Video classification with keras

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Video classification = N images classification (N = \# of frames)
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Subsequent frames are correlated with *semantic contents*.

> Temporal dimension > video classification results improval

(i.e., LSTM, RNN ···)

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Rolling prediction averaging!

Image classification (CNN) > Video classification (Rolling averaging)

Image classification

- 1. Input: Image
- 2. Prediction
- 3. The largest corresponding probability >> The label

Video classification

- 1. Input: Frame
- 2. Loop over all frames
- 3. Prediction individually and independently
- 4. The largest corresponding probability >> The label

"Prediction flickering"

Image classification

- 1. Input: Image
- 2. Prediction
- 3. The largest corresponding probability >> The label

Video classification

- 1. Input: Frame
- 2. Loop over all frames
- 3. Prediction individually and independently
- 4. A list of the last *K* predictions
- 5. The average of the last *K* predictions
- 6. The largest corresponding probability >> The label

"Smooting out"

The sports classification dataset



















1.Swimming	12.Gymnasium
2.Badminton	13.Weight lifting
3.Wrestling	14.Volleyball
4.Olympic Shooting	15.Table tennis
5.Cricket	16.Baseball
6.Football	17.Formula 1
7.Tennis	18.Moto GP

8.Hockey

9.Ice Hockey

10.Kabaddi

11.WWE

19.Chess

20.Boxing

21.Fencing

22.Basketba

The sports classification dataset



















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- 1. Take a network pre-trained on a dataset.
- 2. Utilize the network to recognize image/object categories it was not trained on.

Advantages?

- Train a network with a new dataset > Cost + time loss, Not working
- Hundred of parameters

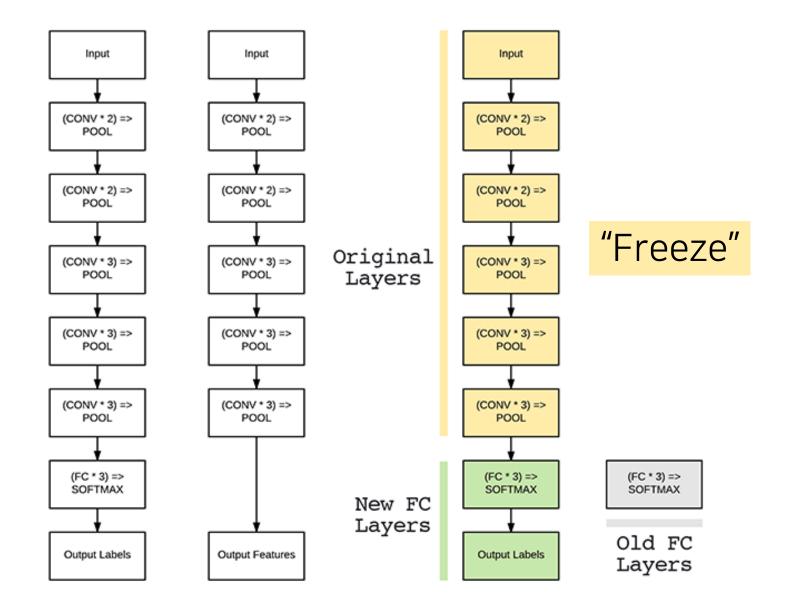
Two steps of transfer learning

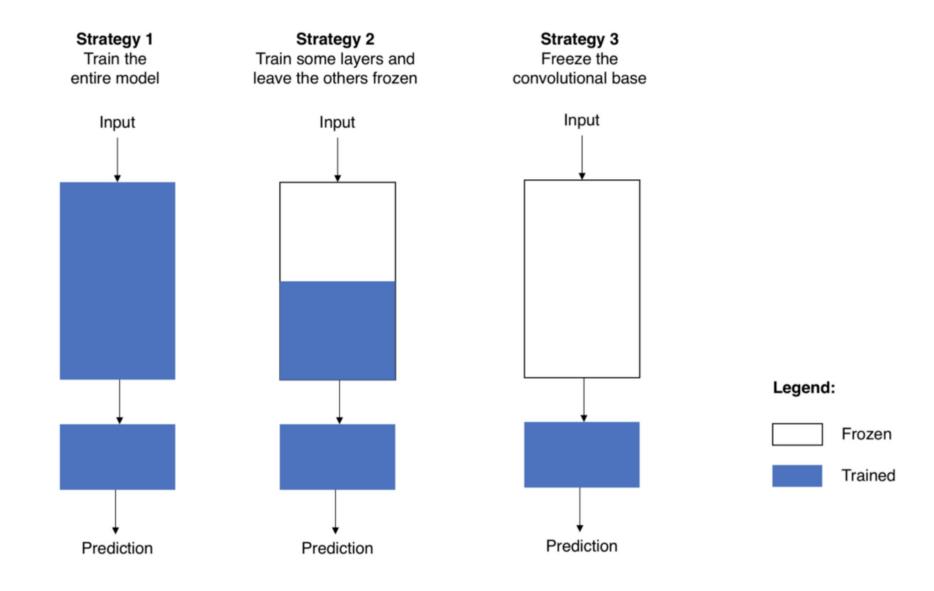
- 1. Via feature extraction
 - Pre-trained network = Feature extractor
- 2. Via fine-tuning

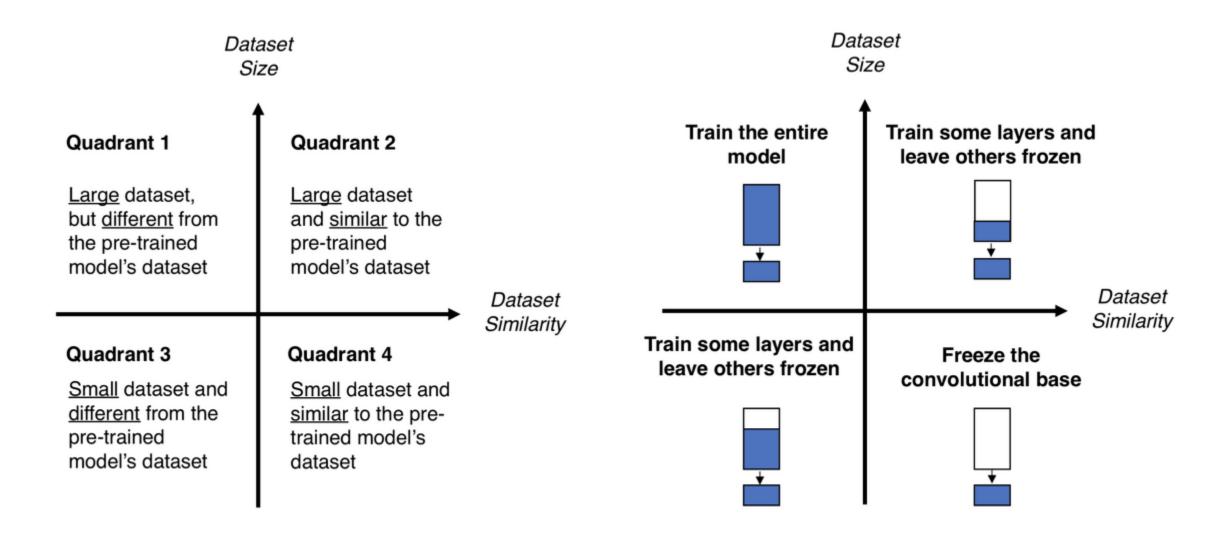
Q. 무조건 좋을까?

Feature extraction이 어떻게 되는 것에 따라 다르다. 데이터의 분포(특성)이 다를 경우

VGG16

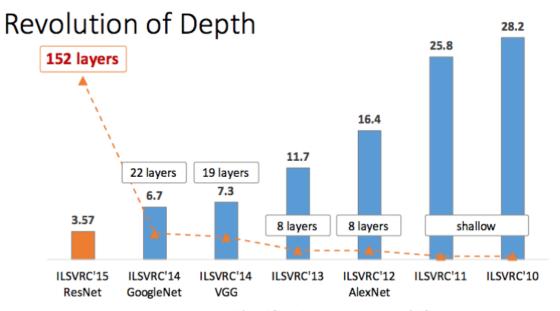


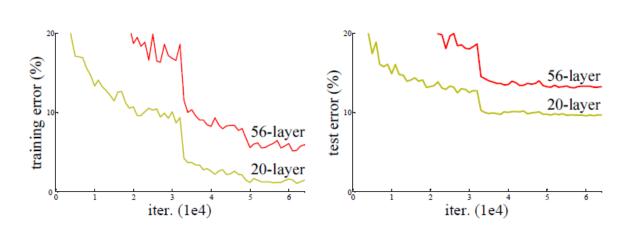




ResNet-50

- 2015 ImageNet Large Scale Visual Recognition Challenge(ILSVRC) winner.
- Developed by Microsoft
- "Deep Residual Learning for Image Recognition" (Kaiming He et al.,)
- Gradient vanishing >> Residual block (skip connection)

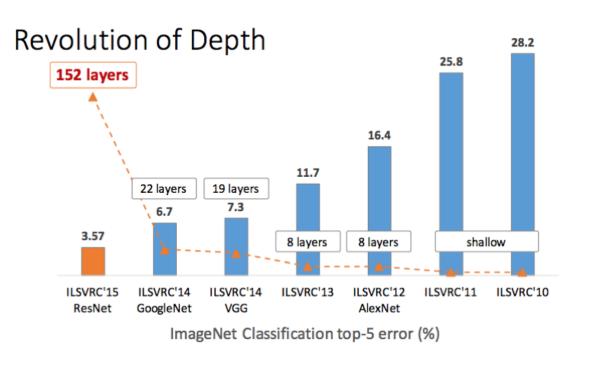


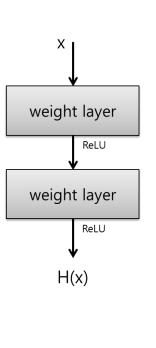


ImageNet Classification top-5 error (%)

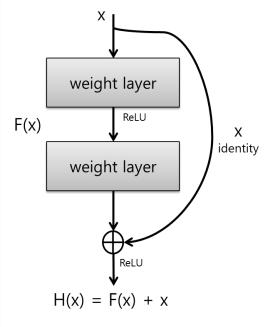
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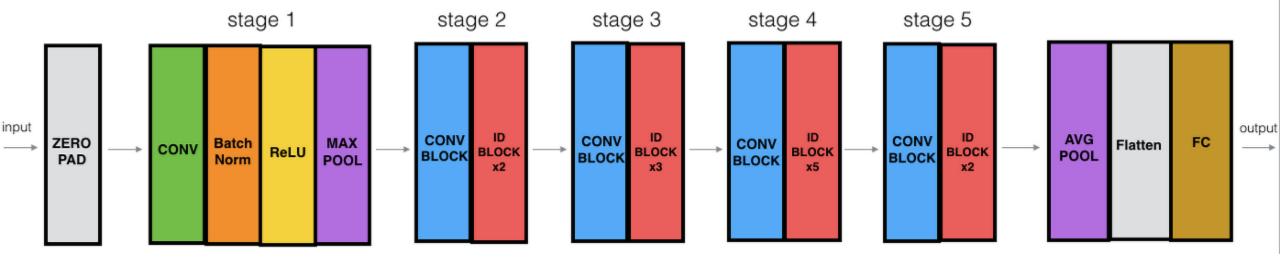






Residual block

ResNet-50



layer name	output size	18-layer	34-layer	50-layer	101-layer	152-layer	
conv1	112×112	/×1, 64, stride 2					
		3×3 max pool, stride 2					
conv2_x	56×56	$\left[\begin{array}{c} 3\times3,64\\ 3\times3,64 \end{array}\right]\times2$	$\left[\begin{array}{c} 3\times3,64\\ 3\times3,64 \end{array}\right]\times3$	$\begin{bmatrix} 1 \times 1, 64 \\ 3 \times 3, 64 \\ 1 \times 1, 256 \end{bmatrix} \times 3$	$\begin{bmatrix} 1 \times 1, 64 \\ 3 \times 3, 64 \\ 1 \times 1, 256 \end{bmatrix} \times 3$	$\begin{bmatrix} 1 \times 1, 64 \\ 3 \times 3, 64 \\ 1 \times 1, 256 \end{bmatrix} \times 3$	
conv3_x	28×28	$\left[\begin{array}{c} 3\times3,128\\ 3\times3,128 \end{array}\right]\times2$	$\left[\begin{array}{c} 3\times3,128\\ 3\times3,128 \end{array}\right]\times4$	$\begin{bmatrix} 1 \times 1, 128 \\ 3 \times 3, 128 \\ 1 \times 1, 512 \end{bmatrix} \times 4$	$\begin{bmatrix} 1 \times 1, 128 \\ 3 \times 3, 128 \\ 1 \times 1, 512 \end{bmatrix} \times 4$	\[\begin{pmatrix} 1 \times 1, 128 \\ 3 \times 3, 128 \\ 1 \times 1, 512 \end{pmatrix} \times 8	
conv4_x	14×14	$\left[\begin{array}{c} 3\times3,256\\ 3\times3,256 \end{array}\right]\times2$	$\left[\begin{array}{c} 3 \times 3, 256 \\ 3 \times 3, 256 \end{array}\right] \times 6$	$\begin{bmatrix} 1 \times 1, 256 \\ 3 \times 3, 256 \\ 1 \times 1, 1024 \end{bmatrix} \times 6$	\[\begin{array}{c} 1 \times 1, 256 \\ 3 \times 3, 256 \\ 1 \times 1, 1024 \end{array} \] \times 23	\[\begin{array}{c} 1 \times 1, 256 \\ 3 \times 3, 256 \\ 1 \times 1, 1024 \end{array} \] \times 36	
conv5_x	7×7	$\left[\begin{array}{c} 3\times3,512\\ 3\times3,512 \end{array}\right]\times2$	$\left[\begin{array}{c}3\times3,512\\3\times3,512\end{array}\right]\times3$	$\begin{bmatrix} 1 \times 1, 512 \\ 3 \times 3, 512 \\ 1 \times 1, 2048 \end{bmatrix} \times 3$	$\begin{bmatrix} 1 \times 1, 512 \\ 3 \times 3, 512 \\ 1 \times 1, 2048 \end{bmatrix} \times 3$	$\begin{bmatrix} 1 \times 1, 512 \\ 3 \times 3, 512 \\ 1 \times 1, 2048 \end{bmatrix} \times 3$	
	1×1	average pool, 1000-d fc, softmax					
FL(OPs	1.8×10 ⁹	3.6×10^{9}	3.8×10^{9}	7.6×10^9	11.3×10 ⁹	