

Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \dot{V}_m
Concentric \rightarrow Eccentric

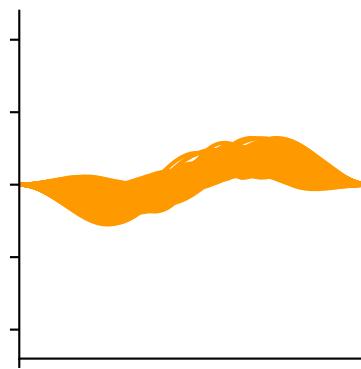
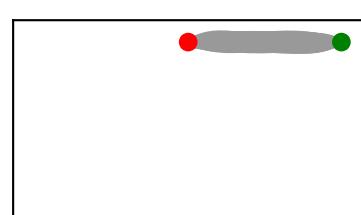
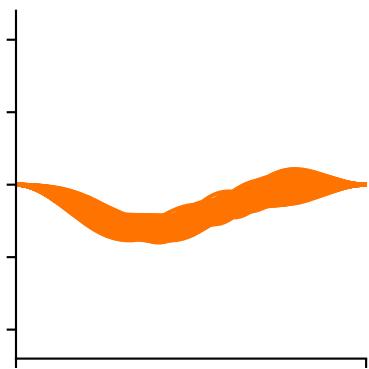
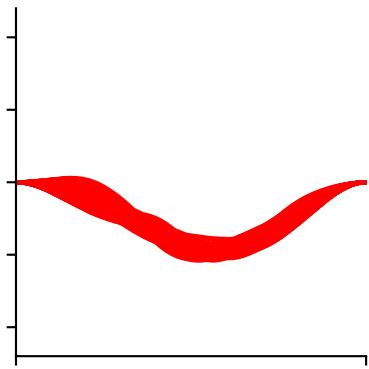
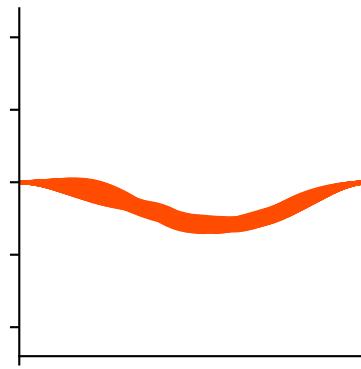
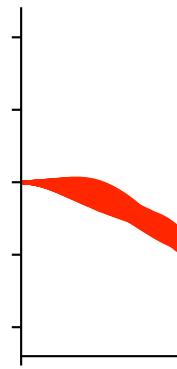
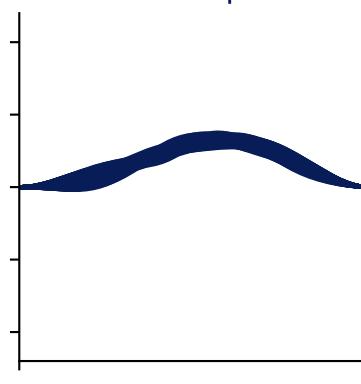
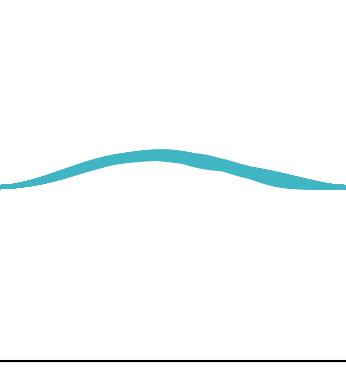
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-1

Start

Finish



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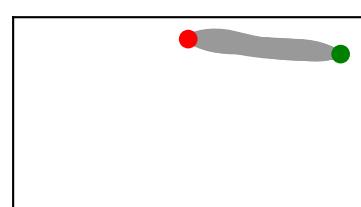
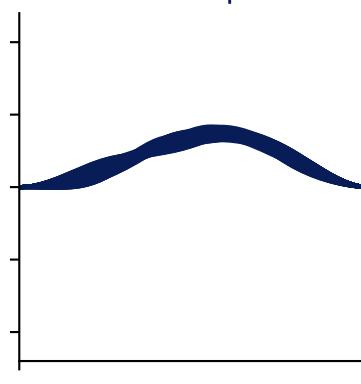
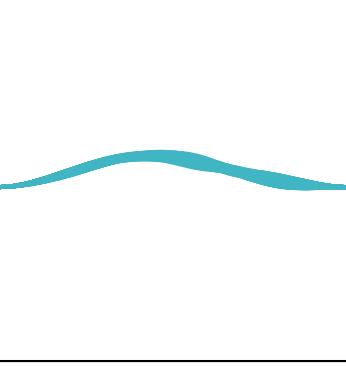
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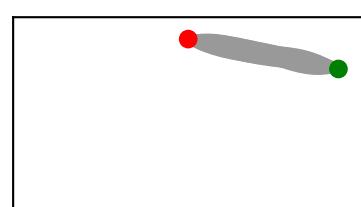
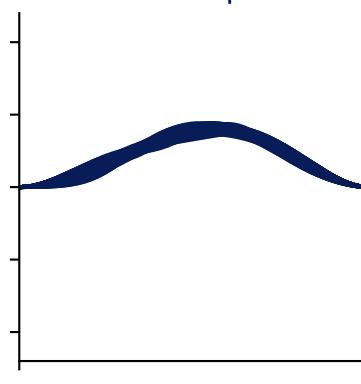
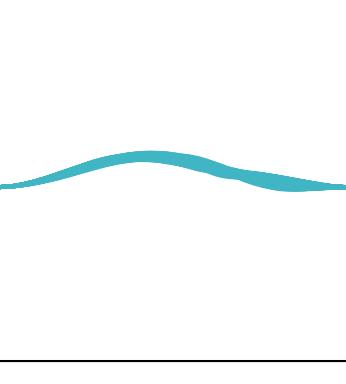
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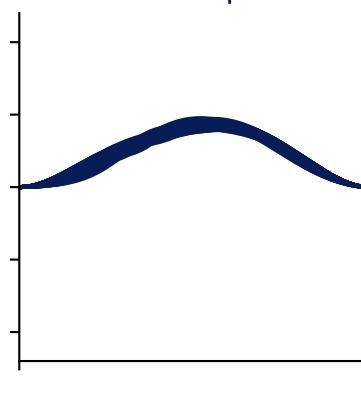
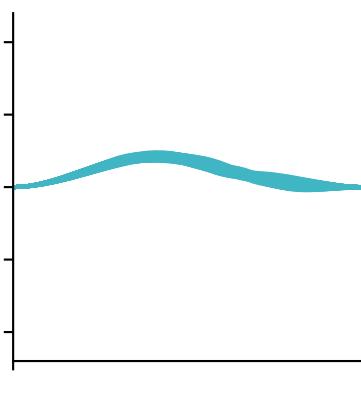
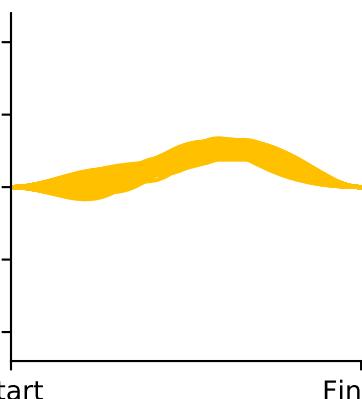
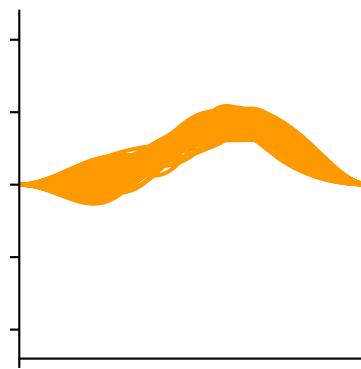
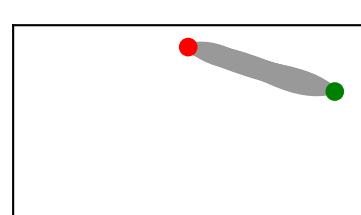
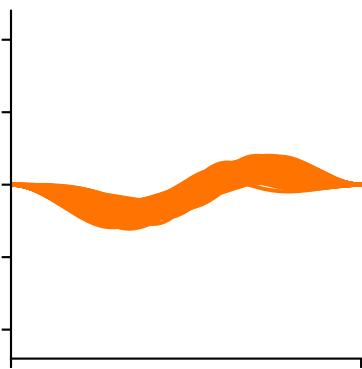
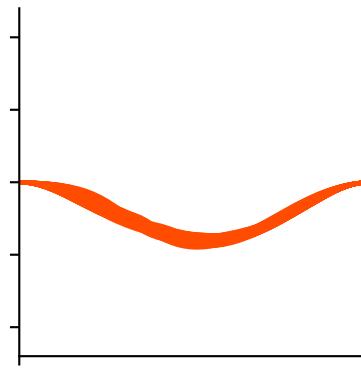
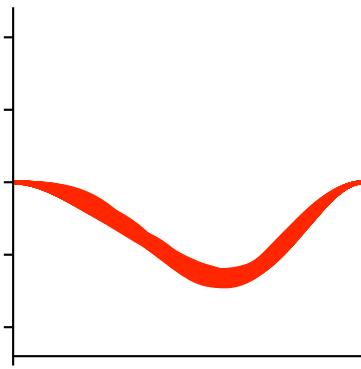
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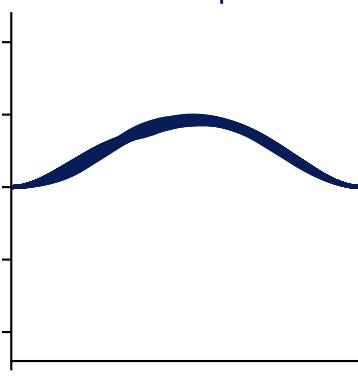
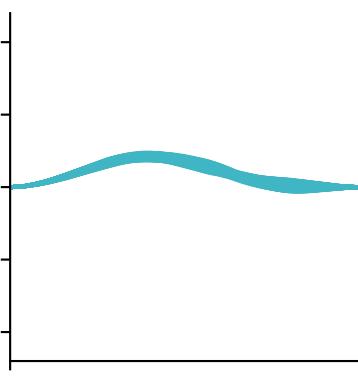
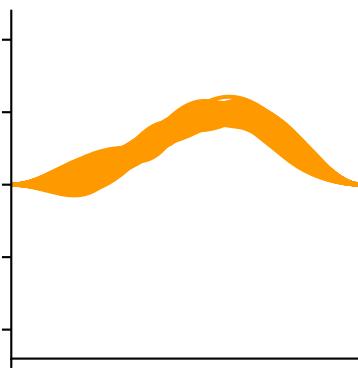
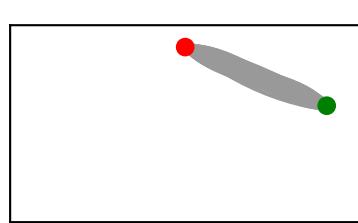
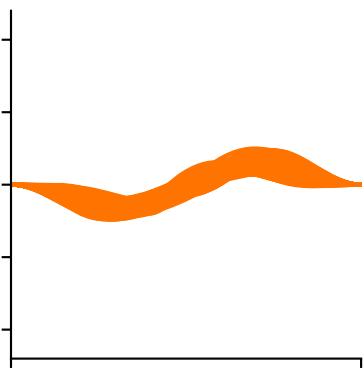
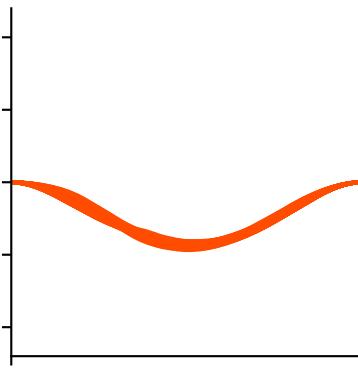
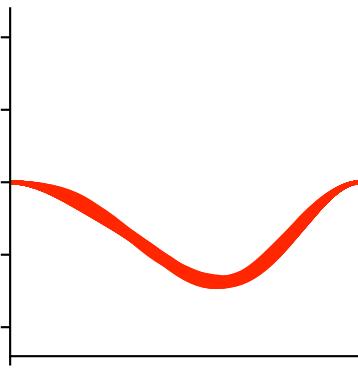
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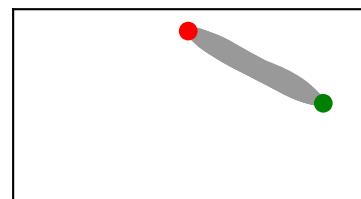
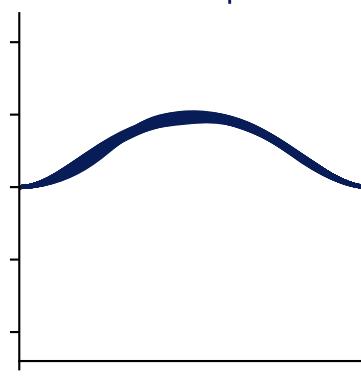
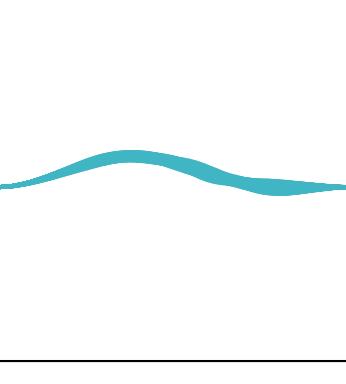
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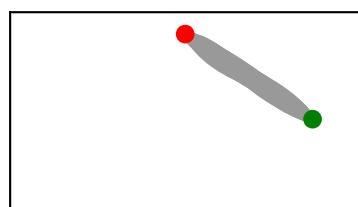
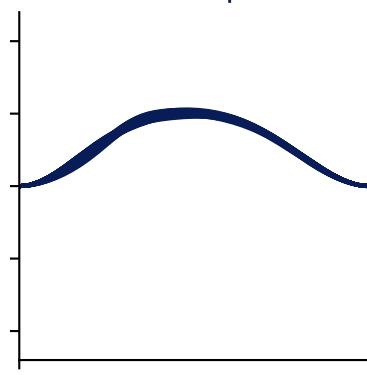
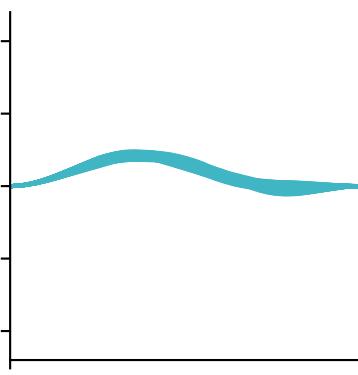
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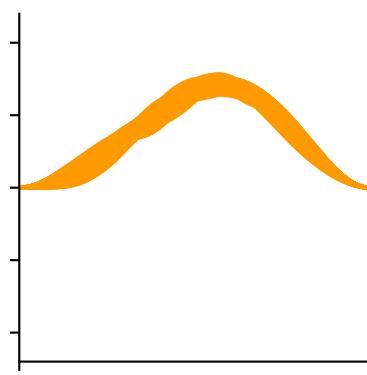
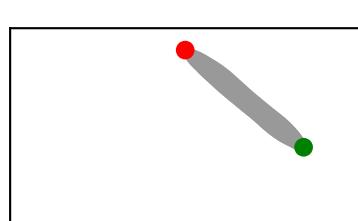
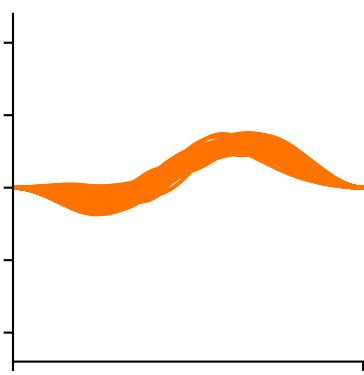
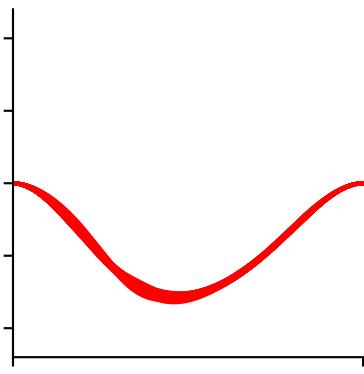
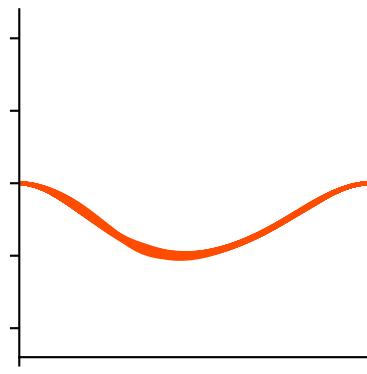
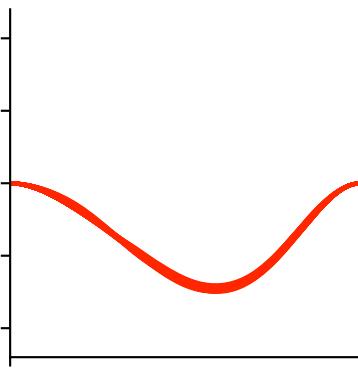
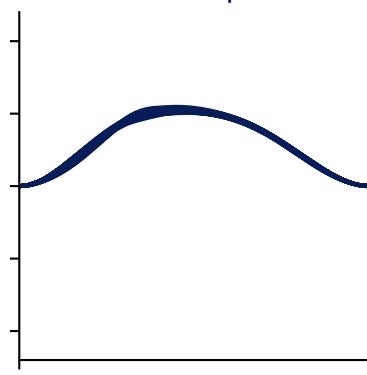
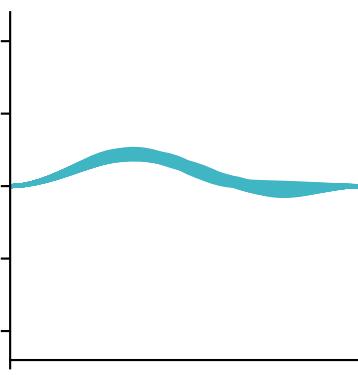
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Concentric \leftrightarrow Eccentric

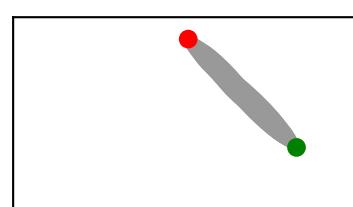
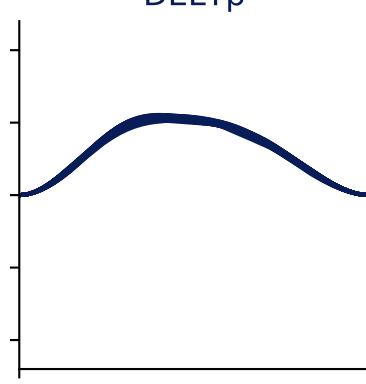
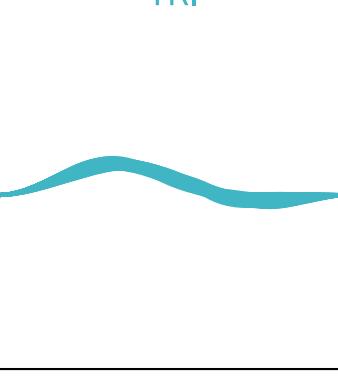
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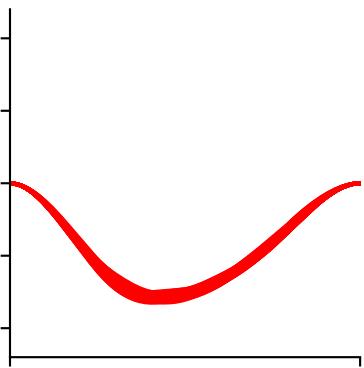
Start

Finish

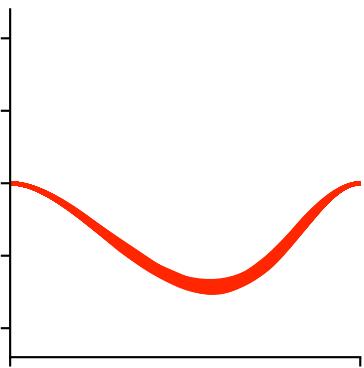


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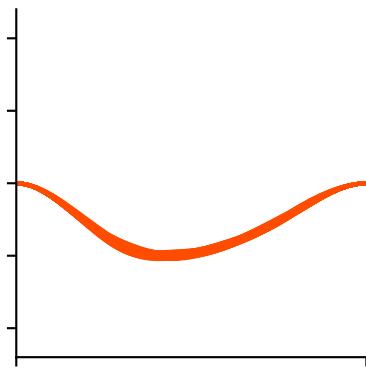
PC



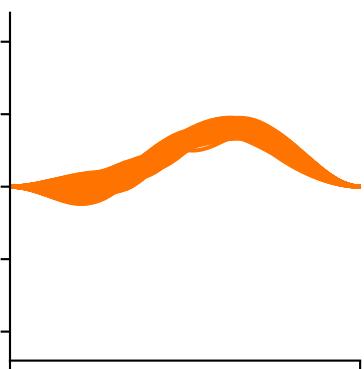
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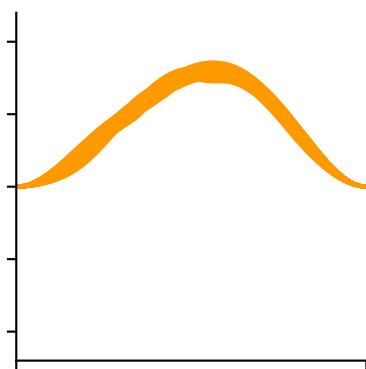
CB



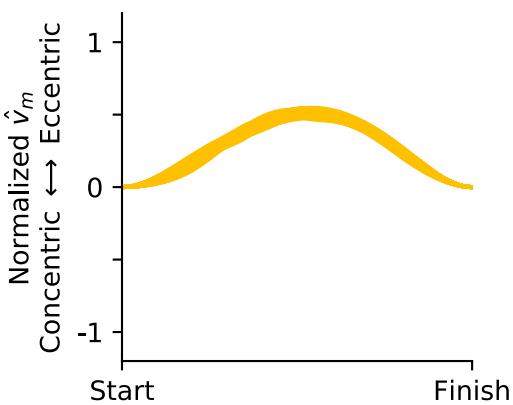
BIC



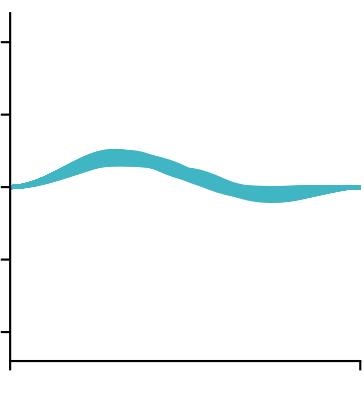
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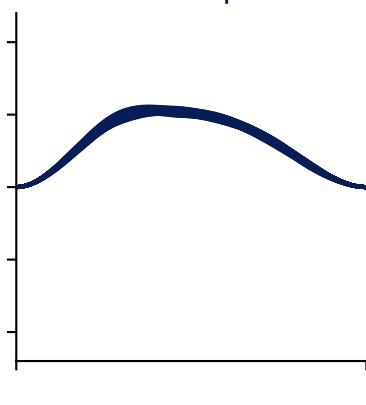
ECRB



TRI



DELTp



Normalized \hat{V}_m → Eccentric

Fixed Final Position
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Concentric \leftrightarrow Eccentric

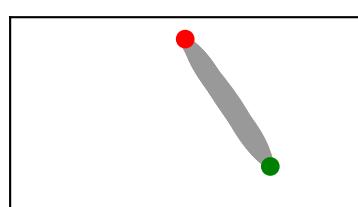
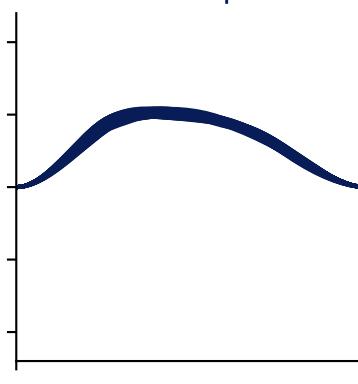
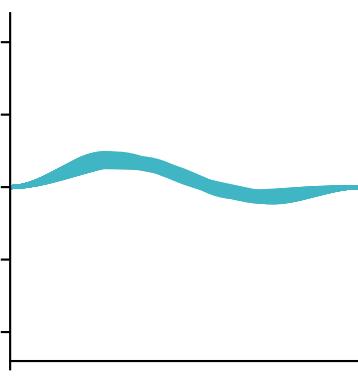
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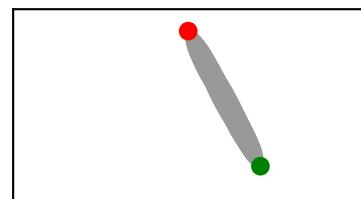
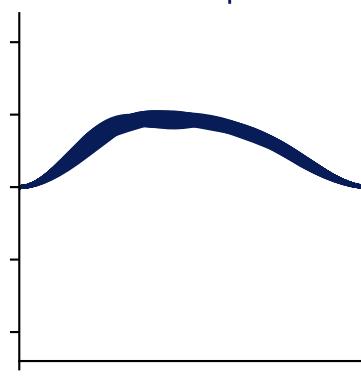
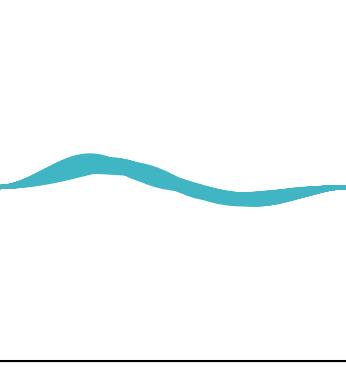
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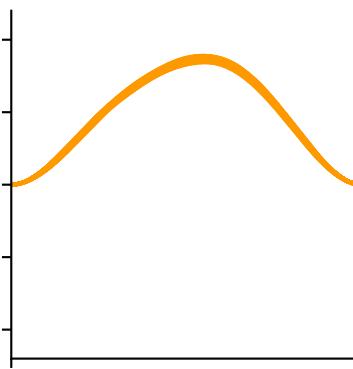
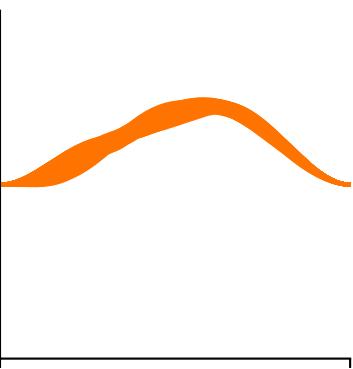
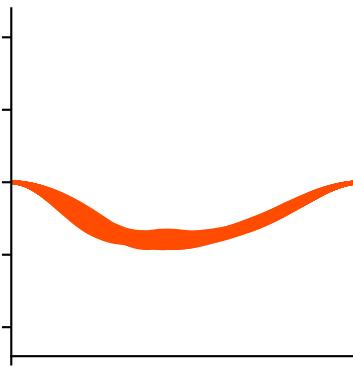
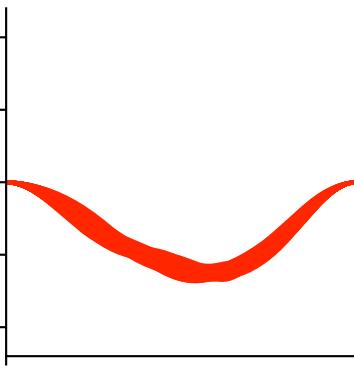
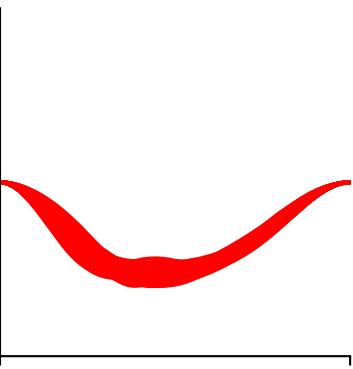
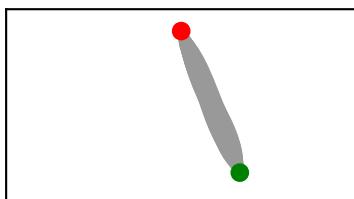
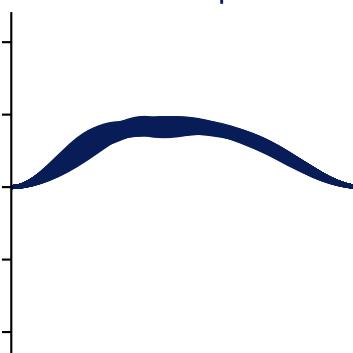
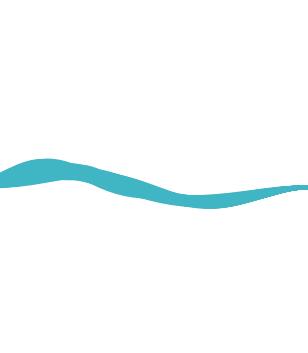
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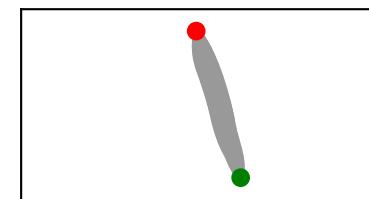
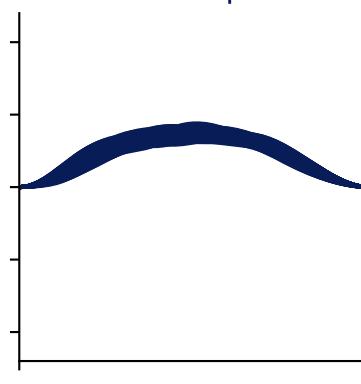
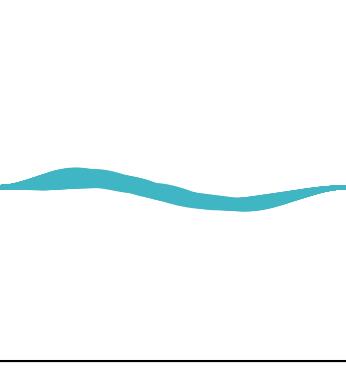
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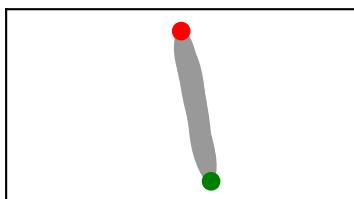
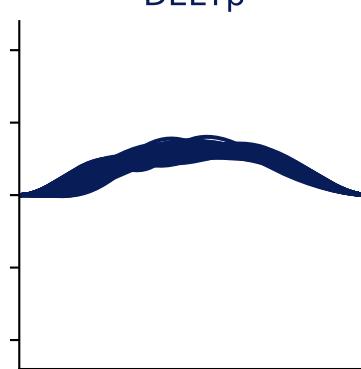
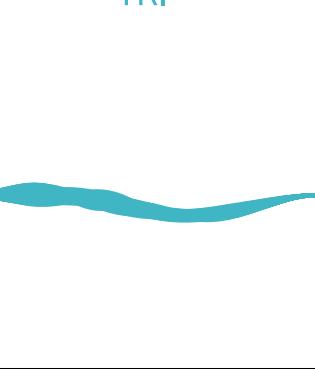
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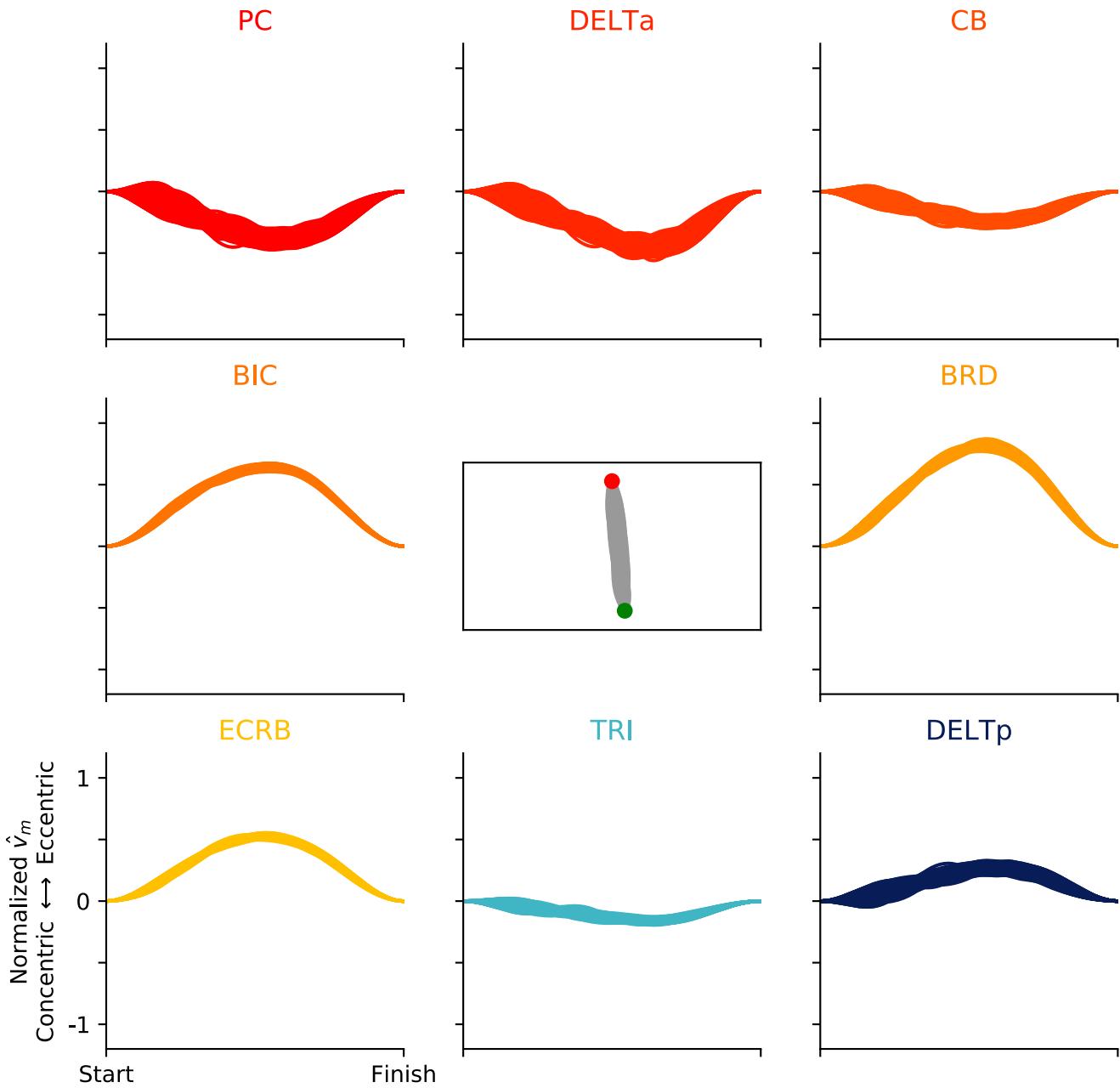
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Start

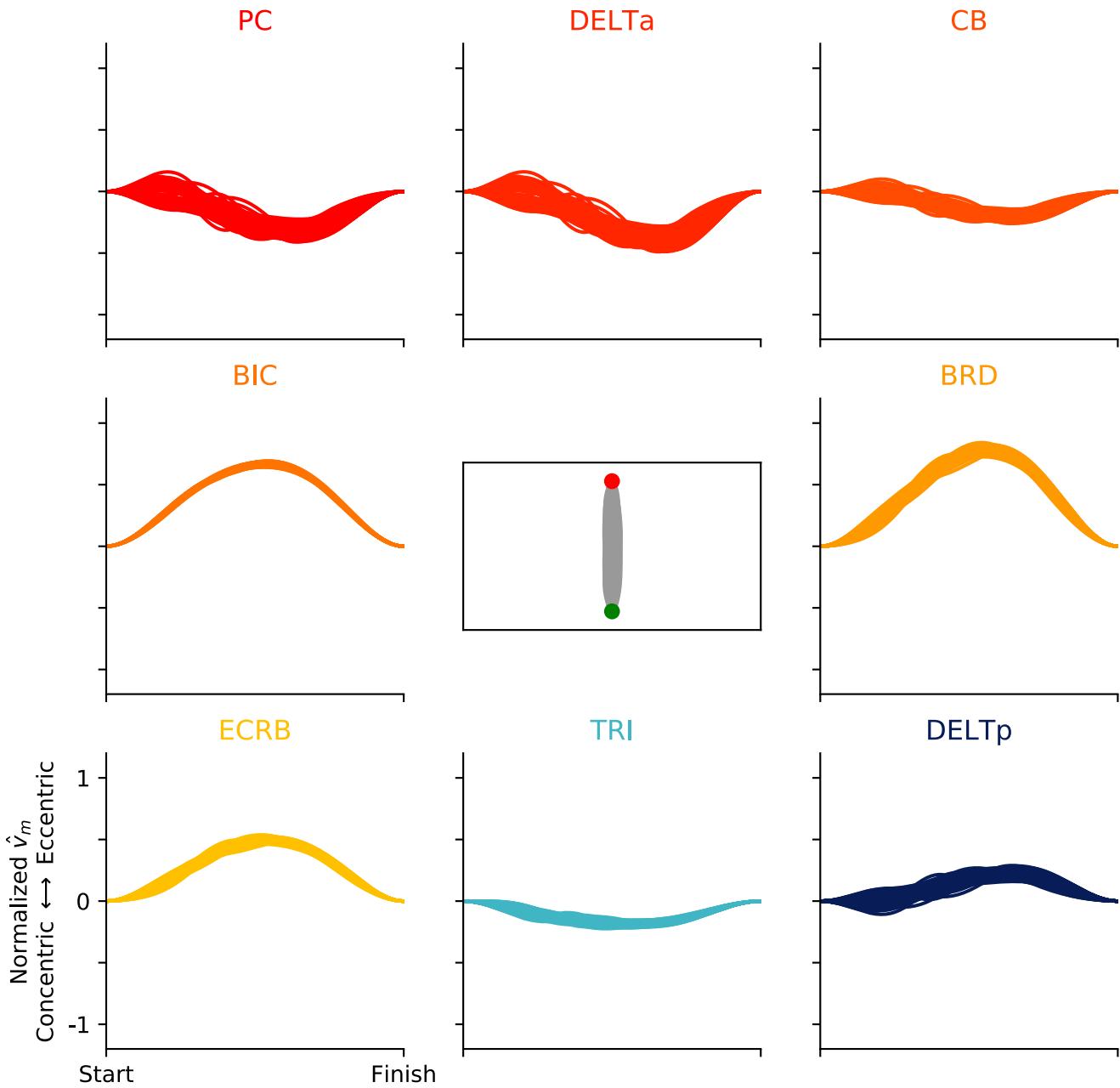
Finish



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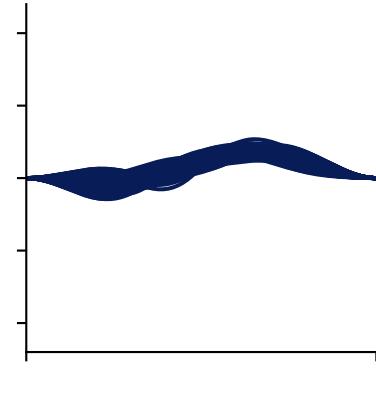
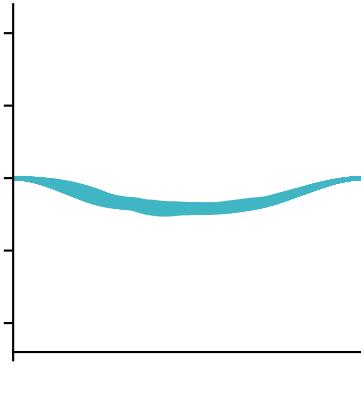
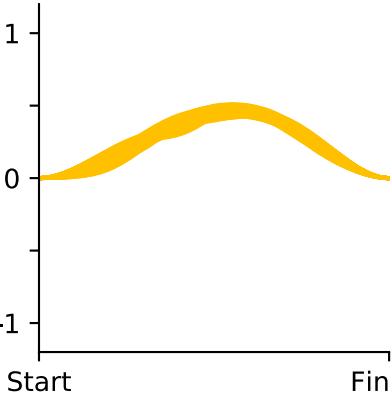
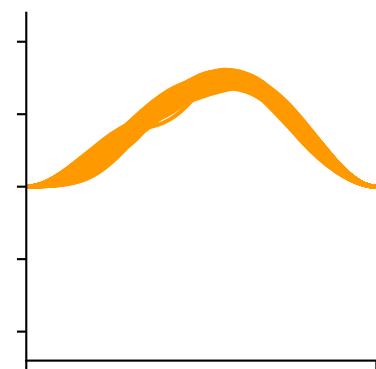
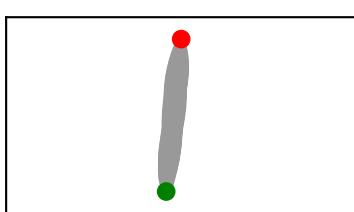
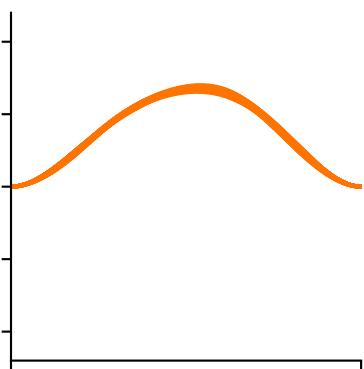
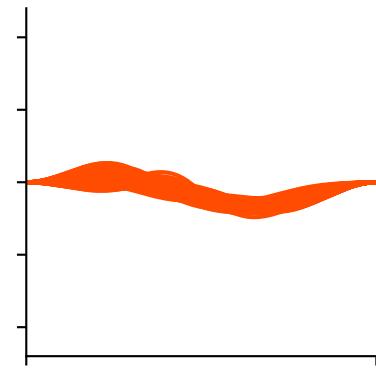
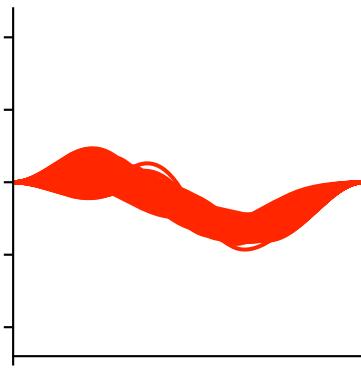
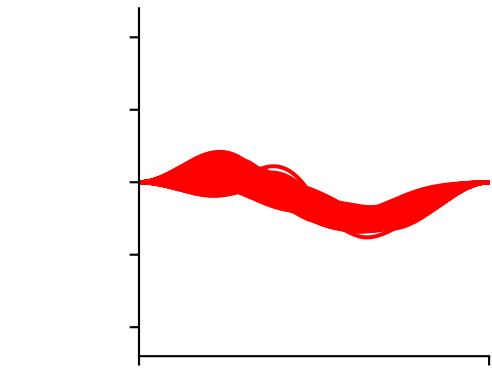
Normalized \dot{V}_m
Concentric \leftrightarrow Eccentric

1

-1

Start

Finish



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

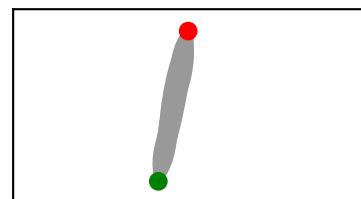
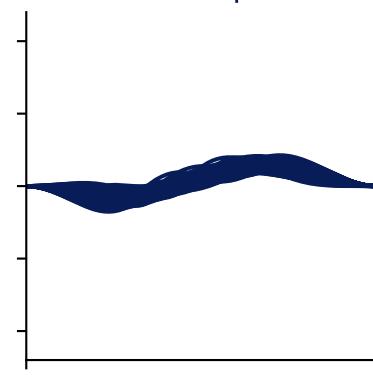
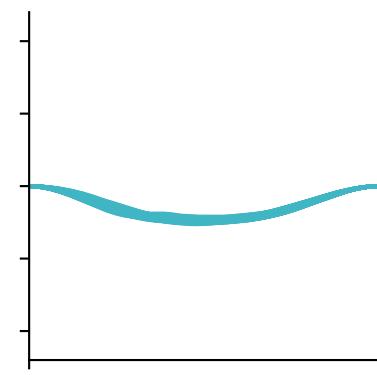
Normalized \hat{V}_m
Concentric \leftrightarrow Eccentric

1

-1

Start

Finish



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \hat{V}_m
Concentric \leftrightarrow Eccentric

1

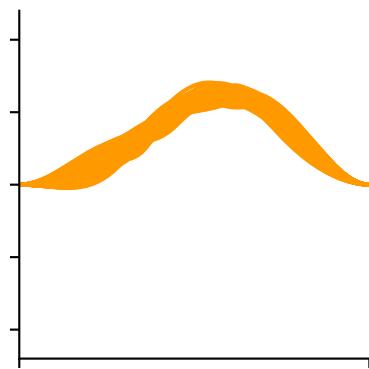
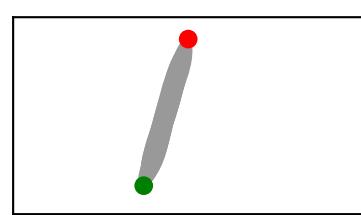
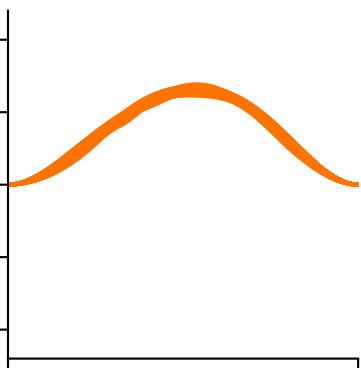
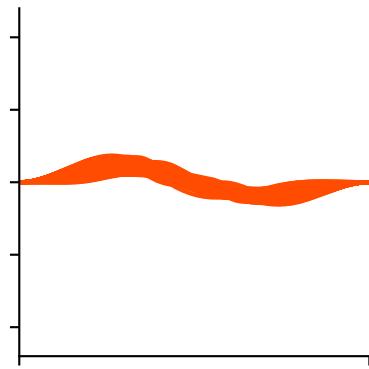
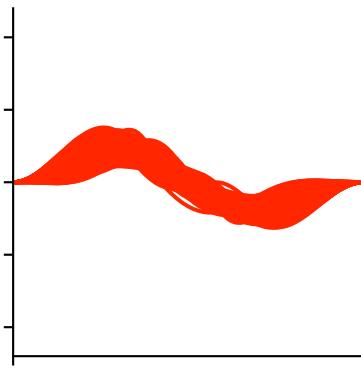
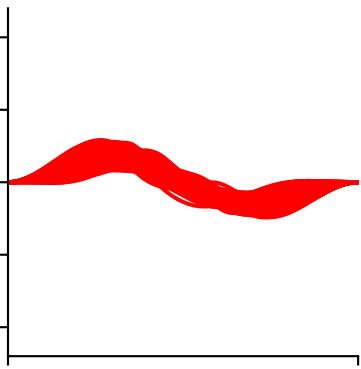
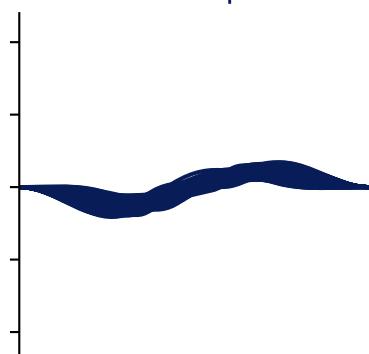
-1

Start

Finish



TRI



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \hat{V}_m
Concentric \rightarrow Eccentric

1

0

-1

Start

Finish



TRI



DELTp



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \dot{V}_m → Eccentric

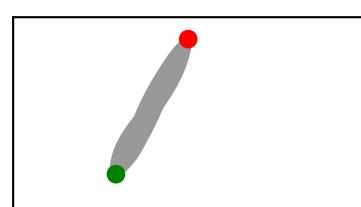
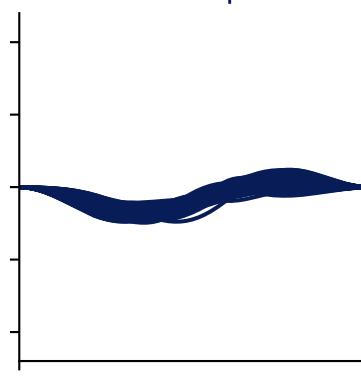
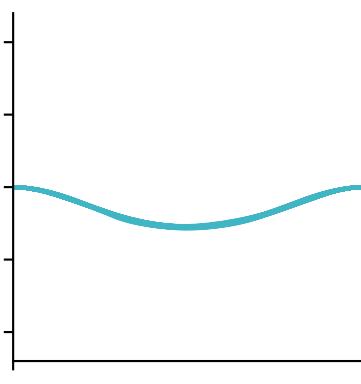
1

0

-1

Start

Finish



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \dot{V}_m
Concentric \rightarrow Eccentric

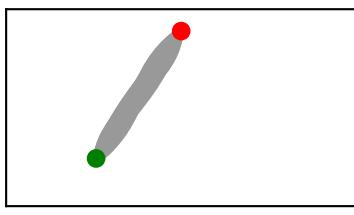
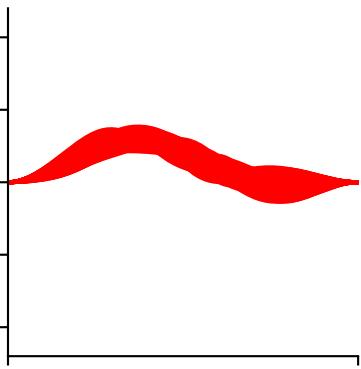
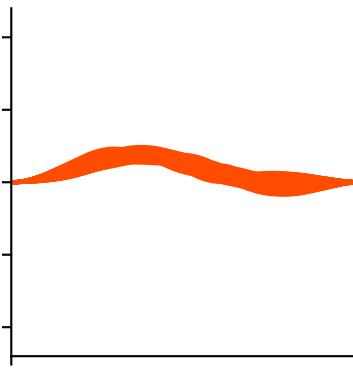
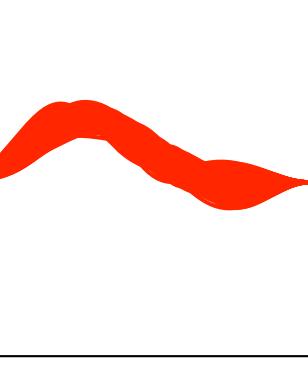
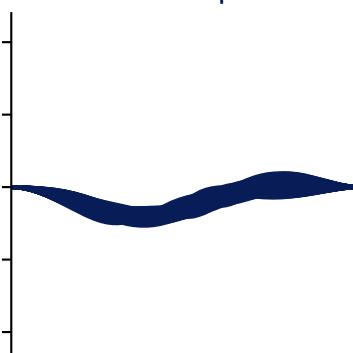
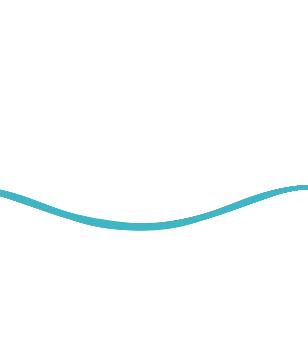
1

0

Start

Finish

-1



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

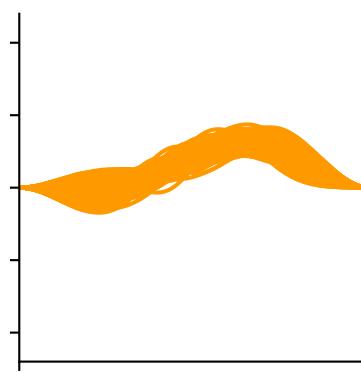
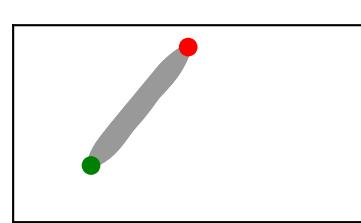
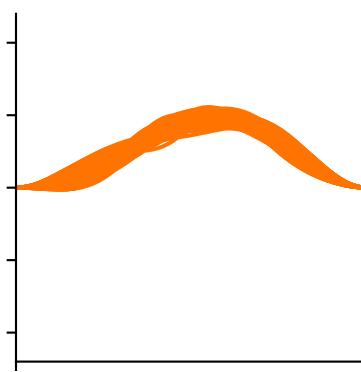
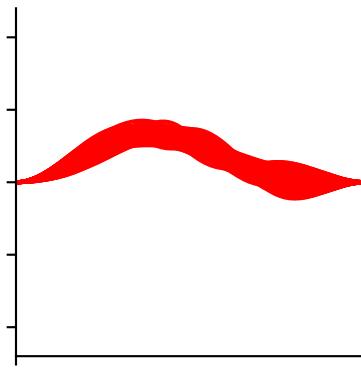
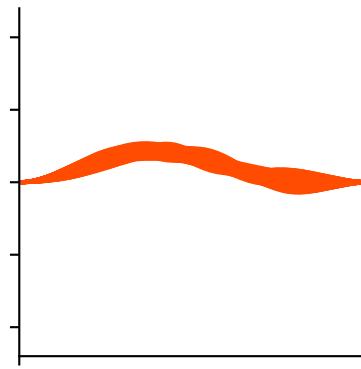
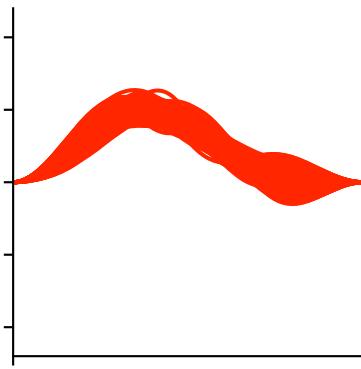
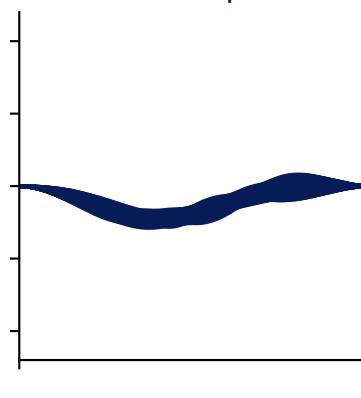
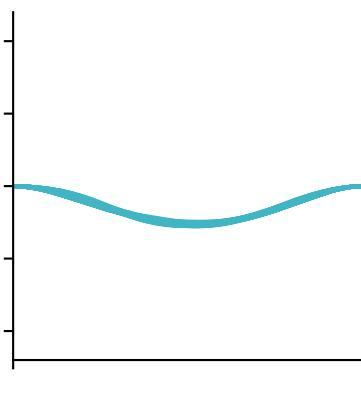
Normalized \dot{V}_m
Concentric \rightarrow Eccentric

1

0

Start

Finish



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \hat{V}_m → Eccentric

1

0

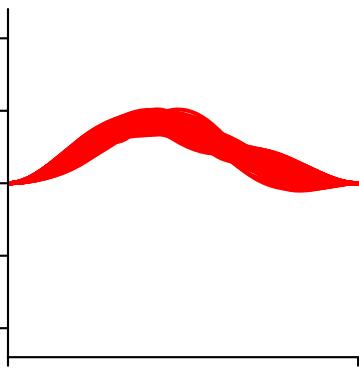
-1

Start

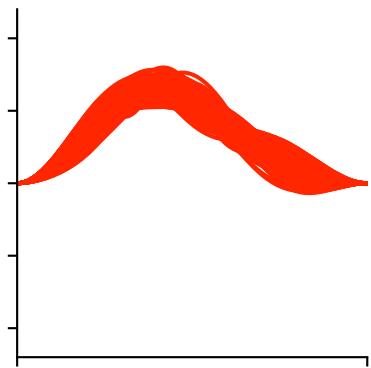
Finish

Fixed Final Position
Movement Duration : 1 sec

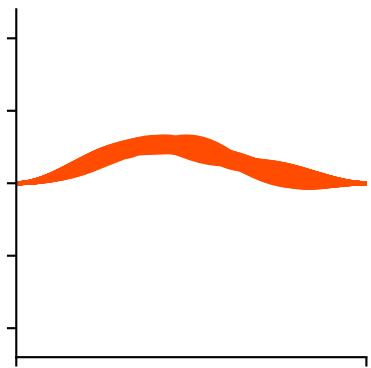
PC



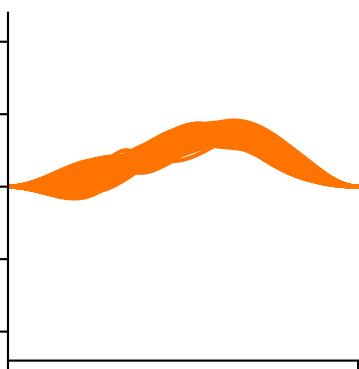
DELTa



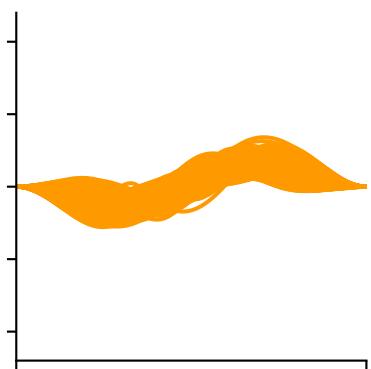
CB



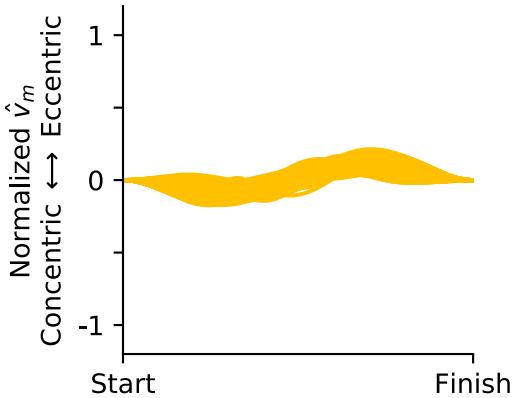
BIC



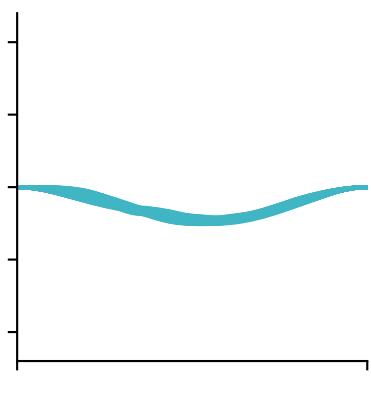
BRD



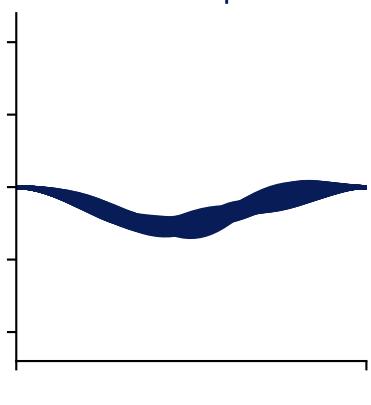
ECRB



TRI



DELTp



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \dot{V}_m Eccentric

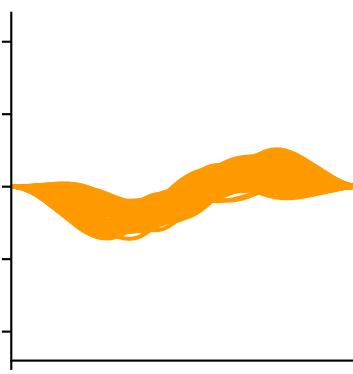
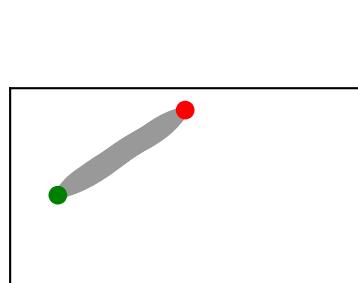
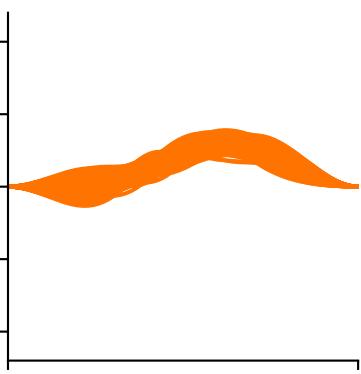
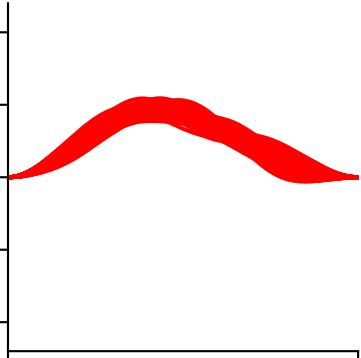
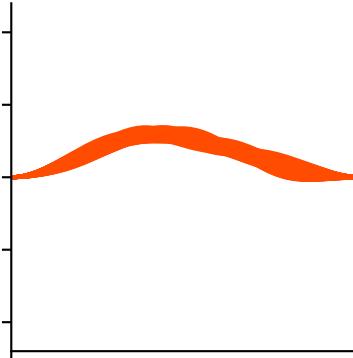
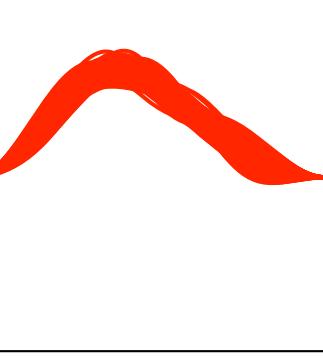
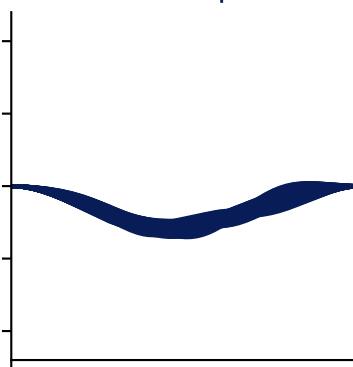
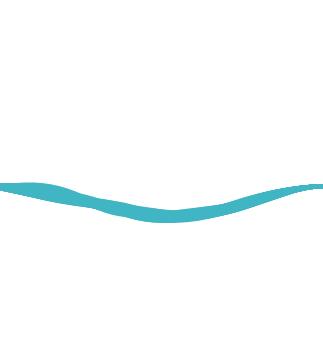
1

0

-1

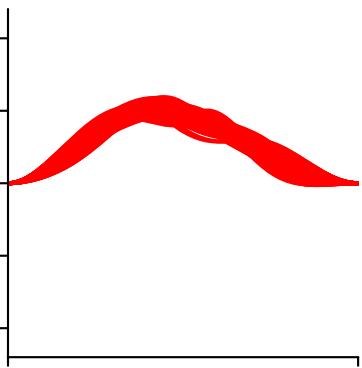
Start

Finish

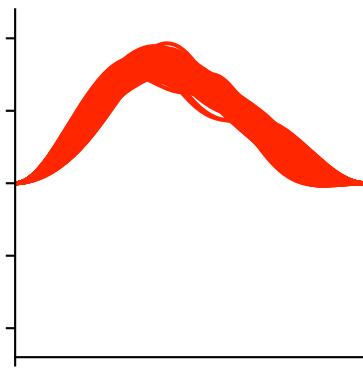


Fixed Final Position
Movement Duration : 1 sec

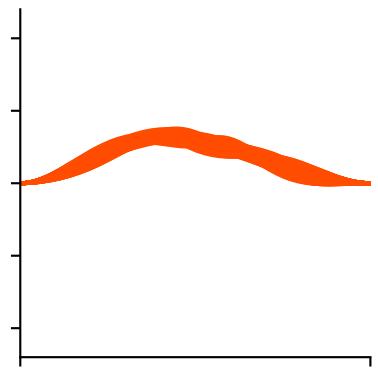
PC



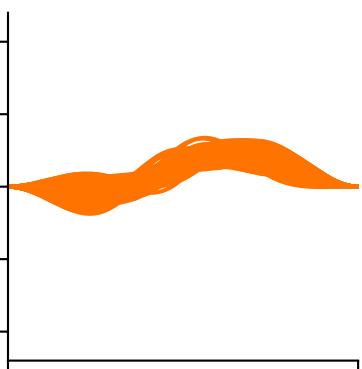
DELTa



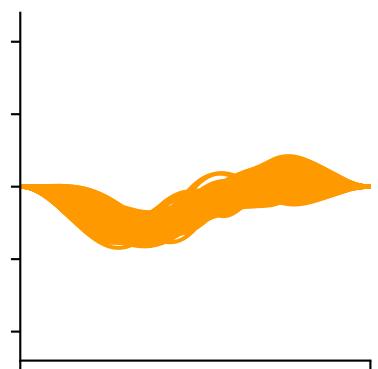
CB



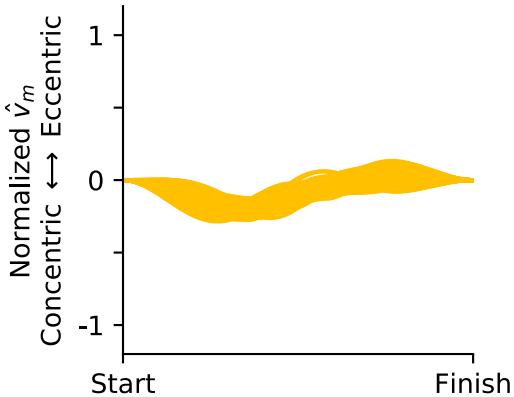
BIC



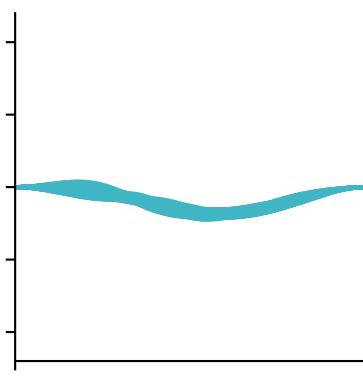
BRD



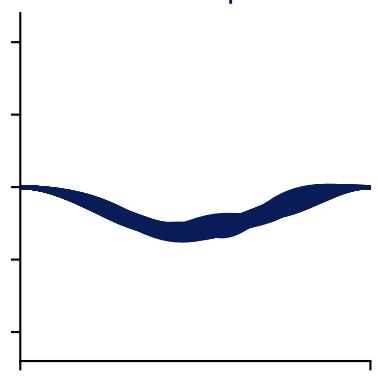
ECRB



TRI



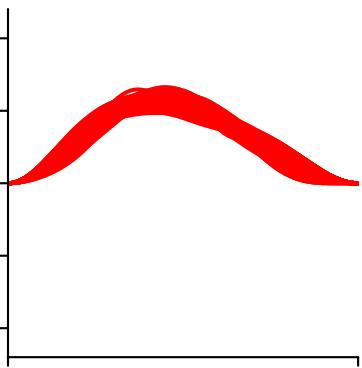
DELTp



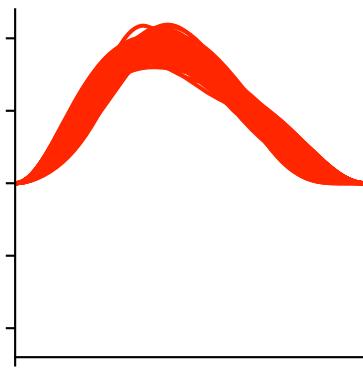
Normalized \dot{V}_m Eccentric → Concentric

Fixed Final Position
Movement Duration : 1 sec

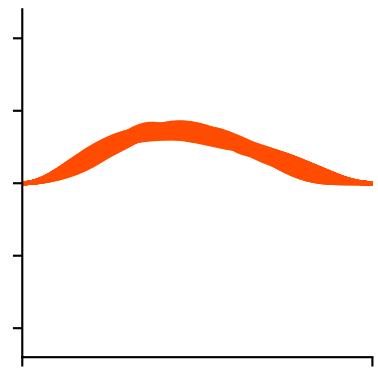
PC



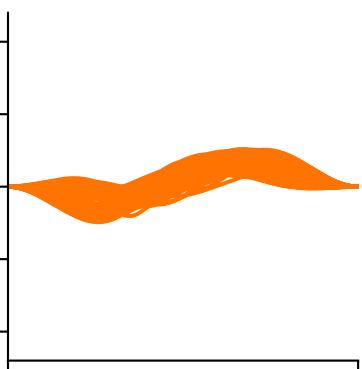
DELTa



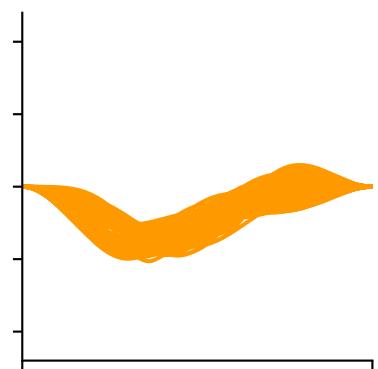
CB



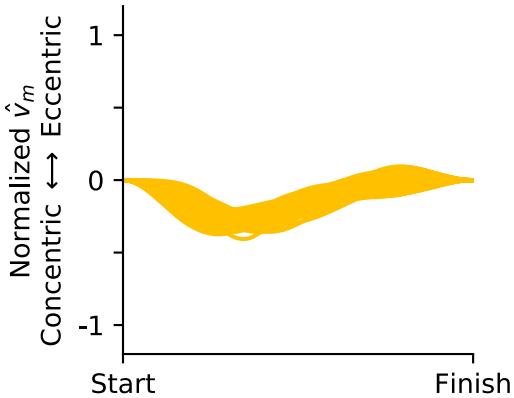
BIC



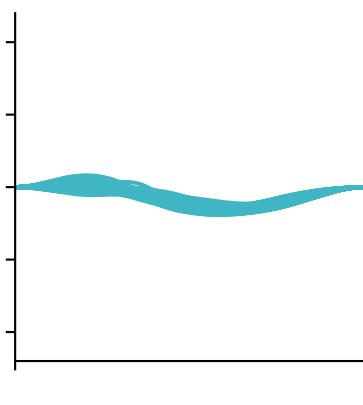
BRD



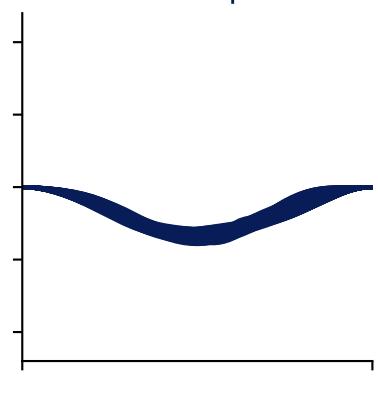
ECRB



TRI



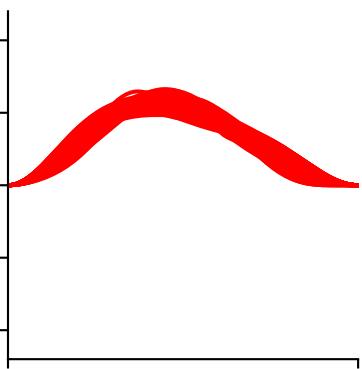
DELTp



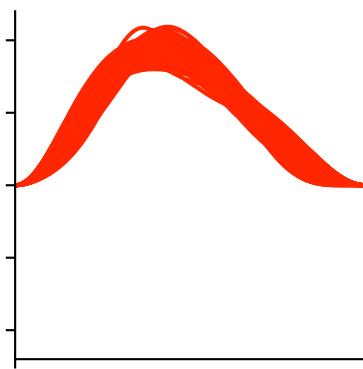
Normalized \dot{V}_m → Eccentric

Fixed Final Position
Movement Duration : 1 sec

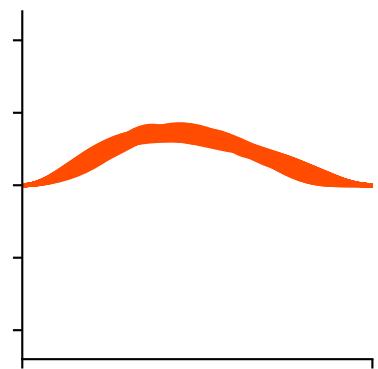
PC



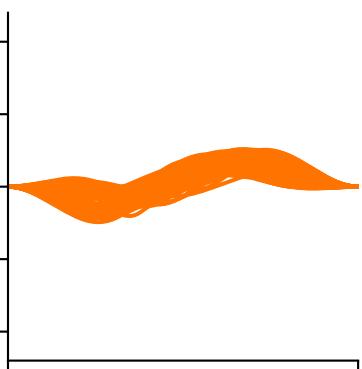
DELTa



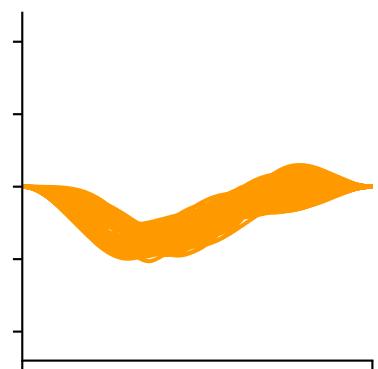
CB



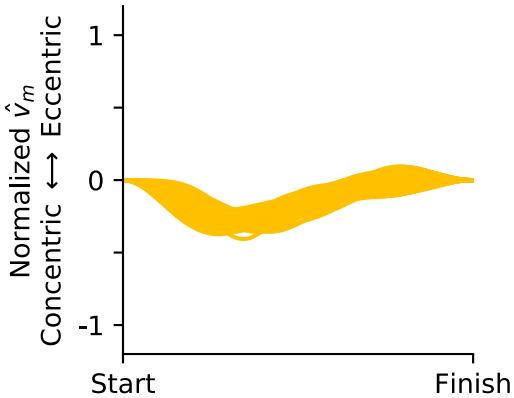
BIC



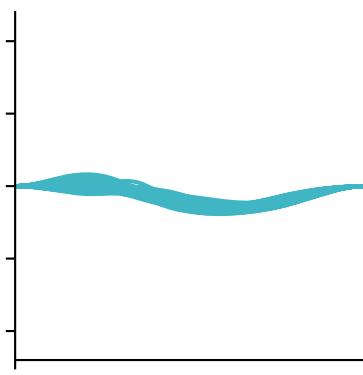
BRD



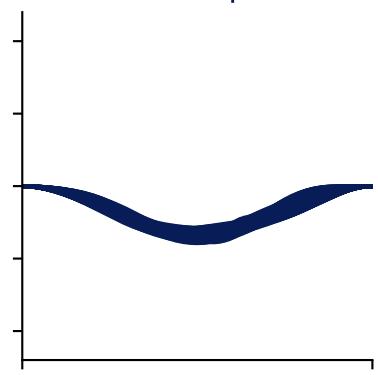
ECRB



TRI



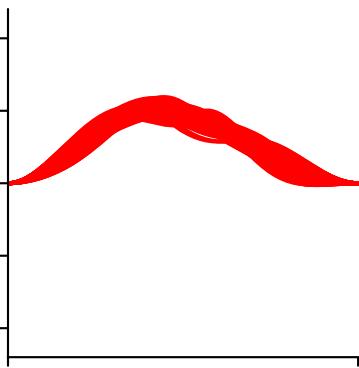
DELTp



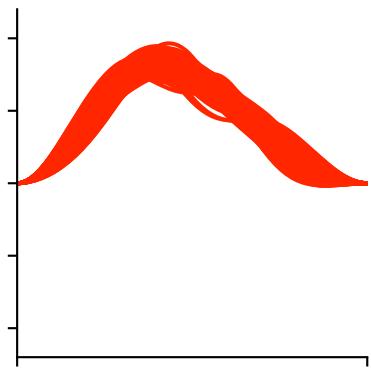
Normalized \dot{V}_m Eccentric → Concentric

Fixed Final Position
Movement Duration : 1 sec

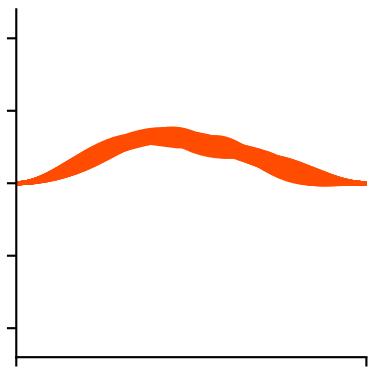
PC



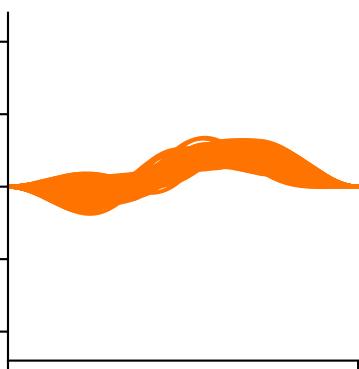
DELTa



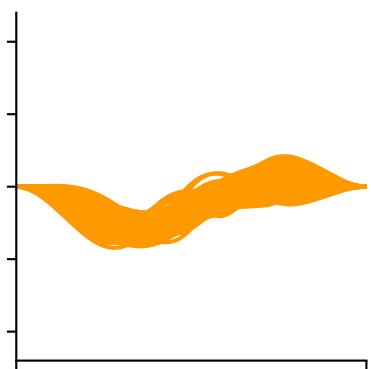
CB



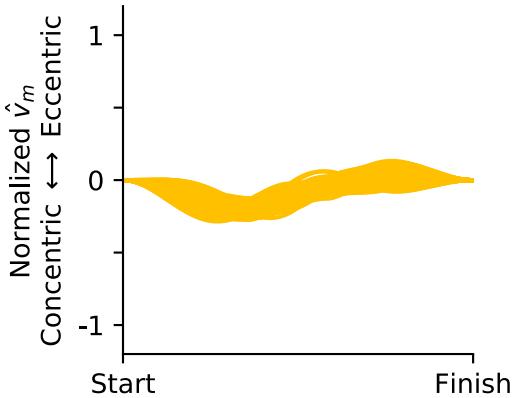
BIC



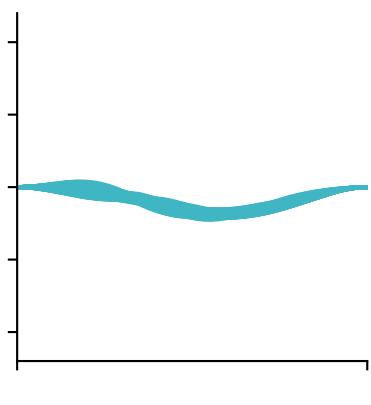
BRD



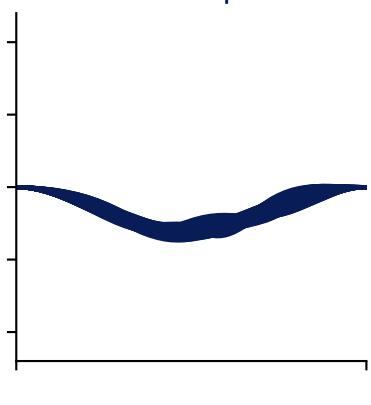
ECRB



TRI



DELTp



Normalized \dot{V}_m Eccentric → Concentric

Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \dot{V}_m Eccentric

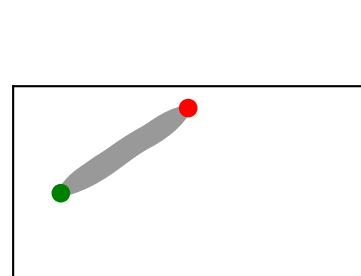
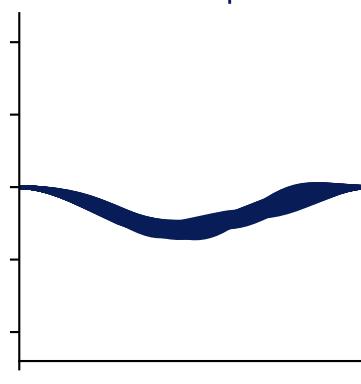
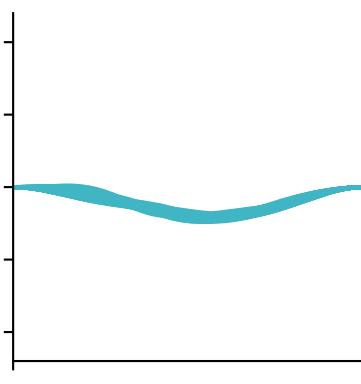
1

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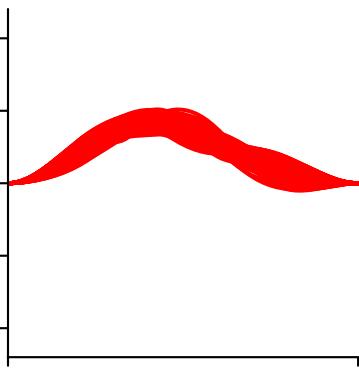
Start

Finish

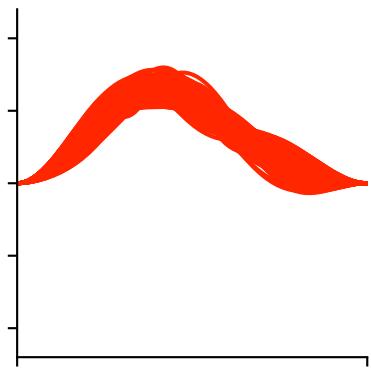


Fixed Final Position
Movement Duration : 1 sec

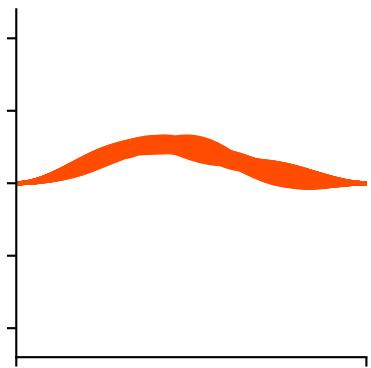
PC



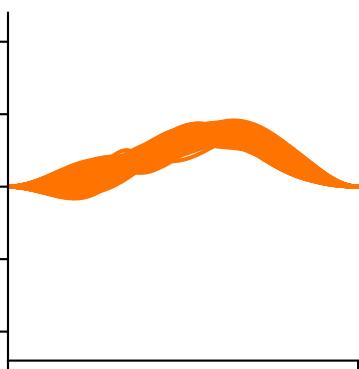
DELTa



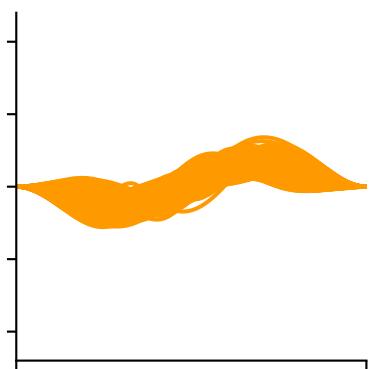
CB



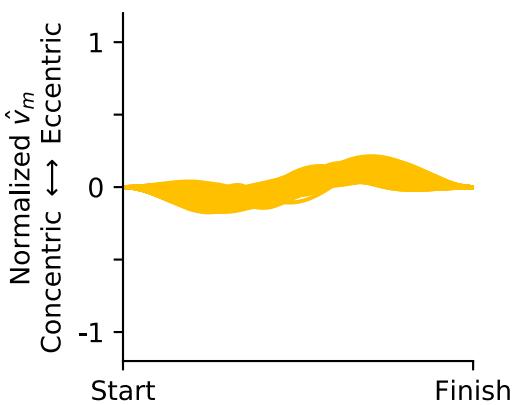
BIC



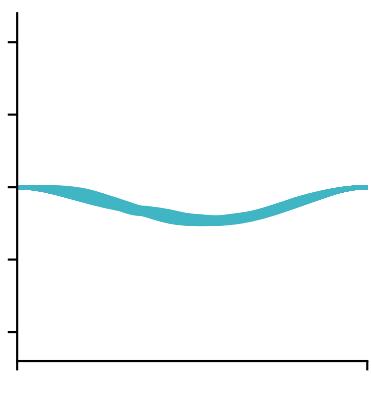
BRD



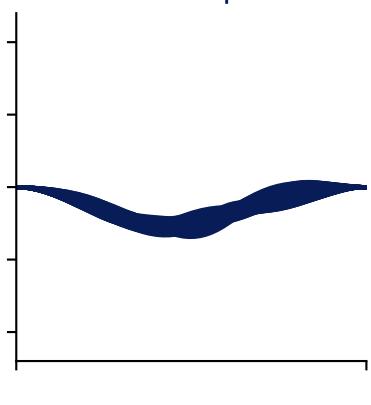
ECRB



TRI



DELTp



Normalized \hat{V}_m → Eccentric

1
0
-1

Start

Finish

Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \hat{V}_m
Concentric \rightarrow Eccentric

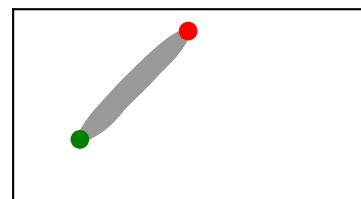
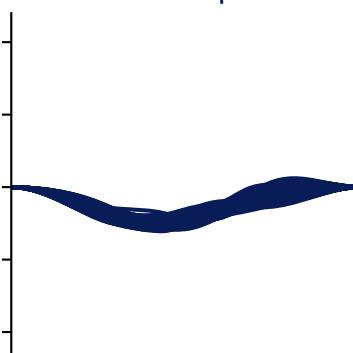
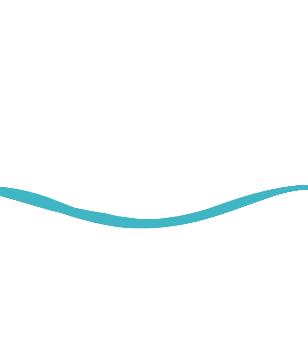
1

0

-1

Start

Finish



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \dot{V}_m Eccentric → Concentric

1

0

Start

Finish

Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \dot{V}_m
Concentric \rightarrow Eccentric

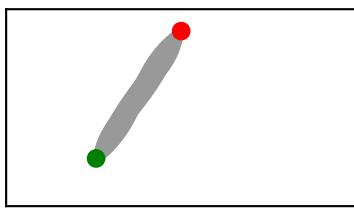
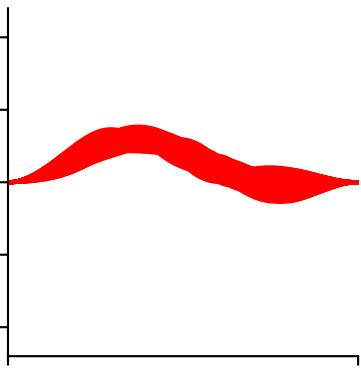
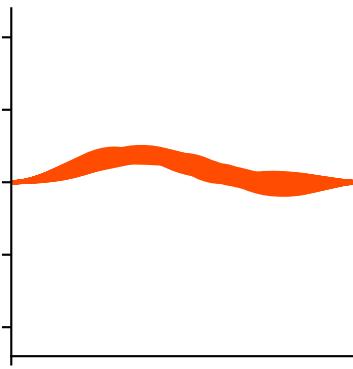
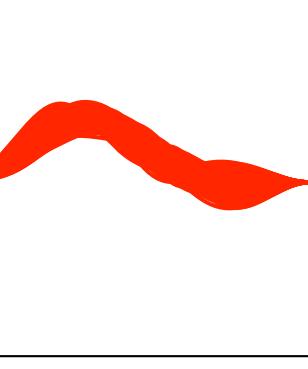
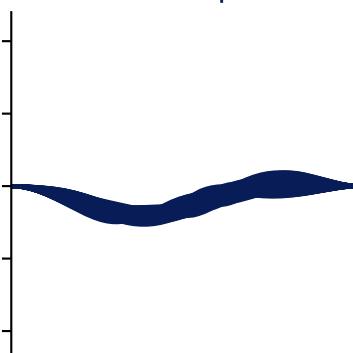
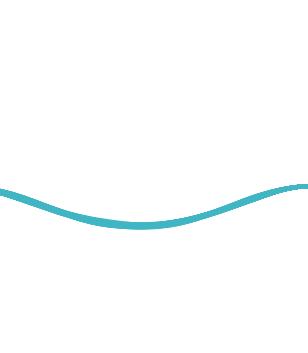
1

0

Start

Finish

-1



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \hat{V}_m
Concentric \rightarrow Eccentric

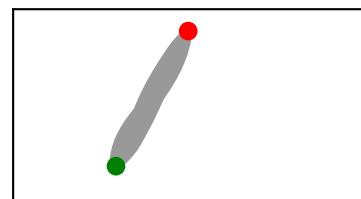
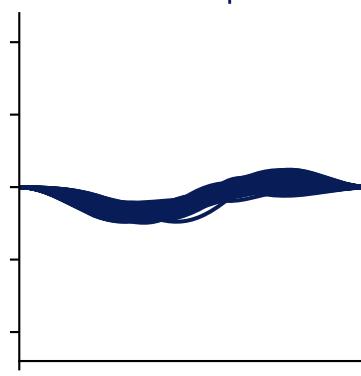
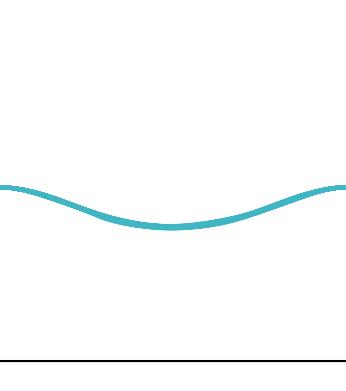
1

0

-1

Start

Finish



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \hat{V}_m
Concentric \rightarrow Eccentric

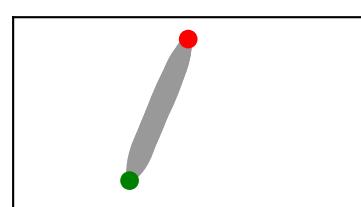
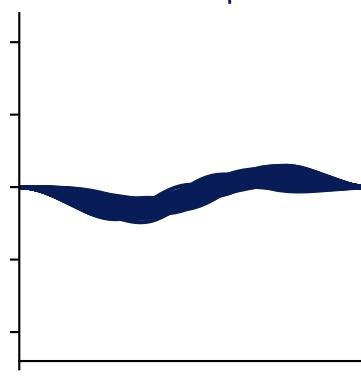
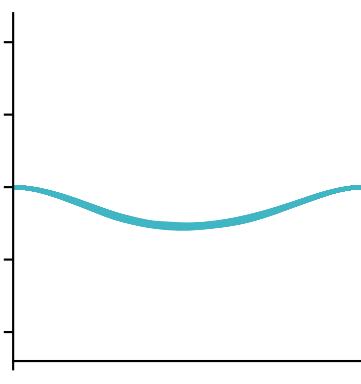
1

0

-1

Start

Finish



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \dot{V}_m
Concentric \rightarrow Eccentric

1

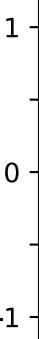
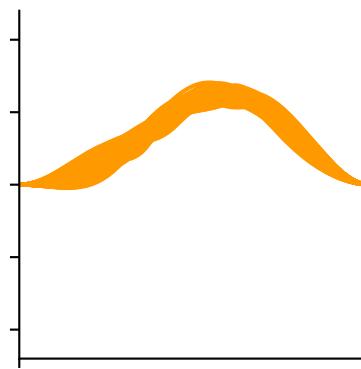
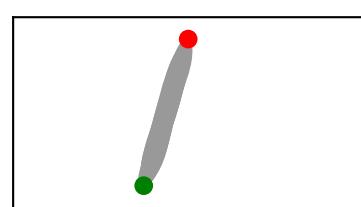
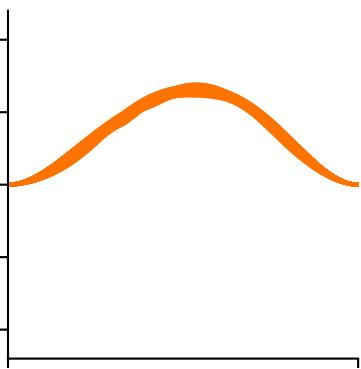
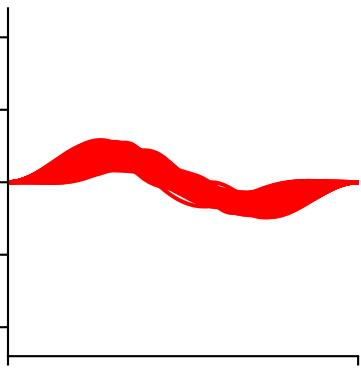
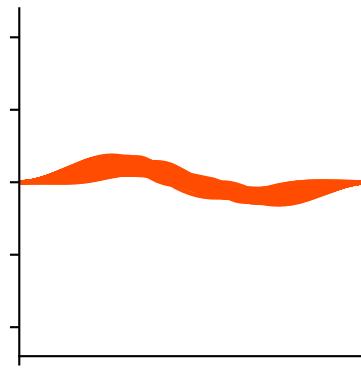
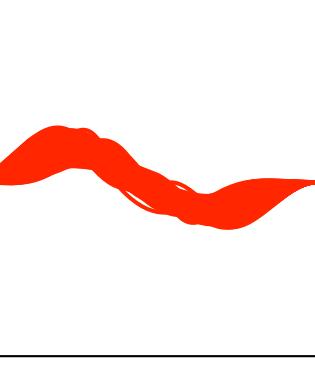
-1

Start

Finish

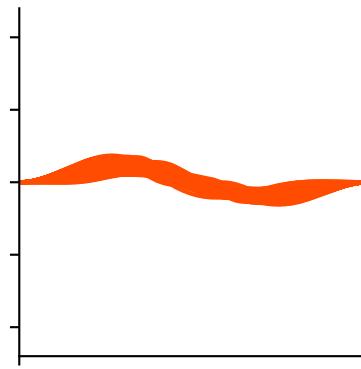
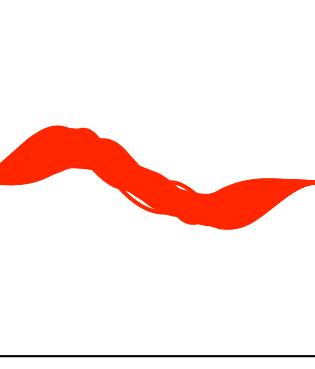
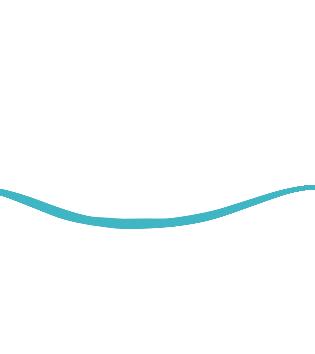


TRI



Start

Finish



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

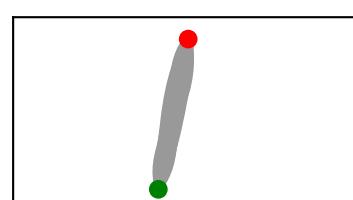
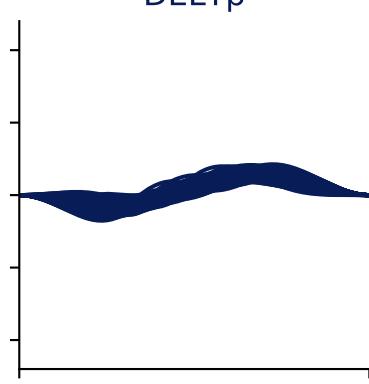
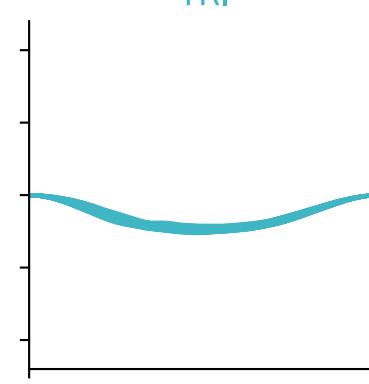
Normalized \dot{V}_m
Concentric \rightarrow Eccentric

1

-1

Start

Finish



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \dot{V}_m
Concentric \leftrightarrow Eccentric

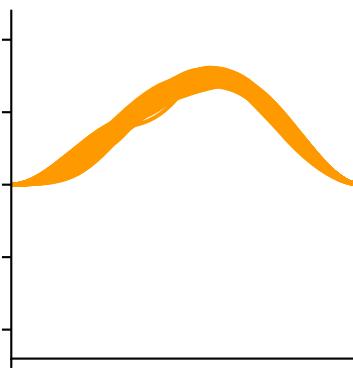
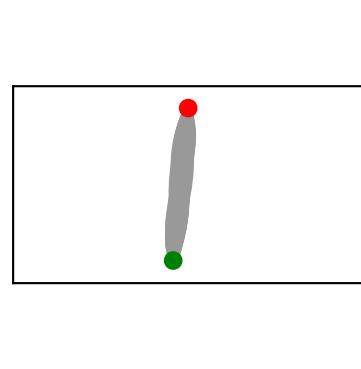
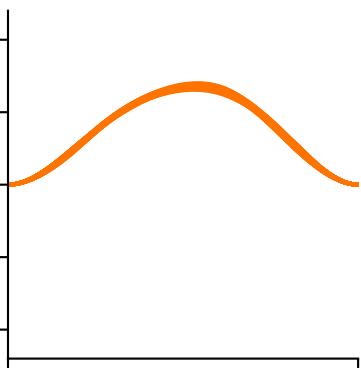
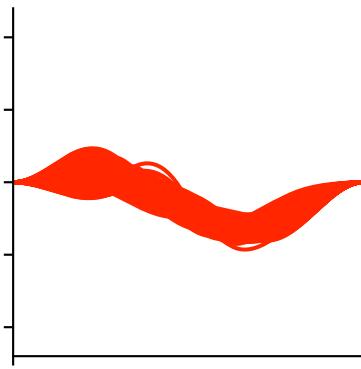
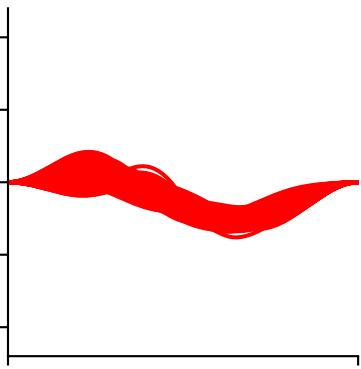
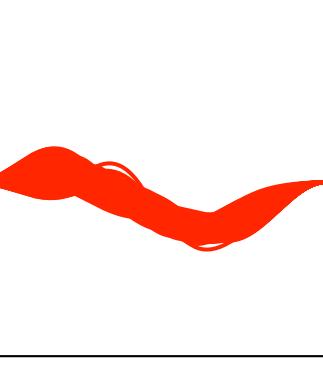
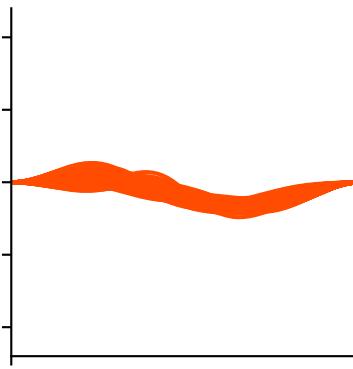
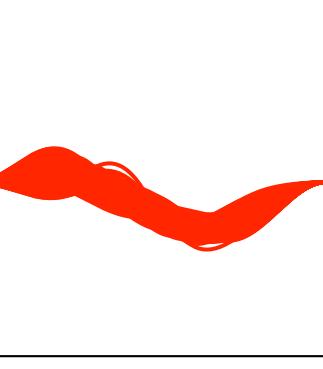
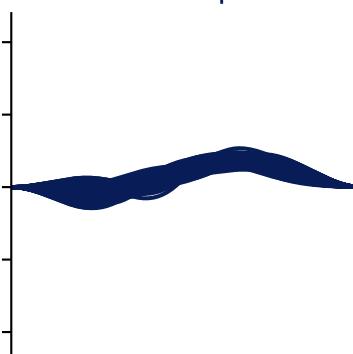
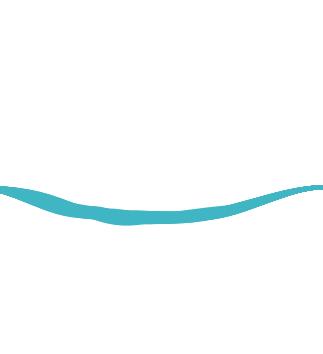
1

0

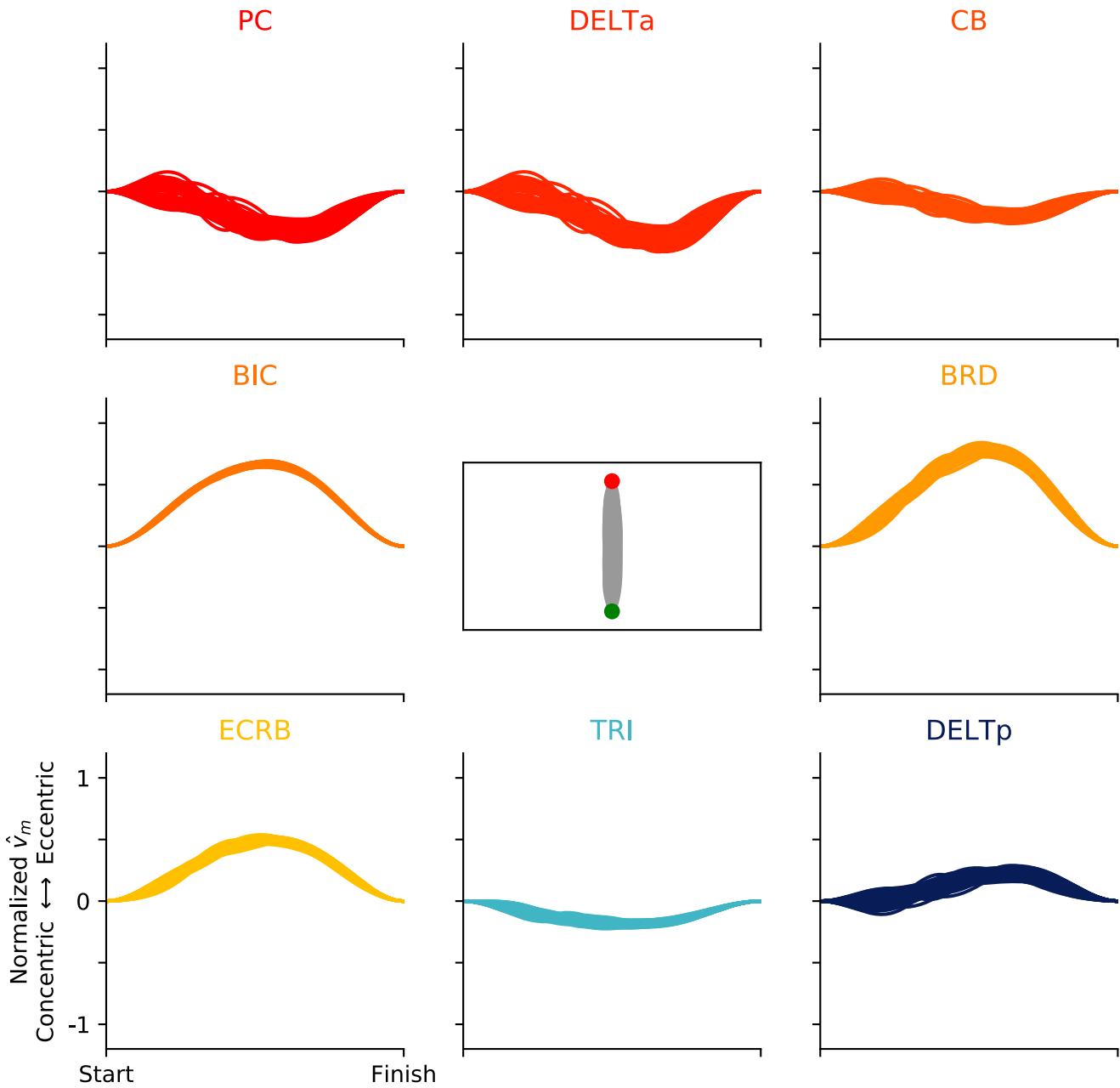
-1

Start

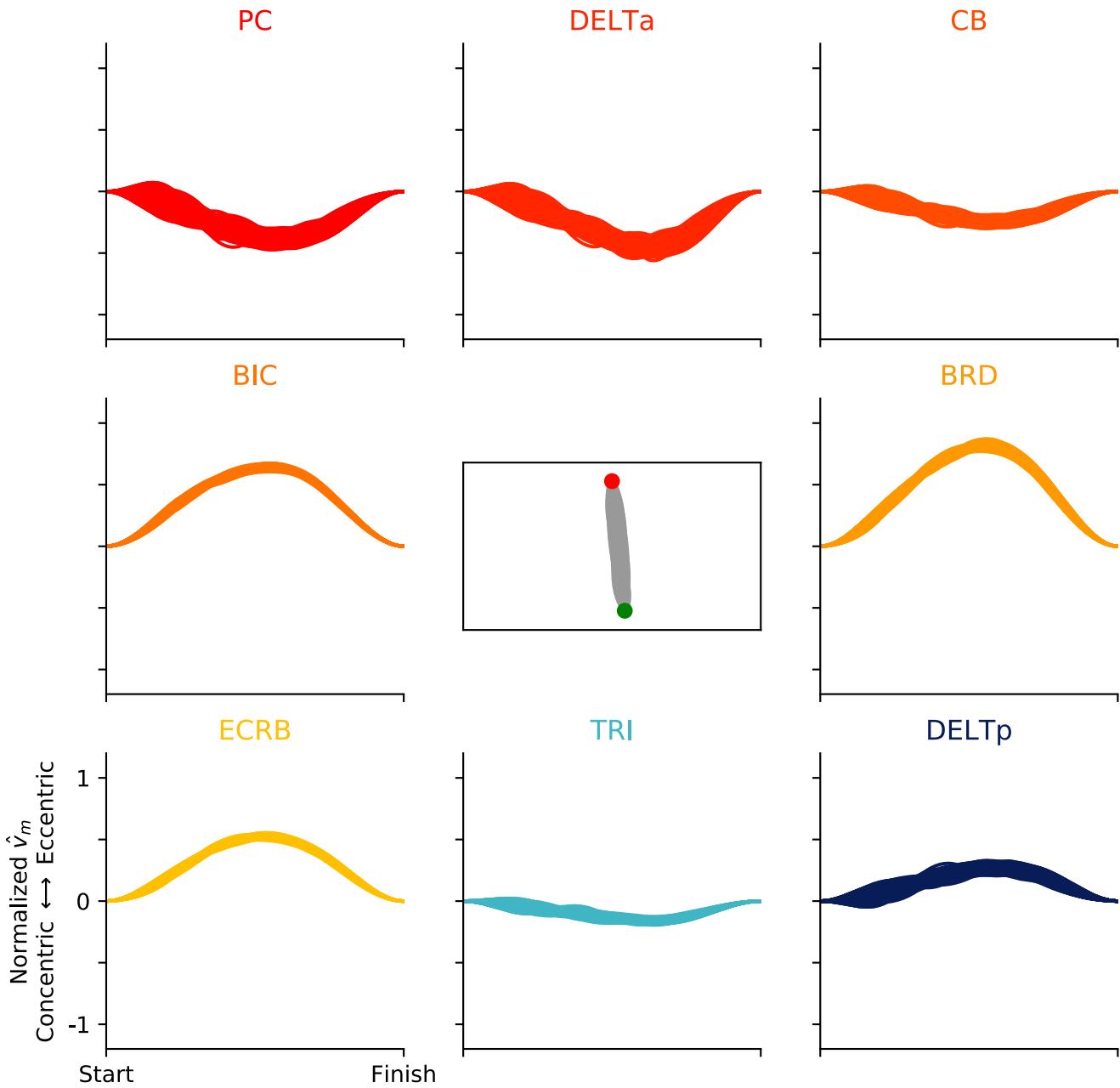
Finish



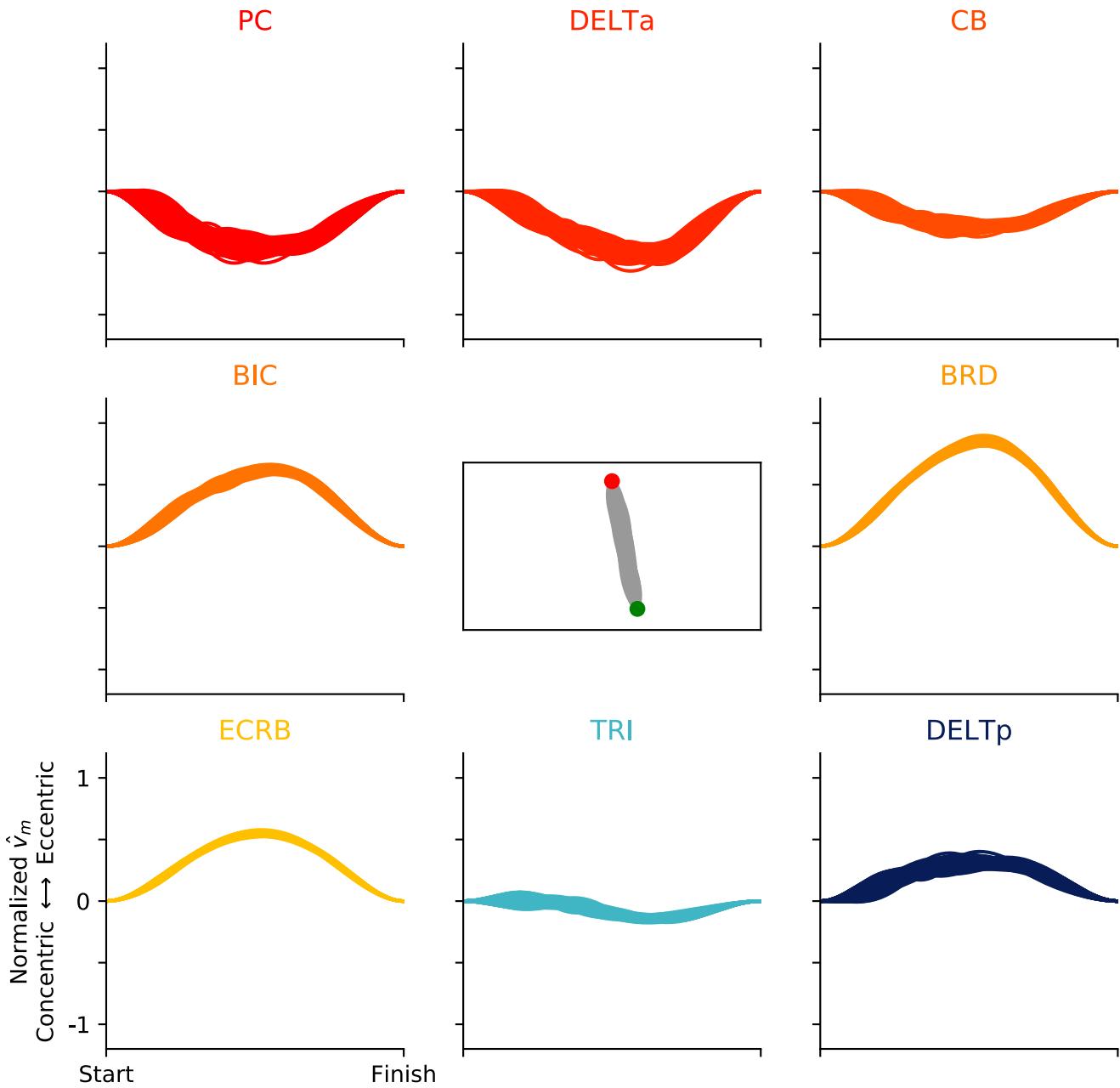
Fixed Final Position
Movement Duration : 1 sec



Fixed Final Position
Movement Duration : 1 sec



Fixed Final Position
Movement Duration : 1 sec



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \hat{V}_m
Concentric \leftrightarrow Eccentric

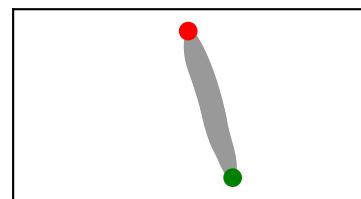
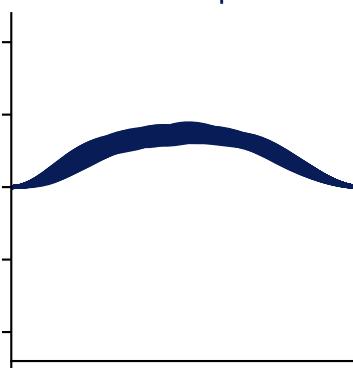
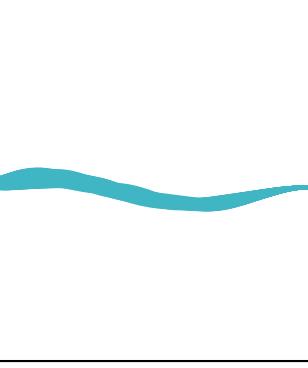
1

0

-1

Start

Finish



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \dot{V}_m
Concentric \leftrightarrow Eccentric

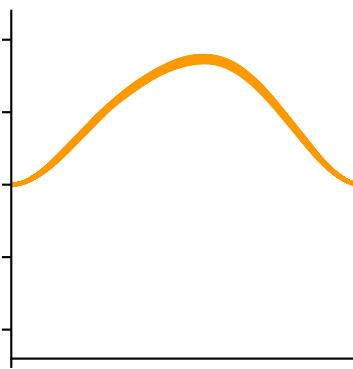
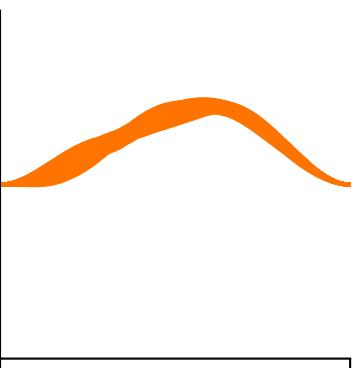
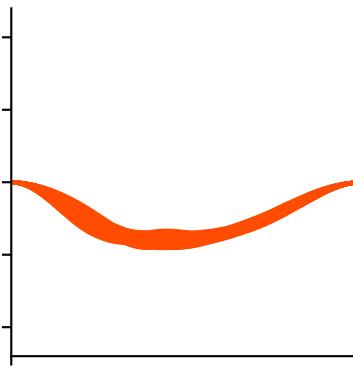
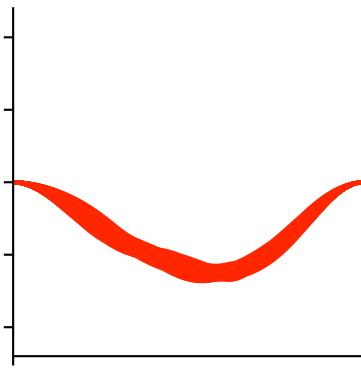
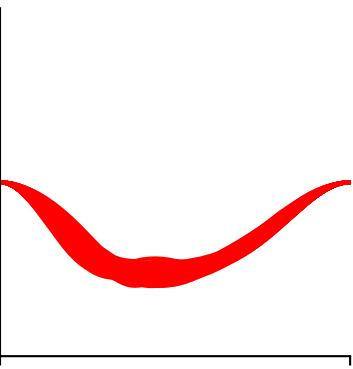
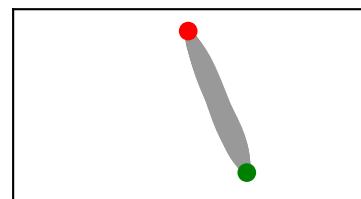
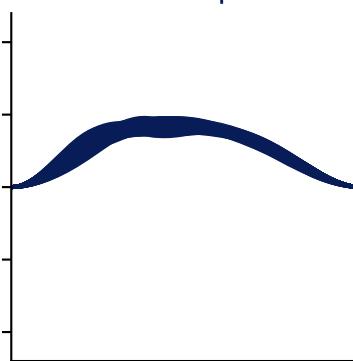
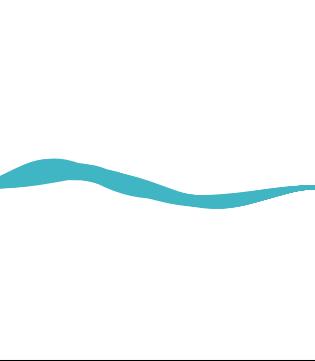
1

0

-1

Start

Finish



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \hat{V}_m
Concentric \leftrightarrow Eccentric

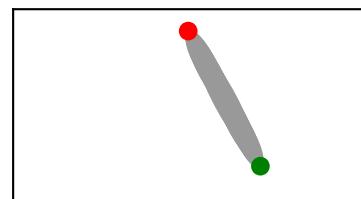
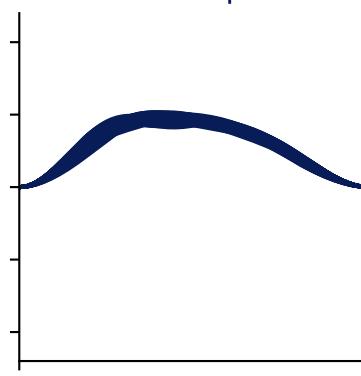
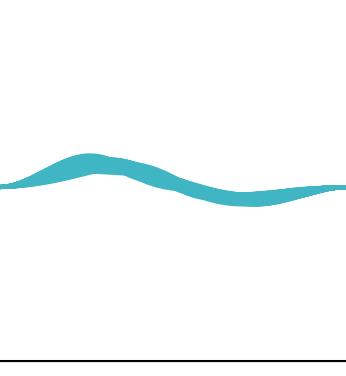
1

0

-1

Start

Finish



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \dot{V}_m
Concentric \leftrightarrow Eccentric

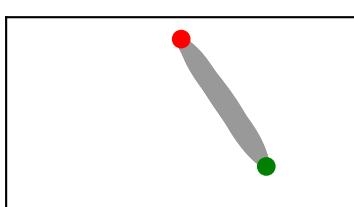
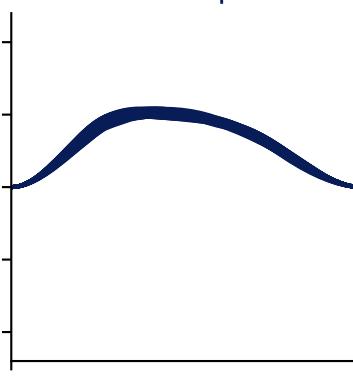
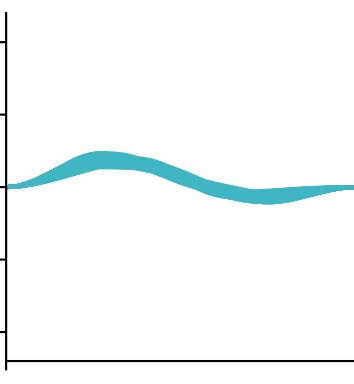
1

0

-1

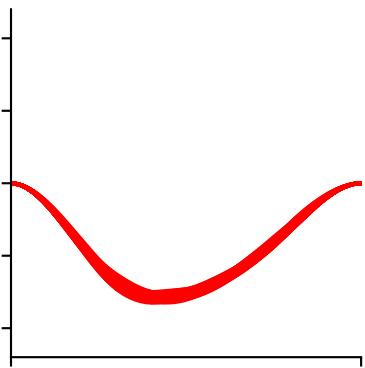
Start

Finish

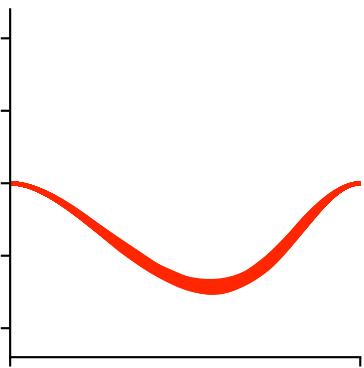


Fixed Final Position
Movement Duration : 1 sec

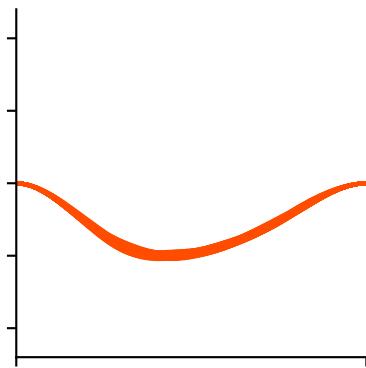
PC



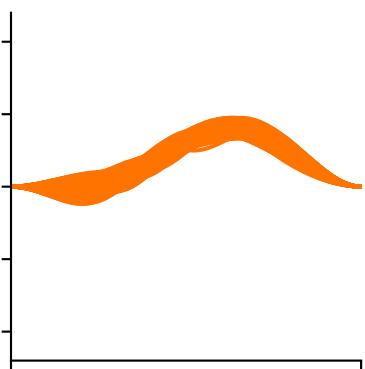
DELTa



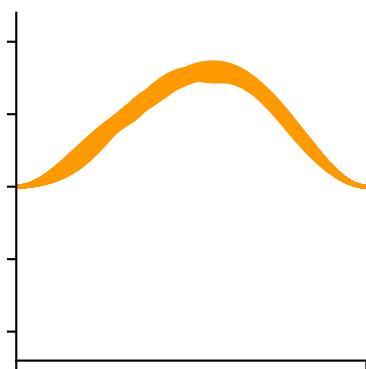
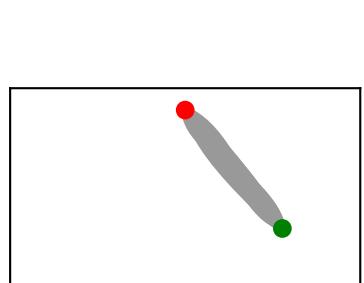
CB



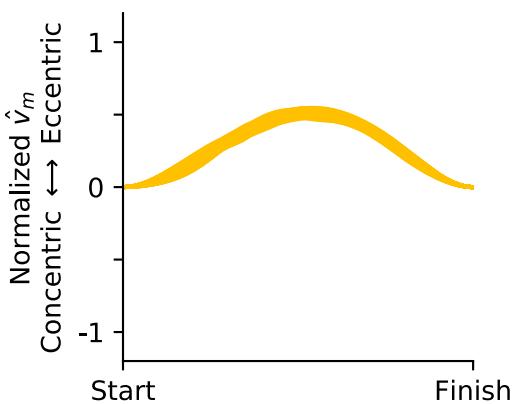
BIC



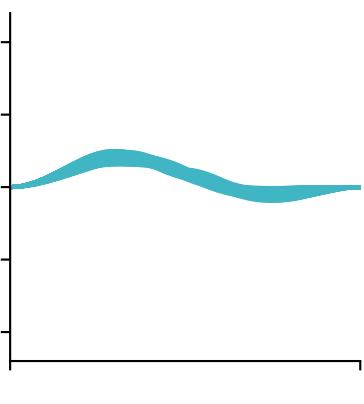
BRD



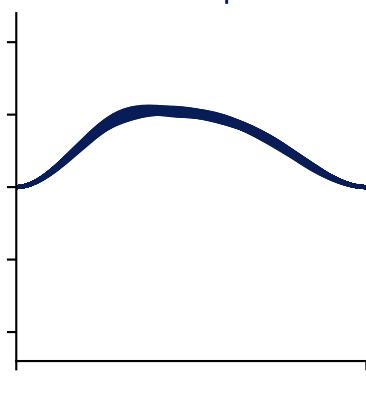
ECRB



TRI



DELTp



Normalized \hat{V}_m → Eccentric

Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \hat{V}_m
Concentric \leftrightarrow Eccentric

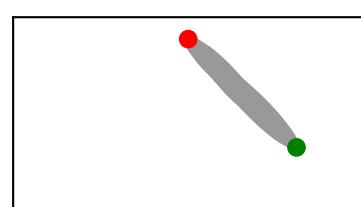
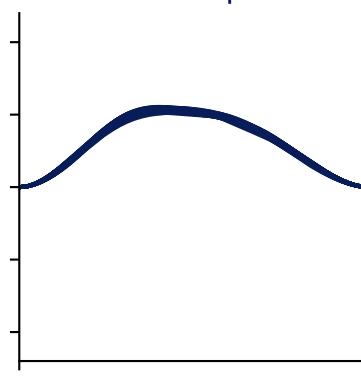
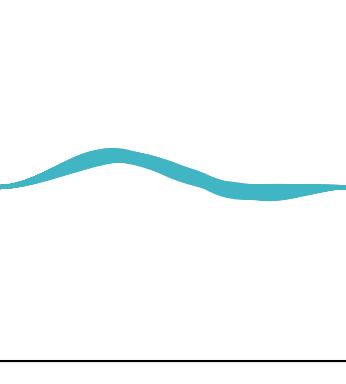
1

0

-1

Start

Finish



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \dot{V}_m
Concentric \rightarrow Eccentric

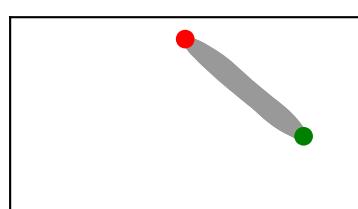
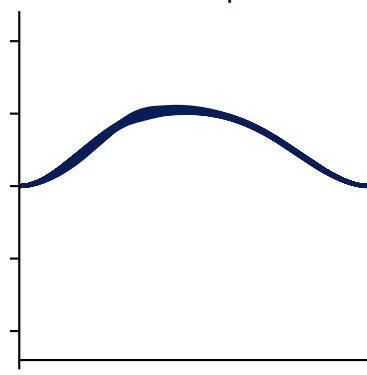
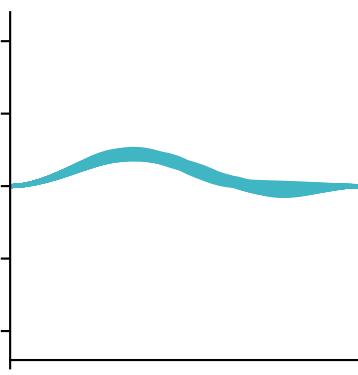
1

0

-1

Start

Finish



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \dot{V}_m
Concentric \rightarrow Eccentric

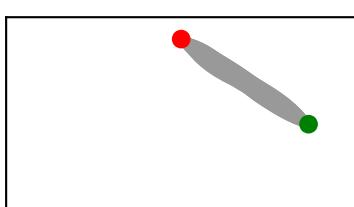
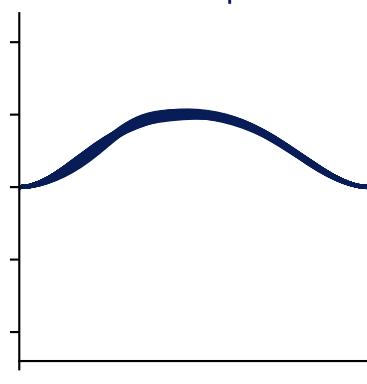
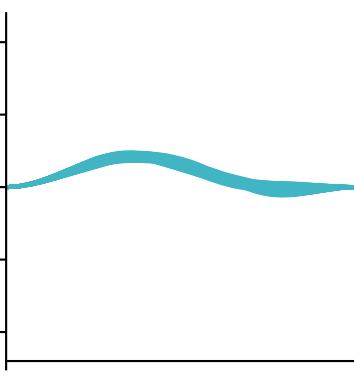
1

0

-1

Start

Finish



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \dot{V}_m
Concentric \rightarrow Eccentric

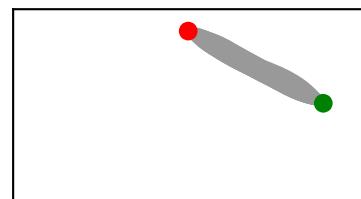
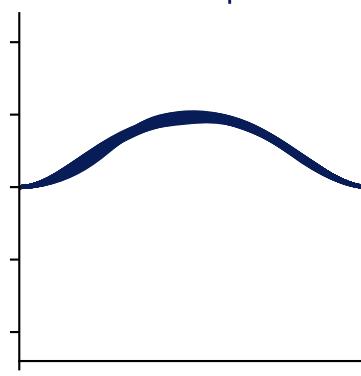
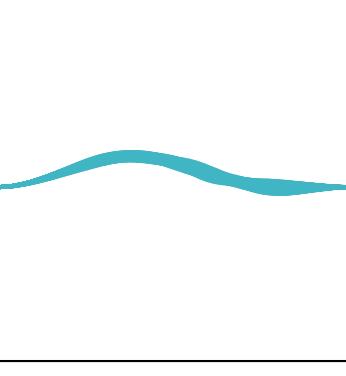
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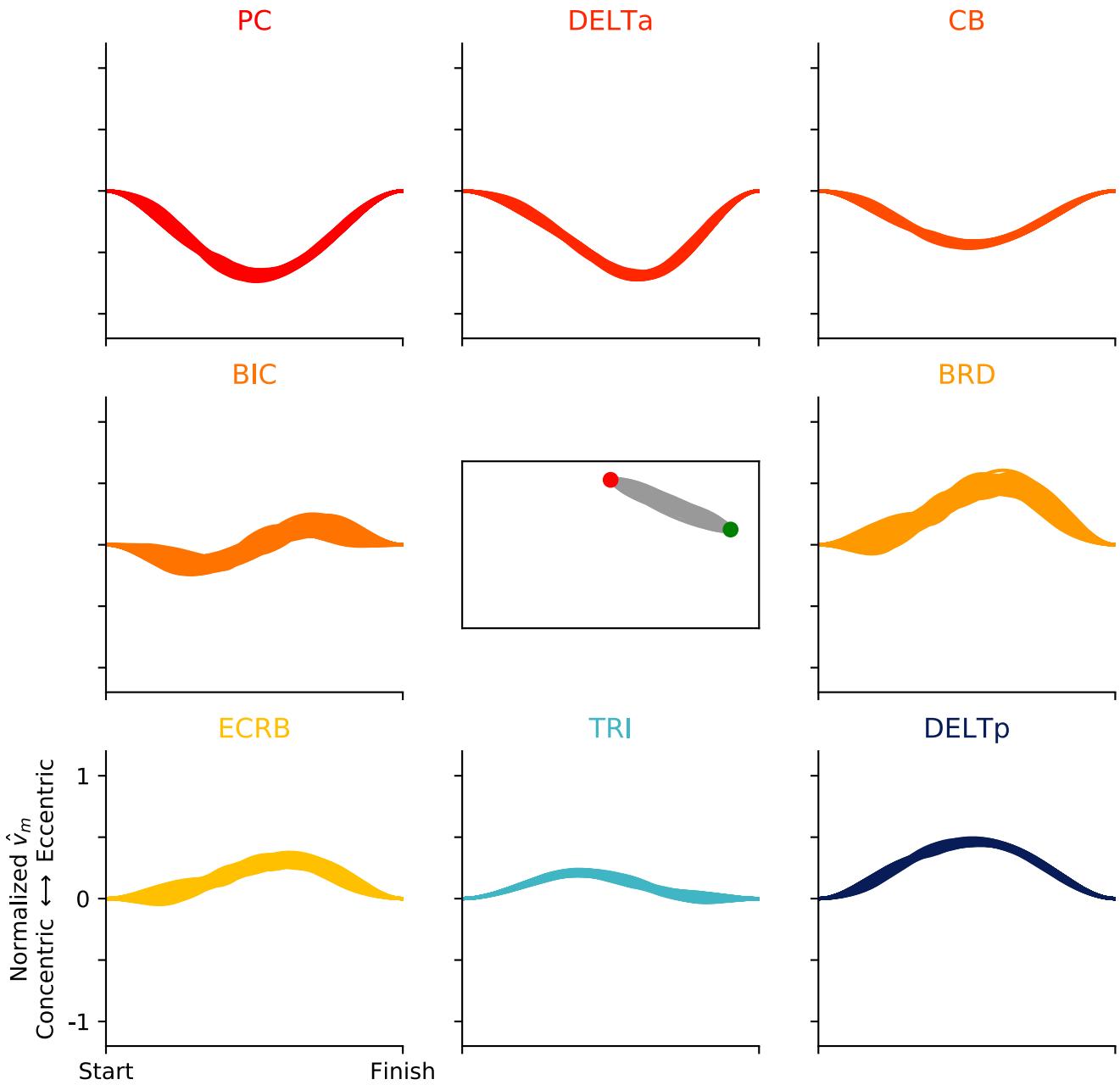
-1

Start

Finish



Fixed Final Position
Movement Duration : 1 sec



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

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TRI

DELTp

Normalized \dot{V}_m → Eccentric

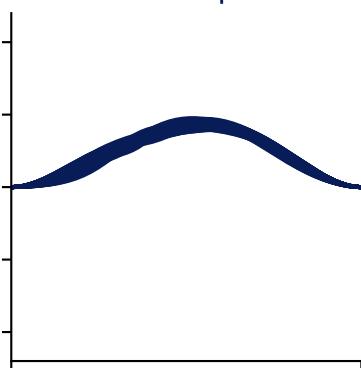
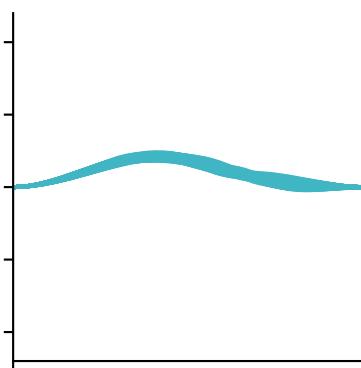
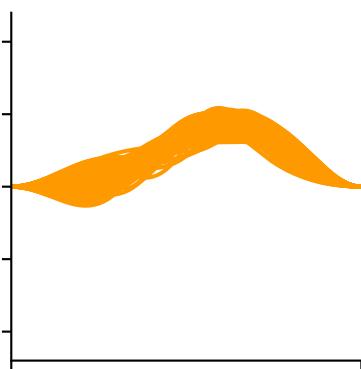
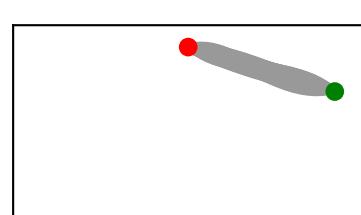
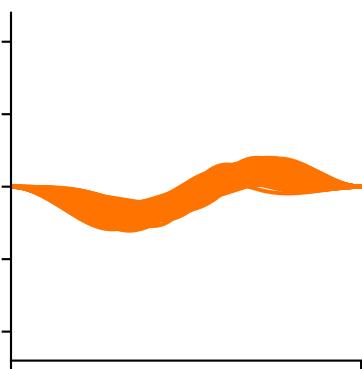
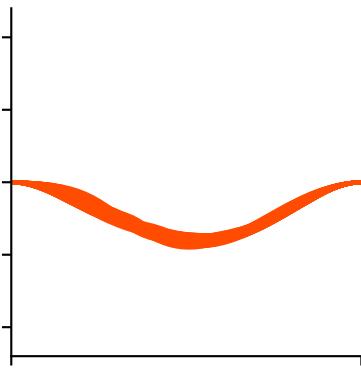
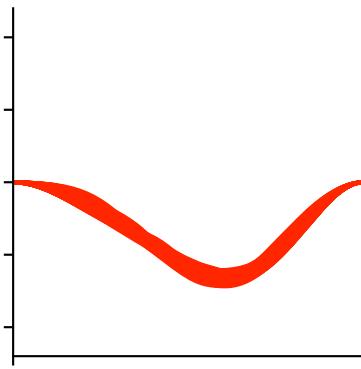
1

0

-1

Start

Finish



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

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Normalized \hat{V}_m
Concentric \rightarrow Eccentric

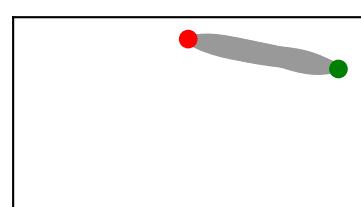
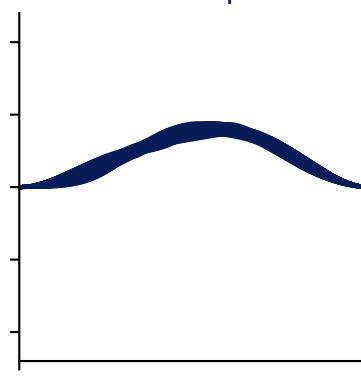
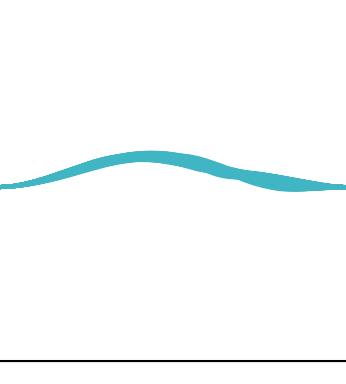
1

0

-1

Start

Finish



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

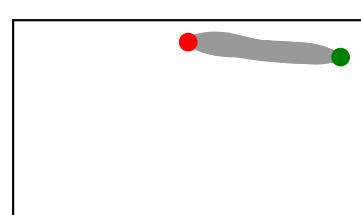
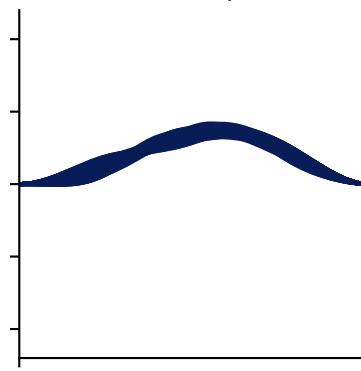
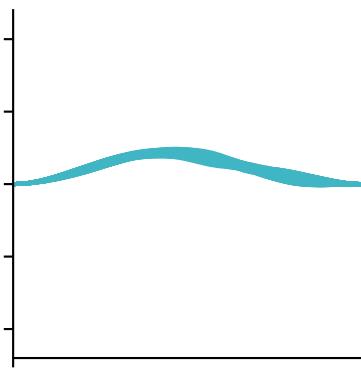
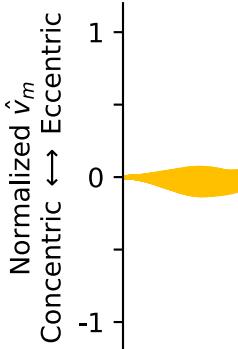
BIC

BRD

ECRB

TRI

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Fixed Final Position
Movement Duration : 1 sec

PC

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1

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