

Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

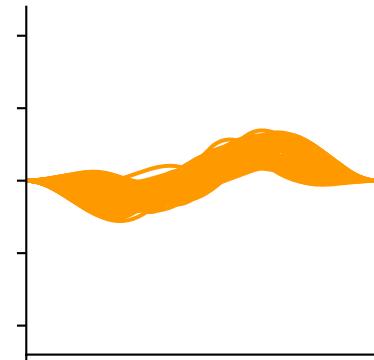
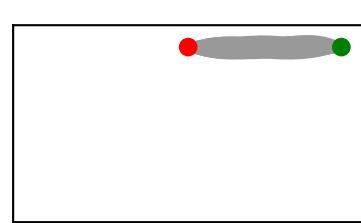
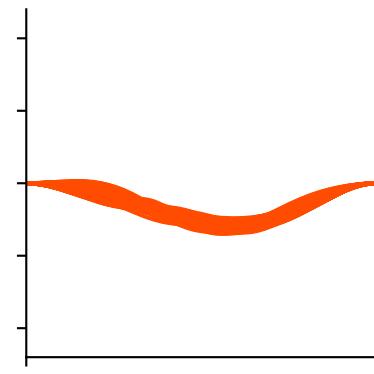
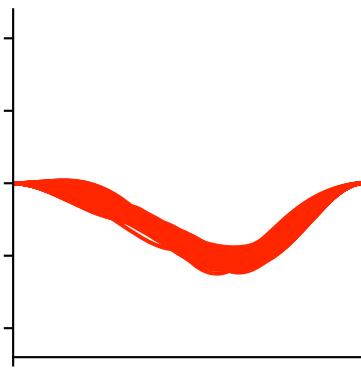
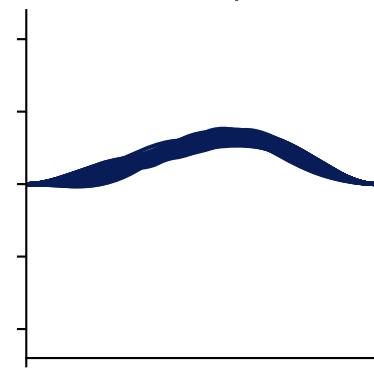
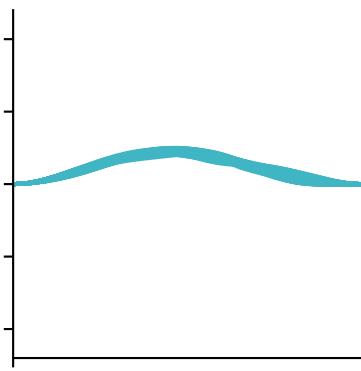
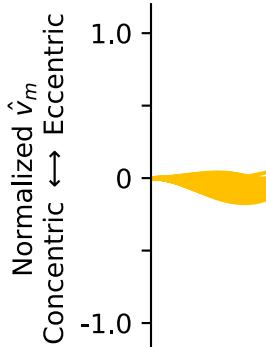
BIC

BRD

ECRB

TRI

DELTp



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

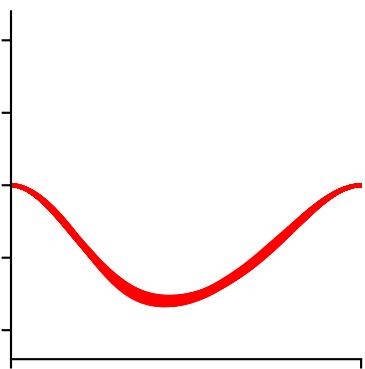
Normalized \hat{v}_m
Concentric \rightarrow Eccentric

Start

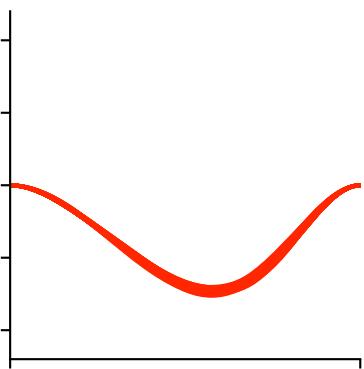
Finish

Fixed Final Position
Movement Duration : 1 sec

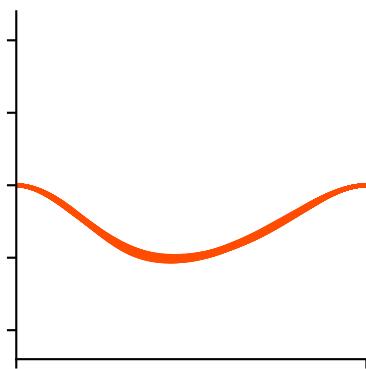
PC



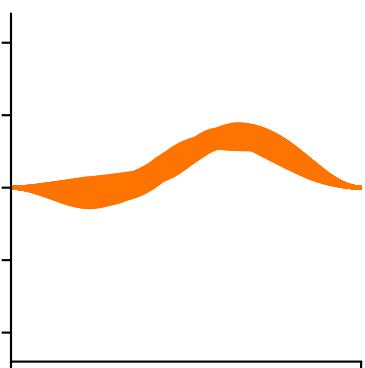
DELTa



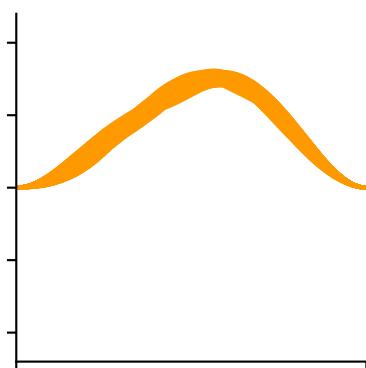
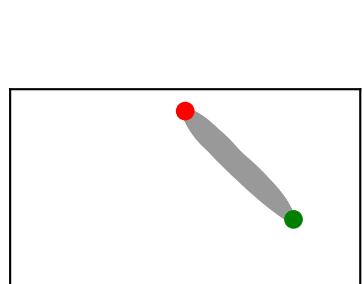
CB



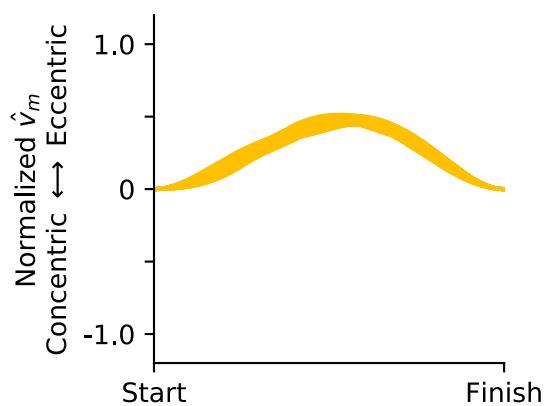
BIC



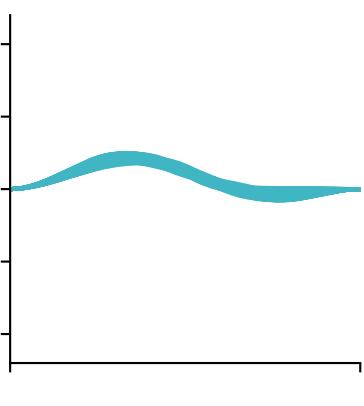
BRD



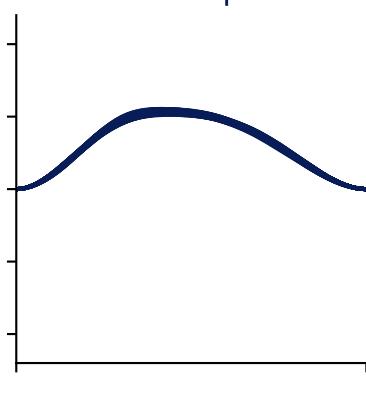
ECRB



TRI

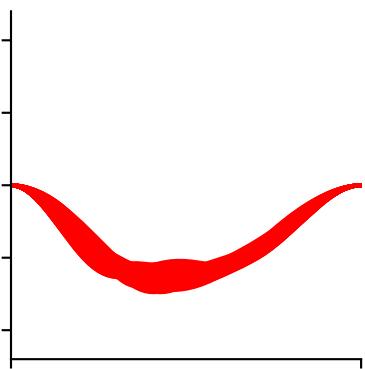


DELTp

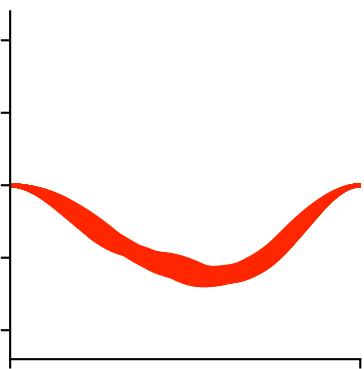


Fixed Final Position
Movement Duration : 1 sec

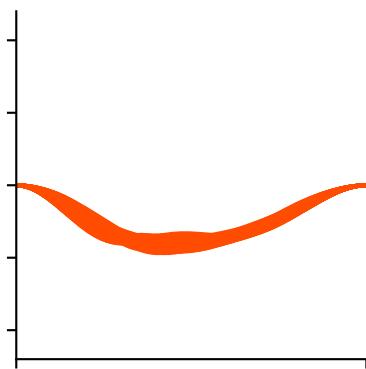
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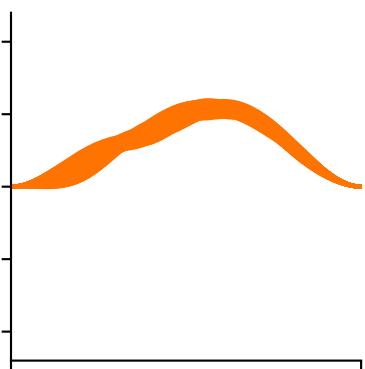
DELTa



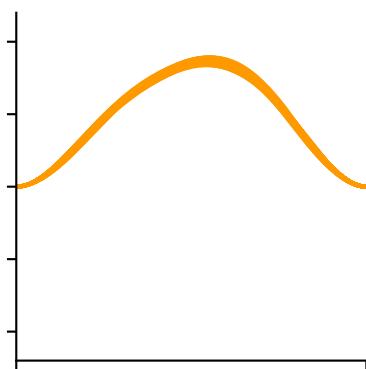
CB



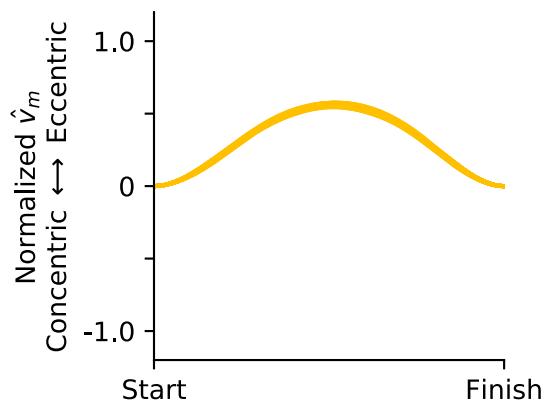
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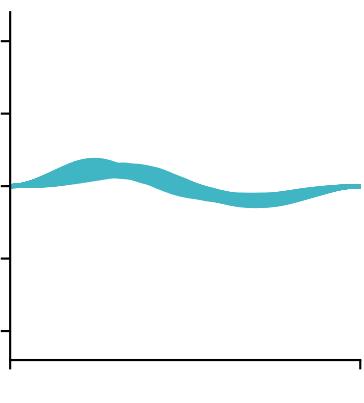
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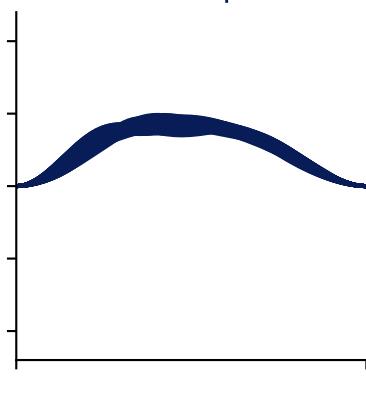
ECRB



TRI



DELTp



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

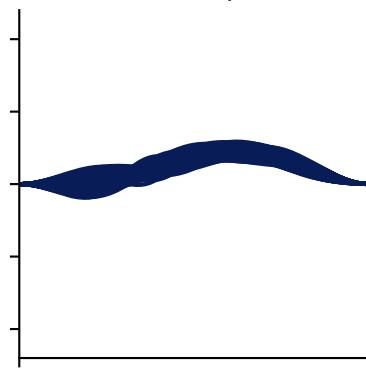
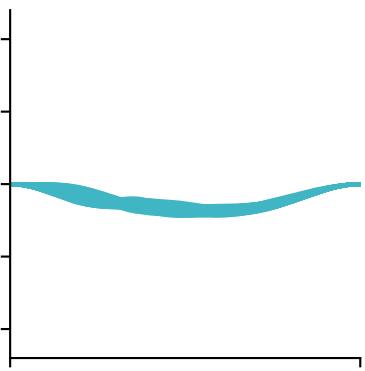
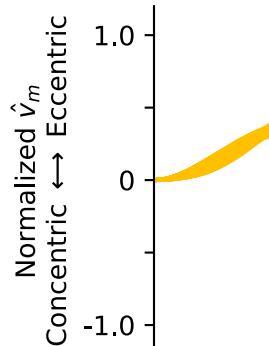
BIC

BRD

ECRB

TRI

DELTp



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

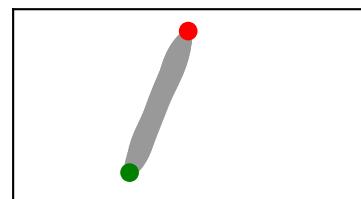
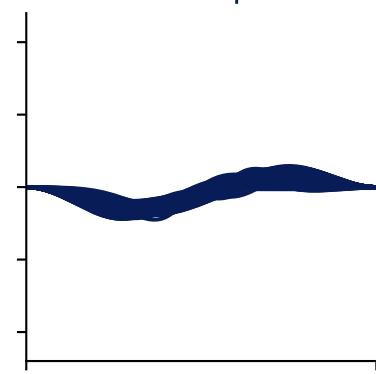
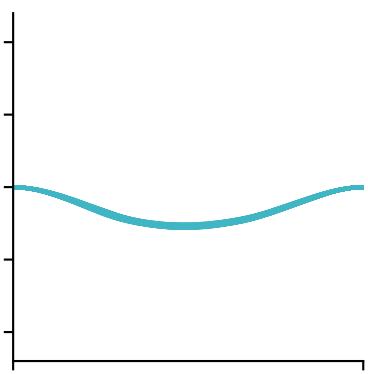
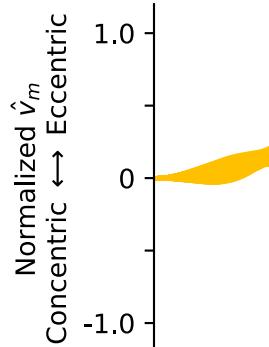
BIC

BRD

ECRB

TRI

DELTp



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

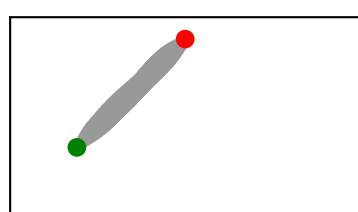
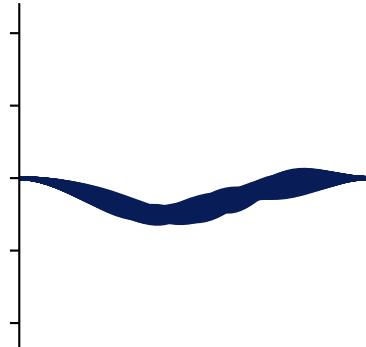
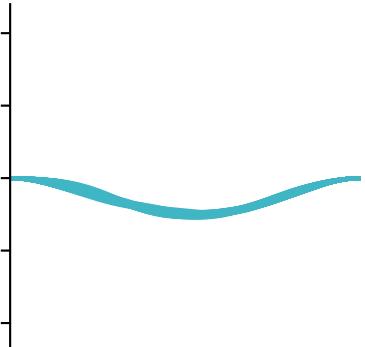
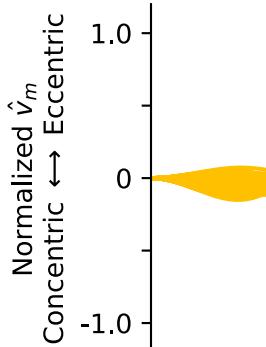
BIC

BRD

ECRB

TRI

DELTp



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

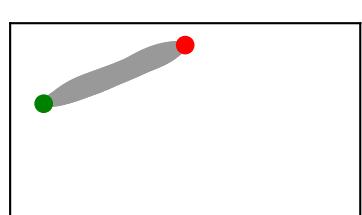
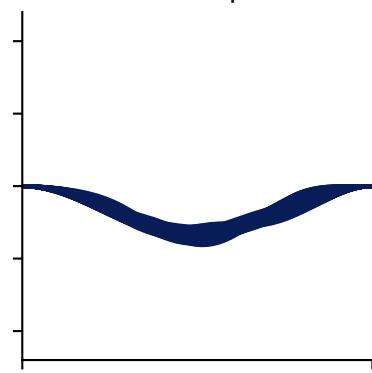
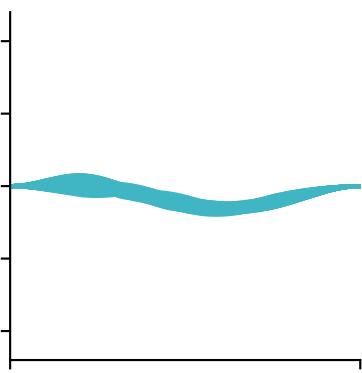
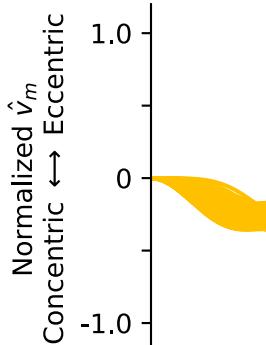
BIC

BRD

ECRB

TRI

DELTp



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

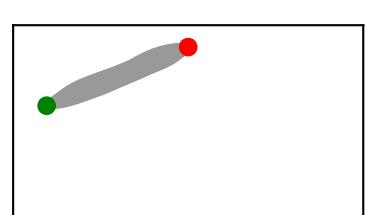
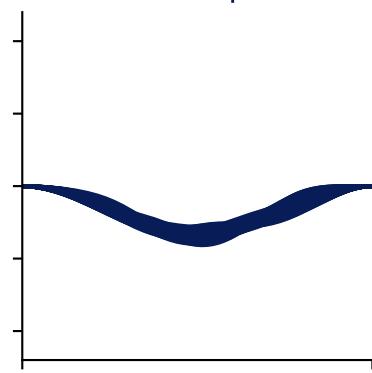
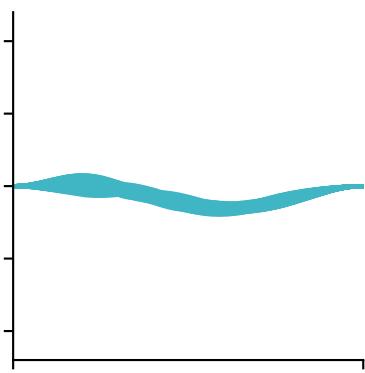
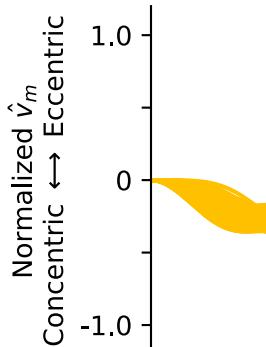
BIC

BRD

ECRB

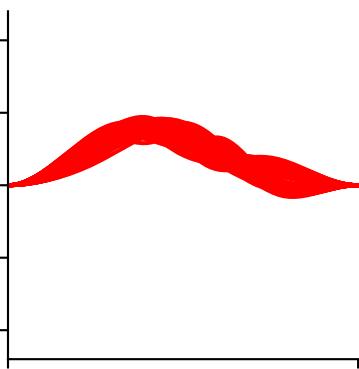
TRI

DELTp

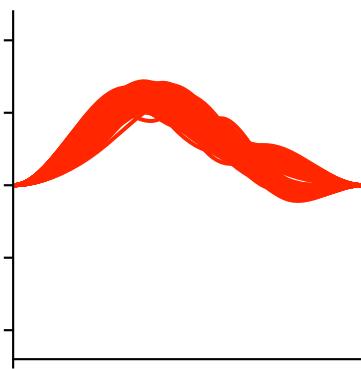


Fixed Final Position
Movement Duration : 1 sec

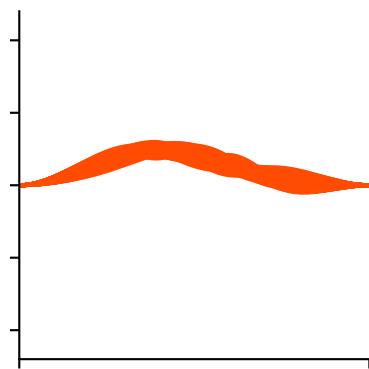
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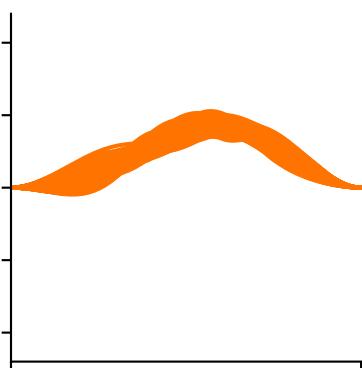
DELTa



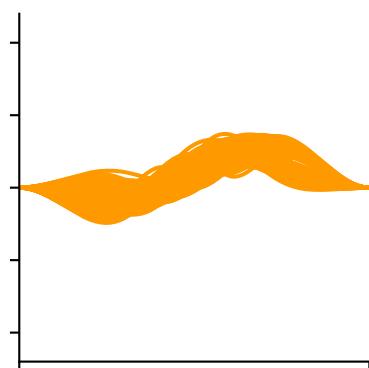
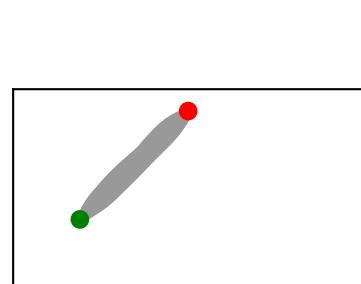
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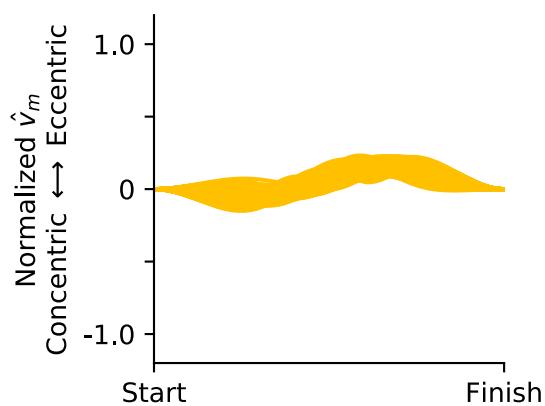
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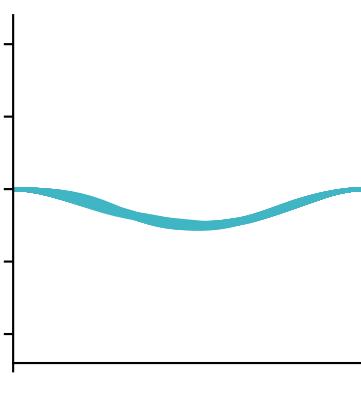
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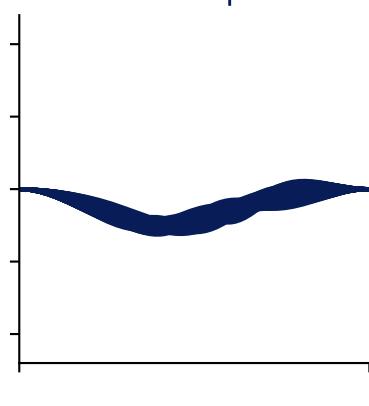
ECRB



TRI



DELTp



Normalized \hat{v}_m
Concentric \rightarrow Eccentric

1.0
0
-1.0

Start

Finish

Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

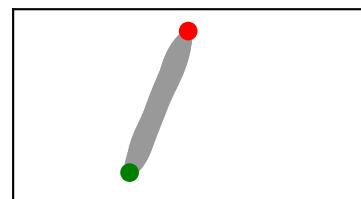
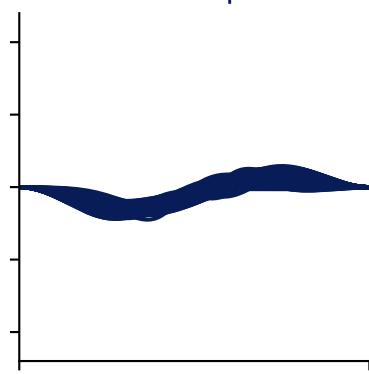
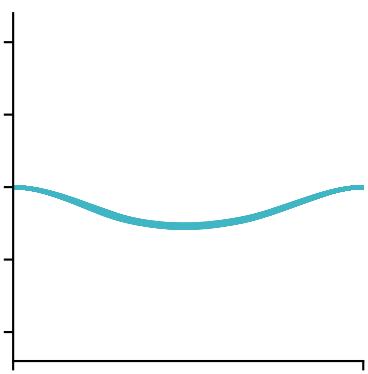
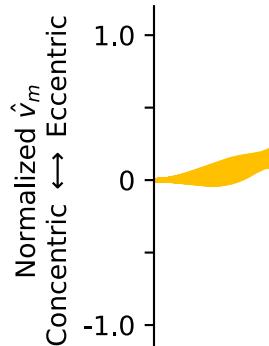
BIC

BRD

ECRB

TRI

DELTp



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

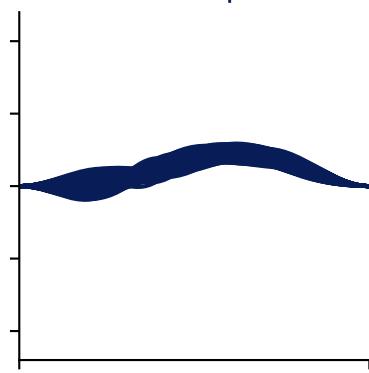
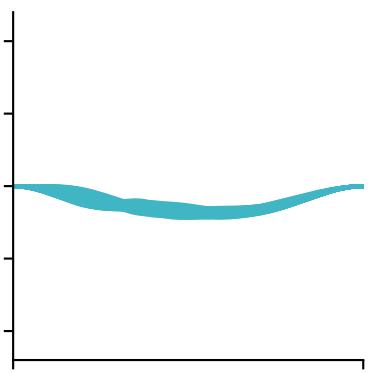
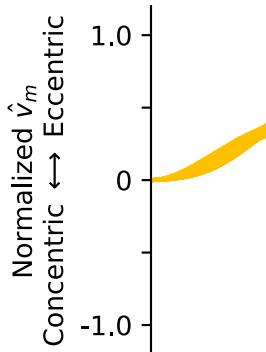
BIC

BRD

ECRB

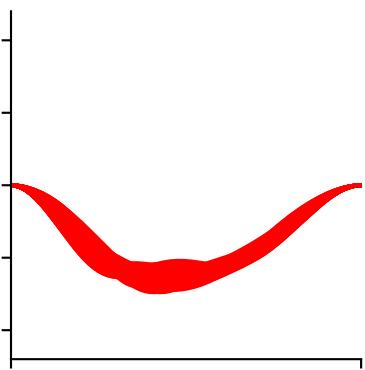
TRI

DELTp

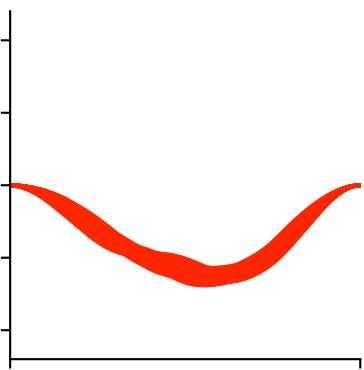


Fixed Final Position
Movement Duration : 1 sec

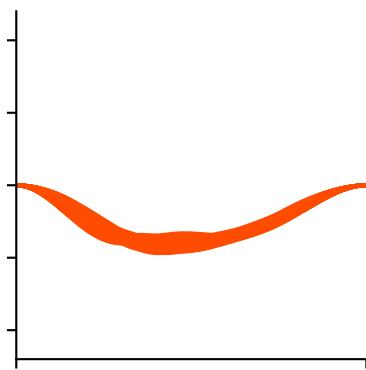
PC



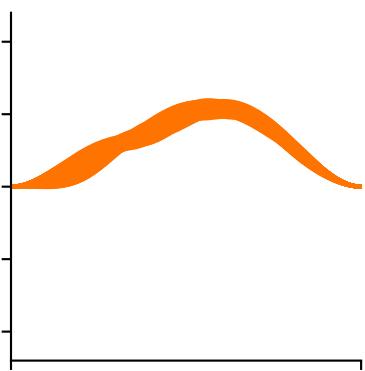
DELTa



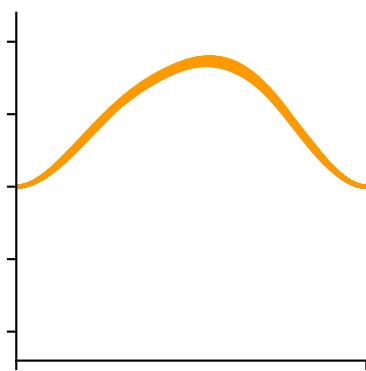
CB



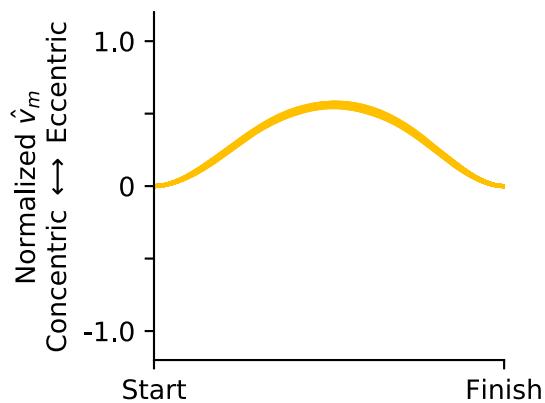
BIC



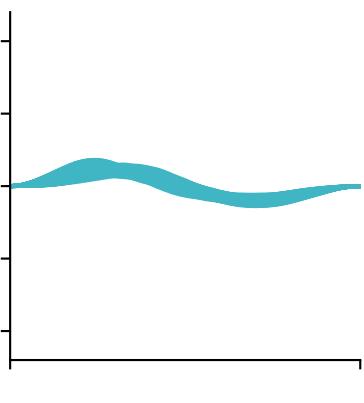
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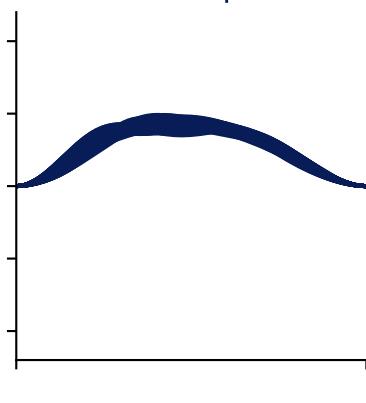
ECRB



TRI



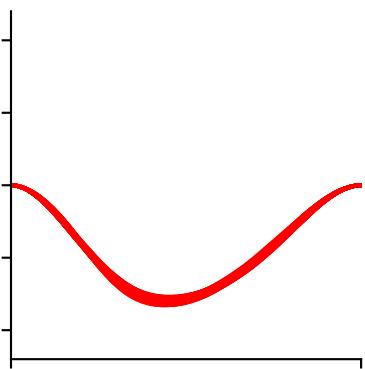
DELTp



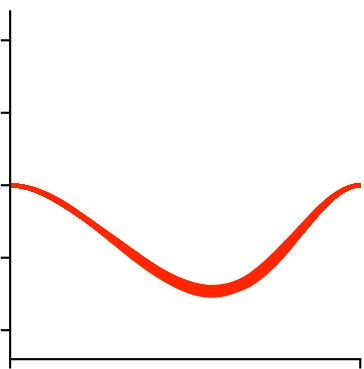
Normalized \hat{v}_m
Concentric \rightarrow Eccentric

Fixed Final Position
Movement Duration : 1 sec

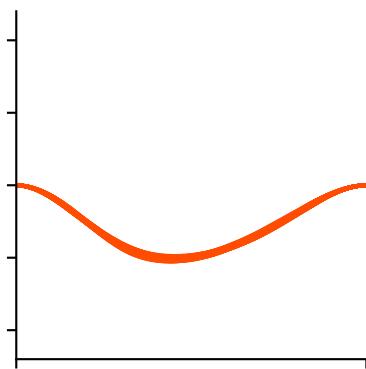
PC



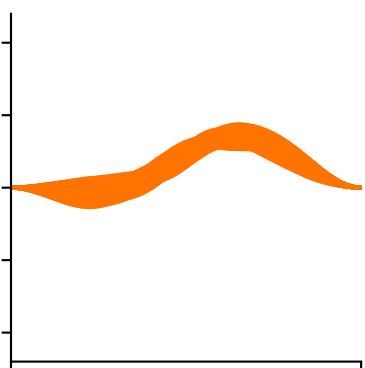
DELTa



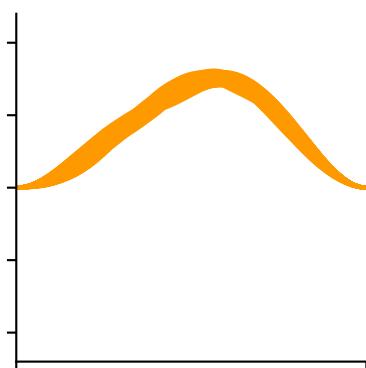
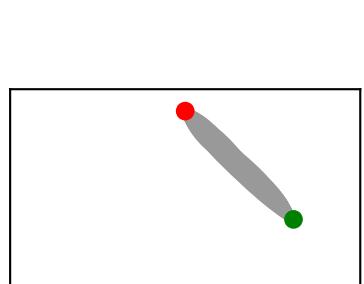
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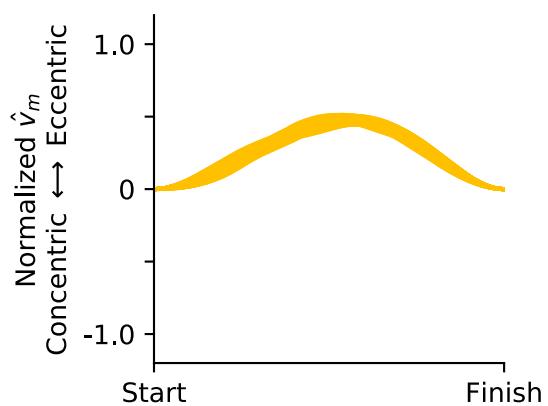
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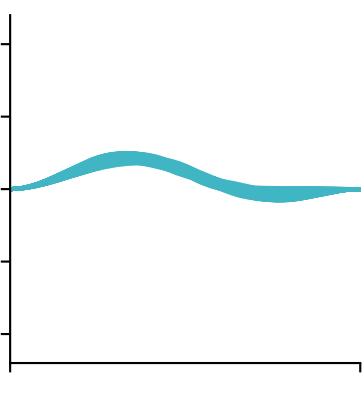
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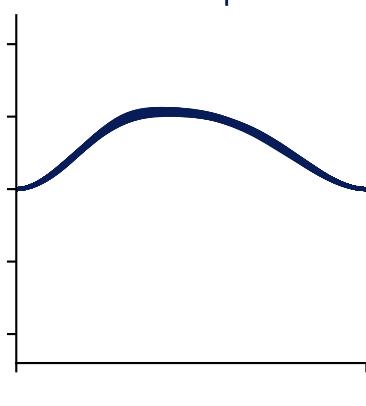
ECRB



TRI



DELTp



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Concentric \rightarrow Eccentric

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Movement Duration : 1 sec

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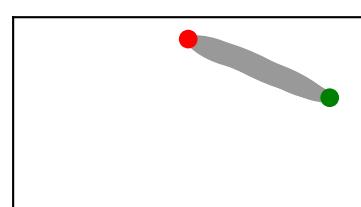
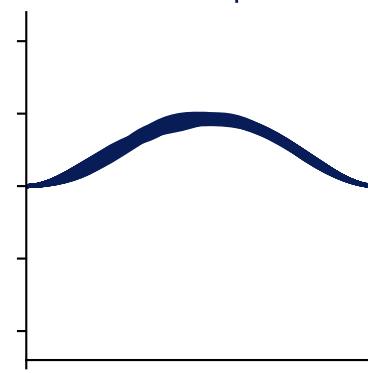
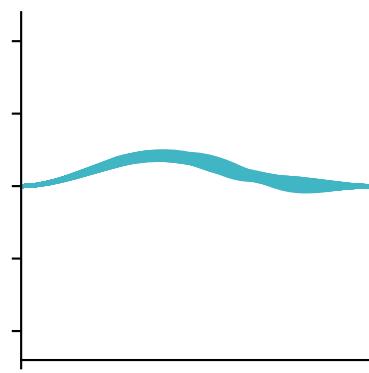
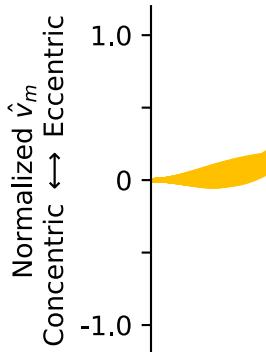
BIC

BRD

ECRB

TRI

DELTp



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Movement Duration : 1 sec

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