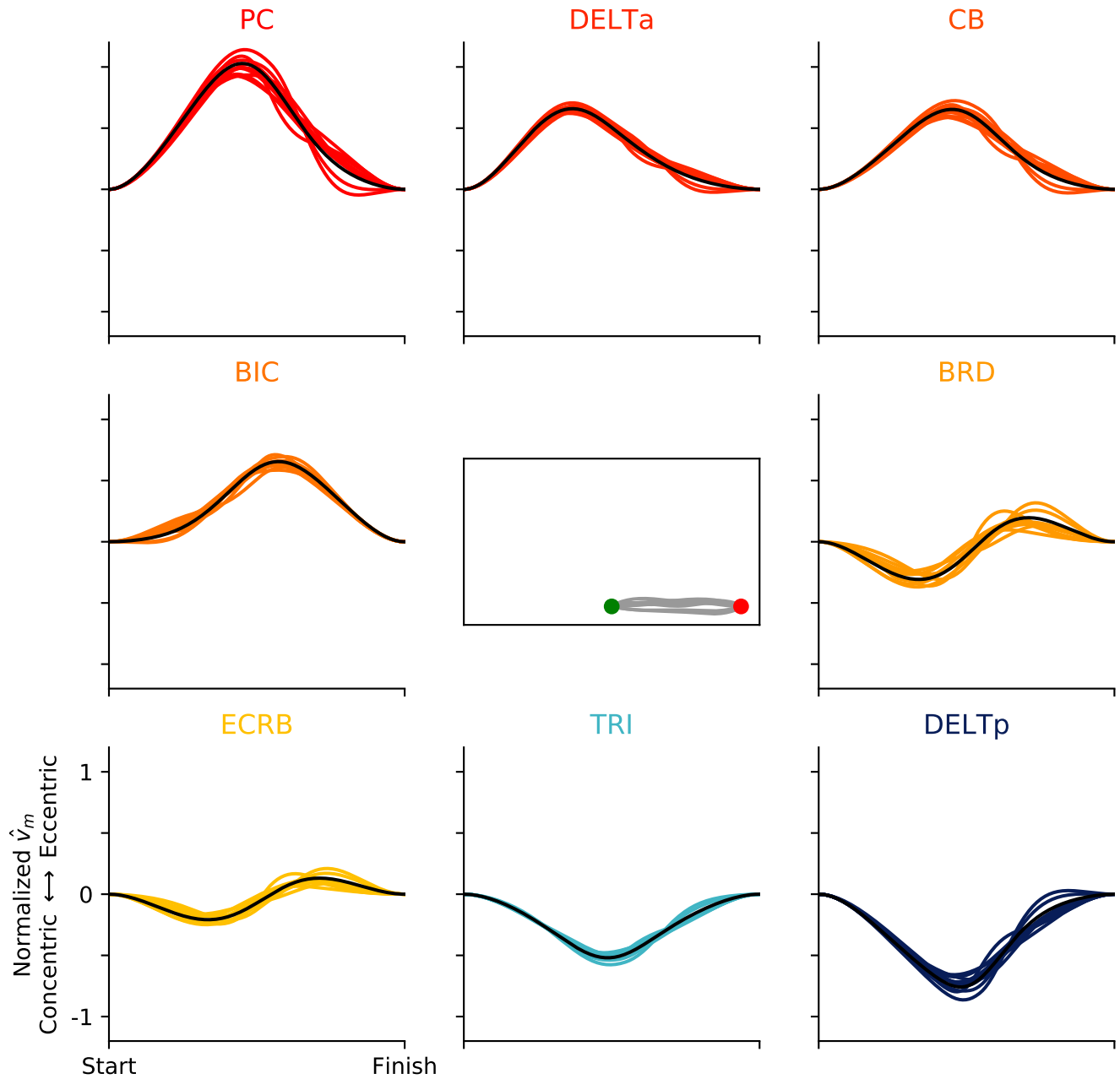
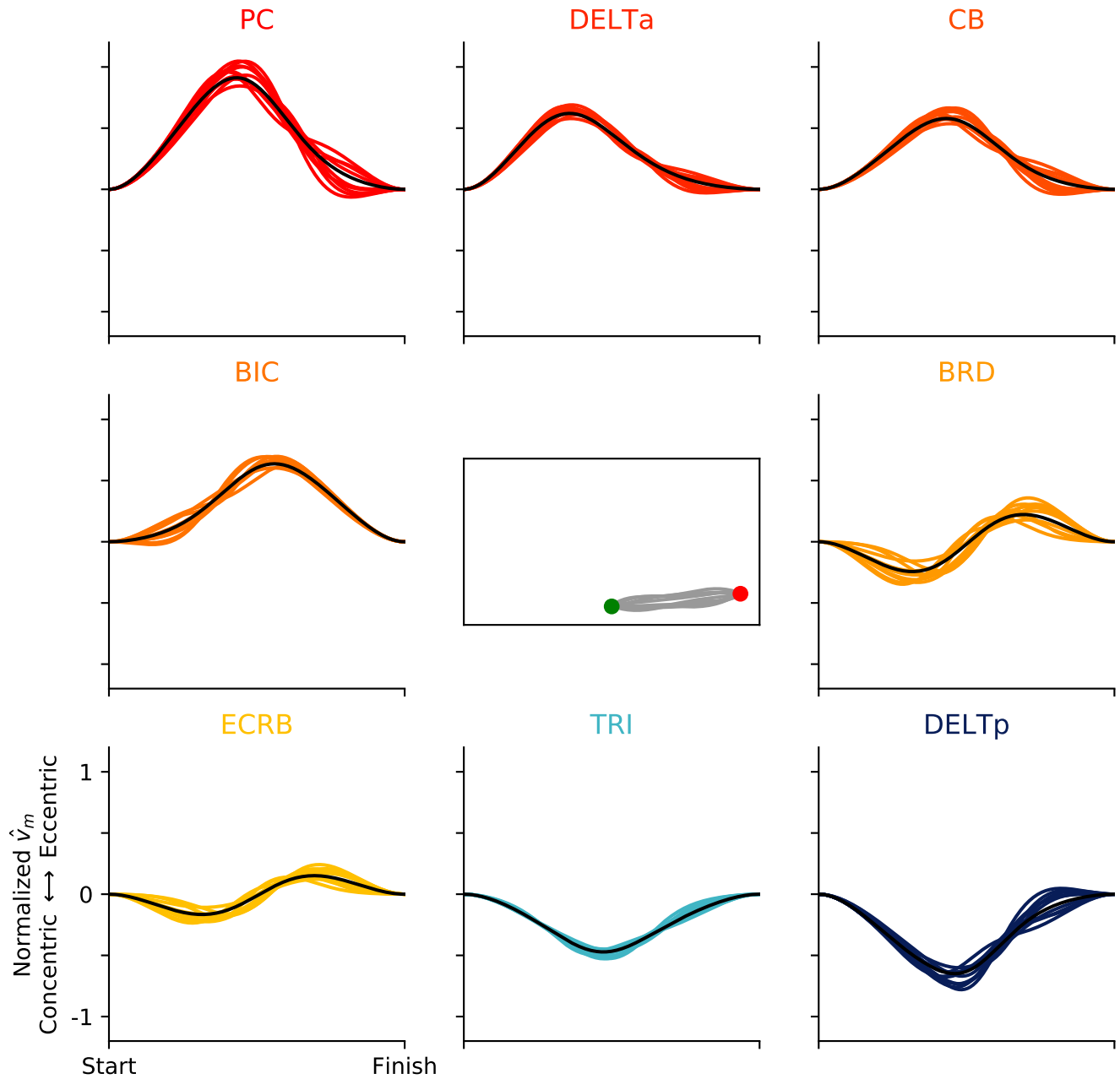


Fixed Initial Position  
Movement Duration : 1 sec

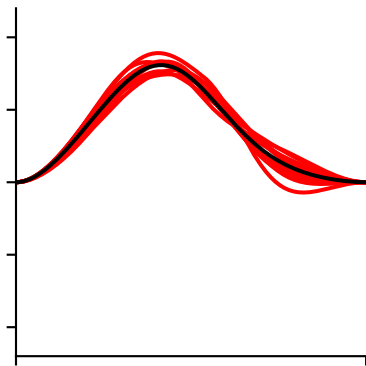


Fixed Initial Position  
Movement Duration : 1 sec

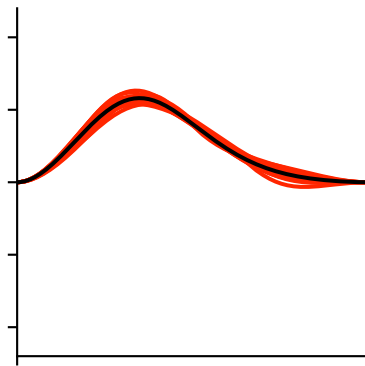


Fixed Initial Position  
Movement Duration : 1 sec

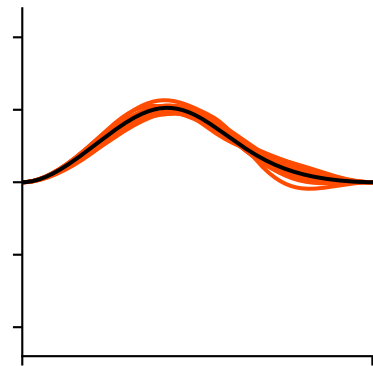
PC



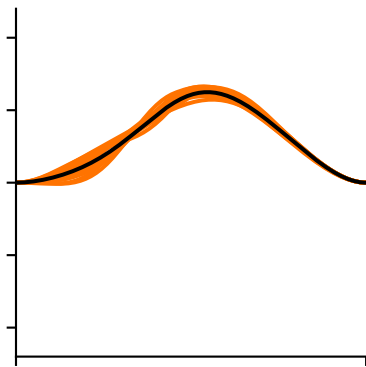
DELTAa



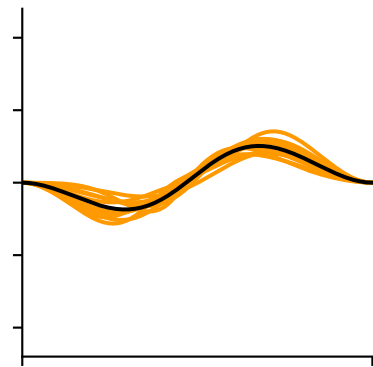
CB



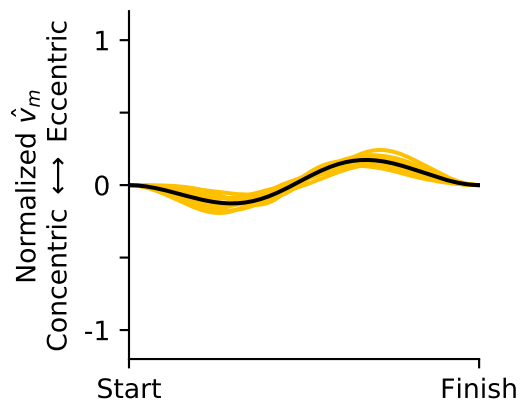
BIC



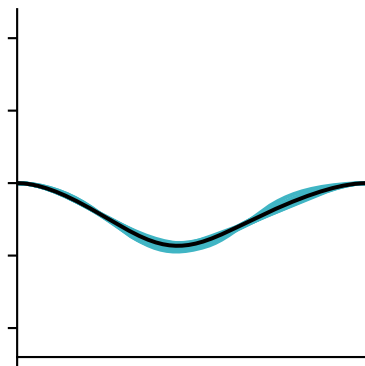
BRD



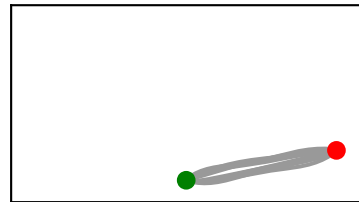
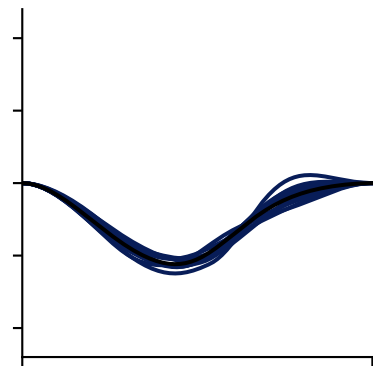
ECRB



TRI

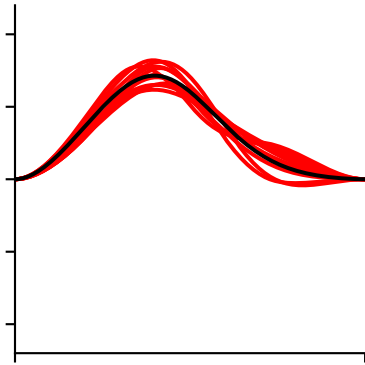


DELTP

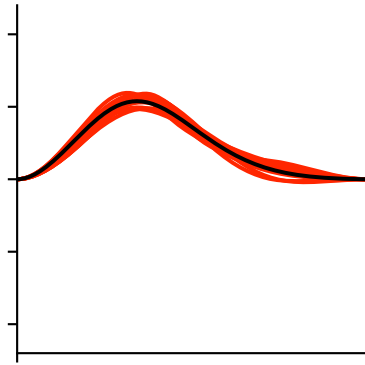


Fixed Initial Position  
Movement Duration : 1 sec

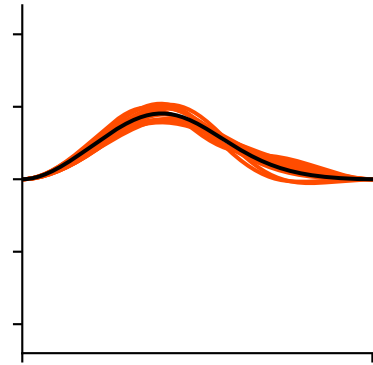
PC



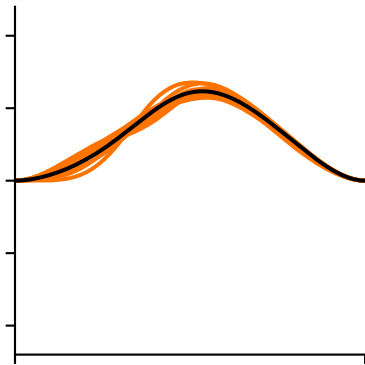
DELTAa



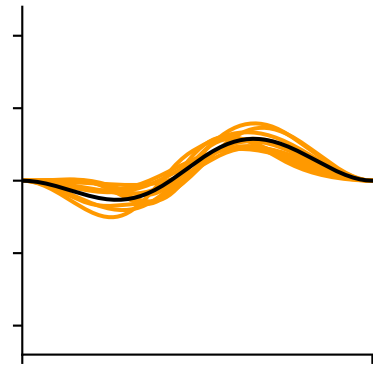
CB



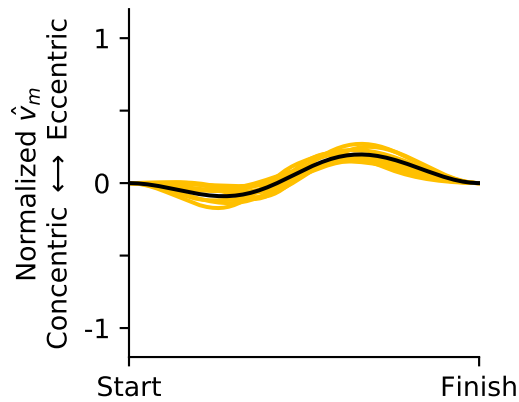
BIC



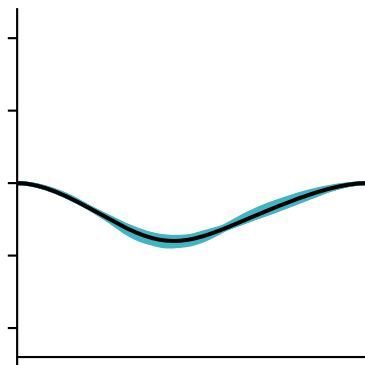
BRD



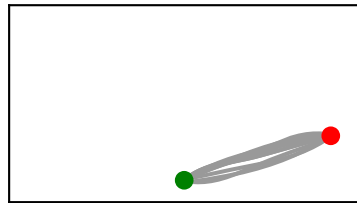
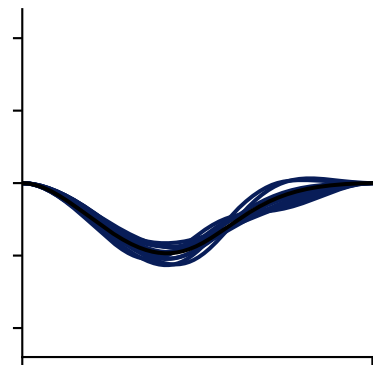
ECRB



TRI

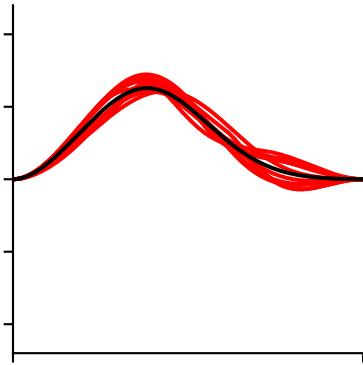


DELTP

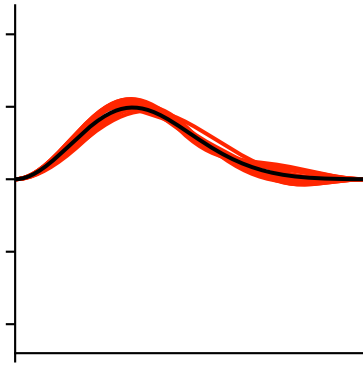


Fixed Initial Position  
Movement Duration : 1 sec

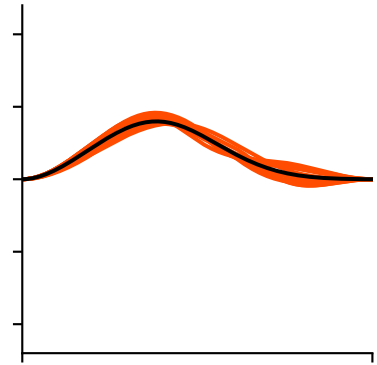
PC



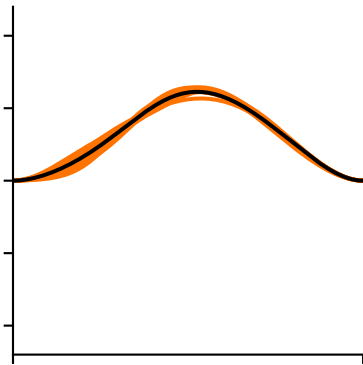
DELTAa



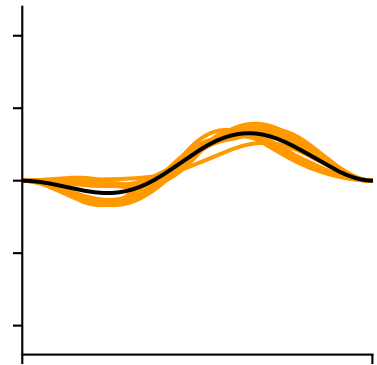
CB



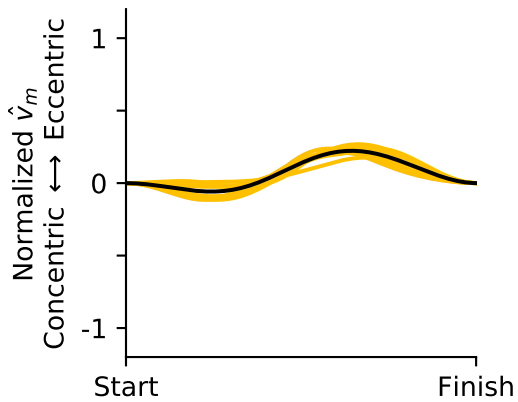
BIC



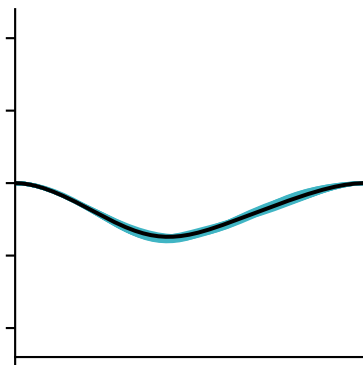
BRD



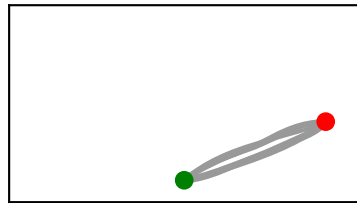
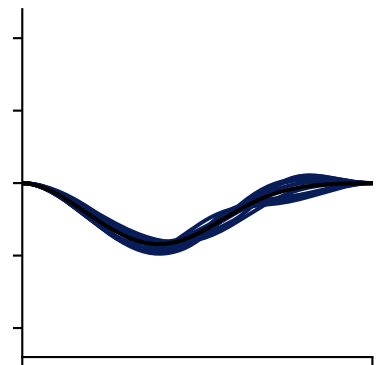
ECRB



TRI

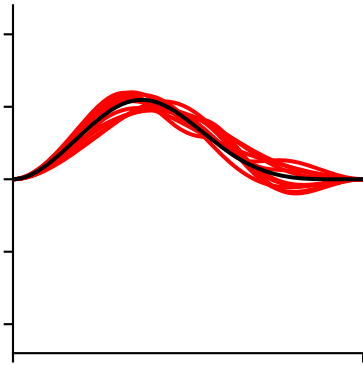


DELTP

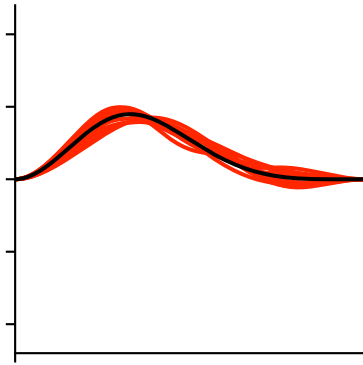


Fixed Initial Position  
Movement Duration : 1 sec

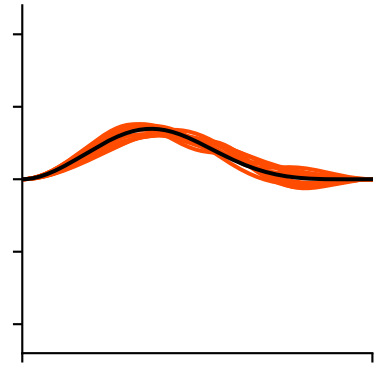
PC



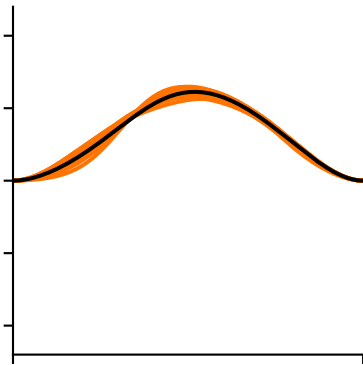
DELTAa



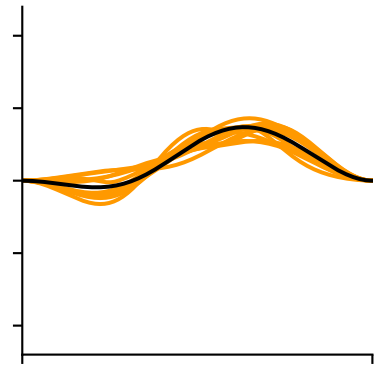
CB



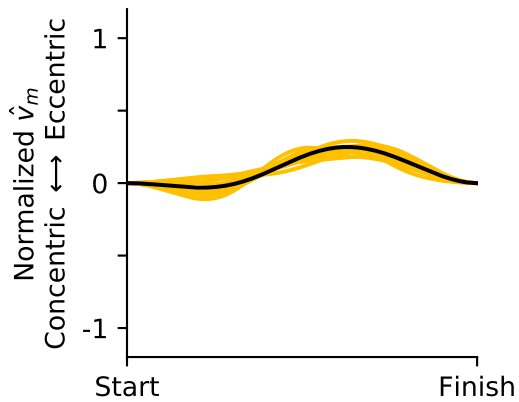
BIC



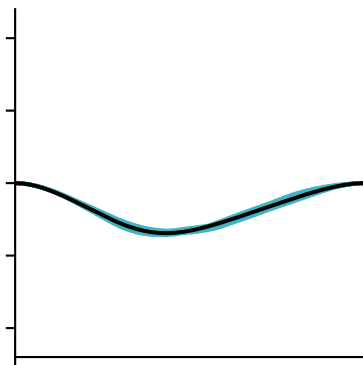
BRD



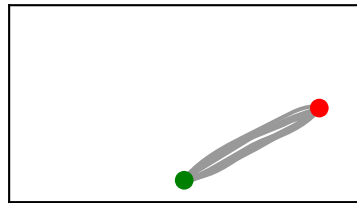
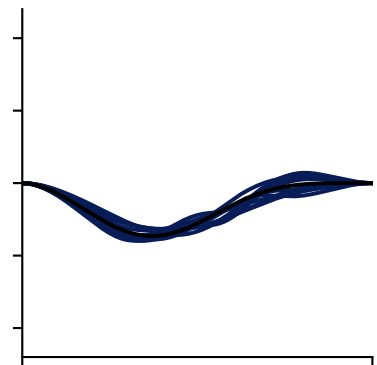
ECRB



TRI

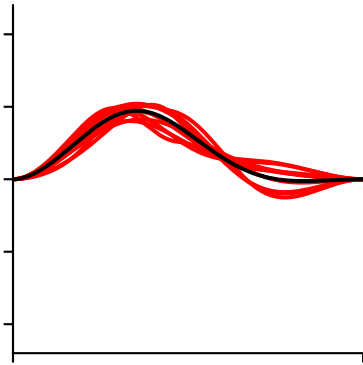


DELTP

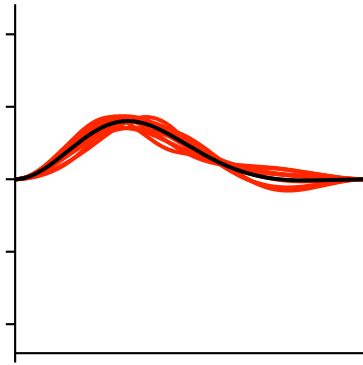


Fixed Initial Position  
Movement Duration : 1 sec

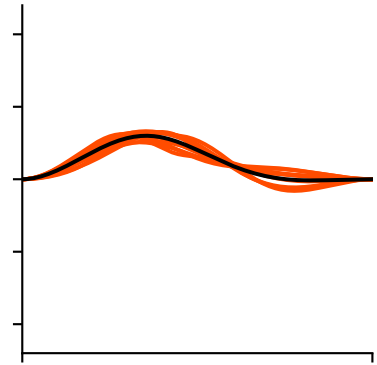
PC



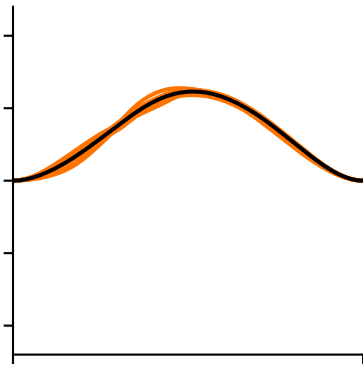
DELTAa



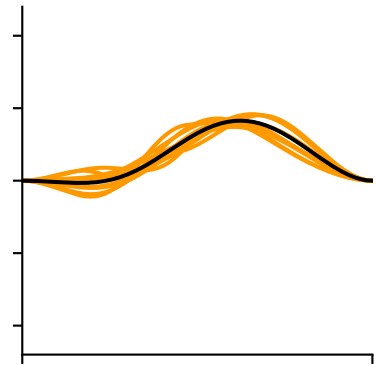
CB



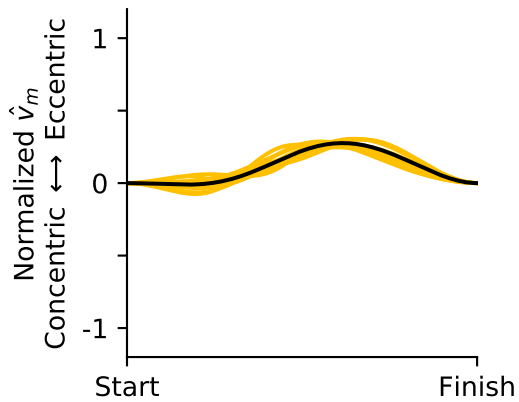
BIC



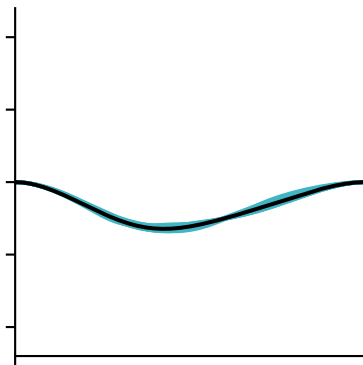
BRD



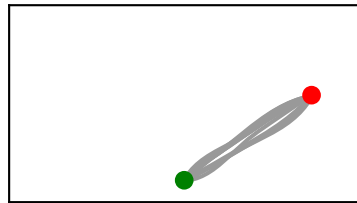
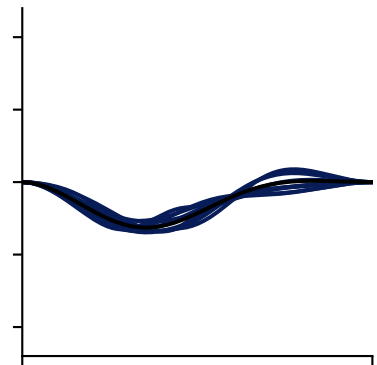
ECRB



TRI

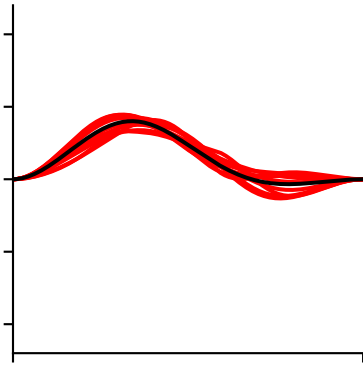


DELTP

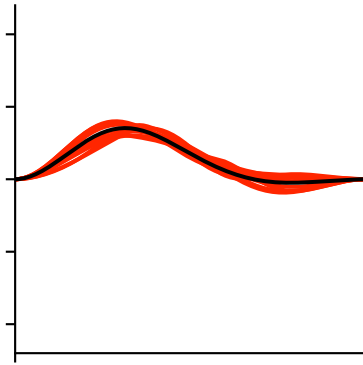


Fixed Initial Position  
Movement Duration : 1 sec

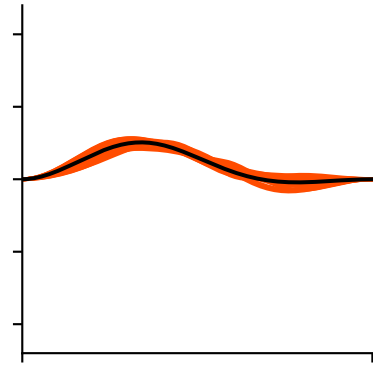
PC



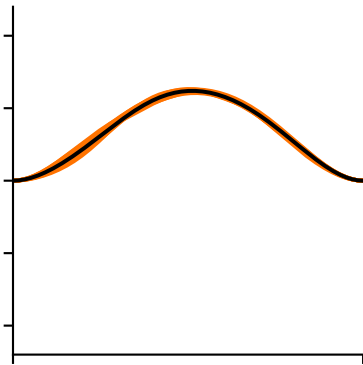
DELTAa



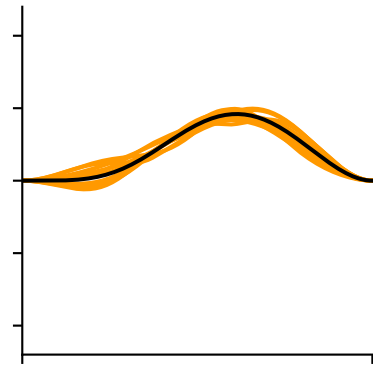
CB



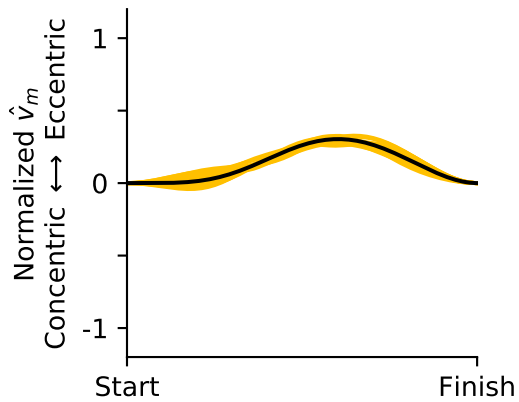
BIC



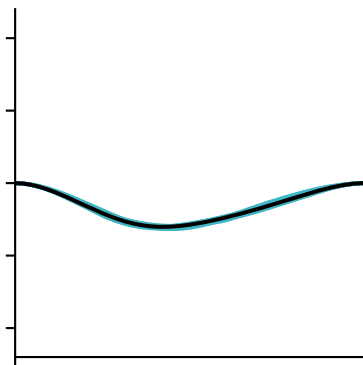
BRD



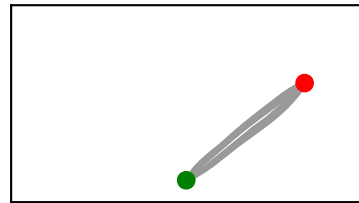
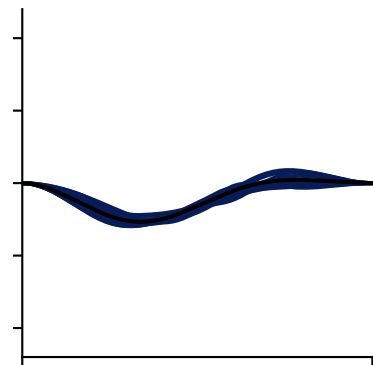
ECRB



TRI



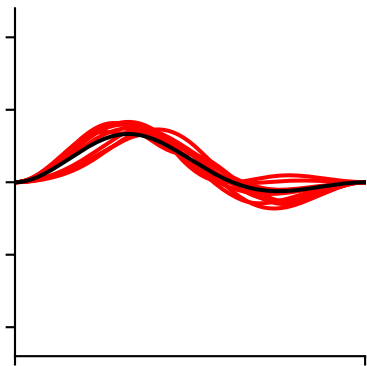
DELTP



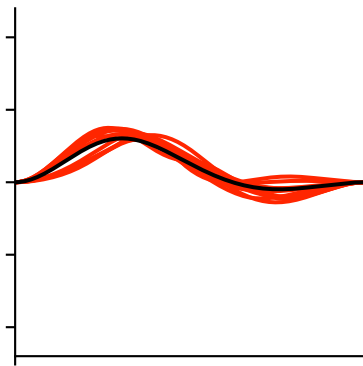


Fixed Initial Position  
Movement Duration : 1 sec

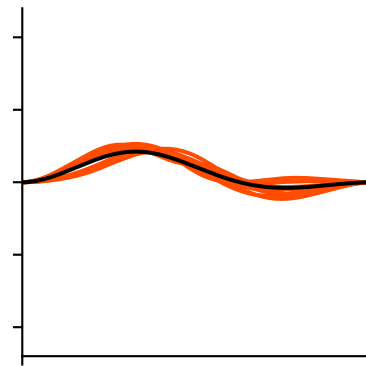
PC



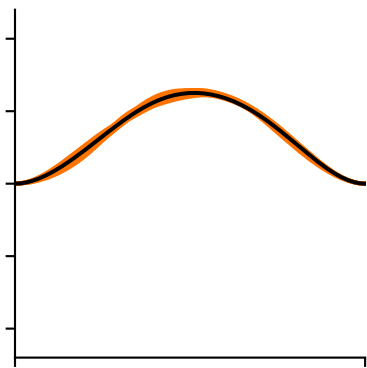
DELTA<sub>a</sub>



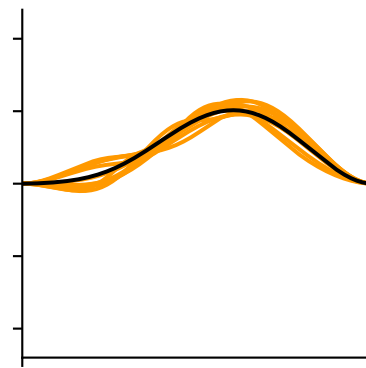
CB



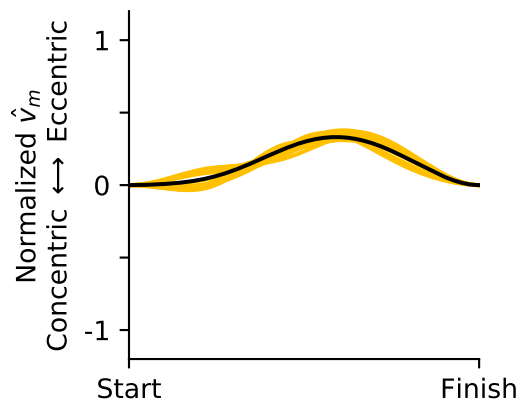
BIC



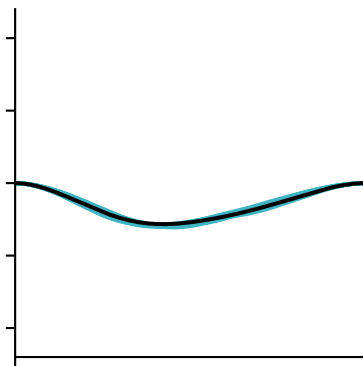
BRD



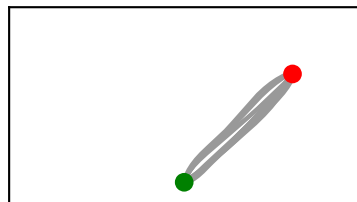
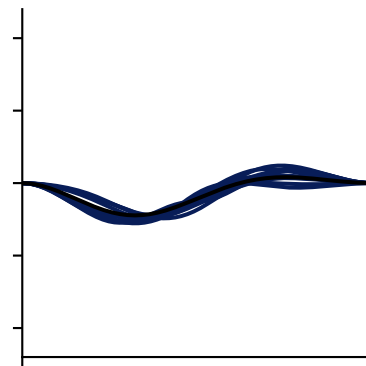
ECRB



TRI

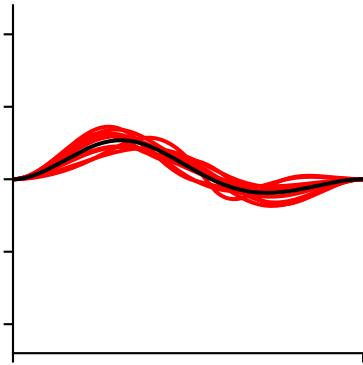


DELTA<sub>p</sub>

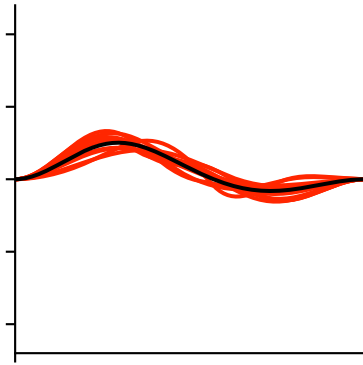


Fixed Initial Position  
Movement Duration : 1 sec

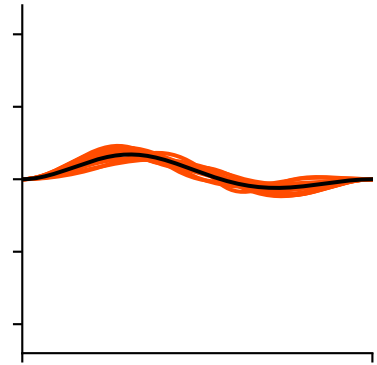
PC



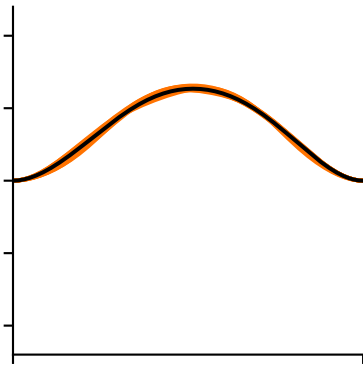
DELTAa



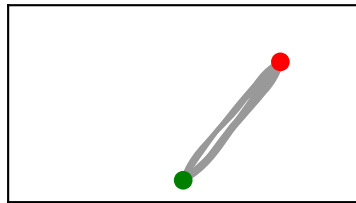
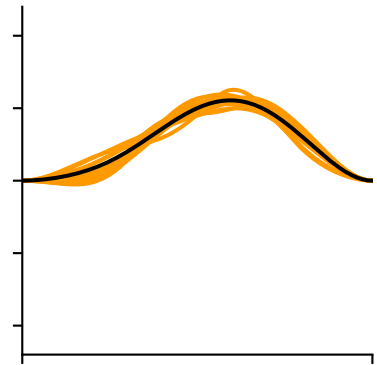
CB



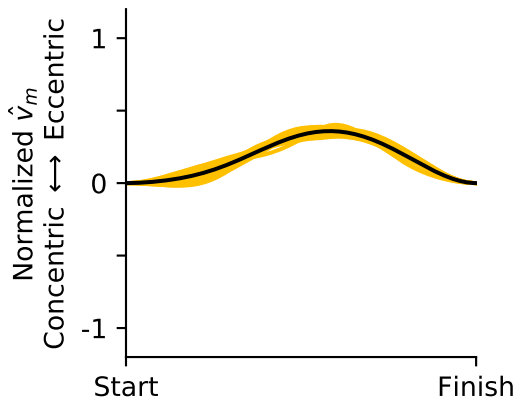
BIC



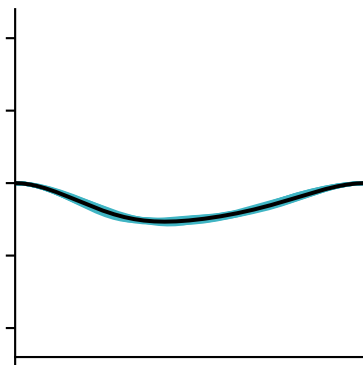
BRD



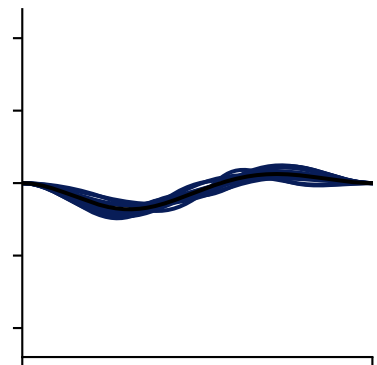
ECRB



TRI



DELTP



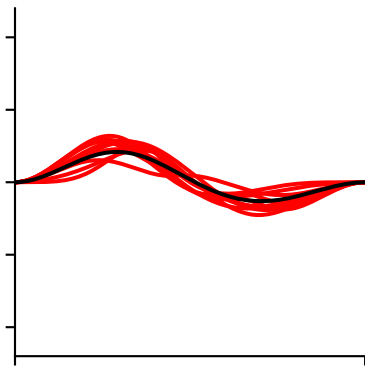
Normalized  $\hat{v}_m$   
Concentric  $\leftrightarrow$  Eccentric

Start

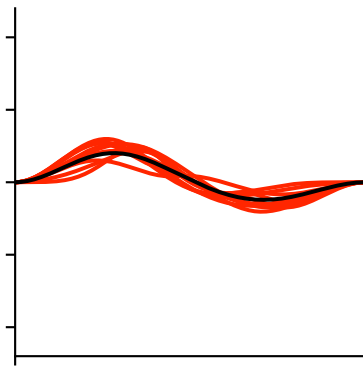
Finish

Fixed Initial Position  
Movement Duration : 1 sec

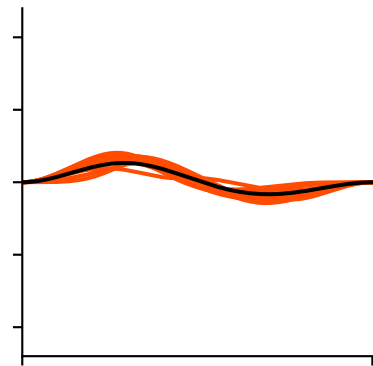
PC



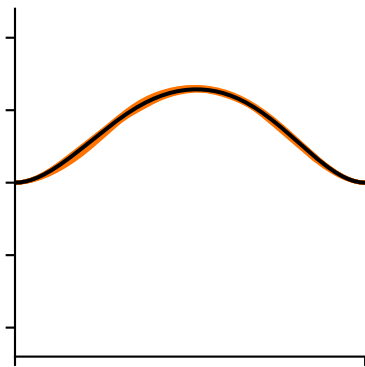
DELTAa



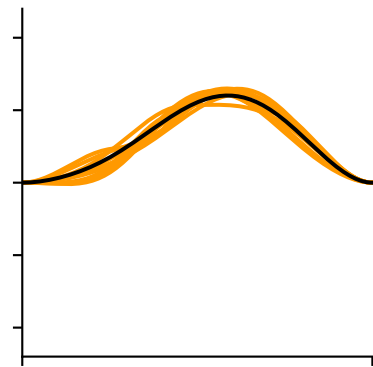
CB



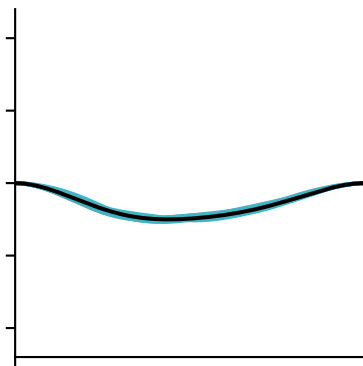
BIC



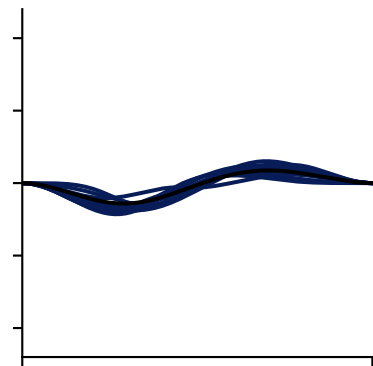
BRD



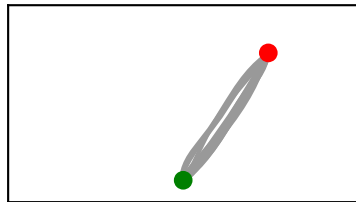
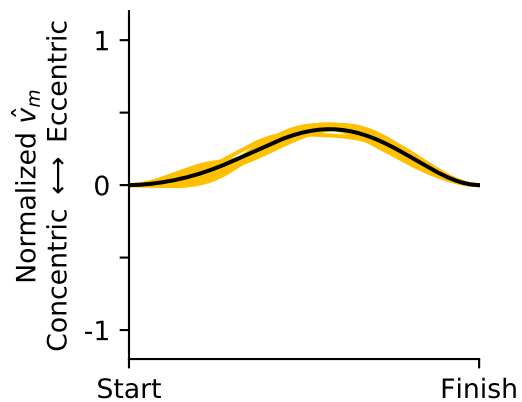
TRI



DELTP

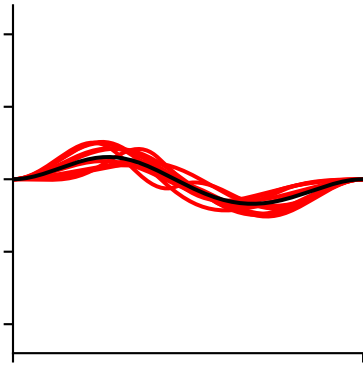


ECRB

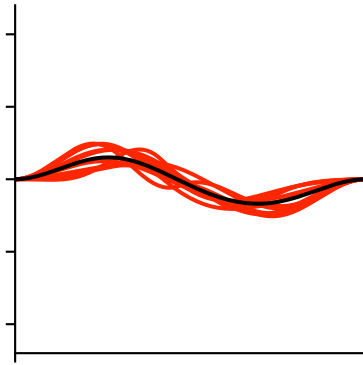


Fixed Initial Position  
Movement Duration : 1 sec

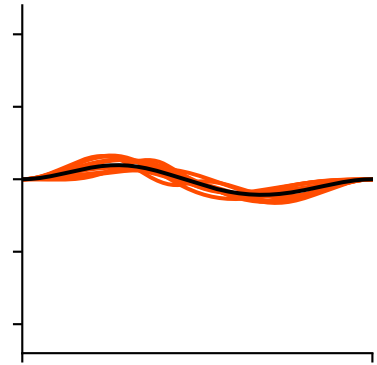
PC



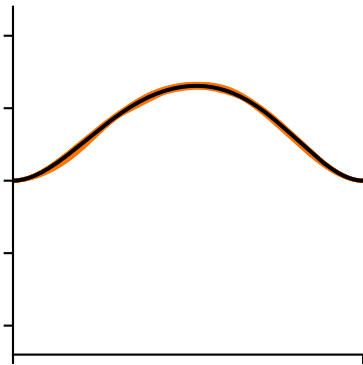
DELTa



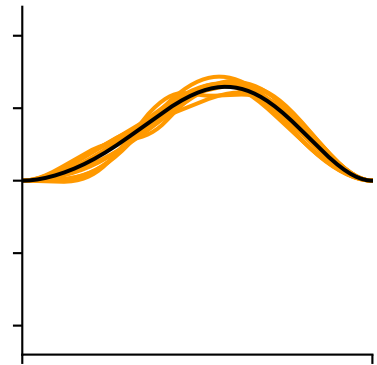
CB



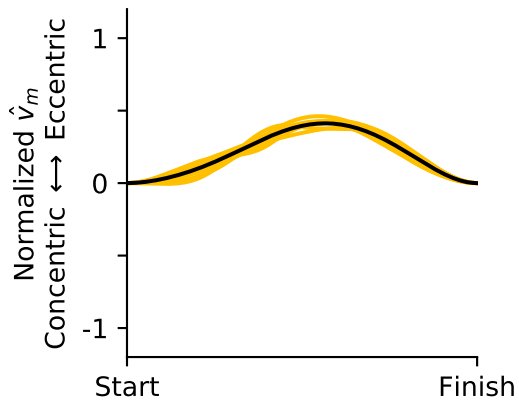
BIC



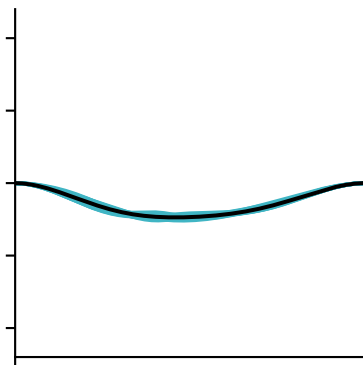
BRD



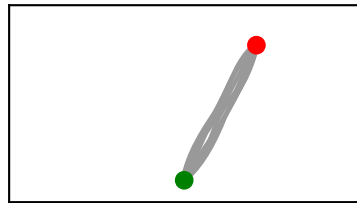
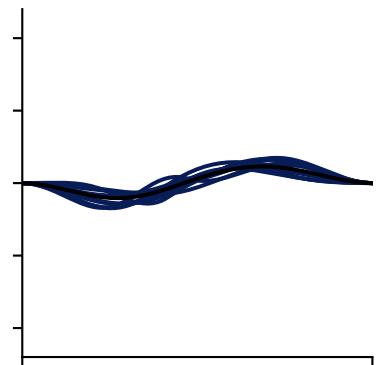
ECRB



TRI

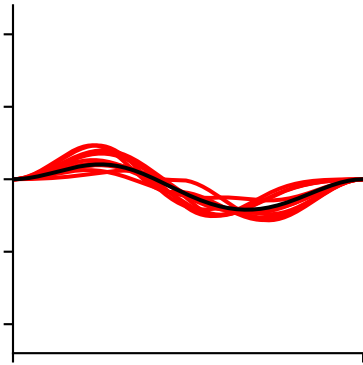


DELTp

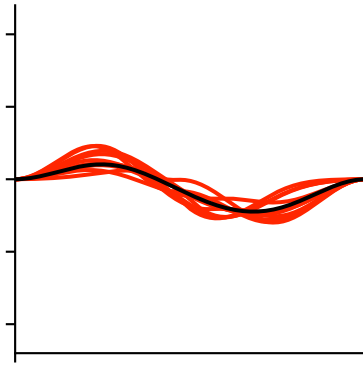


Fixed Initial Position  
Movement Duration : 1 sec

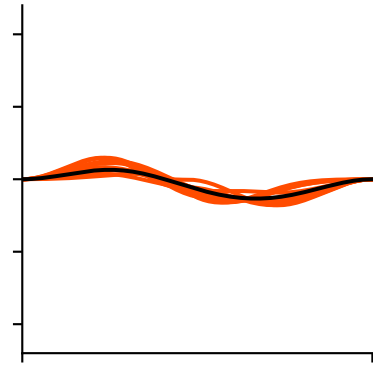
PC



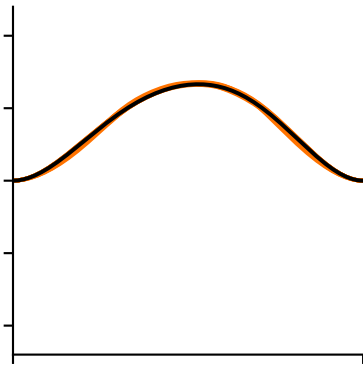
DELTAa



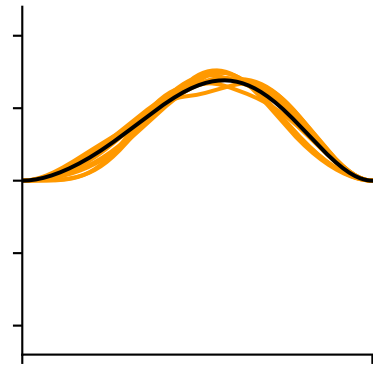
CB



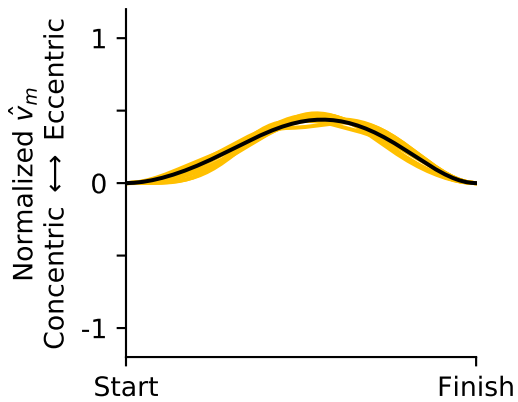
BIC



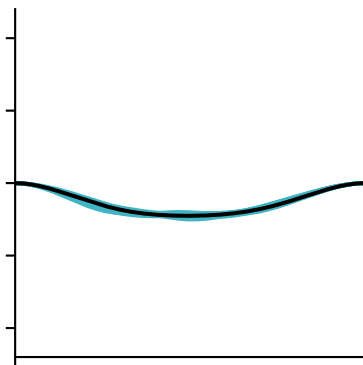
BRD



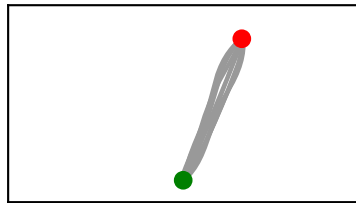
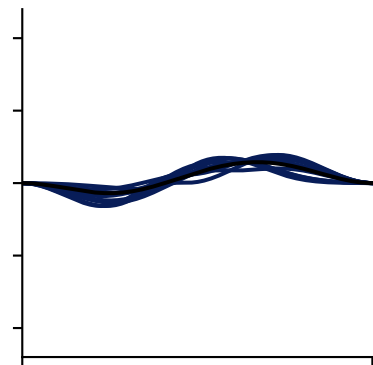
ECRB



TRI

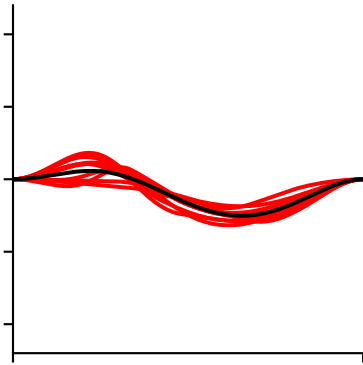


DELTP

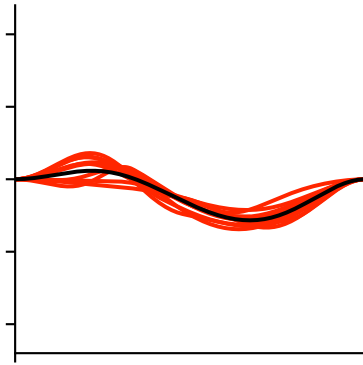


Fixed Initial Position  
Movement Duration : 1 sec

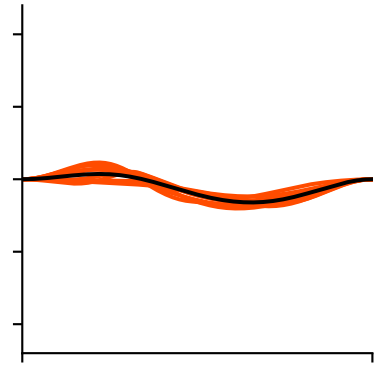
PC



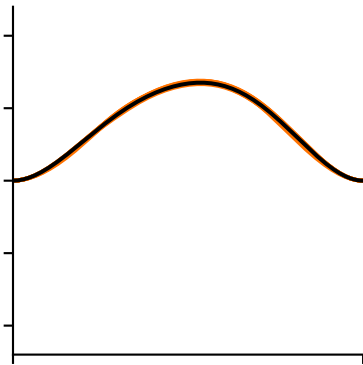
DELTa



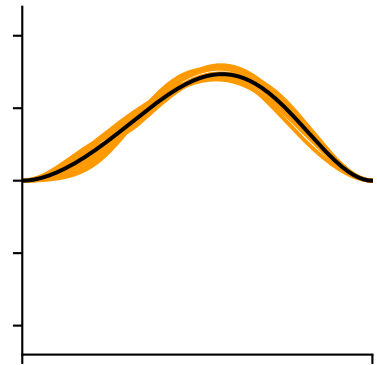
CB



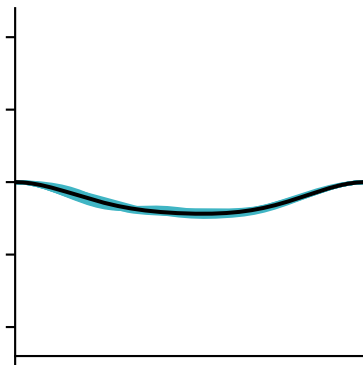
BIC



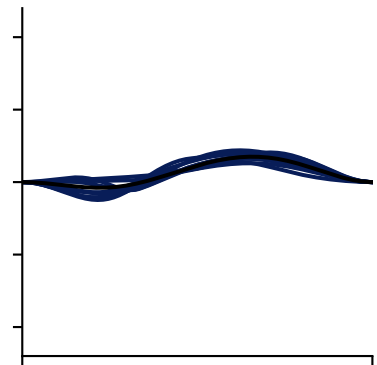
BRD



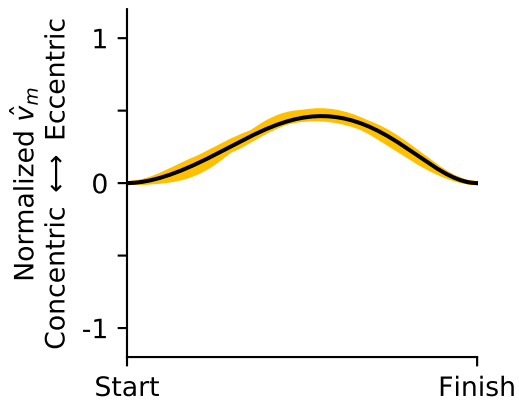
TRI



DELTp

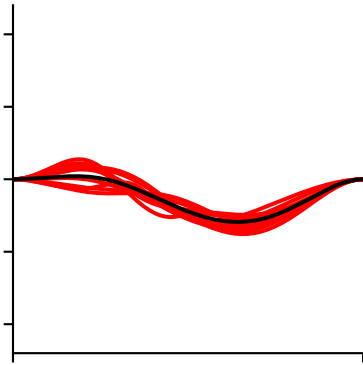


ECRB

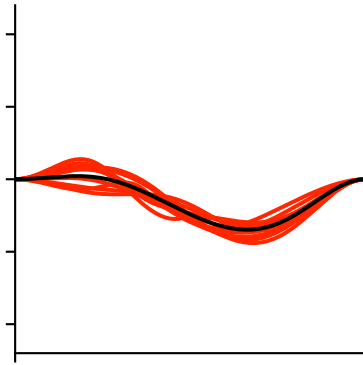


Fixed Initial Position  
Movement Duration : 1 sec

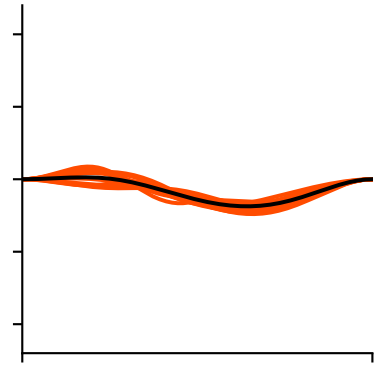
PC



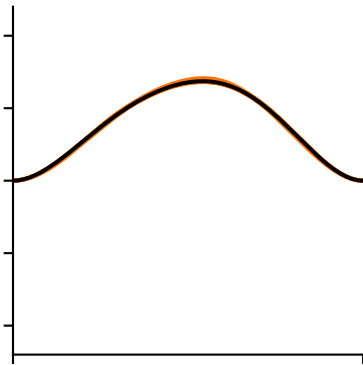
DELTAa



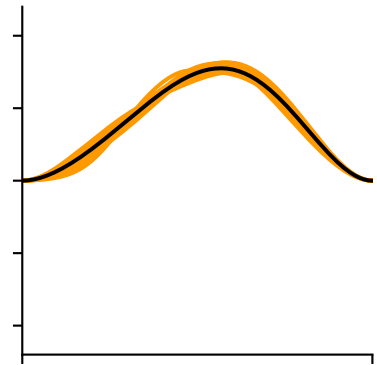
CB



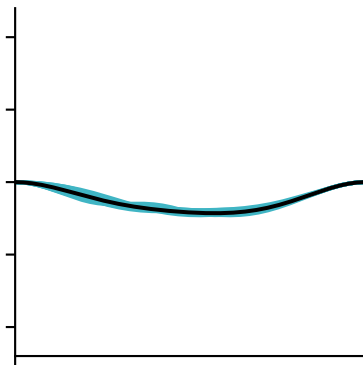
BIC



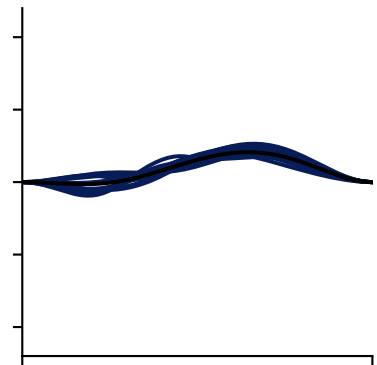
BRD



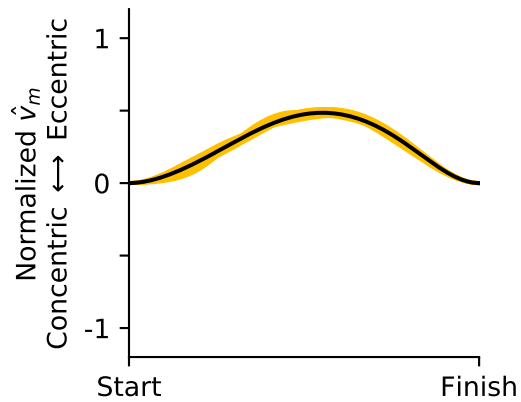
TRI



DELTP

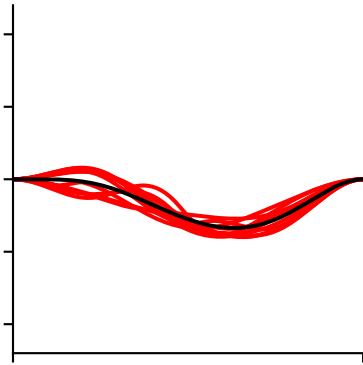


ECRB

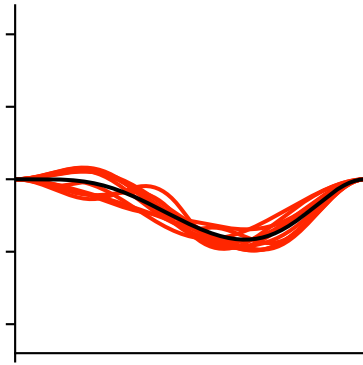


Fixed Initial Position  
Movement Duration : 1 sec

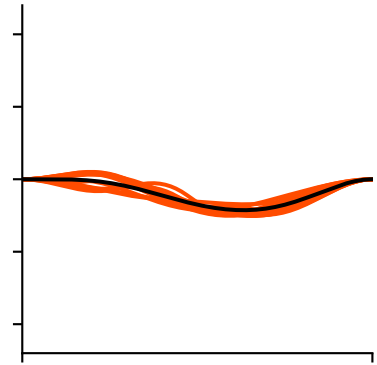
PC



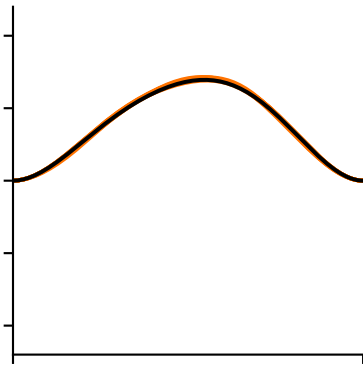
DELTAa



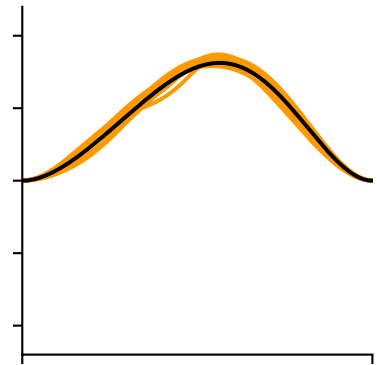
CB



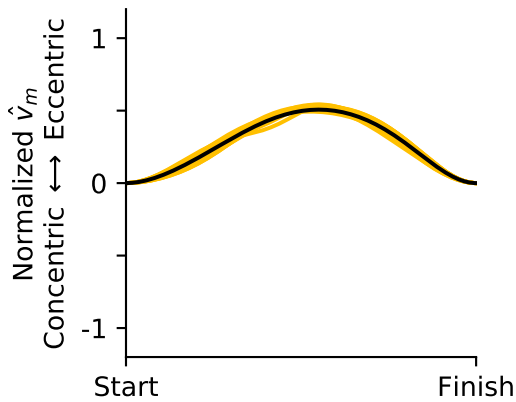
BIC



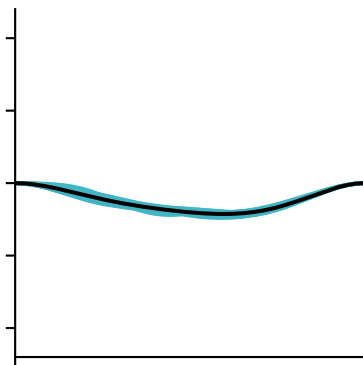
BRD



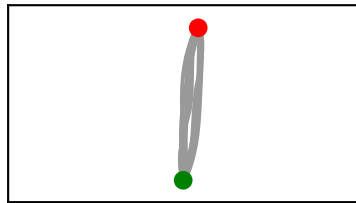
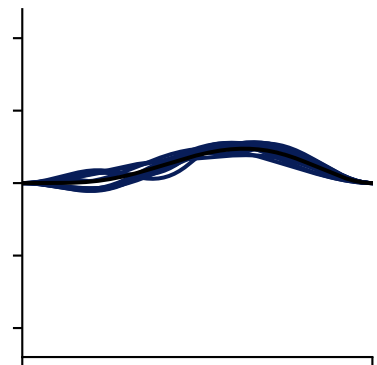
ECRB



TRI



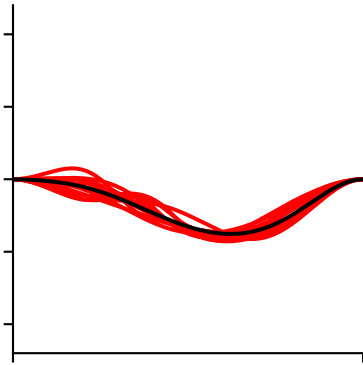
DELTP



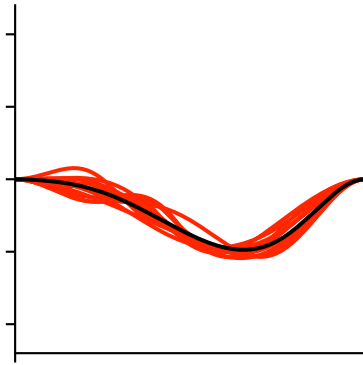


Fixed Initial Position  
Movement Duration : 1 sec

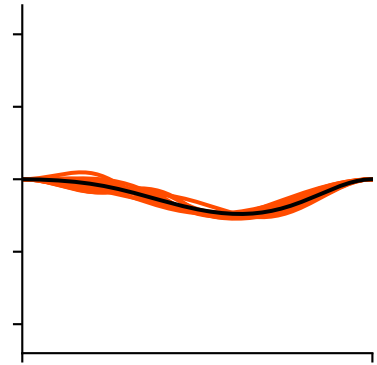
PC



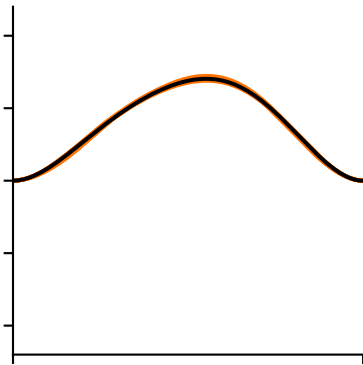
DELTAa



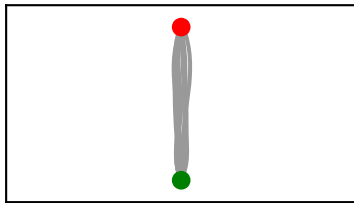
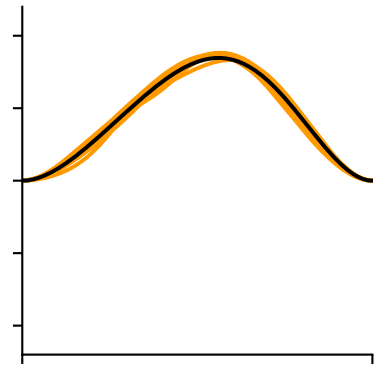
CB



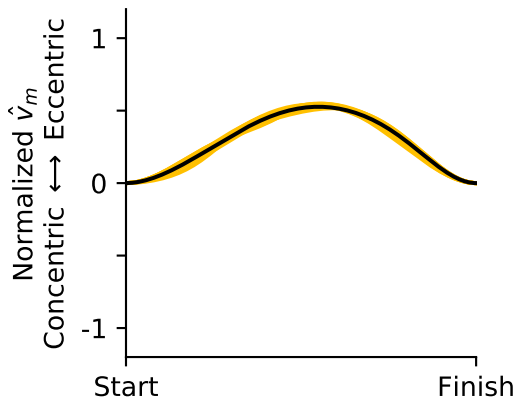
BIC



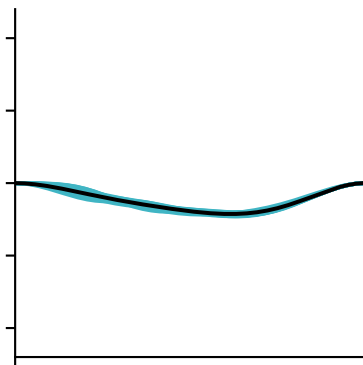
BRD



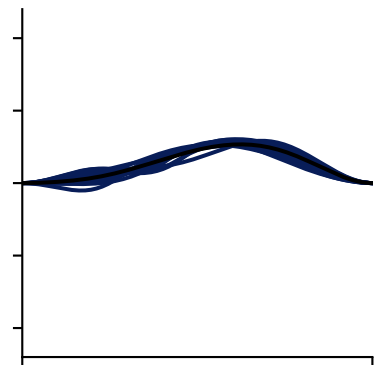
ECRB



TRI

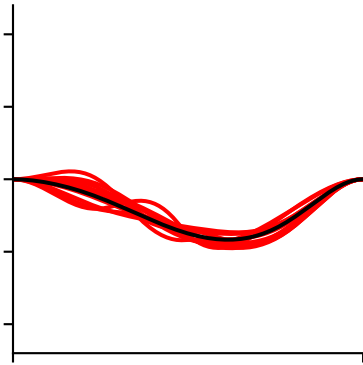


DELTP

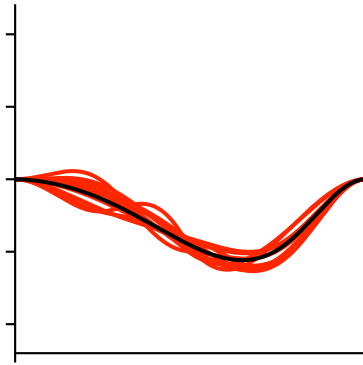


Fixed Initial Position  
Movement Duration : 1 sec

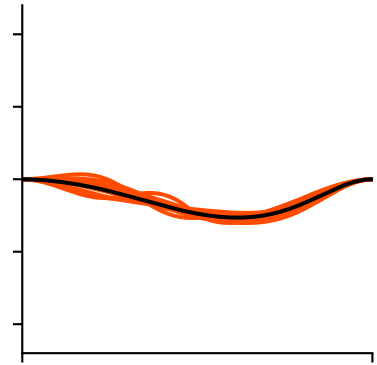
PC



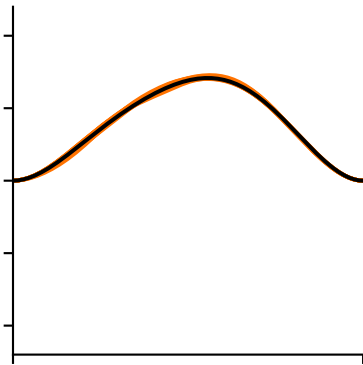
DELTa



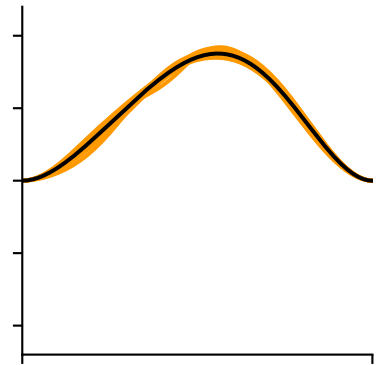
CB



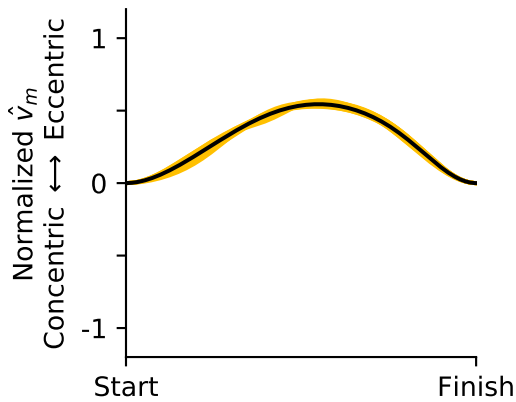
BIC



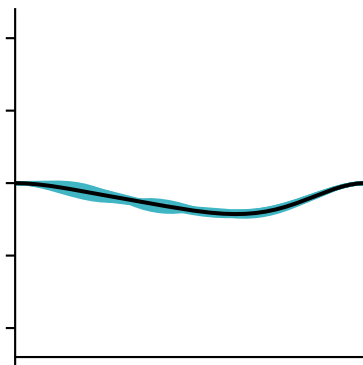
BRD



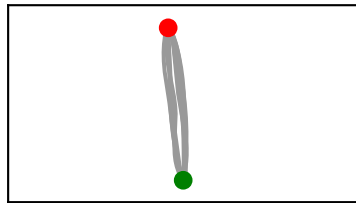
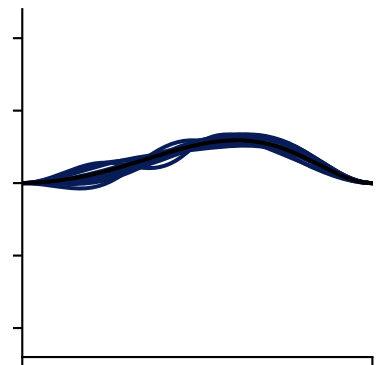
ECRB



TRI

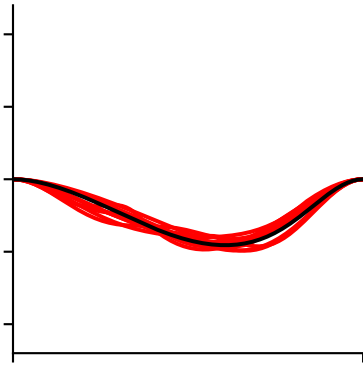


DELTp

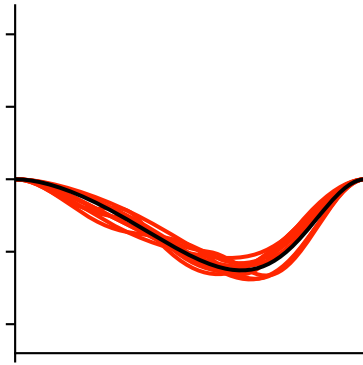


Fixed Initial Position  
Movement Duration : 1 sec

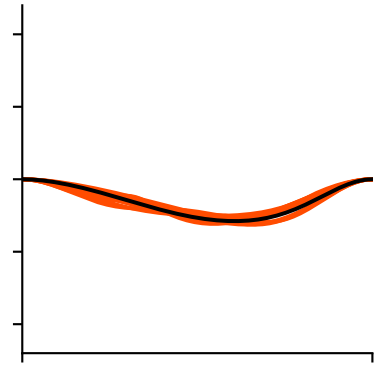
PC



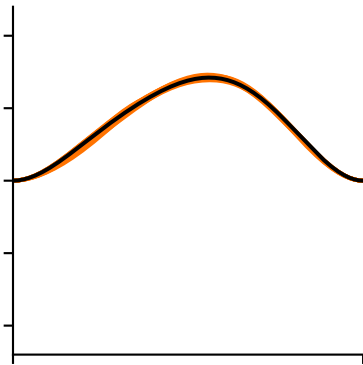
DELTAa



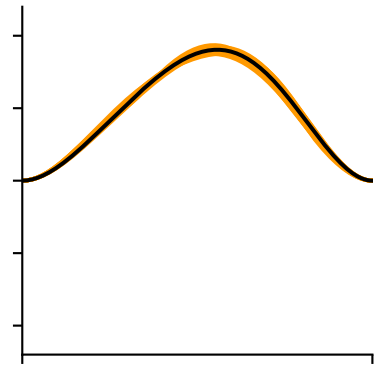
CB



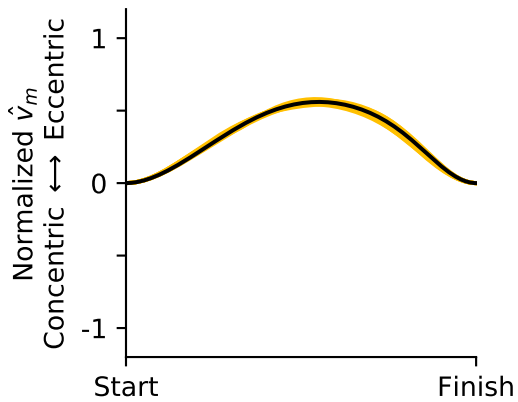
BIC



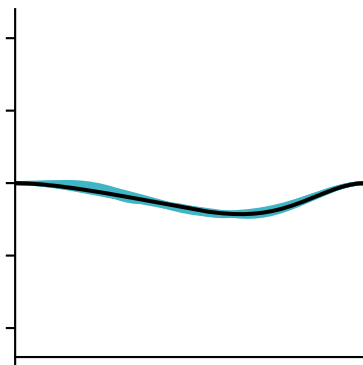
BRD



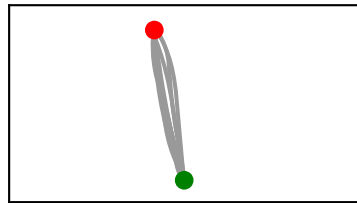
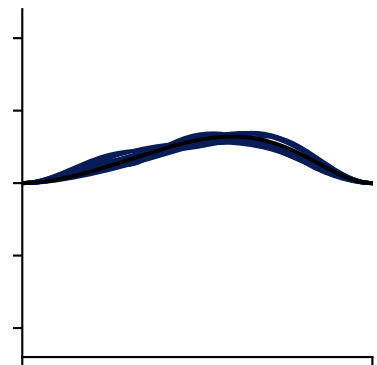
ECRB



TRI

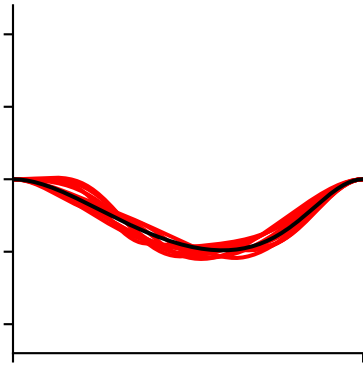


DELTP

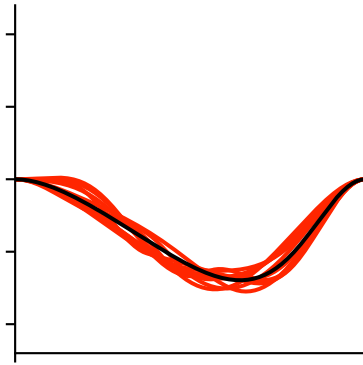


Fixed Initial Position  
Movement Duration : 1 sec

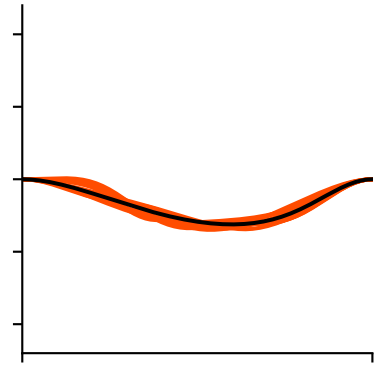
PC



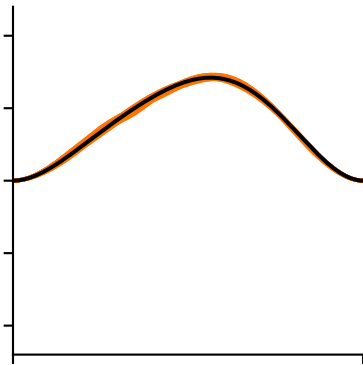
DELTAa



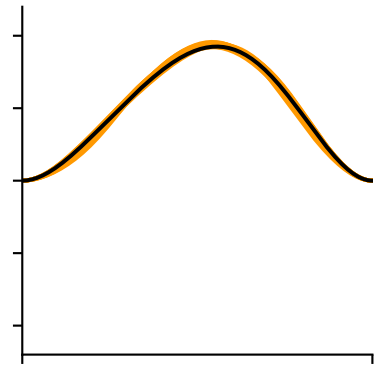
CB



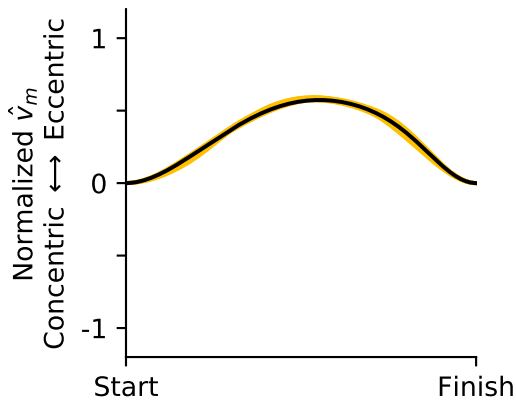
BIC



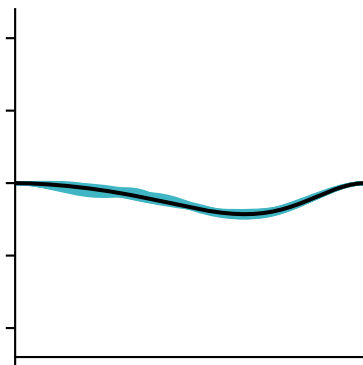
BRD



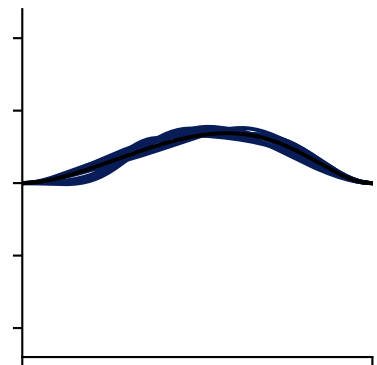
ECRB



TRI

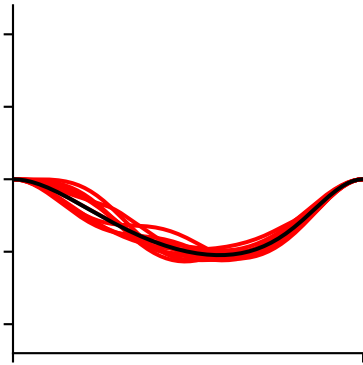


DELTP

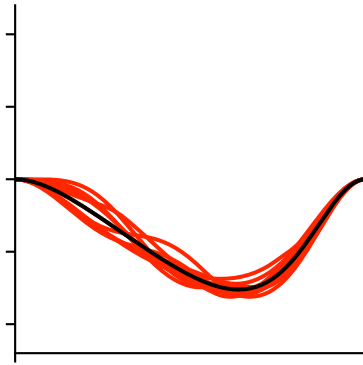


Fixed Initial Position  
Movement Duration : 1 sec

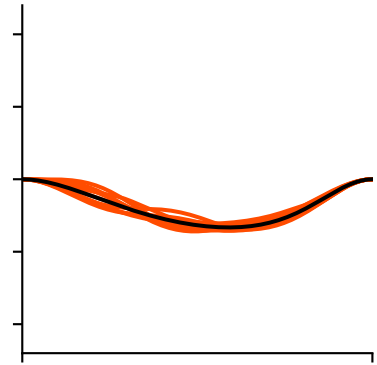
PC



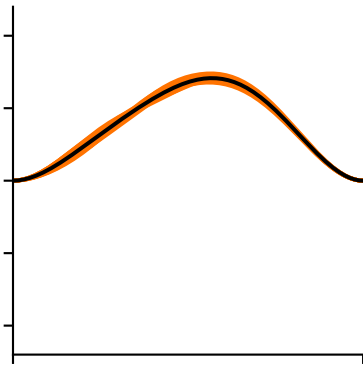
DELTAa



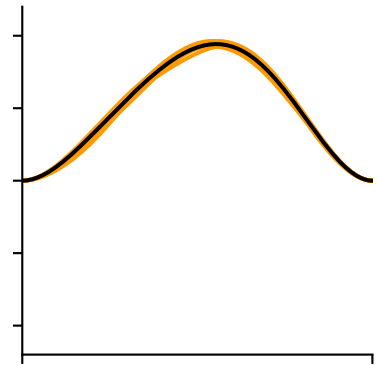
CB



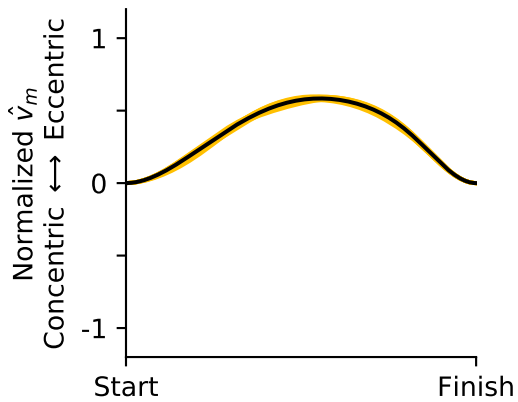
BIC



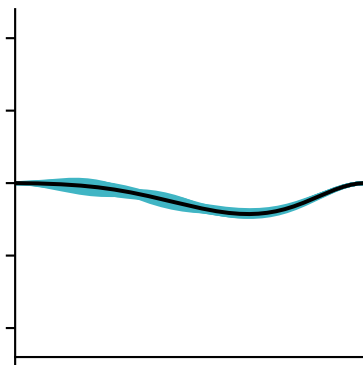
BRD



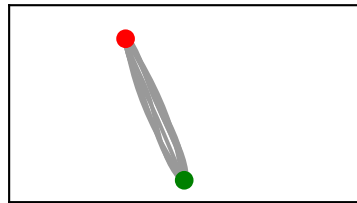
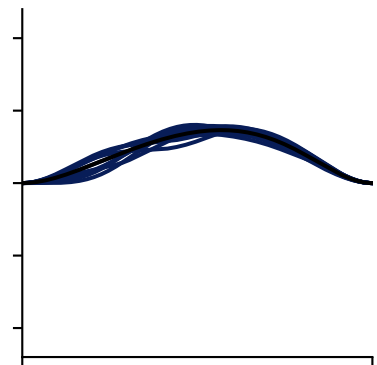
ECRB



TRI

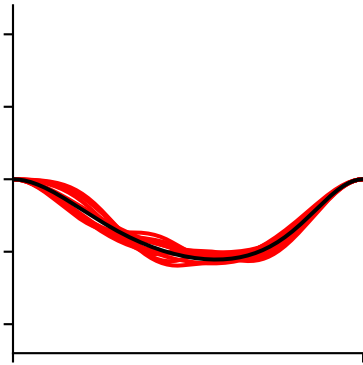


DELTP

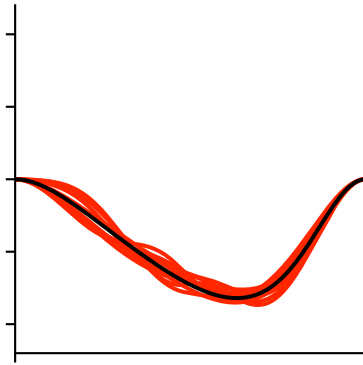


Fixed Initial Position  
Movement Duration : 1 sec

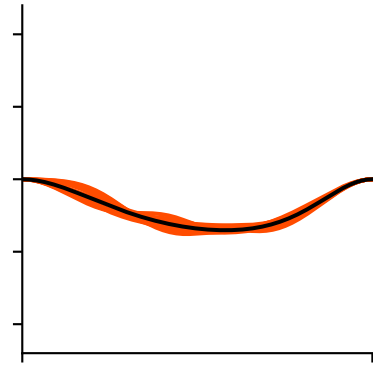
PC



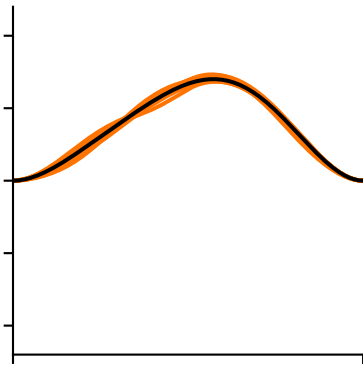
DELTAa



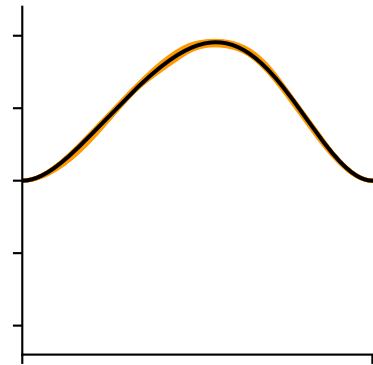
CB



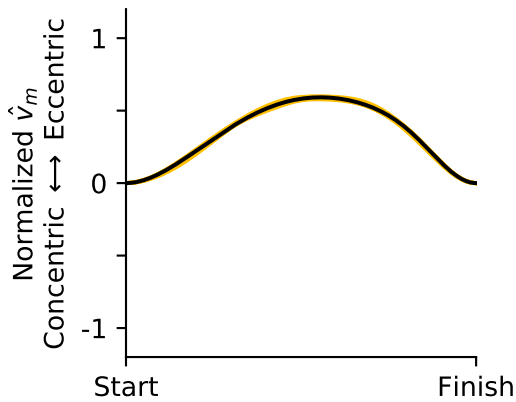
BIC



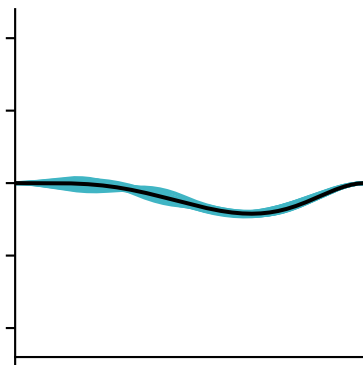
BRD



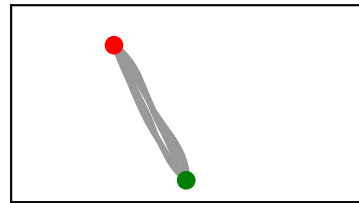
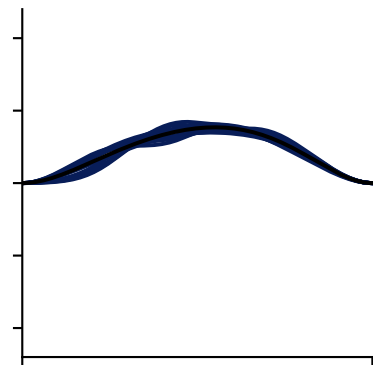
ECRB



TRI

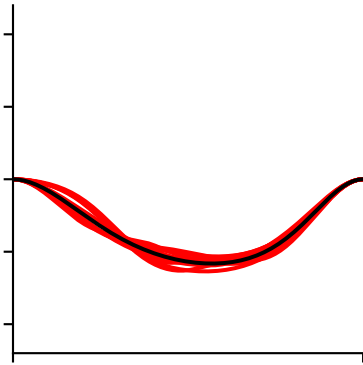


DELTP

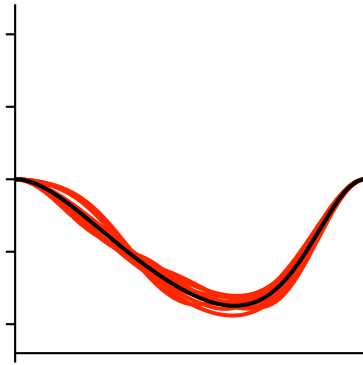


Fixed Initial Position  
Movement Duration : 1 sec

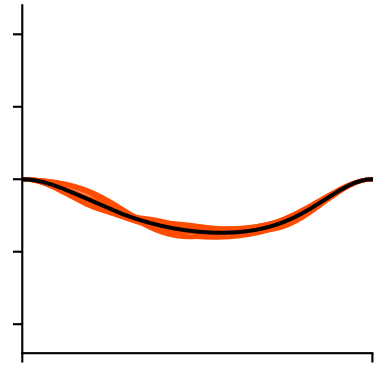
PC



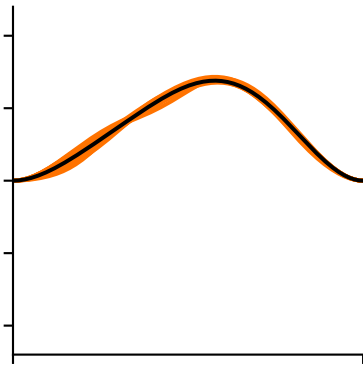
DELTAa



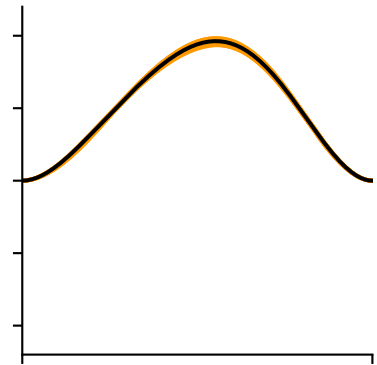
CB



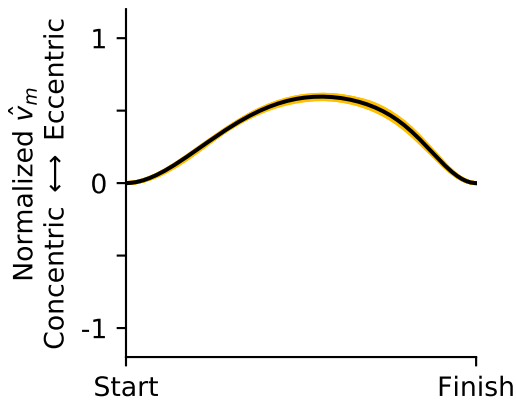
BIC



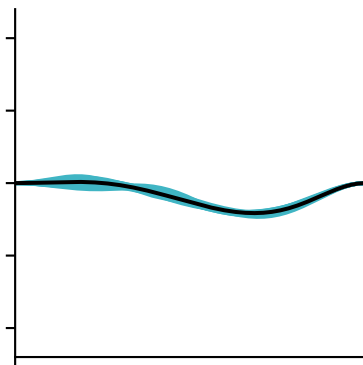
BRD



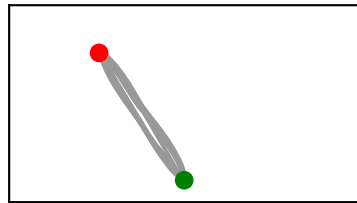
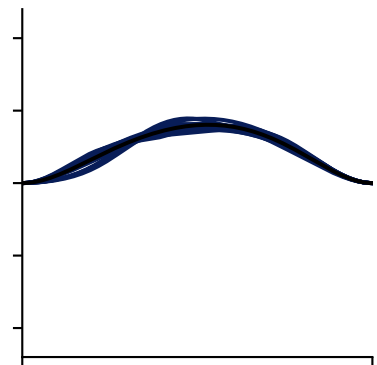
ECRB



TRI

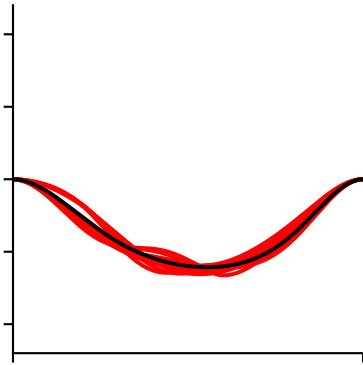


DELTP

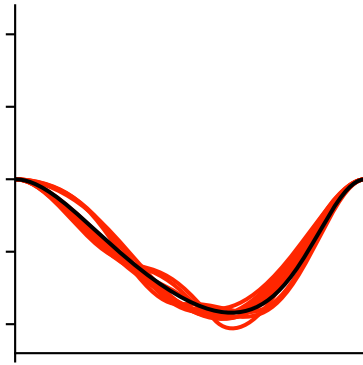


Fixed Initial Position  
Movement Duration : 1 sec

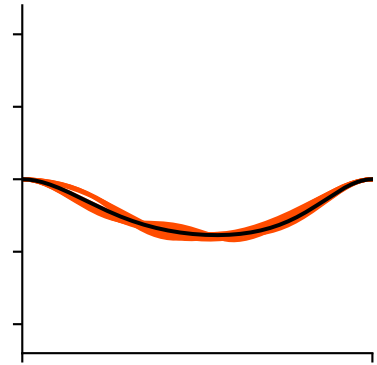
PC



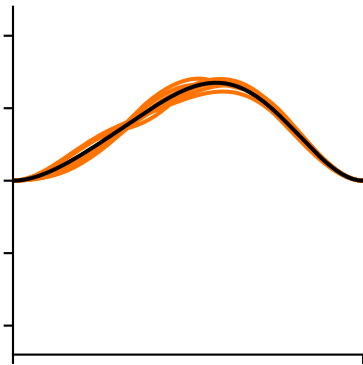
DELTAa



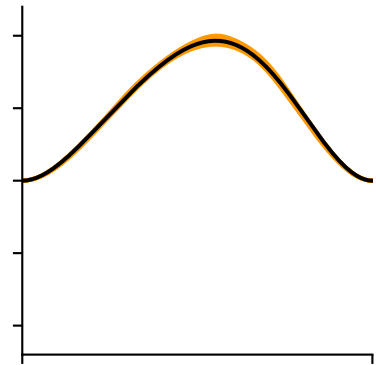
CB



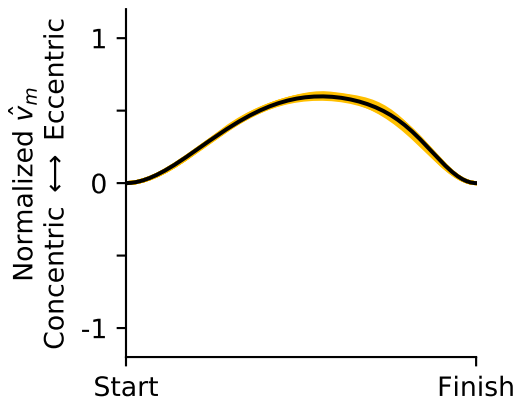
BIC



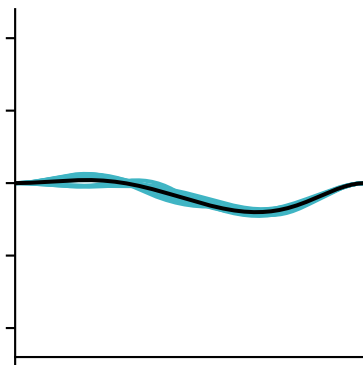
BRD



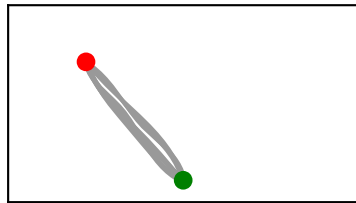
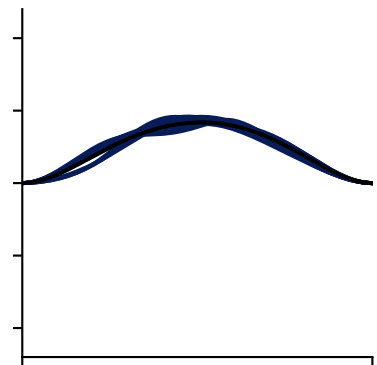
ECRB



TRI



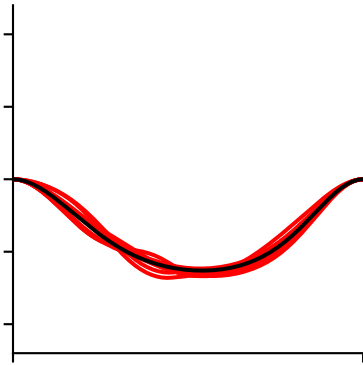
DELTP



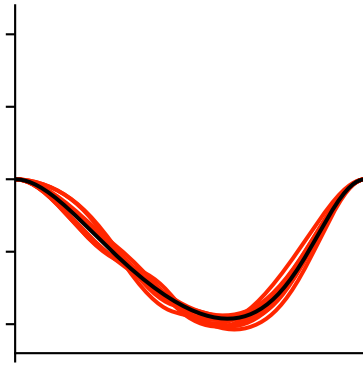


Fixed Initial Position  
Movement Duration : 1 sec

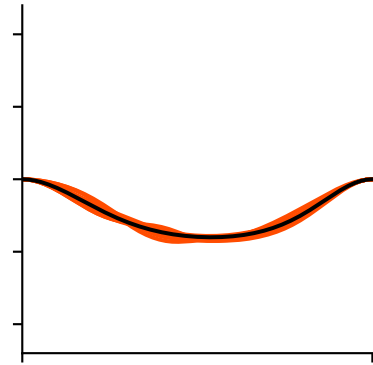
PC



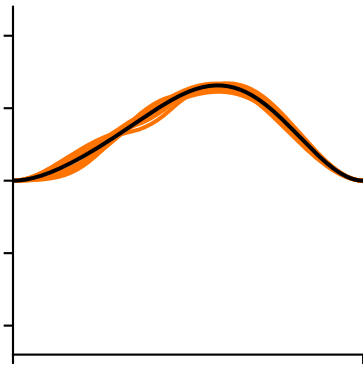
DELTAa



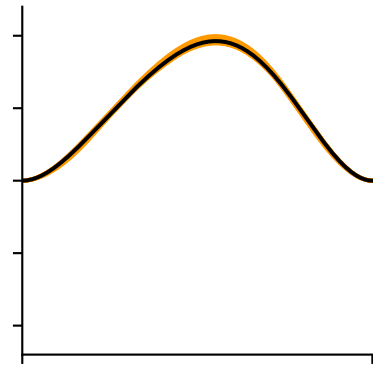
CB



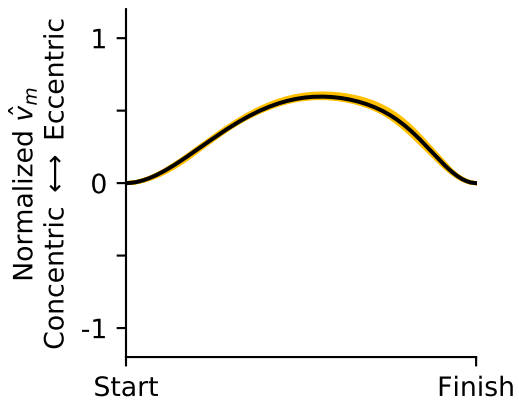
BIC



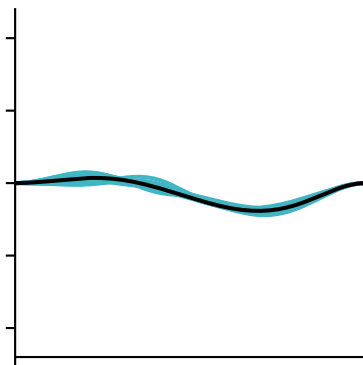
BRD



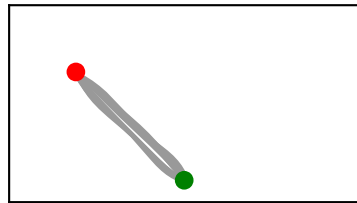
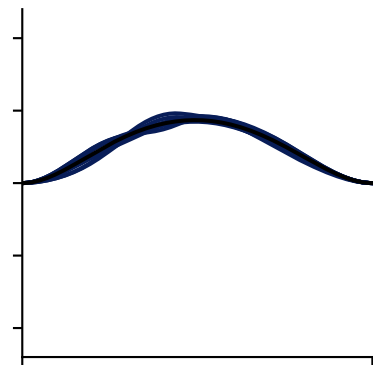
ECRB



TRI

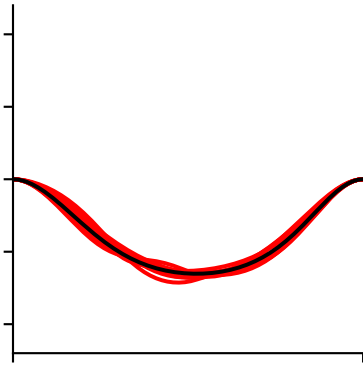


DELTP

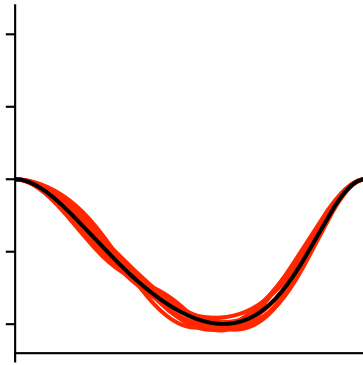


Fixed Initial Position  
Movement Duration : 1 sec

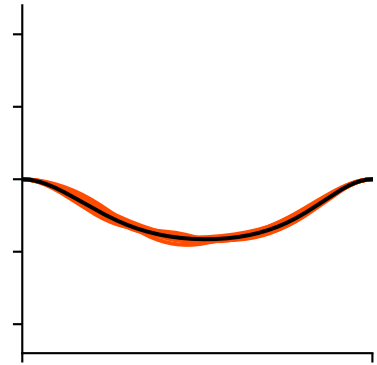
PC



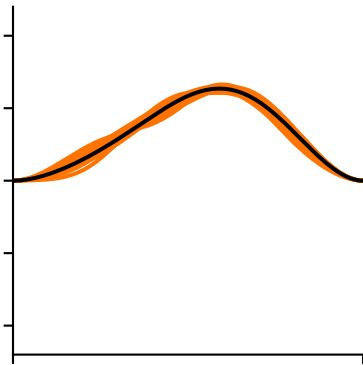
DELTa



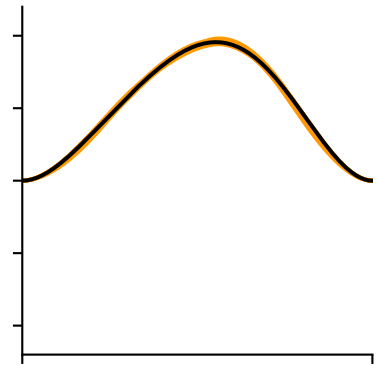
CB



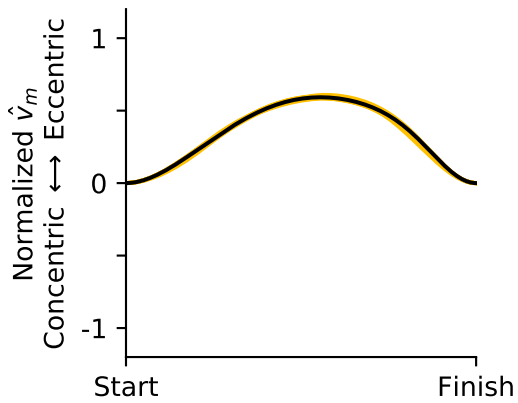
BIC



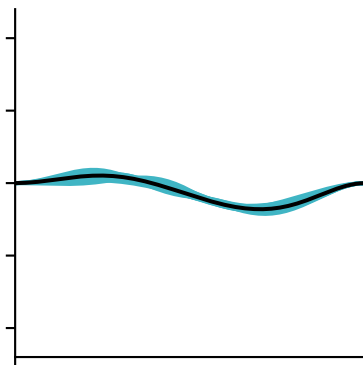
BRD



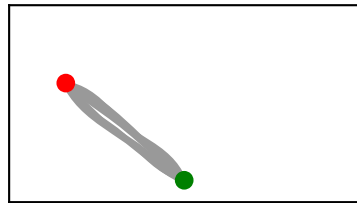
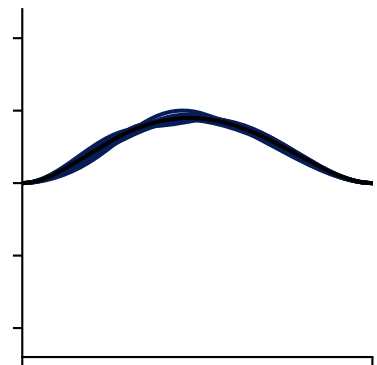
ECRB



TRI

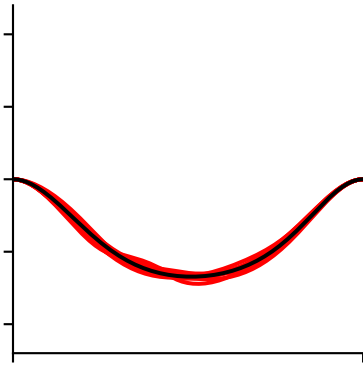


DELTp

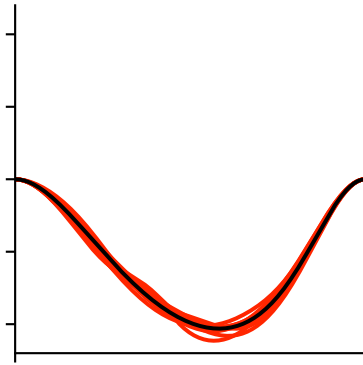


Fixed Initial Position  
Movement Duration : 1 sec

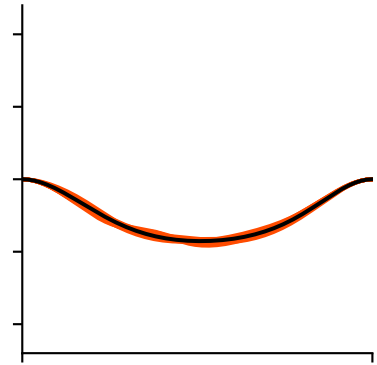
PC



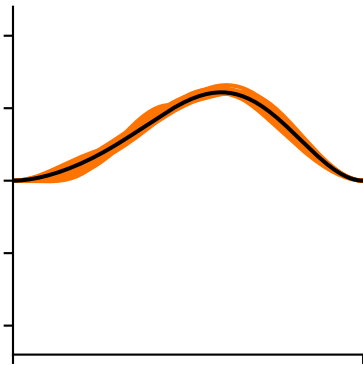
DELTAa



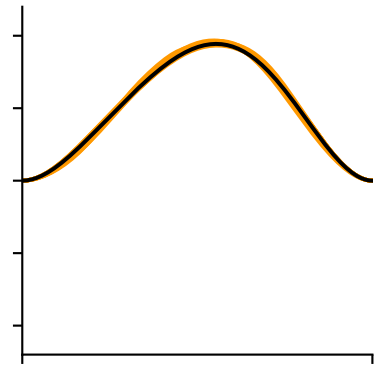
CB



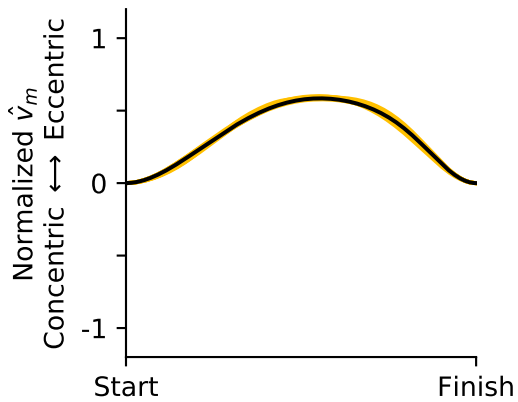
BIC



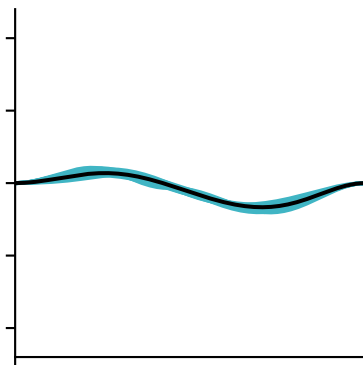
BRD



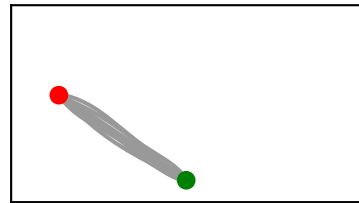
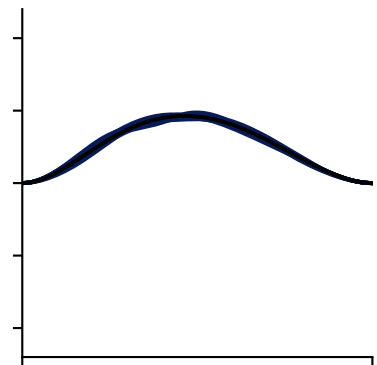
ECRB



TRI

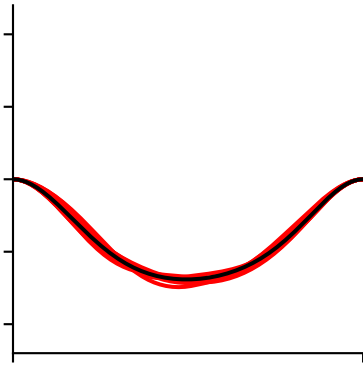


DELTP

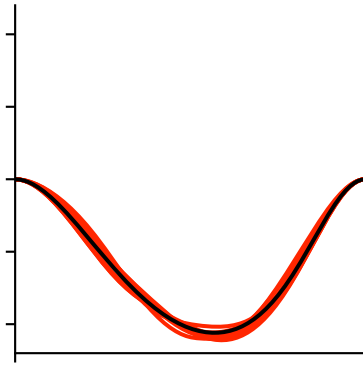


Fixed Initial Position  
Movement Duration : 1 sec

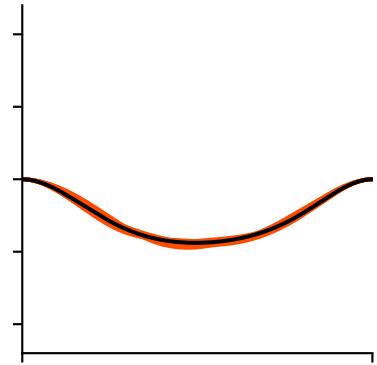
PC



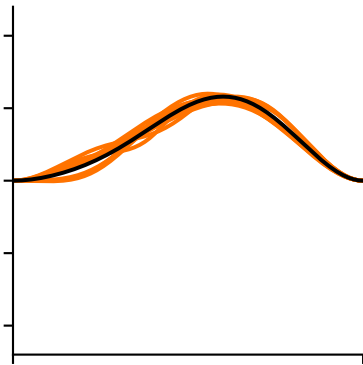
DELTAa



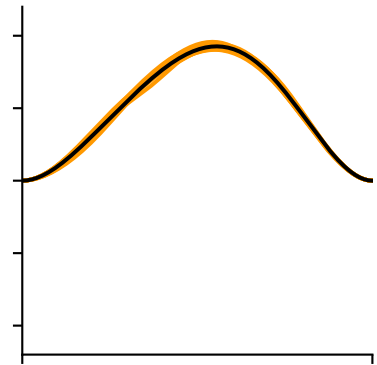
CB



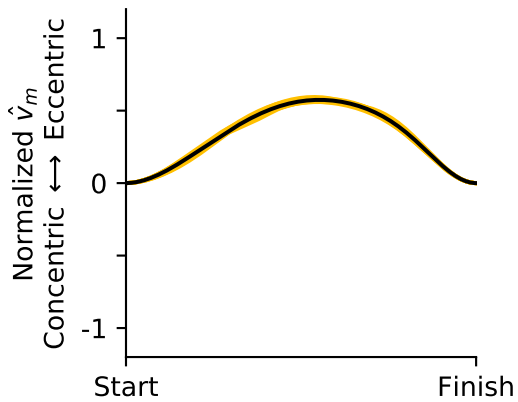
BIC



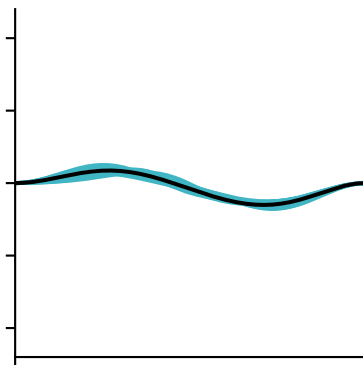
BRD



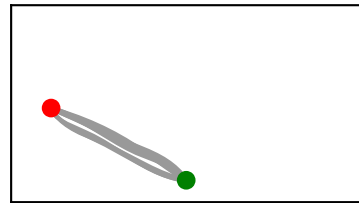
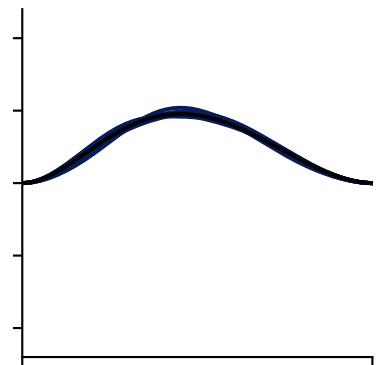
ECRB



TRI



DELTP



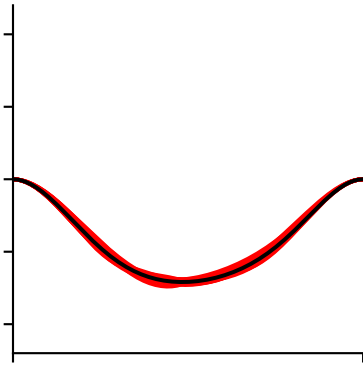
Normalized  $\hat{v}_m$   
Concentric  $\leftrightarrow$  Eccentric

Start

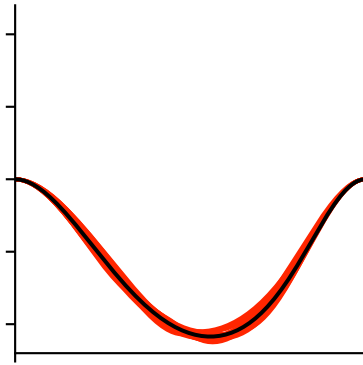
Finish

Fixed Initial Position  
Movement Duration : 1 sec

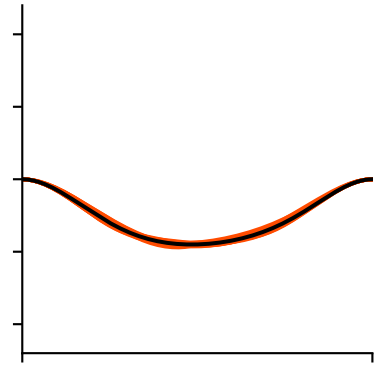
PC



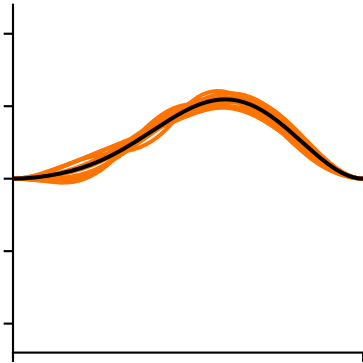
DELTa



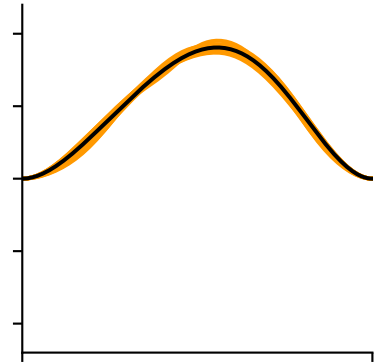
CB



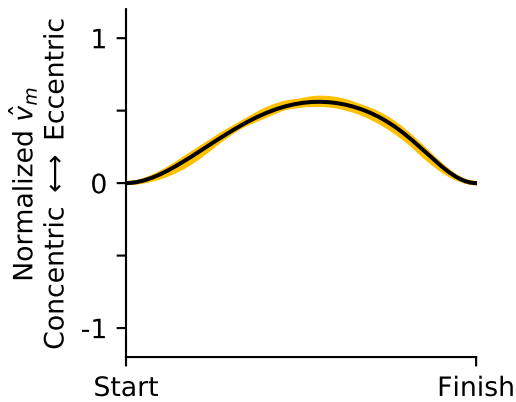
BIC



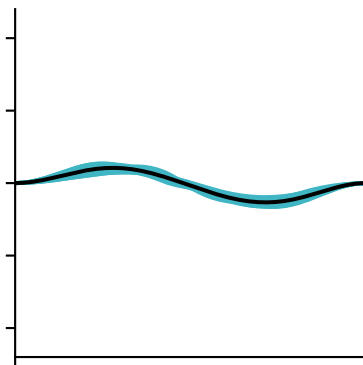
BRD



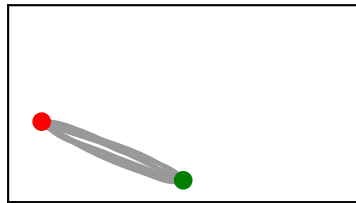
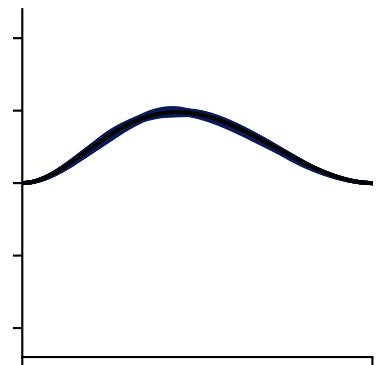
ECRB



TRI

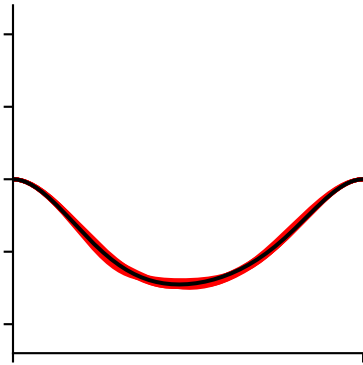


DELTp

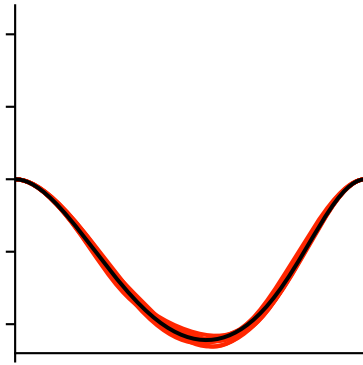


Fixed Initial Position  
Movement Duration : 1 sec

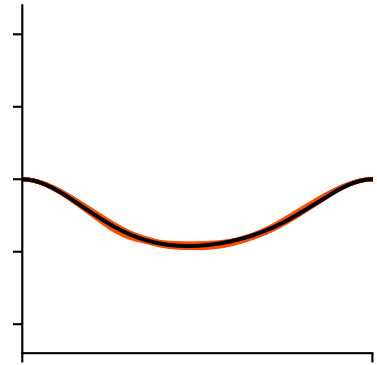
PC



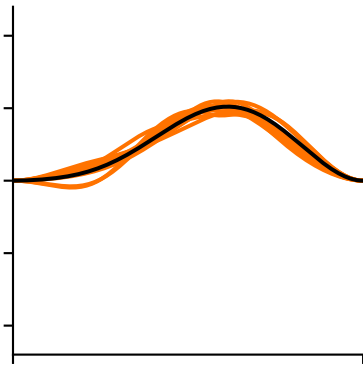
DELTAa



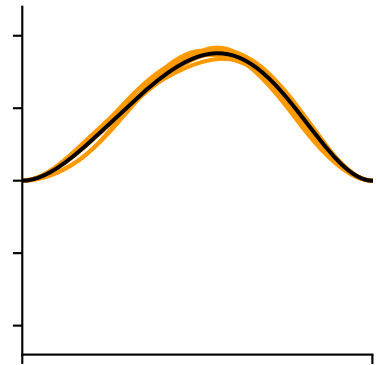
CB



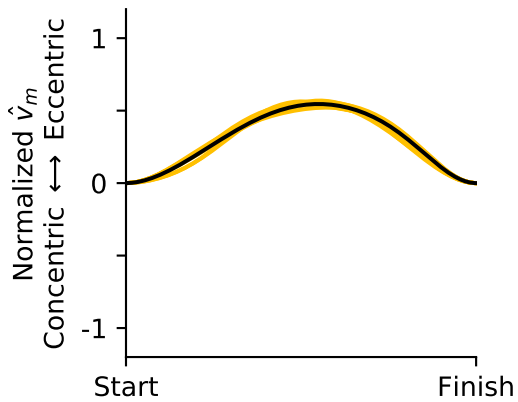
BIC



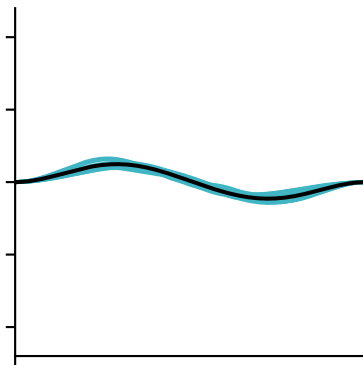
BRD



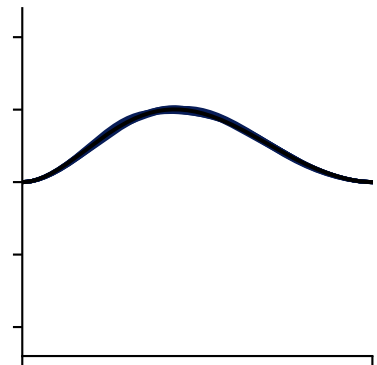
ECRB



TRI



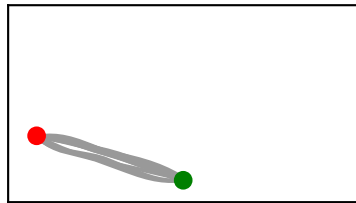
DELTP



Normalized  $\hat{v}_m$   
Concentric  $\leftrightarrow$  Eccentric

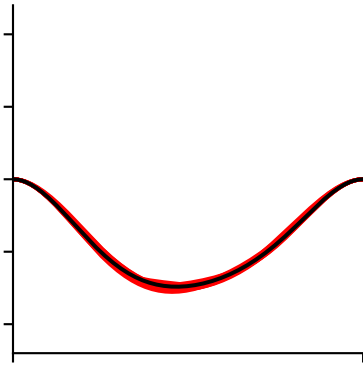
Start

Finish

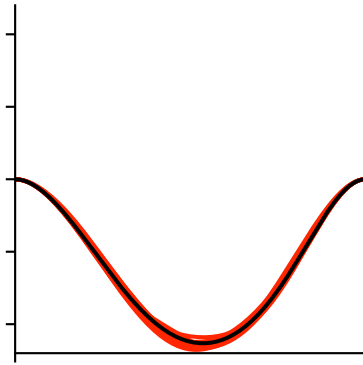


Fixed Initial Position  
Movement Duration : 1 sec

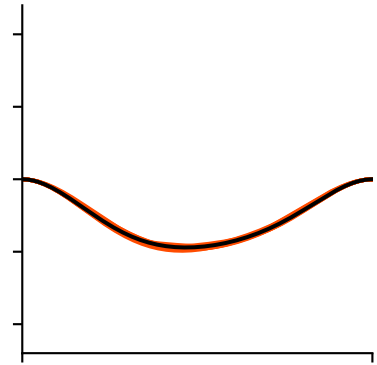
PC



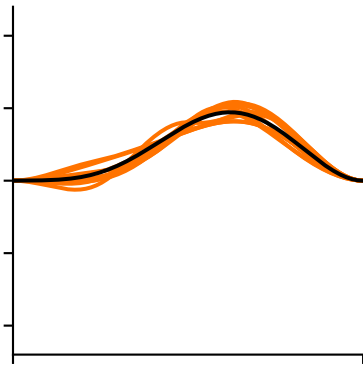
DELTa



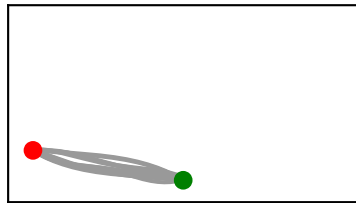
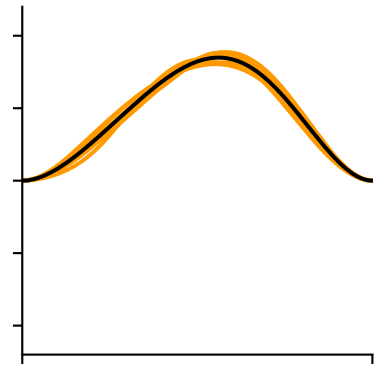
CB



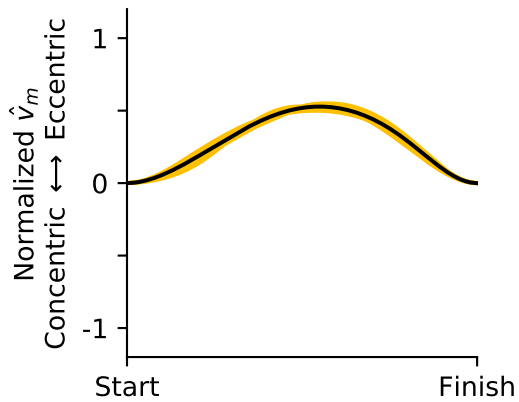
BIC



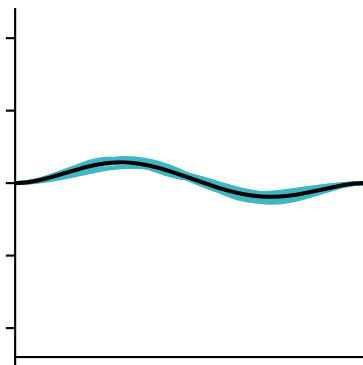
BRD



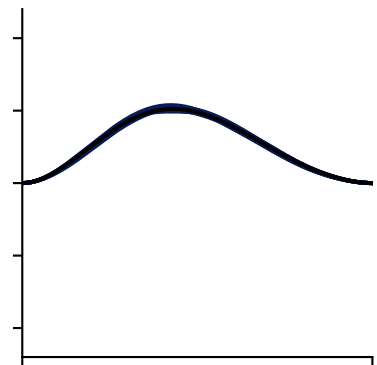
ECRB



TRI

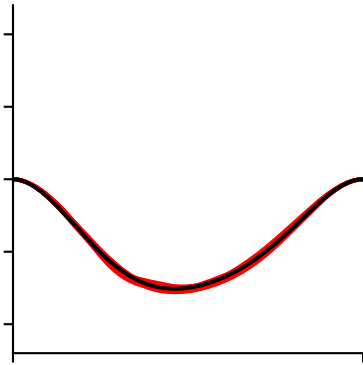


DELTp

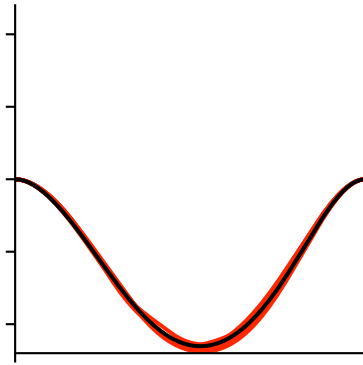


Fixed Initial Position  
Movement Duration : 1 sec

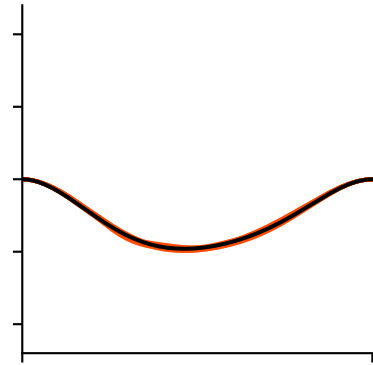
PC



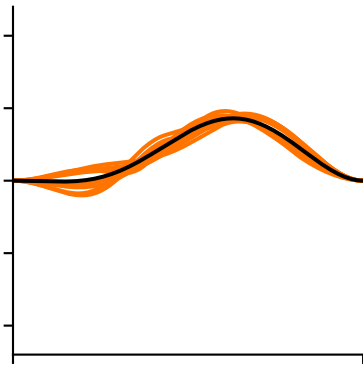
DELTa



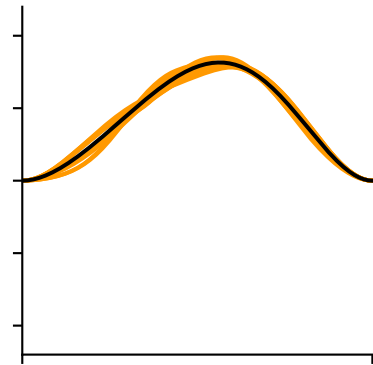
CB



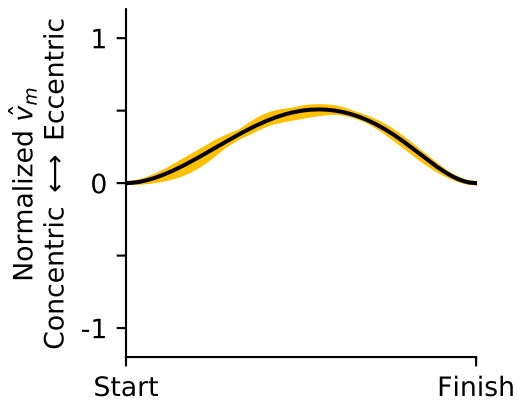
BIC



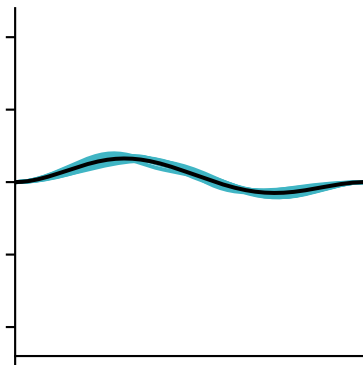
BRD



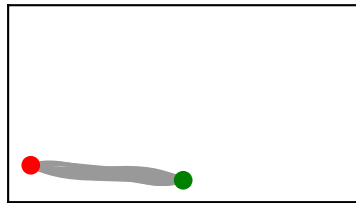
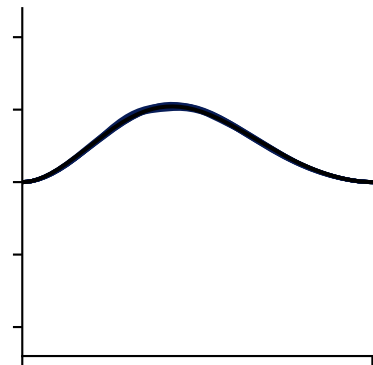
ECRB



TRI



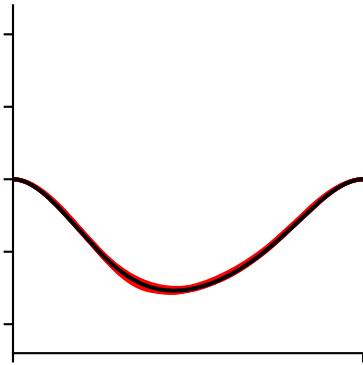
DELTp



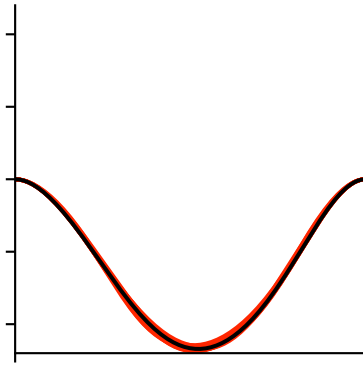


Fixed Initial Position  
Movement Duration : 1 sec

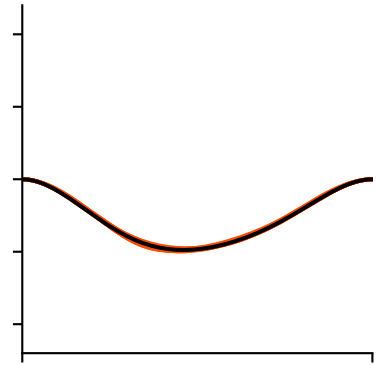
PC



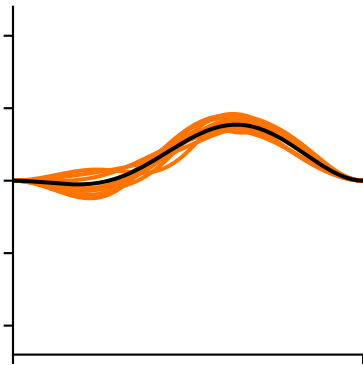
DELTAa



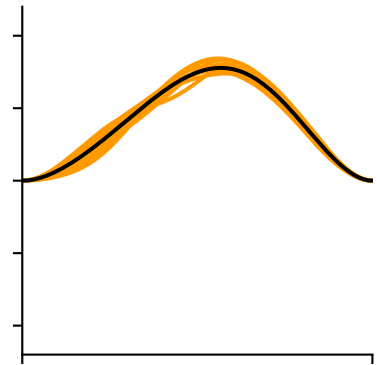
CB



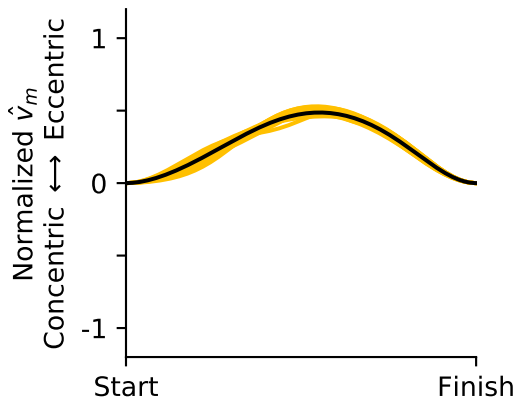
BIC



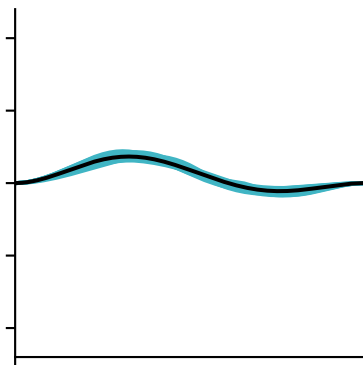
BRD



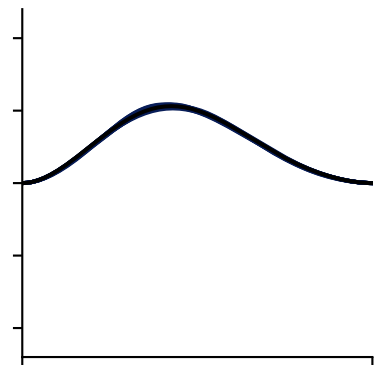
ECRB



TRI



DELTP



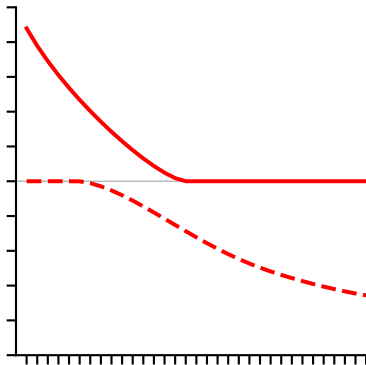
Normalized  $\hat{v}_m$   
Concentric  $\leftrightarrow$  Eccentric

Start

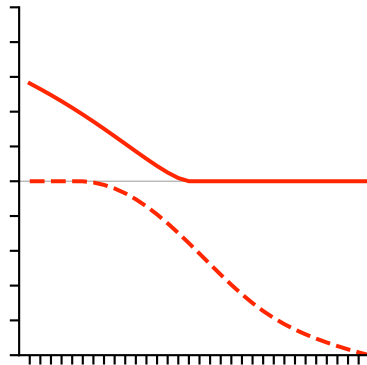
Finish

Fixed Initial Position  
Movement Duration : 1 sec

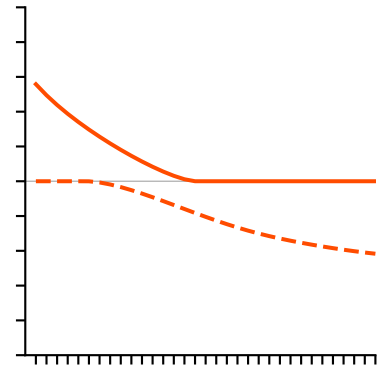
PC



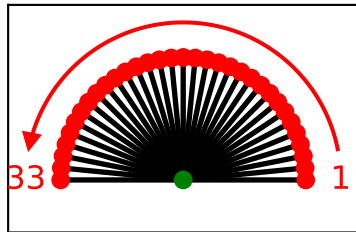
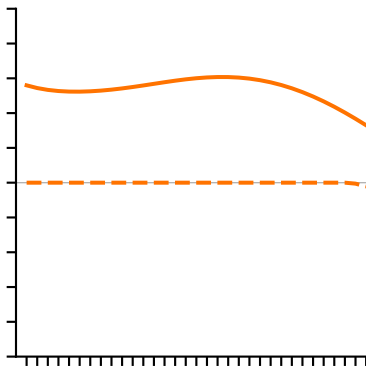
DELTAa



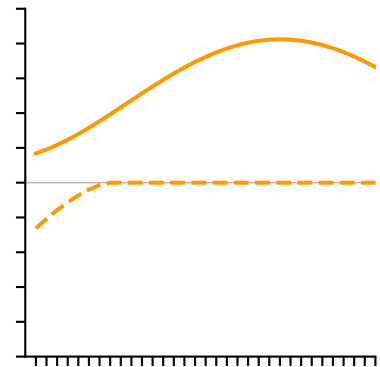
CB



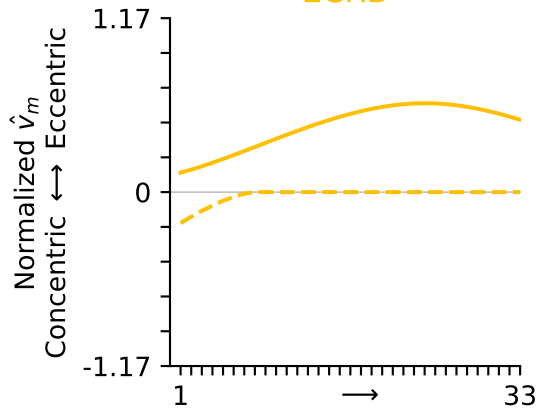
BIC



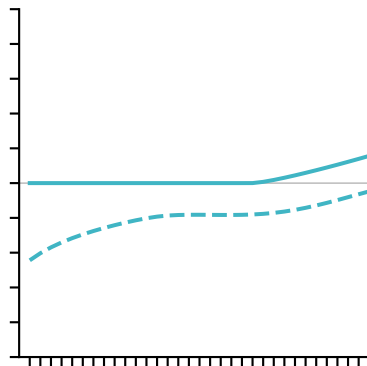
BRD



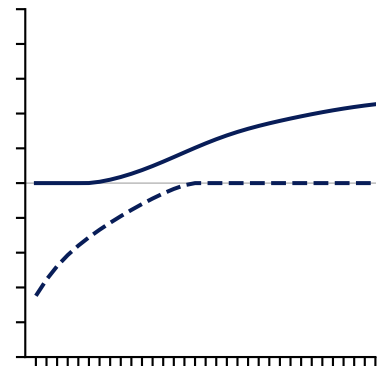
ECRB



TRI

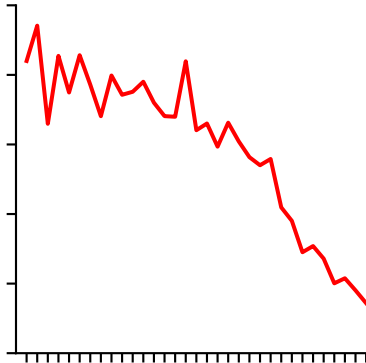


DELTP

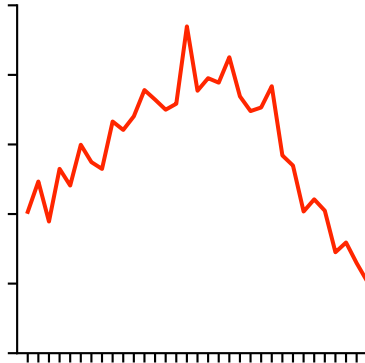


Fixed Initial Position  
Movement Duration : 1 sec

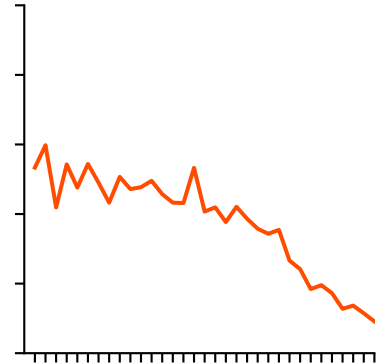
PC



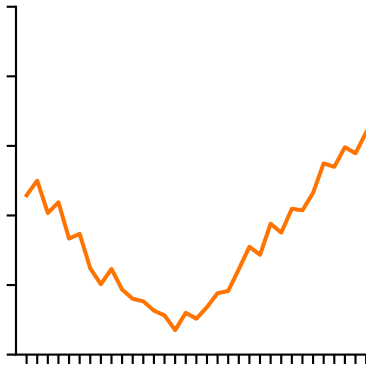
DELTa



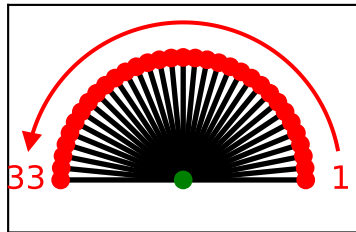
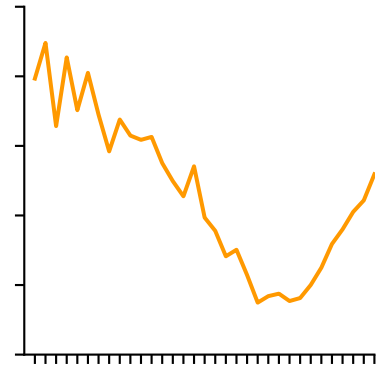
CB



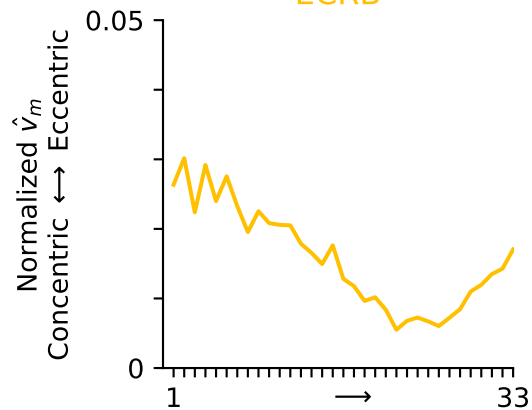
BIC



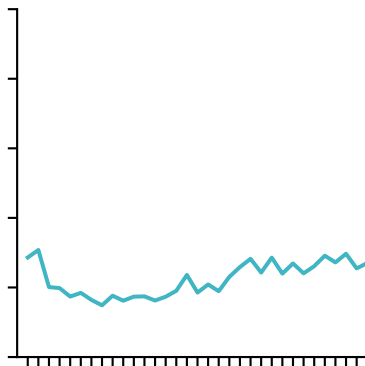
BRD



ECRB



TRI



DELTp

