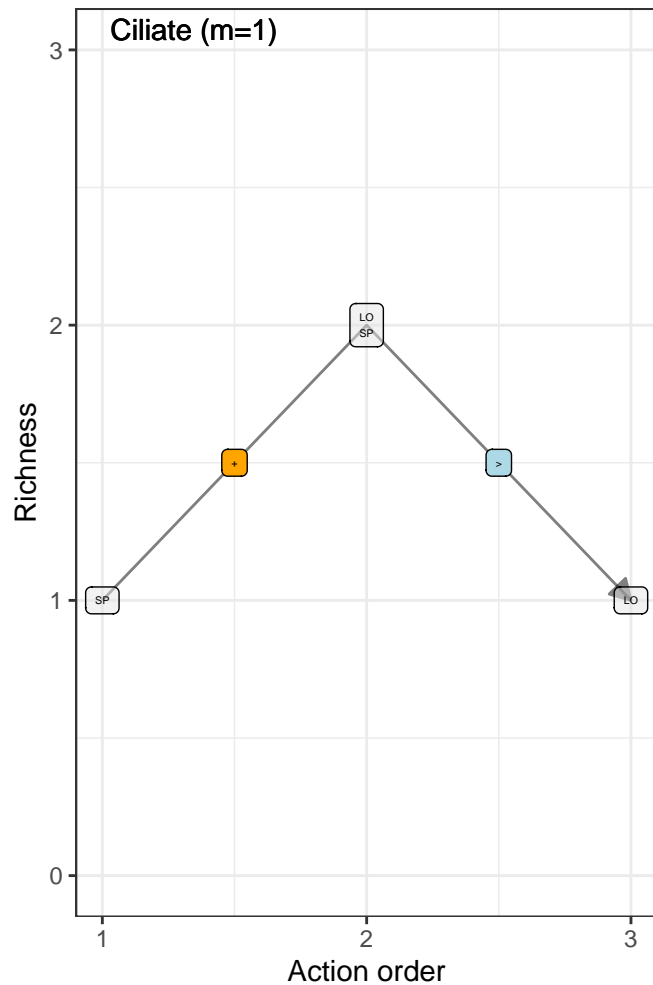
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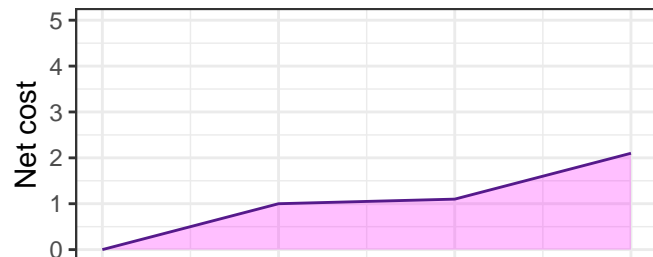
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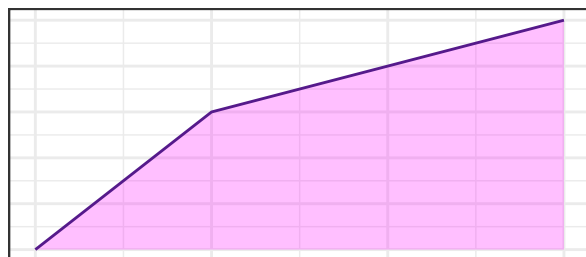
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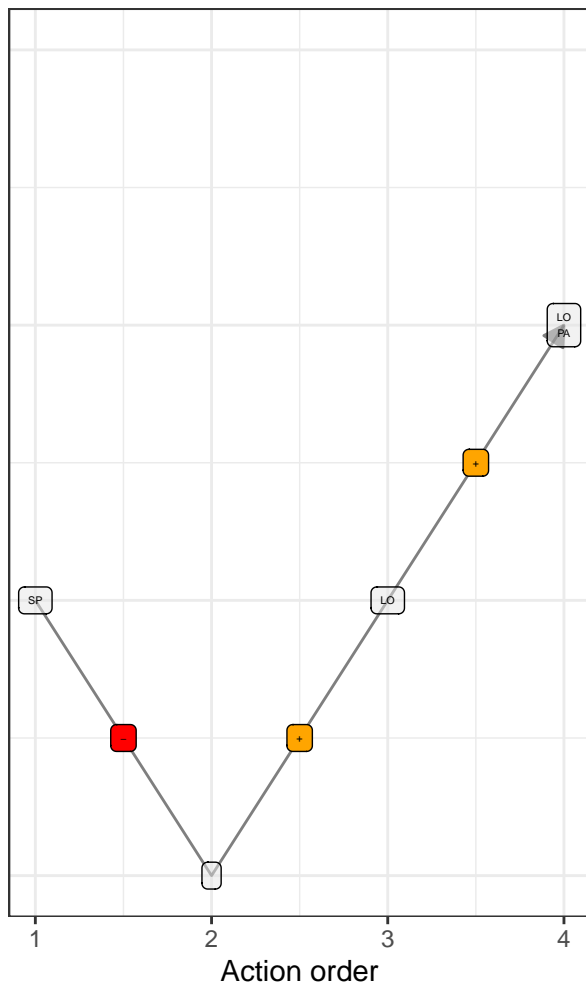
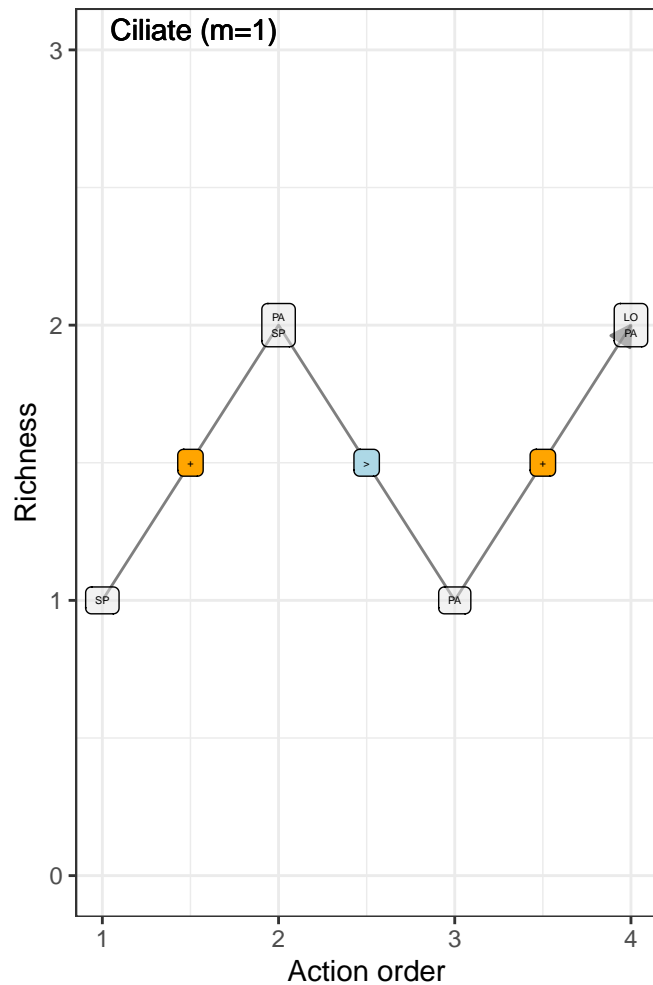
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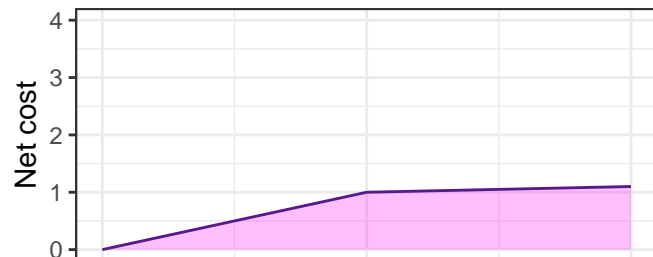
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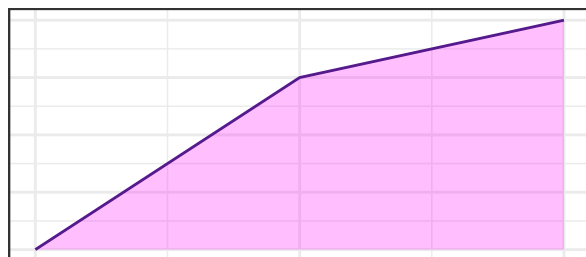
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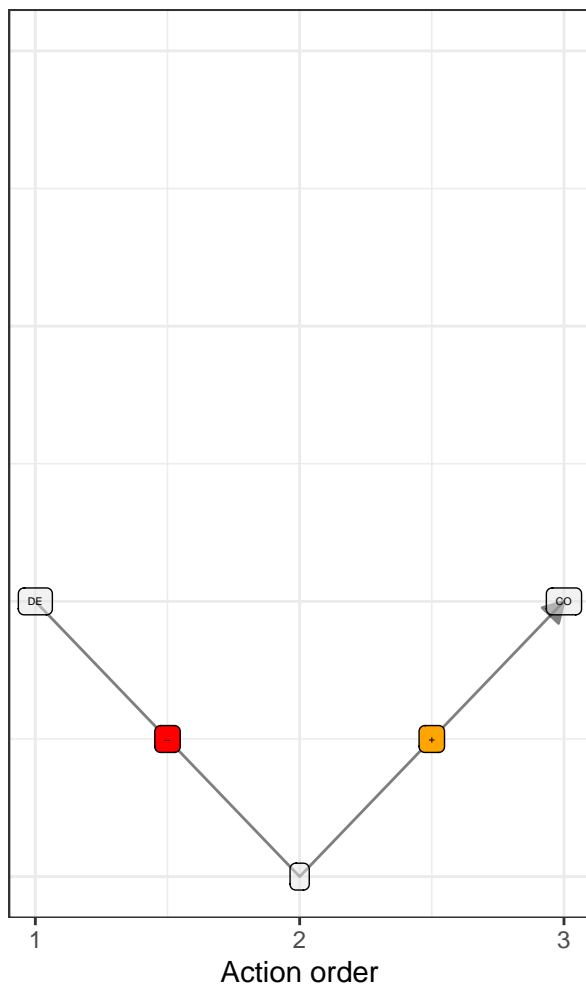
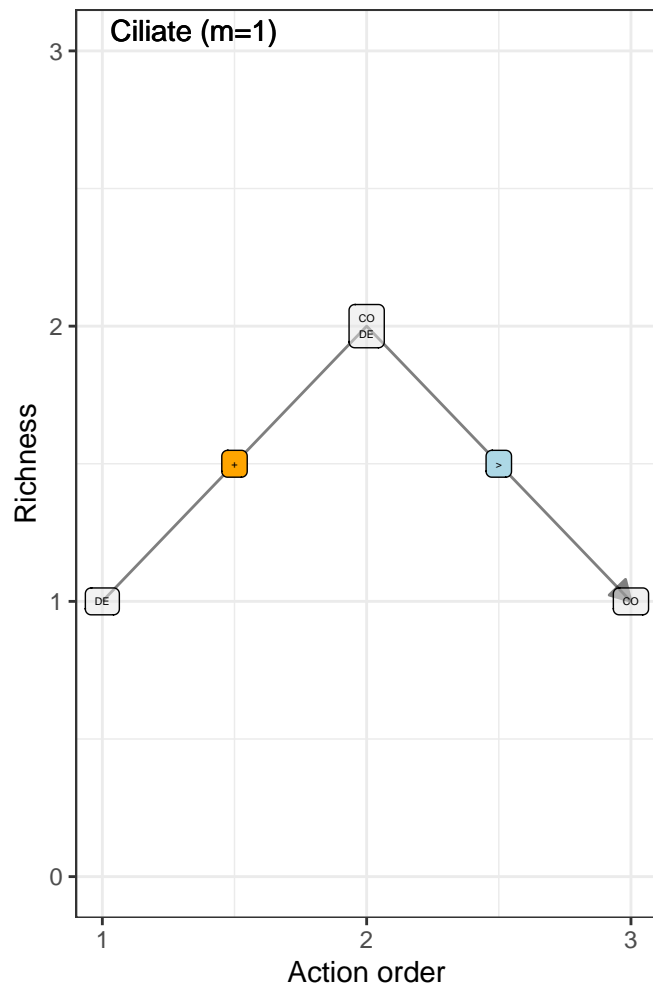
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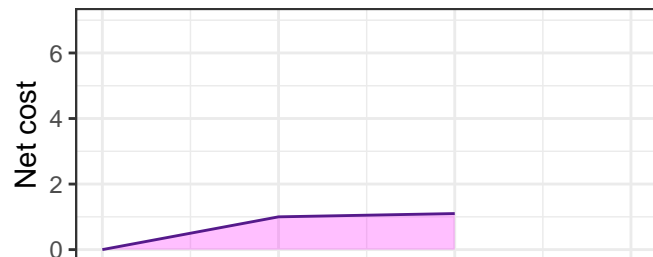
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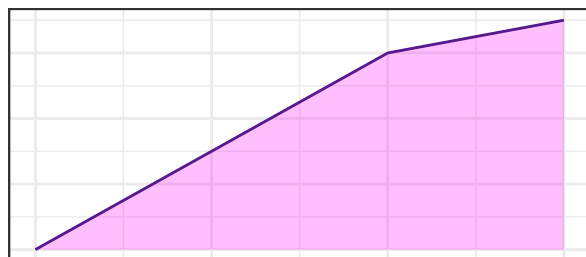
Ciliate (m=1)



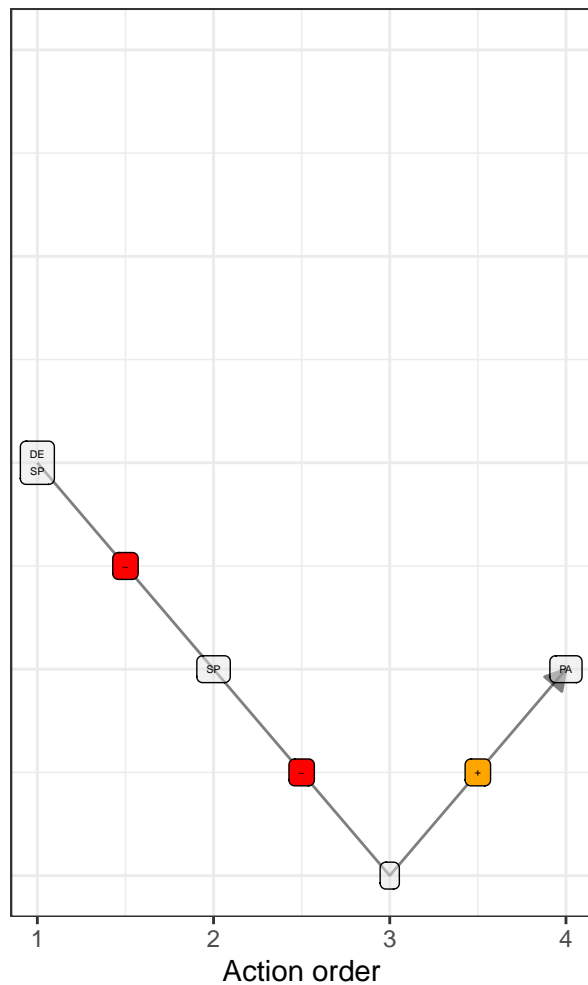
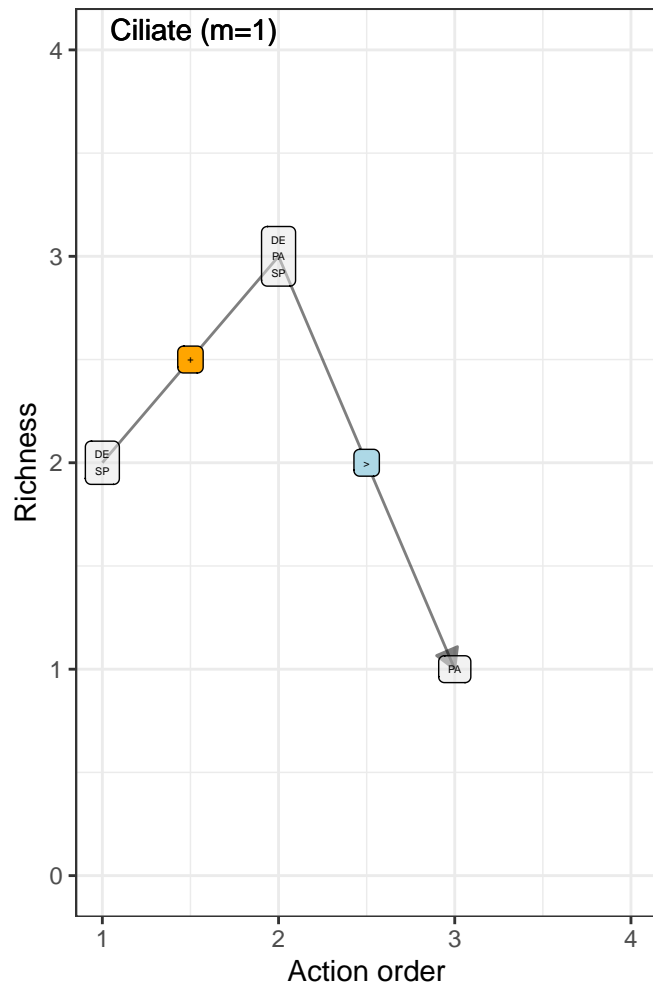
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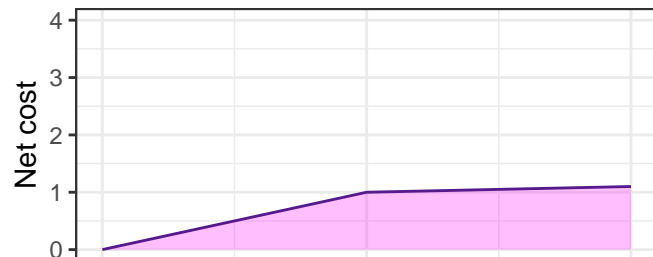
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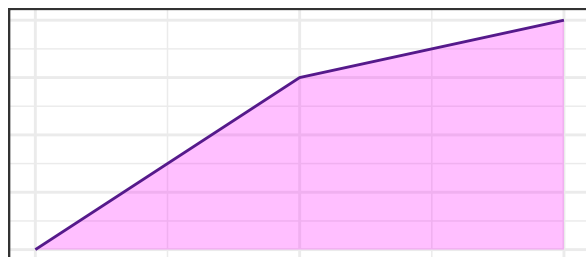
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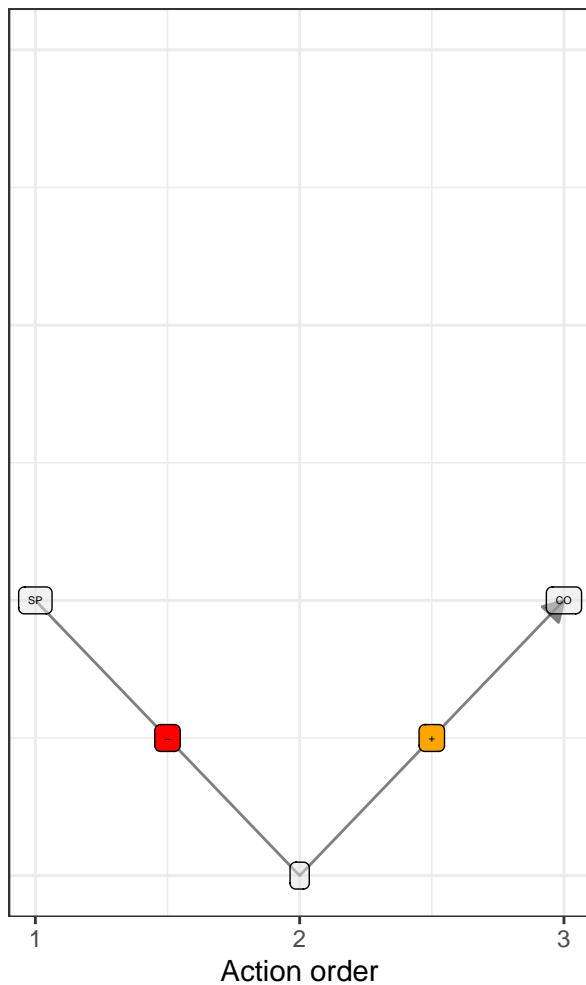
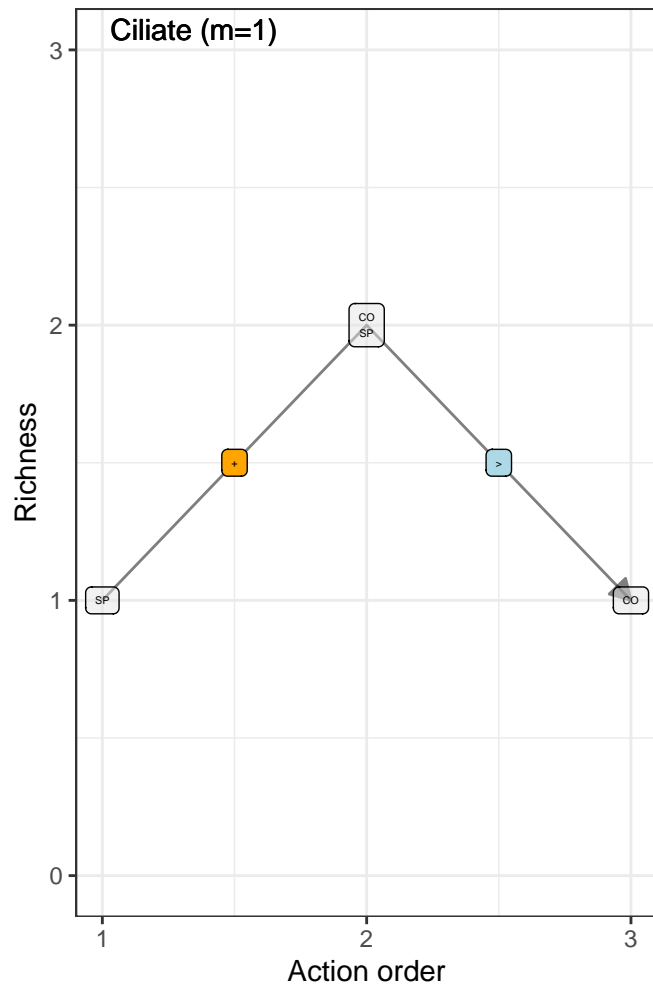
Optimal path



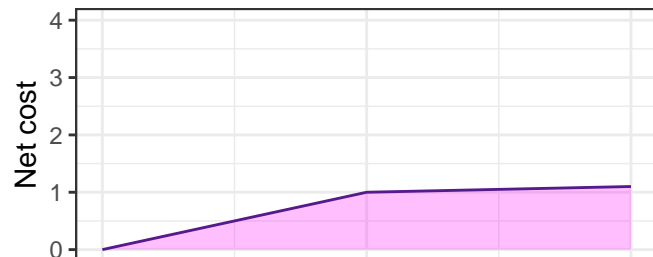
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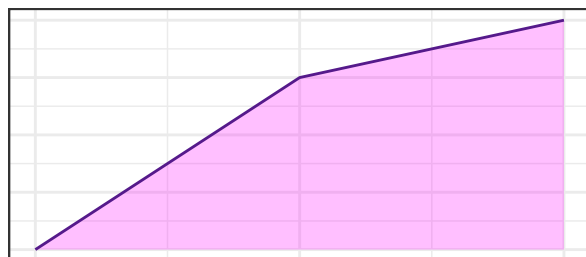
Ciliate (m=1)



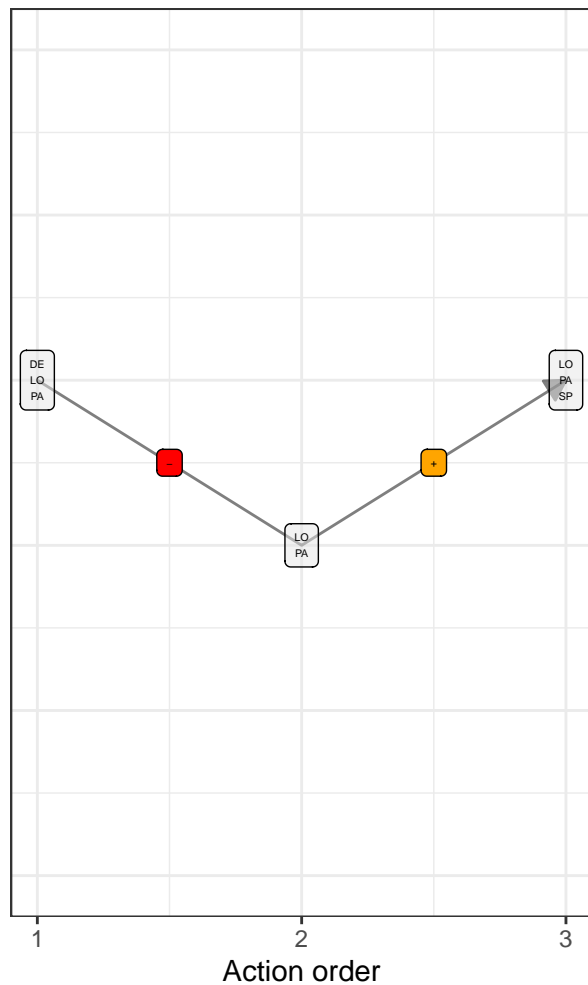
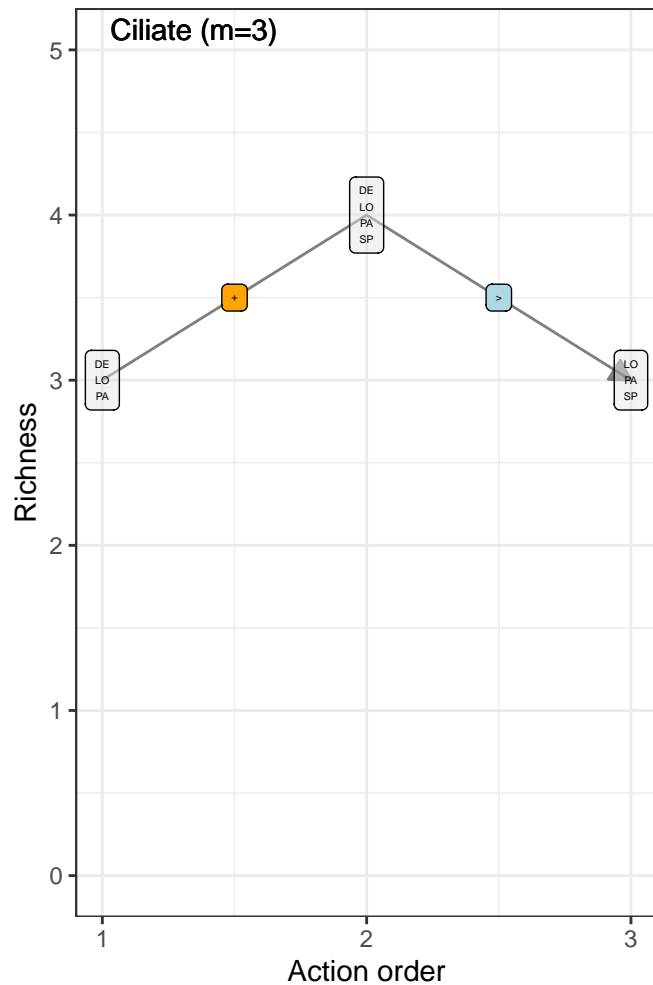
Optimal path



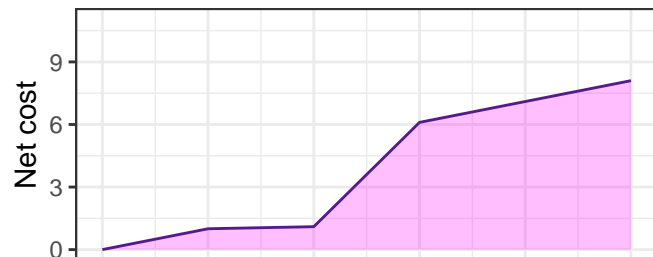
Nominal path



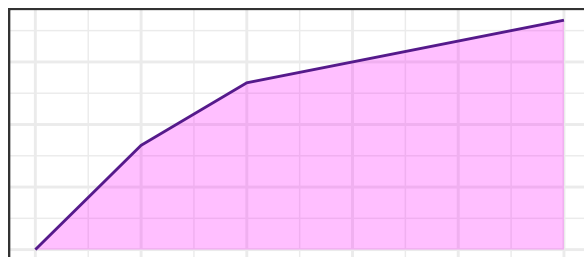
Ciliate (m=3)



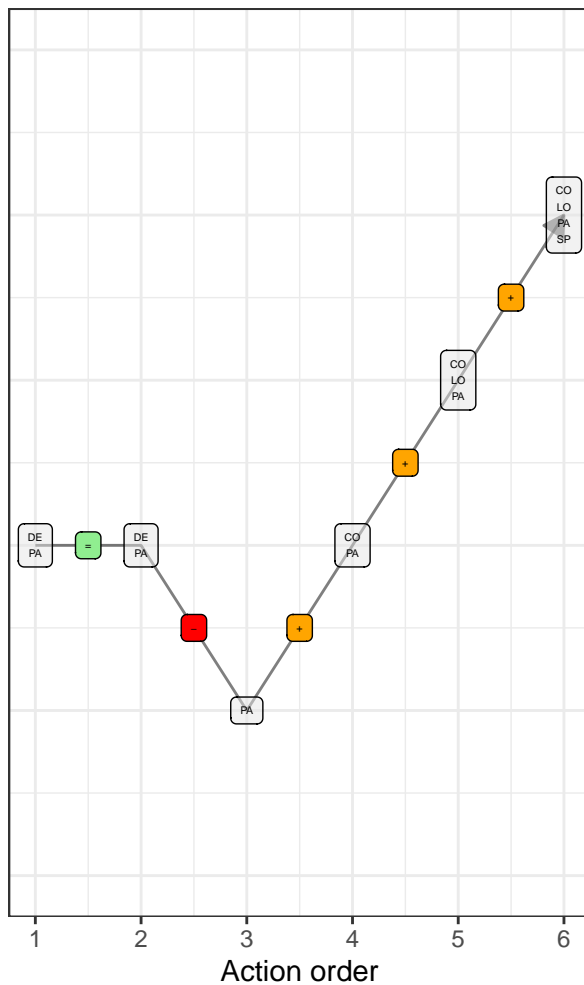
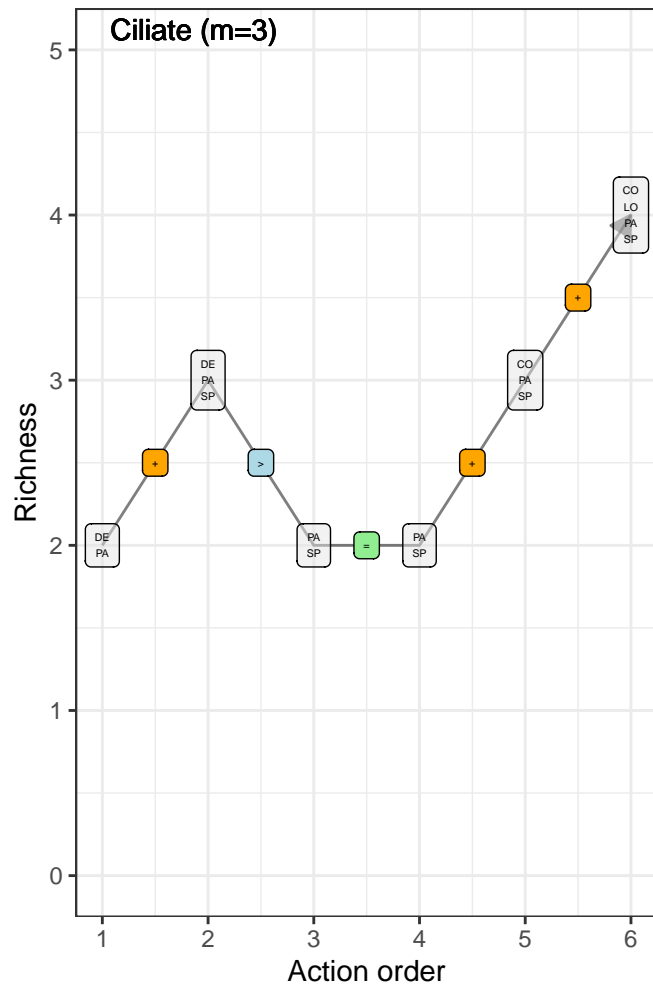
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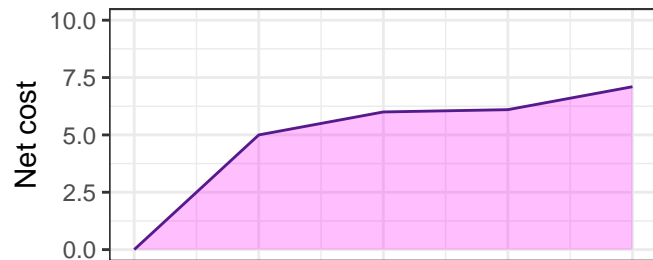
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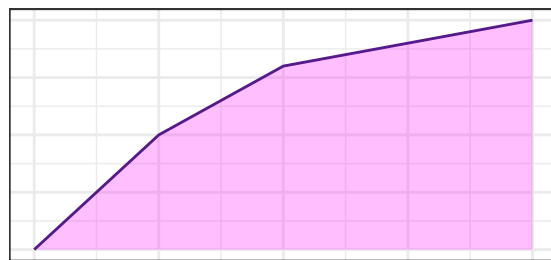
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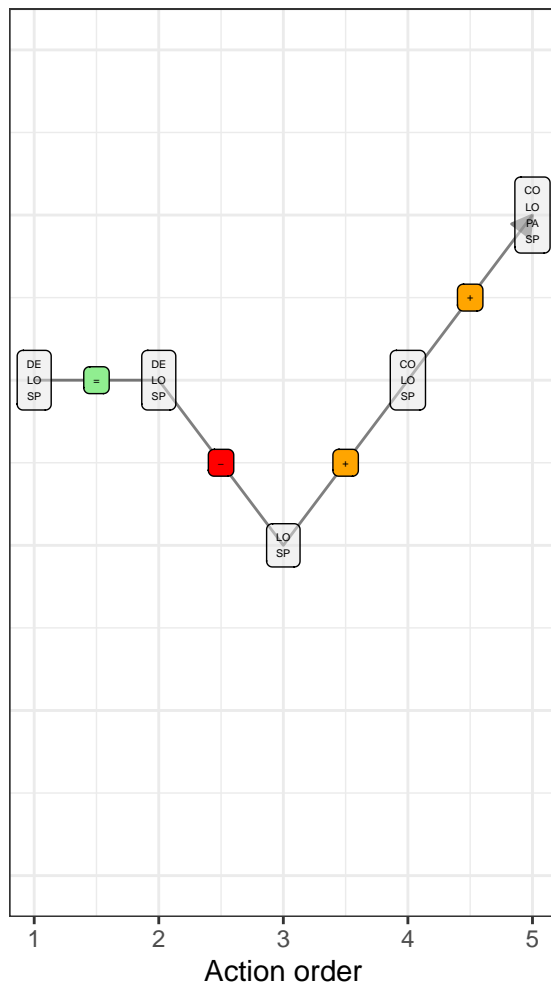
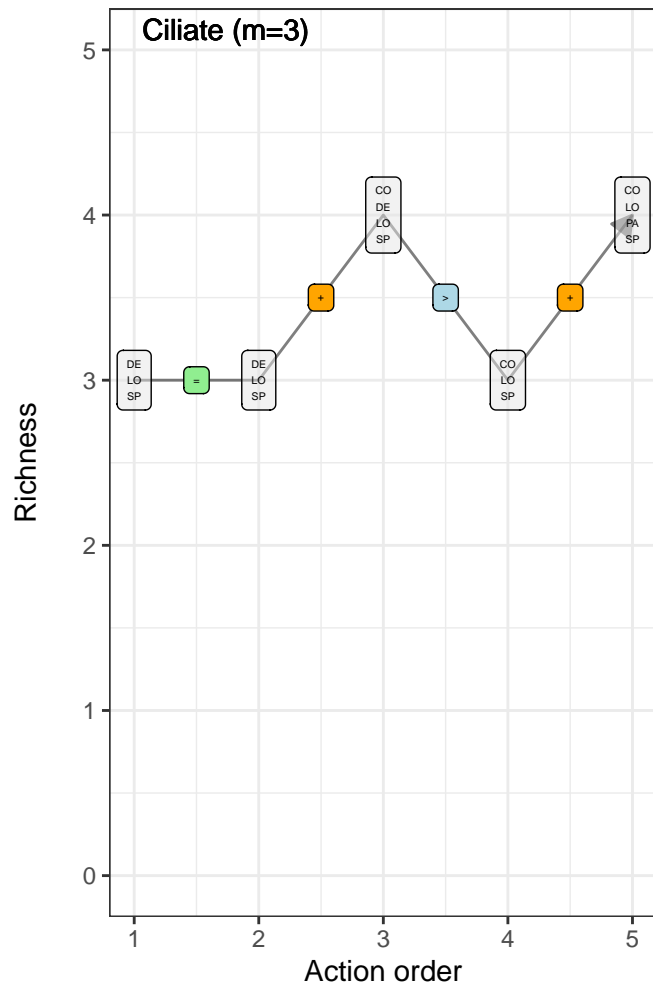
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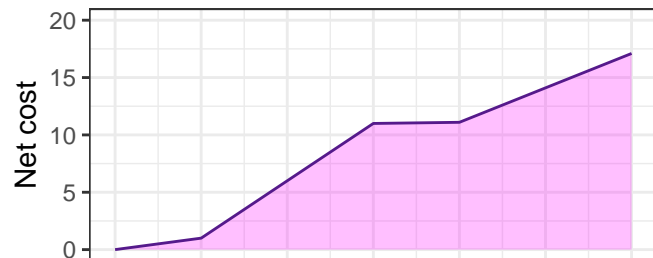
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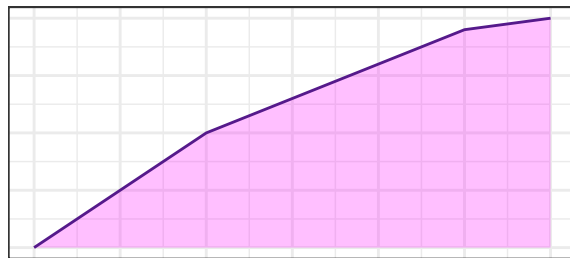
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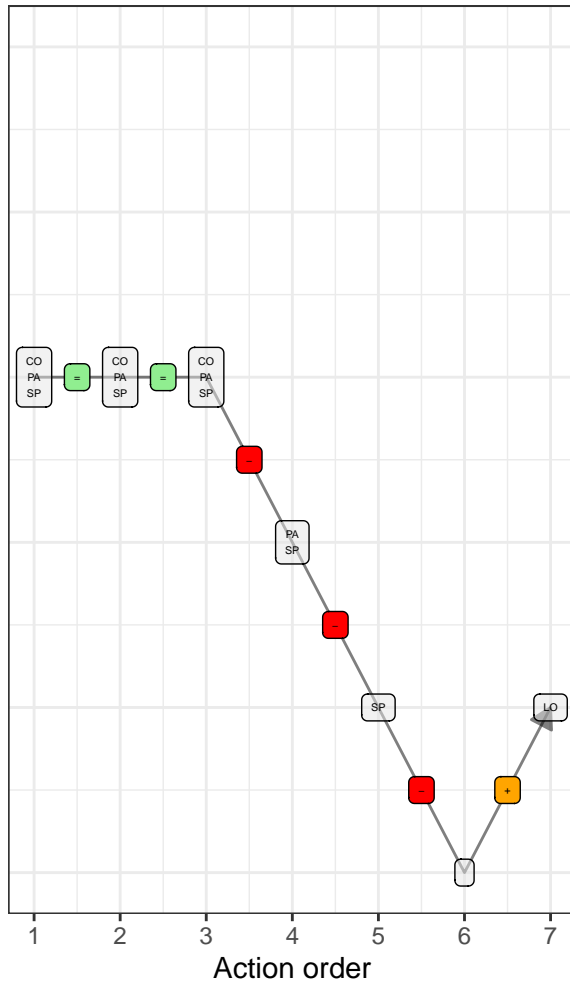
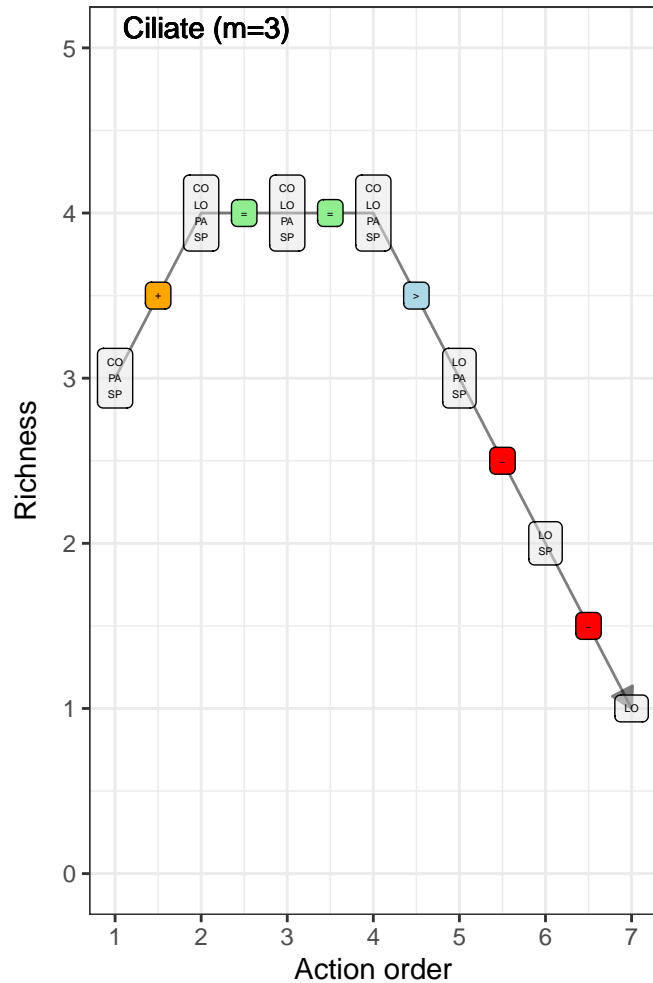
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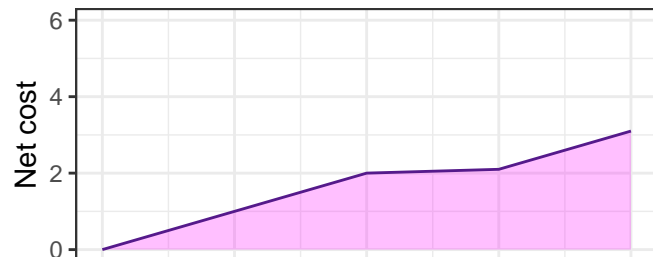
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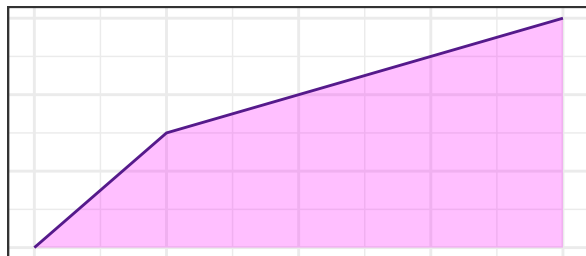
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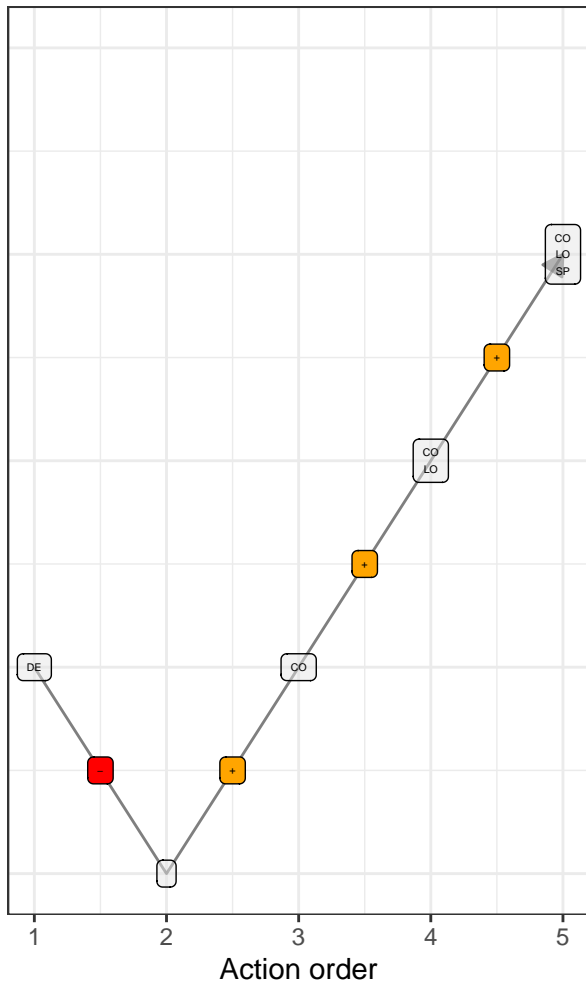
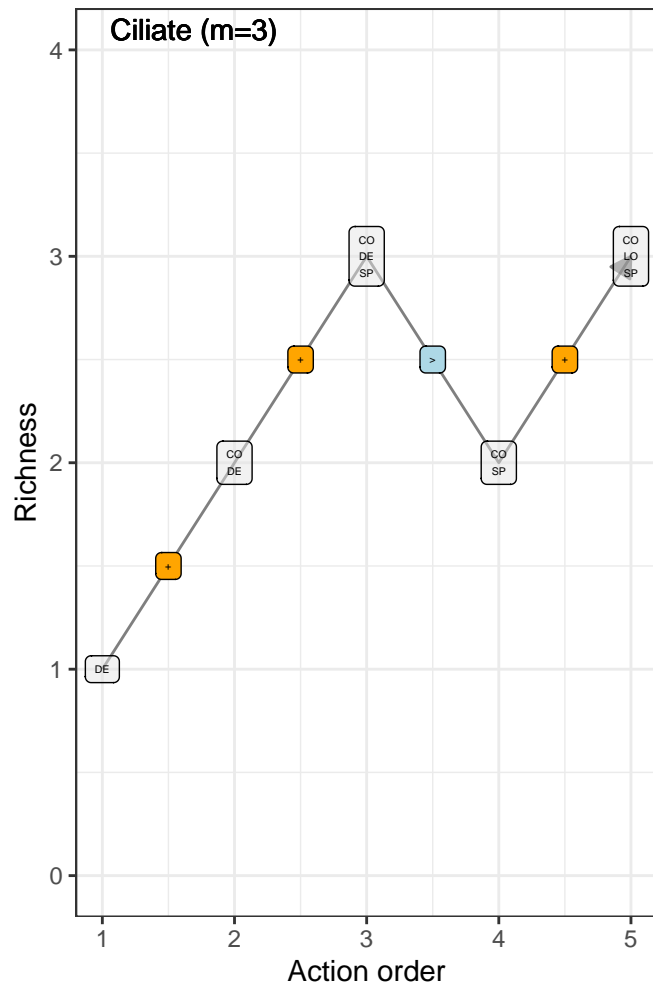
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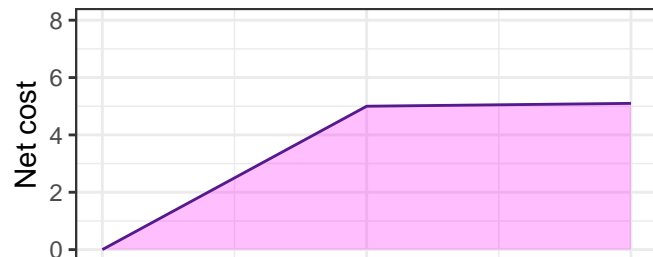
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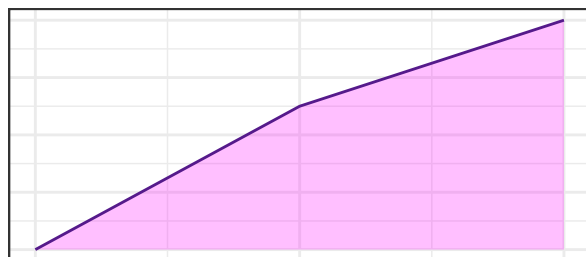
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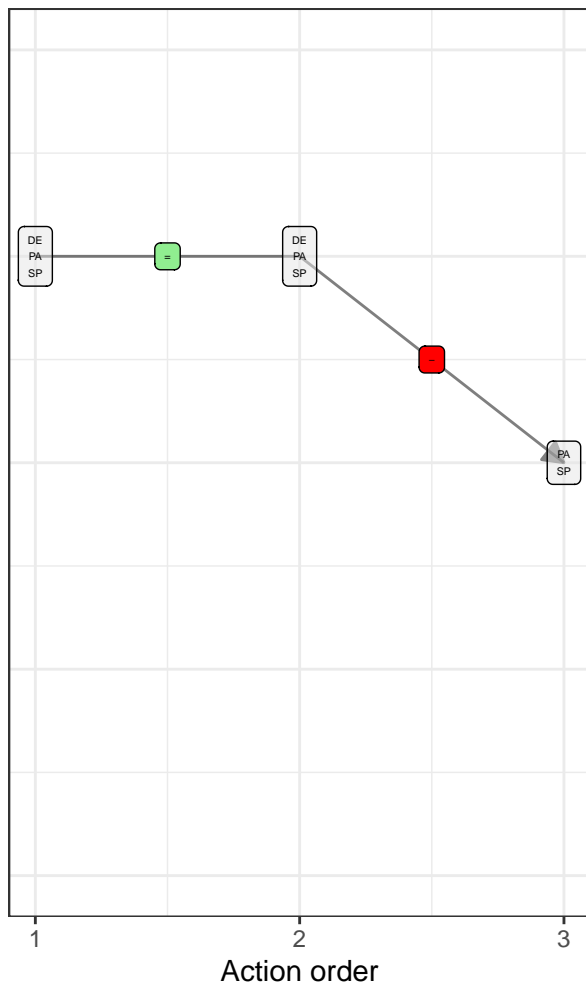
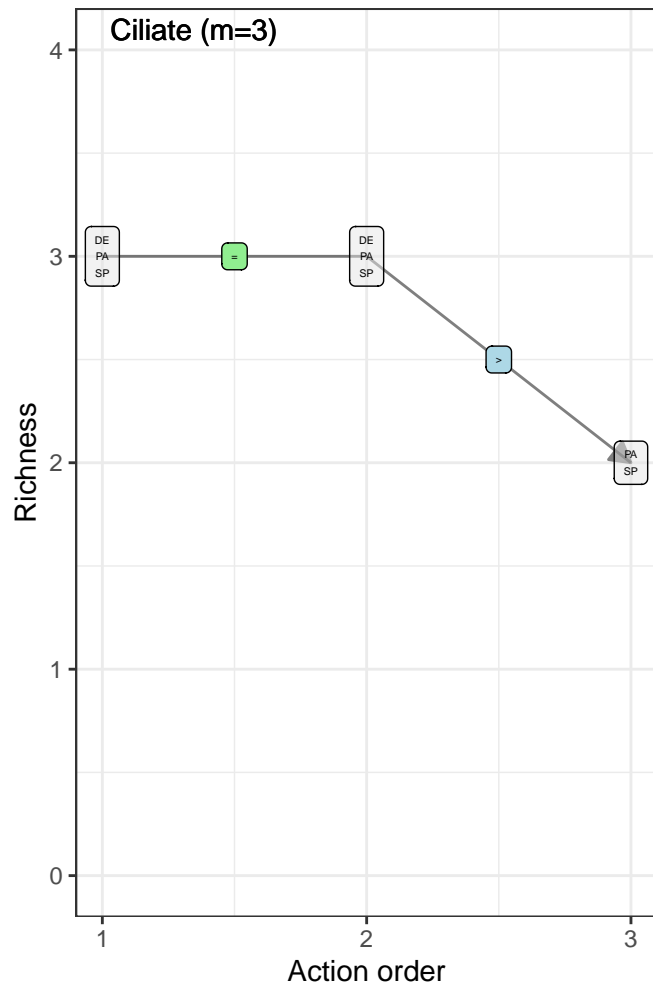
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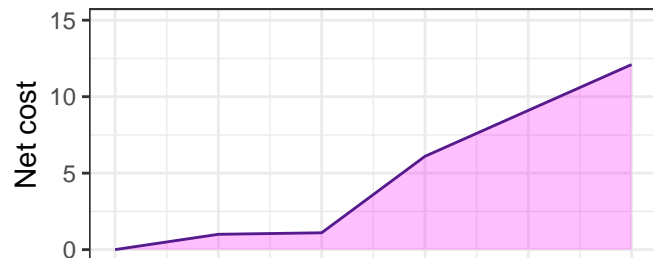
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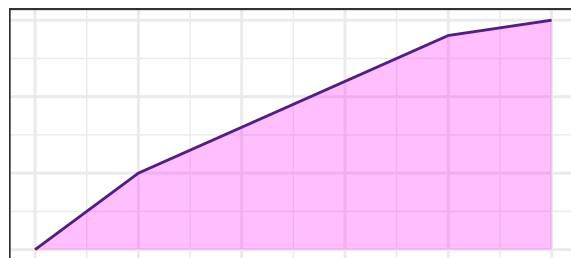
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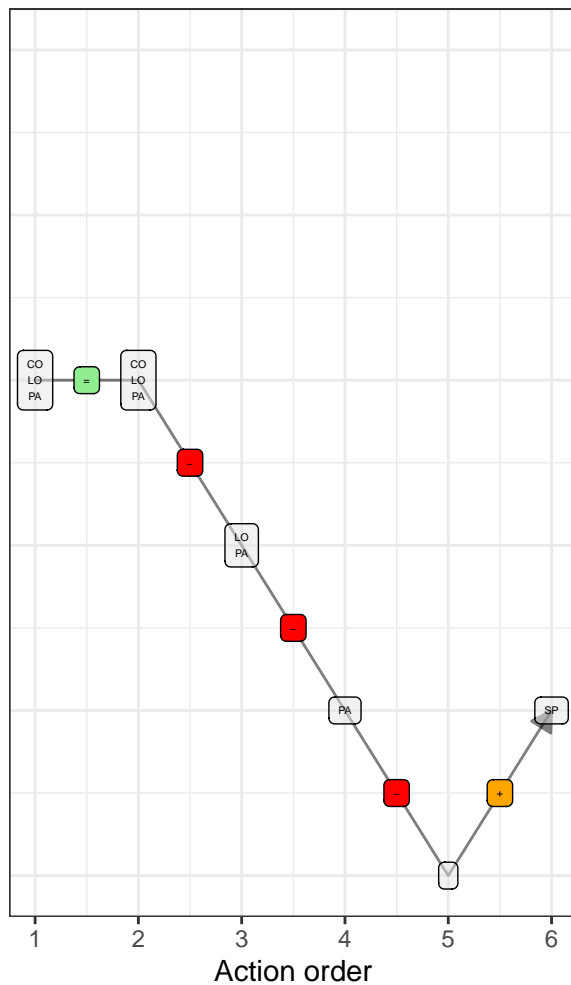
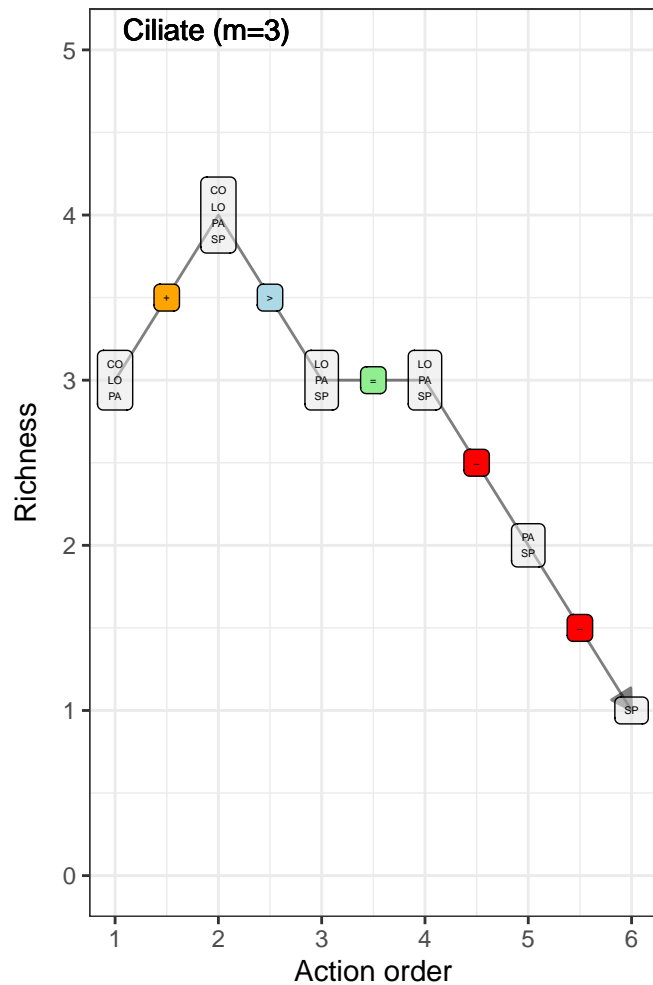
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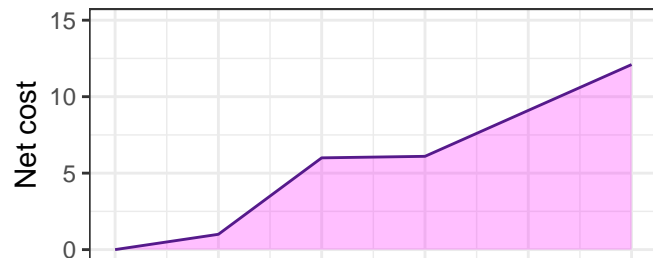
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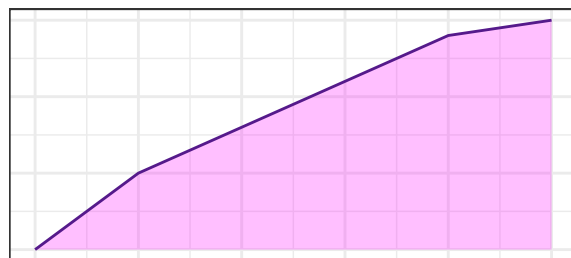
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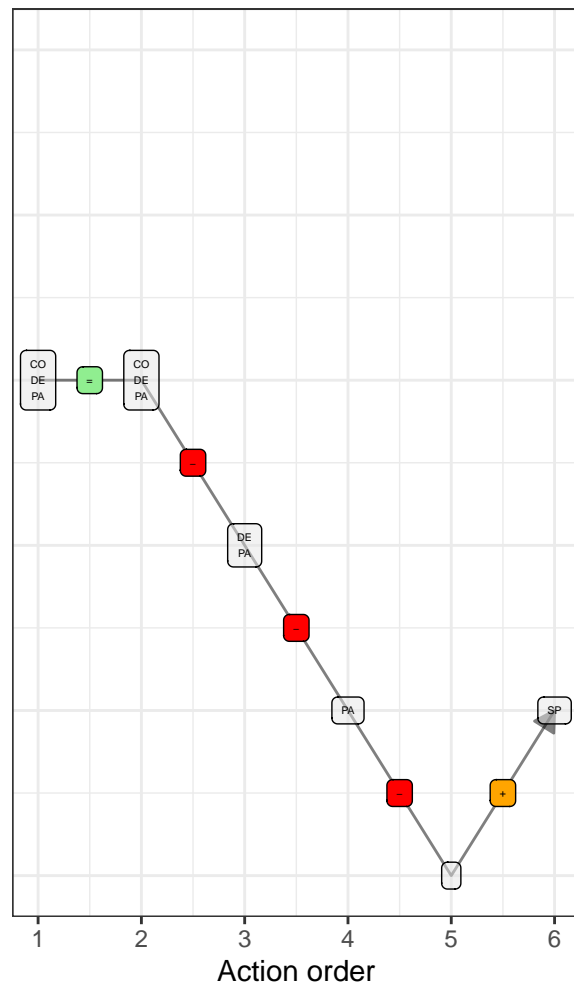
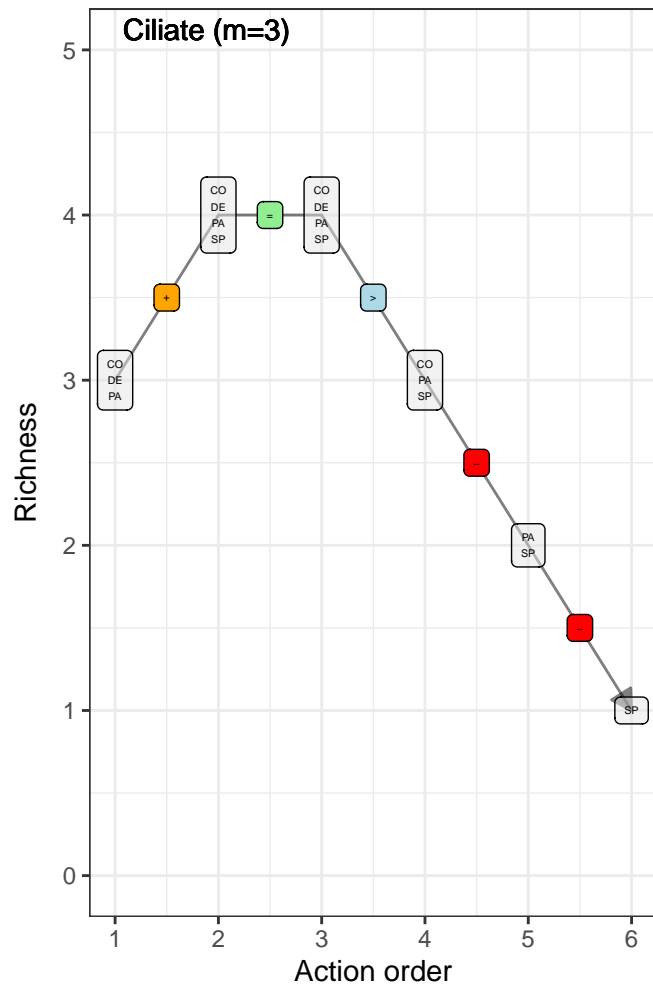
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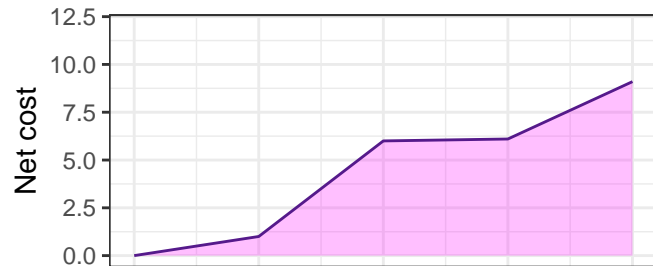
Nominal path



Ciliate (m=3)



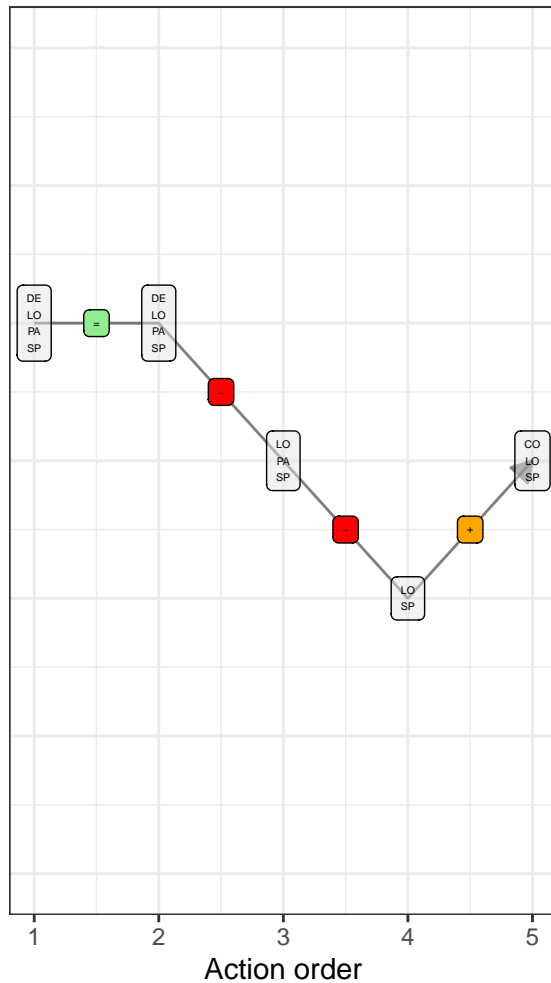
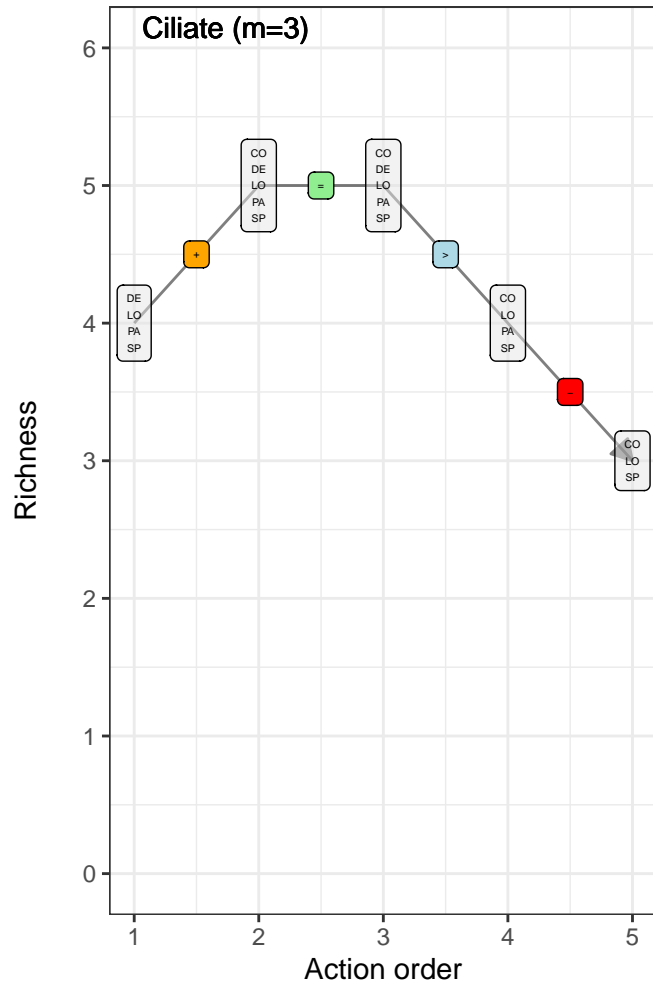
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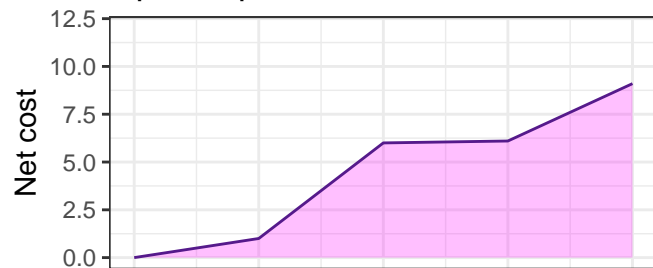
Nominal path



Ciliate (m=3)



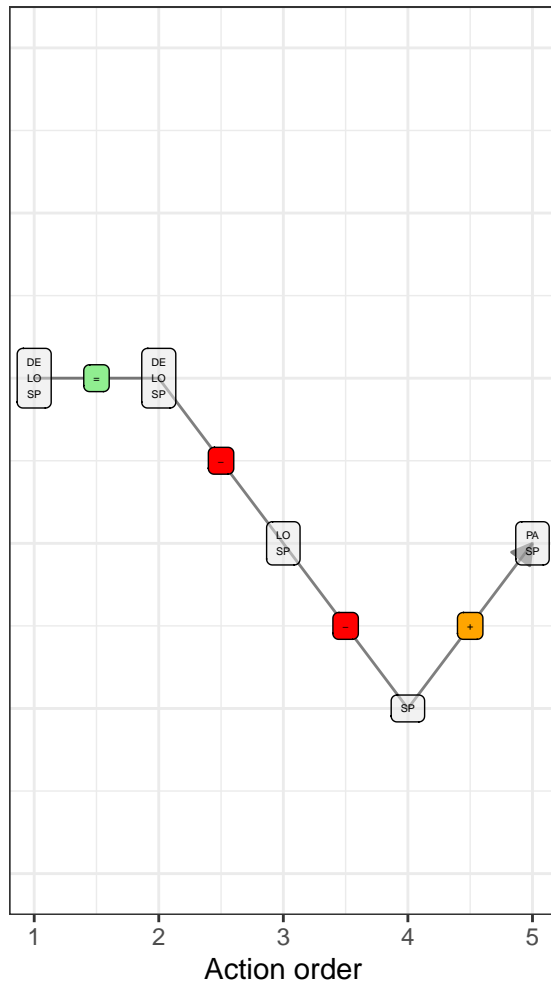
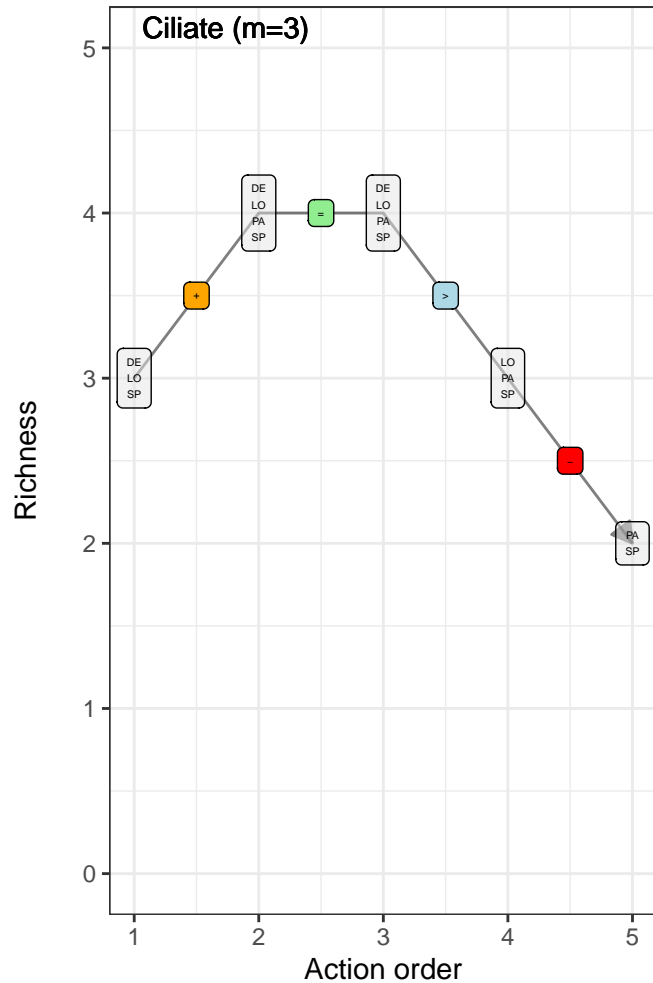
Optimal path



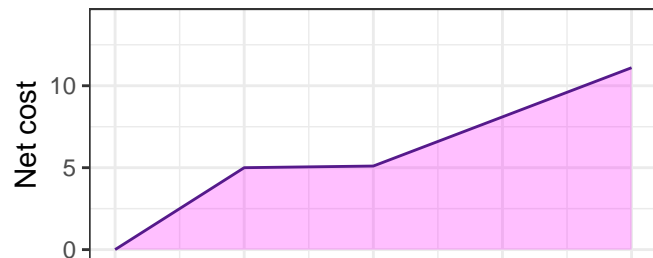
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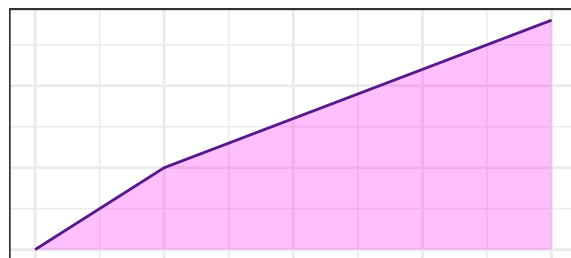
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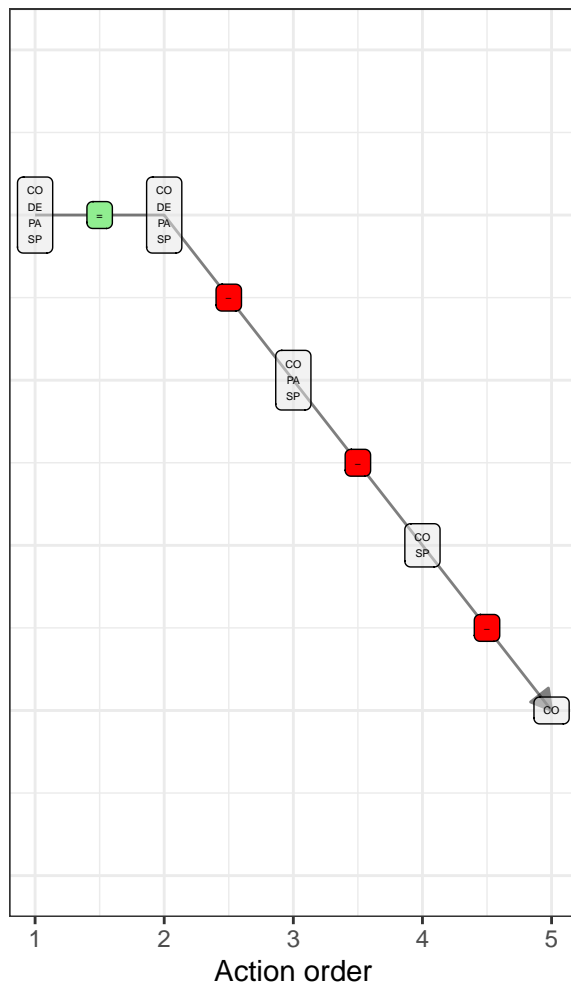
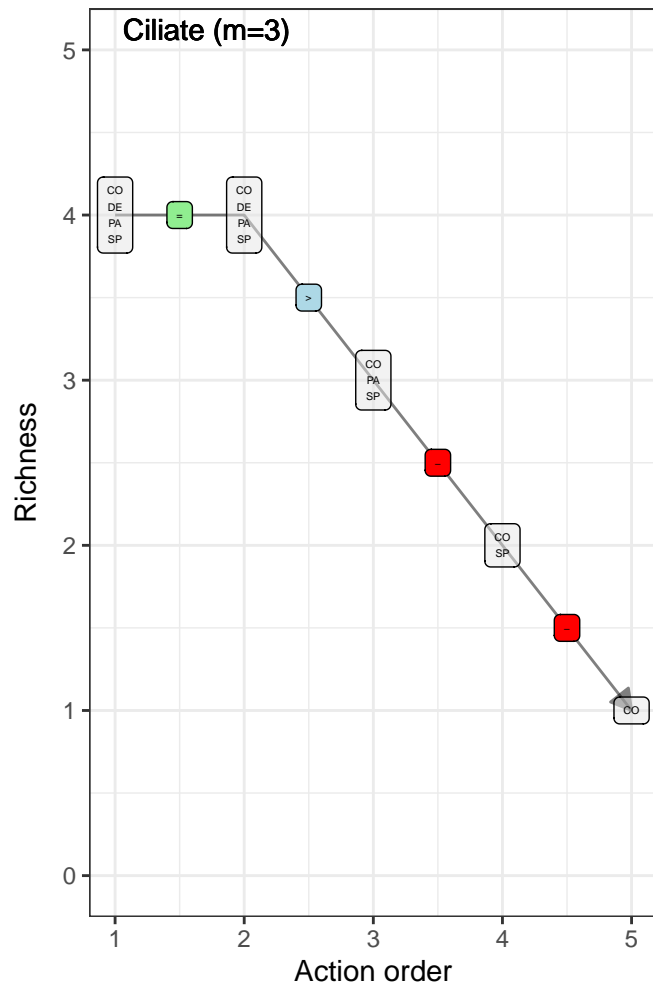
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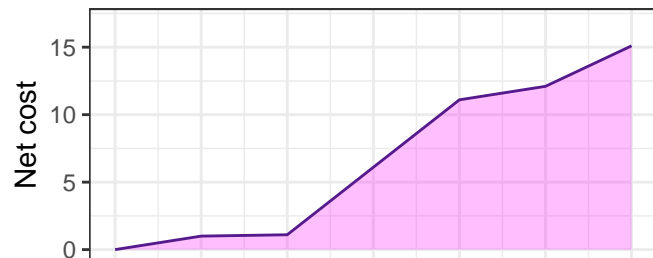
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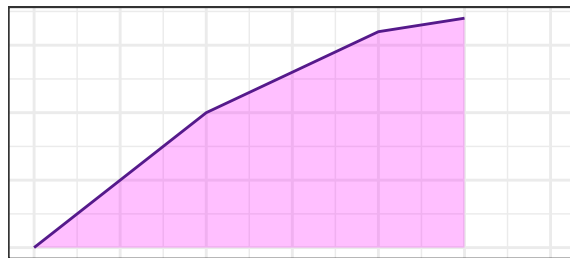
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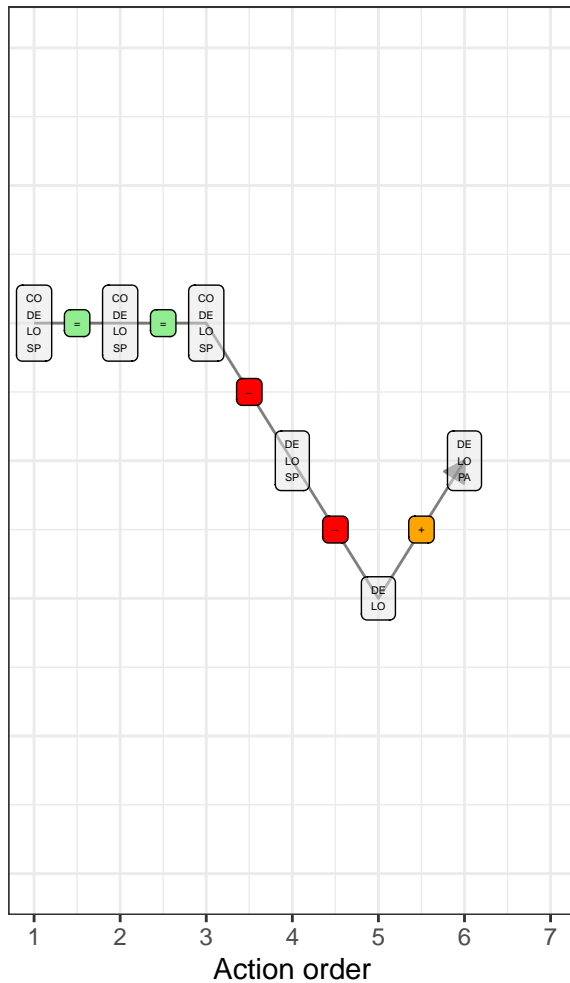
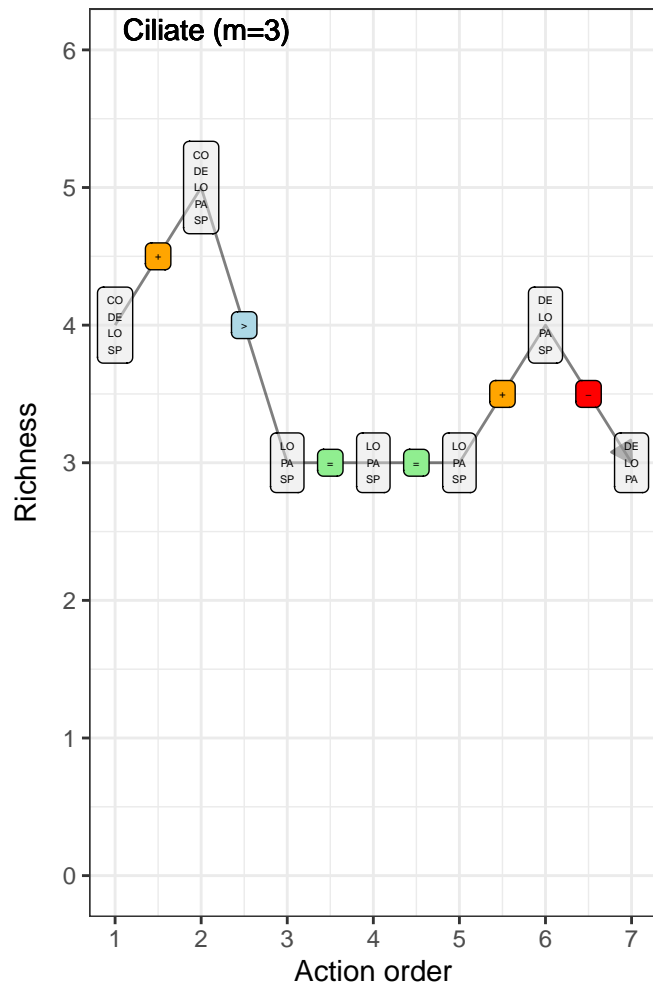
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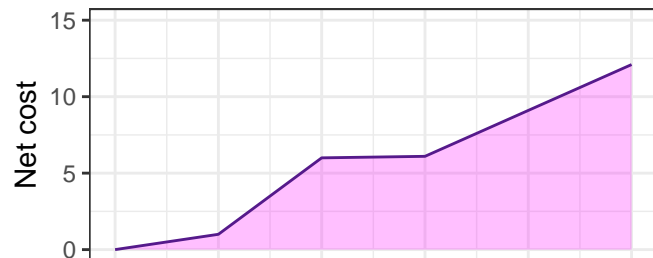
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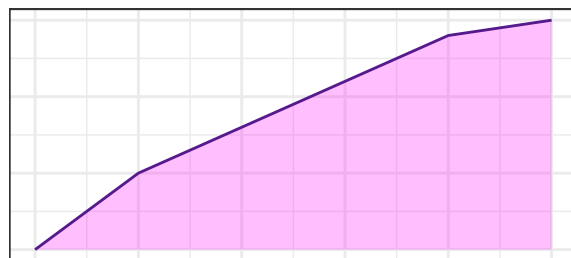
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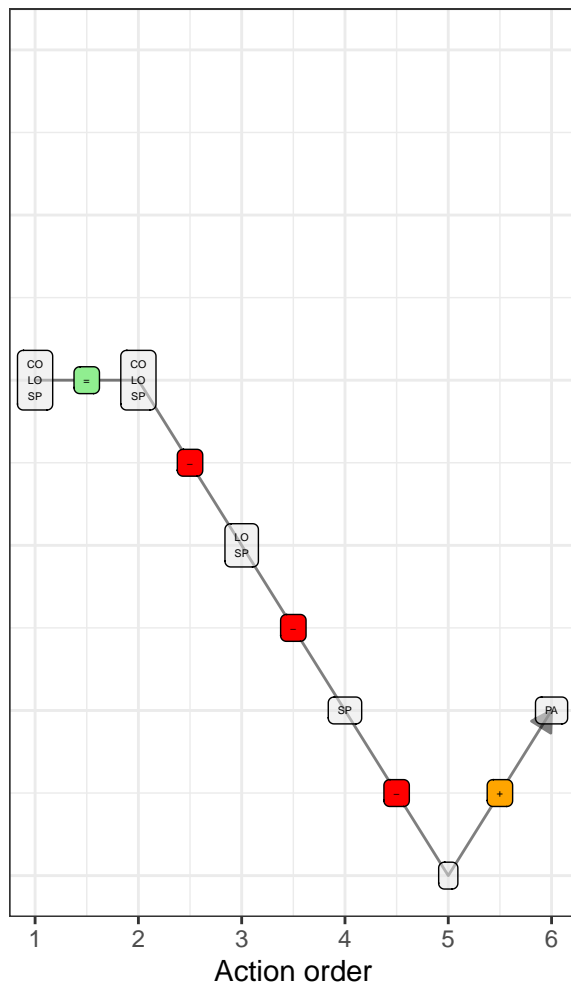
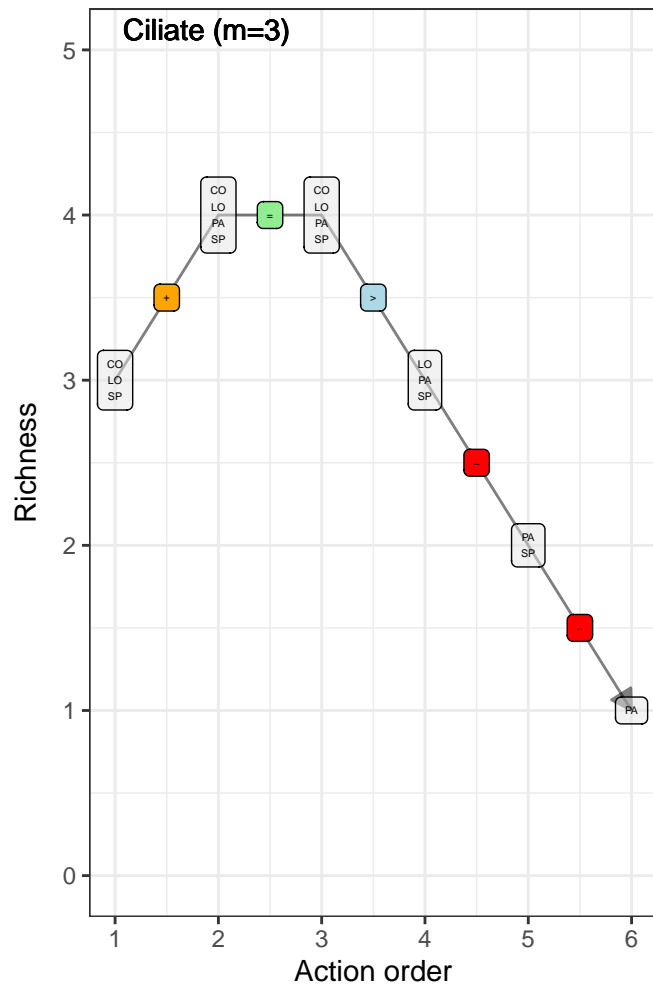
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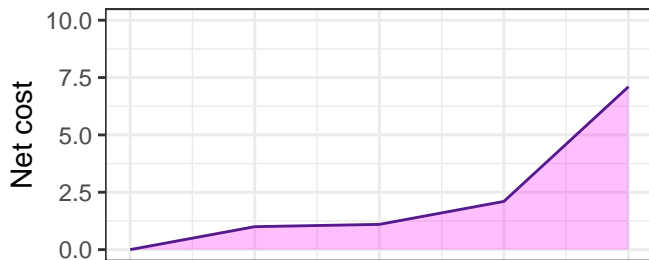
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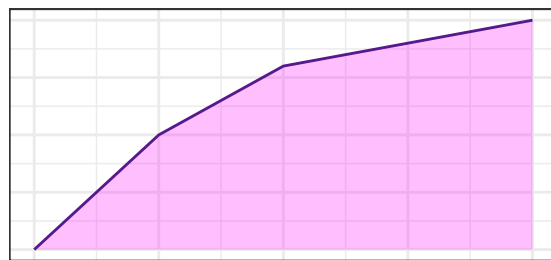
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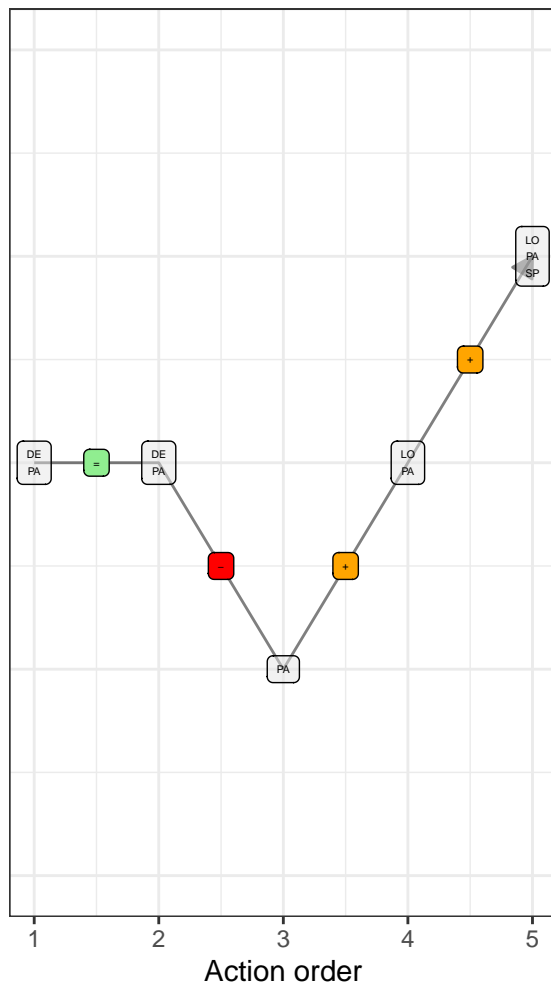
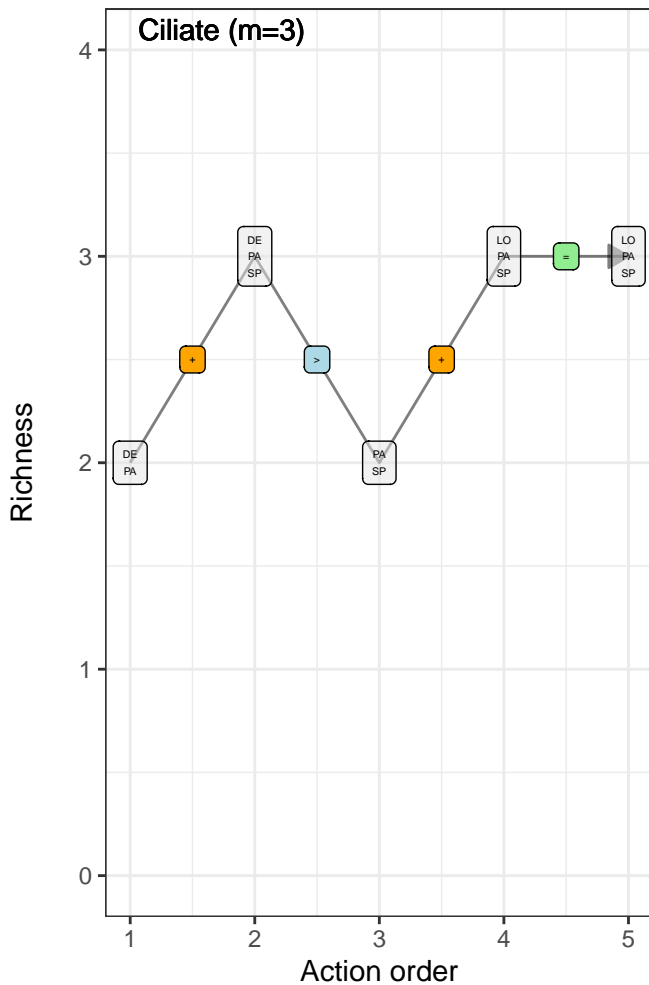
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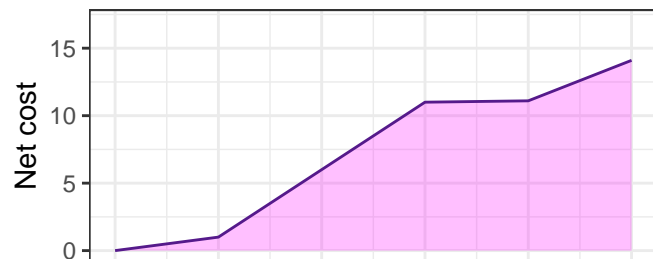
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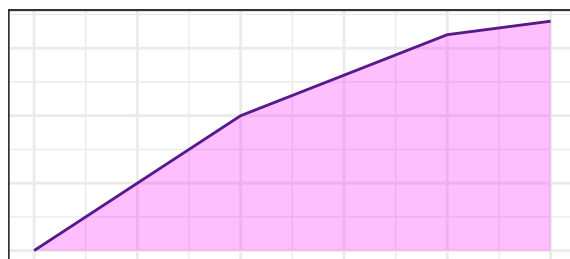
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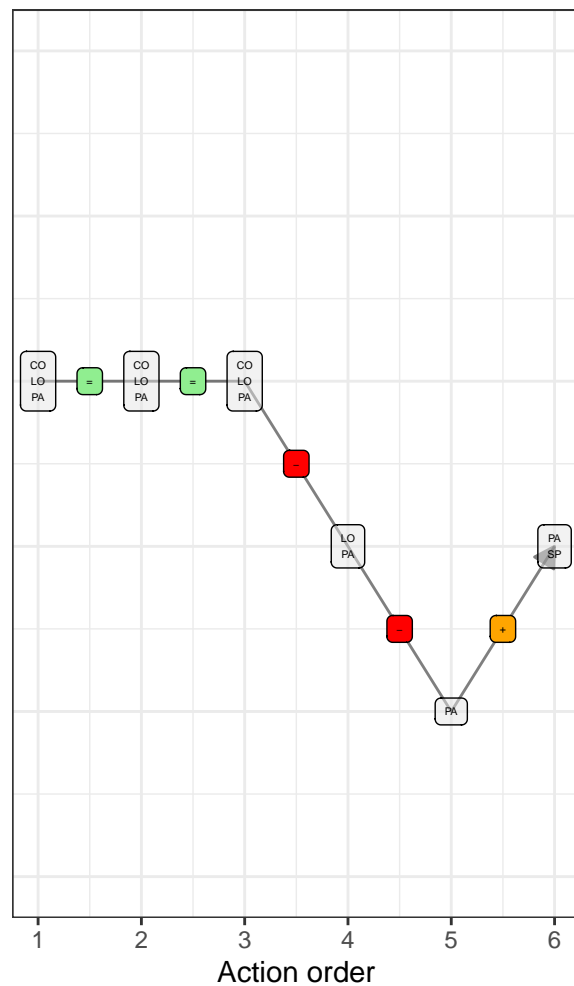
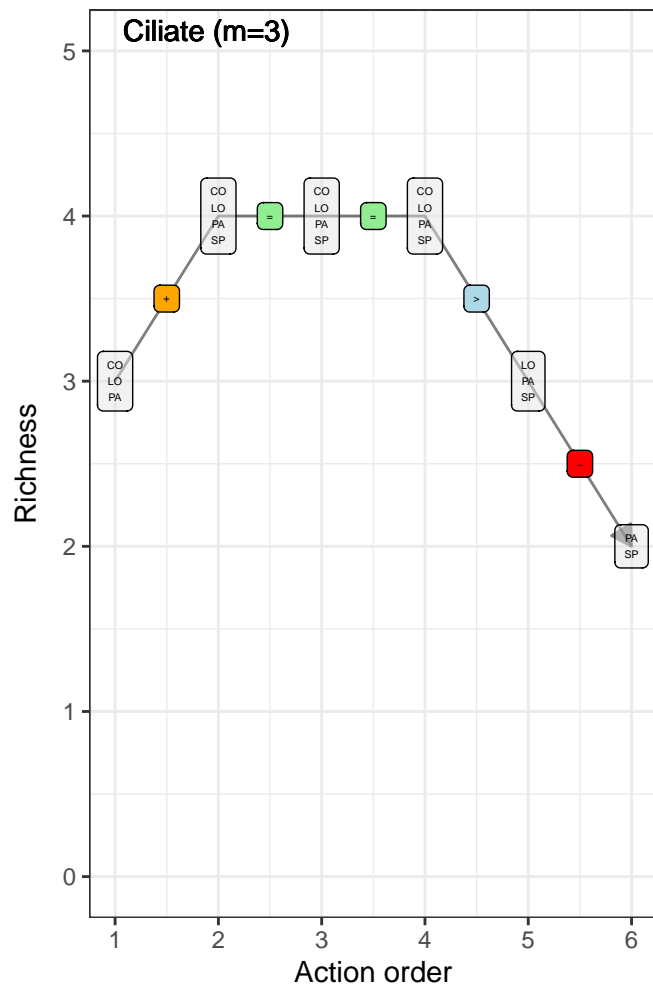
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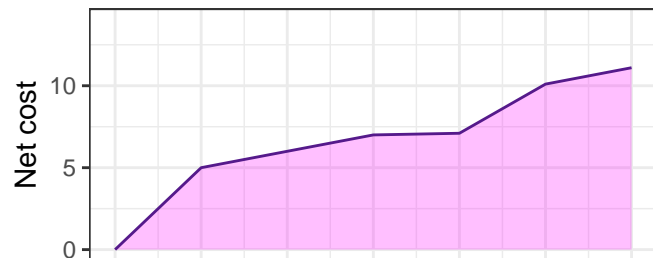
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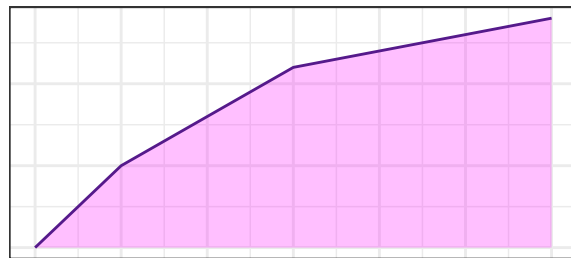
Ciliate (m=3)



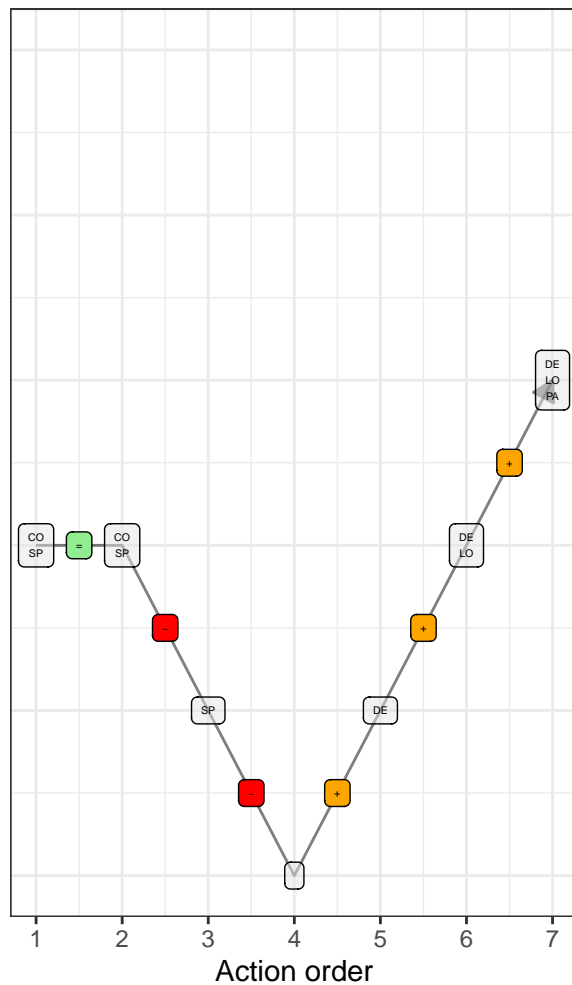
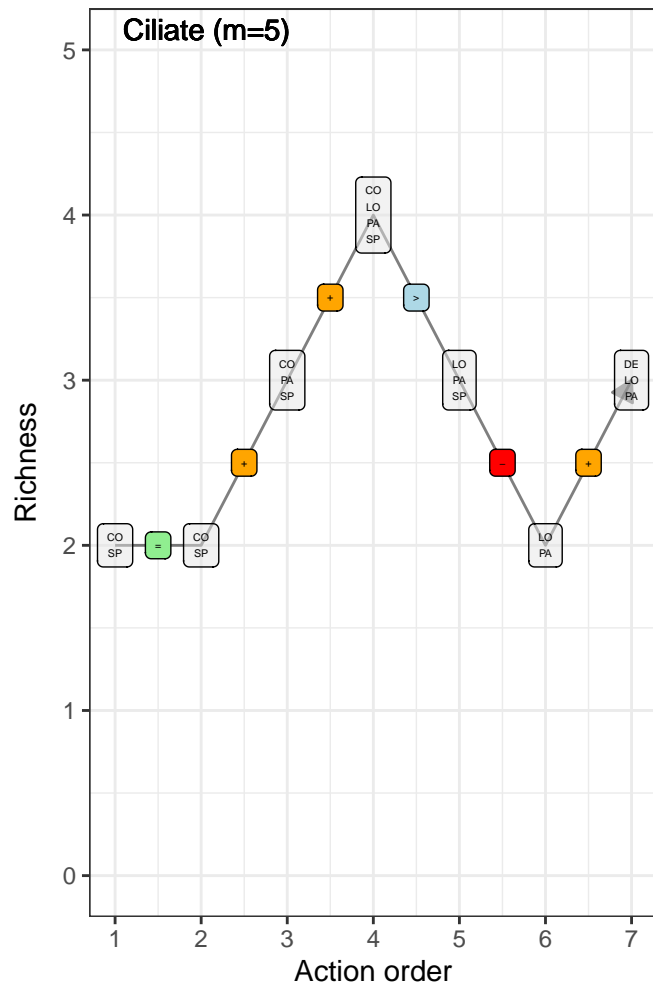
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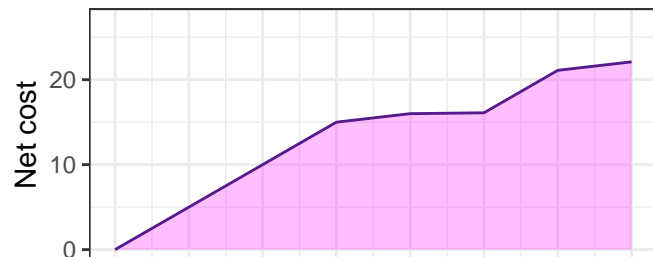
Nominal path



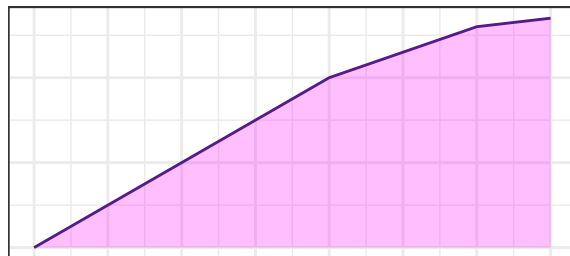
Ciliate (m=5)



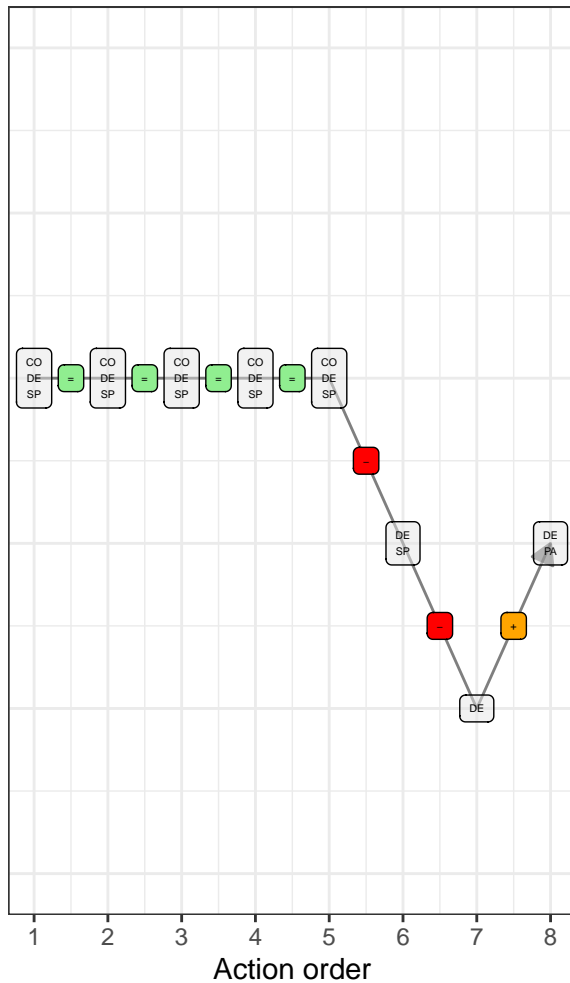
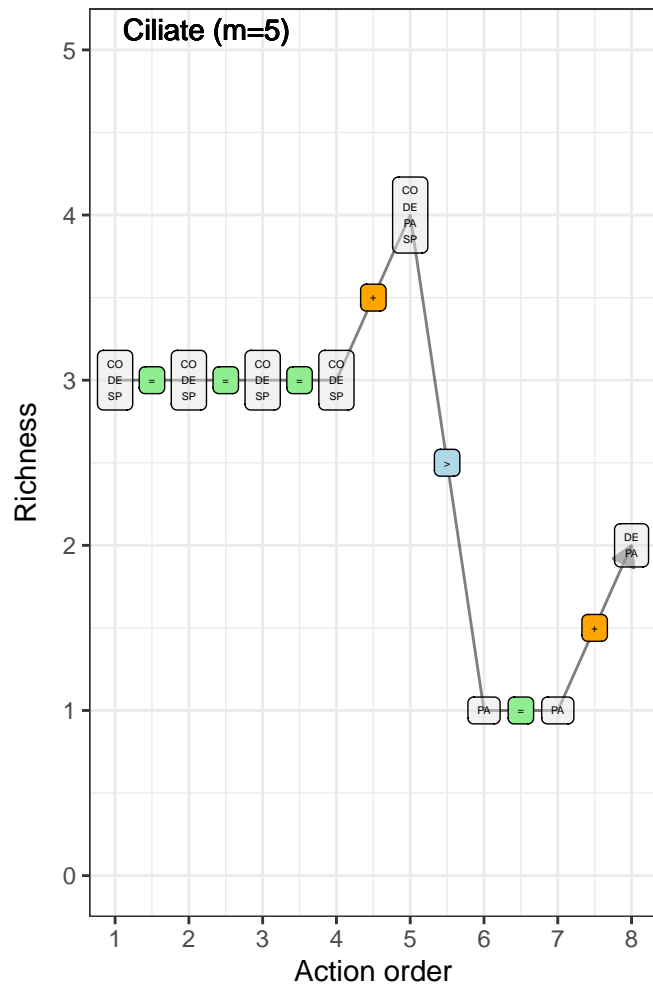
Optimal path



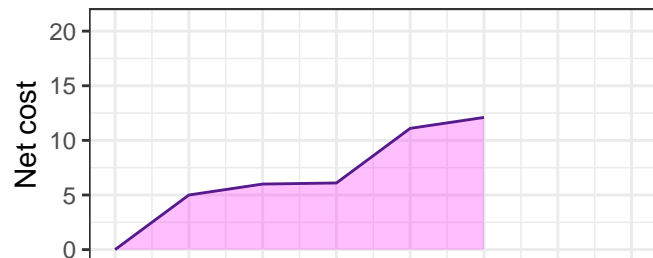
Nominal path



Ciliate (m=5)



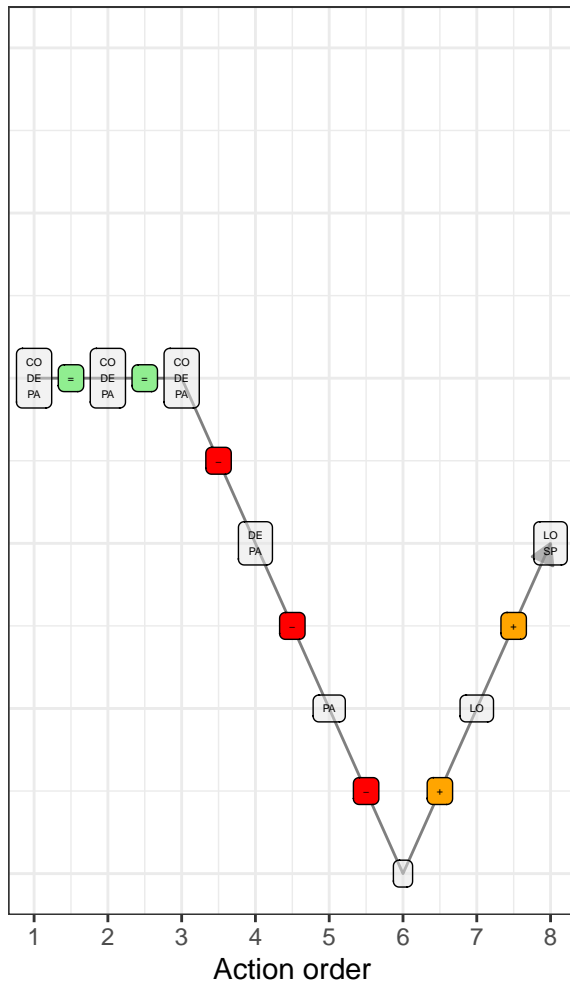
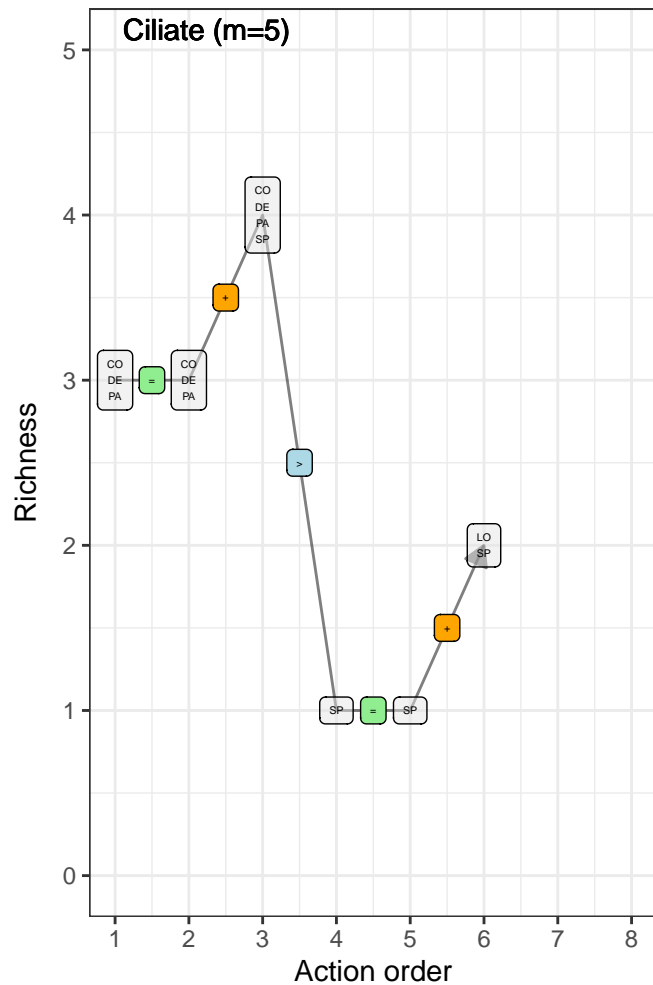
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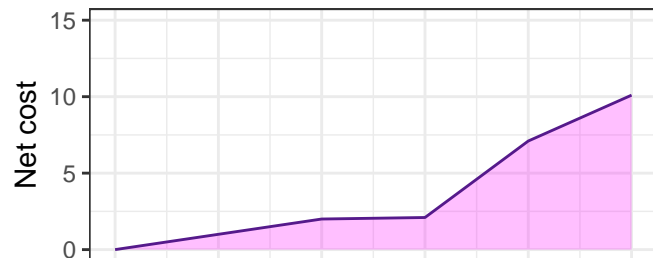
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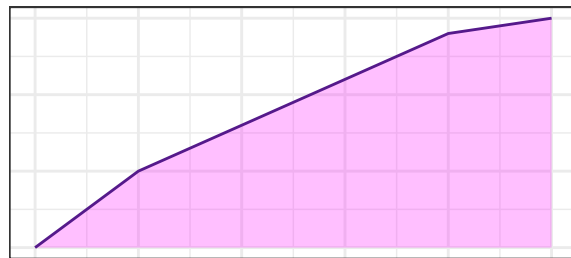
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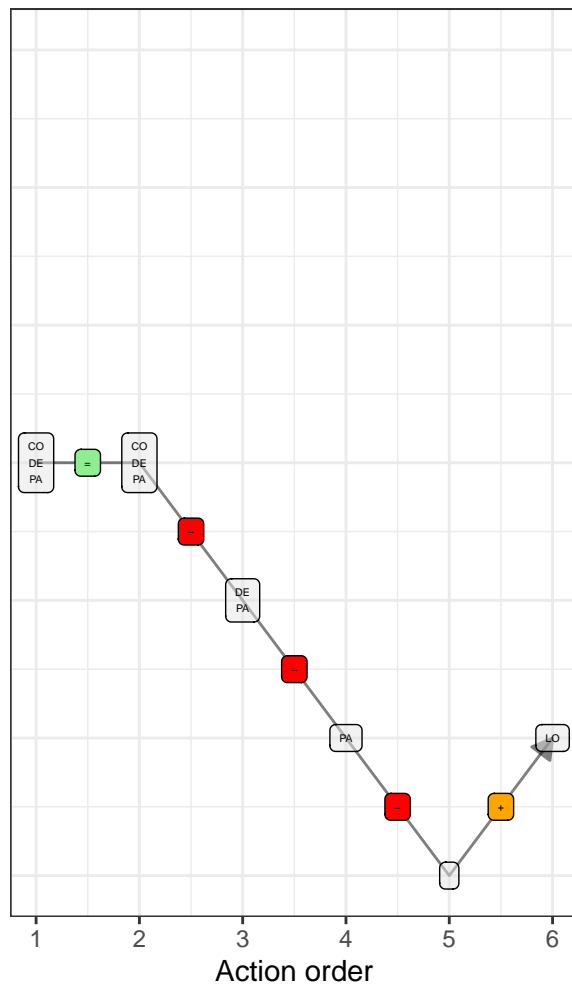
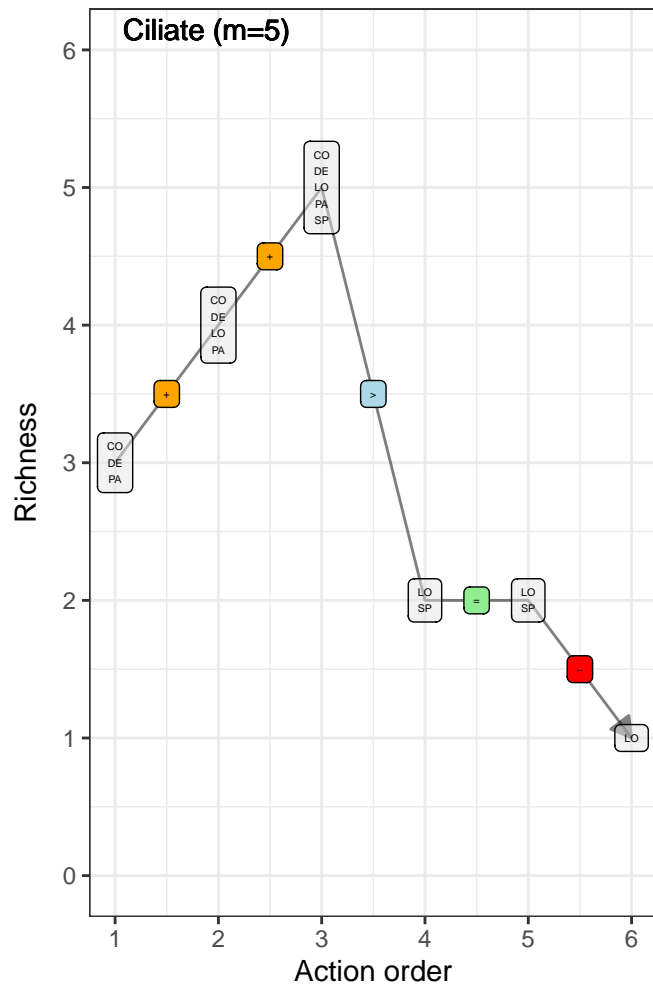
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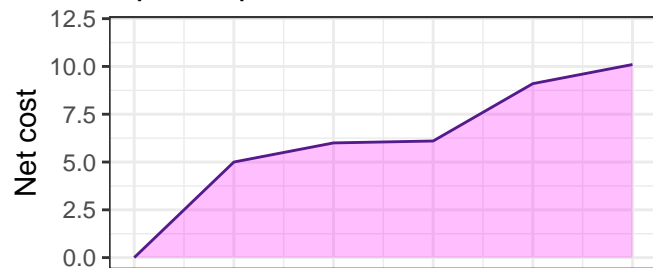
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Ciliate (m=5)



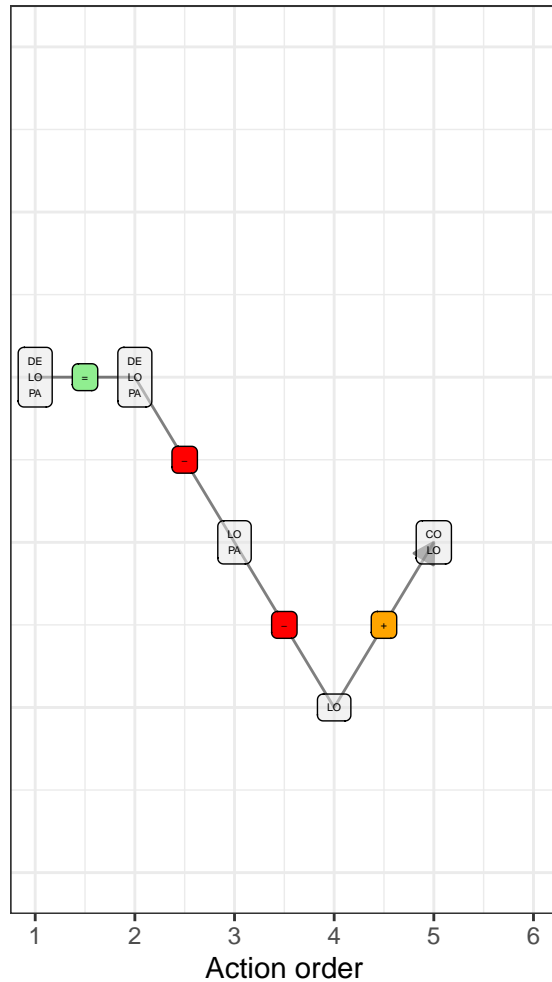
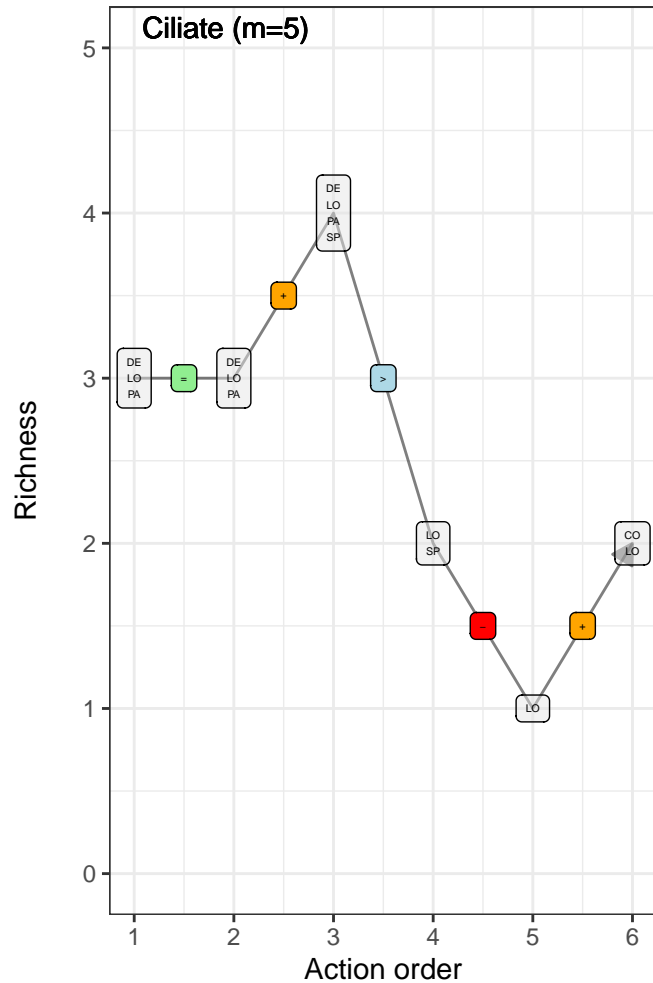
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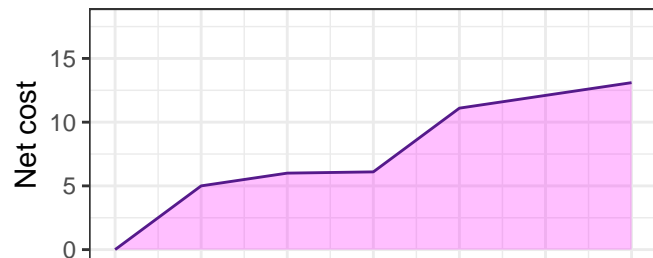
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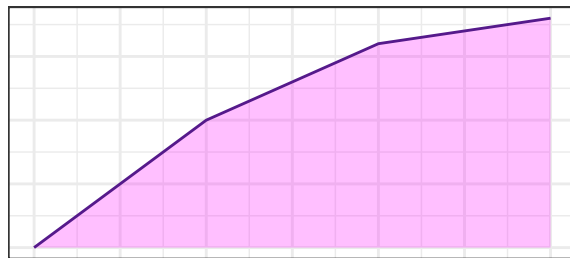
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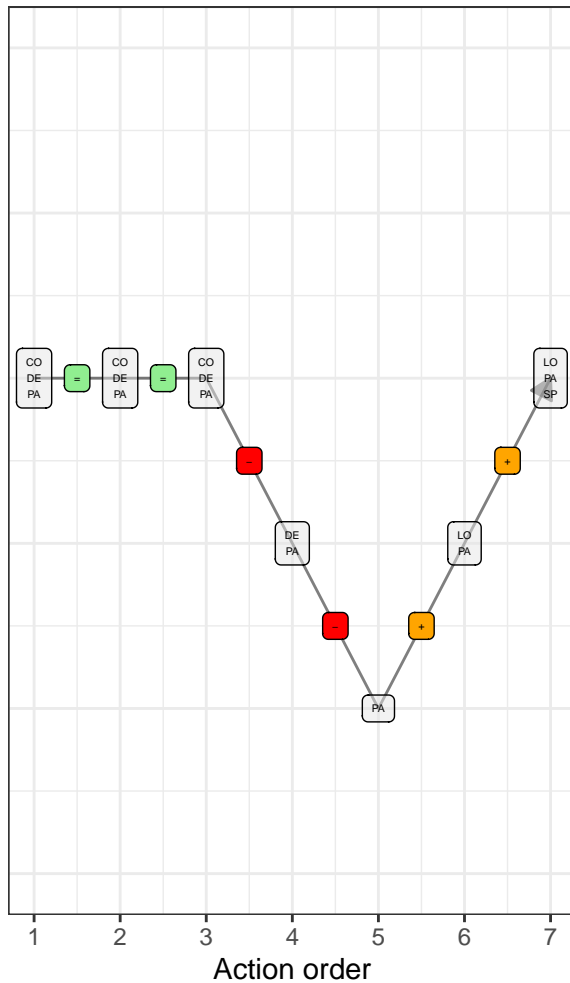
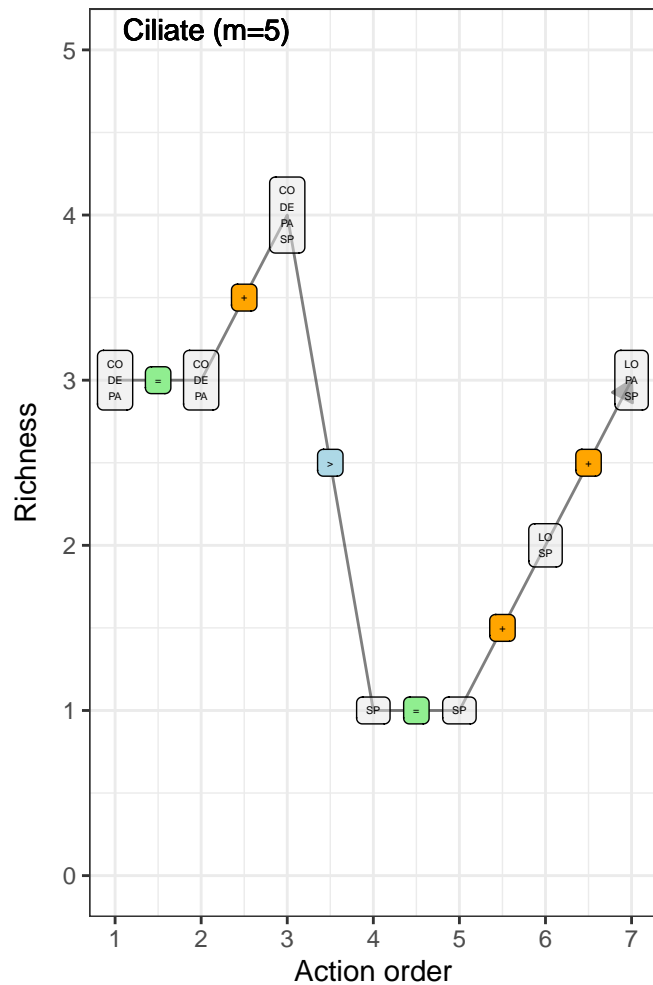
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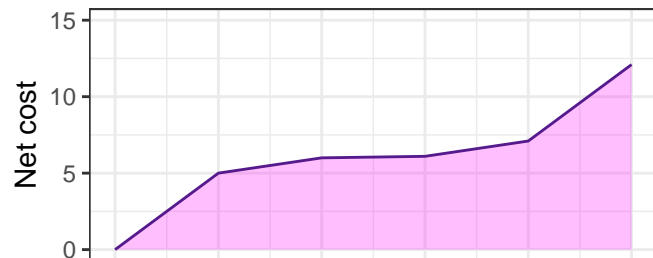
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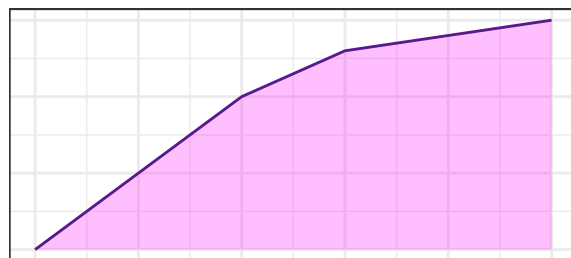
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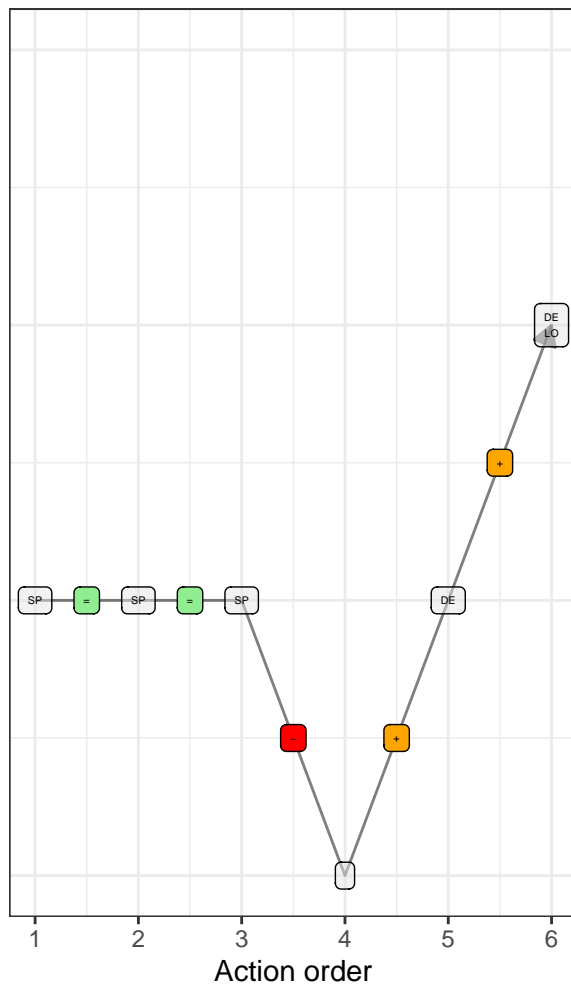
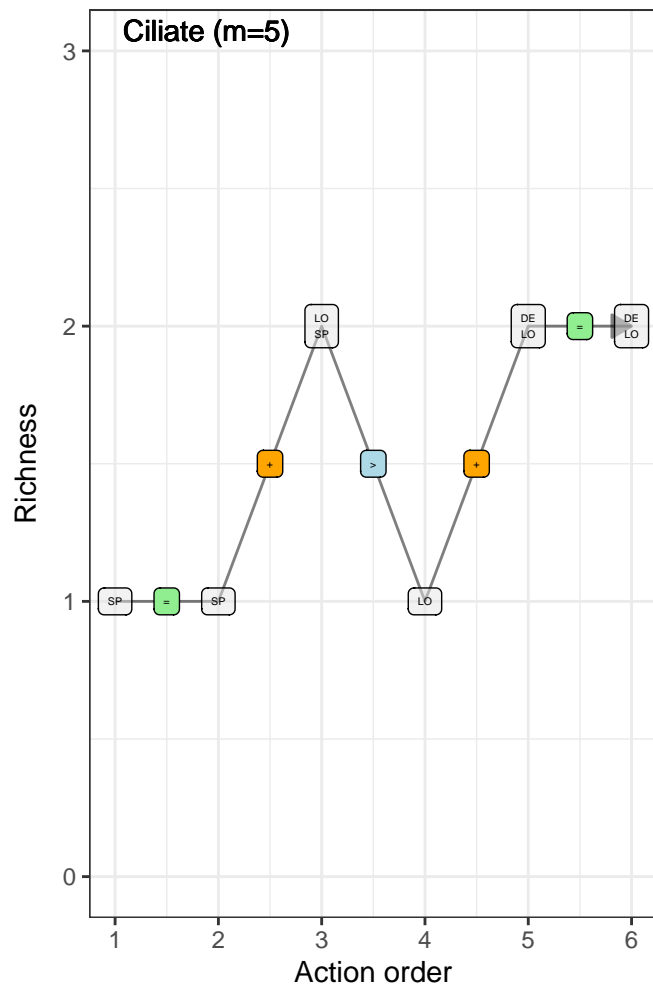
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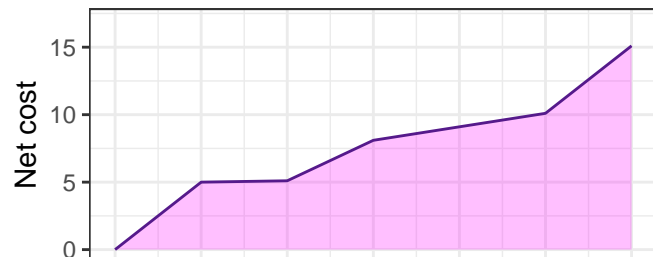
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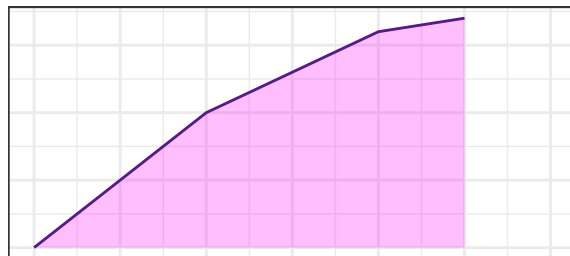
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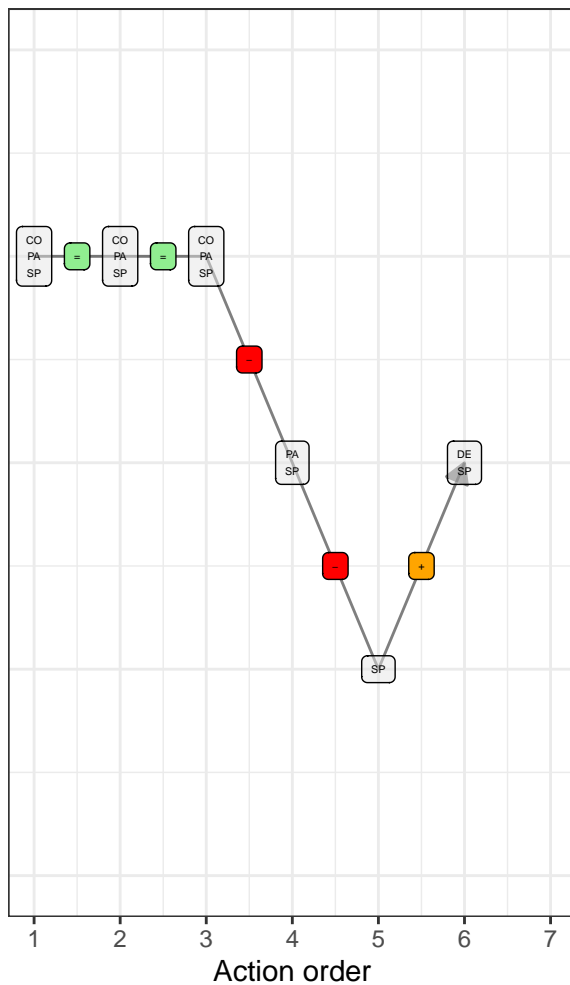
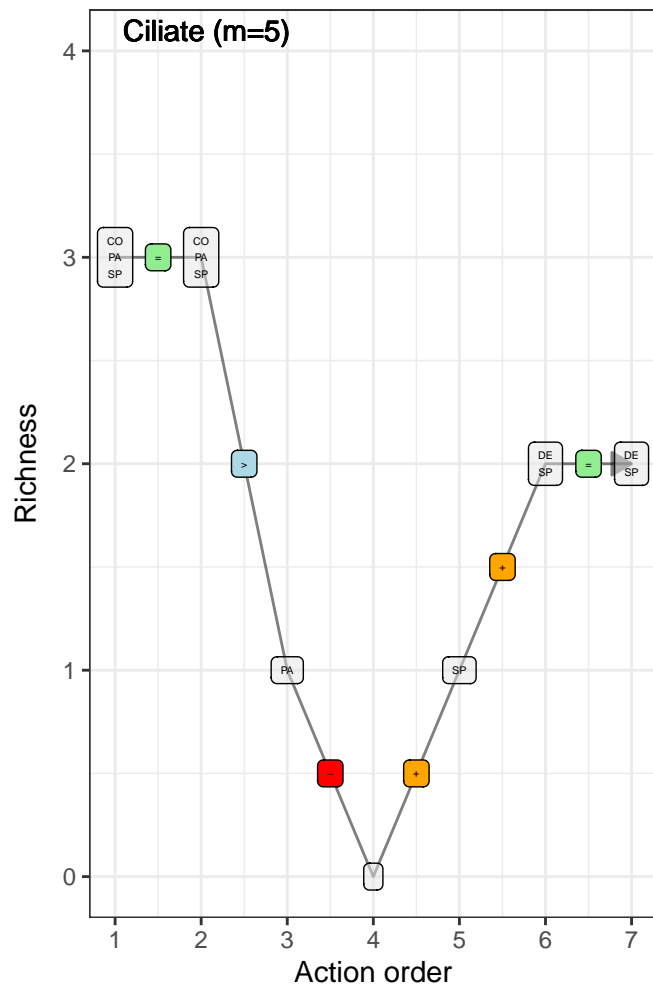
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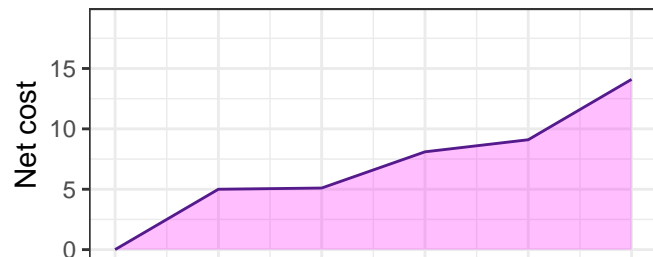
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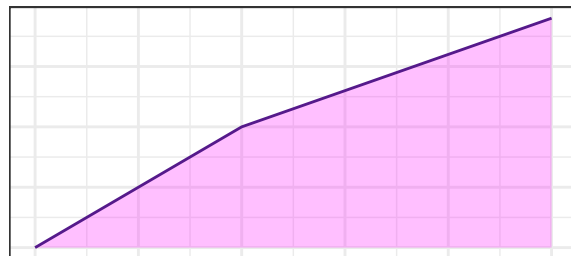
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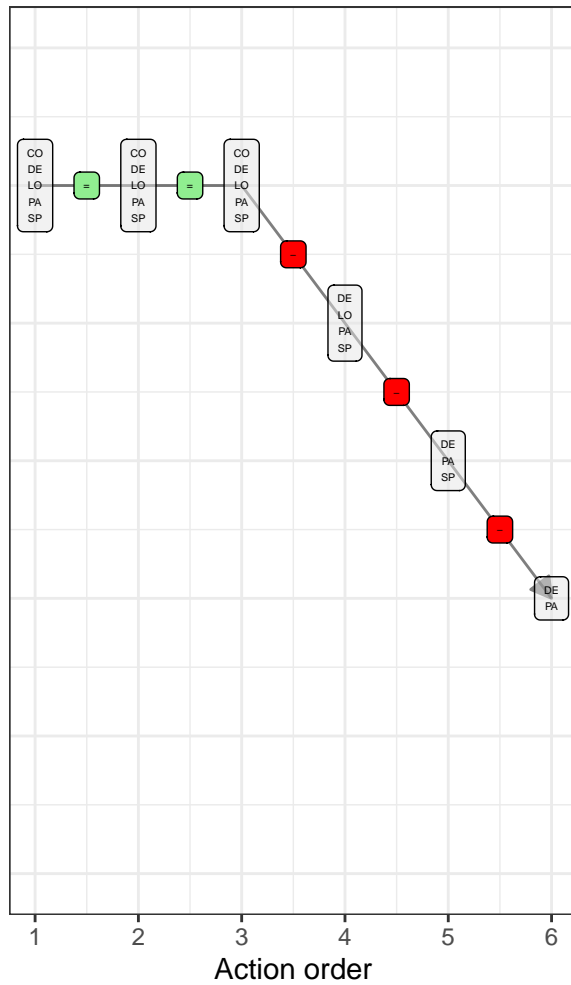
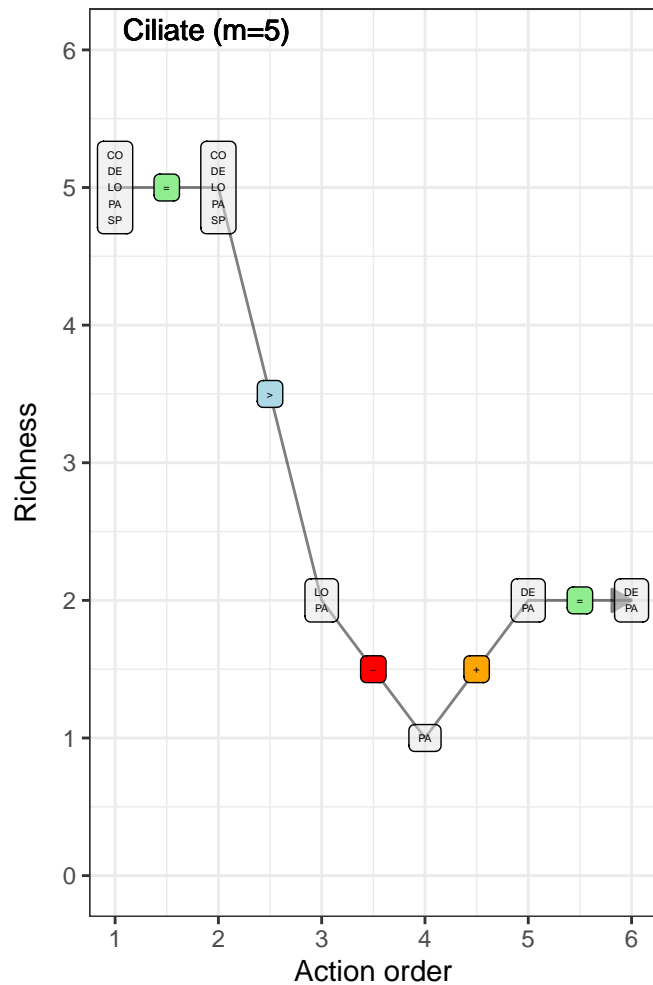
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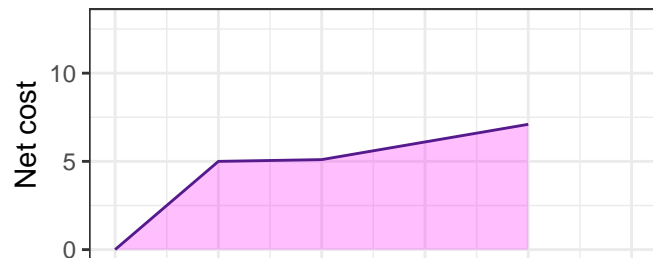
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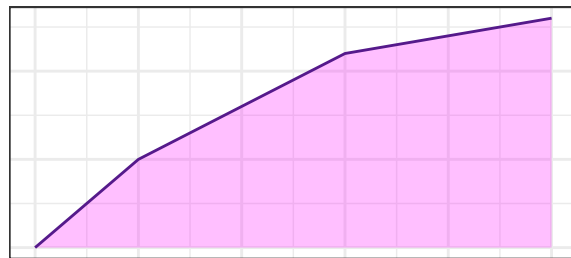
Ciliate (m=5)



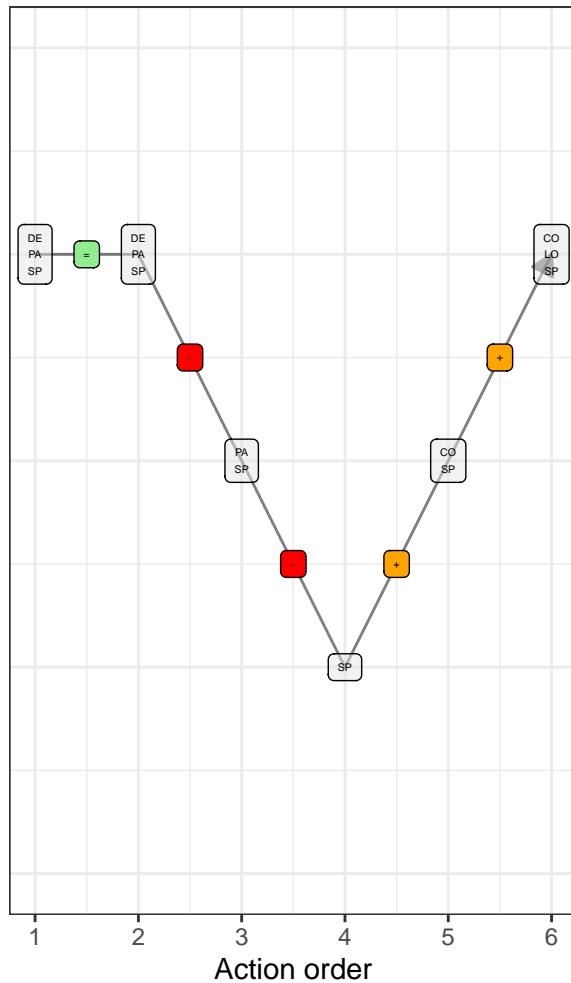
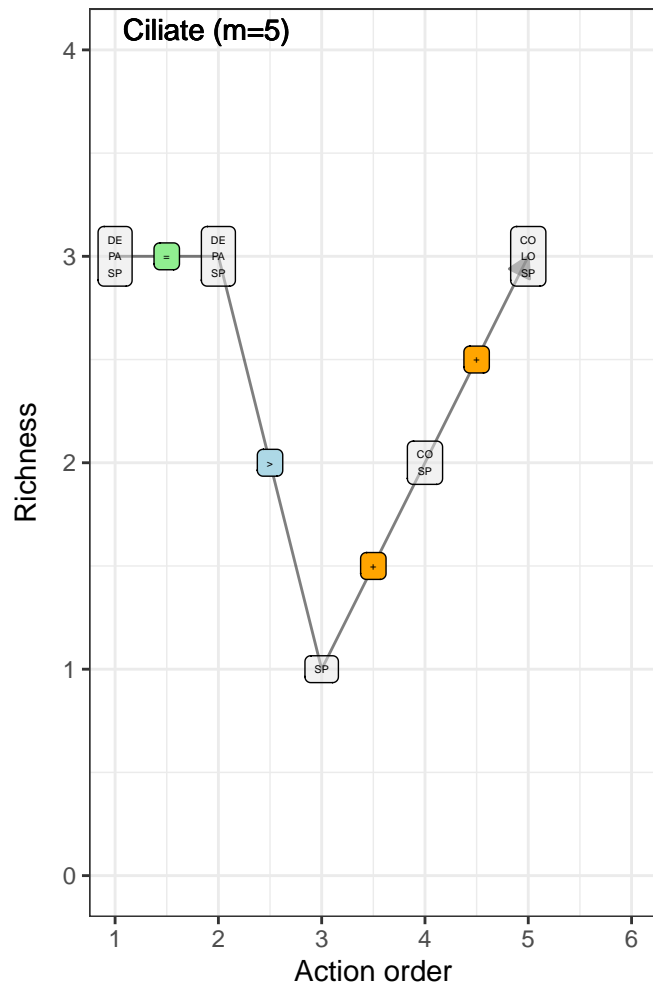
Optimal path



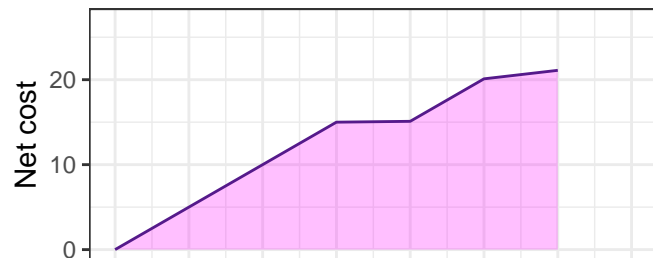
Nominal path



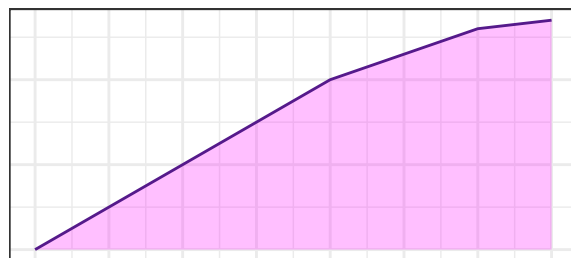
Ciliate (m=5)



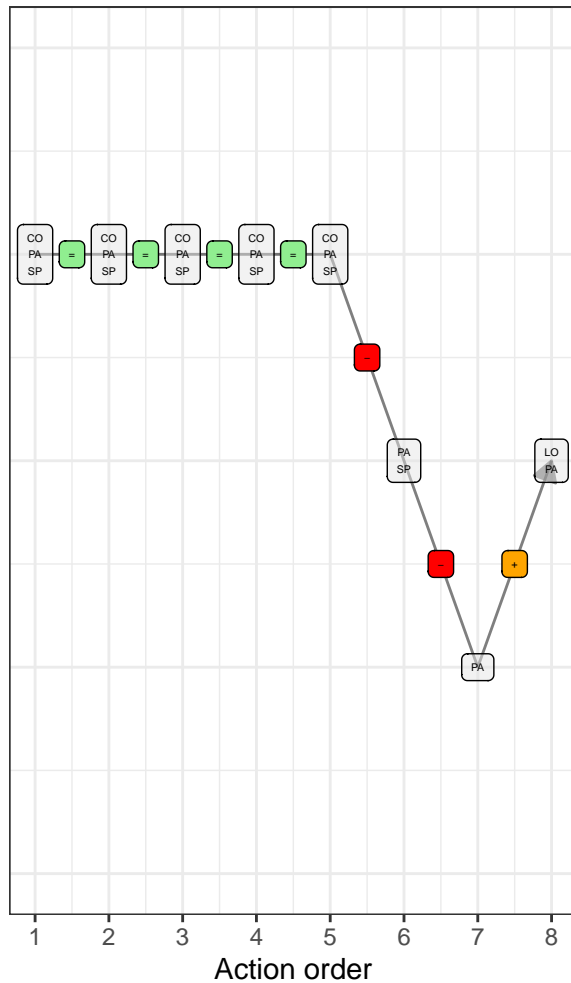
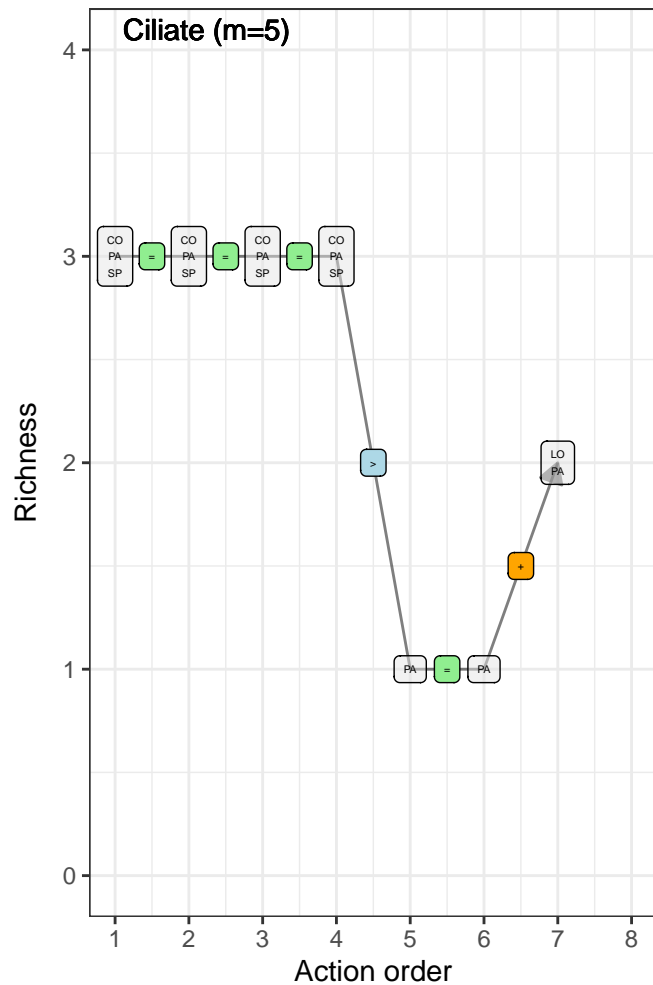
Optimal path



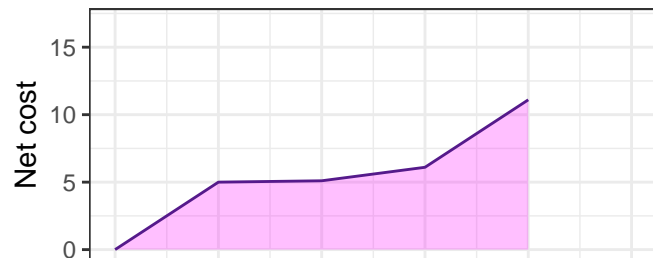
Nominal path



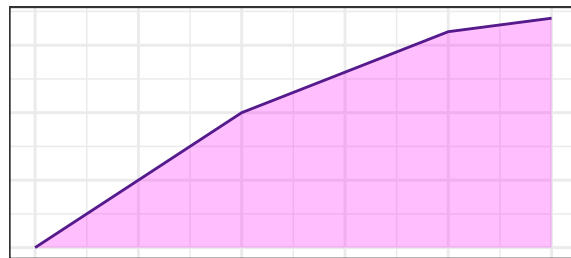
Ciliate (m=5)



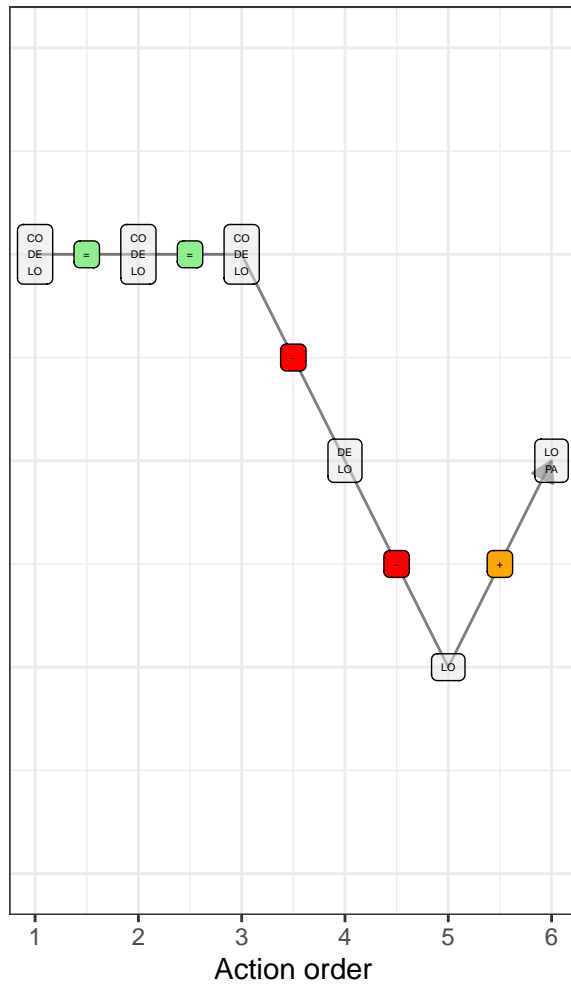
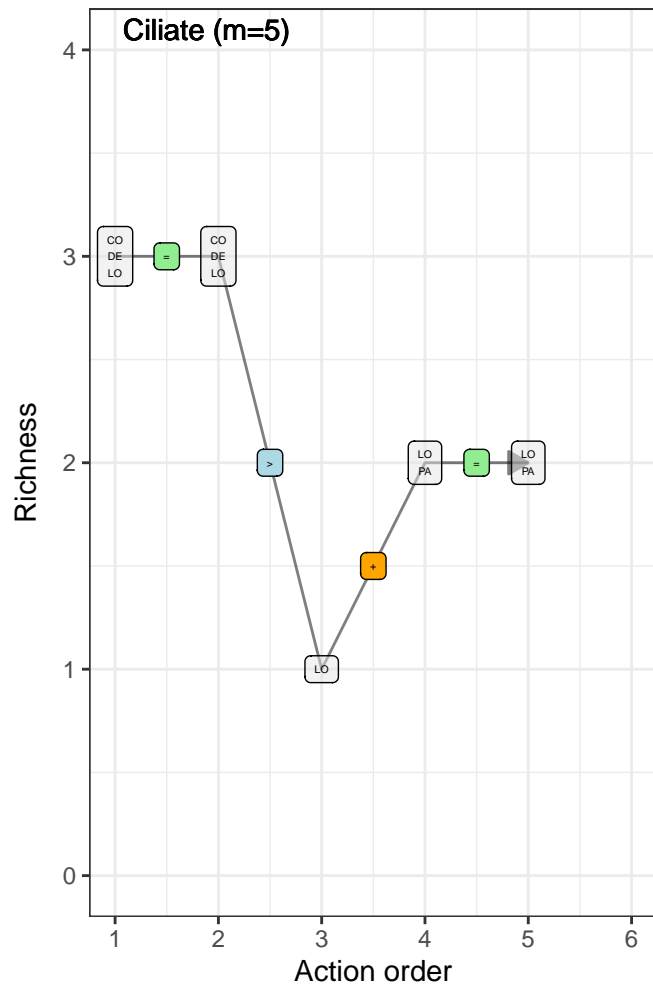
Optimal path



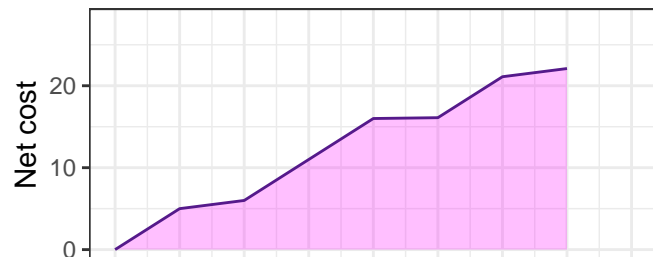
Nominal path



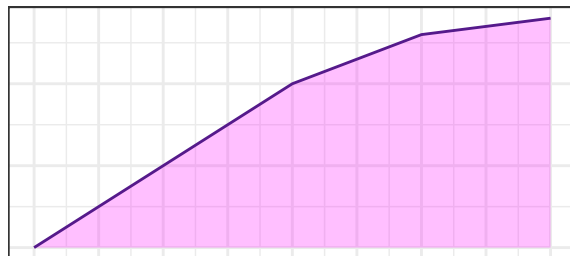
Ciliate (m=5)



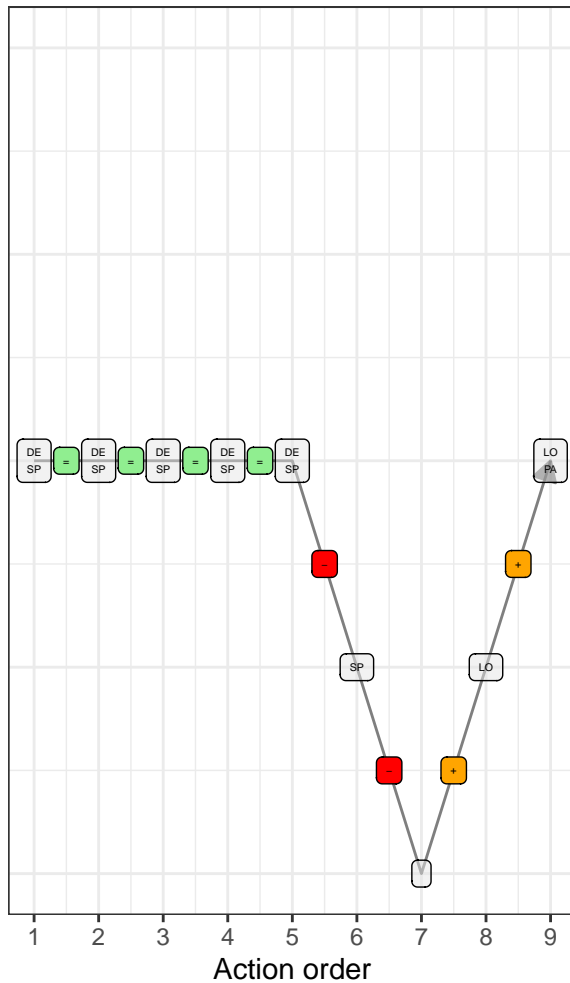
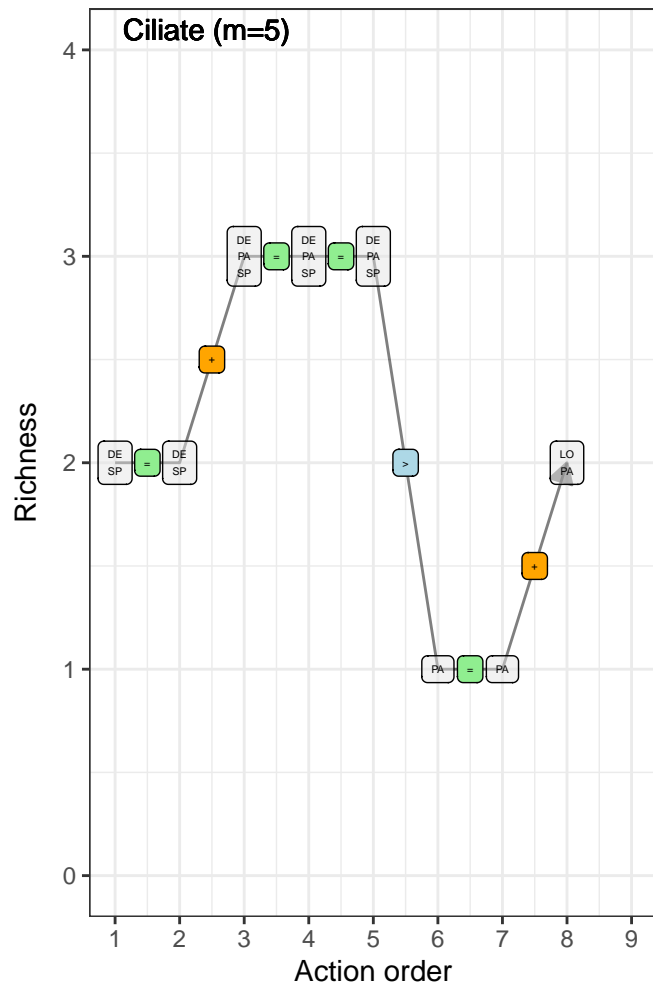
Optimal path



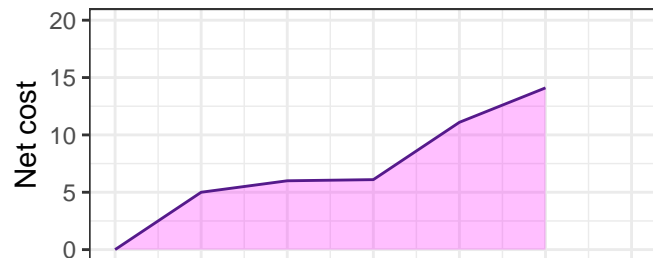
Nominal path



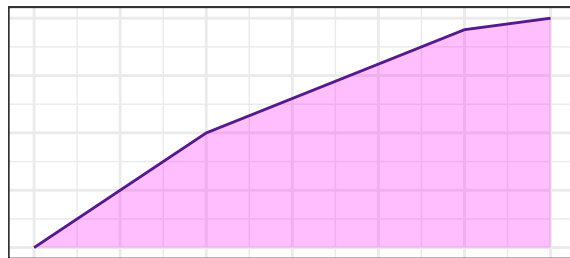
Ciliate (m=5)



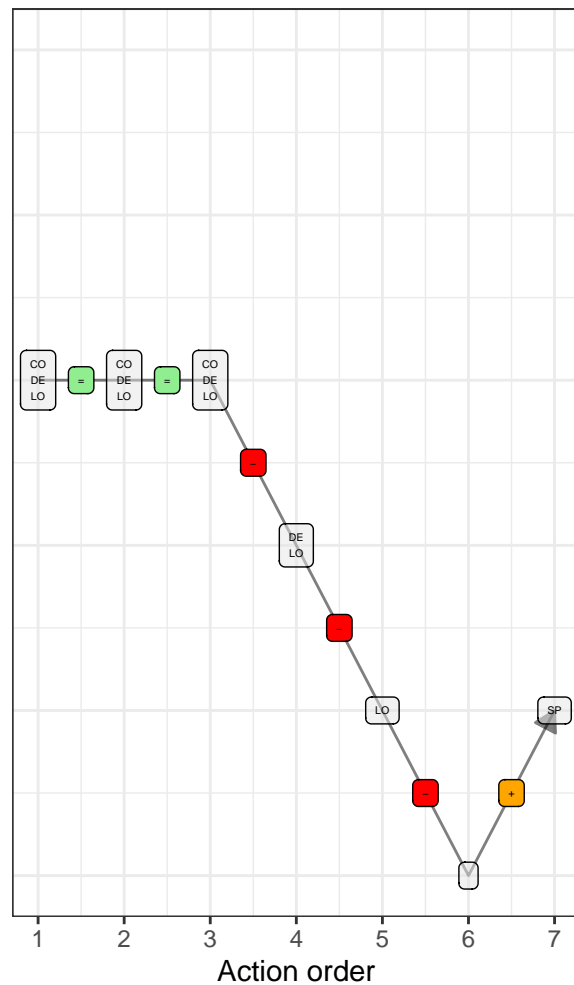
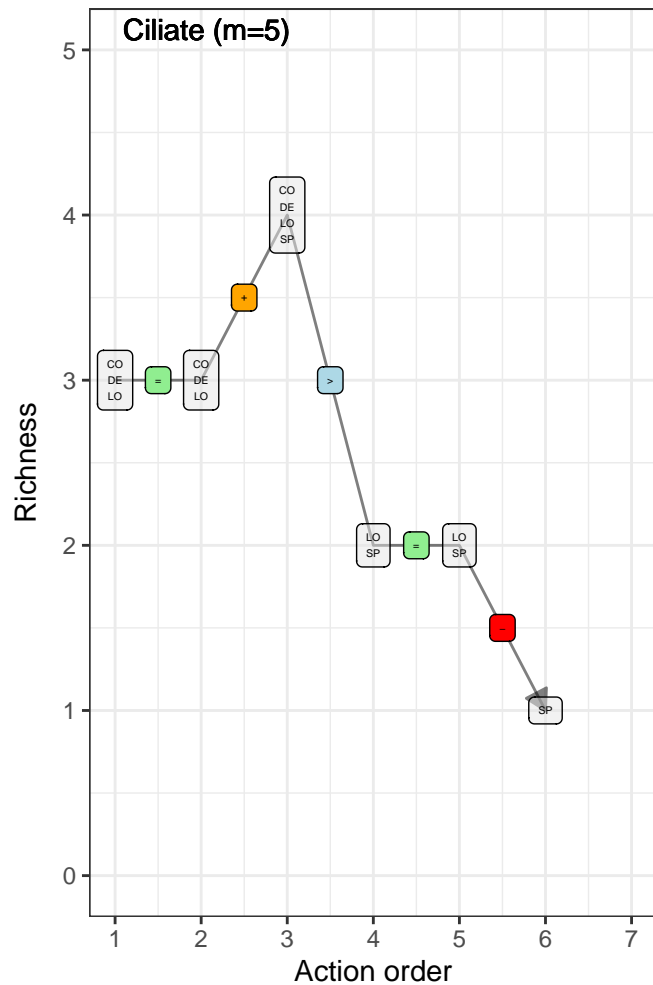
Optimal path



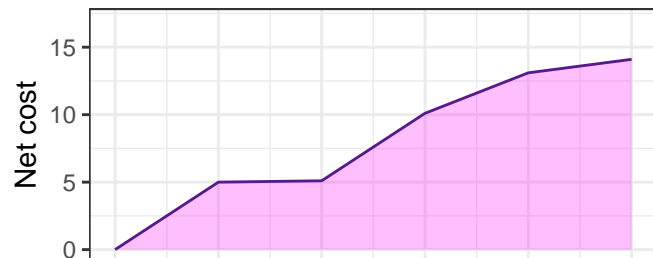
Nominal path



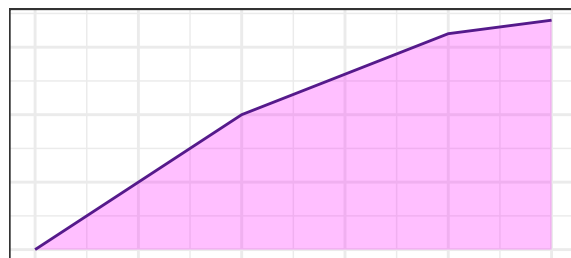
Ciliate (m=5)



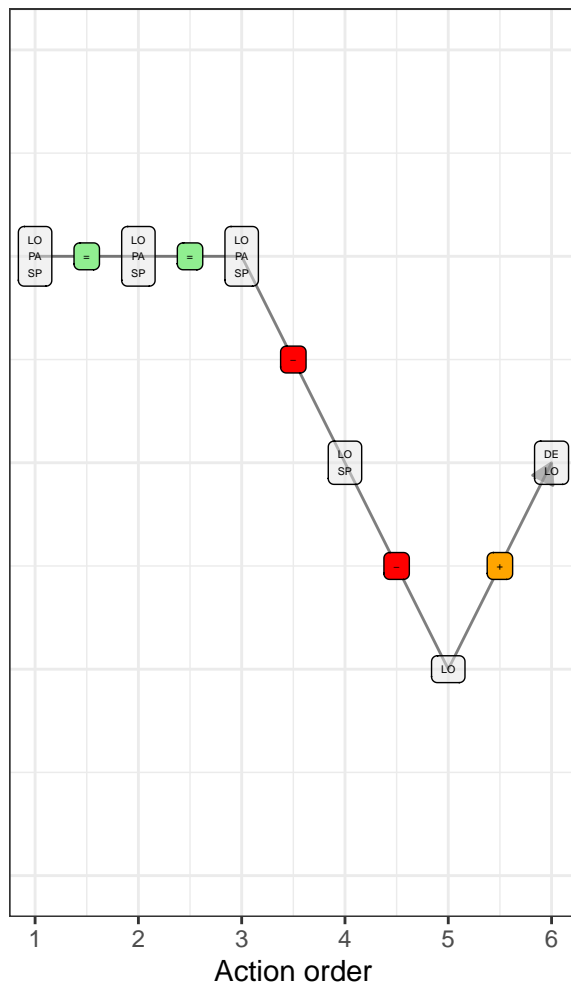
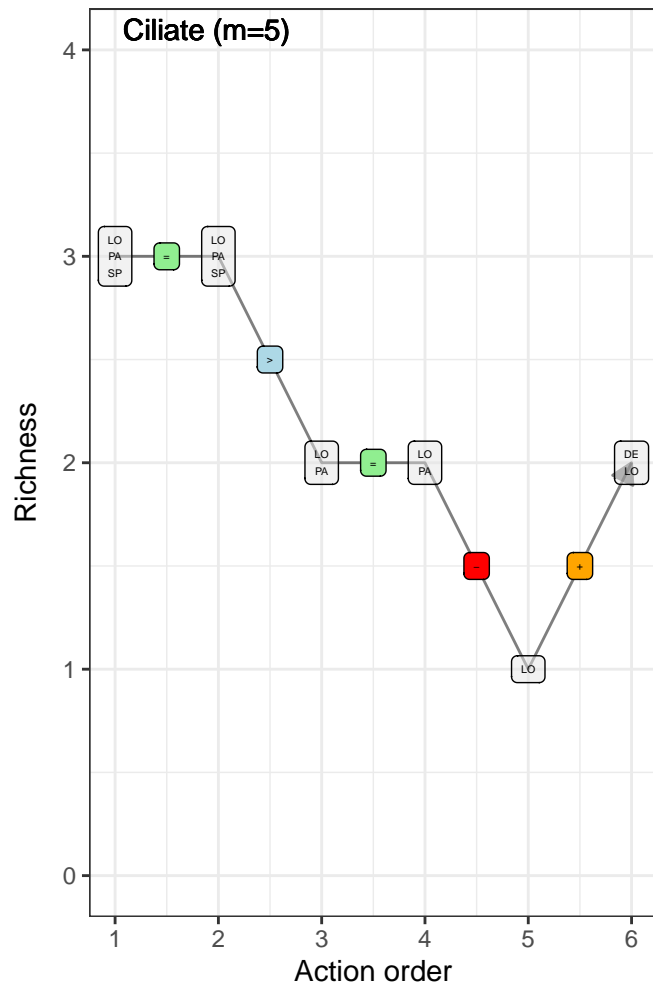
Optimal path



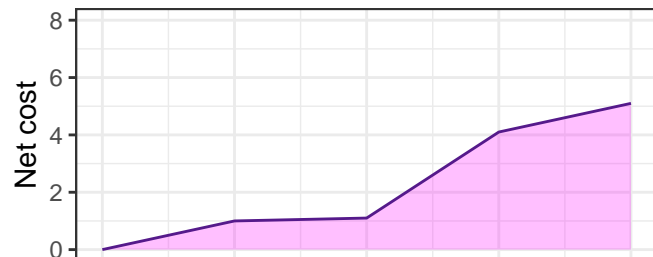
Nominal path



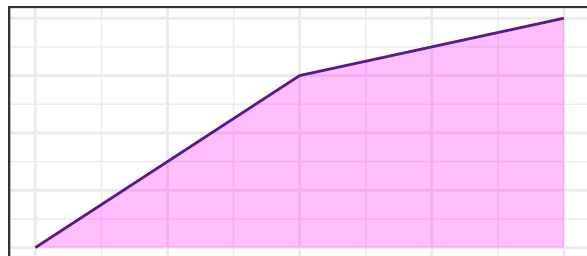
Ciliate (m=5)



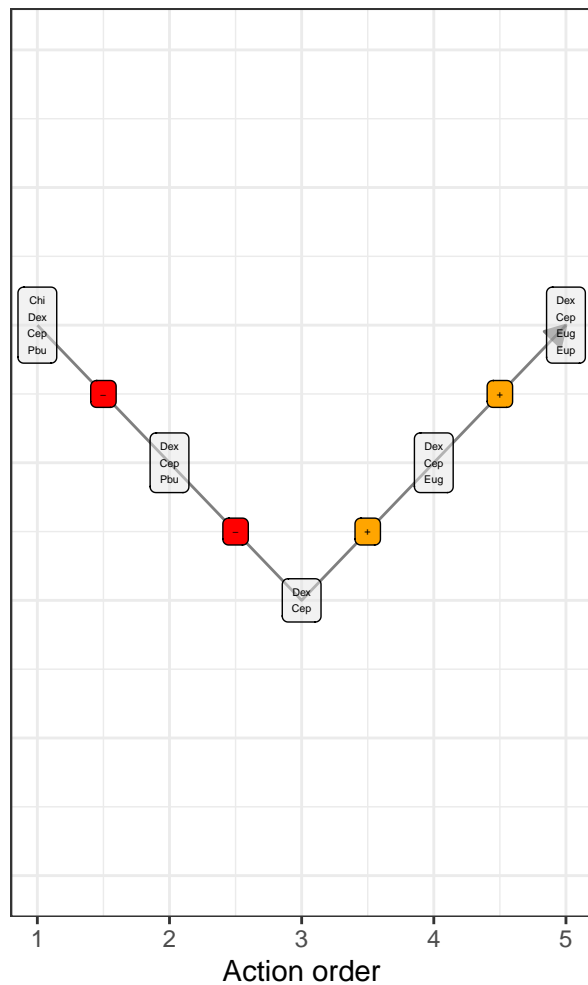
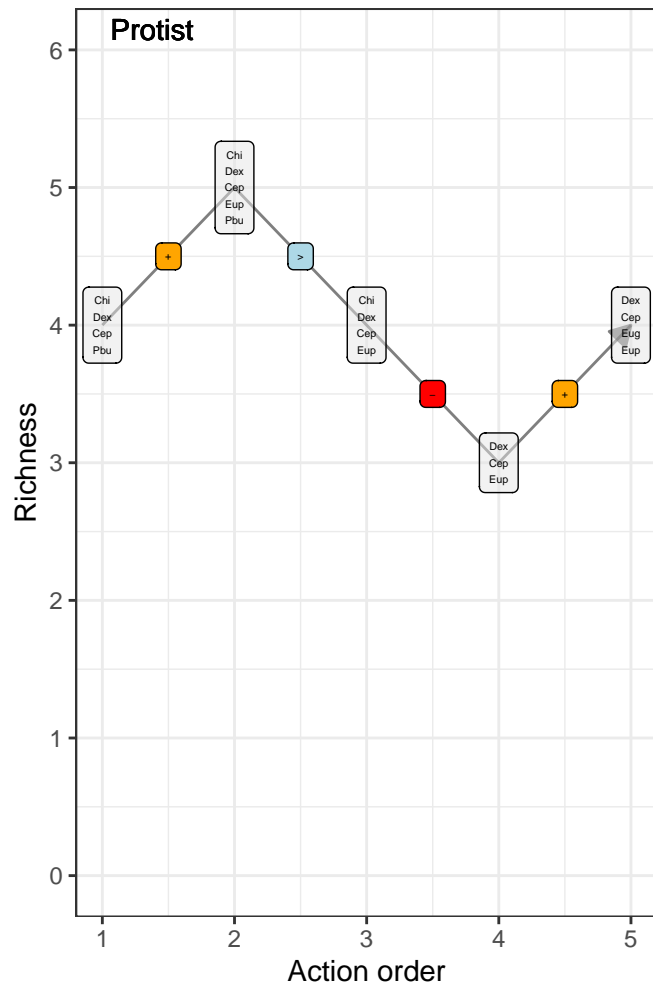
Optimal path



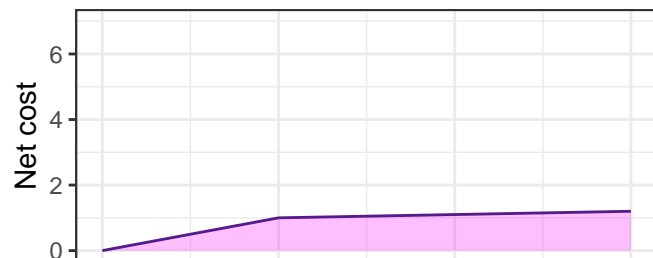
Nominal path



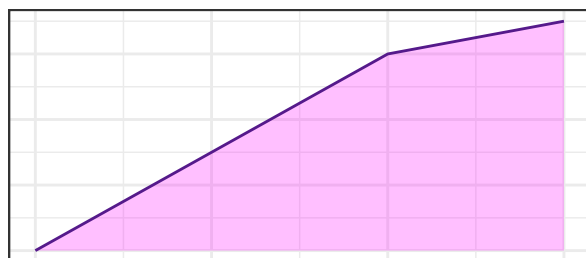
Protist



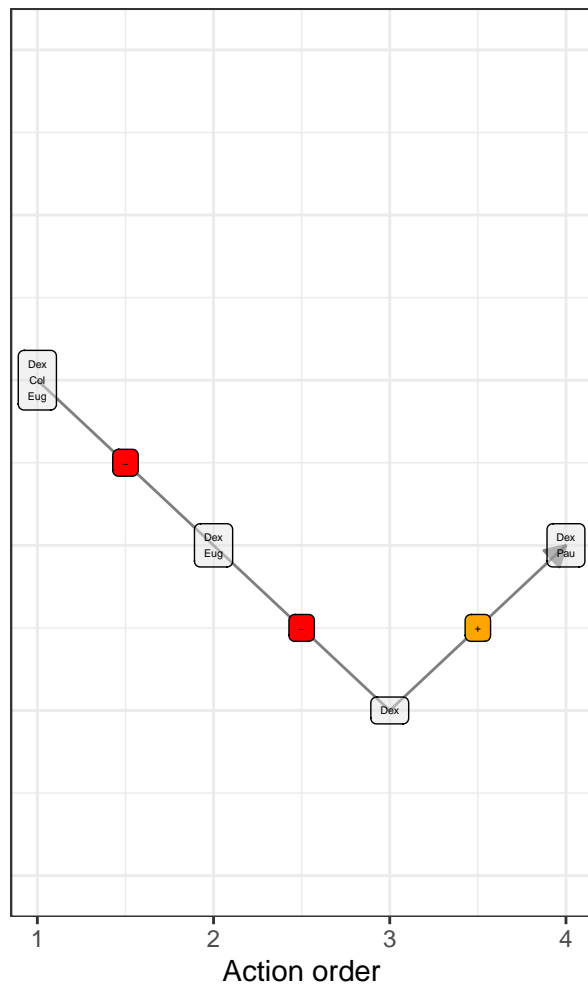
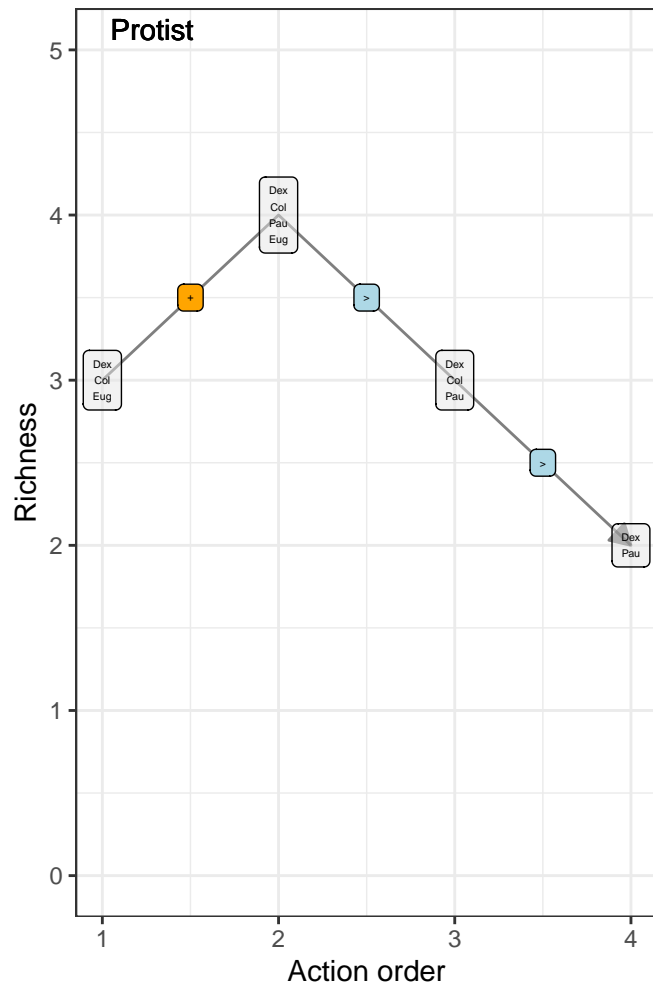
Optimal path



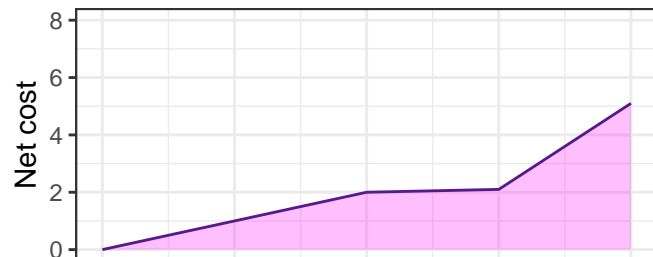
Nominal path



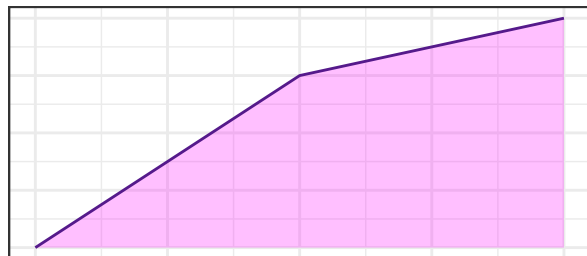
Protist



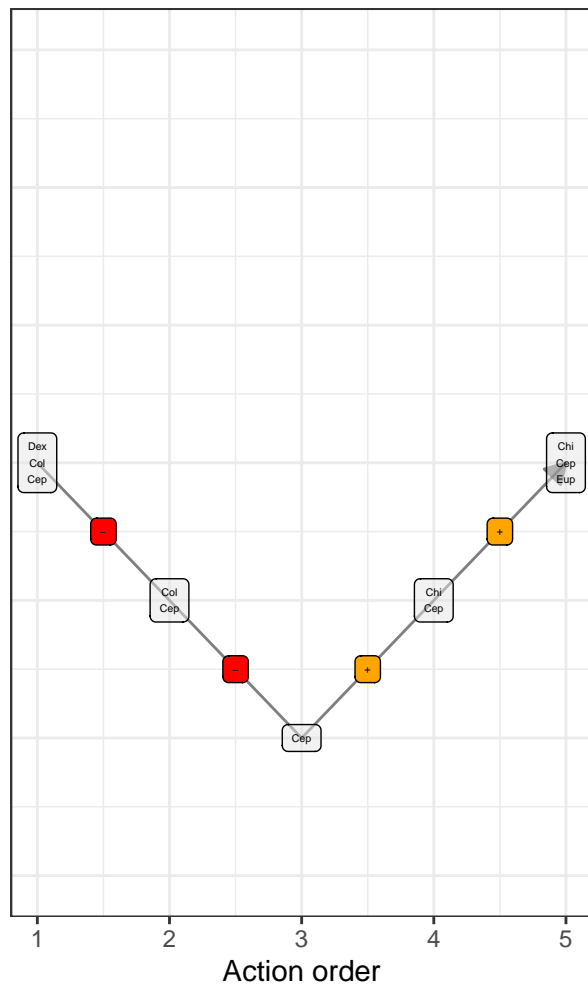
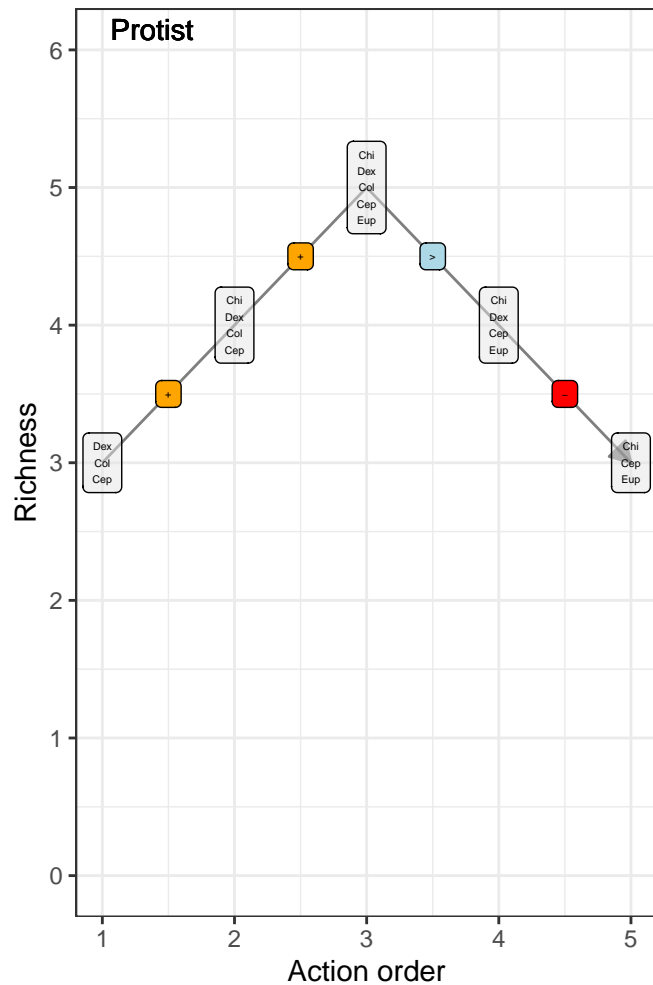
Optimal path



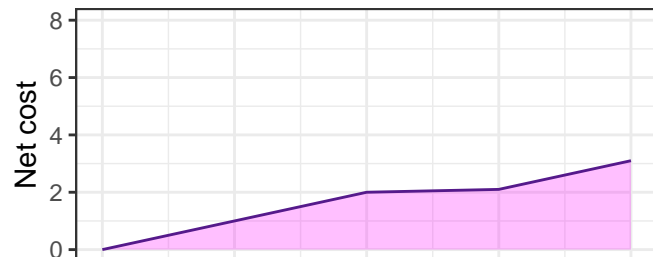
Nominal path



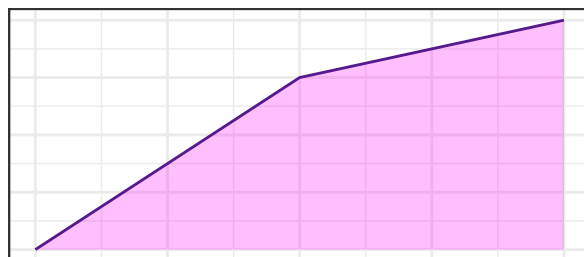
Protist



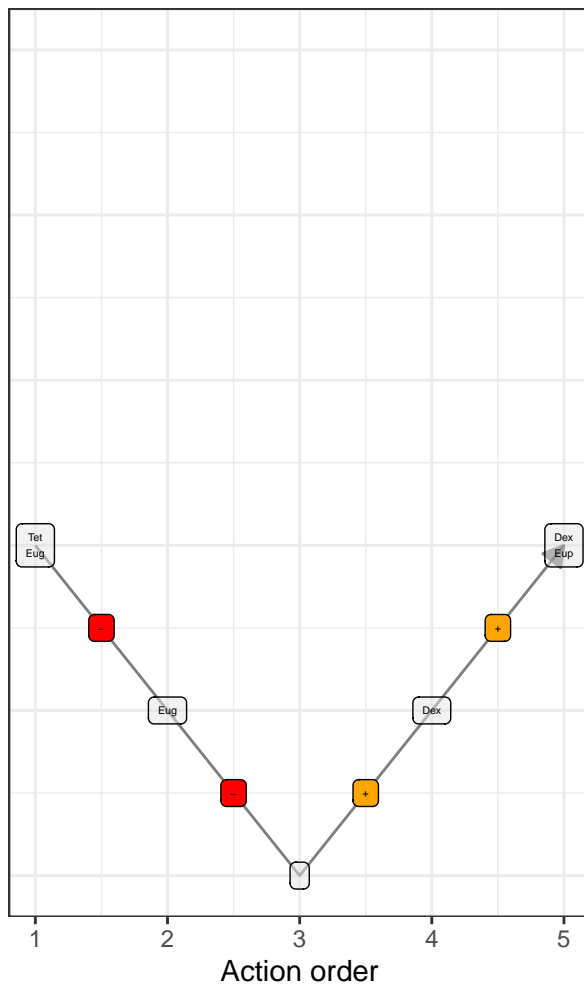
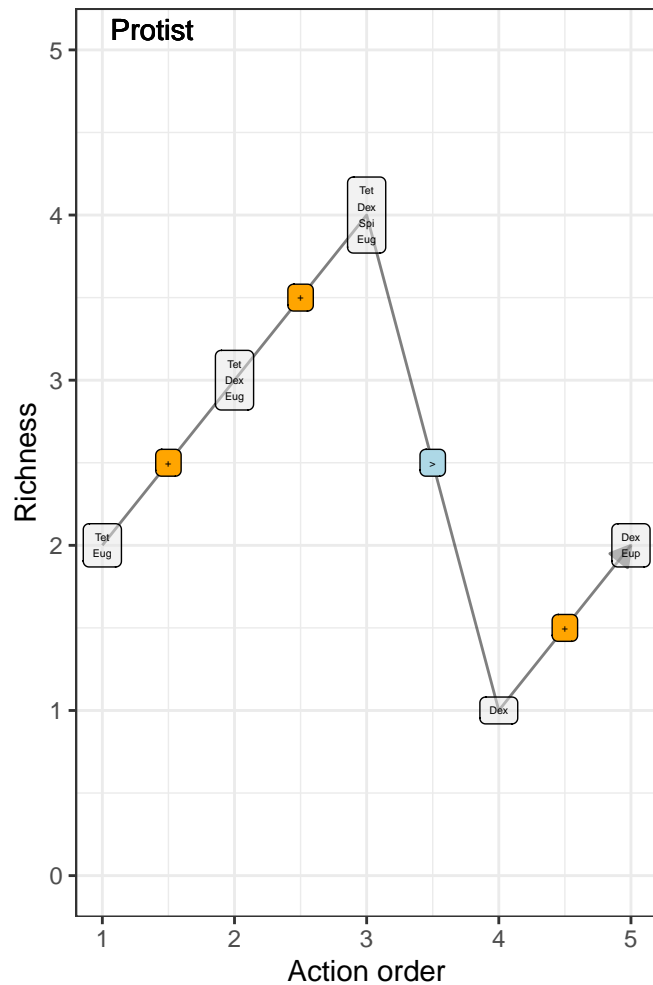
Optimal path



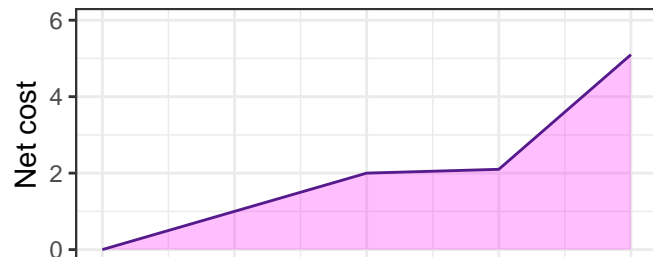
Nominal path



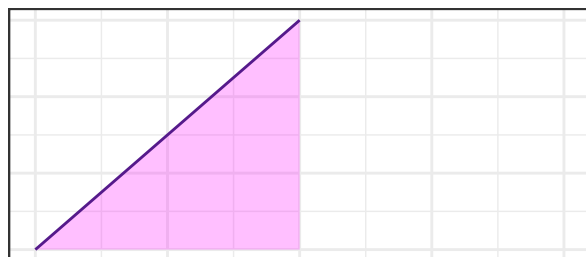
Protist



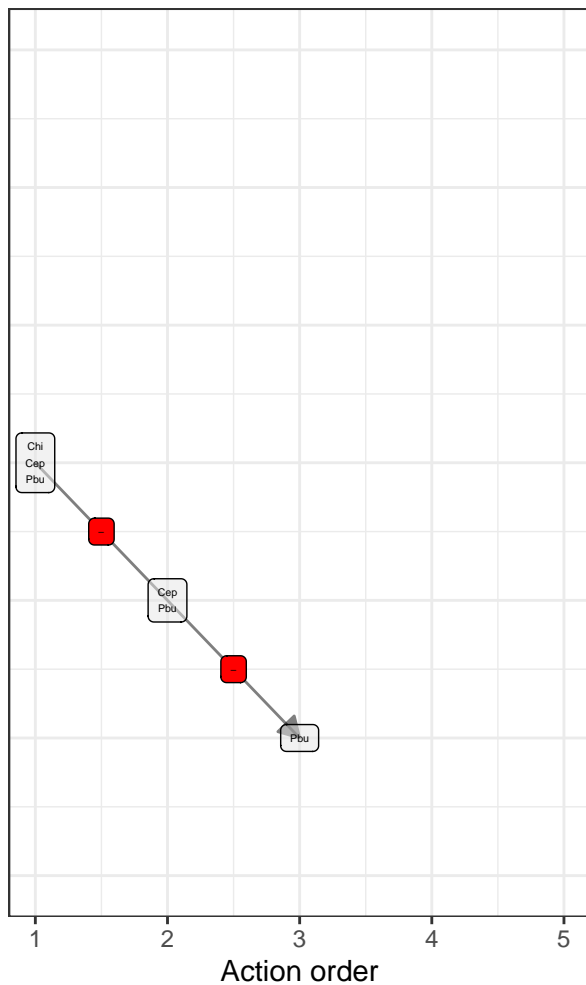
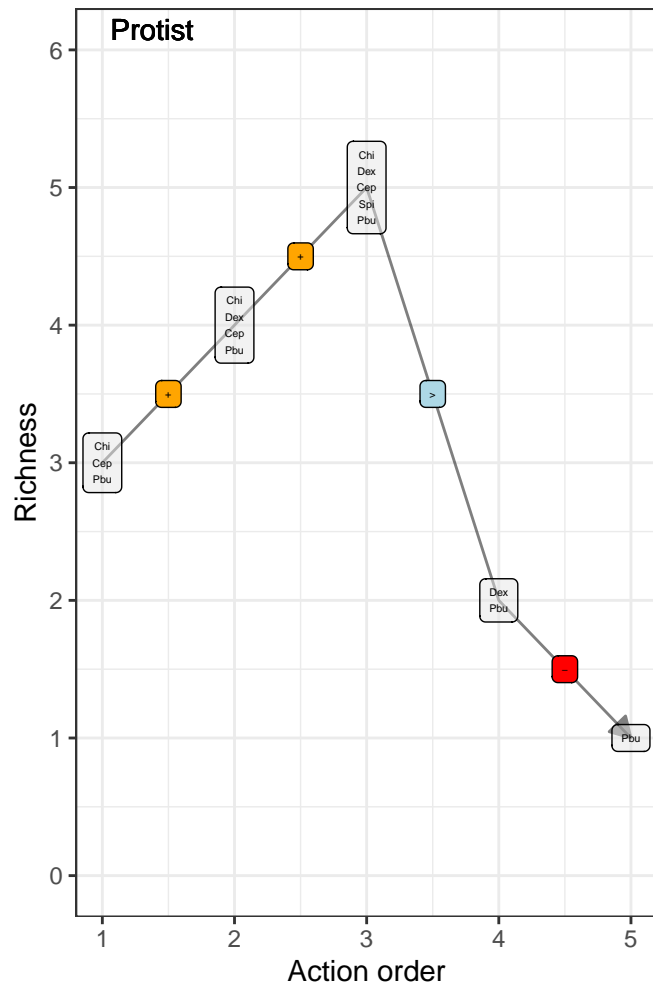
Optimal path



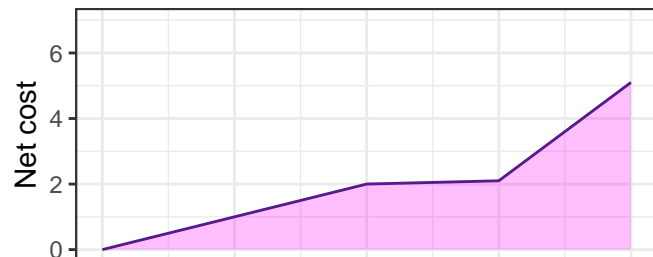
Nominal path



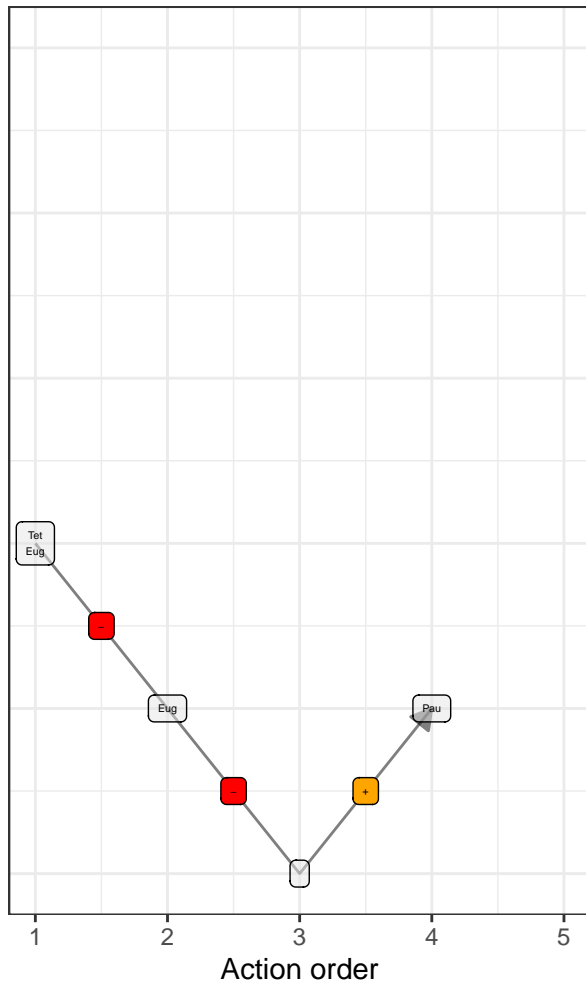
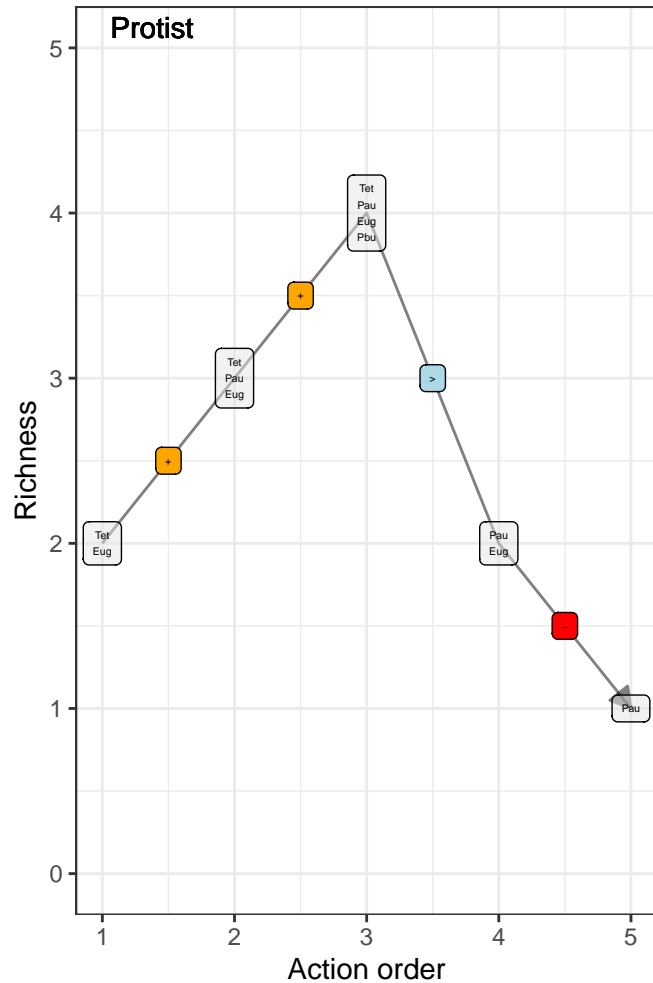
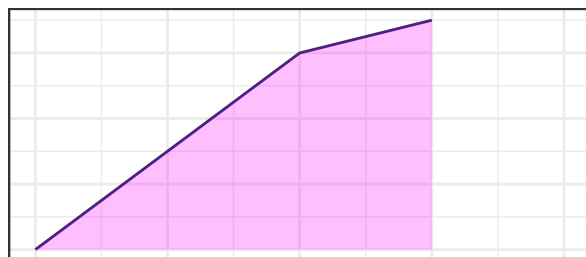
Protist



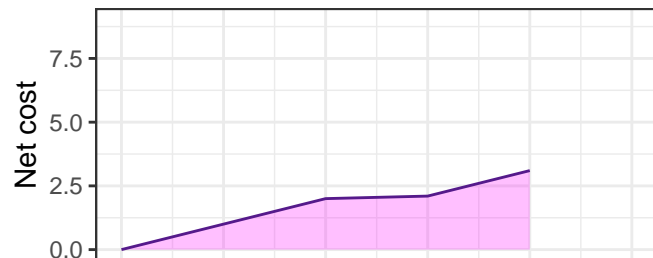
Optimal path



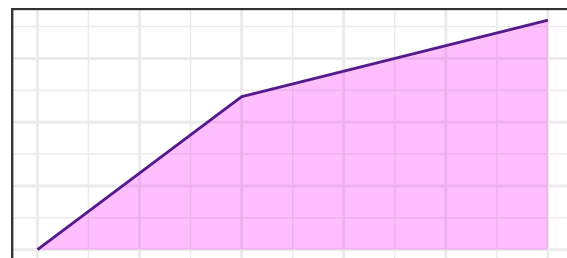
Nominal path



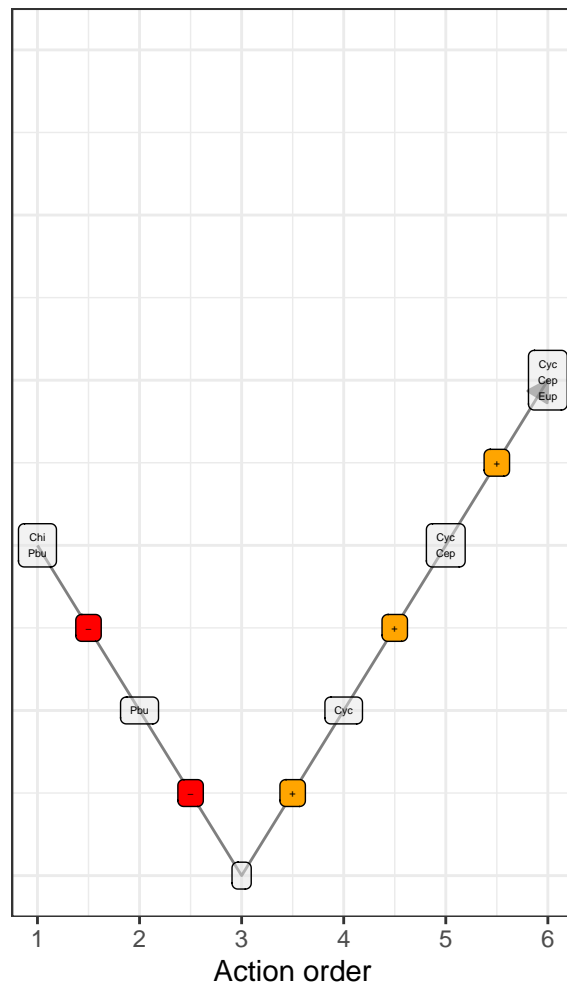
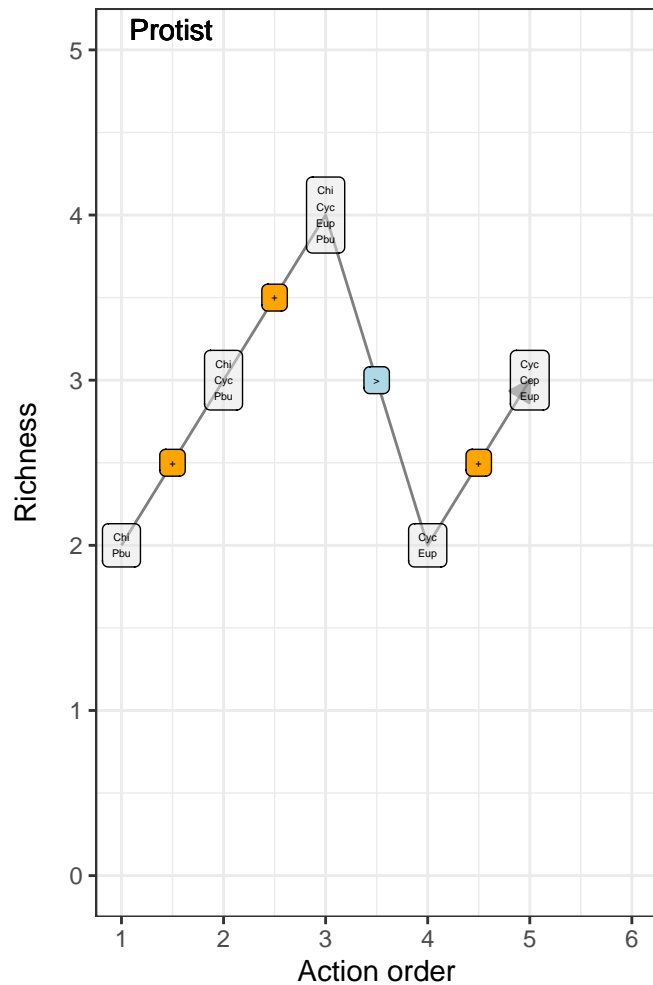
Optimal path



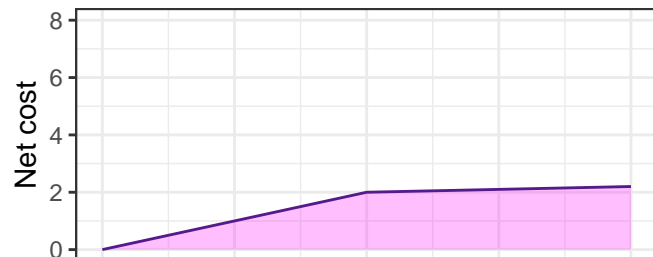
Nominal path



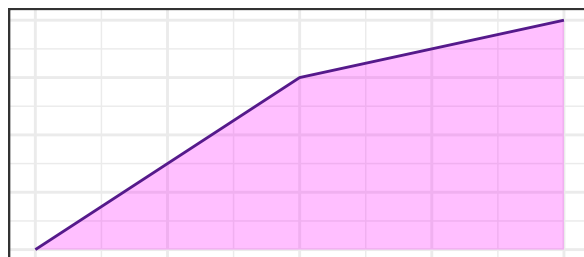
Protist



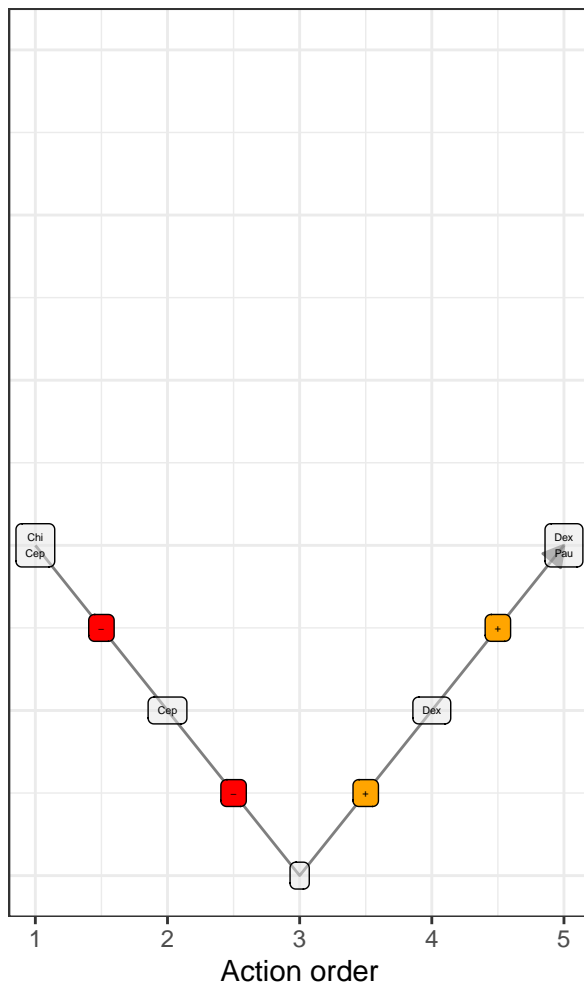
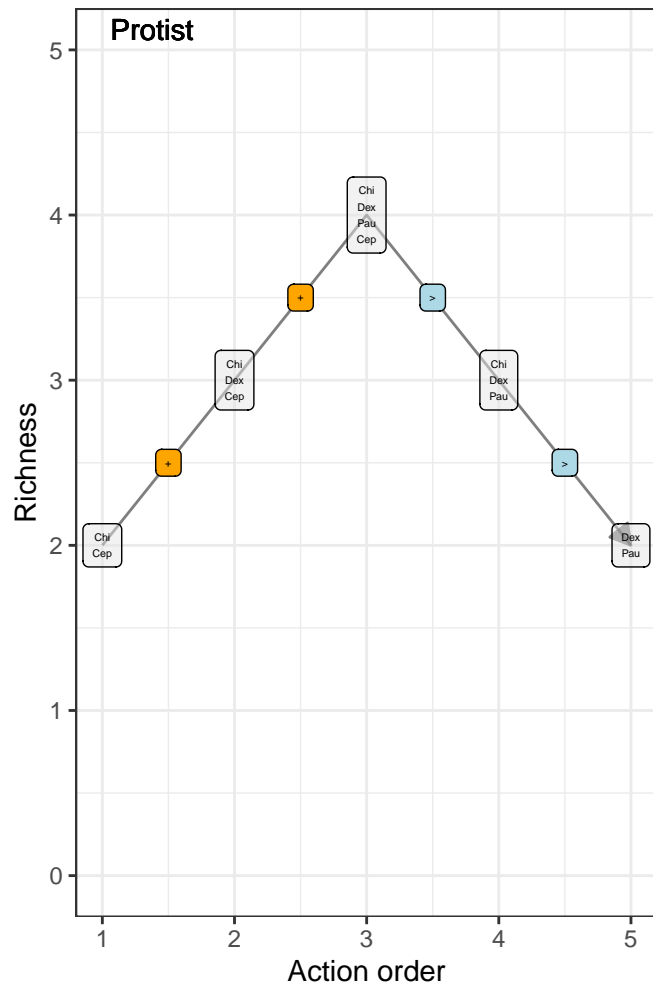
Optimal path



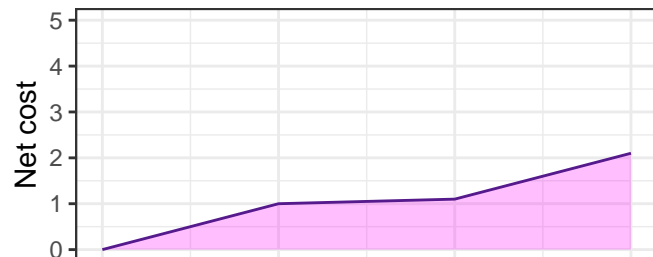
Nominal path



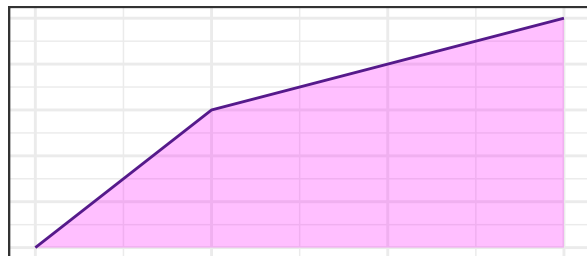
Protist



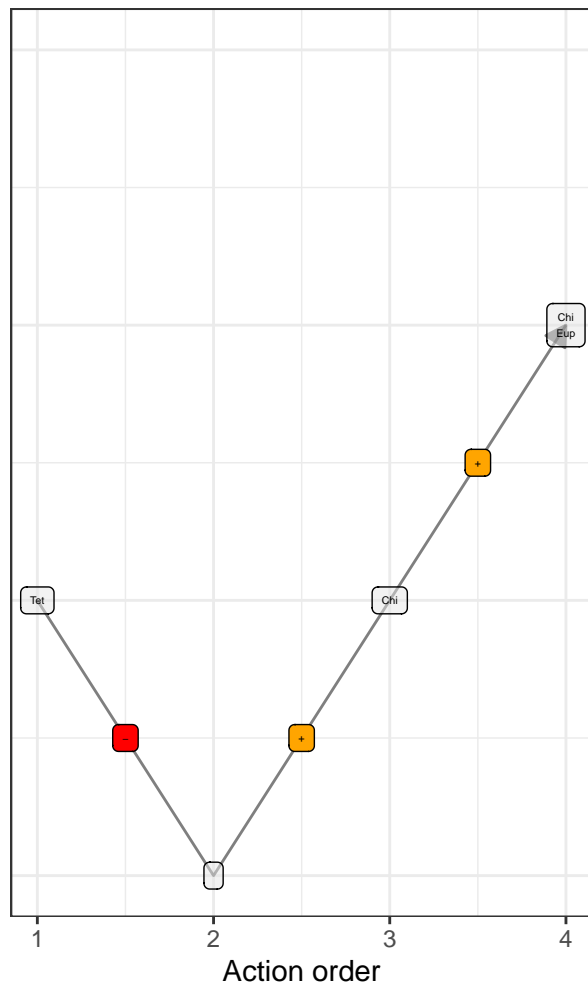
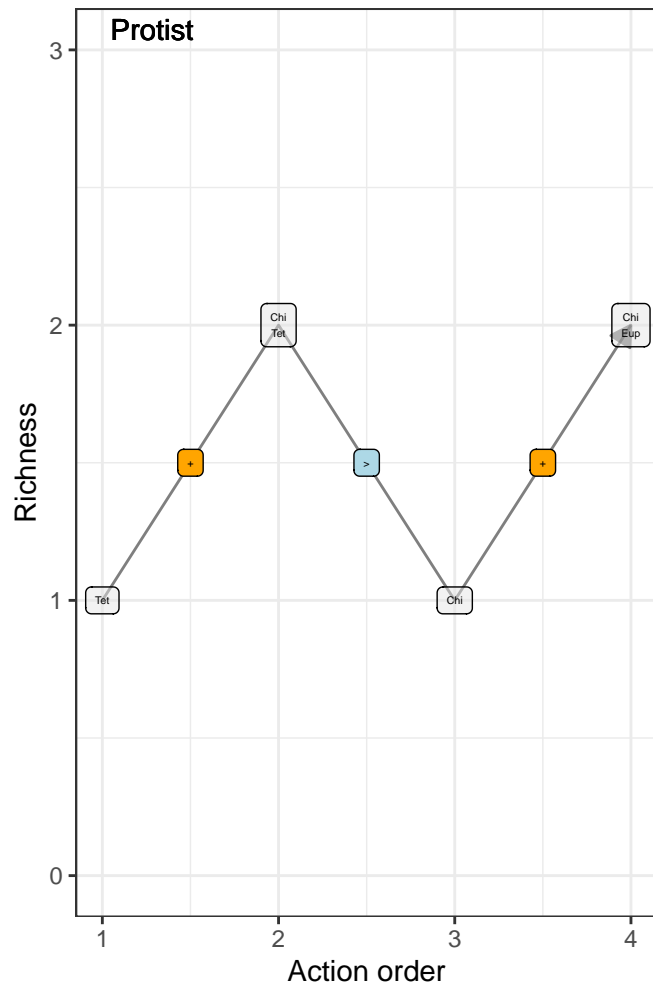
Optimal path



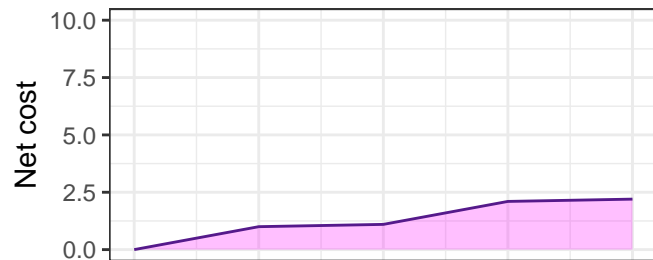
Nominal path



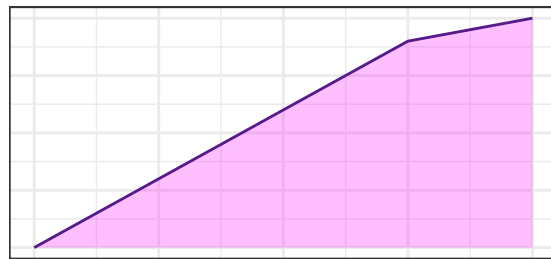
Protist



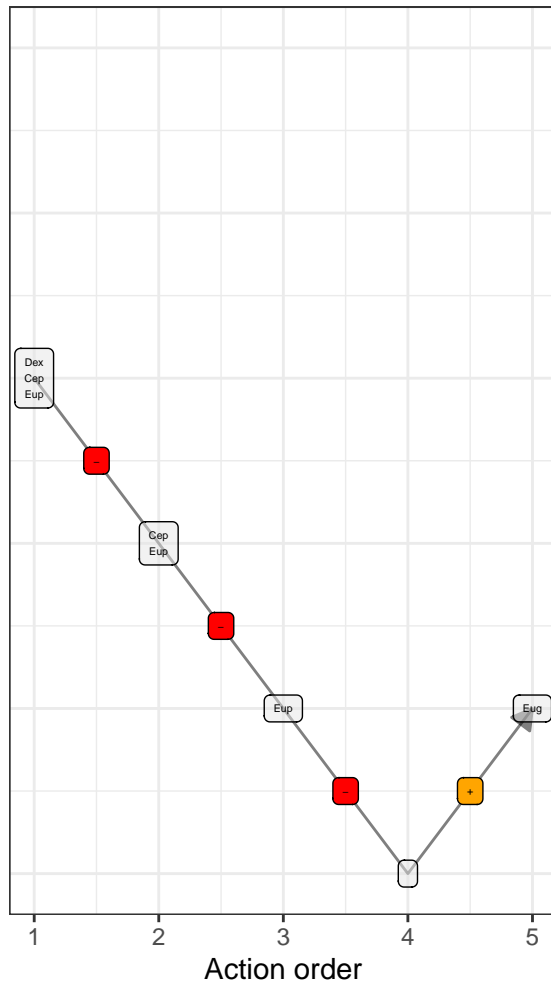
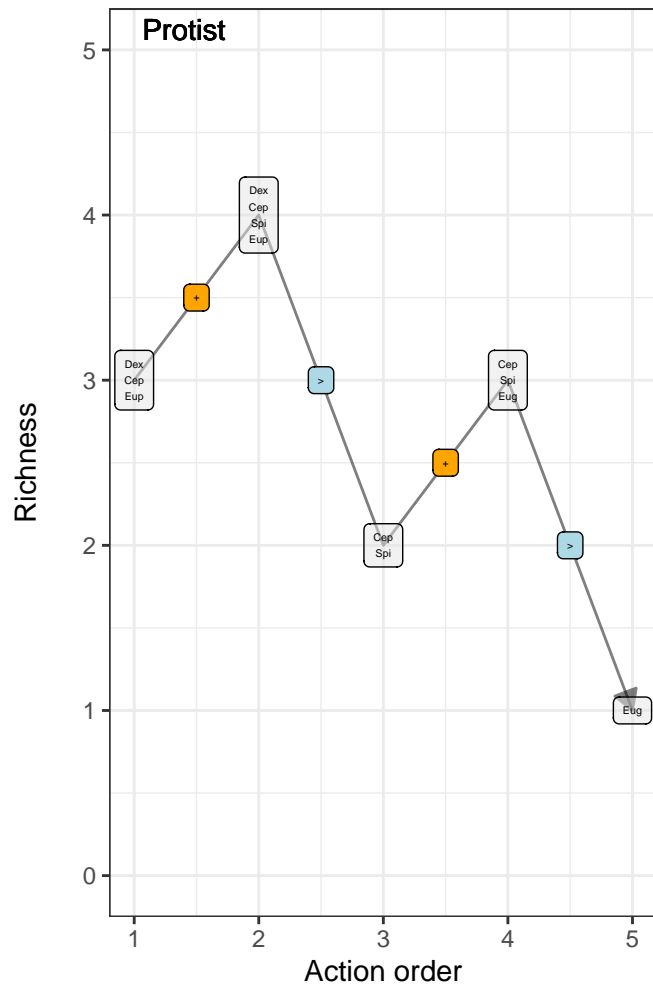
Optimal path



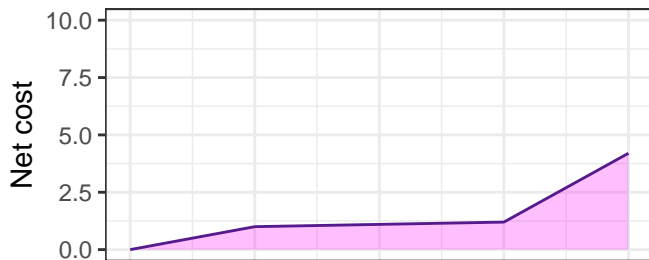
Nominal path



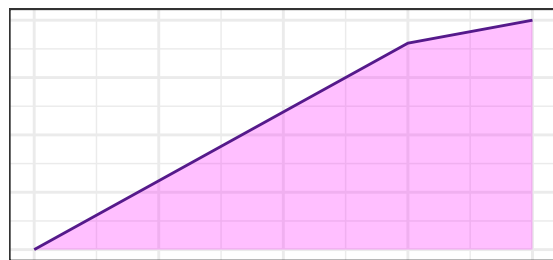
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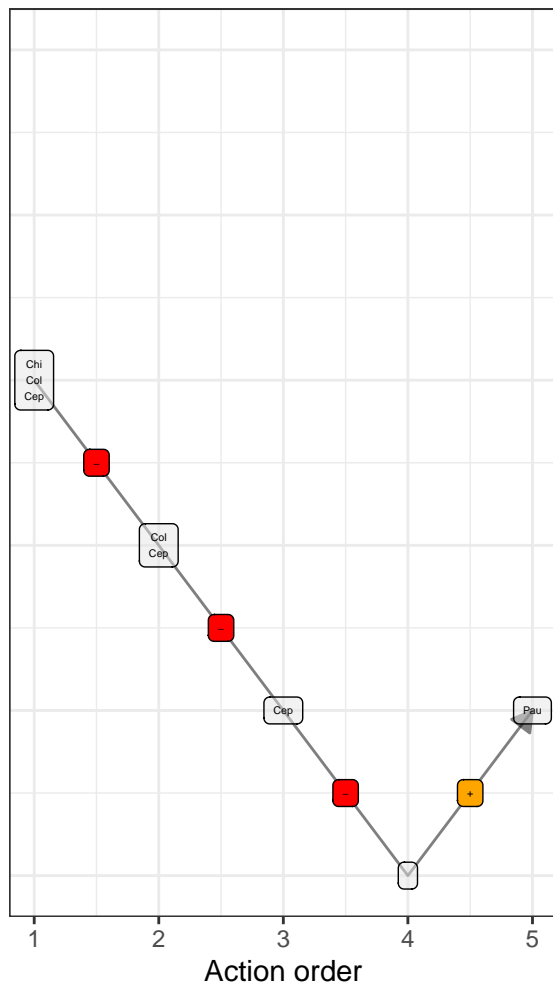
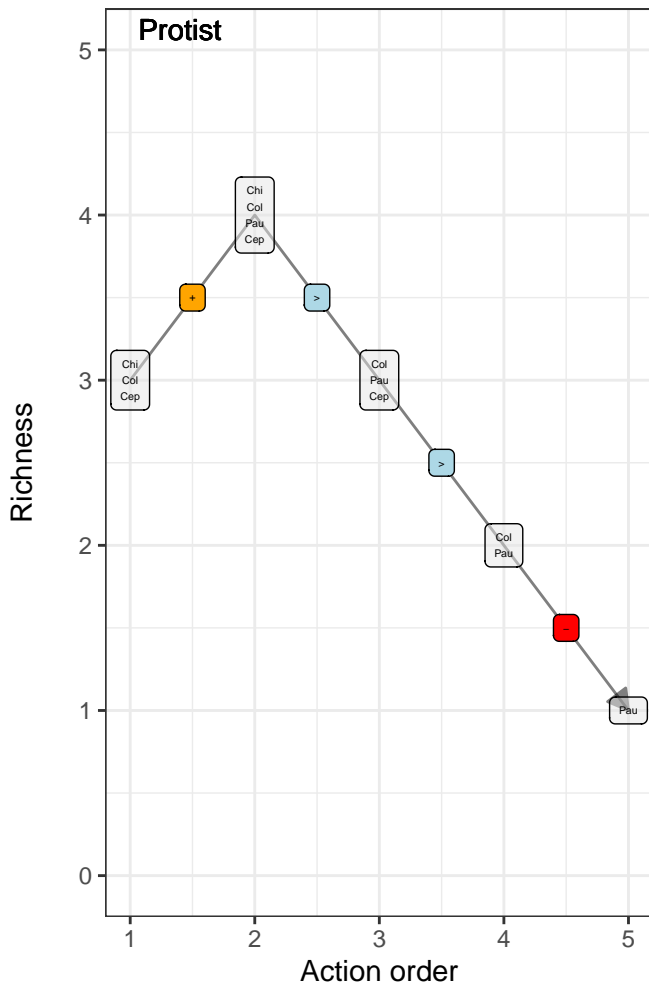
Optimal path



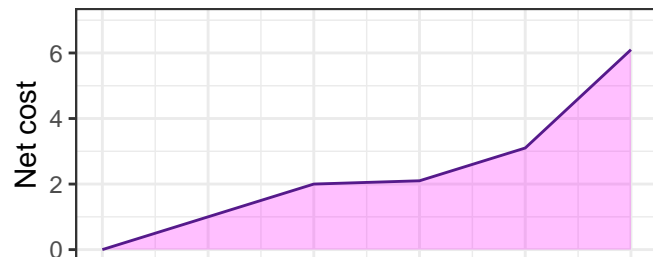
Nominal path



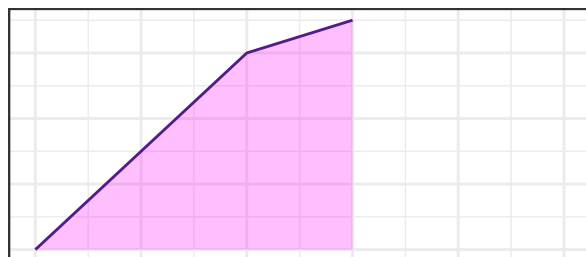
Protist



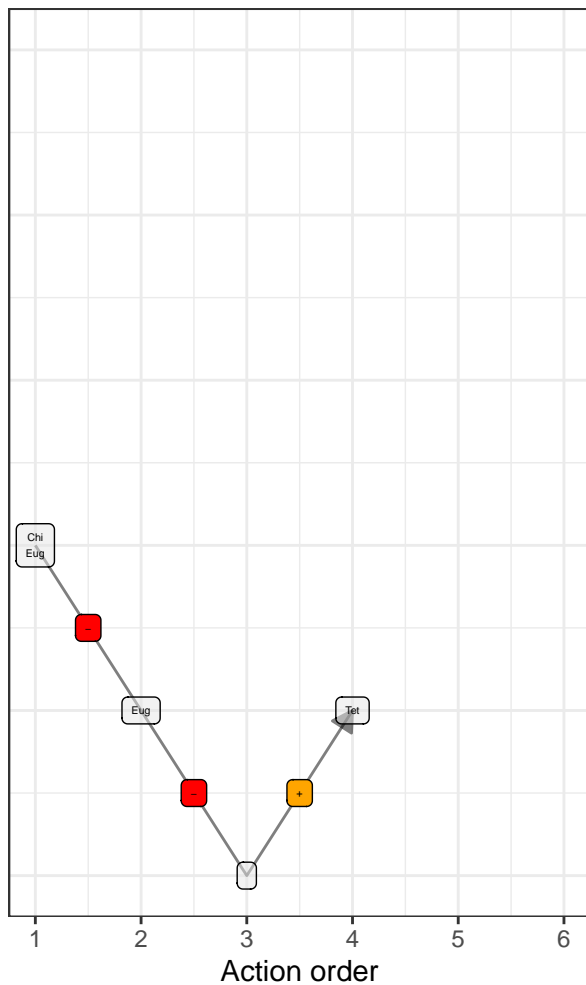
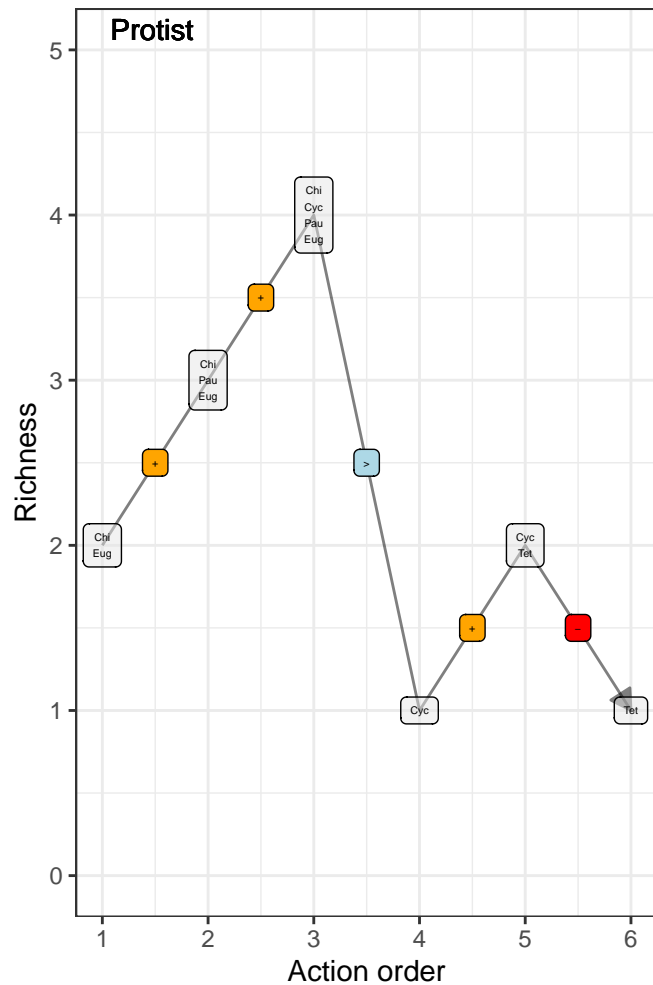
Optimal path



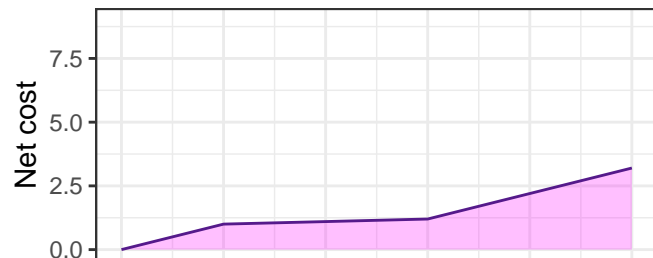
Nominal path



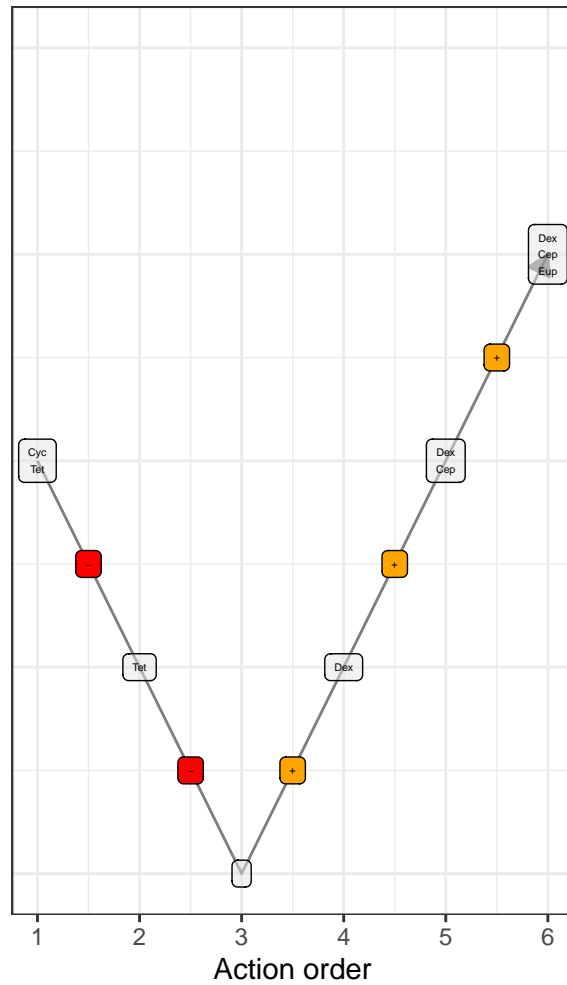
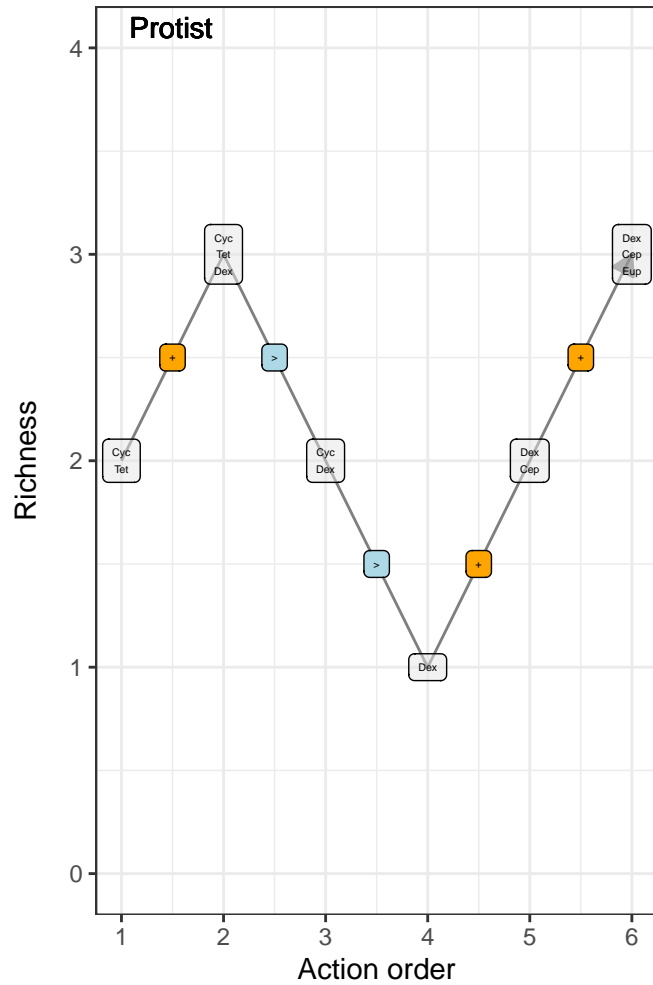
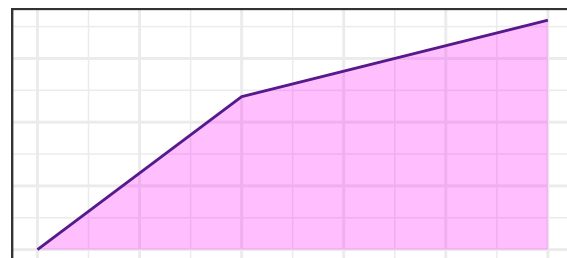
Protist



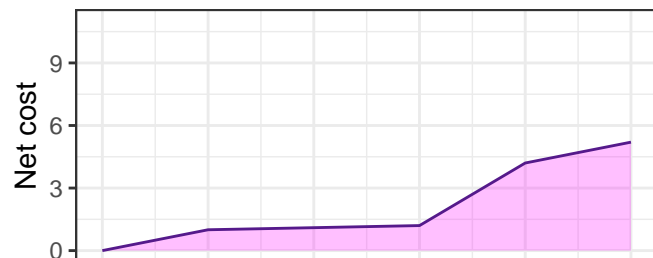
Optimal path



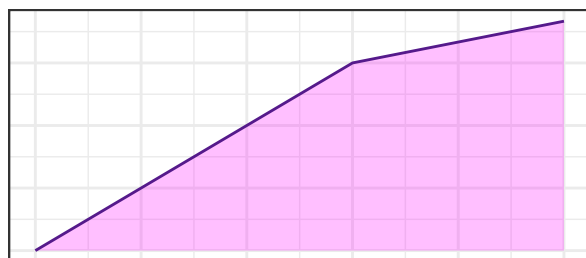
Nominal path



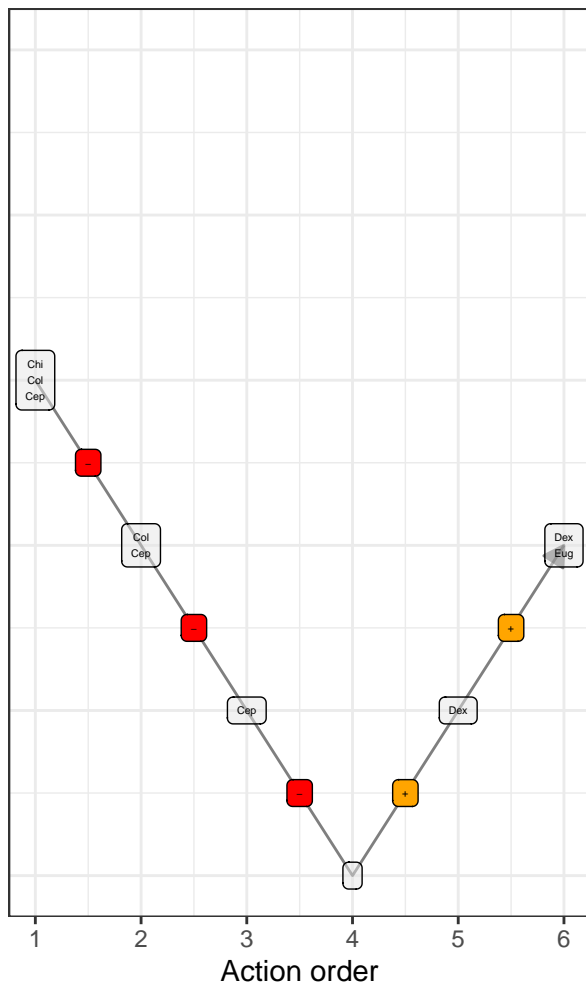
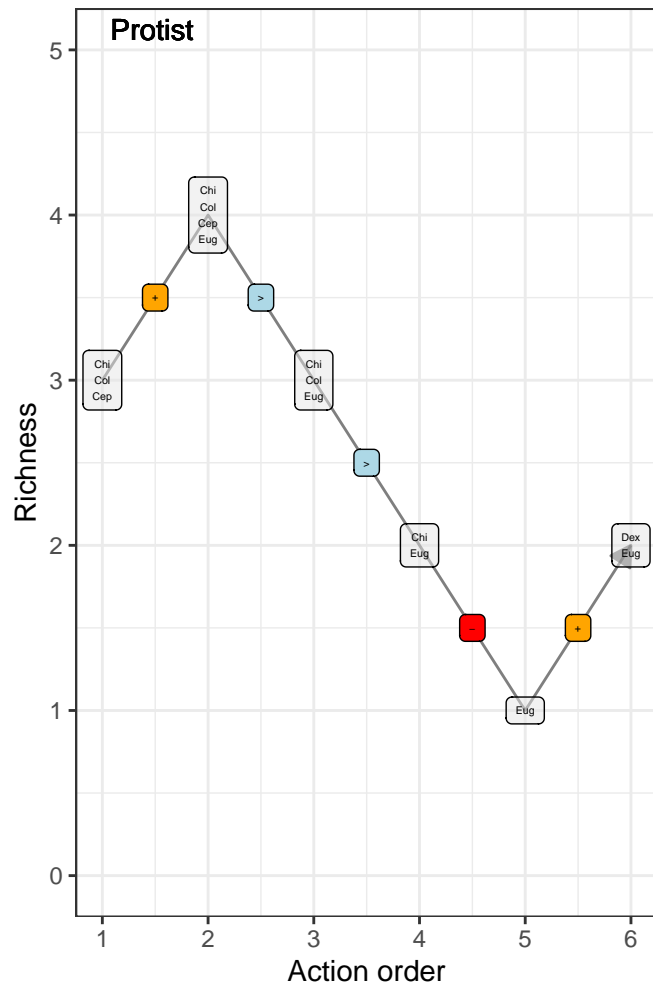
Optimal path



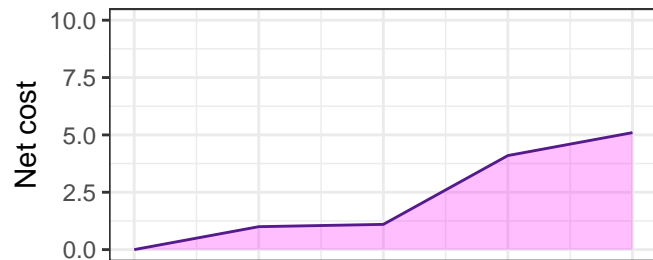
Nominal path



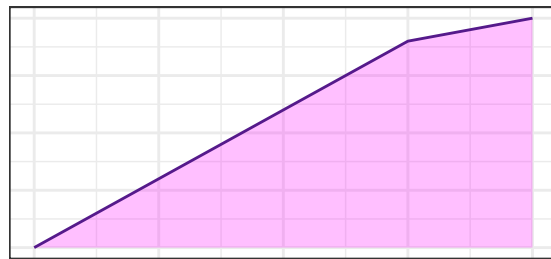
Protist



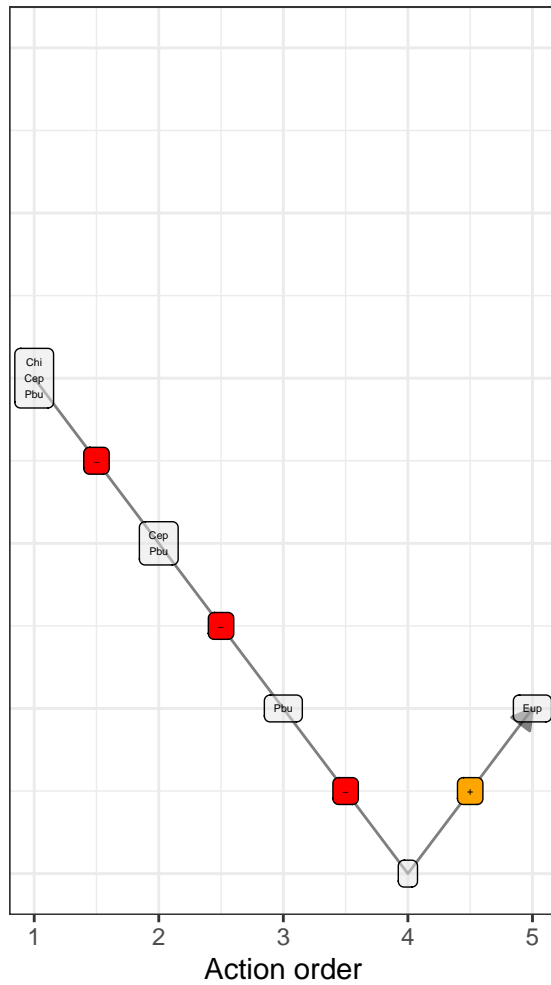
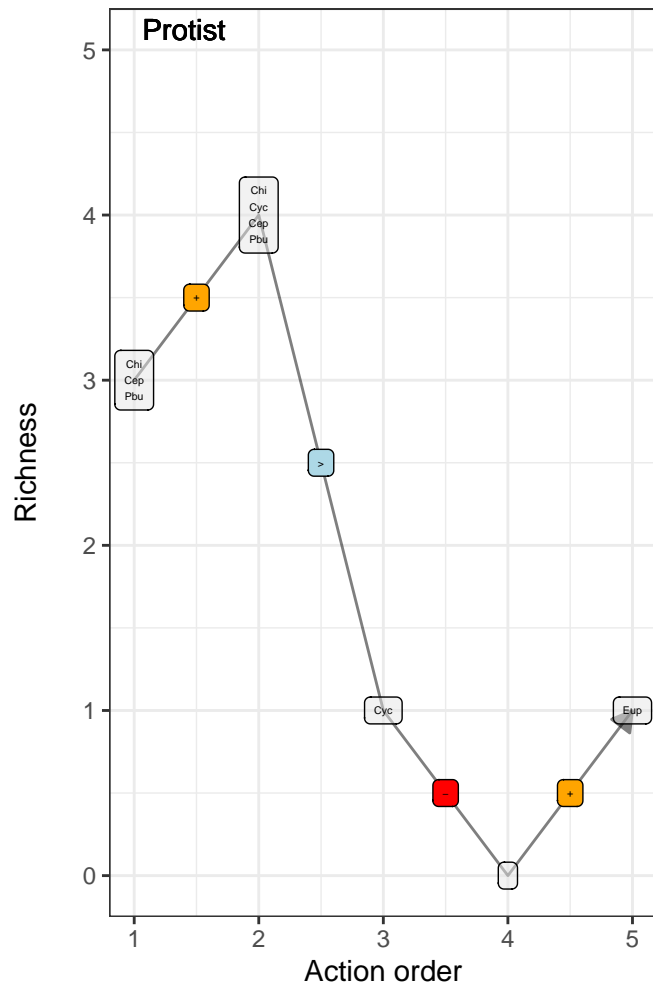
Optimal path



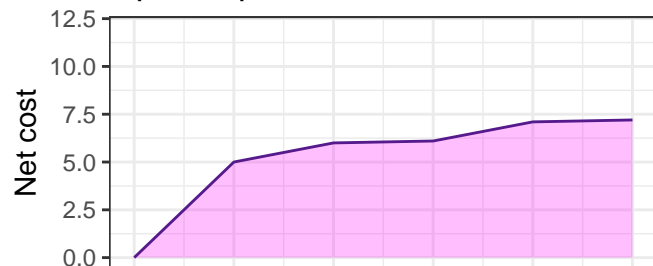
Nominal path



Protist



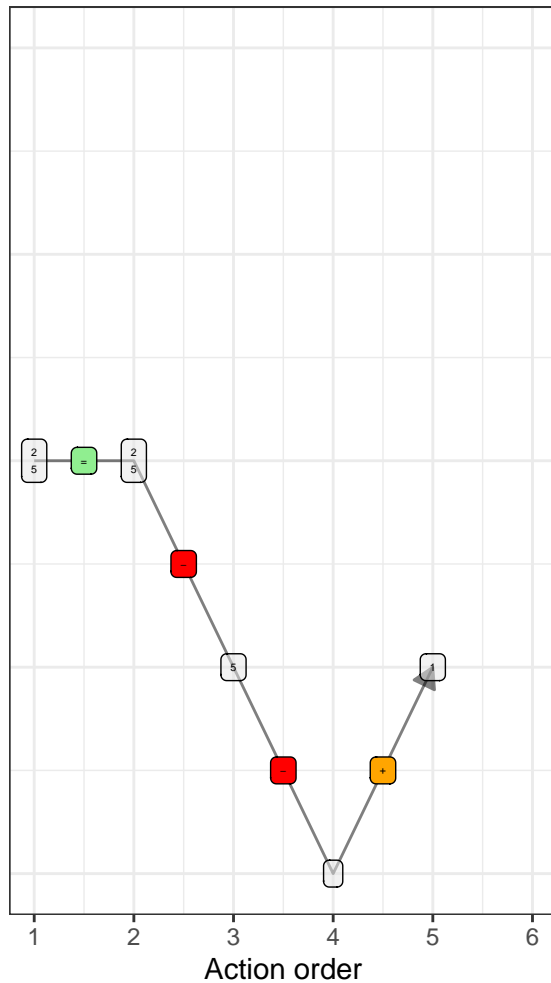
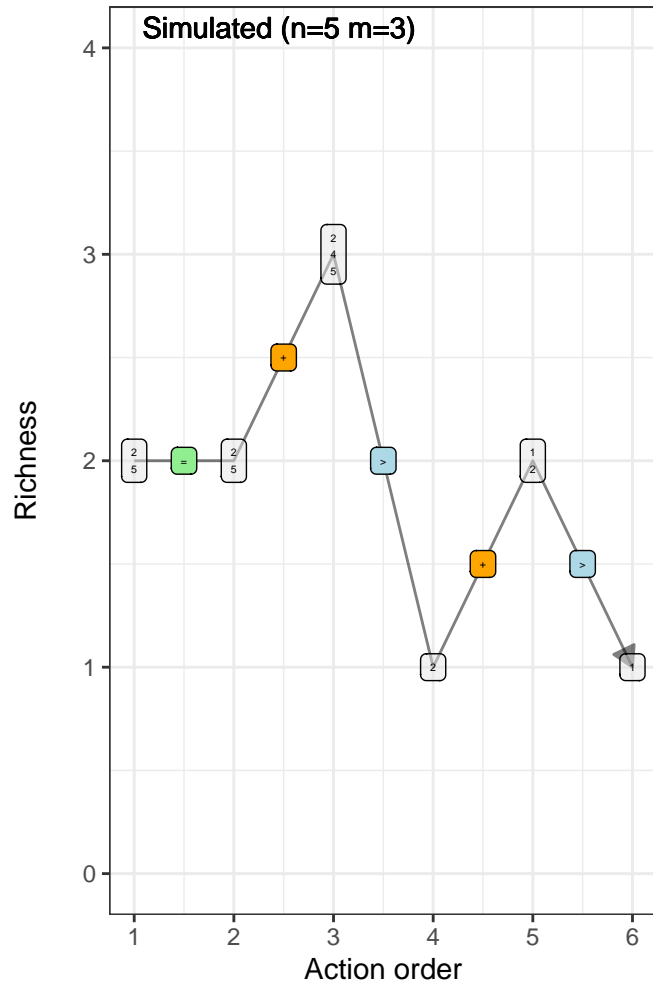
Optimal path



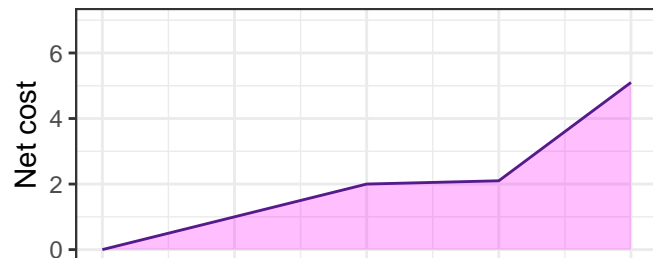
Nominal path



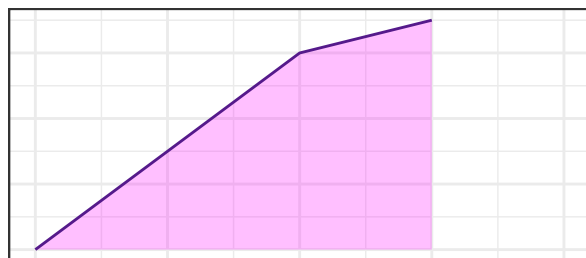
Simulated (n=5 m=3)



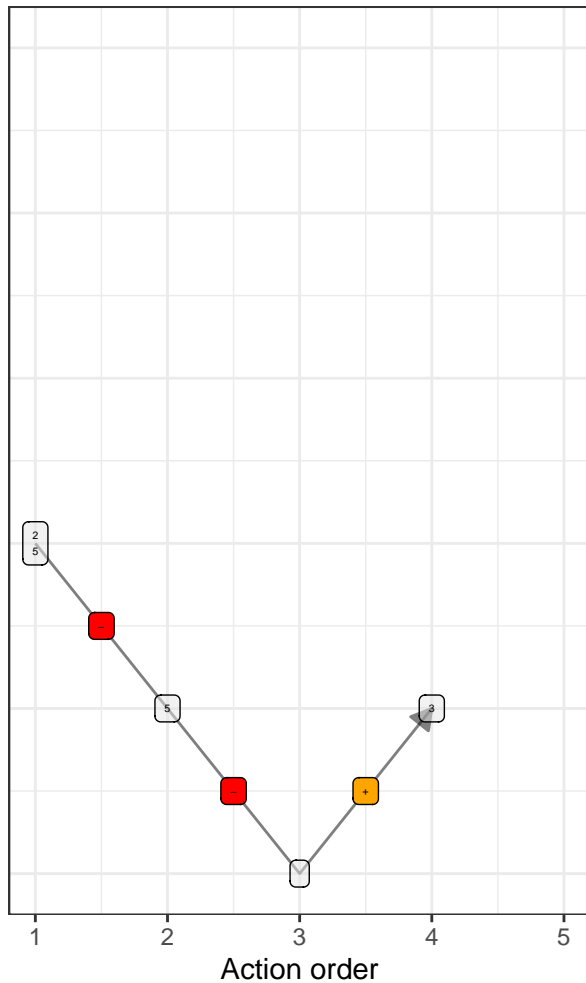
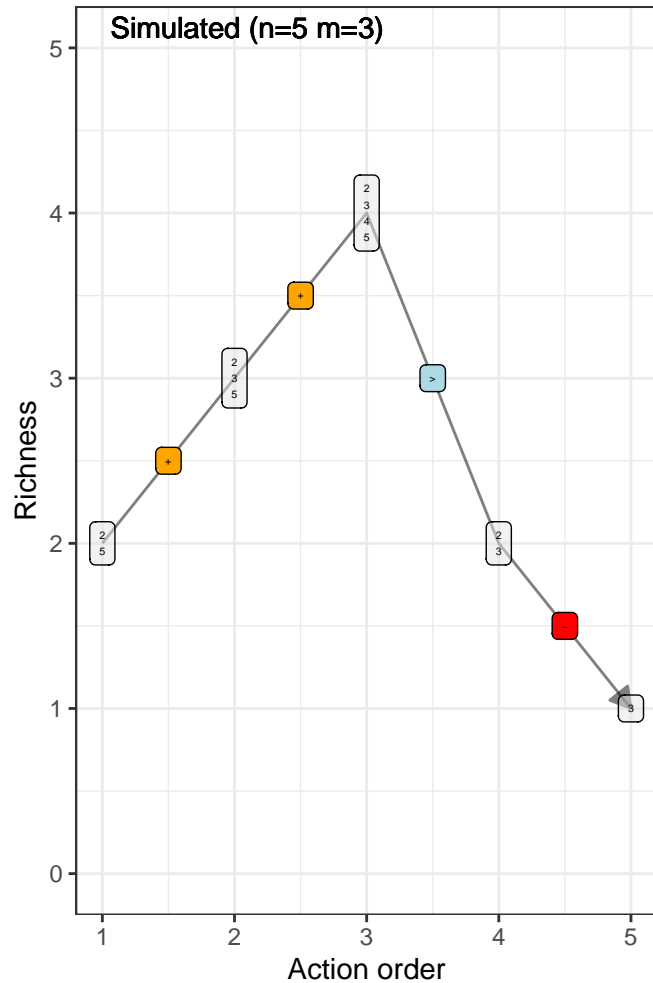
Optimal path



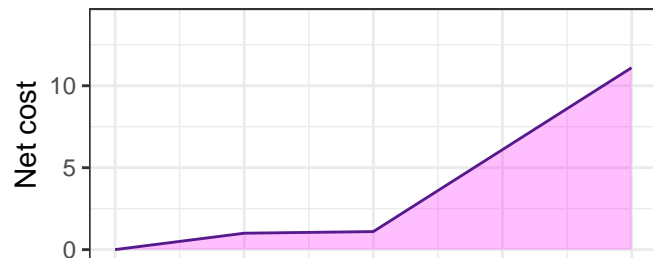
Nominal path



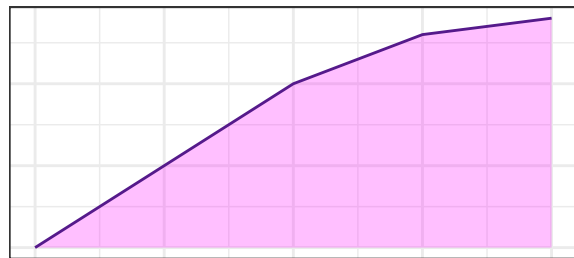
Simulated (n=5 m=3)



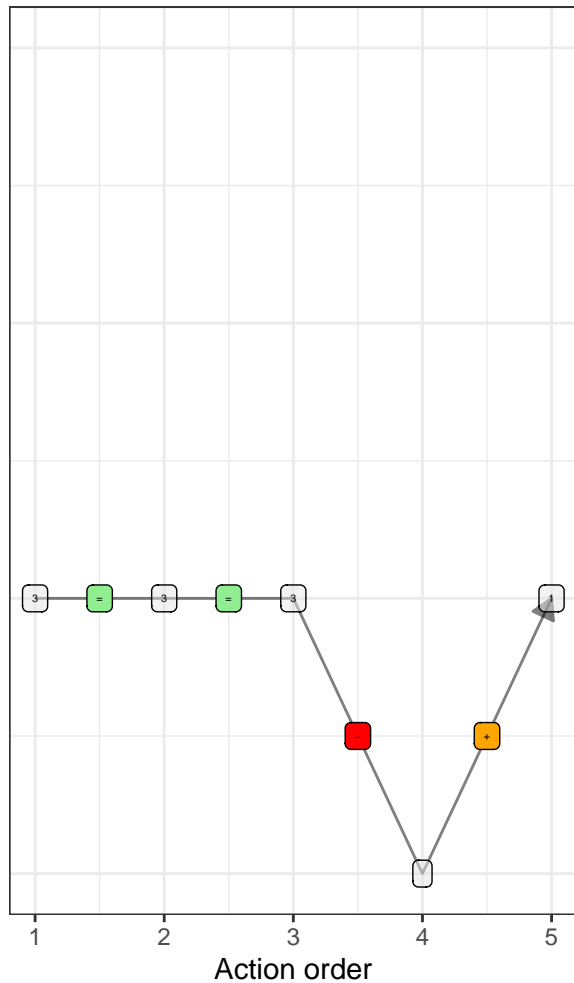
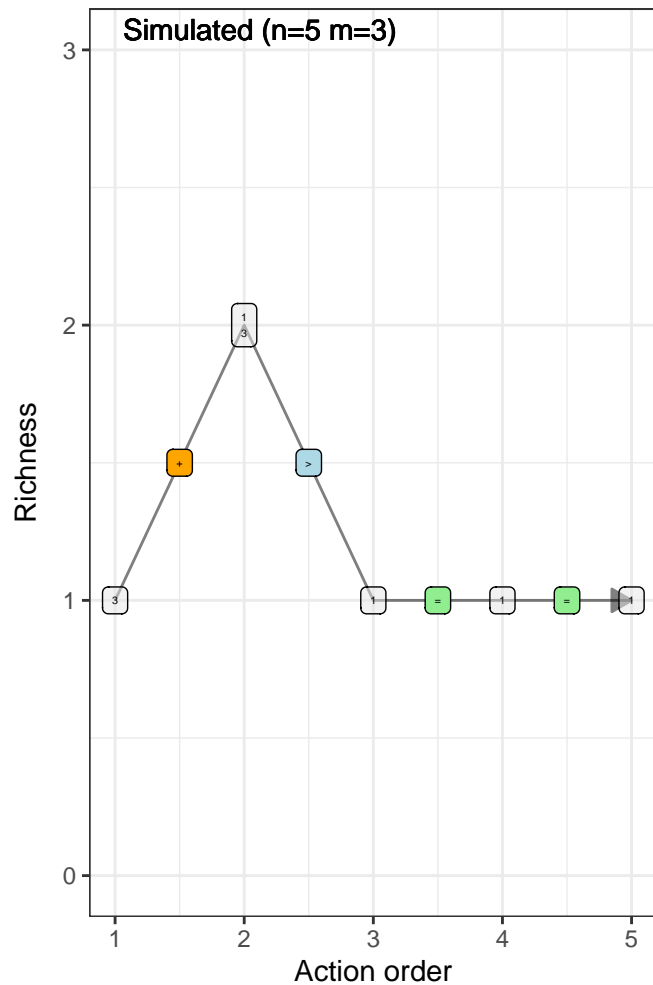
Optimal path



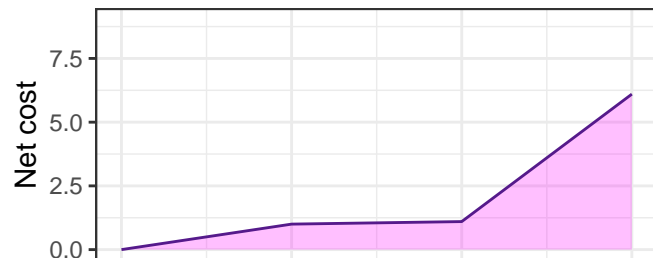
Nominal path



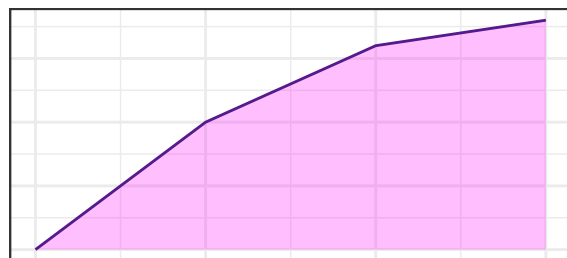
Simulated (n=5 m=3)



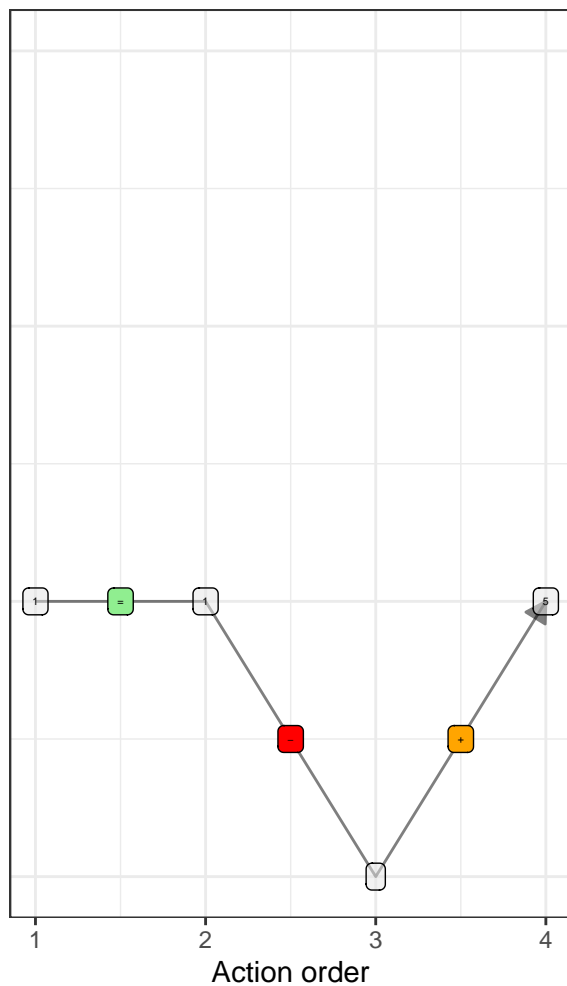
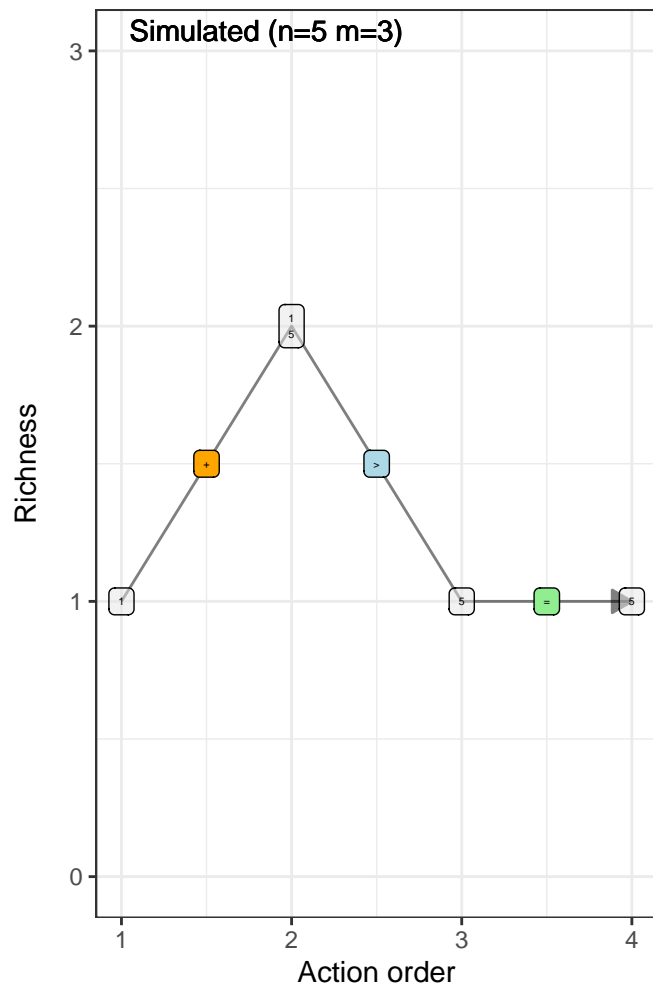
Optimal path



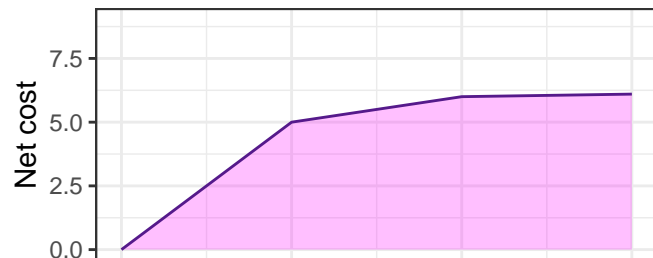
Nominal path



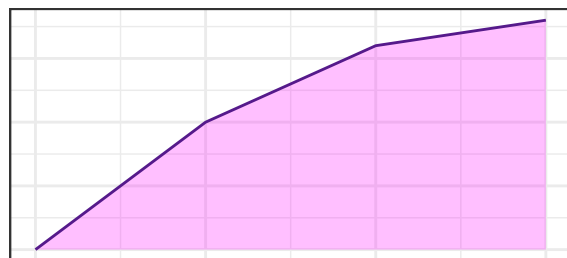
Simulated (n=5 m=3)



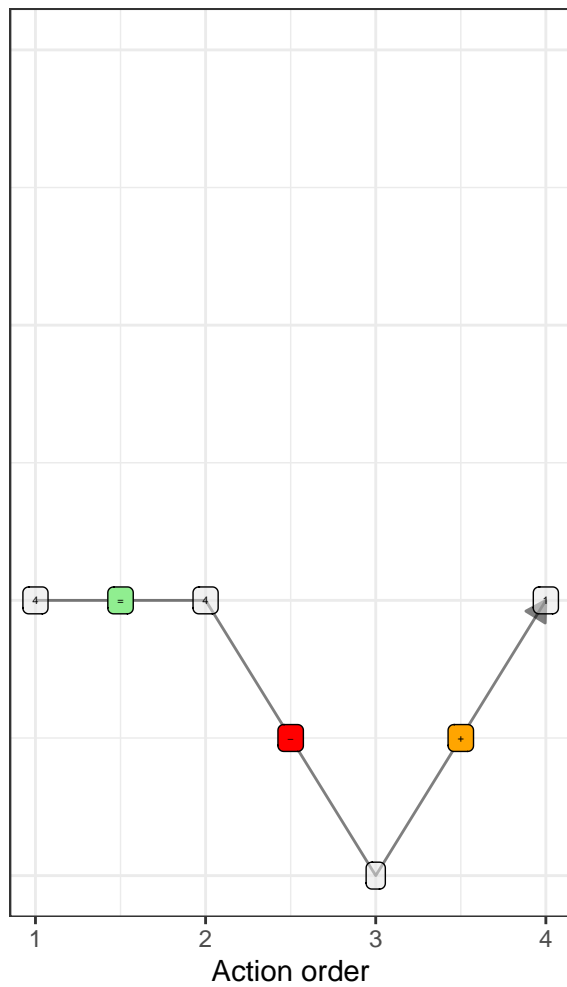
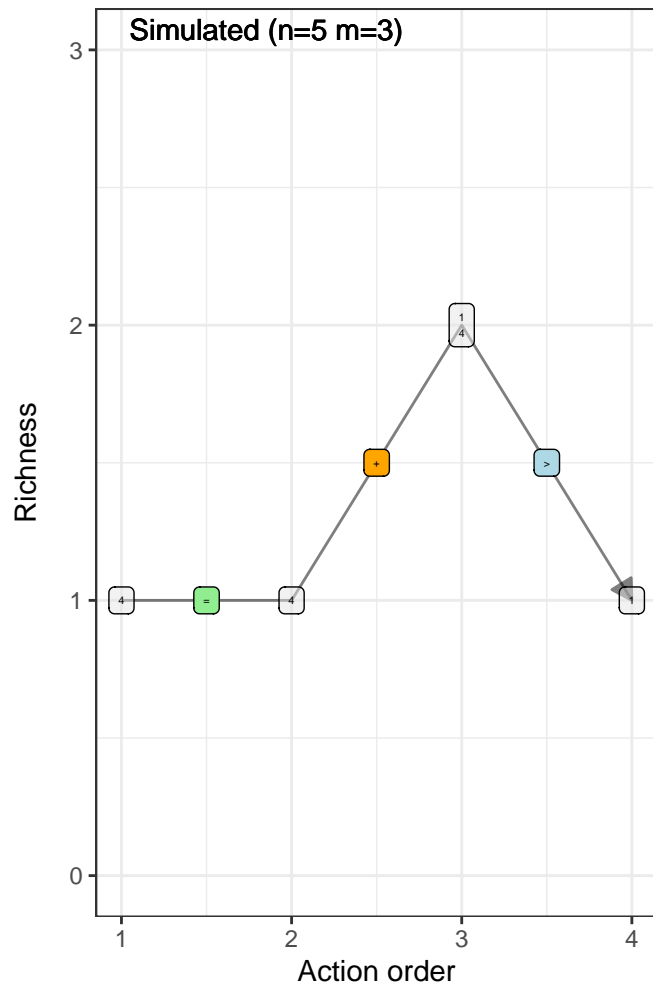
Optimal path



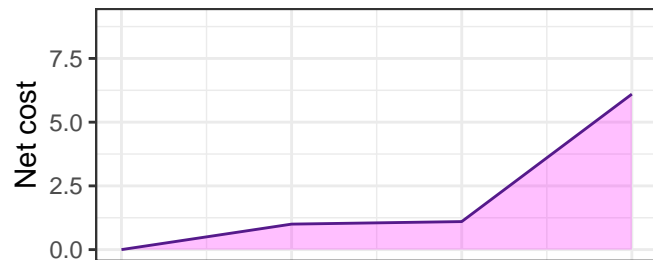
Nominal path



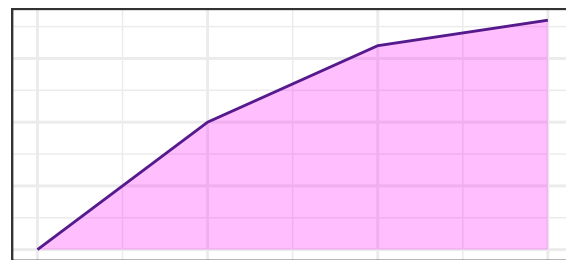
Simulated (n=5 m=3)



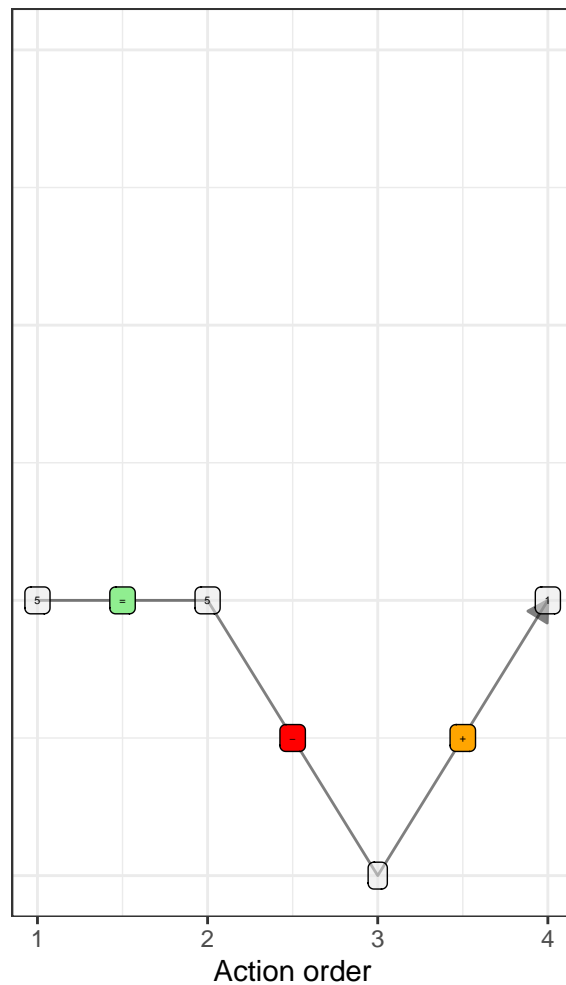
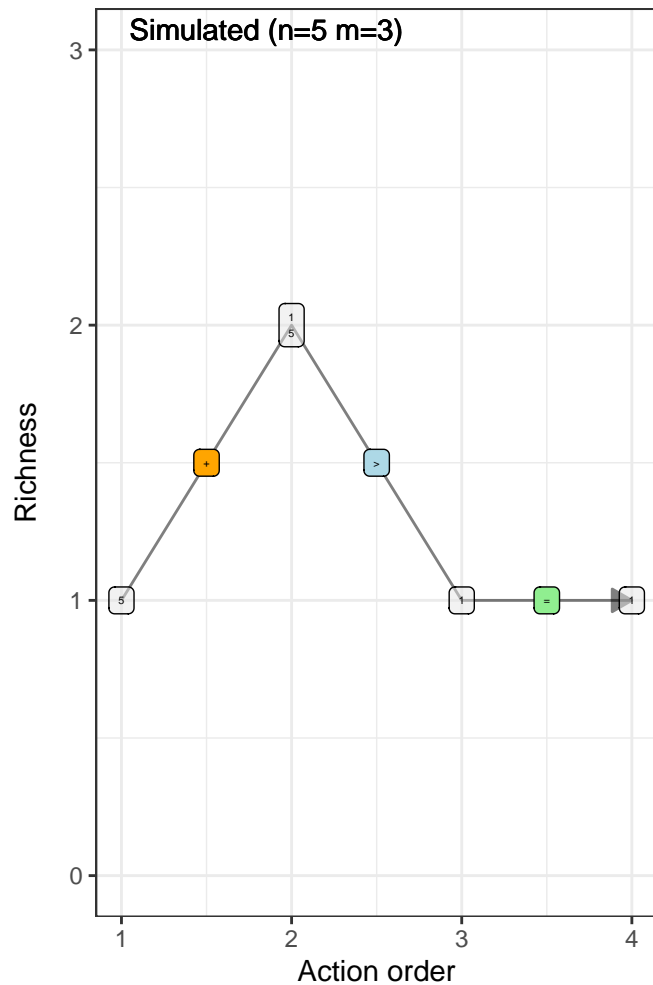
Optimal path



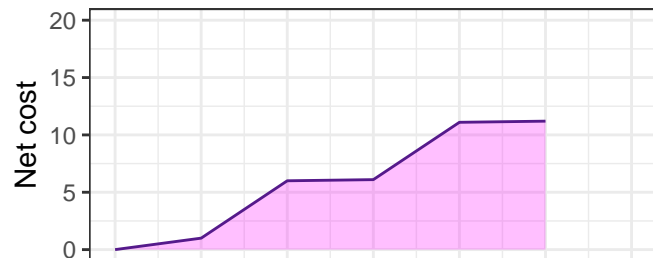
Nominal path



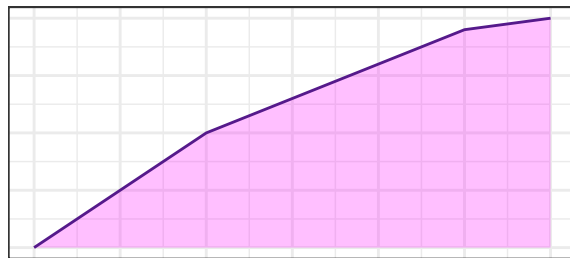
Simulated (n=5 m=3)



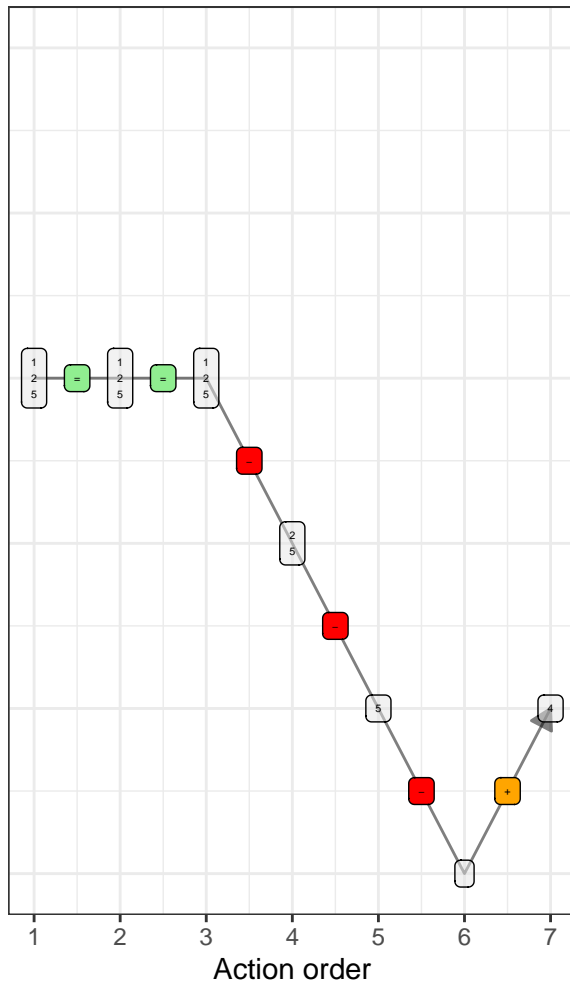
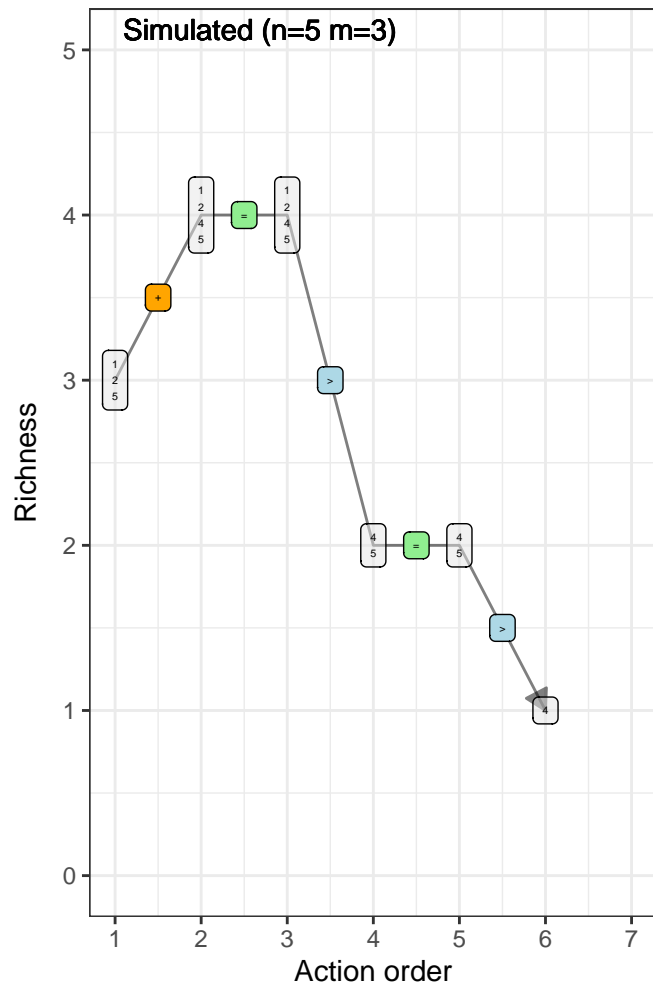
Optimal path



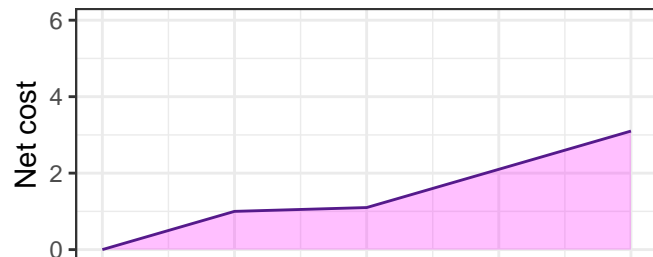
Nominal path



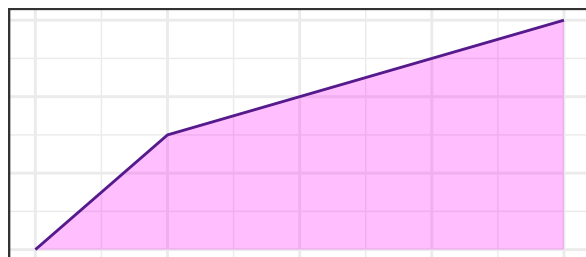
Simulated (n=5 m=3)



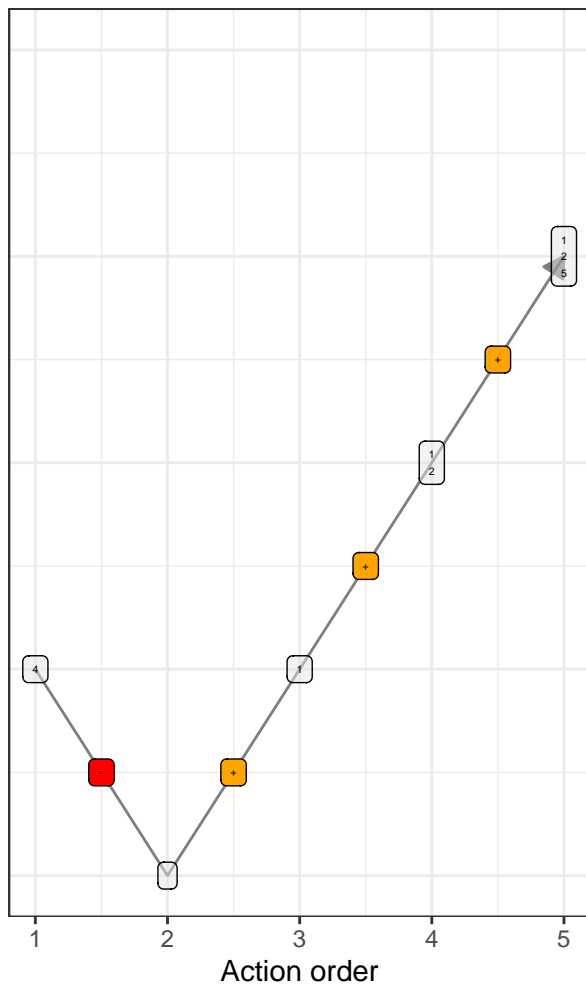
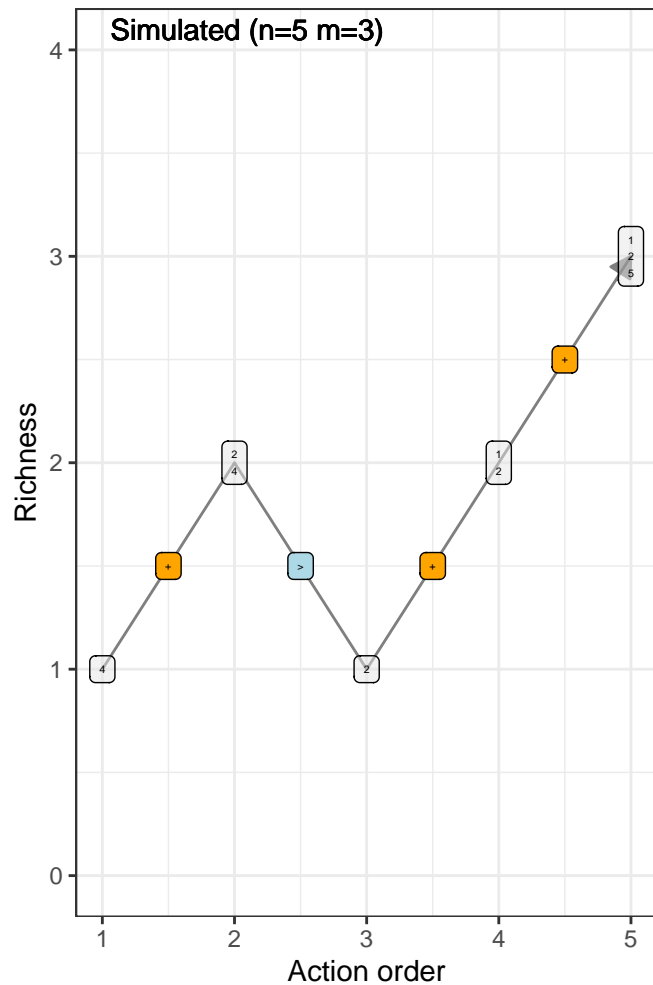
Optimal path



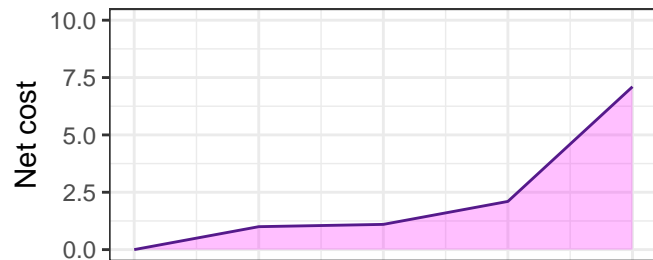
Nominal path



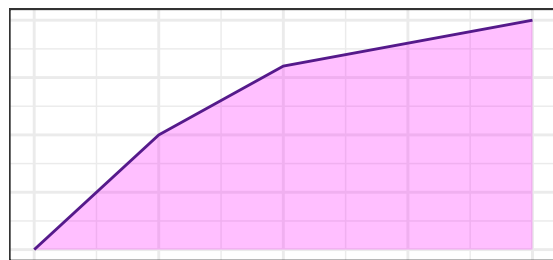
Simulated (n=5 m=3)



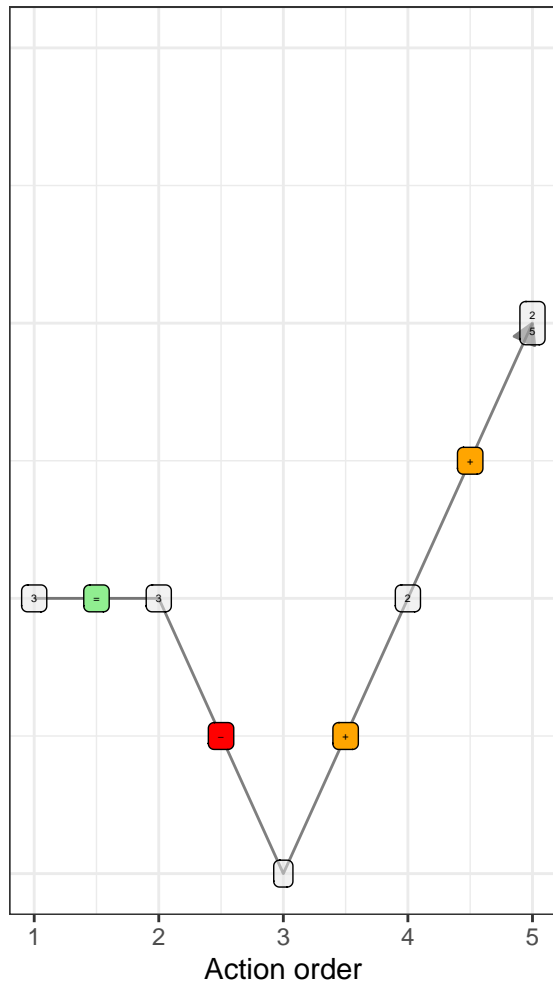
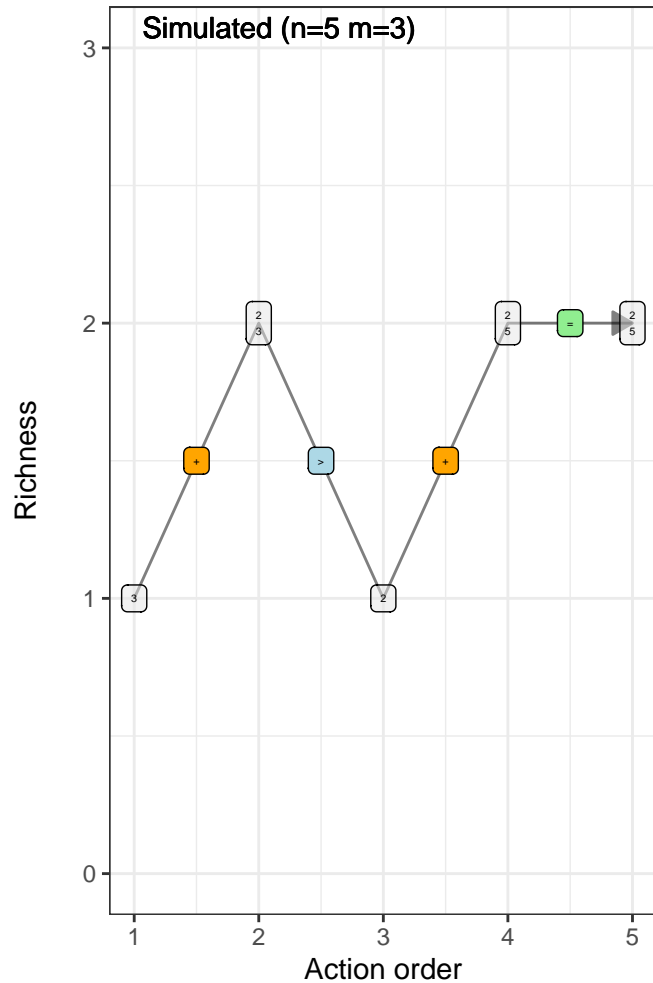
Optimal path



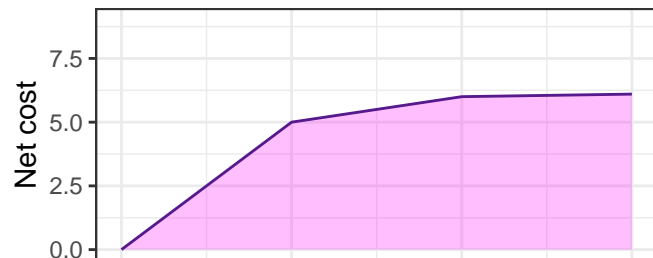
Nominal path



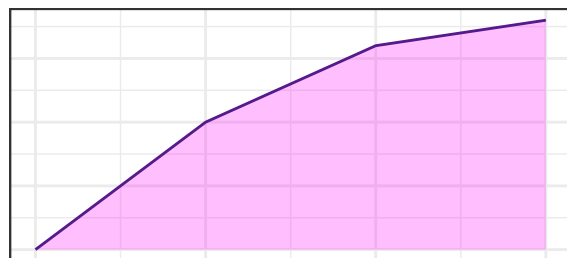
Simulated (n=5 m=3)



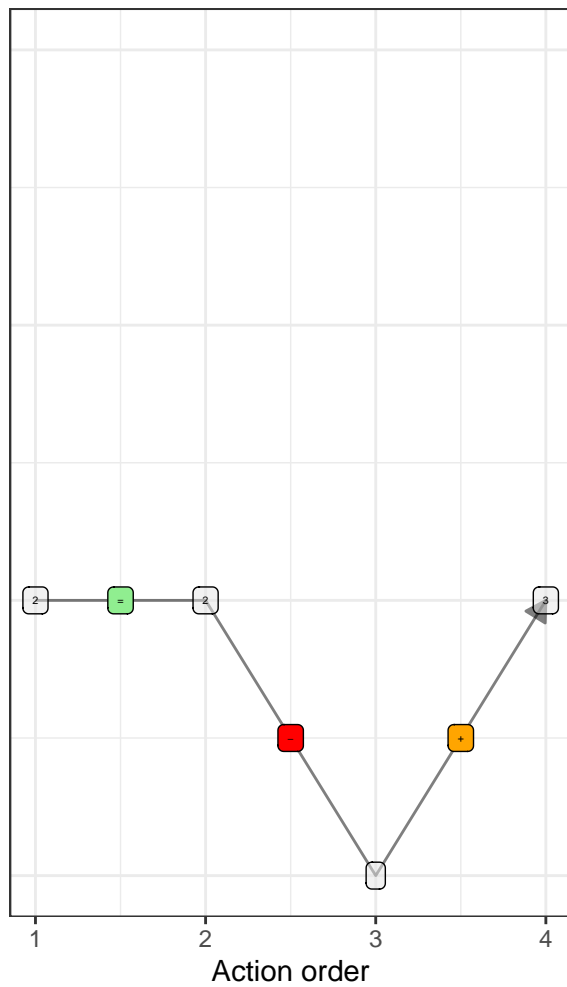
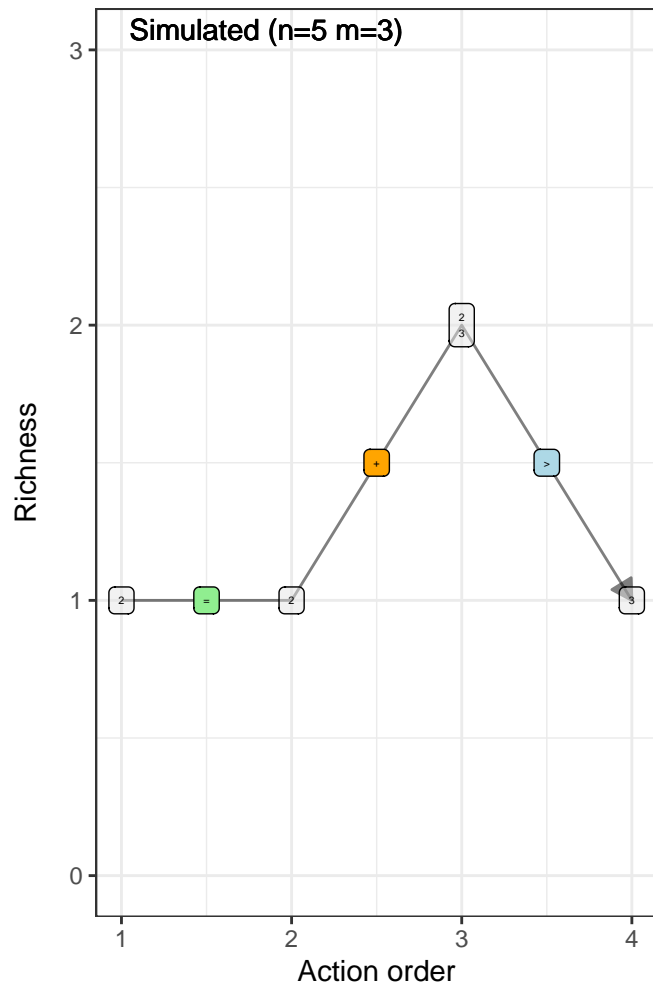
Optimal path



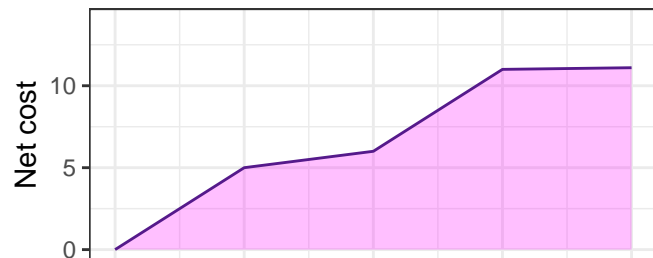
Nominal path



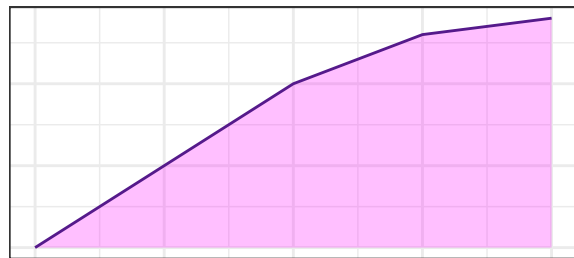
Simulated (n=5 m=3)



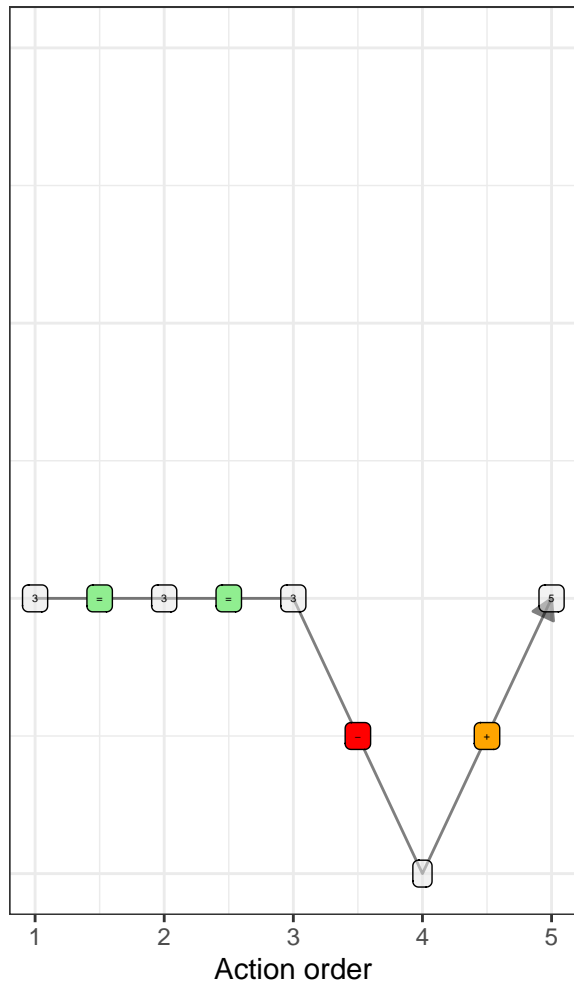
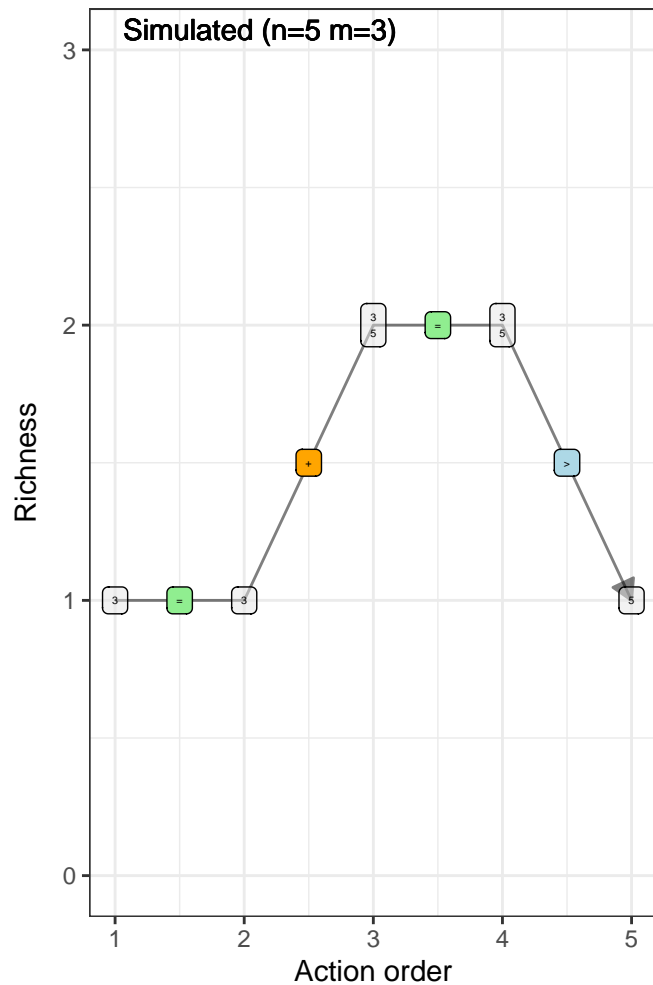
Optimal path



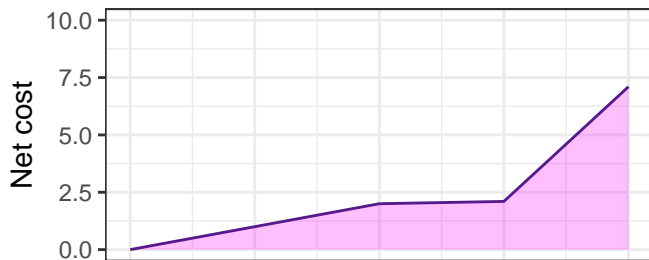
Nominal path



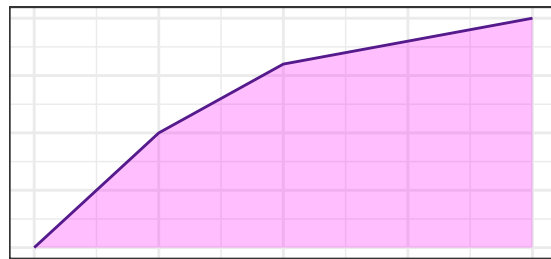
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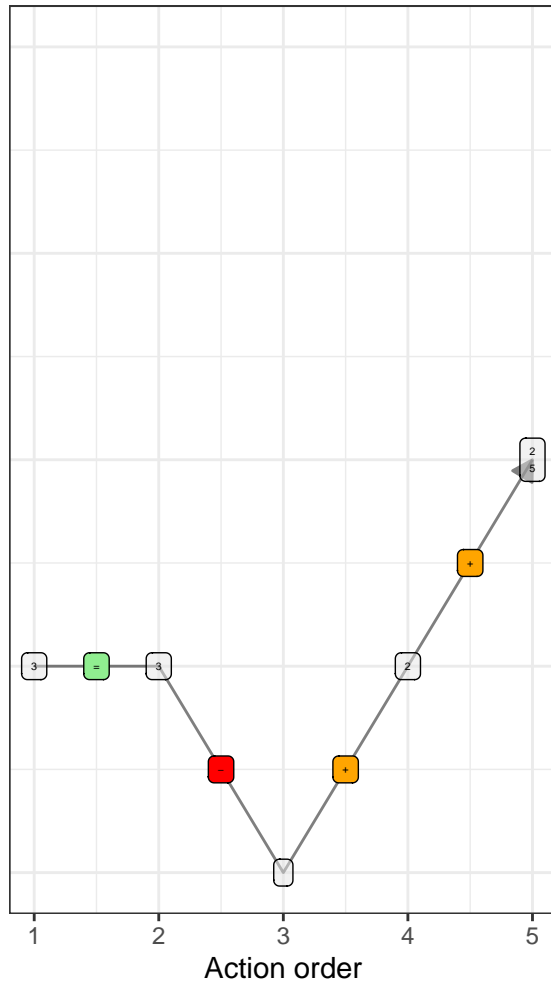
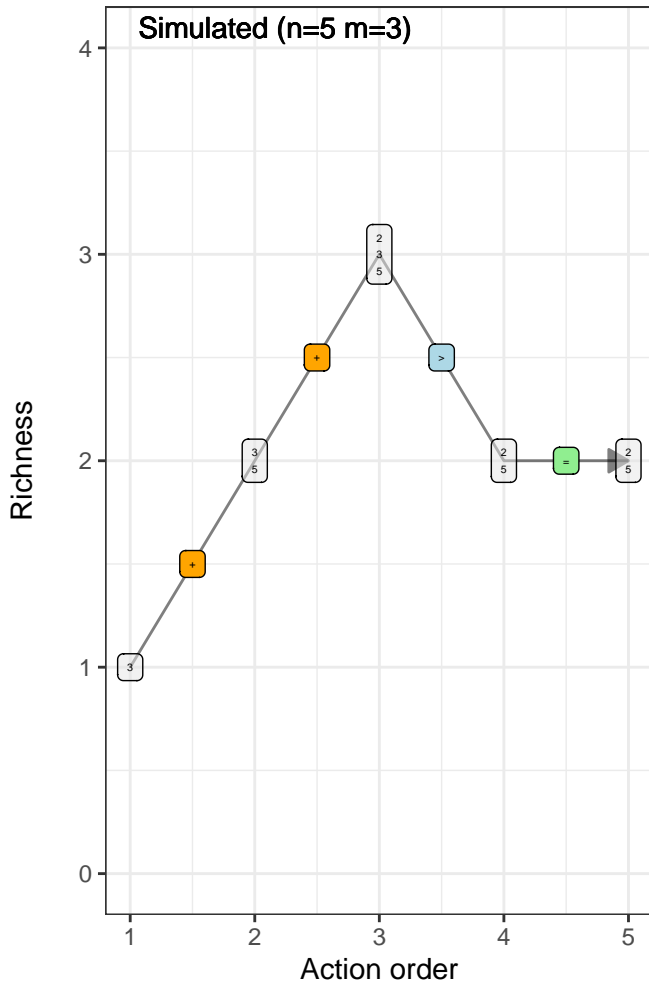
Optimal path



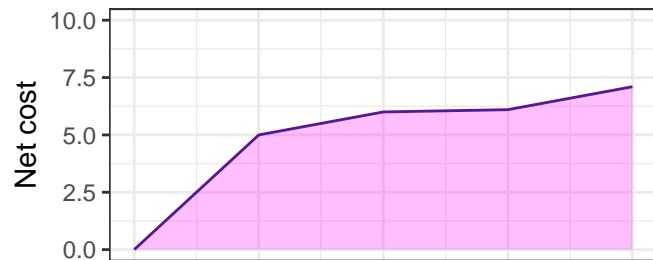
Nominal path



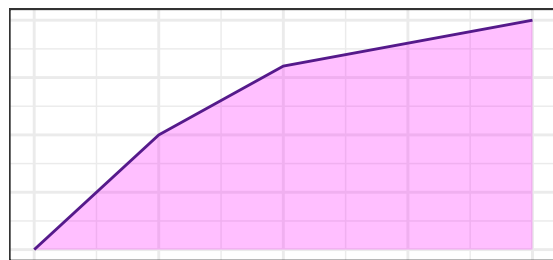
Simulated (n=5 m=3)



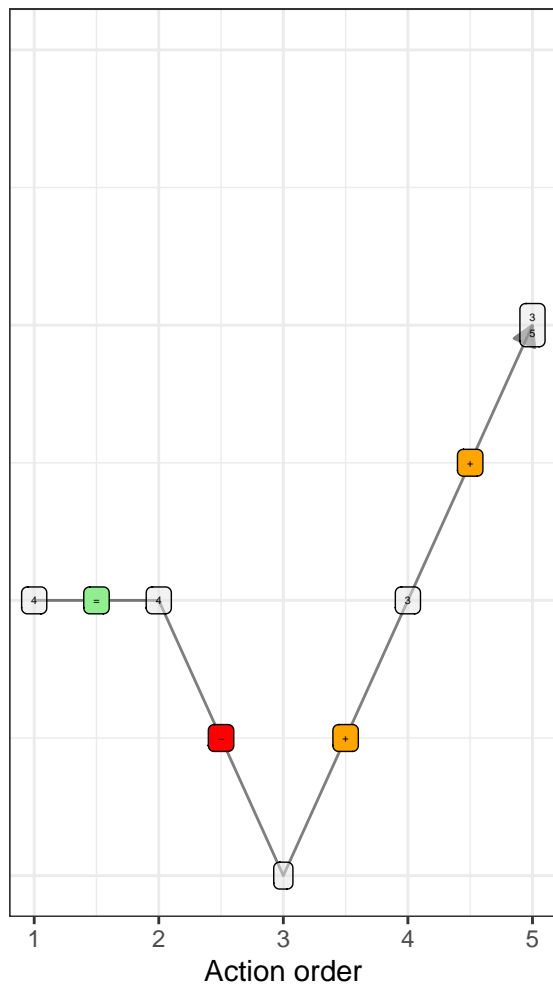
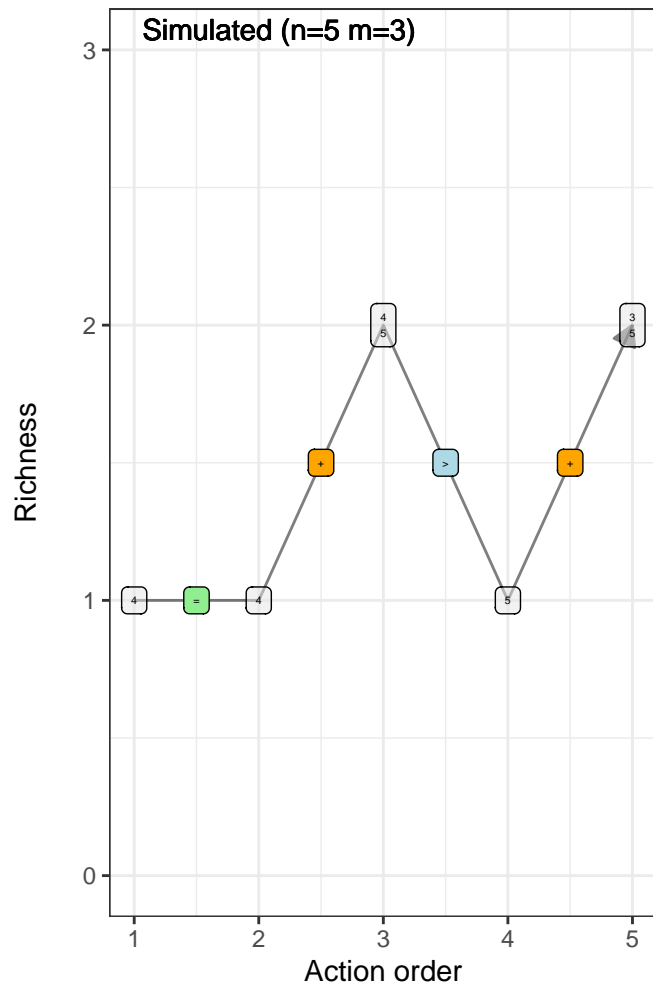
Optimal path



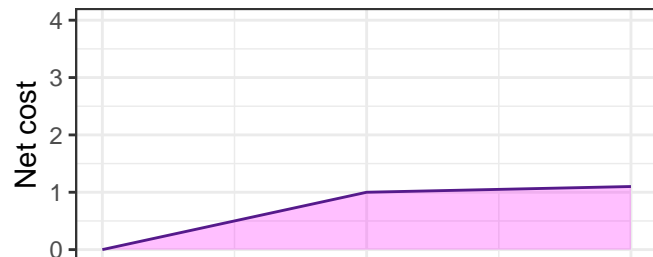
Nominal path



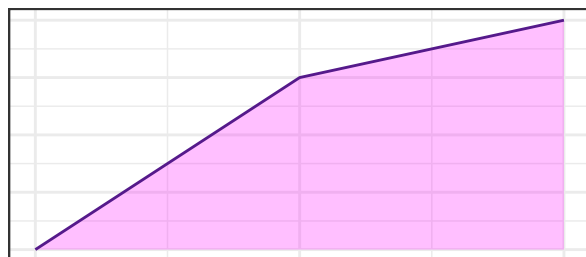
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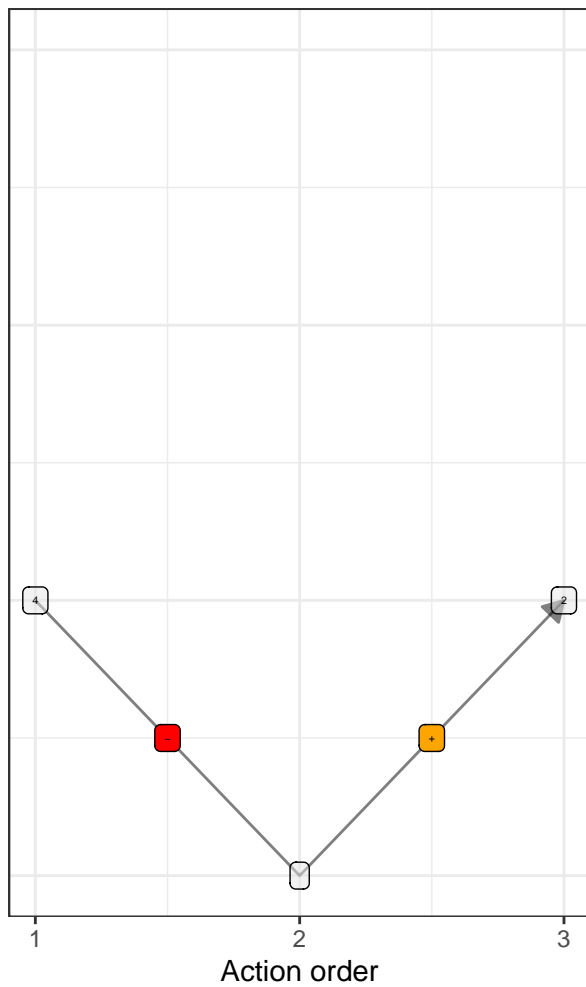
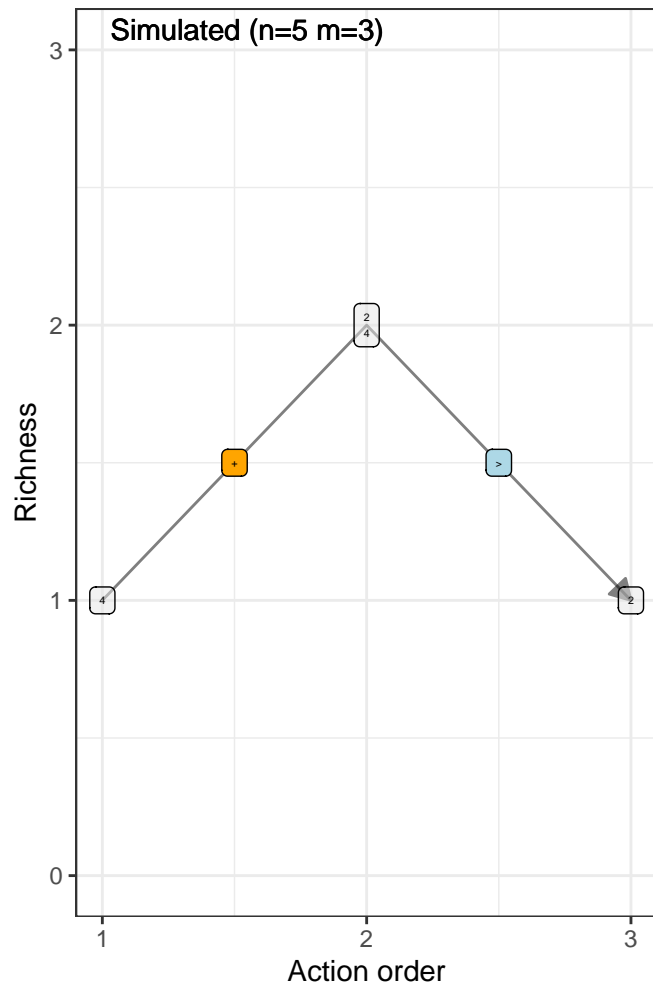
Optimal path



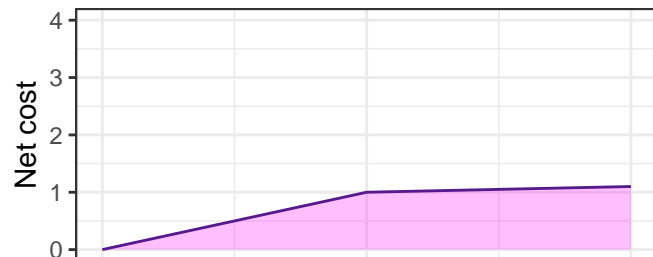
Nominal path



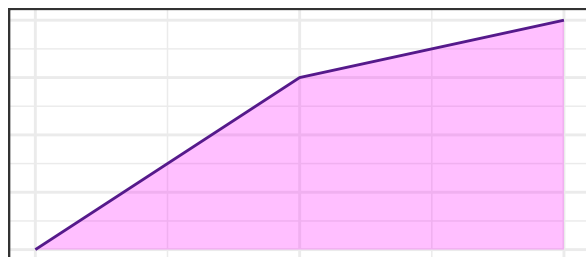
Simulated (n=5 m=3)



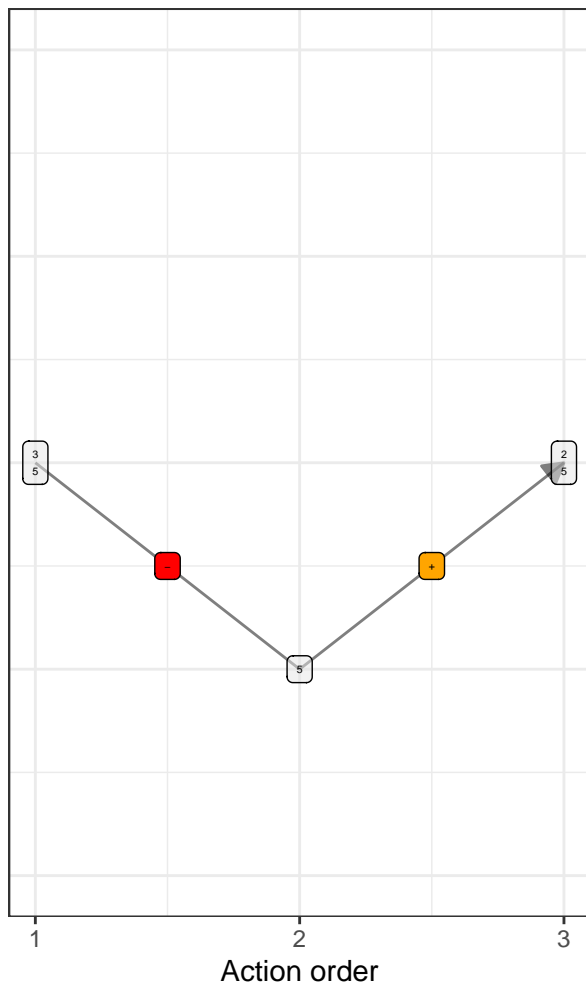
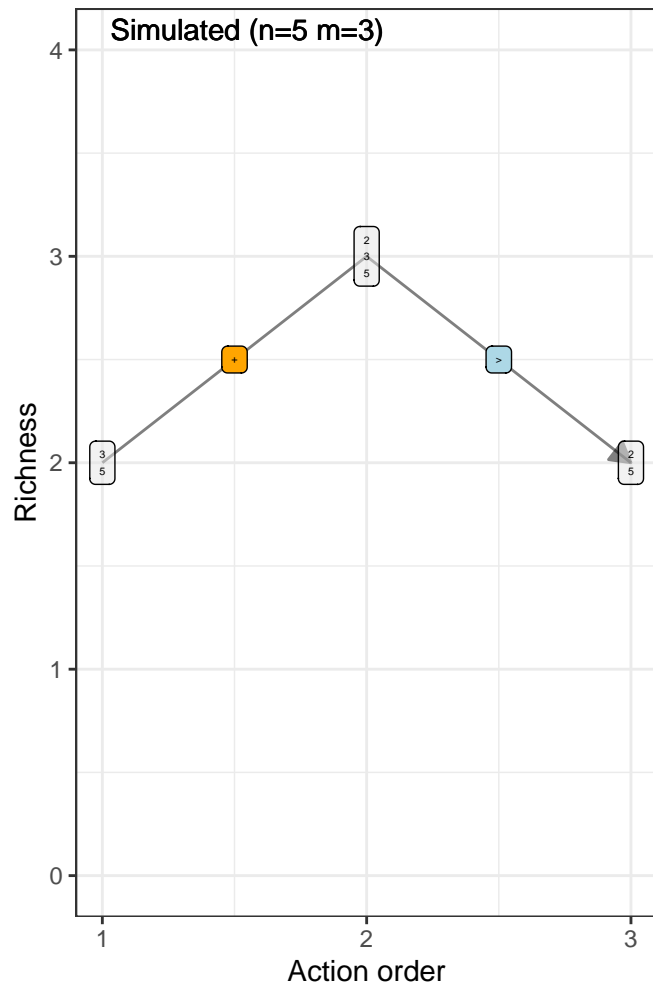
Optimal path



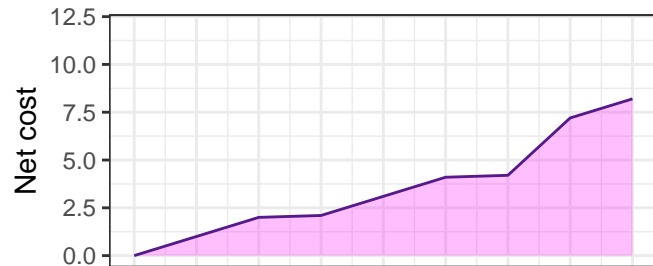
Nominal path



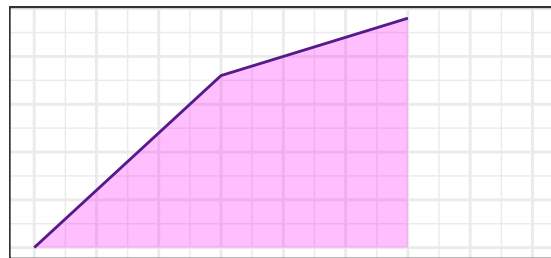
Simulated (n=5 m=3)



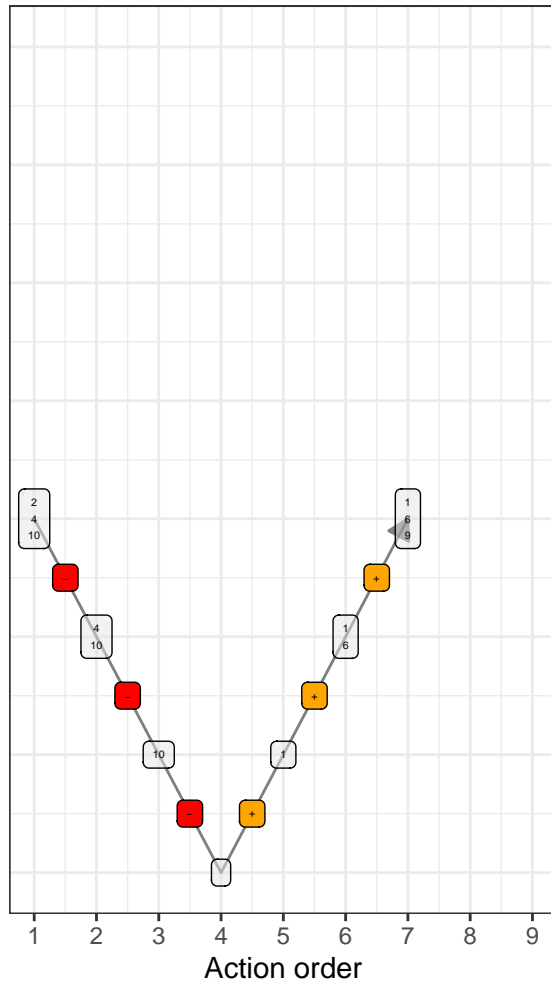
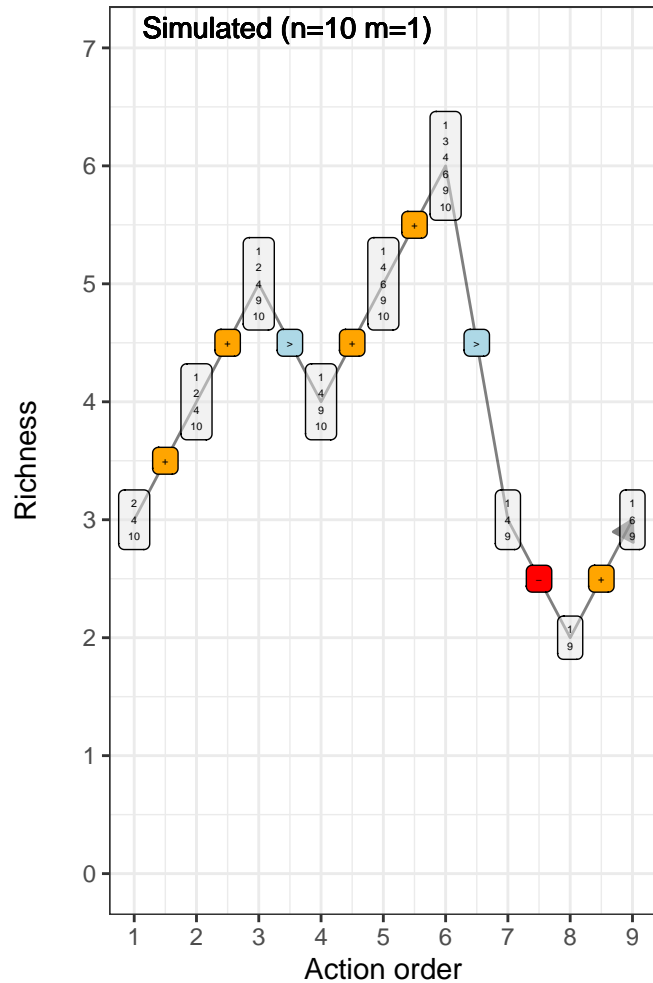
Optimal path



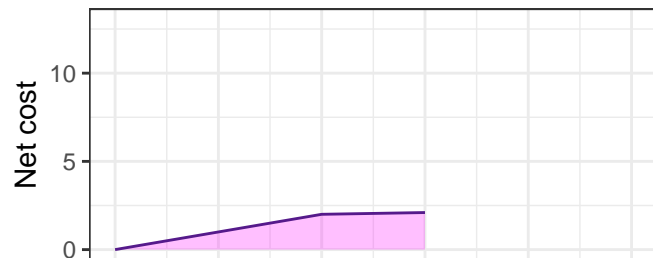
Nominal path



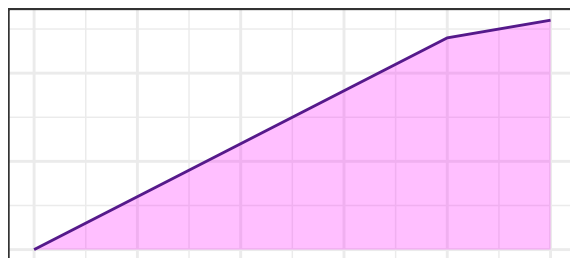
Simulated (n=10 m=1)



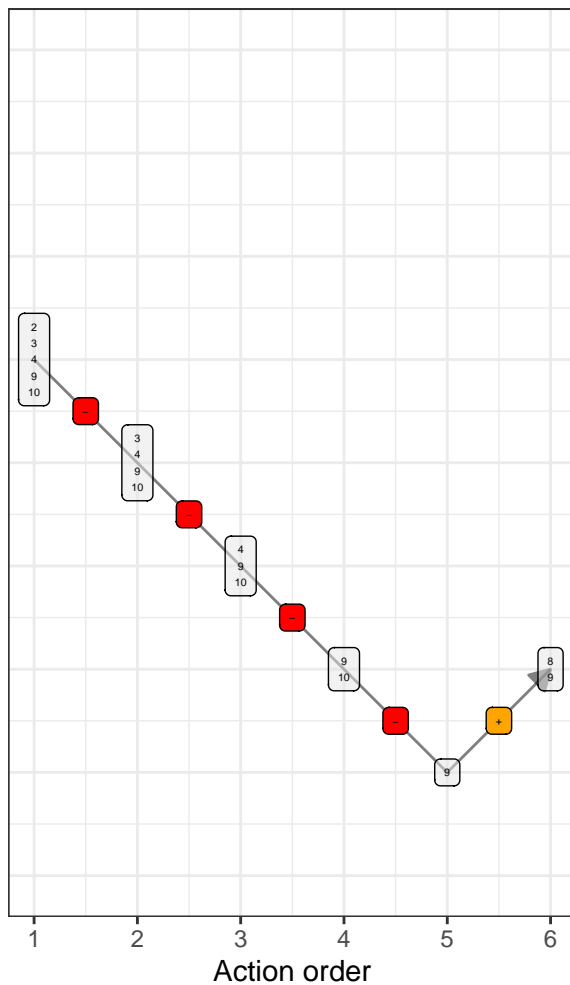
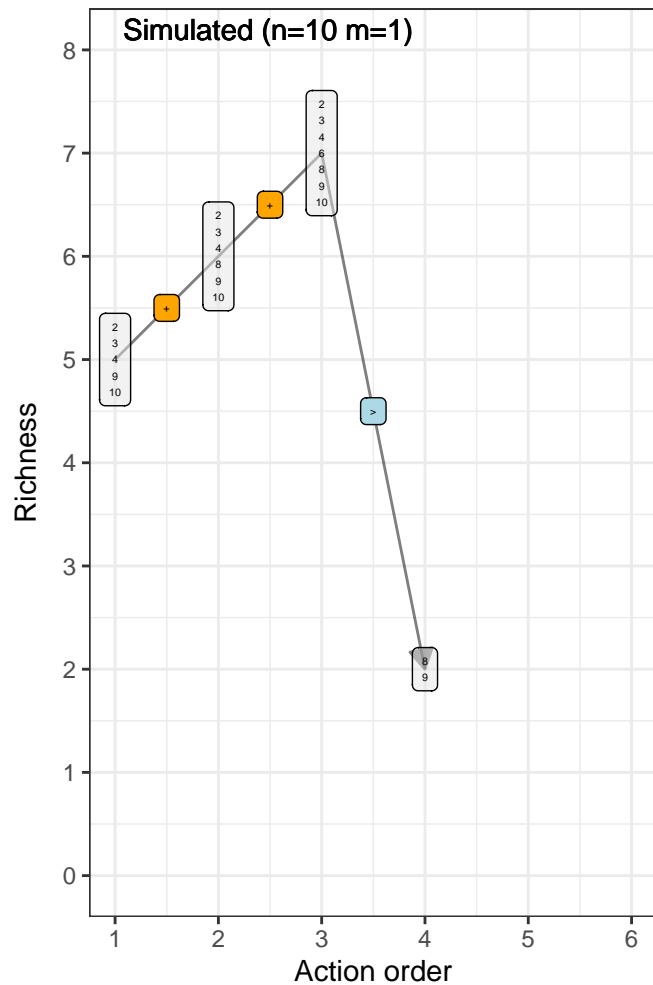
Optimal path



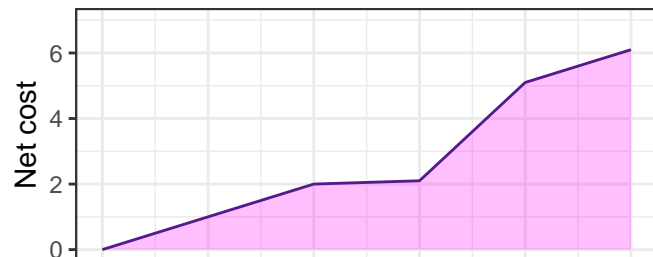
Nominal path



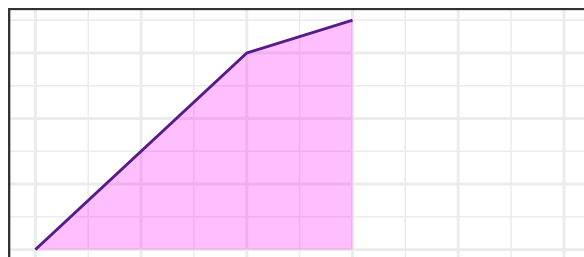
Simulated (n=10 m=1)



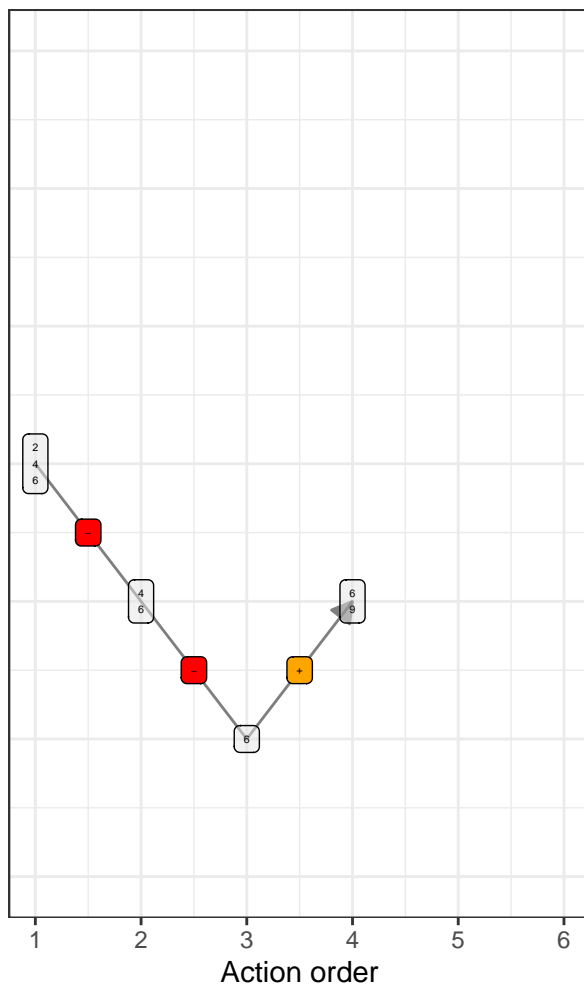
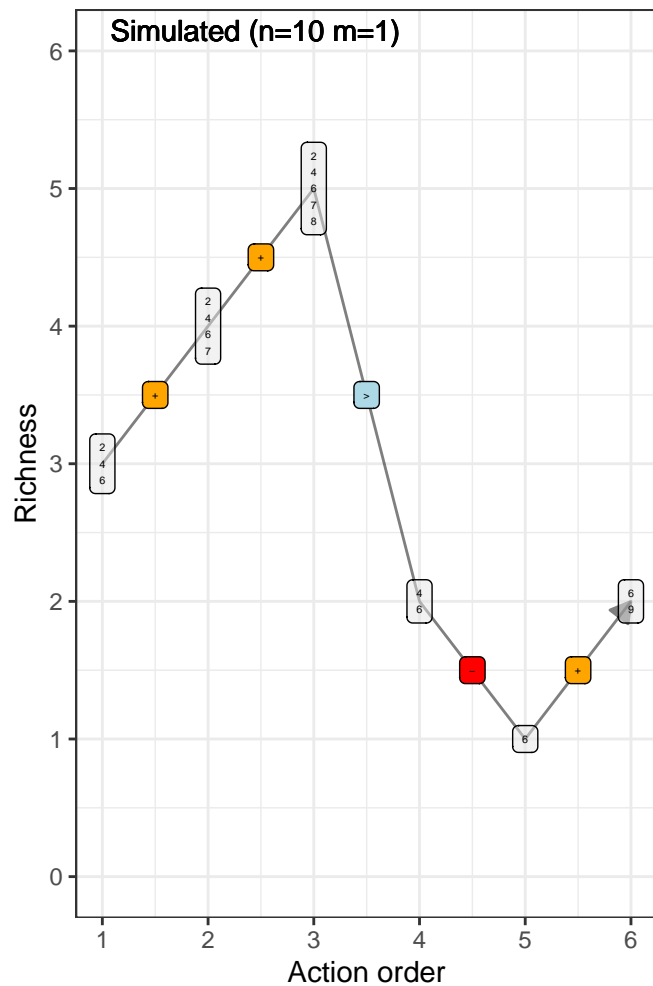
Optimal path



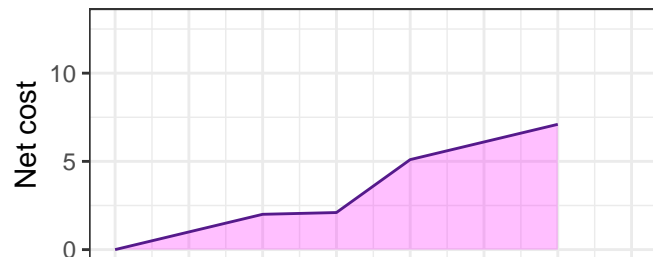
Nominal path



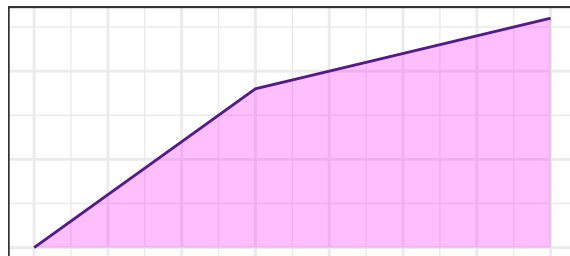
Simulated (n=10 m=1)



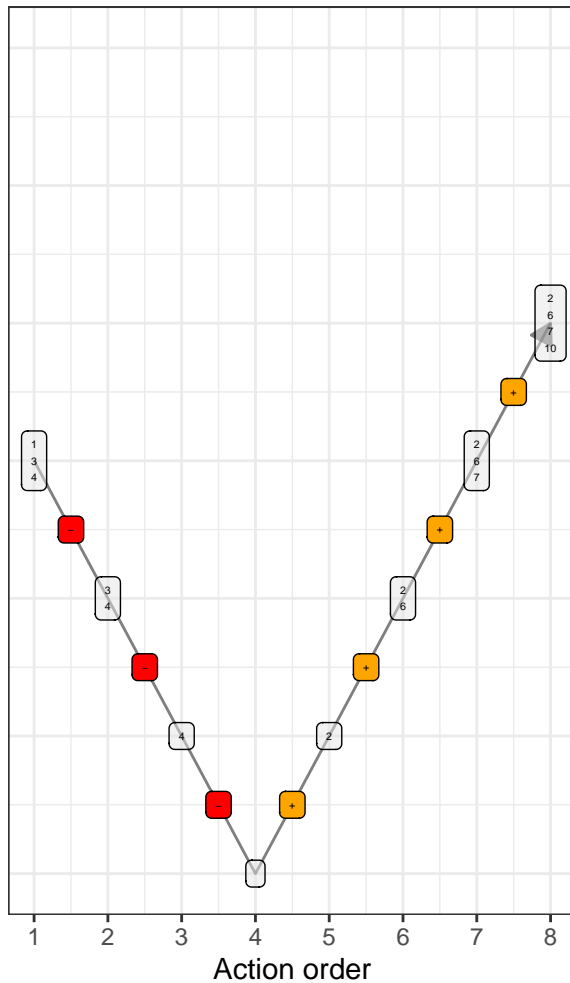
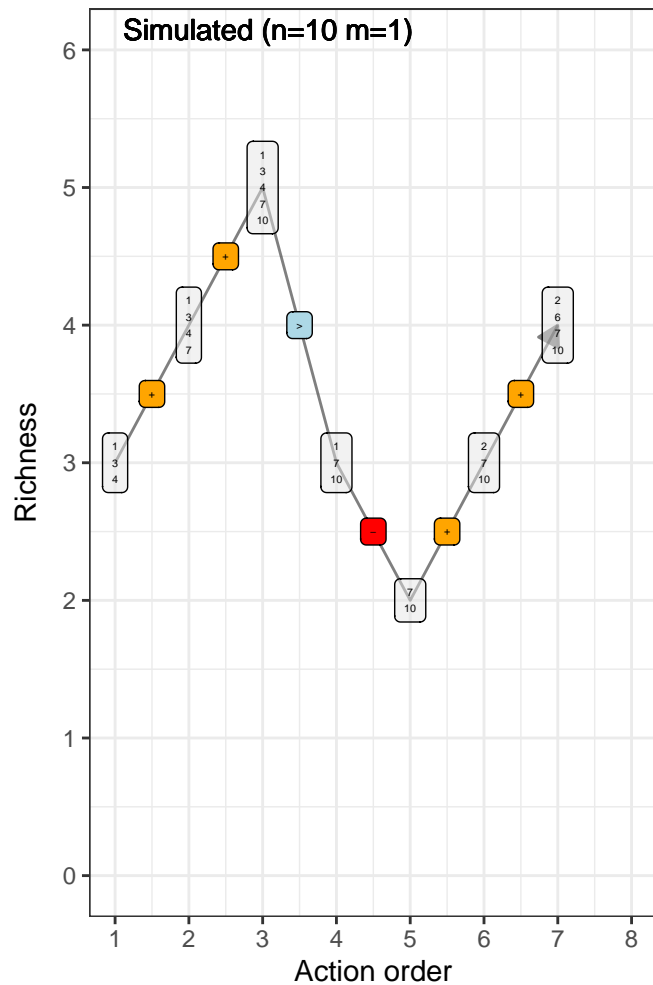
Optimal path



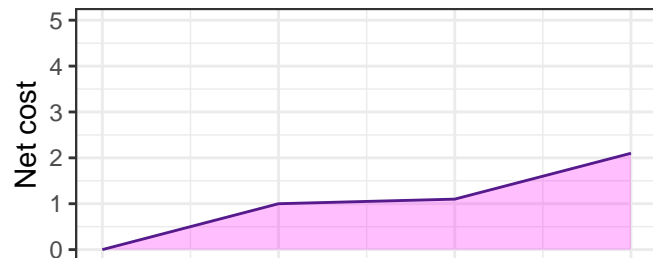
Nominal path



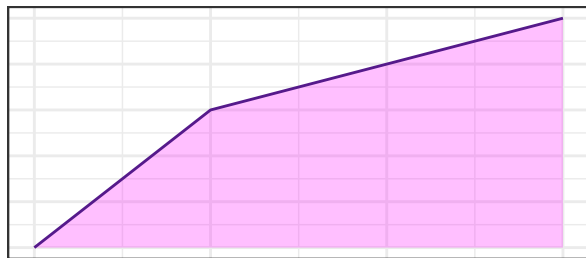
Simulated (n=10 m=1)



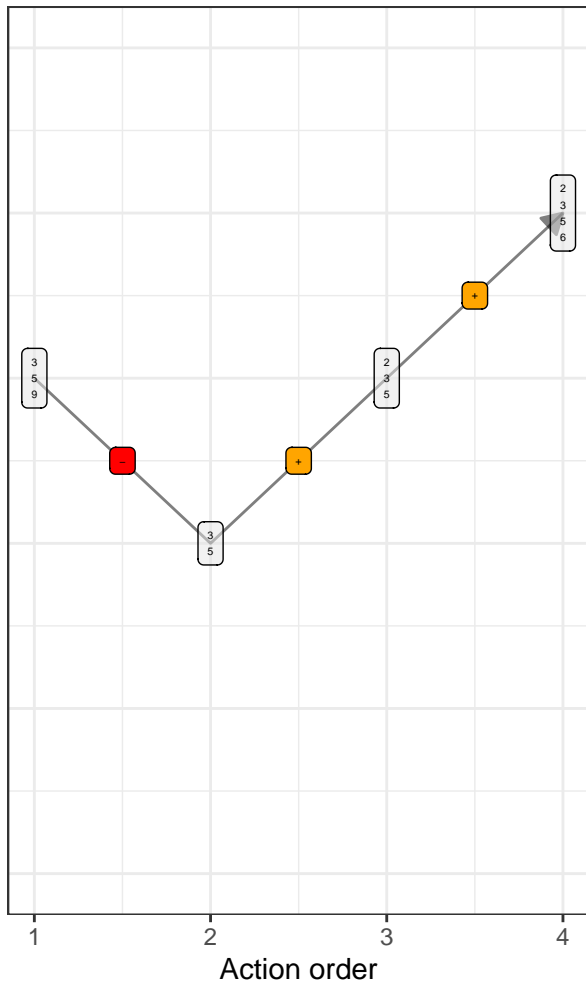
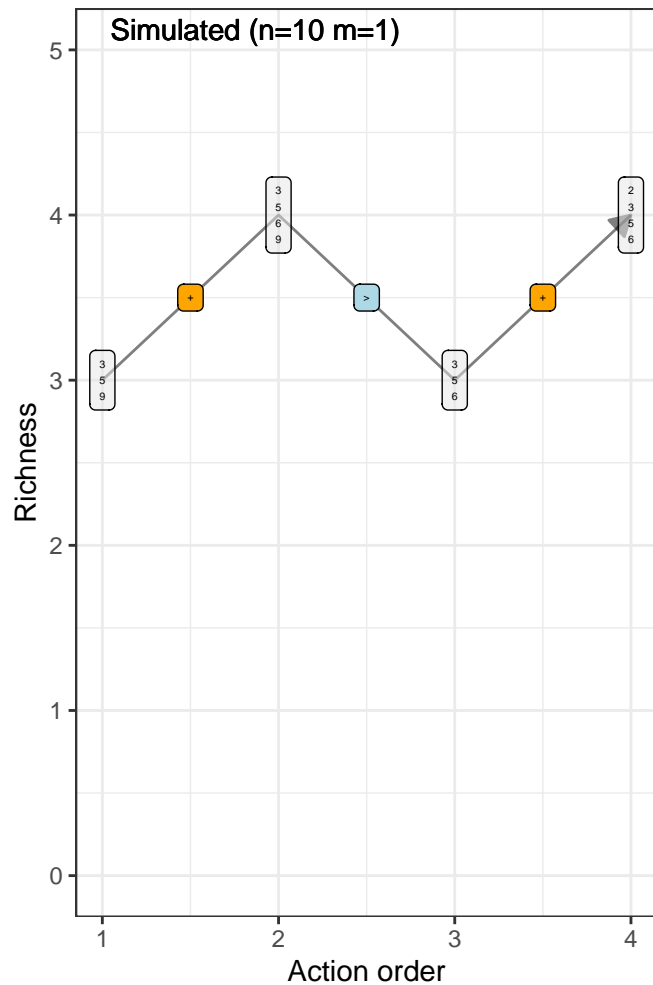
Optimal path



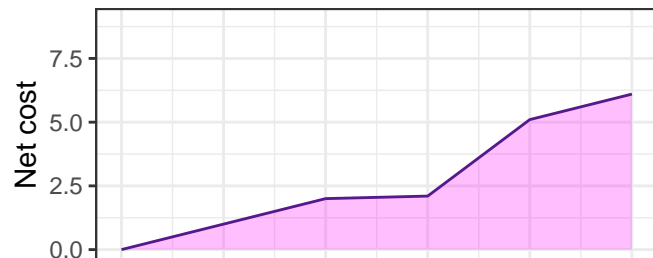
Nominal path



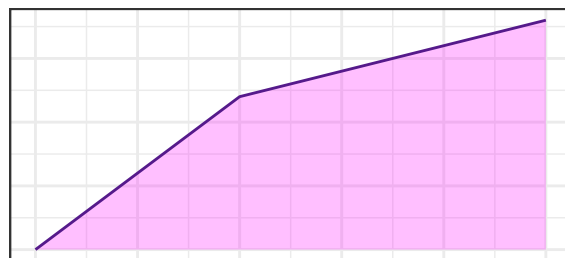
Simulated (n=10 m=1)



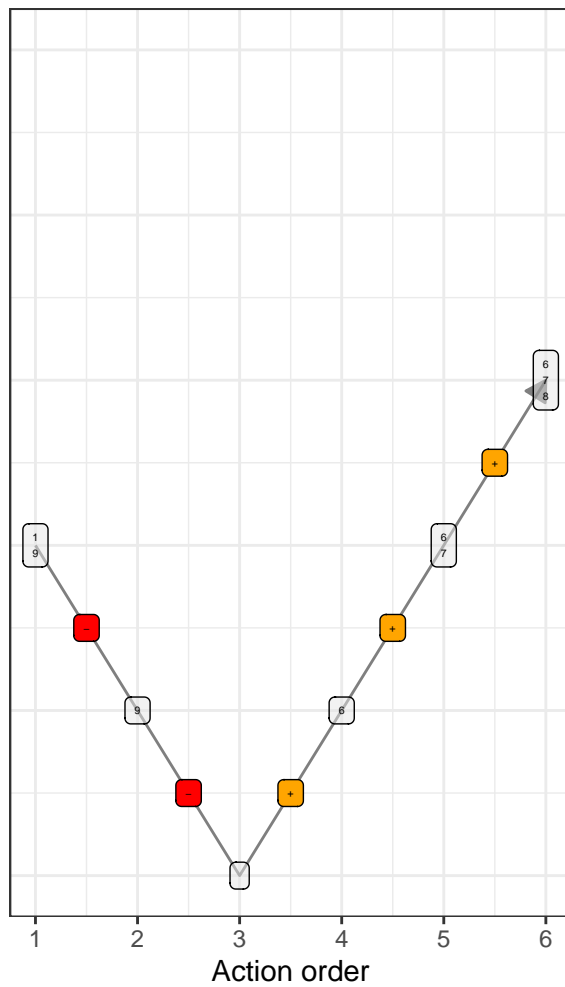
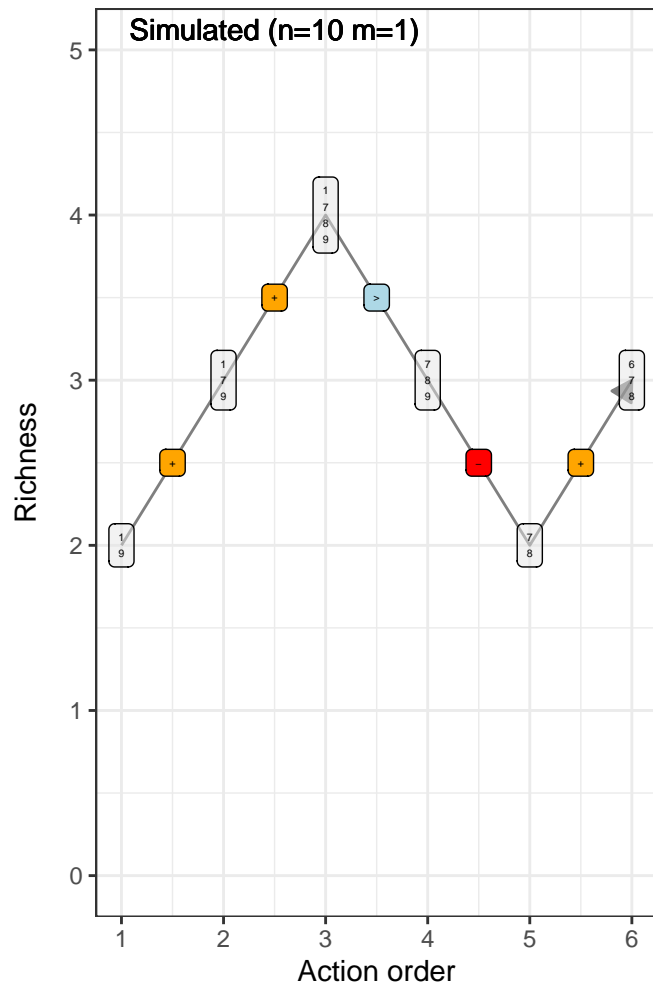
Optimal path



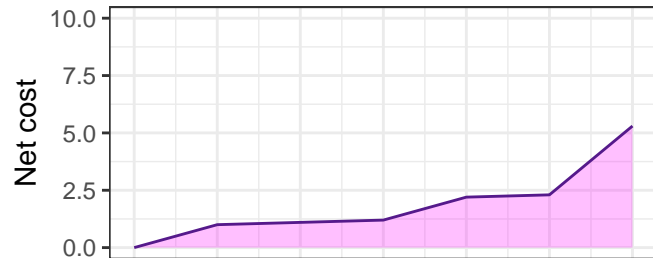
Nominal path



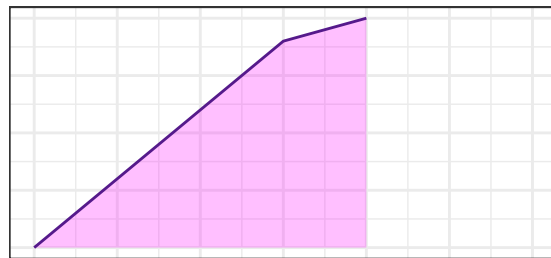
Simulated (n=10 m=1)



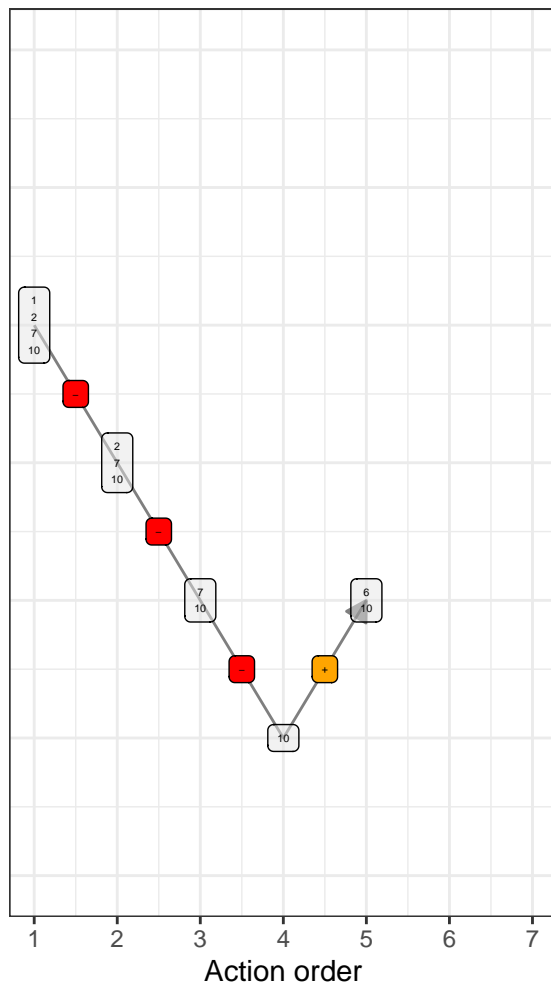
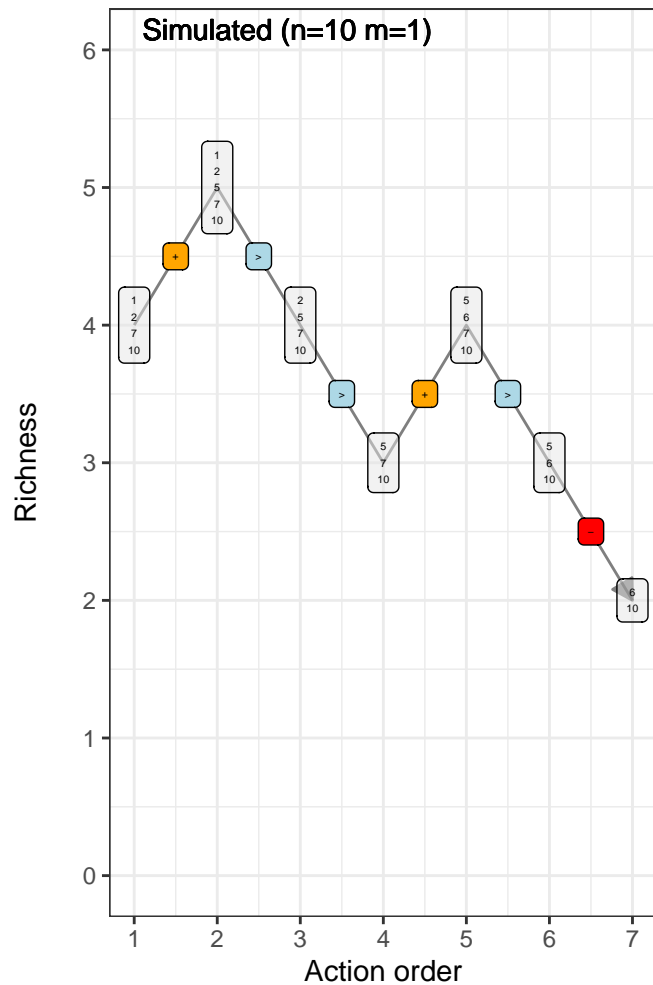
Optimal path



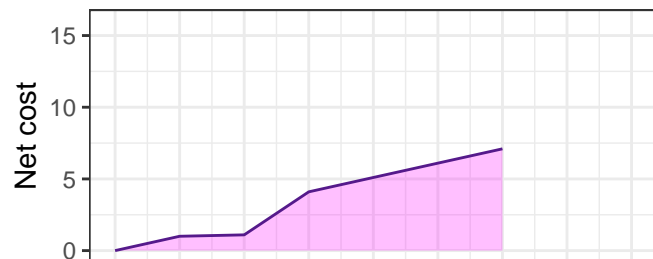
Nominal path



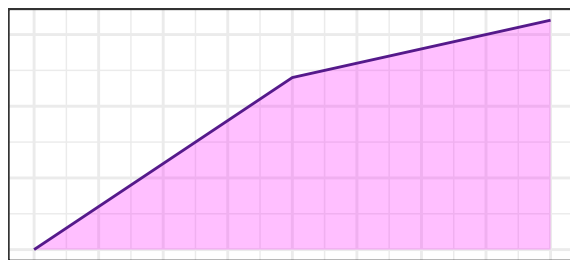
Simulated (n=10 m=1)



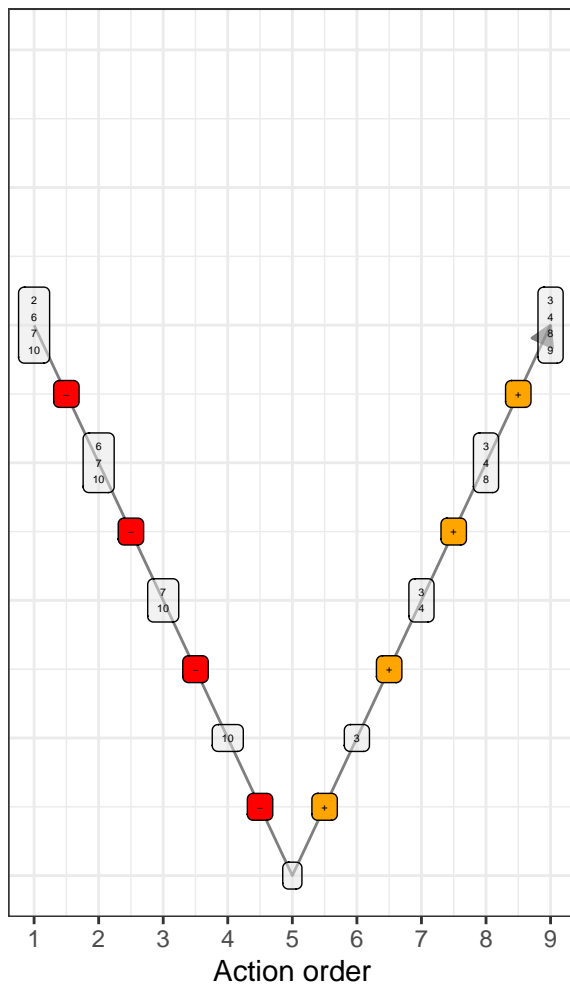
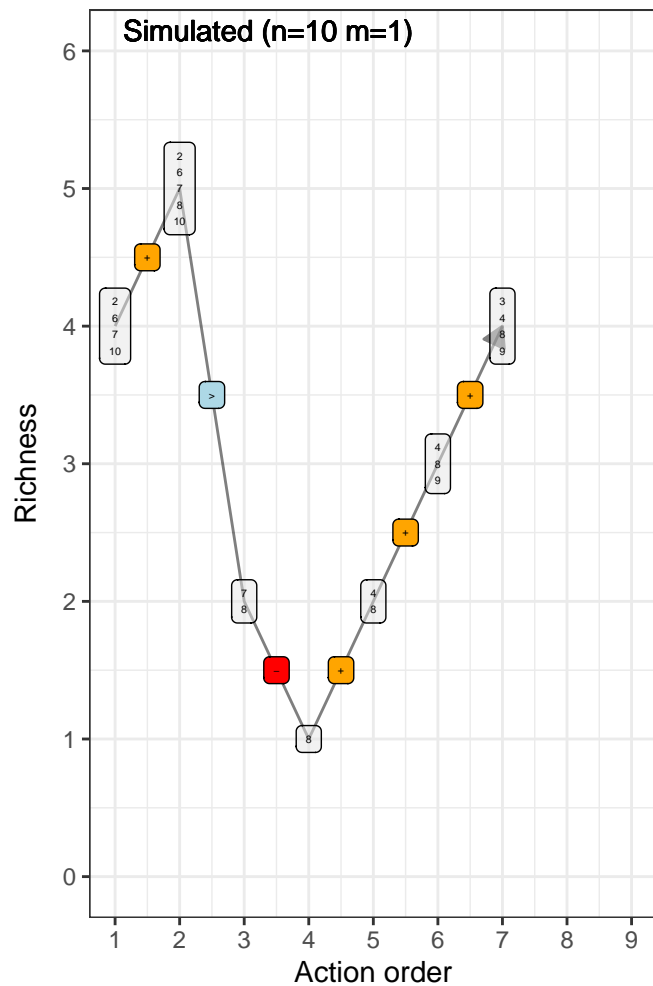
Optimal path



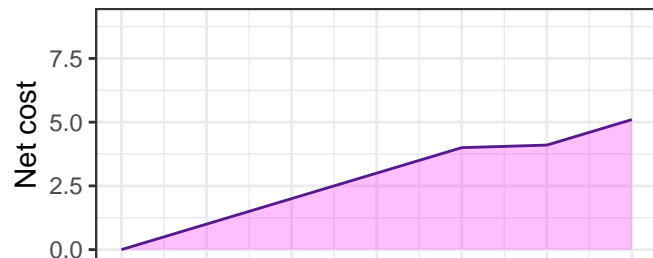
Nominal path



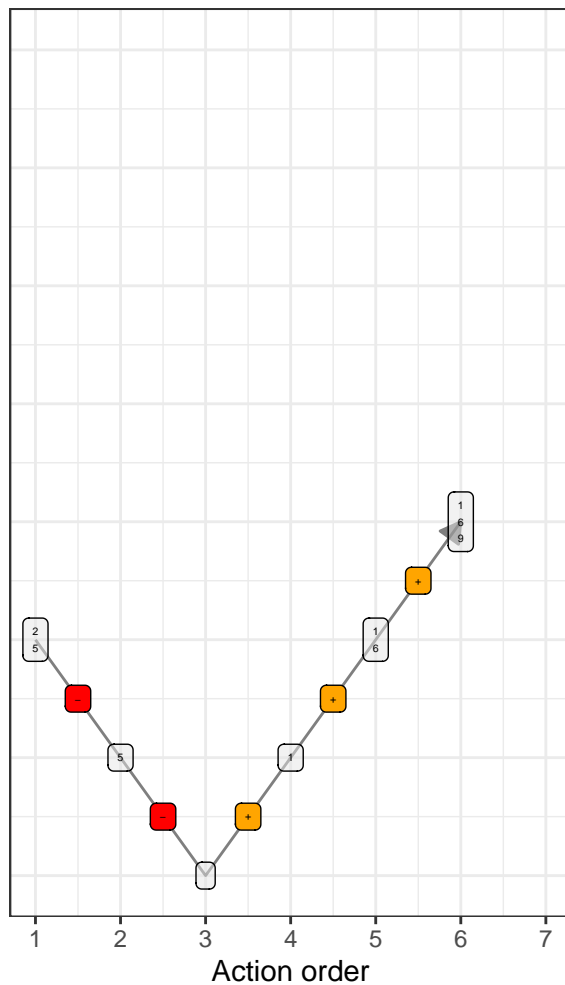
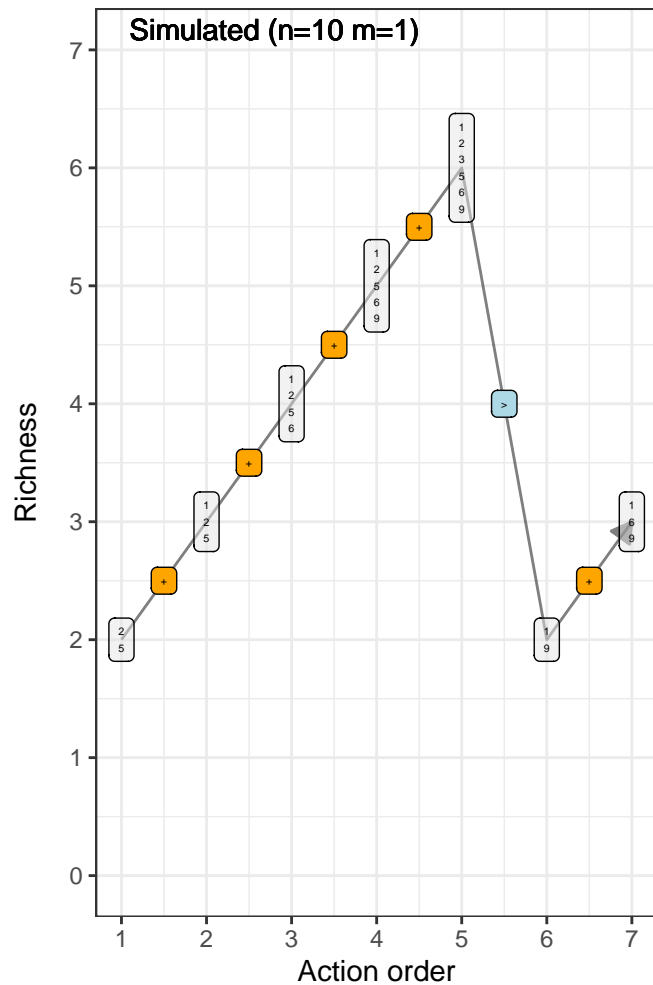
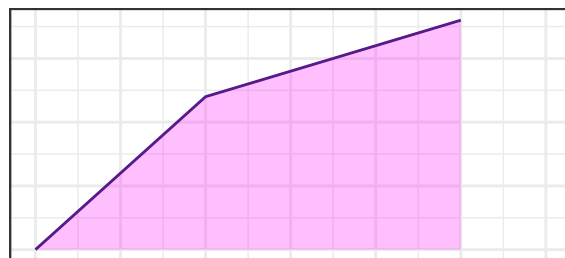
Simulated (n=10 m=1)



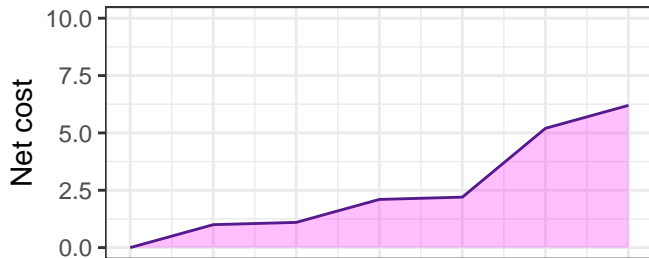
Optimal path



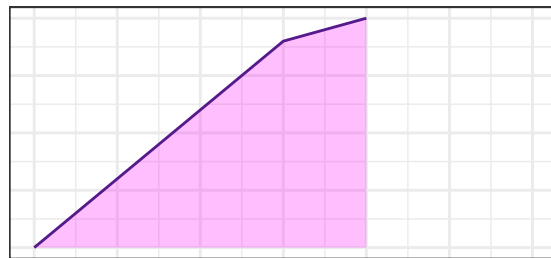
Nominal path



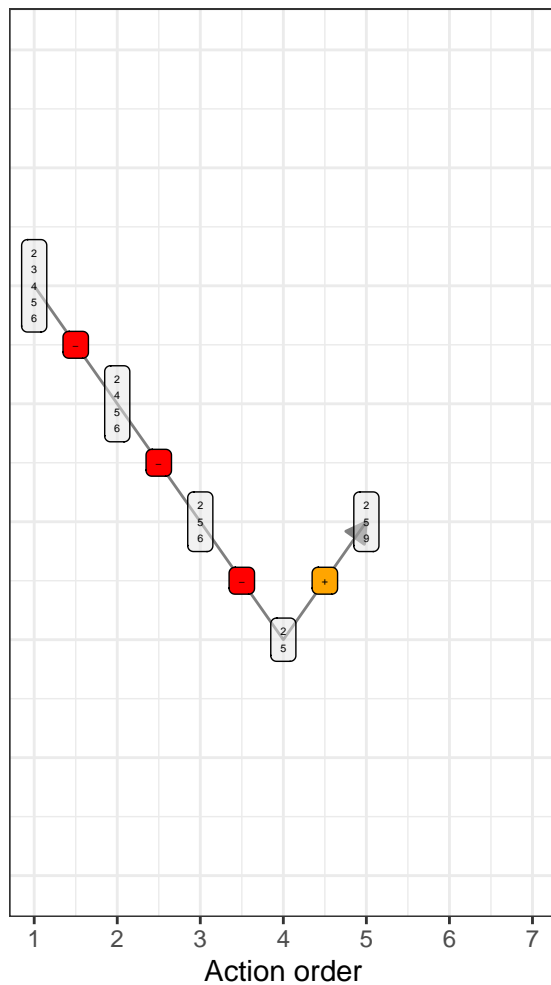
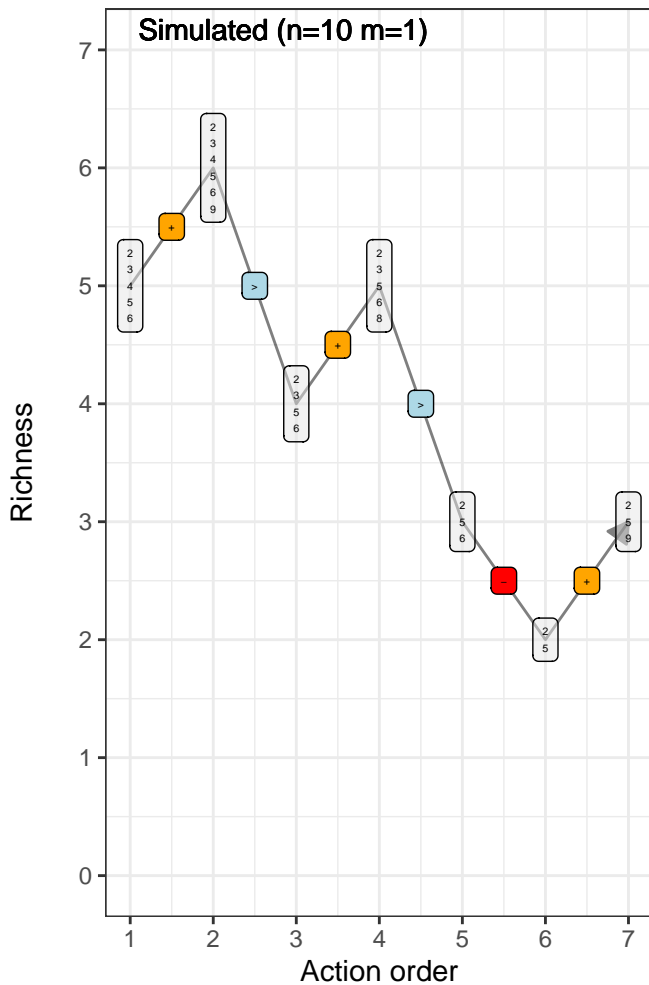
Optimal path



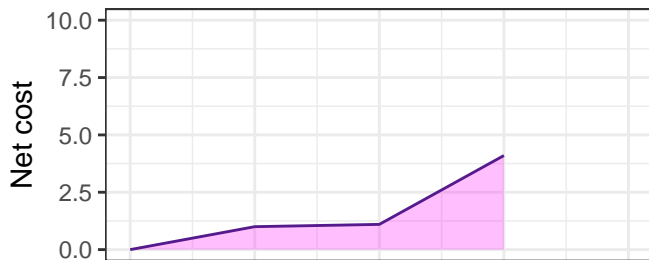
Nominal path



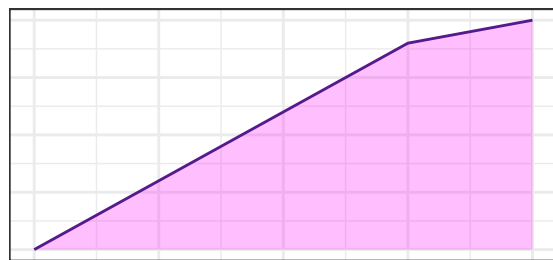
Simulated (n=10 m=1)



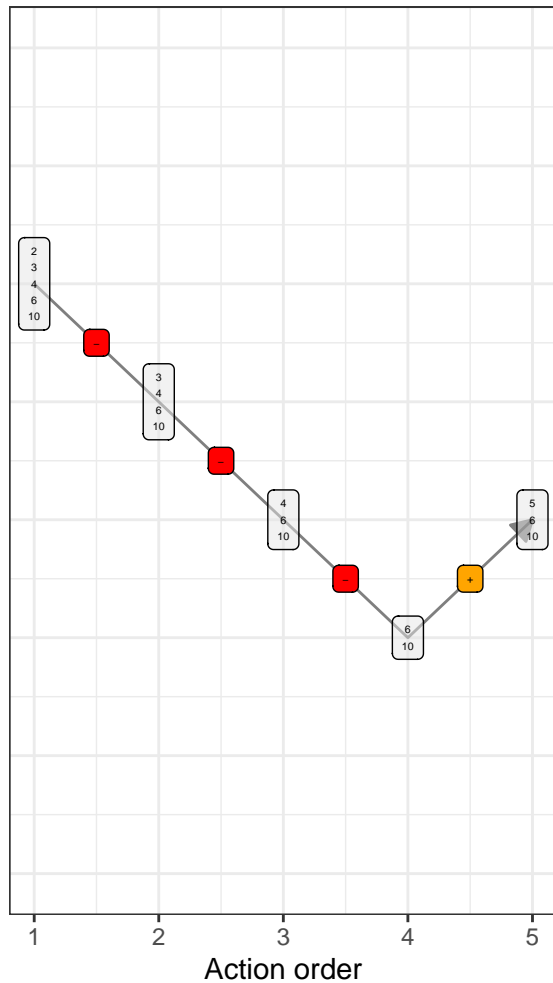
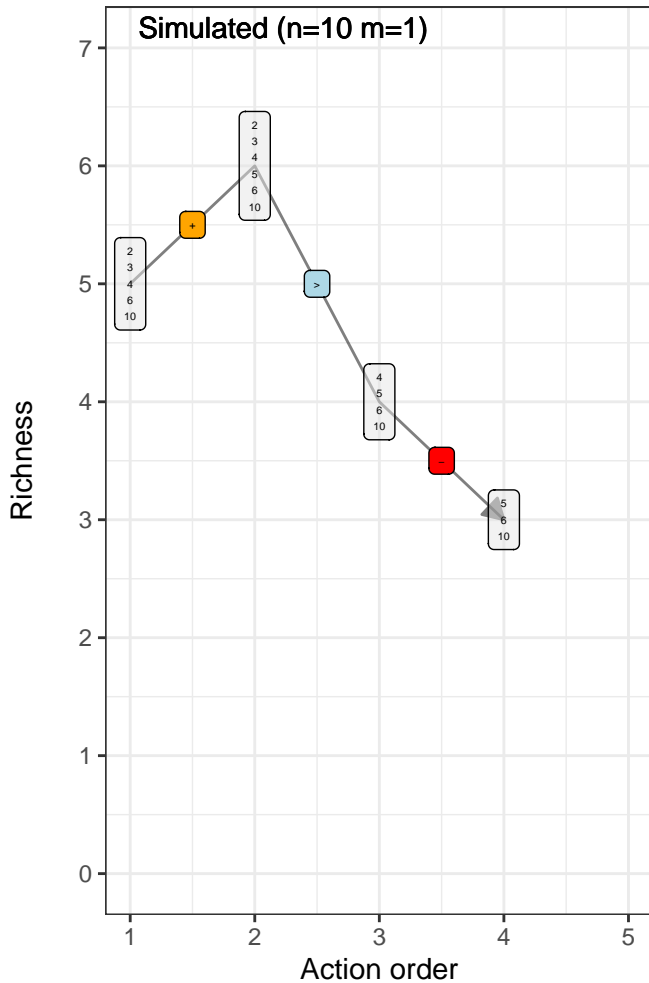
Optimal path



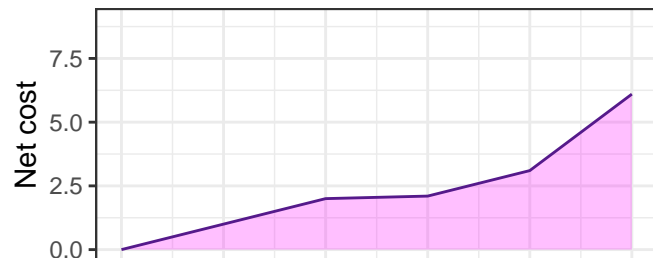
Nominal path



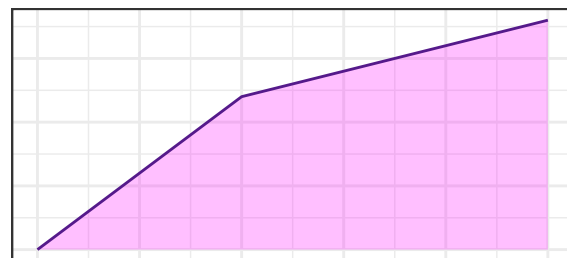
Simulated (n=10 m=1)



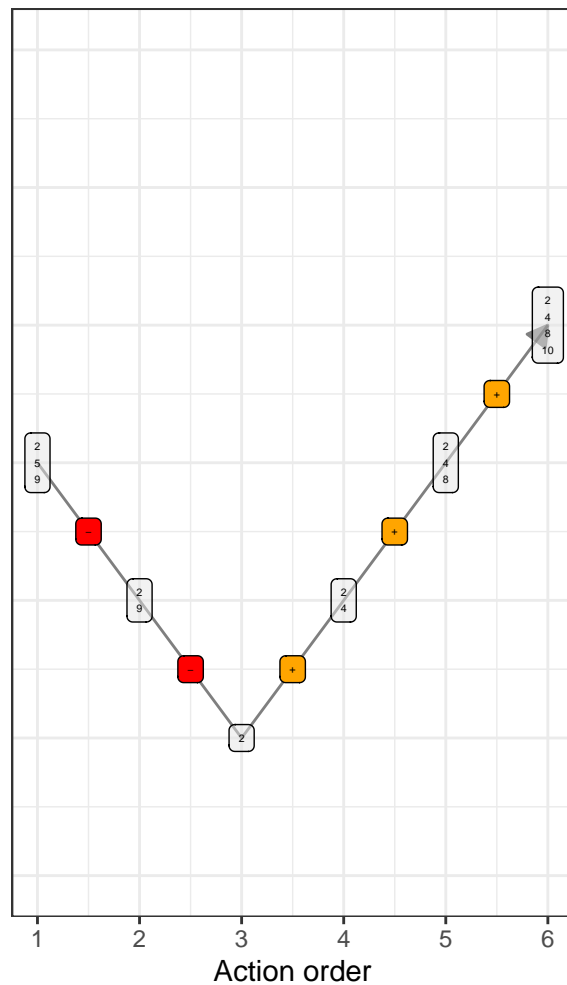
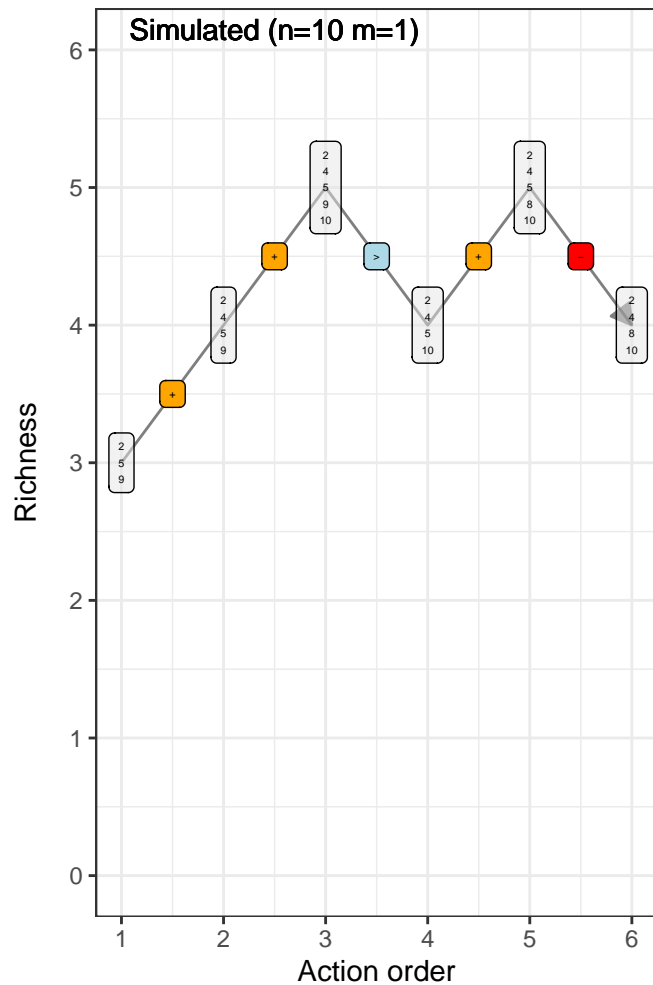
Optimal path



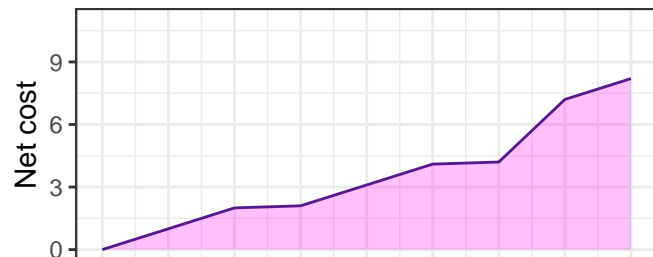
Nominal path



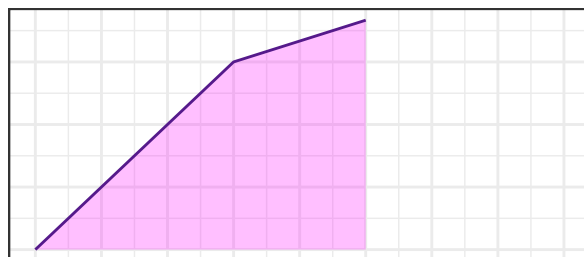
Simulated (n=10 m=1)



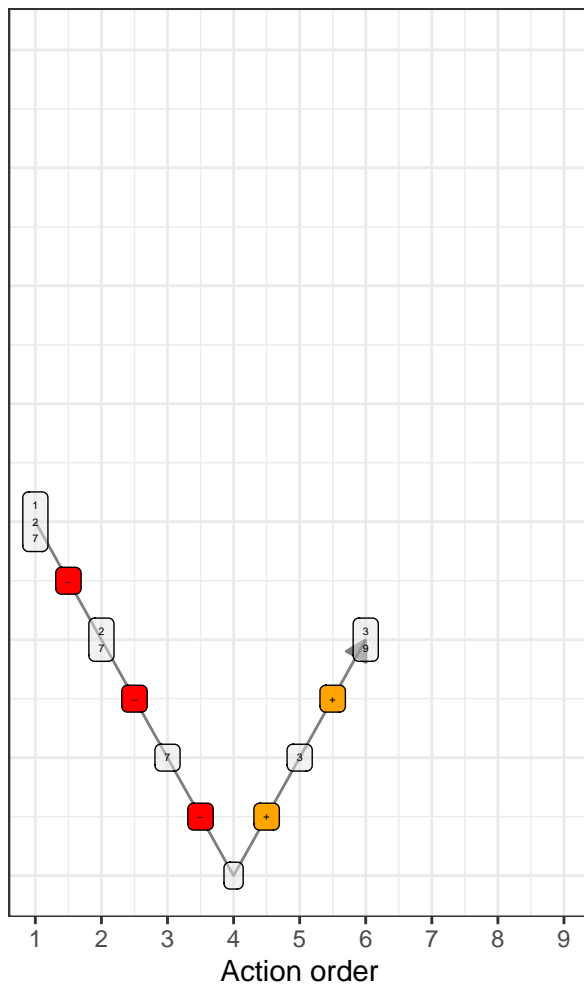
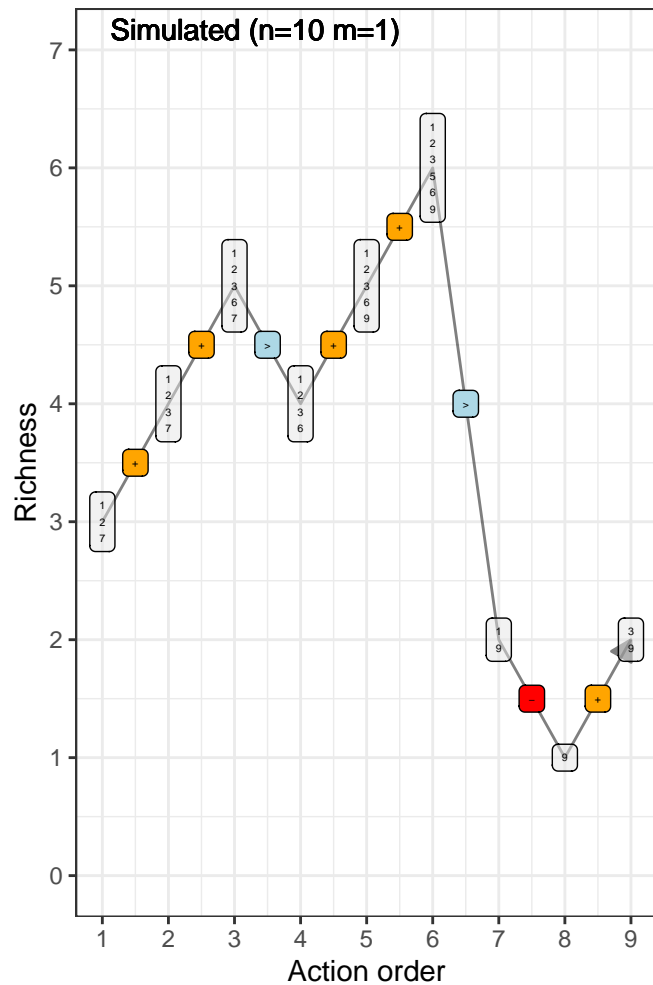
Optimal path



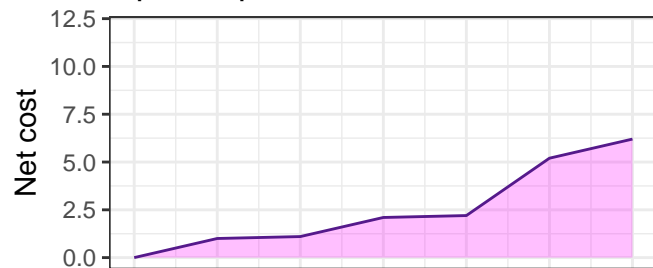
Nominal path



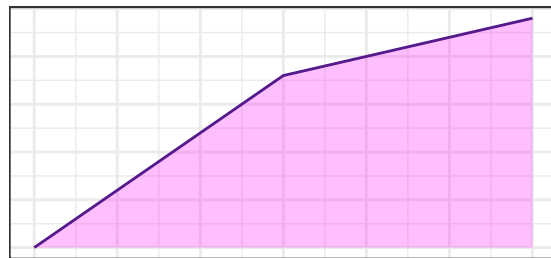
Simulated (n=10 m=1)



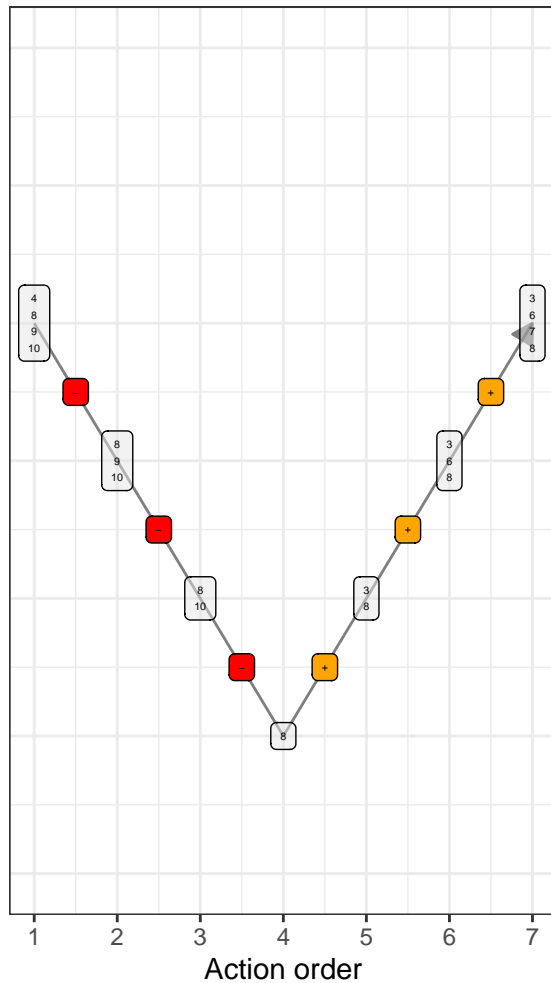
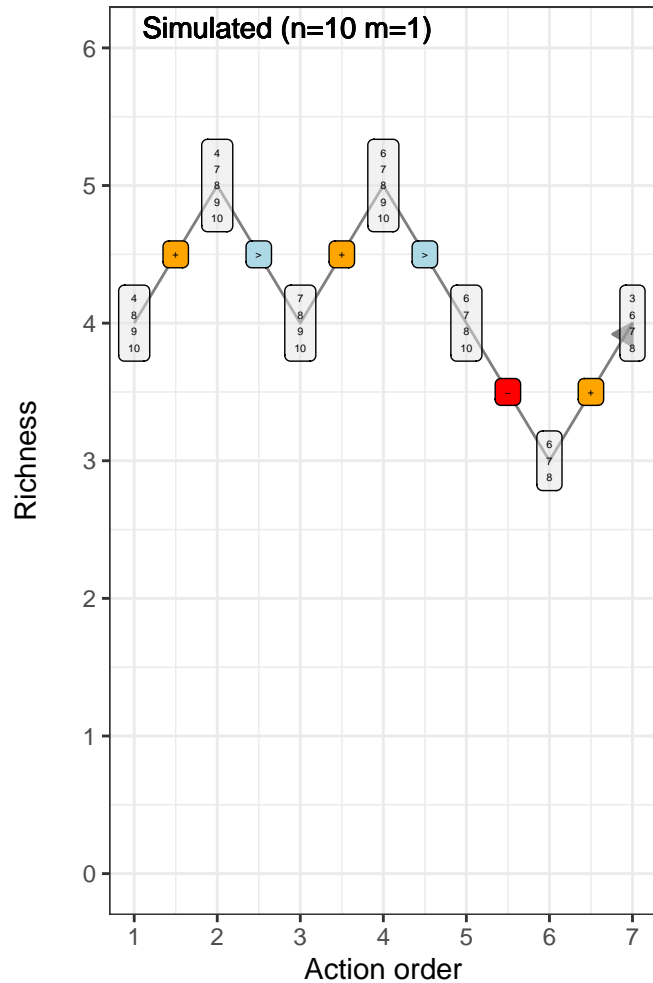
Optimal path



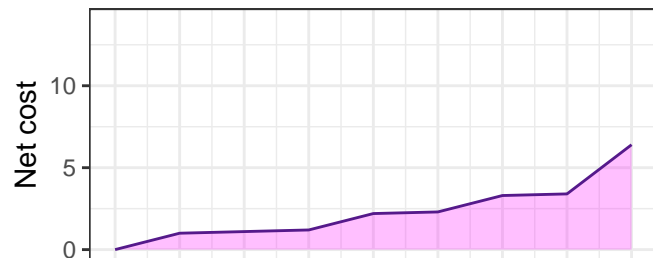
Nominal path



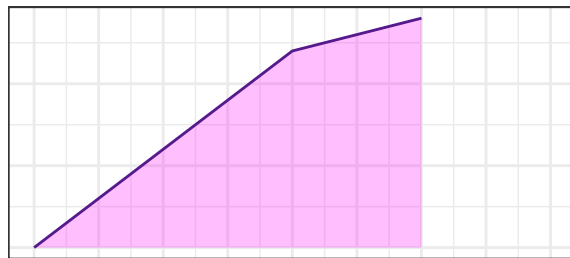
Simulated (n=10 m=1)



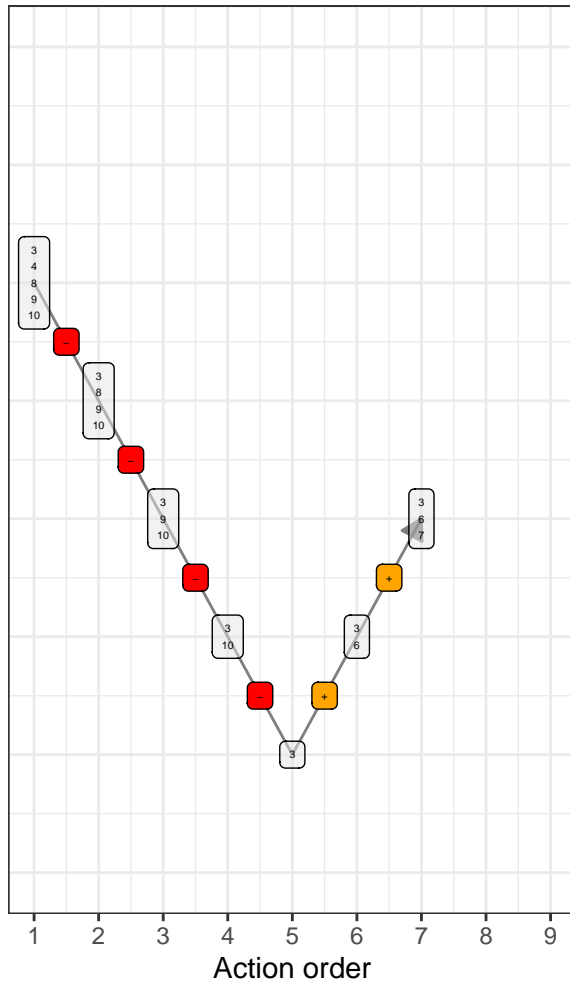
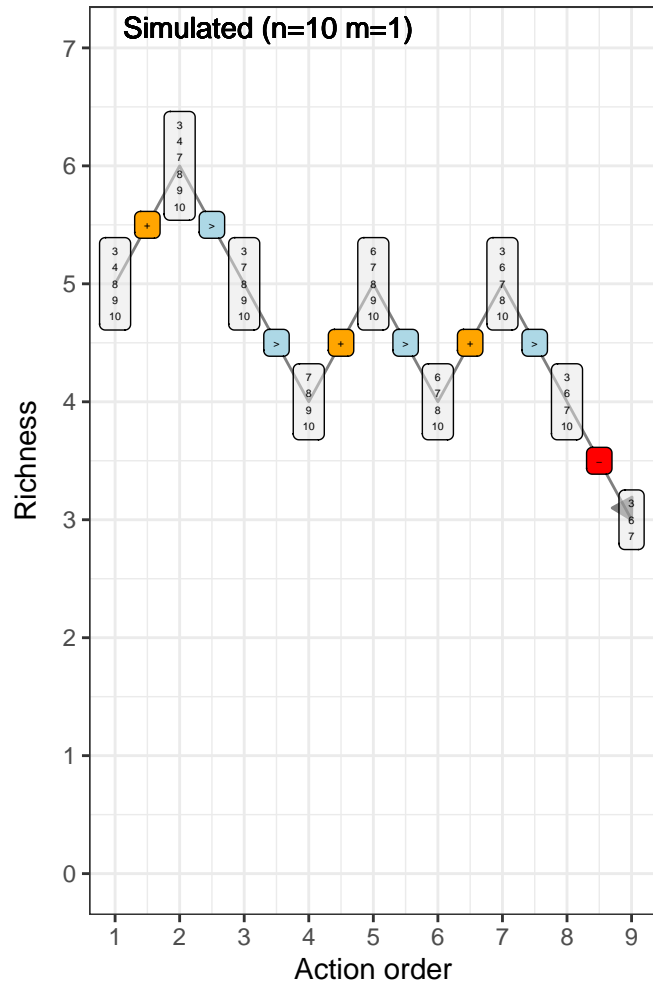
Optimal path



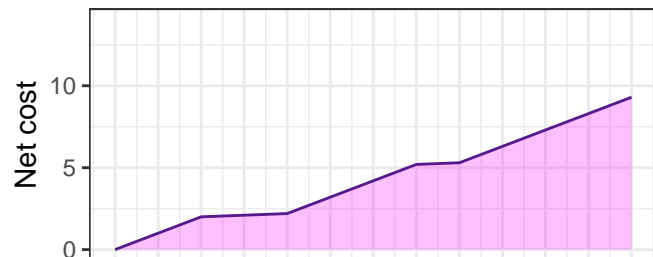
Nominal path



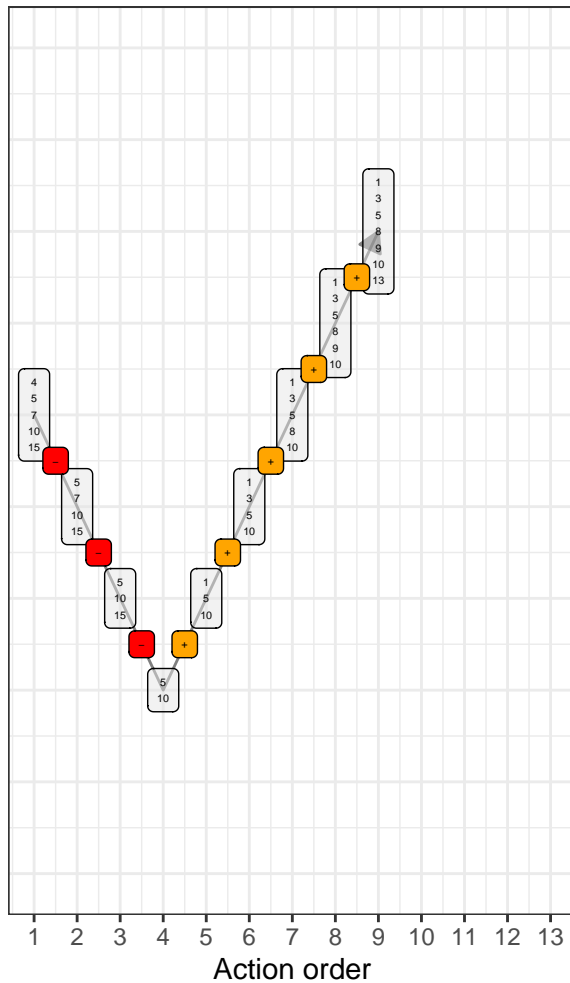
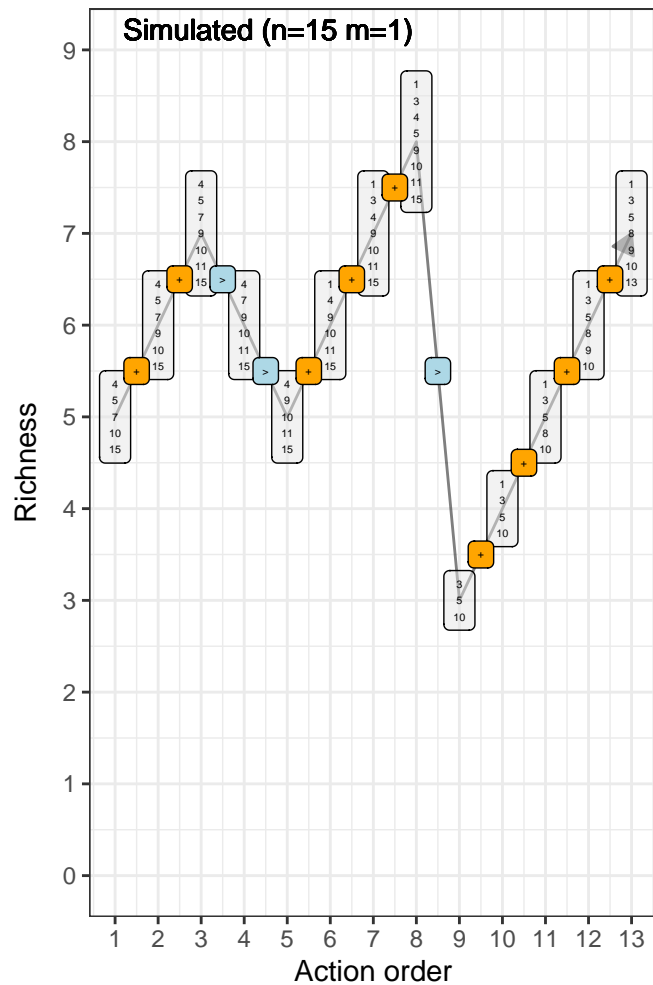
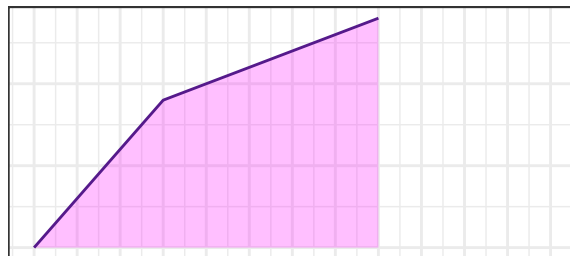
Simulated (n=10 m=1)



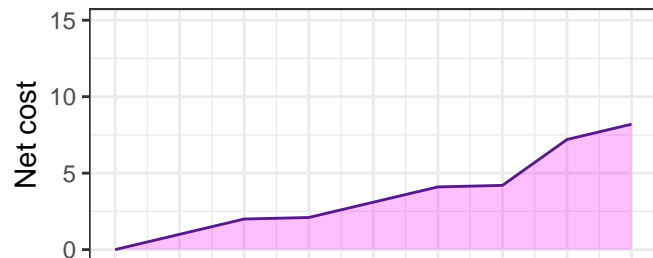
Optimal path



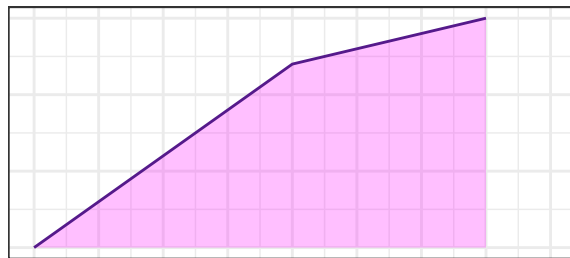
Nominal path



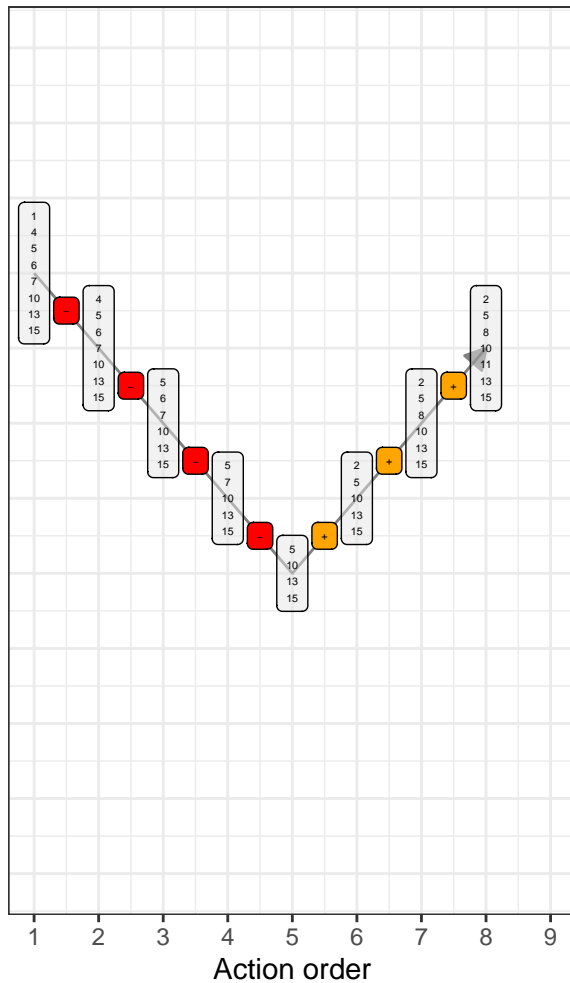
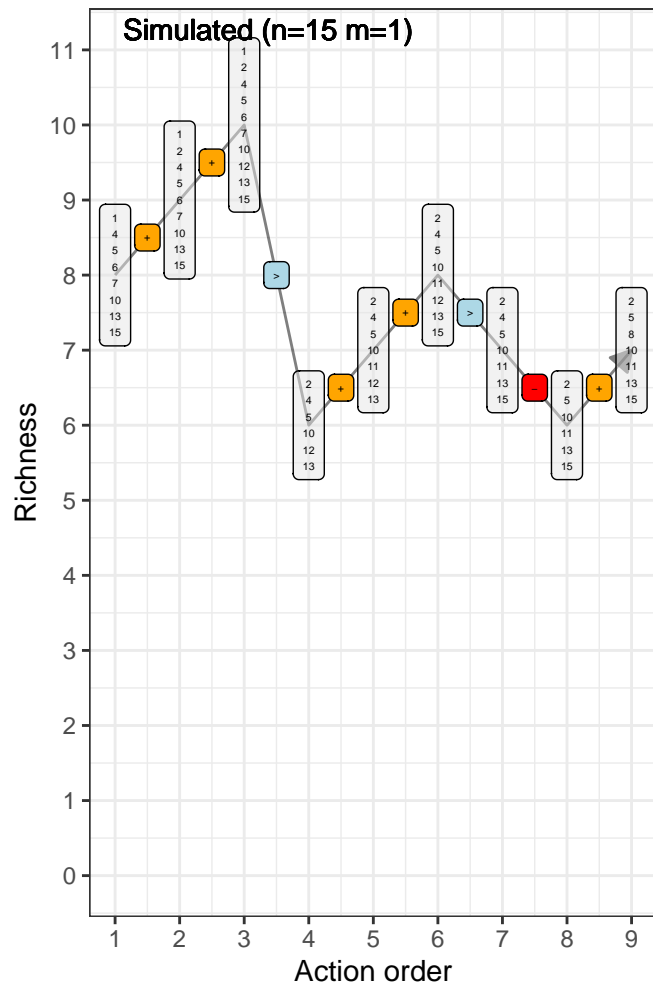
Optimal path



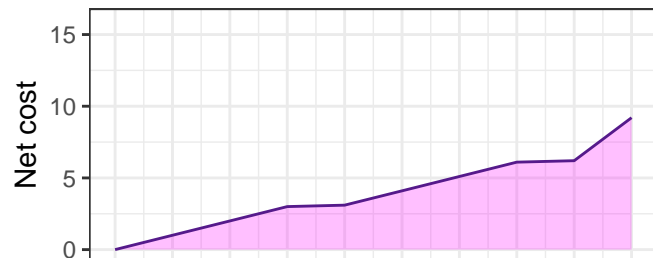
Nominal path



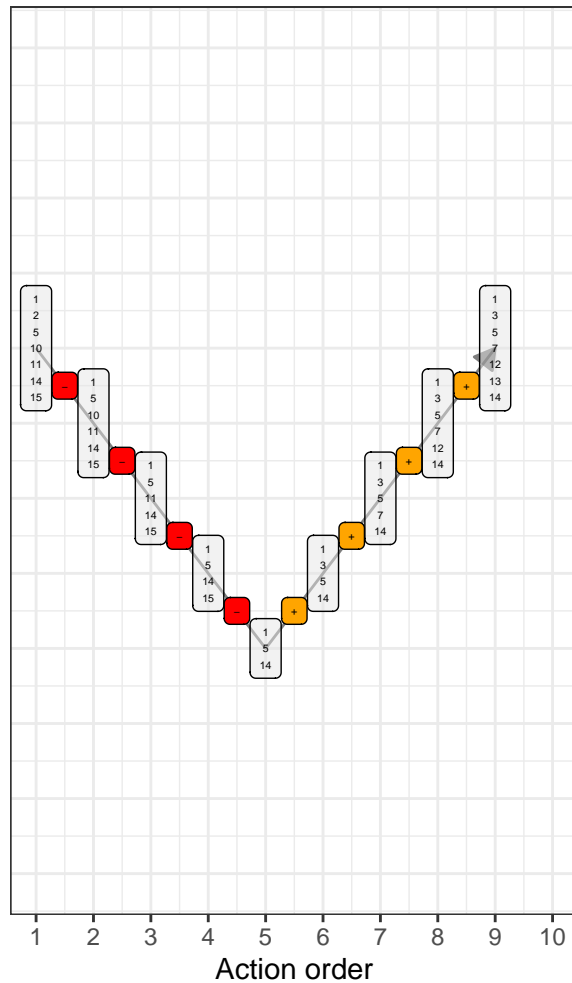
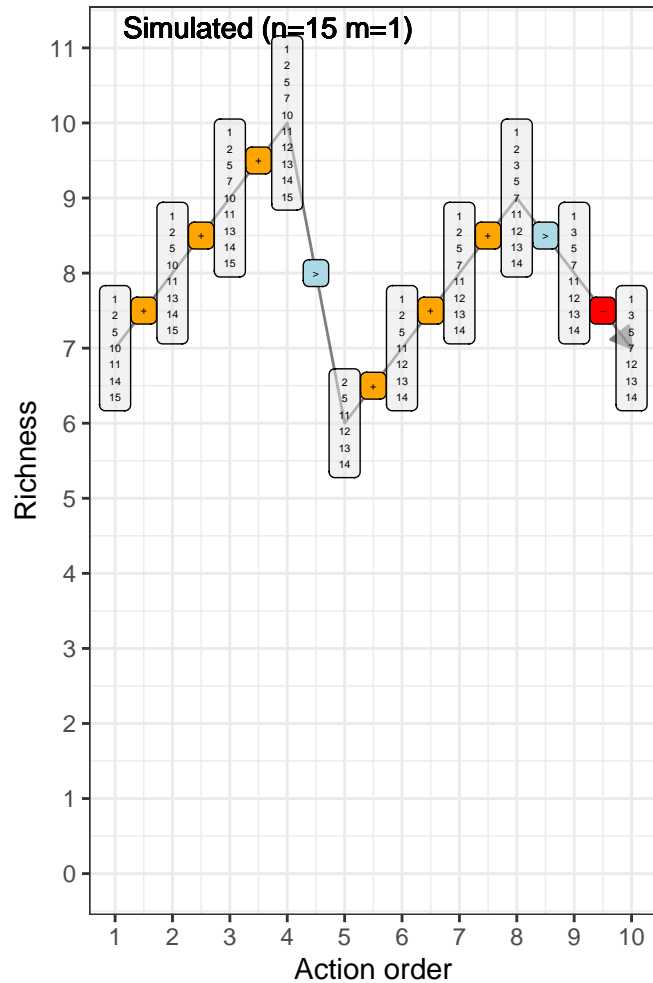
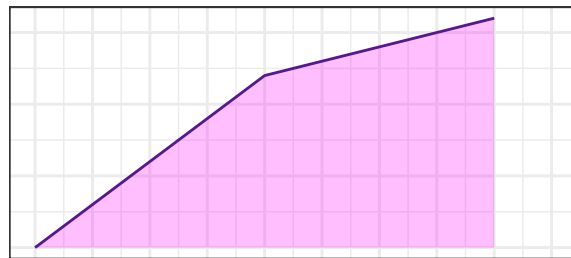
Simulated (n=15 m=1)



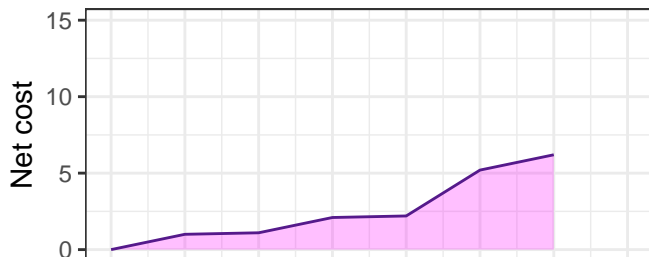
Optimal path



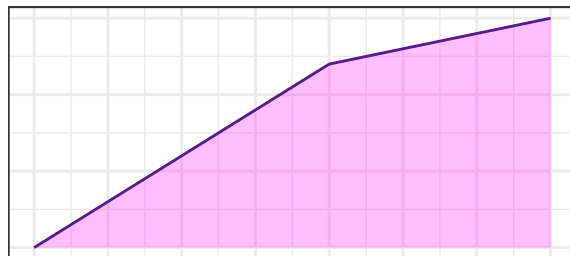
Nominal path



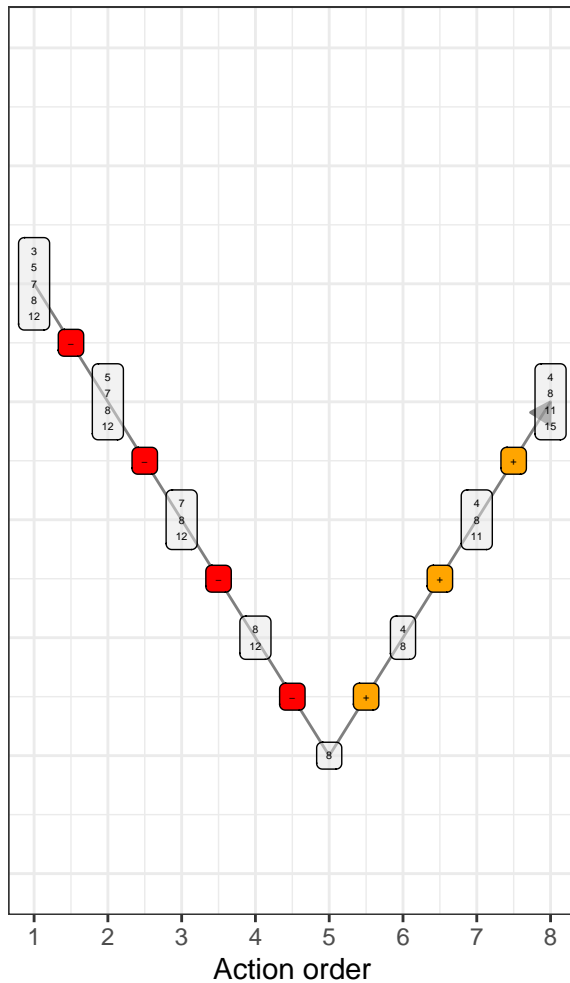
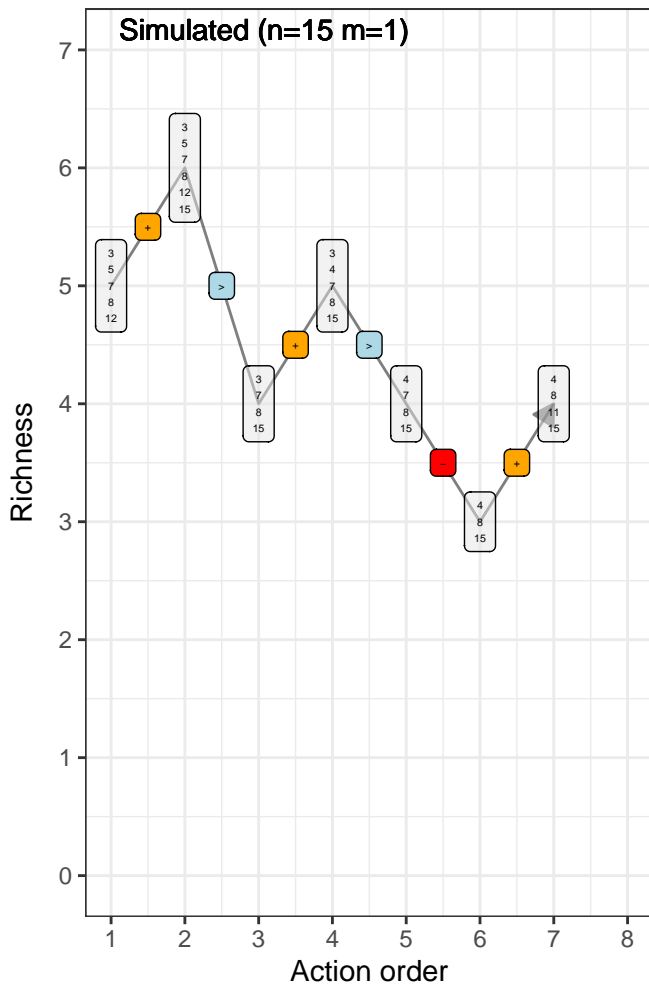
Optimal path



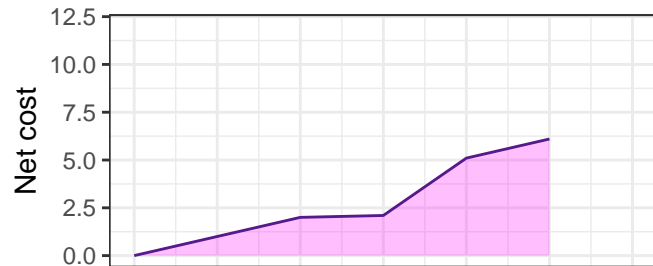
Nominal path



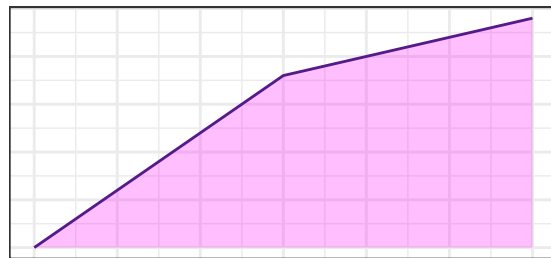
Simulated (n=15 m=1)



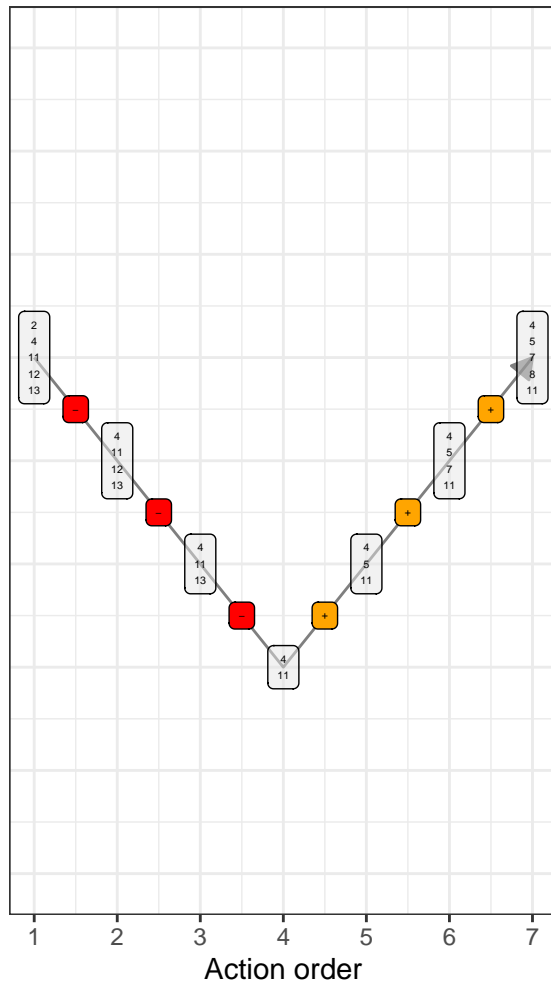
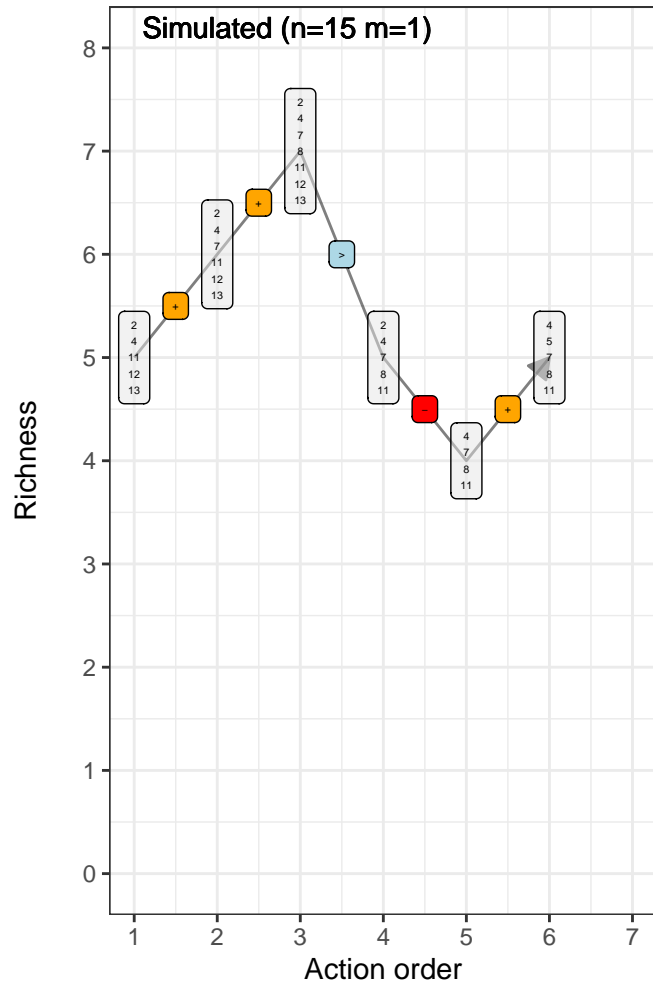
Optimal path



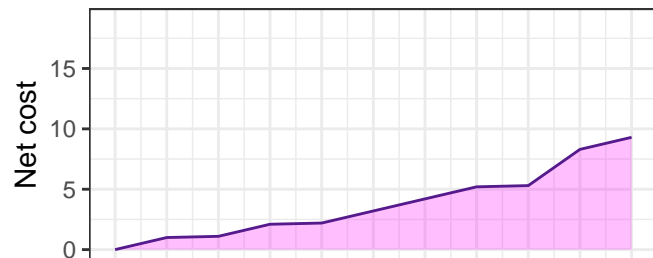
Nominal path



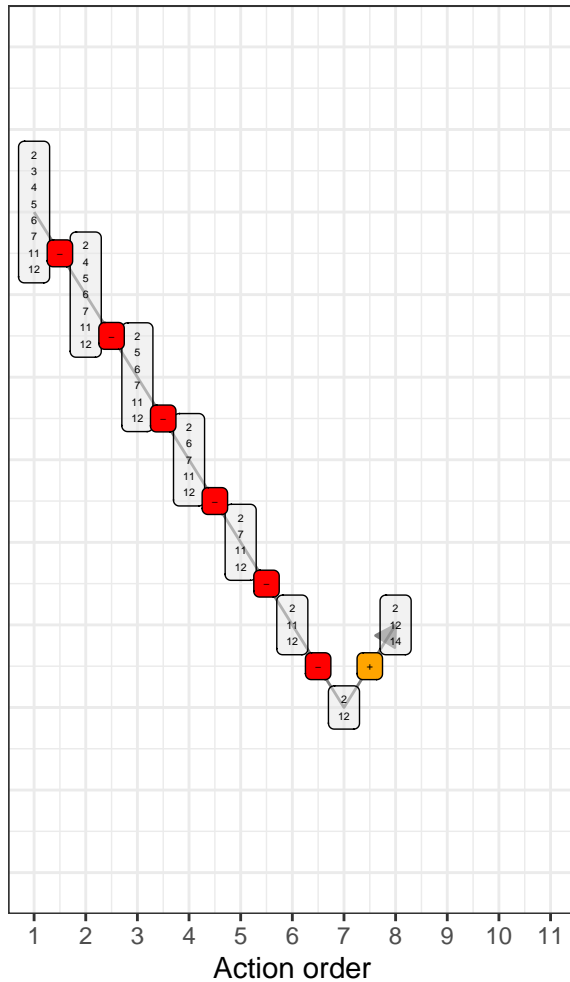
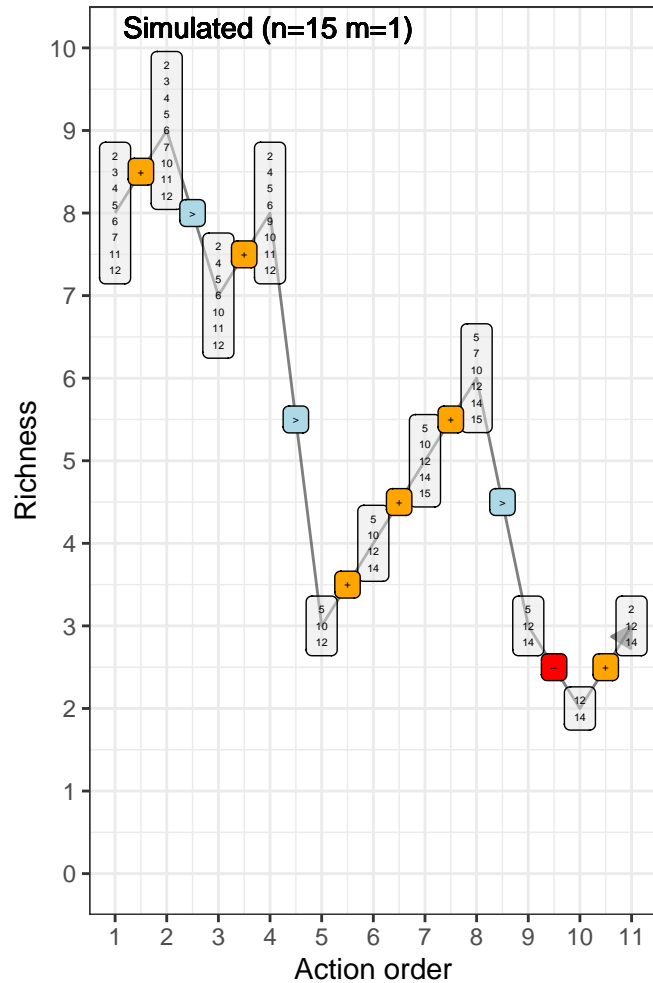
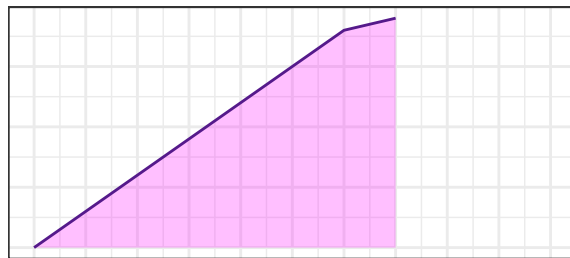
Simulated (n=15 m=1)



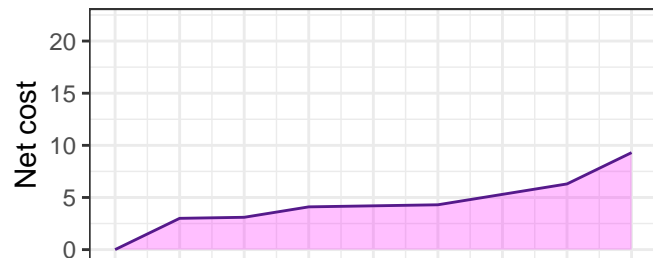
Optimal path



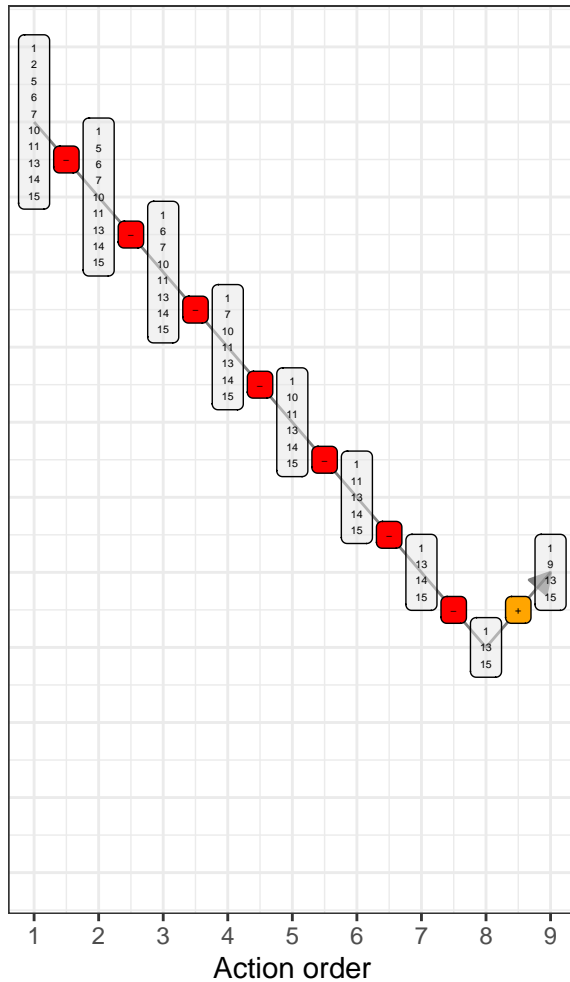
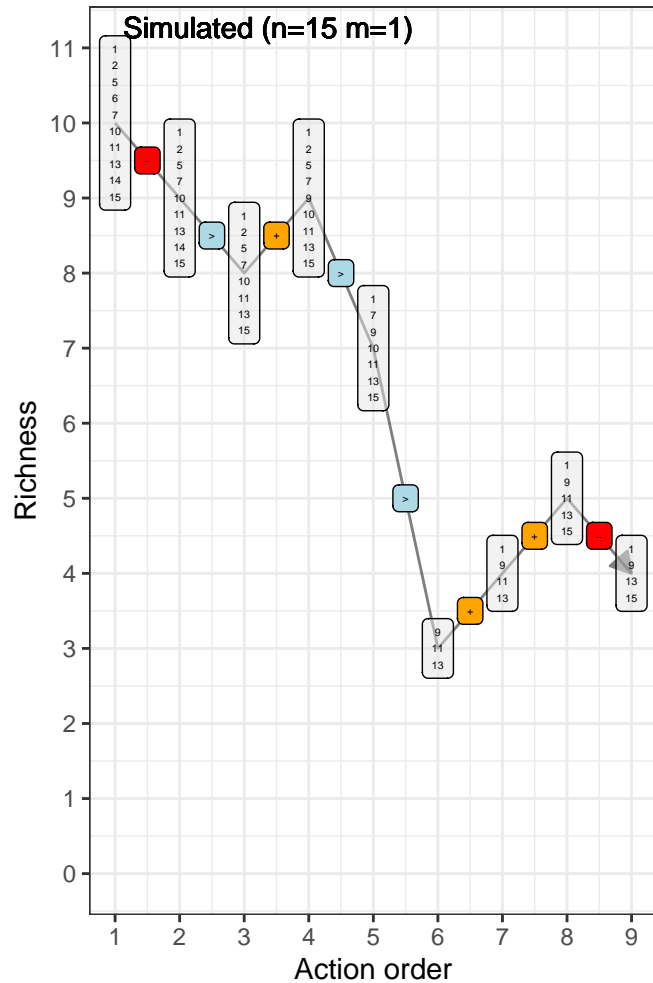
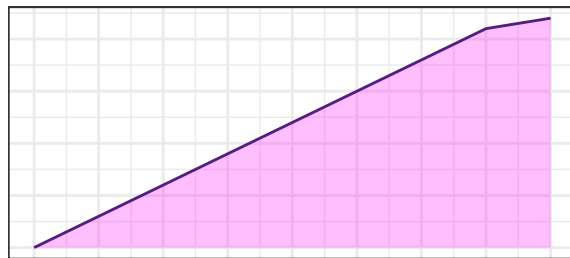
Nominal path



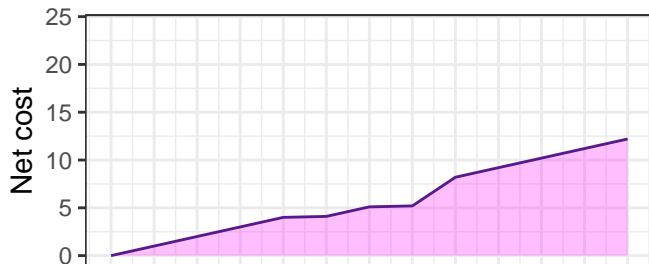
Optimal path



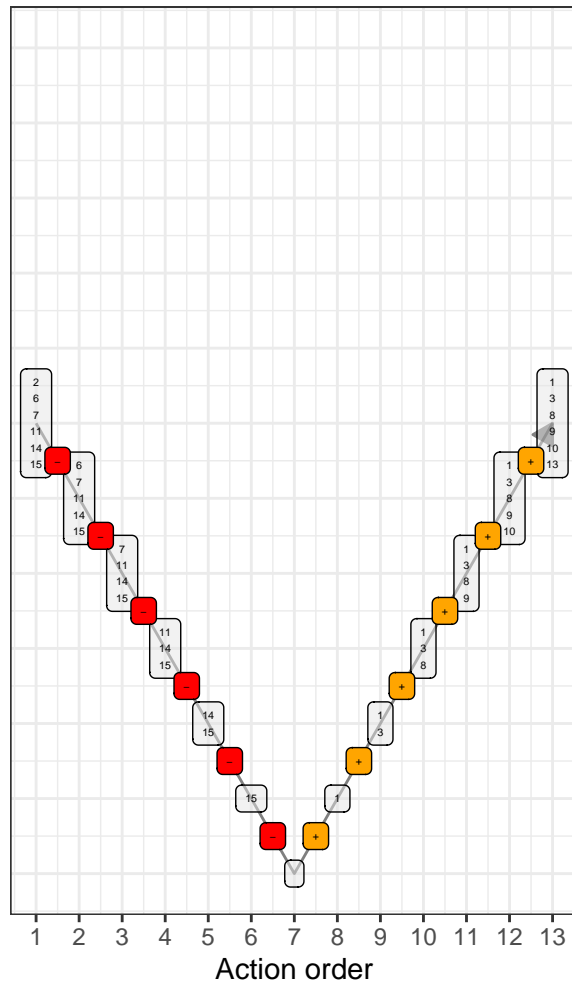
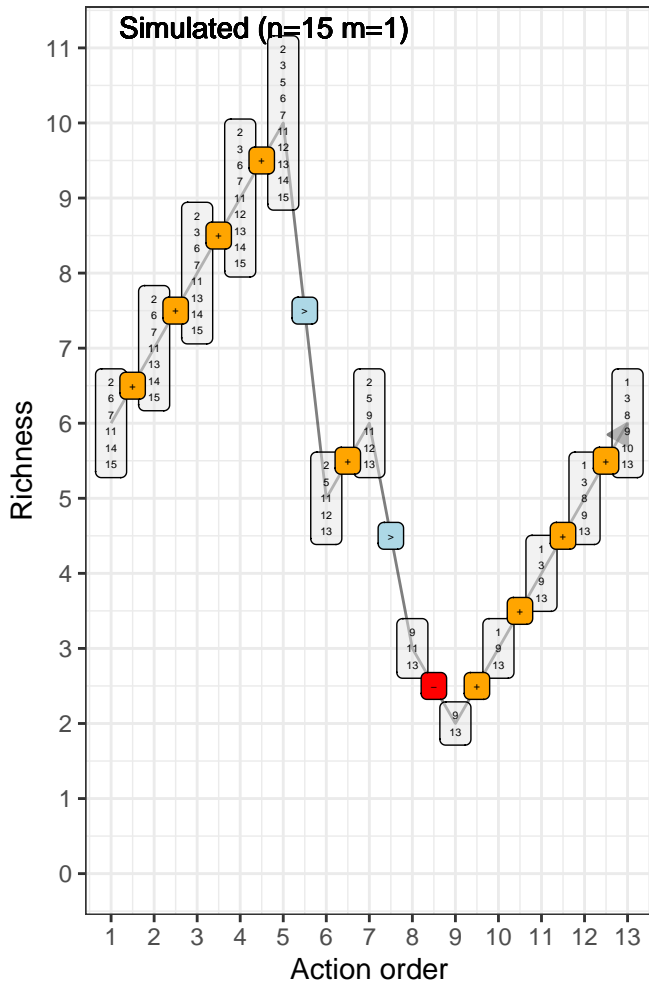
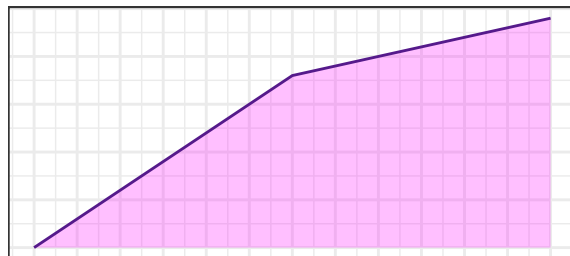
Nominal path



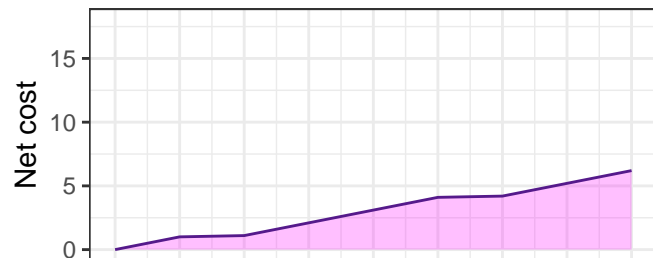
Optimal path



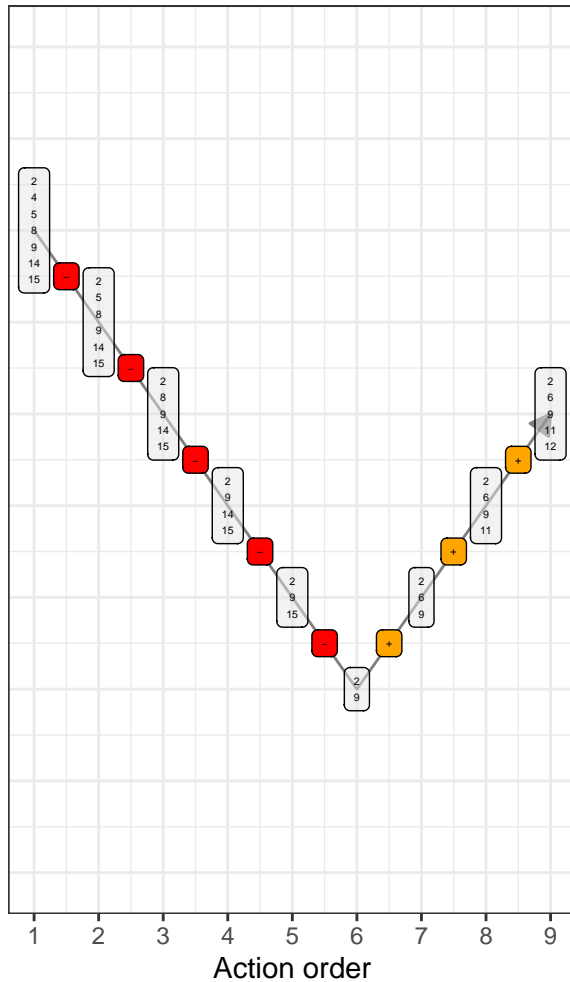
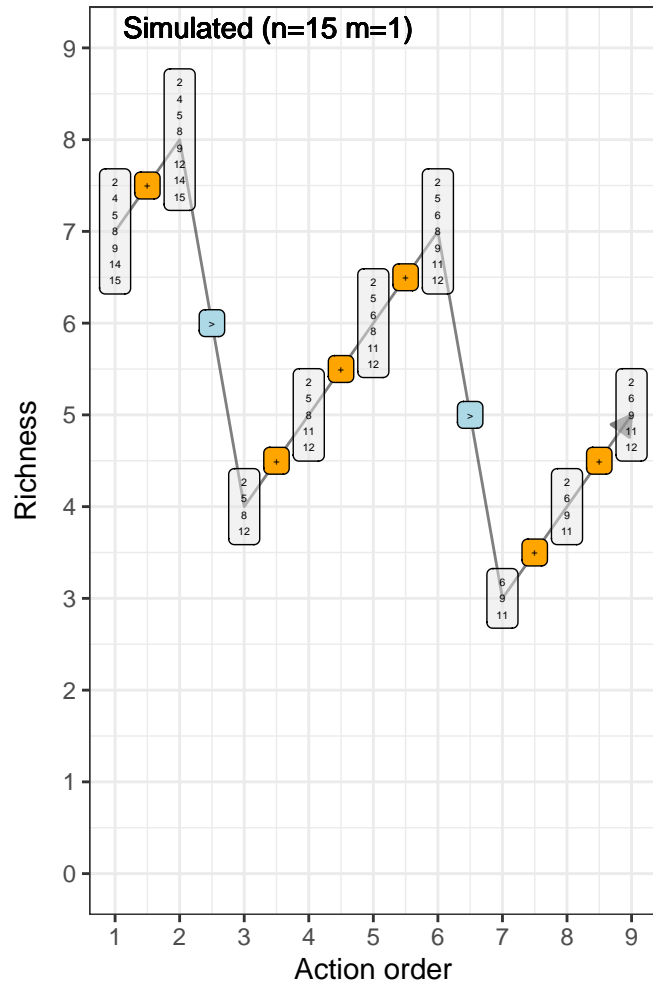
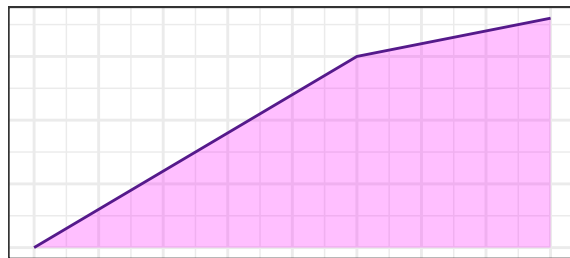
Nominal path



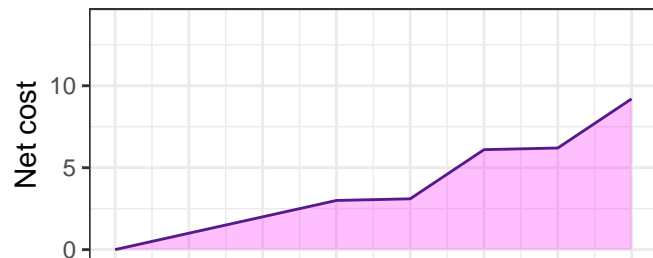
Optimal path



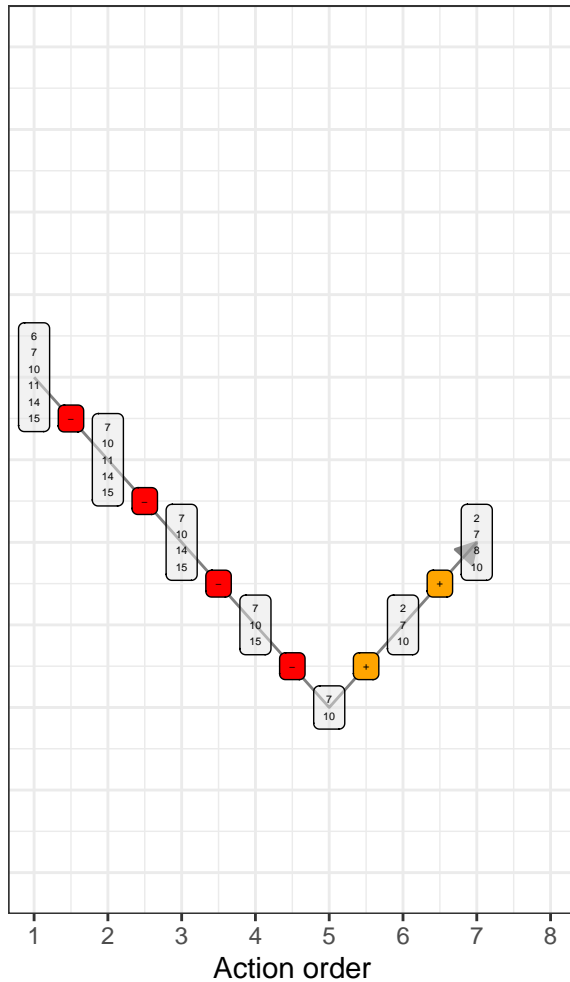
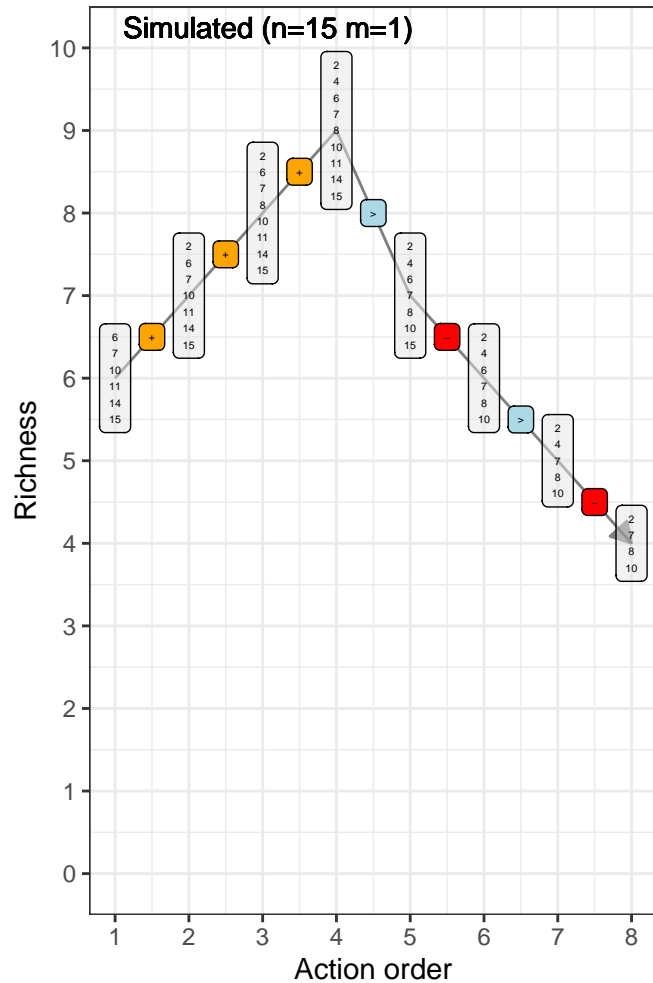
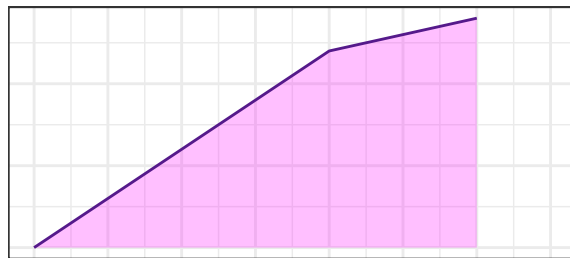
Nominal path



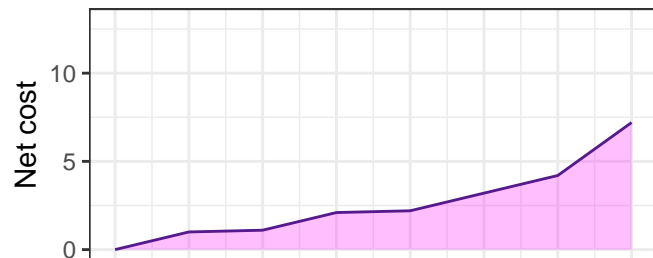
Optimal path



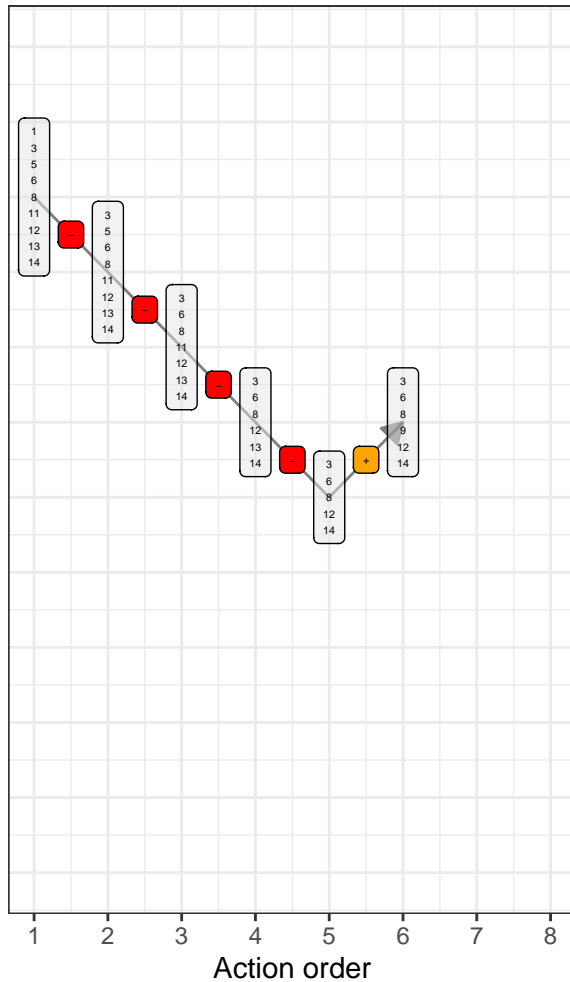
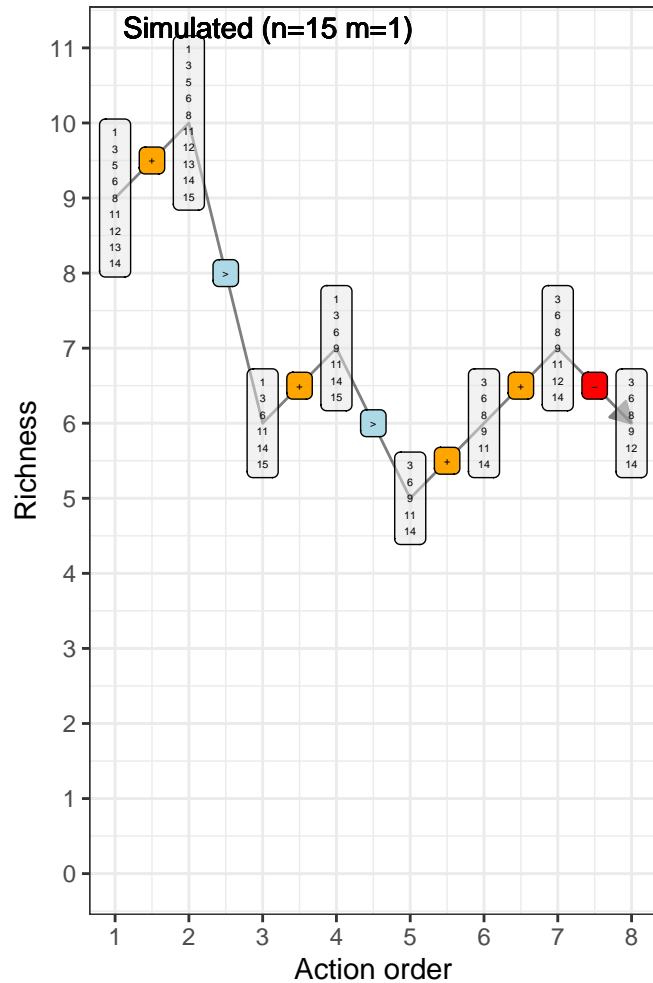
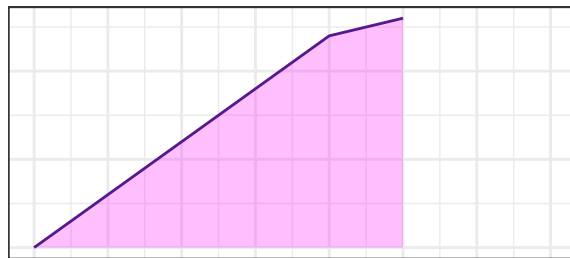
Nominal path



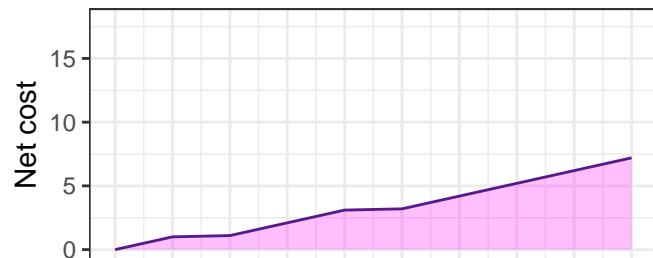
Optimal path



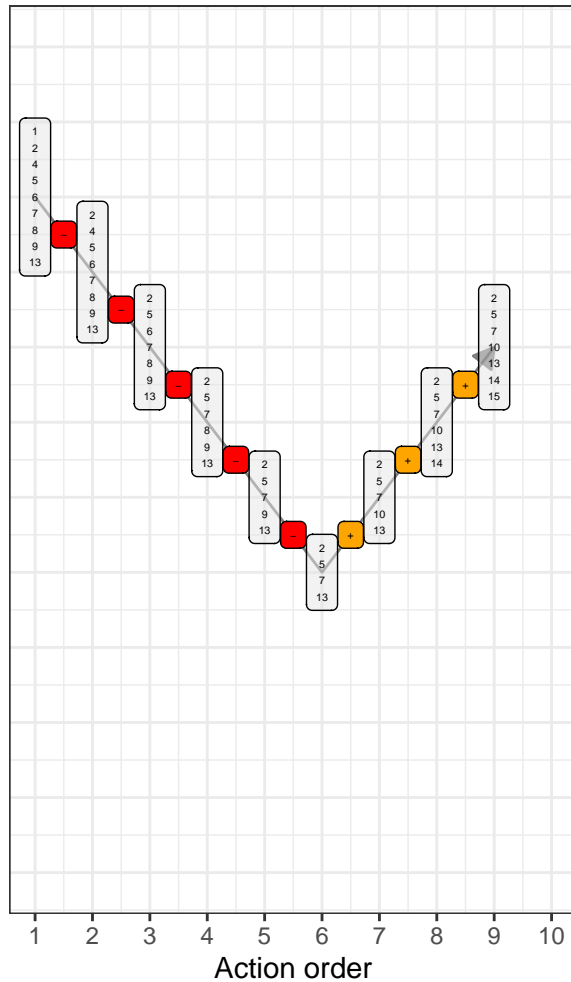
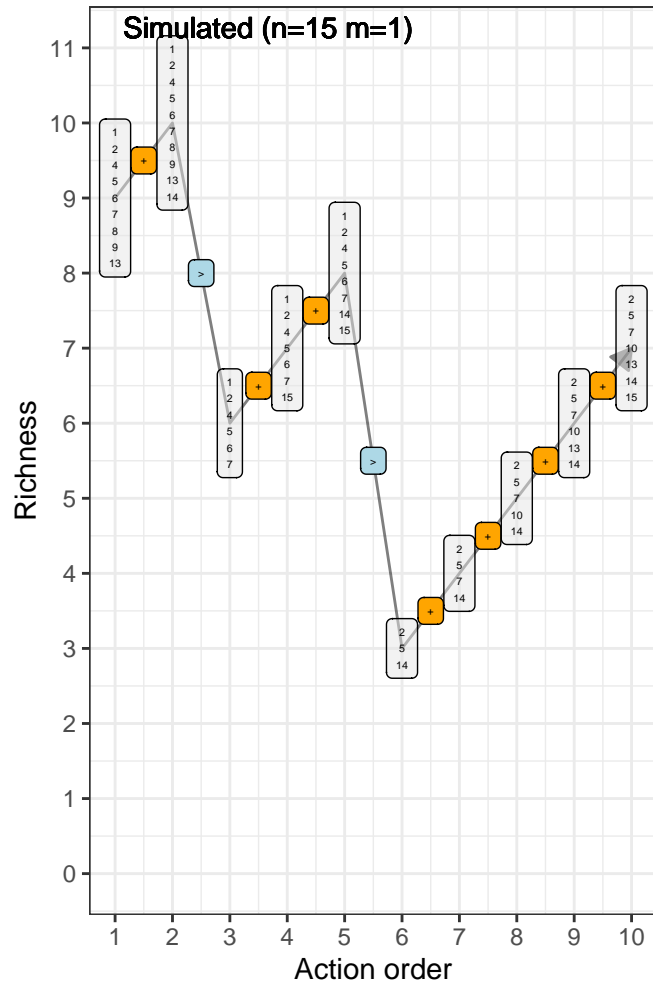
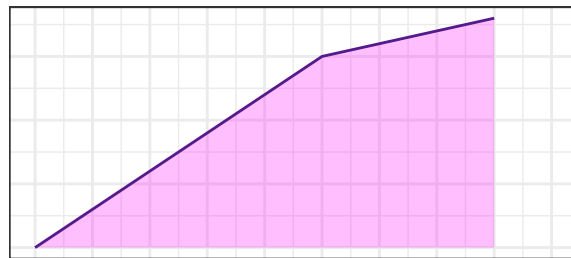
Nominal path



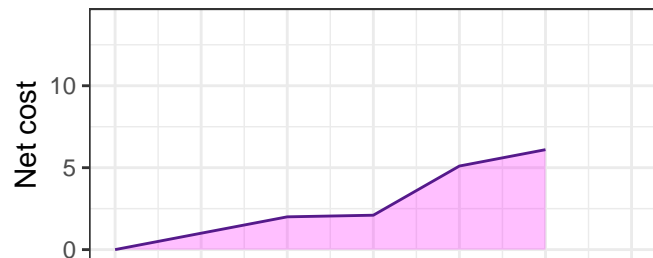
Optimal path



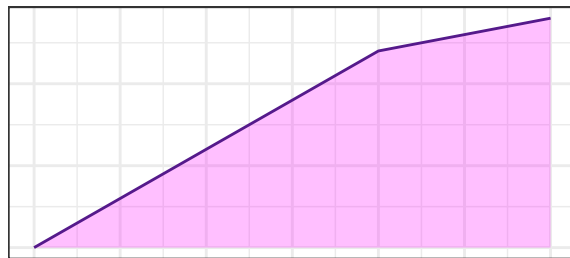
Nominal path



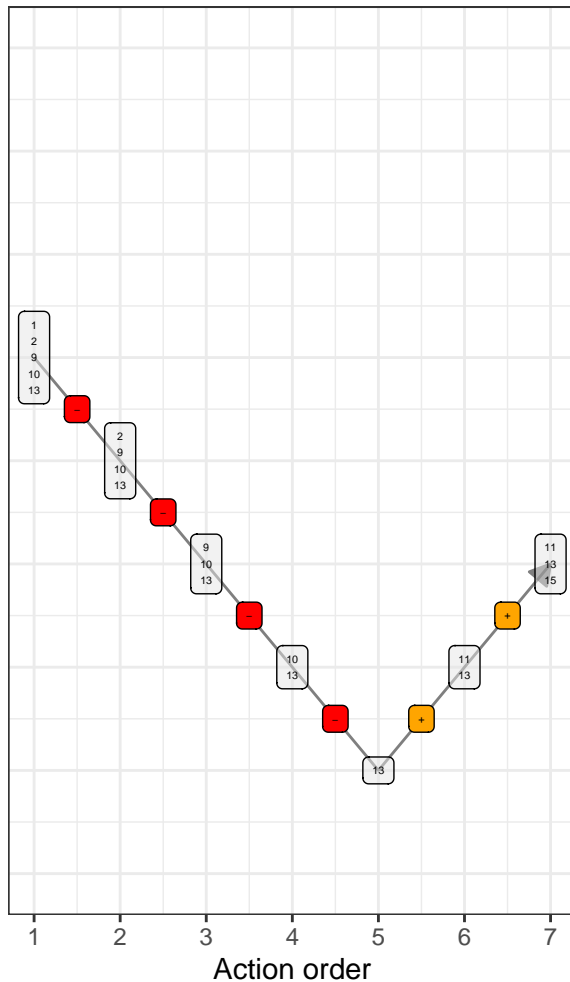
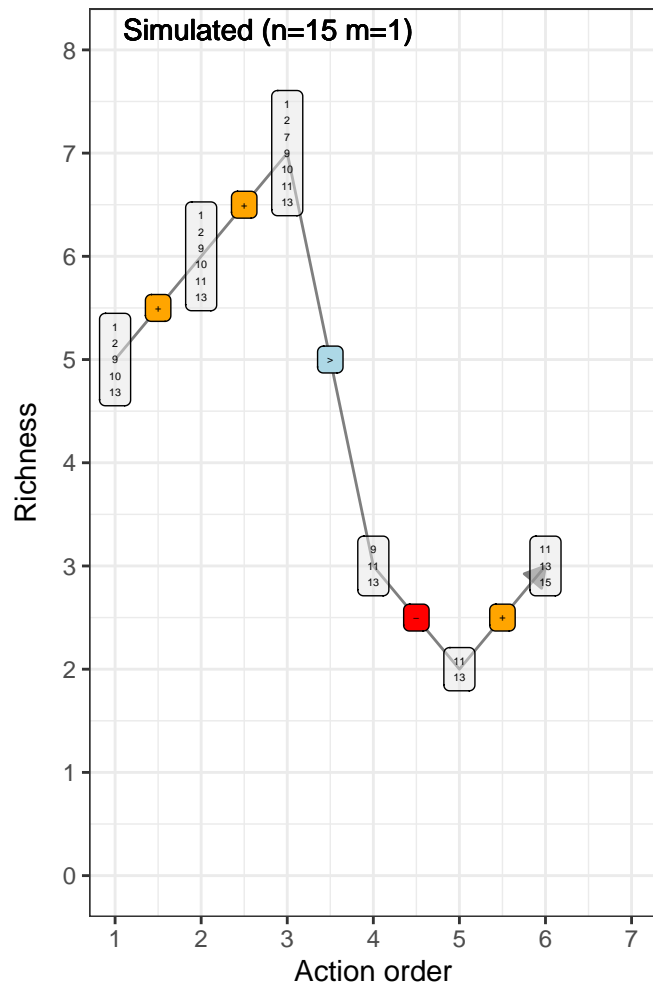
Optimal path



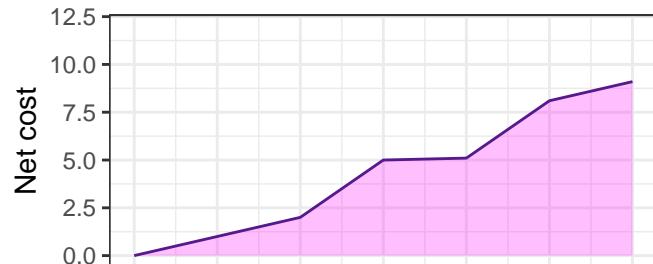
Nominal path



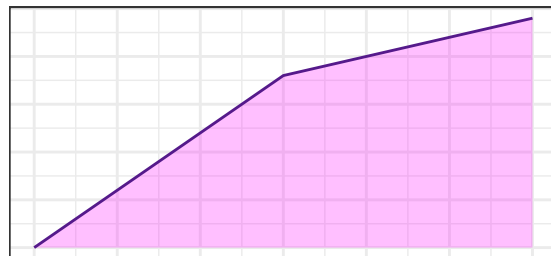
Simulated (n=15 m=1)



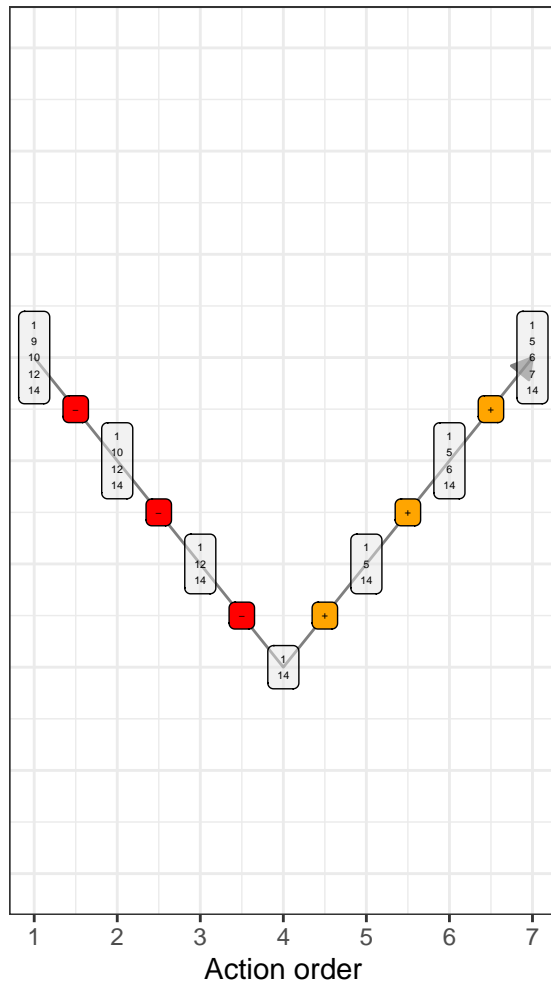
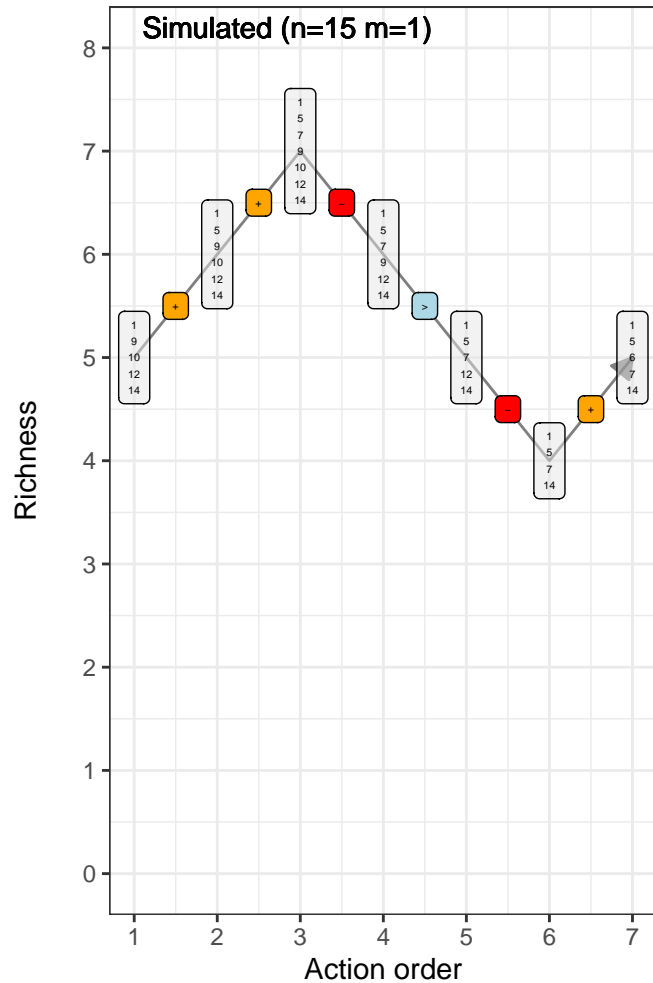
Optimal path



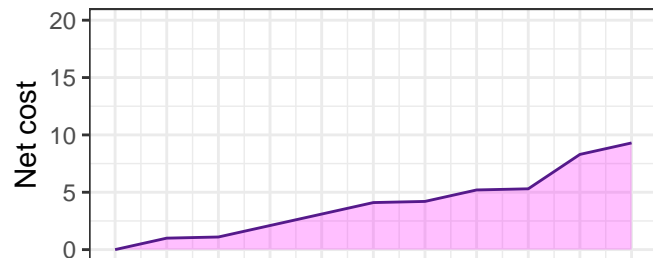
Nominal path



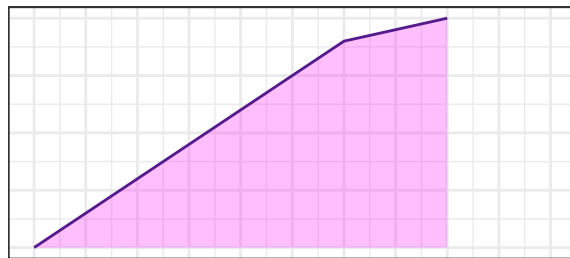
Simulated (n=15 m=1)



Optimal path



Nominal path



Simulated (n=15 m=1)

