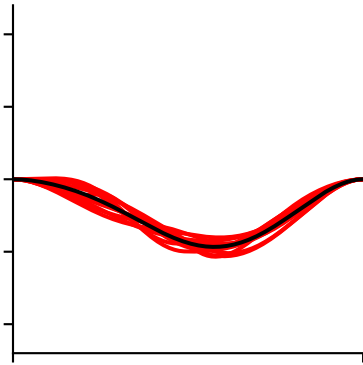
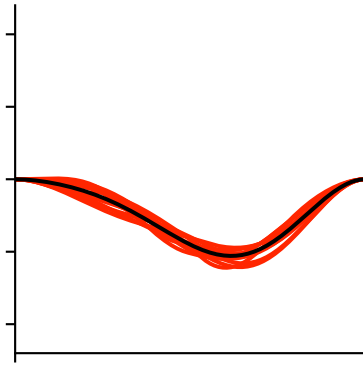


Fixed Final Position
Movement Duration : 1 sec

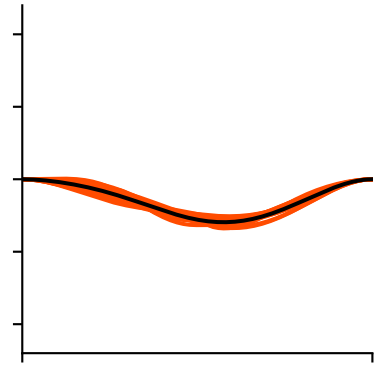
PC



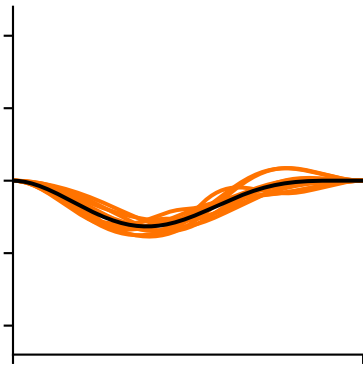
DELTAa



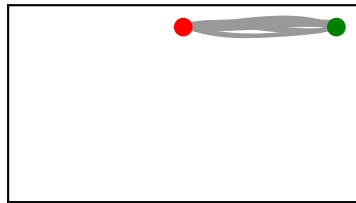
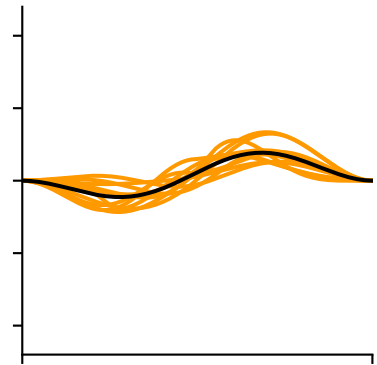
CB



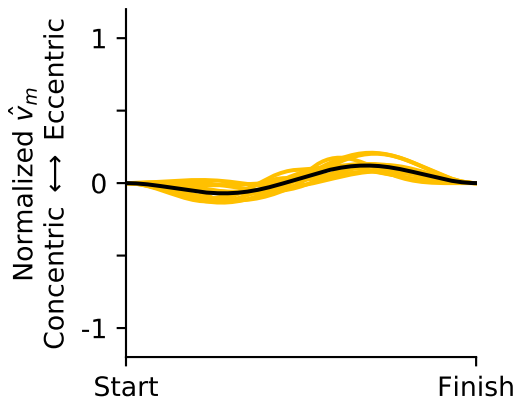
BIC



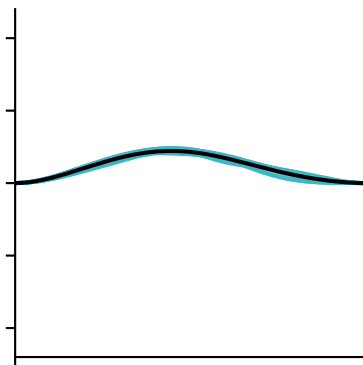
BRD



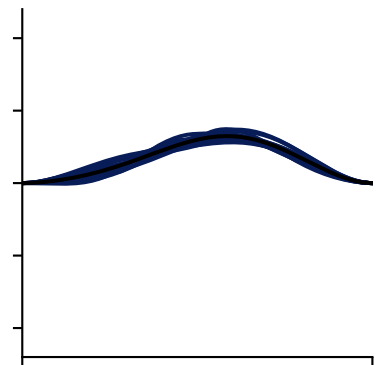
ECRB



TRI

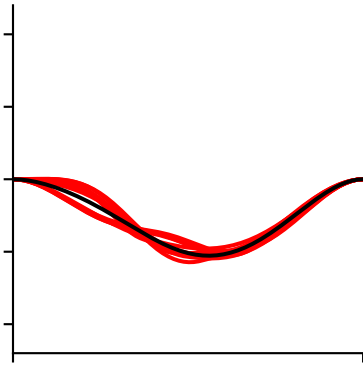


DELTP

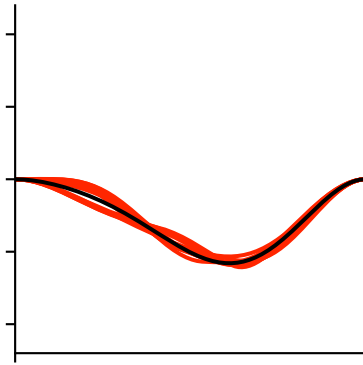


Fixed Final Position
Movement Duration : 1 sec

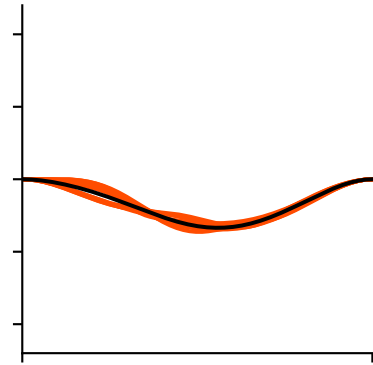
PC



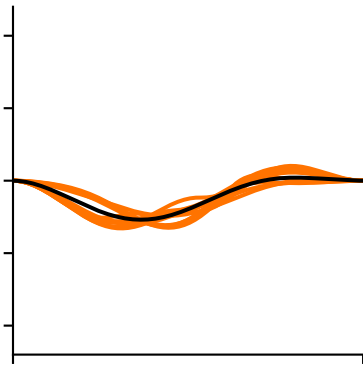
DELTAa



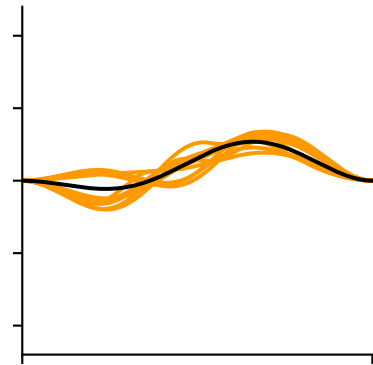
CB



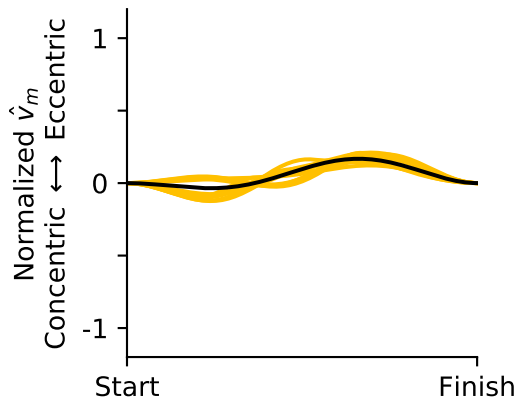
BIC



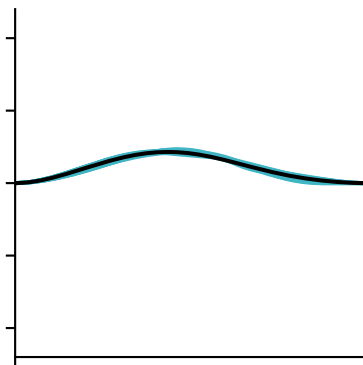
BRD



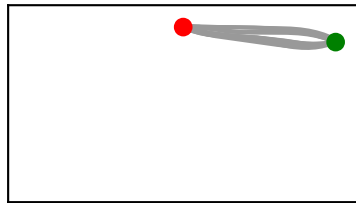
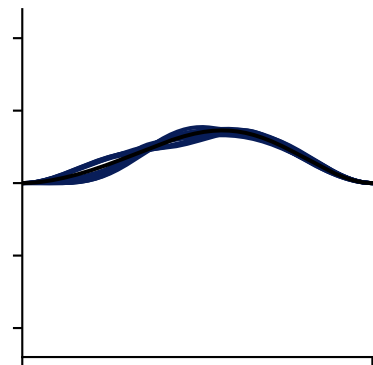
ECRB



TRI

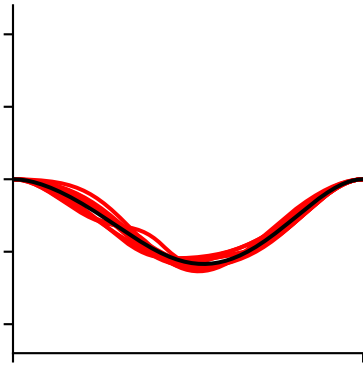


DELTP

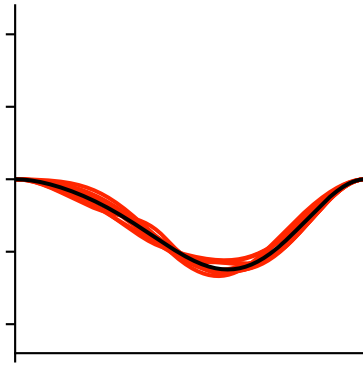


Fixed Final Position
Movement Duration : 1 sec

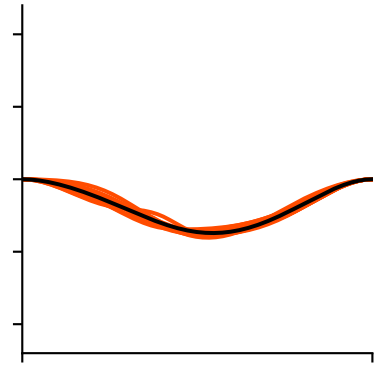
PC



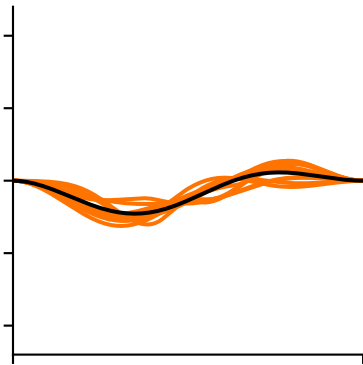
DELTAa



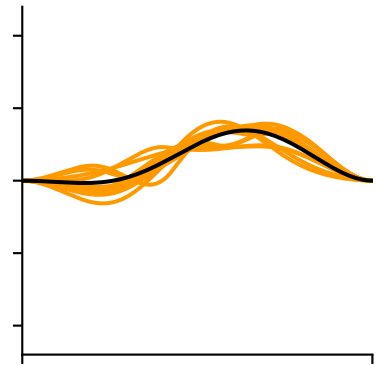
CB



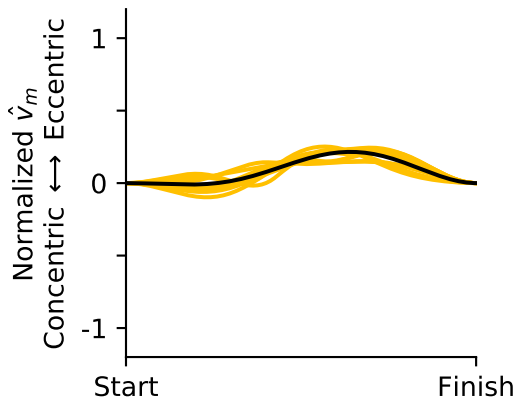
BIC



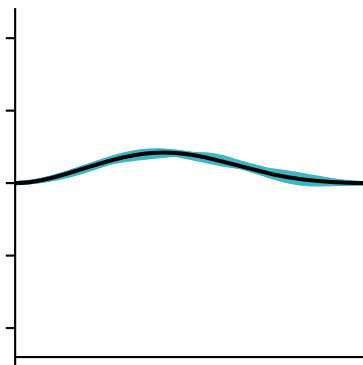
BRD



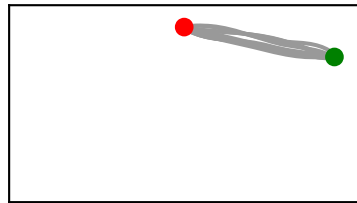
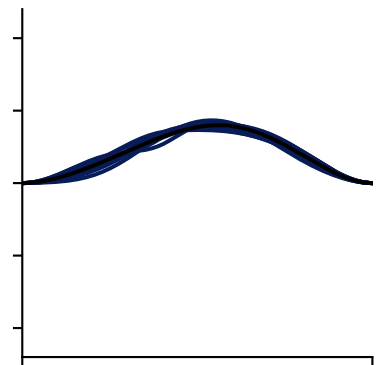
ECRB



TRI

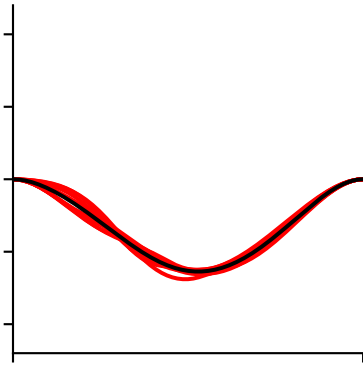


DELTP

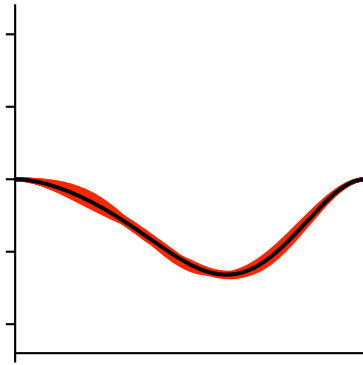


Fixed Final Position
Movement Duration : 1 sec

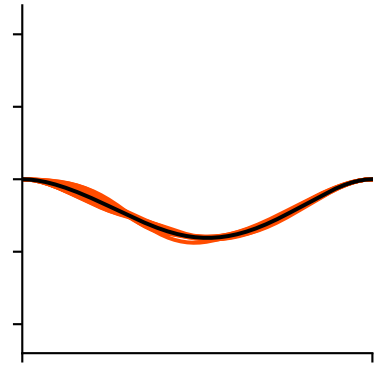
PC



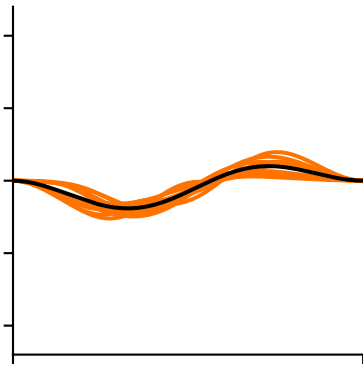
DELTAa



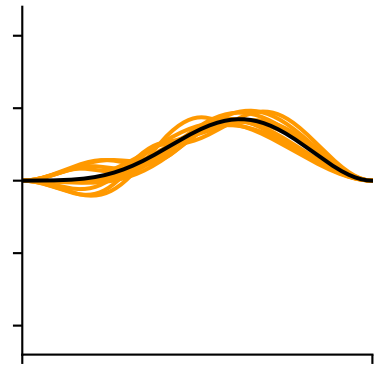
CB



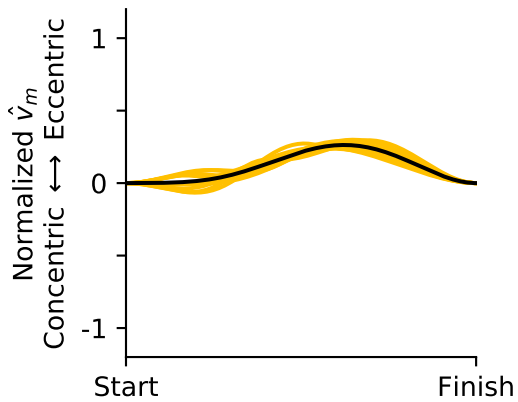
BIC



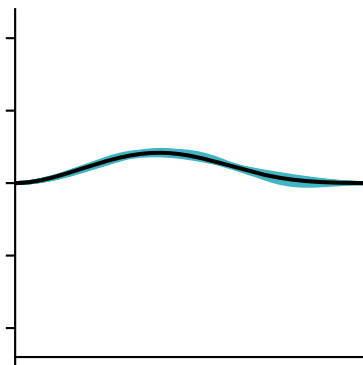
BRD



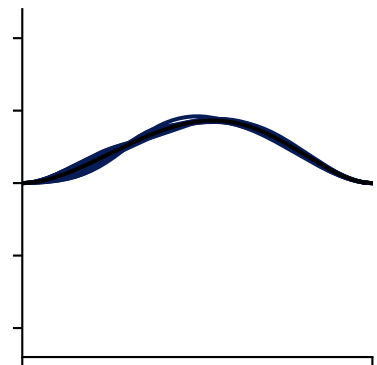
ECRB



TRI



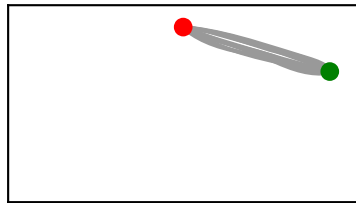
DELTP



Normalized \hat{v}_m
Concentric \leftrightarrow Eccentric

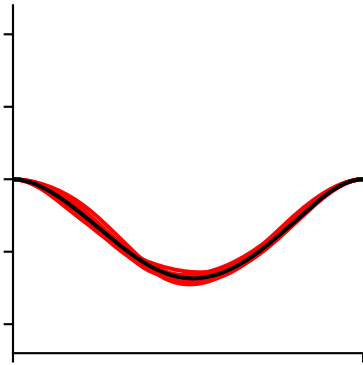
Start

Finish

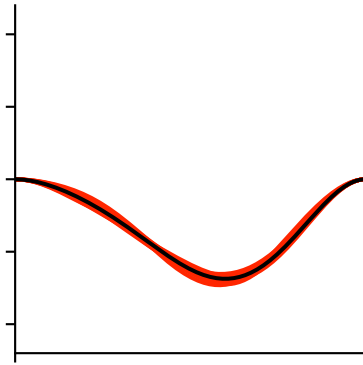


Fixed Final Position
Movement Duration : 1 sec

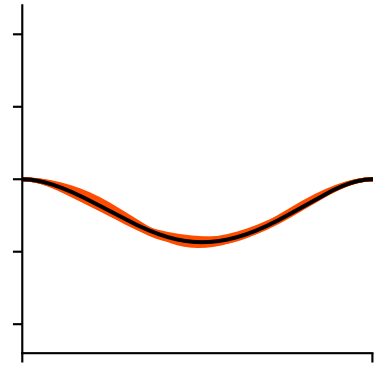
PC



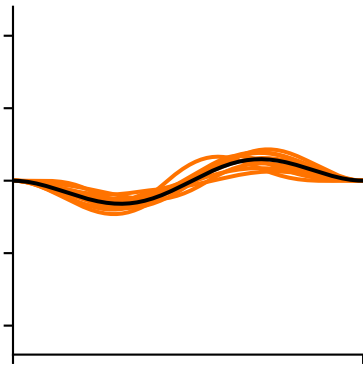
DELTAa



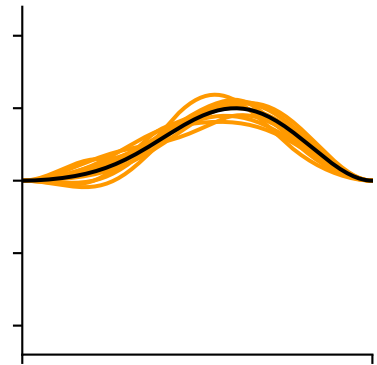
CB



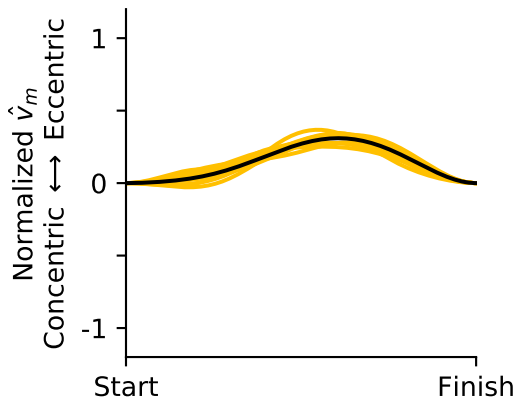
BIC



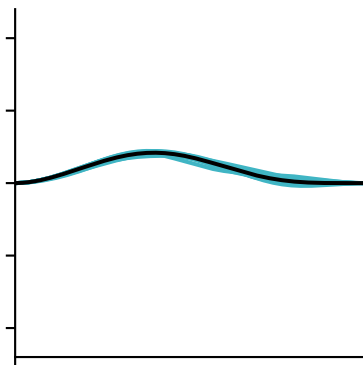
BRD



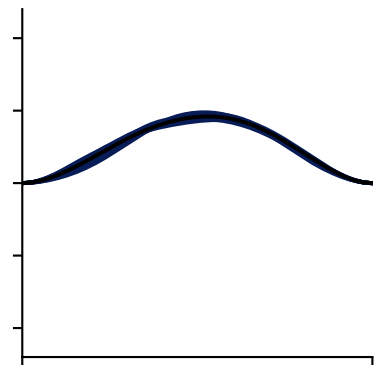
ECRB



TRI



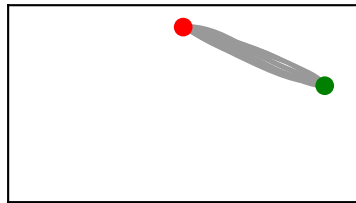
DELTP



Normalized \hat{v}_m
Concentric \leftrightarrow Eccentric

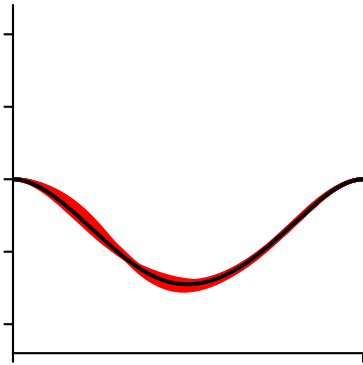
Start

Finish

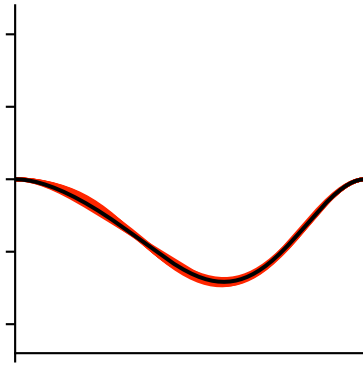


Fixed Final Position
Movement Duration : 1 sec

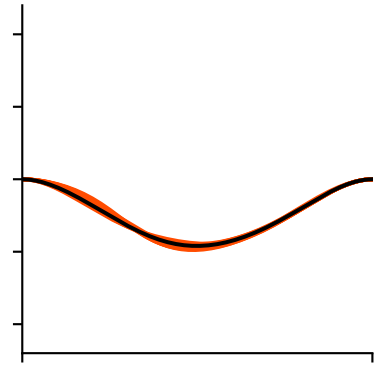
PC



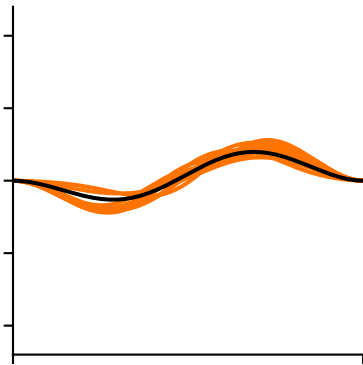
DELTAa



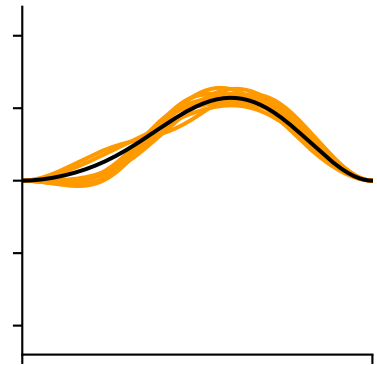
CB



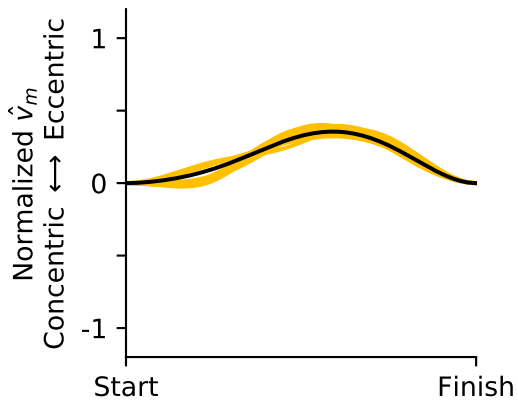
BIC



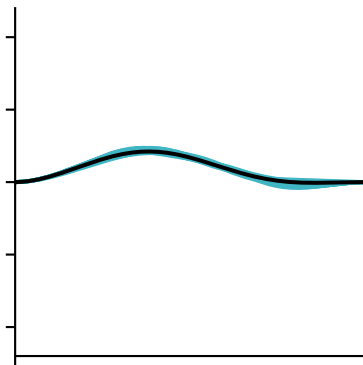
BRD



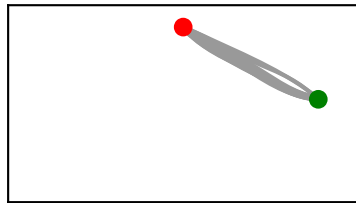
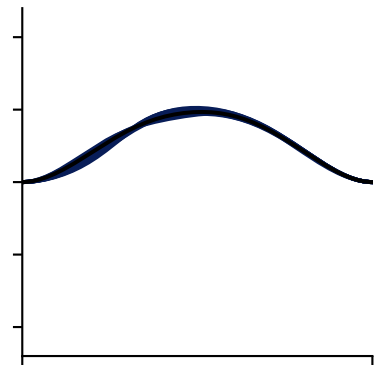
ECRB



TRI

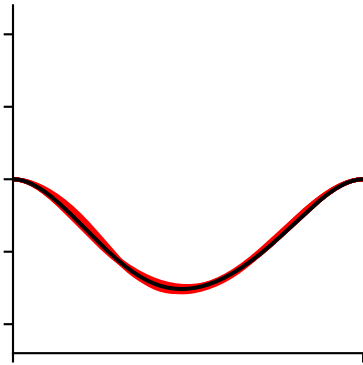


DELTP

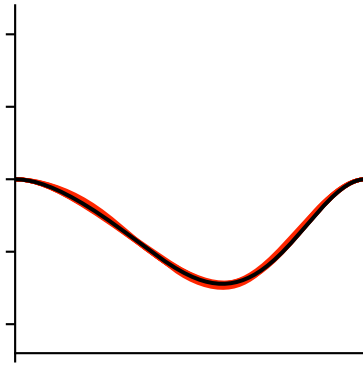


Fixed Final Position
Movement Duration : 1 sec

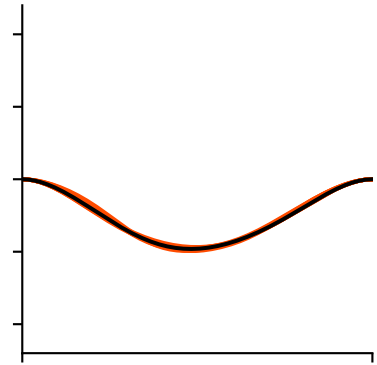
PC



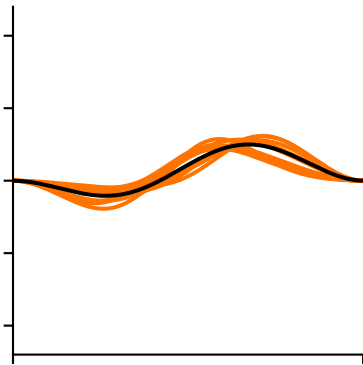
DELTAa



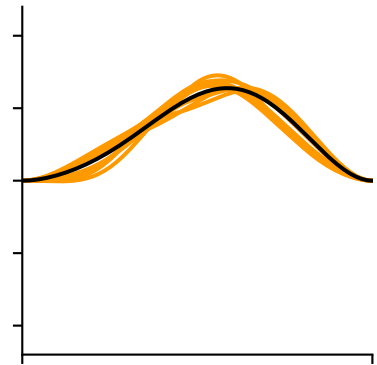
CB



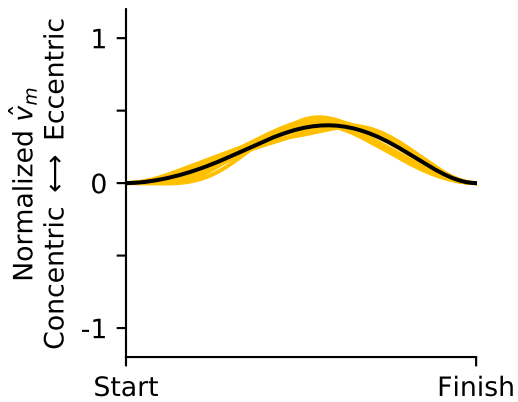
BIC



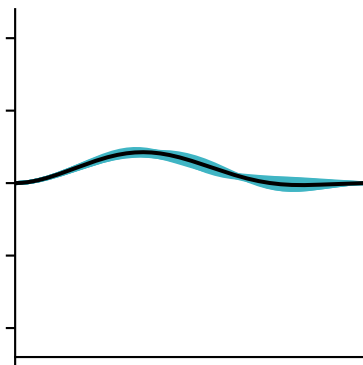
BRD



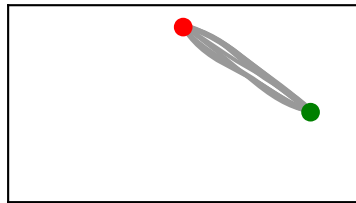
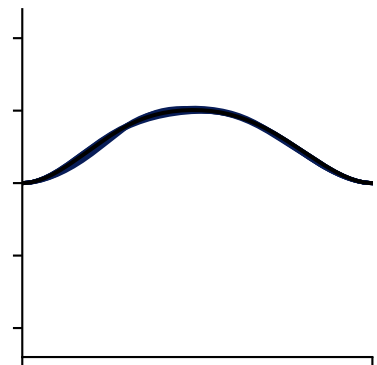
ECRB



TRI

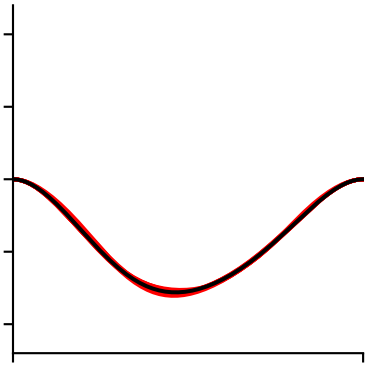


DELTP

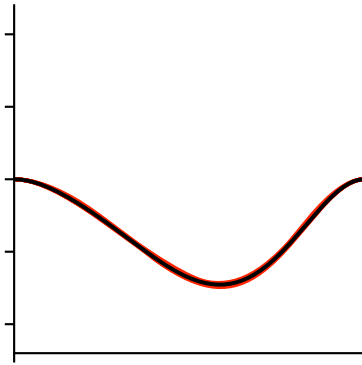


Fixed Final Position
Movement Duration : 1 sec

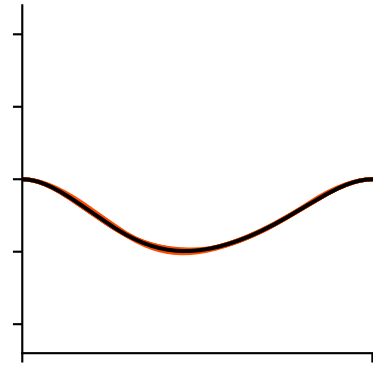
PC



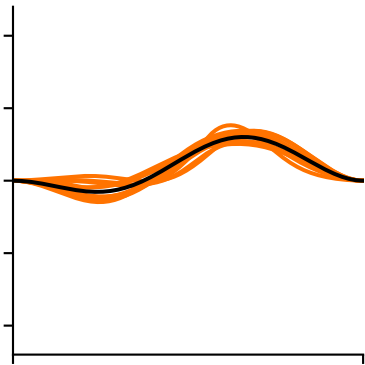
DELTA_a



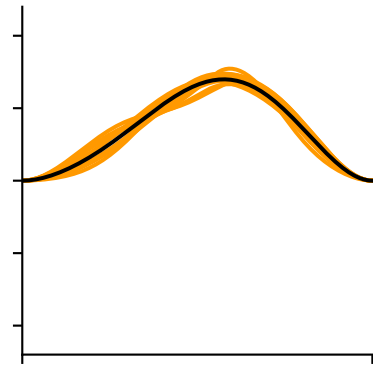
CB



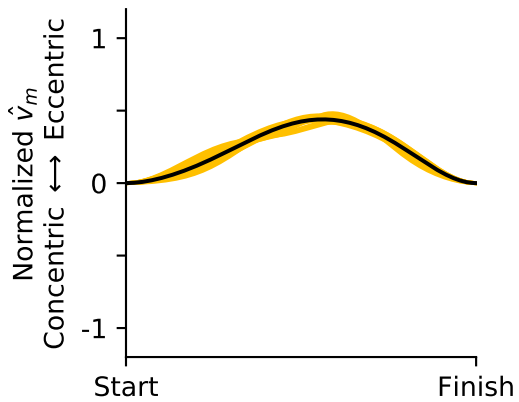
BIC



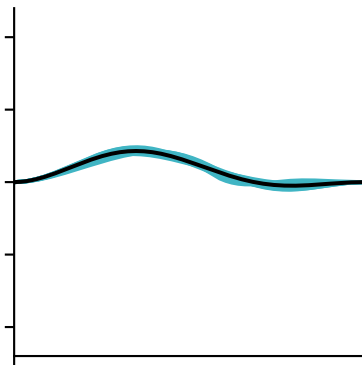
BRD



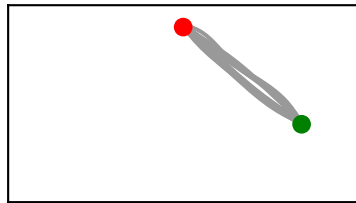
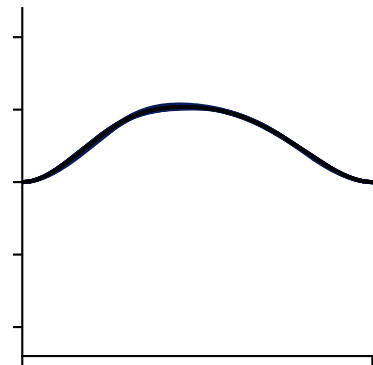
ECRB



TRI

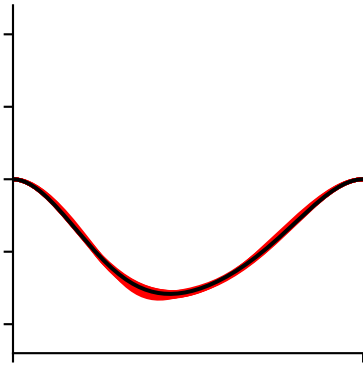


DELTP

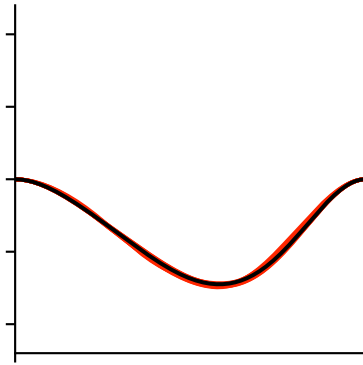


Fixed Final Position
Movement Duration : 1 sec

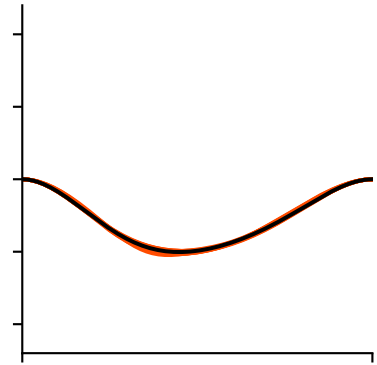
PC



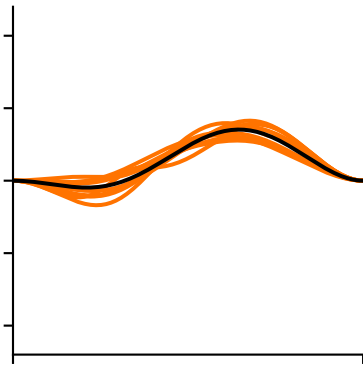
DELTAa



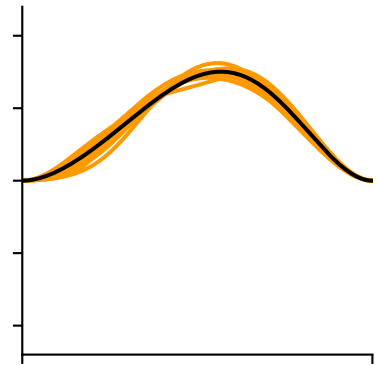
CB



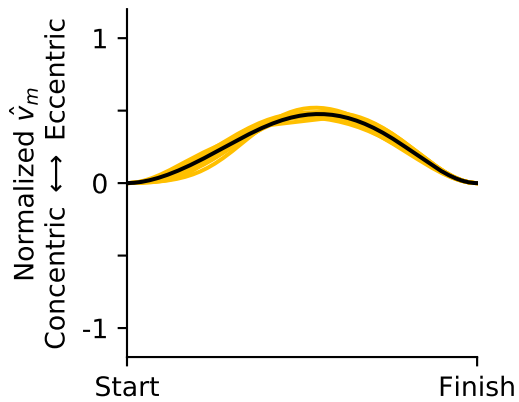
BIC



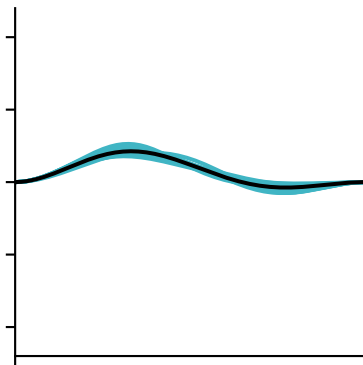
BRD



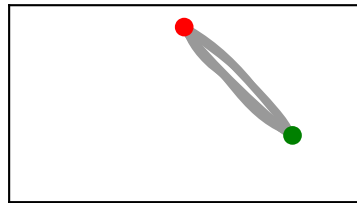
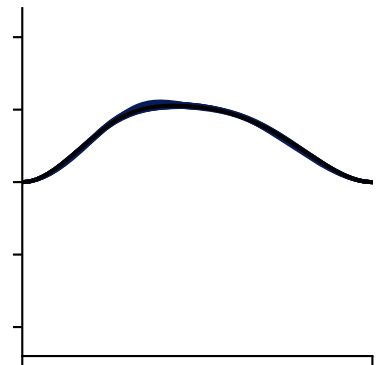
ECRB



TRI

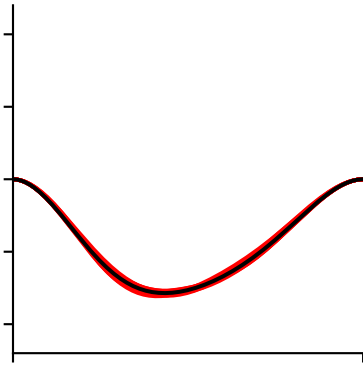


DELTP

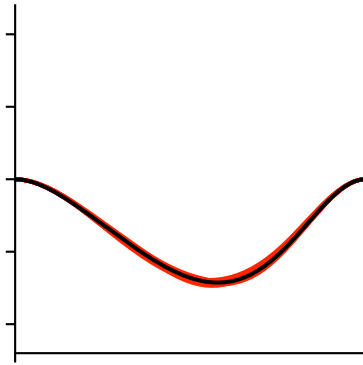


Fixed Final Position
Movement Duration : 1 sec

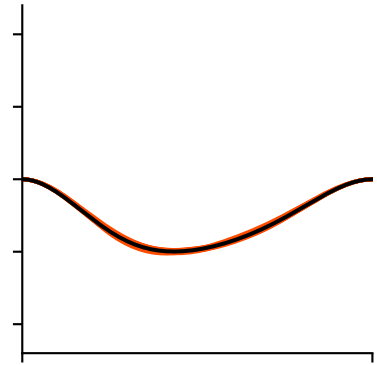
PC



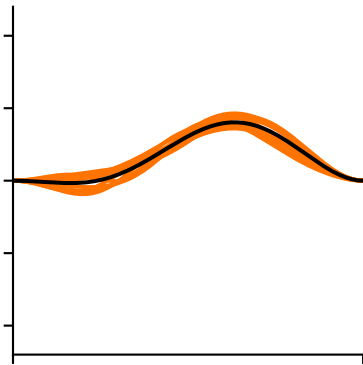
DELTAa



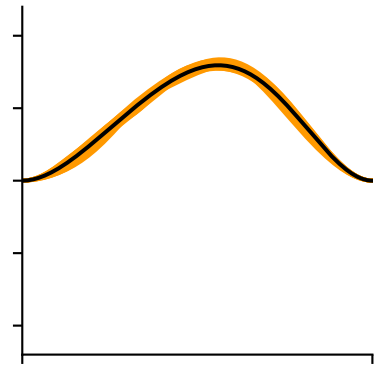
CB



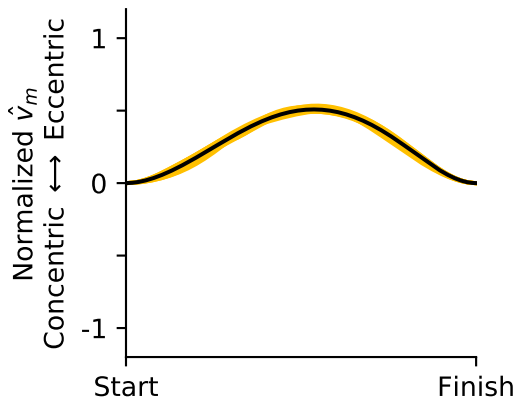
BIC



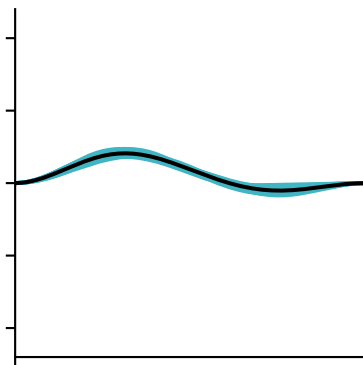
BRD



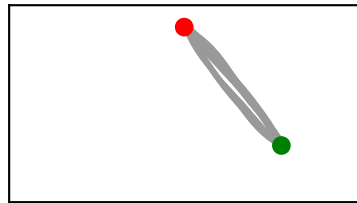
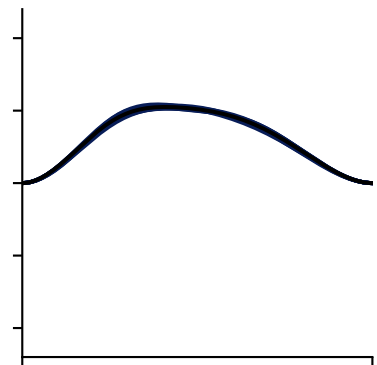
ECRB



TRI

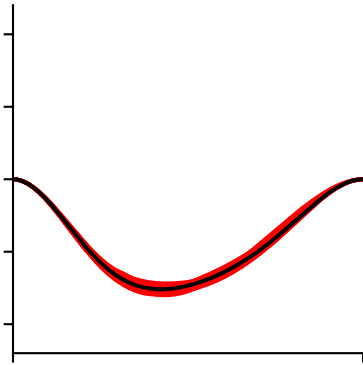


DELTP

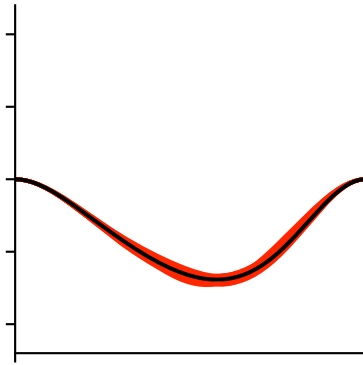


Fixed Final Position
Movement Duration : 1 sec

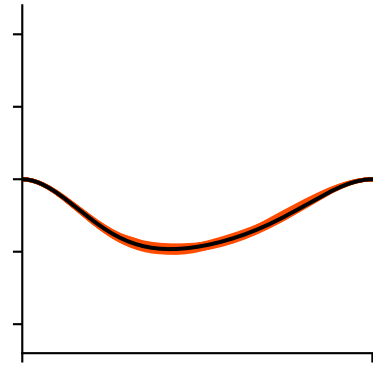
PC



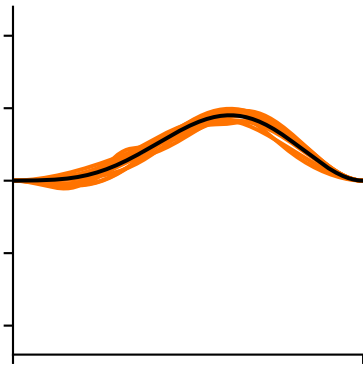
DELTA_a



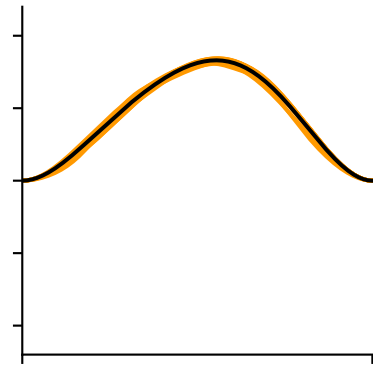
CB



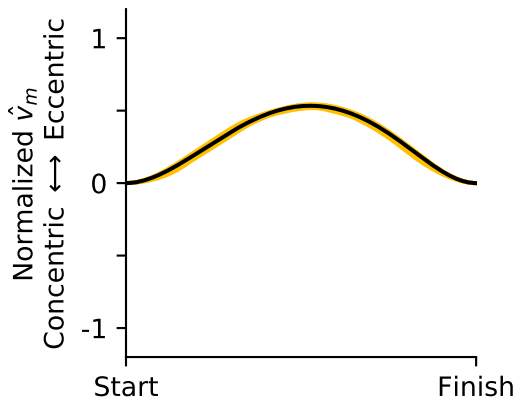
BIC



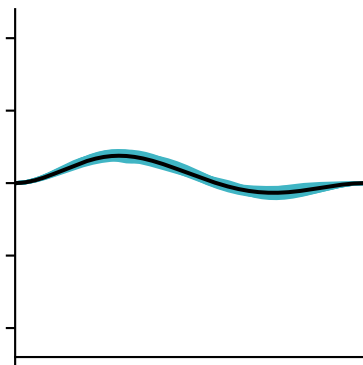
BRD



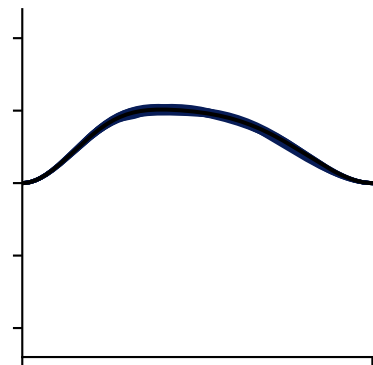
ECRB



TRI



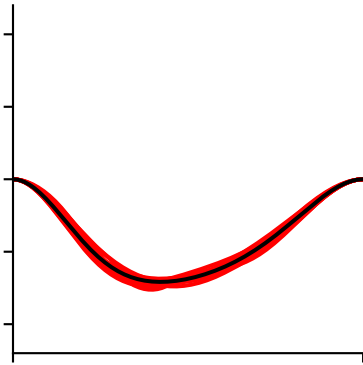
DELTA_p



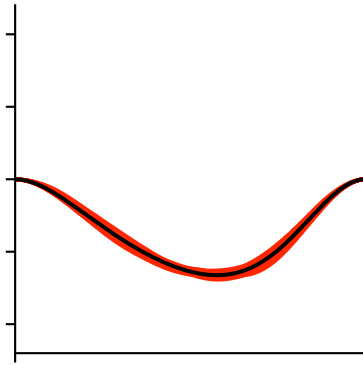
Normalized \hat{v}_m
Concentric ↔ Eccentric

Fixed Final Position
Movement Duration : 1 sec

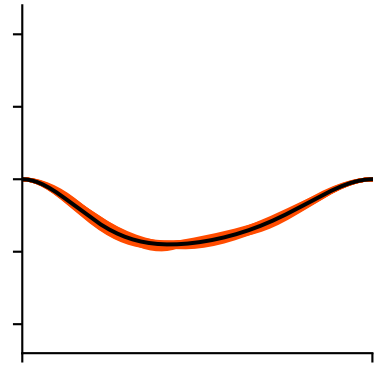
PC



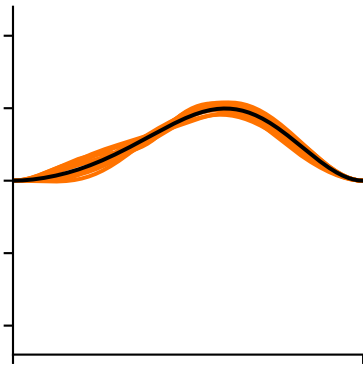
DELTAa



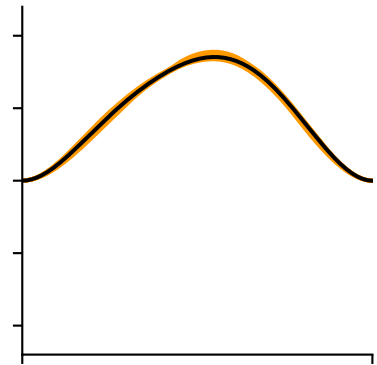
CB



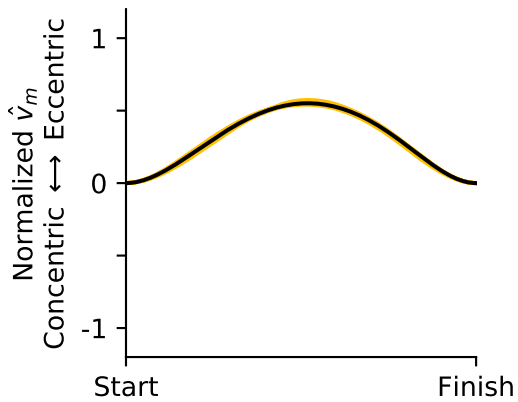
BIC



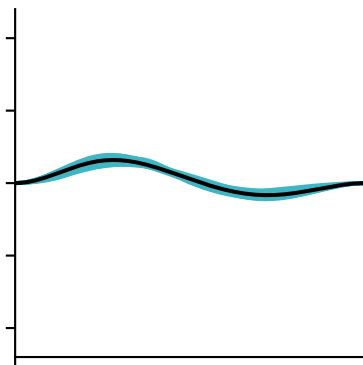
BRD



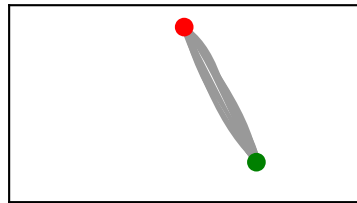
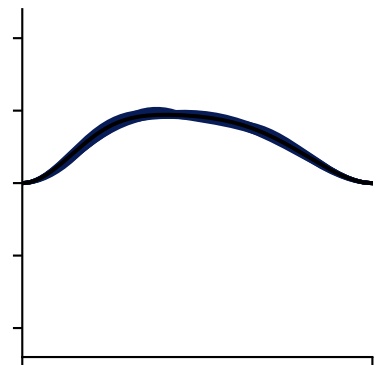
ECRB



TRI

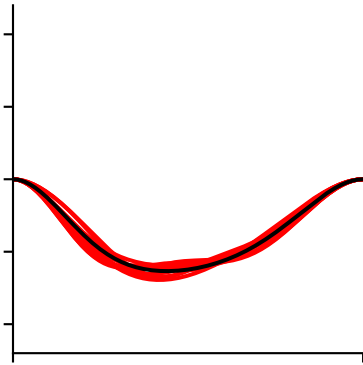


DELTP

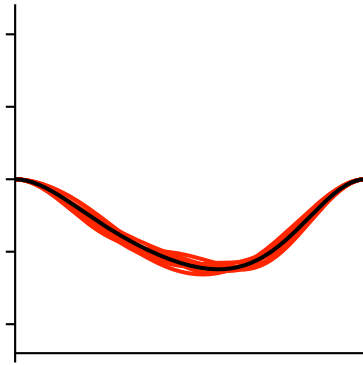


Fixed Final Position
Movement Duration : 1 sec

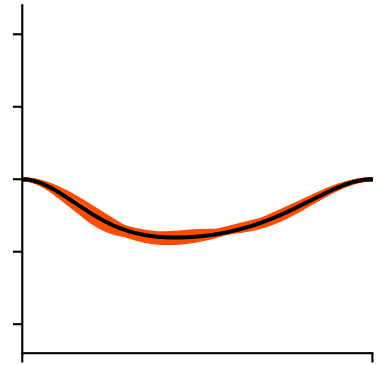
PC



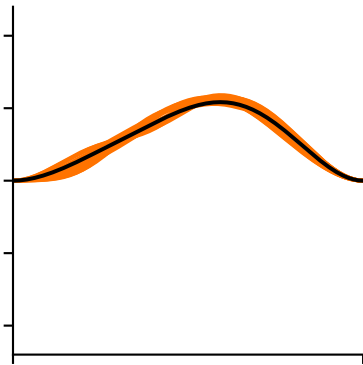
DELTAa



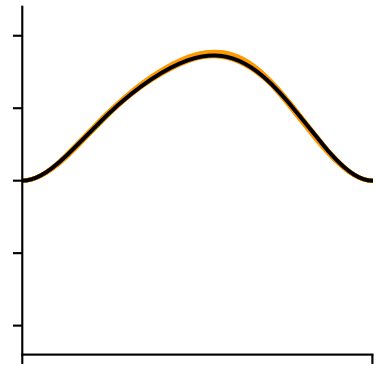
CB



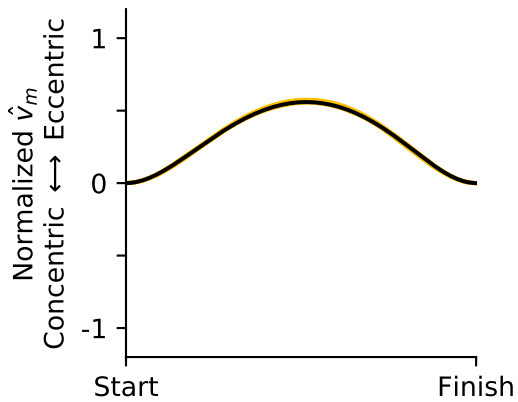
BIC



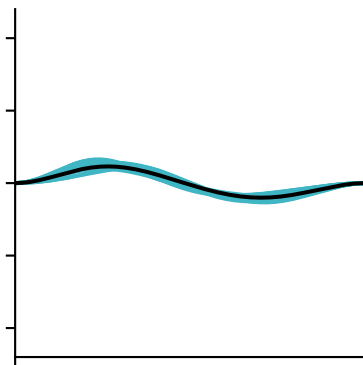
BRD



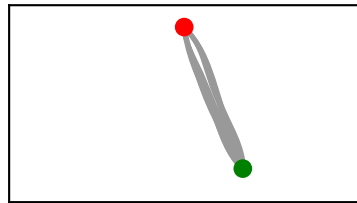
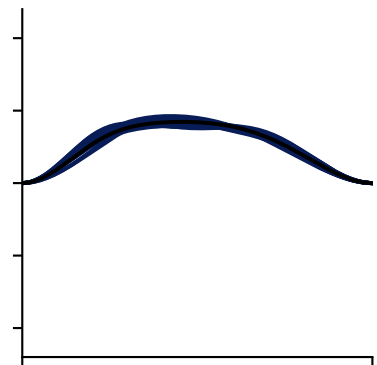
ECRB



TRI

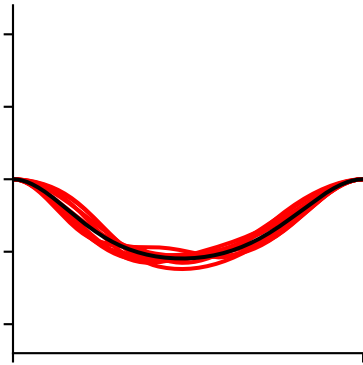


DELTP

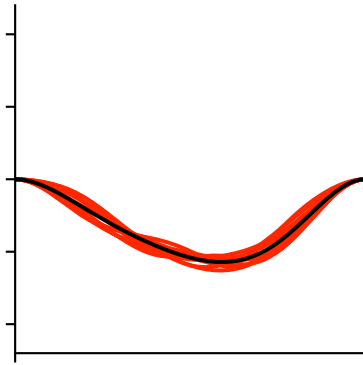


Fixed Final Position
Movement Duration : 1 sec

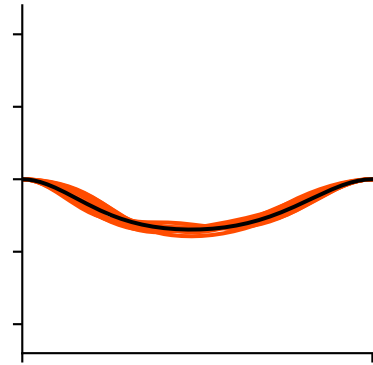
PC



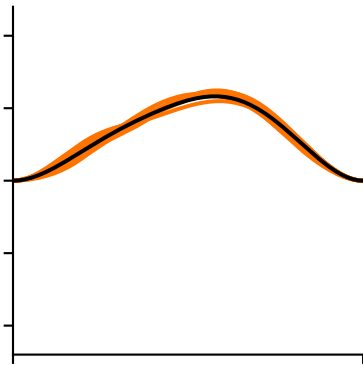
DELTAa



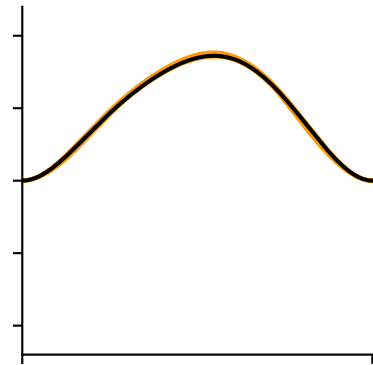
CB



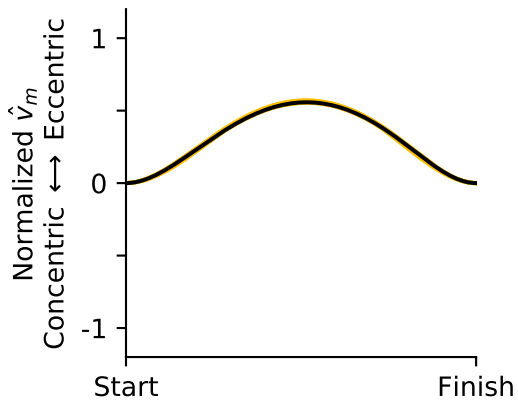
BIC



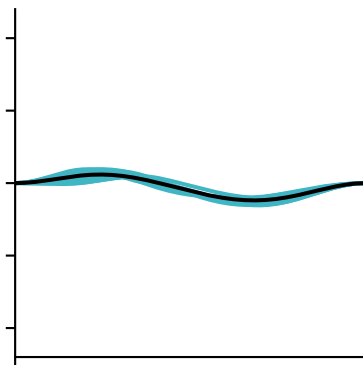
BRD



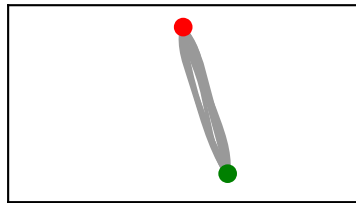
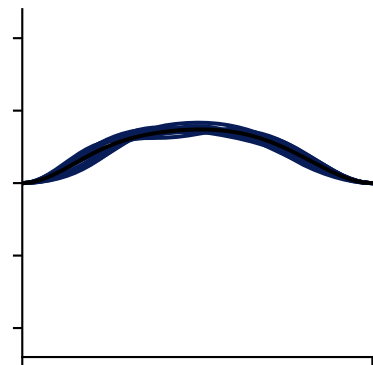
ECRB



TRI

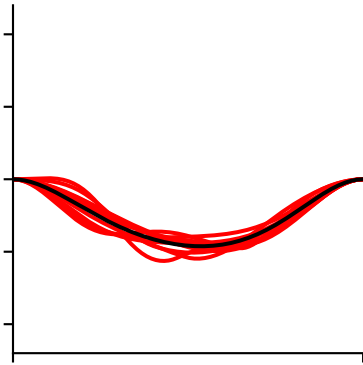


DELTP

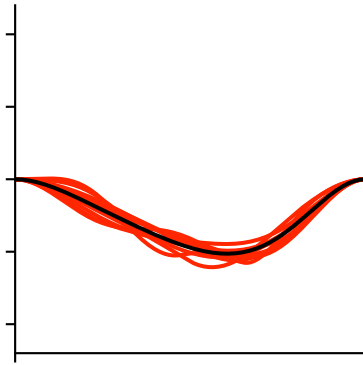


Fixed Final Position
Movement Duration : 1 sec

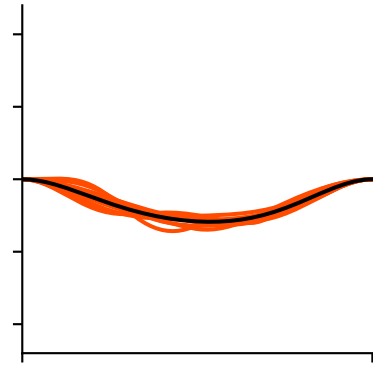
PC



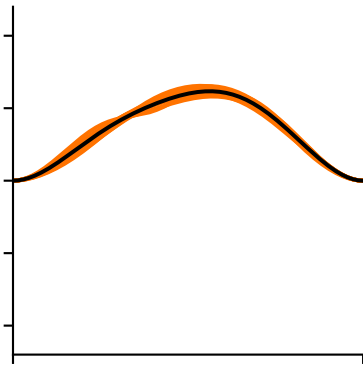
DELTAa



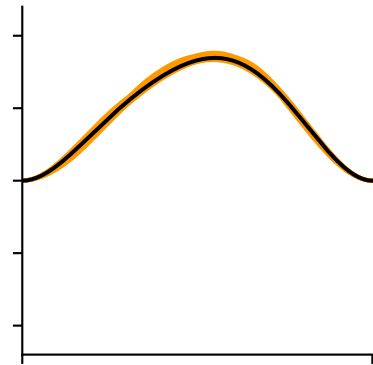
CB



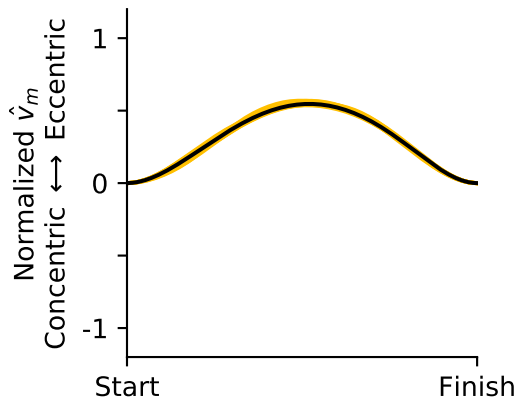
BIC



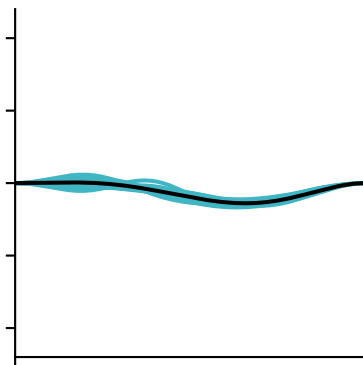
BRD



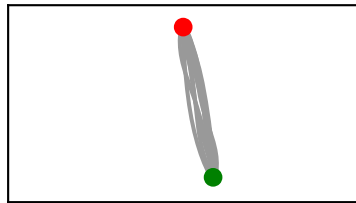
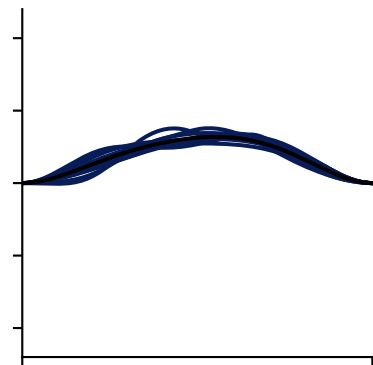
ECRB



TRI

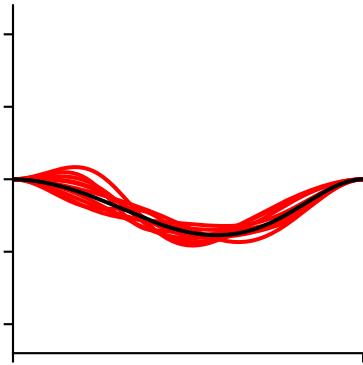


DELTP

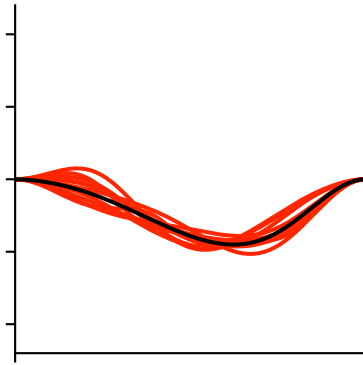


Fixed Final Position
Movement Duration : 1 sec

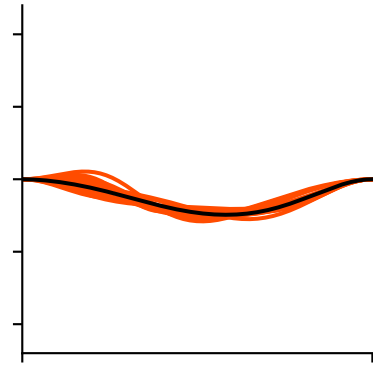
PC



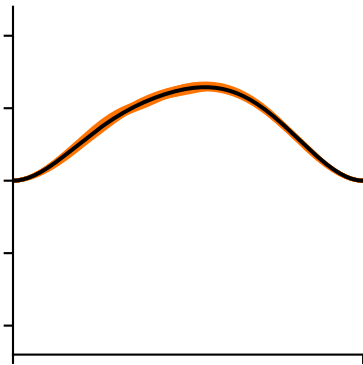
DELTAa



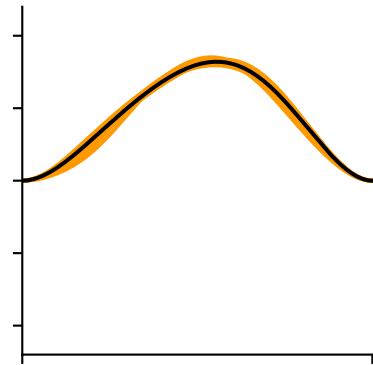
CB



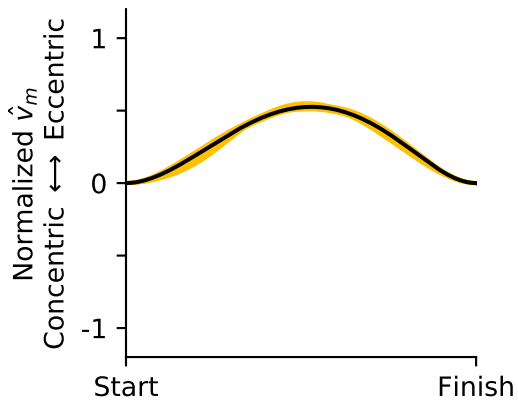
BIC



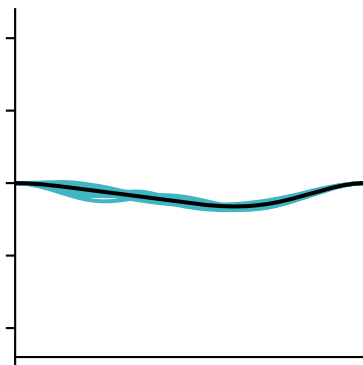
BRD



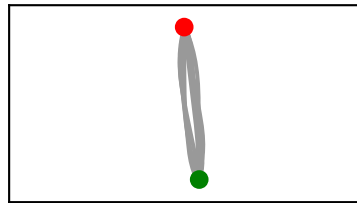
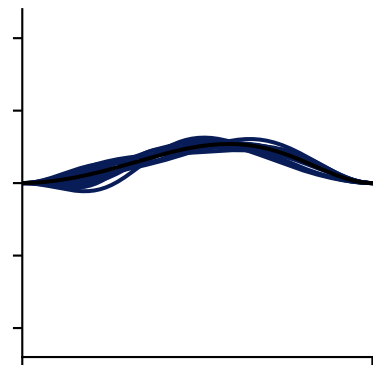
ECRB



TRI

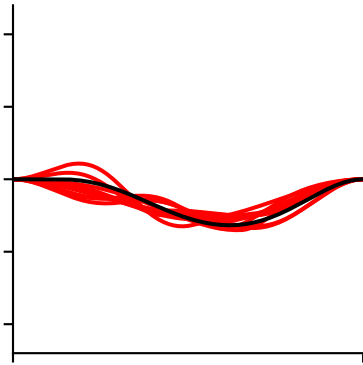


DELTP

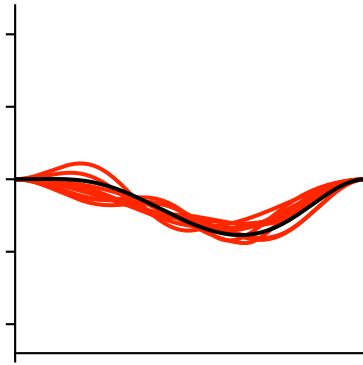


Fixed Final Position
Movement Duration : 1 sec

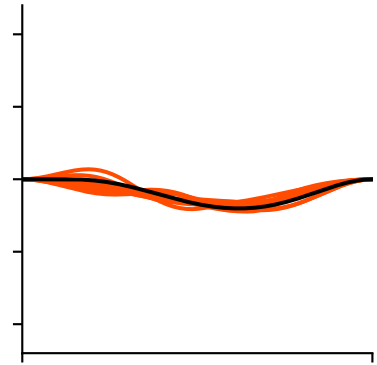
PC



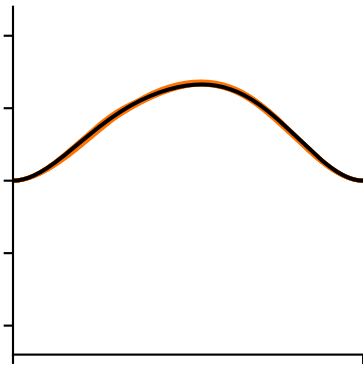
DELTAa



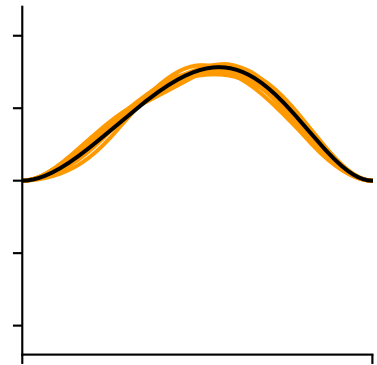
CB



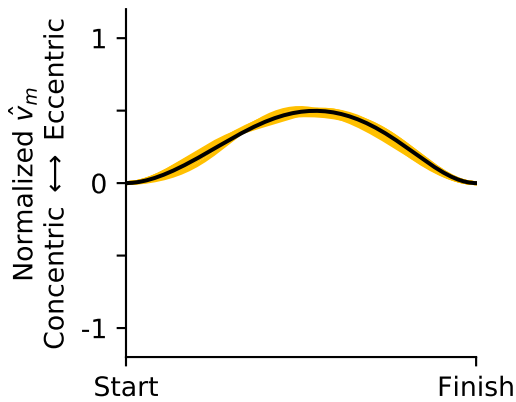
BIC



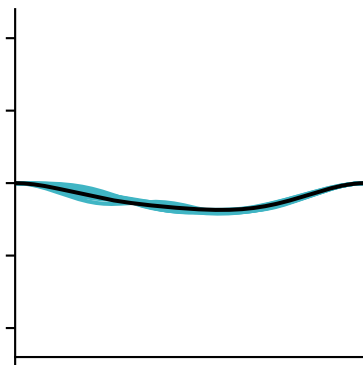
BRD



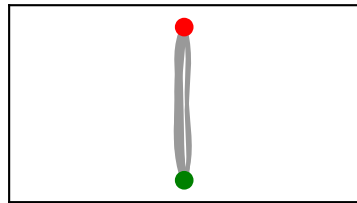
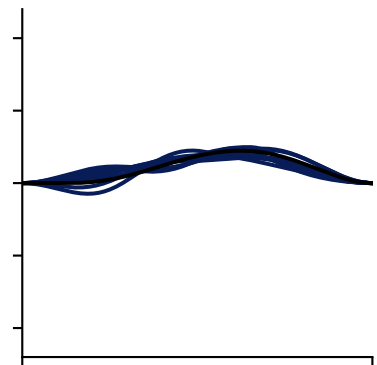
ECRB



TRI

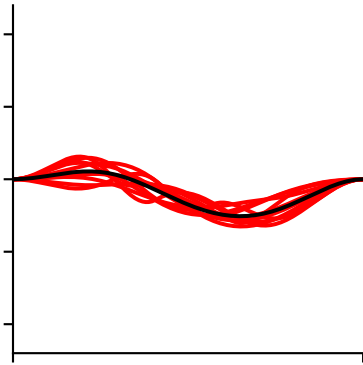


DELTP

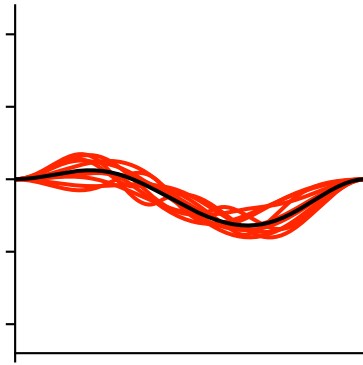


Fixed Final Position
Movement Duration : 1 sec

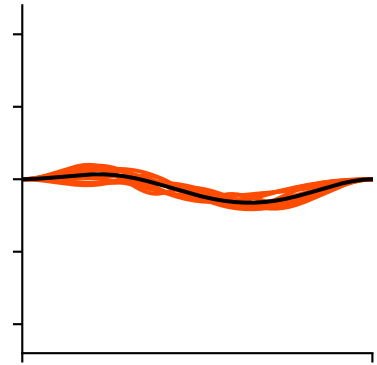
PC



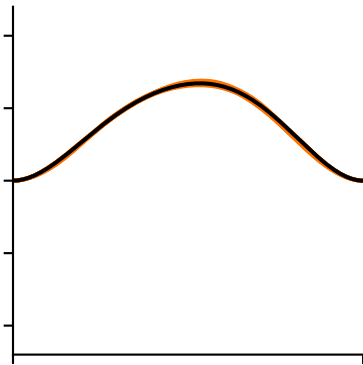
DELTa



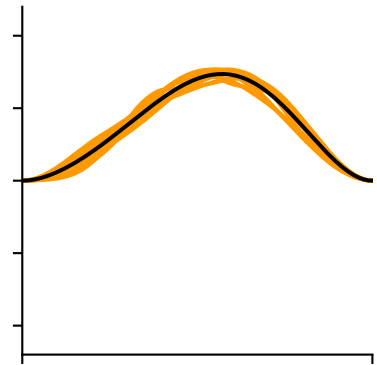
CB



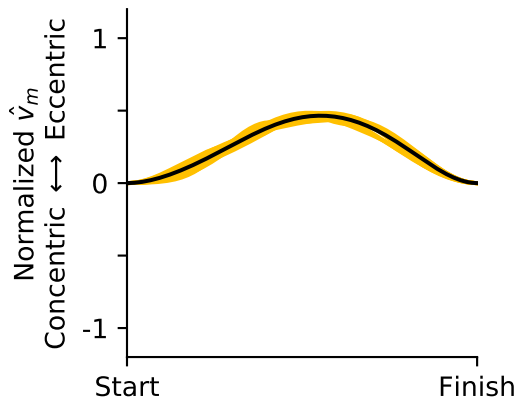
BIC



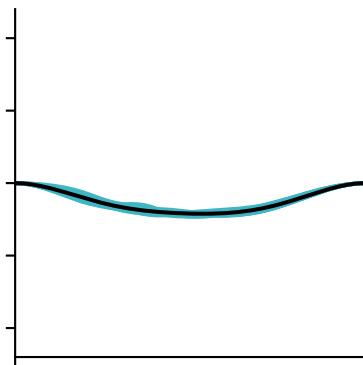
BRD



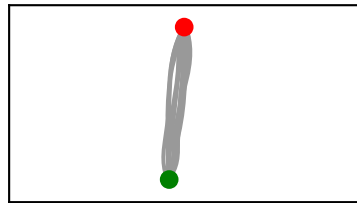
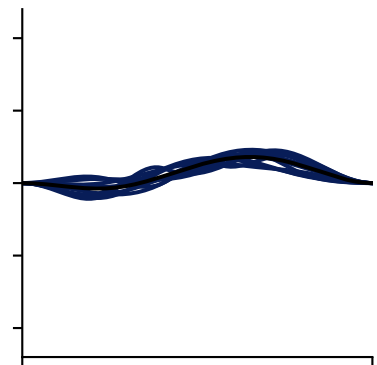
ECRB



TRI

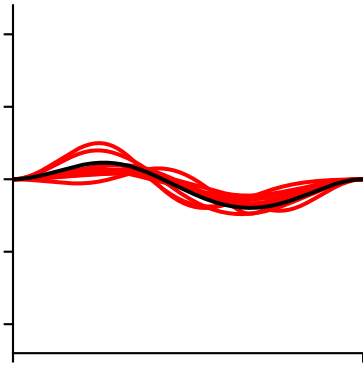


DELTp

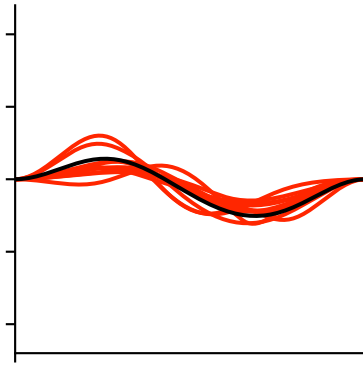


Fixed Final Position
Movement Duration : 1 sec

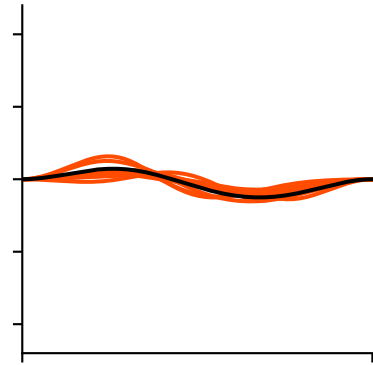
PC



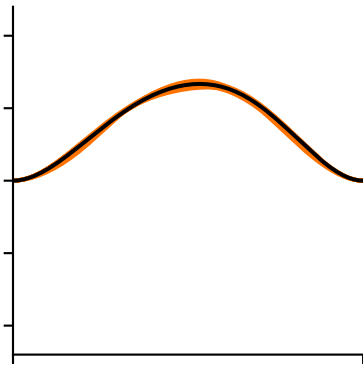
DELTAa



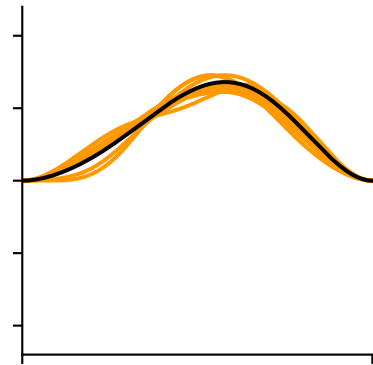
CB



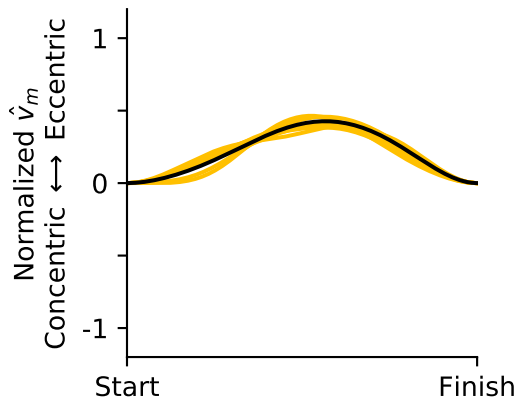
BIC



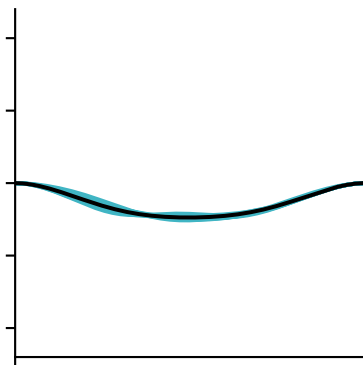
BRD



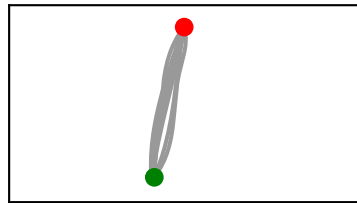
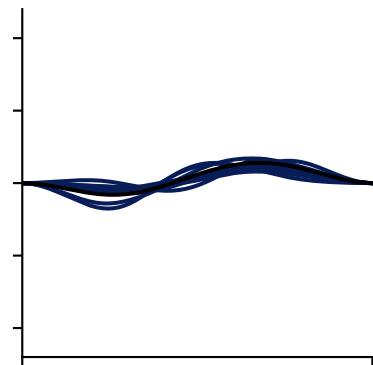
ECRB



TRI

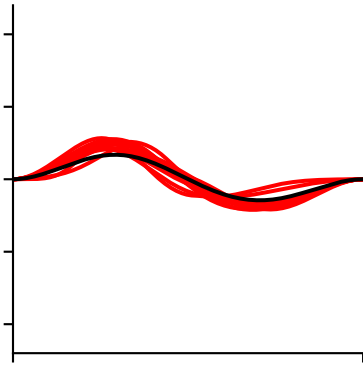


DELTP

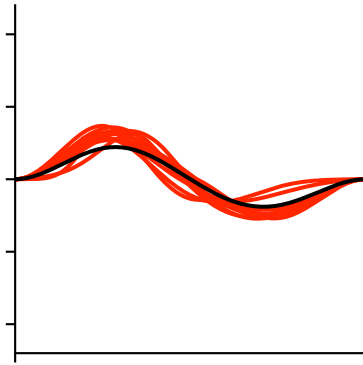


Fixed Final Position
Movement Duration : 1 sec

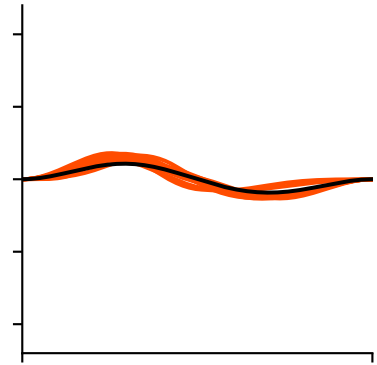
PC



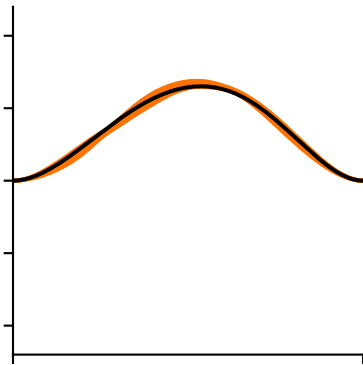
DELTAa



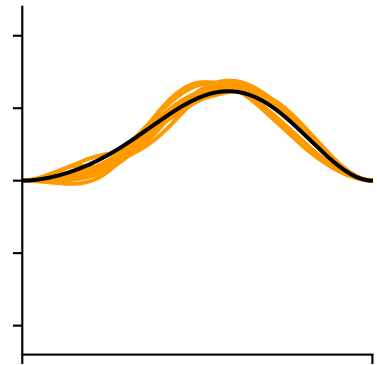
CB



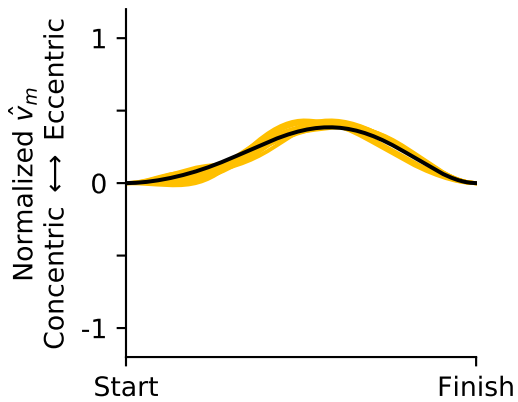
BIC



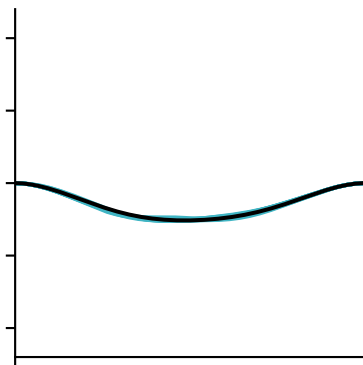
BRD



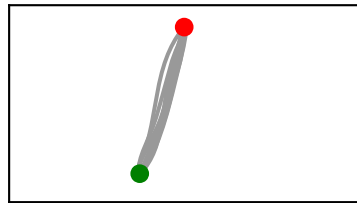
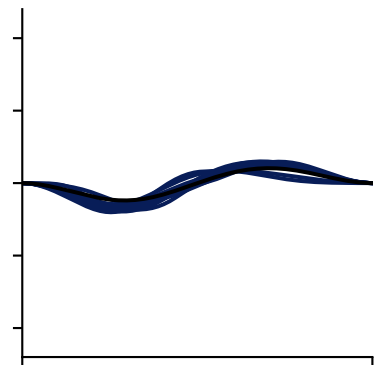
ECRB



TRI

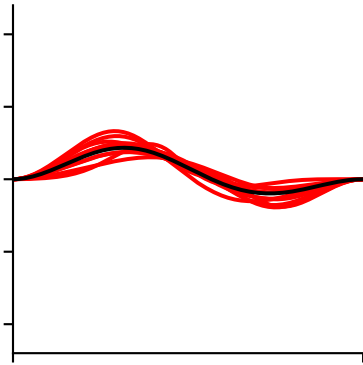


DELTP

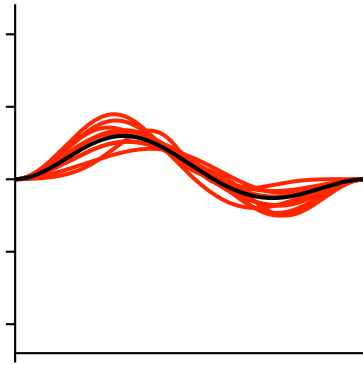


Fixed Final Position
Movement Duration : 1 sec

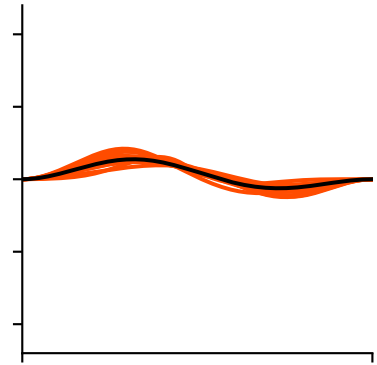
PC



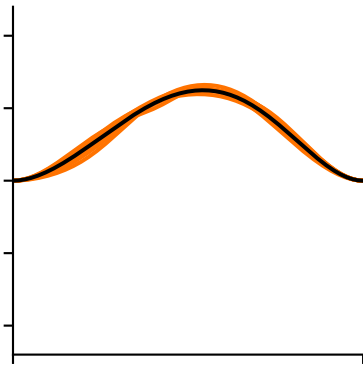
DELTAa



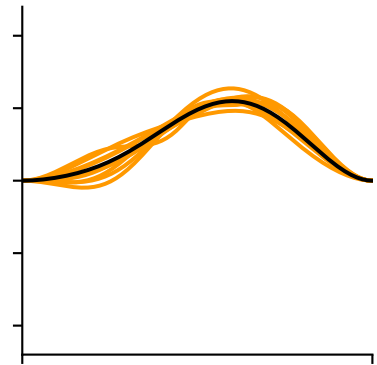
CB



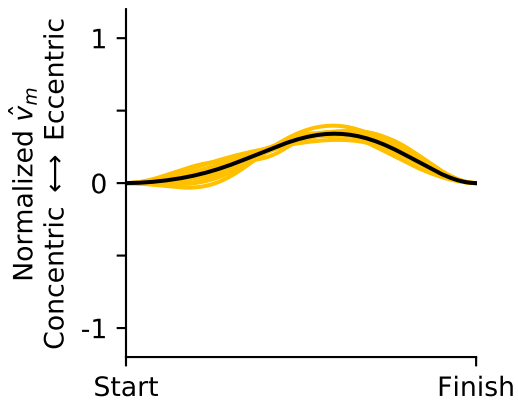
BIC



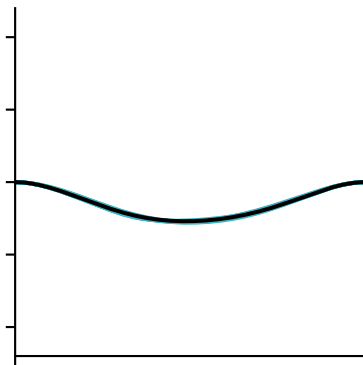
BRD



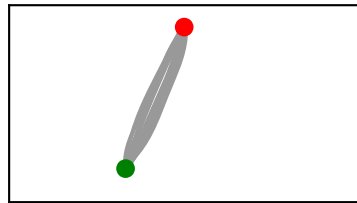
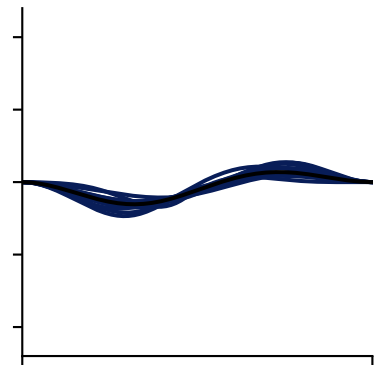
ECRB



TRI

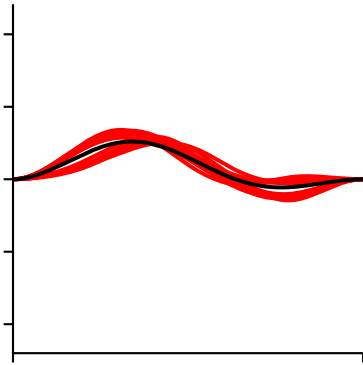


DELTP

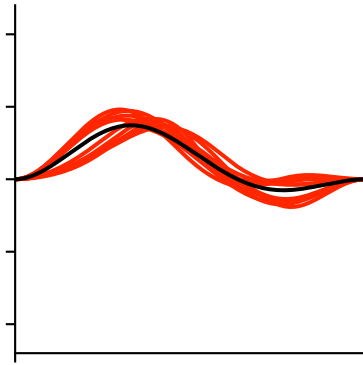


Fixed Final Position
Movement Duration : 1 sec

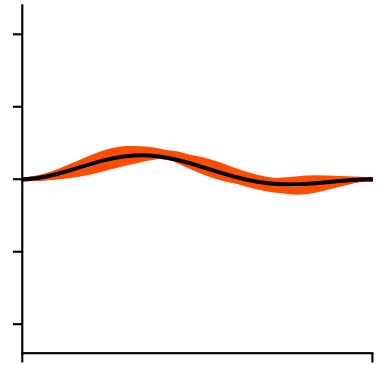
PC



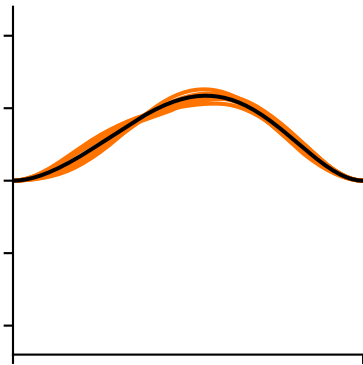
DELTAa



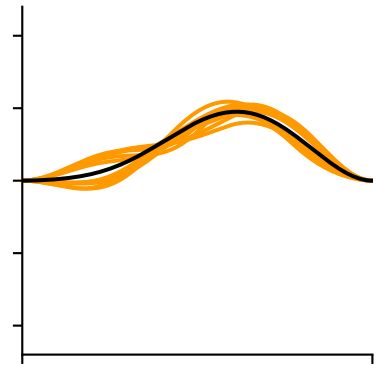
CB



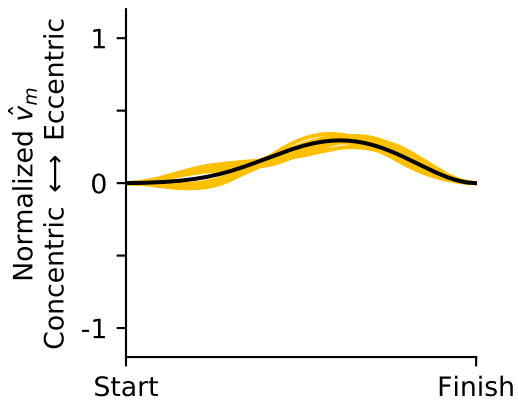
BIC



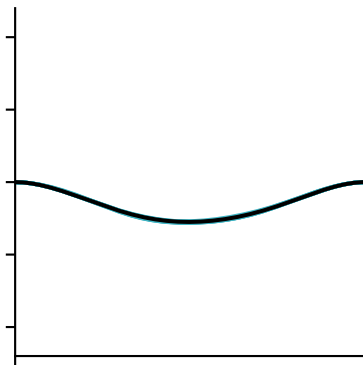
BRD



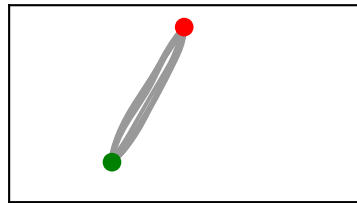
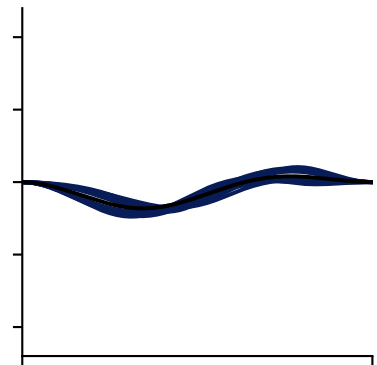
ECRB



TRI

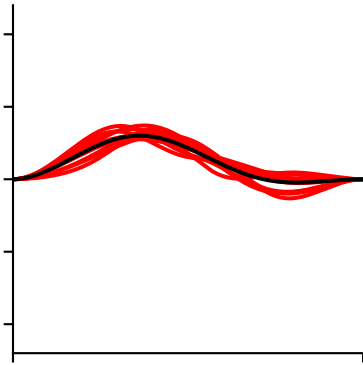


DELTP

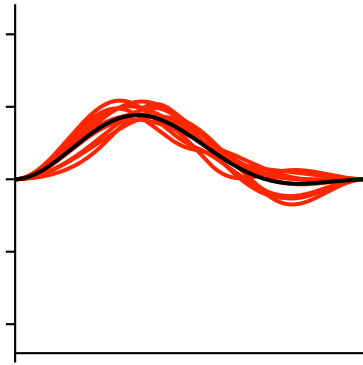


Fixed Final Position
Movement Duration : 1 sec

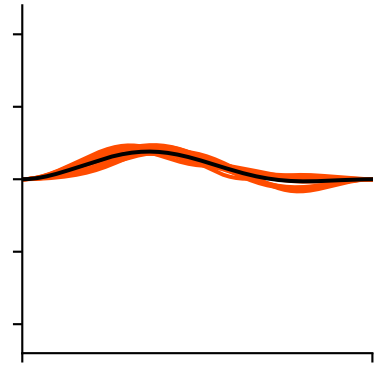
PC



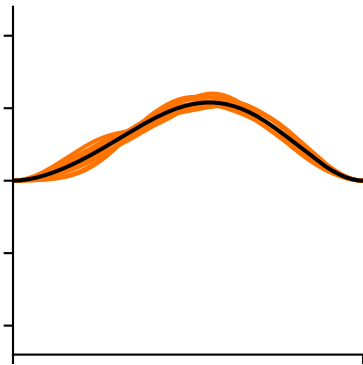
DELTAa



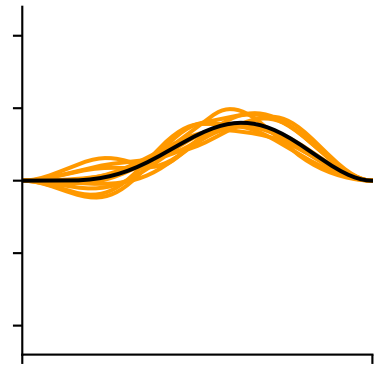
CB



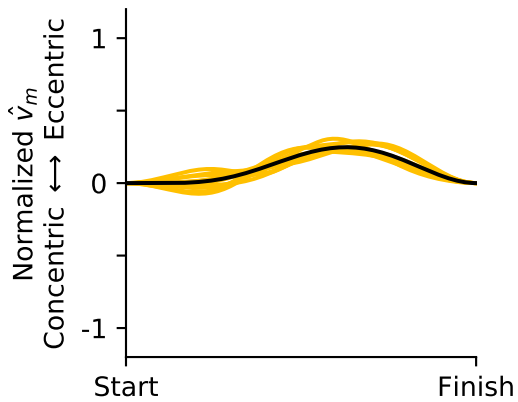
BIC



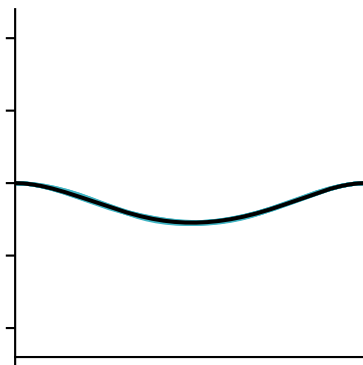
BRD



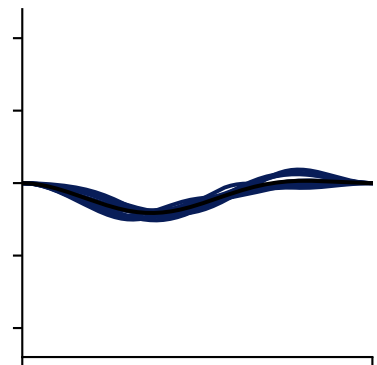
ECRB



TRI

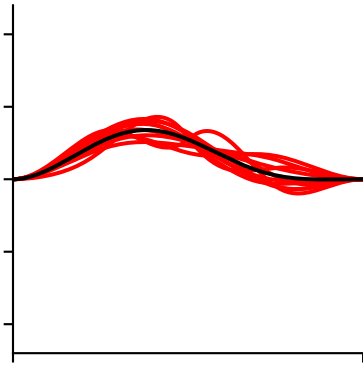


DELTP

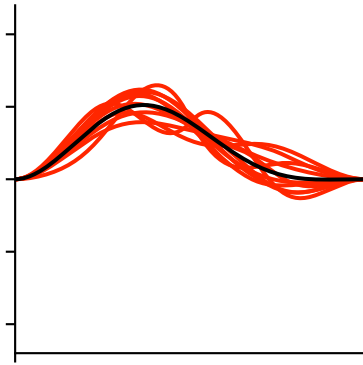


Fixed Final Position
Movement Duration : 1 sec

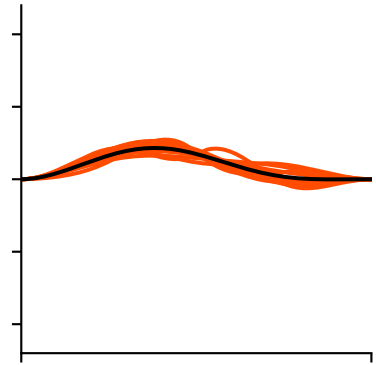
PC



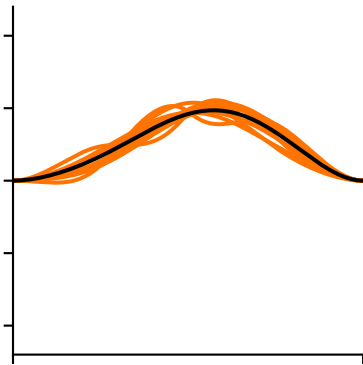
DELTAa



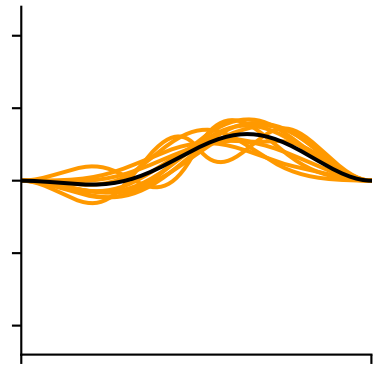
CB



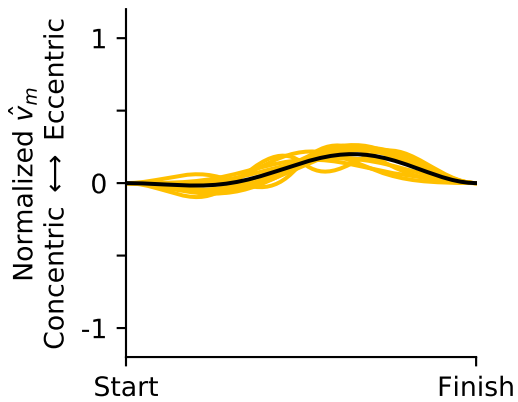
BIC



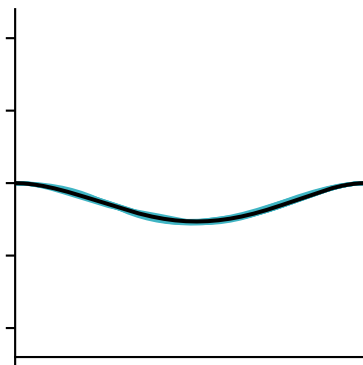
BRD



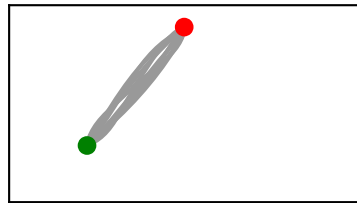
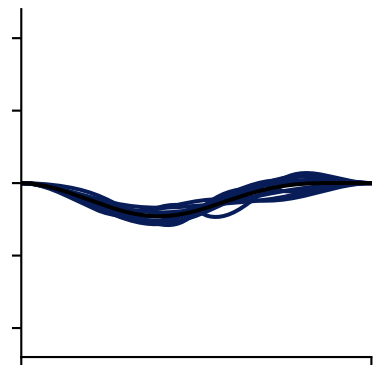
ECRB



TRI

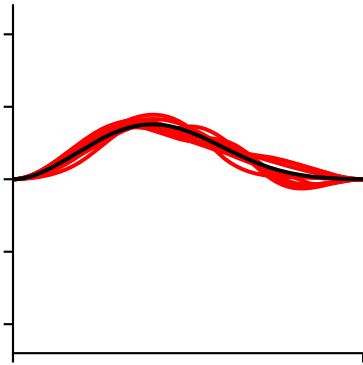


DELTP

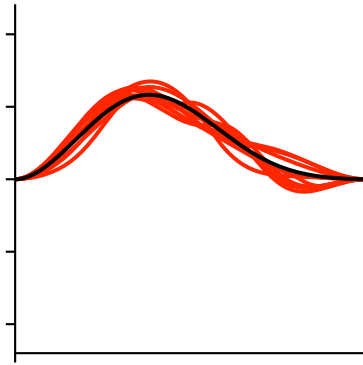


Fixed Final Position
Movement Duration : 1 sec

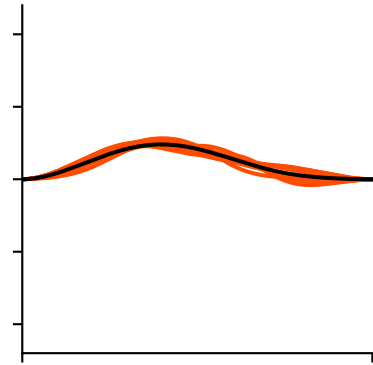
PC



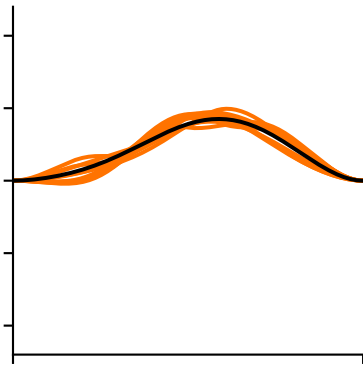
DELTa



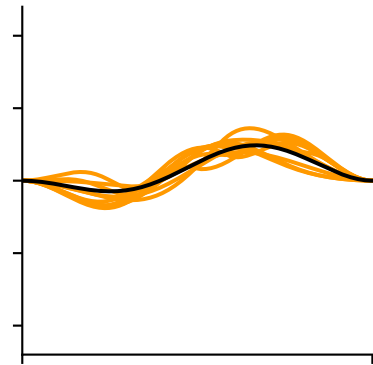
CB



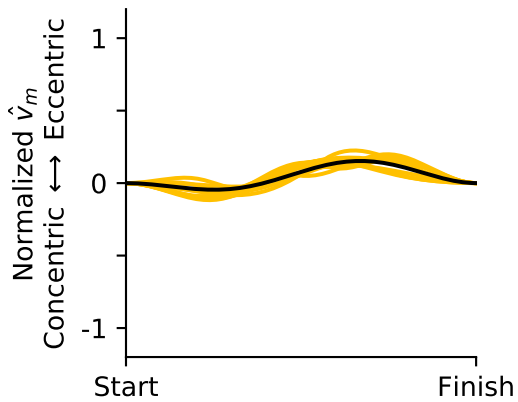
BIC



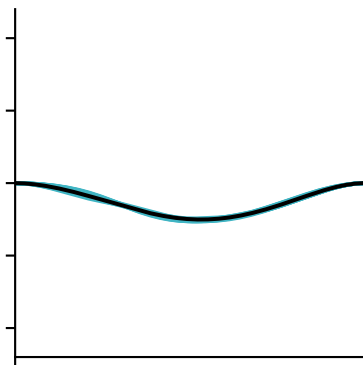
BRD



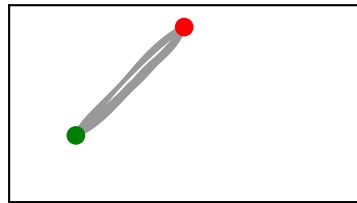
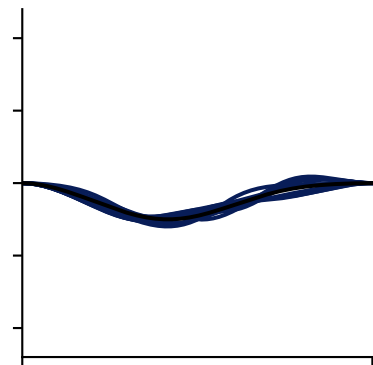
ECRB



TRI

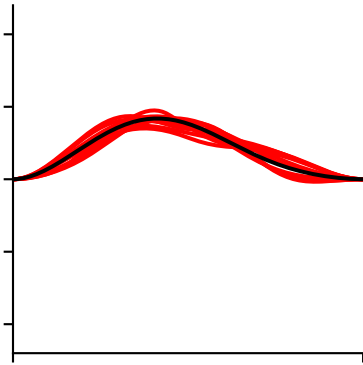


DELTp

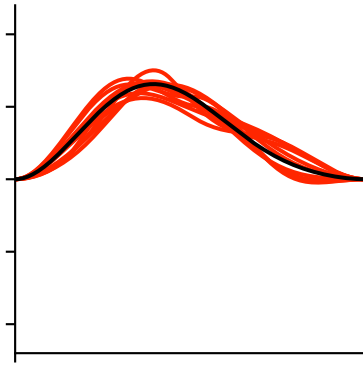


Fixed Final Position
Movement Duration : 1 sec

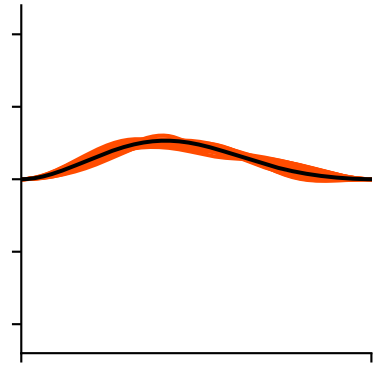
PC



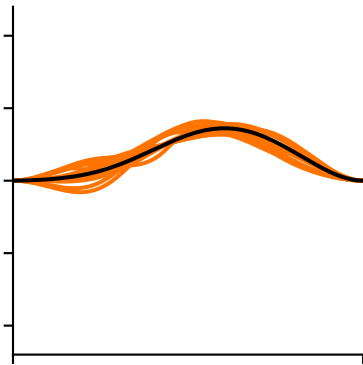
DELTAa



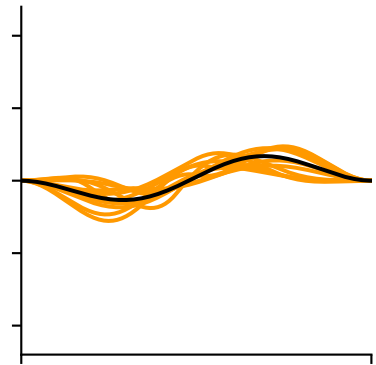
CB



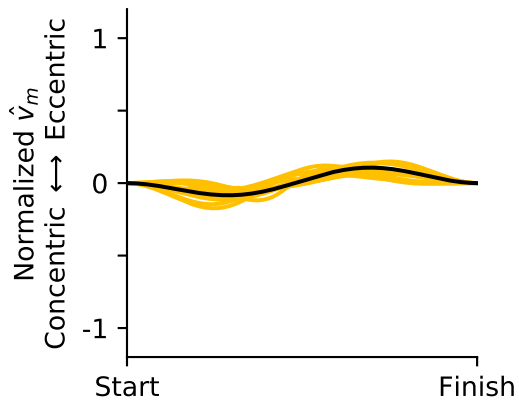
BIC



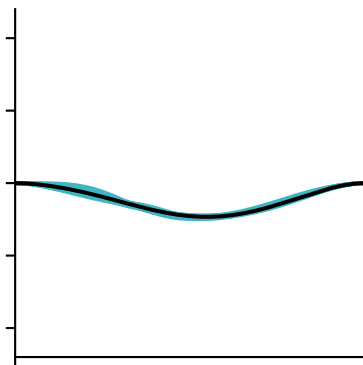
BRD



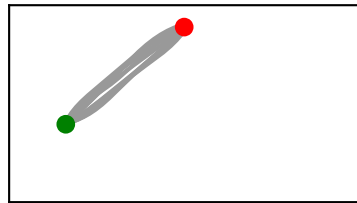
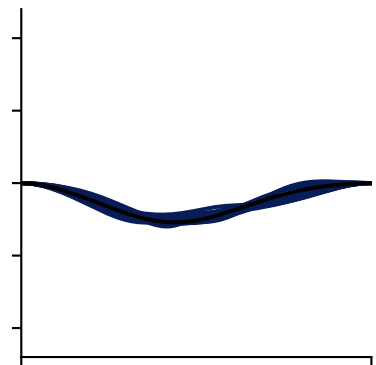
ECRB



TRI

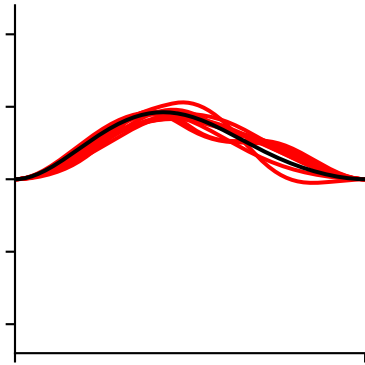


DELTP

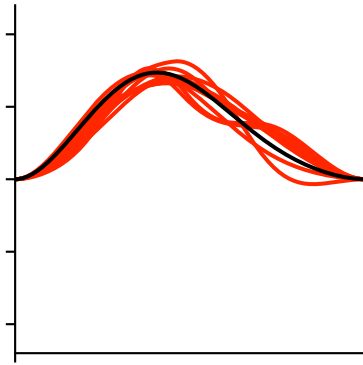


Fixed Final Position
Movement Duration : 1 sec

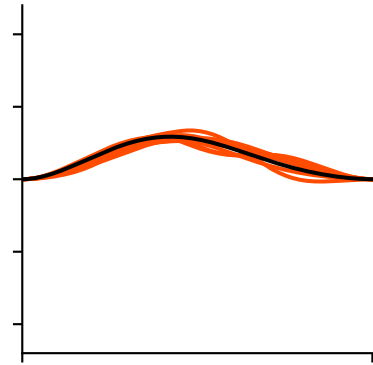
PC



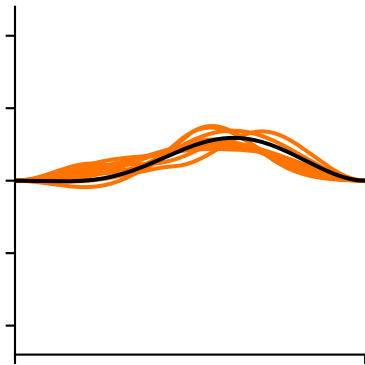
DELTAa



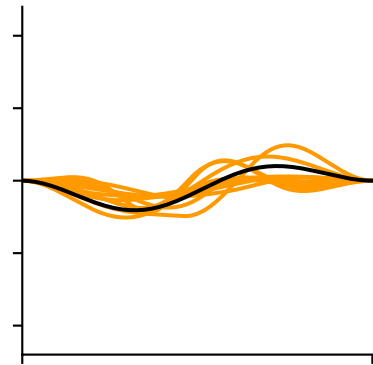
CB



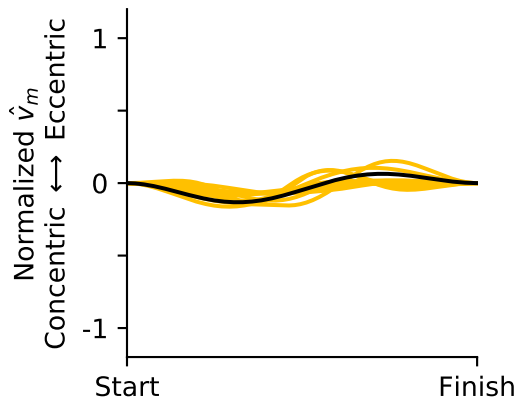
BIC



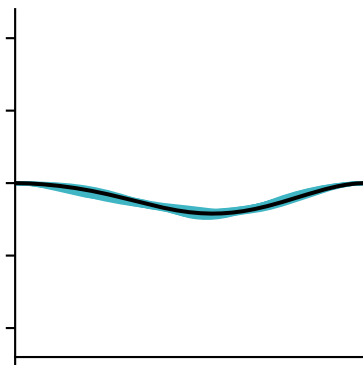
BRD



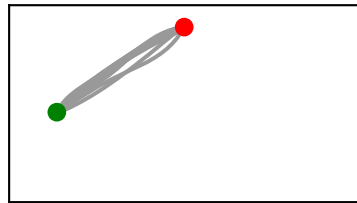
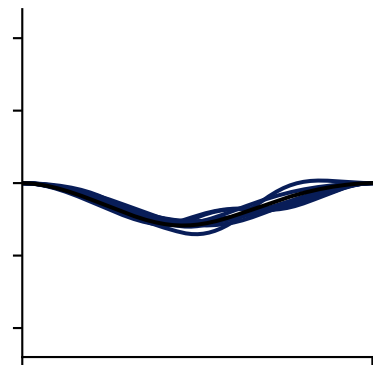
ECRB



TRI

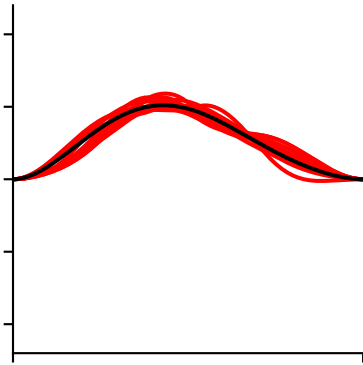


DELTP

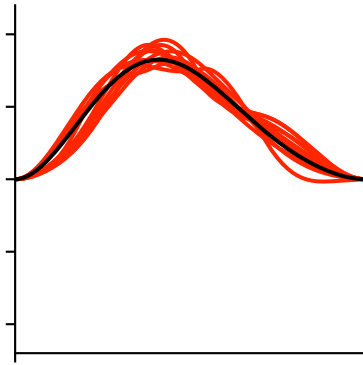


Fixed Final Position
Movement Duration : 1 sec

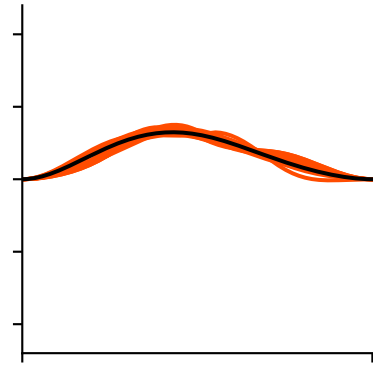
PC



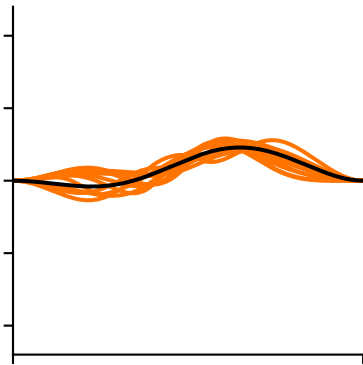
DELTAa



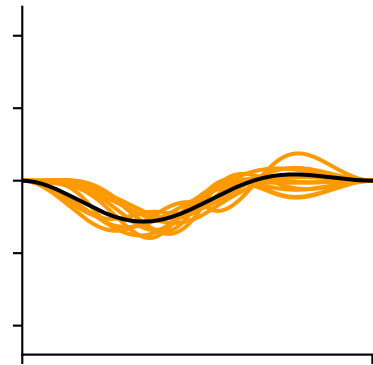
CB



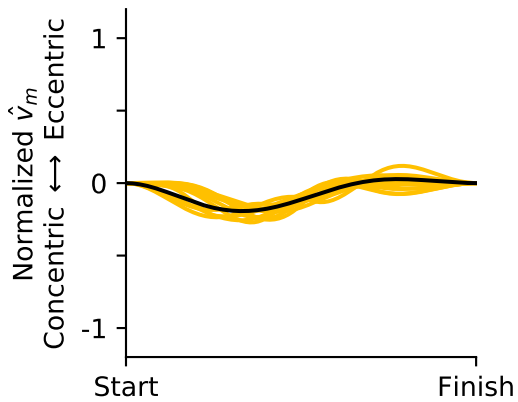
BIC



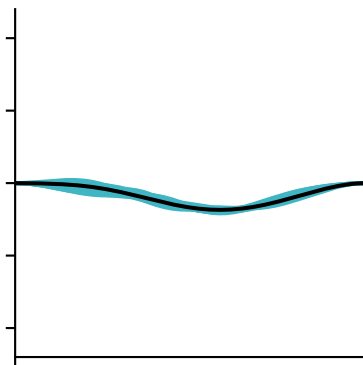
BRD



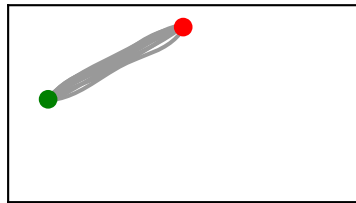
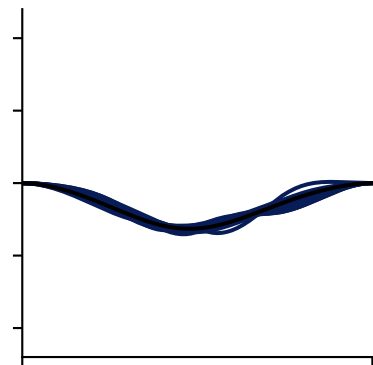
ECRB



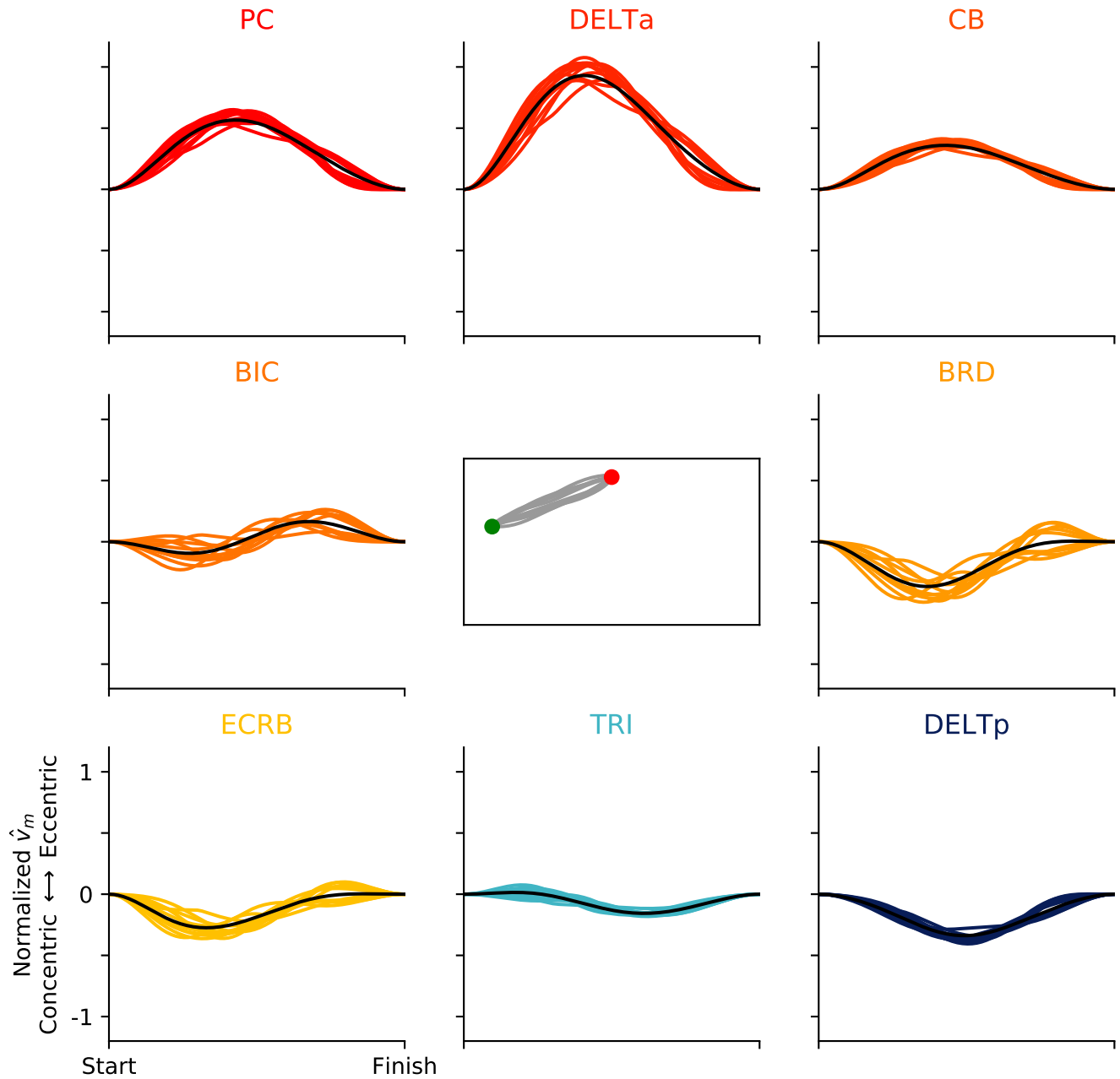
TRI



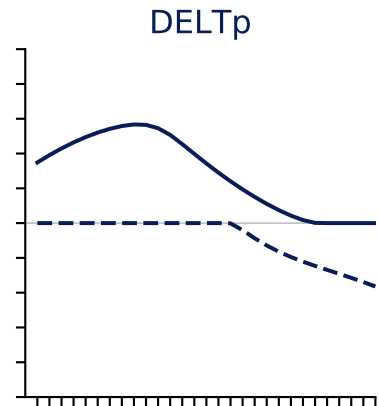
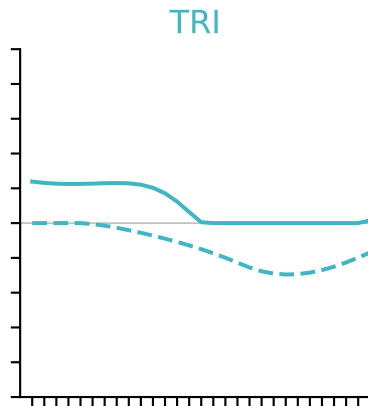
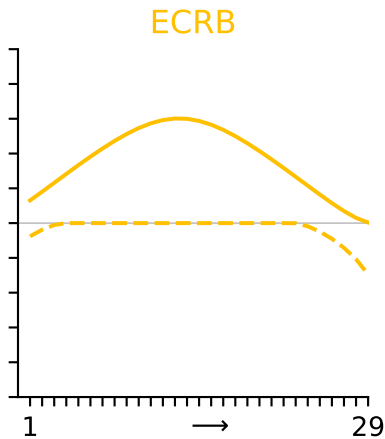
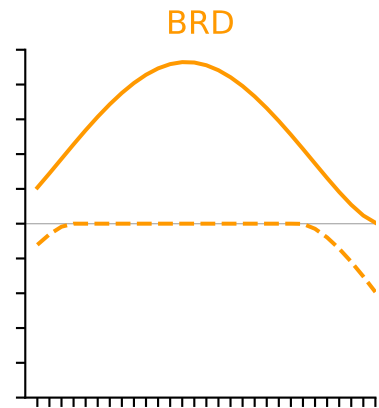
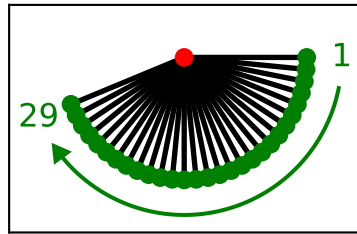
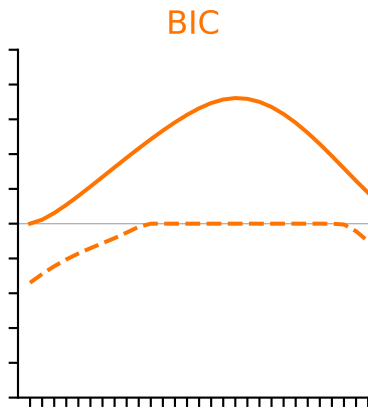
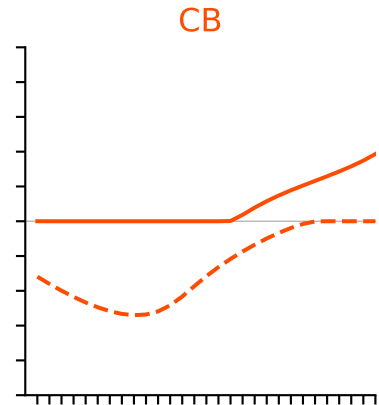
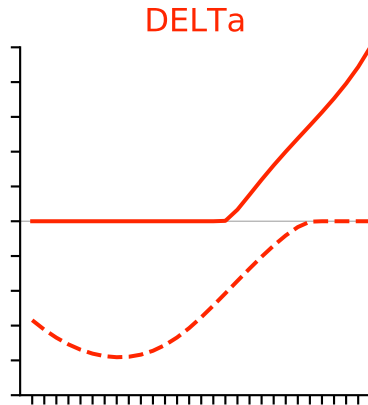
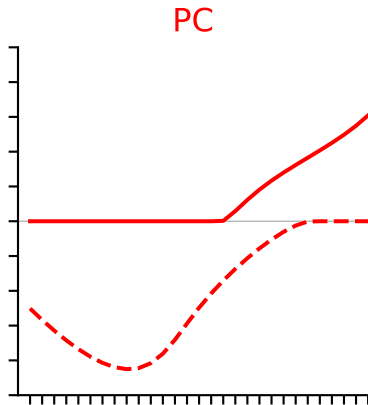
DELTP



Fixed Final Position
Movement Duration : 1 sec



Fixed Final Position
Movement Duration : 1 sec



Normalized \hat{v}_m
Concentric \leftrightarrow Eccentric

0.93

0

-0.93

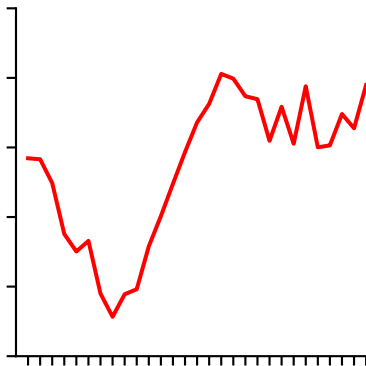
1

\rightarrow

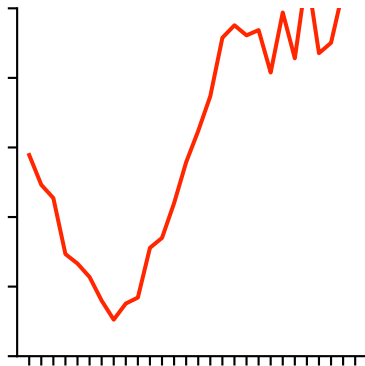
29

Fixed Final Position
Movement Duration : 1 sec

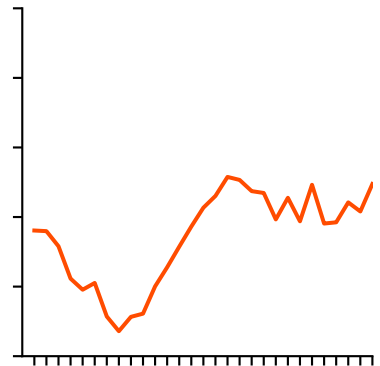
PC



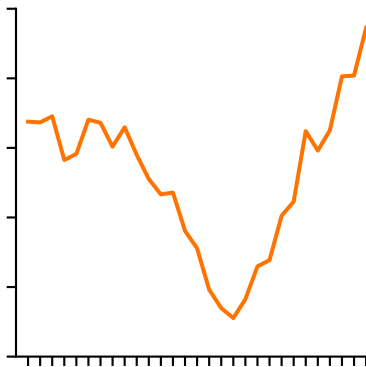
DELTAa



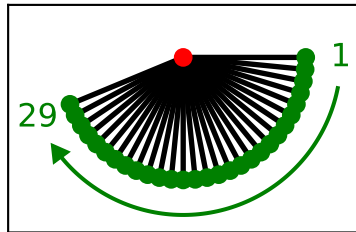
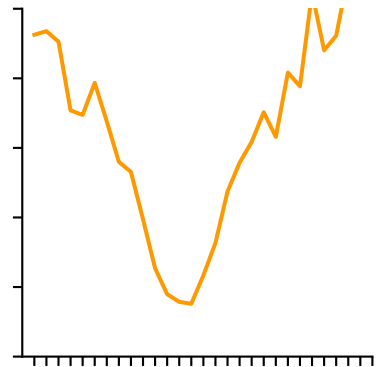
CB



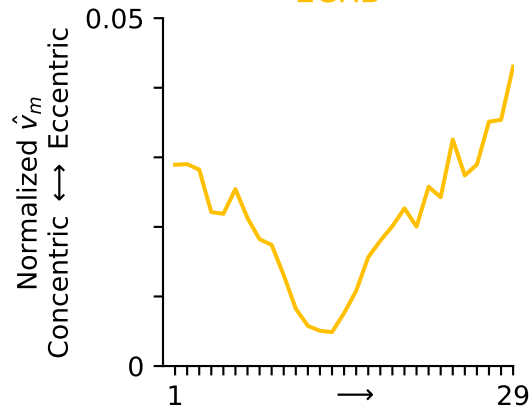
BIC



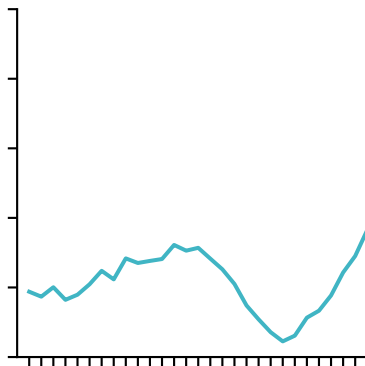
BRD



ECRB



TRI



DELTP

