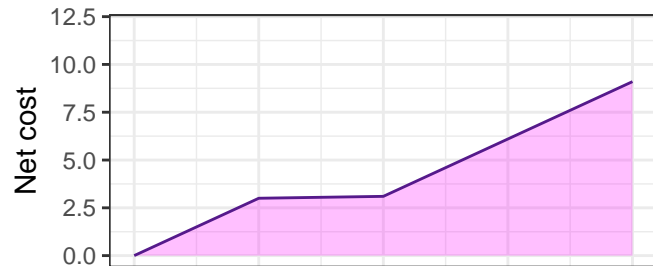
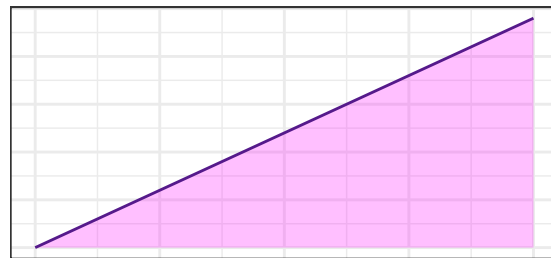


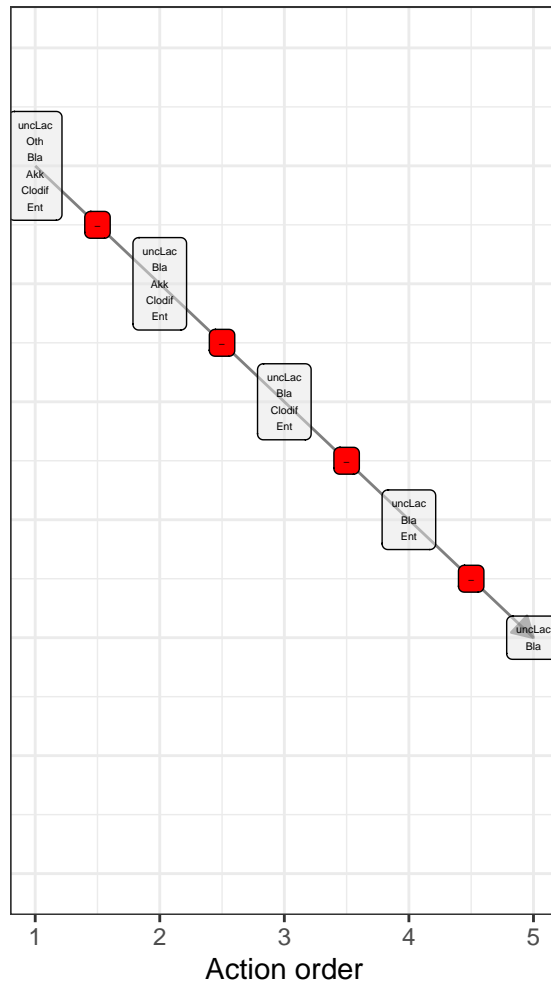
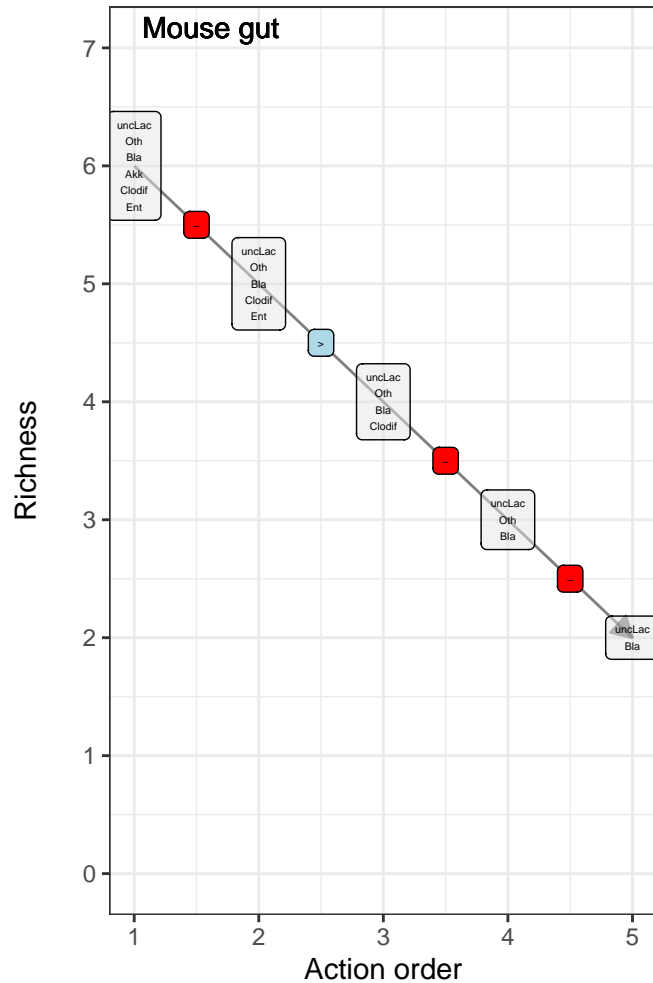
Optimal path



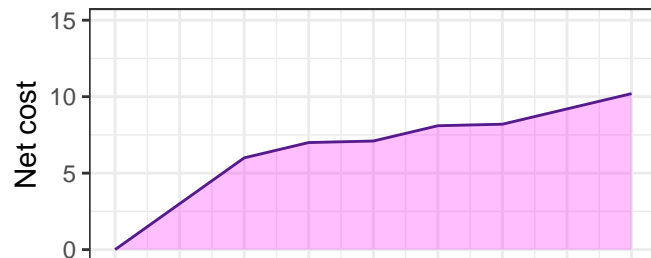
Nominal path



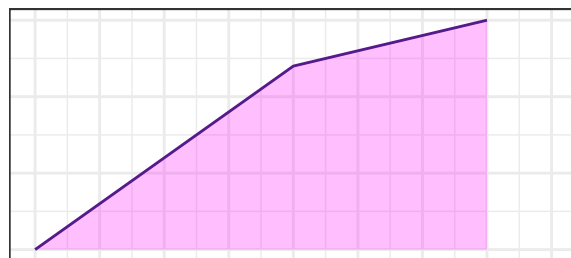
Mouse gut



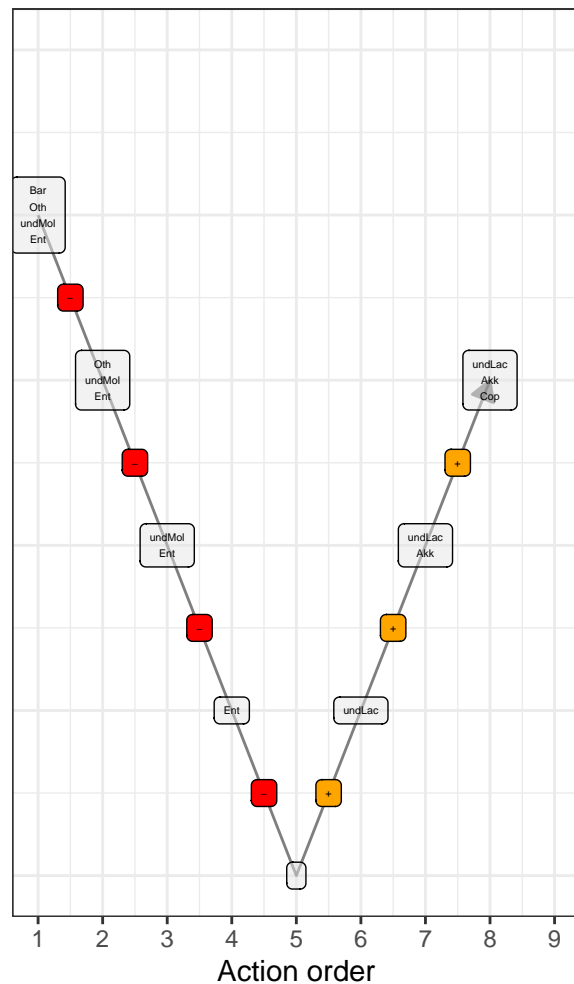
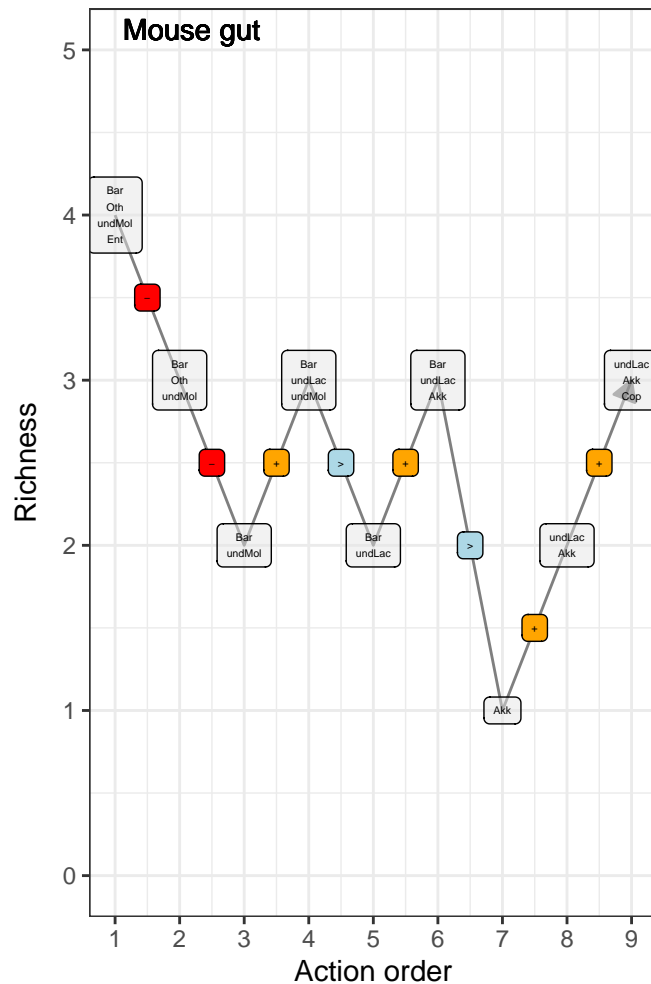
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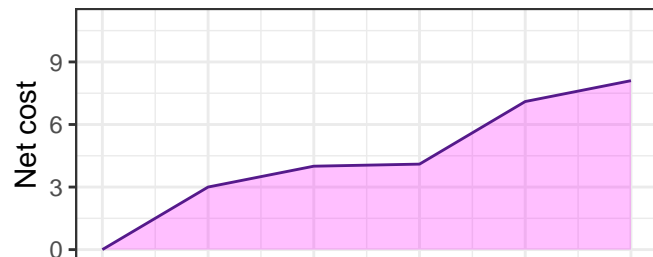
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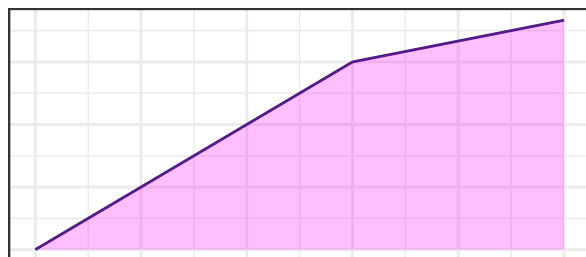
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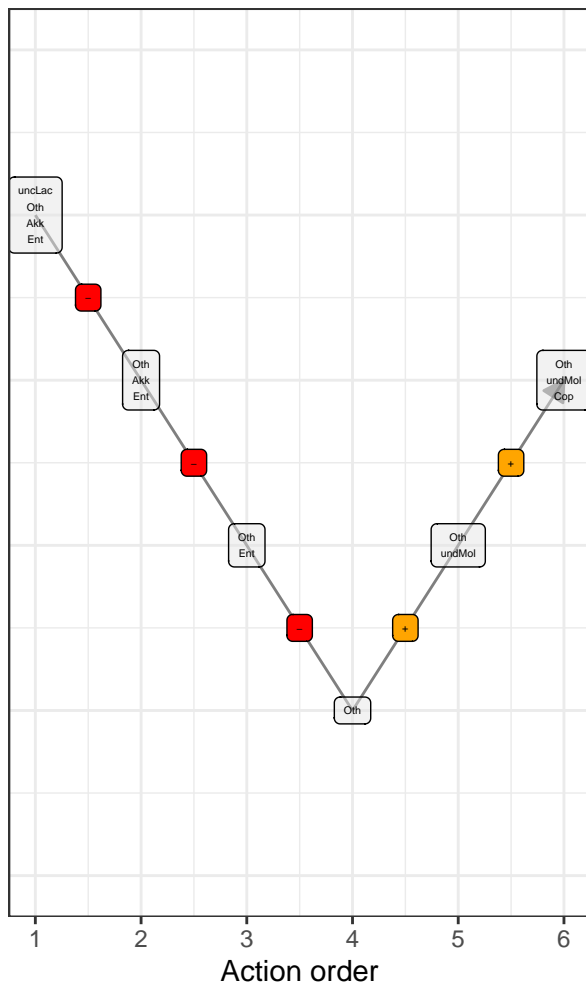
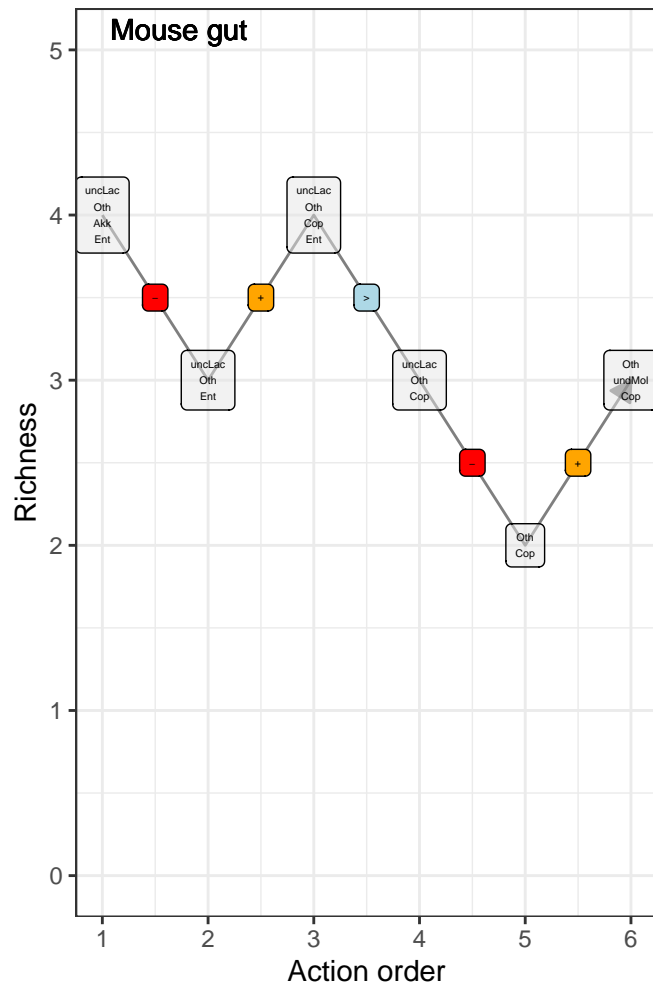
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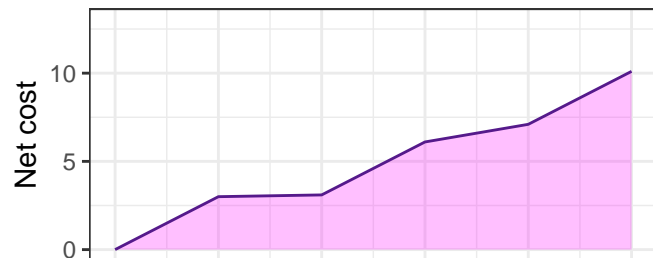
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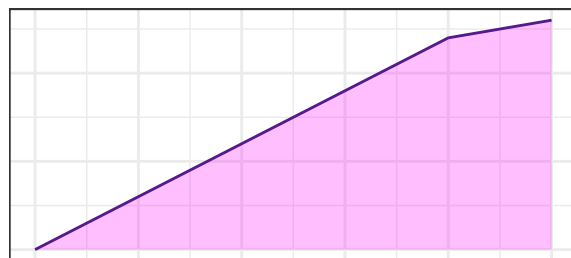
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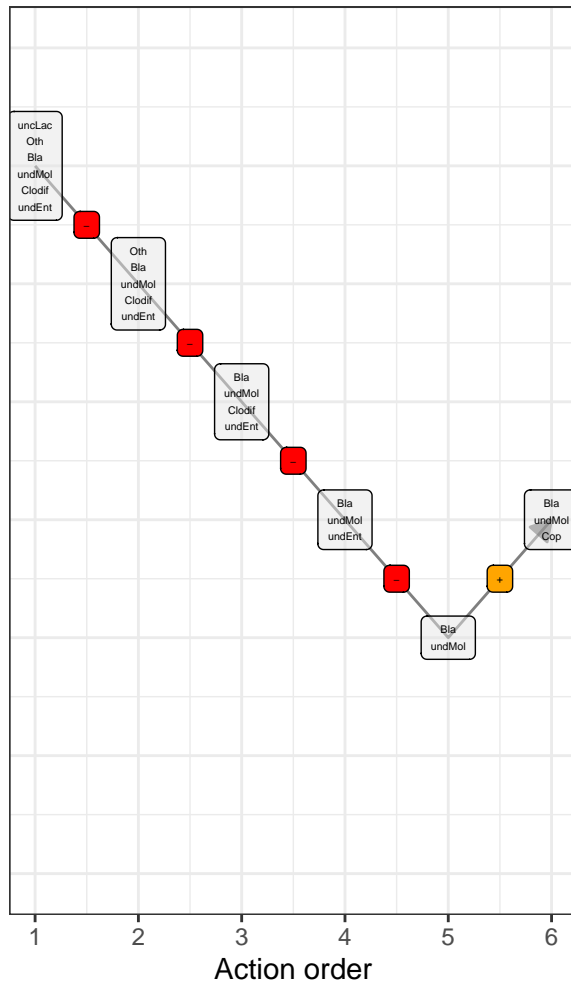
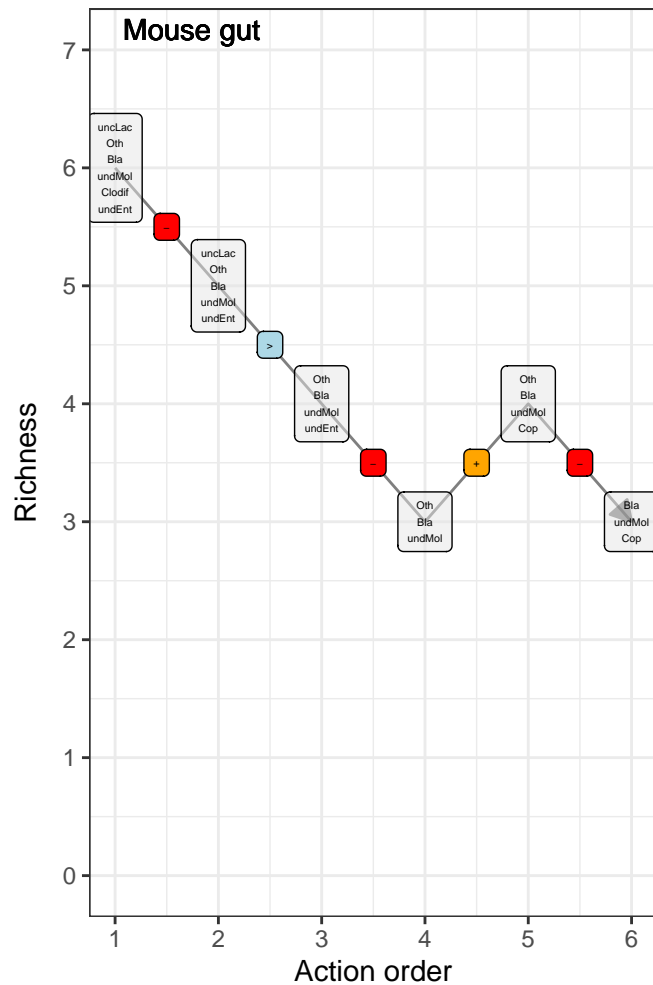
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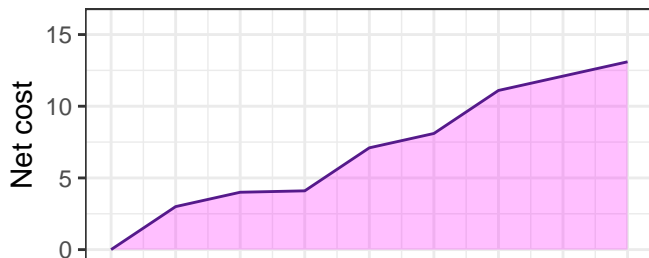
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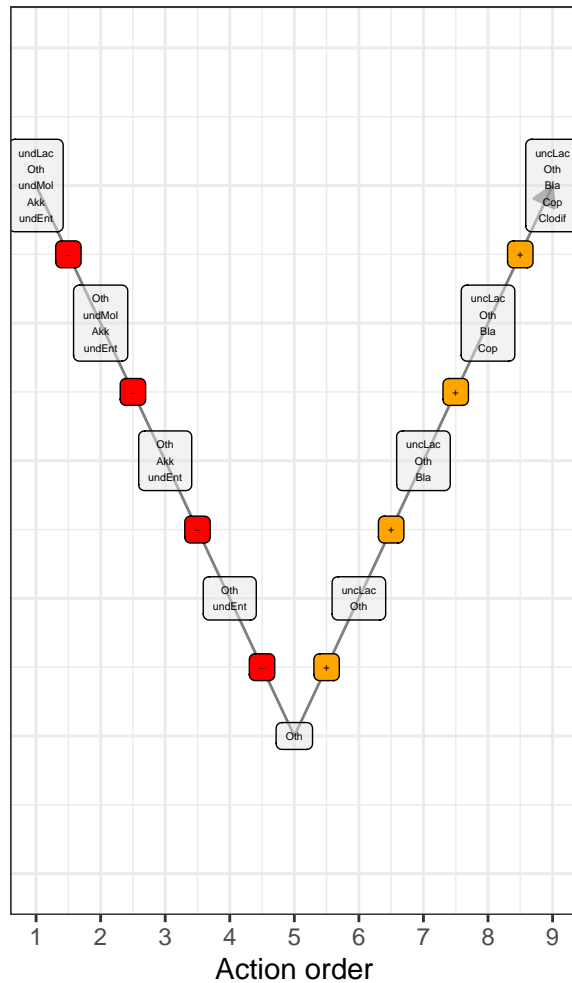
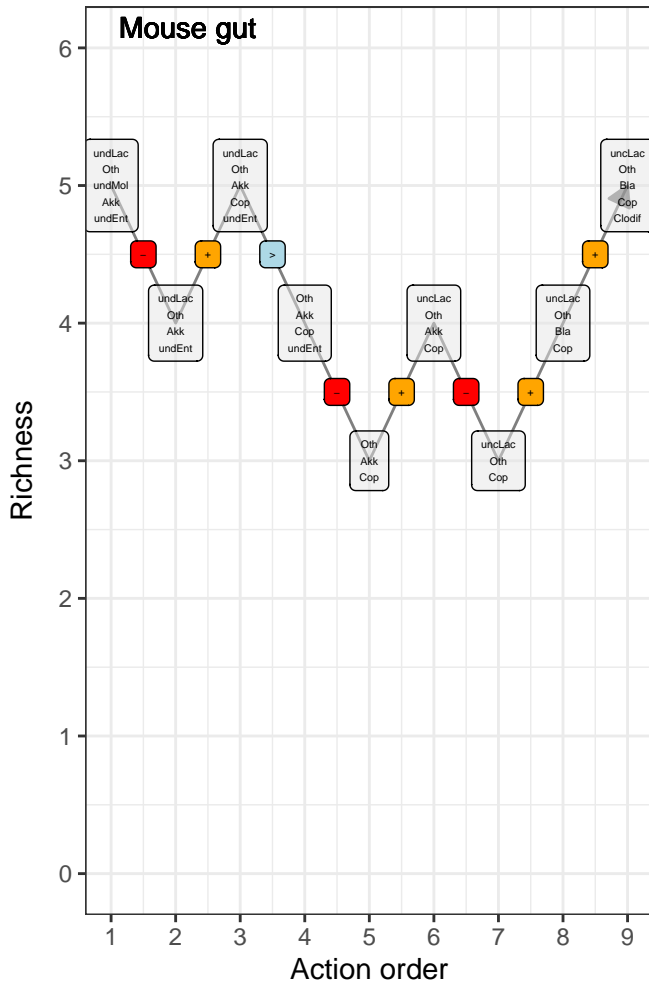
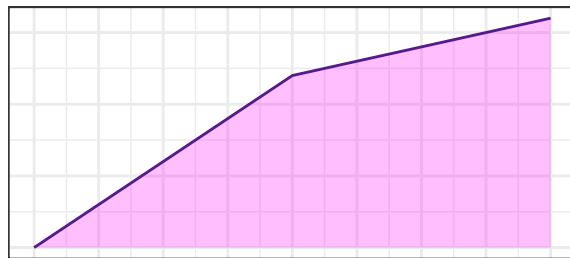
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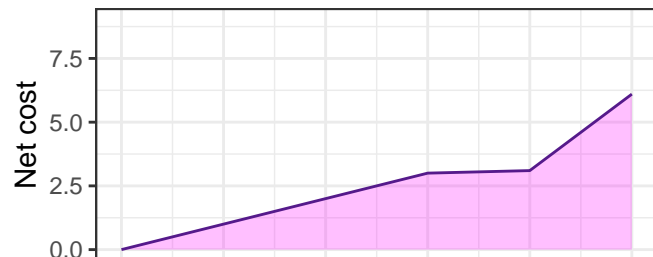
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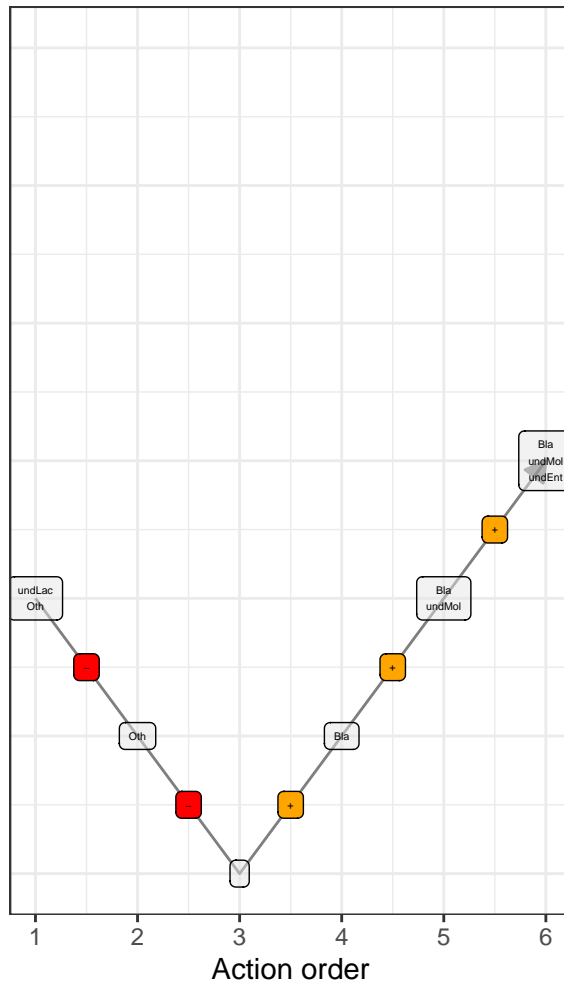
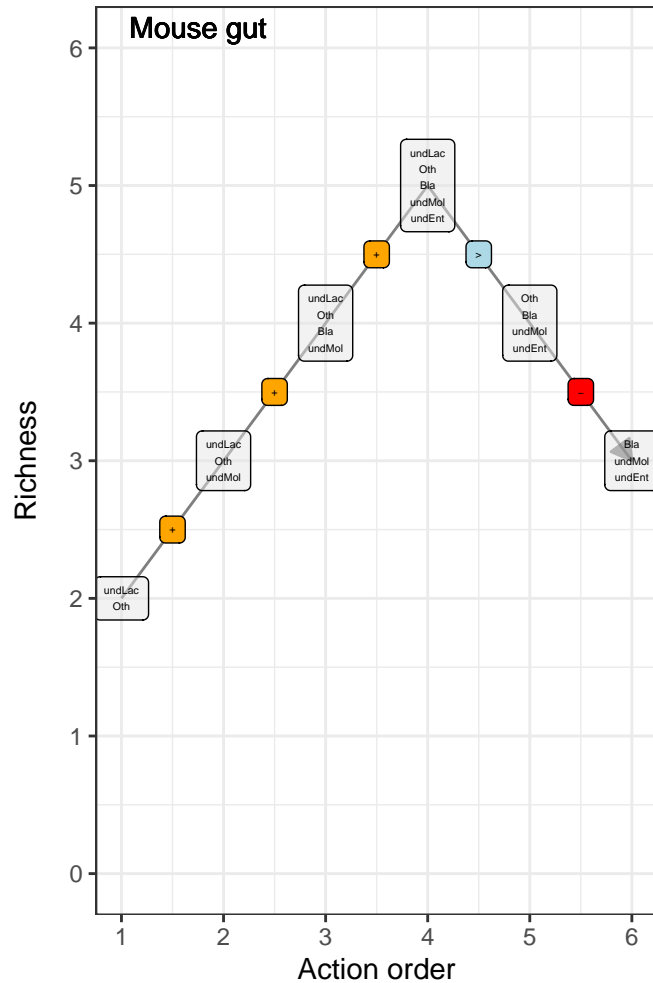
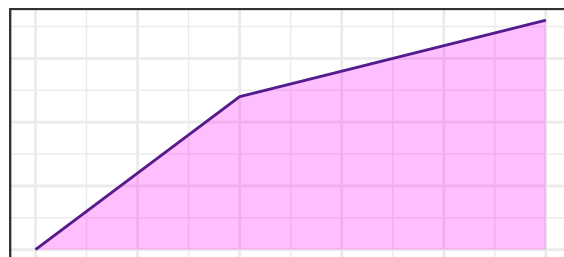
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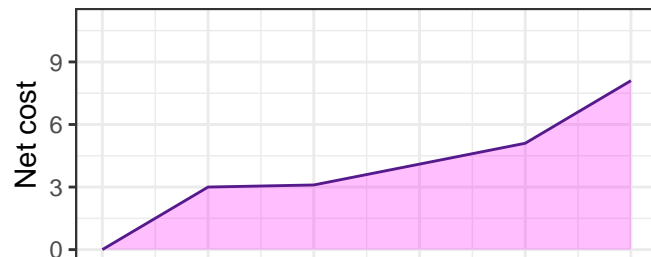
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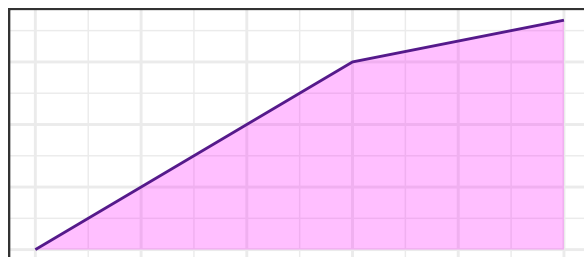
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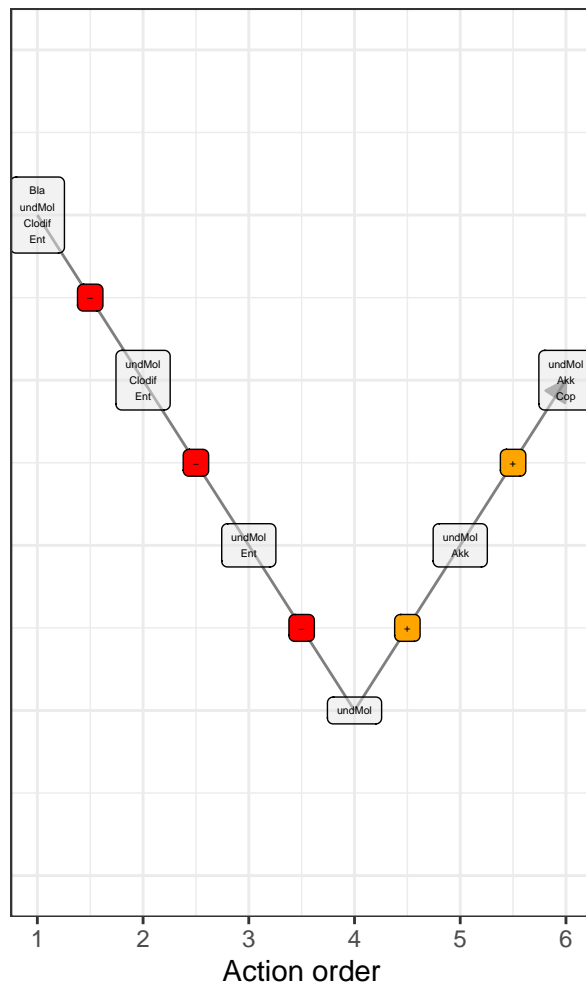
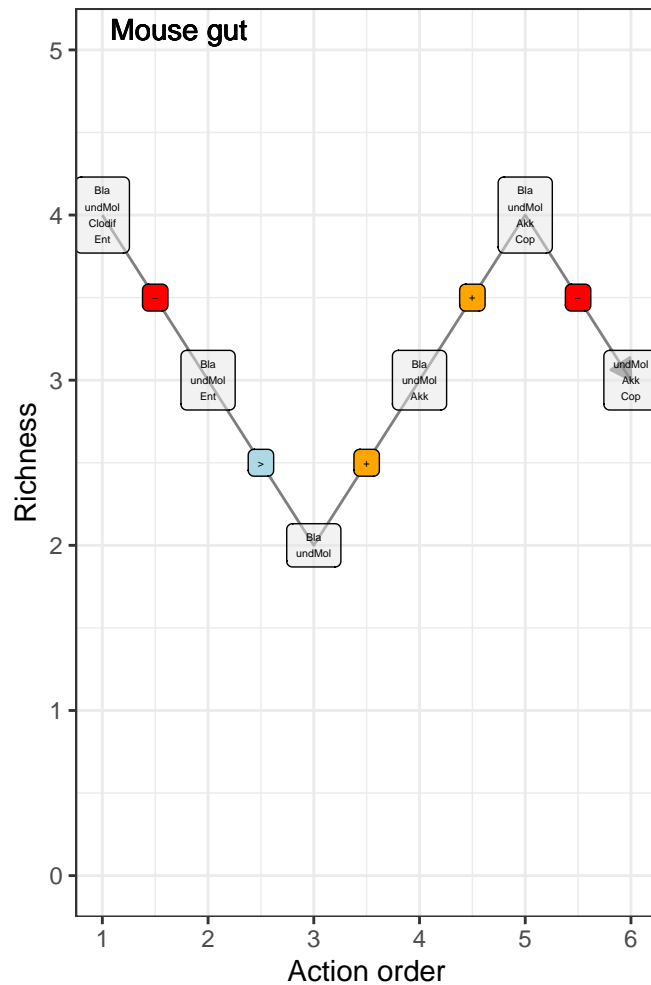
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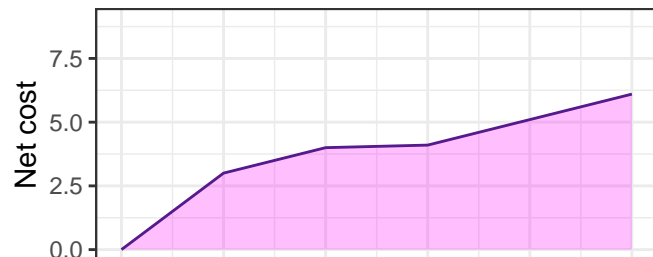
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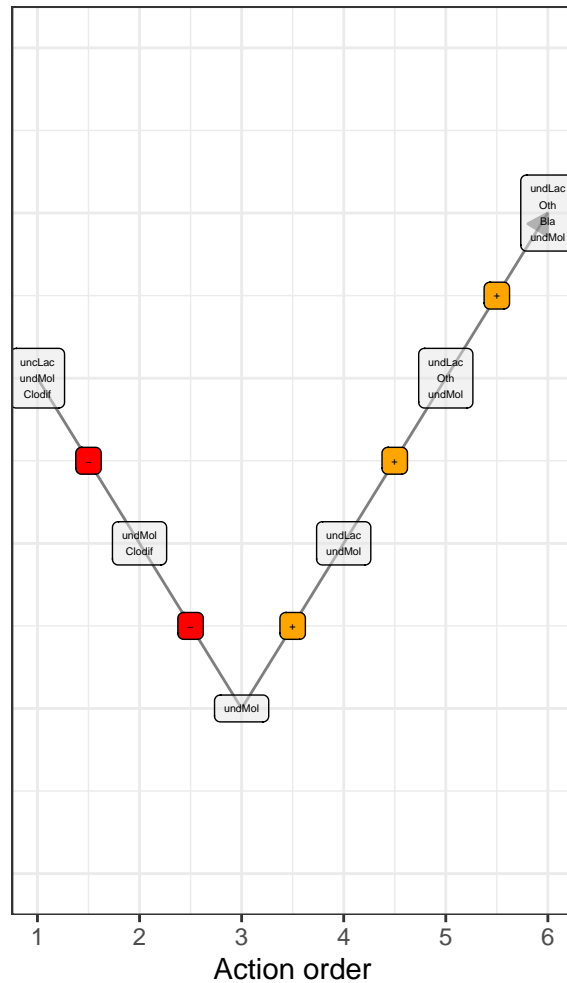
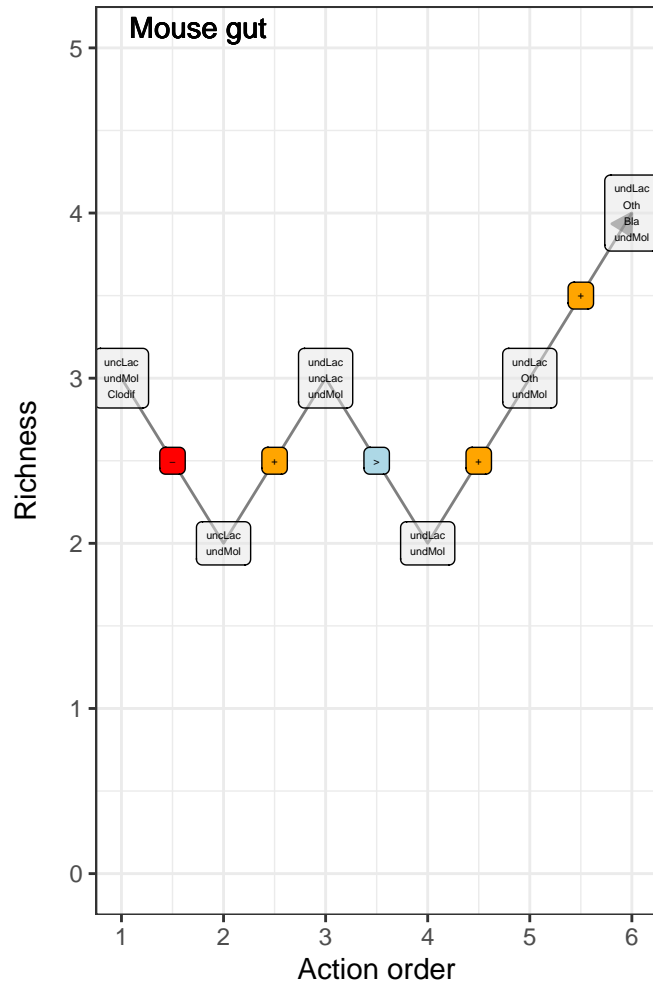
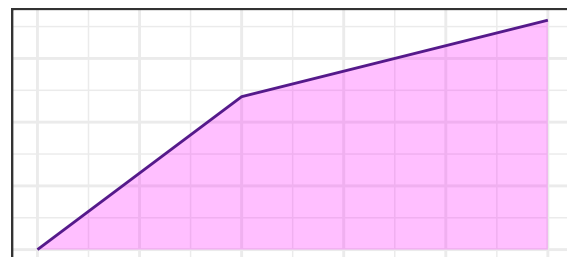
Mouse gut



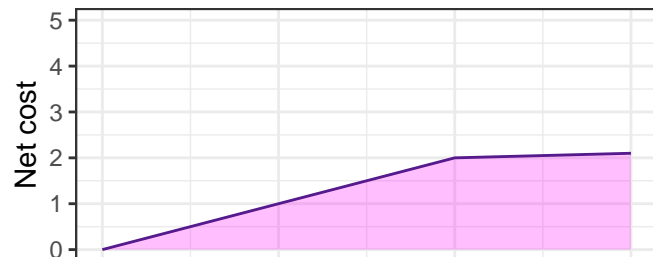
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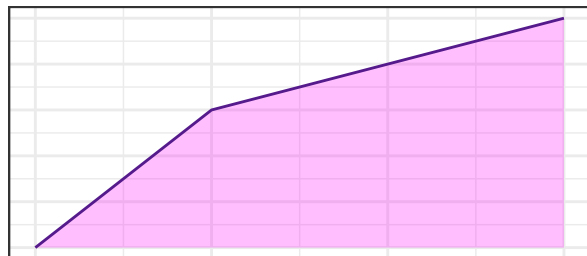
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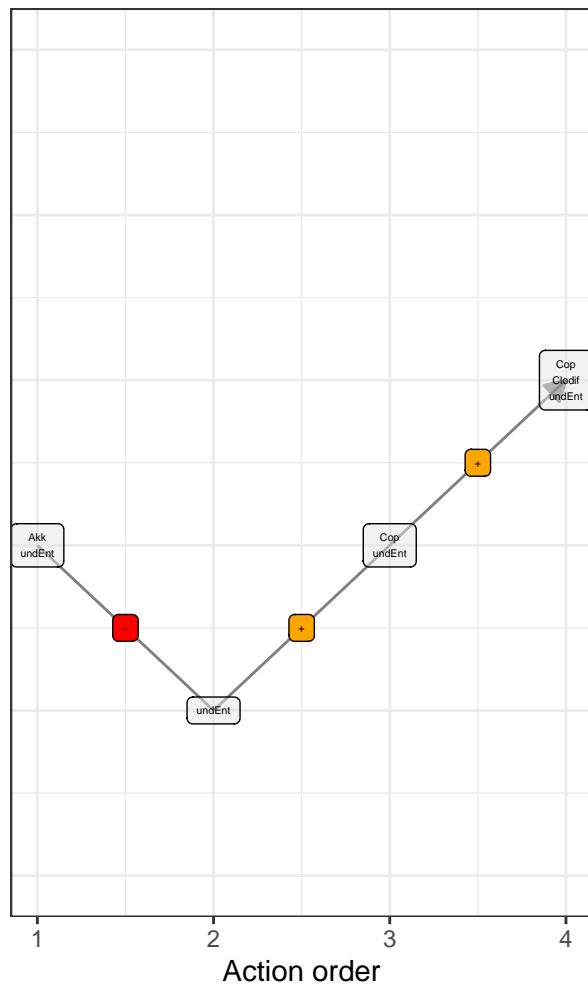
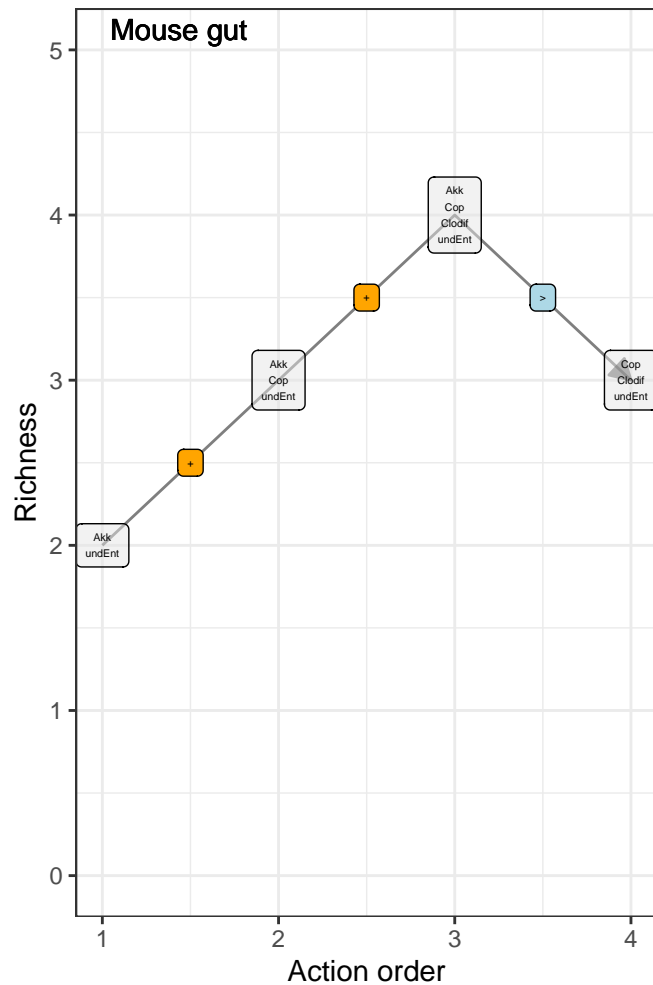
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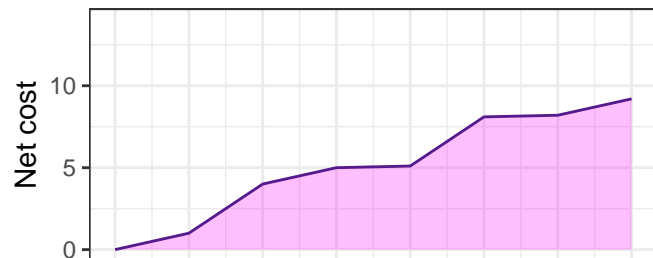
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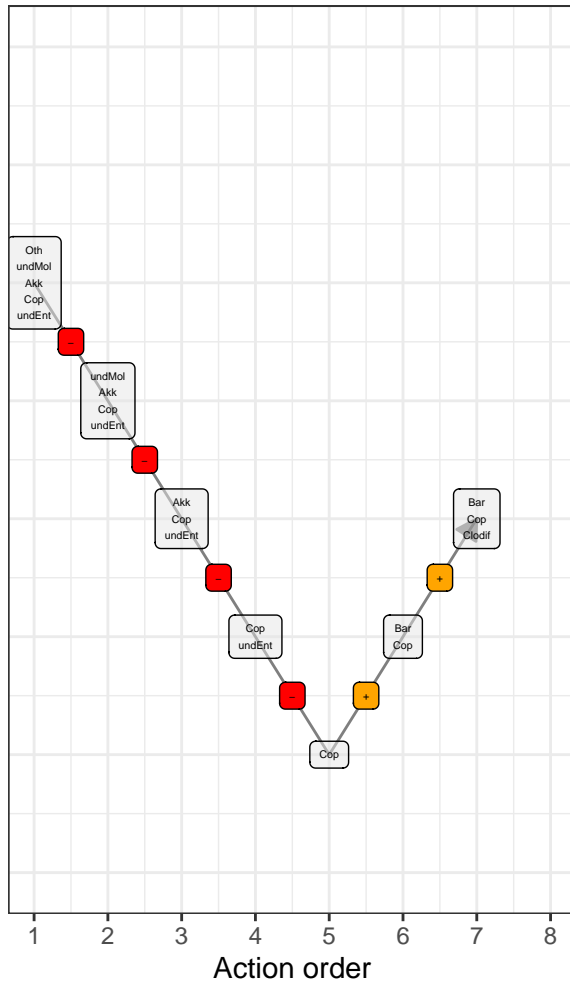
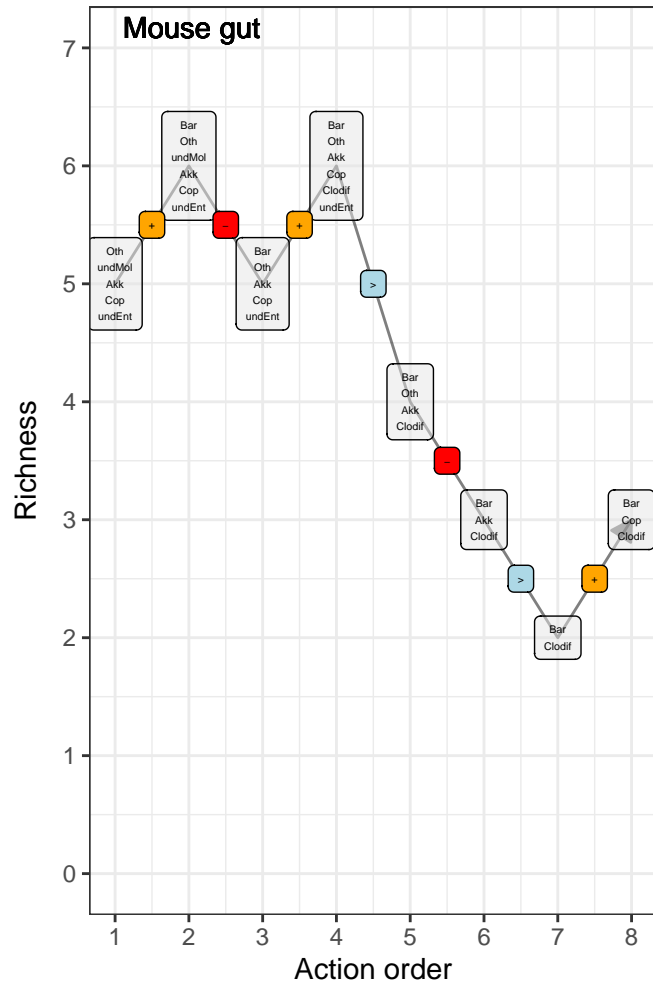
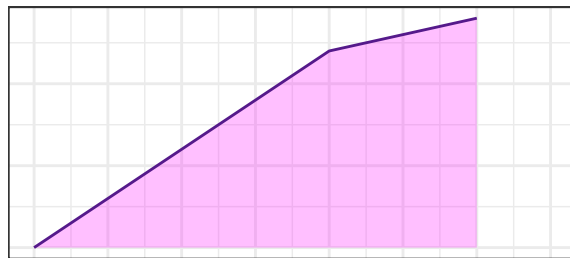
Mouse gut



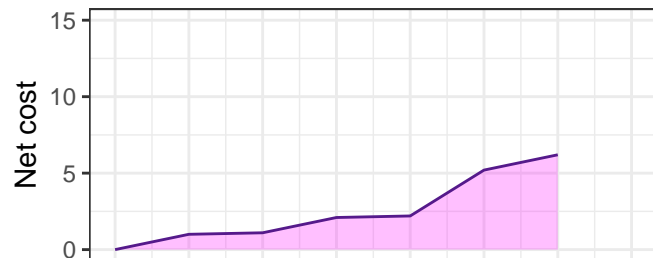
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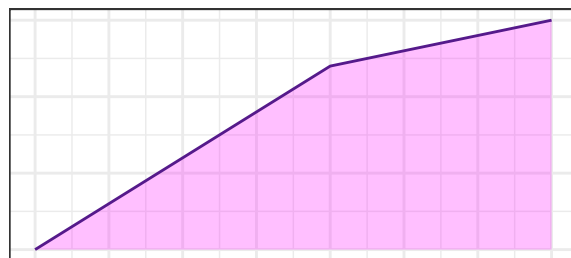
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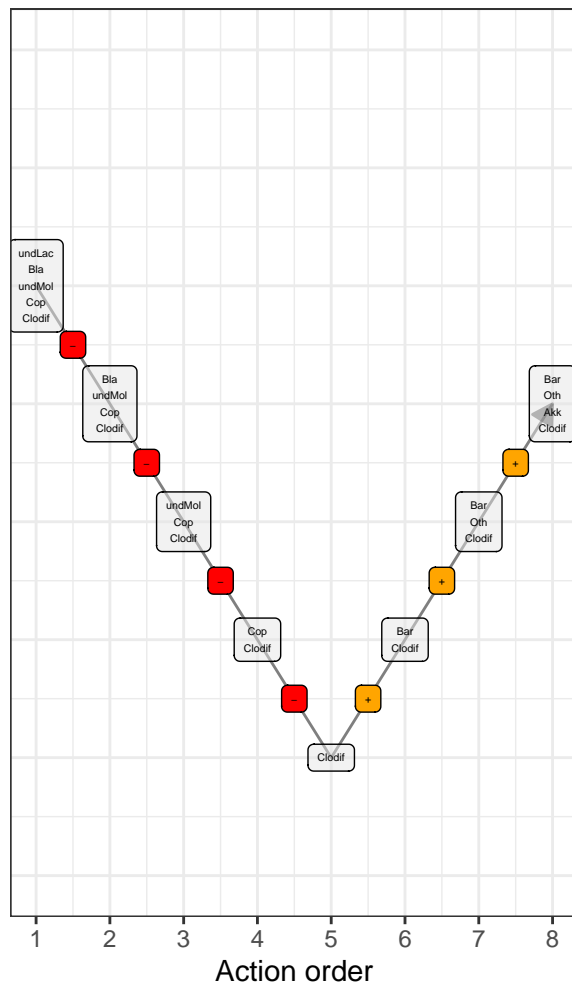
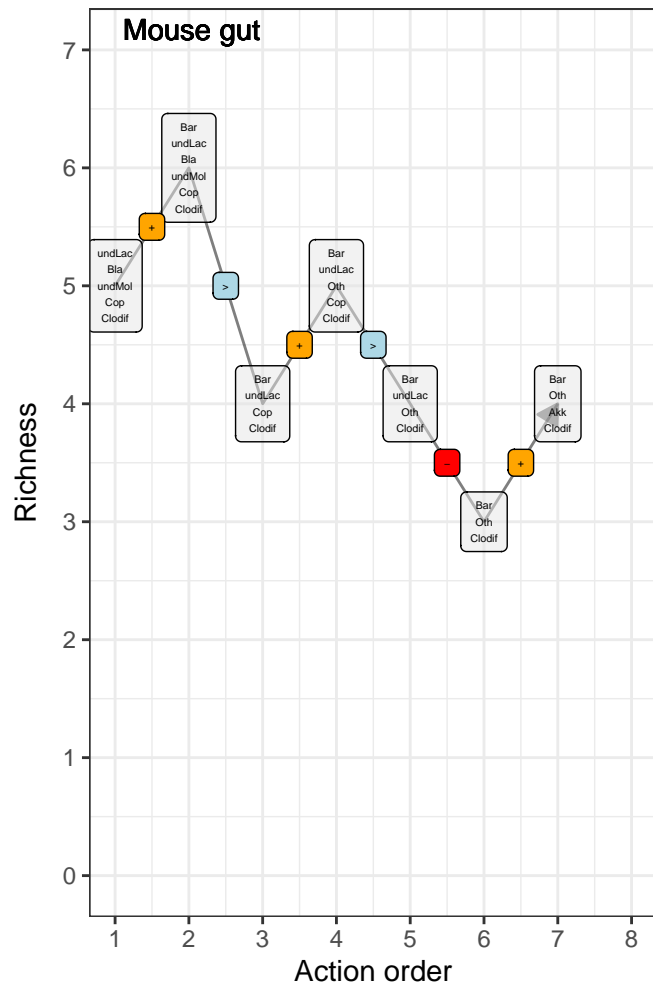
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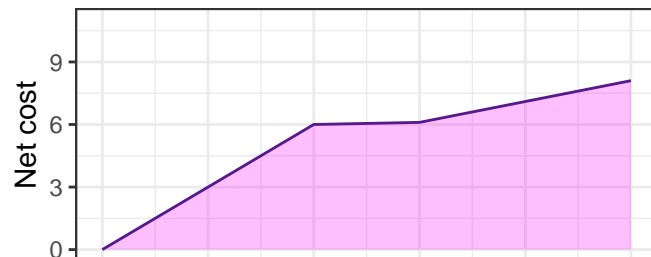
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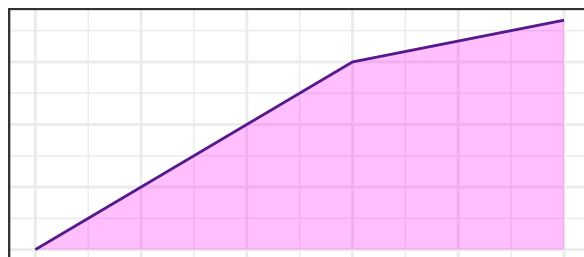
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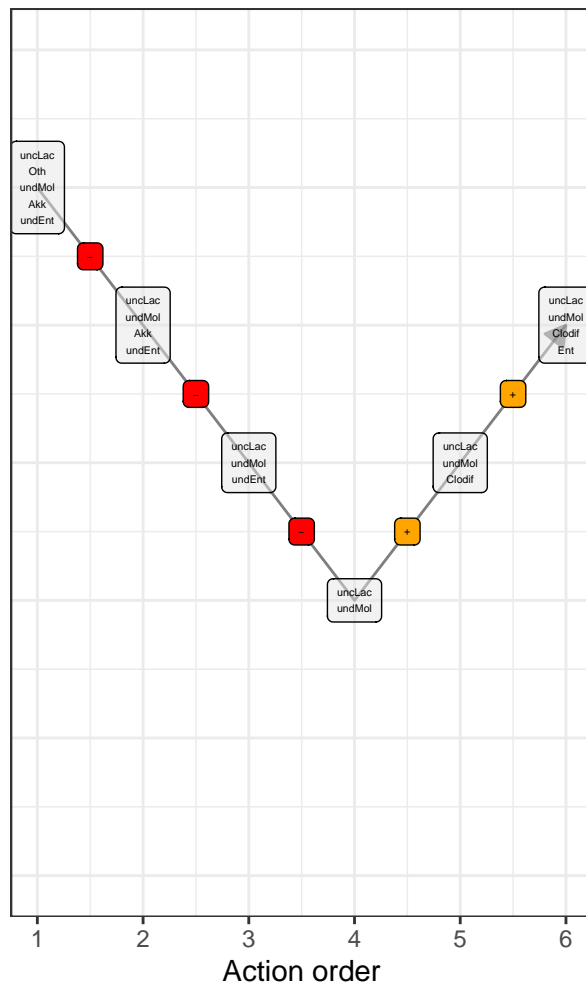
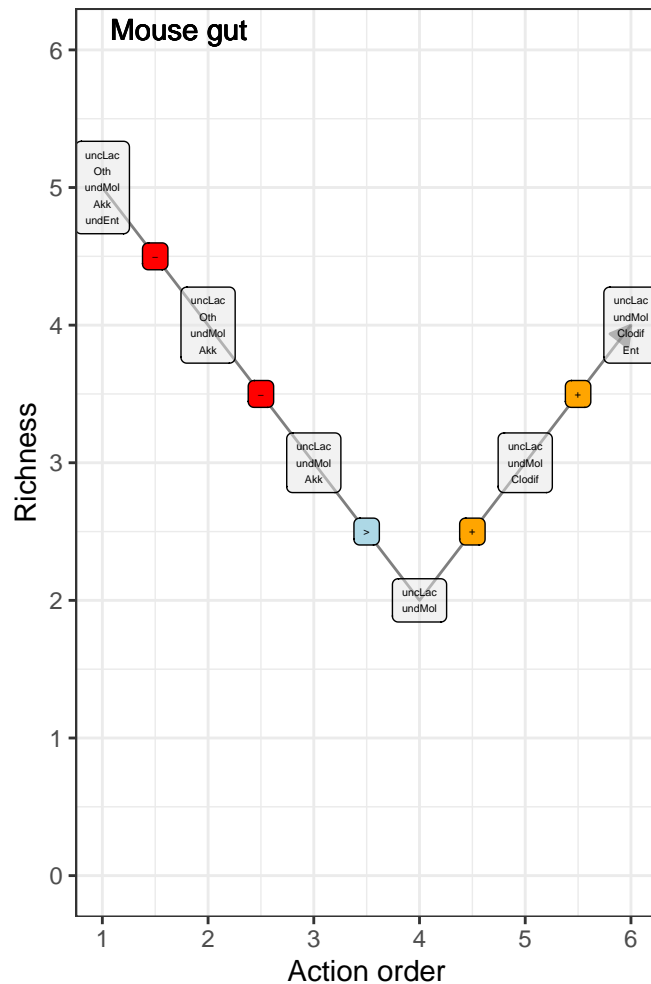
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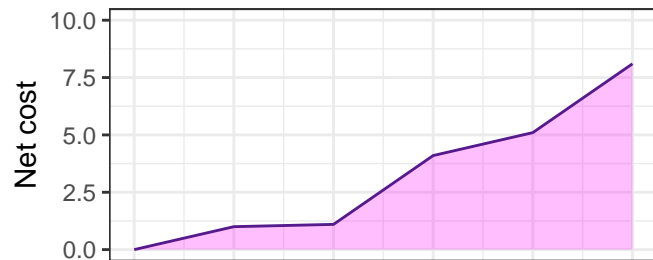
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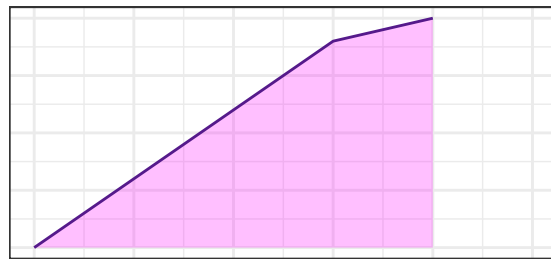
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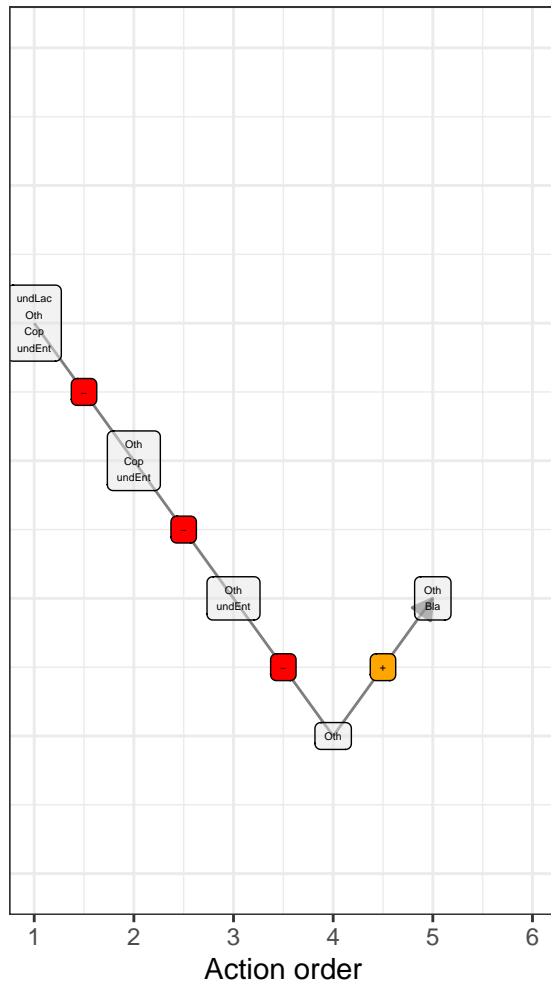
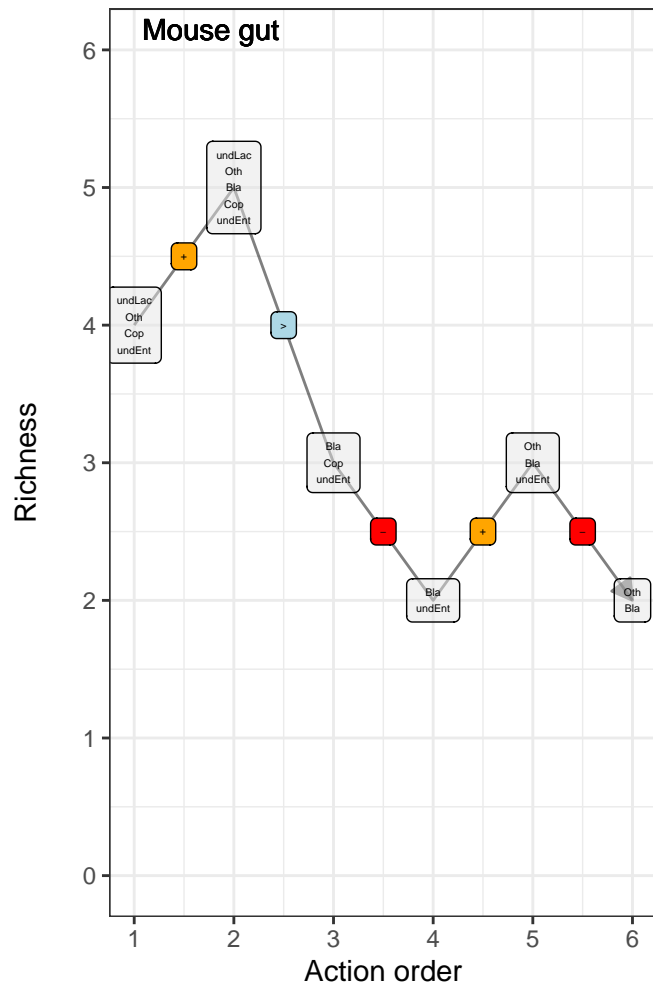
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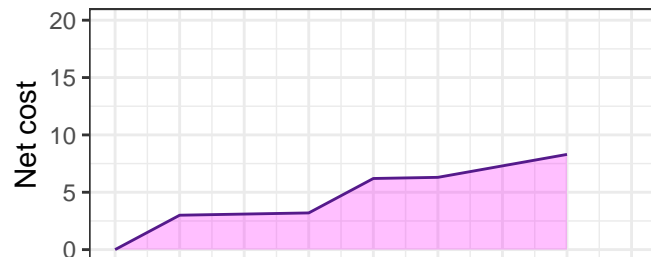
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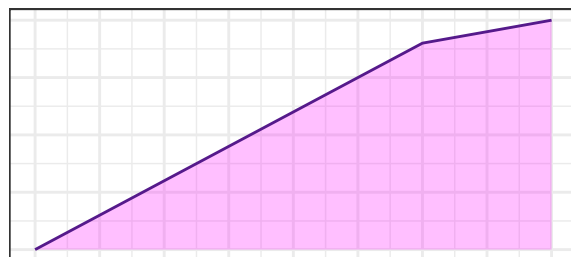
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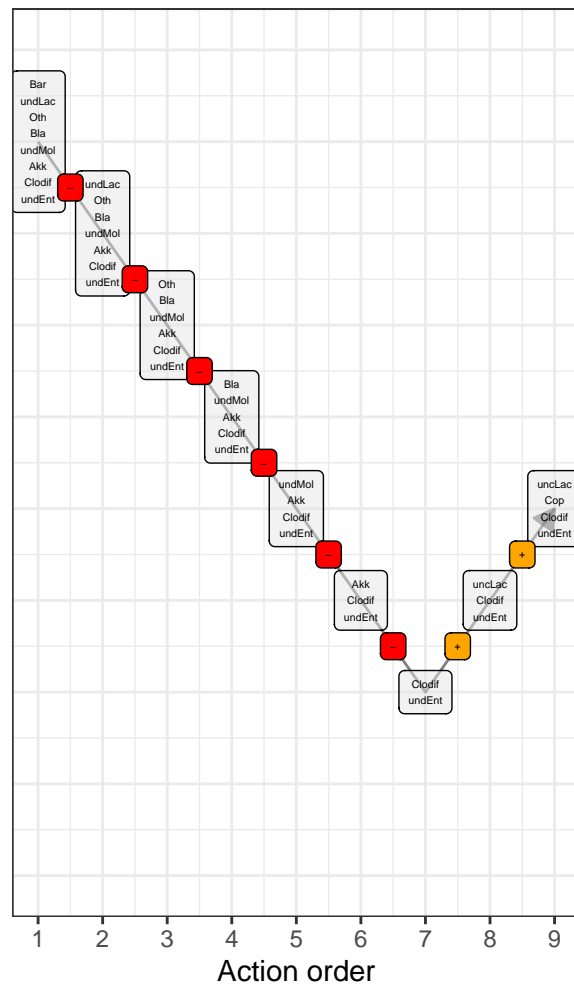
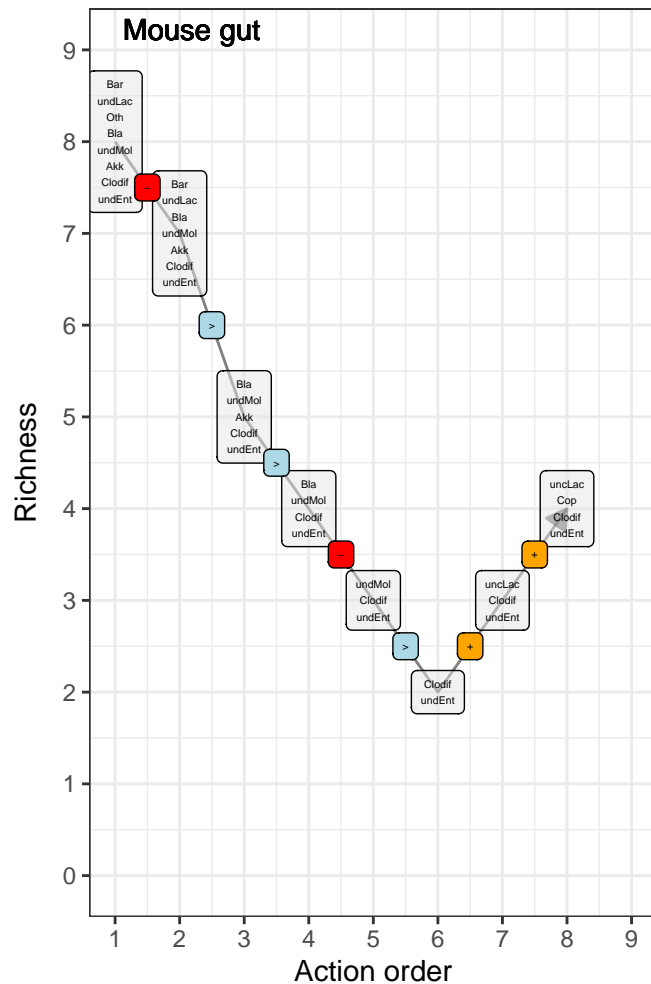
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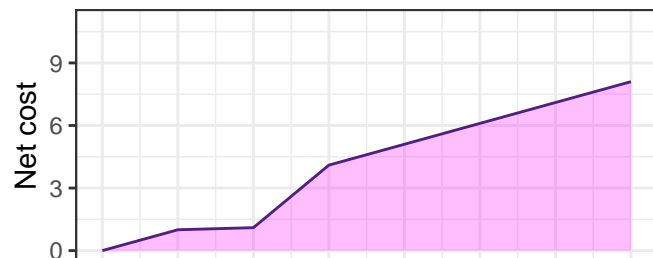
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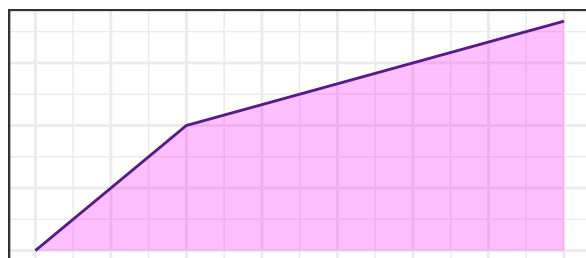
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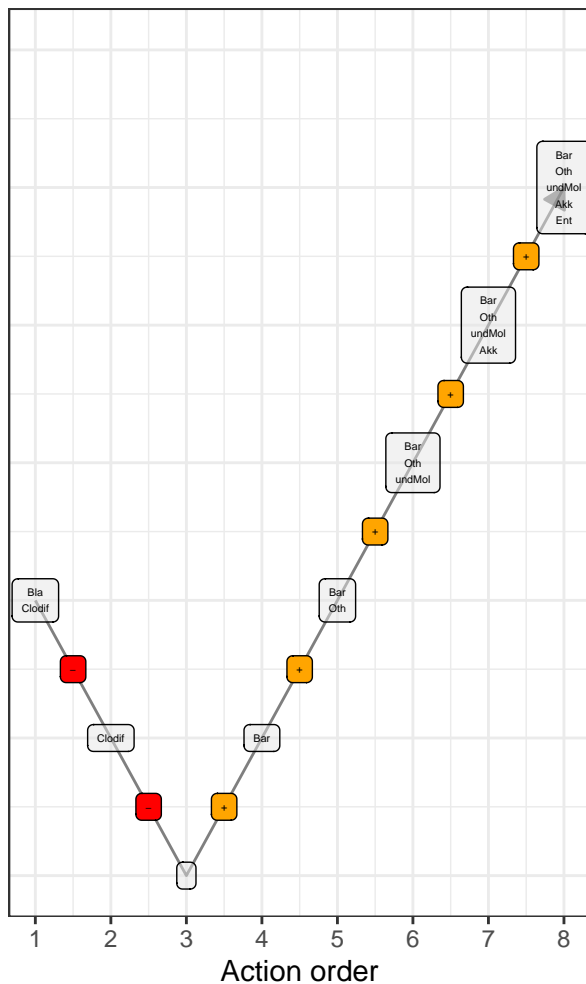
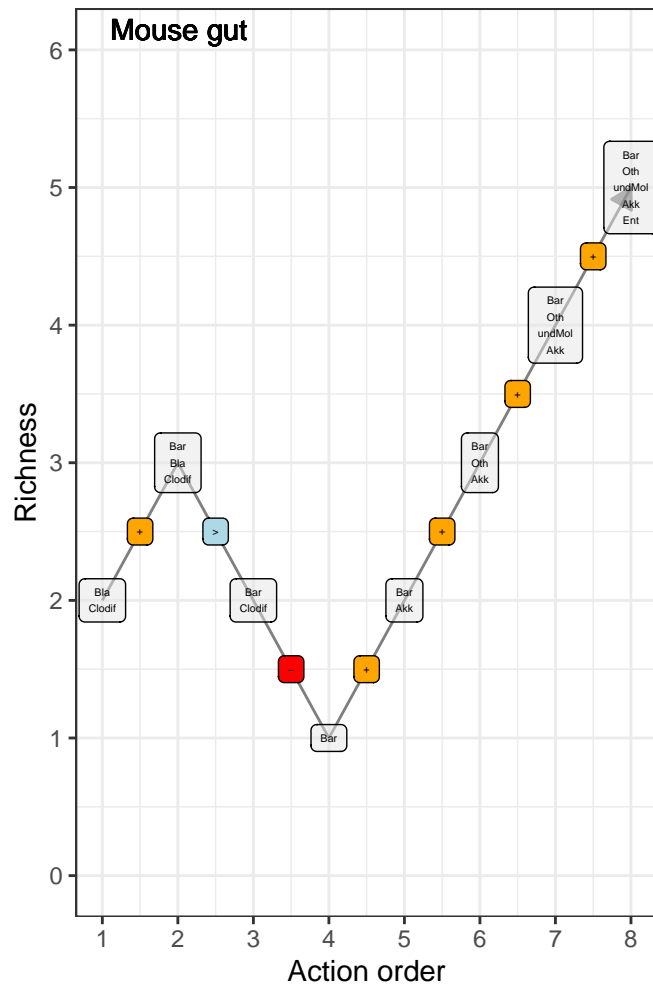
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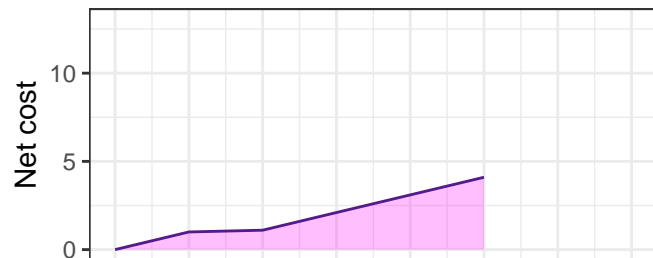
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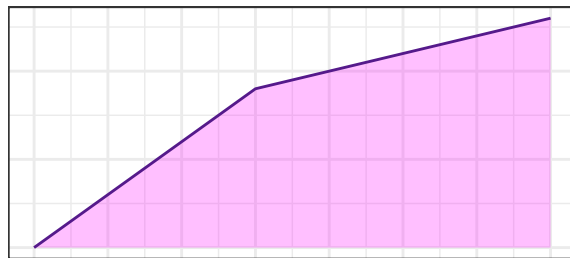
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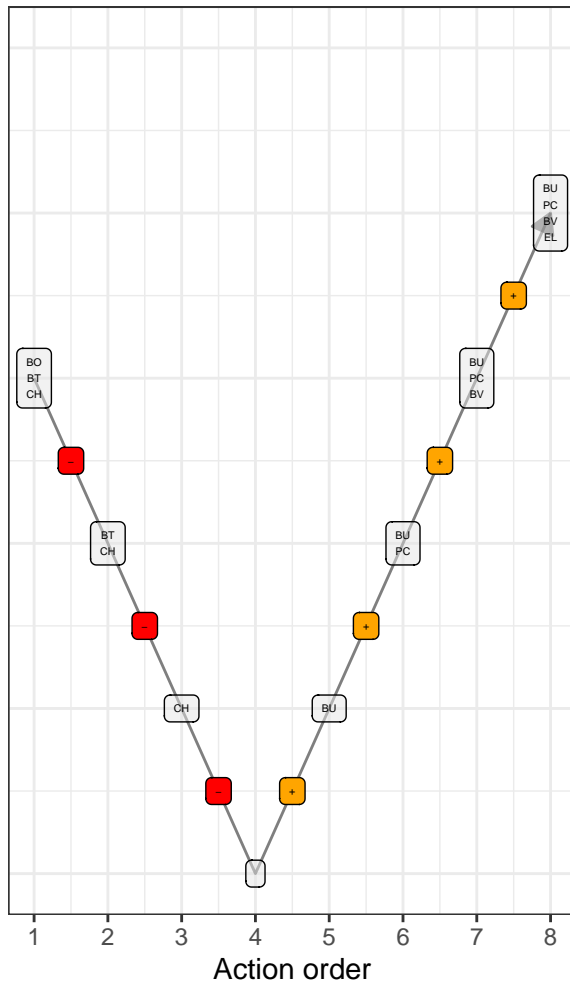
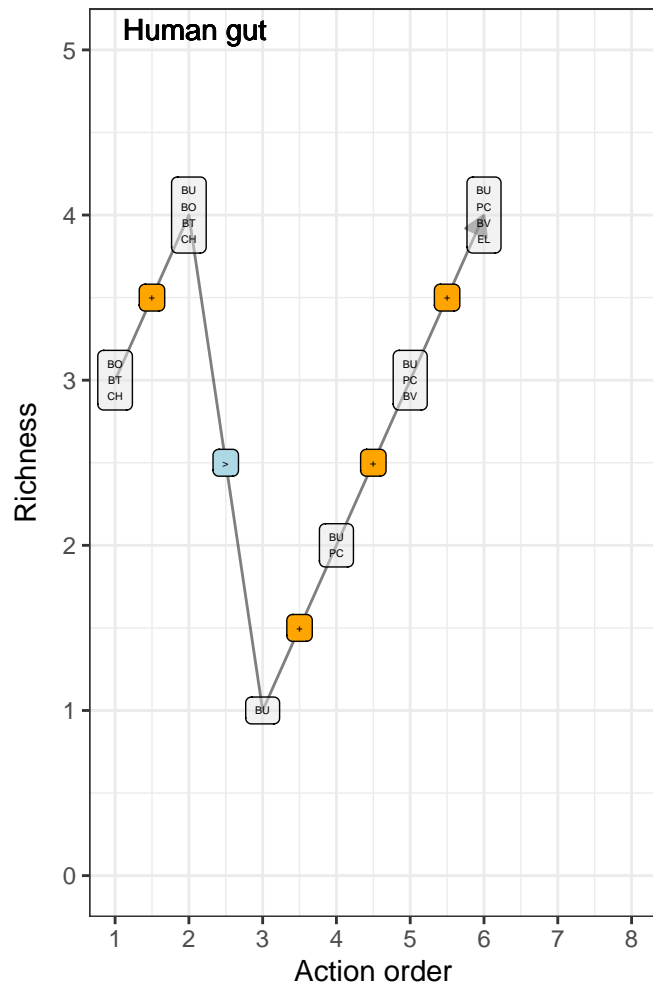
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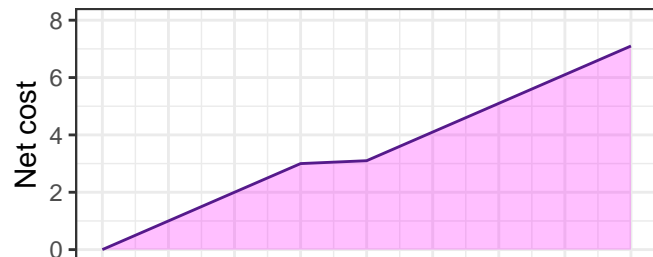
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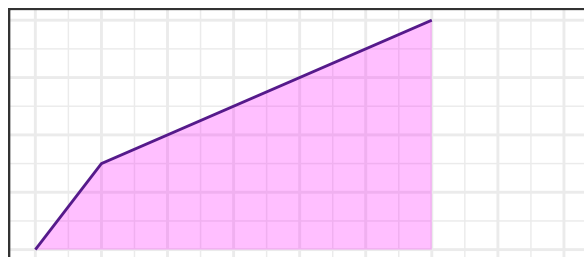
Human gut



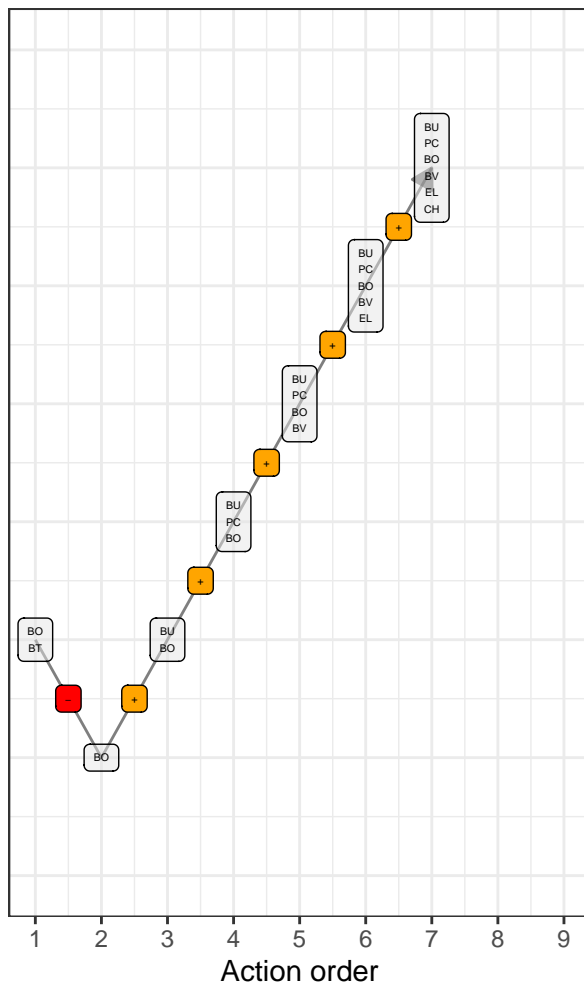
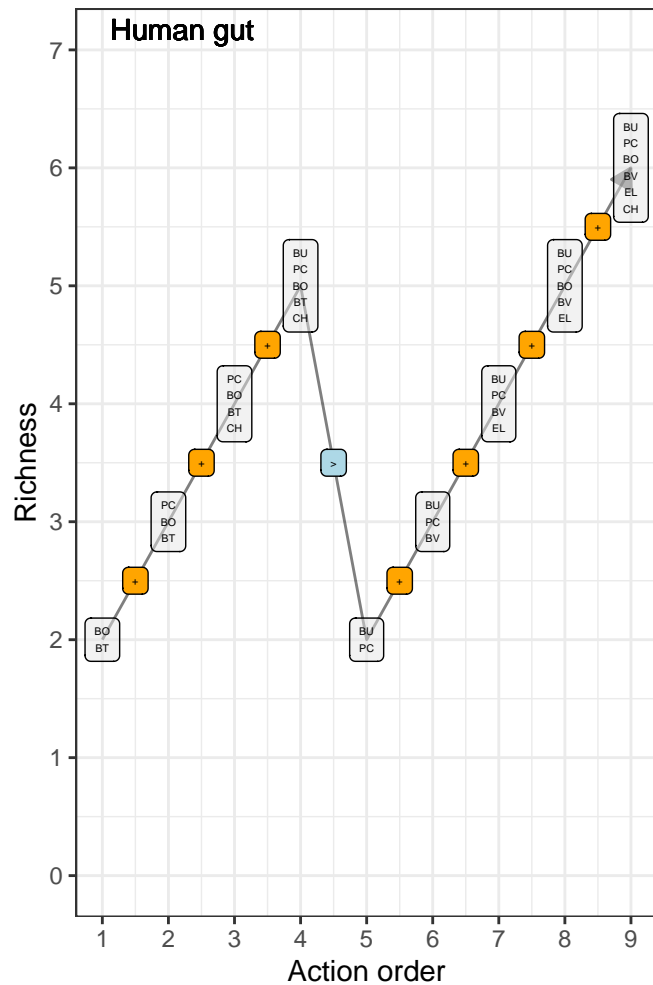
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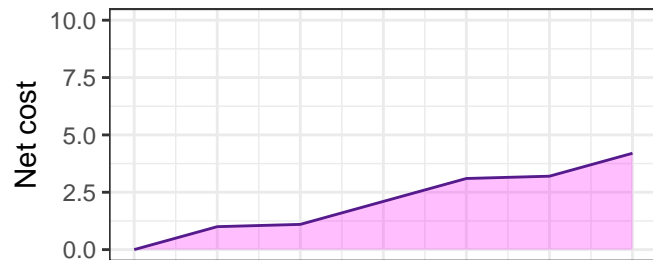
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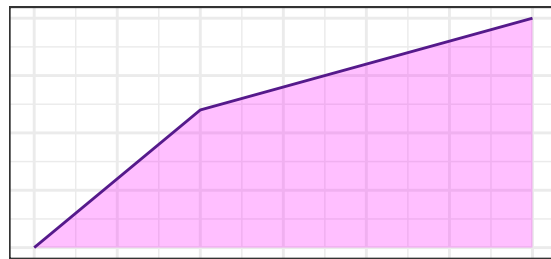
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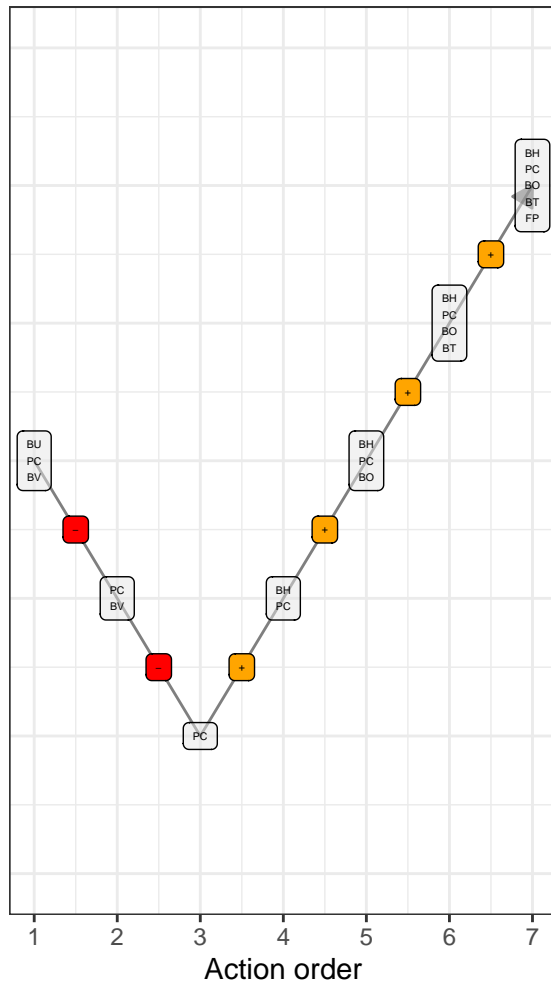
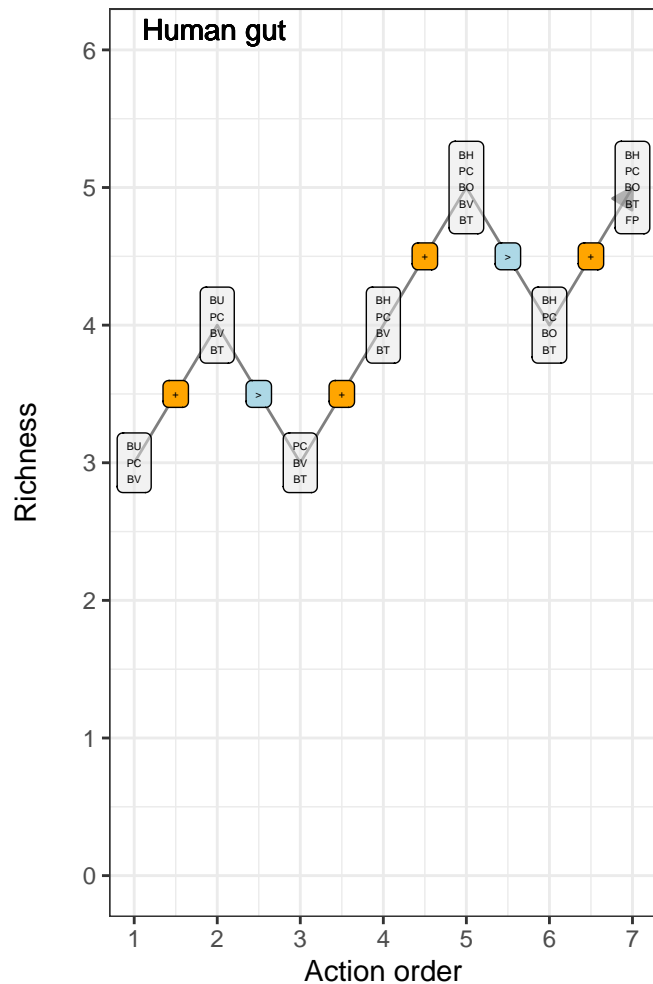
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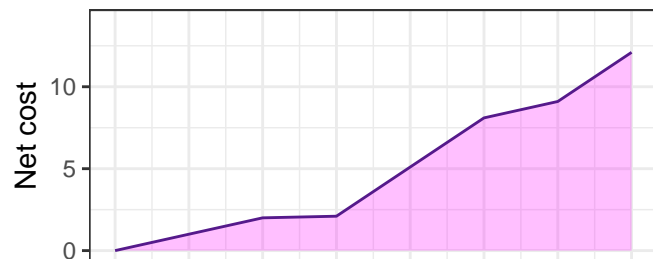
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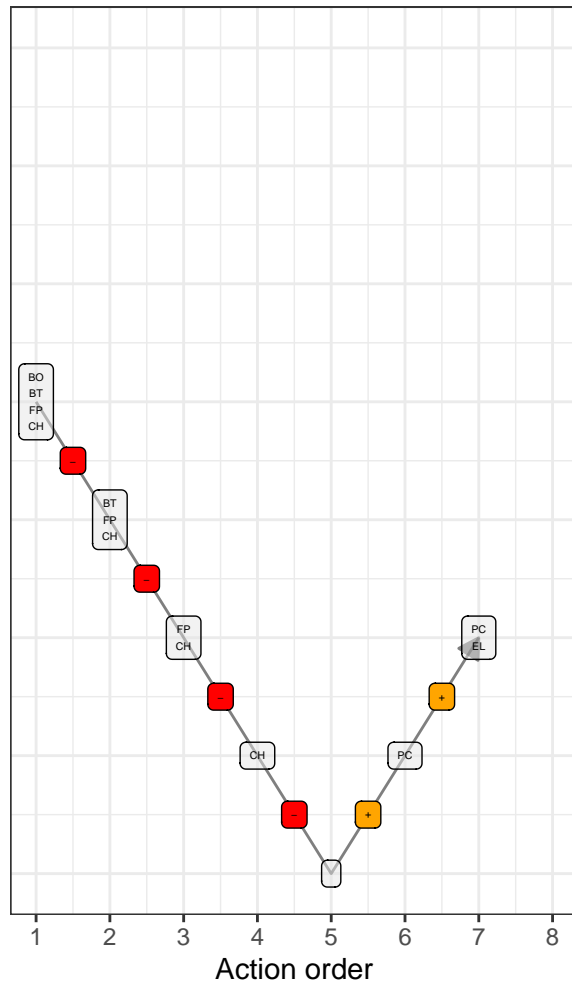
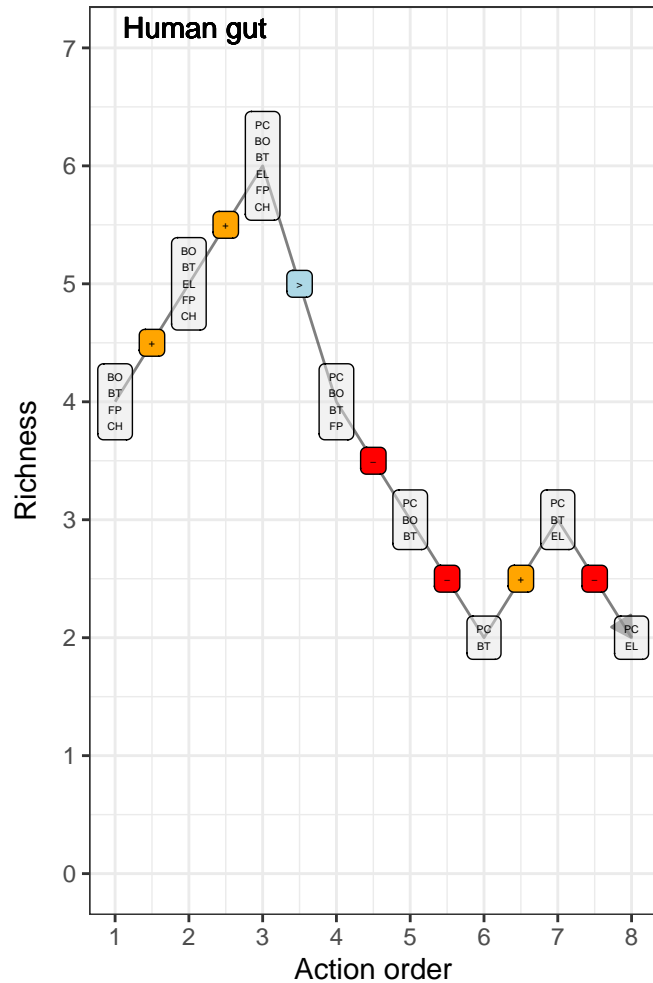
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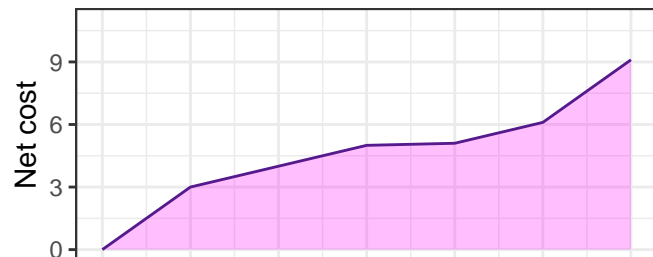
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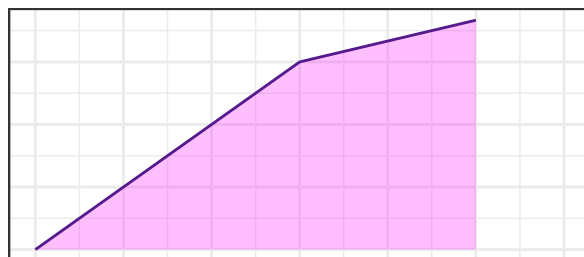
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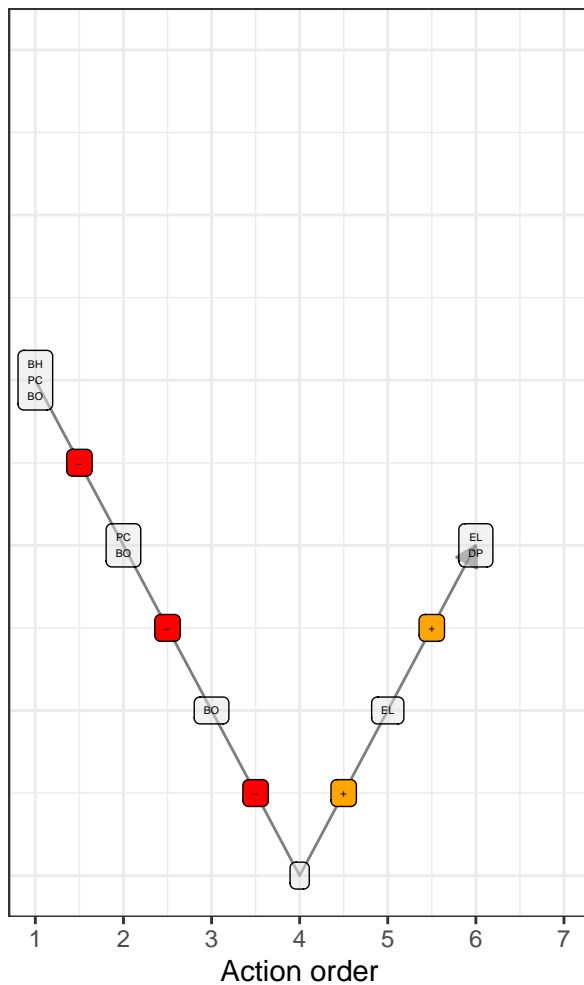
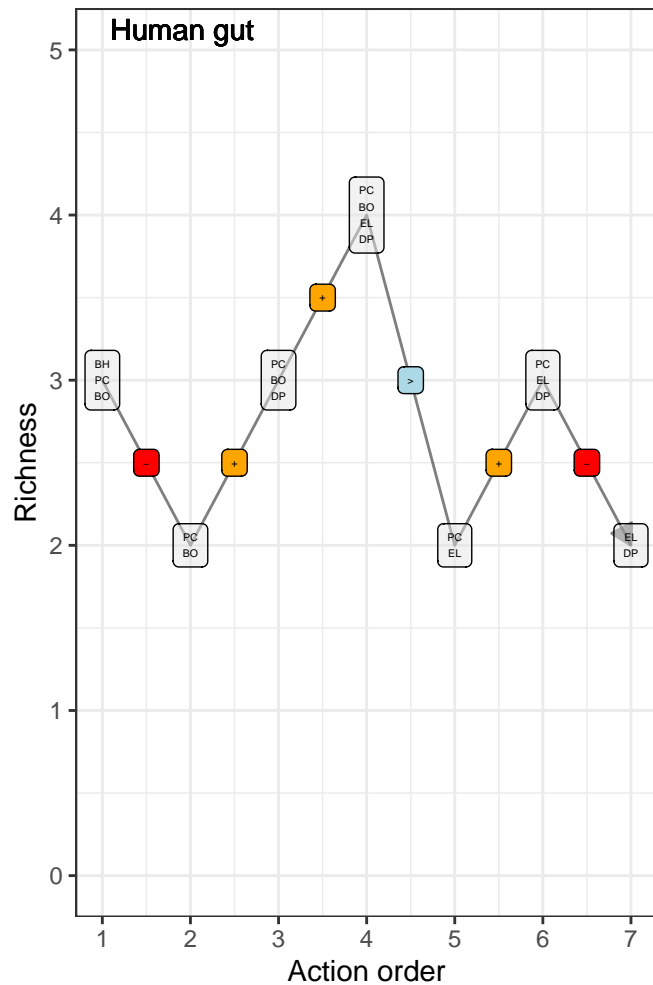
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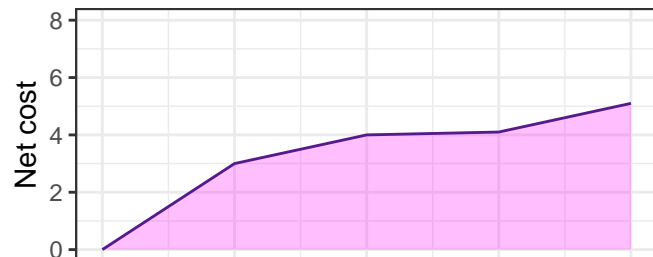
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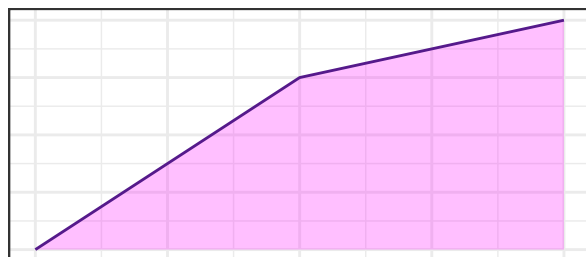
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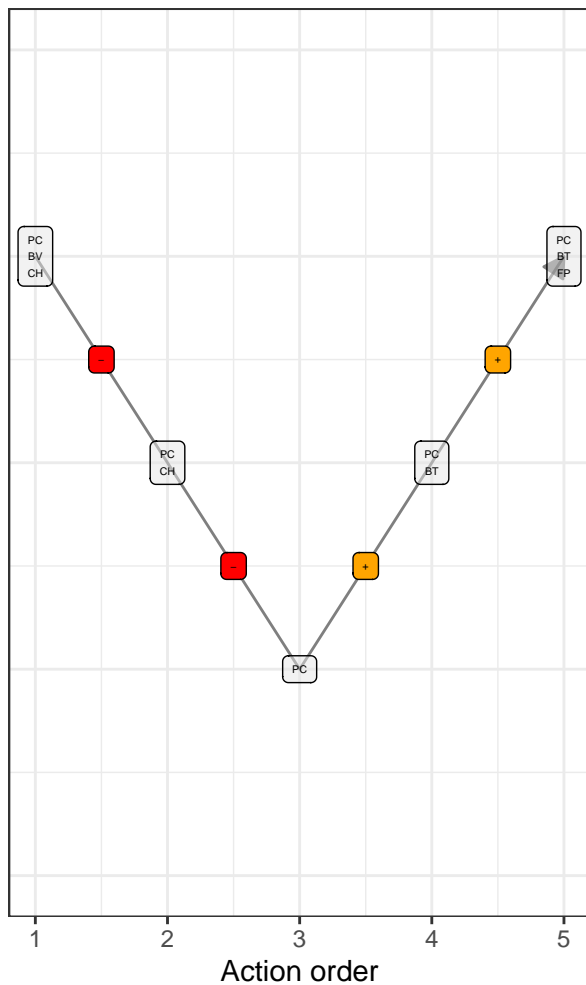
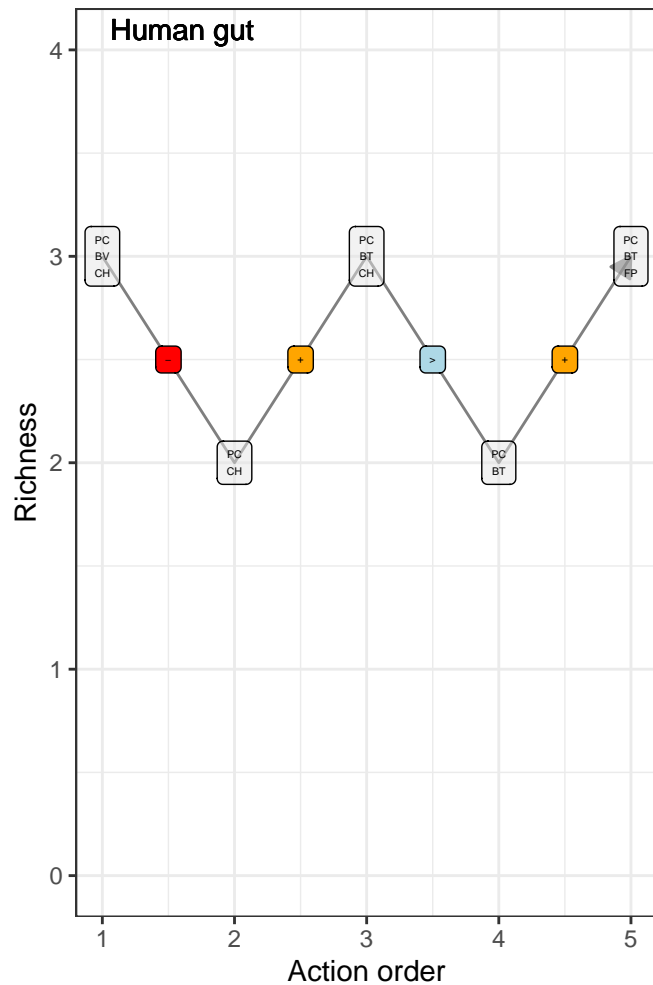
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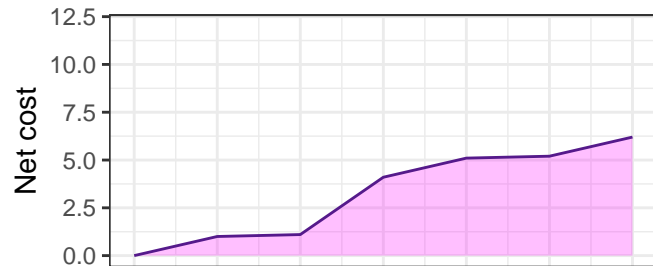
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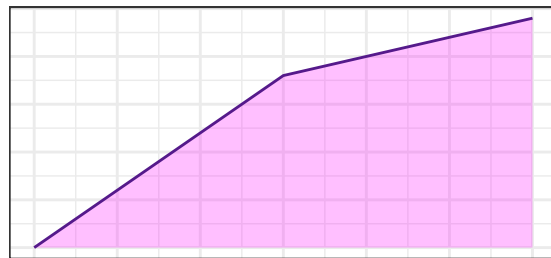
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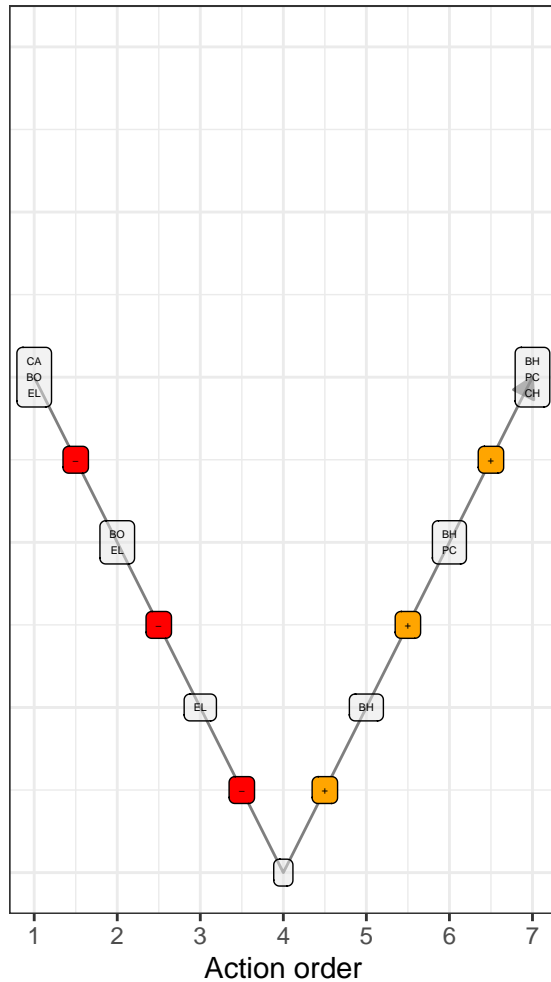
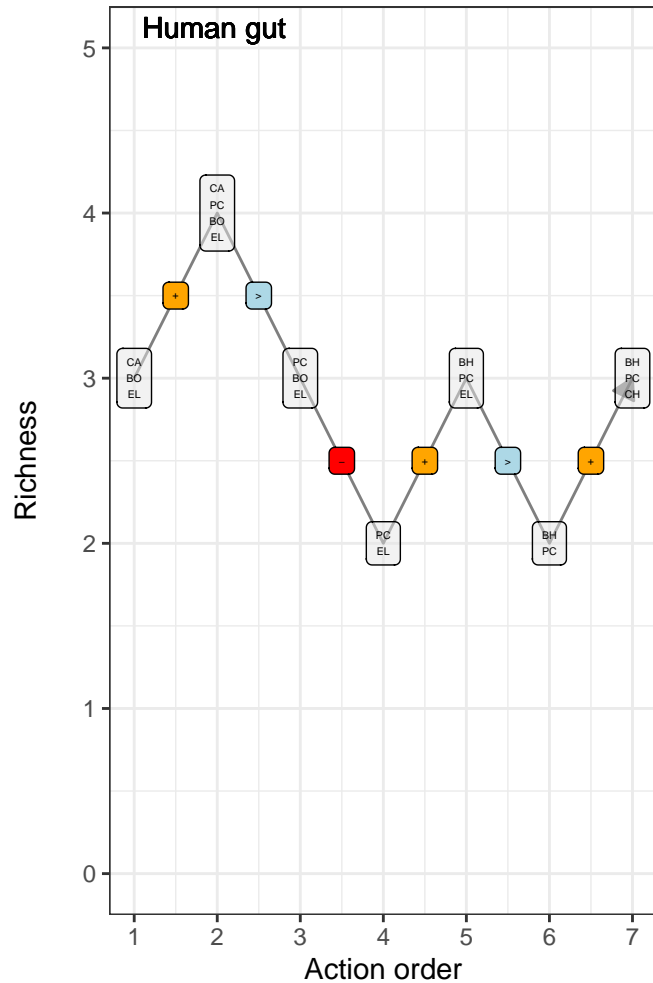
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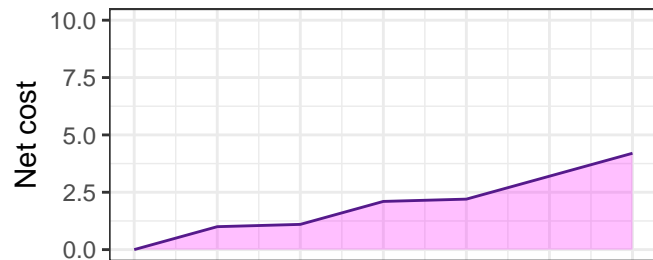
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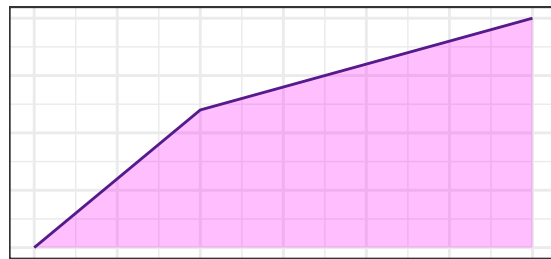
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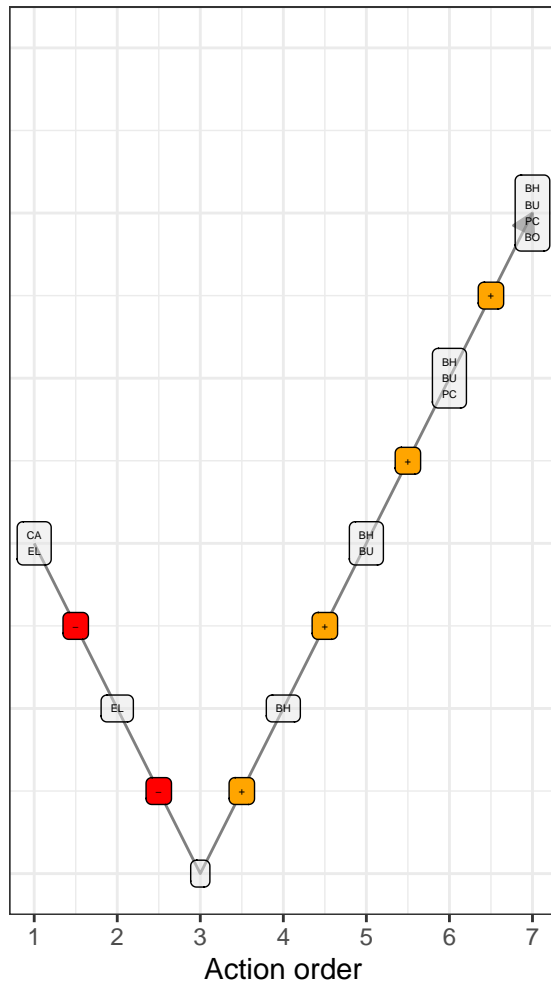
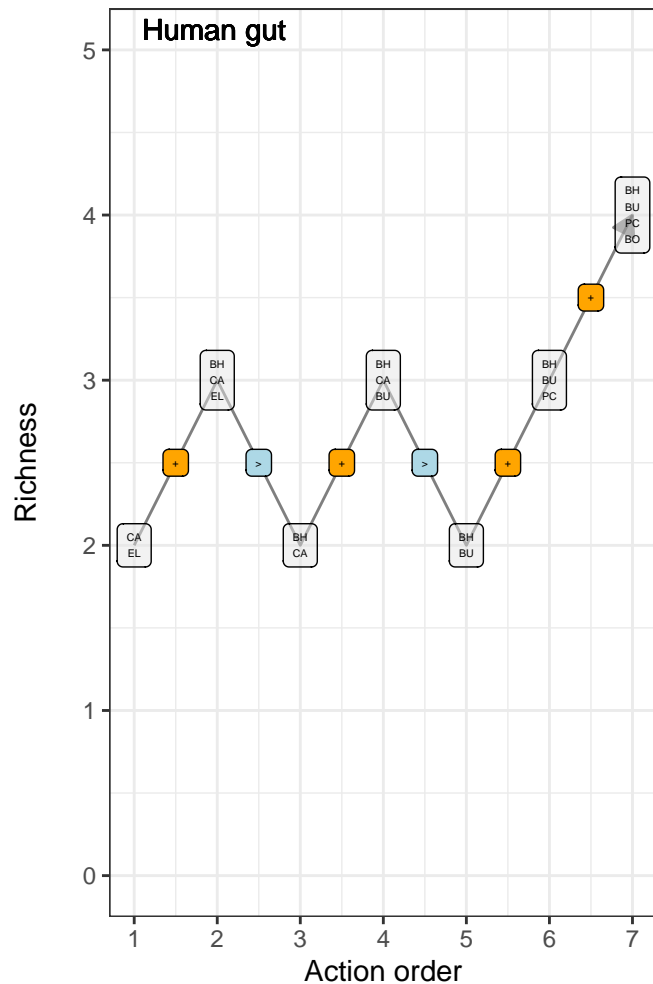
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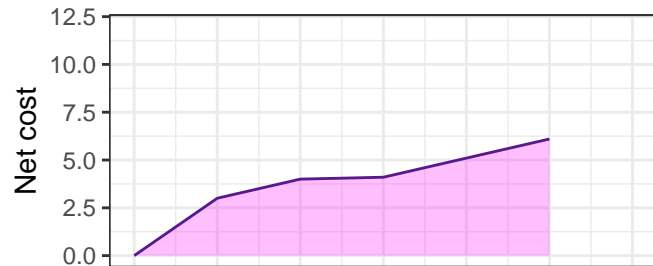
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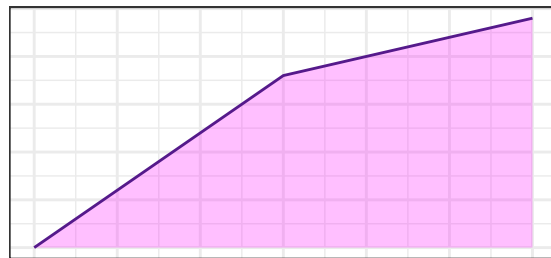
Human gut



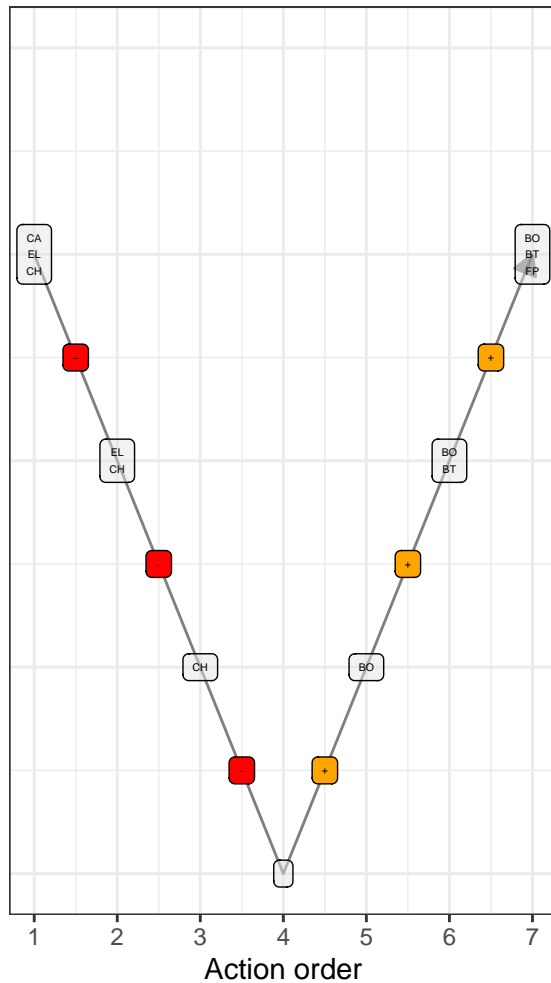
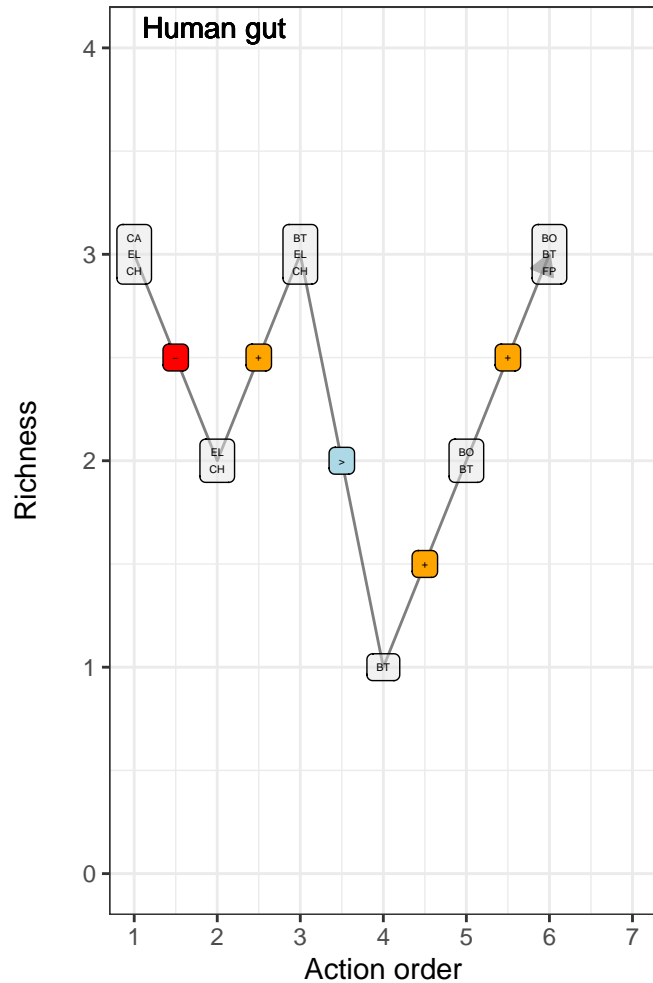
Optimal path



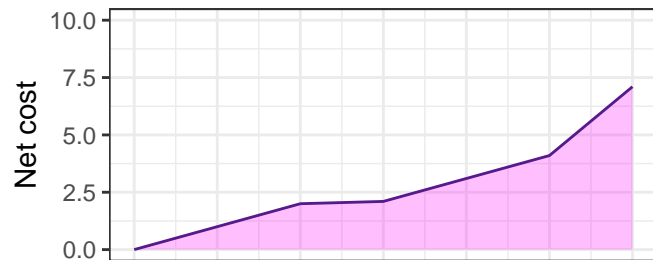
Nominal path



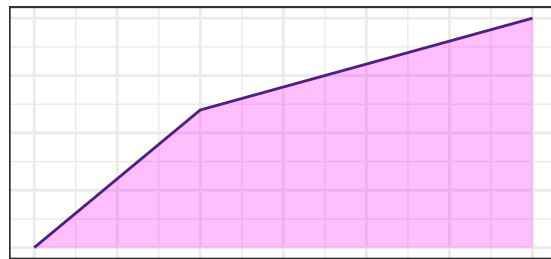
Human gut



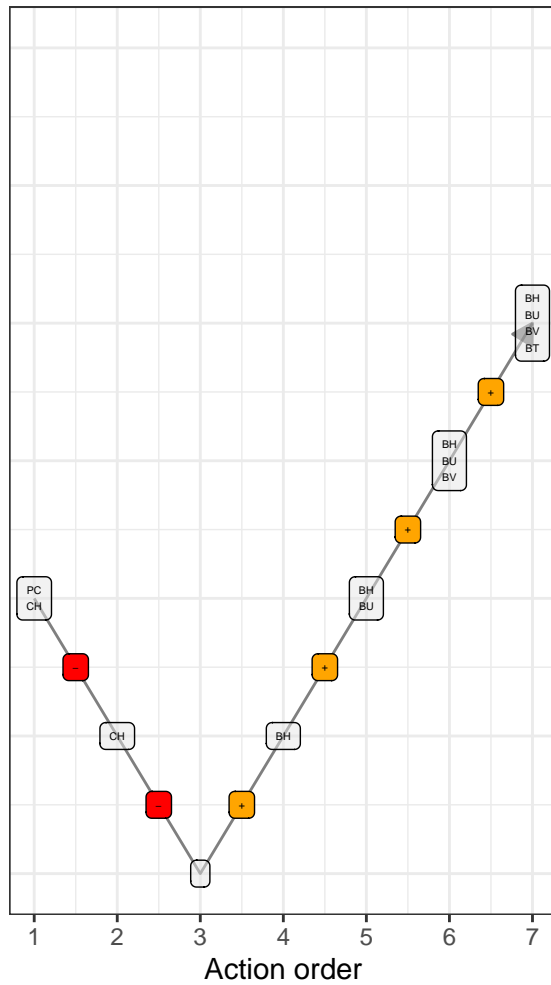
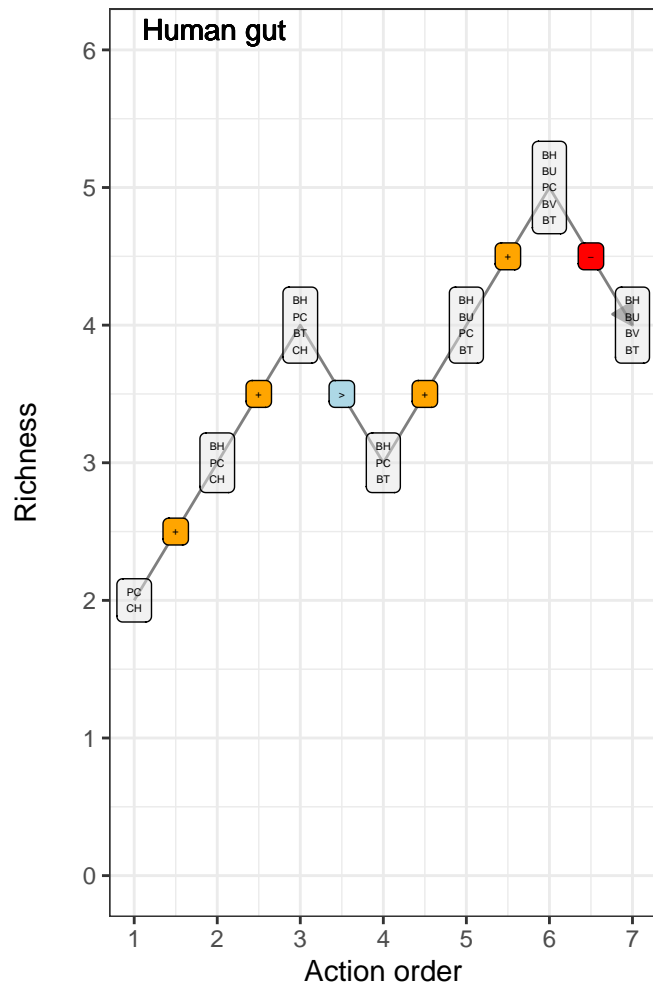
Optimal path



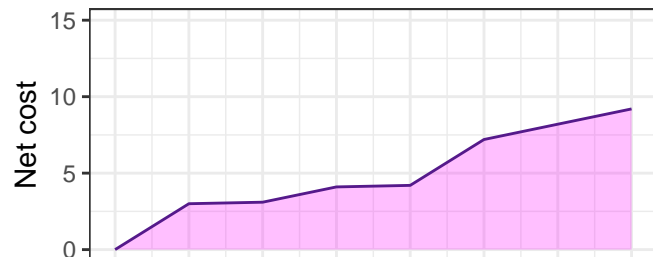
Nominal path



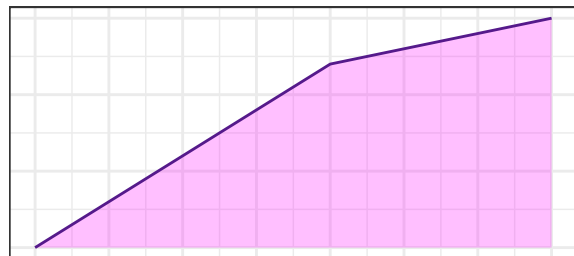
Human gut



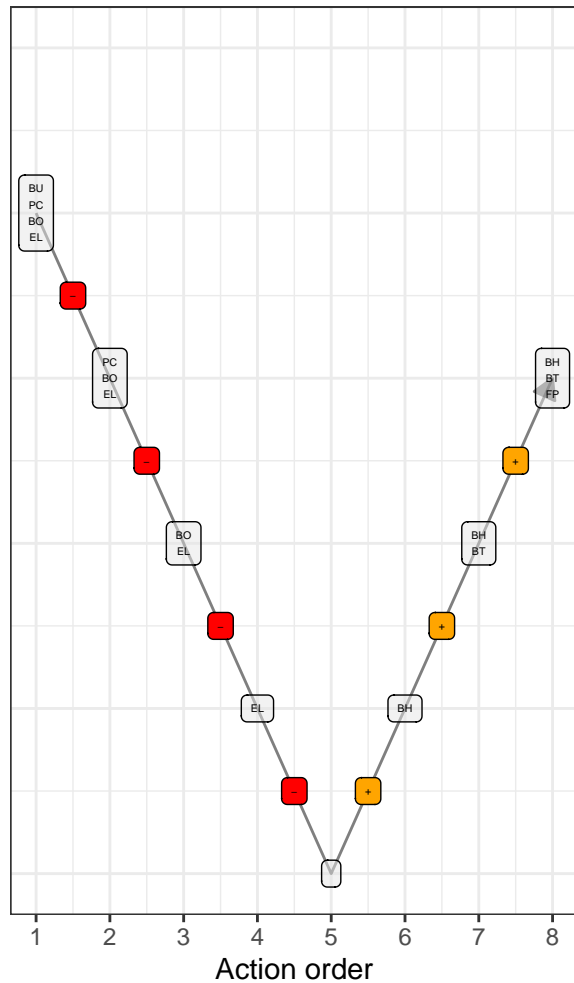
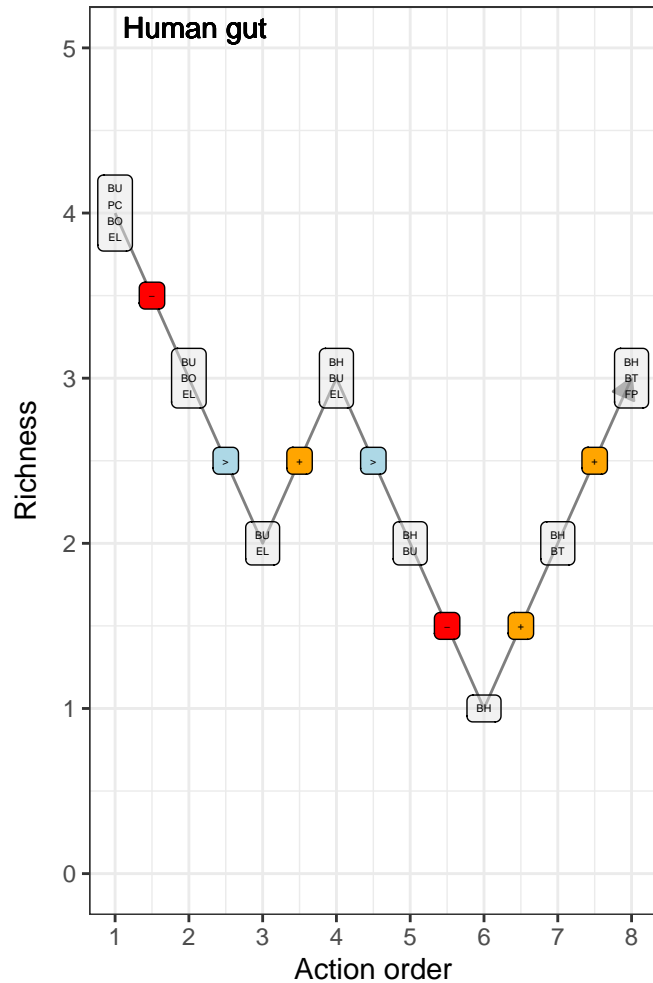
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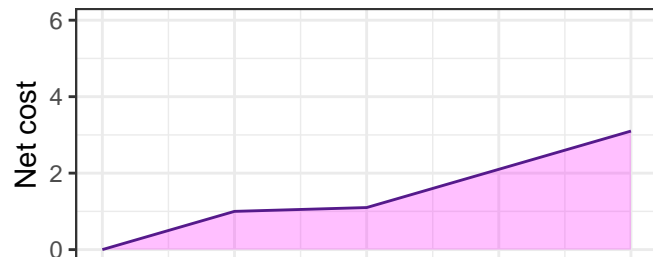
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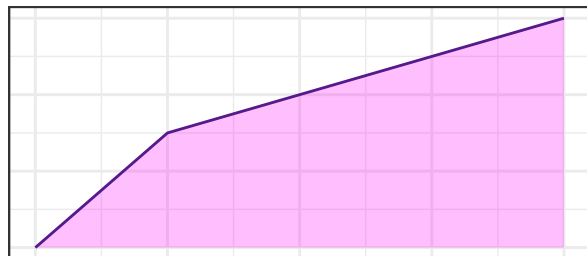
Human gut



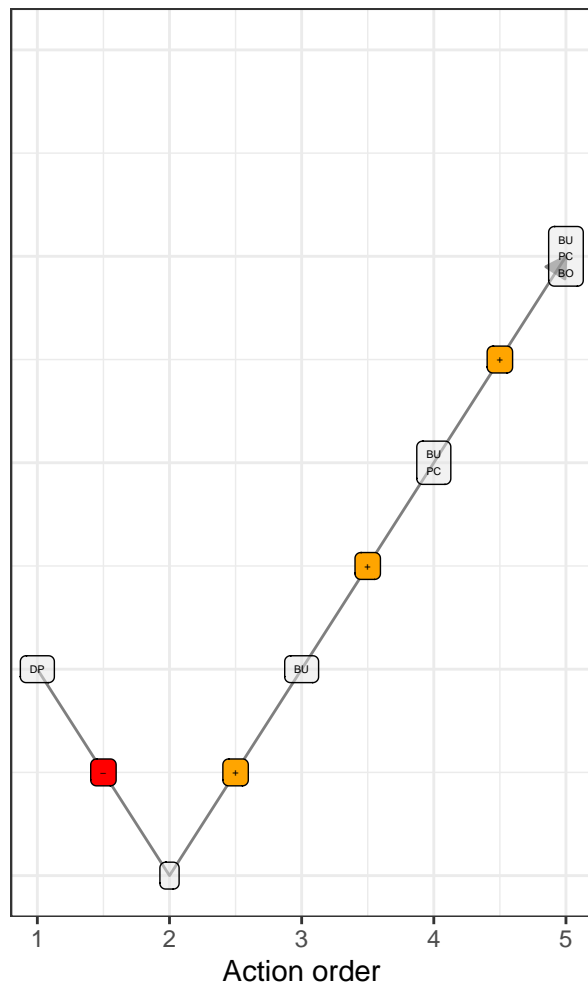
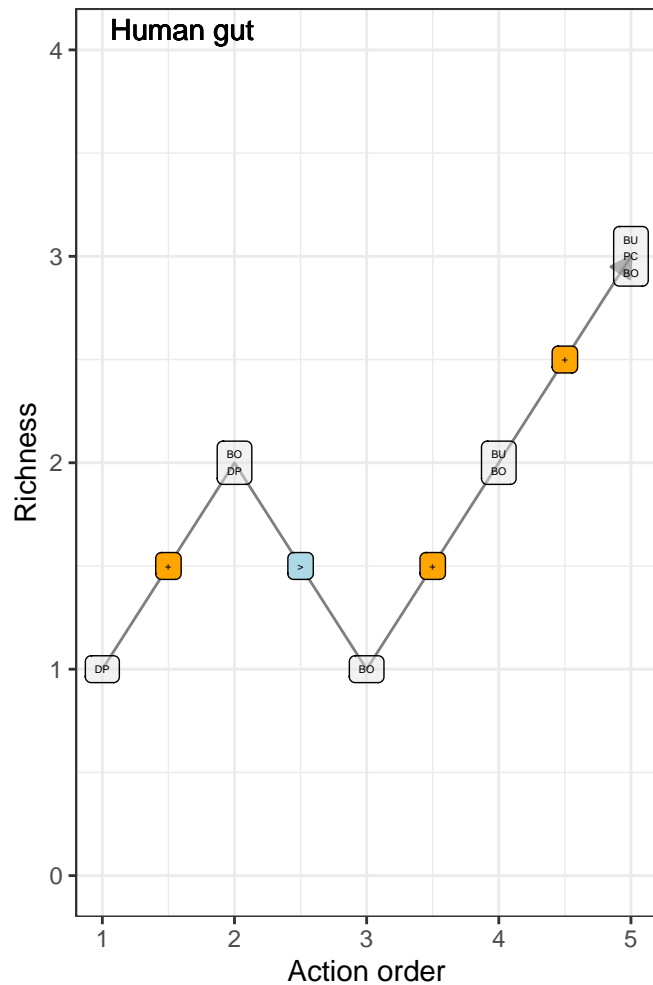
Optimal path



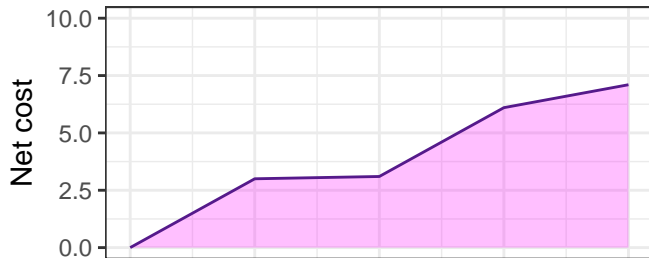
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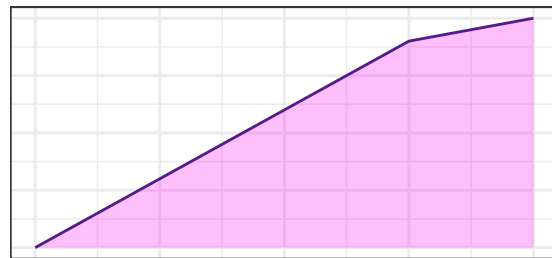
Human gut



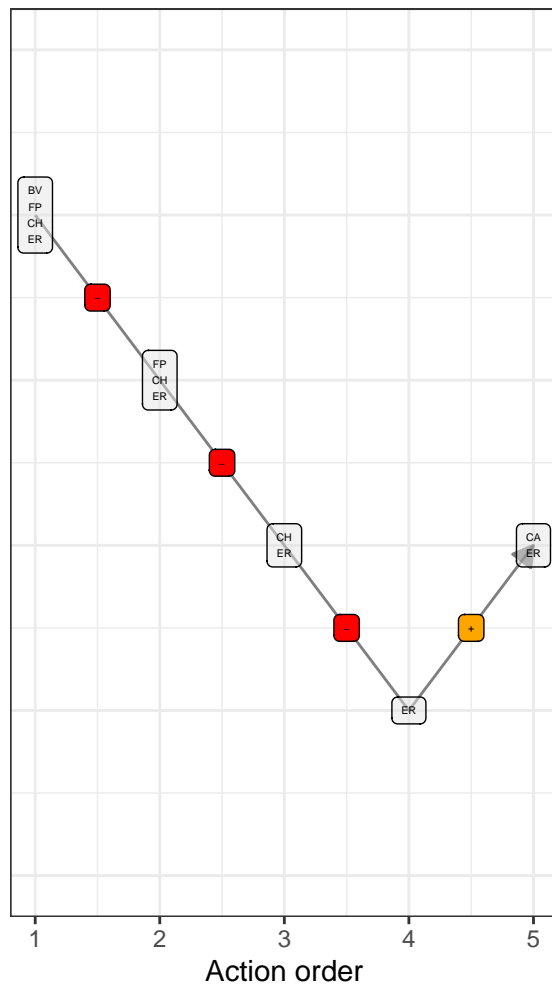
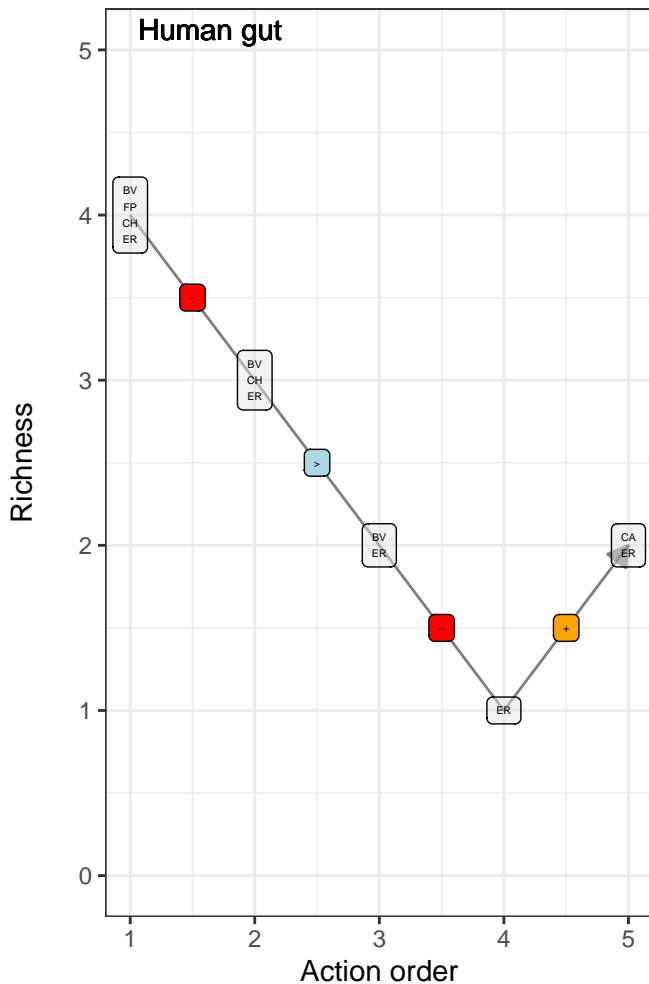
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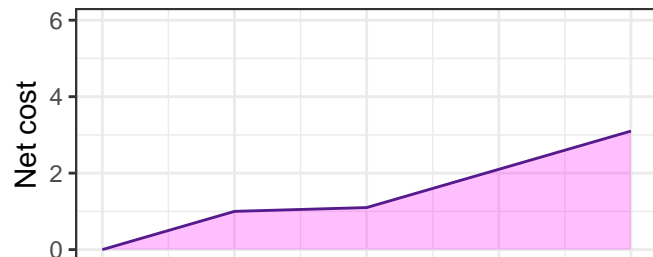
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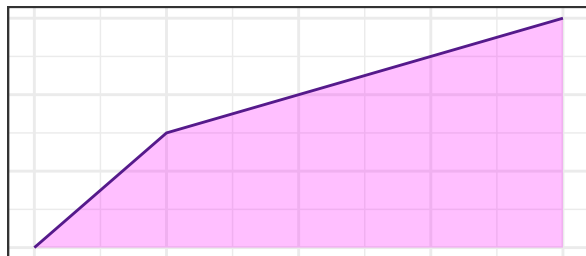
Human gut



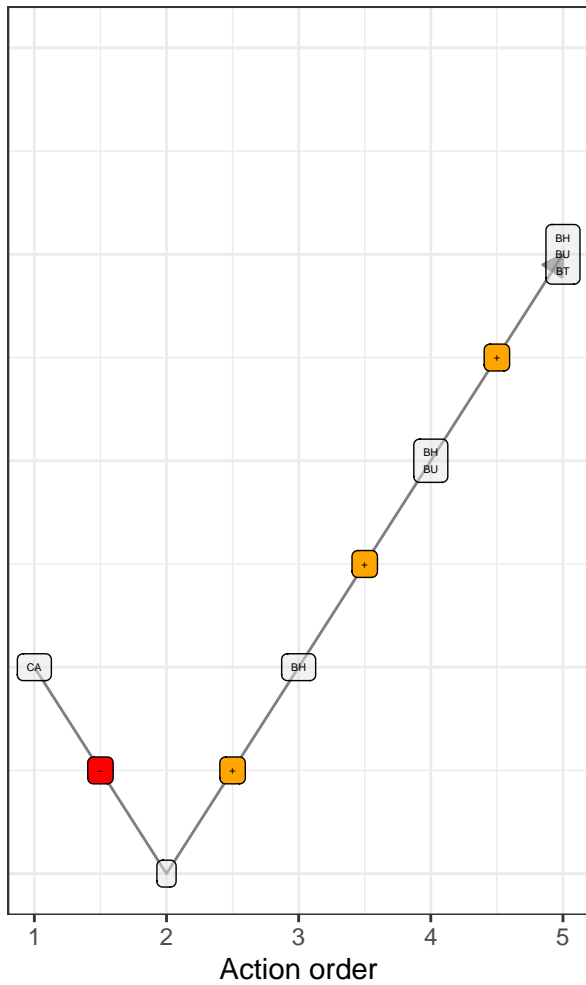
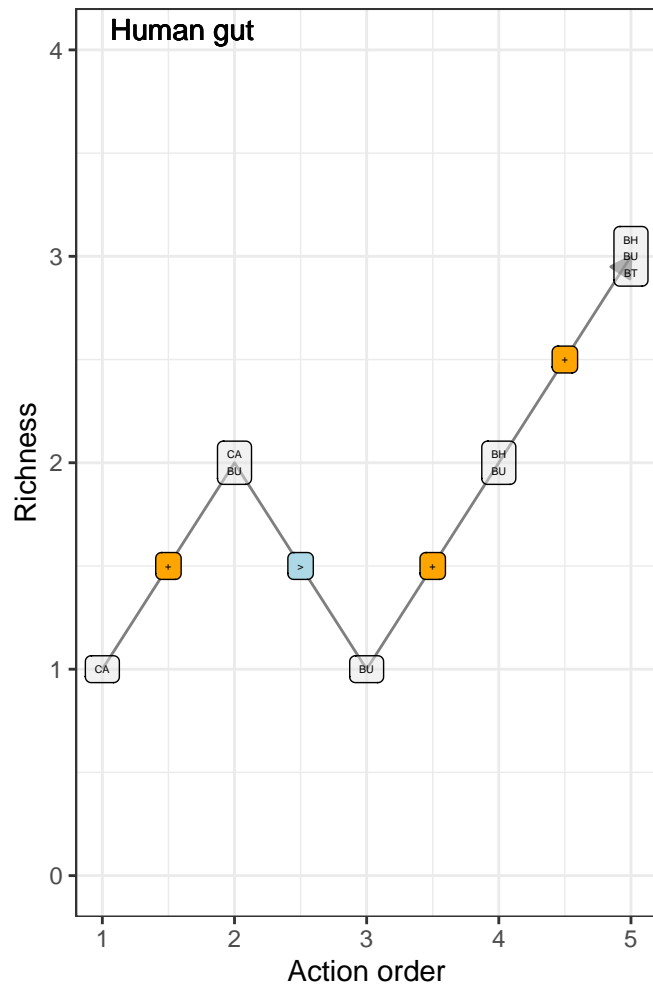
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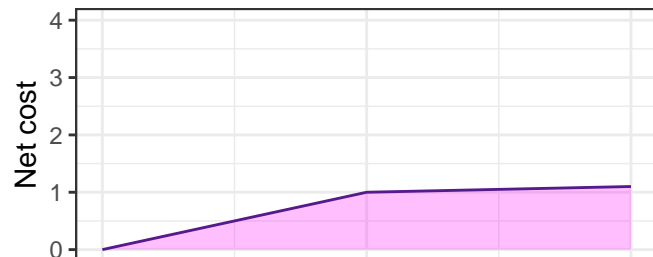
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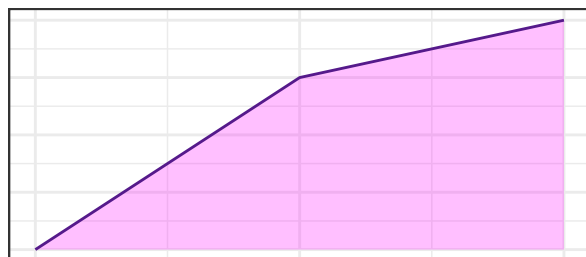
Human gut



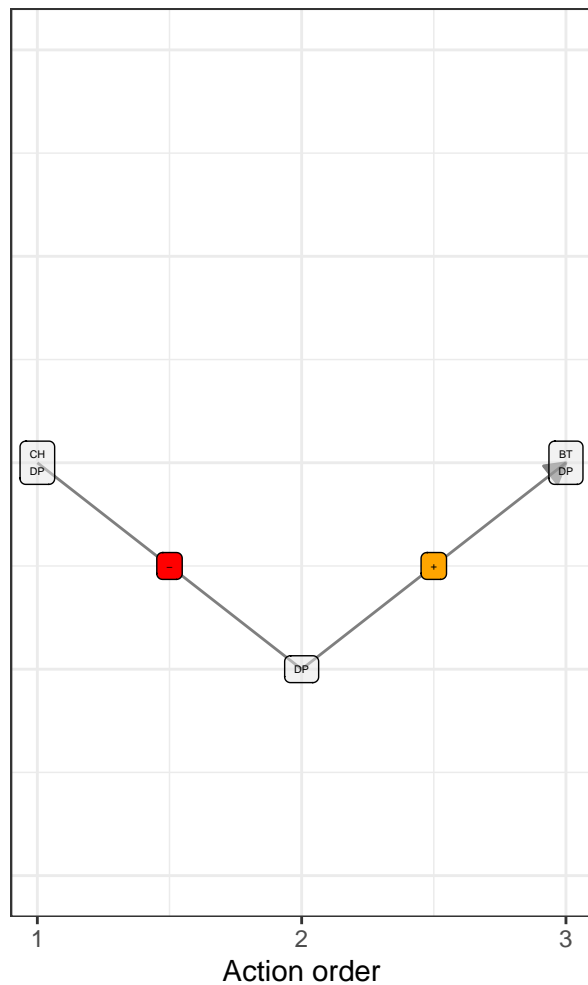
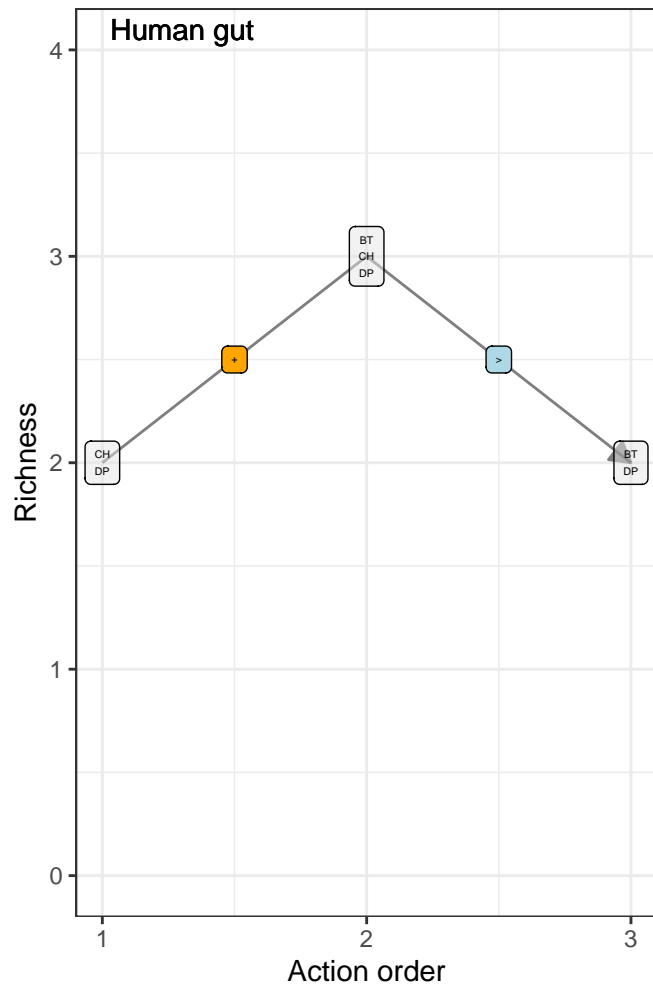
Optimal path



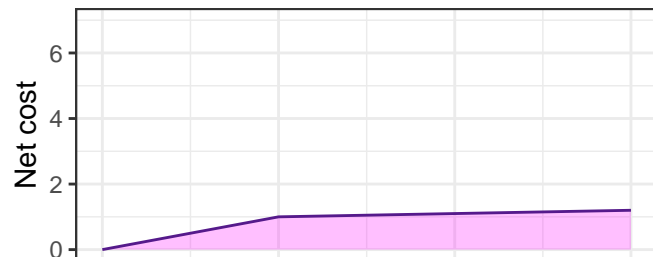
Nominal path



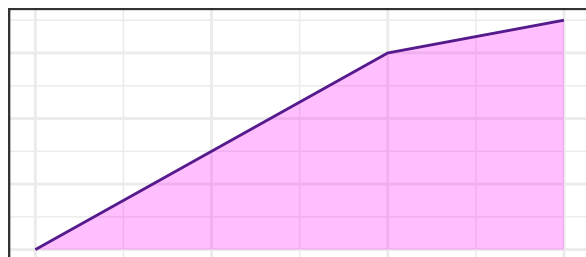
Human gut



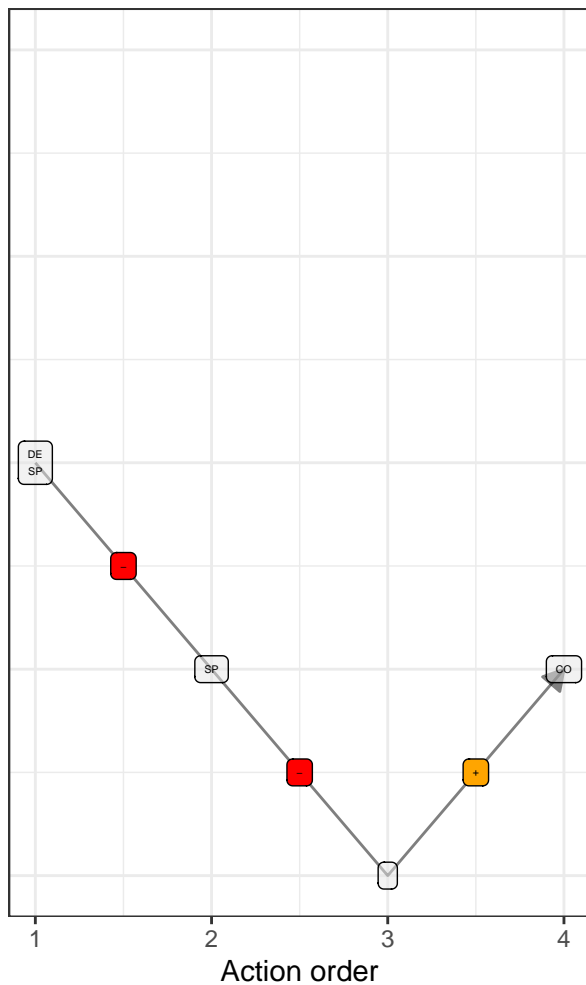
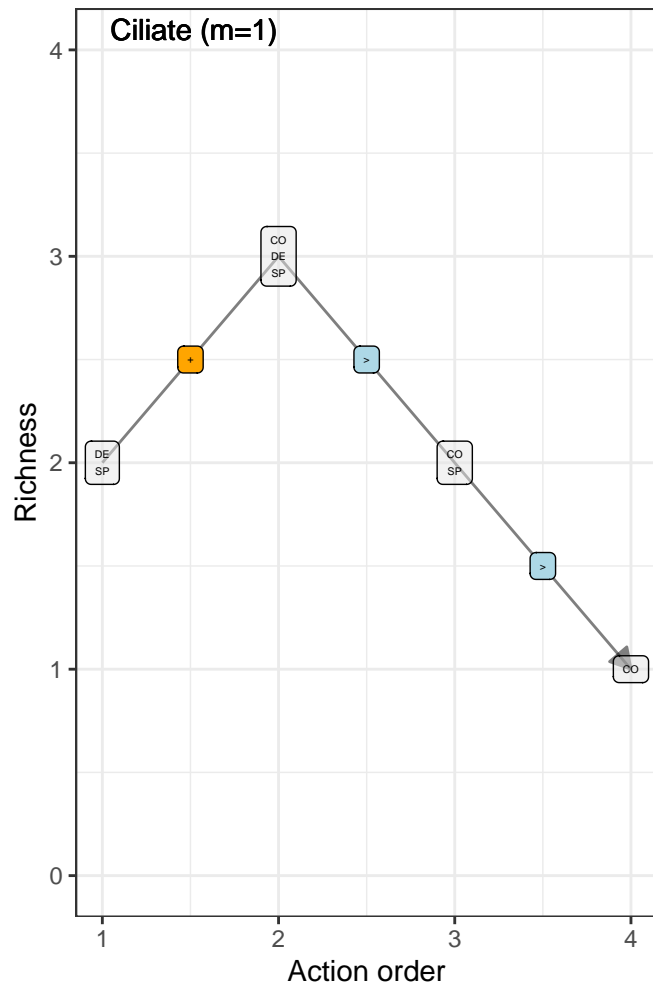
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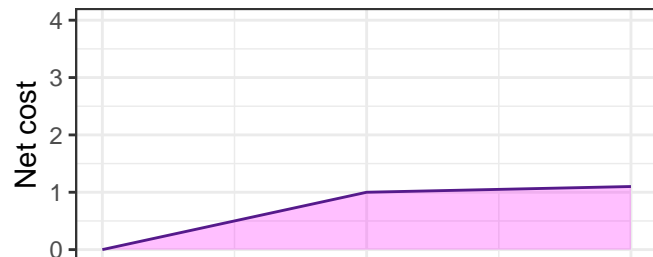
Nominal path



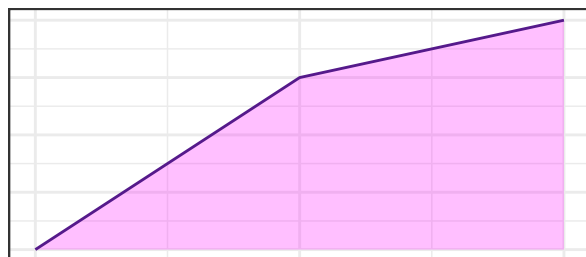
Ciliate (m=1)



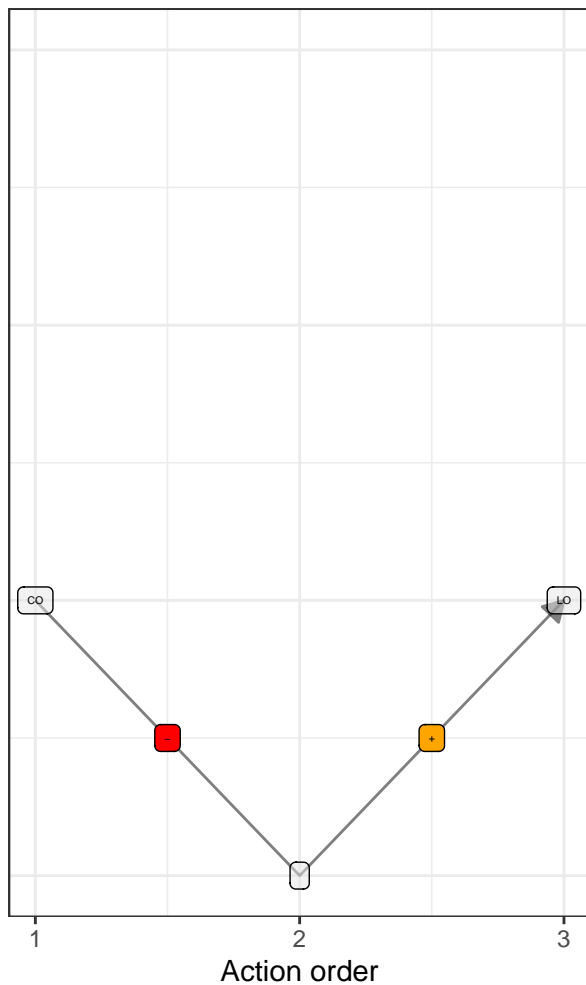
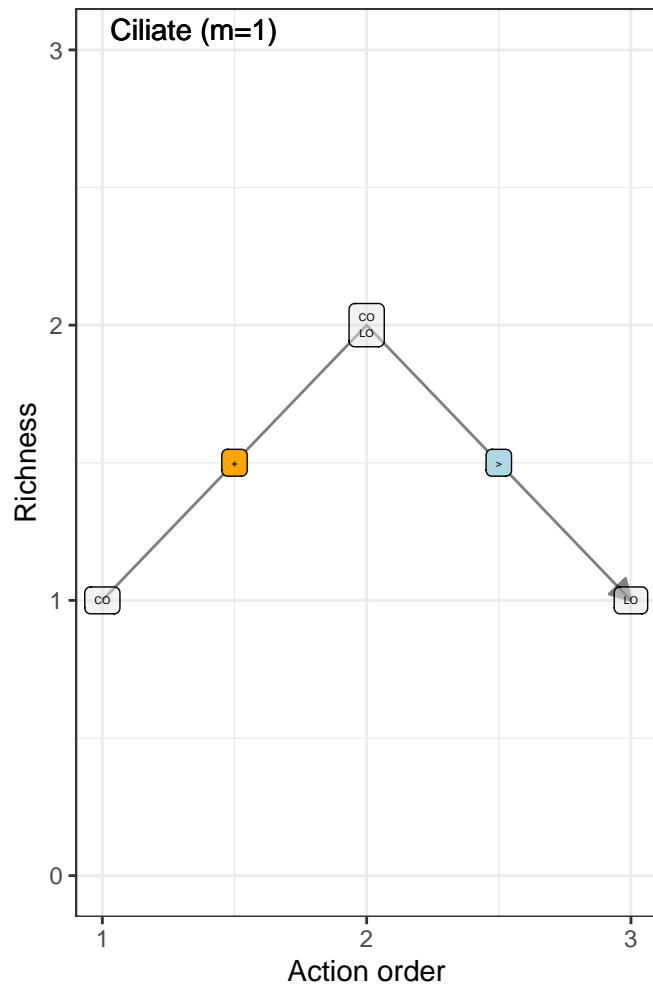
Optimal path



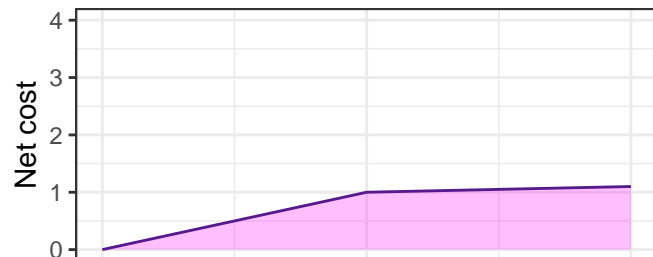
Nominal path



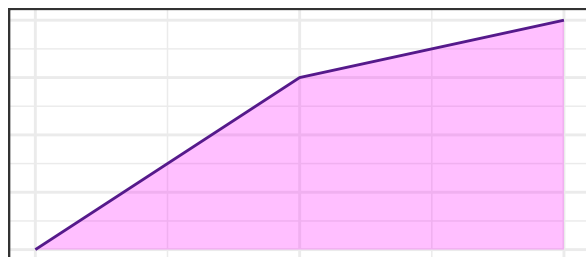
Ciliate (m=1)



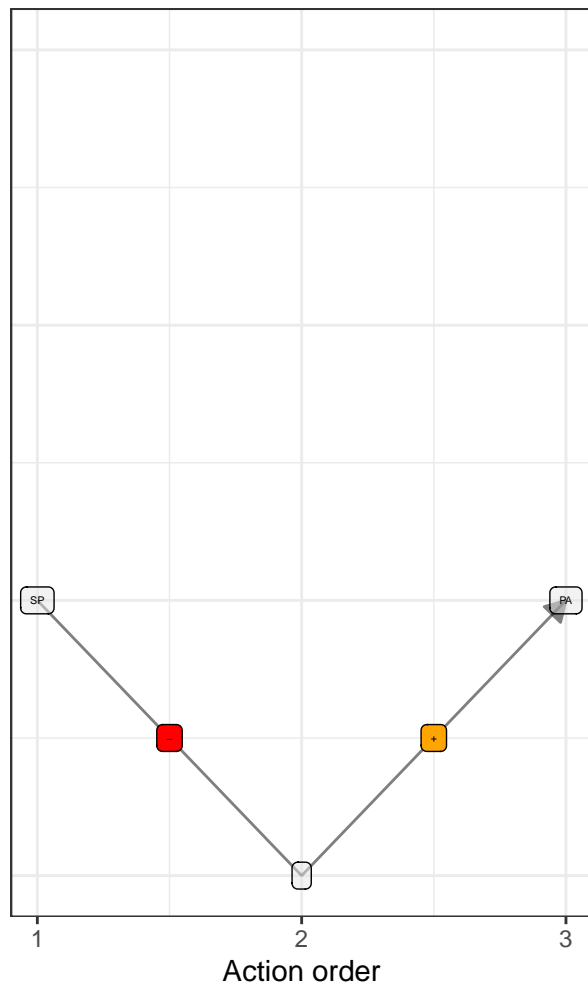
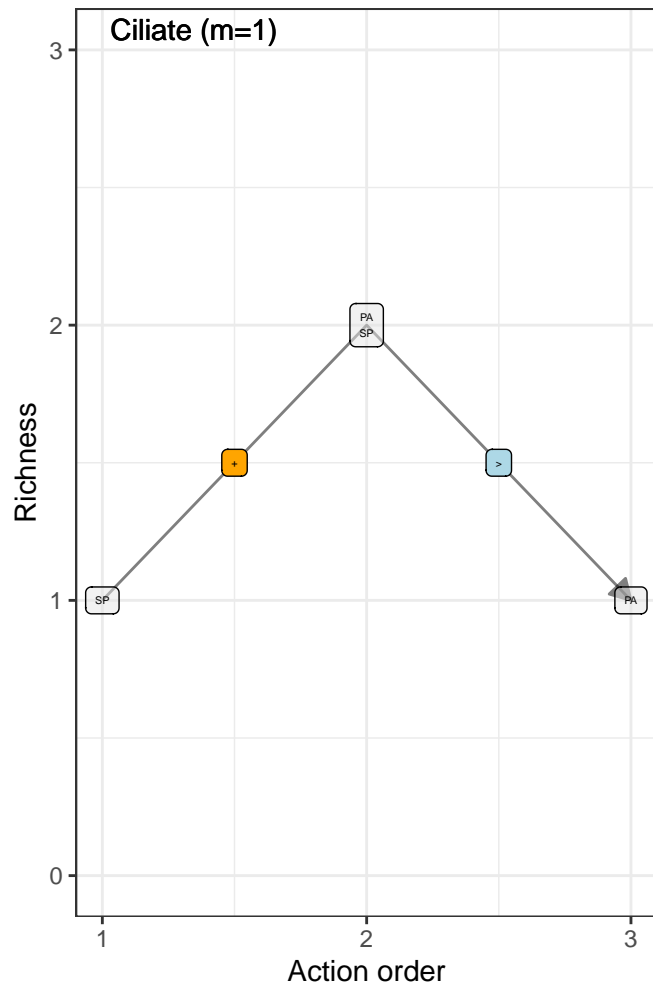
Optimal path



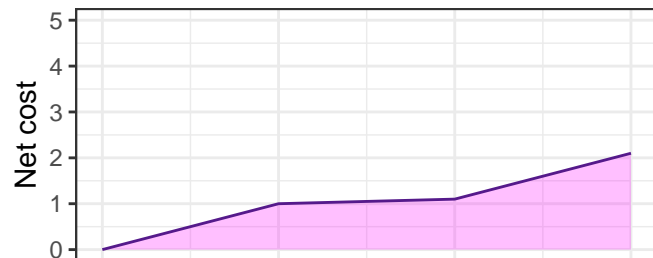
Nominal path



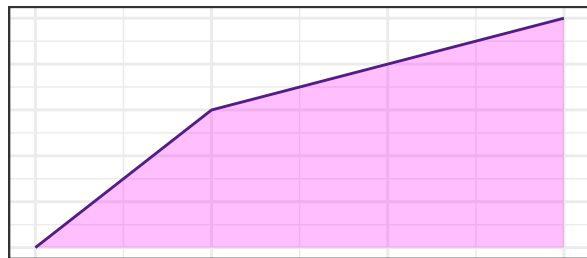
Ciliate (m=1)



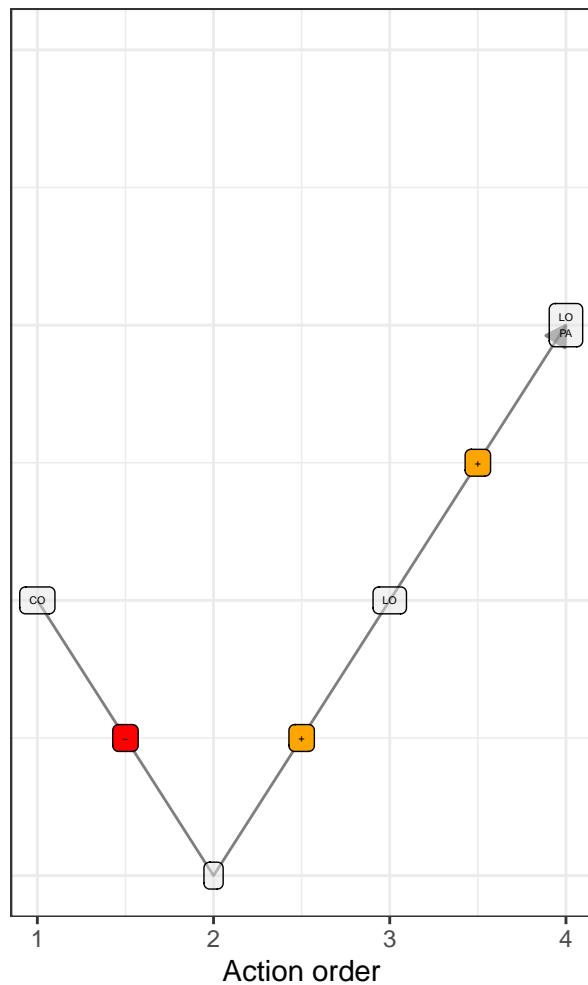
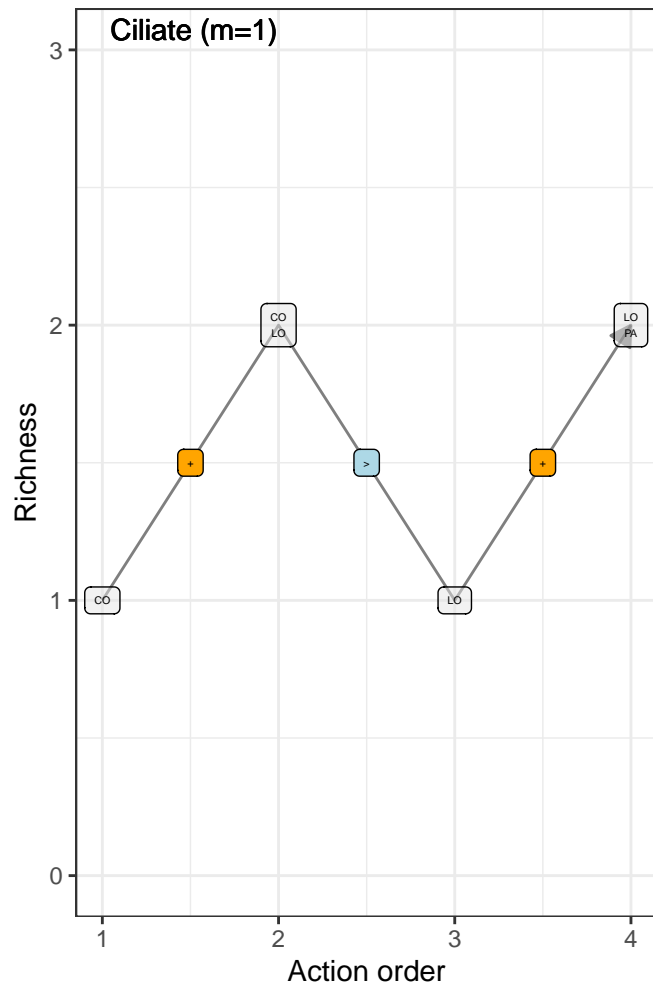
Optimal path



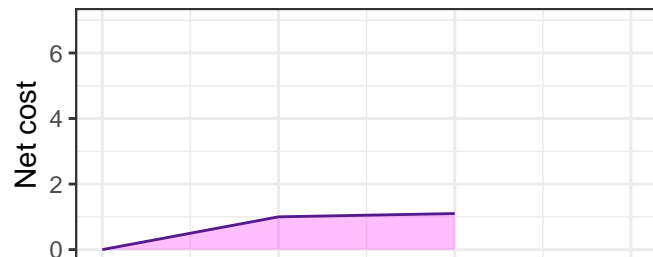
Nominal path



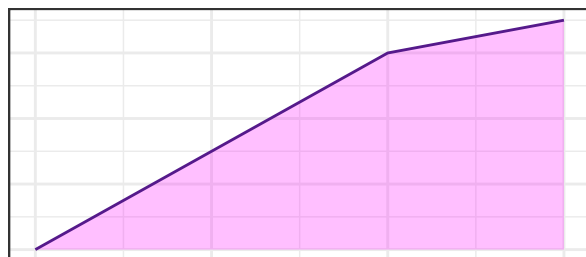
Ciliate (m=1)



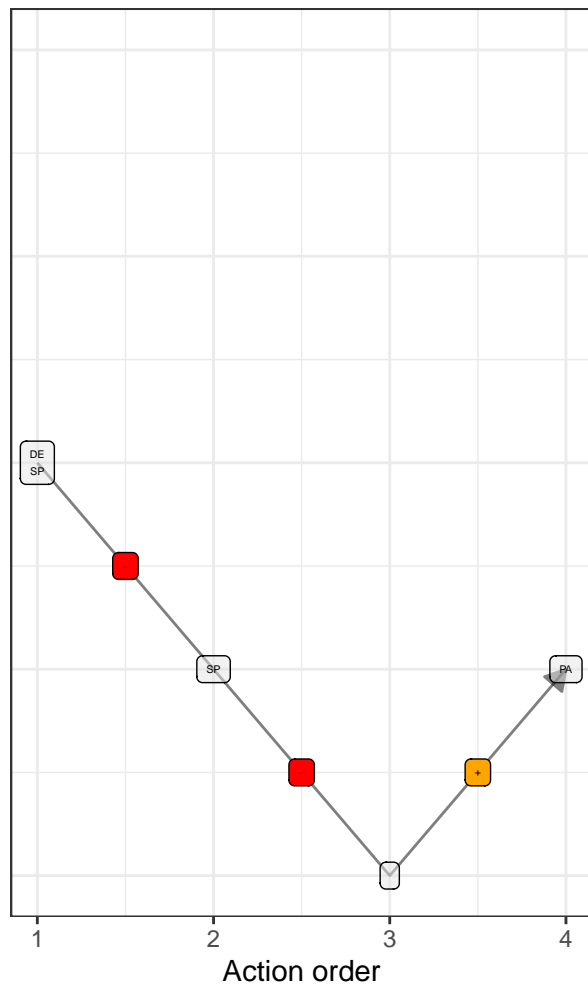
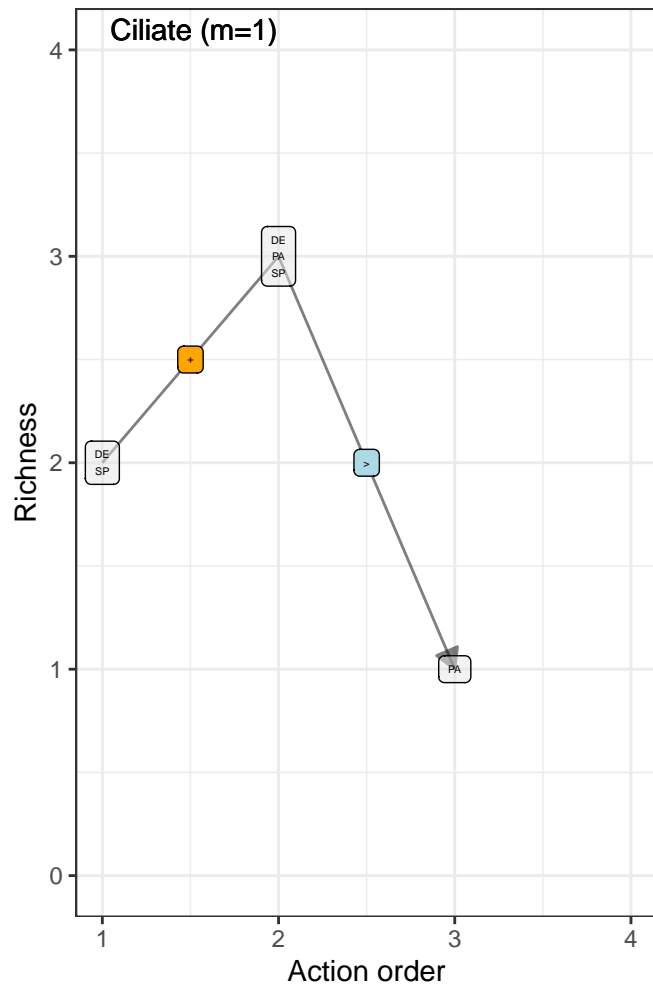
Optimal path



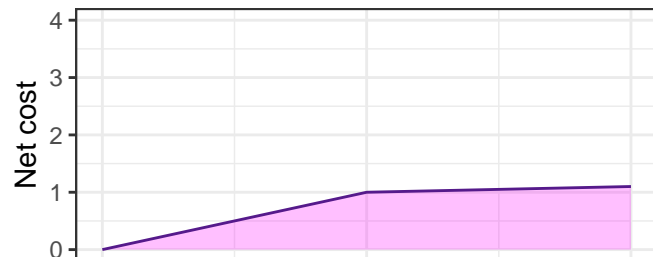
Nominal path



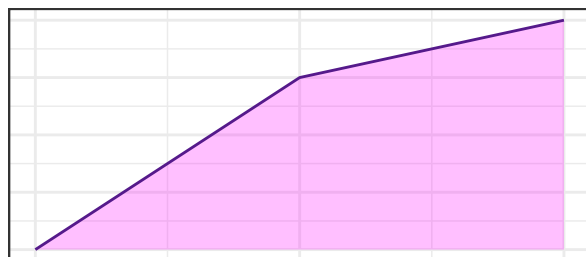
Ciliate (m=1)



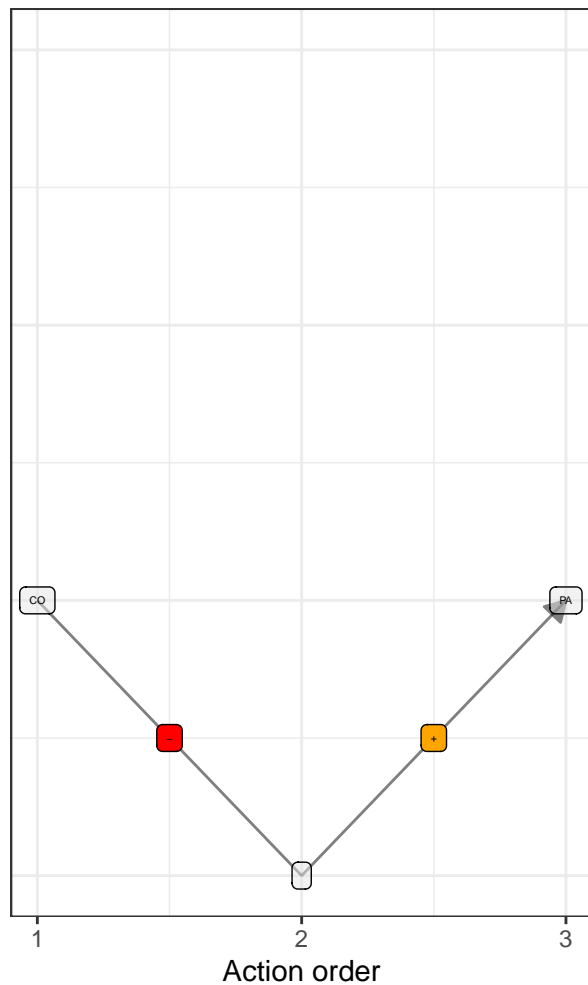
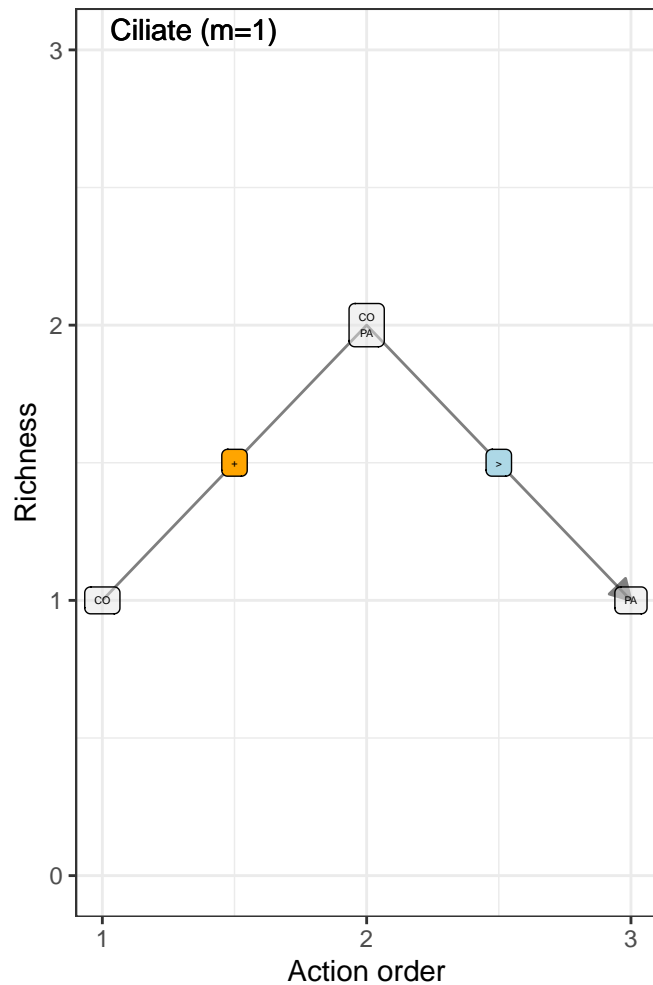
Optimal path



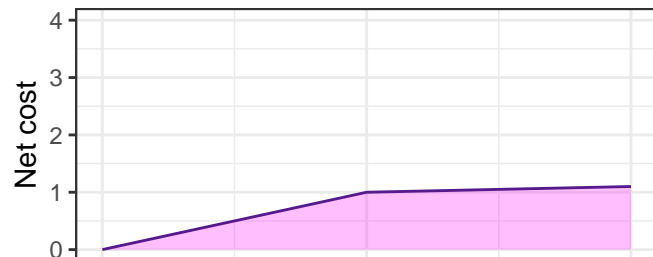
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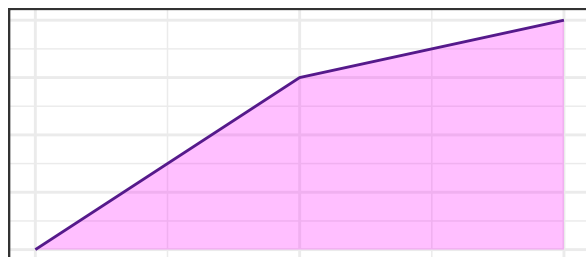
Ciliate (m=1)



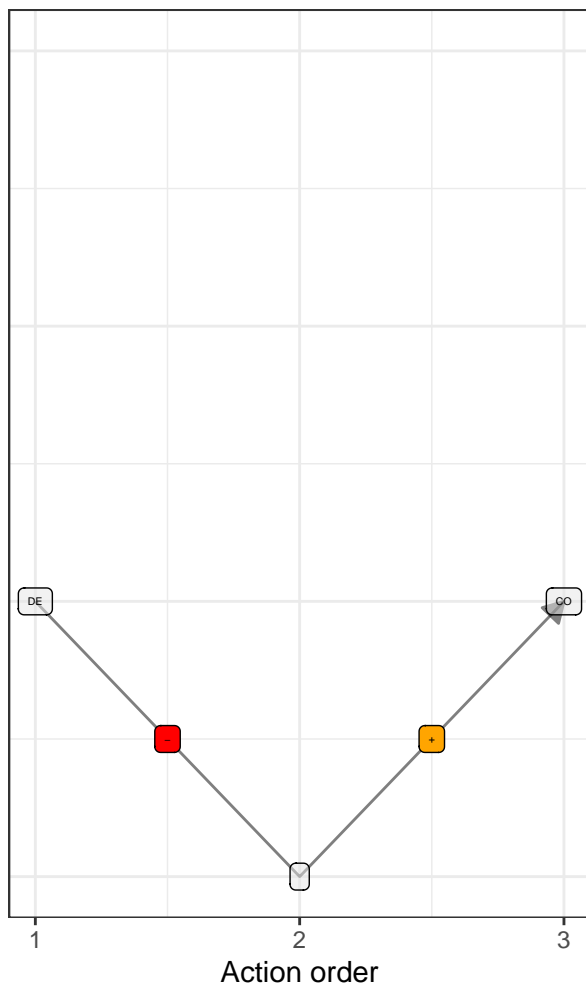
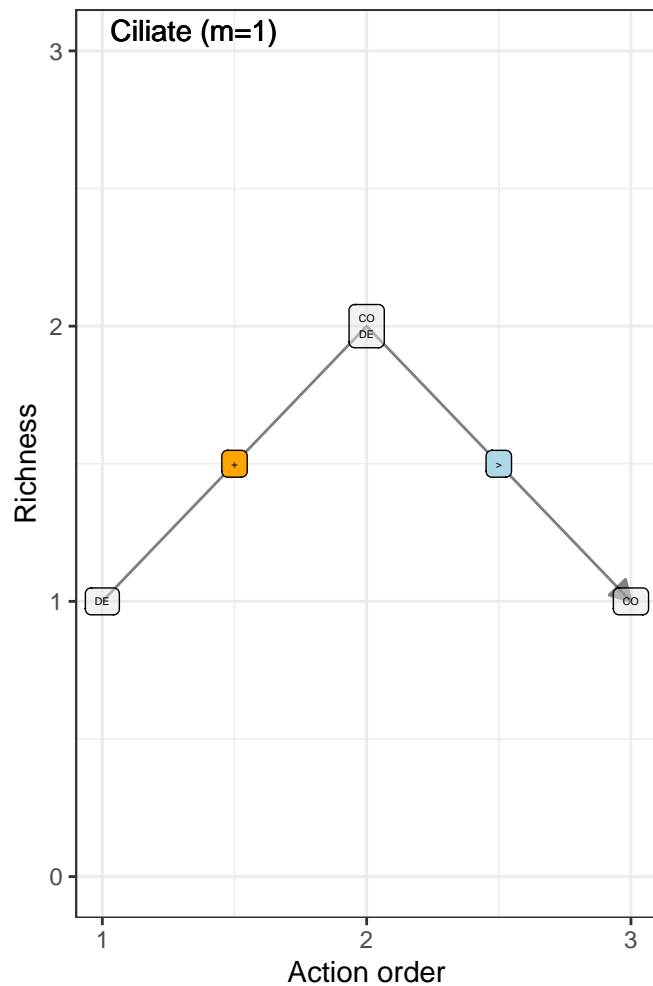
Optimal path



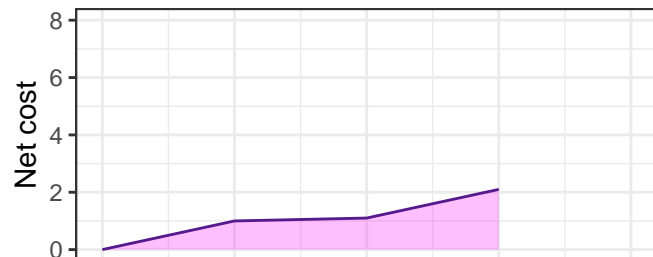
Nominal path



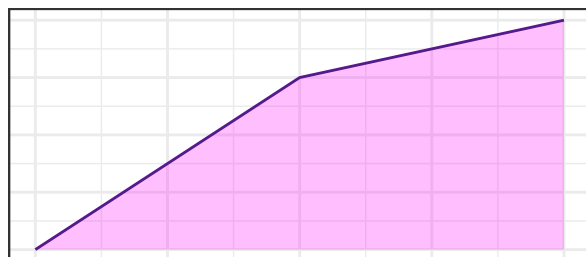
Ciliate (m=1)



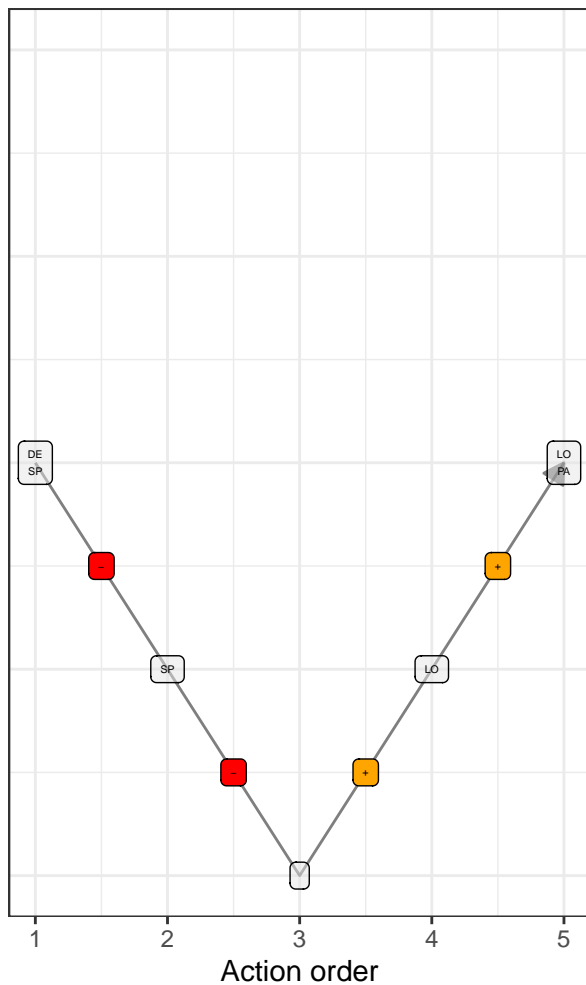
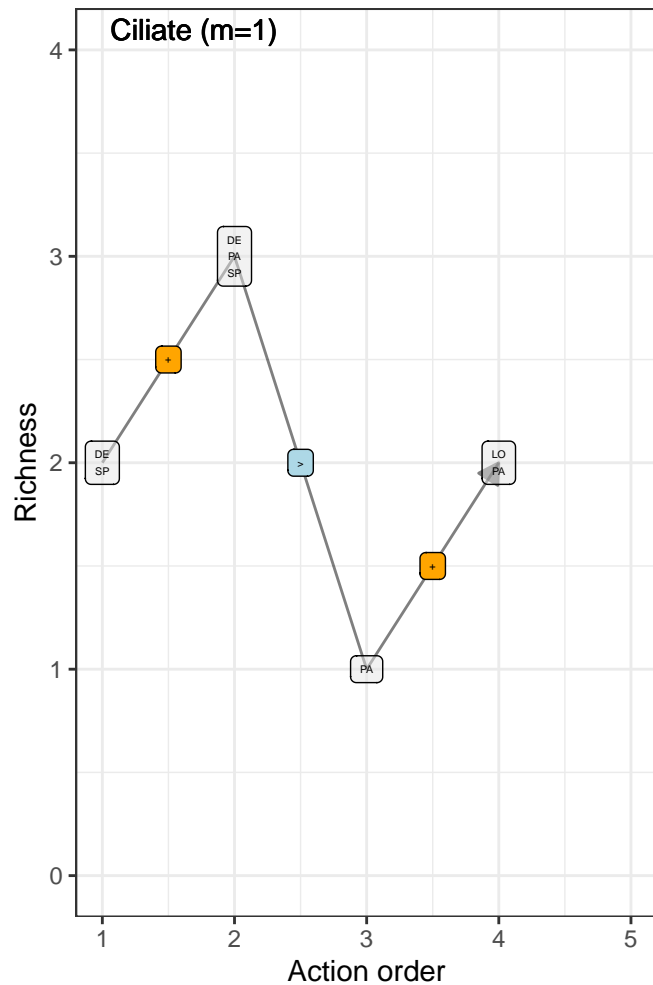
Optimal path



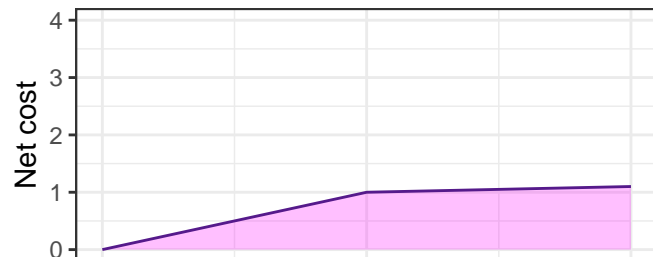
Nominal path



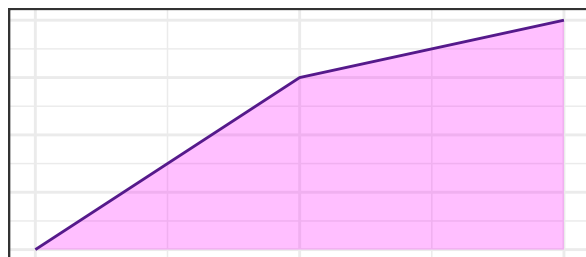
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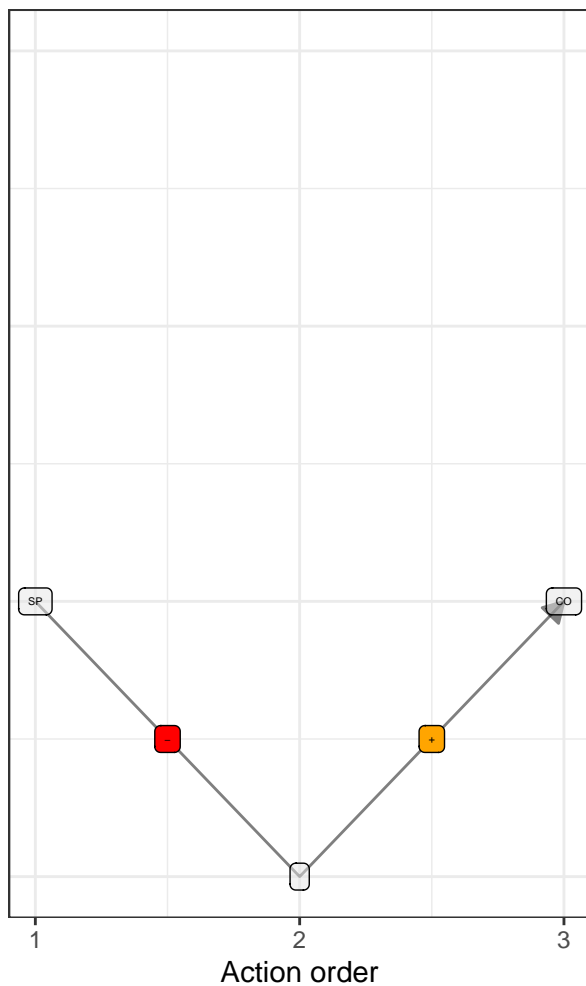
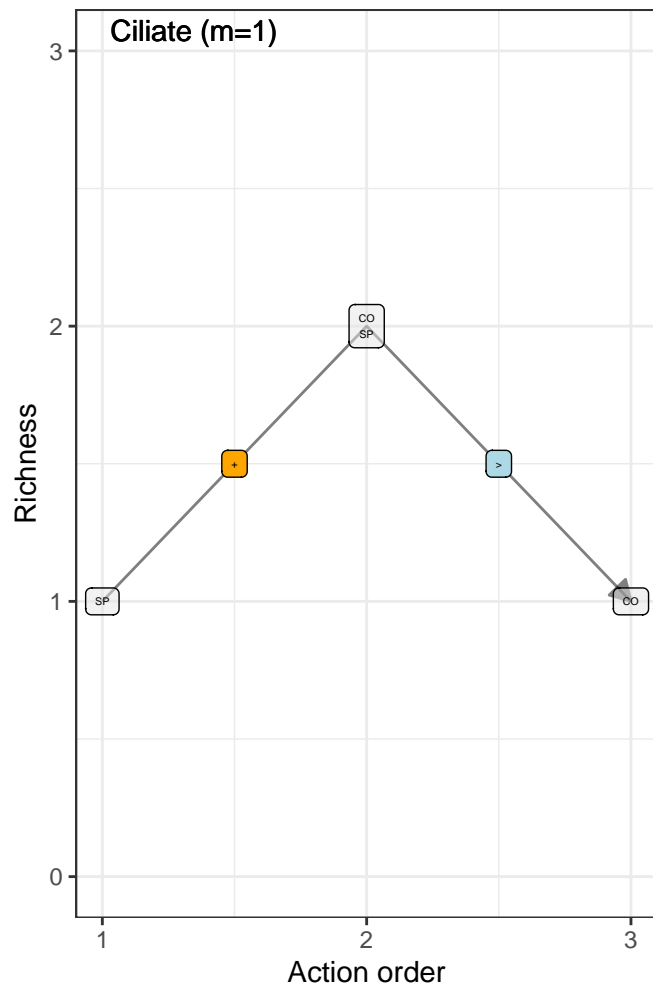
Optimal path



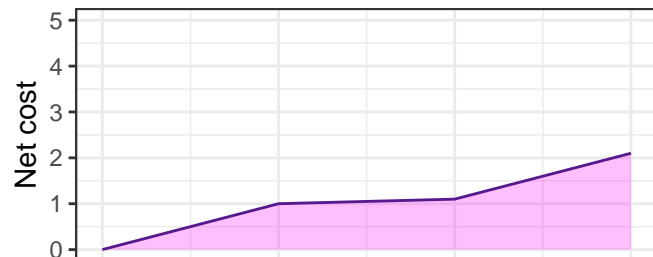
Nominal path



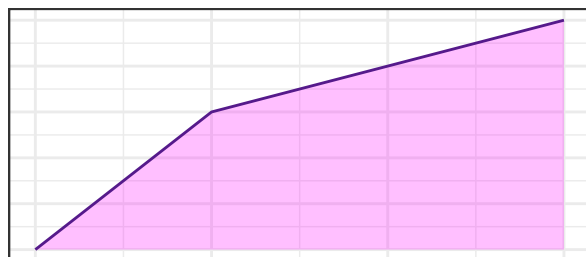
Ciliate (m=1)



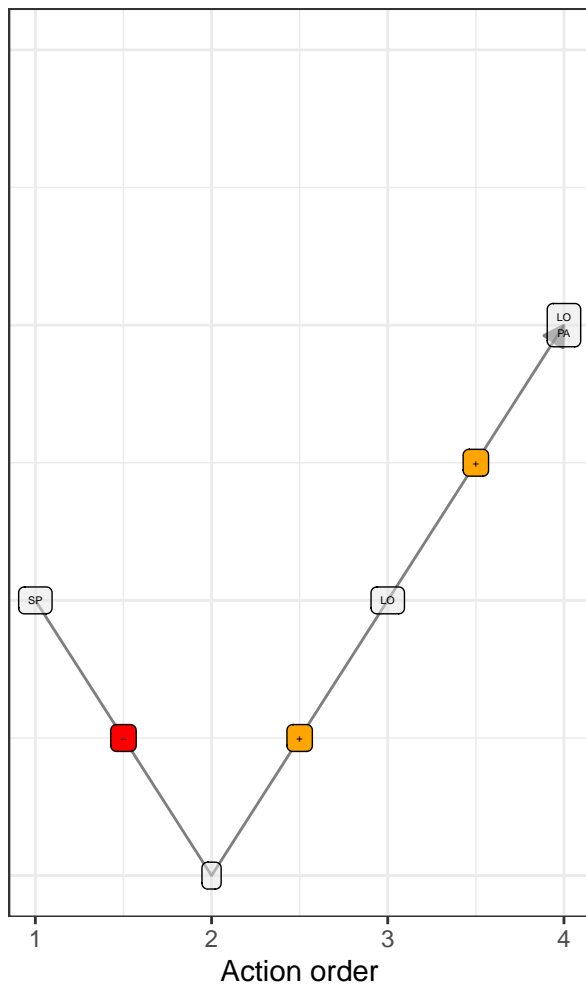
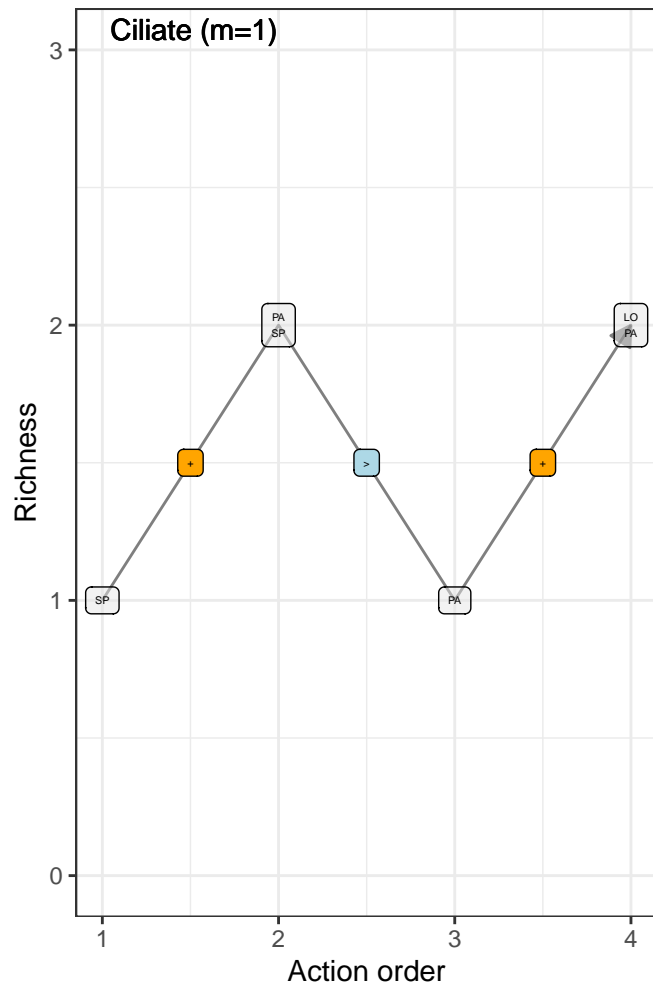
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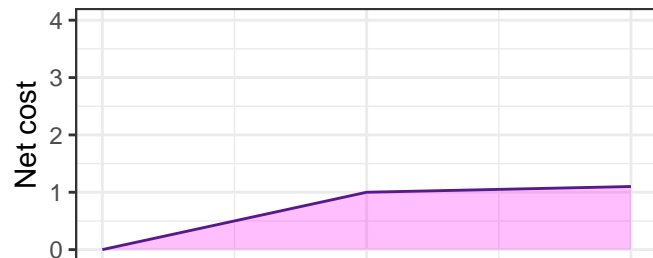
Nominal path



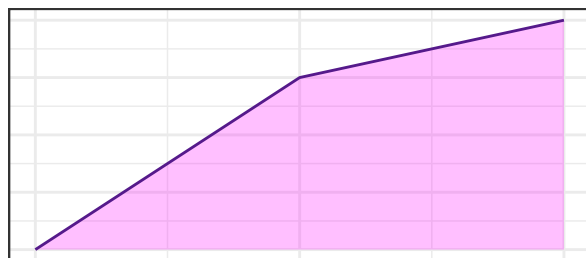
Ciliate (m=1)



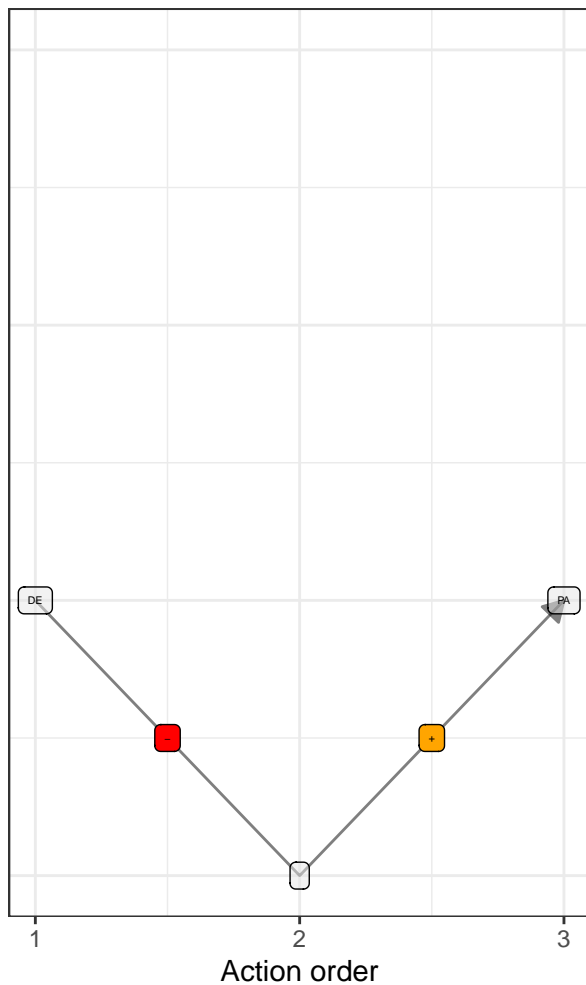
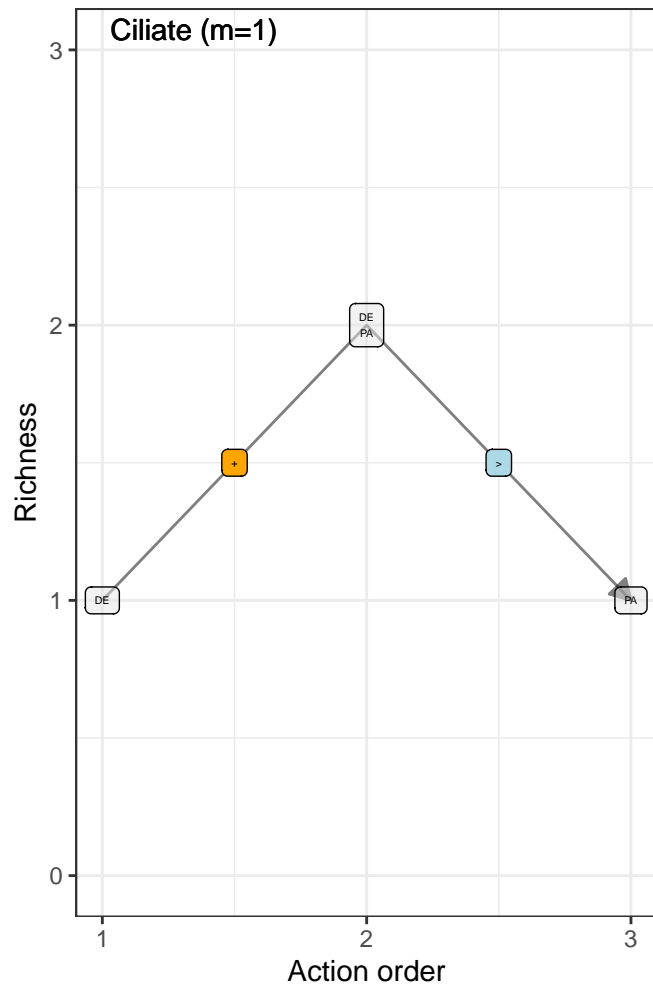
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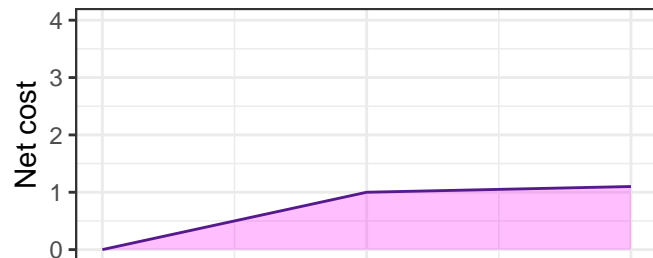
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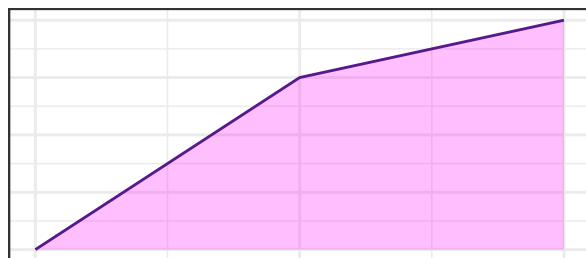
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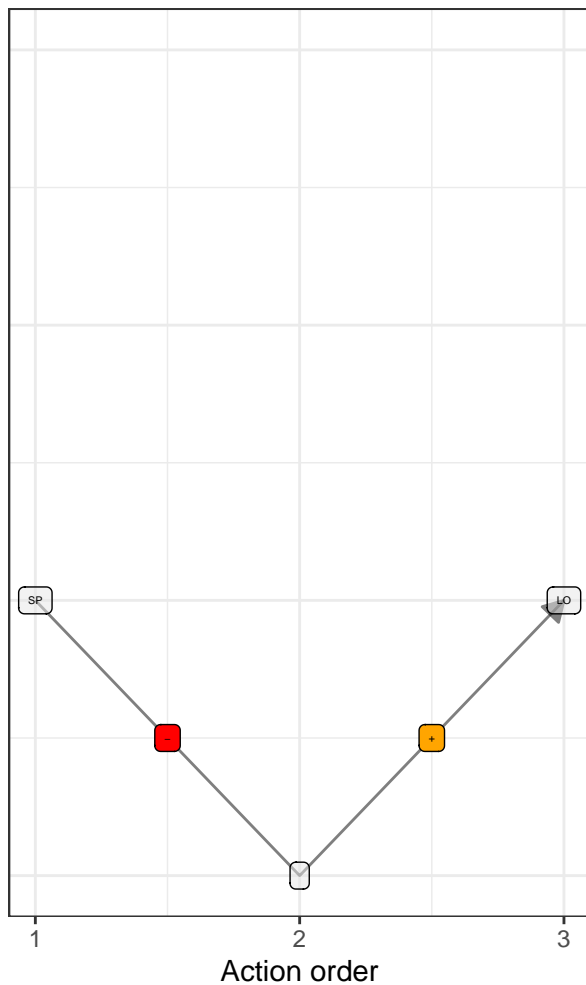
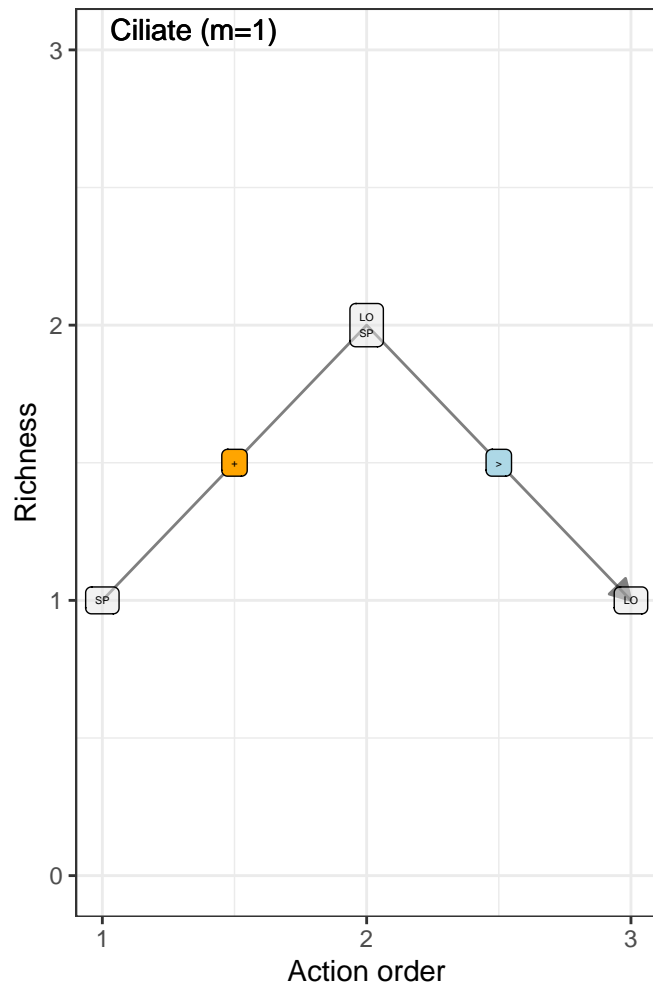
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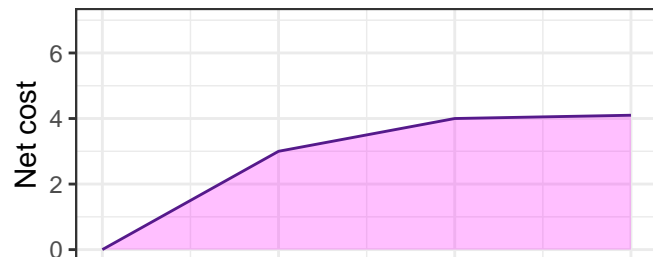
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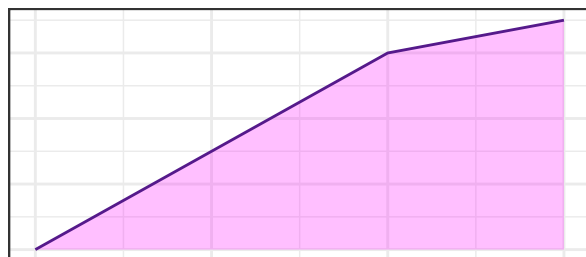
Ciliate (m=1)



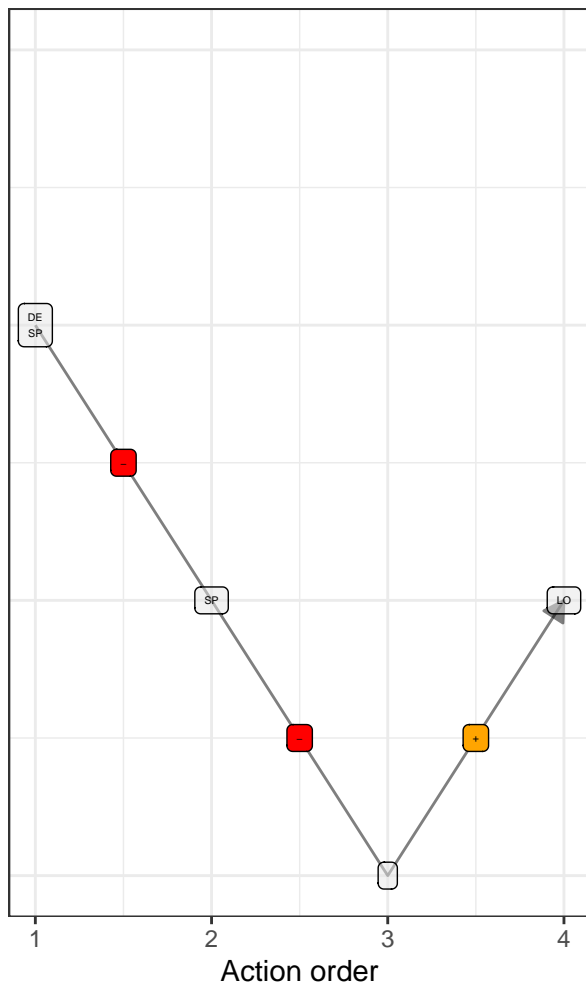
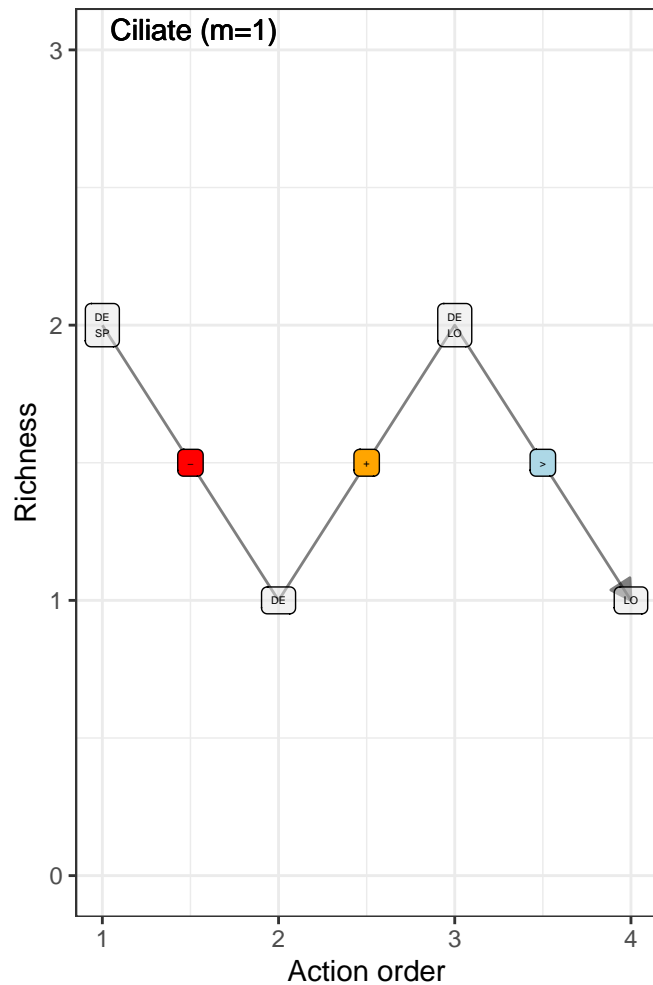
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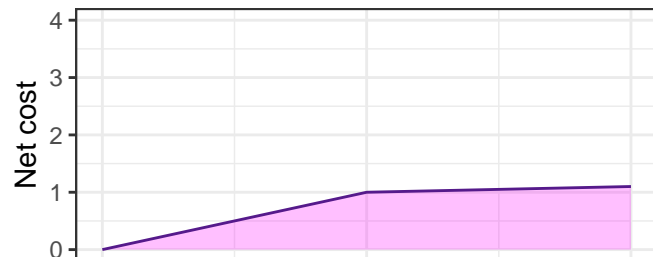
Nominal path



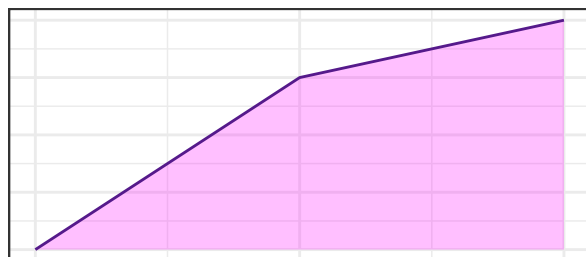
Ciliate (m=1)



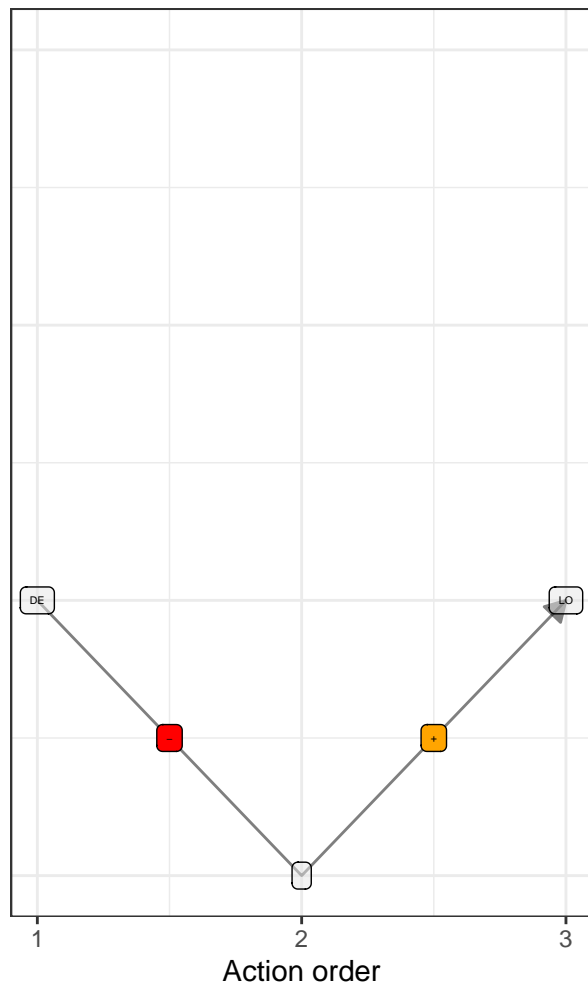
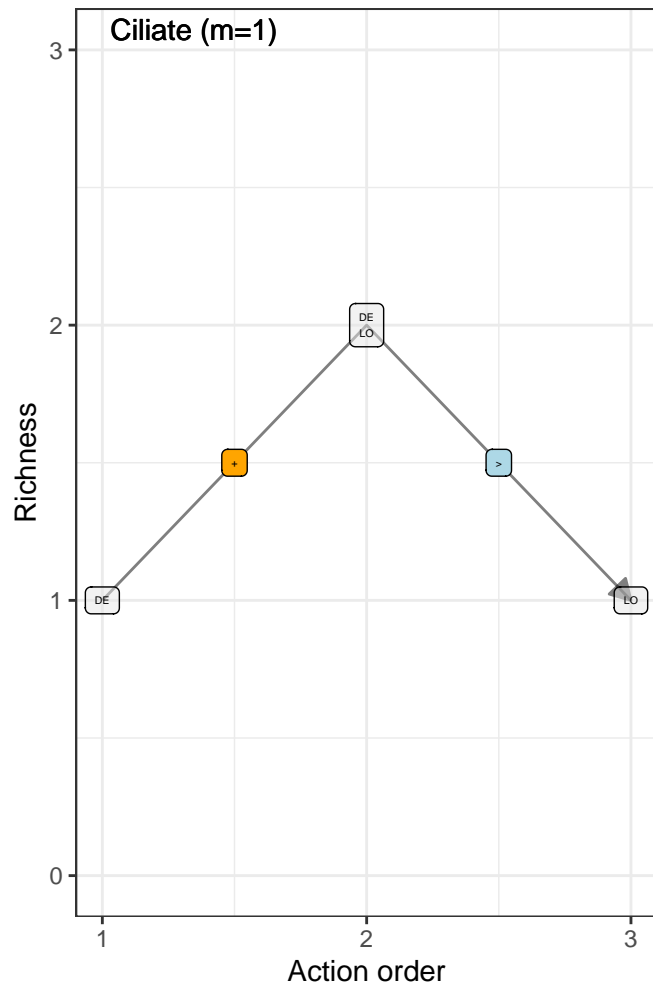
Optimal path



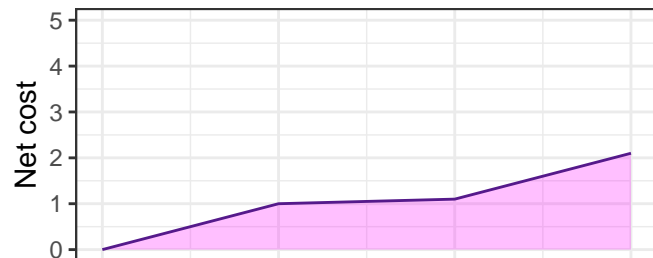
Nominal path



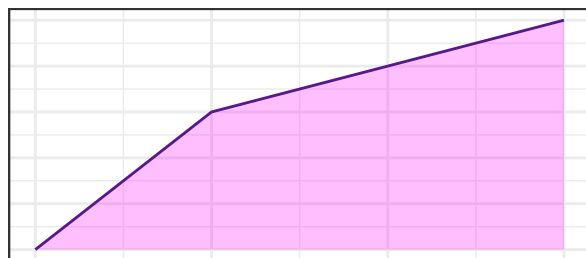
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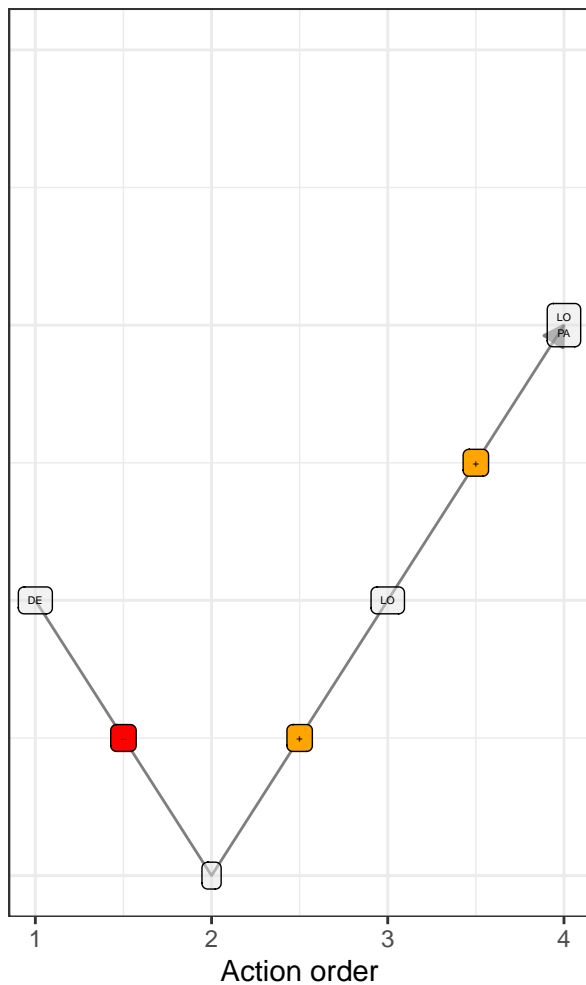
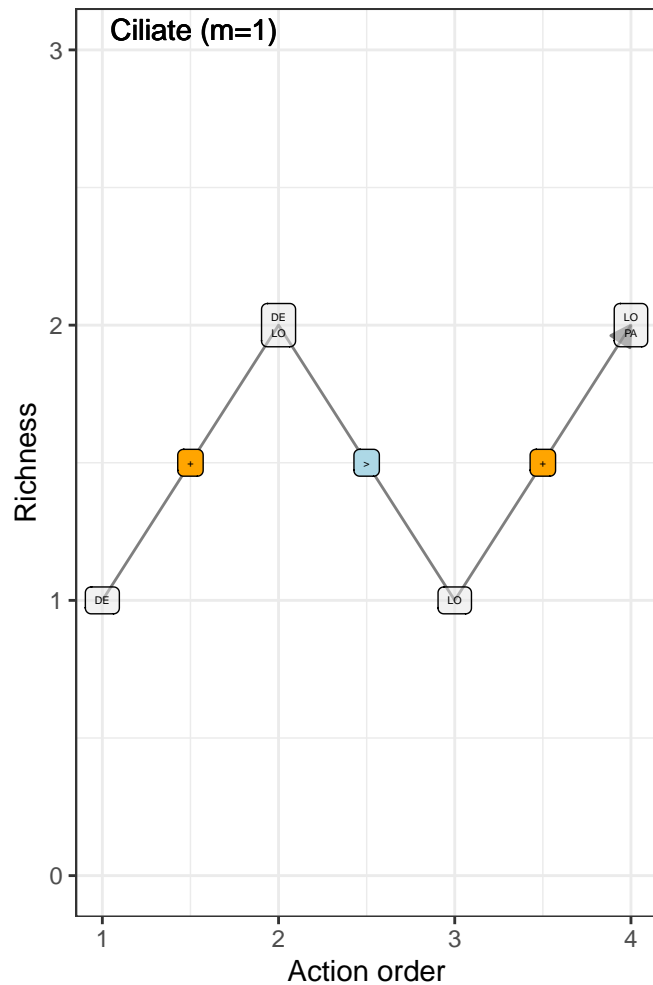
Optimal path



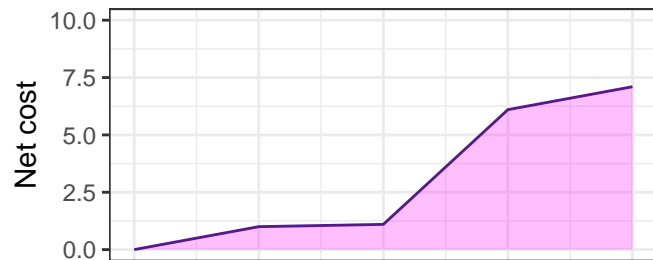
Nominal path



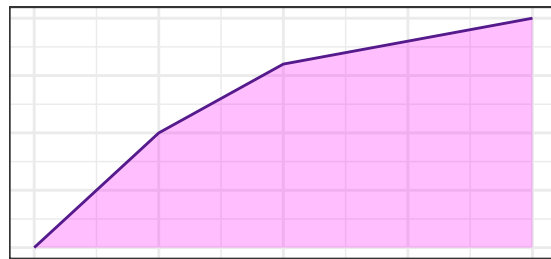
Ciliate (m=1)



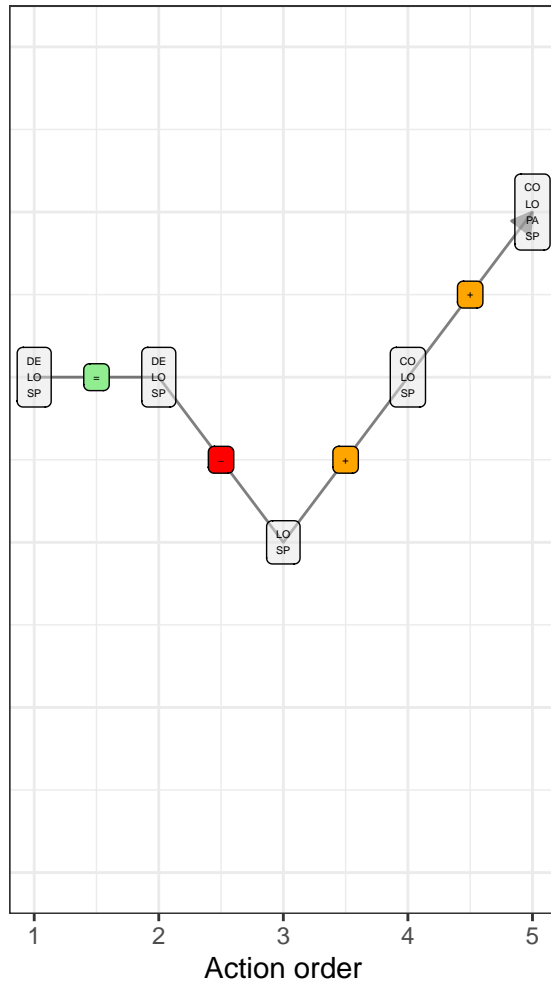
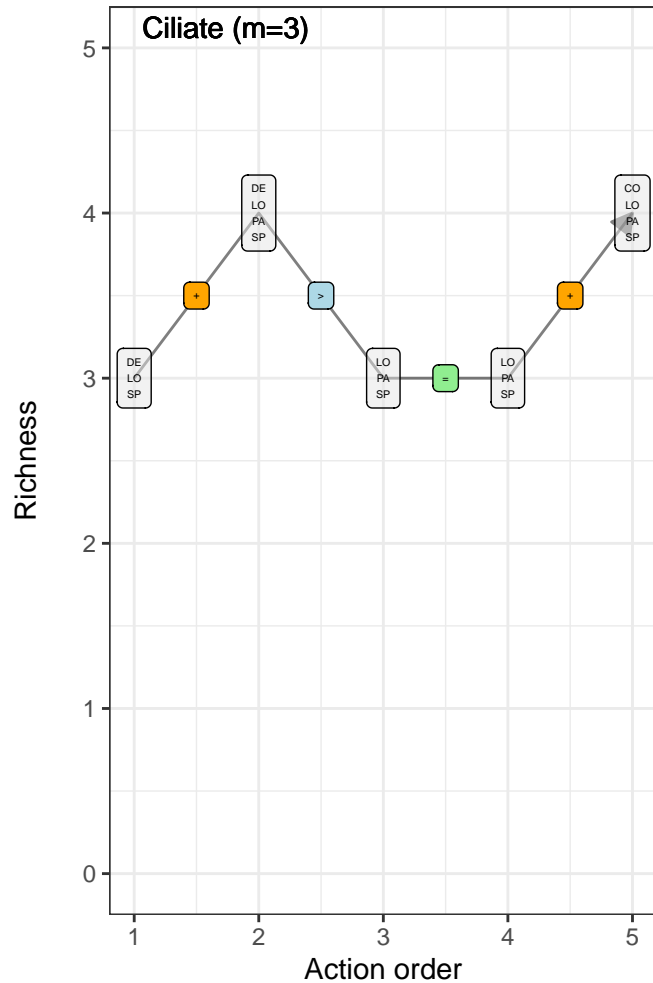
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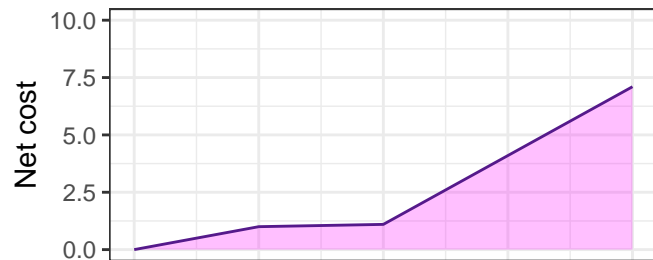
Nominal path



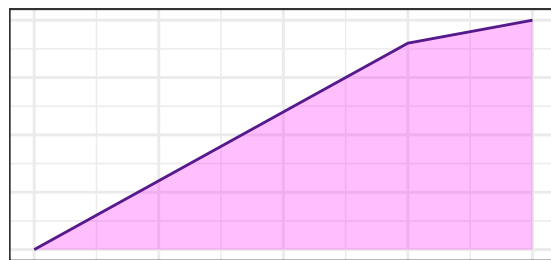
Ciliate (m=3)



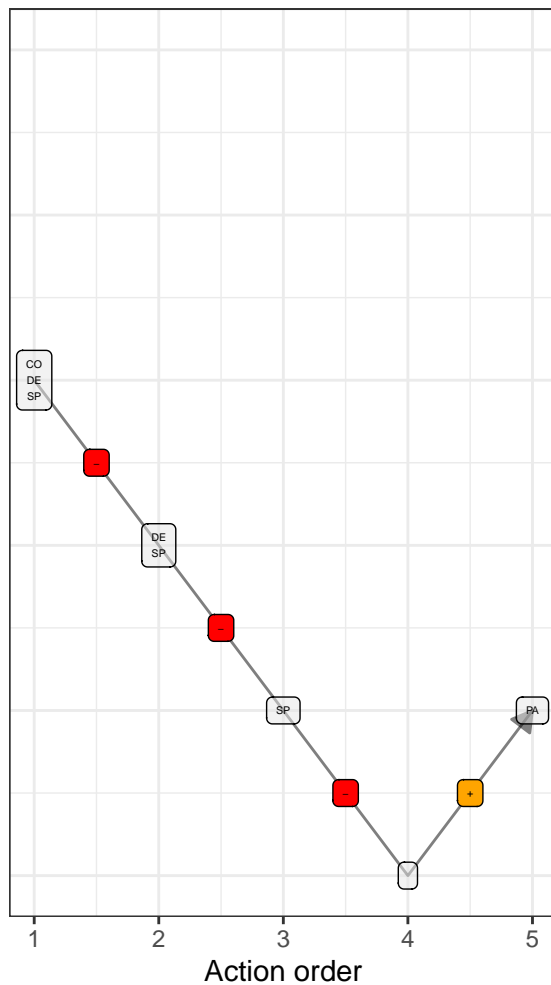
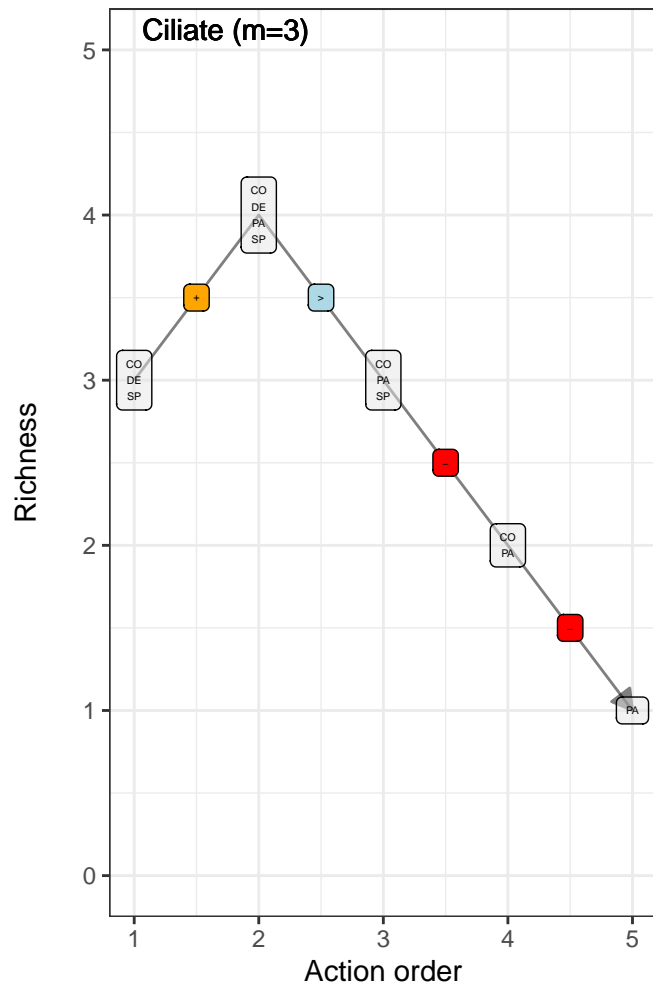
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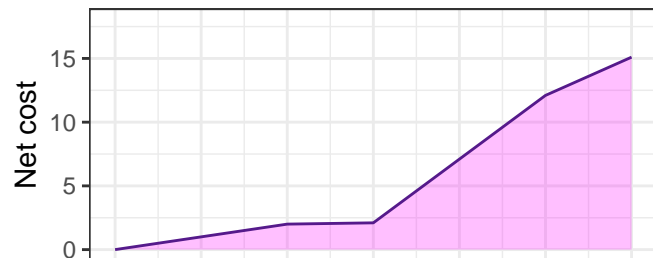
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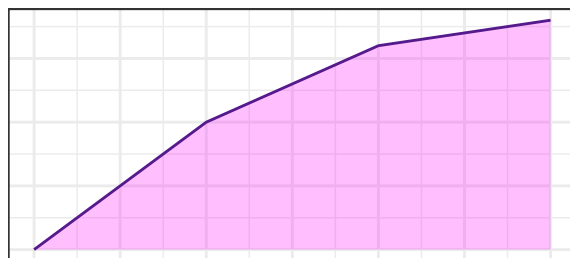
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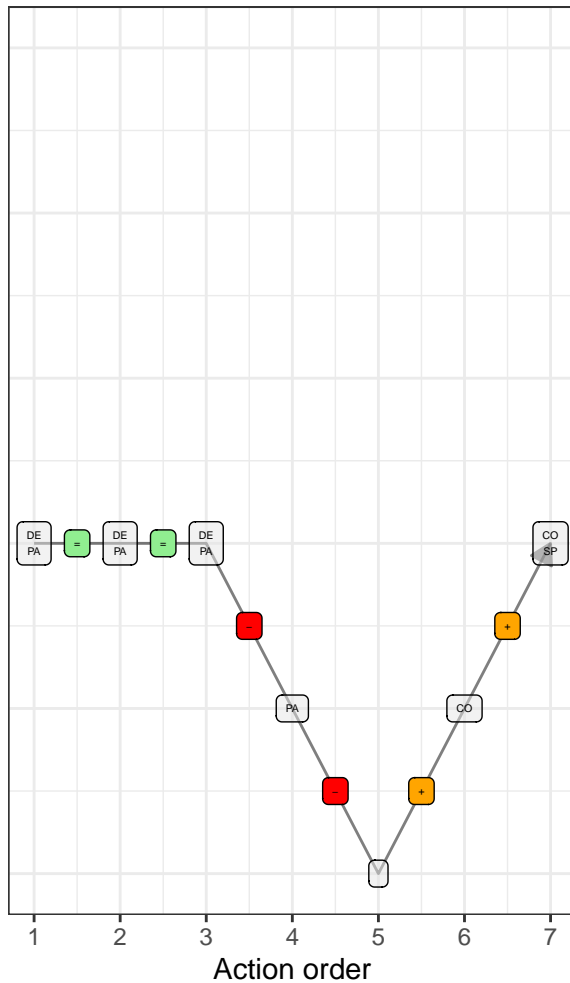
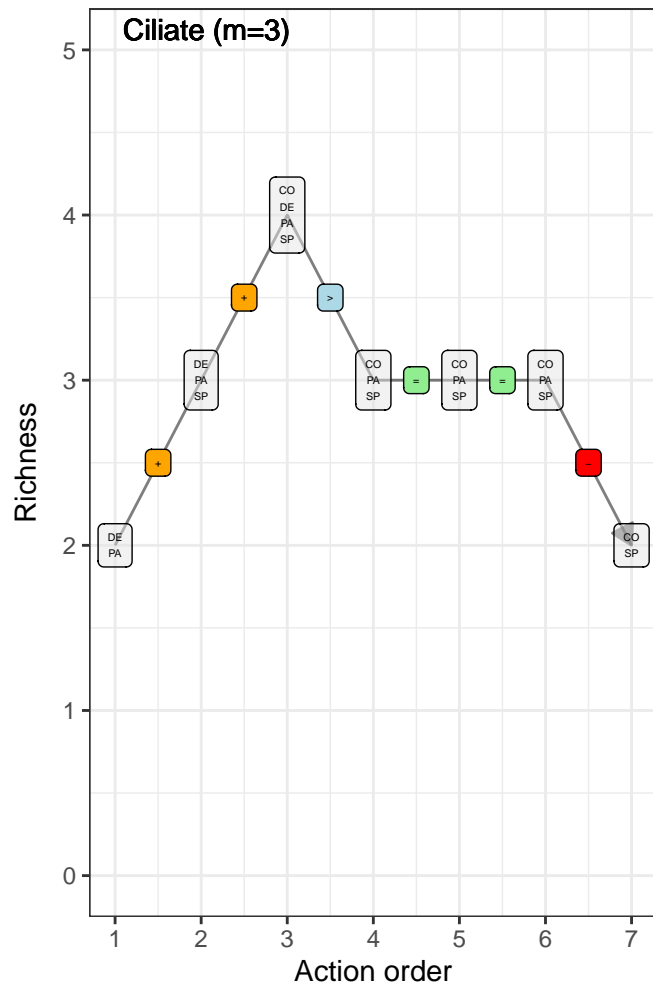
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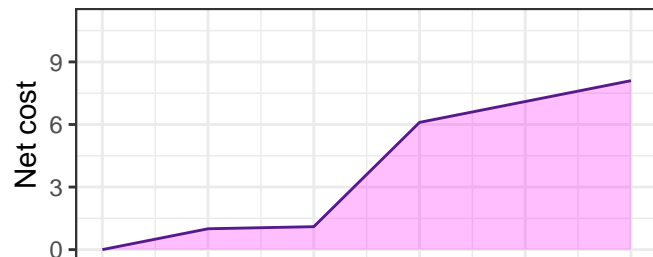
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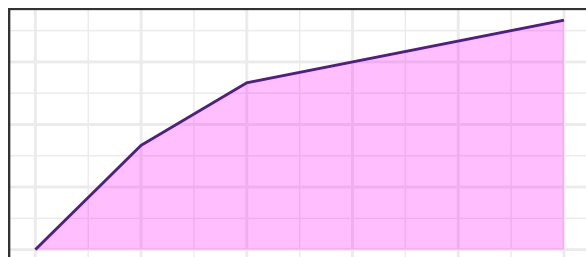
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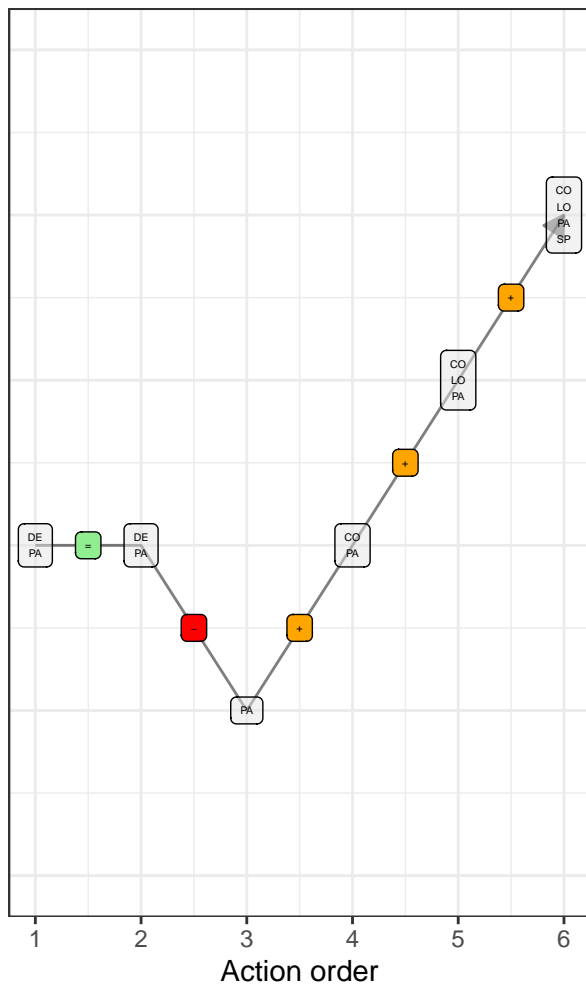
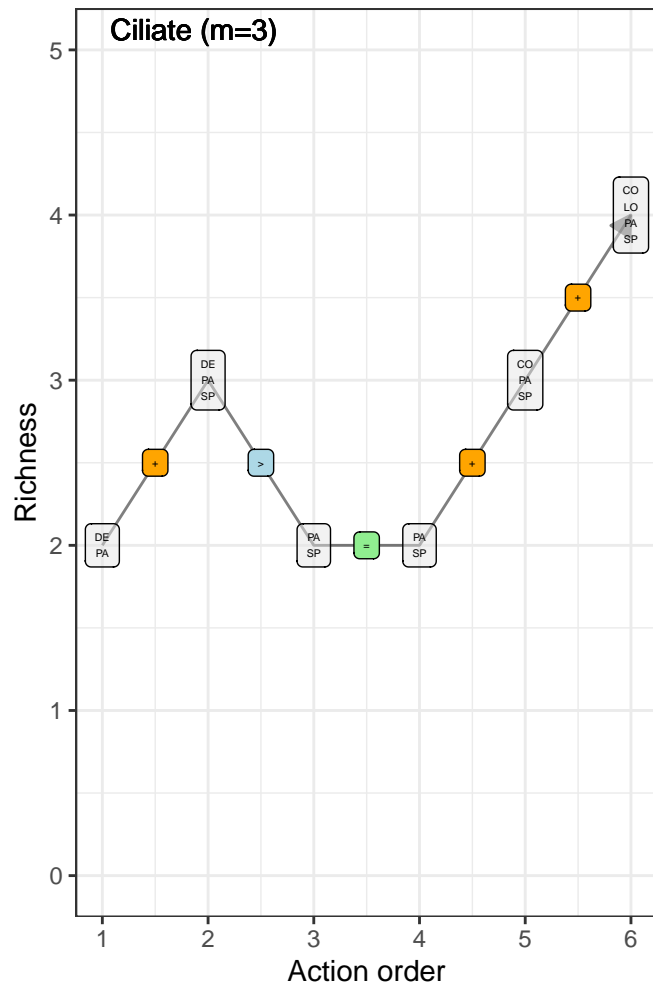
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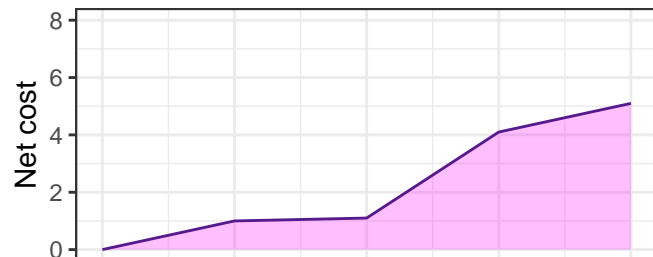
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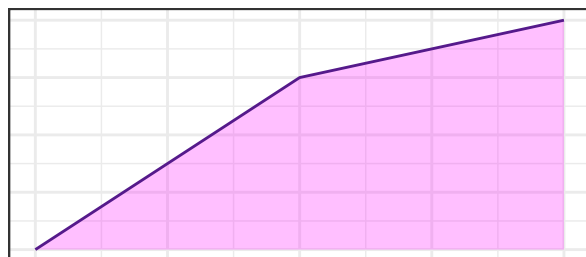
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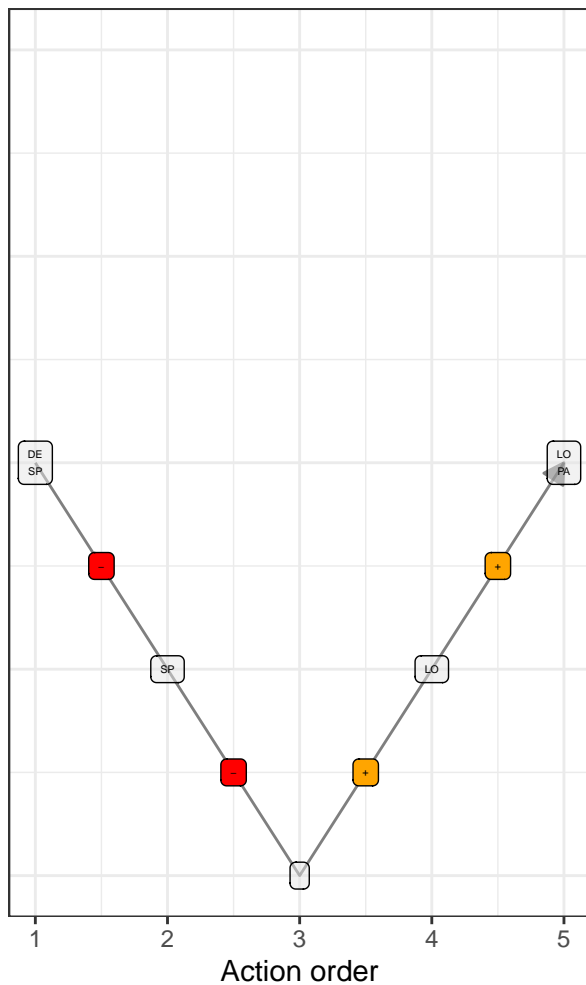
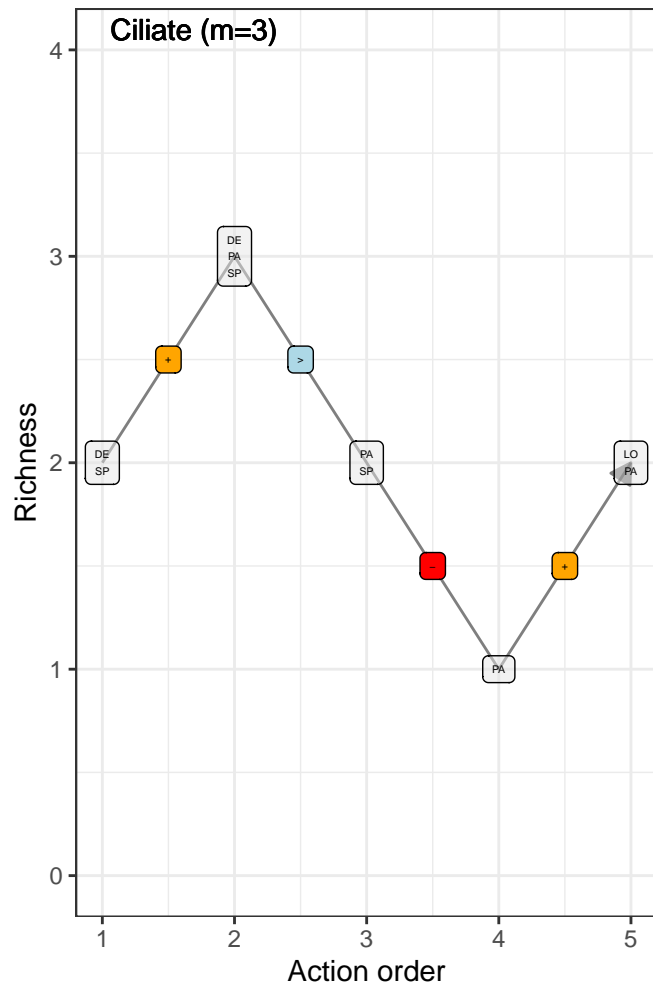
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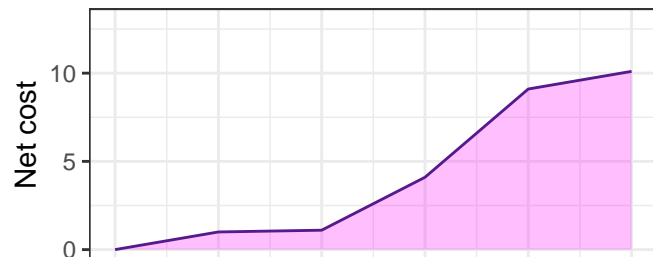
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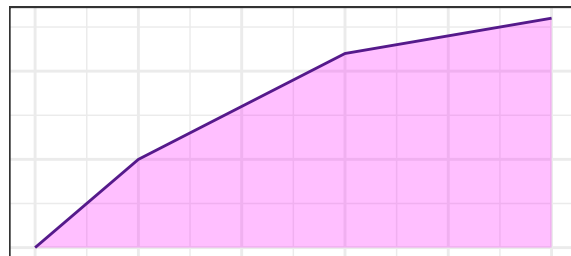
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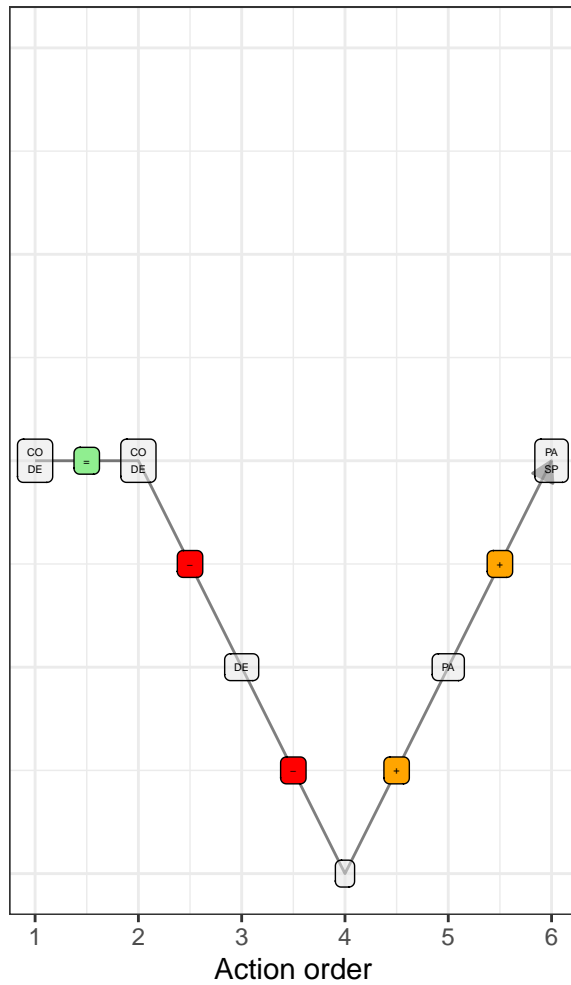
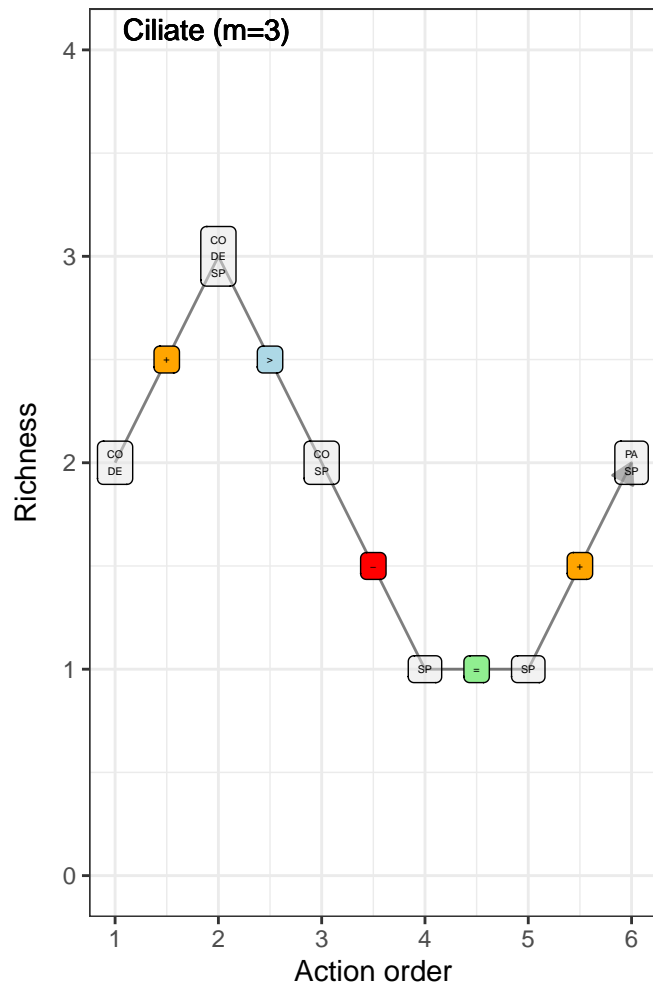
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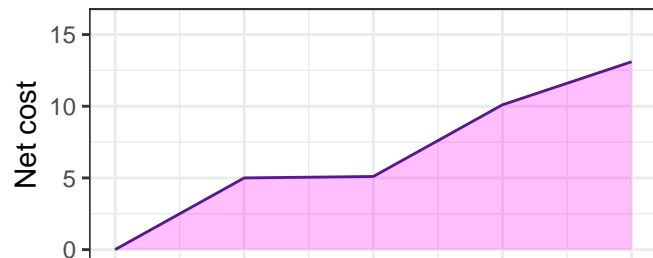
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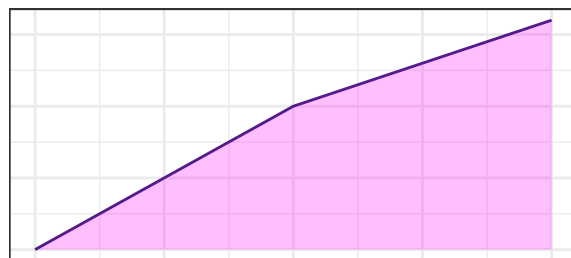
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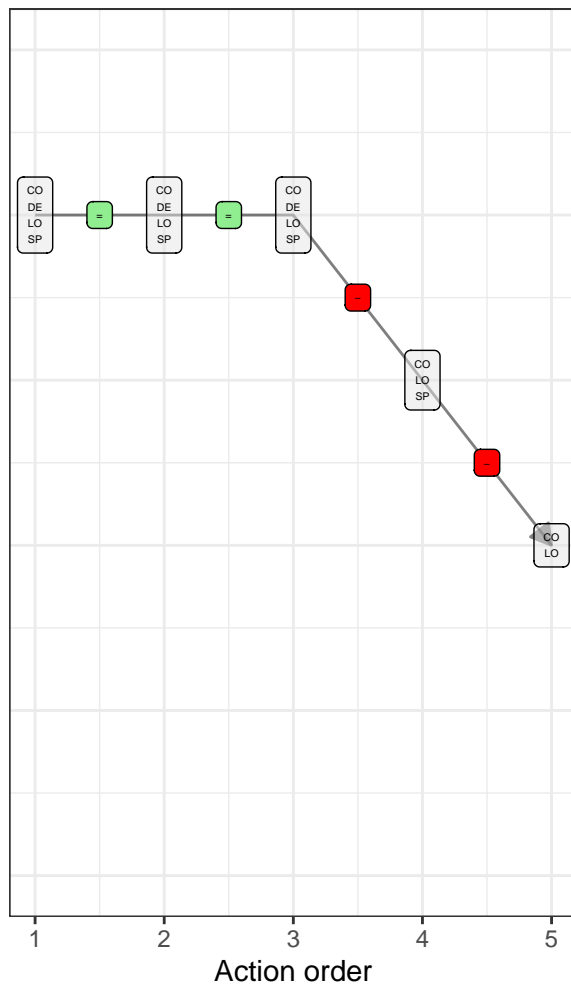
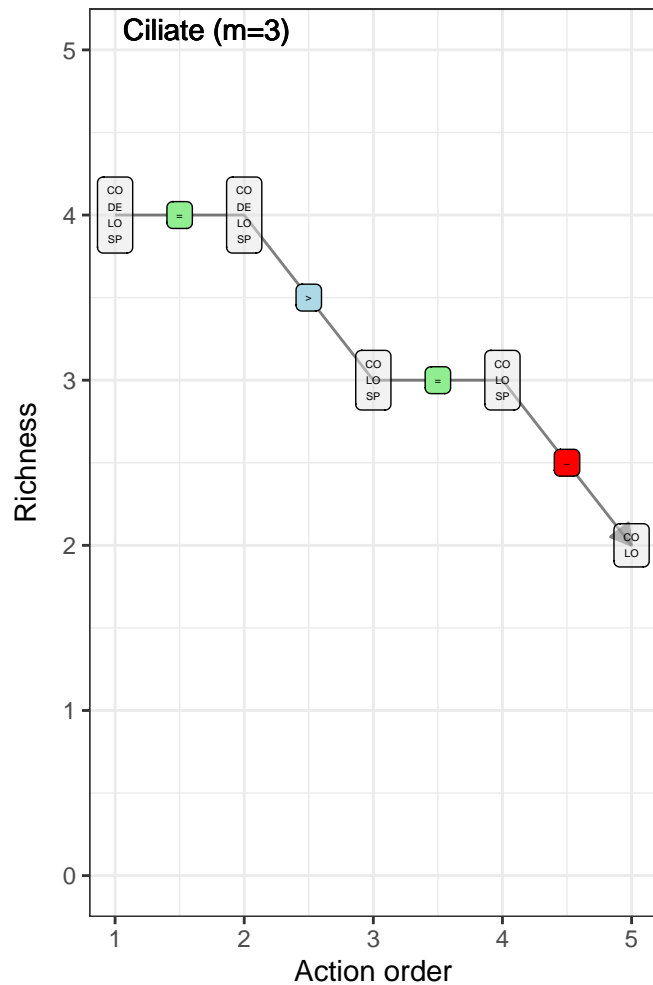
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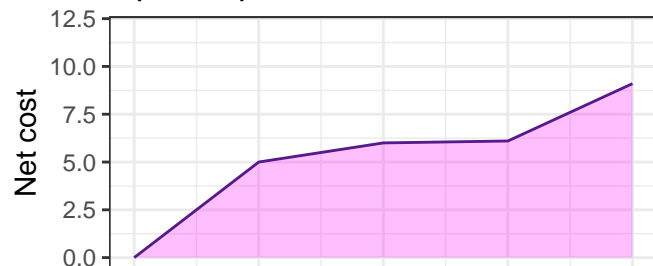
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Ciliate (m=3)



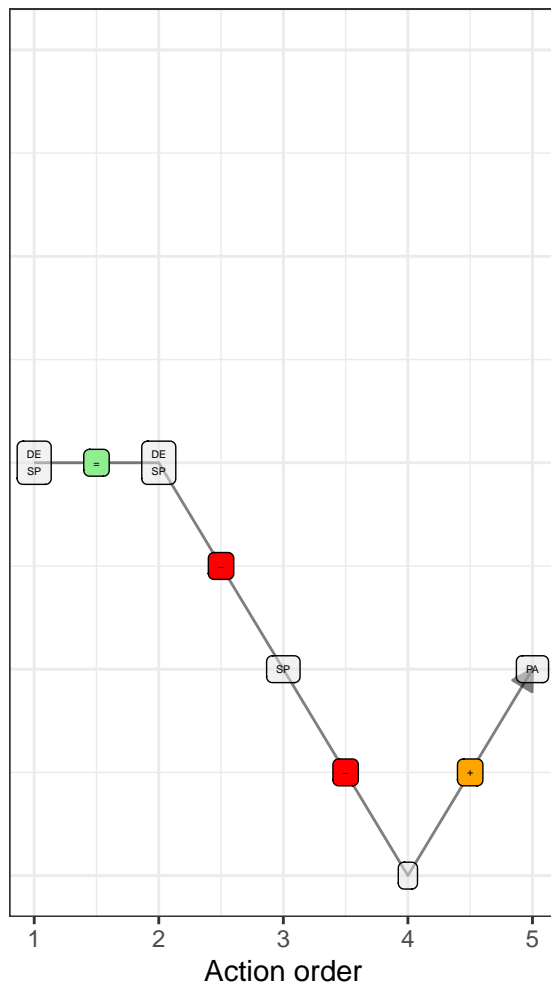
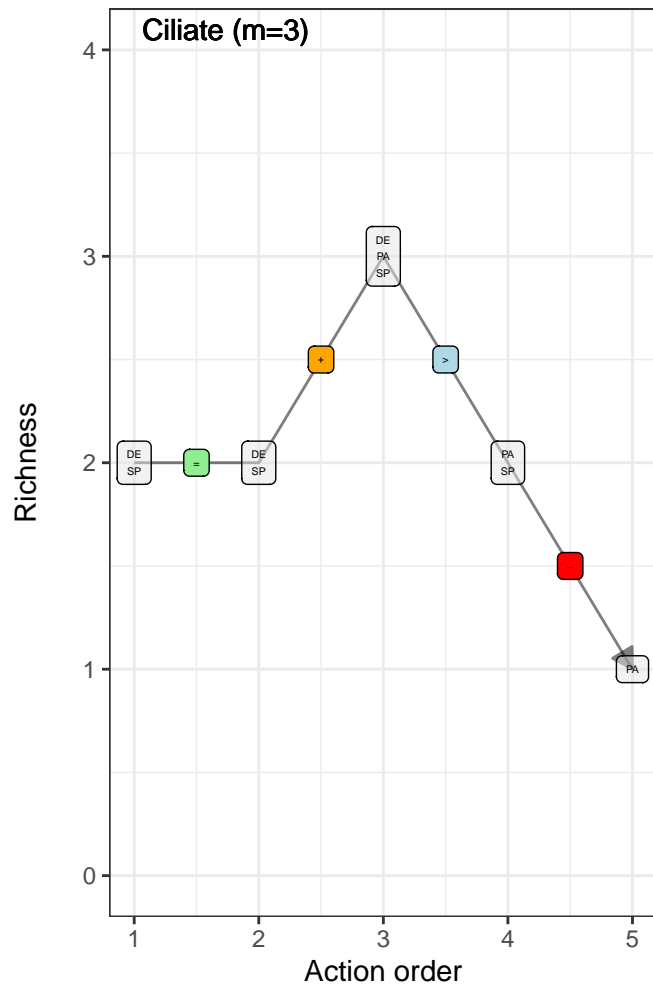
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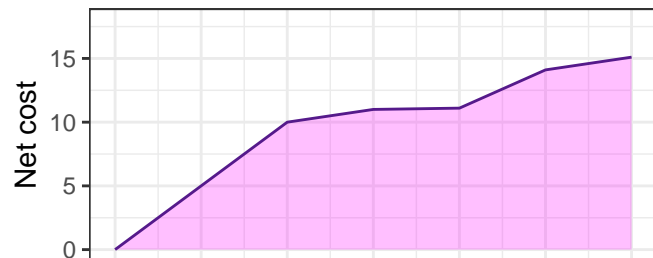
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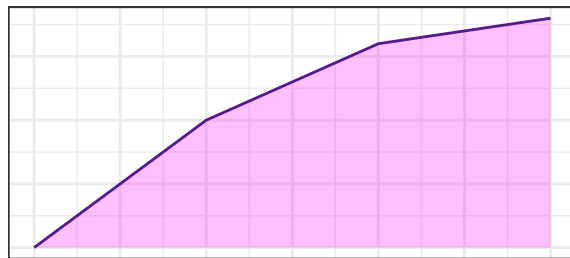
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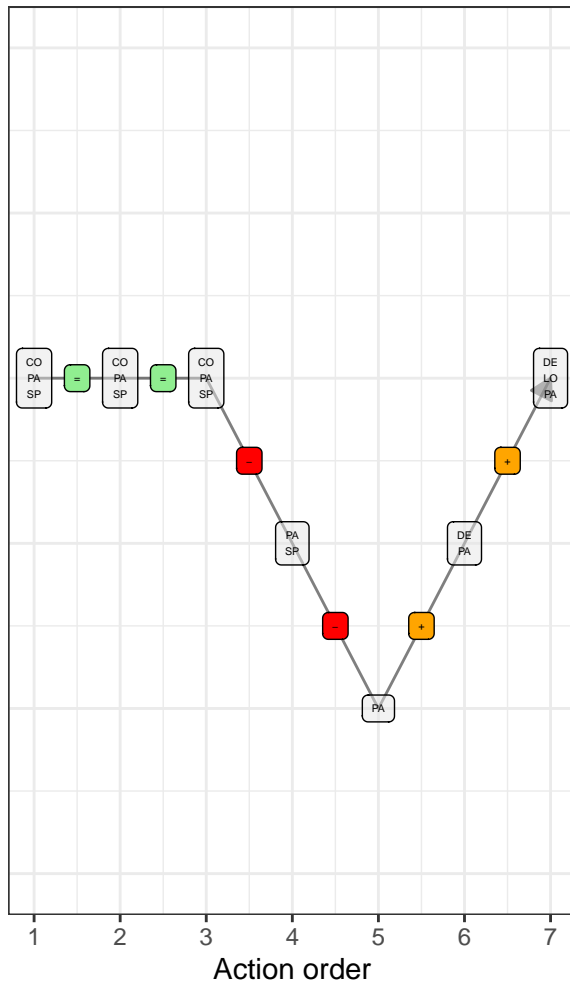
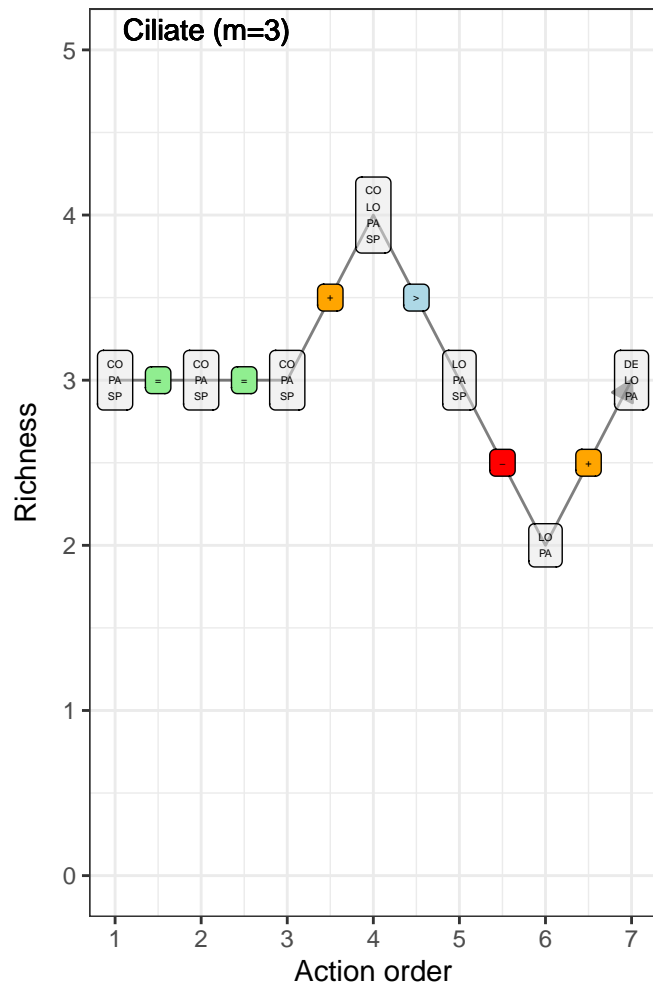
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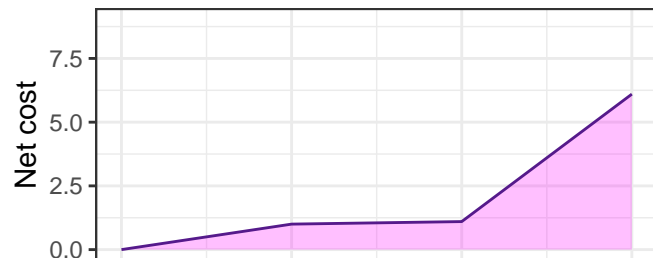
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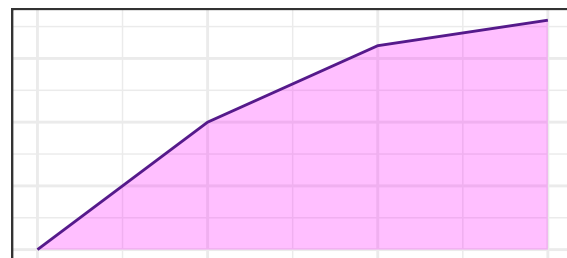
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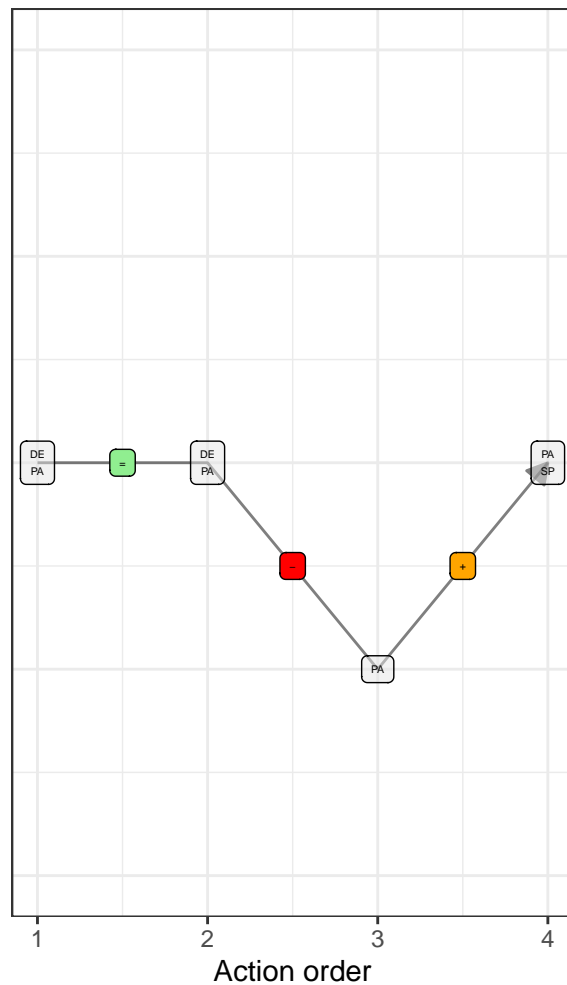
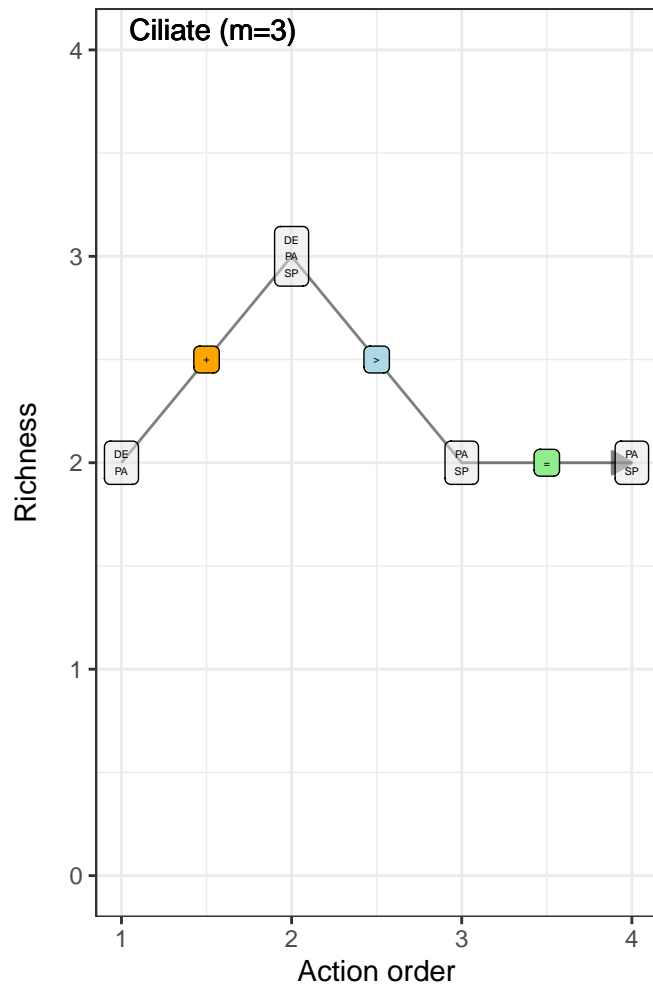
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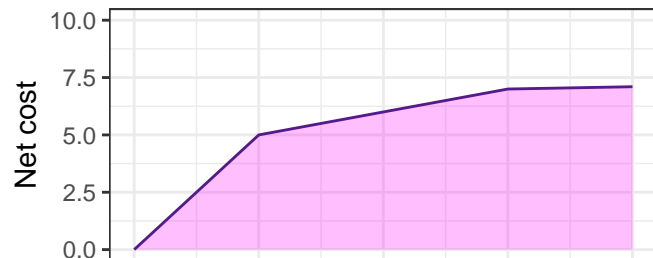
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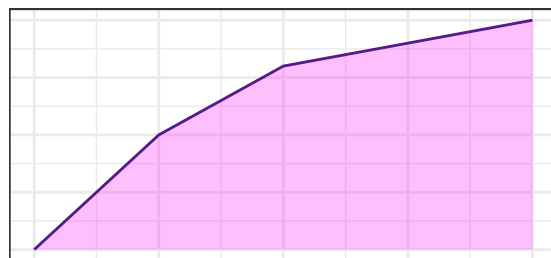
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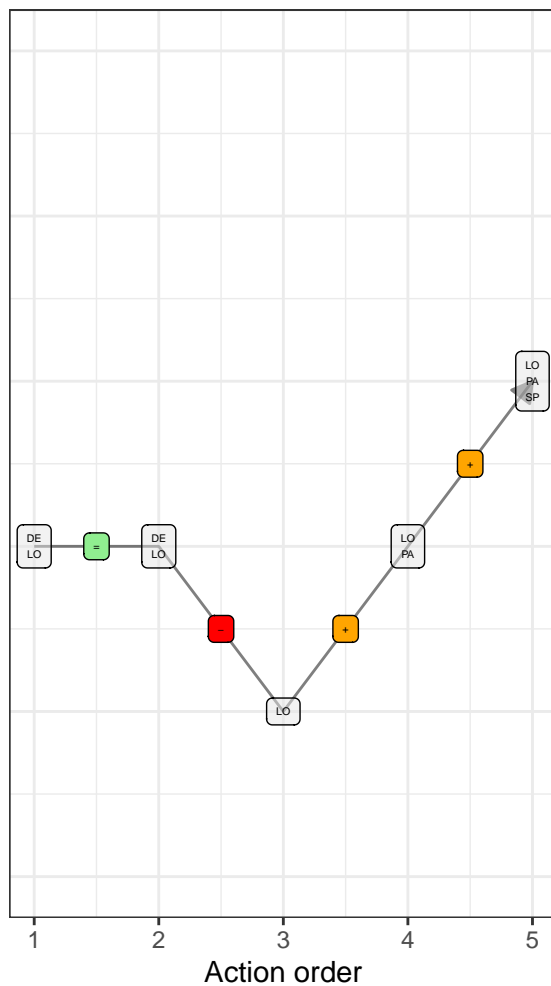
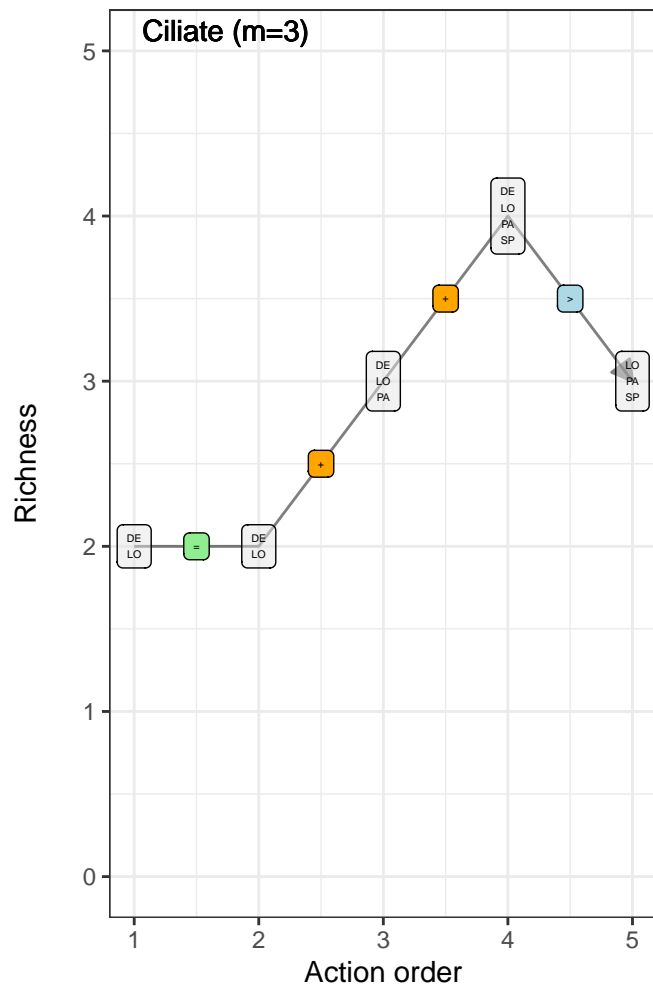
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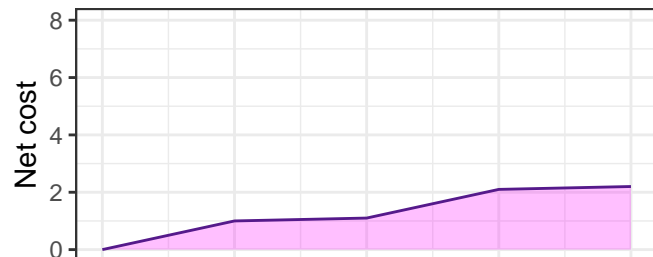
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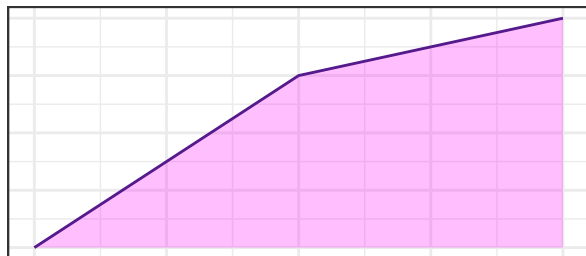
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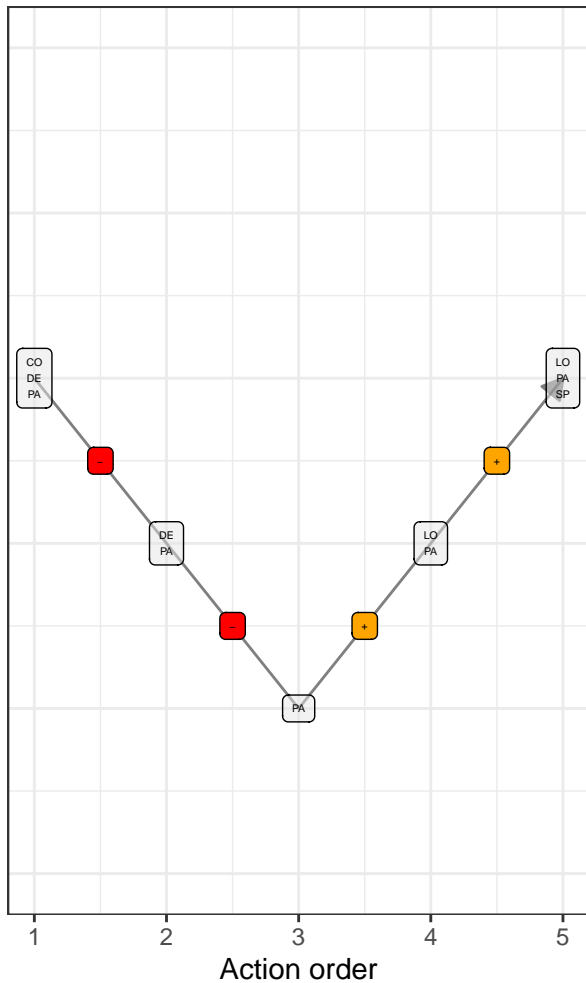
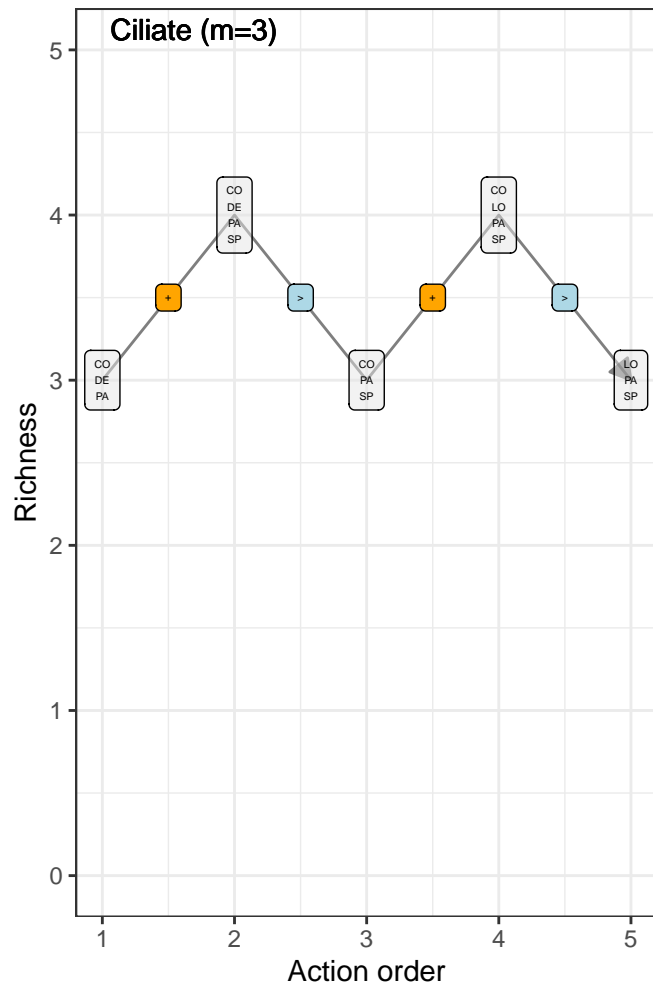
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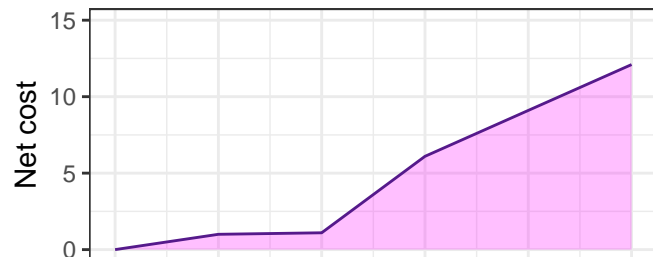
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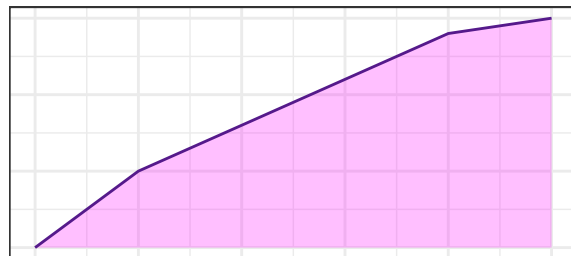
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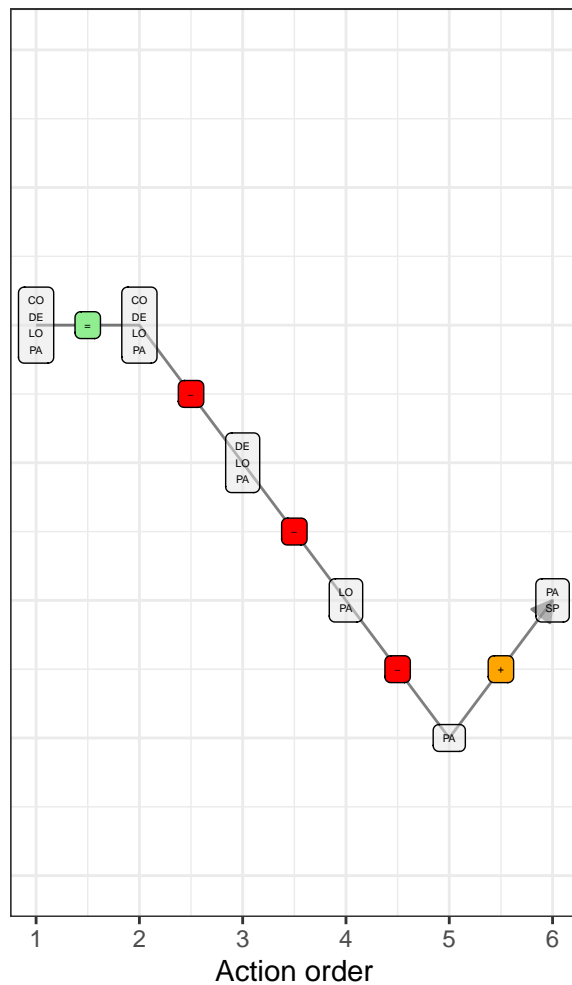
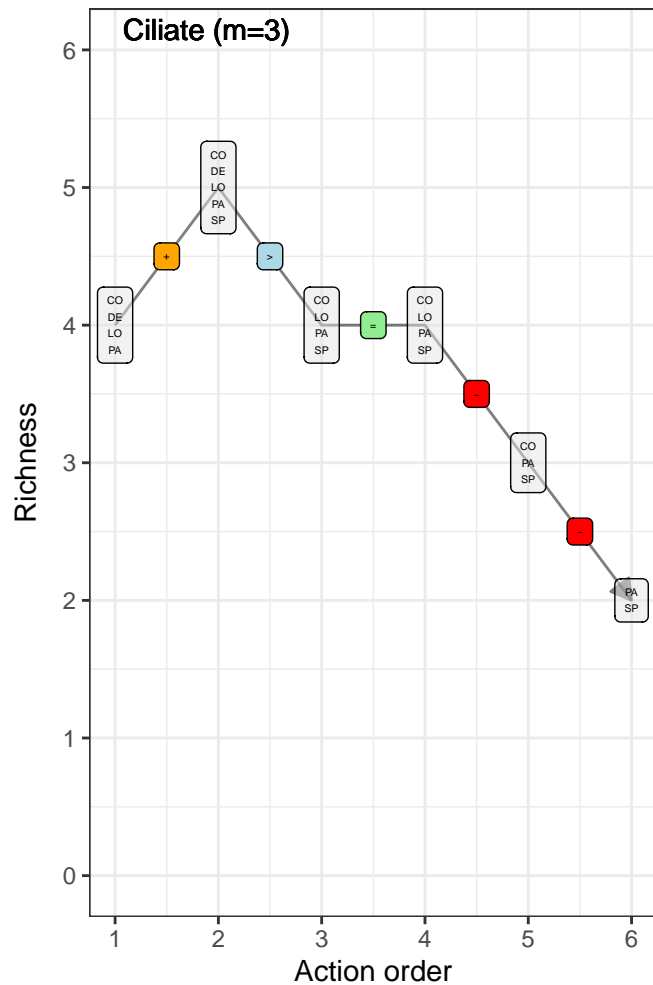
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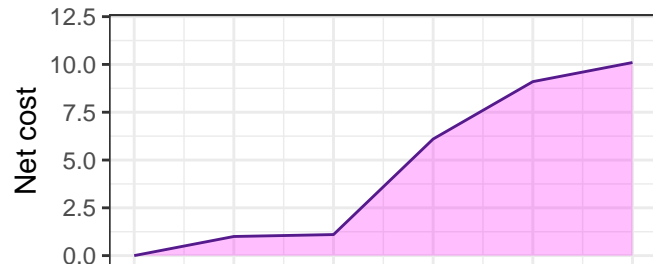
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Ciliate (m=3)



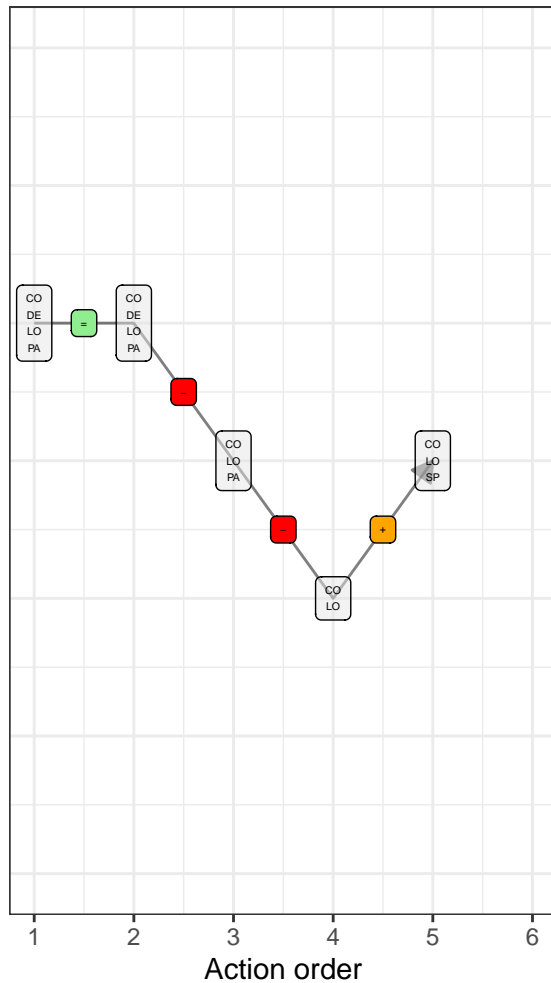
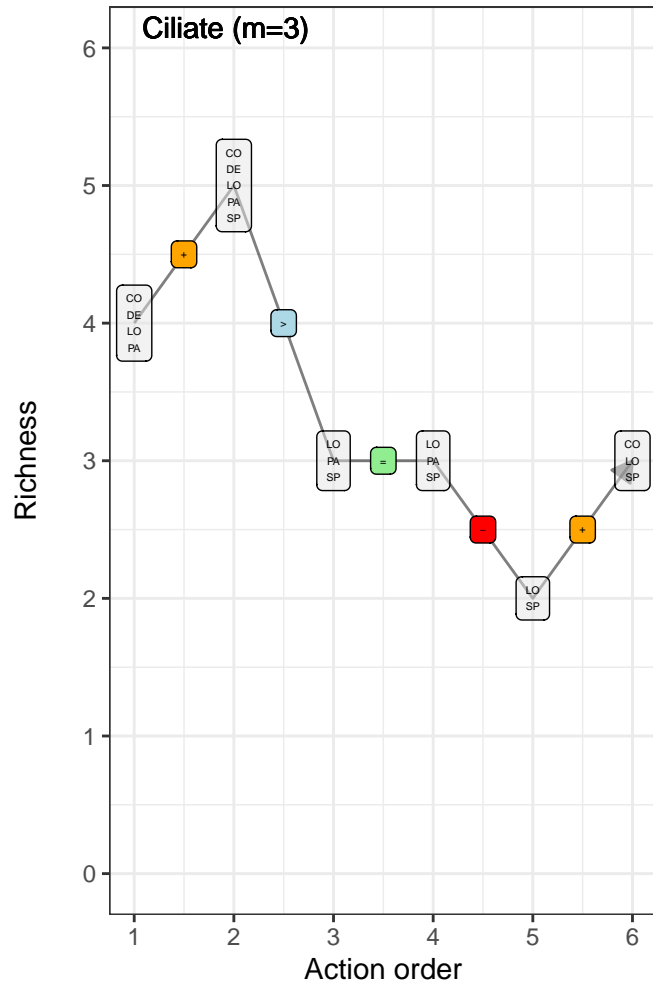
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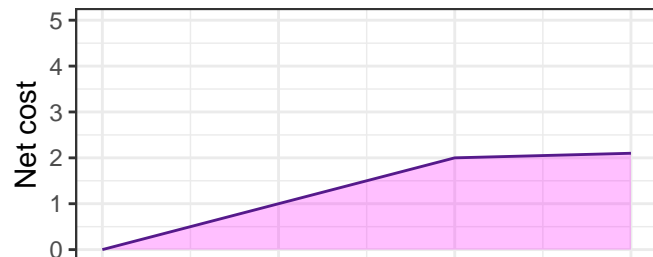
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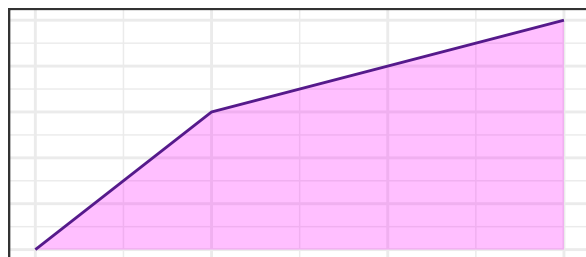
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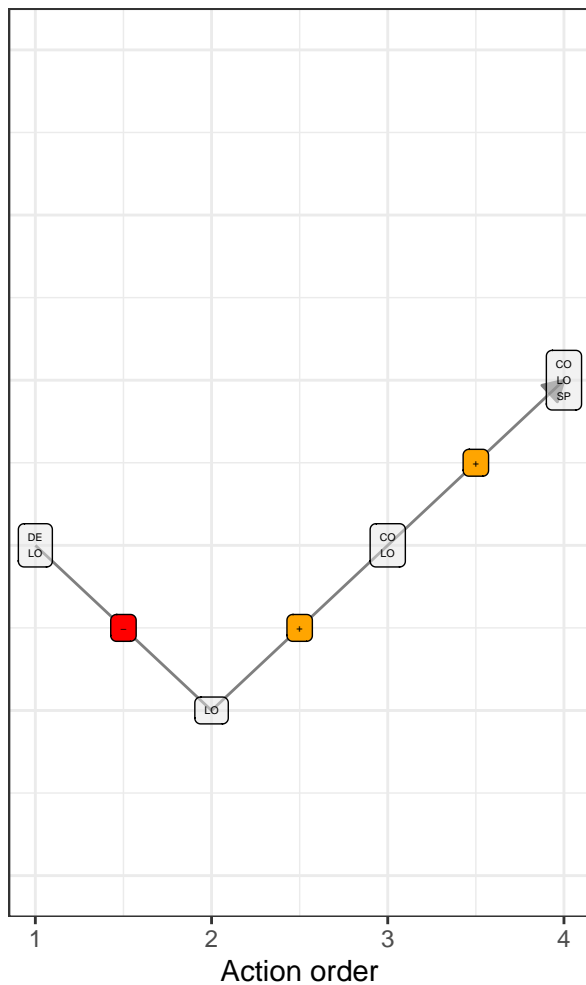
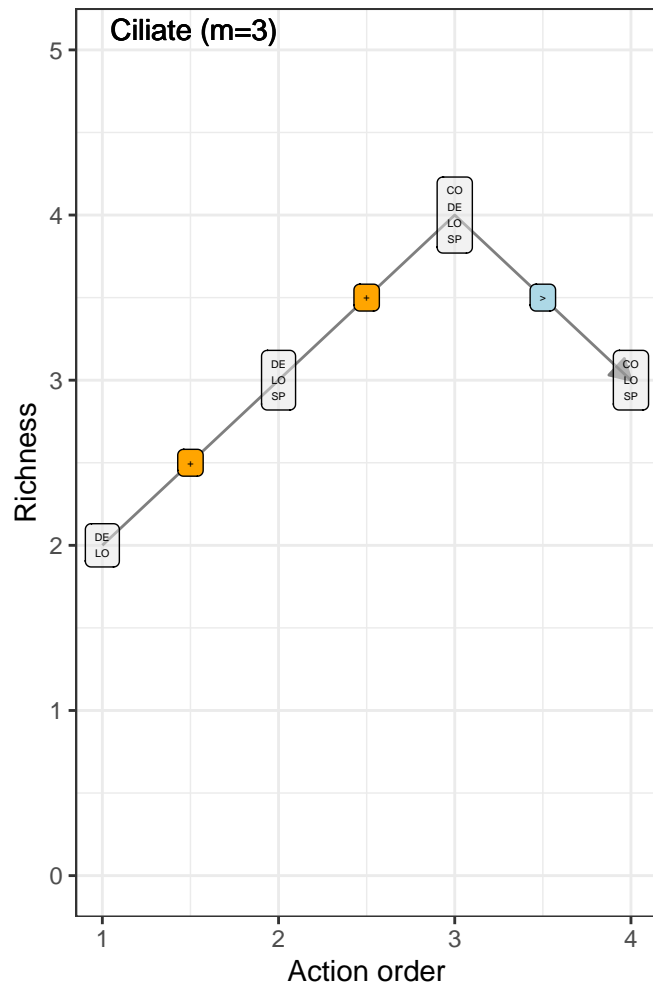
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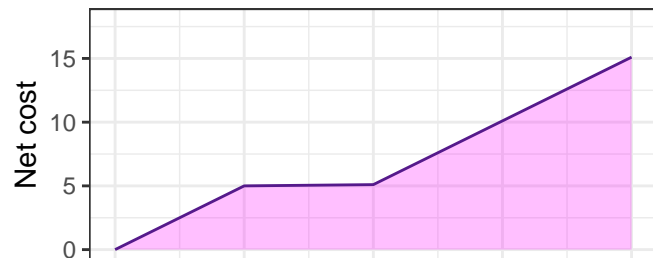
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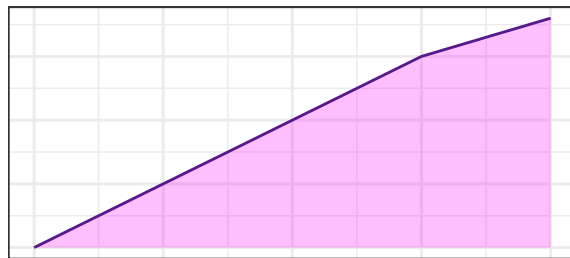
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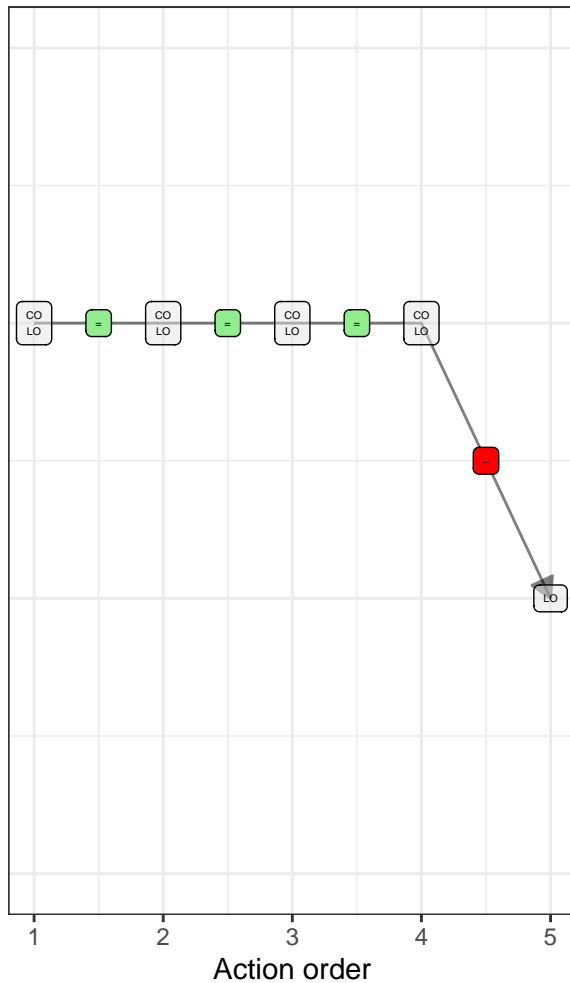
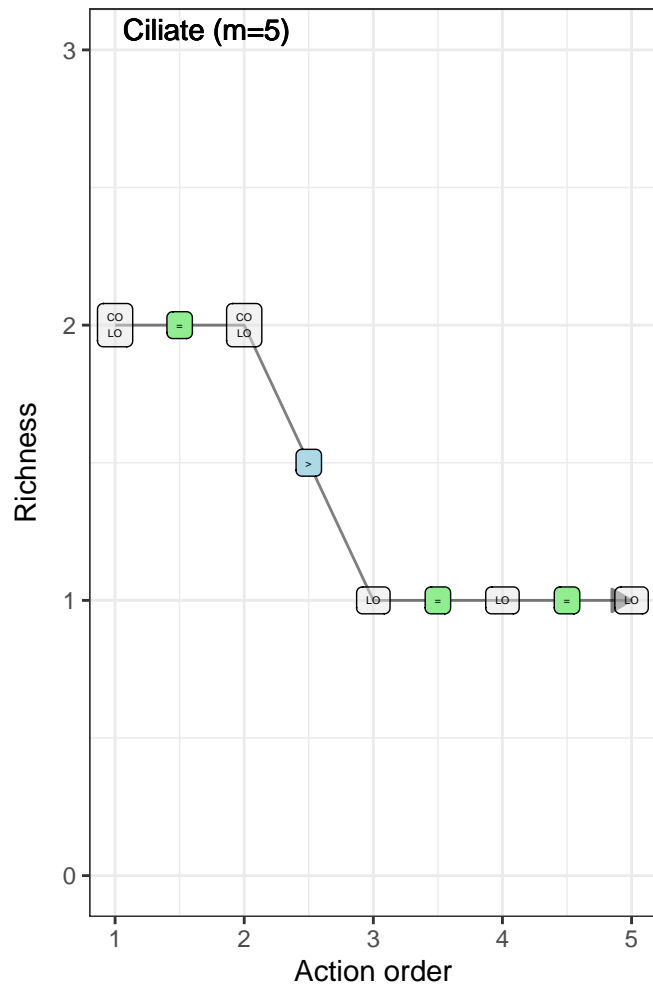
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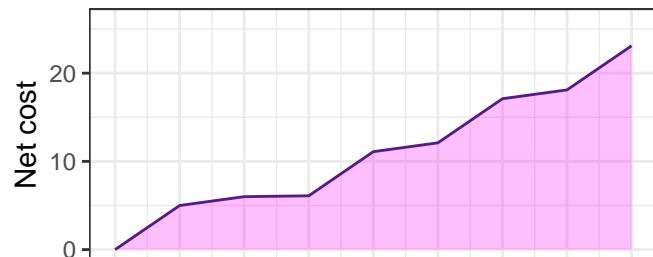
Nominal path



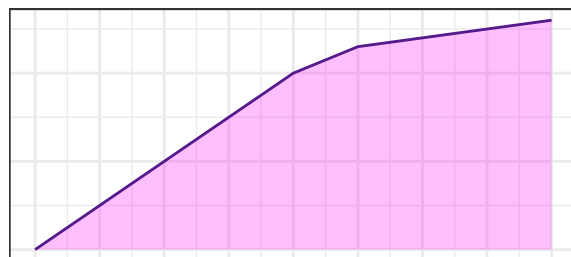
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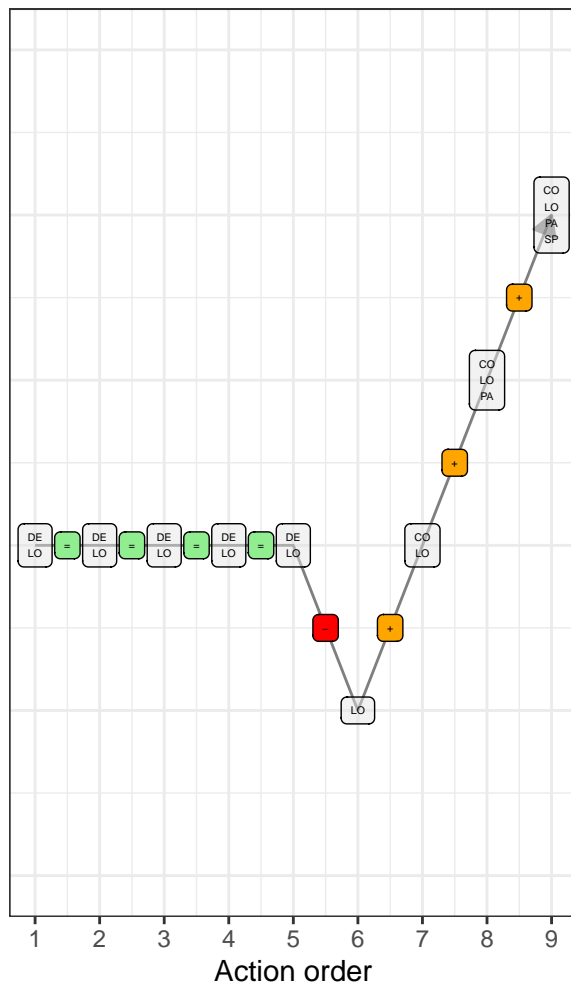
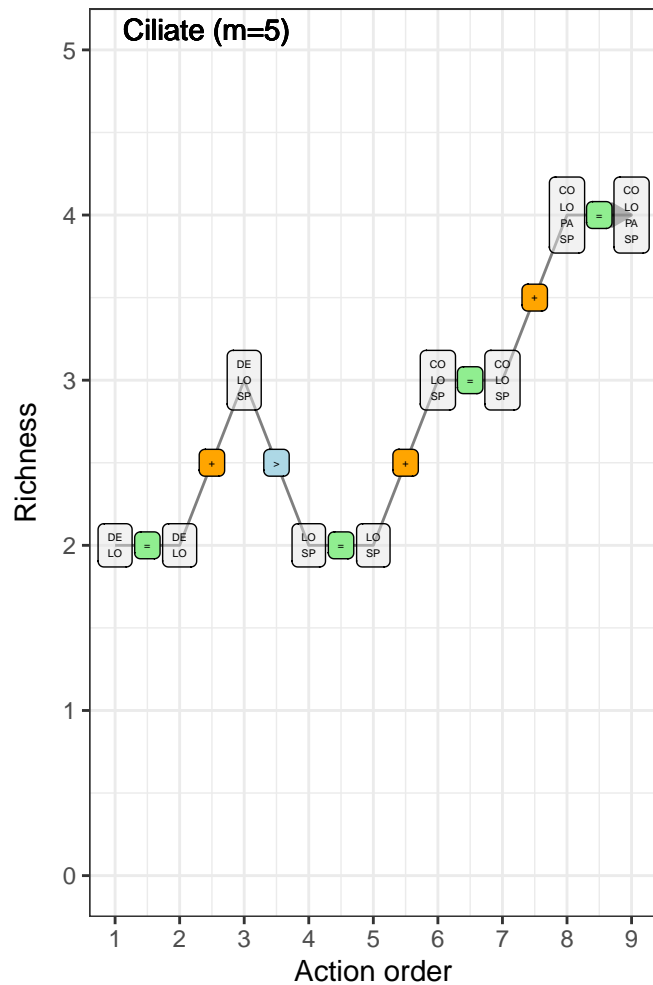
Optimal path



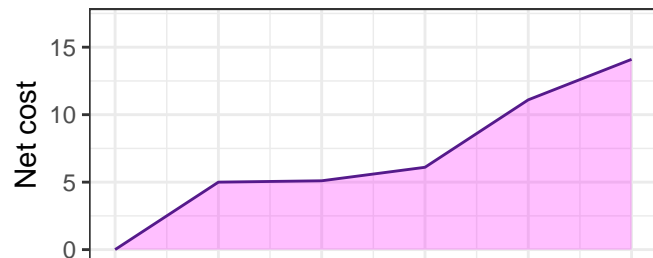
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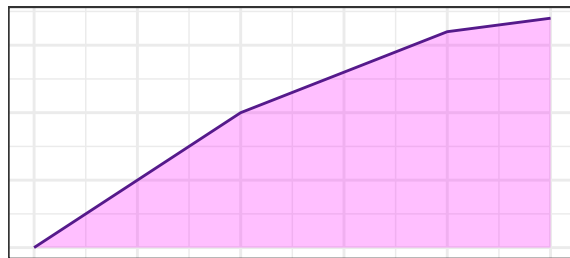
Ciliate (m=5)



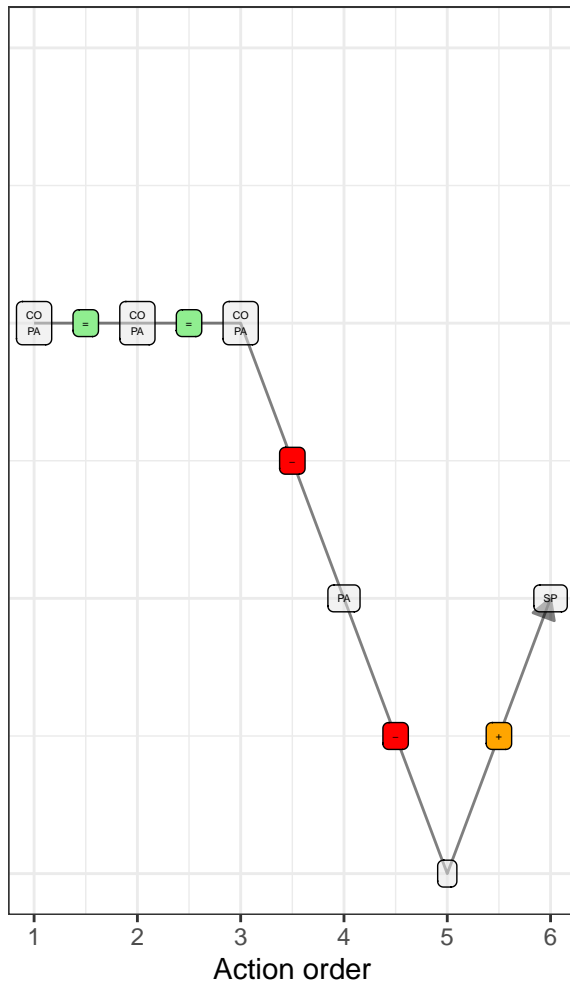
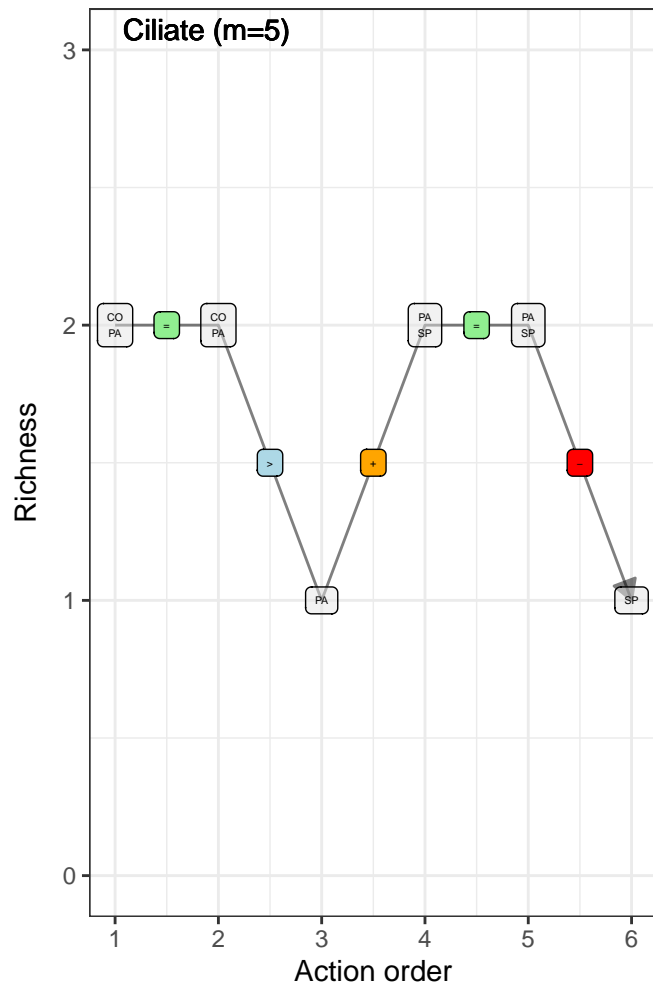
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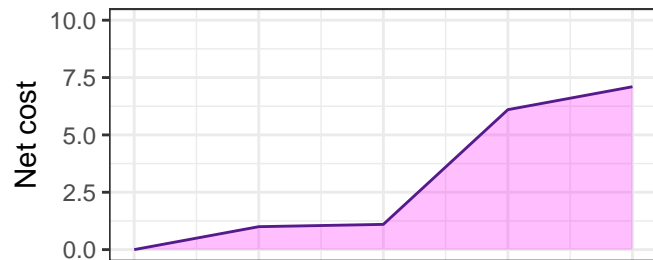
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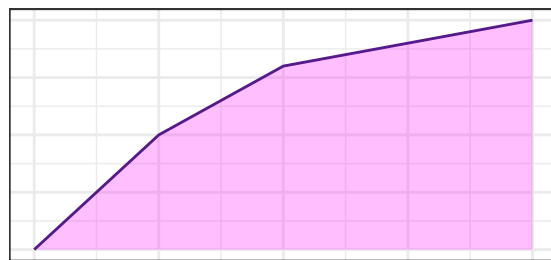
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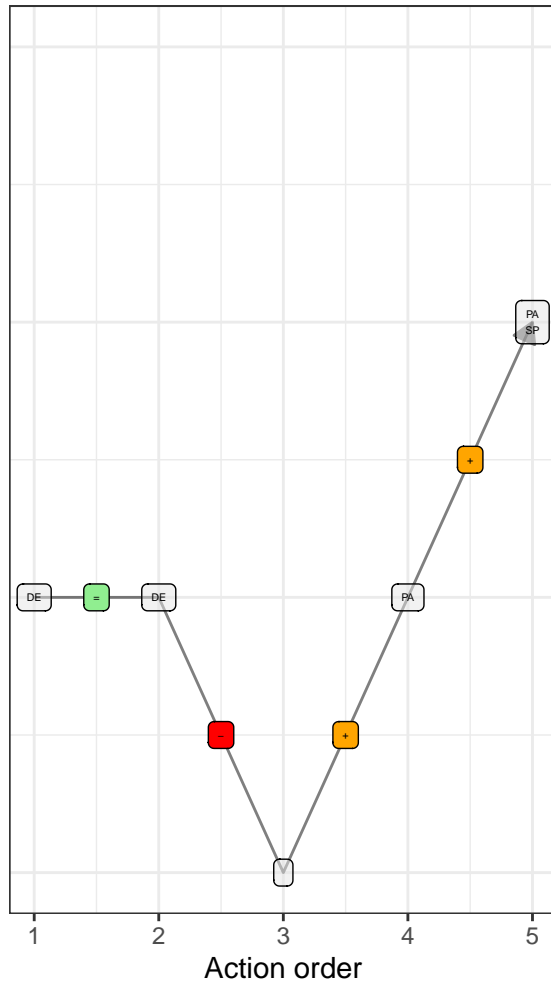
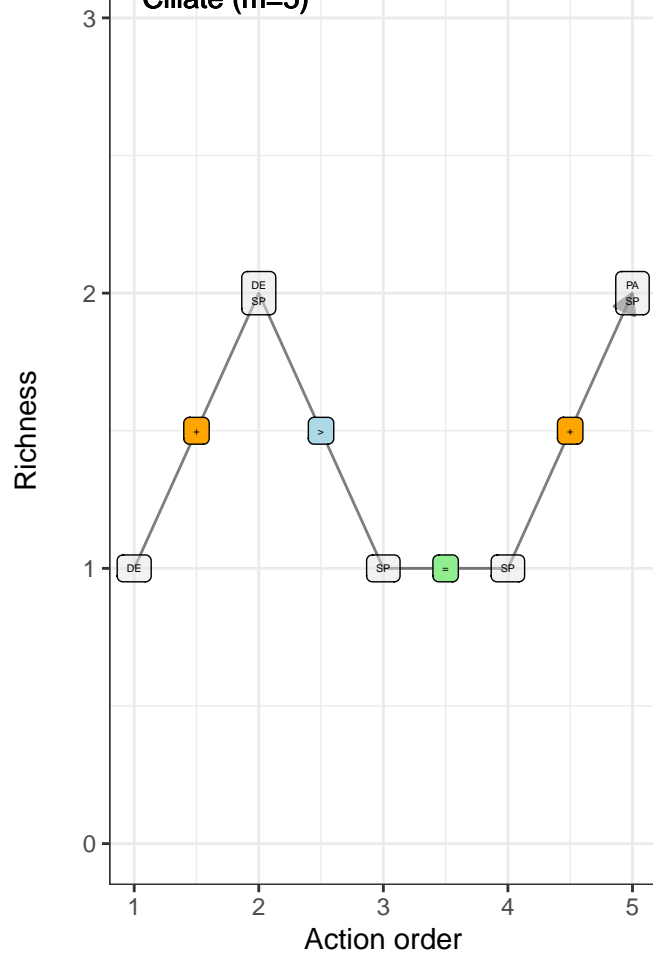
Optimal path



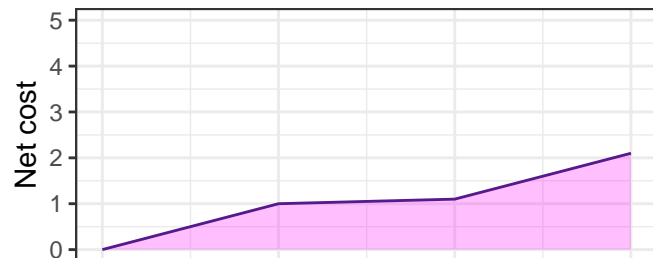
Nominal path



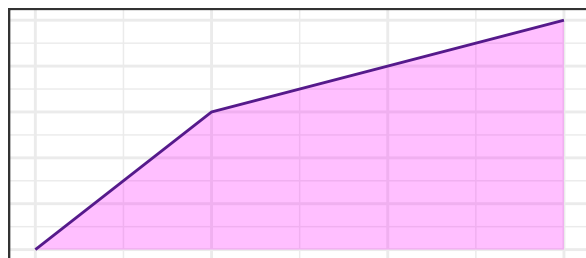
Ciliate (m=5)



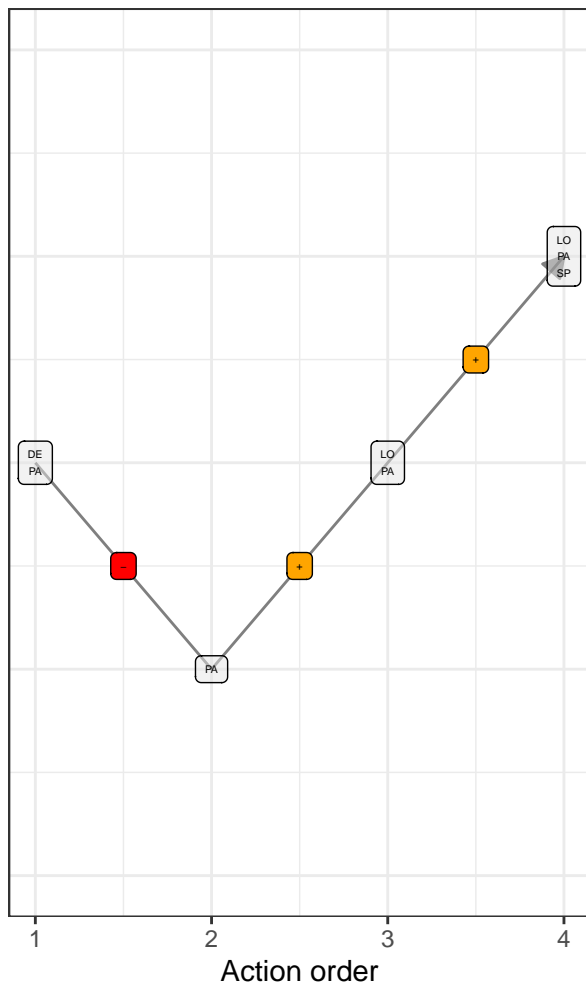
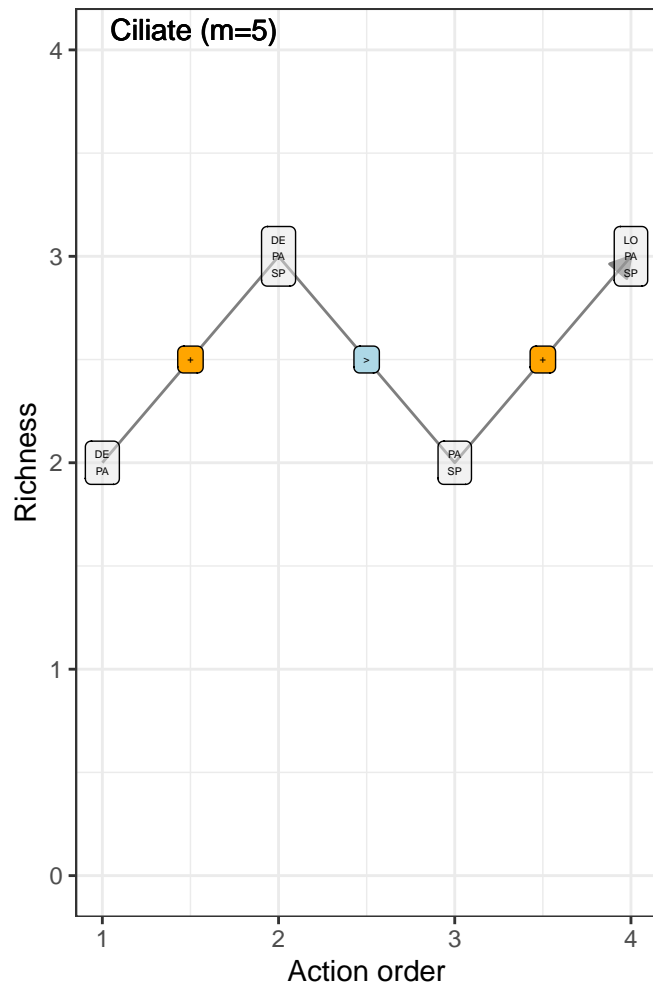
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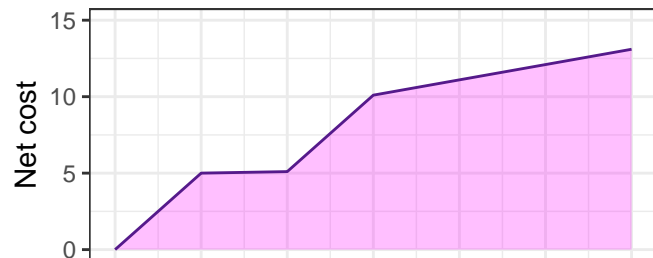
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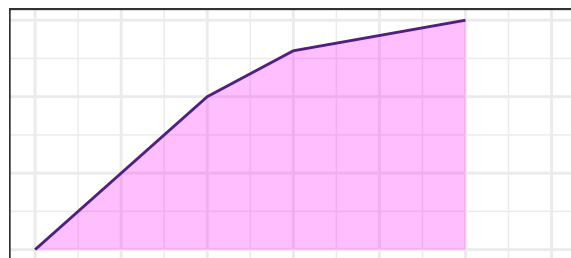
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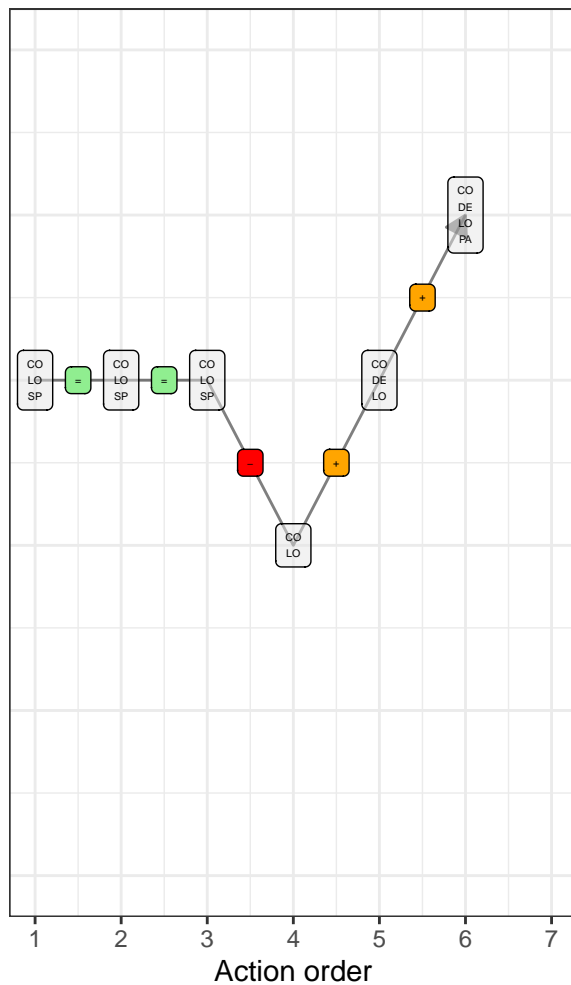
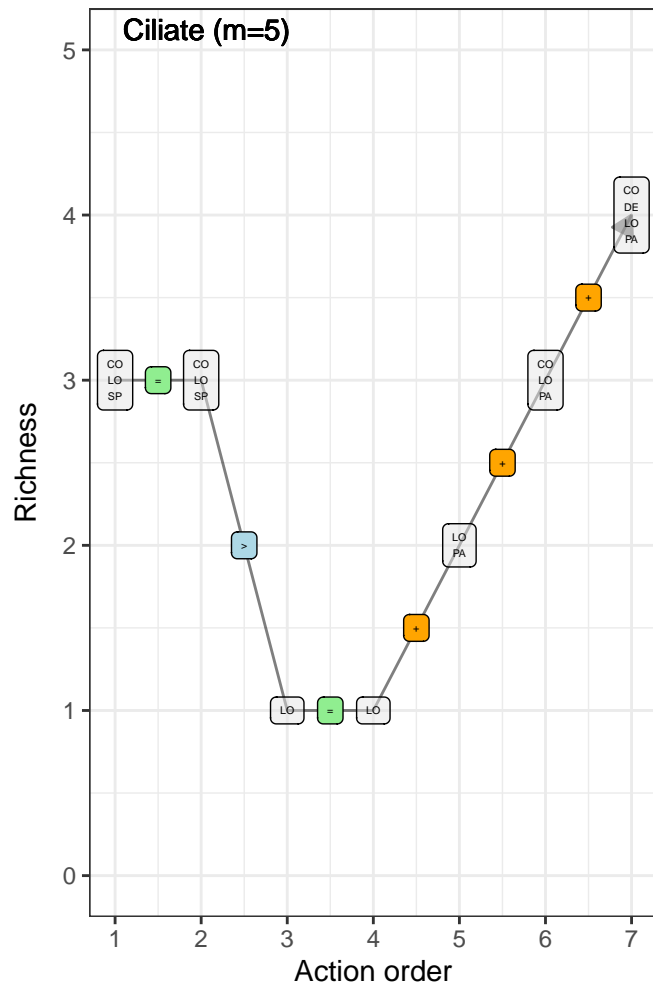
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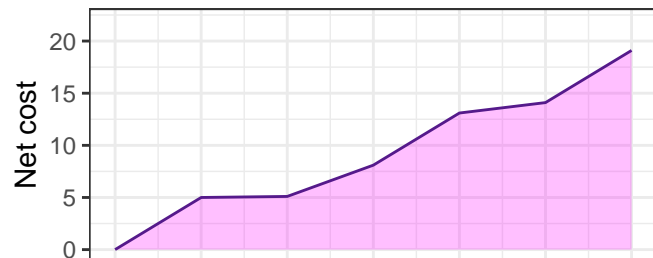
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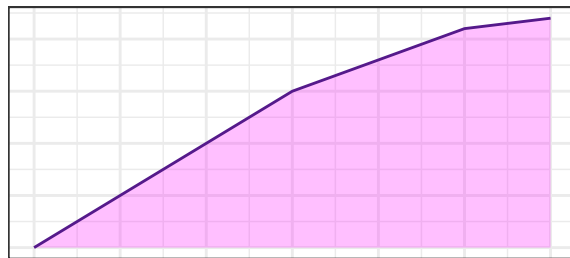
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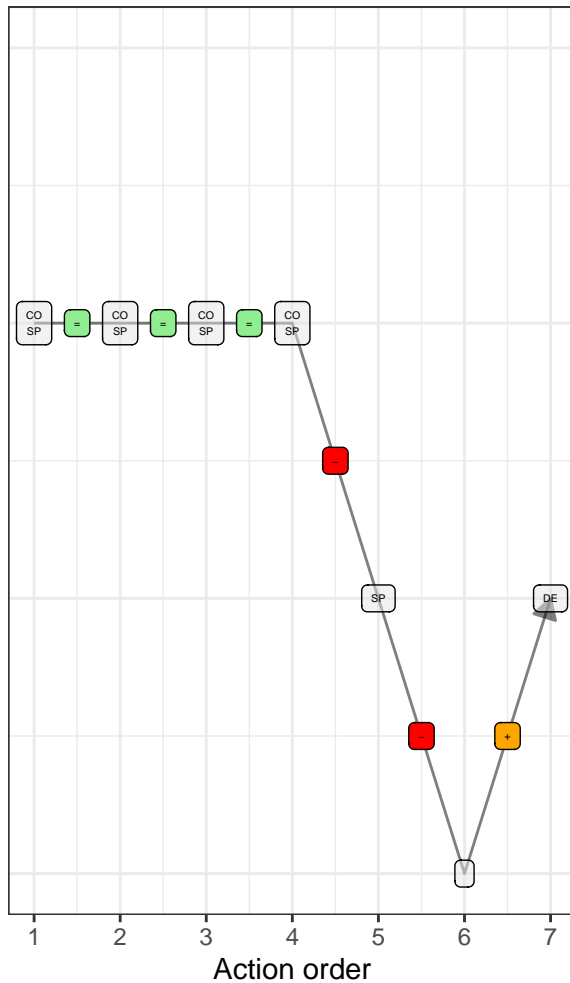
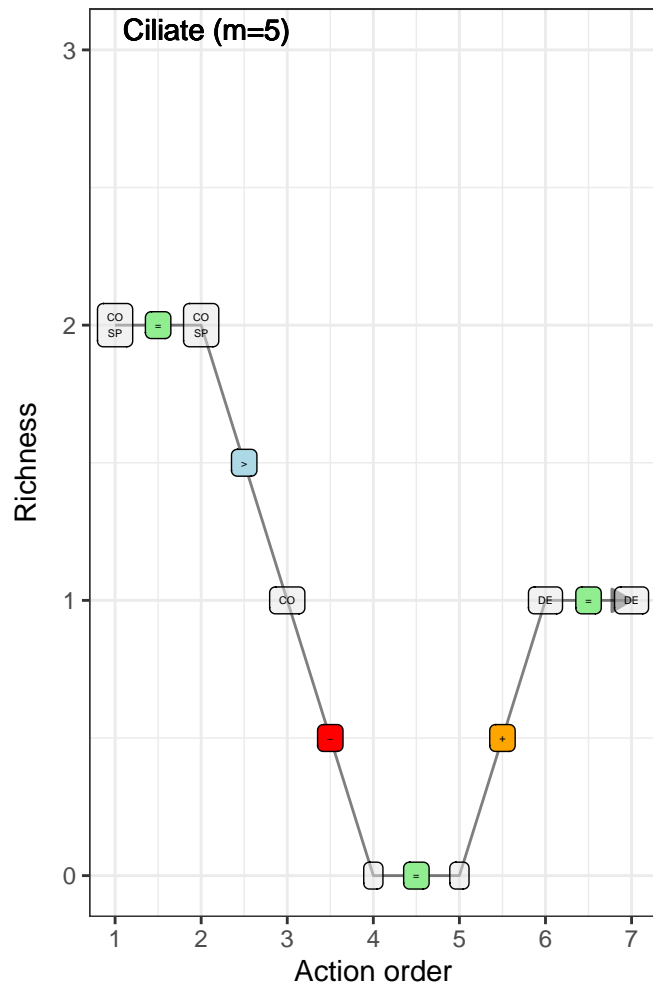
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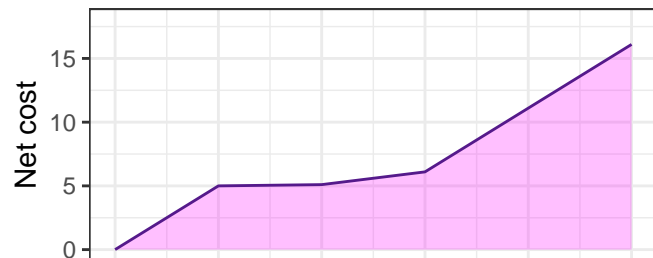
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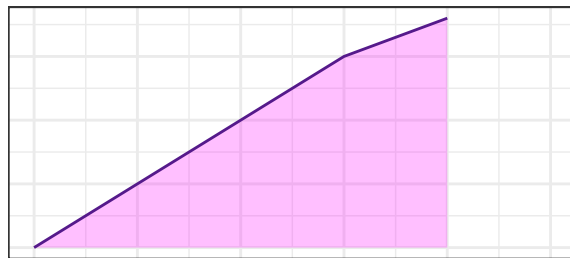
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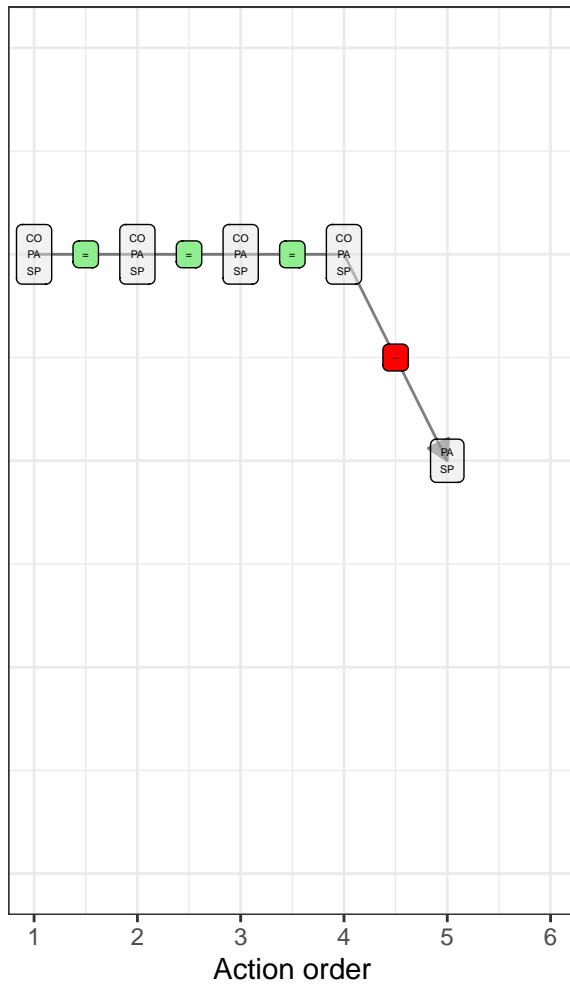
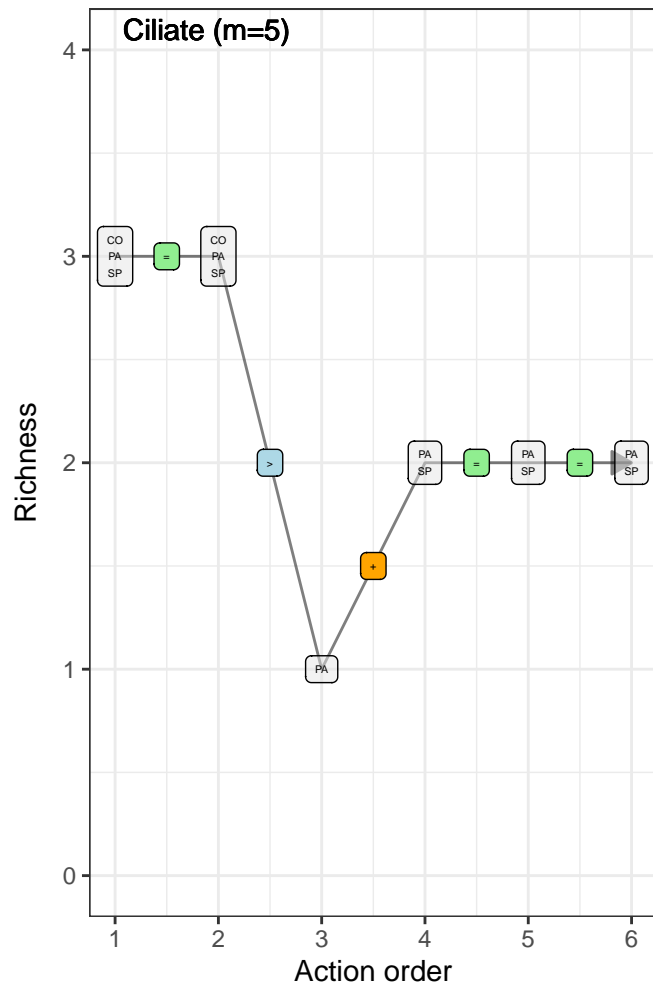
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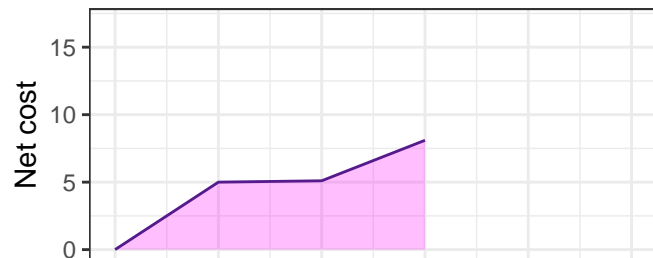
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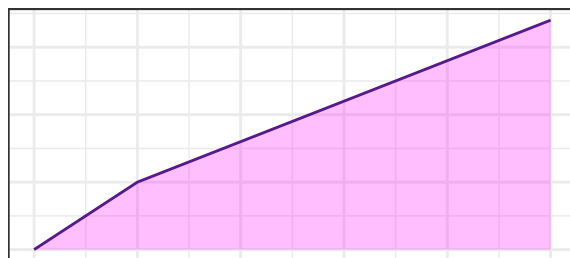
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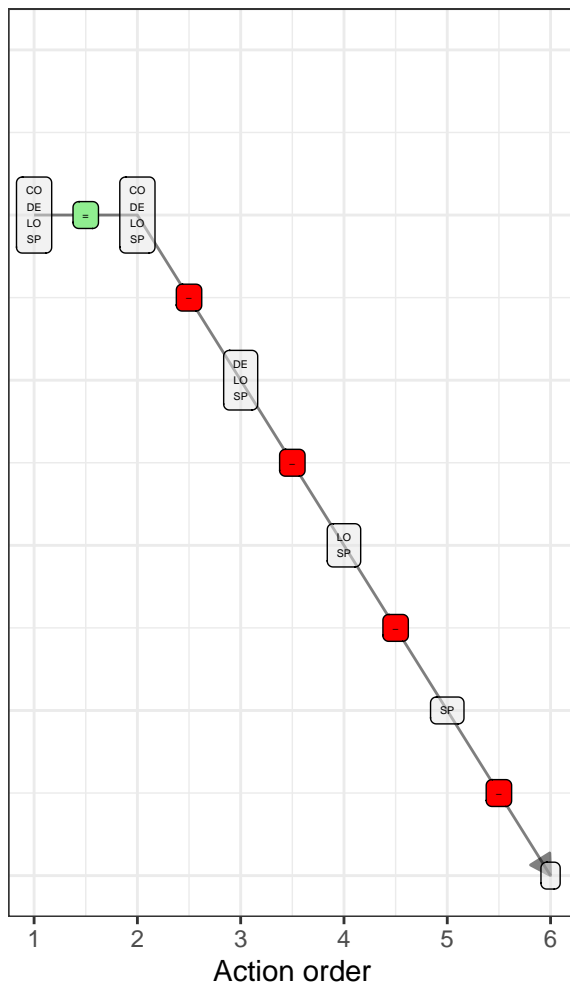
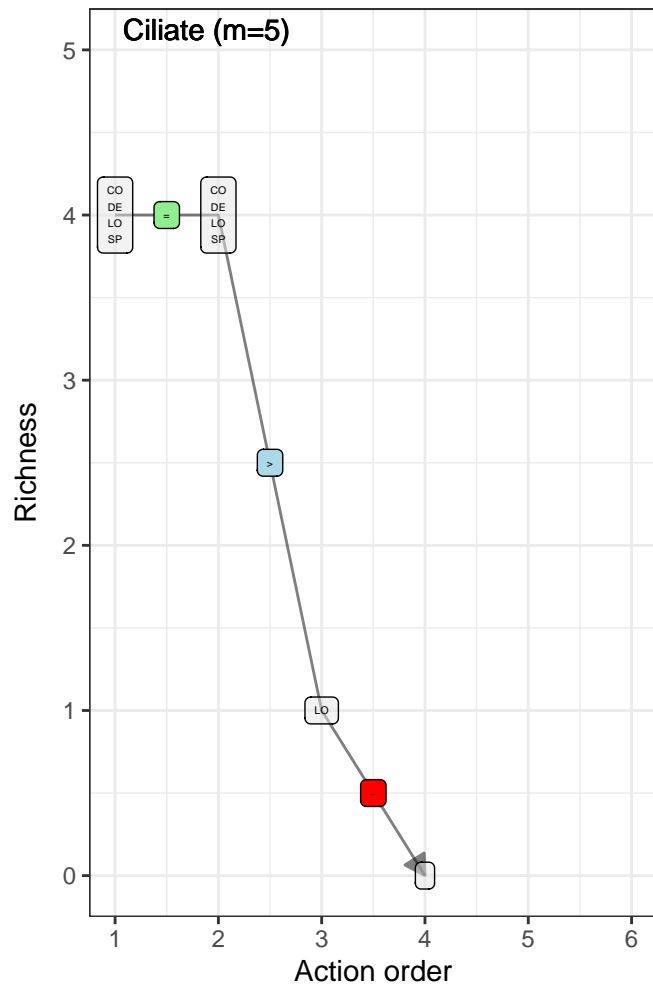
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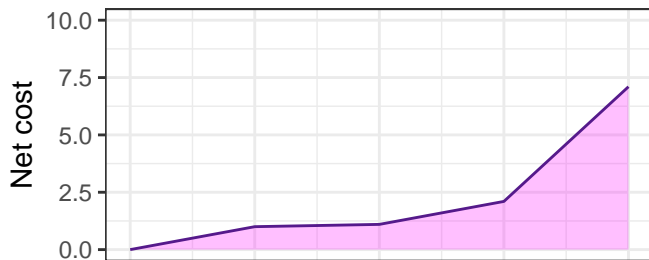
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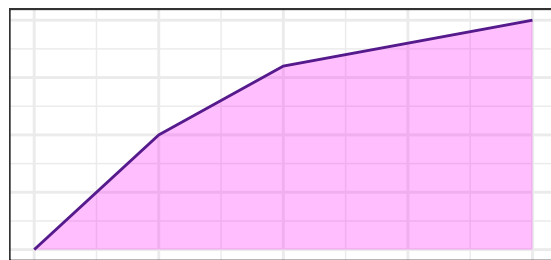
Ciliate (m=5)



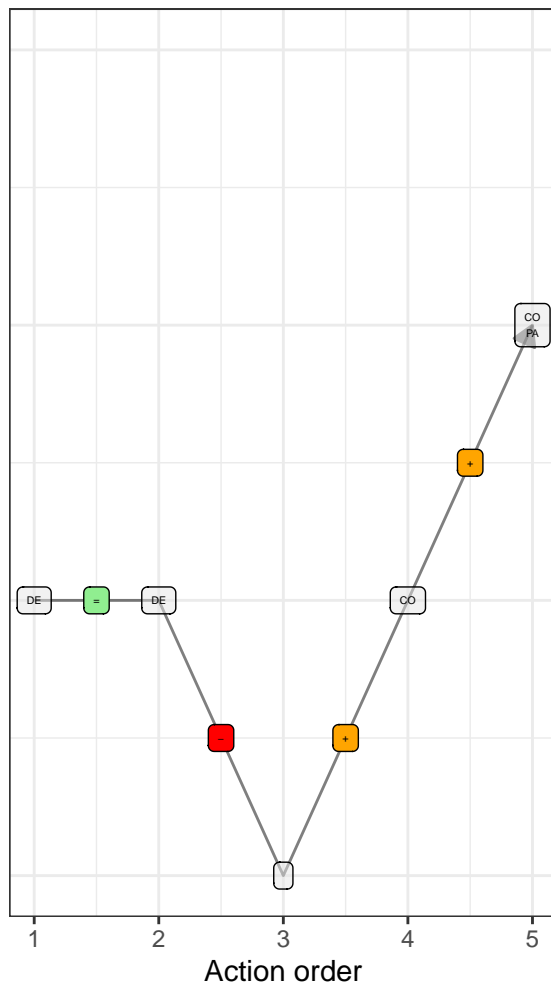
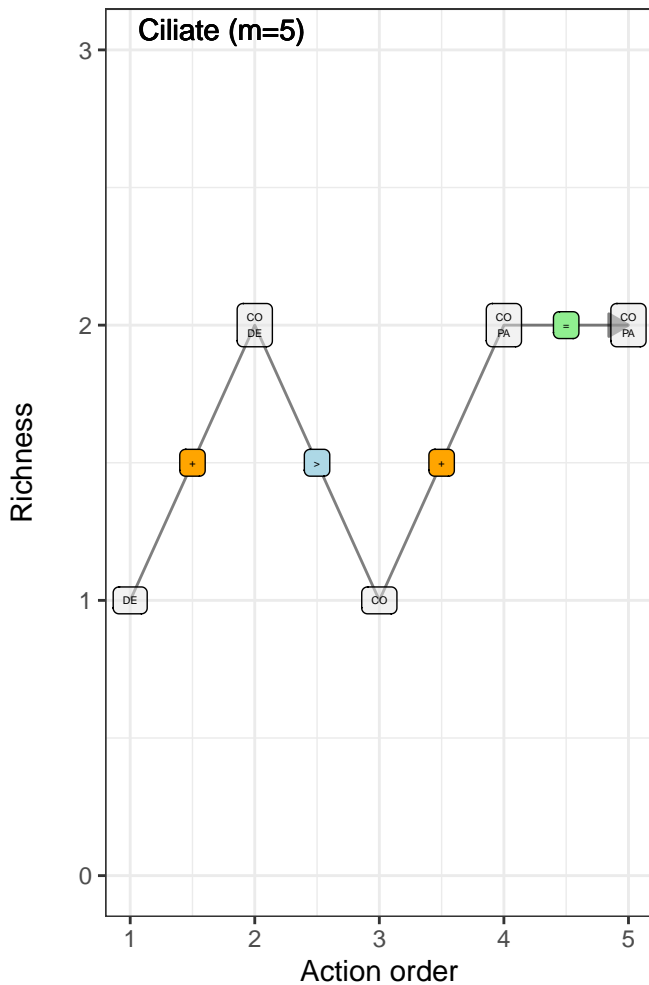
Optimal path



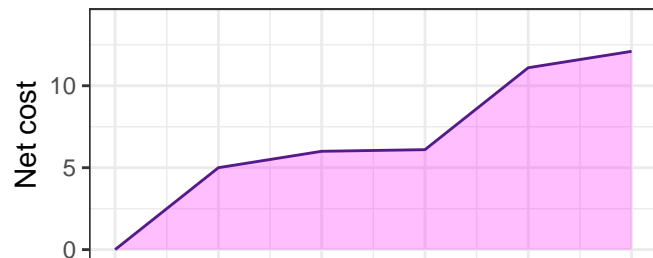
Nominal path



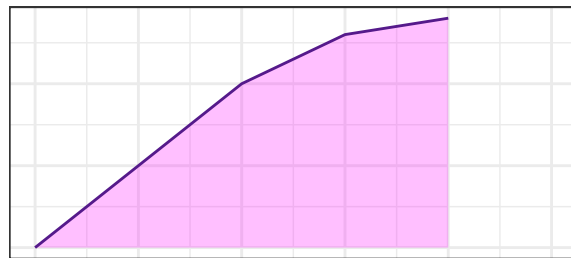
Ciliate (m=5)



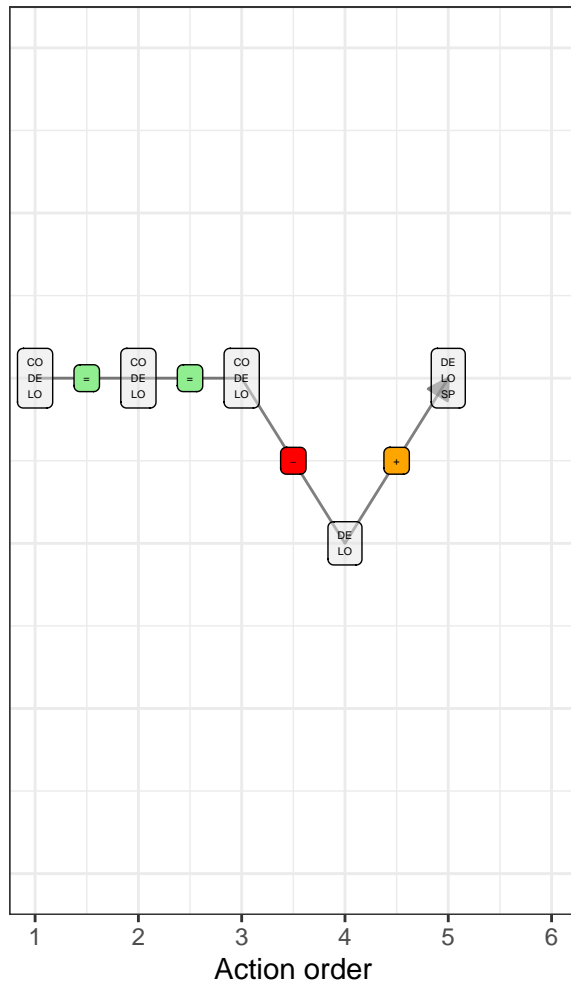
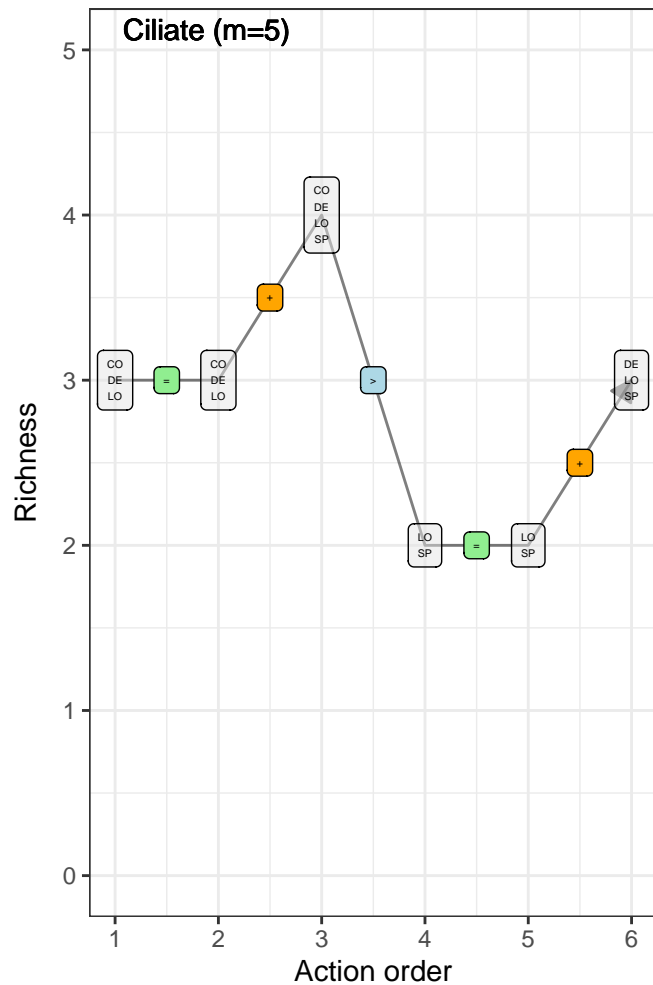
Optimal path



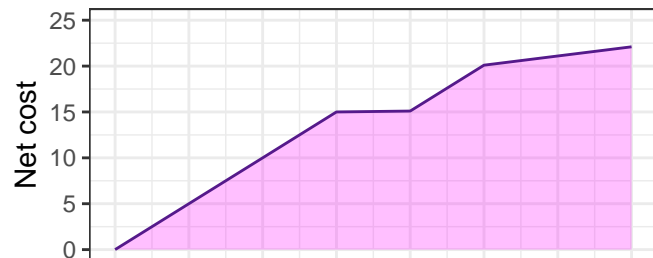
Nominal path



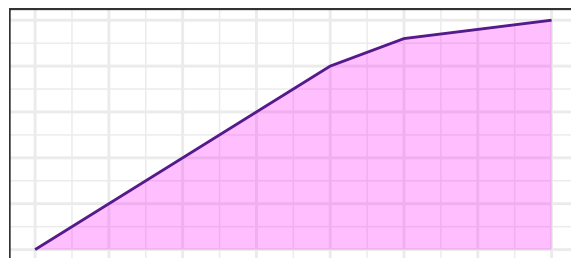
Ciliate (m=5)



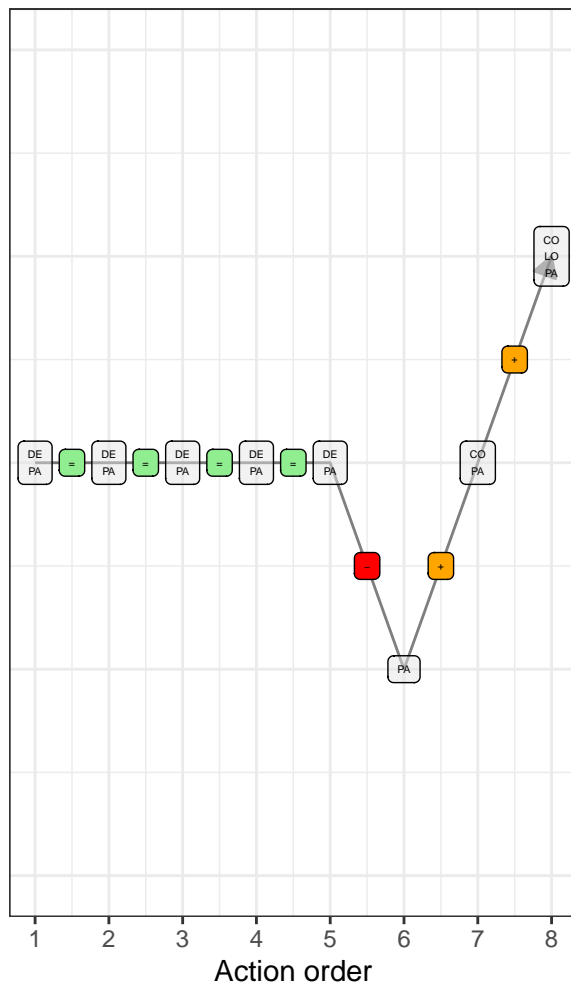
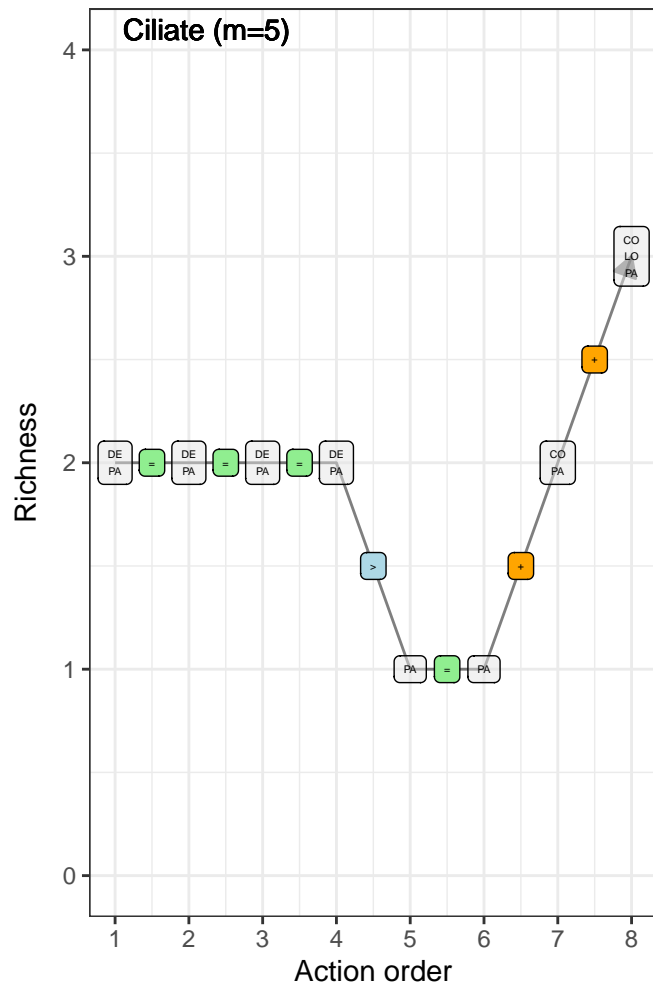
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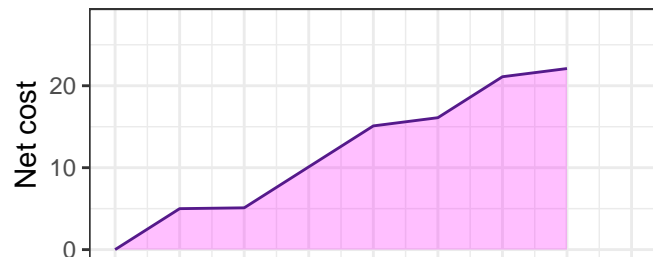
Nominal path



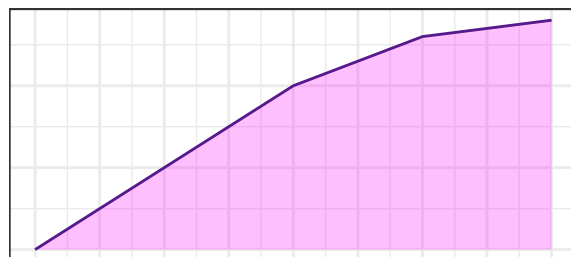
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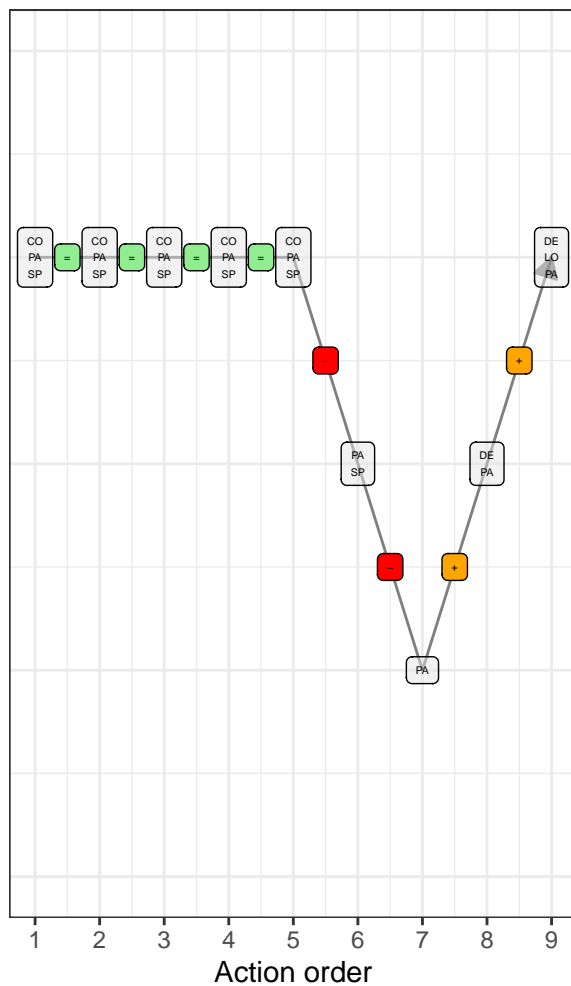
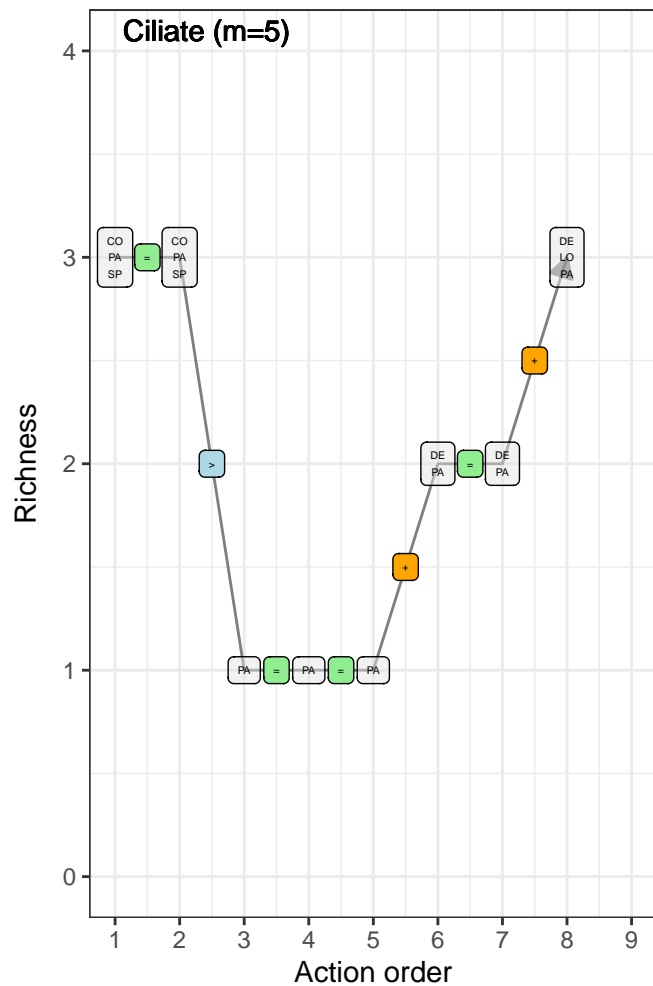
Optimal path



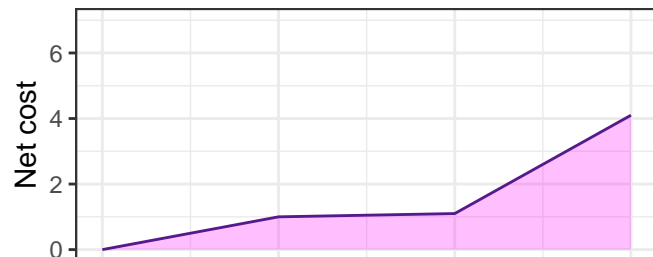
Nominal path



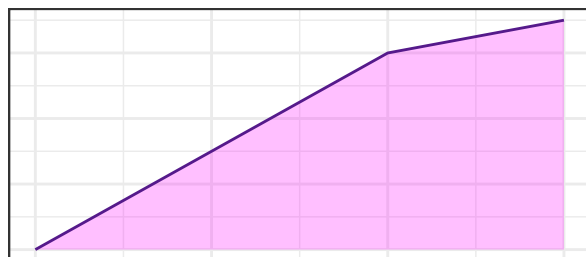
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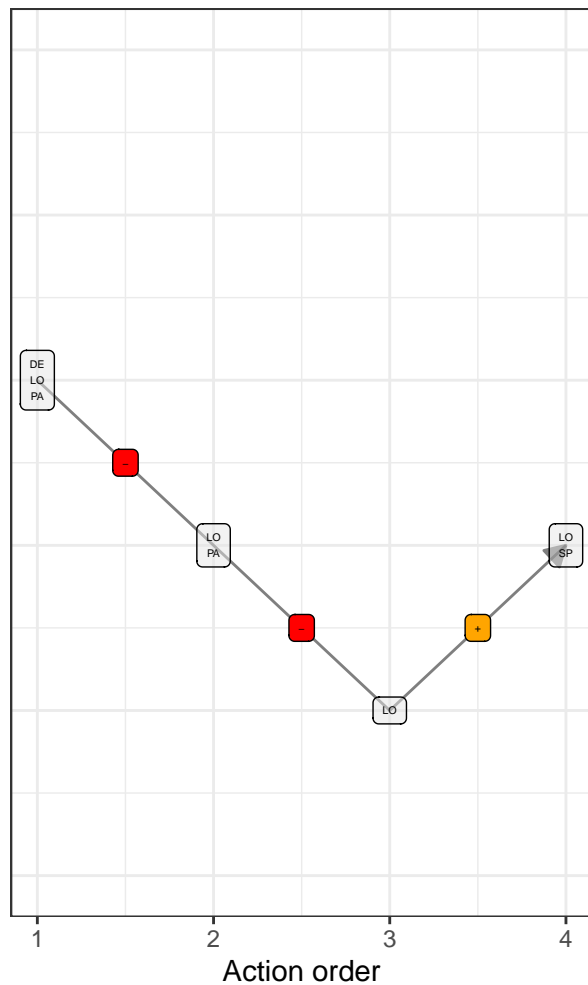
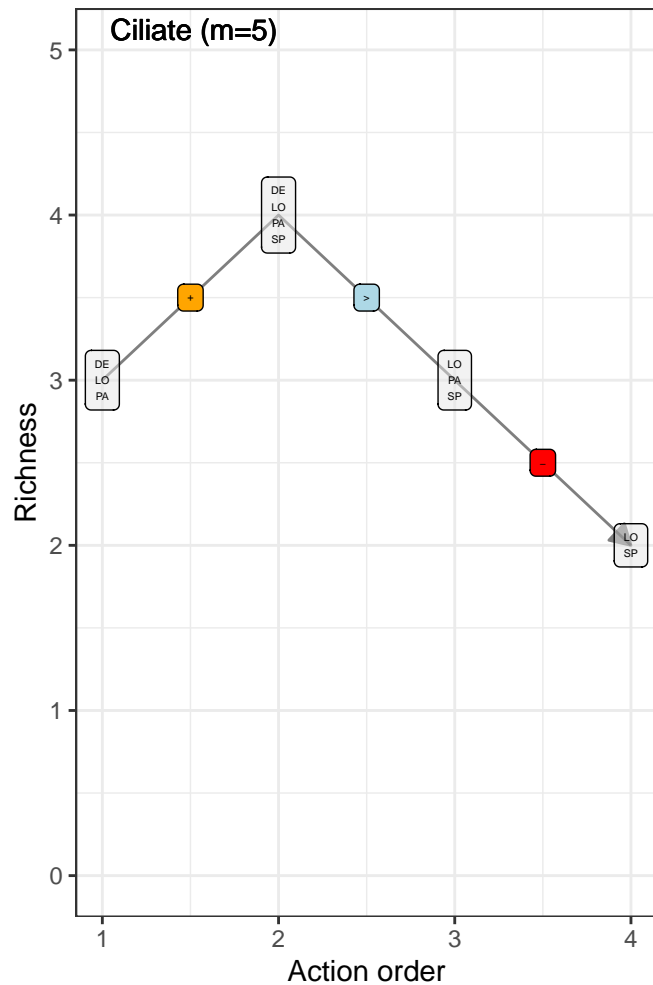
Optimal path



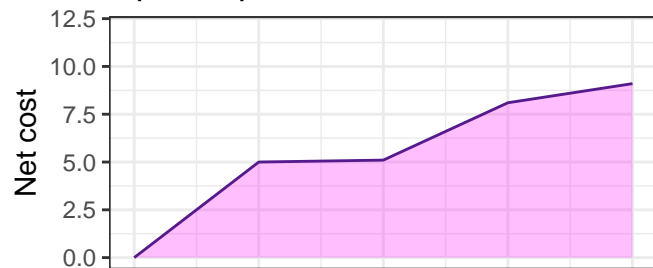
Nominal path



Ciliate (m=5)



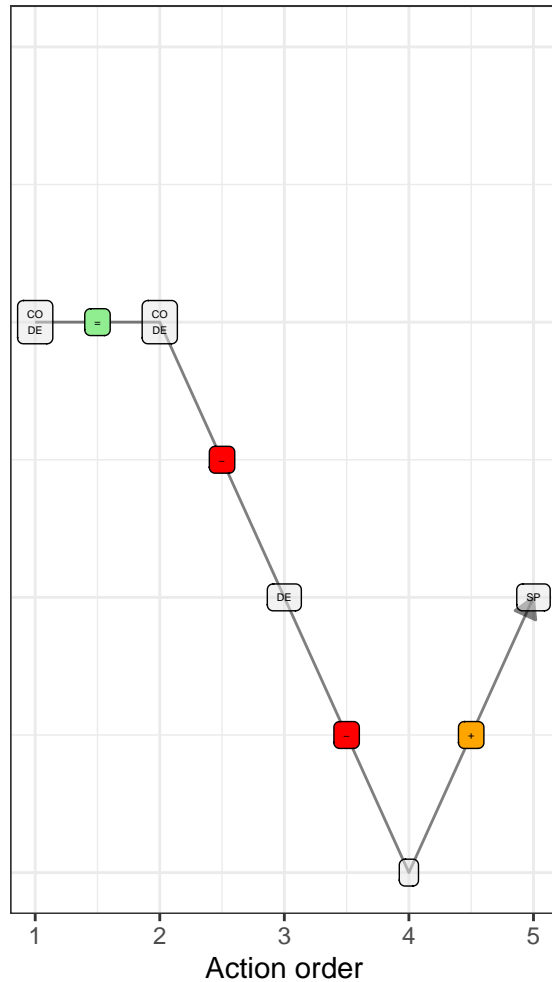
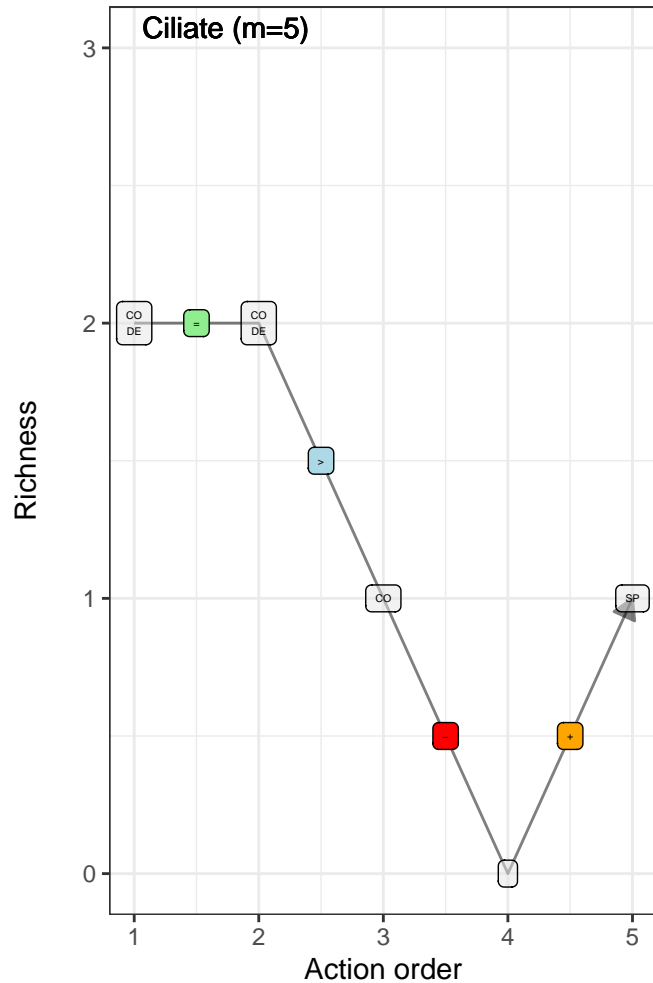
Optimal path



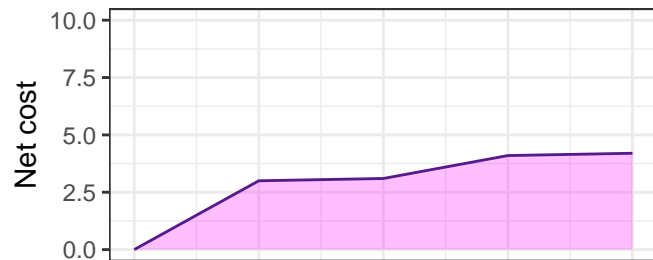
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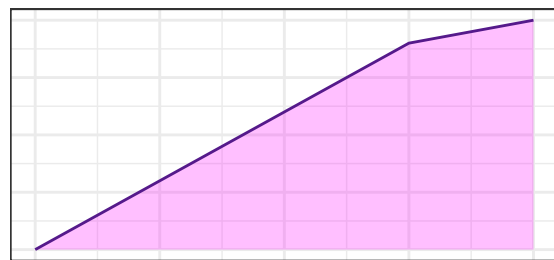
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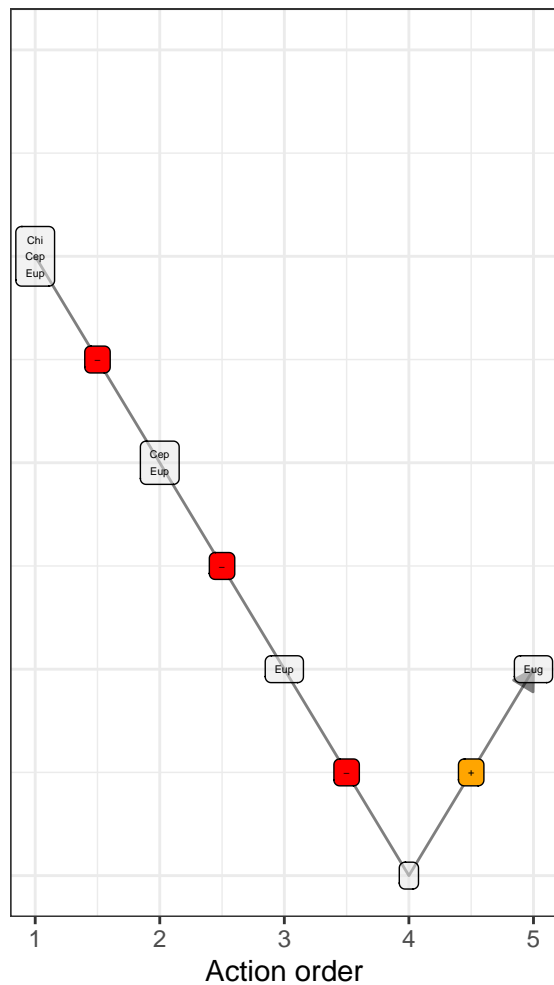
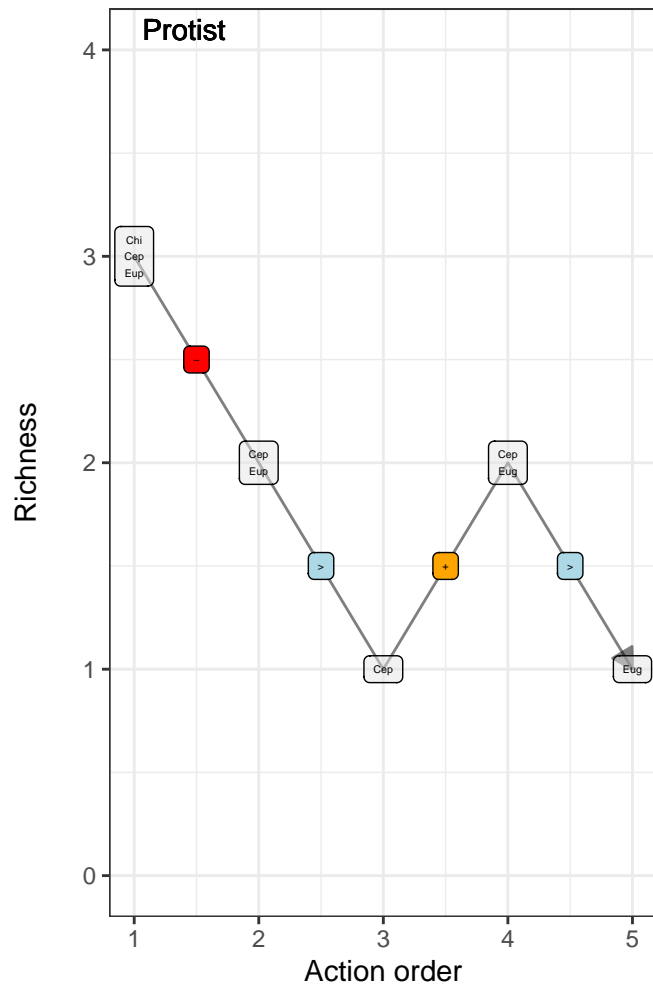
Optimal path



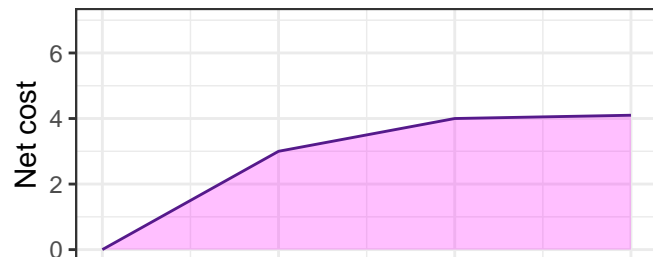
Nominal path



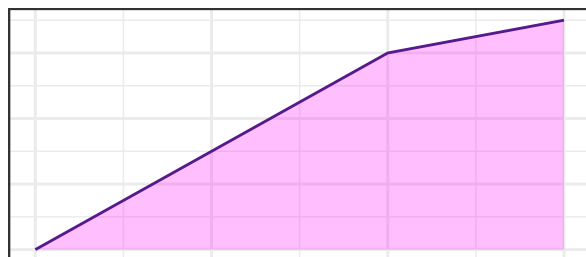
Protist



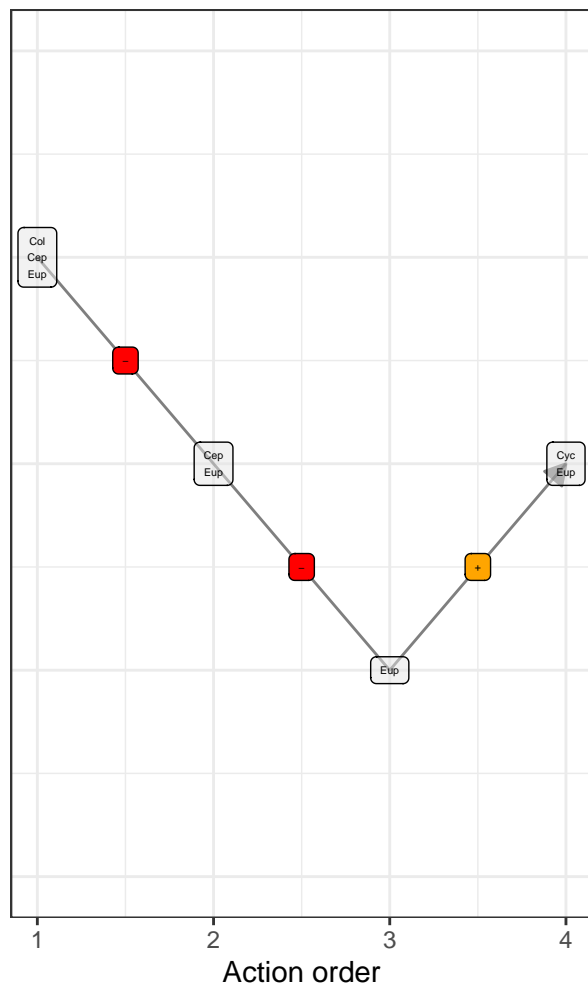
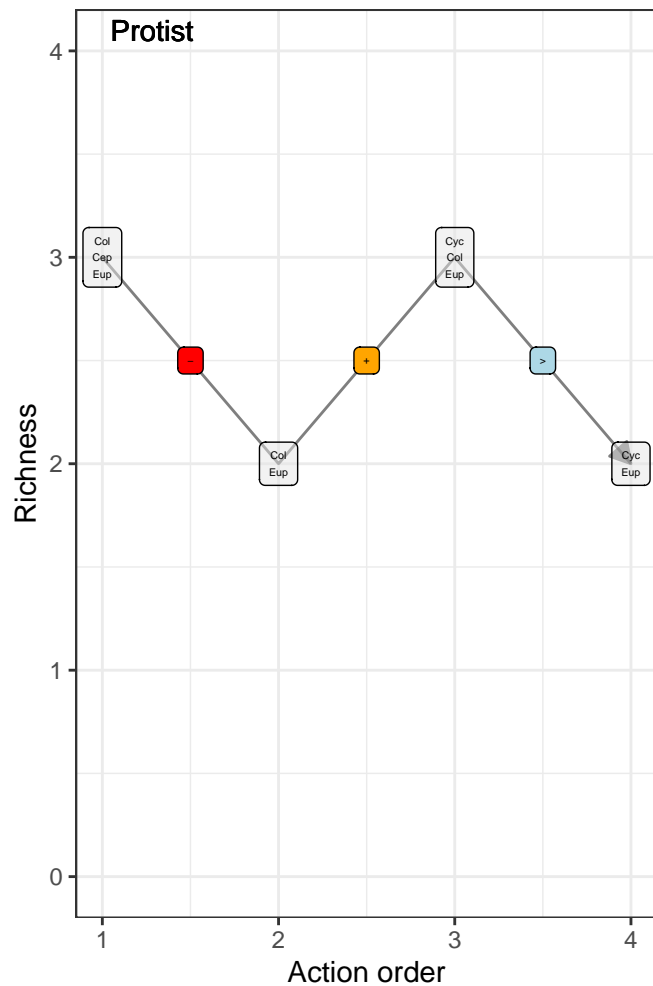
Optimal path



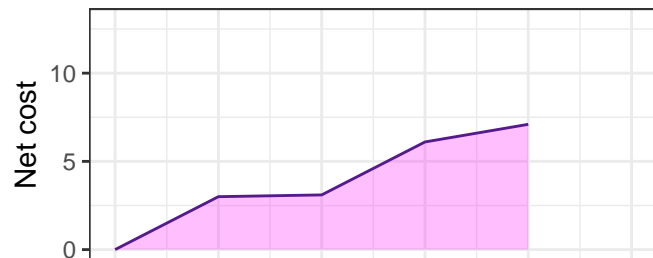
Nominal path



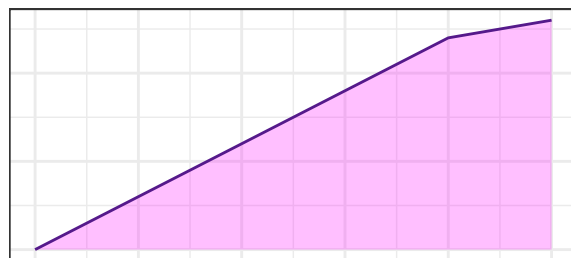
Protist



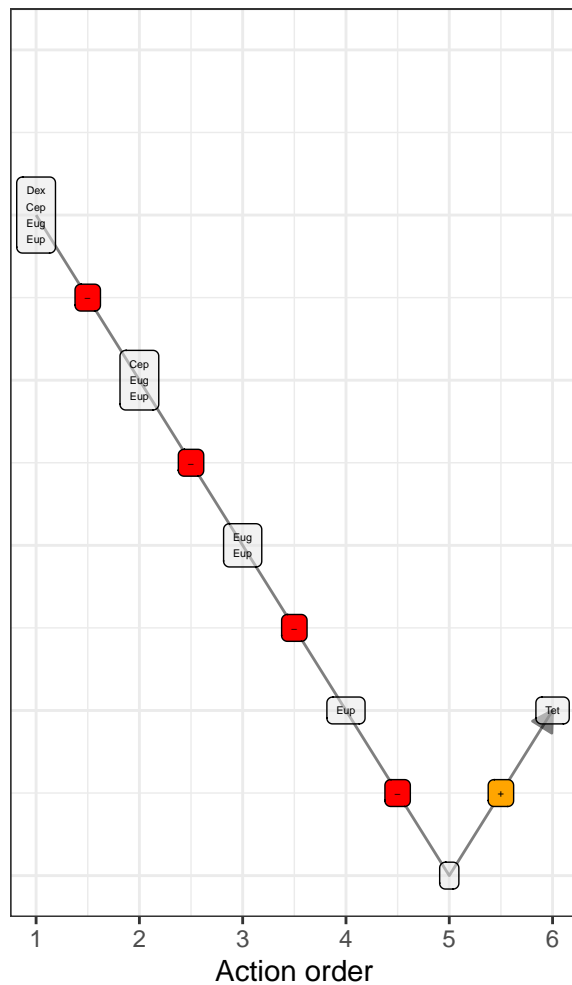
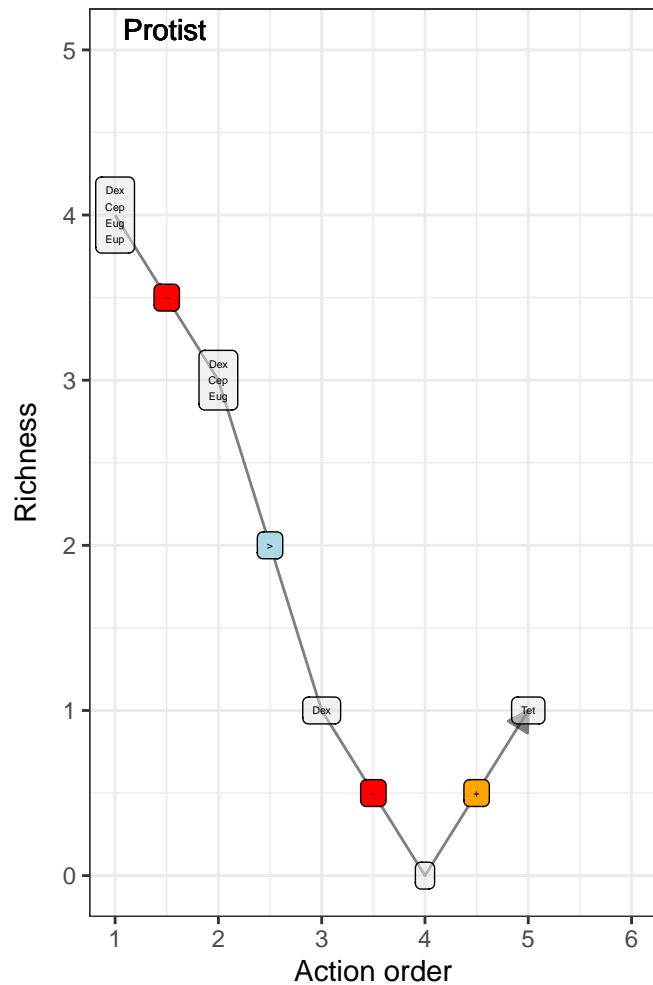
Optimal path



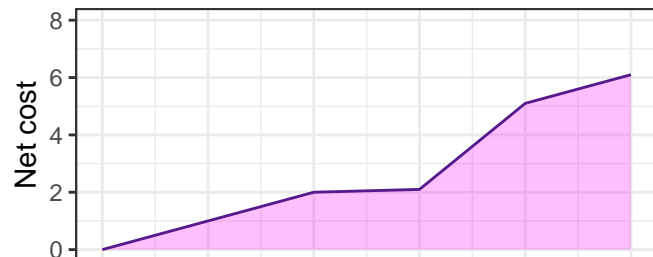
Nominal path



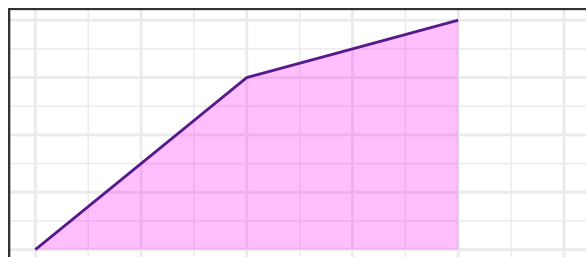
Protist



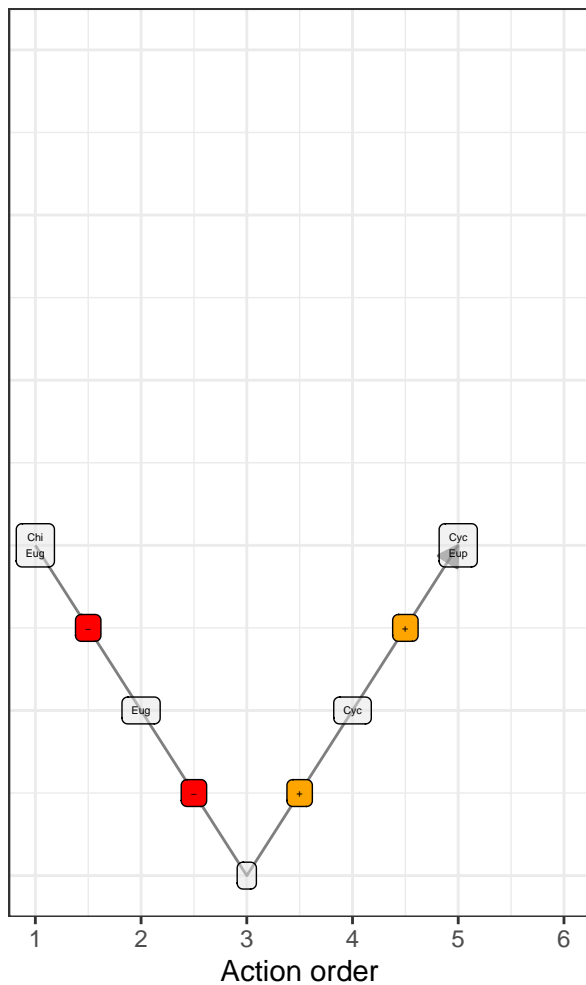
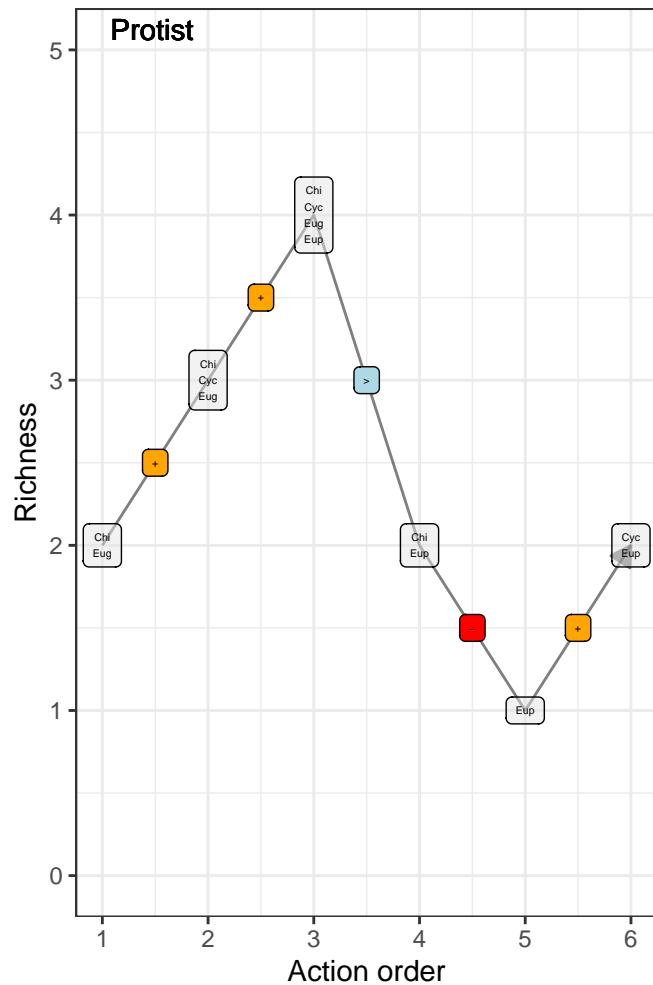
Optimal path



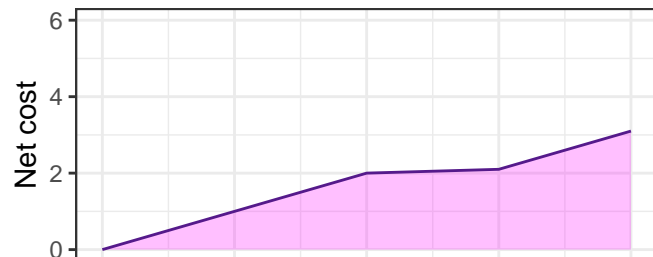
Nominal path



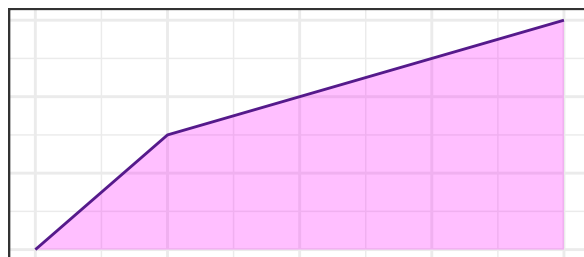
Protist



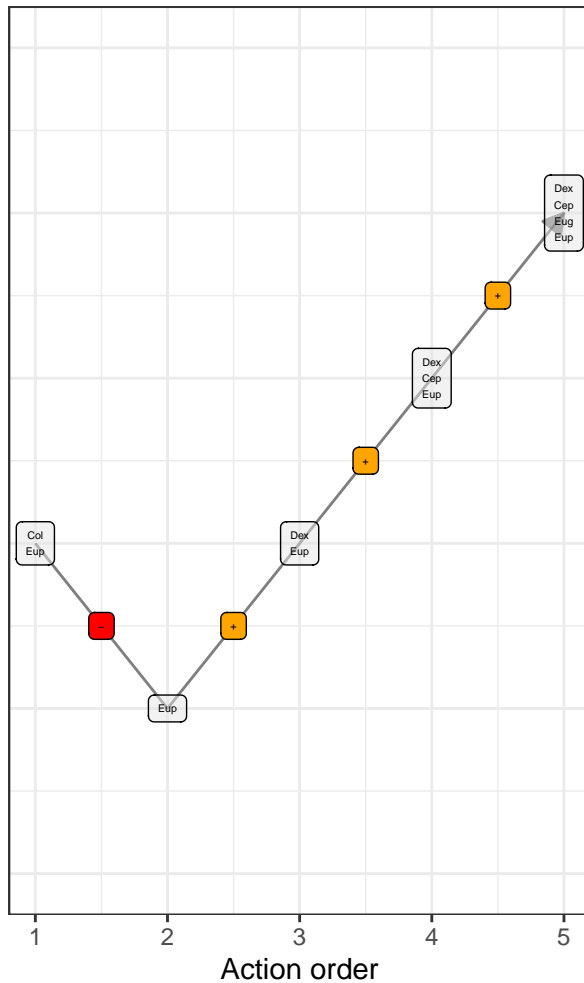
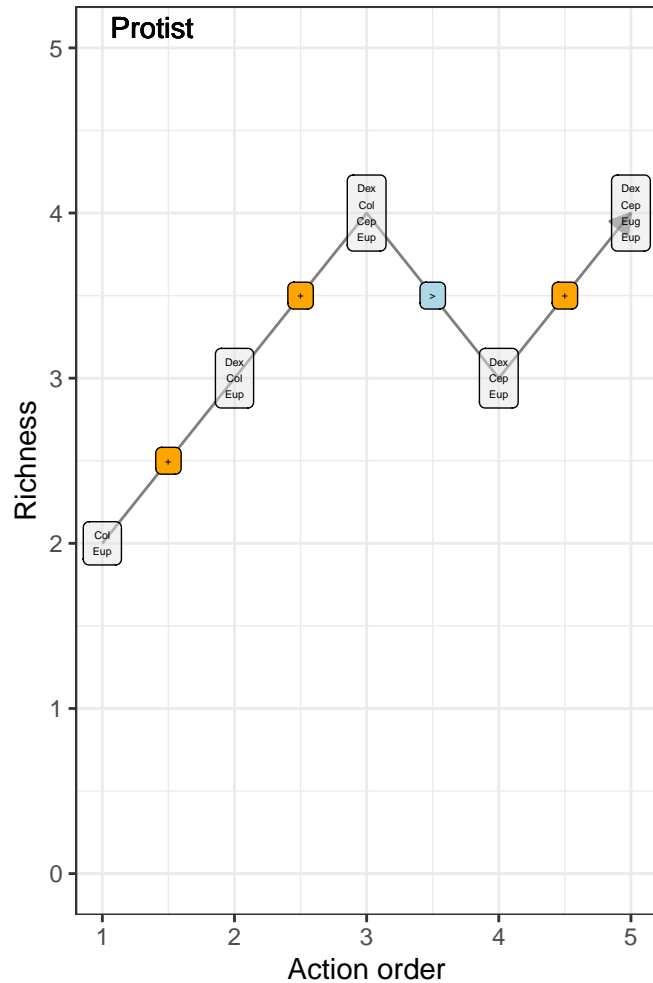
Optimal path



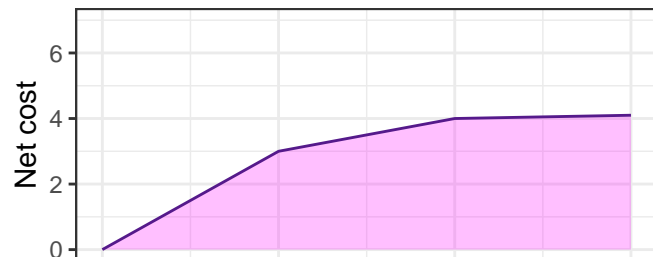
Nominal path



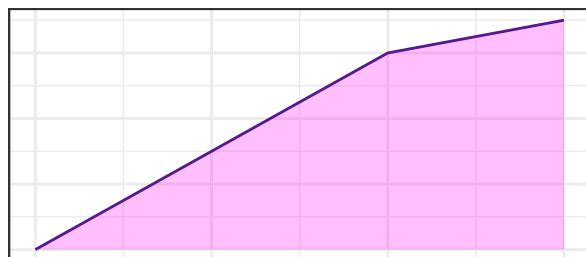
Protist



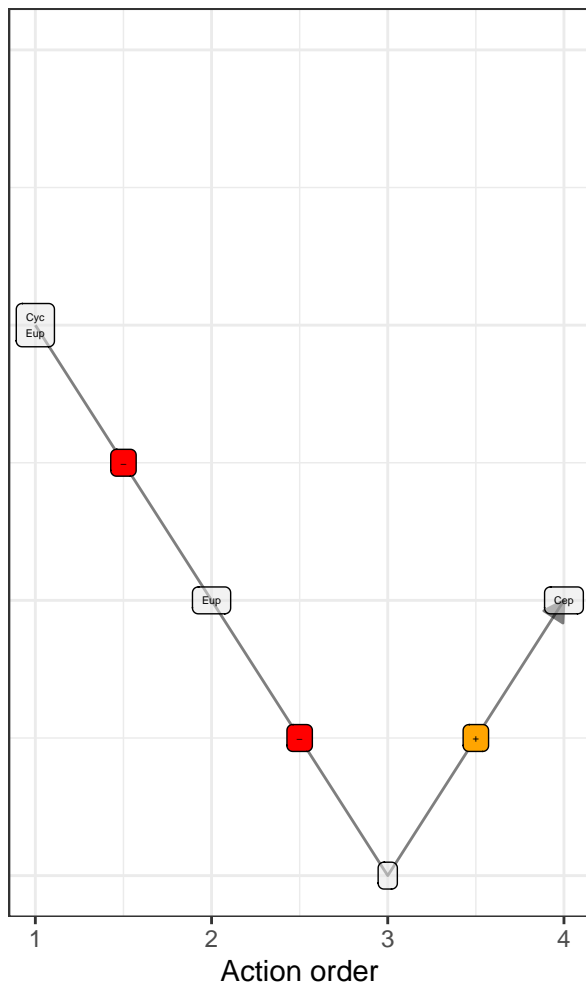
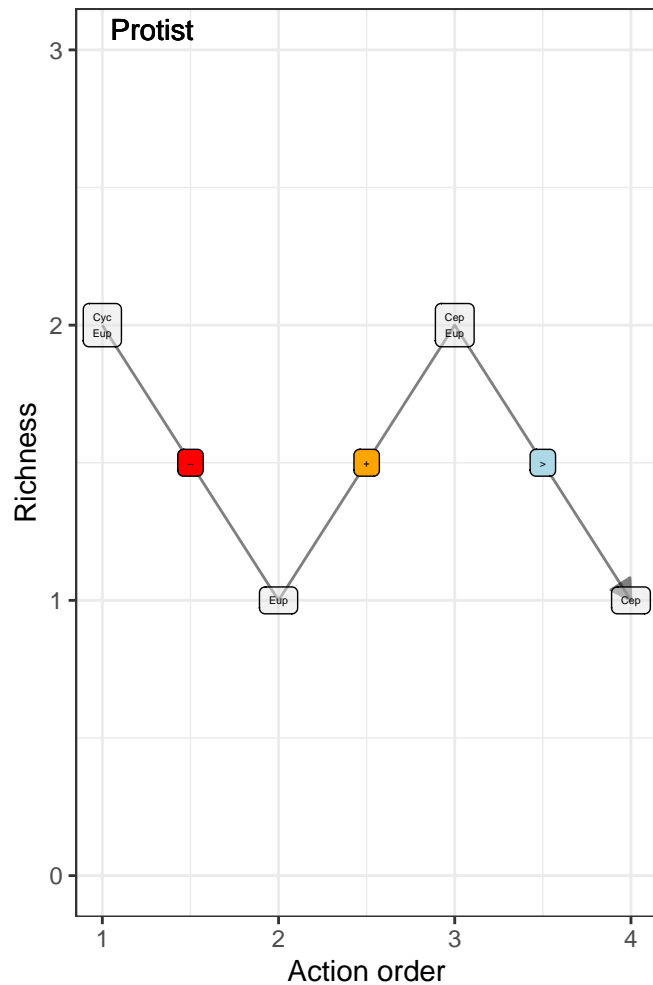
Optimal path



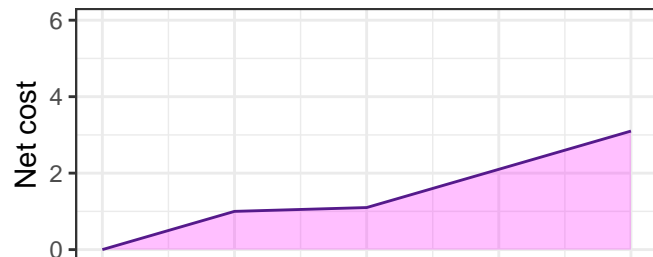
Nominal path



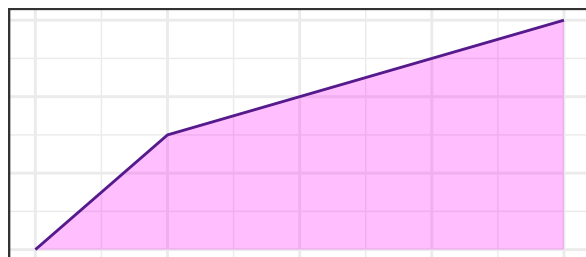
Protist



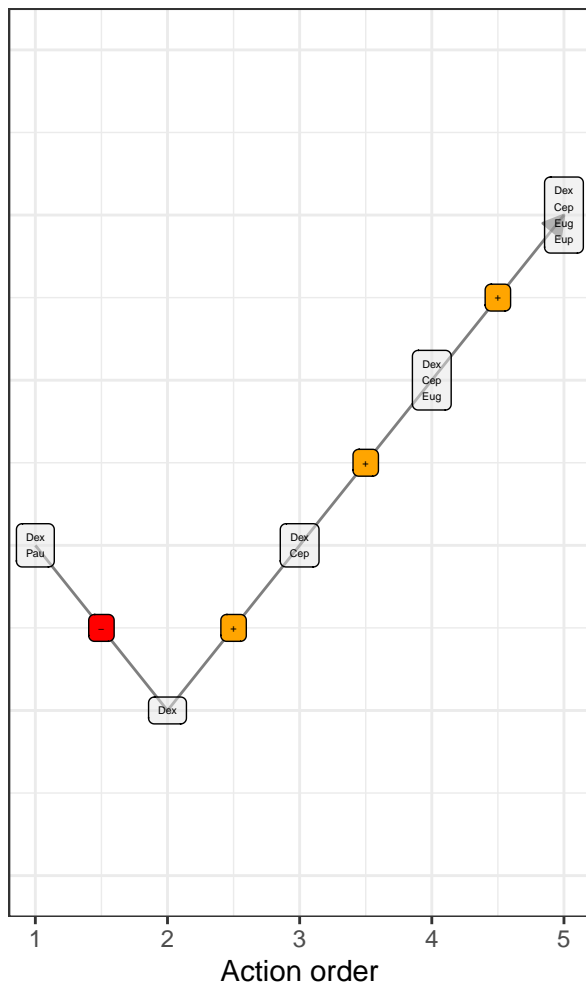
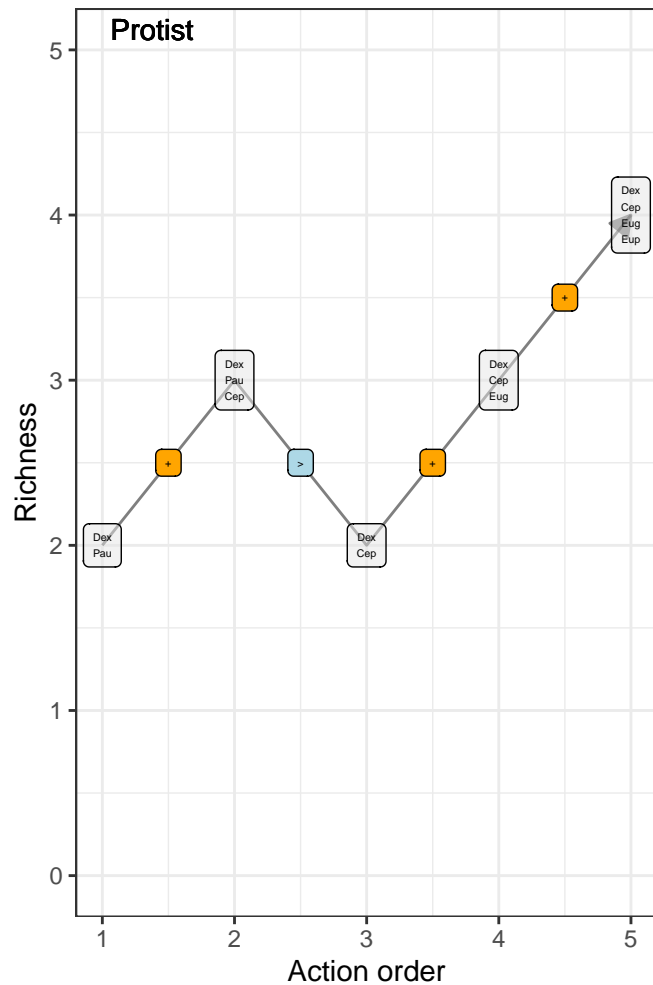
Optimal path



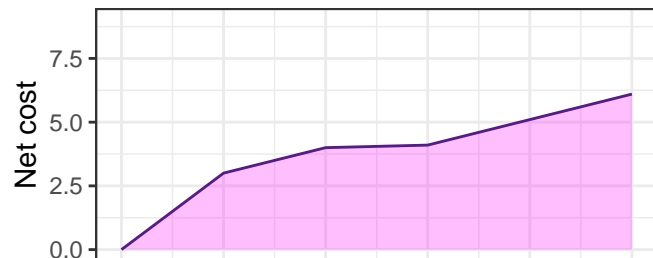
Nominal path



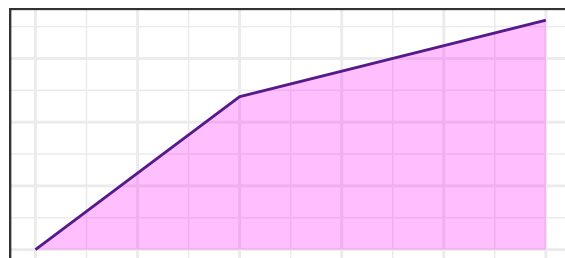
Protist



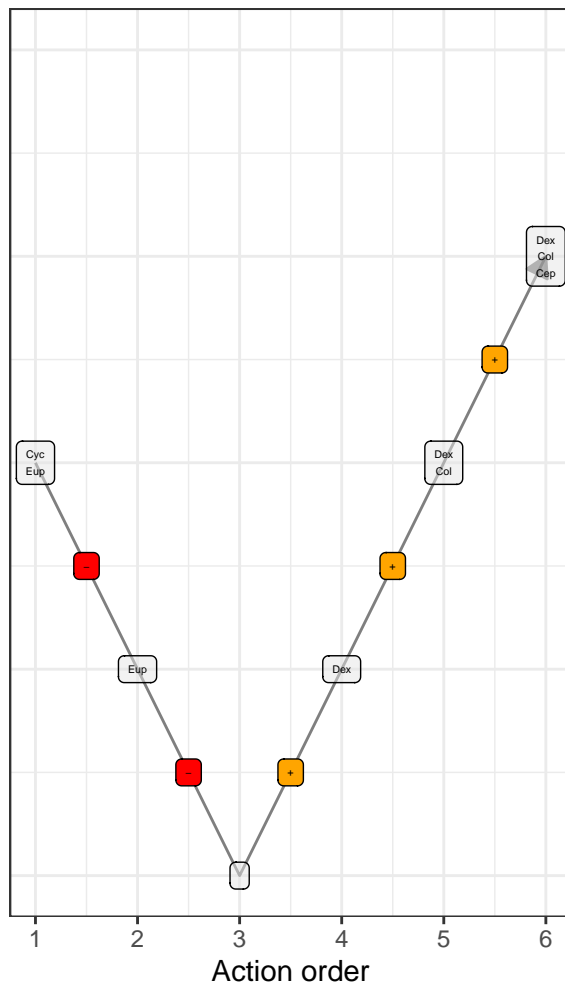
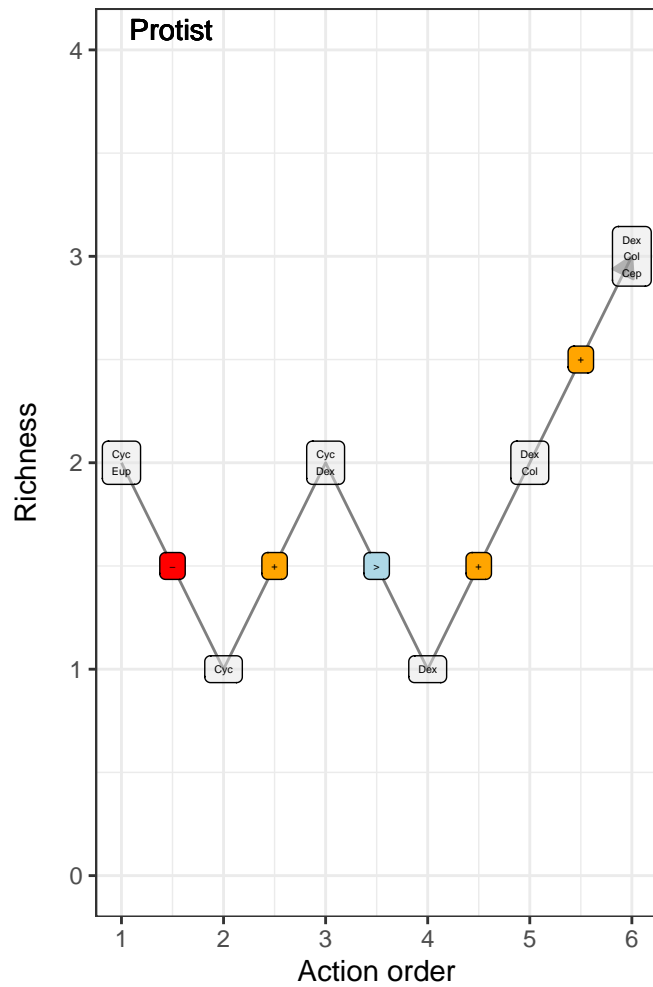
Optimal path



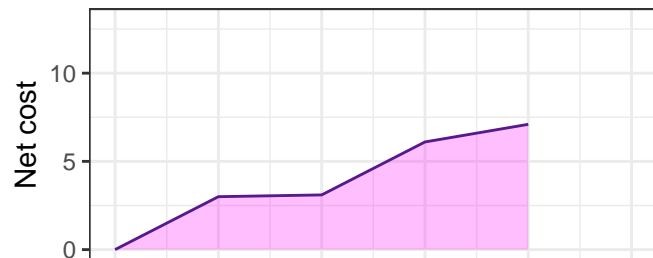
Nominal path



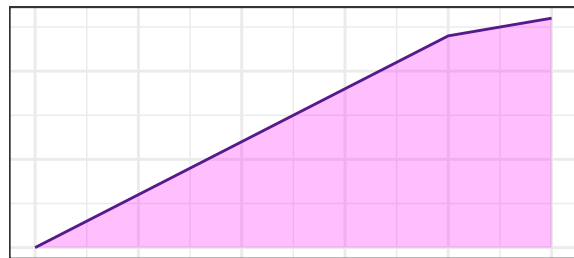
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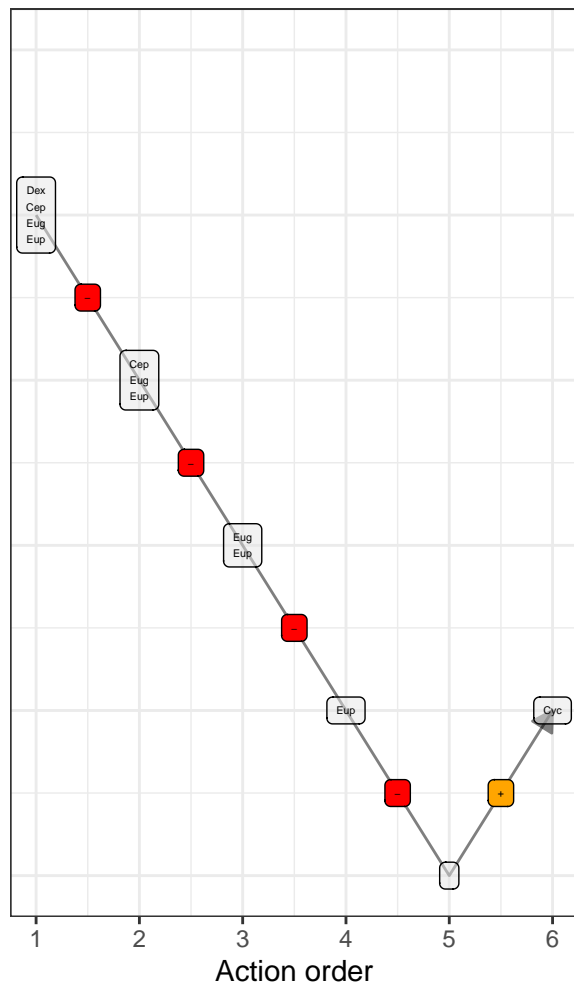
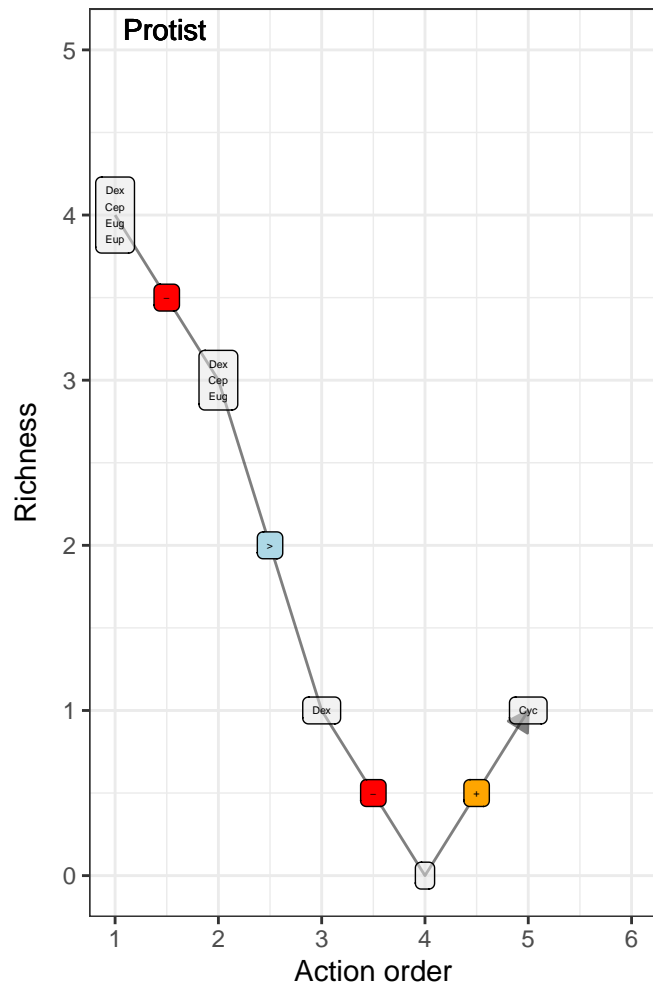
Optimal path



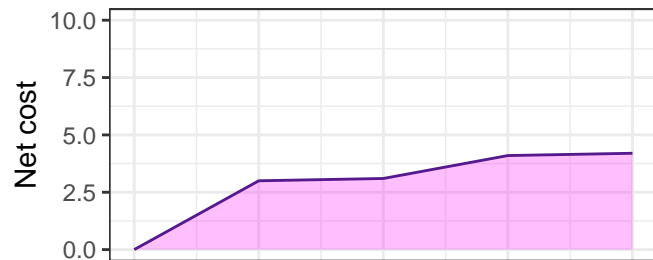
Nominal path



Protist



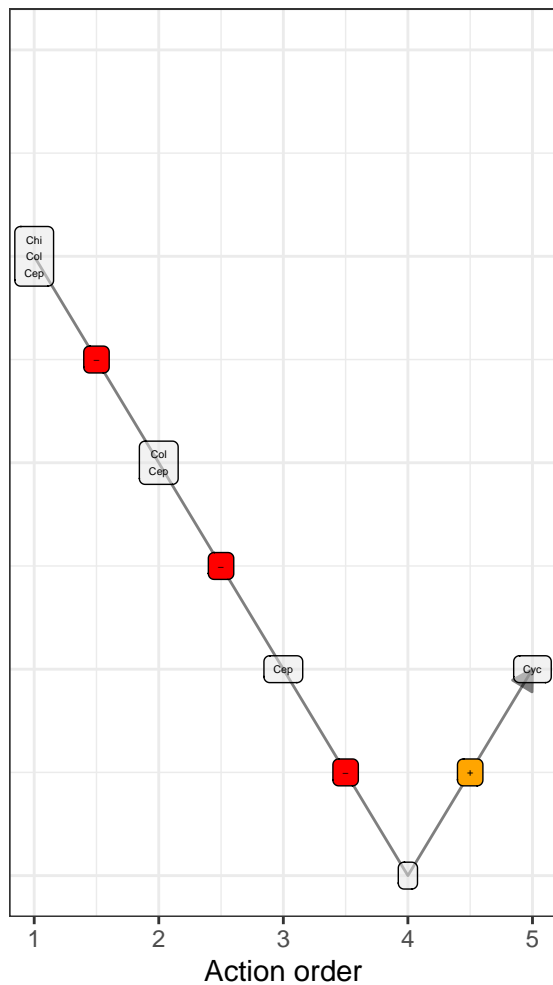
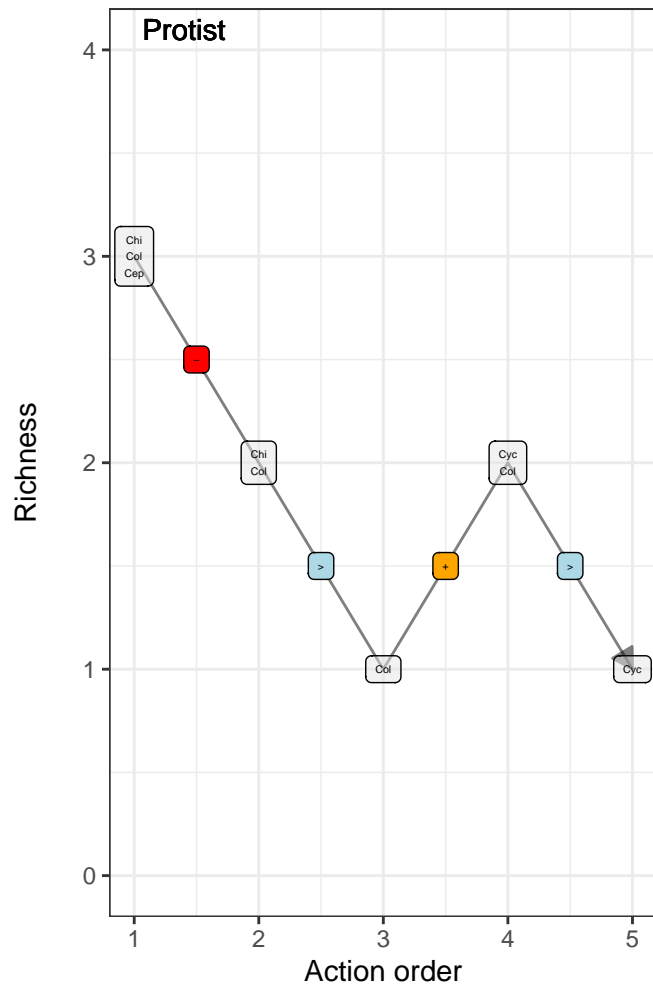
Optimal path



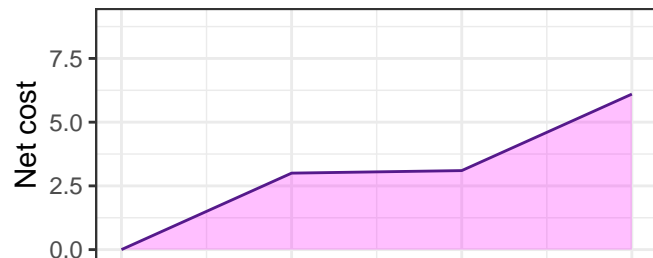
Nominal path



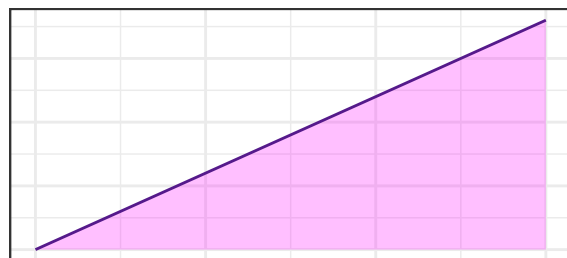
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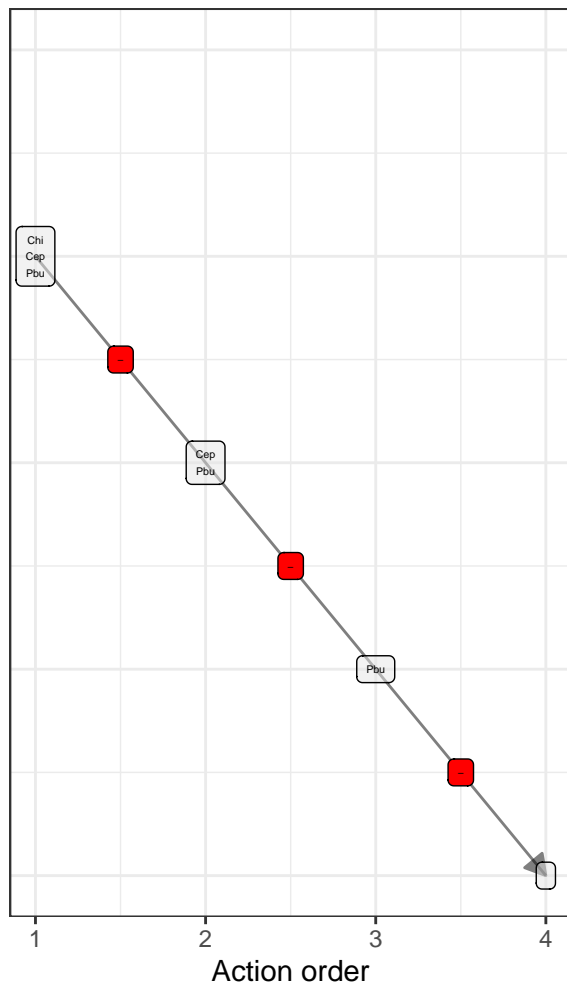
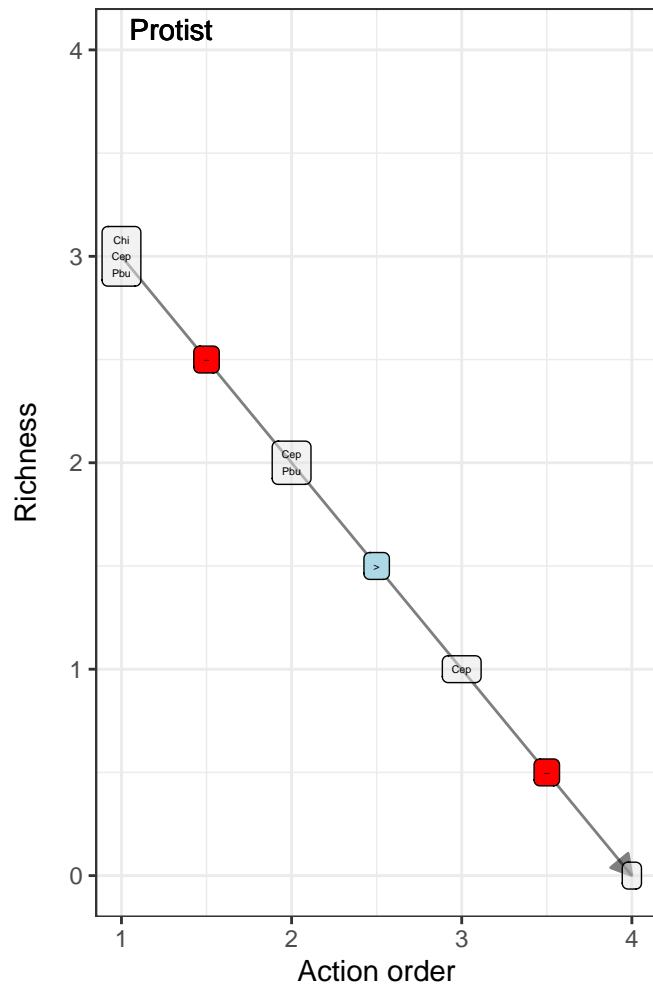
Optimal path



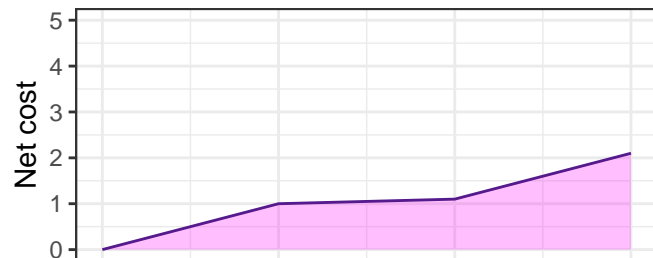
Nominal path



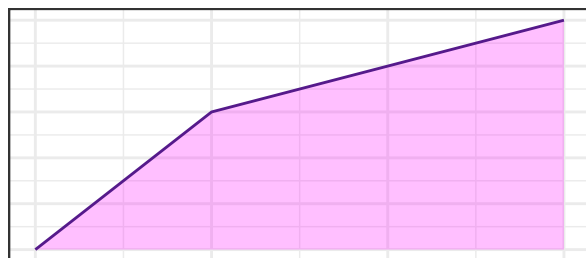
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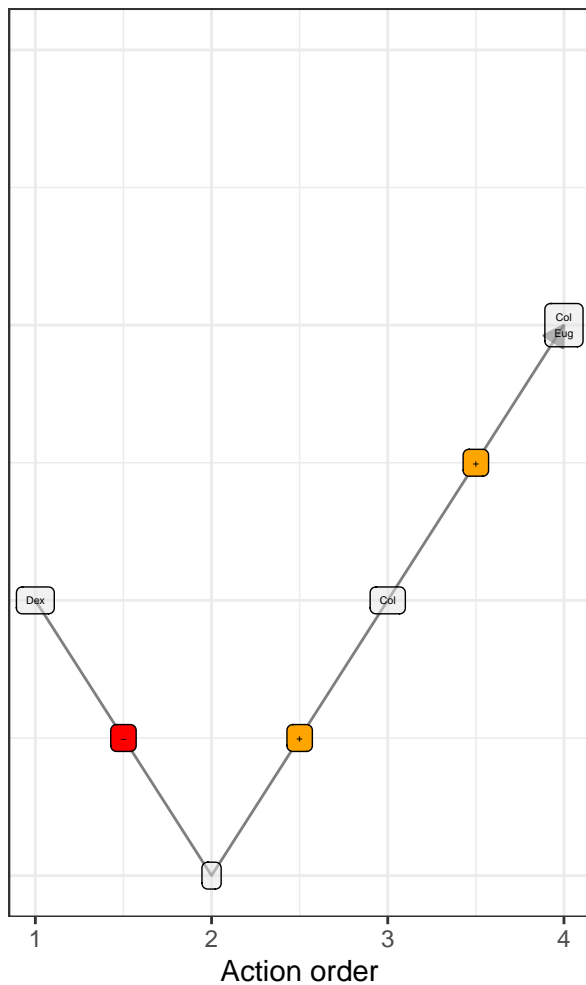
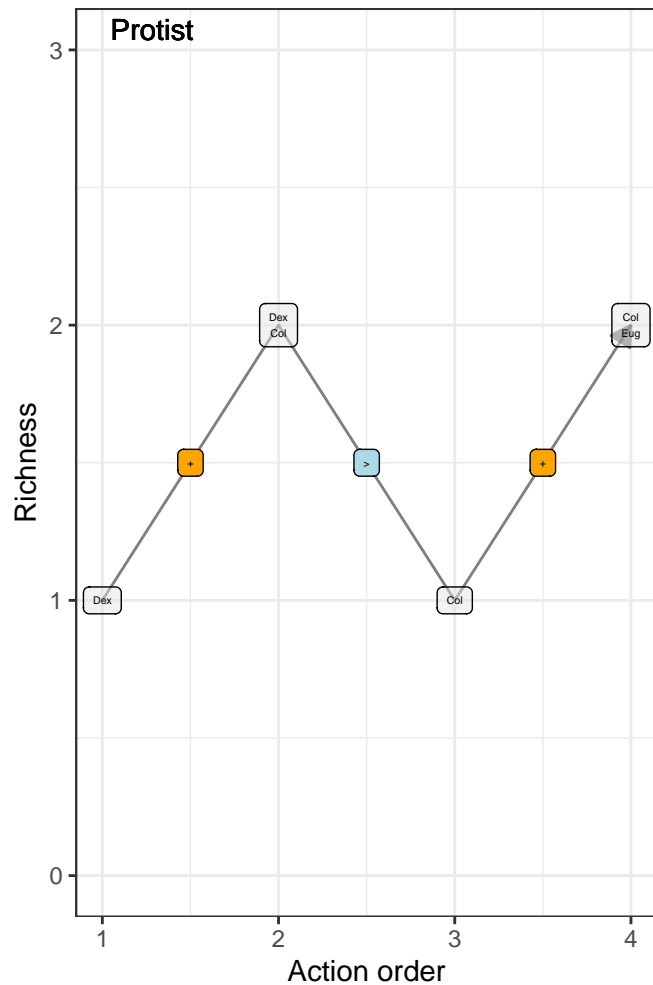
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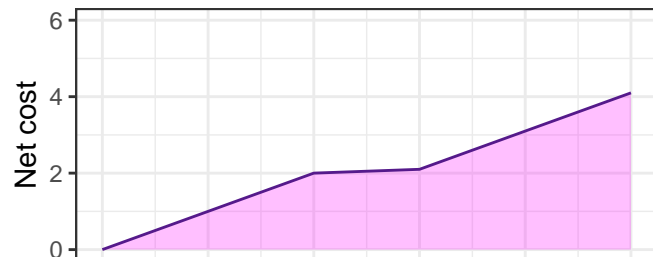
Nominal path



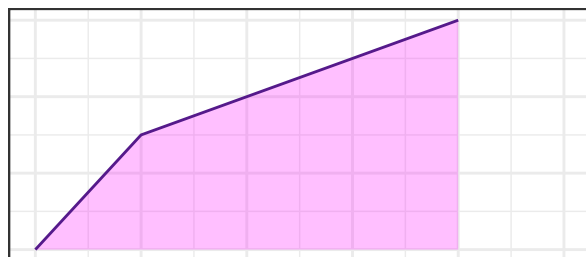
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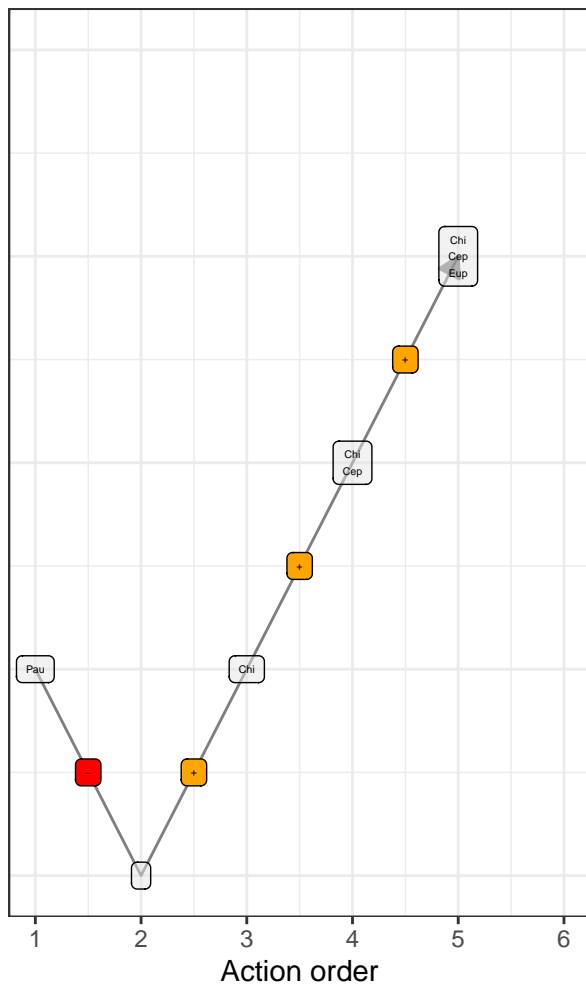
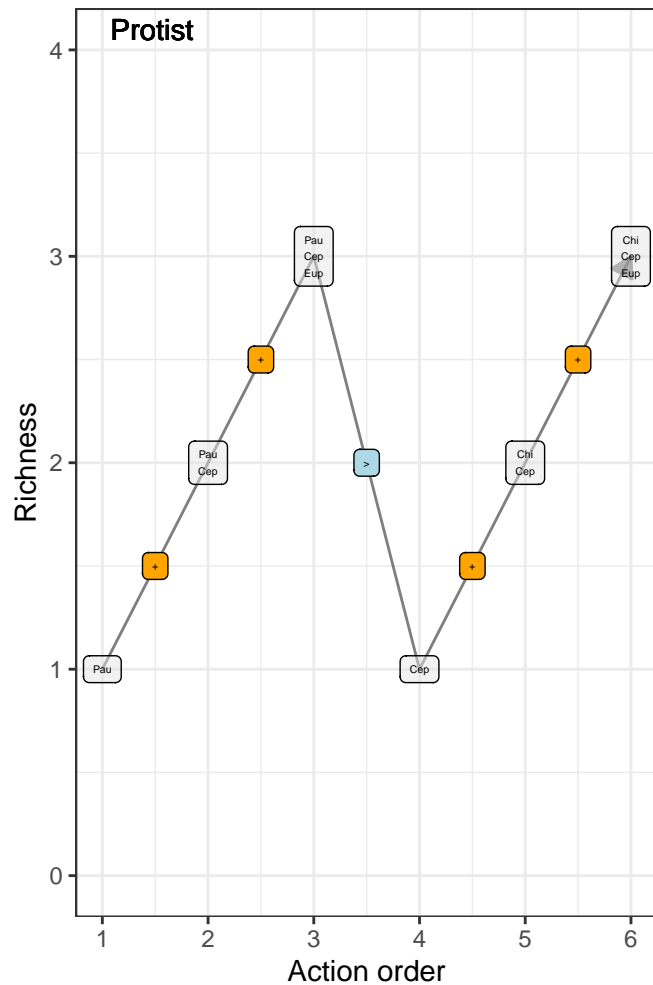
Optimal path



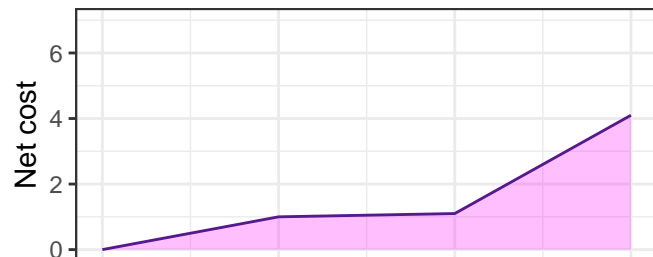
Nominal path



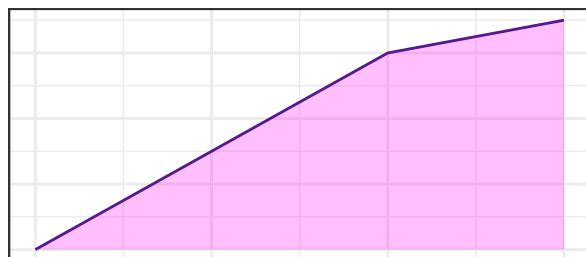
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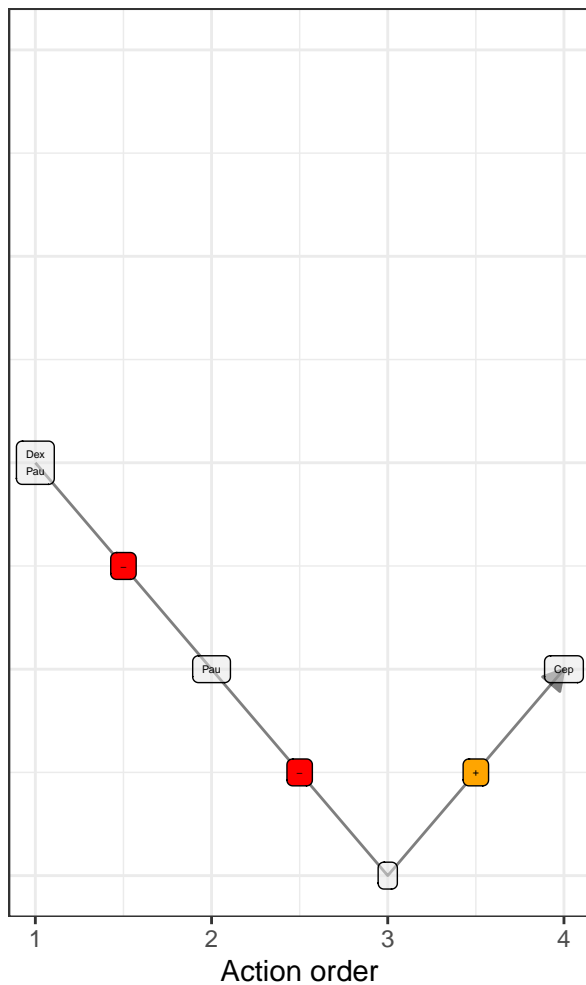
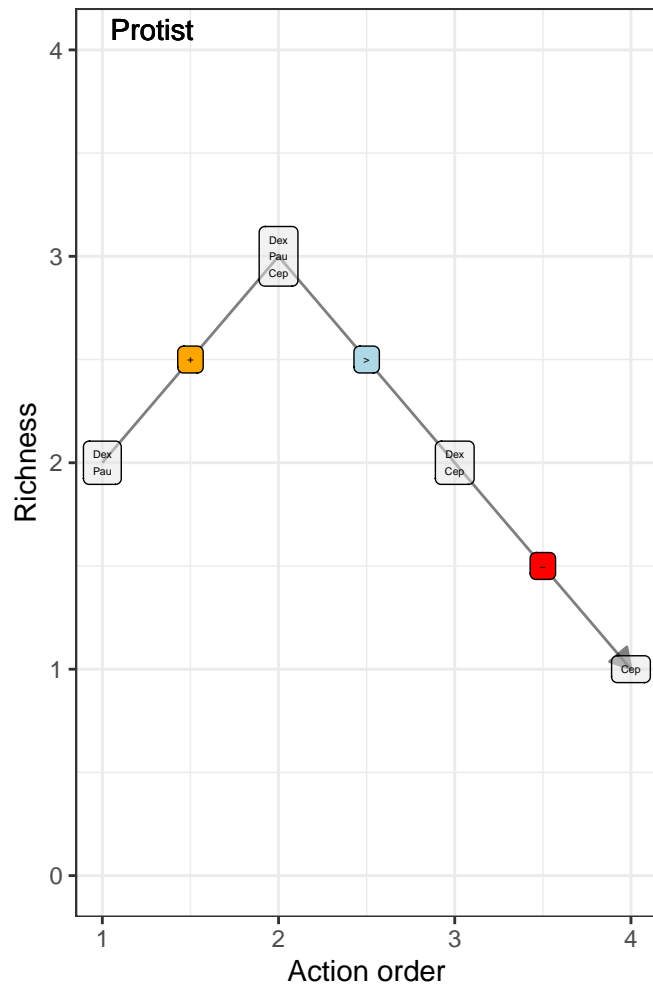
Optimal path



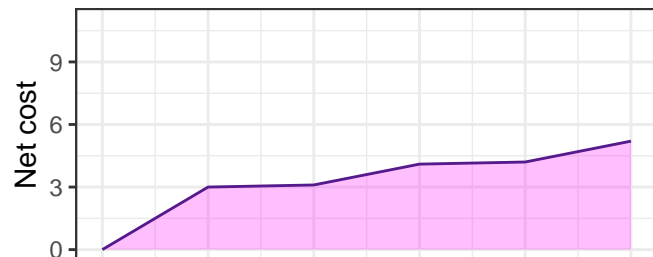
Nominal path



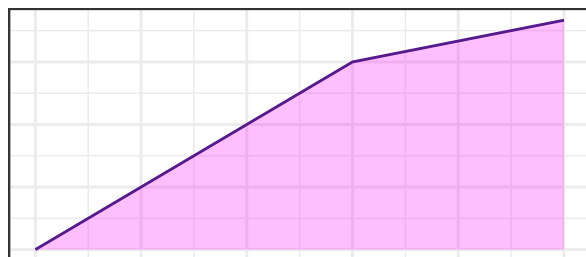
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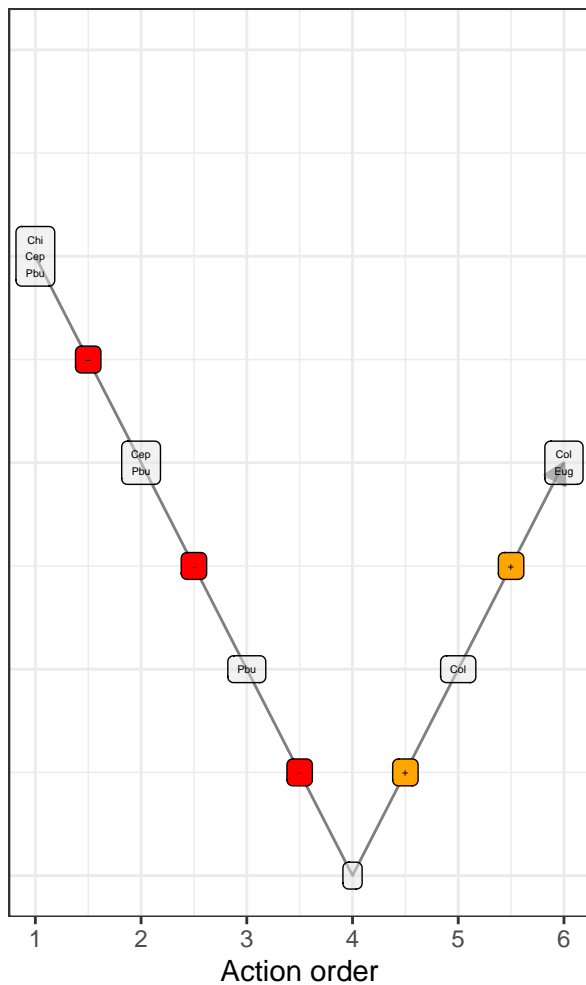
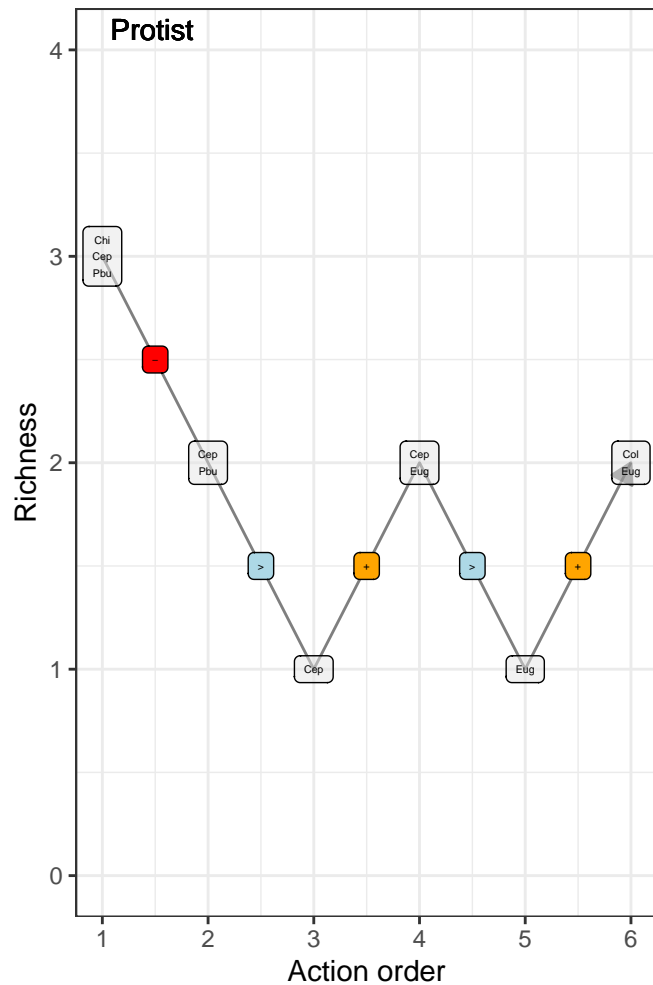
Optimal path



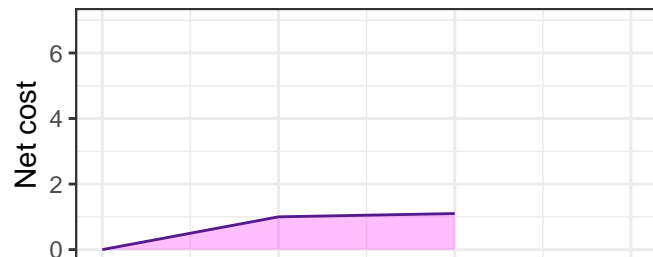
Nominal path



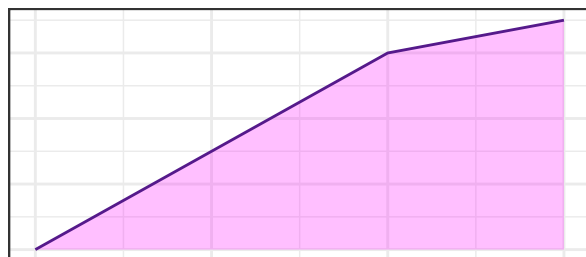
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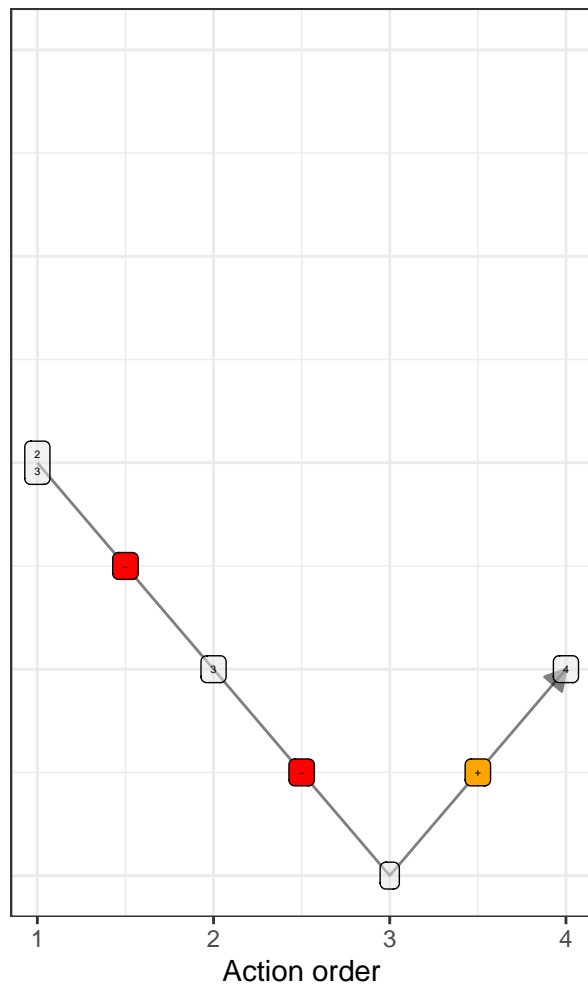
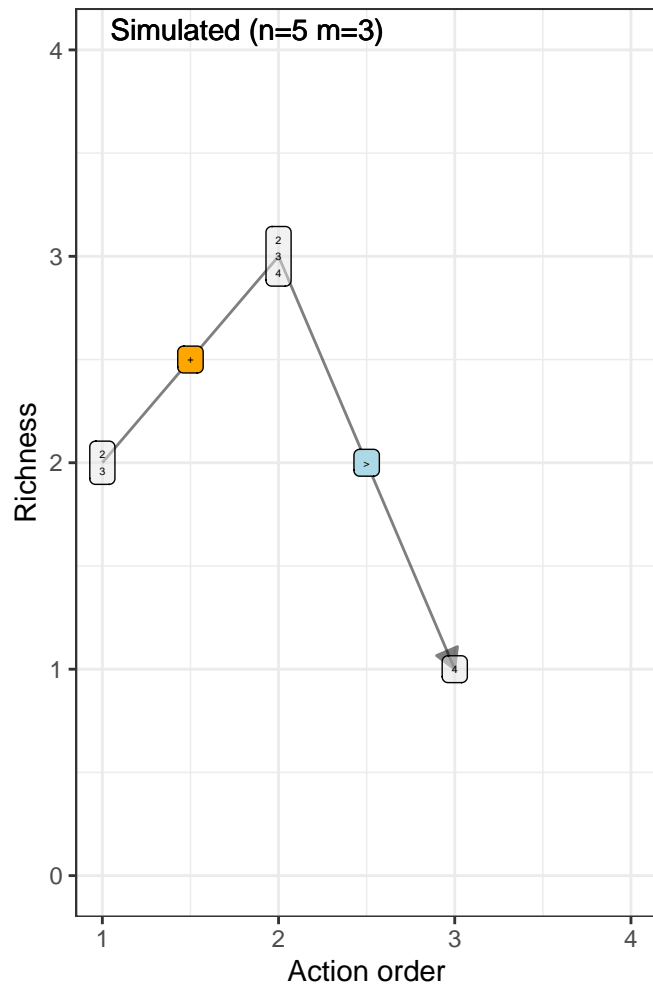
Optimal path



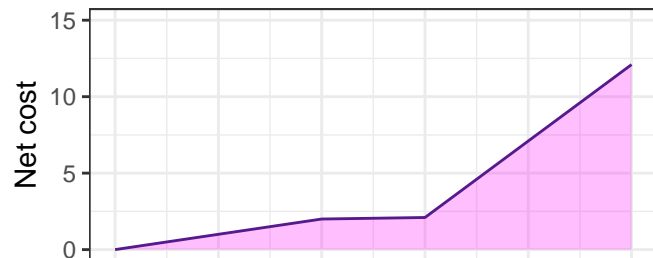
Nominal path



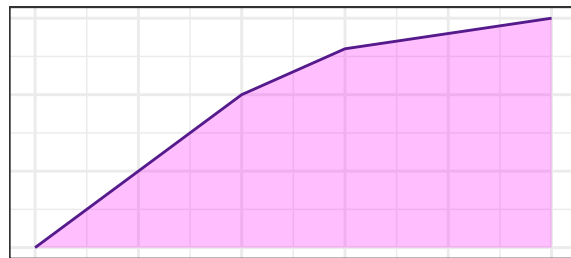
Simulated (n=5 m=3)



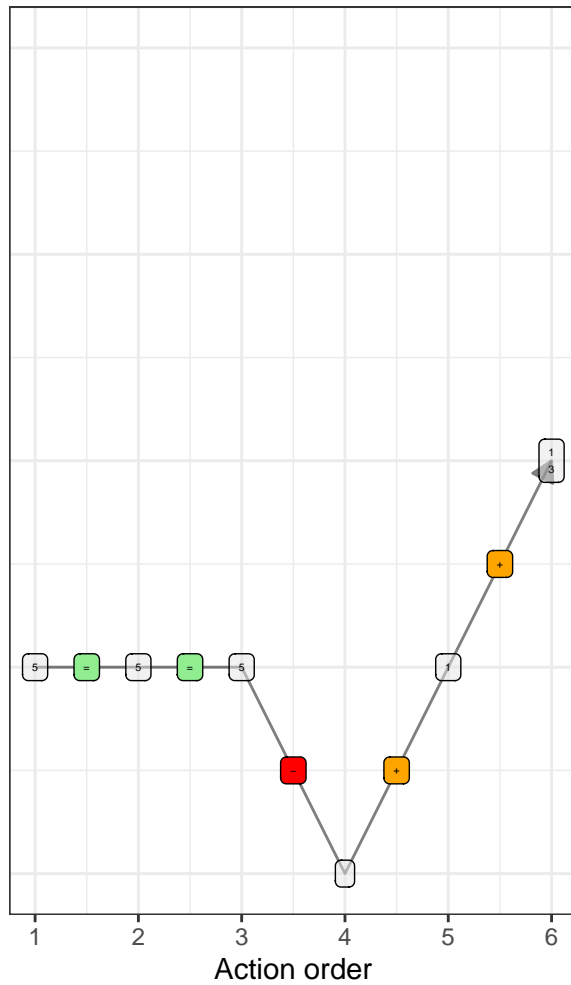
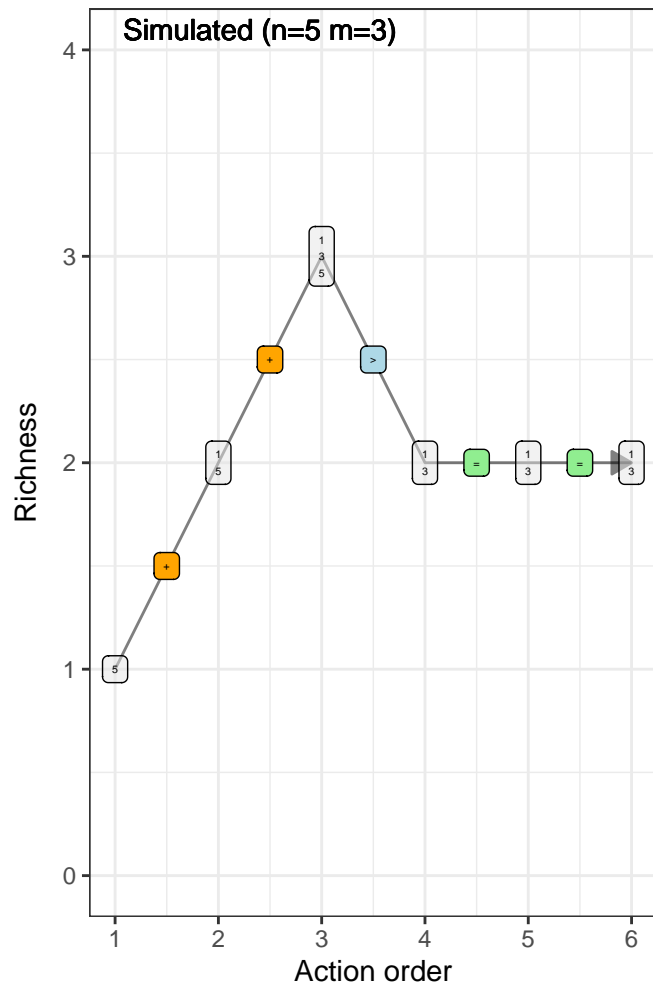
Optimal path



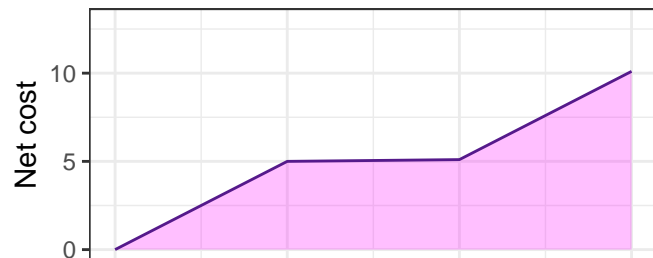
Nominal path



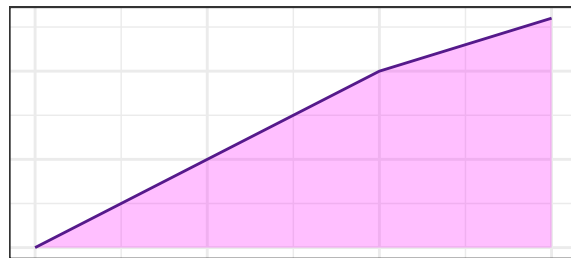
Simulated (n=5 m=3)



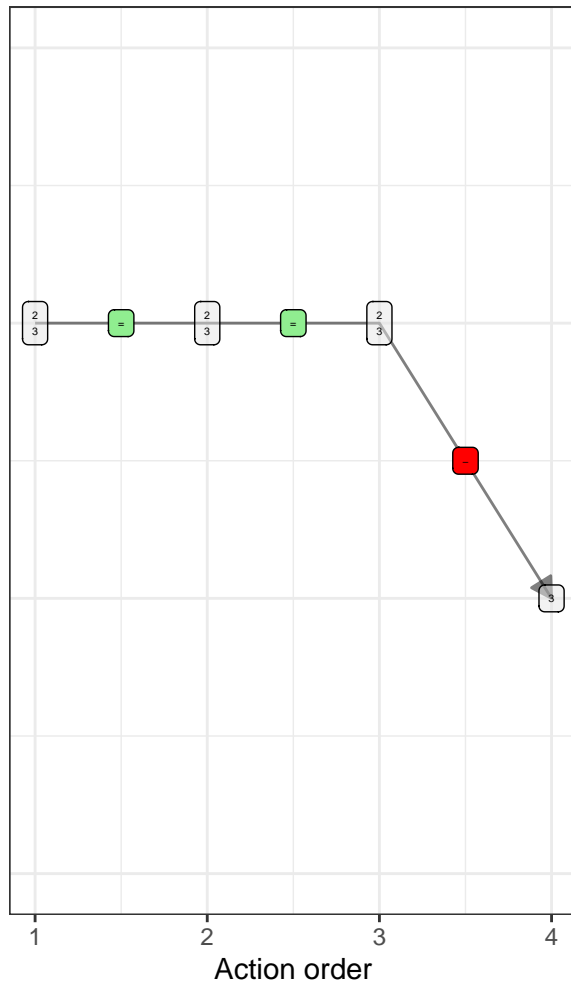
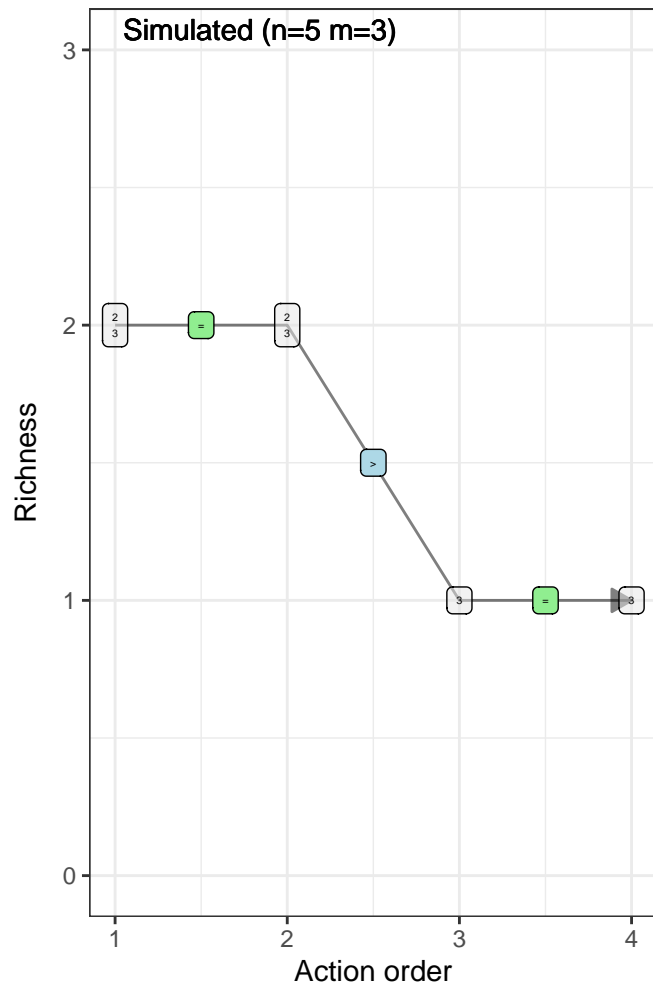
Optimal path



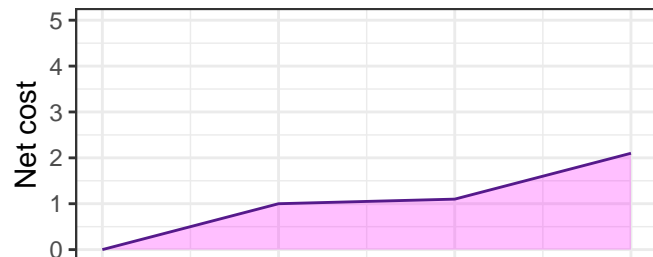
Nominal path



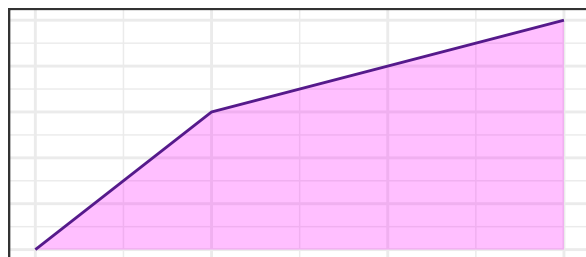
Simulated (n=5 m=3)



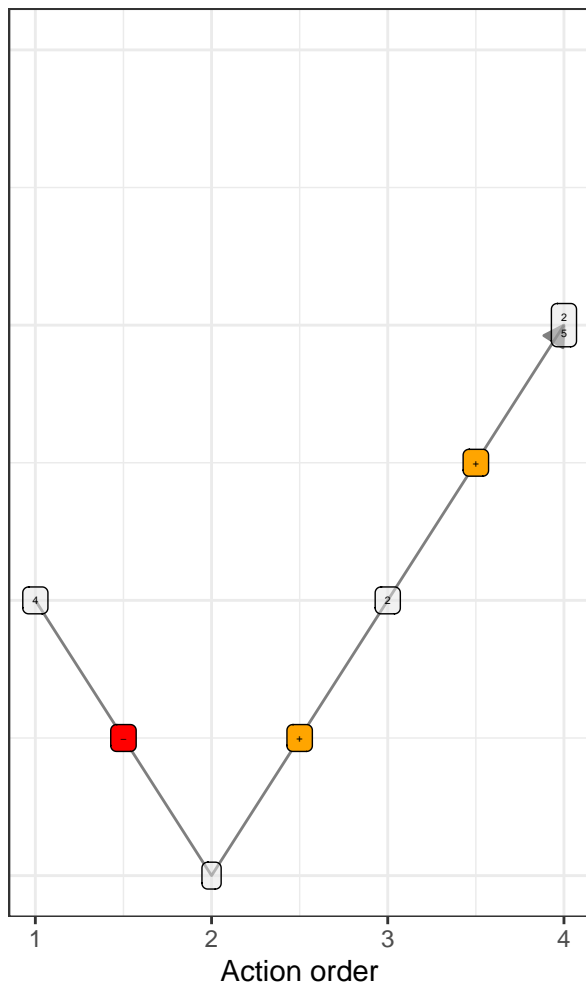
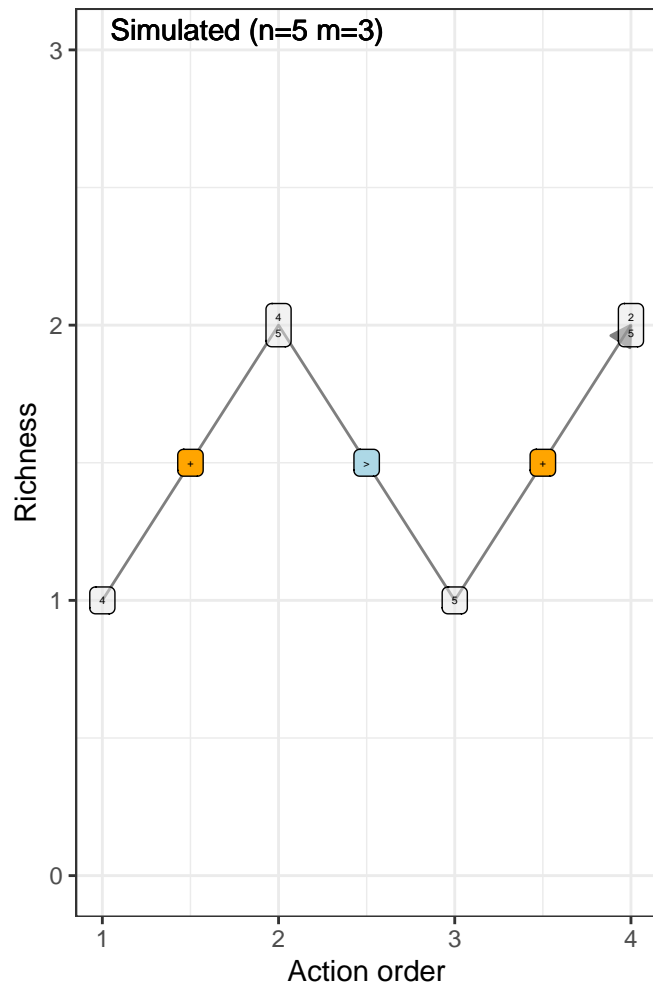
Optimal path



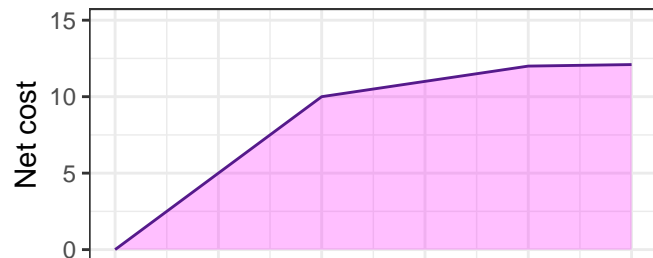
Nominal path



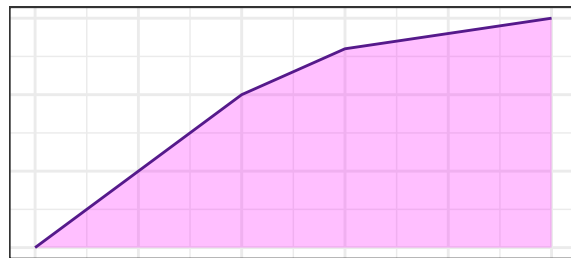
Simulated (n=5 m=3)



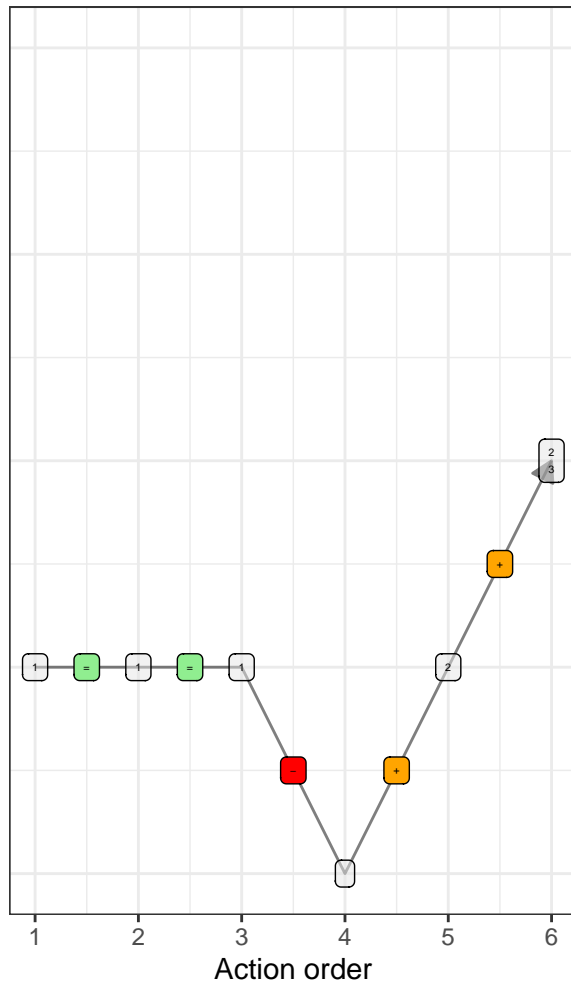
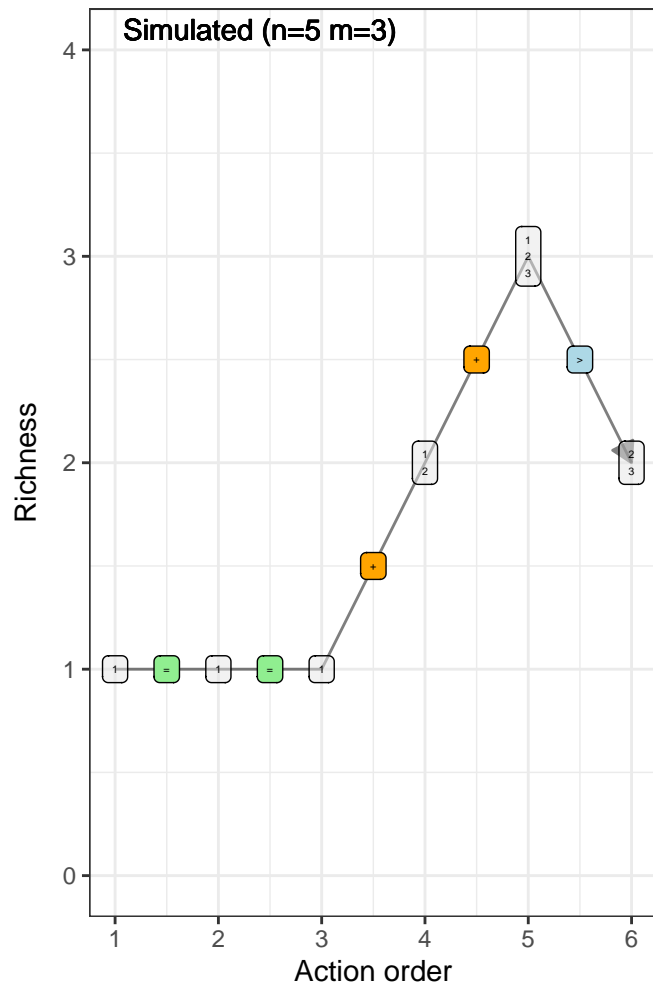
Optimal path



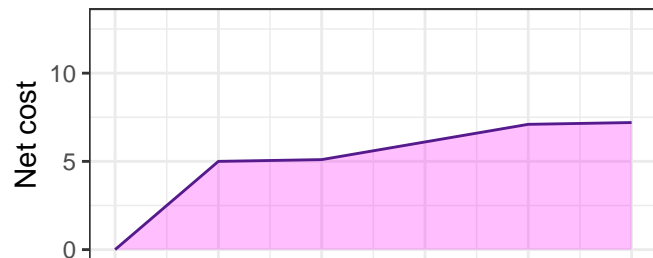
Nominal path



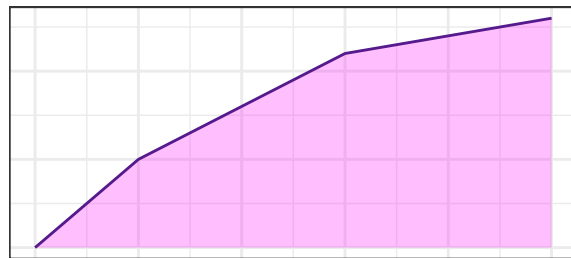
Simulated (n=5 m=3)



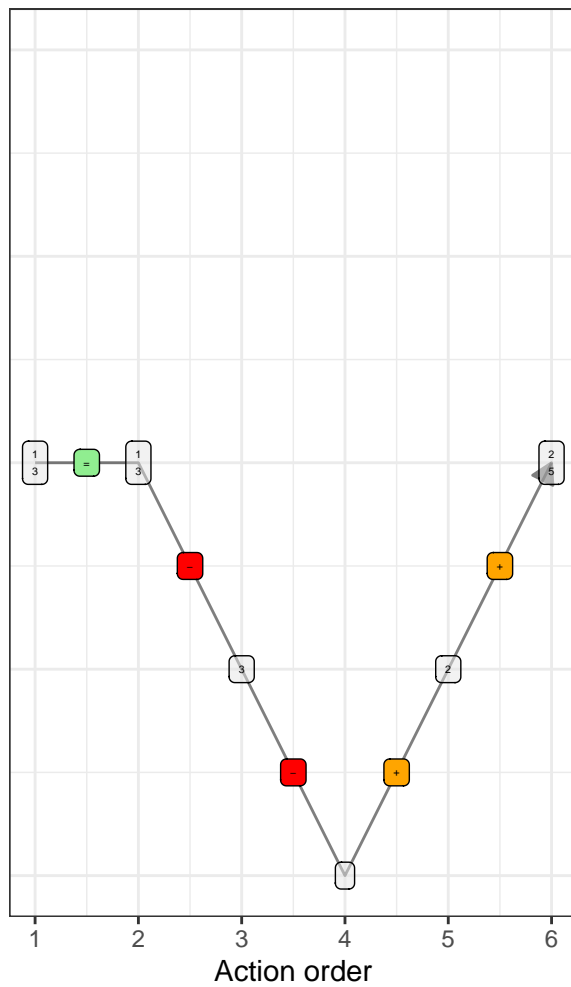
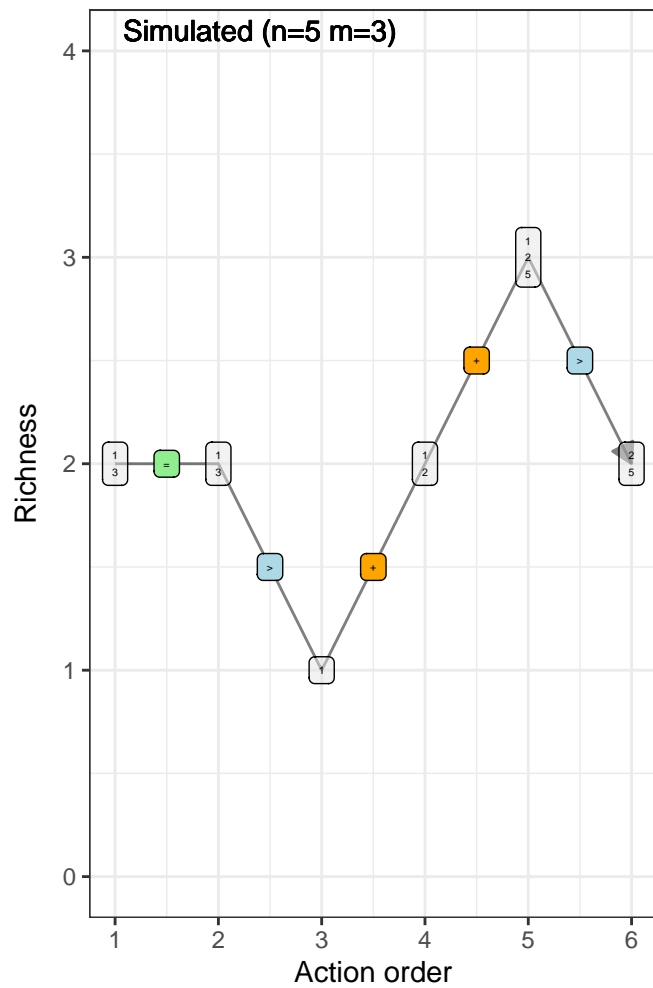
Optimal path



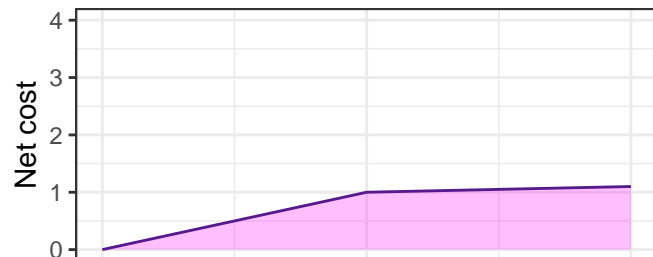
Nominal path



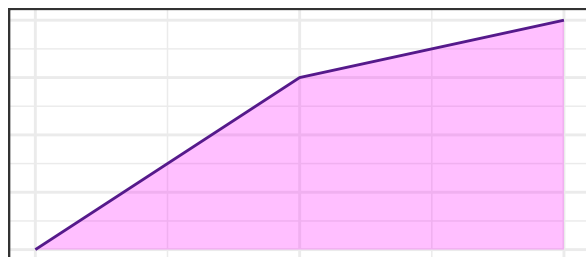
Simulated (n=5 m=3)



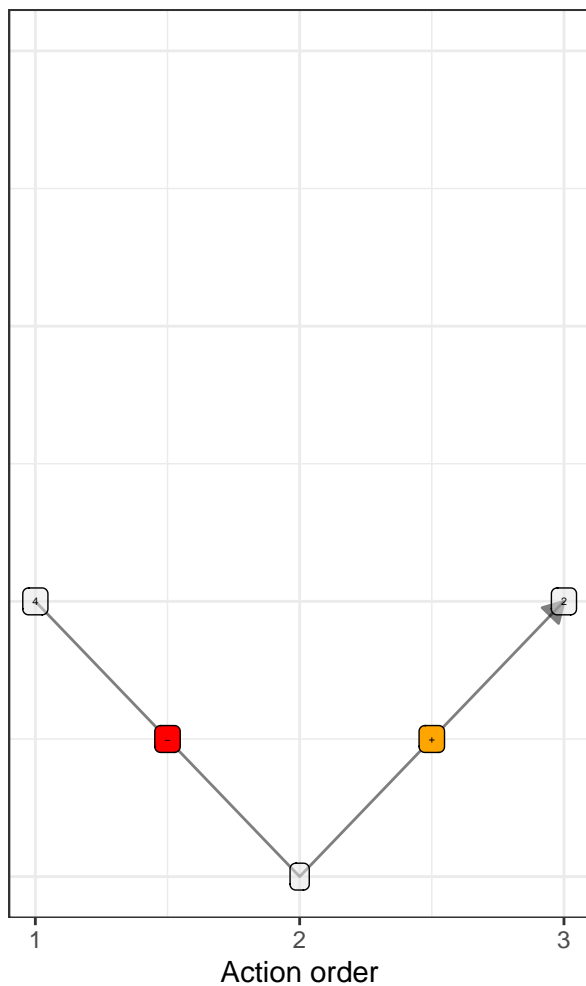
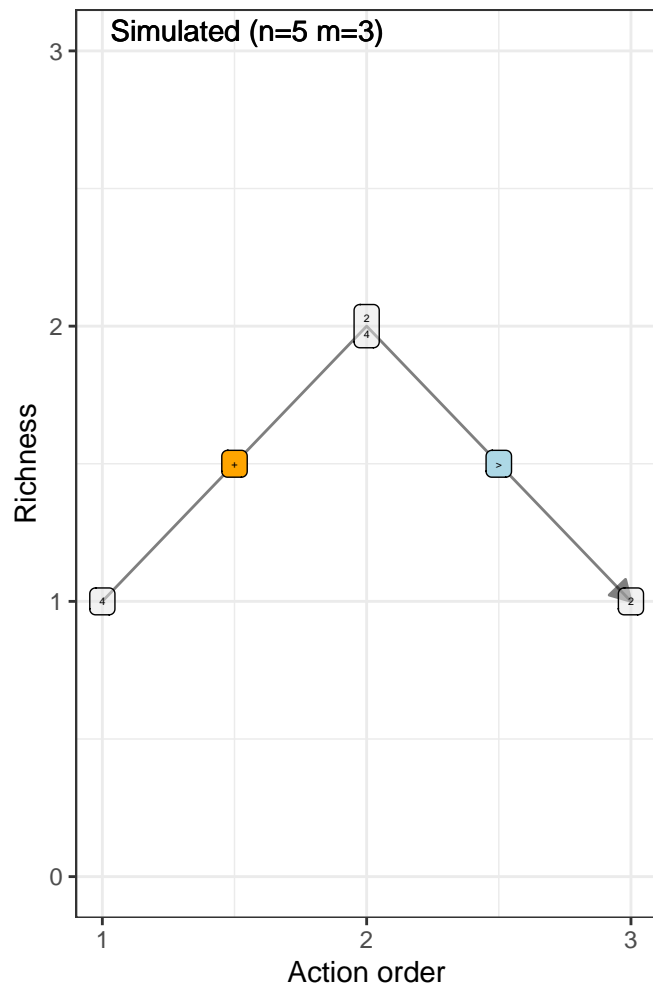
Optimal path



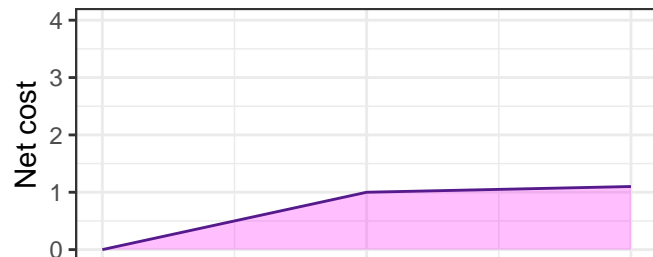
Nominal path



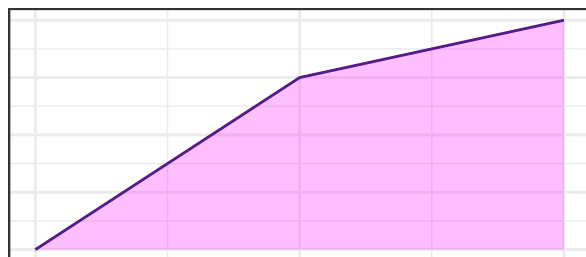
Simulated (n=5 m=3)



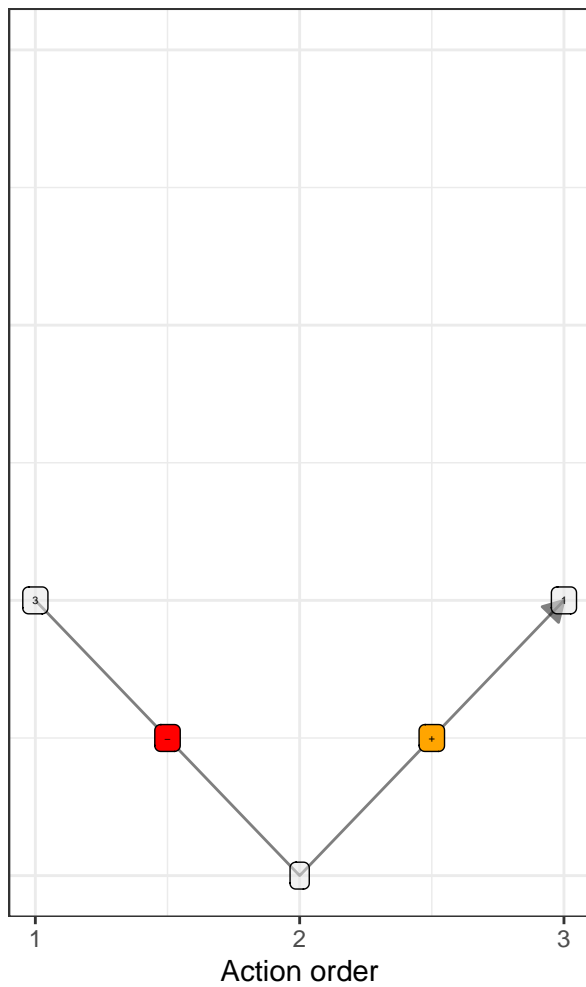
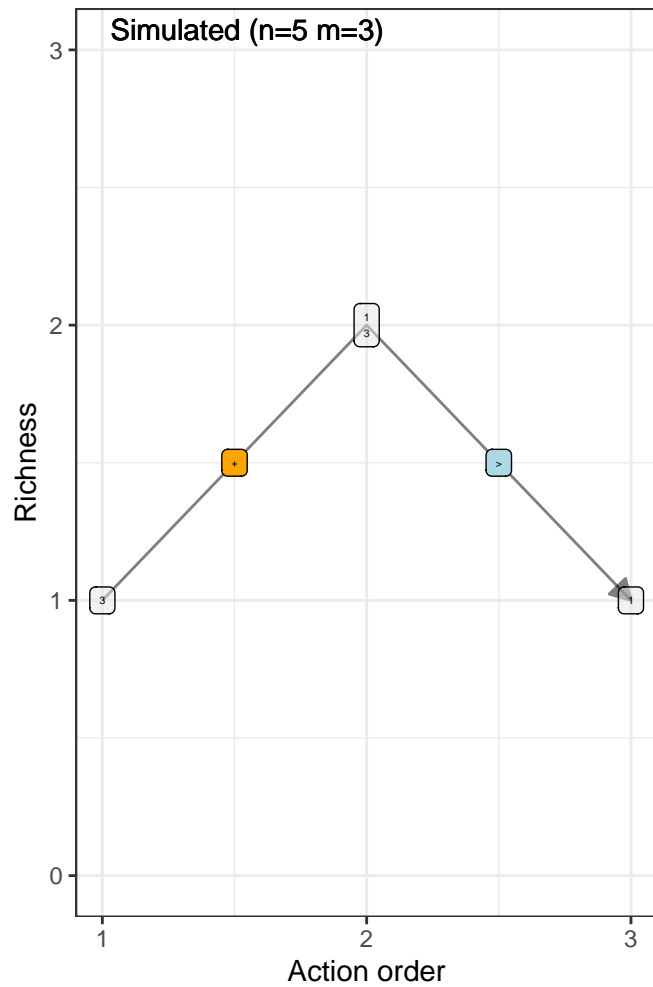
Optimal path



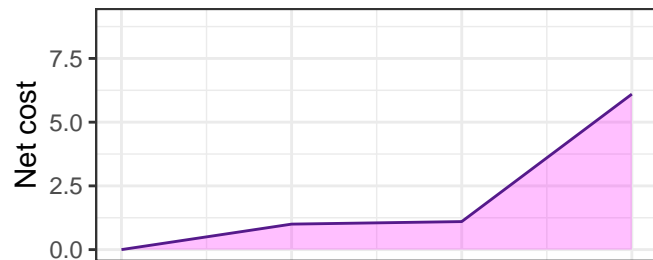
Nominal path



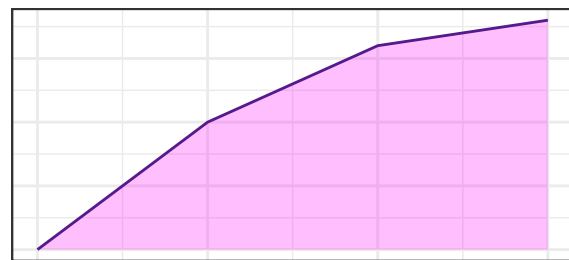
Simulated (n=5 m=3)



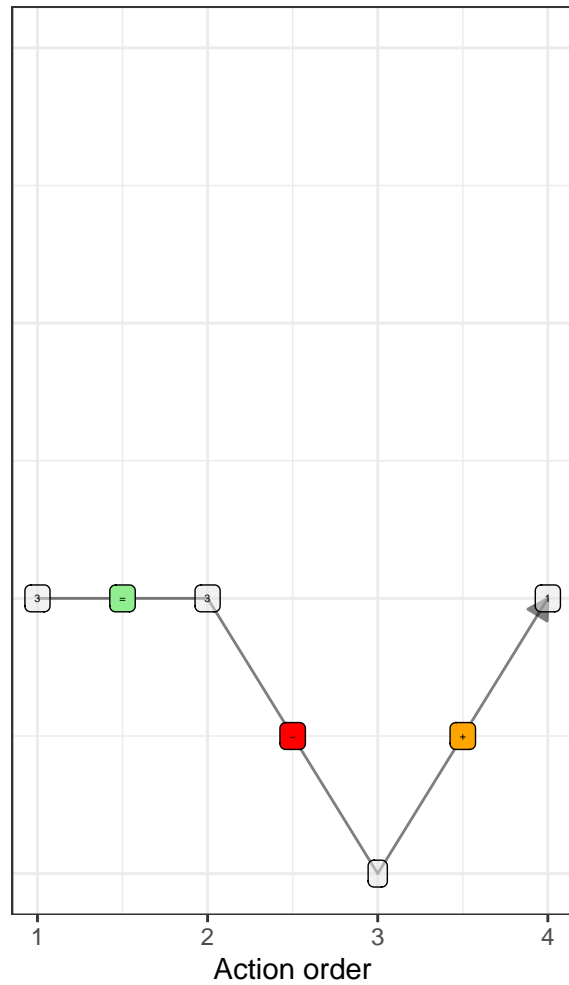
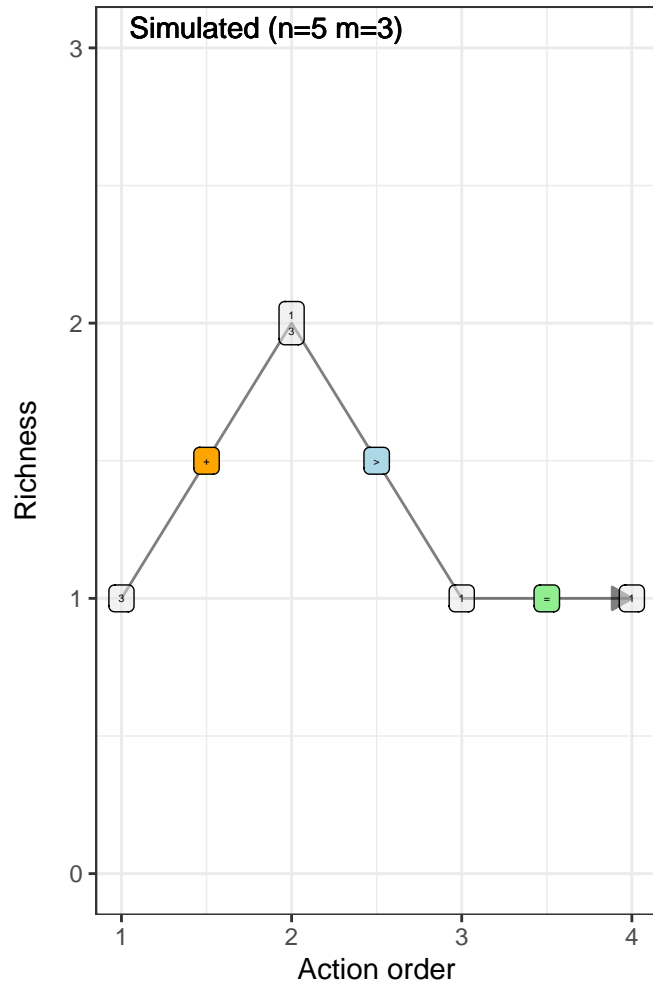
Optimal path



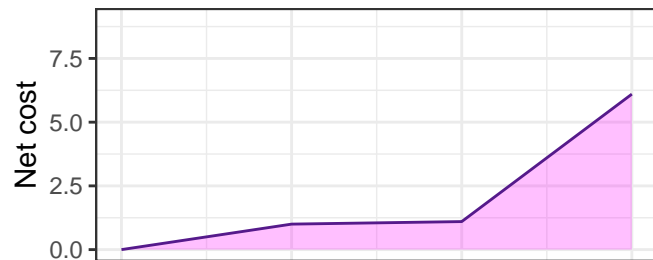
Nominal path



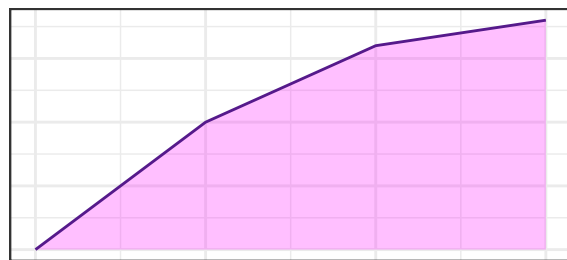
Simulated (n=5 m=3)



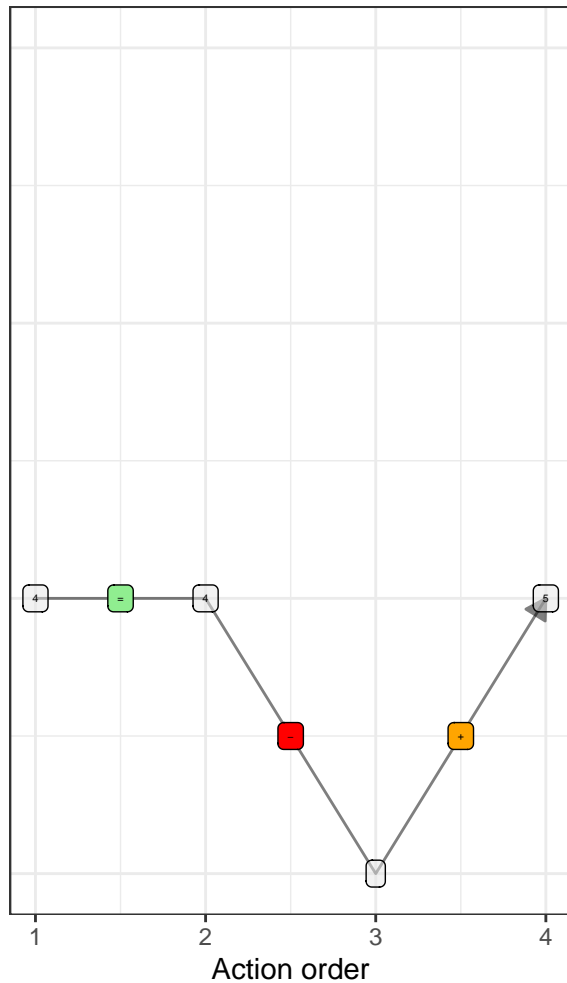
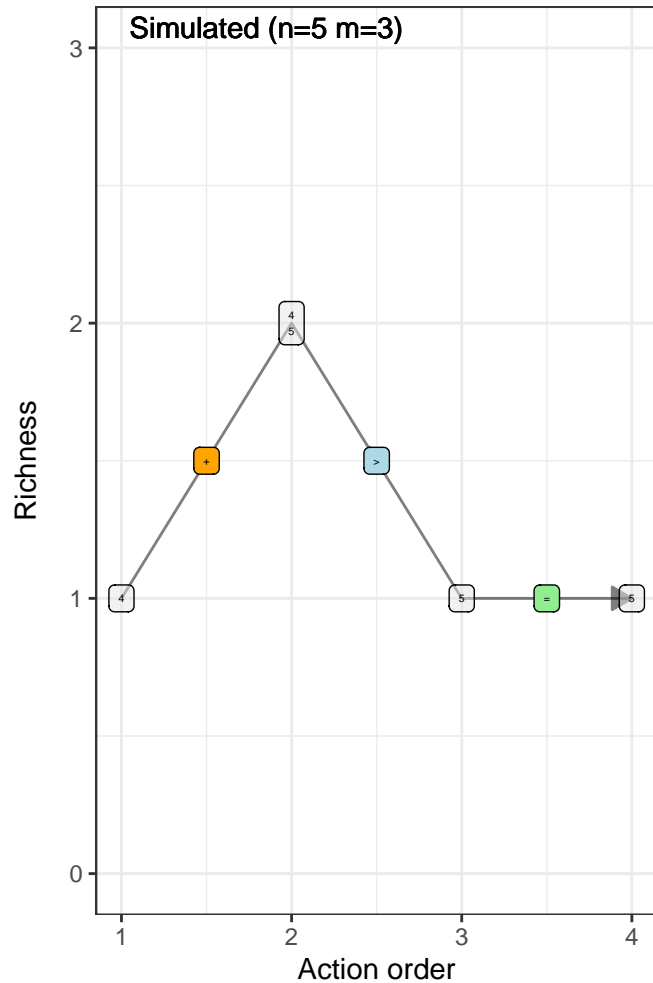
Optimal path



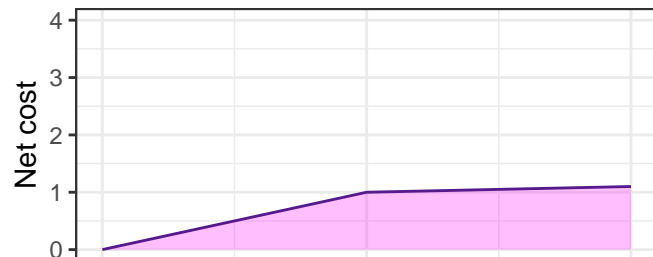
Nominal path



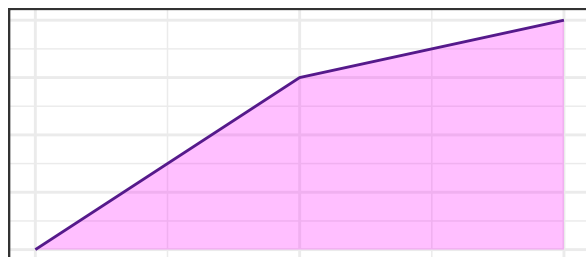
Simulated (n=5 m=3)



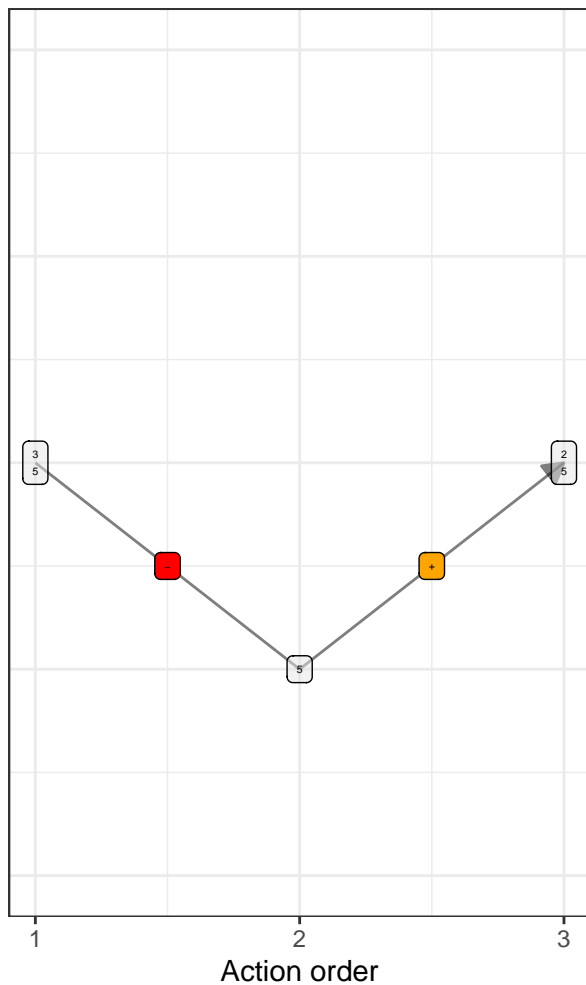
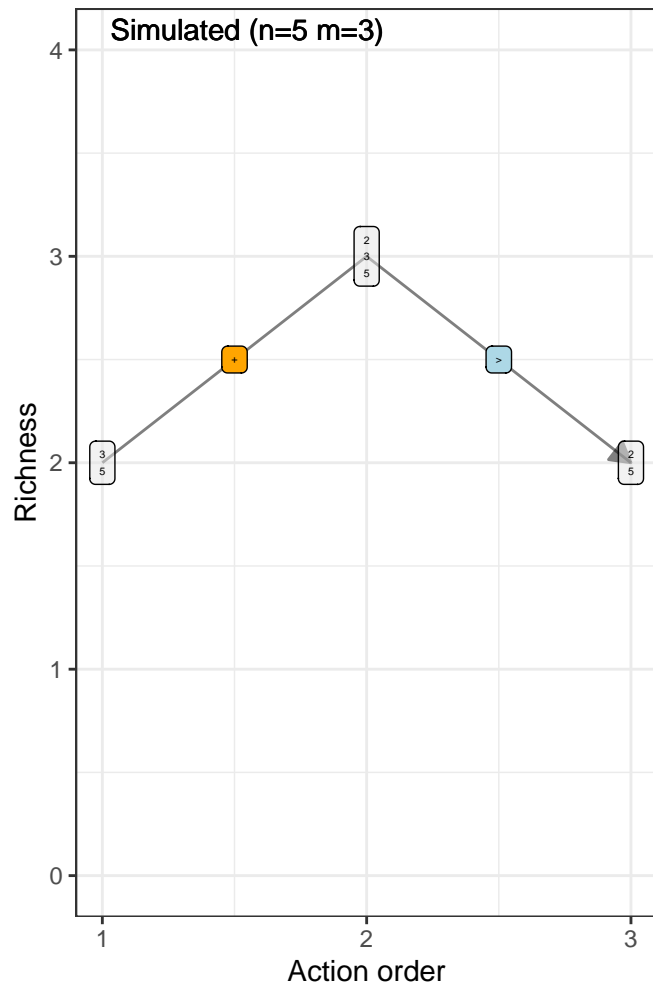
Optimal path



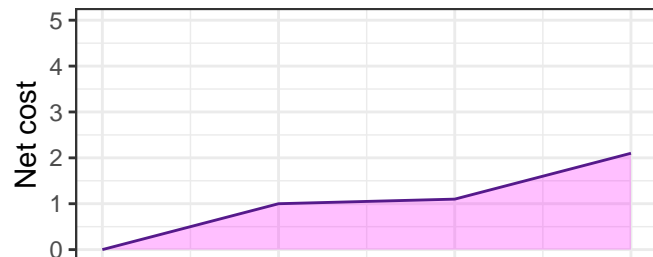
Nominal path



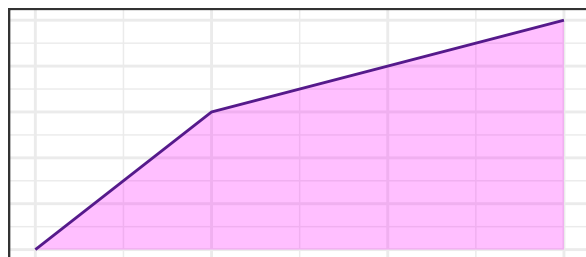
Simulated (n=5 m=3)



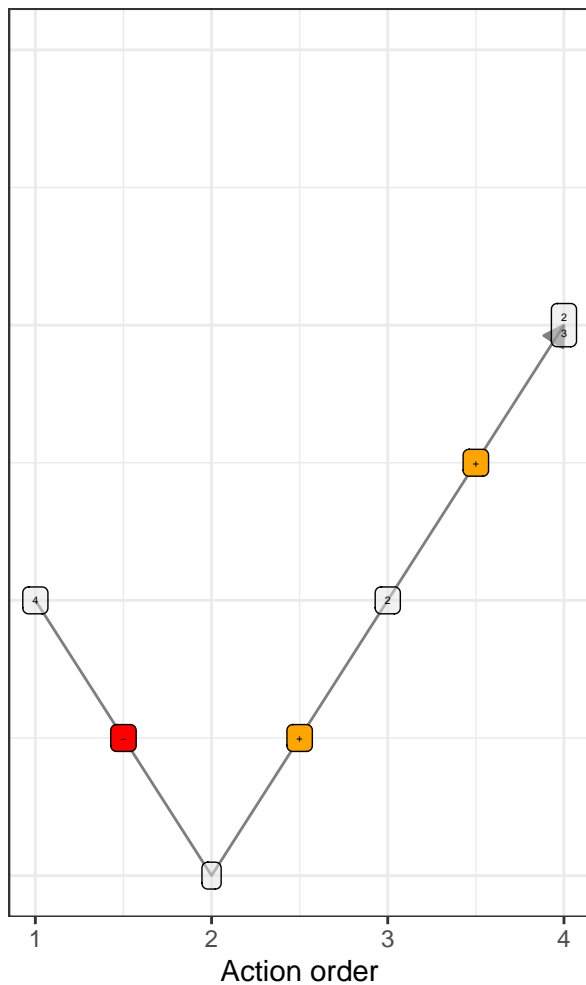
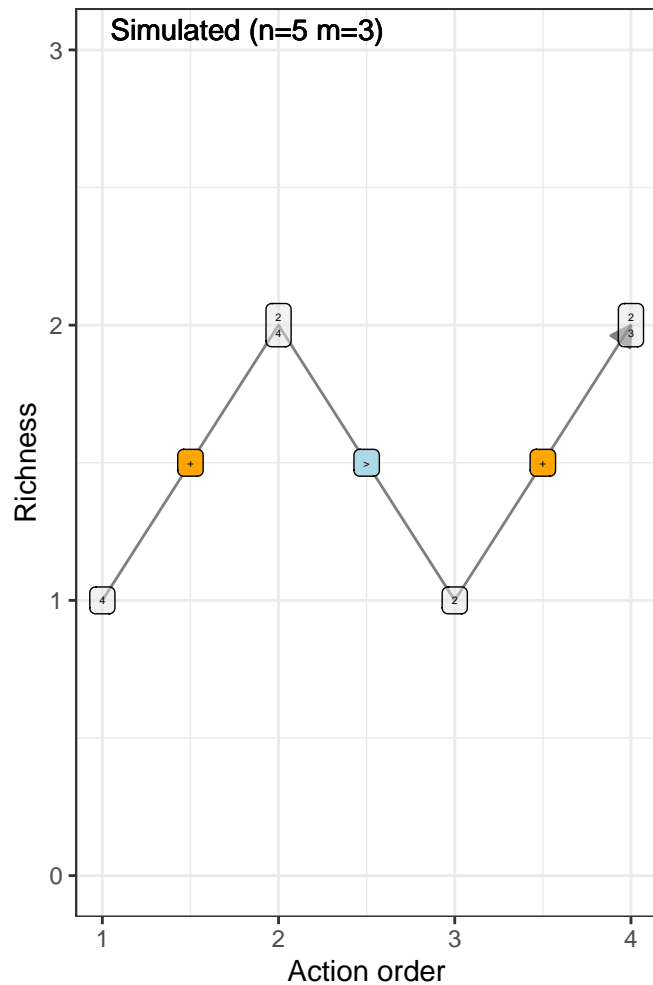
Optimal path



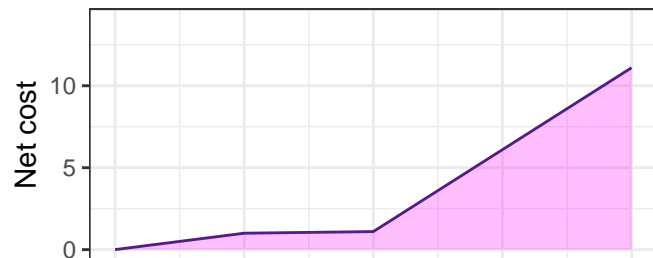
Nominal path



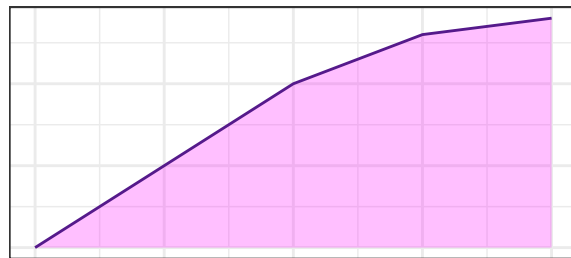
Simulated (n=5 m=3)



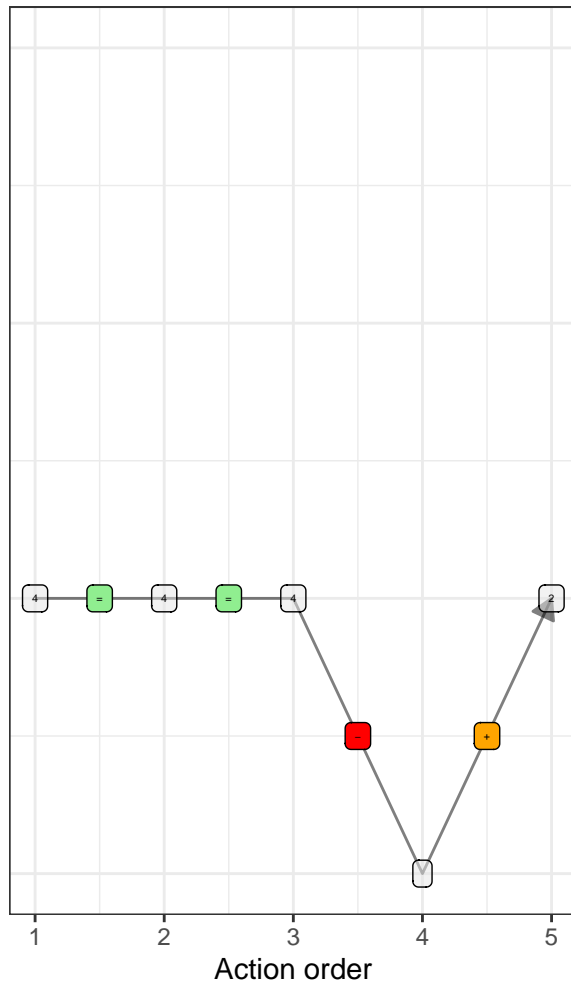
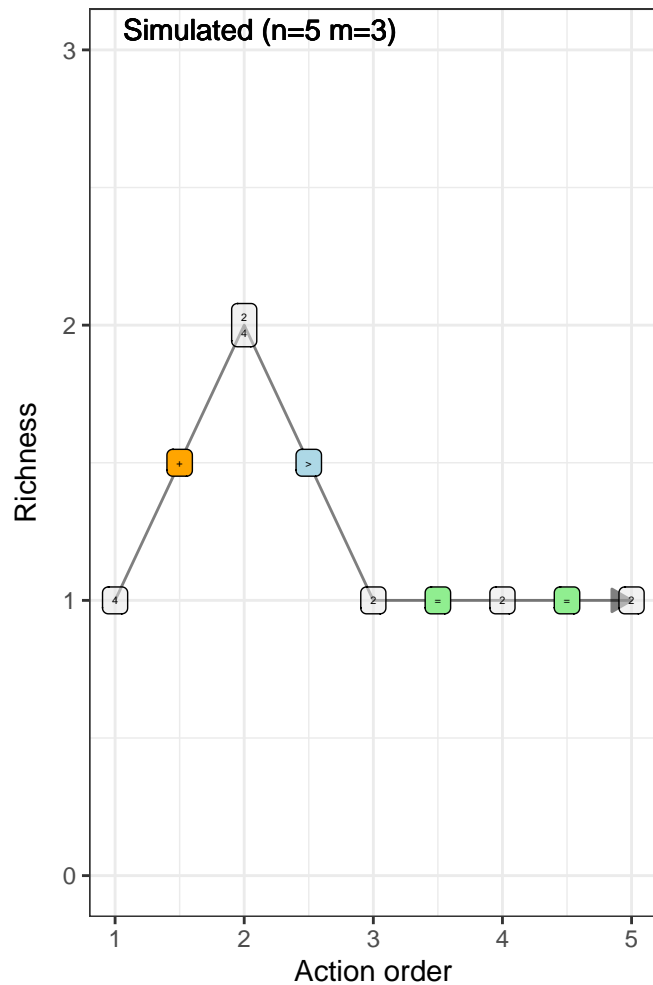
Optimal path



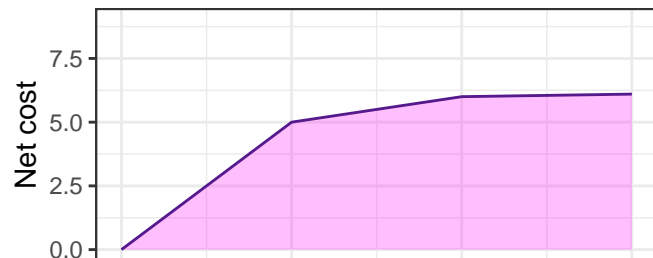
Nominal path



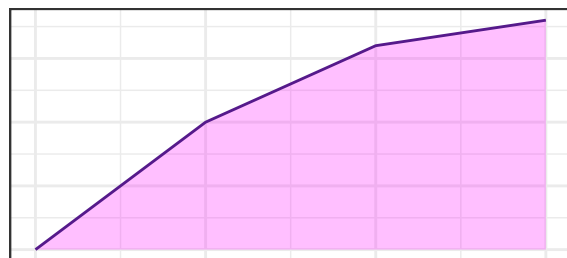
Simulated (n=5 m=3)



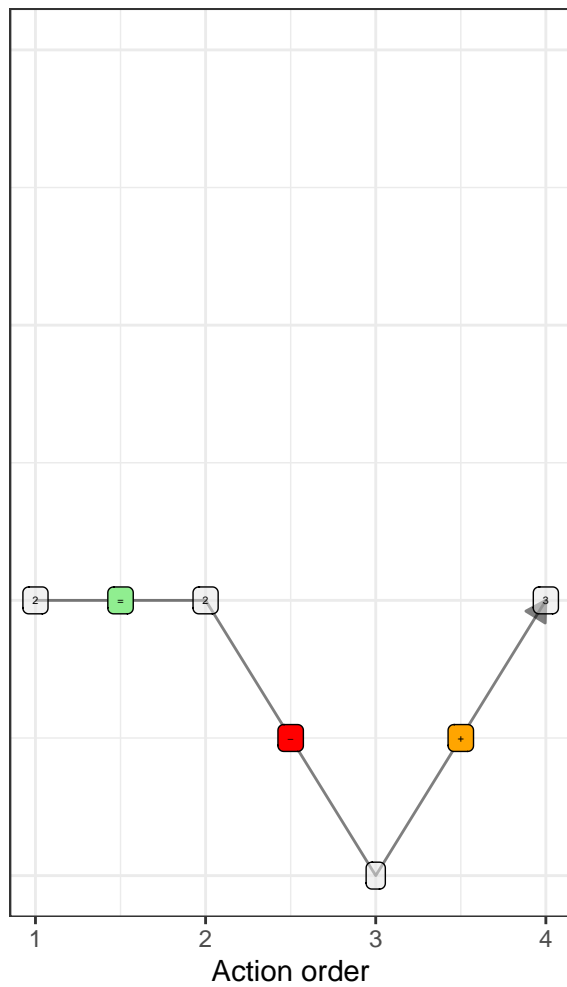
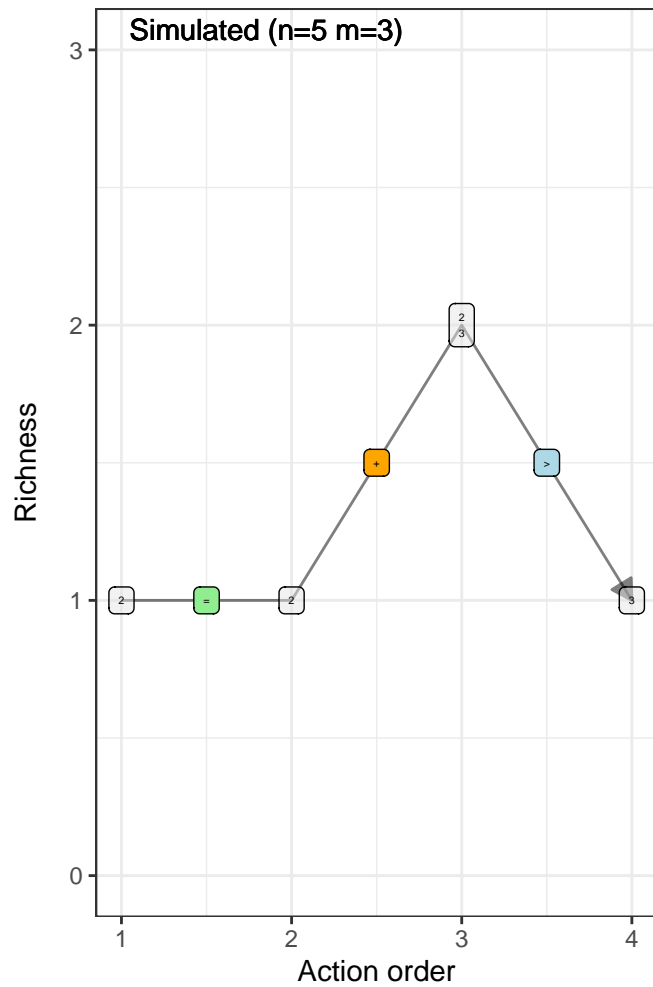
Optimal path



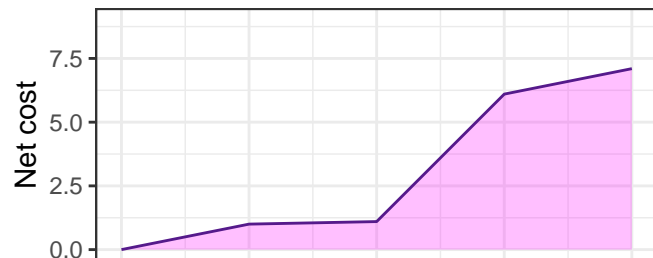
Nominal path



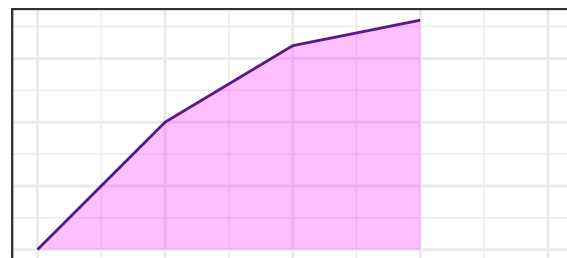
Simulated (n=5 m=3)



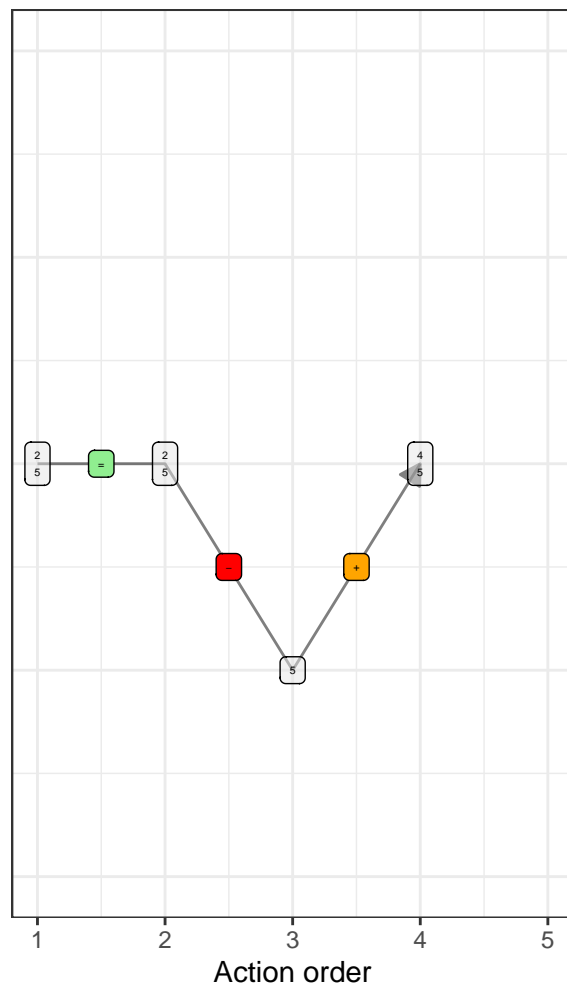
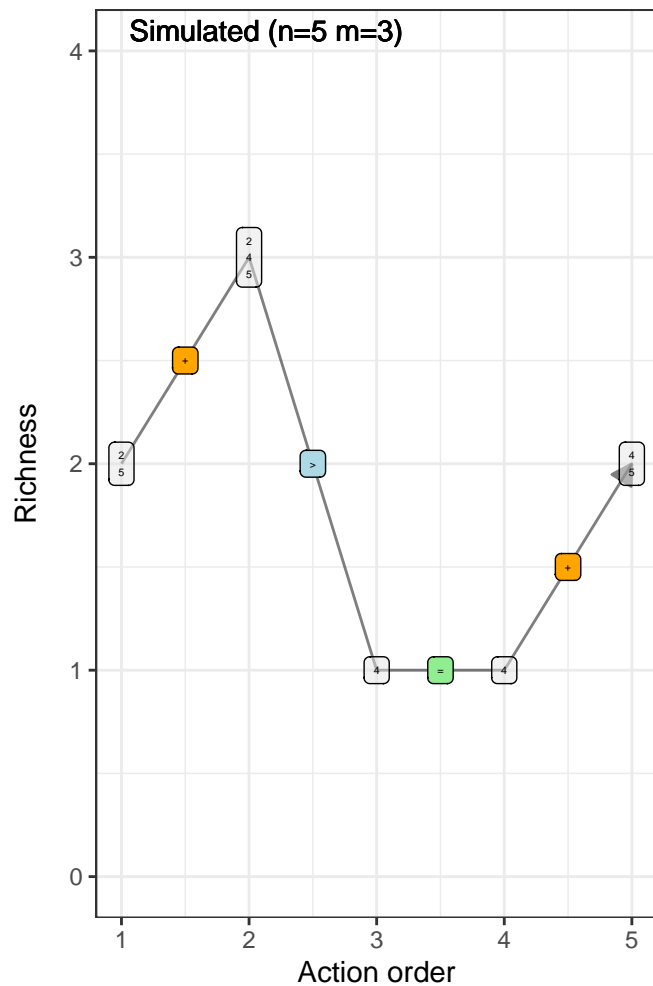
Optimal path



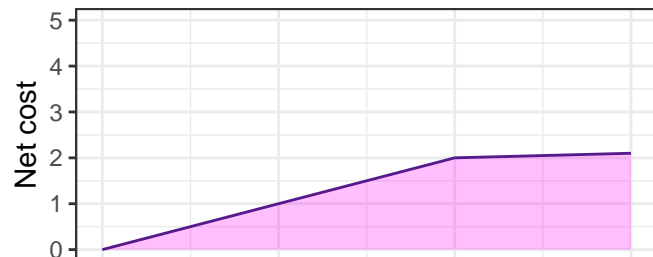
Nominal path



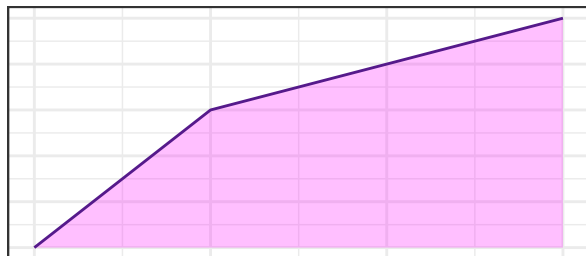
Simulated (n=5 m=3)



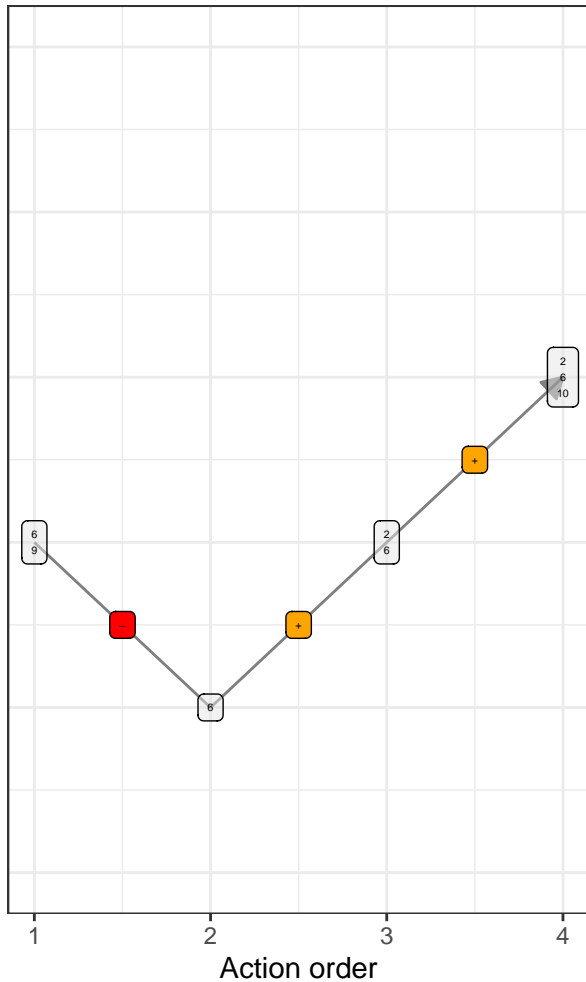
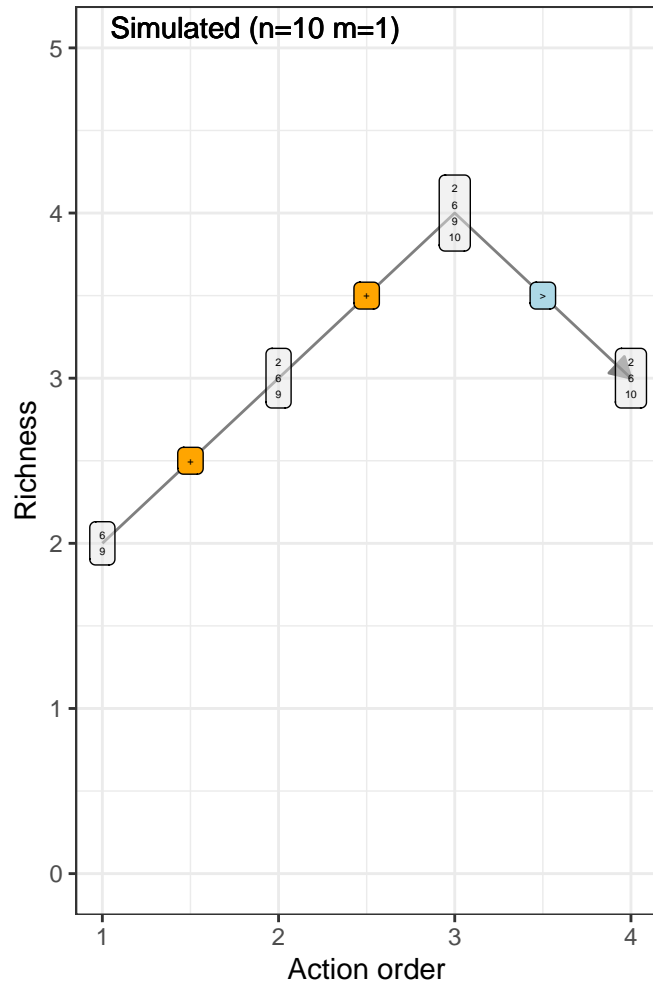
Optimal path



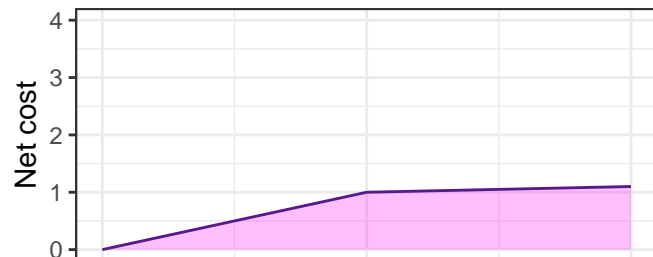
Nominal path



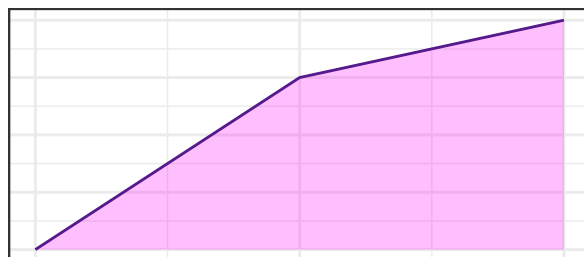
Simulated (n=10 m=1)



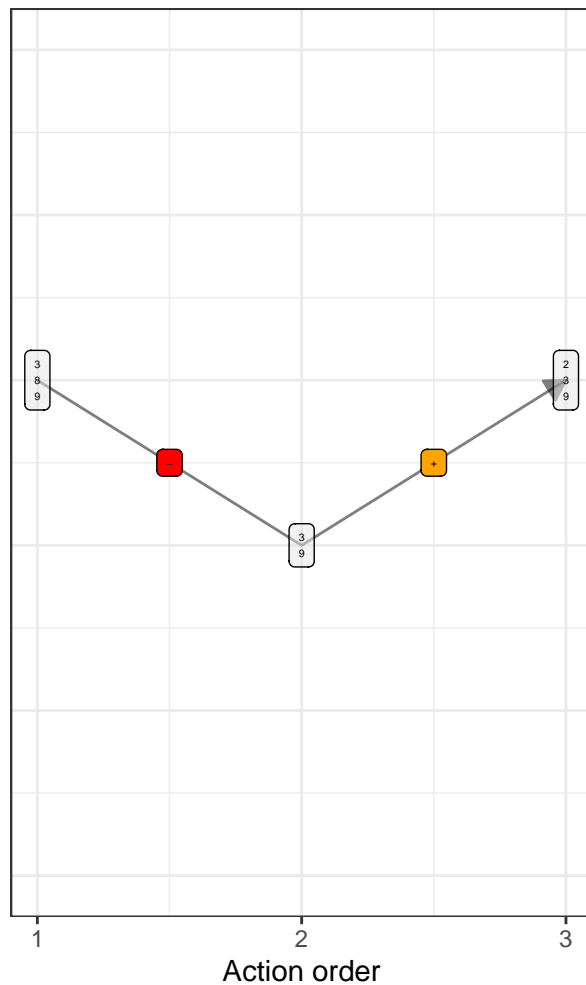
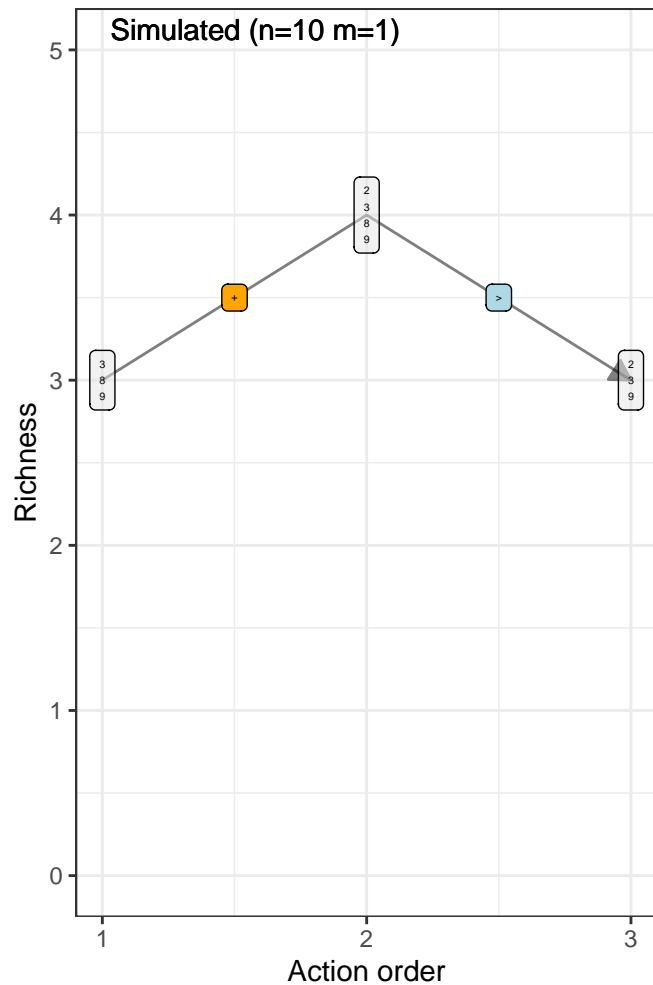
Optimal path



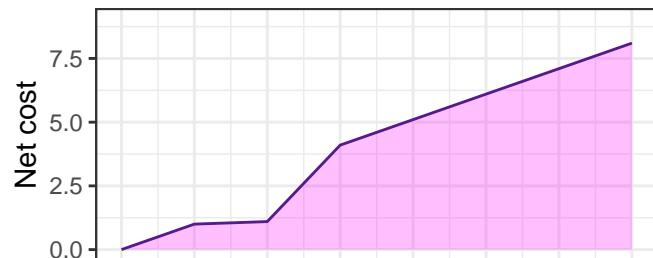
Nominal path



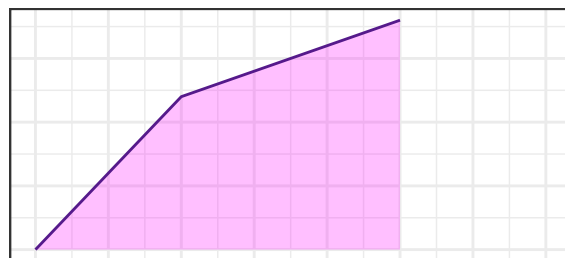
Simulated (n=10 m=1)



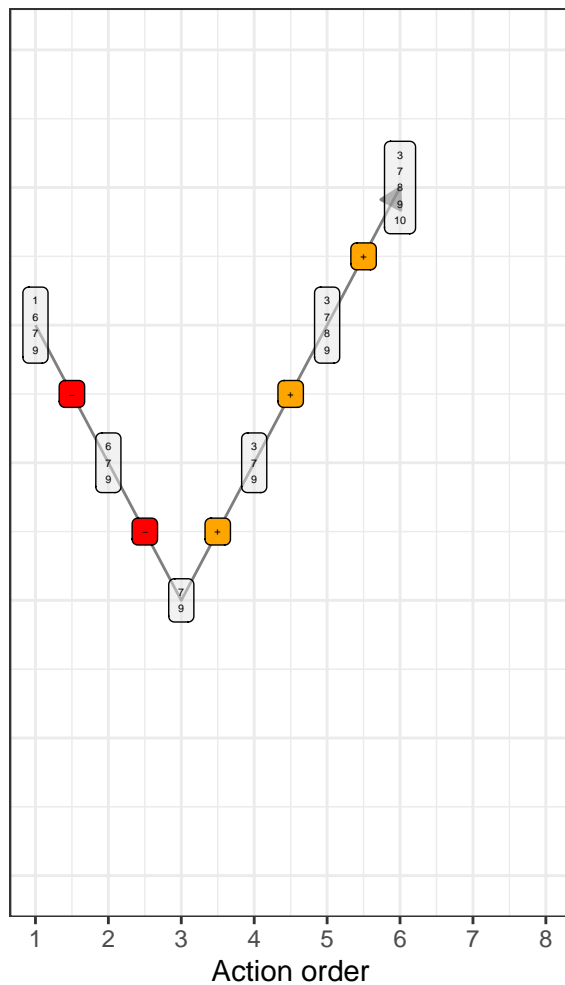
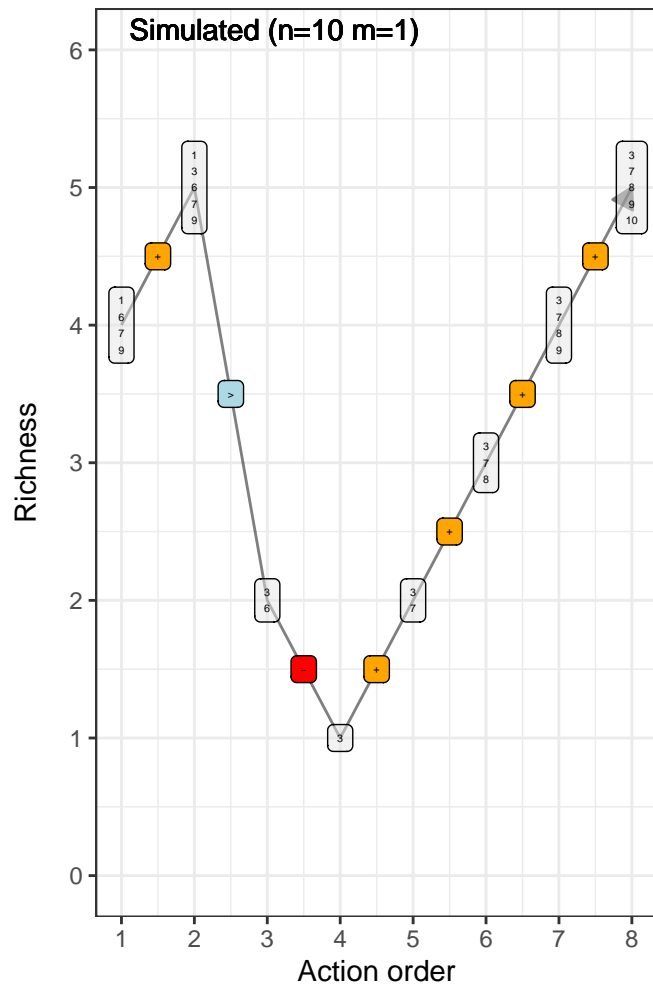
Optimal path



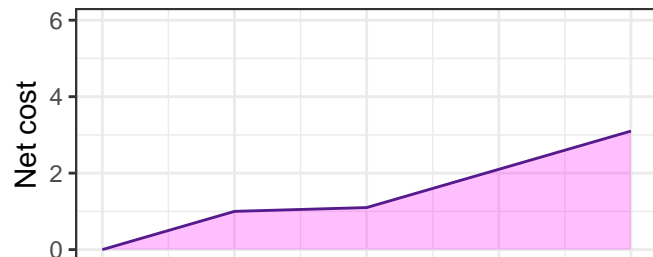
Nominal path



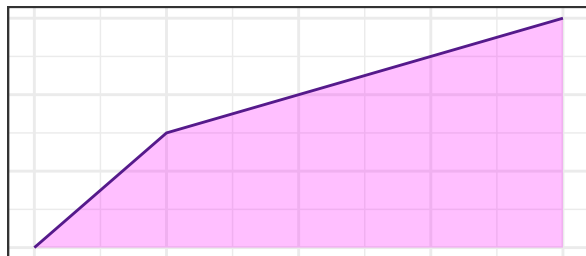
Simulated (n=10 m=1)



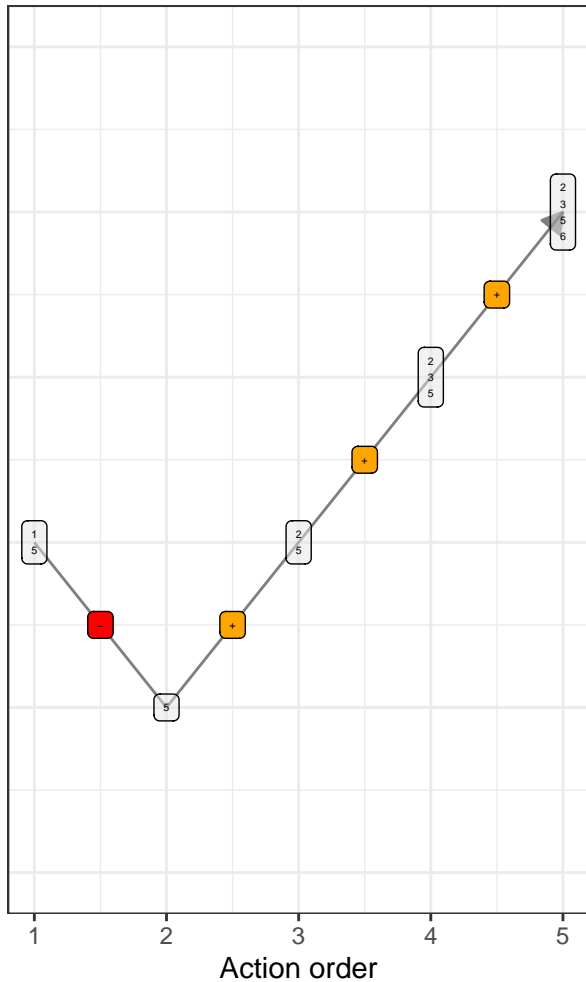
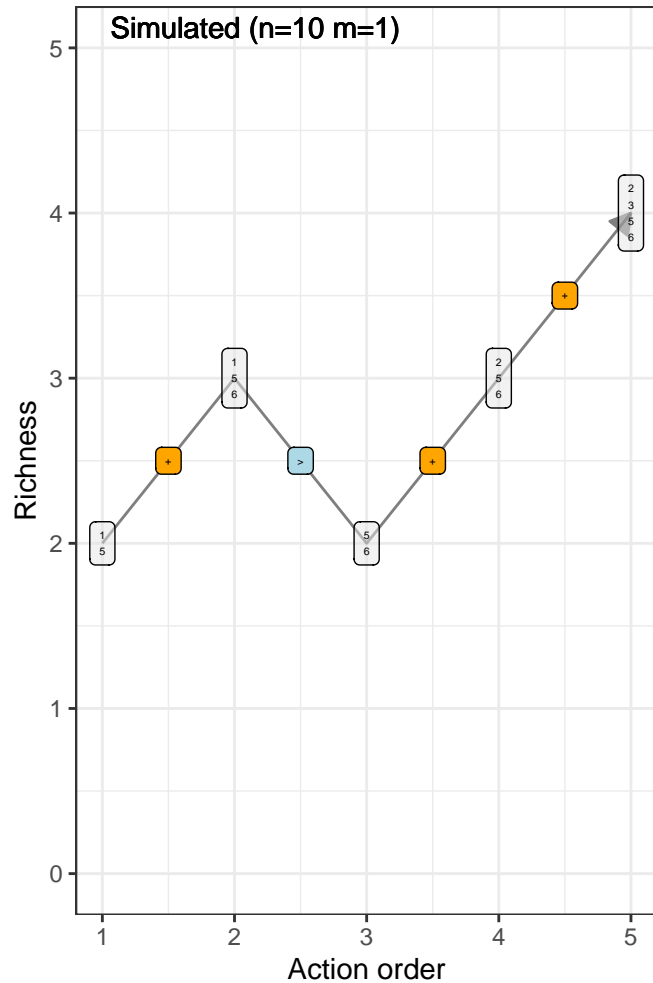
Optimal path



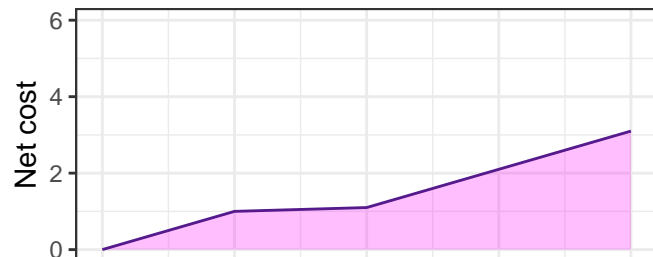
Nominal path



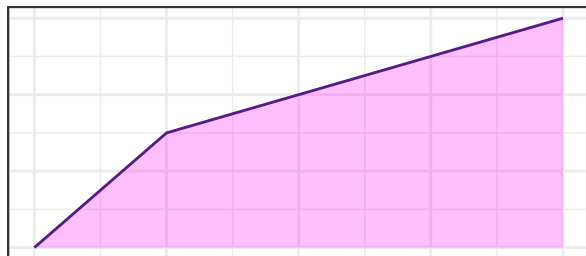
Simulated (n=10 m=1)



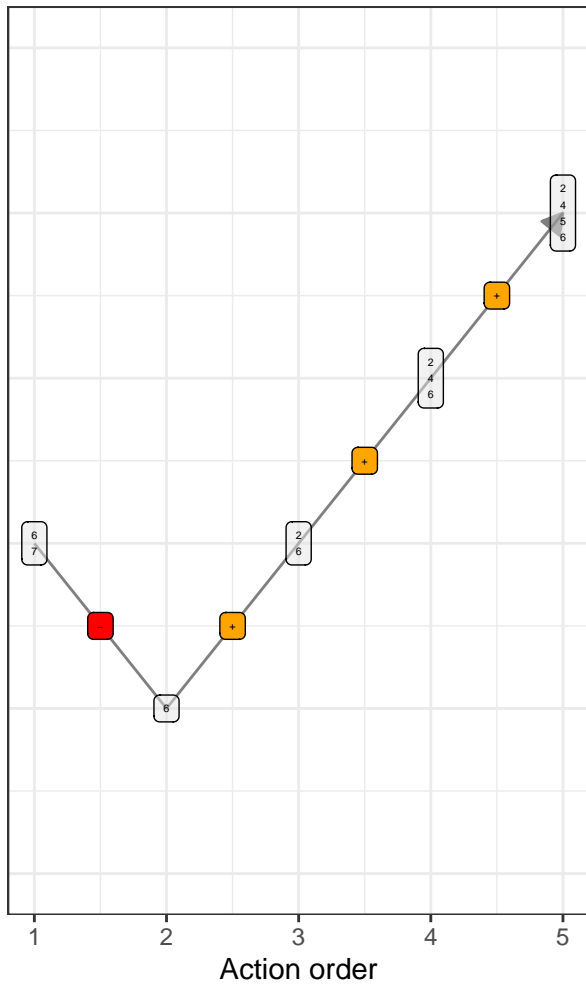
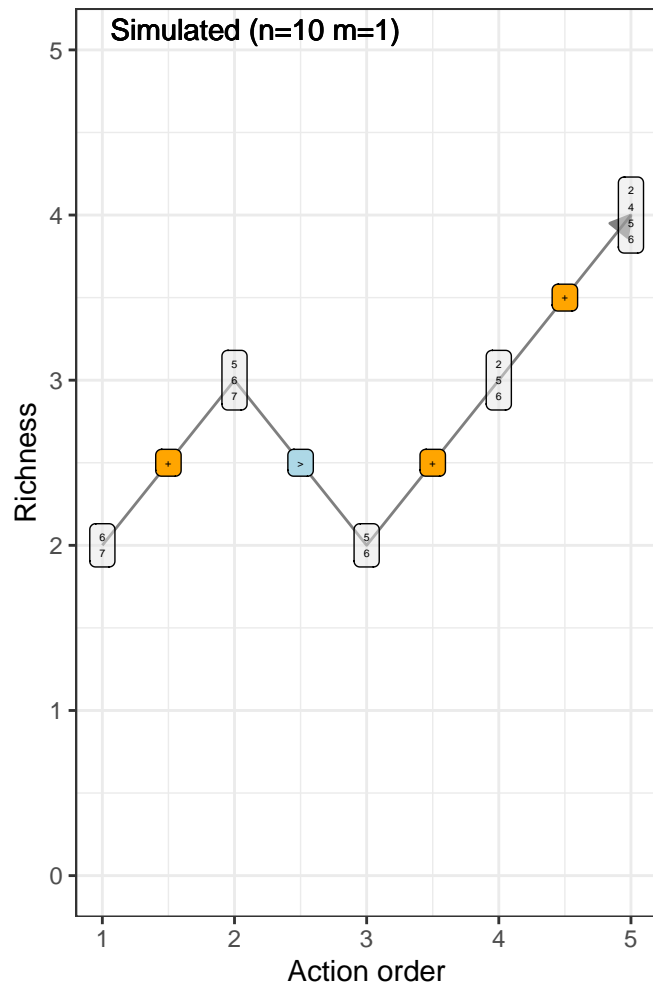
Optimal path



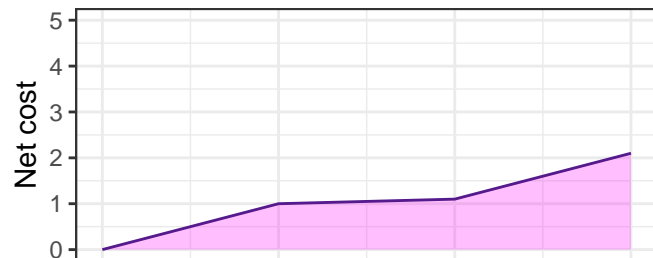
Nominal path



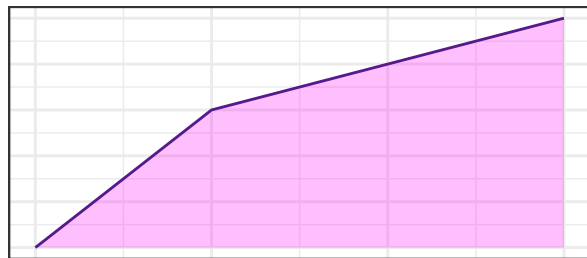
Simulated (n=10 m=1)



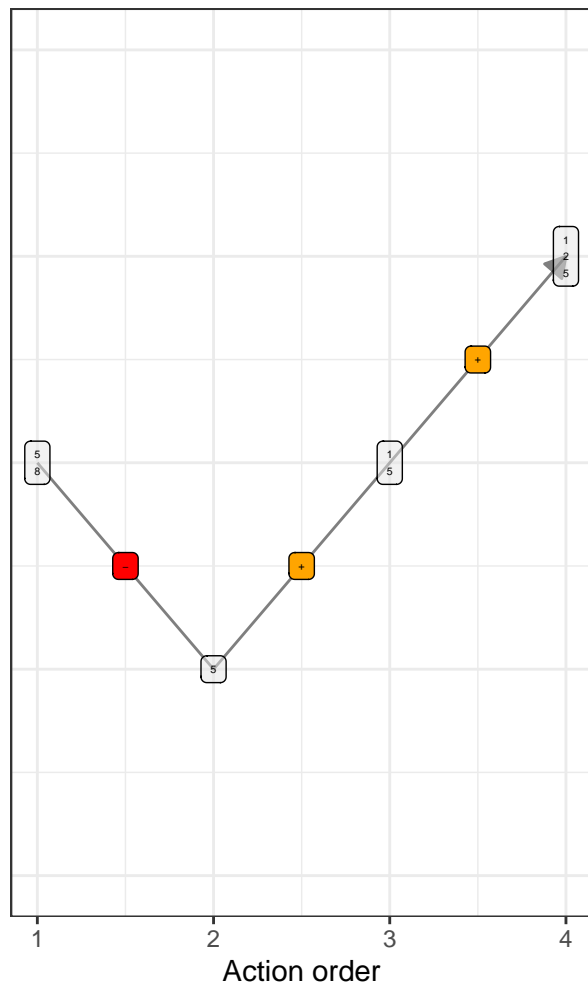
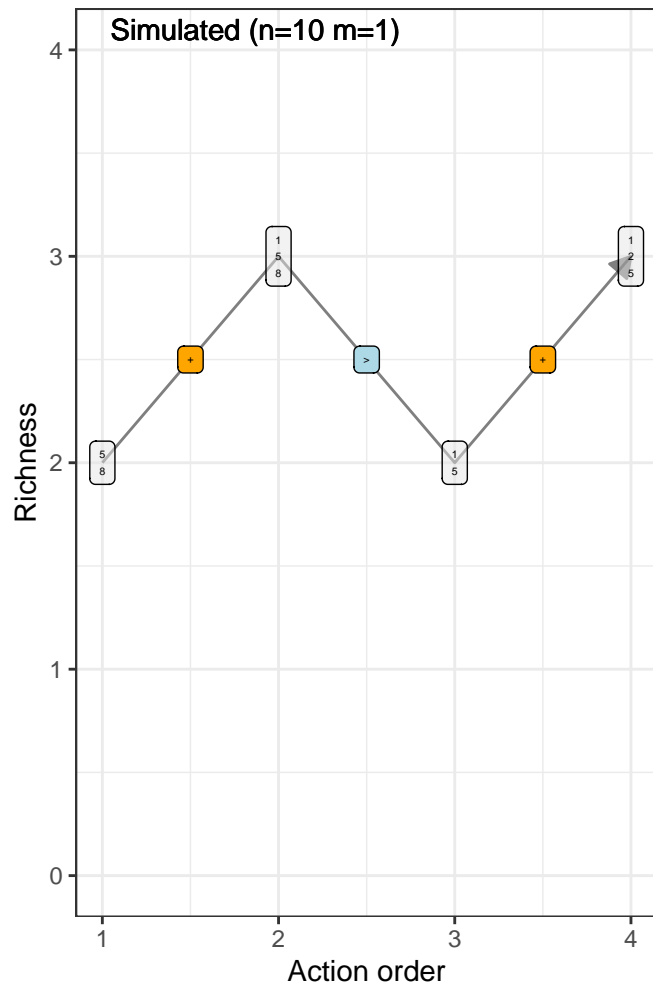
Optimal path



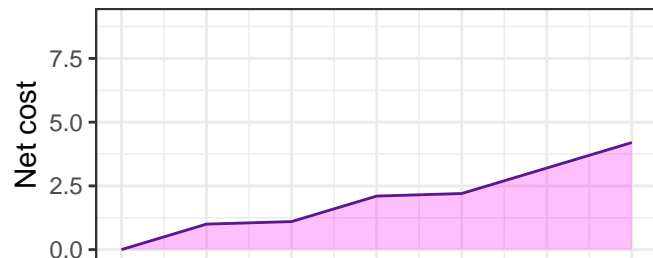
Nominal path



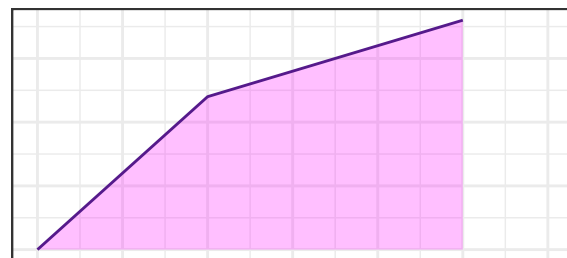
Simulated (n=10 m=1)



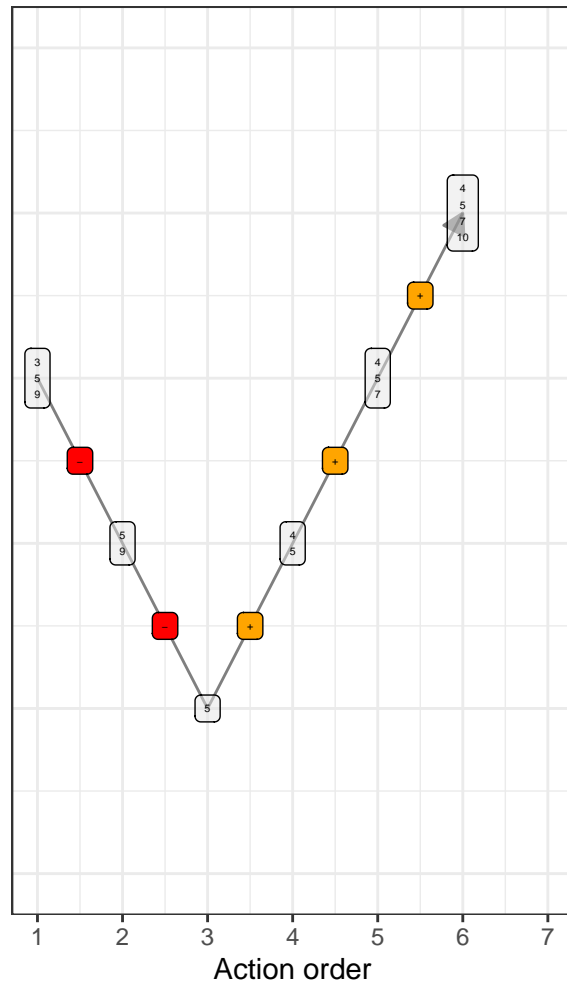
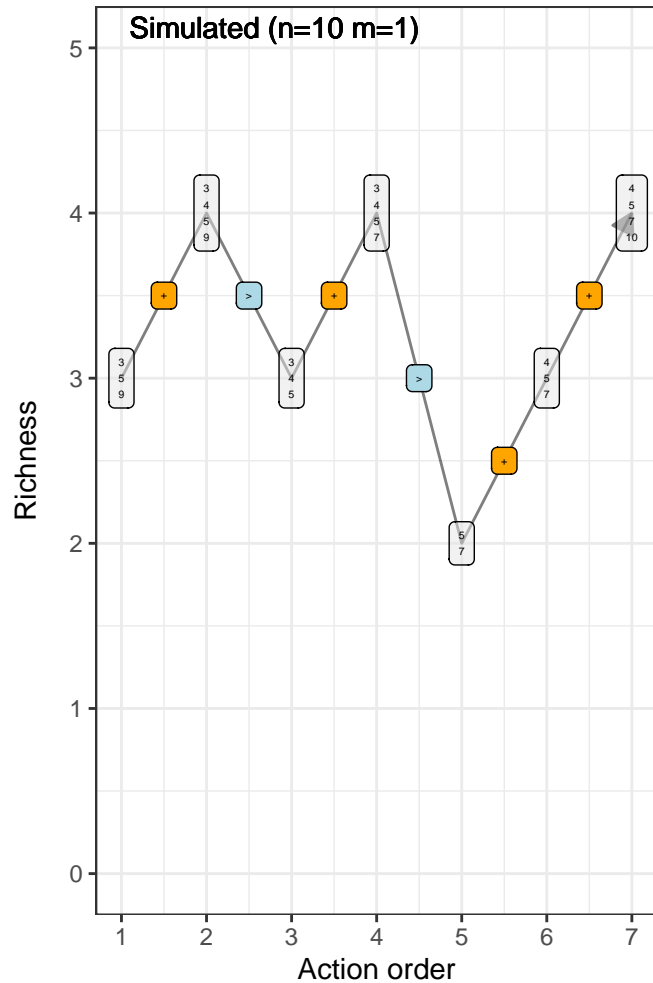
Optimal path



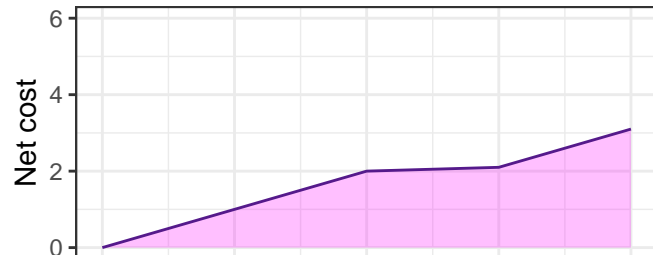
Nominal path



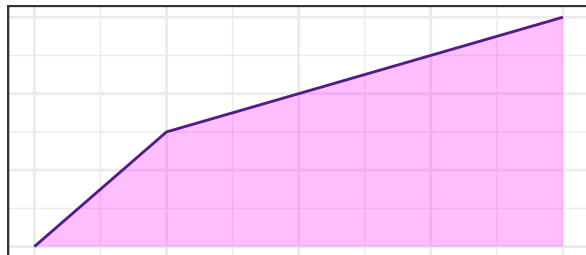
Simulated (n=10 m=1)



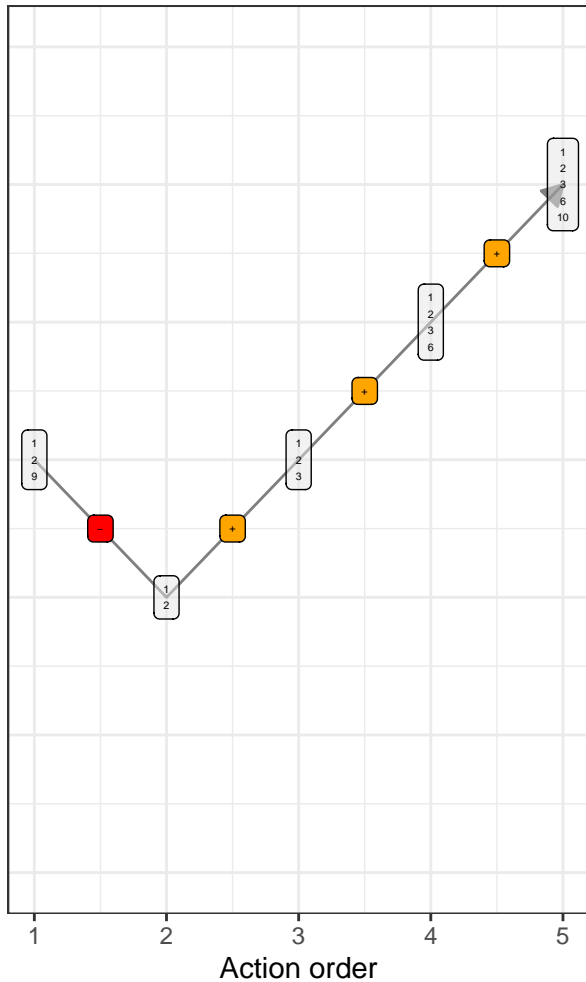
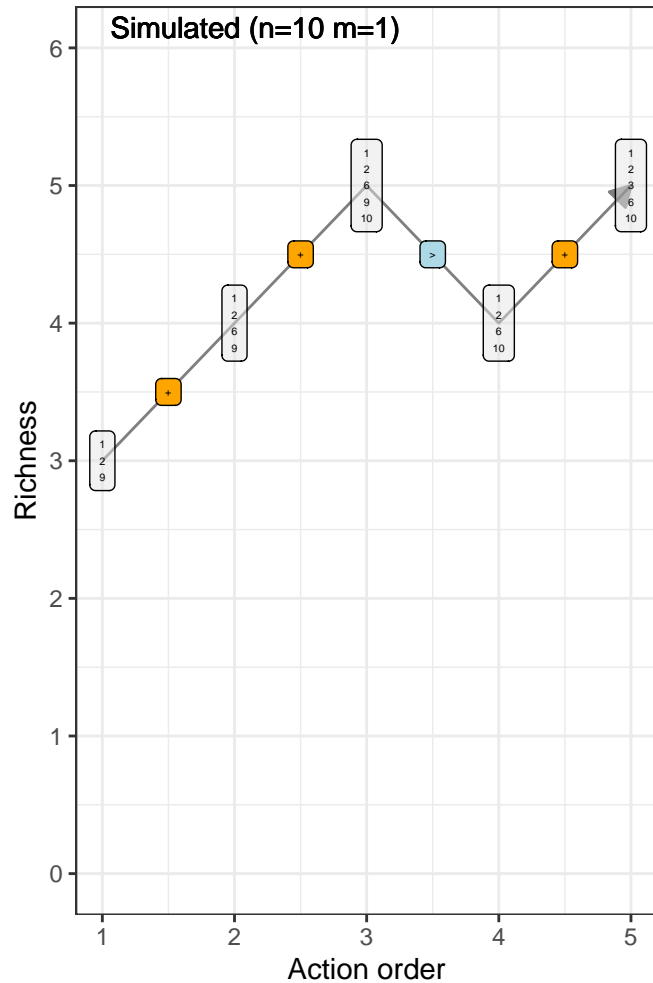
Optimal path



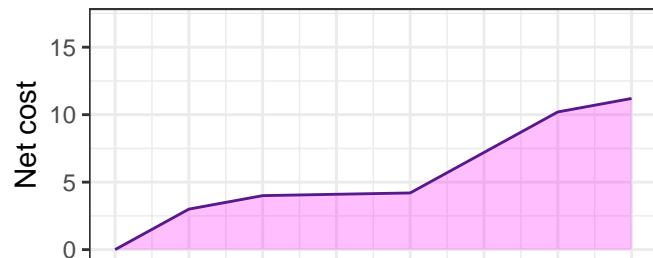
Nominal path



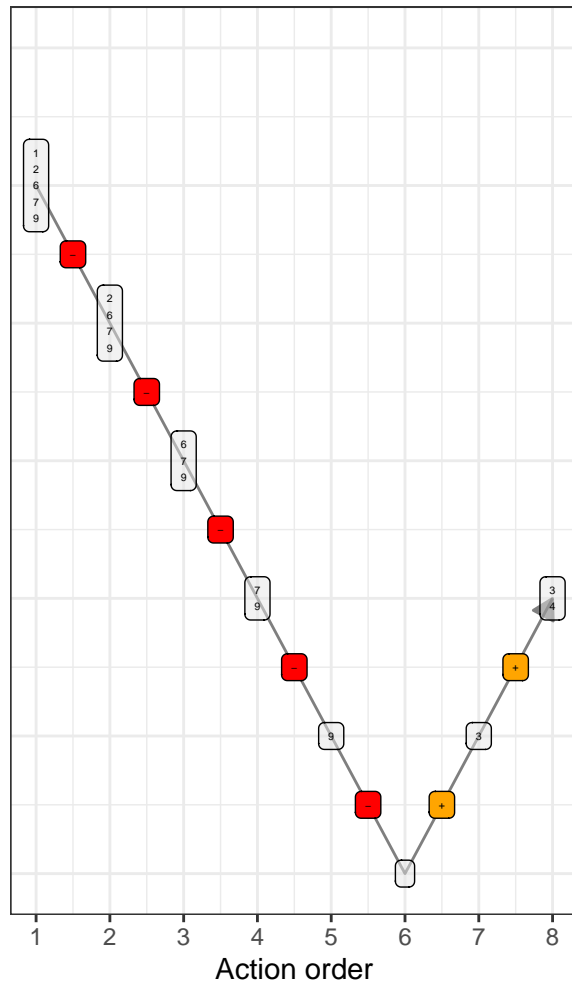
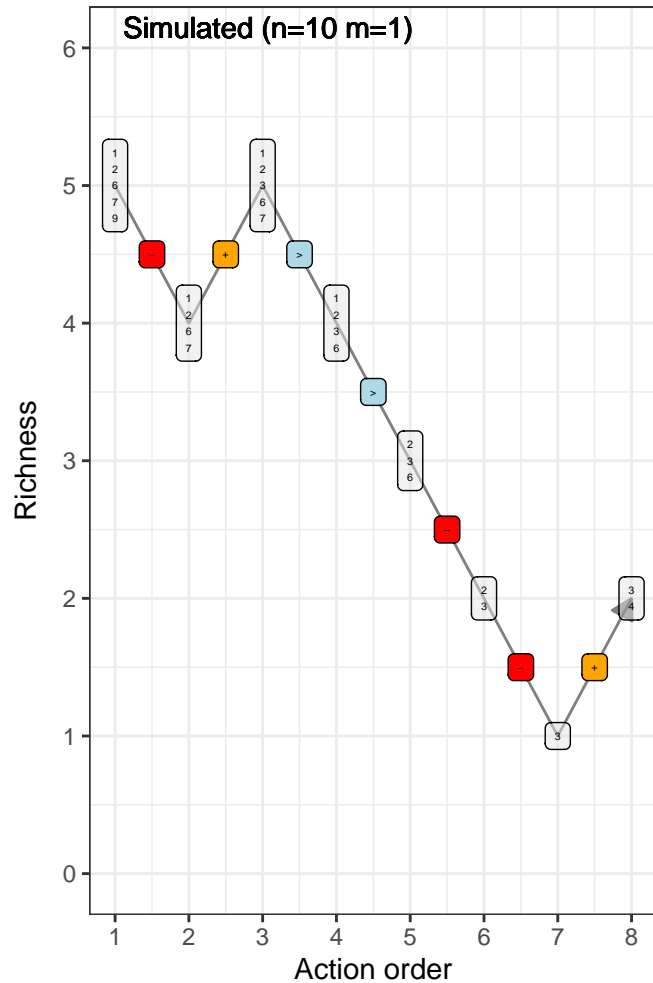
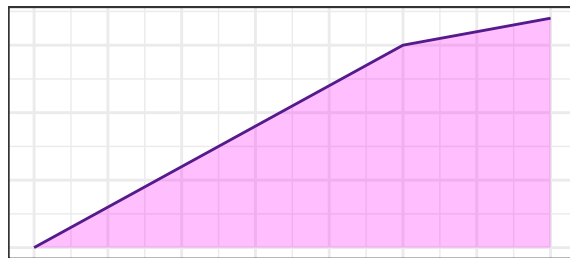
Simulated (n=10 m=1)



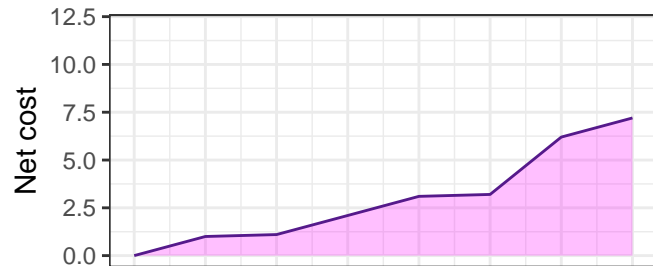
Optimal path



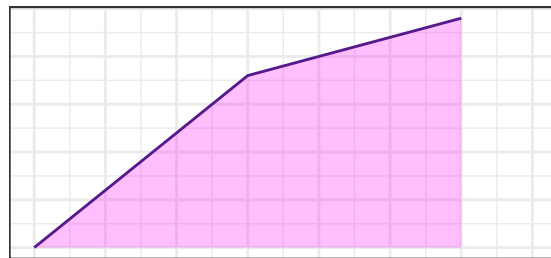
Nominal path



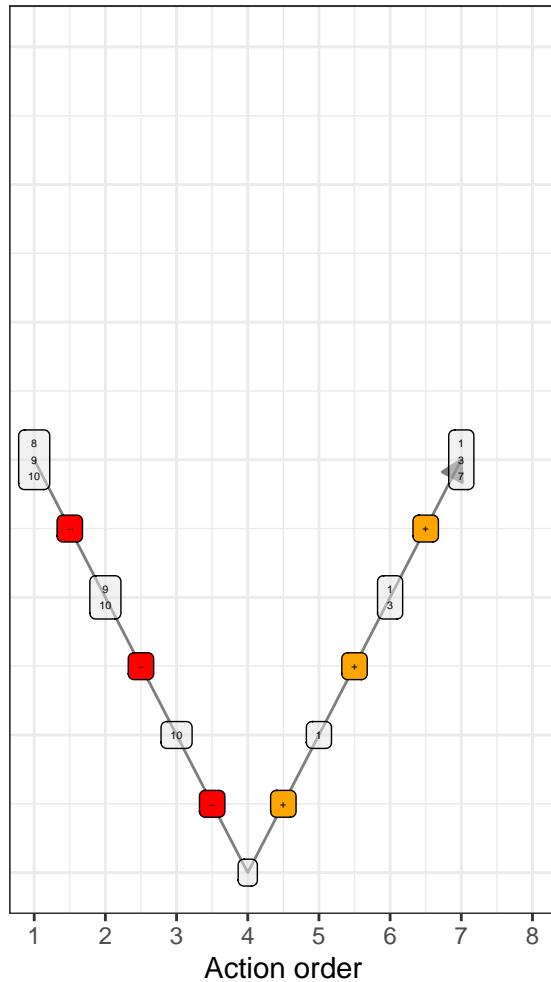
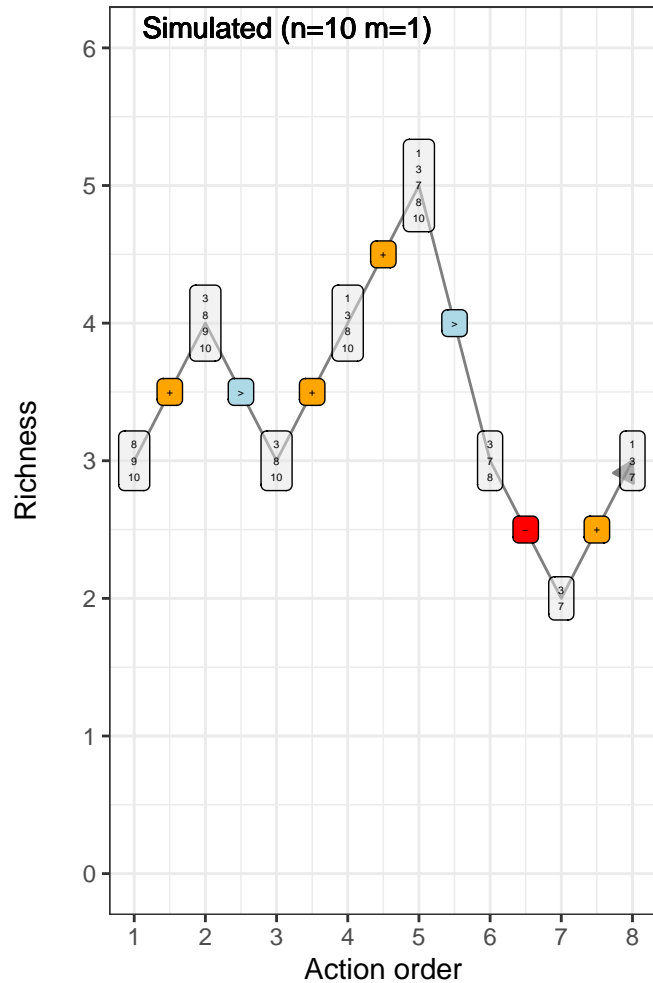
Optimal path



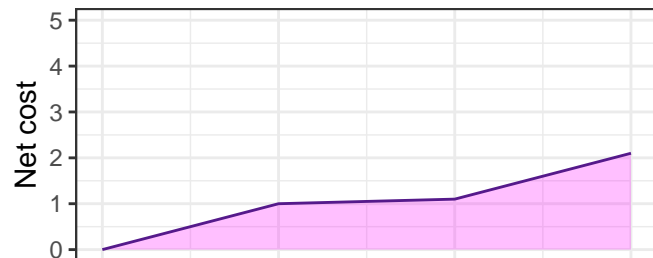
Nominal path



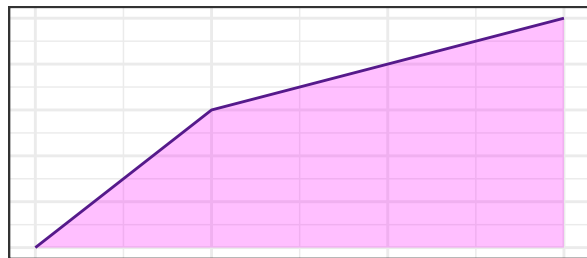
Simulated (n=10 m=1)



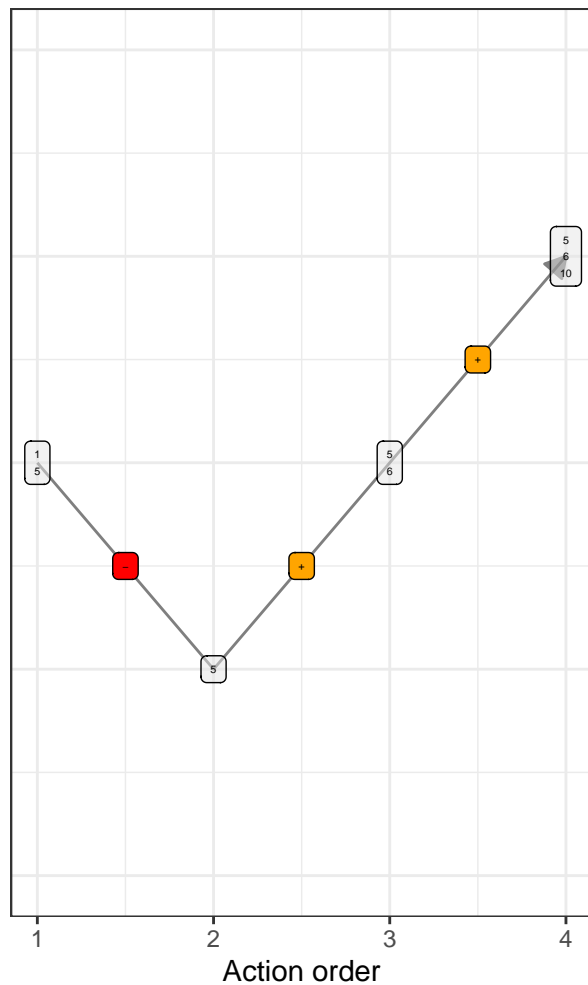
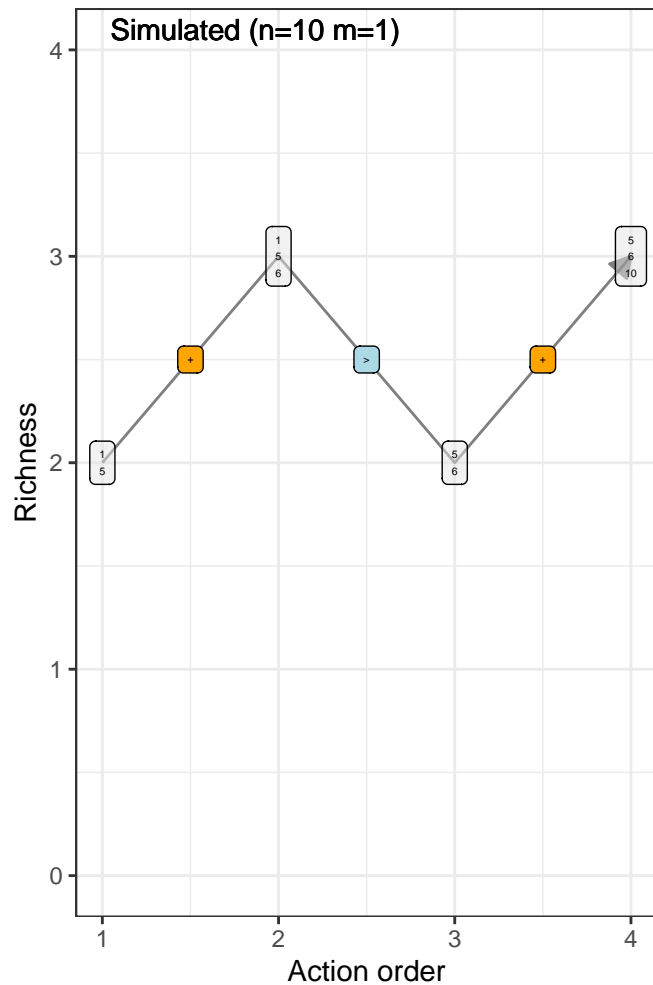
Optimal path



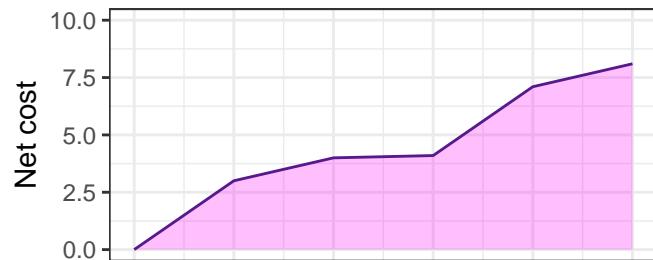
Nominal path



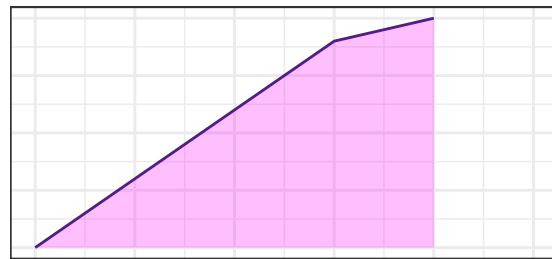
Simulated (n=10 m=1)



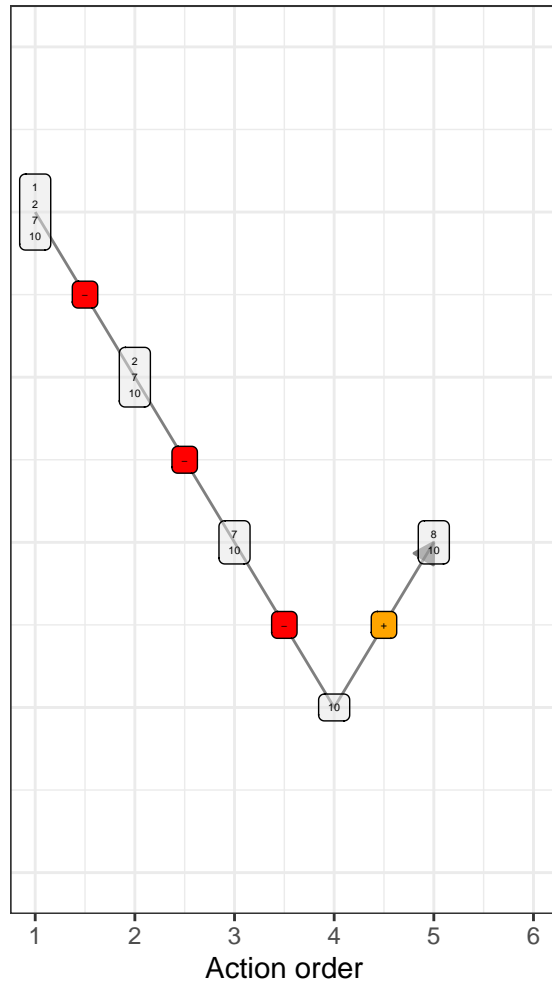
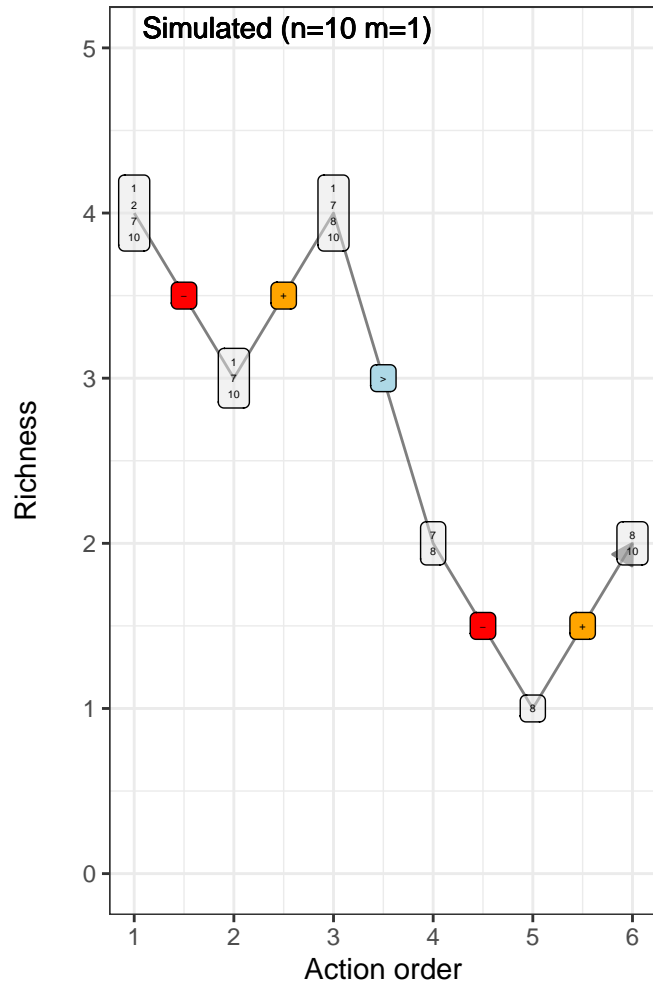
Optimal path



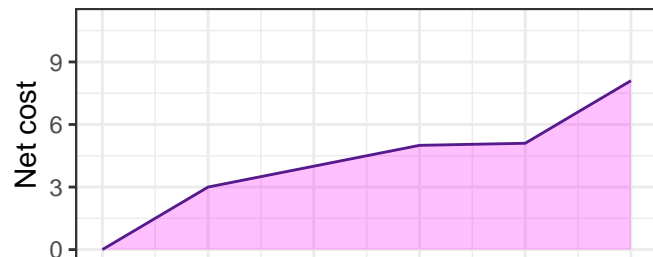
Nominal path



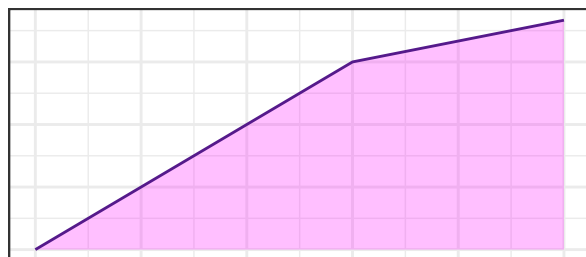
Simulated (n=10 m=1)



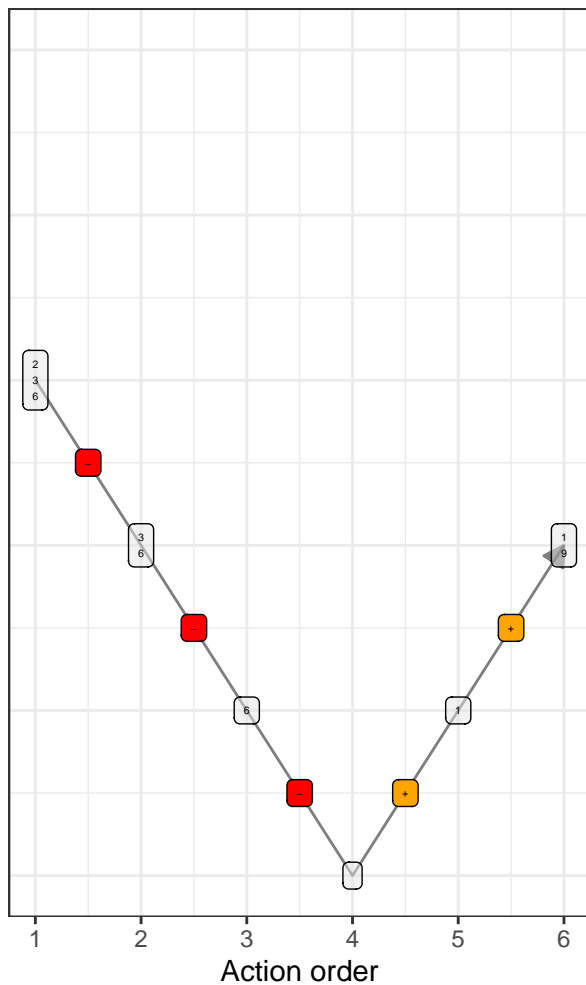
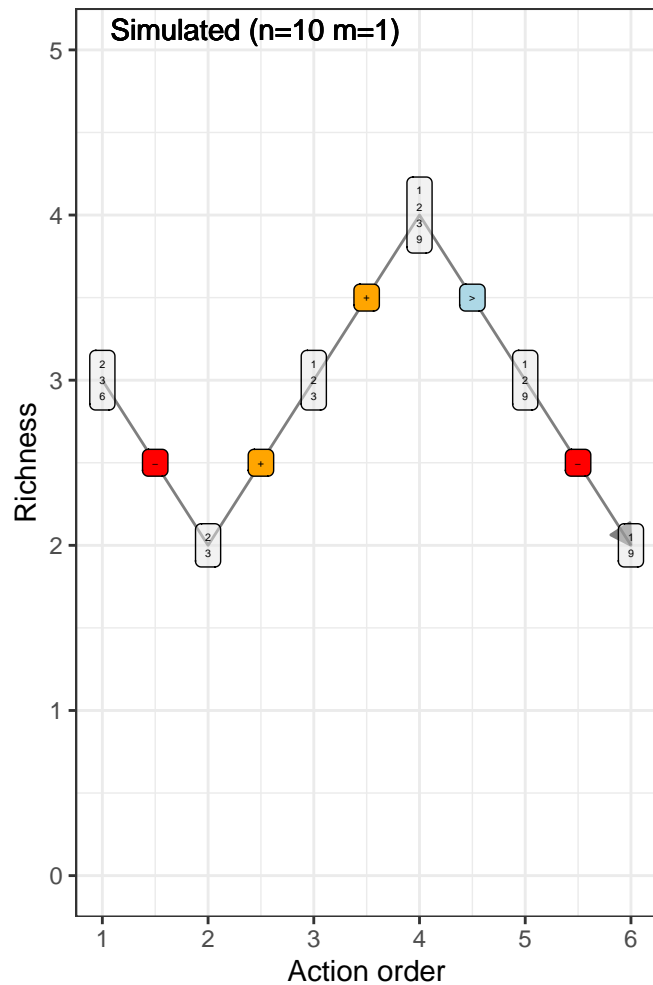
Optimal path



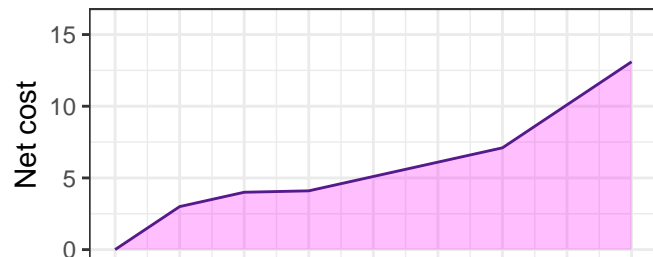
Nominal path



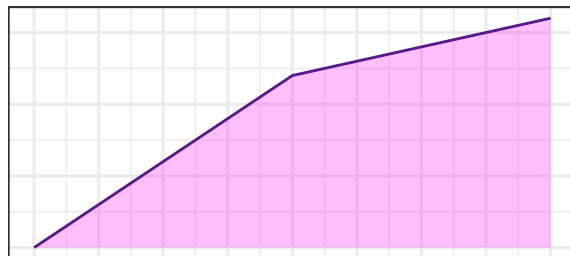
Simulated (n=10 m=1)



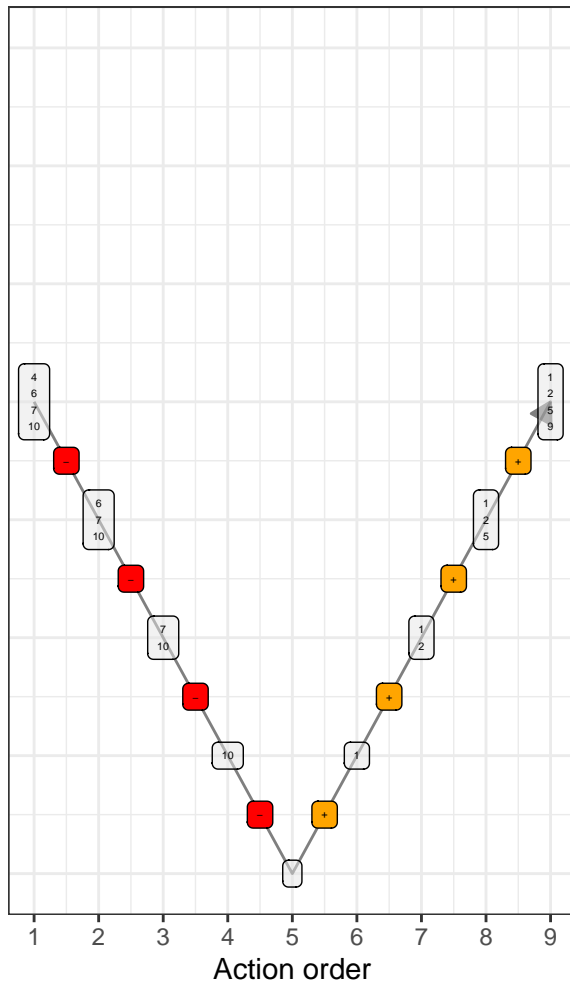
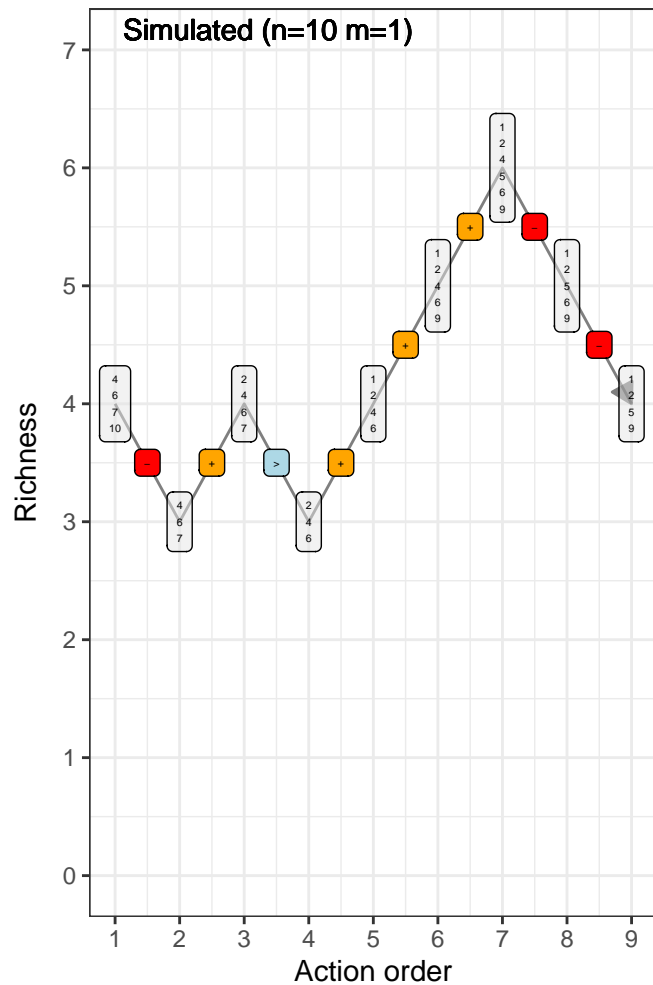
Optimal path



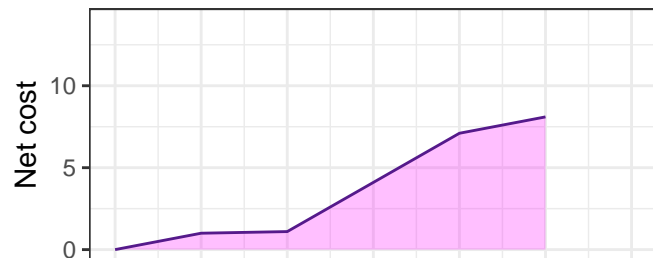
Nominal path



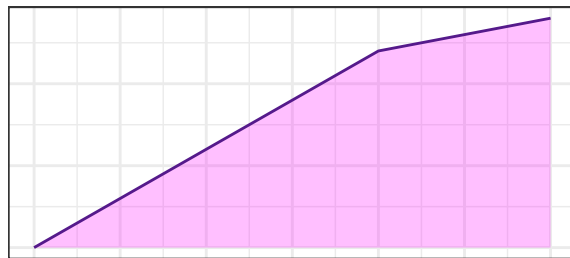
Simulated (n=10 m=1)



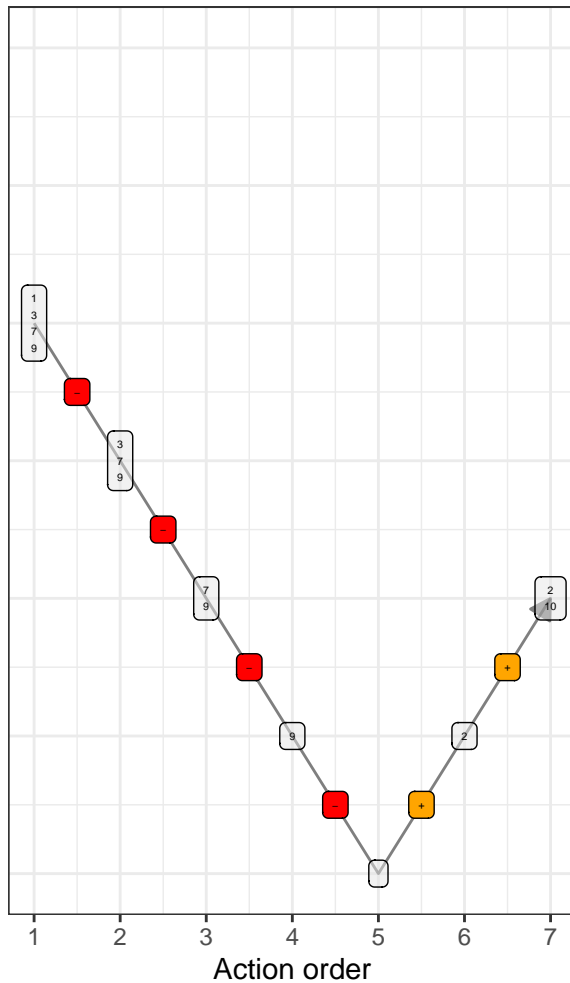
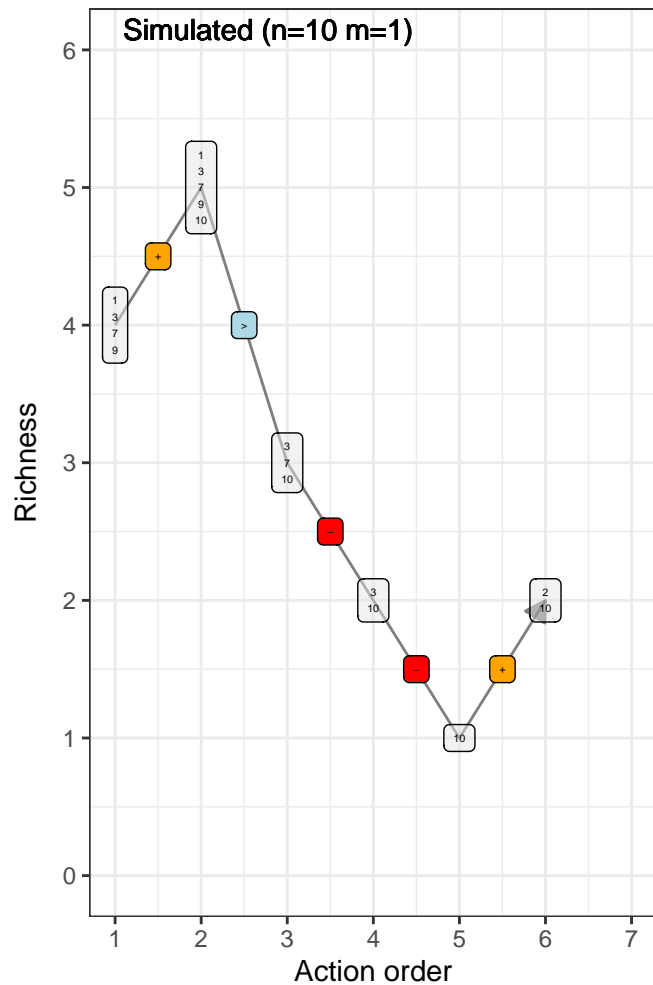
Optimal path



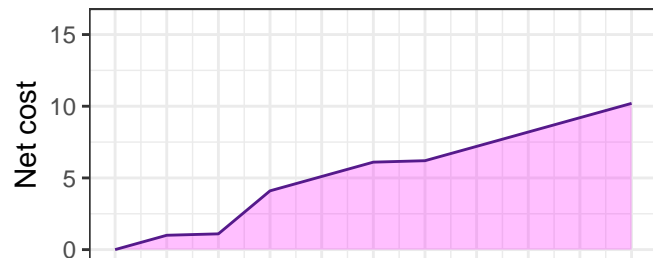
Nominal path



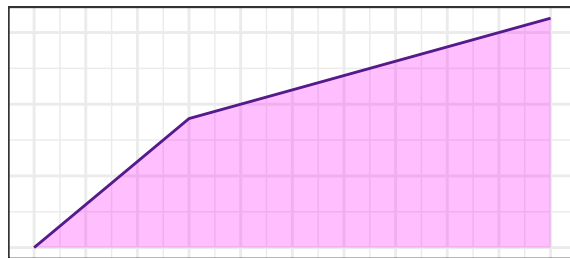
Simulated (n=10 m=1)



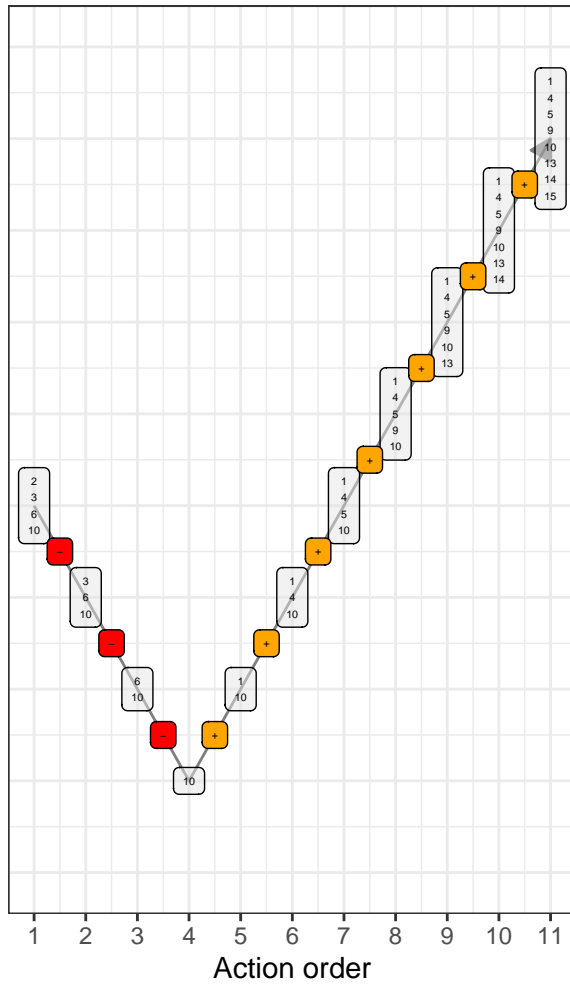
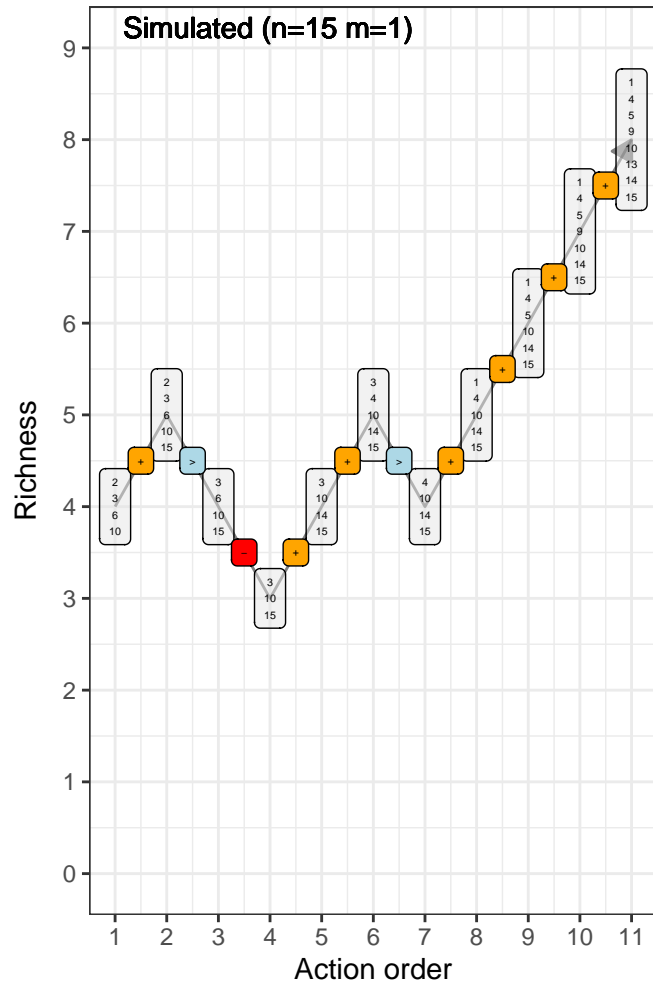
Optimal path



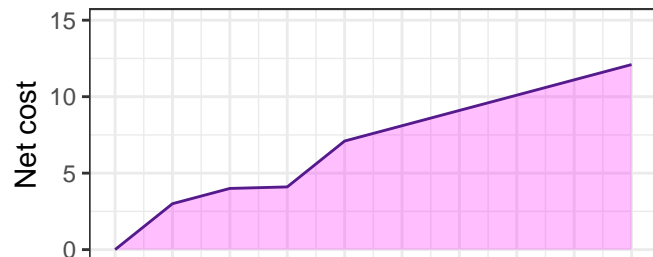
Nominal path



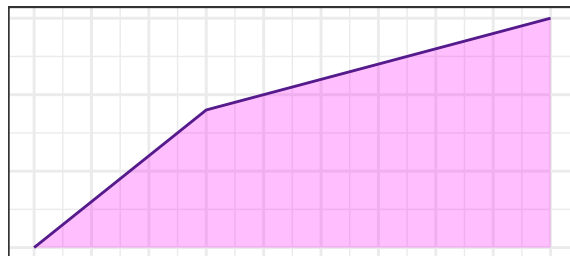
Simulated (n=15 m=1)



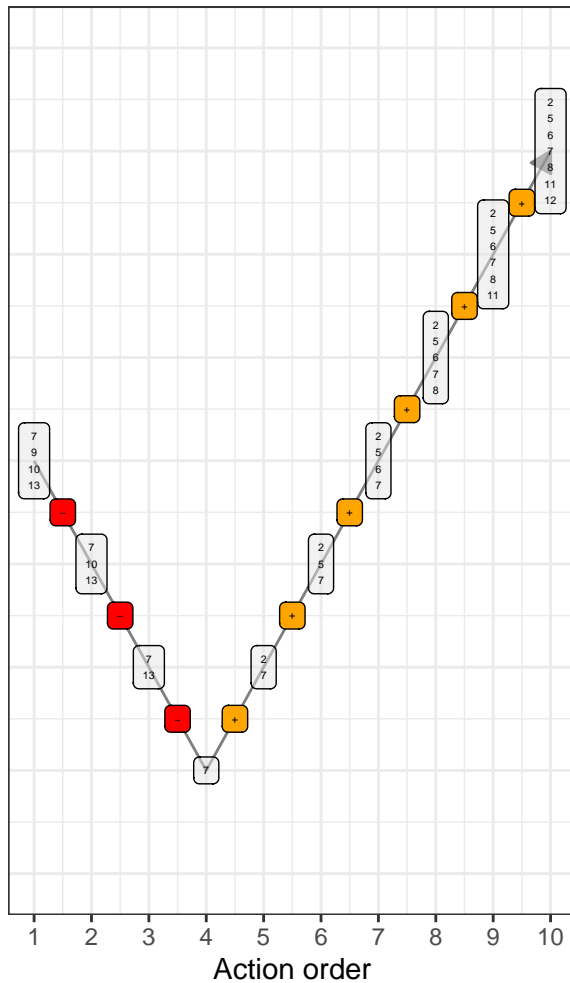
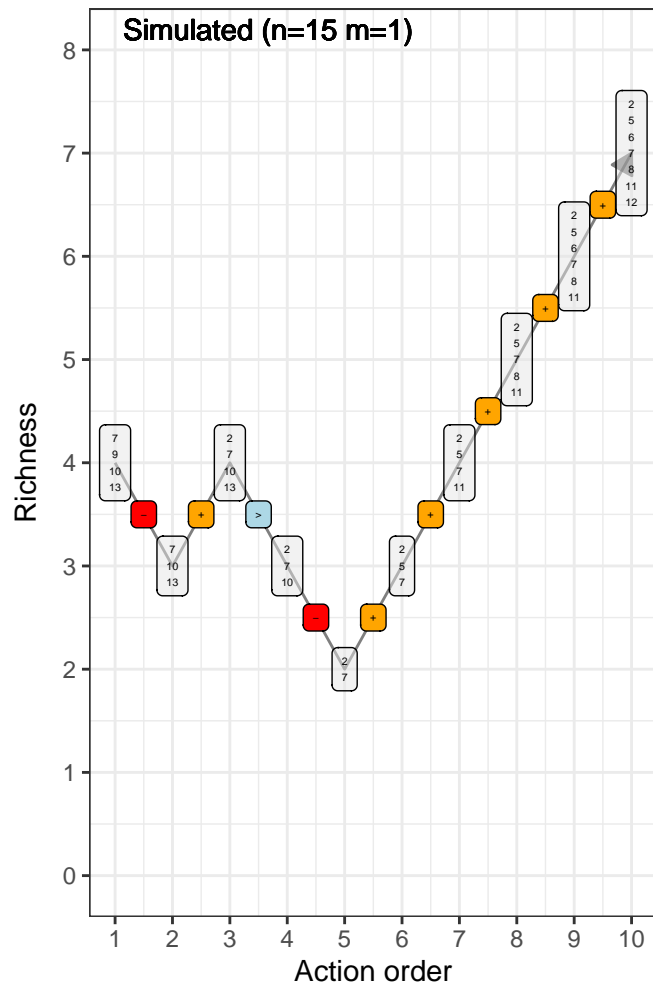
Optimal path



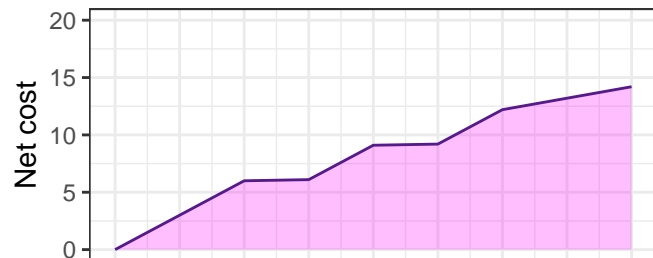
Nominal path



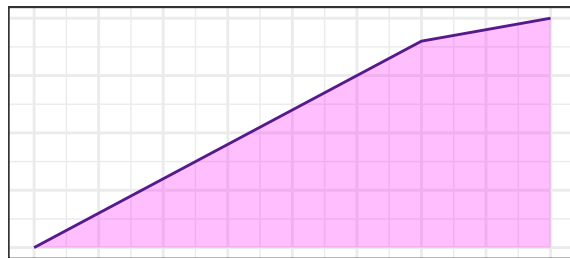
Simulated (n=15 m=1)



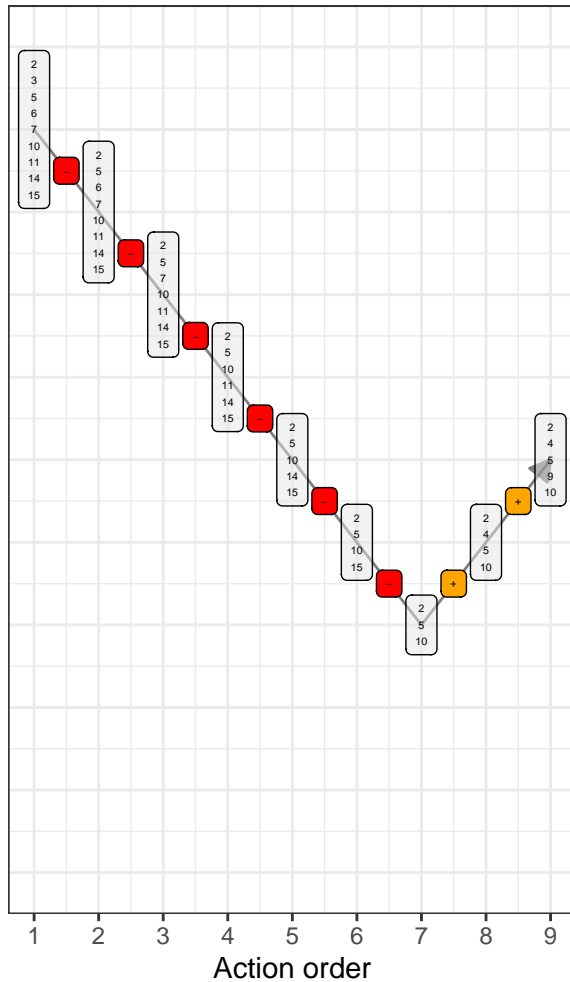
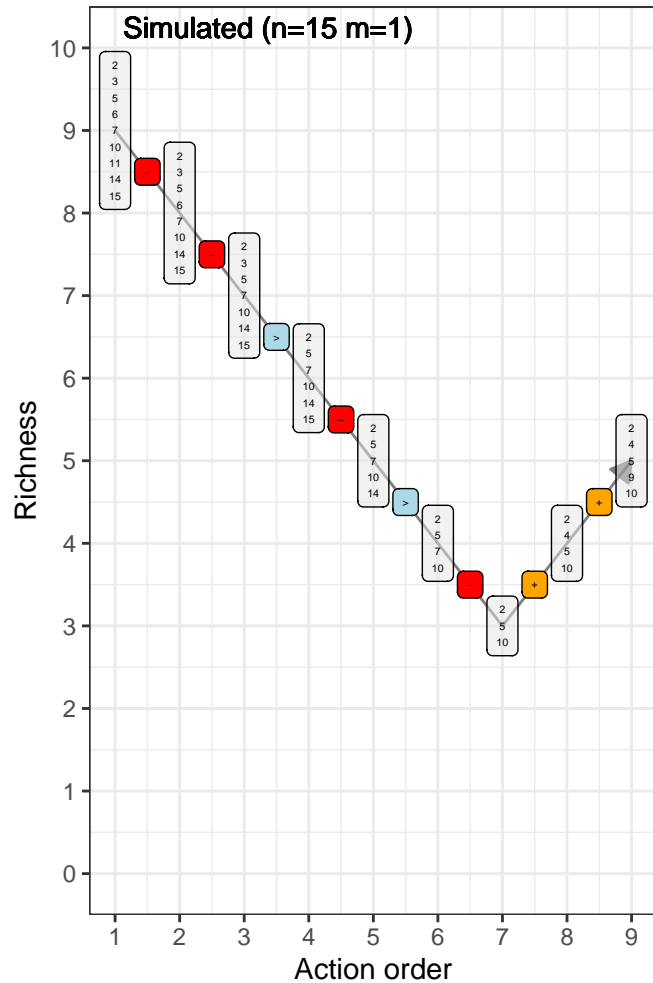
Optimal path



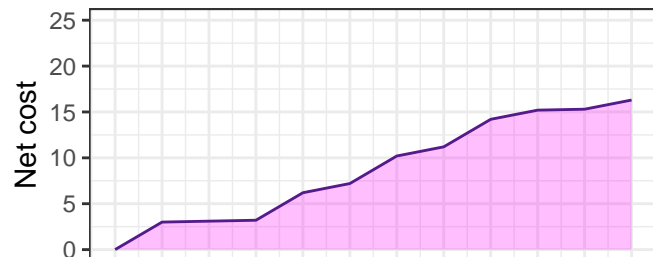
Nominal path



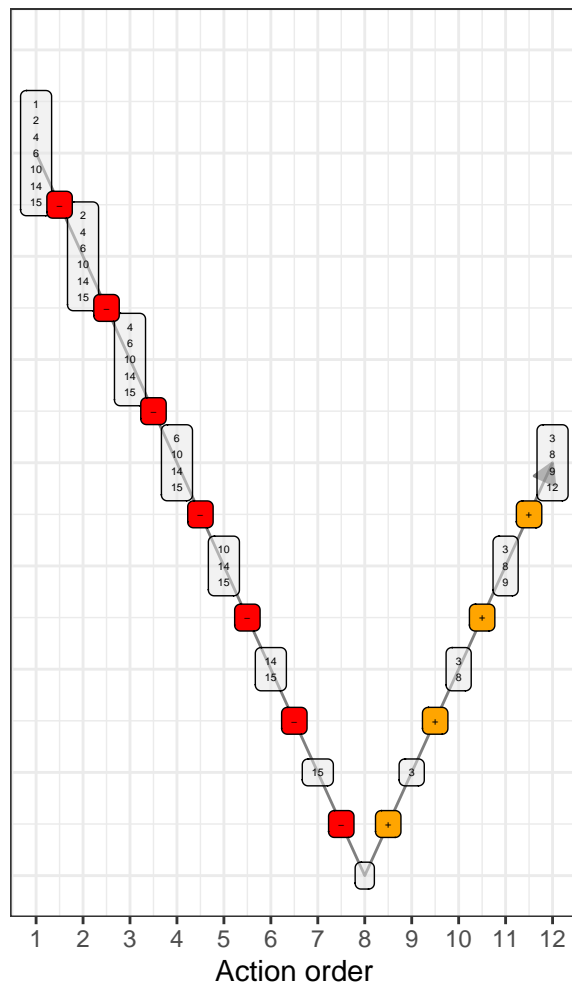
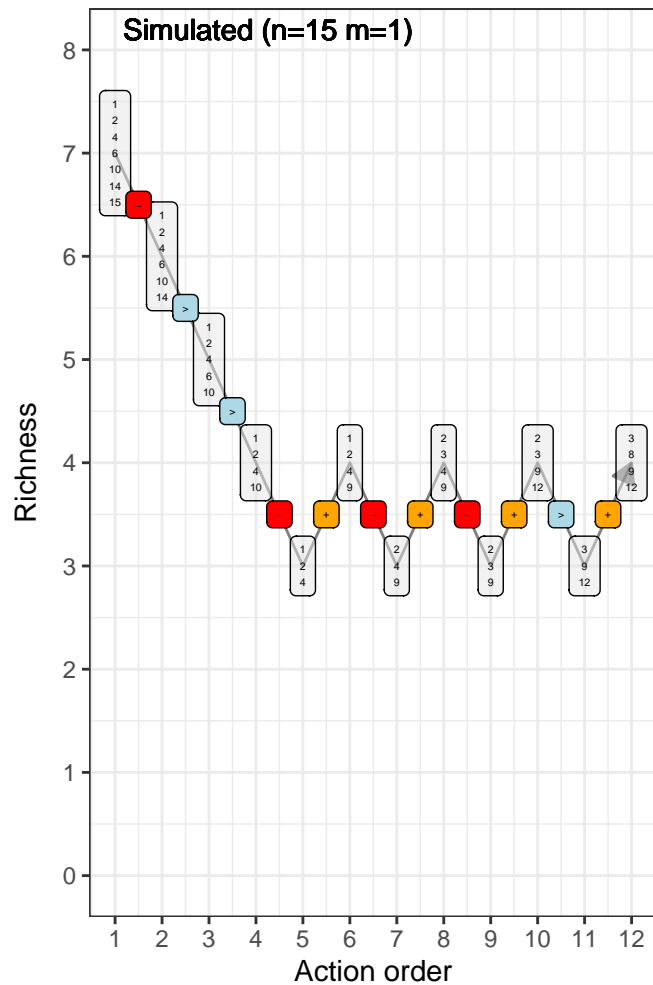
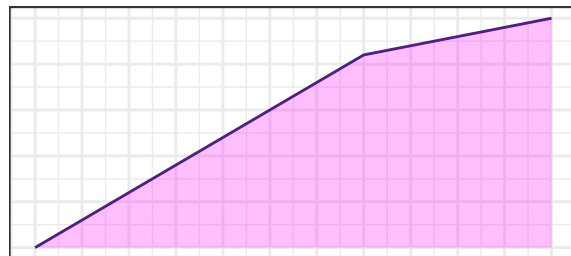
Simulated (n=15 m=1)



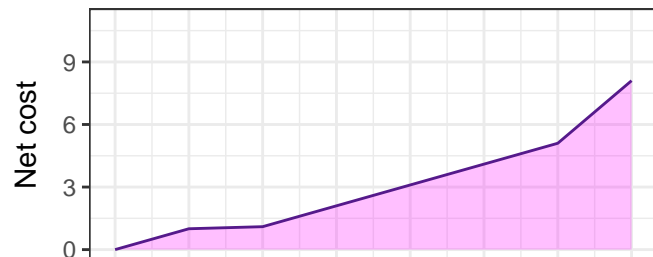
Optimal path



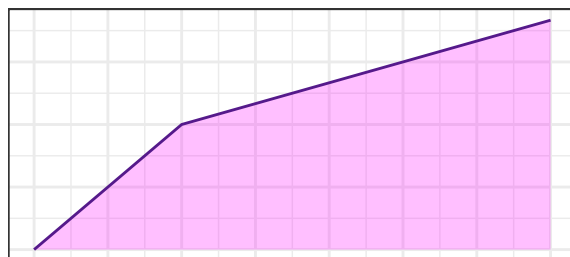
Nominal path



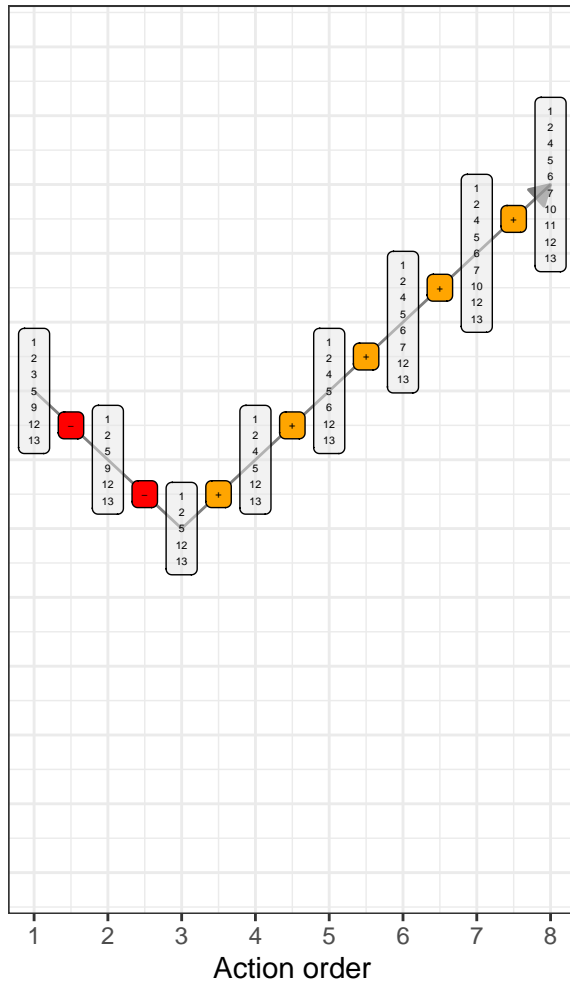
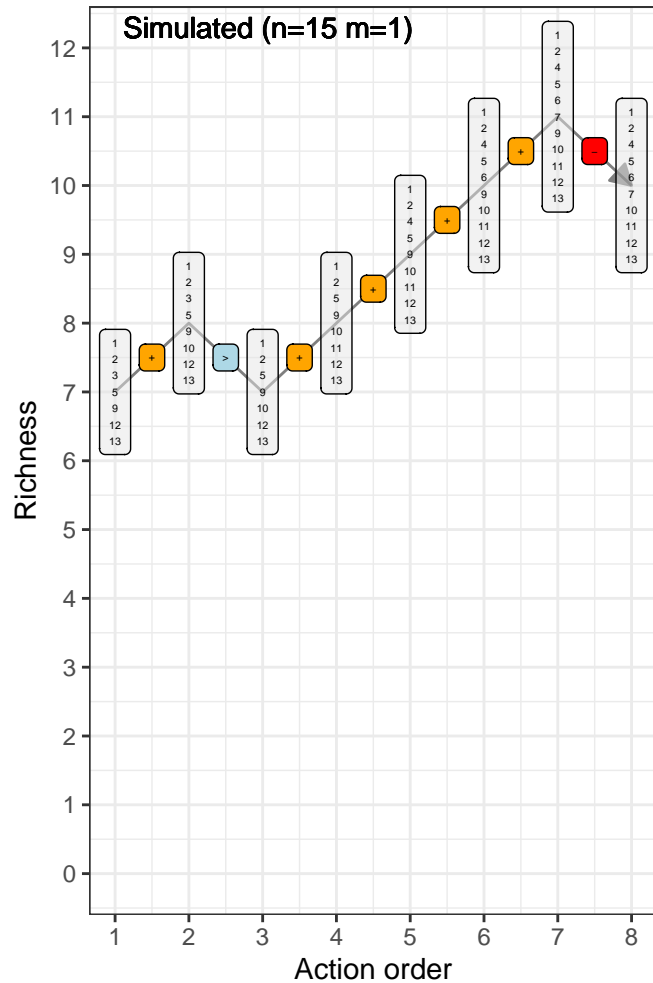
Optimal path



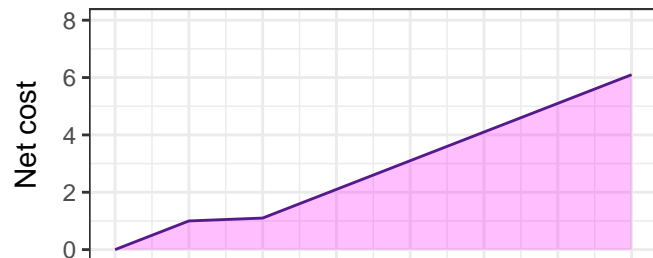
Nominal path



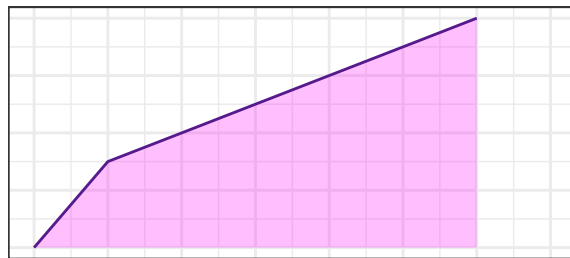
Simulated (n=15 m=1)



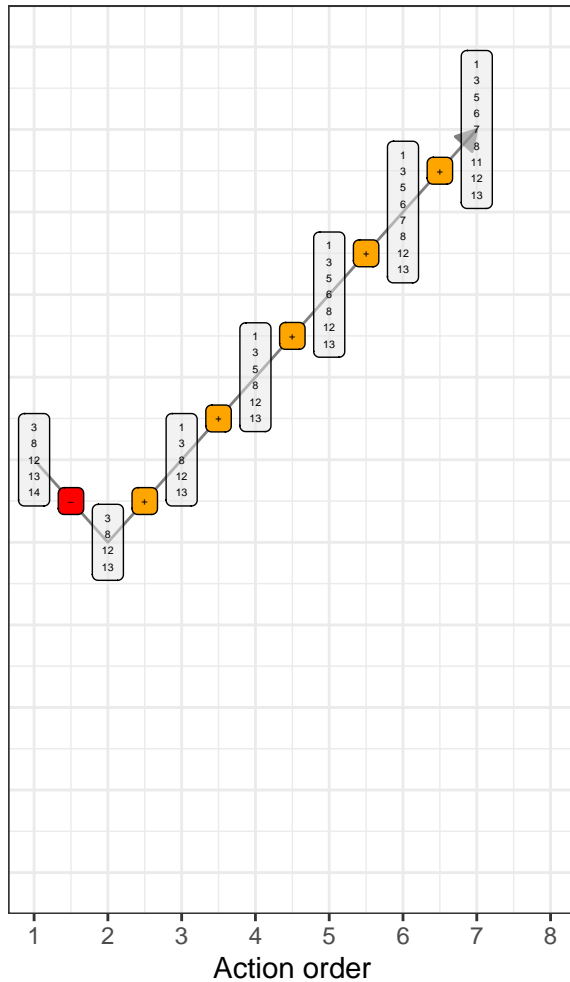
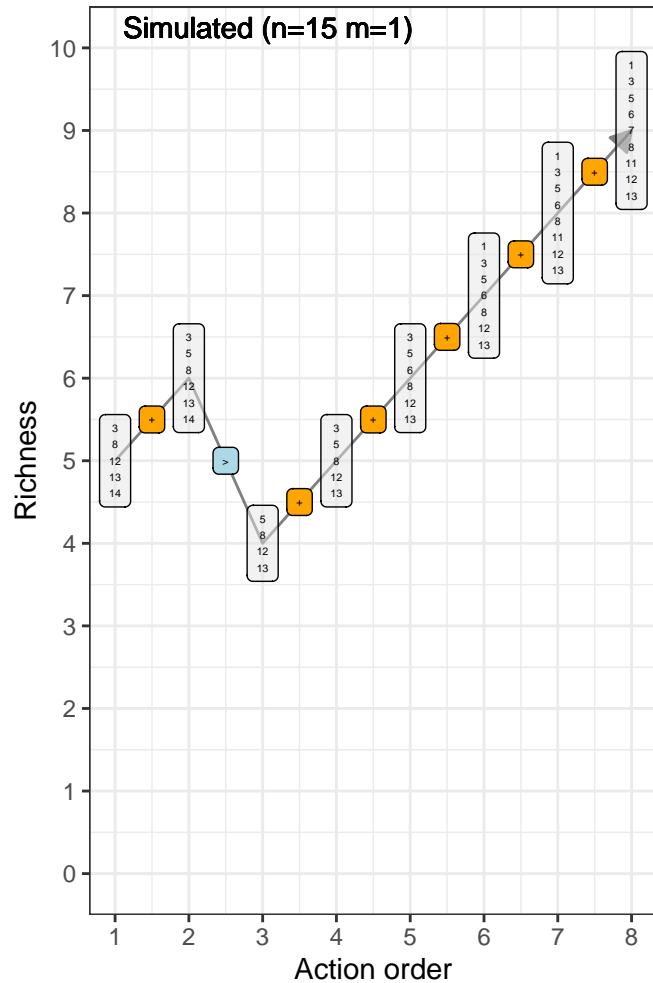
Optimal path



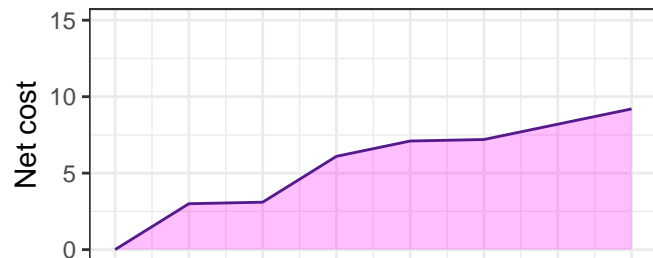
Nominal path



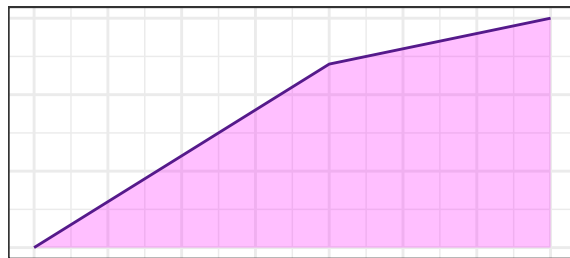
Simulated (n=15 m=1)



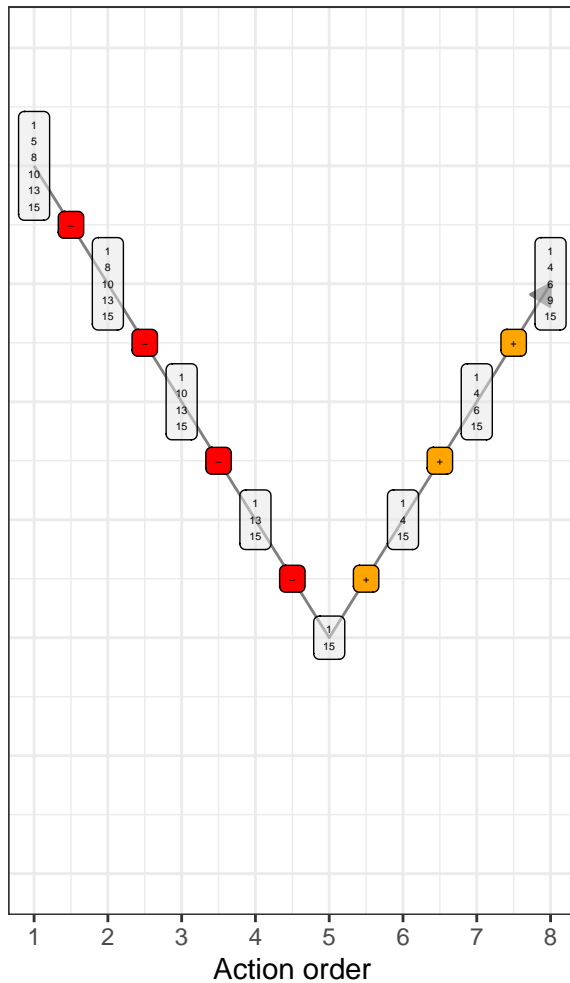
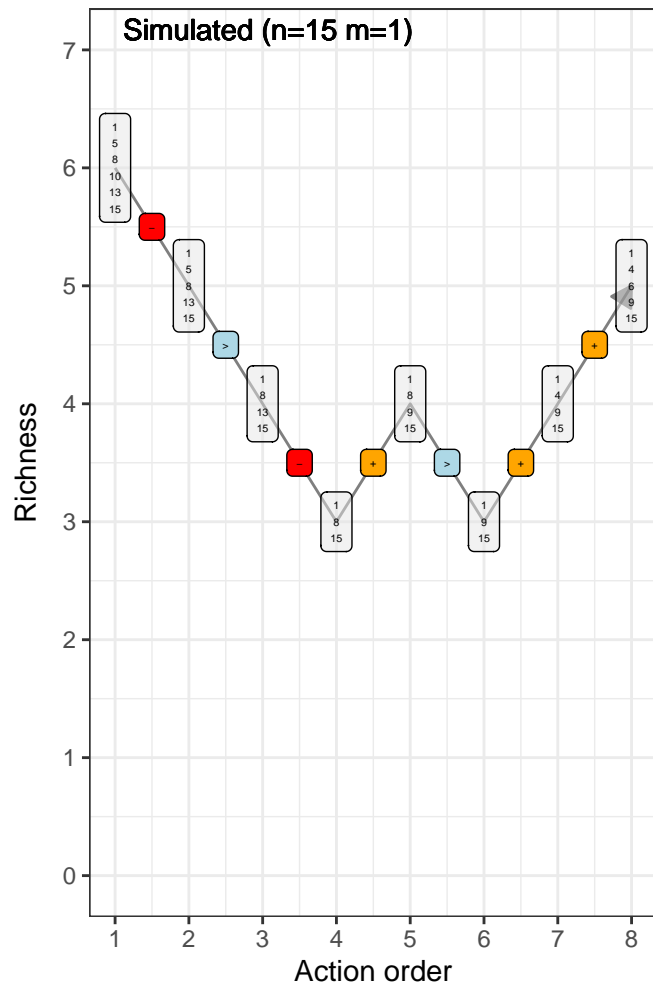
Optimal path



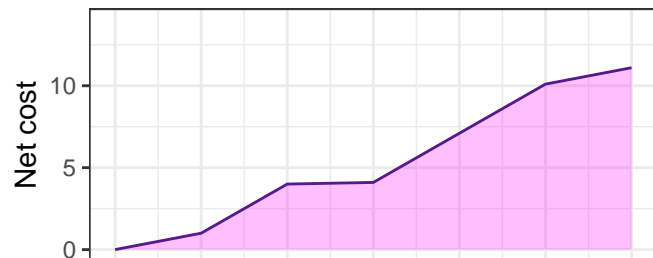
Nominal path



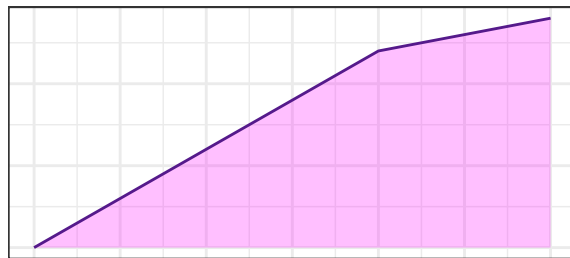
Simulated (n=15 m=1)



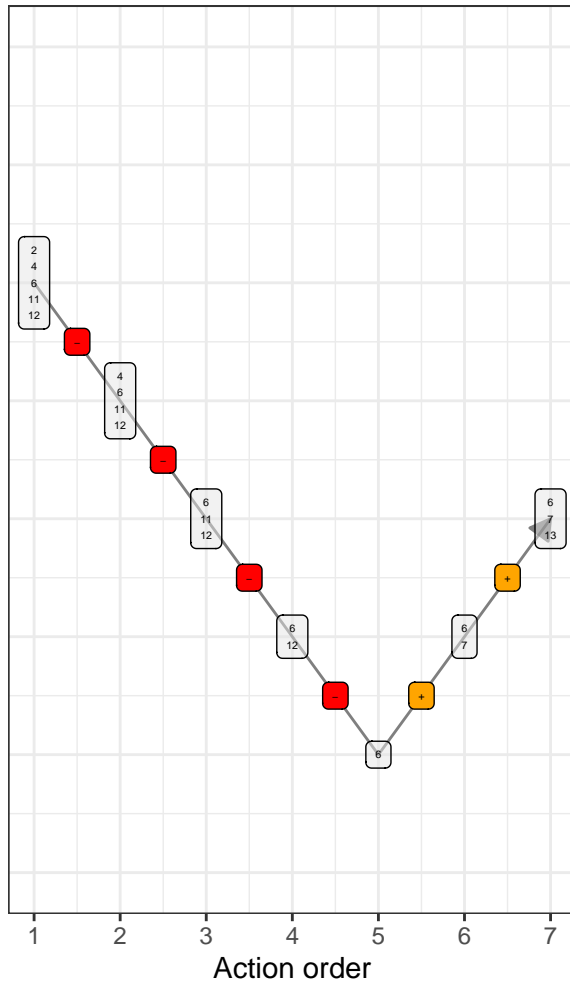
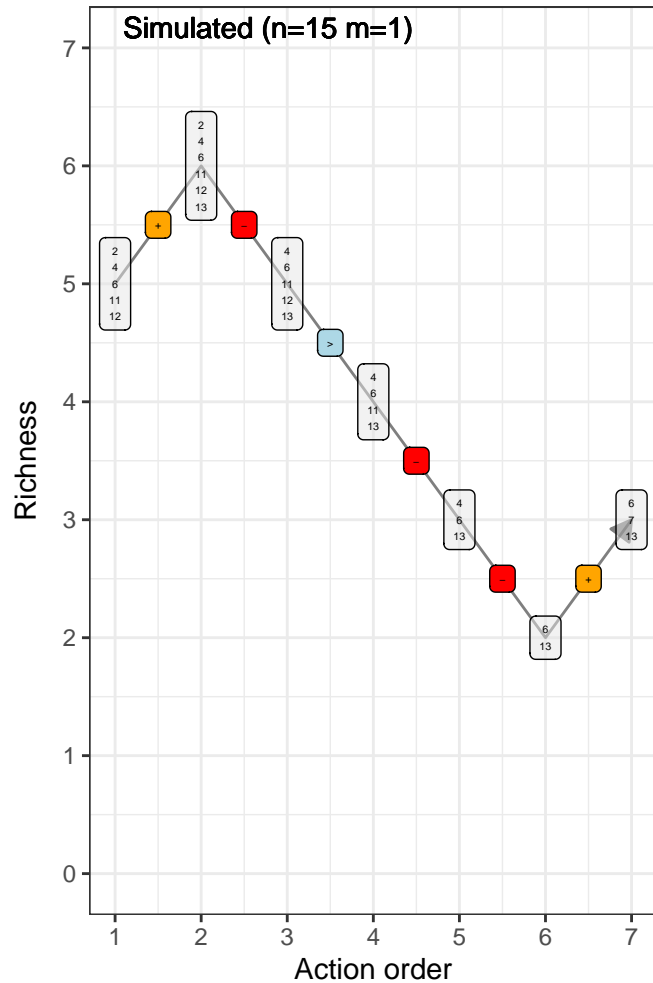
Optimal path



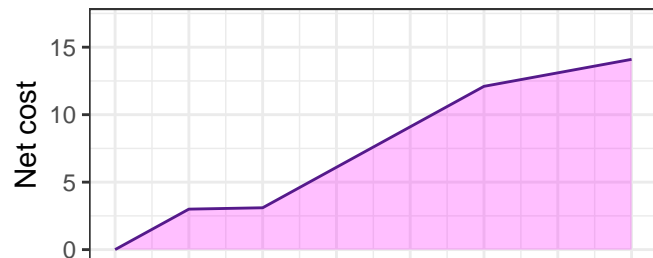
Nominal path



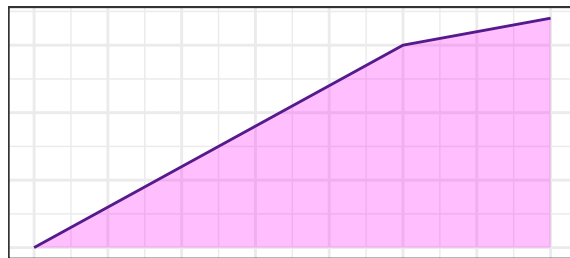
Simulated (n=15 m=1)



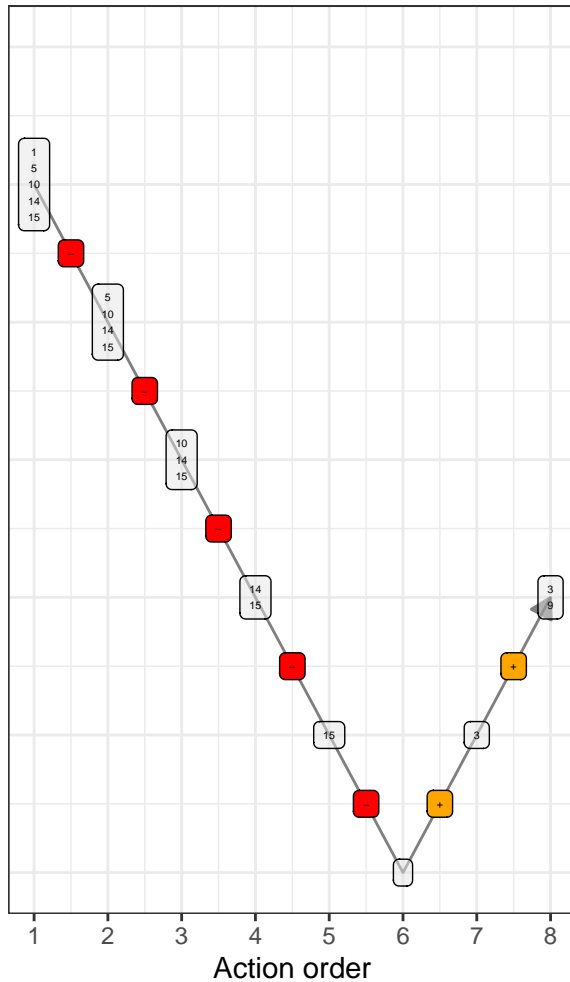
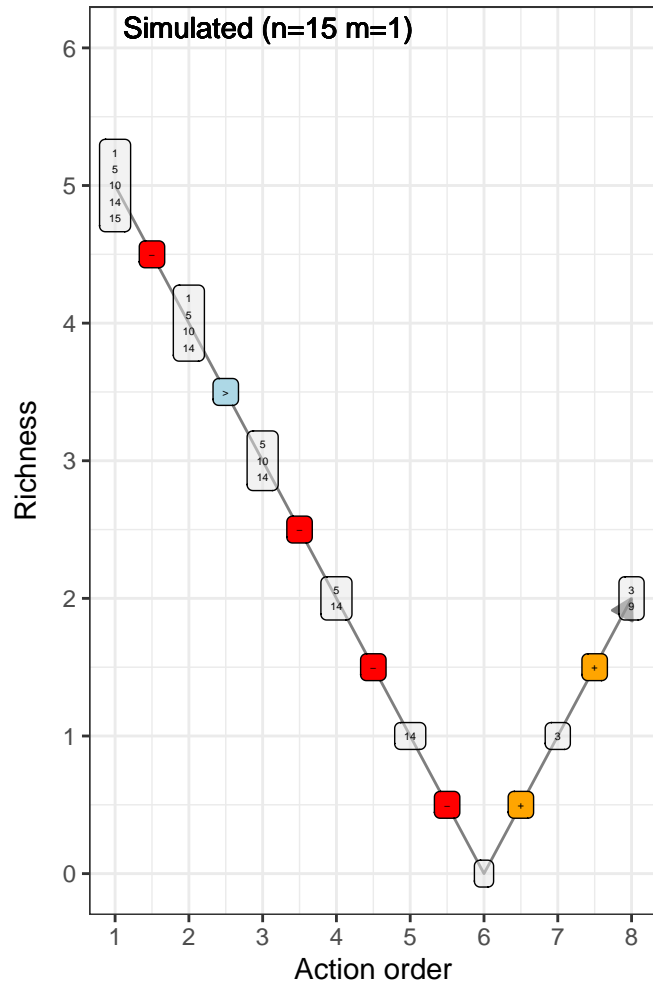
Optimal path



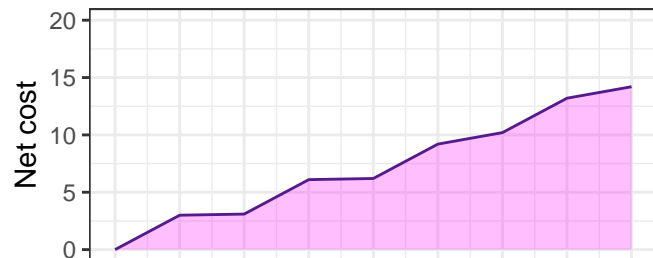
Nominal path



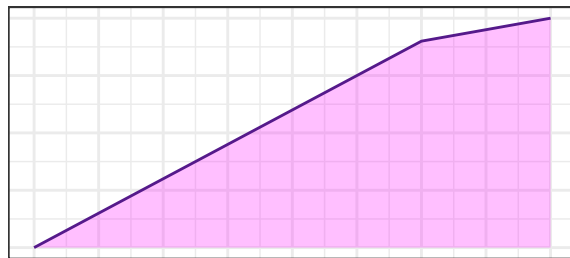
Simulated (n=15 m=1)



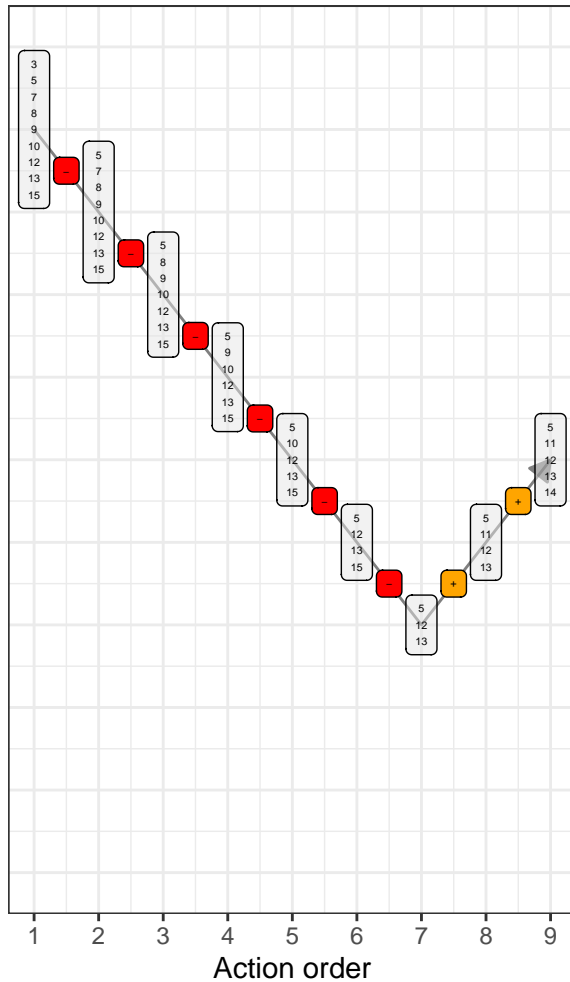
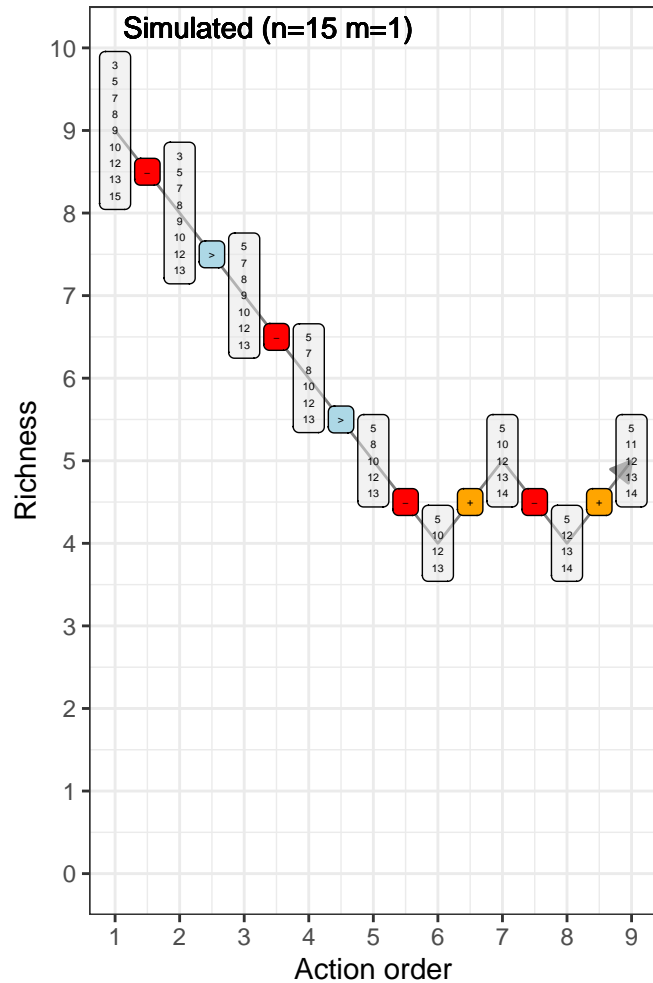
Optimal path



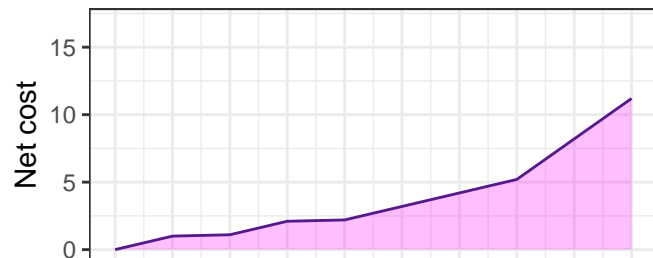
Nominal path



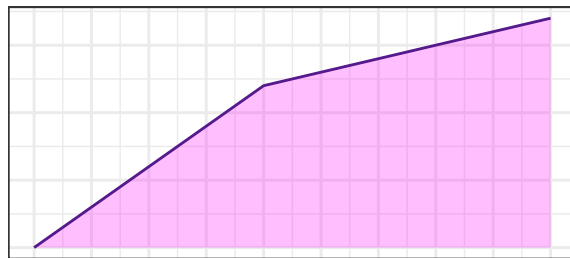
Simulated (n=15 m=1)



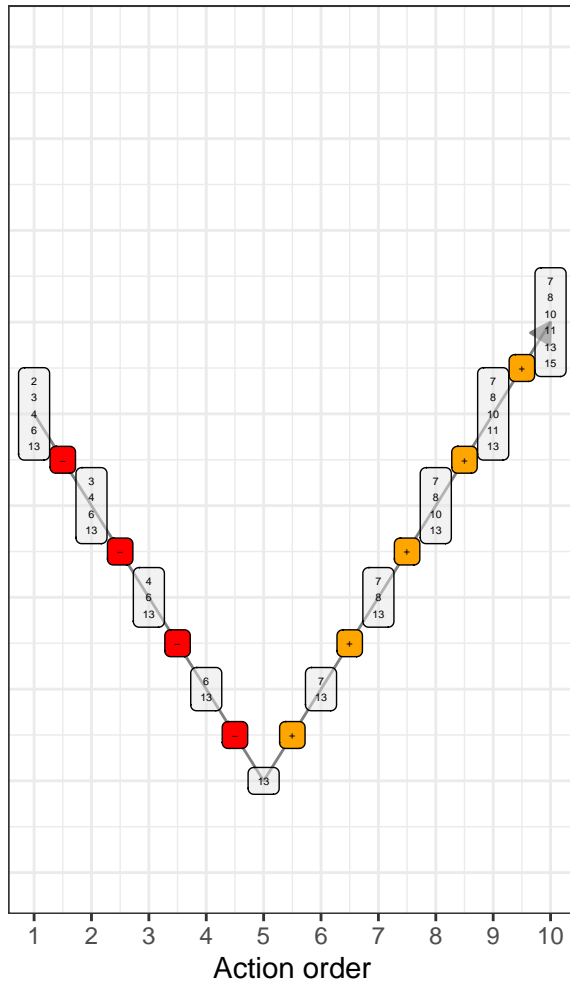
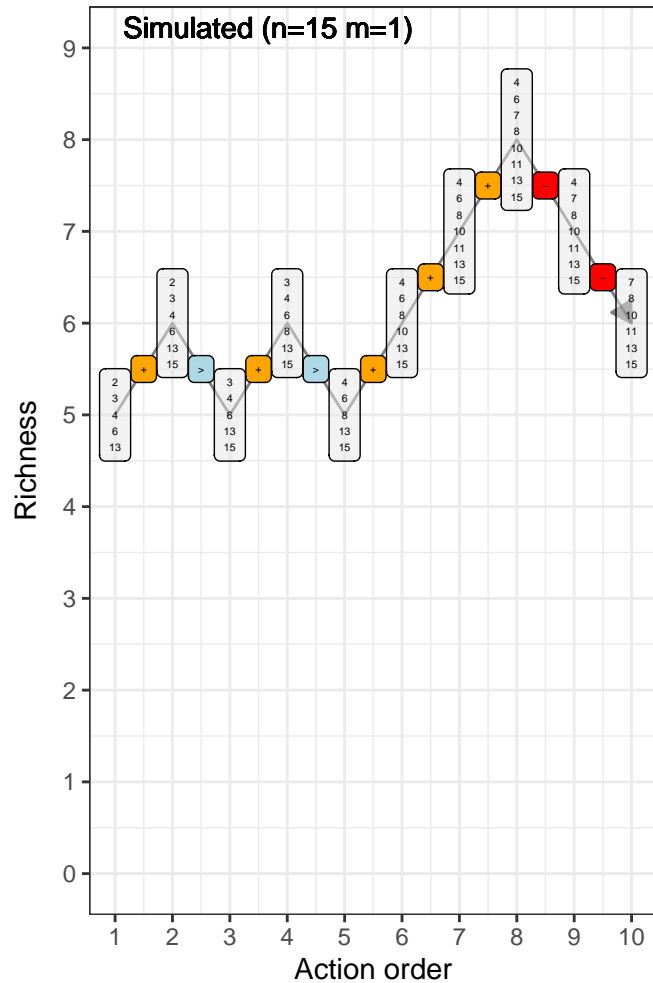
Optimal path



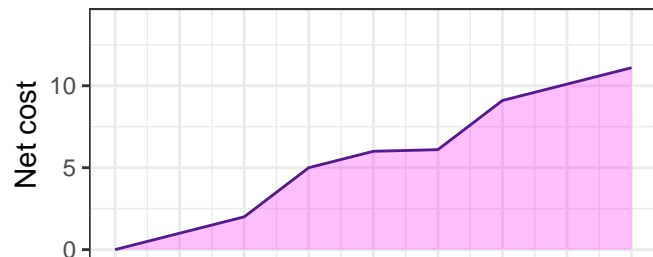
Nominal path



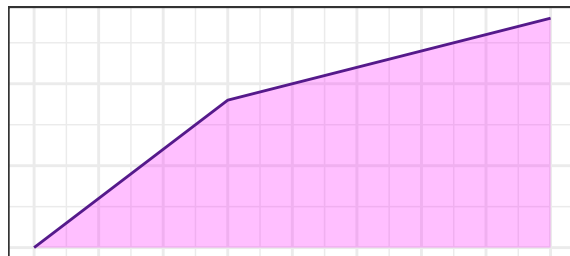
Simulated (n=15 m=1)



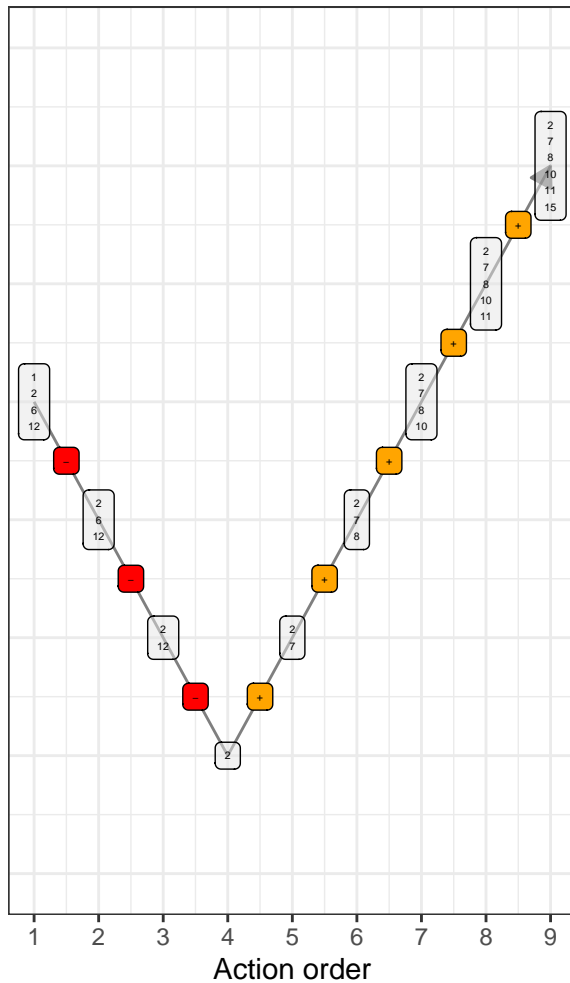
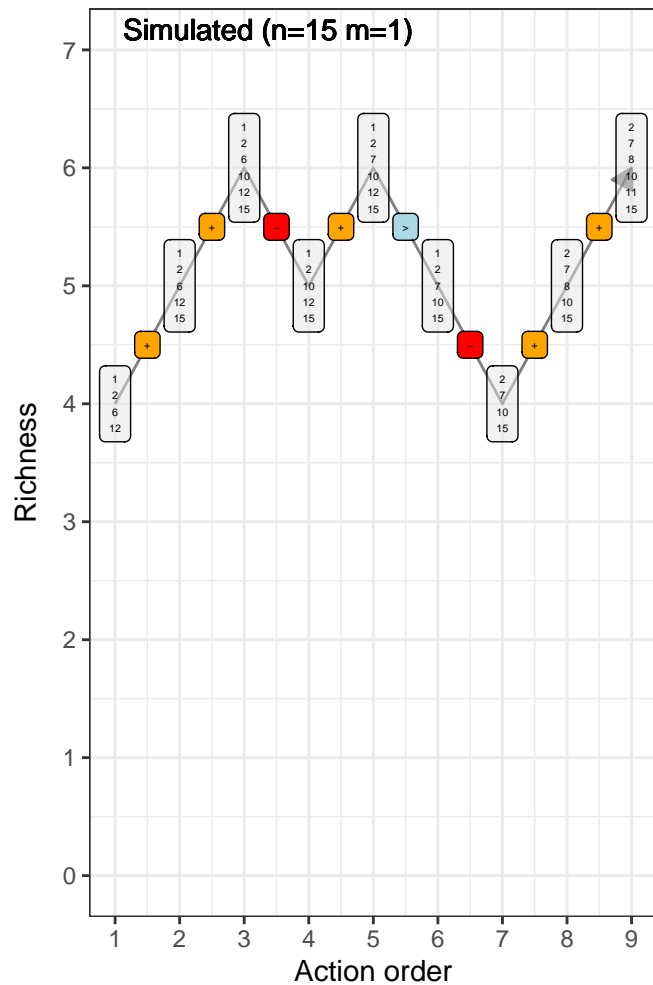
Optimal path



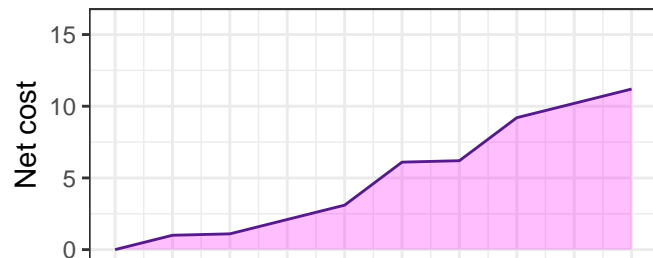
Nominal path



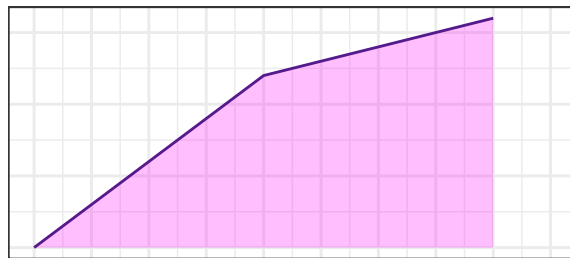
Simulated (n=15 m=1)



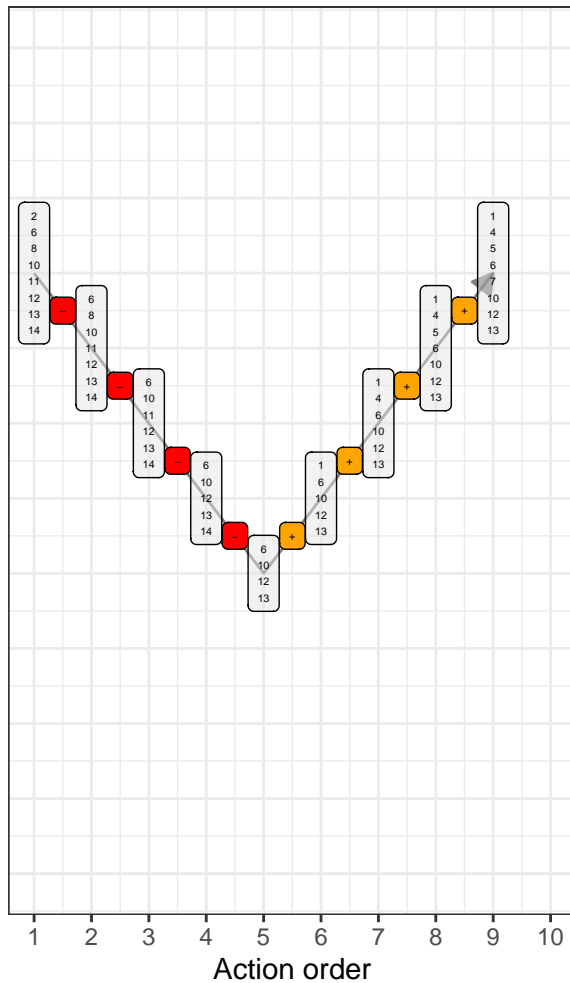
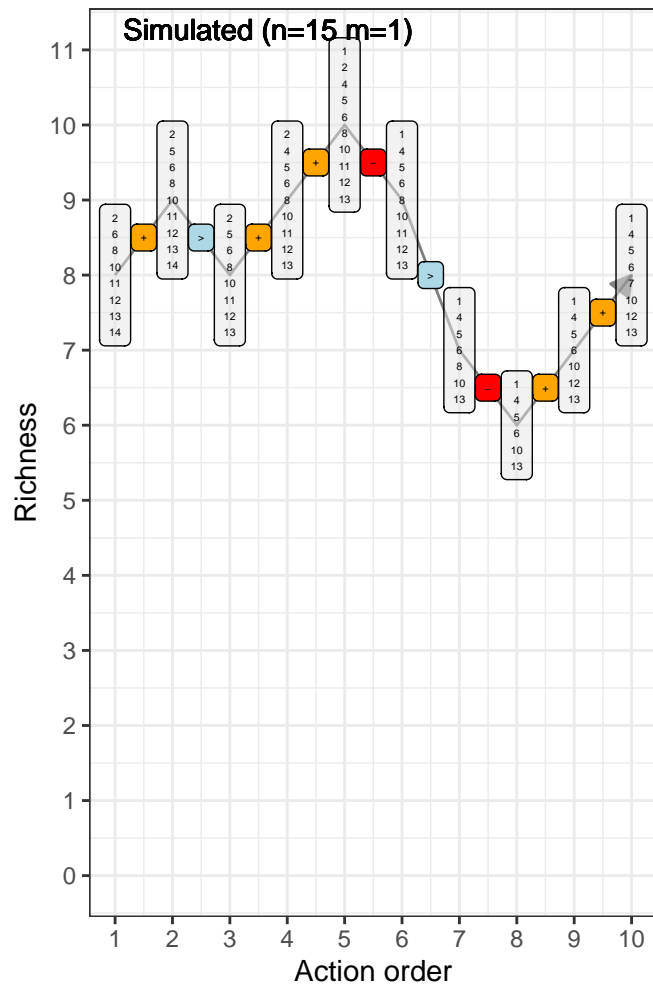
Optimal path



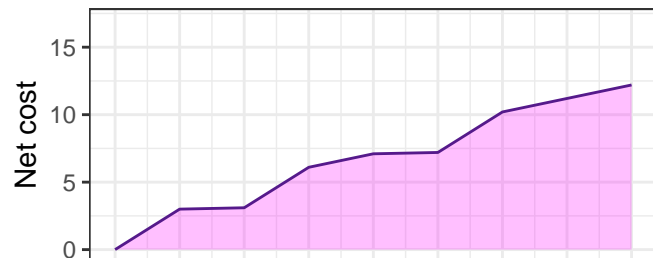
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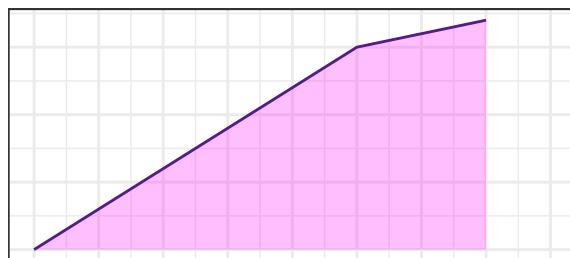
Simulated (n=15 m=1)



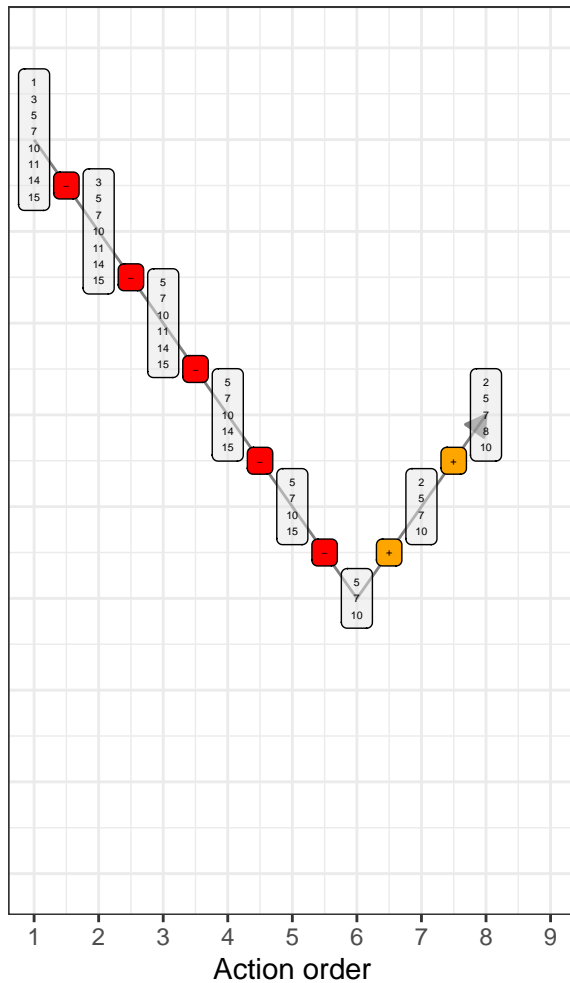
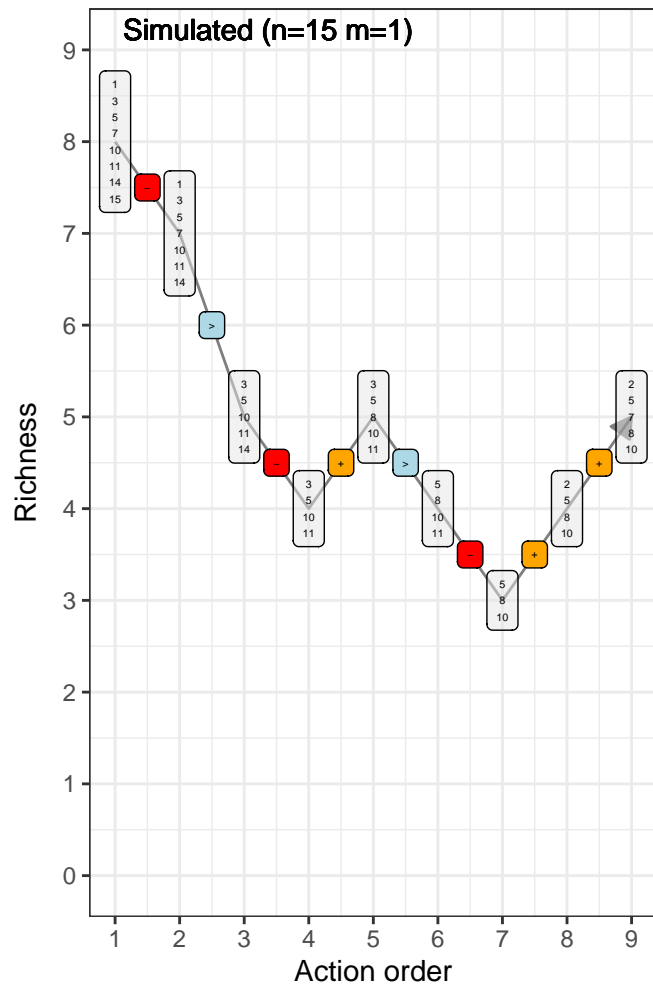
Optimal path



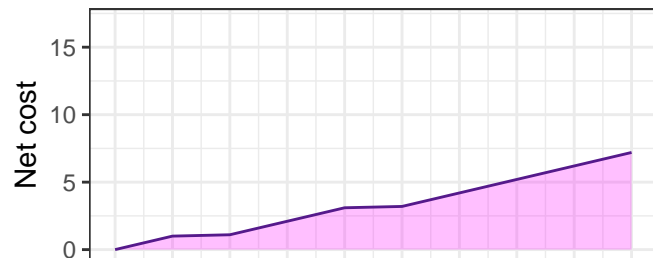
Nominal path



Simulated (n=15 m=1)



Optimal path



Nominal path

