# Generalized additive (mixed) models

```
library(mgcv)
library(gratia)
library(tidyverse)
```

#### **Additive models**

- generally a way to specify more complex (smooth) terms based on individual covariates:  $\mu = \beta_0 + f_1(x_1) + f_2(x_2) + \dots$
- lots of ways to generate  $f_i(x_i)$ : kernel estimators, locally weighted polynomials, ... see T. J. Hastie and Tibshirani (1990), T. Hastie, Tibshirani, and Friedman (2009) (backfitting algorithm etc.)
- we will focus on

### **Basis expansions**

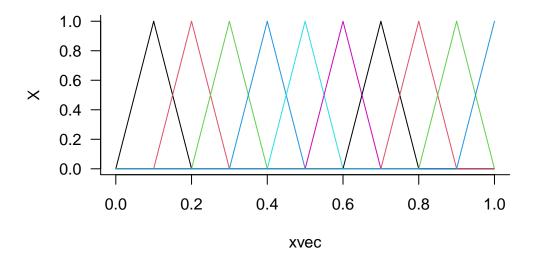
- (theoretically) infinitely expandable
- e.g. polynomials ('regular'/raw, orthogonal, Legendre, Hermite)
- wavelet, Fourier
- splines: **piecewise polynomial** with continuity/smoothness constraints

### Spline degree

```
xvec <- seq(0, 1, length.out = 101)
sfun <- function(d = 3, type = "bs", ...) {
   if (type == "bs") {
        X <- splines::bs(xvec, df = 10, degree = d)
   } else {
        X <- splines::ns(xvec, df = 10)</pre>
```

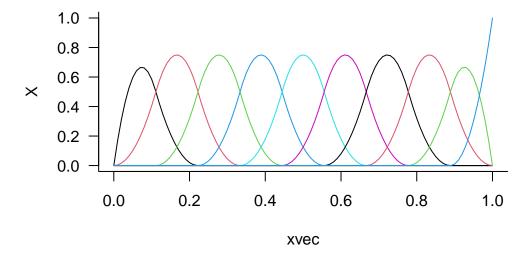
```
}
  par(bty = "l", las = 1)
  matplot(xvec, X, type = "l", lty = 1, ...)
}
sfun(d = 1, main = "degree-1")
```

# degree-1



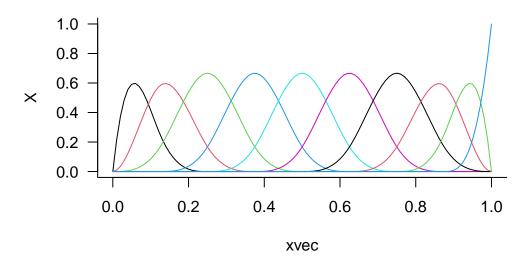
sfun(d = 2, main = "degree-2")

# degree-2



```
sfun(d = 3, main = "degree-3")
```

## degree-3



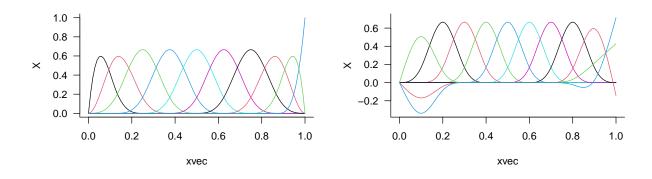
## spline terminology

- **knots**: breakpoints (boundary, interior)
- order-M (ESL): continuous derivatives up to order M-2 (cubic, M=4)
- typically M = 1, 2, 4
- number of knots = df (degrees of freedom) -1 -intercept

## Spline choices

- continuous derivatives up to d-1
- truncated polynomial basis (simple)
- B-splines: complex, but minimal support/maximum sparsity
- natural splines: extra constraint, derivatives > 1 vanish at boundaries

```
par(mfrow = c(1,2))
sfun()
sfun(type = "ns")
```



### choosing knot locations

• generally not that important: evenly spaced, or evenly spaced based on quantiles

#### choosing basis dimension

- in principle could expand dimension to match total number of points (interpolation spline)
- ... but that would overfit
- AIC, adjusted  $R^2$ , cross-validation ...

#### smoothing splines

- as many knots as data points
- plus squared-second-derivative ("wiggliness") penalty

$$RSS + \lambda \int (f''(t))^2 dt$$

- defined on an infinite-dimensional space
- minimizer is a natural cubic spline with knots at  $x_i$

$$(\mathbf{y} - \mathbf{Z}\mathbf{b})^{\top}(\mathbf{y} - \mathbf{Z}\mathbf{b}) + \lambda \mathbf{b}^{\top}\Omega\mathbf{b}$$

with 
$$\{\Omega\}_{jk}=\int \mathbf{Z}_{j}''(t)\mathbf{Z}_{k}''(t)\,dt$$
 \$\$

- generalized ridge regression: penalize by  $\lambda\Omega_N$  rather than  $\lambda I$
- same data augmentation methods as before except that now we use  $\sqrt{\lambda}C$  where C is a matrix, and the "square root" (Cholesky factor) of  $\Omega_N$

See Simon N. Wood (2017), Perperoglou et al. (2019)

#### connection to mixed models

- note that  $\lambda \mathbf{b}^{\top} \Omega \mathbf{b}$  is equivalent to  $(1/\sigma^2) \mathbf{b} \Sigma'^{-1} \mathbf{b}^{\top}$ ; if  $\Sigma'$  is a *scaled* covariance matrix (i.e.  $\Sigma = \sigma^2 \Sigma$ ), then this is the core of the MVN log-likelihood  $\log L(\mathbf{b}|\Sigma)$  (all we're missing is a factor of  $\mathrm{Det}(\Sigma)^{-1/2}$  and a normalization constant)
- So we can fit this with any of the mixed model machinery, provided we can set up the correct covariance matrix

#### generalized cross-validation score

- very close to AIC
- Larsen (2015), Golub, Heath, and Wahba (1979)
- minimize RSS/ $(\text{Tr}(\mathbf{I} \mathbf{S}(\lambda)))^2$ , where S is
- "a rotation-invariant version of PRESS"  $(\sum (e_i/(1-h_{ii}))^2)$
- replace RSS with approximation of deviance,

$$||\sqrt{\mathbf{W}}(\mathbf{z} - \mathbf{X}\beta)||^2$$

for generalized (non-Gaussian) models

## ML criterion, REML criterion

- treat spline smoothing as a *mixed model* problem
- spline (penalized) parameters are **u**
- $y|u \sim N(\mathbf{X}\beta + \mathbf{Z}\mathbf{u}, \sigma^2\mathbf{I}); \mathbf{u} \sim N(0, (\sigma^2/\lambda)\mathbf{W}^{-1})$
- ullet where the  ${f W}$  is the penalty matrix
- corresponds to minimizing  $||\mathbf{y} \mathbf{X}\boldsymbol{\beta} \mathbf{Z}\mathbf{u}||^2 + \lambda \mathbf{u}^{\mathsf{T}}\mathbf{W}\mathbf{u}$
- $\bullet$  "fixed effects are viewed as random effects with improper uniform priors and are integrated out" (Wood 2011)
- Laplace approximation

#### practical stuff

- Simon Wood is insanely smart, and mgcv is insanely powerful and flexible
- gratia package (named after Grace Wahba
- available 'smooths' (bases + penalty terms): look for strings of the form smooth.construct.\*.smooth.spe
- although you can theoretically have as many knots as data points, fewer is often good enough/computationally efficient

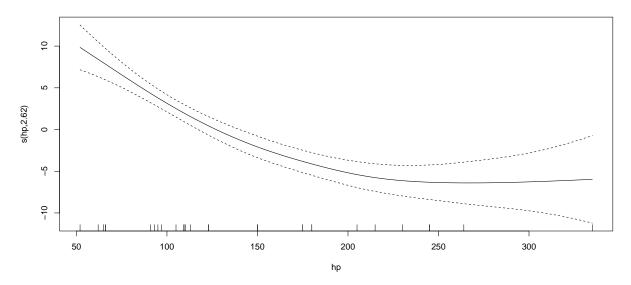
```
[1] "ad"
                      "cc"
                             "ср"
                                       "cr"
                                               "cs"
                                                        "ds"
 [9] "mrf"
             "ps"
                      "re"
                              "sf"
                                       "so"
                                               "sos"
                                                        "sw"
[17] "tensor" "tp"
                      "ts"
g1 <- gam(mpg ~ s(hp), data = mtcars)</pre>
summary(g1)
Family: gaussian
Link function: identity
Formula:
mpg ~ s(hp)
Parametric coefficients:
           Estimate Std. Error t value Pr(>|t|)
(Intercept) 20.0906 0.5487 36.62 <2e-16 ***
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
Approximate significance of smooth terms:
       edf Ref.df
                    F p-value
s(hp) 2.618 3.263 26.26 <2e-16 ***
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
R-sq.(adj) = 0.735 Deviance explained = 75.7%
GCV = 10.862 Scale est. = 9.6335 n = 32
```

Plot:

"gp"

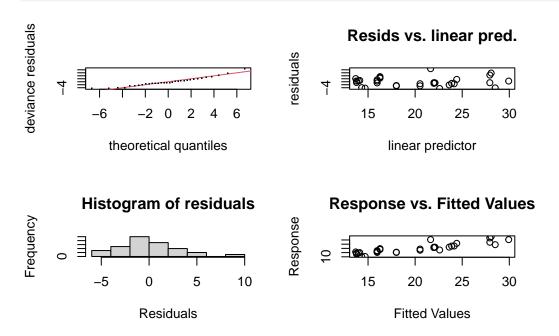
"t2"

## plot(g1)



Check:

## gam.check(g1)



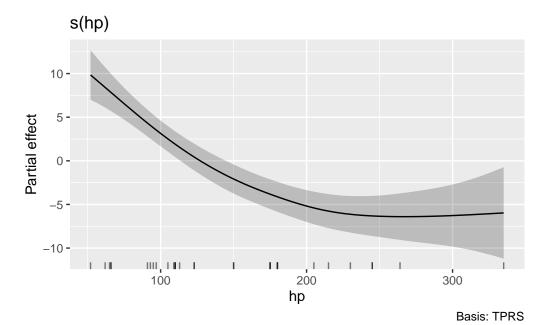
Method: GCV Optimizer: magic Smoothing parameter selection converged after 4 iterations.

The RMS GCV score gradient at convergence was 4.290111e-05 . The Hessian was positive definite. Model rank =  $10 \ / \ 10$ 

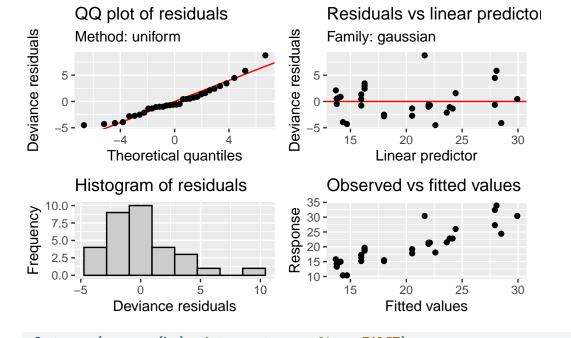
Basis dimension (k) checking results. Low p-value (k-index<1) may indicate that k is too low, especially if edf is close to k'.

k' edf k-index p-value s(hp) 9.00 2.62 0.87 0.15

## draw(g1)

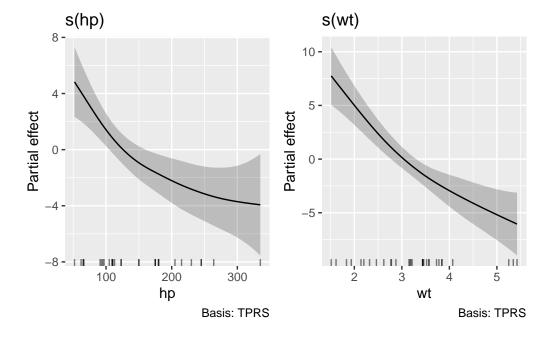


appraise(g1)



g2 <- gam(mpg ~ s(hp), data = mtcars, fit = FALSE)

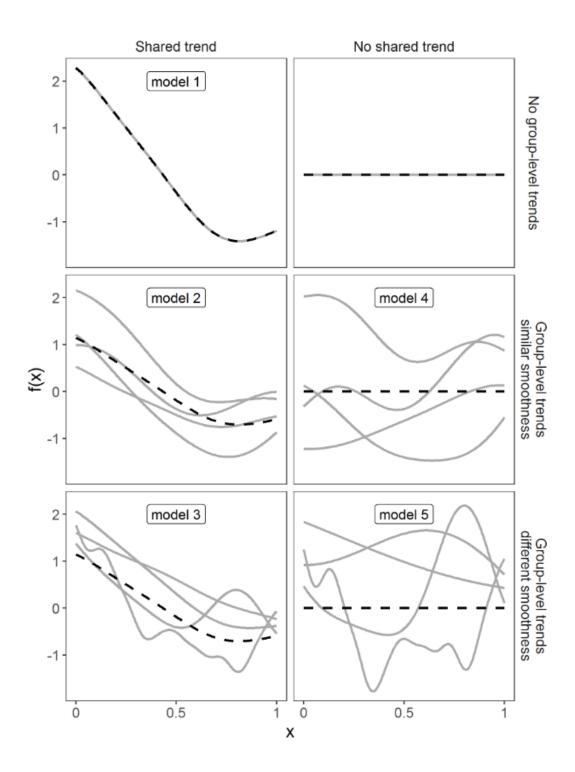
concurvity: CV question, Ramsay, Burnett, and Krewski (2003)



#### concurvity(g3)

```
para s(hp) s(wt)
worst 2.53539e-18 0.9575001 0.9575001
observed 2.53539e-18 0.6883189 0.6968782
estimate 2.53539e-18 0.4784240 0.7978191
```

Many options: simple random effects (bs = "re"); cyclic splines (make x(0) = x(T); bs="cc"); multidimensional splines (thin-plate, tensor product (te()); spherical (Duchon) splines (bs = "sos"); Markov random fields (bs = "mrf"); Gaussian processes (bs = "gp"); splines by category (by= argument); hierarchical splines (Pedersen et al. 2019); constrained splines (scam package, Pya and Wood (2015)); soap film splines; etc etc etc etc etc ...



#### Duality between Z and correlation structure

- Hefley et al. (2017)
- "first-order specification":  $\mathbf{y} \sim N(\mathbf{X}\beta + \mathbf{Z}\mathbf{b}, \sigma_{\epsilon}^2\mathbf{I})$
- "second-order specification:  $\mathbf{y} \sim N(\mathbf{X}\beta, \sigma_{\epsilon}^2 \mathbf{I} + \sigma_{\mathbf{b}}^2 \Sigma)$
- if **b** are iid Normal, integrating first-order specification shows that  $\Sigma = \mathbf{Z}\mathbf{Z}^{\top}$
- e.g. latent-variable specification of an AR1 correlation structure
- e.g. phyloglmm

#### Penalty matrices as

• Simon N. Wood (2004)

#### Computational tricks

- work with precision matrix where possible  $\Sigma^{-1}$
- for a multivariate normal response,  $\Sigma_{ij}^{-1} = \Sigma_{ji}^{-1} = 0 \leftrightarrow x_i$  and  $x_j$  are conditionally independent
- e.g. precision matrix of AR1 is tridiagonal with diagonal  $1+\rho^2$ , first off-diagonal elements  $-\rho$  (see here)
- work with reduced-rank forms where necessary

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