

# Computational Astrophysic

## Homework 4

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### Theorem

In this problem, we conduct a convolution operation on the given input picture using a Gaussian filter of size  $N \times N$  (same as the input picture size) to generate the output image:

$$O_{i,j} = \sum_k \sum_l I_{k,l} F_{[i-k],[j-l]},$$

where  $N = 1024$ ,  $O_{i,j}$  is the pixel of row  $i$  column  $j$ ,  $I_{kl}$  is the pixel of the input picture of row  $k$  column  $l$ , and  $F_{[i-k],[j-l]}$  is the pixel of the Gaussian filter at row  $(i - k) \bmod(N)$  and column  $(j - l) \bmod(N)$ . The component  $F_{[i-k],[j-l]}$  is constructed according to:

$$F_{[i-k],[j-l]} = A e^{-\frac{[i-k]^2}{2\sigma^2}} e^{-\frac{[j-l]^2}{2\sigma^2}} = \frac{e^{-\frac{[i-k]^2}{2\sigma^2}} e^{-\frac{[j-l]^2}{2\sigma^2}}}{\sum_{[i-k]} \sum_{[j-l]} e^{-\frac{[i-k]^2}{2\sigma^2}} e^{-\frac{[j-l]^2}{2\sigma^2}}},$$

$A$  is the normalization constant.

Instead of using direct integration, the matrix  $O_{i,j}$  can be calculated efficient by discrete Fourier transform, as proven below:

$$\begin{aligned} O_{k_\alpha, k_\beta} &= \sum_i \sum_j O_{i,j} e^{ik_\alpha i} e^{ik_\beta j} = \sum_k \sum_l I_{k,l} e^{ik_\alpha k} e^{ik_\beta l} \sum_i \sum_j F_{[i-k],[j-l]} e^{ik_\alpha [i-k]} e^{ik_\beta [j-l]} = I_{k_\alpha, k_\beta} F_{k_\alpha, k_\beta} \\ &\Rightarrow O_{i,j} = \frac{1}{N^2} \sum_{k_\alpha} \sum_{k_\beta} I_{k_\alpha, k_\beta} F_{k_\alpha, k_\beta} e^{-ik_\alpha i} e^{-ik_\beta j}. \end{aligned} \quad (1)$$

Thus, by calculating the 2D discrete Fourier transform of both input picture as well as the Gaussian filter, the output image can be easily produced by conducting inverse Fourier transform on the multiply of them.

### Output Images and Power Spectrums

The output images were generated following Eq. (1) using the FFT package of numpy; the power spectrums are obtained by taking the square of amplitude of the output image Fourier components, and plotted in log scale, i.e.  $\log(|O_{k_\alpha, k_\beta}|^2) = 2\log(|O_{k_\alpha, k_\beta}|)$ .

Since the Gaussian filter is nothing but producing a image with pixel  $O_{i,j}$  by averaging over the input picture (set  $I_{i,j}$  as center) with a normal distribution weight function, so effect is quite similar to averaging a region of size  $(\sigma, \sigma)$  with uniform distribution, where  $\sigma$  is the variance of the normal distribution, one expects that the output image should be delicate with more details preserved when  $\sigma$  is small, while become more rough but the large scale trend will be extracted if  $\sigma$  is large. Accordingly, when  $\sigma$  is small, the power spectrum will contain stronger short wave length (high  $k$ ) modes which is essential for constructing the local structures; for large  $\sigma$ , only the long wave length (low  $k$ ) modes survive since all the detail structures have been smeared out.

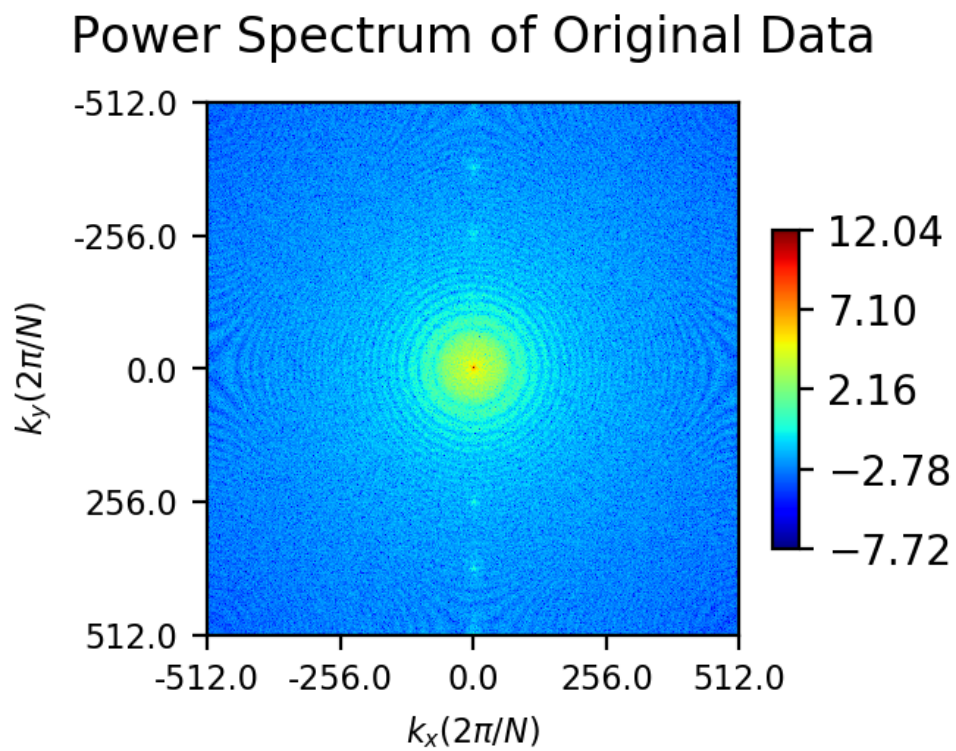
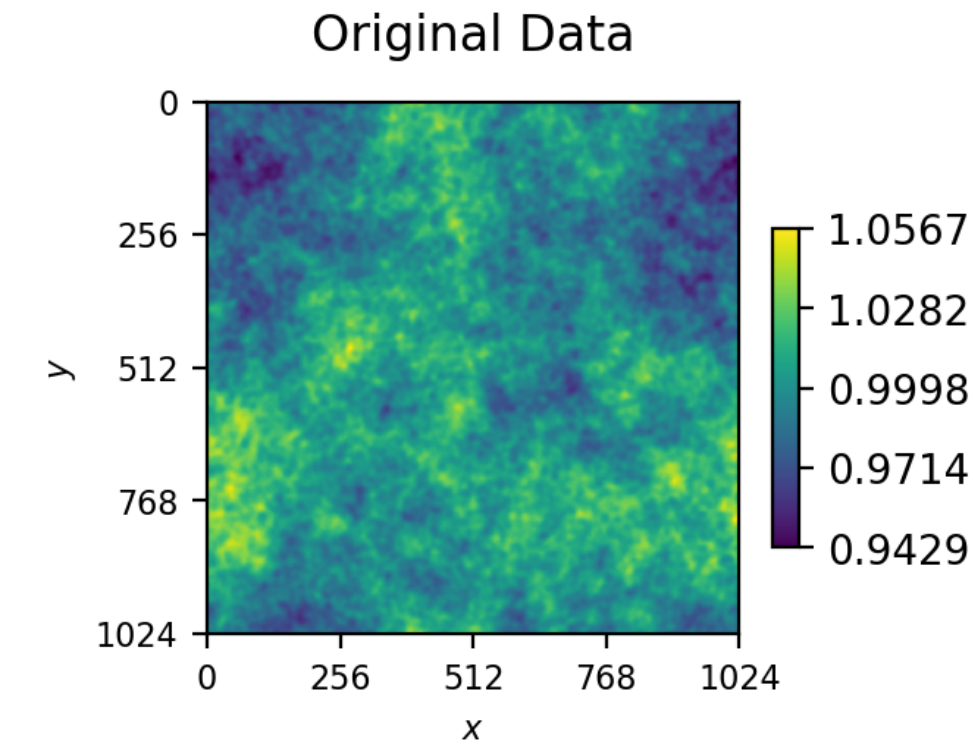
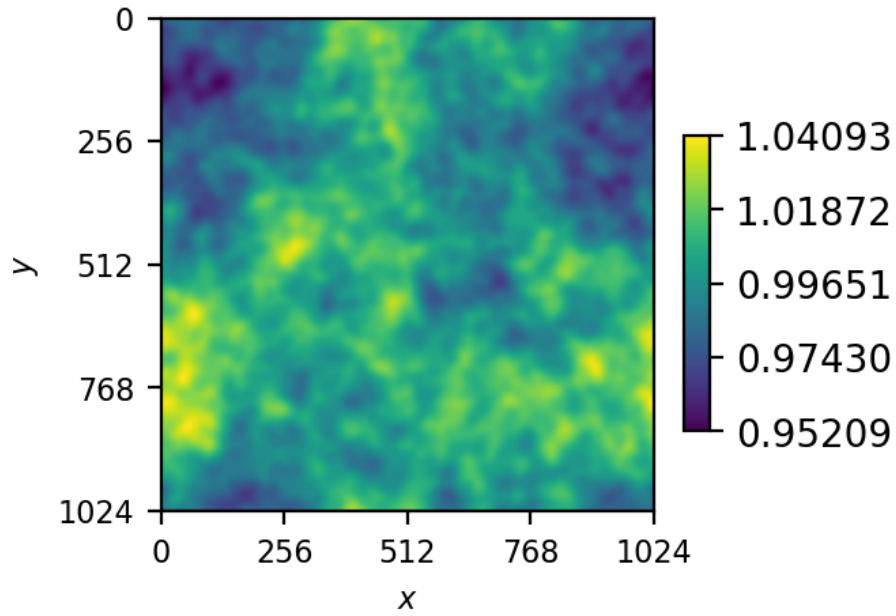


Figure 1: Density Distribution and Power Spectrum for Original Data

### Gaussian Filter with $\sigma=10$ Applied



### Power Spectrum of Gaussian Filter with $\sigma=10$ (log Scale)

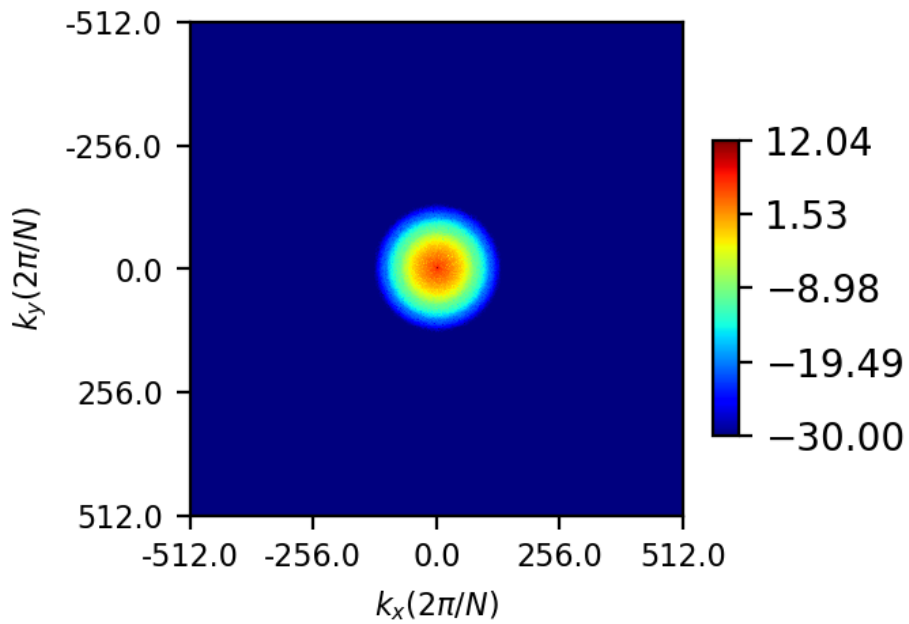
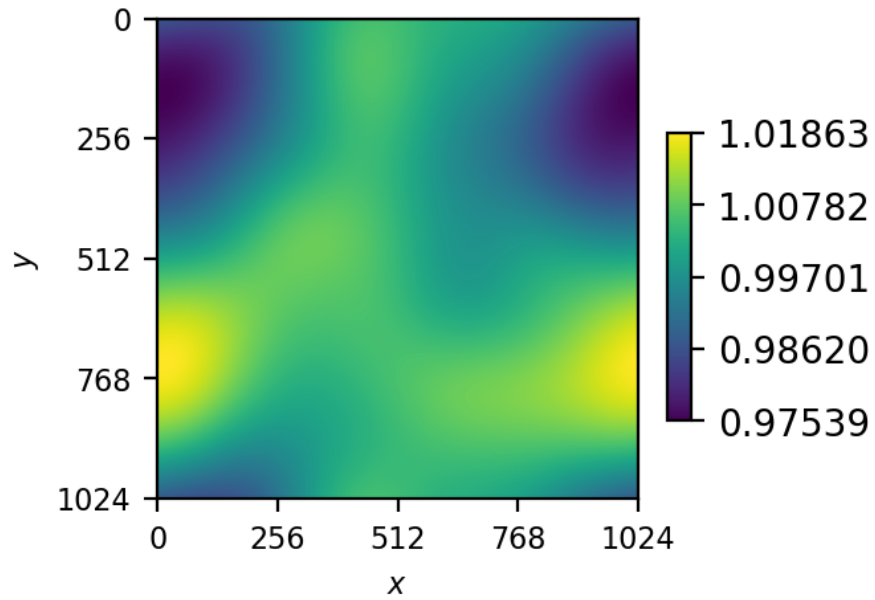


Figure 2: Density Distribution and Spectrum Density for  $\sigma = 10$  Gaussian Filter

### Gaussian Filter with $\sigma=100$ Applied



### Power Spectrum of Gaussian Filter with $\sigma=100$ (log Scale)

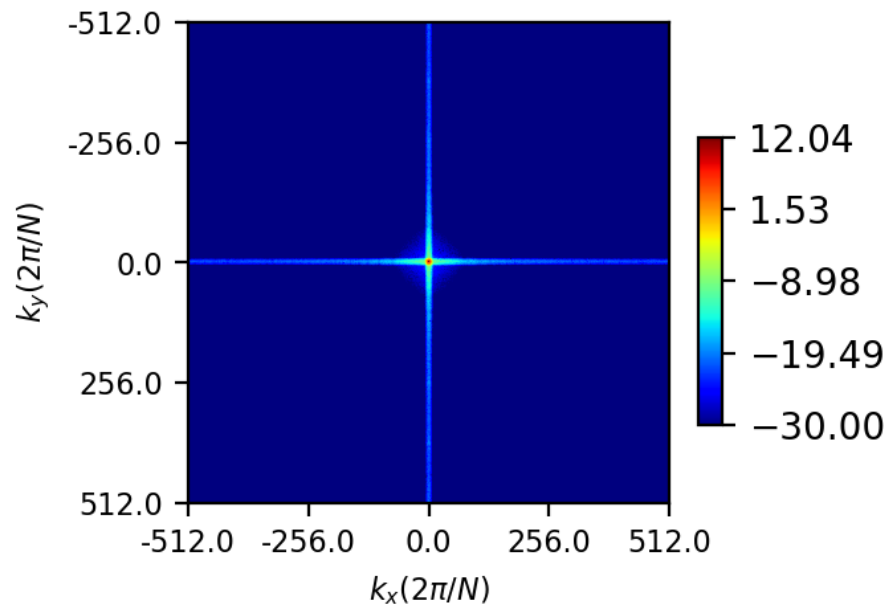


Figure 3: Density Distribution and Spectrum Density for  $\sigma = 100$  Gaussian Filter

## Discussion

The result clearly shows that our expectation is correct: the output image becomes more and more blurring from original data to be filtered by  $\sigma = 10$  and then by  $\sigma = 100$ . Since we average over a wider region when  $\sigma$  is large, if a histogram of each pixel value is plotted, one should expect that bars of histogram become more centralized, due to lost of details and averging with lots of other pixels, which is confirmed by in Fig. 4.

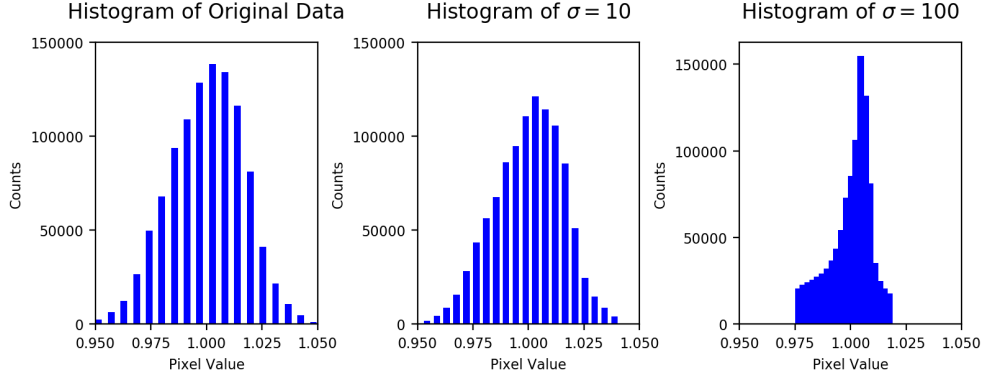


Figure 4: Histogram of Pixel Value for Original Data and Filtered Output

As for the power spectrum, we truncated modes whose square of norm is below  $10^{-30}$  and filled them with  $10^{-30}$ . It can be observed that for the original data, though the dominant components are centered around  $(0,0)$  of  $k_x - k_y$  plane, there are considerable modes extending to high  $k$  region with certain patterns (nearly four-fold symmetry), and no mode is truncated, i.e., various modes contribute to the input image. For  $\sigma = 10$  filter, we see most of the modes are truncated except a circle around the origin with radius  $\approx 128 \frac{2\pi}{N}$ , suggesting only short  $k$  modes are preserved. For  $\sigma = 100$ , the surviving modes are centered in a very narrow circle, and the original cylindrical pattern in the  $\sigma = 10$  case is broken into four-fold symmetry, with a cross situated at the center. I guess this cross comes from some  $x$  symmetry and  $y$  symmetry regions in the output image (shown in Fig. 5). To quantify how the surviving modes change with the  $\sigma$ , the variance of  $k_x$  and  $k_y$  is calculated by:

$$\begin{cases} \text{var}(k_x) = \sqrt{A \sum_{k_\alpha} \sum_{k_\beta} O_{k_\alpha, k_\beta} k_\alpha^2 - (A \sum_{k_\alpha} \sum_{k_\beta} O_{k_\alpha, k_\beta} k_\alpha)^2} \\ \text{var}(k_y) = \sqrt{A \sum_{k_\alpha} \sum_{k_\beta} O_{k_\alpha, k_\beta} k_\beta^2 - (A \sum_{k_\alpha} \sum_{k_\beta} O_{k_\alpha, k_\beta} k_\beta)^2} \end{cases},$$

where  $A = \sum_{k_\alpha} \sum_{k_\beta} O_{k_\alpha, k_\beta}$ . As shown in table 1 and Fig. 6, the variance decreases with increasing  $\sigma$ .

$\sigma$	$\text{var}(k_x)$	$\text{var}(k_y)$
Original	58.20387650	58.87456062
10	4.86205933	4.85042083
100	0.22526556	0.22104553

Table 1: Result of Gauss-Seidel Scheme

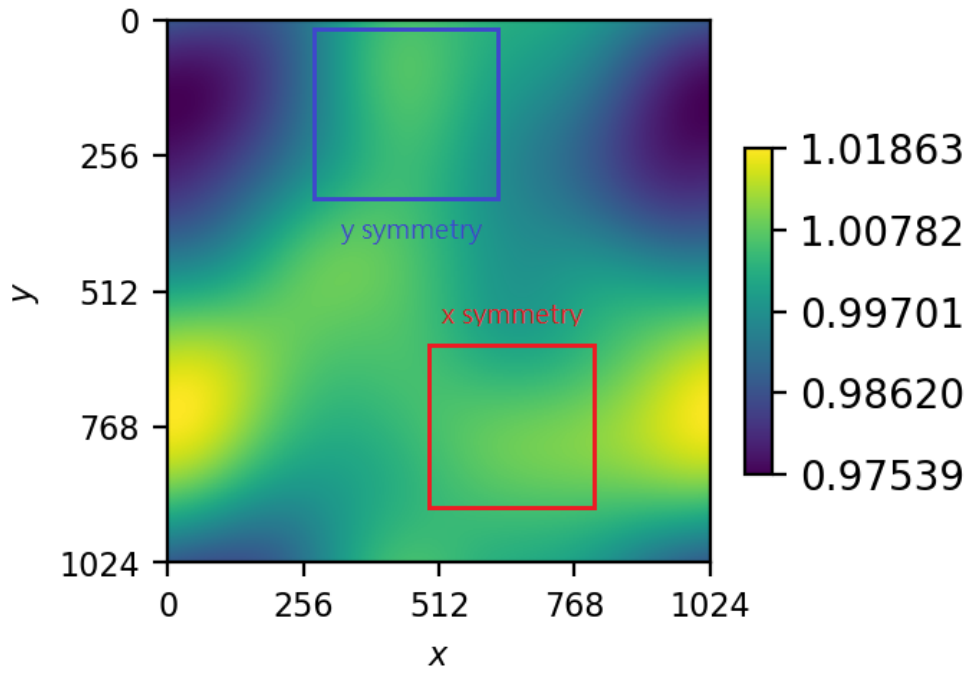


Figure 5: Regions Might Possess  $x$  or  $y$  Symmetry

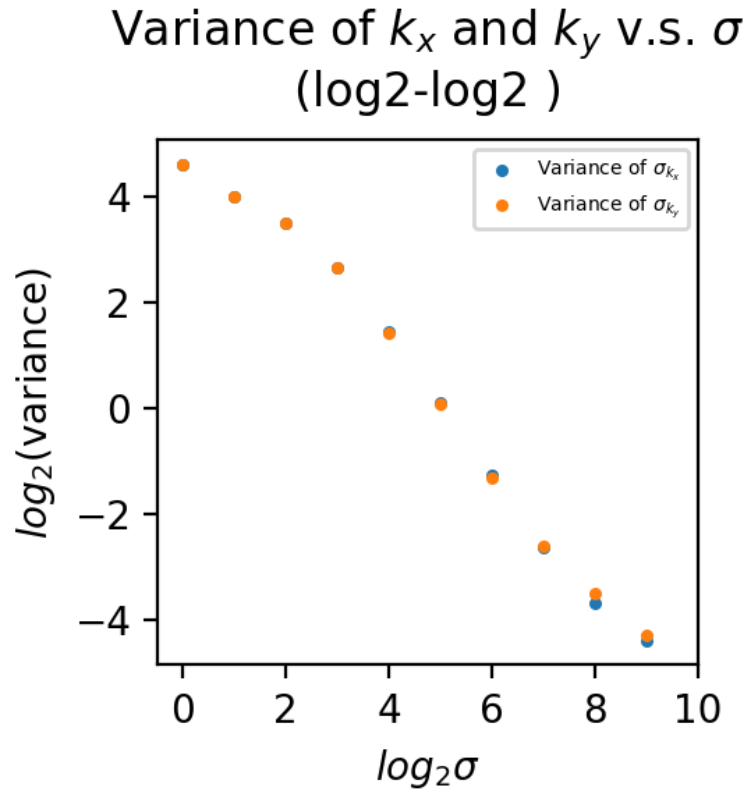


Figure 6: log2-log2 variance v.s.  $\sigma$