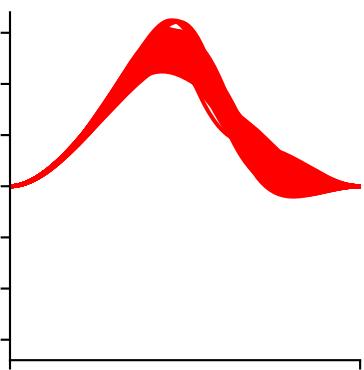
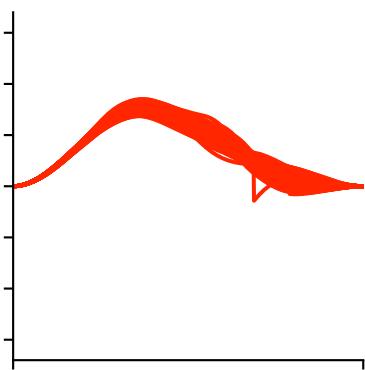


Fixed Initial Position
Movement Duration : 1 sec

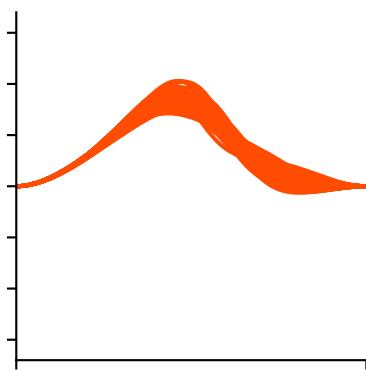
PC



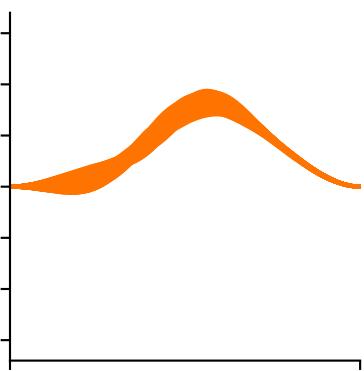
DELTa



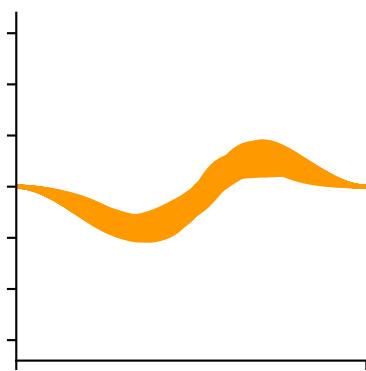
CB



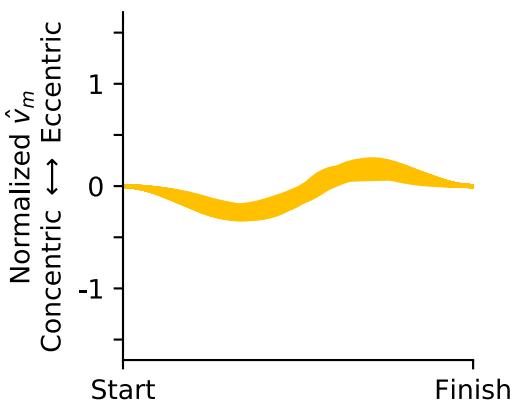
BIC



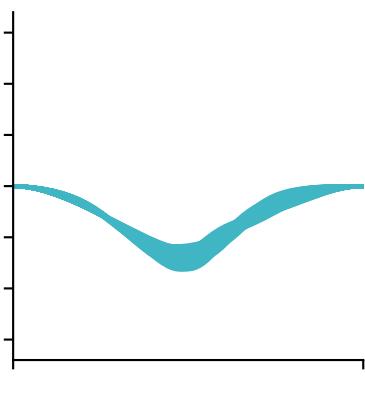
BRD



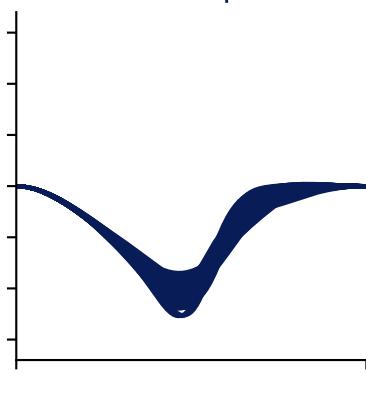
ECRB



TRI



DELTp



Normalized \dot{V}_m → Eccentric

1

0

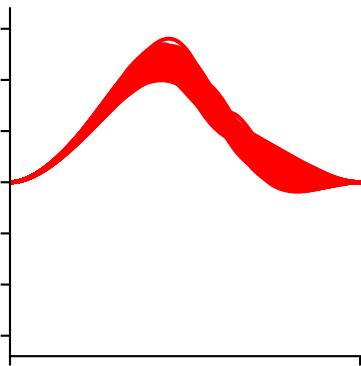
-1

Start

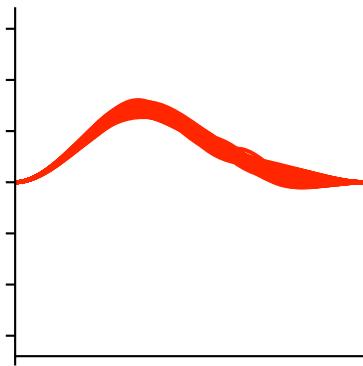
Finish

Fixed Initial Position
Movement Duration : 1 sec

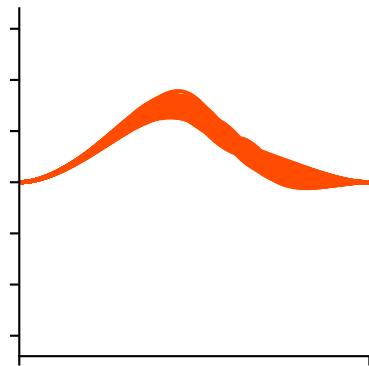
PC



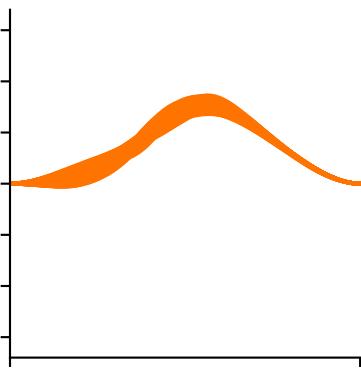
DELTa



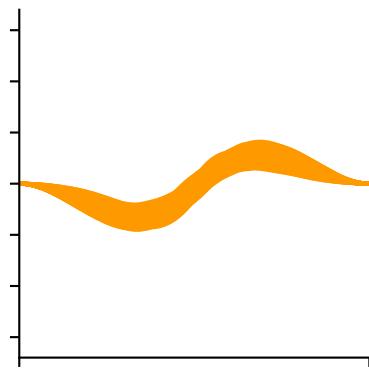
CB



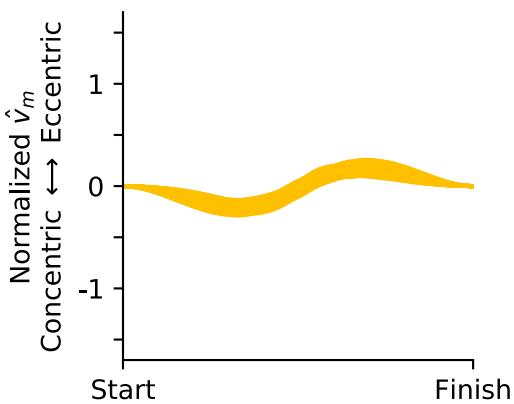
BIC



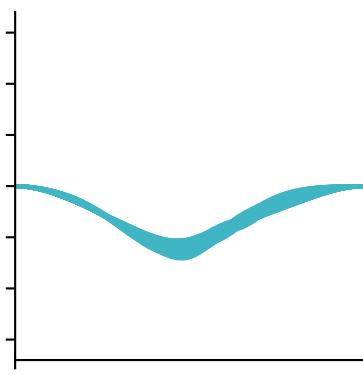
BRD



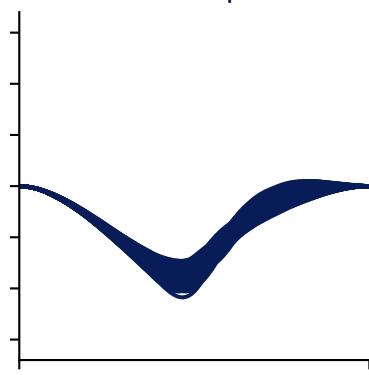
ECRB



TRI



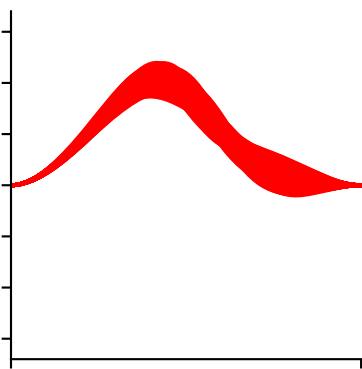
DELTp



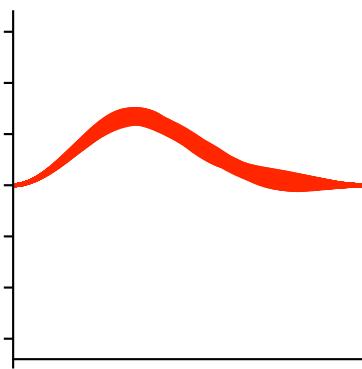
Normalized \dot{V}_m → Eccentric

Fixed Initial Position
Movement Duration : 1 sec

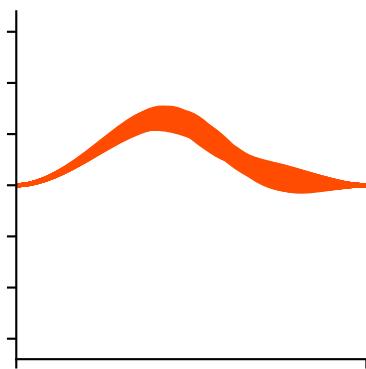
PC



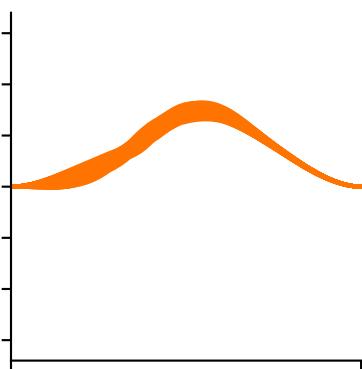
DELTa



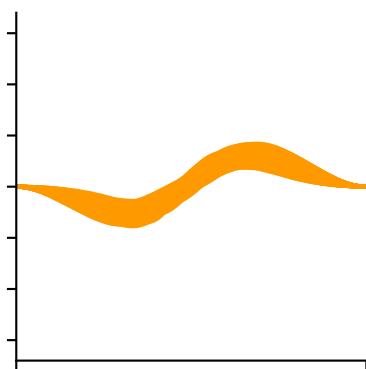
CB



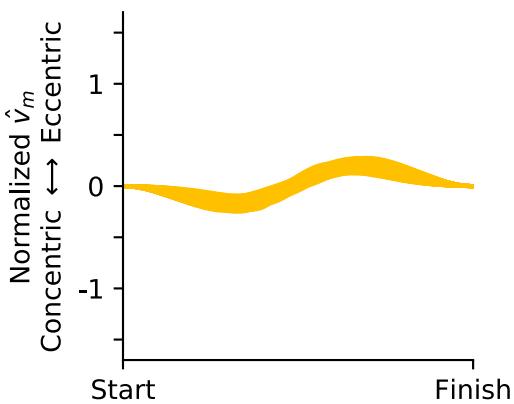
BIC



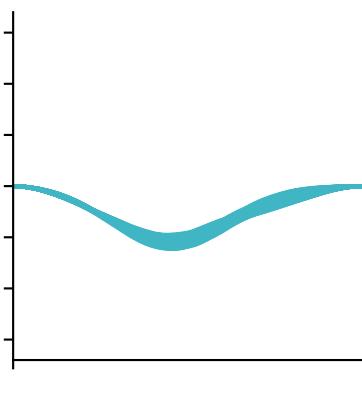
BRD



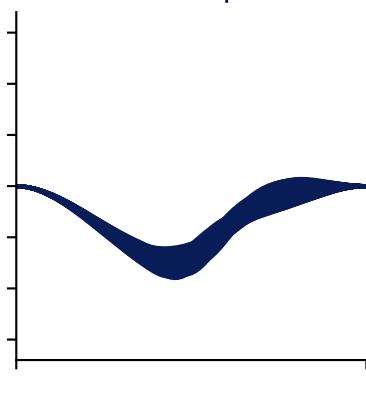
ECRB



TRI



DELTp

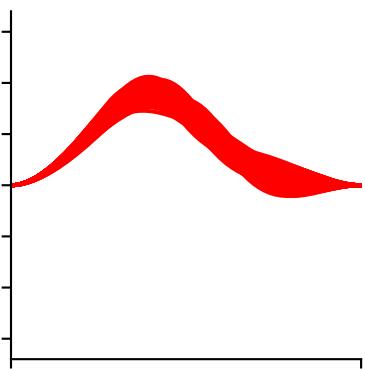


Normalized \hat{V}_m Eccentric
Concentric \leftrightarrow Eccentric

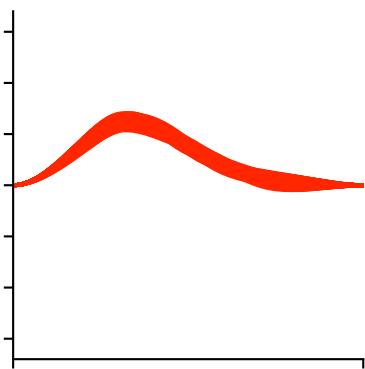
Start Finish

Fixed Initial Position
Movement Duration : 1 sec

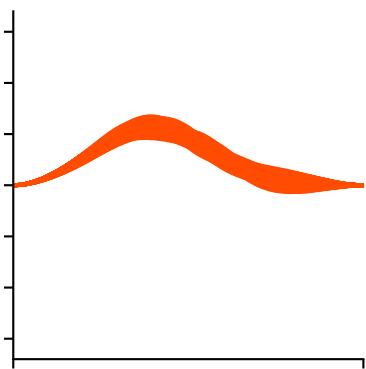
PC



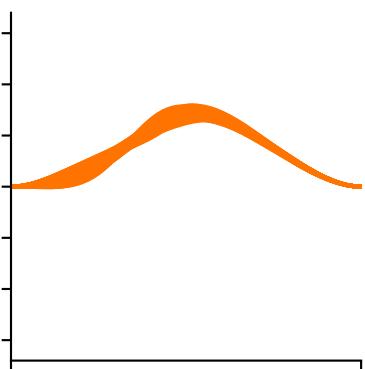
DELTa



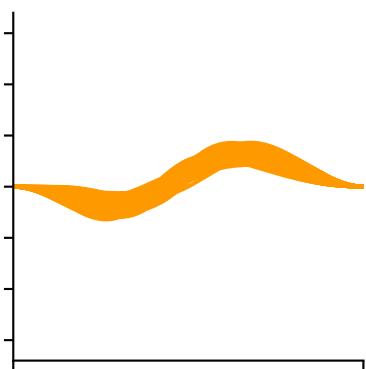
CB



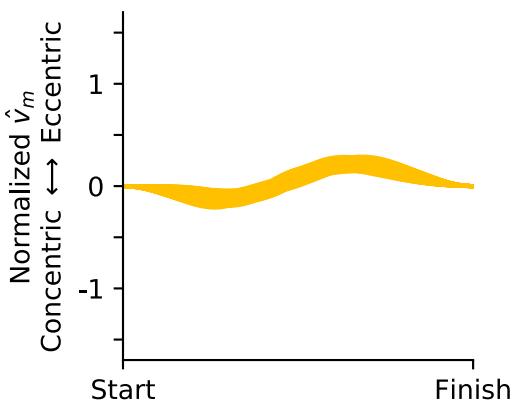
BIC



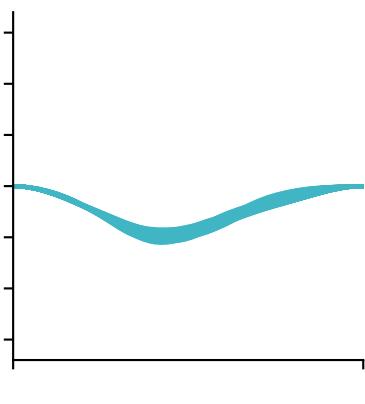
BRD



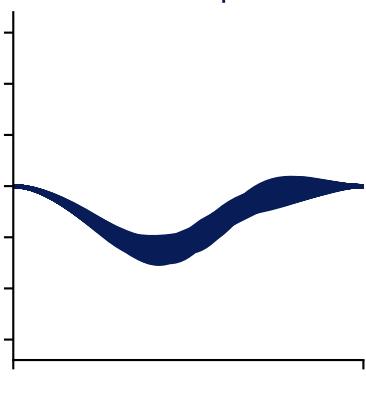
ECRB



TRI



DELTp



Normalized \hat{V}_m → Eccentric

1

0

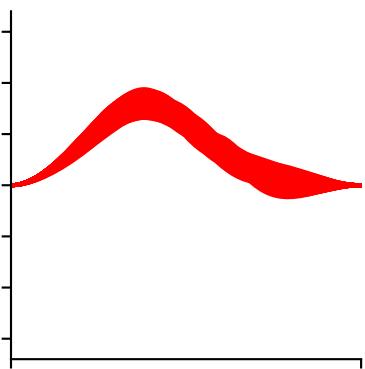
-1

Start

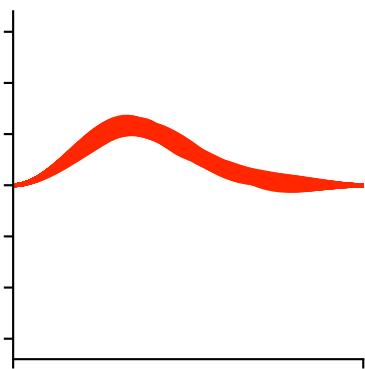
Finish

Fixed Initial Position
Movement Duration : 1 sec

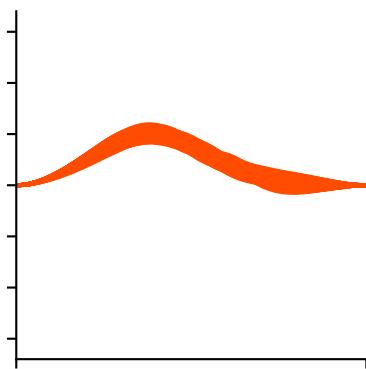
PC



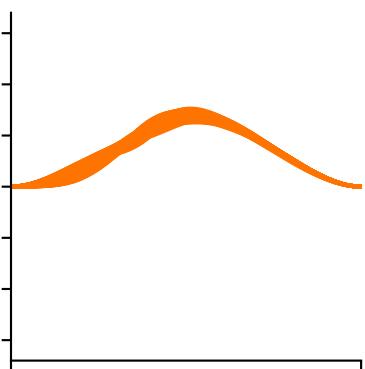
DELTa



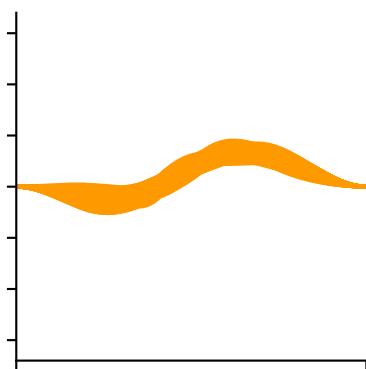
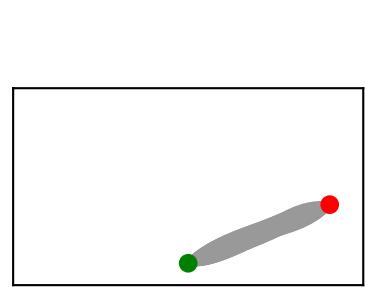
CB



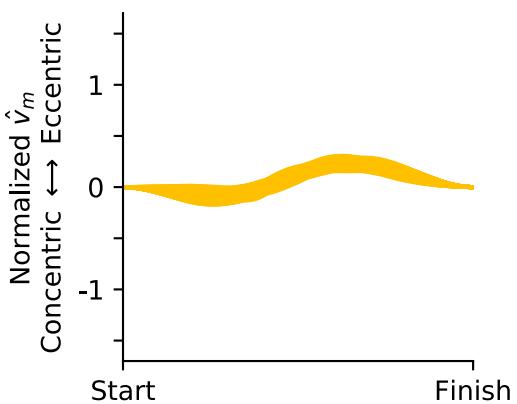
BIC



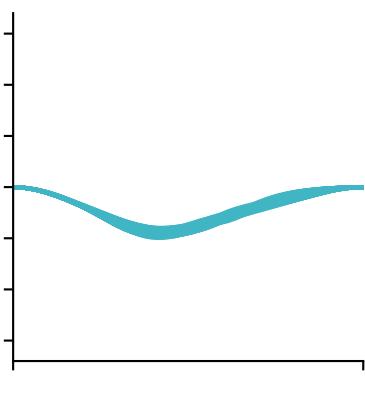
BRD



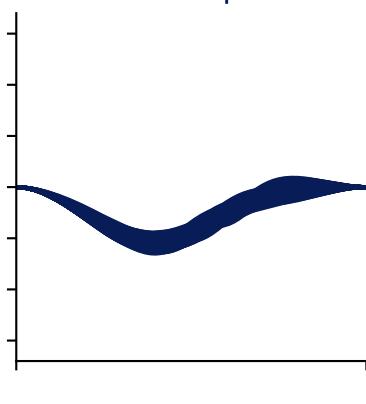
ECRB



TRI



DELTp



Normalized \hat{V}_m
Concentric \leftrightarrow Eccentric

1

0

-1

Start

Finish

Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

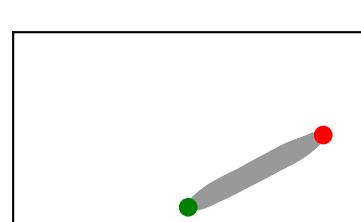
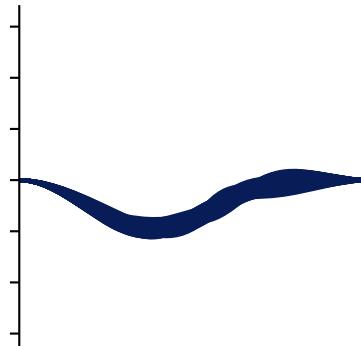
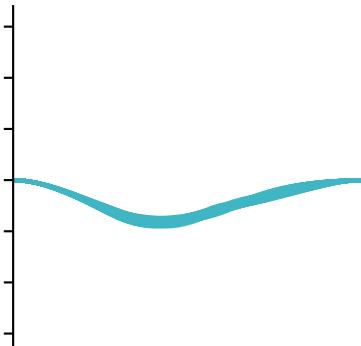
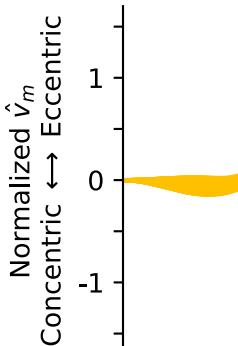
BIC

BRD

ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

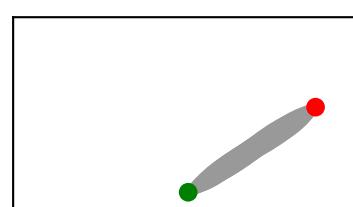
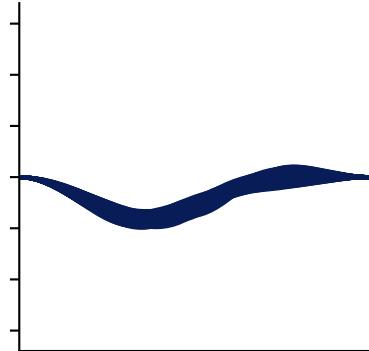
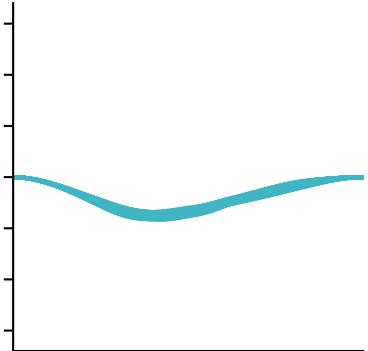
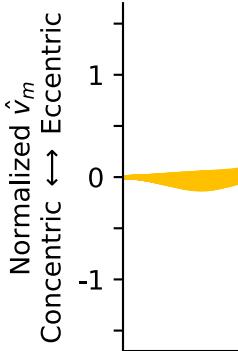
BIC

BRD

ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

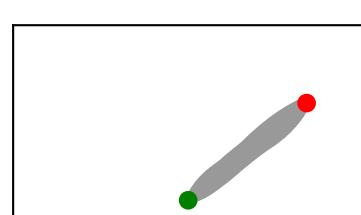
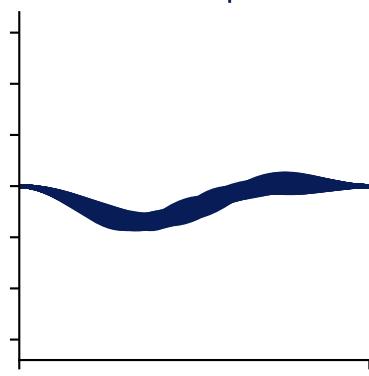
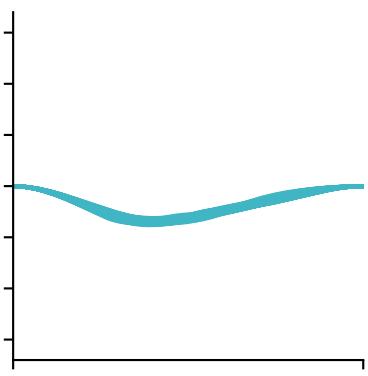
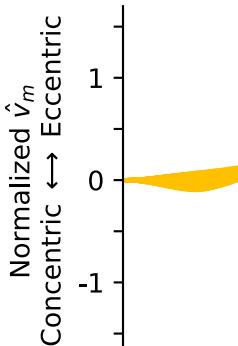
BIC

BRD

ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

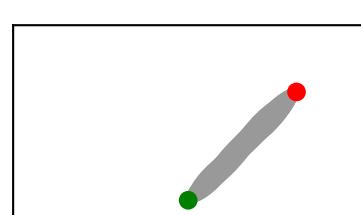
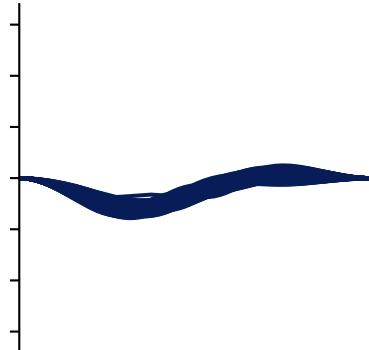
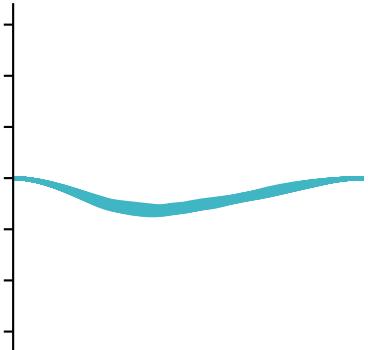
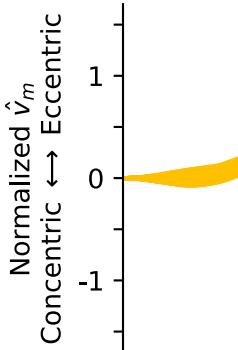
BIC

BRD

ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

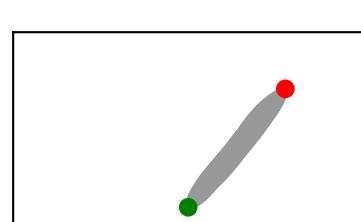
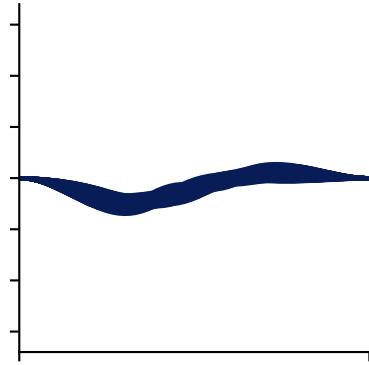
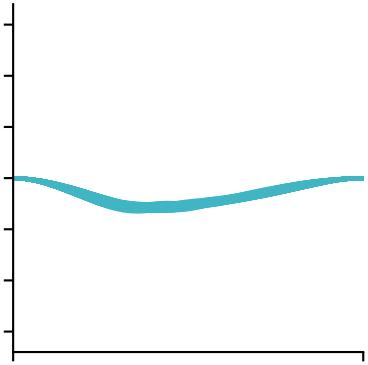
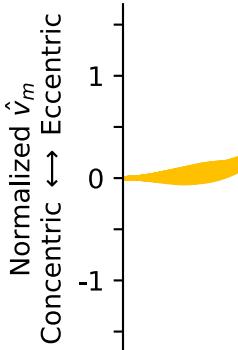
BIC

BRD

ECRB

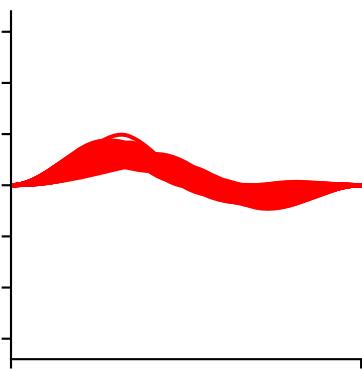
TRI

DELTp

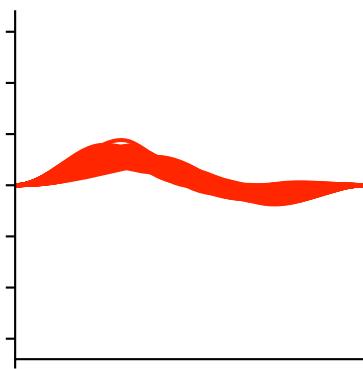


Fixed Initial Position
Movement Duration : 1 sec

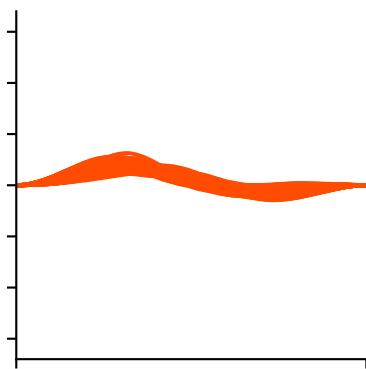
PC



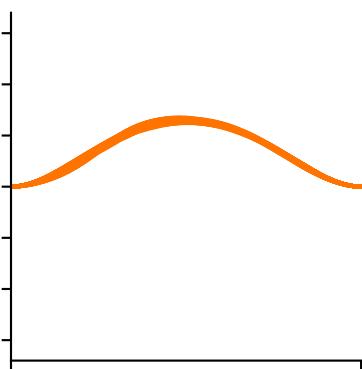
DELTa



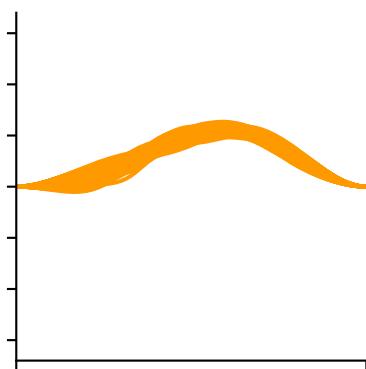
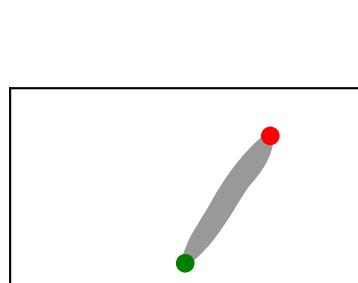
CB



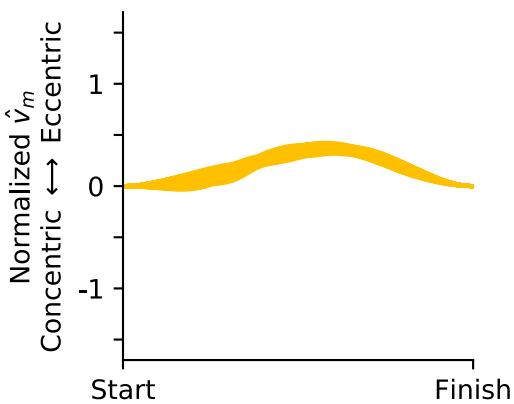
BIC



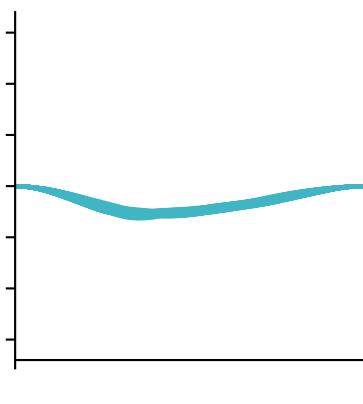
BRD



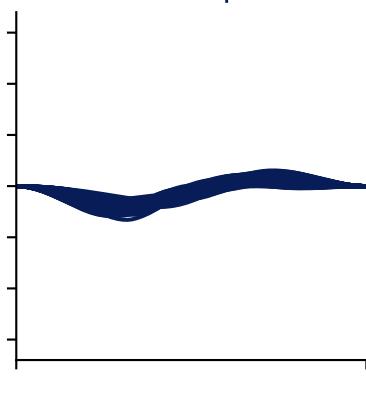
ECRB



TRI



DELTp



Normalized \hat{V}_m
Concentric \leftrightarrow Eccentric

Start Finish

Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

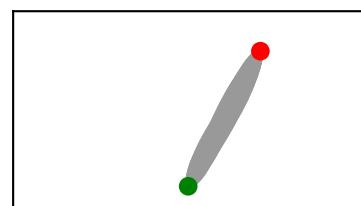
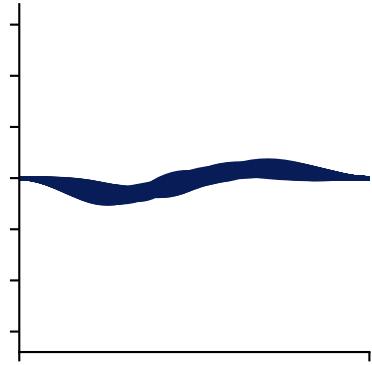
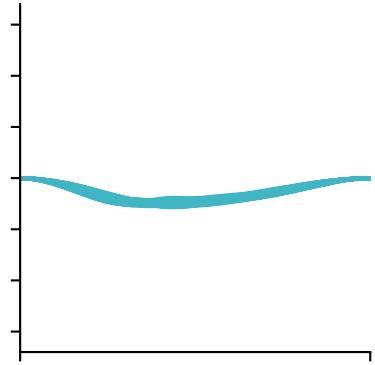
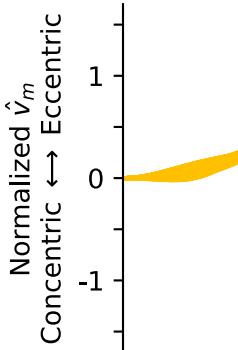
BIC

BRD

ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

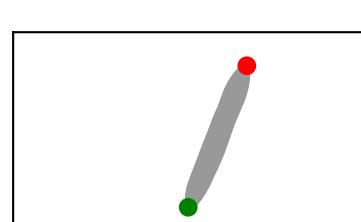
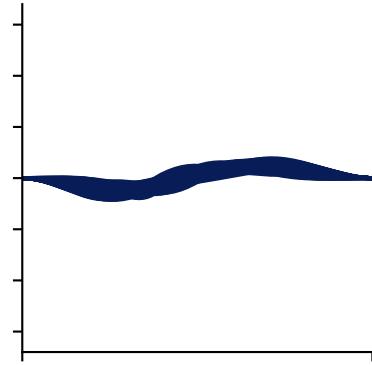
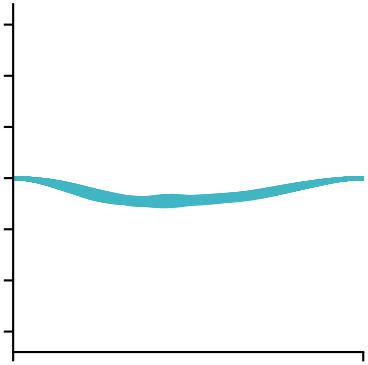
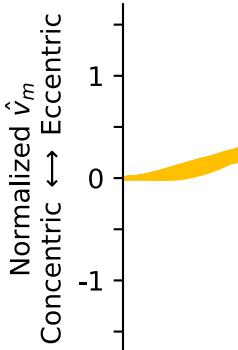
BIC

BRD

ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

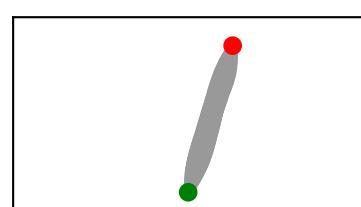
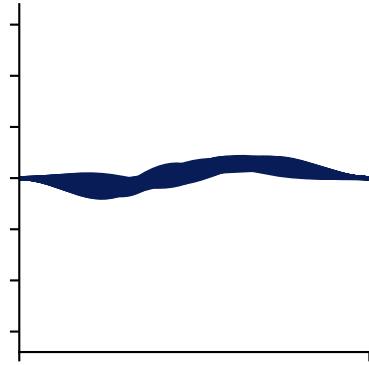
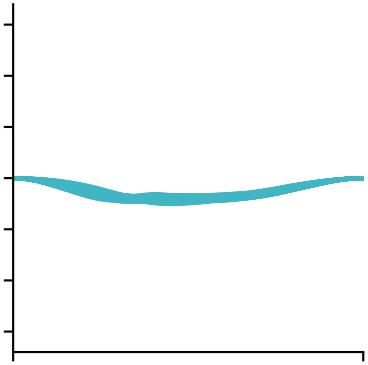
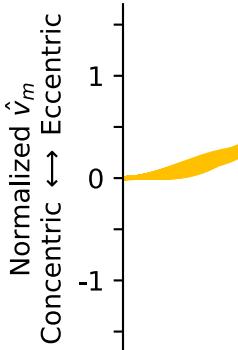
BIC

BRD

ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

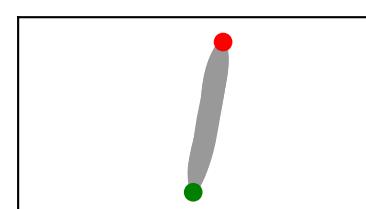
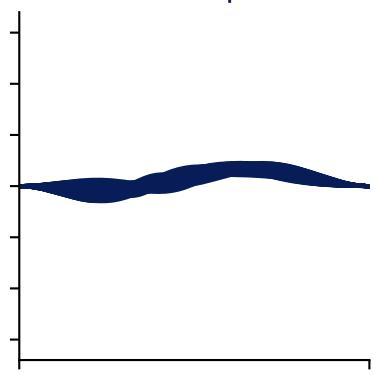
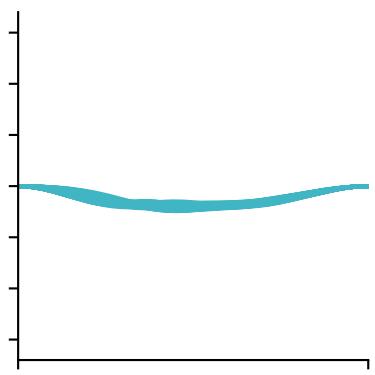
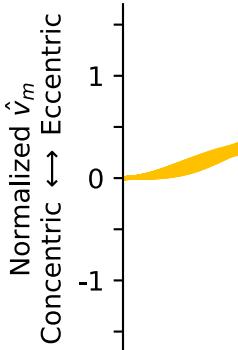
BIC

BRD

ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

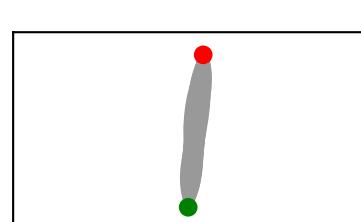
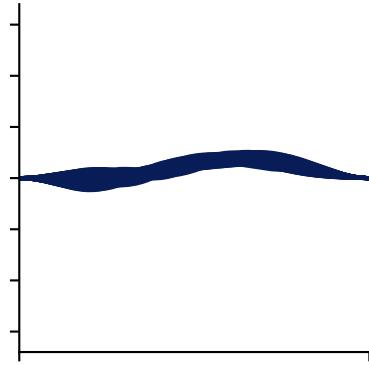
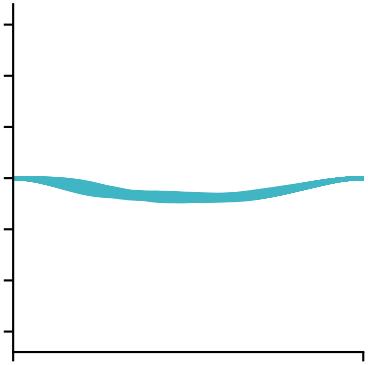
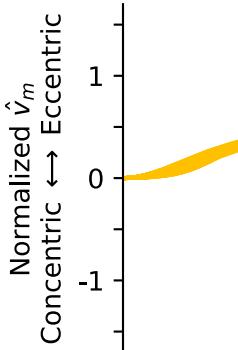
BIC

BRD

ECRB

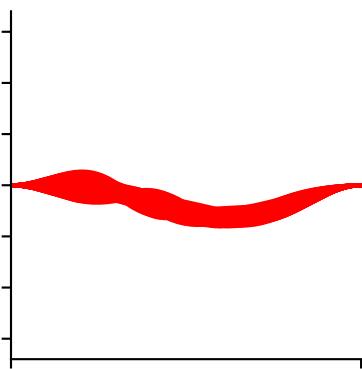
TRI

DELTp

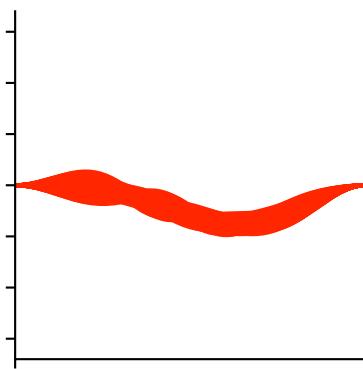


Fixed Initial Position
Movement Duration : 1 sec

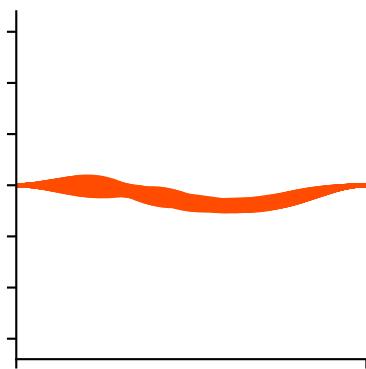
PC



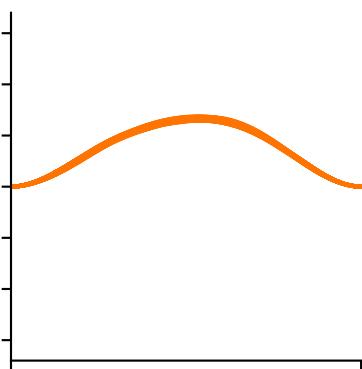
DELTa



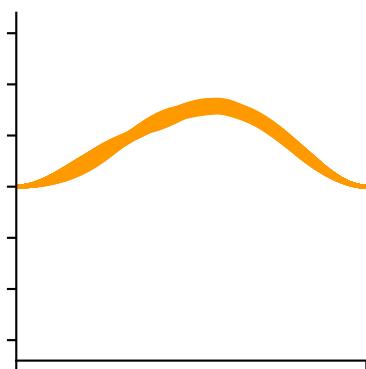
CB



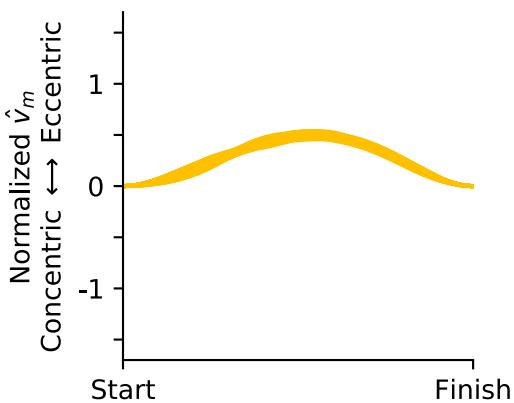
BIC



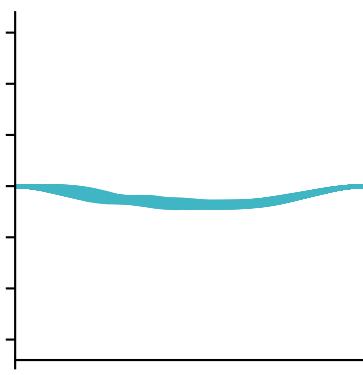
BRD



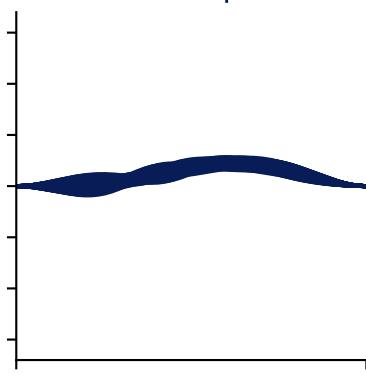
ECRB



TRI



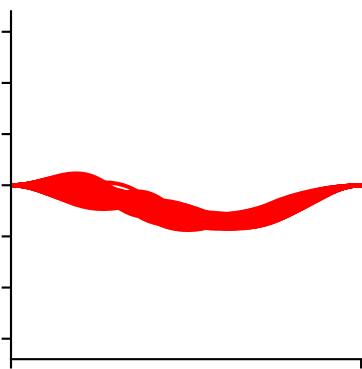
DELTp



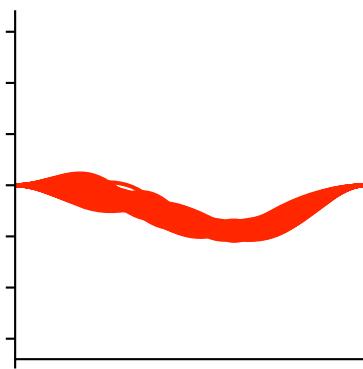
Normalized \dot{V}_m
Concentric \leftrightarrow Eccentric

Fixed Initial Position
Movement Duration : 1 sec

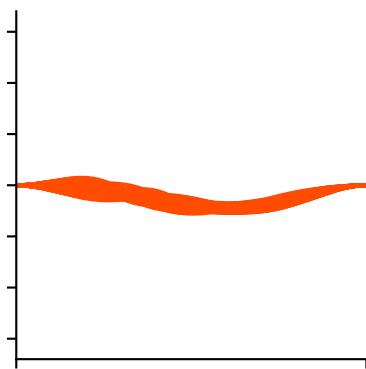
PC



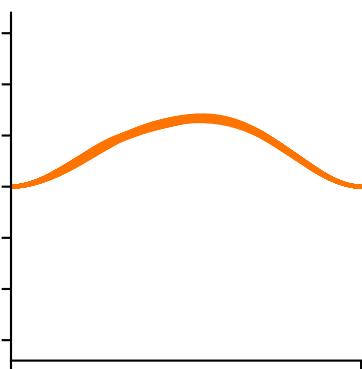
DELTa



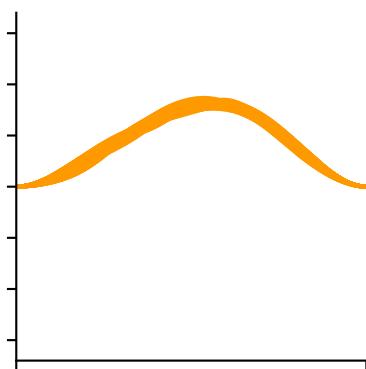
CB



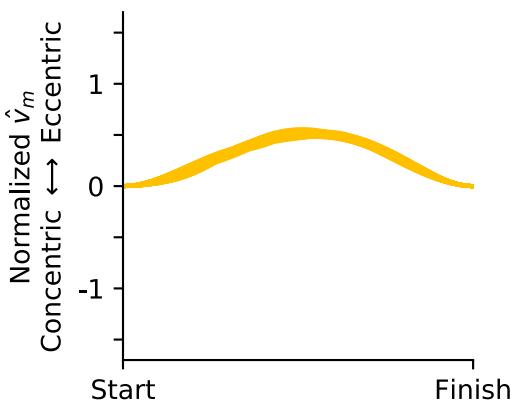
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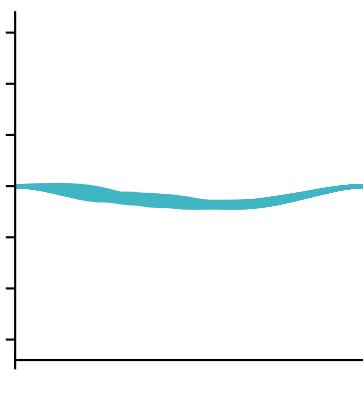
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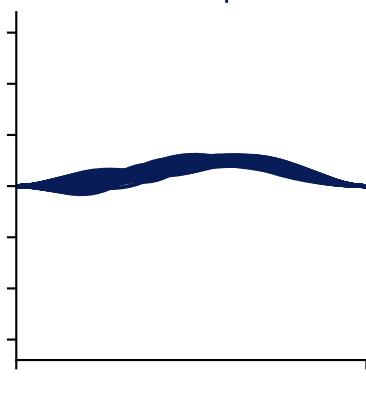
ECRB



TRI

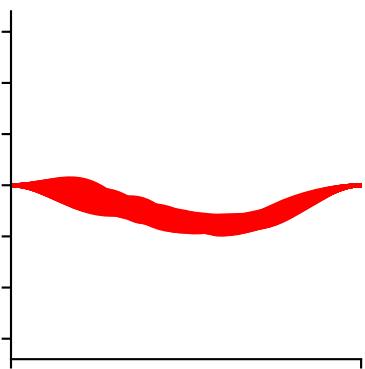


DELTp

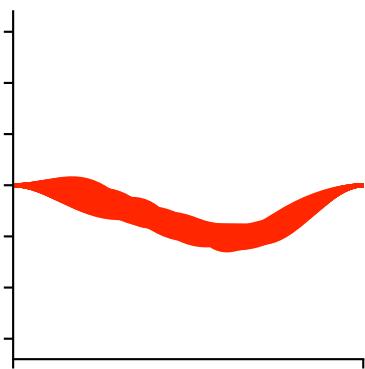


Fixed Initial Position
Movement Duration : 1 sec

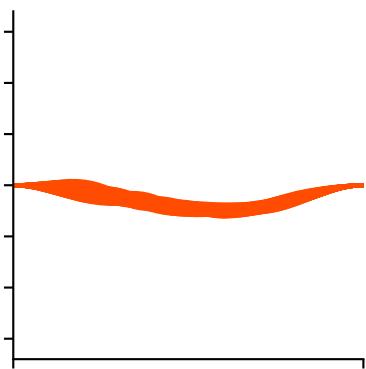
PC



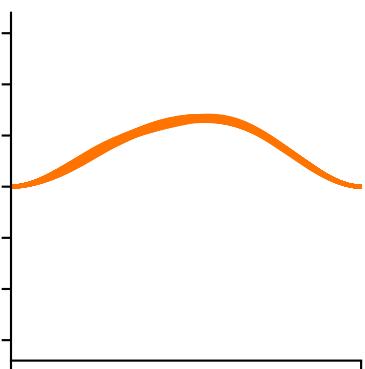
DELTa



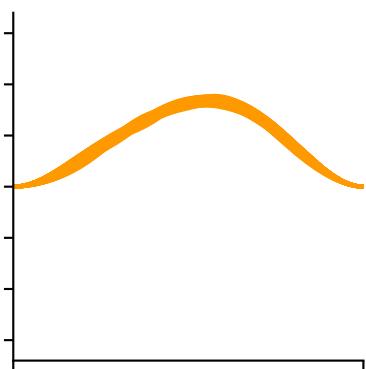
CB



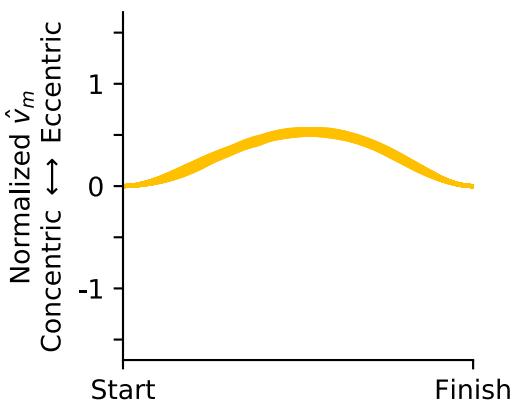
BIC



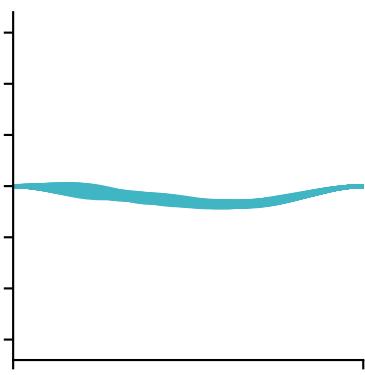
BRD



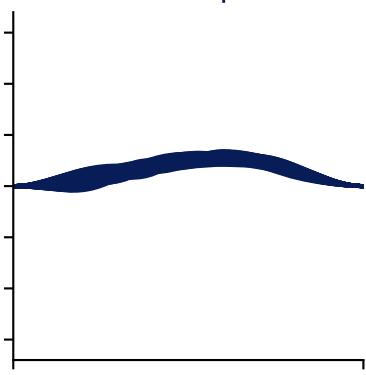
ECRB



TRI

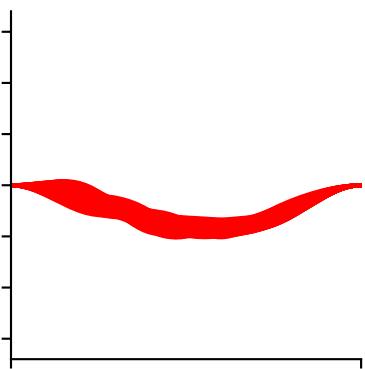


DELTp

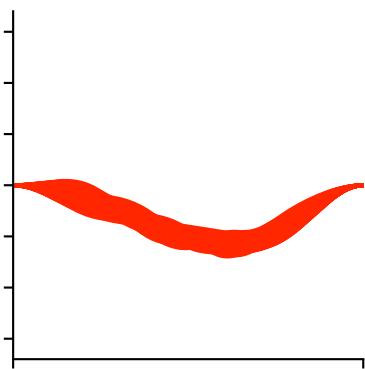


Fixed Initial Position
Movement Duration : 1 sec

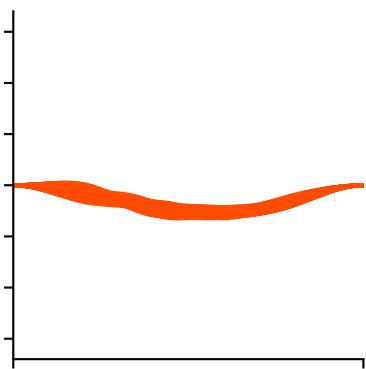
PC



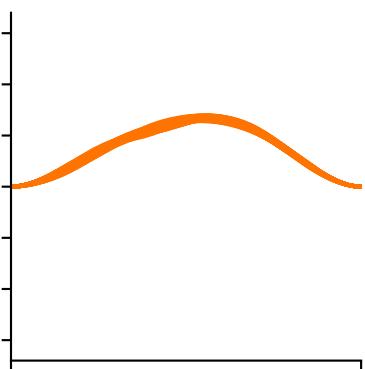
DELTa



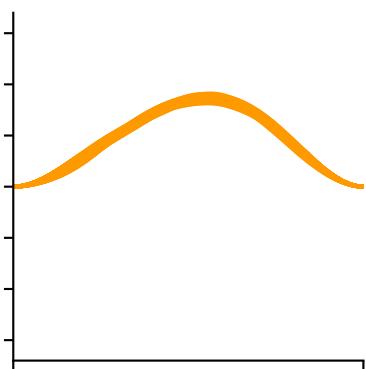
CB



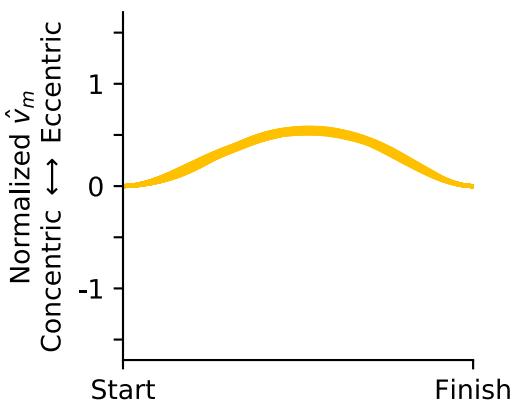
BIC



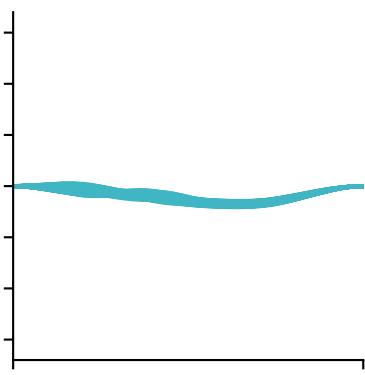
BRD



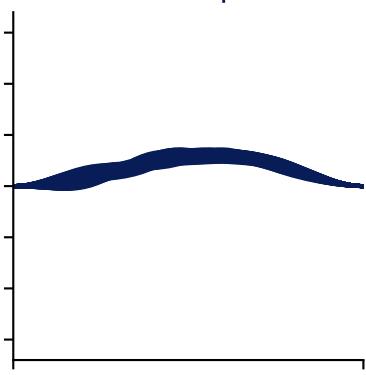
ECRB



TRI



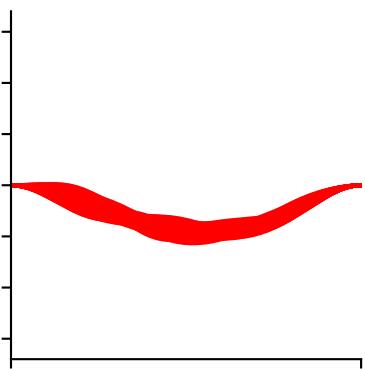
DELTp



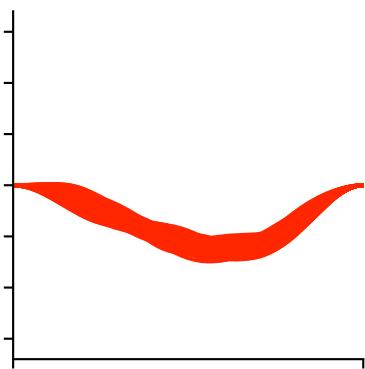
Normalized \dot{V}_m → Eccentric

Fixed Initial Position
Movement Duration : 1 sec

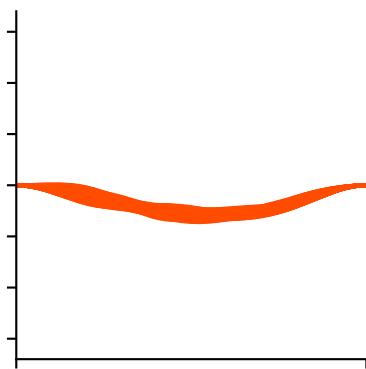
PC



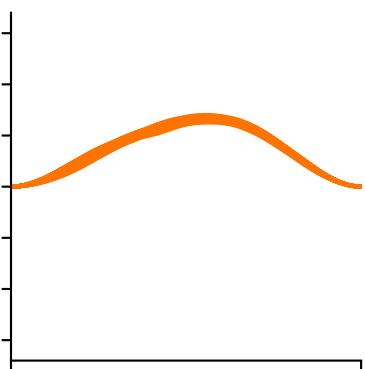
DELTa



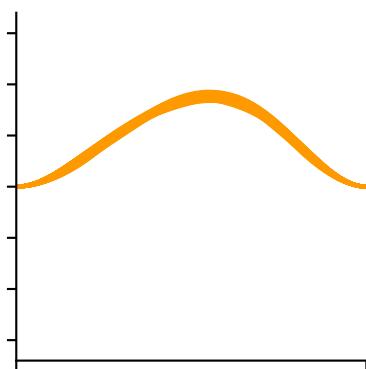
CB



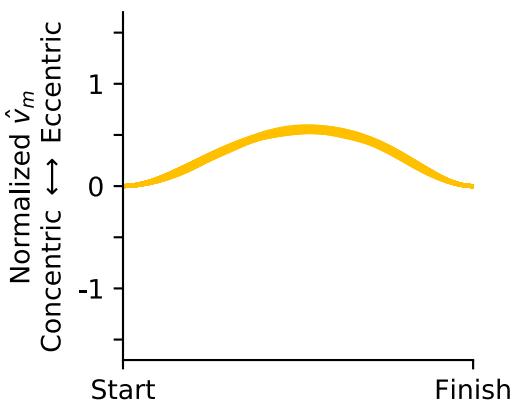
BIC



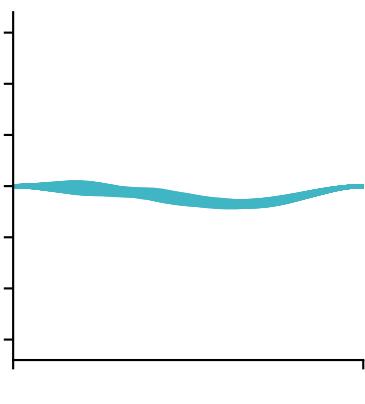
BRD



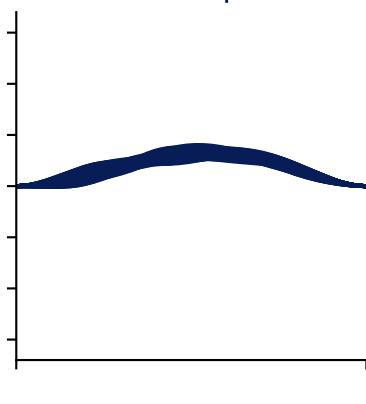
ECRB



TRI



DELTp



Normalized \dot{V}_m
Concentric \leftrightarrow Eccentric

Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

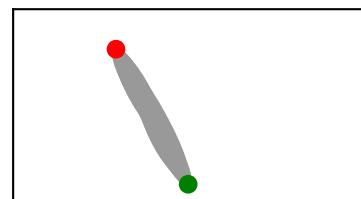
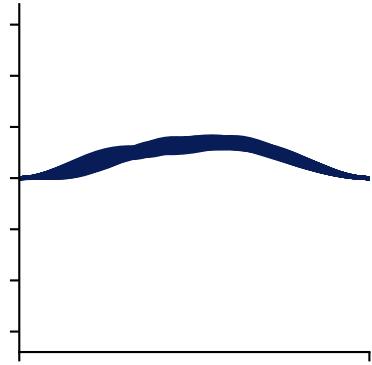
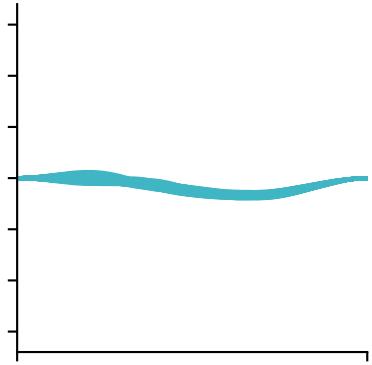
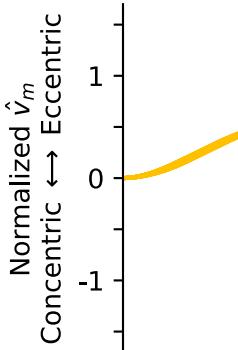
BIC

BRD

ECRB

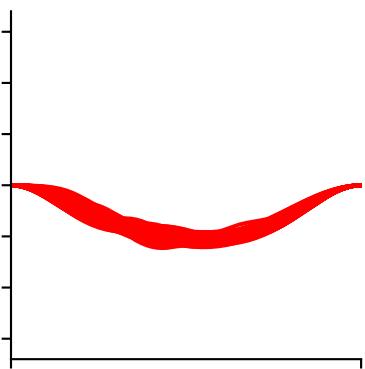
TRI

DELTp

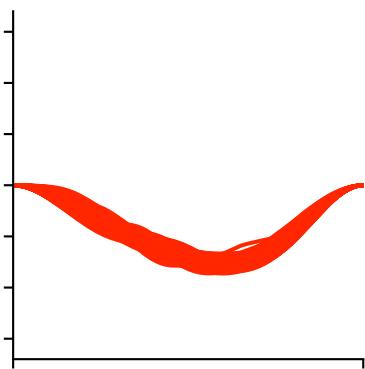


Fixed Initial Position
Movement Duration : 1 sec

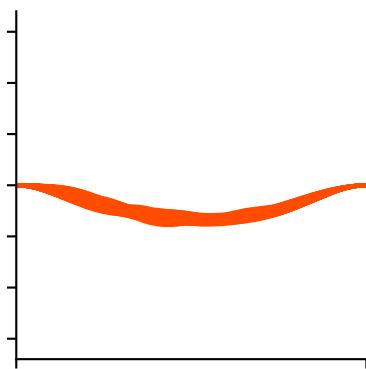
PC



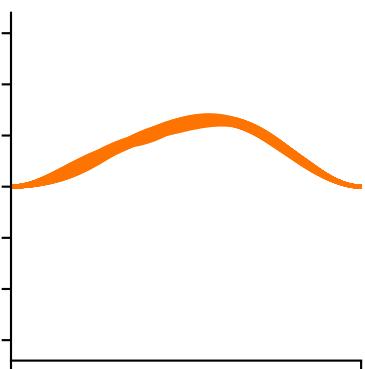
DELTa



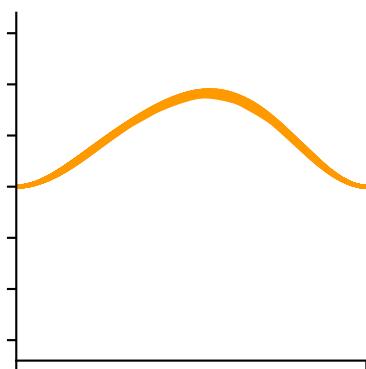
CB



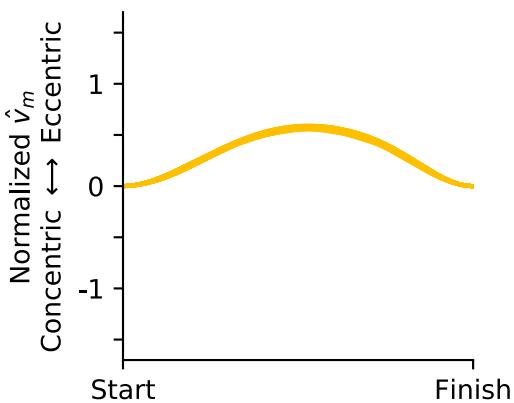
BIC



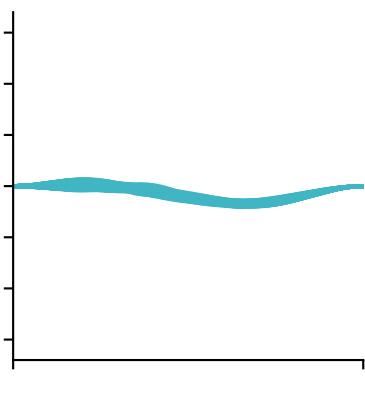
BRD



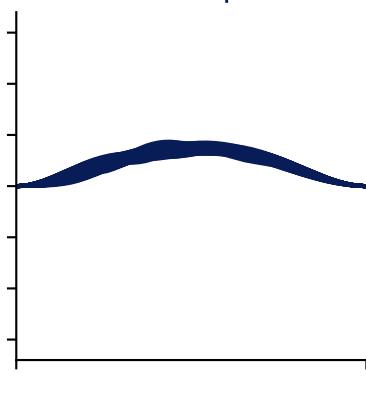
ECRB



TRI



DELTp



Normalized \dot{V}_m → Eccentric

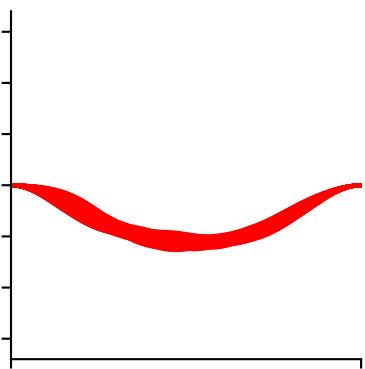
1
0
-1

Start

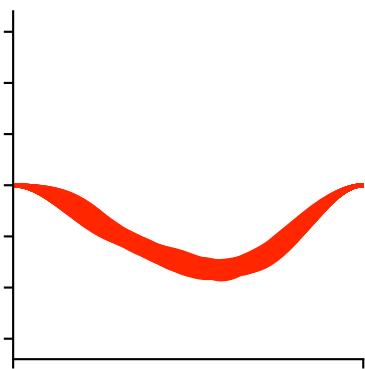
Finish

Fixed Initial Position
Movement Duration : 1 sec

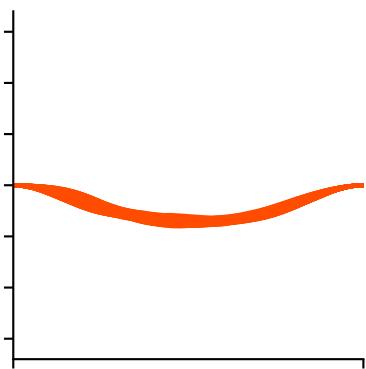
PC



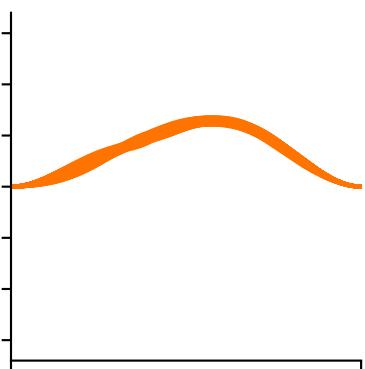
DELTa



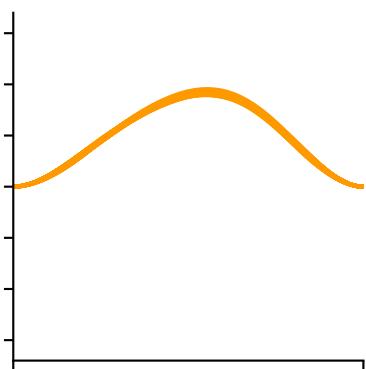
CB



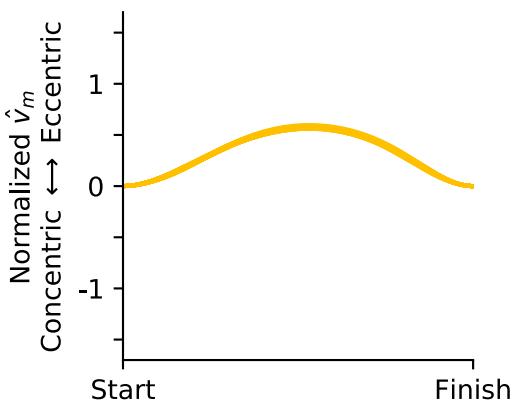
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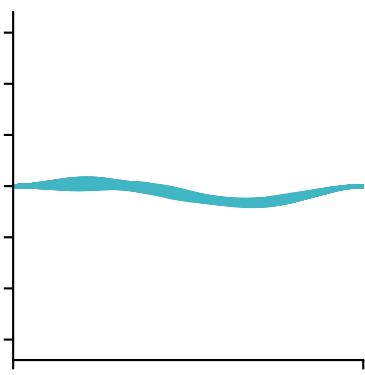
BRD



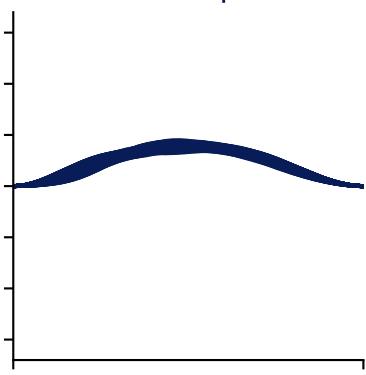
ECRB



TRI



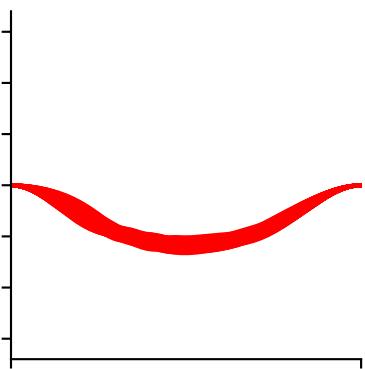
DELTp



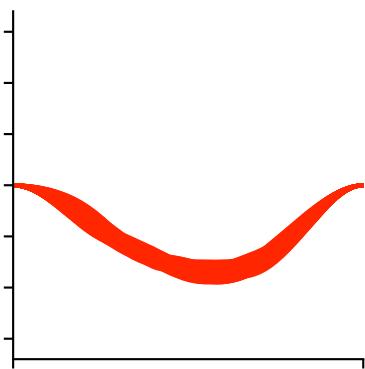
Normalized \dot{V}_m → Eccentric

Fixed Initial Position
Movement Duration : 1 sec

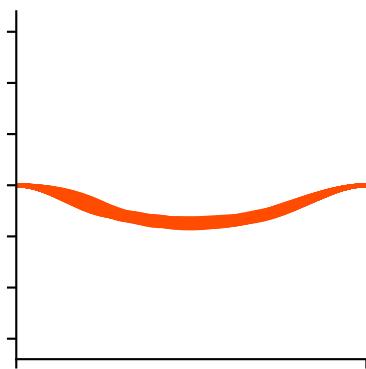
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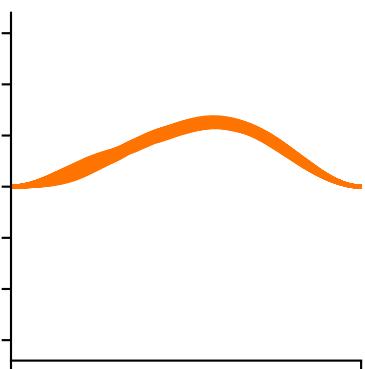
DELTa



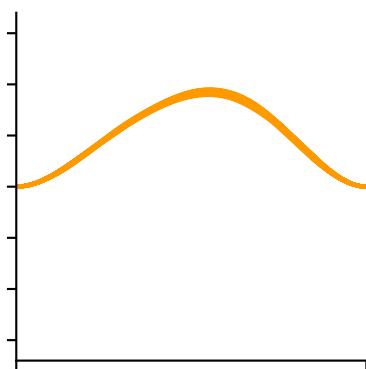
CB



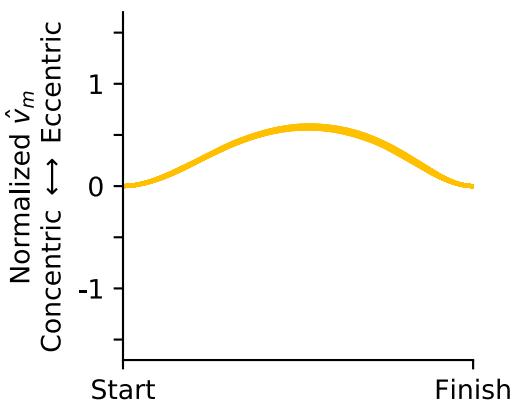
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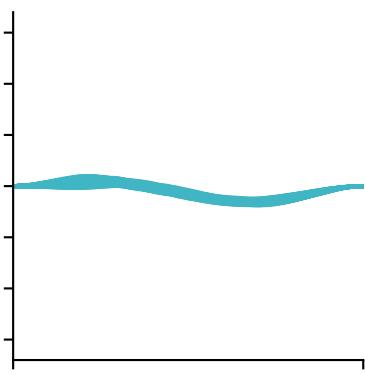
BRD



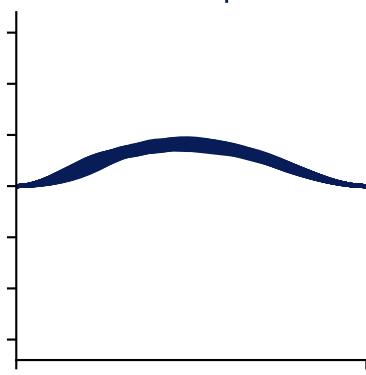
ECRB



TRI



DELTp



Normalized \dot{V}_m → Eccentric

Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

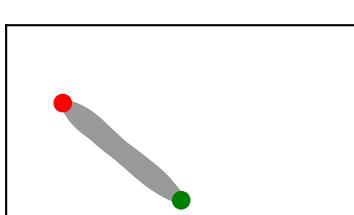
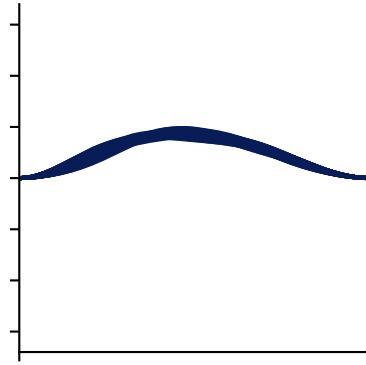
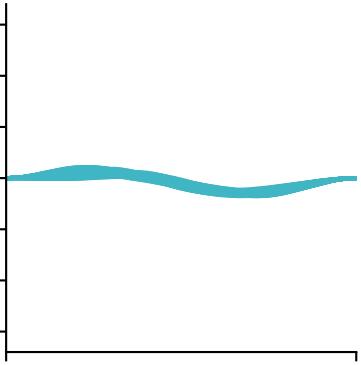
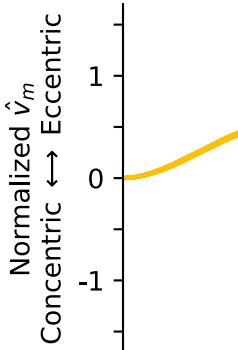
BIC

BRD

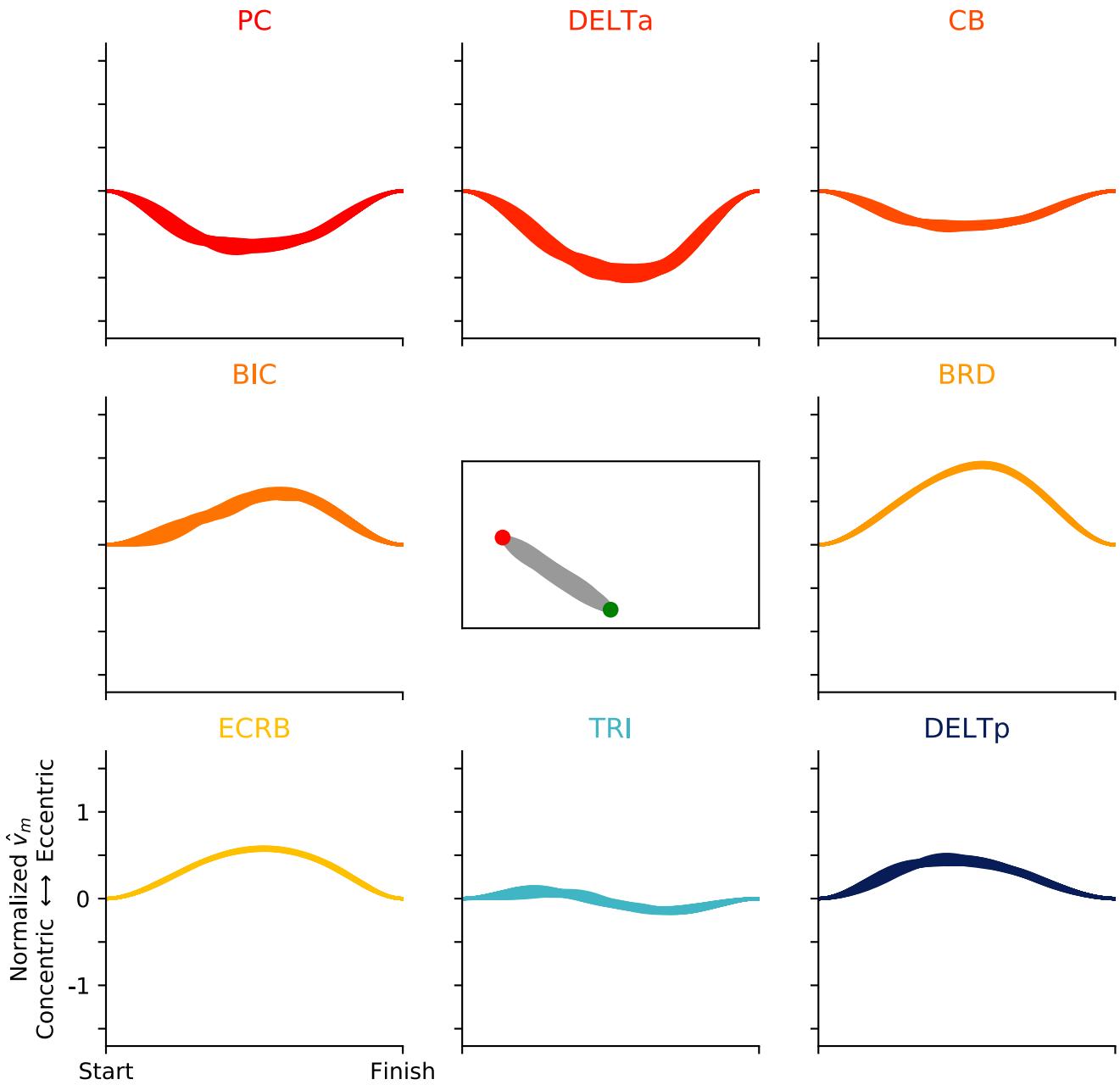
ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

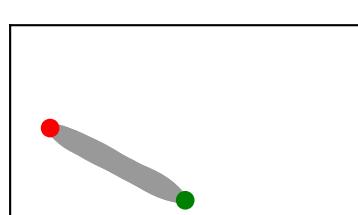
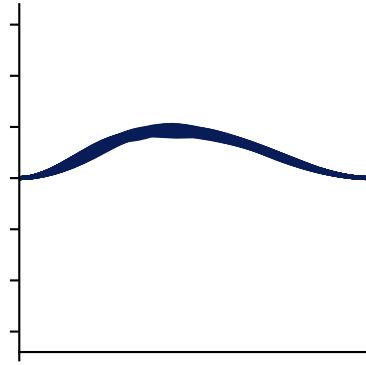
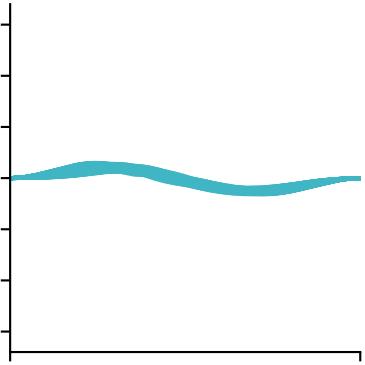
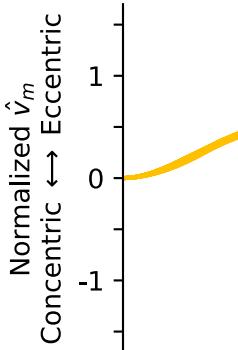
BIC

BRD

ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

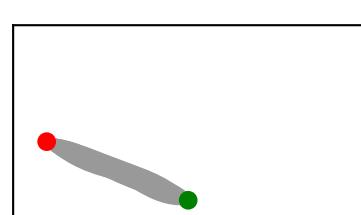
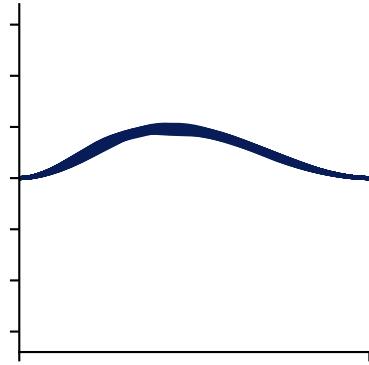
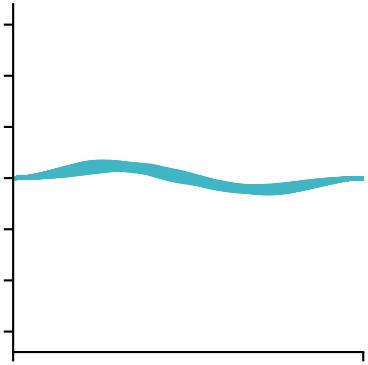
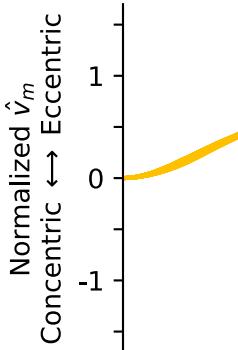
BIC

BRD

ECRB

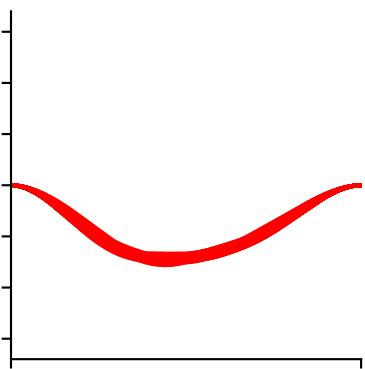
TRI

DELTp

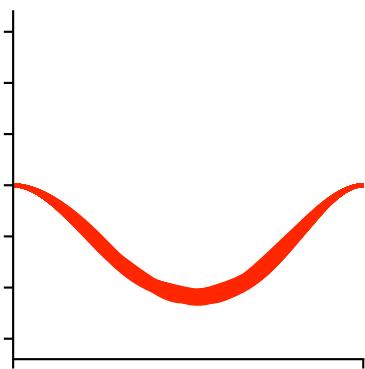


Fixed Initial Position
Movement Duration : 1 sec

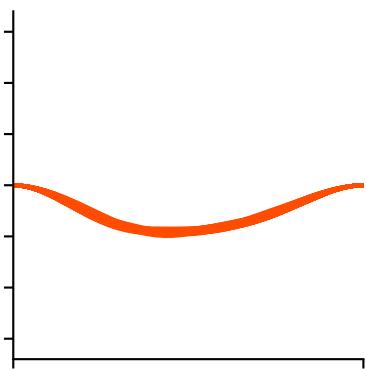
PC



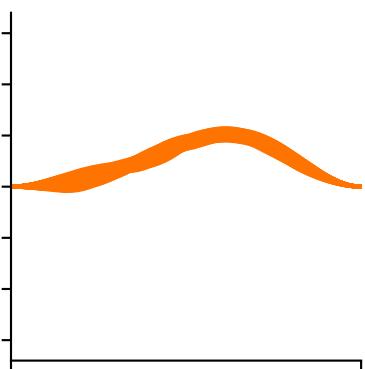
DELTa



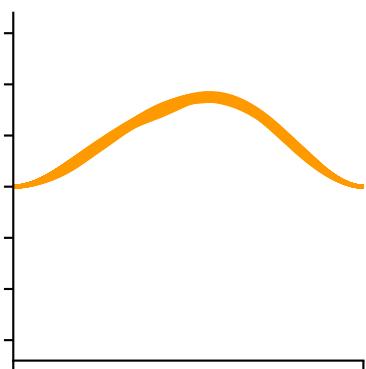
CB



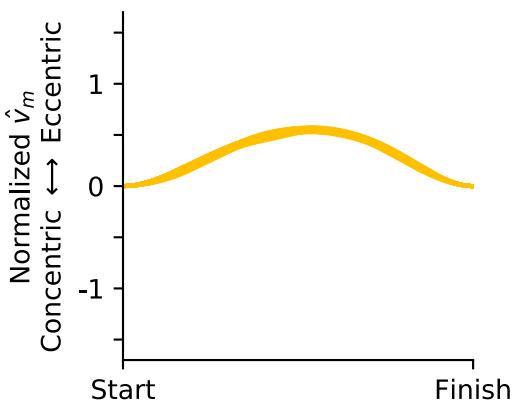
BIC



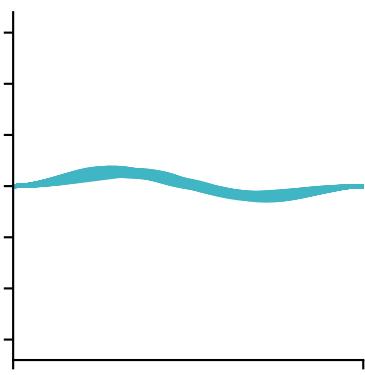
BRD



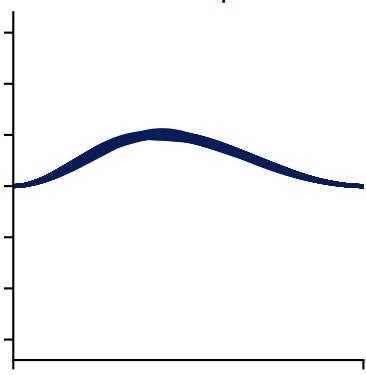
ECRB



TRI



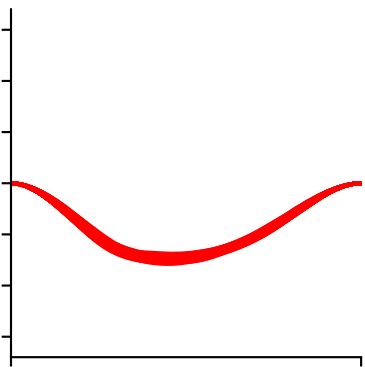
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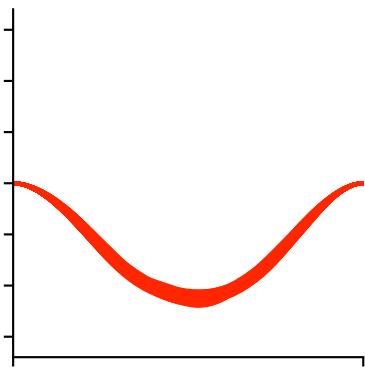
Normalized \dot{V}_m
Concentric \leftrightarrow Eccentric

Fixed Initial Position
Movement Duration : 1 sec

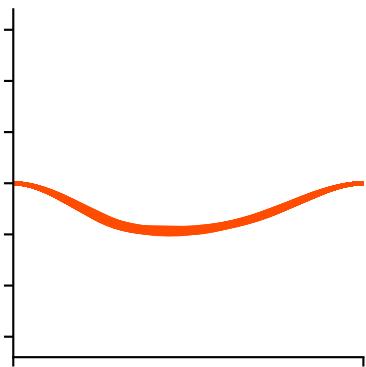
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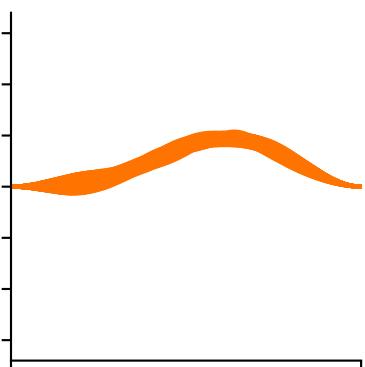
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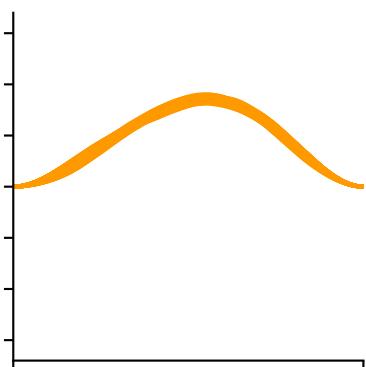
CB



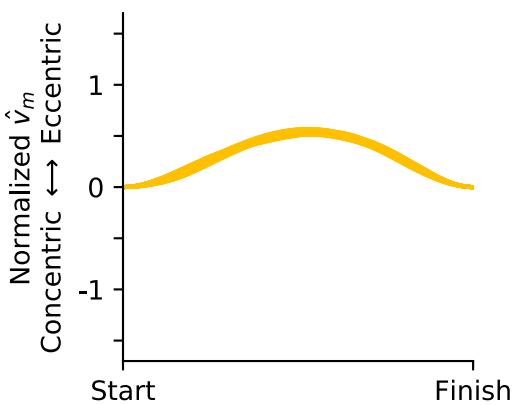
BIC



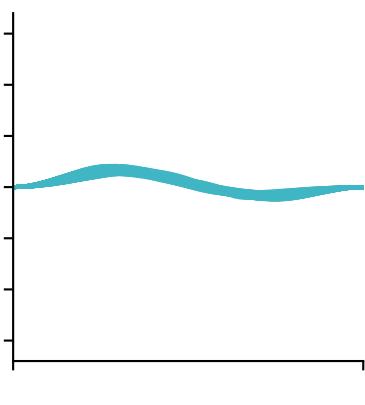
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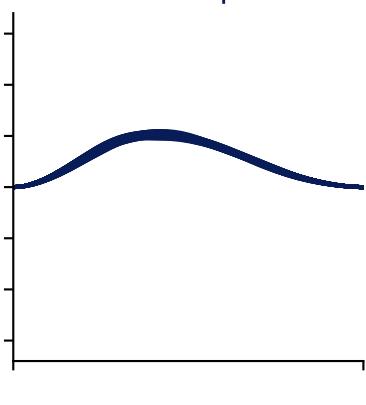
ECRB



TRI



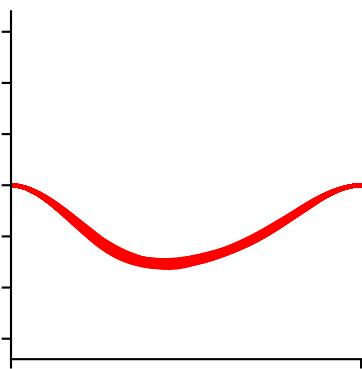
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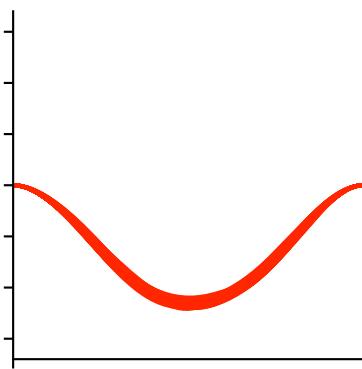
Normalized \dot{V}_m
Concentric \leftrightarrow Eccentric

Fixed Initial Position
Movement Duration : 1 sec

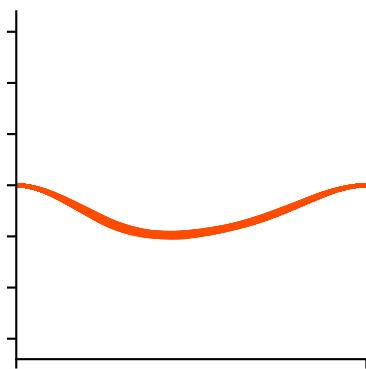
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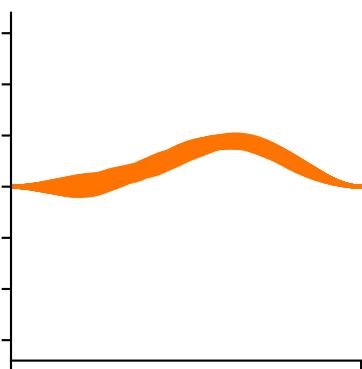
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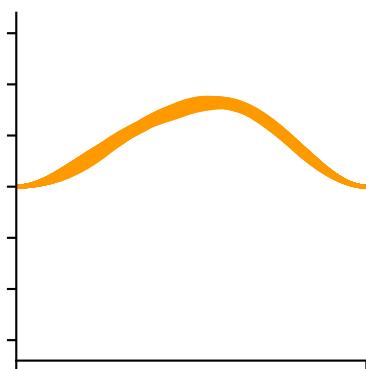
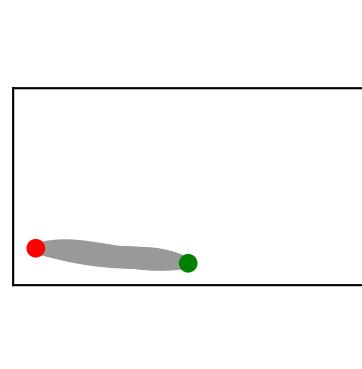
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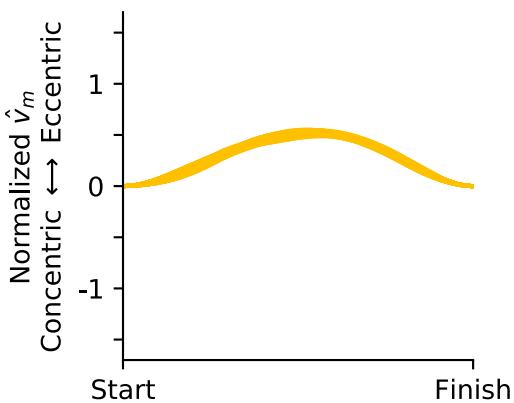
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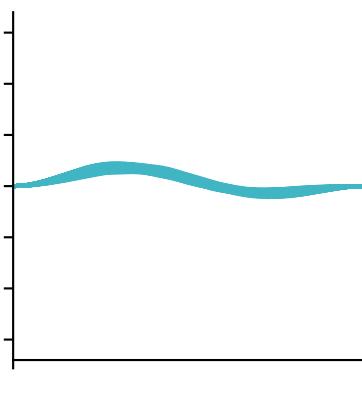
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ECRB



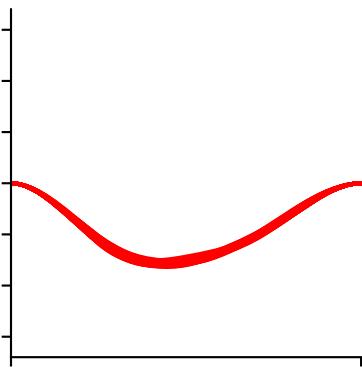
TRI



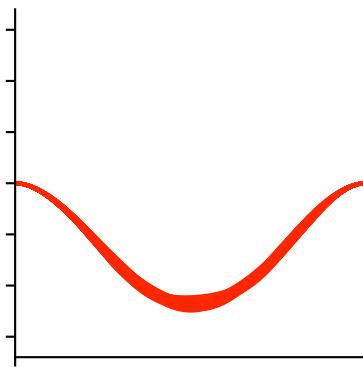
DELTp

Fixed Initial Position
Movement Duration : 1 sec

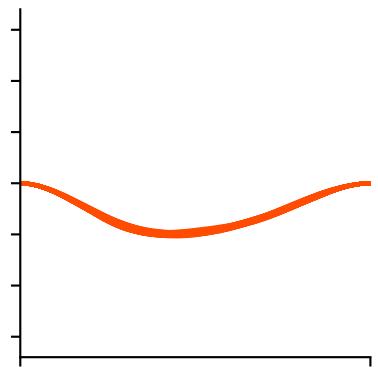
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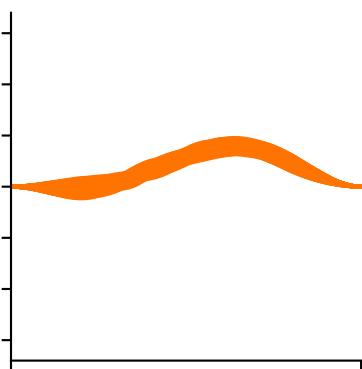
DELTa



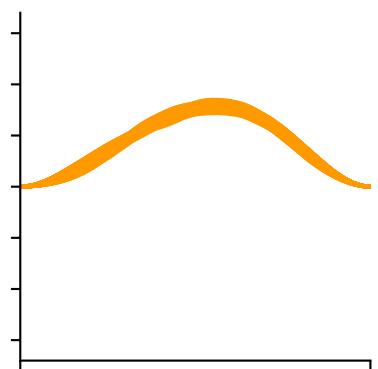
CB



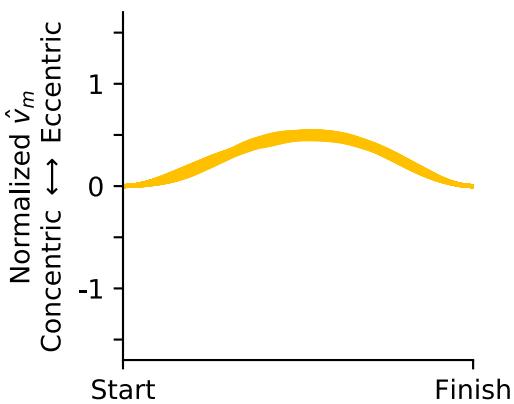
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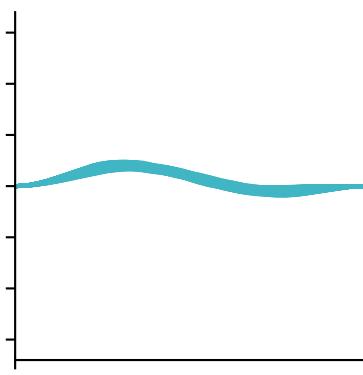
BRD



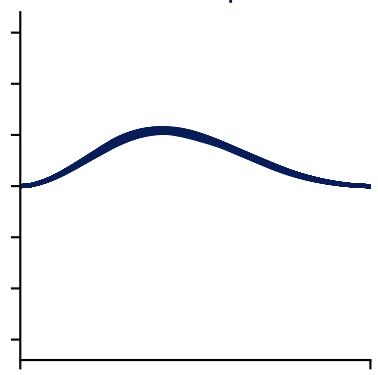
ECRB



TRI

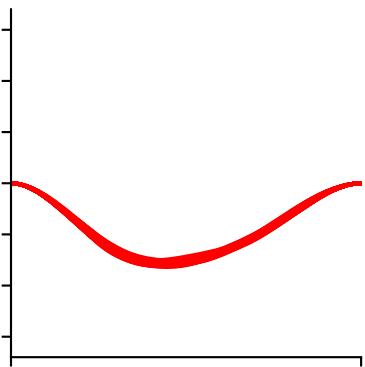


DELTp

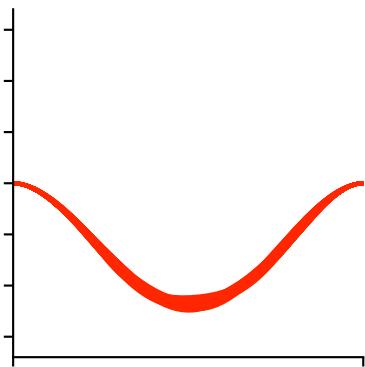


Fixed Initial Position
Movement Duration : 1 sec

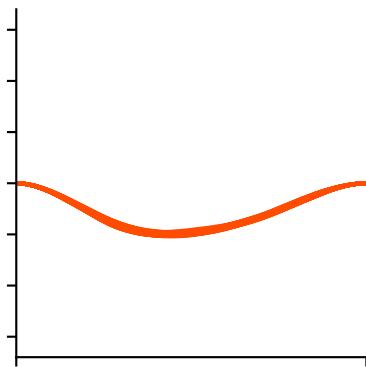
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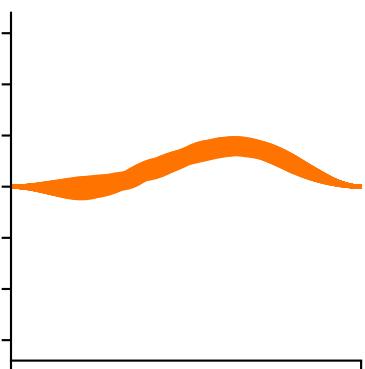
DELTa



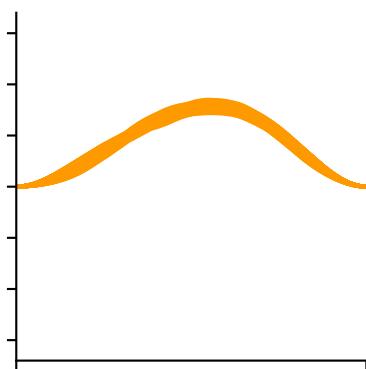
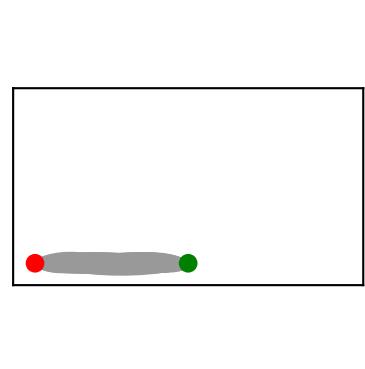
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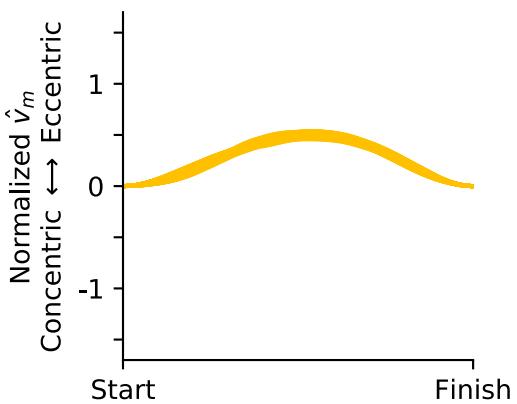
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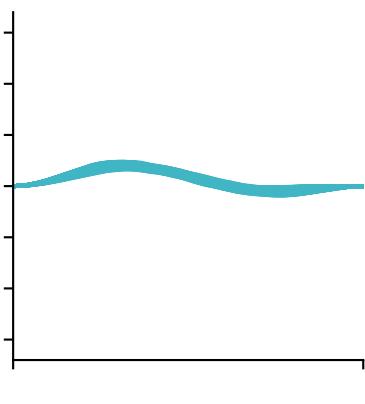
BRD



ECRB



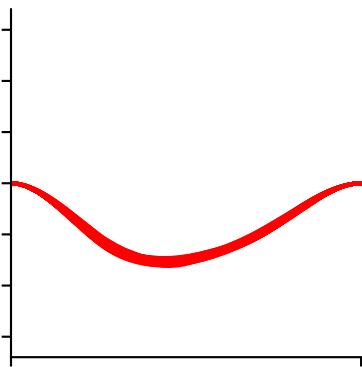
TRI



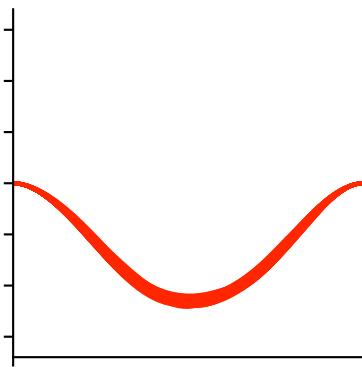
DELTp

Fixed Initial Position
Movement Duration : 1 sec

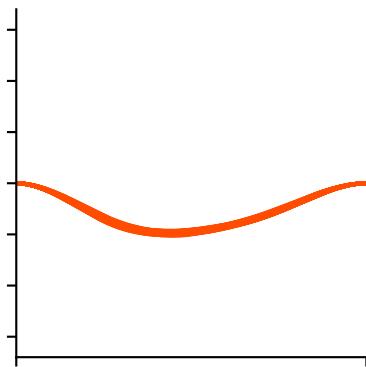
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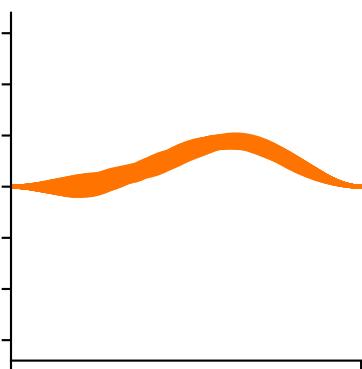
DELTa



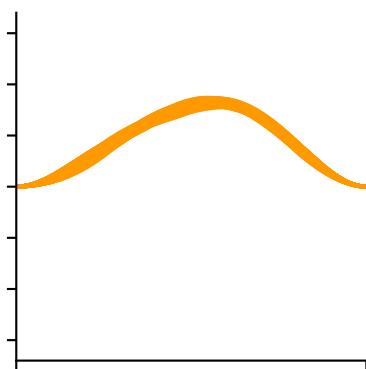
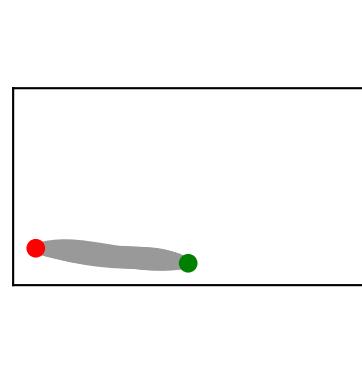
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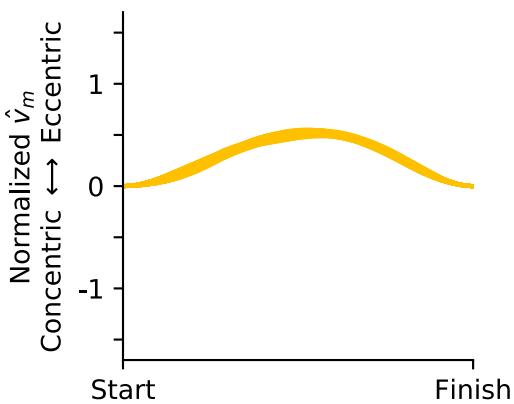
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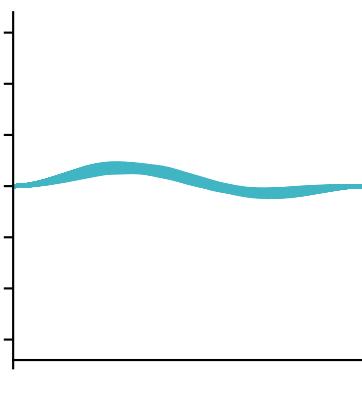
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ECRB



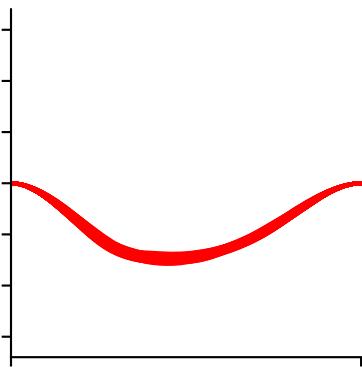
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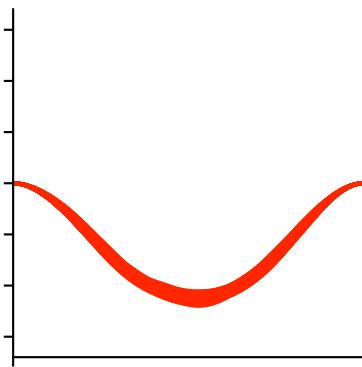
DELTp

Fixed Initial Position
Movement Duration : 1 sec

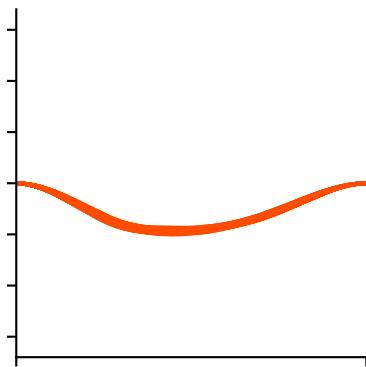
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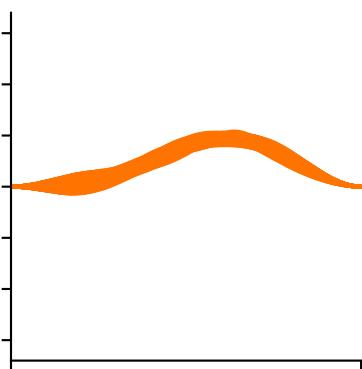
DELTa



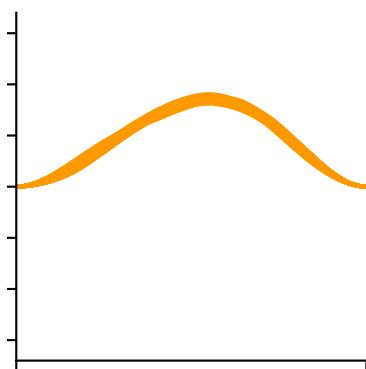
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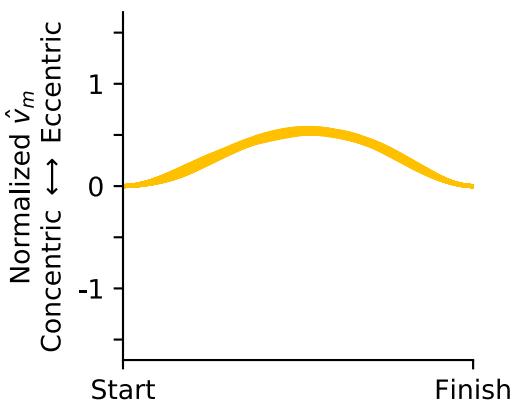
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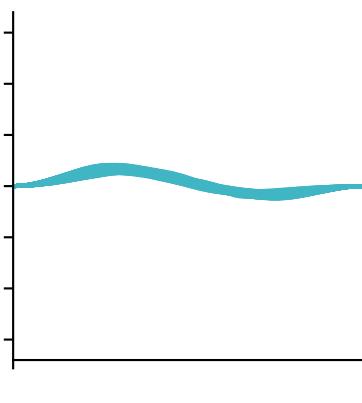
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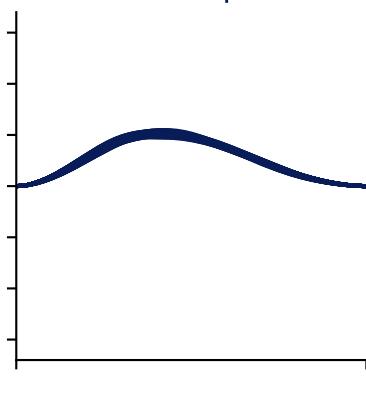
ECRB



TRI



DELTp



Normalized \dot{V}_m → Eccentric

1

0

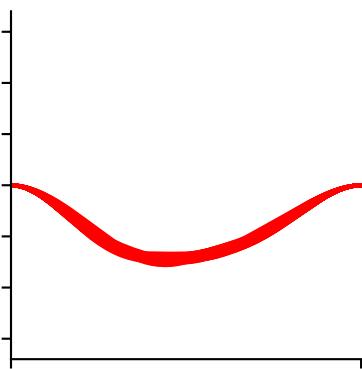
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Start

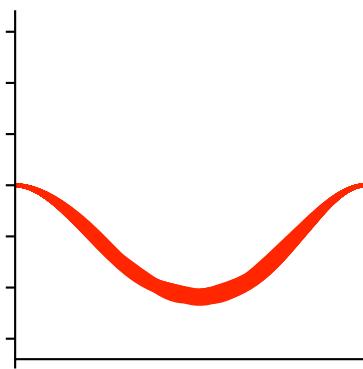
Finish

Fixed Initial Position
Movement Duration : 1 sec

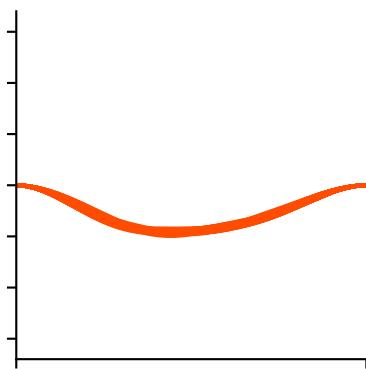
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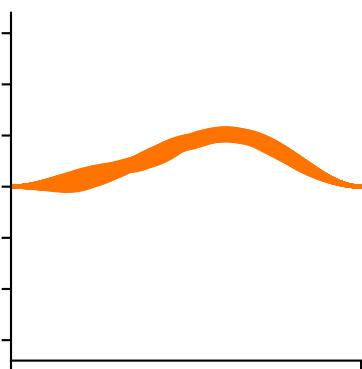
DELTa



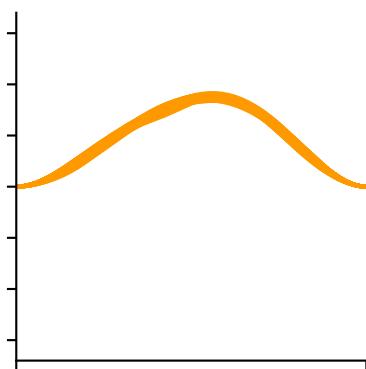
CB



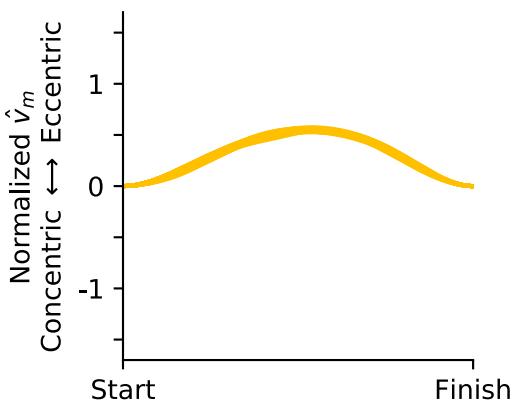
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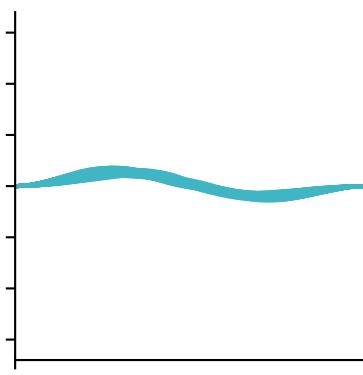
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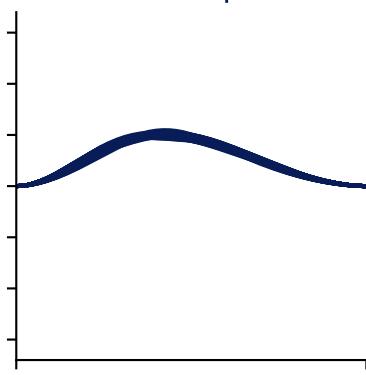
ECRB



TRI



DELTp



Normalized \dot{V}_m
Concentric \leftrightarrow Eccentric

Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

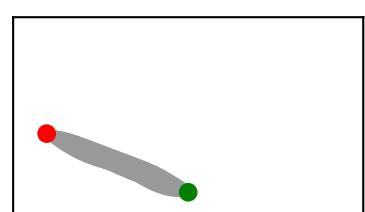
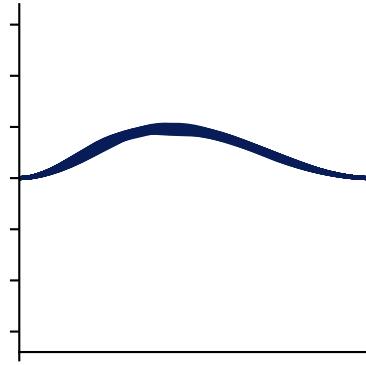
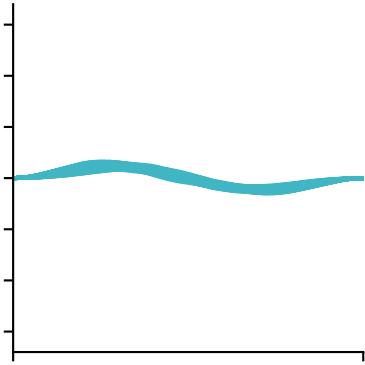
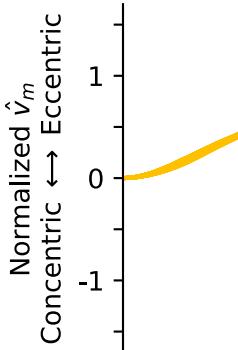
BIC

BRD

ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

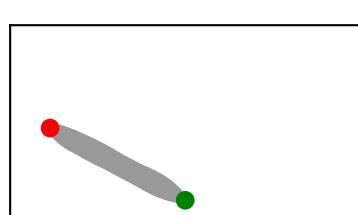
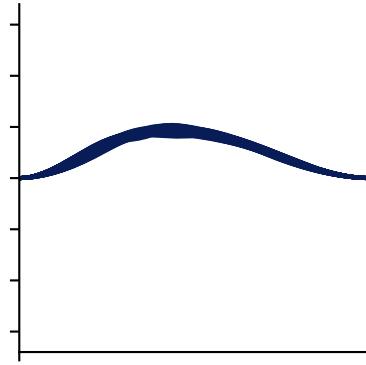
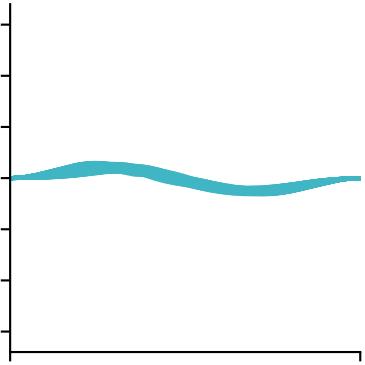
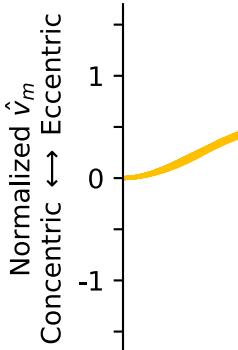
BIC

BRD

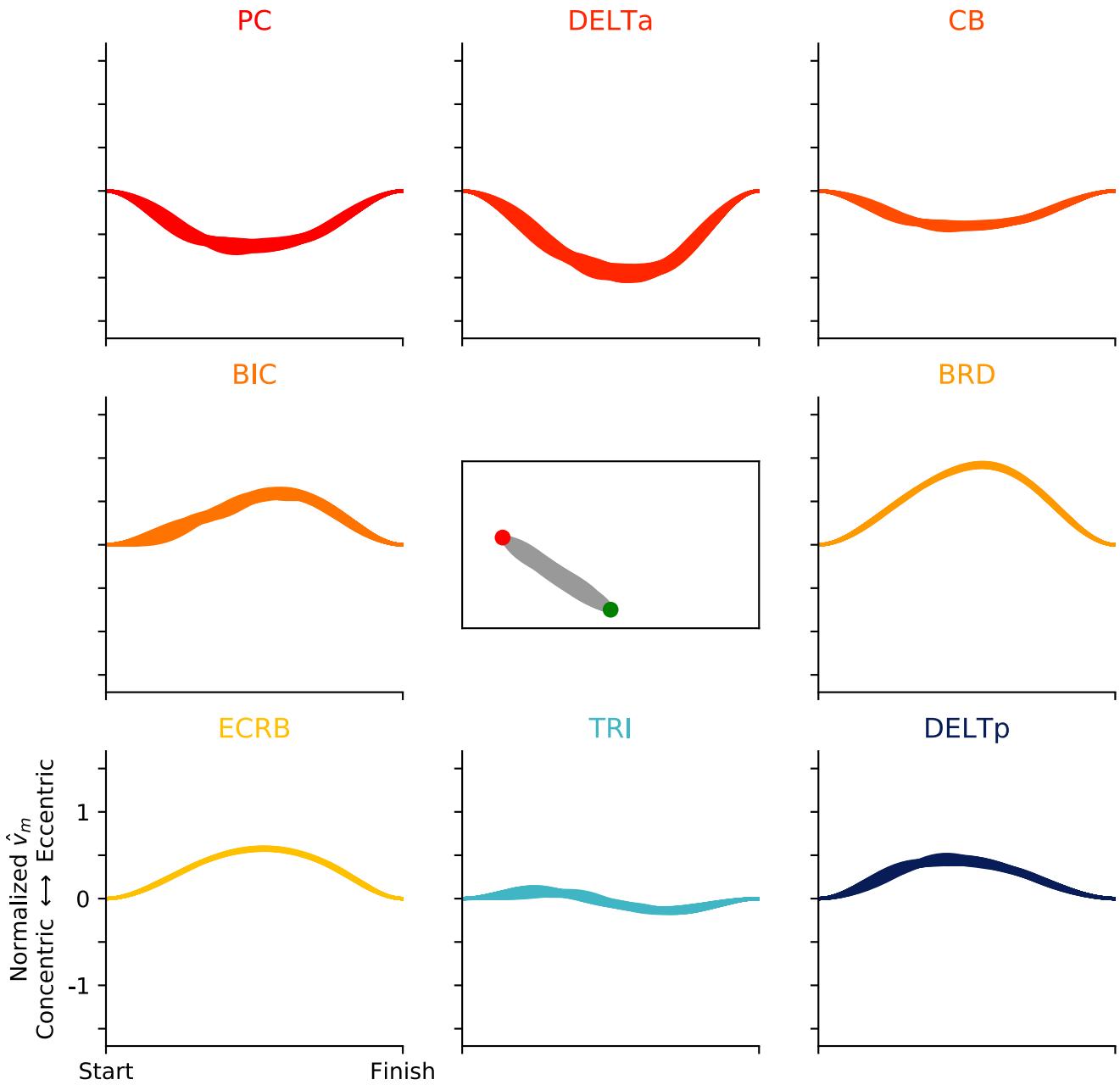
ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

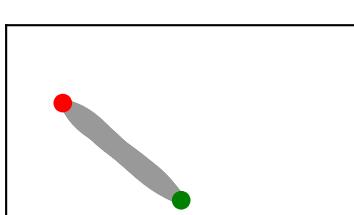
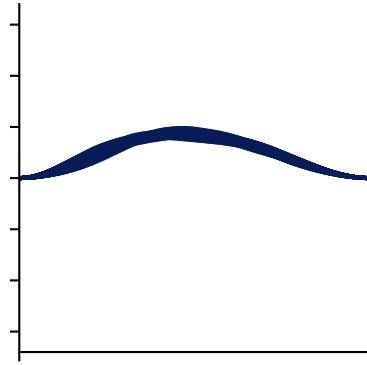
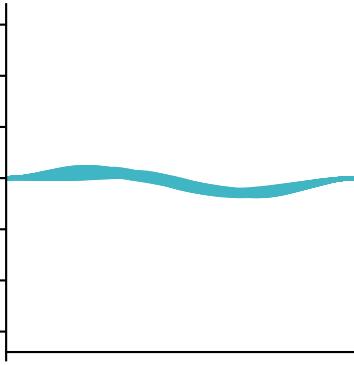
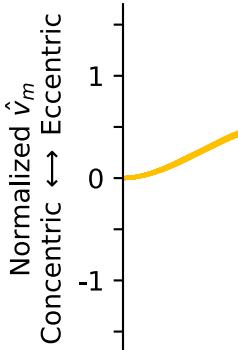
BIC

BRD

ECRB

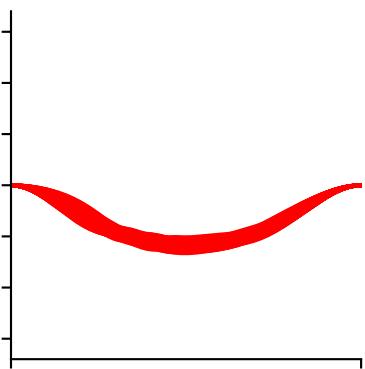
TRI

DELTp

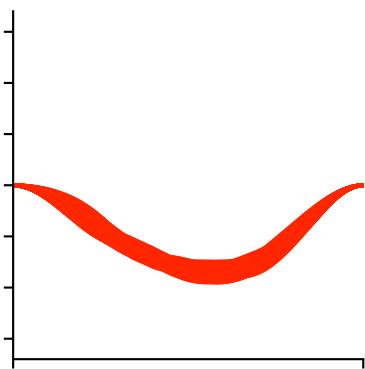


Fixed Initial Position
Movement Duration : 1 sec

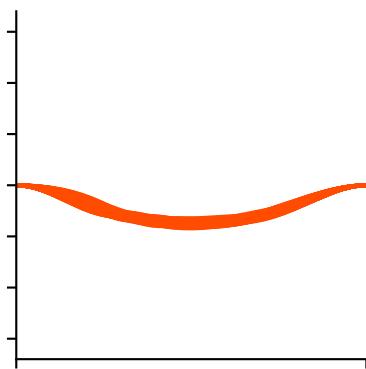
PC



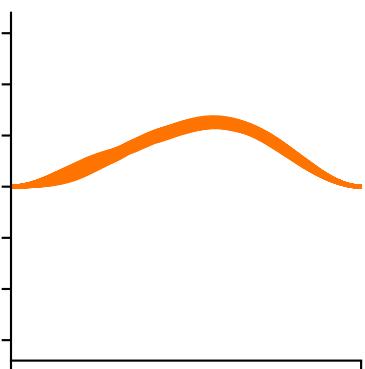
DELTa



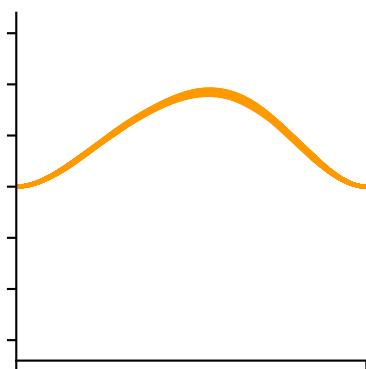
CB



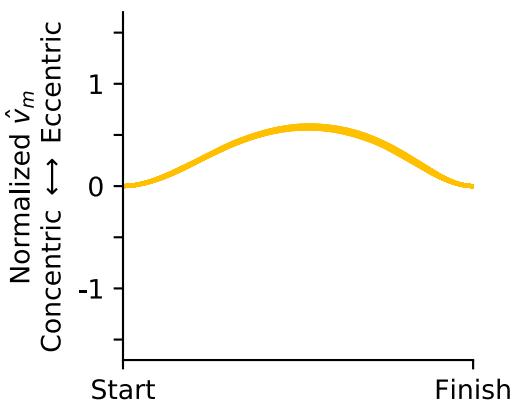
BIC



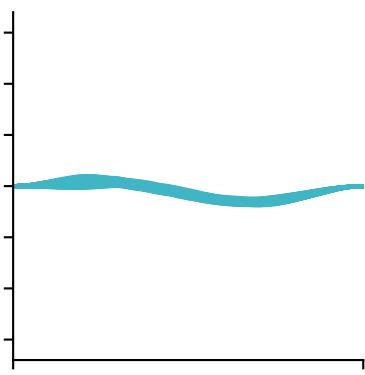
BRD



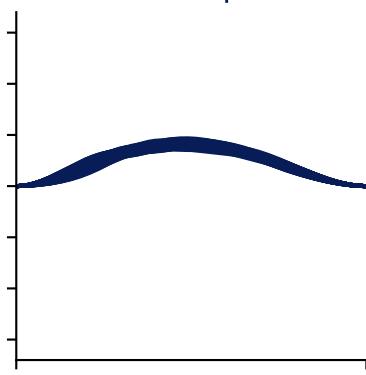
ECRB



TRI



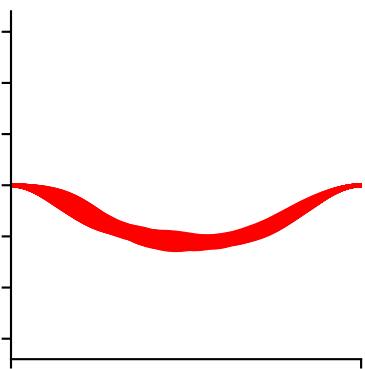
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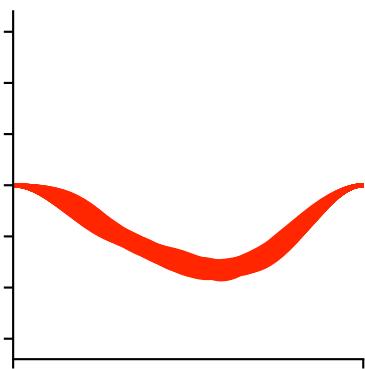
Normalized \dot{V}_m → Eccentric

Fixed Initial Position
Movement Duration : 1 sec

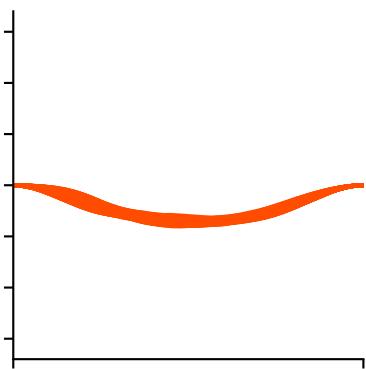
PC



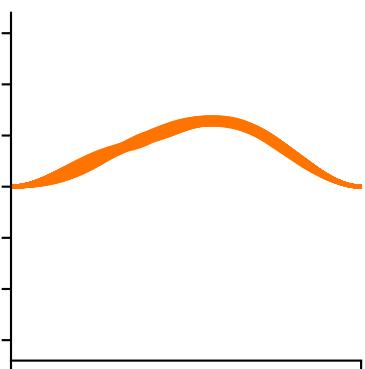
DELTa



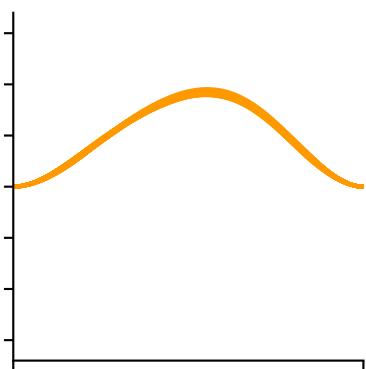
CB



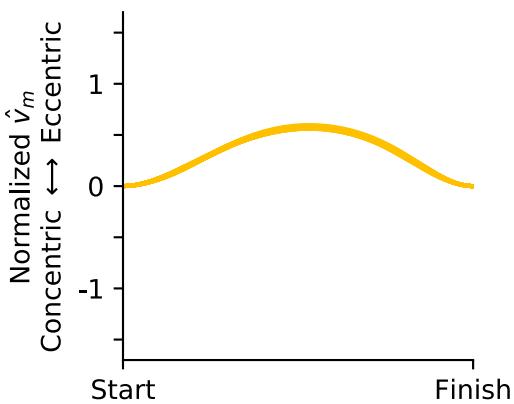
BIC



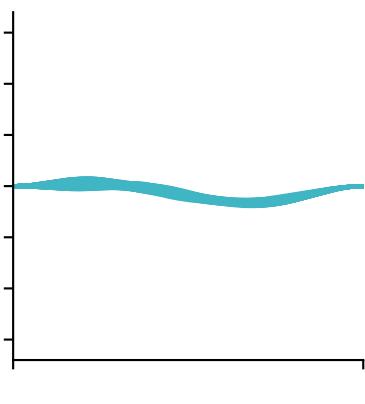
BRD



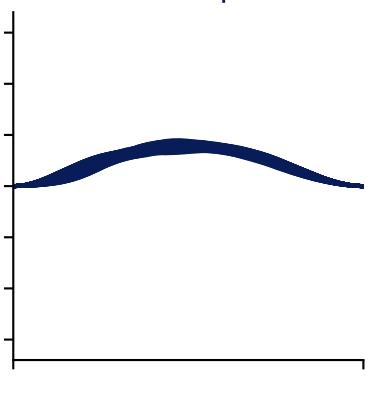
ECRB



TRI



DELTp



Normalized \dot{V}_m
Concentric \leftrightarrow Eccentric

1

0

-1

Start

Finish

Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \dot{V}_m
Concentric \rightarrow Eccentric

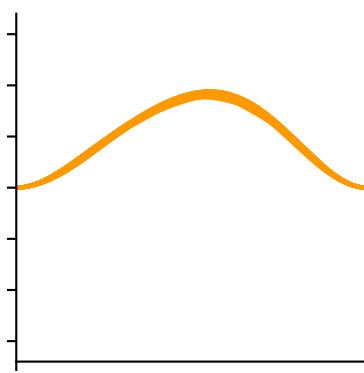
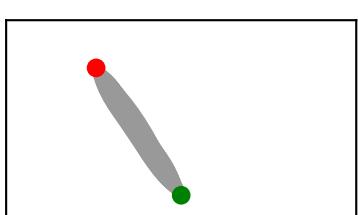
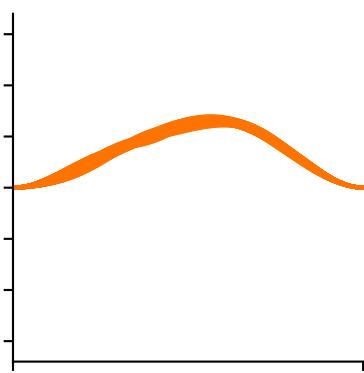
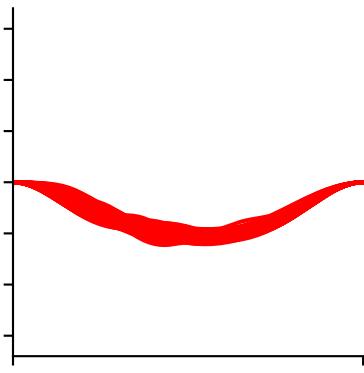
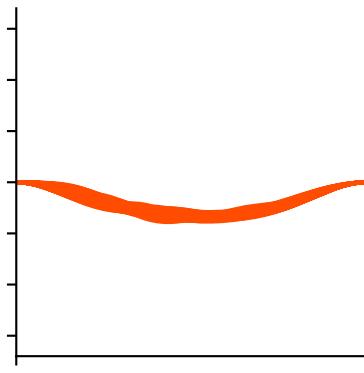
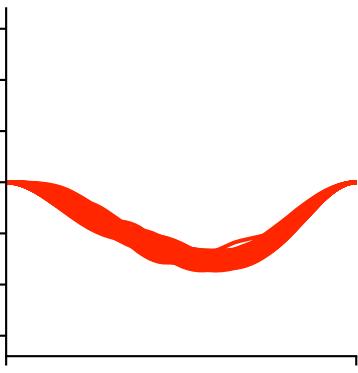
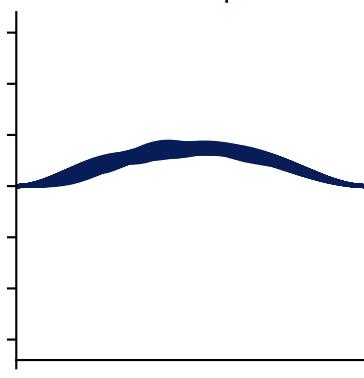
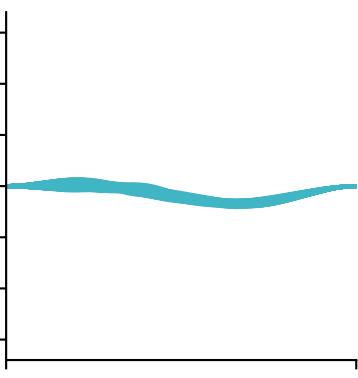
1

0

-1

Start

Finish



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

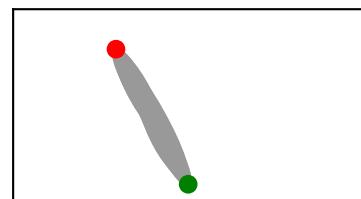
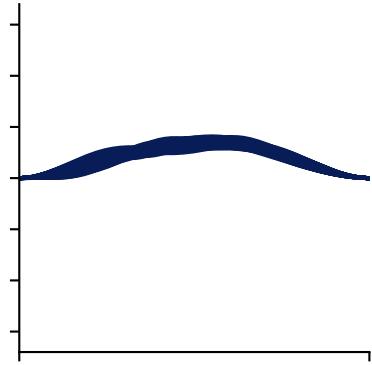
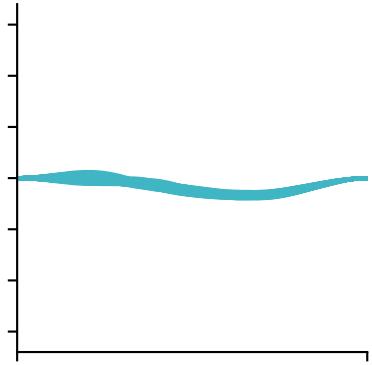
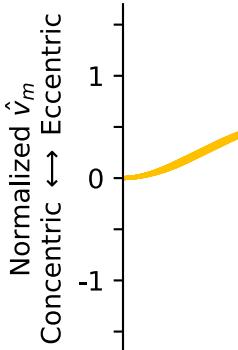
BIC

BRD

ECRB

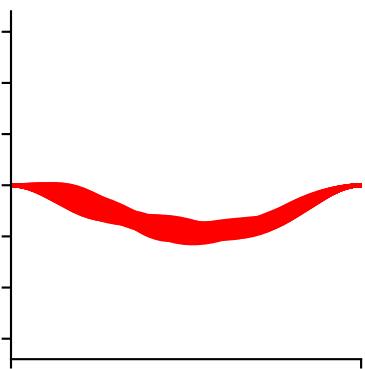
TRI

DELTp

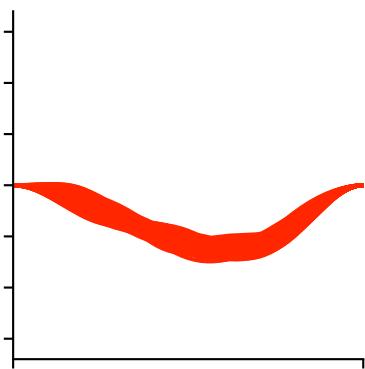


Fixed Initial Position
Movement Duration : 1 sec

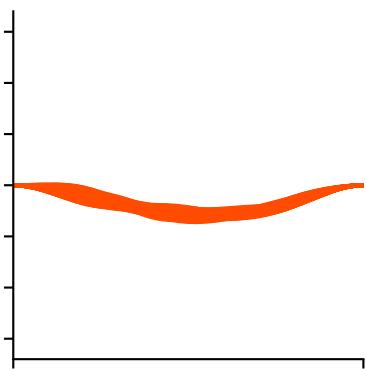
PC



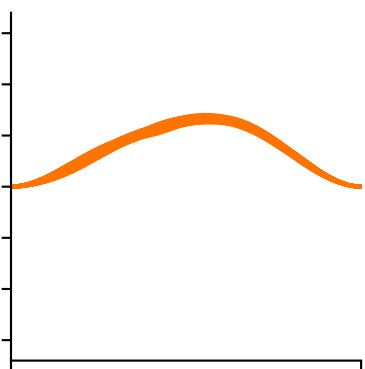
DELTa



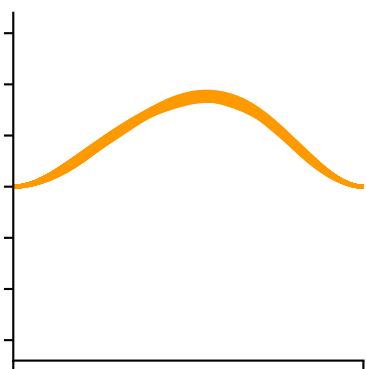
CB



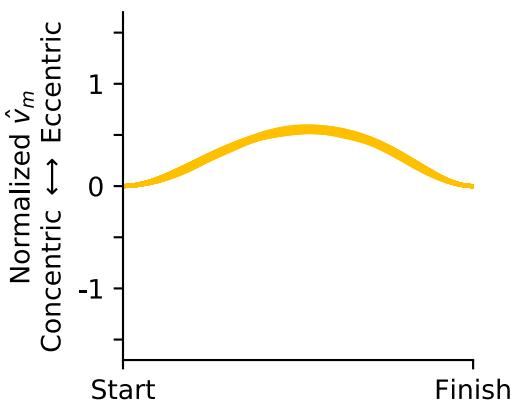
BIC



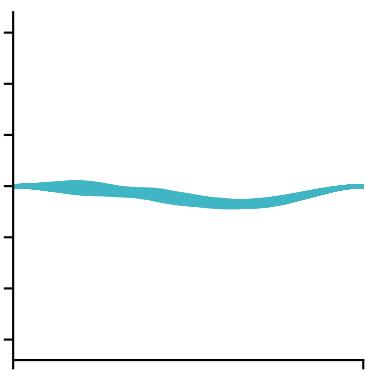
BRD



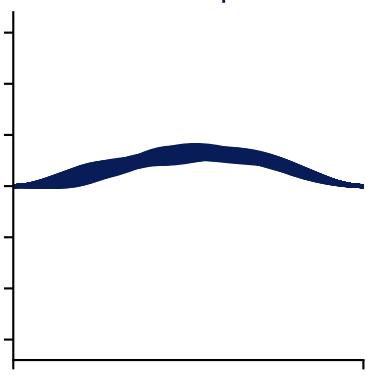
ECRB



TRI



DELTp

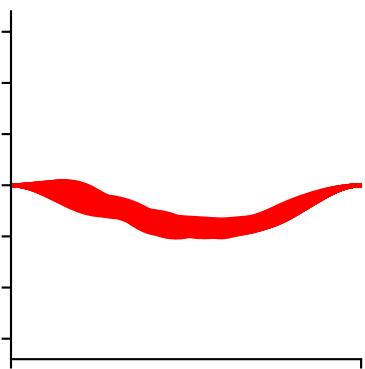


Normalized \dot{V}_m
Concentric \leftrightarrow Eccentric

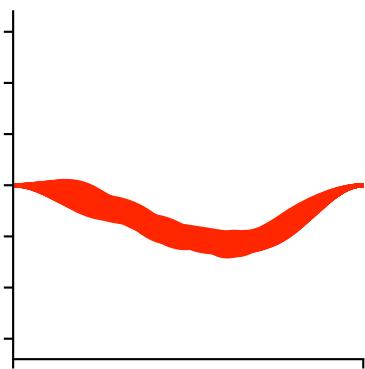
Start Finish

Fixed Initial Position
Movement Duration : 1 sec

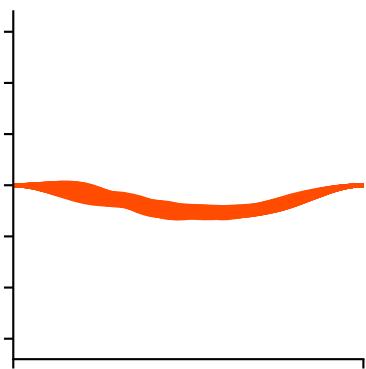
PC



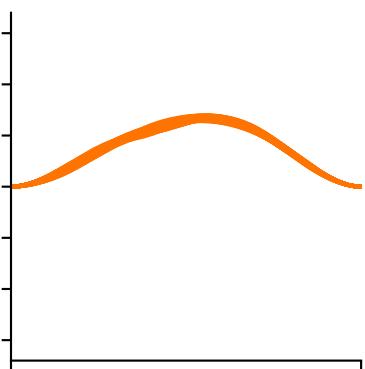
DELTa



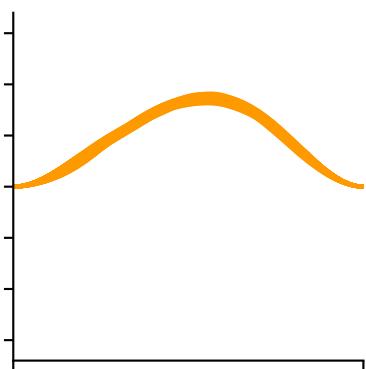
CB



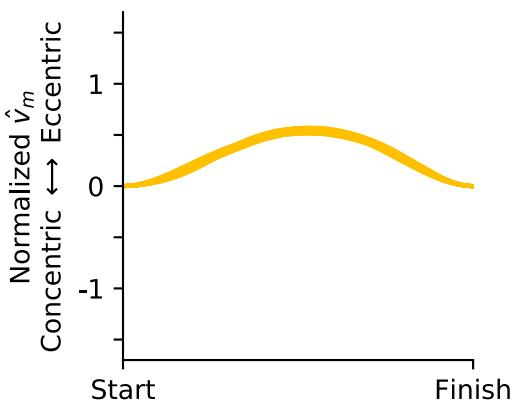
BIC



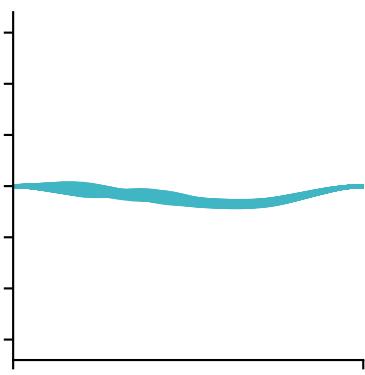
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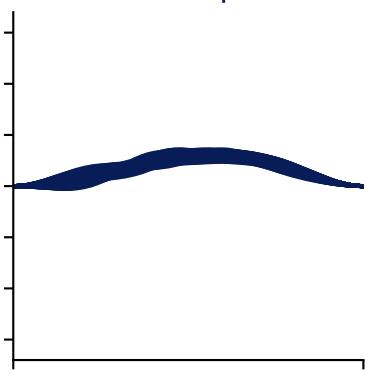
ECRB



TRI



DELTp



Normalized \dot{V}_m → Eccentric

Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

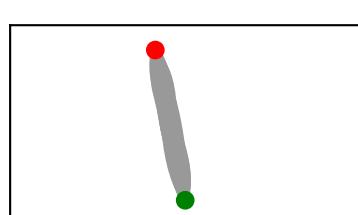
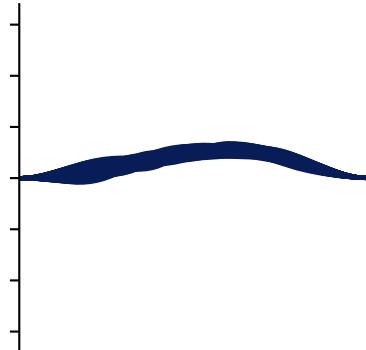
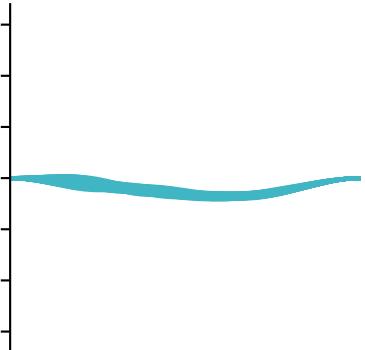
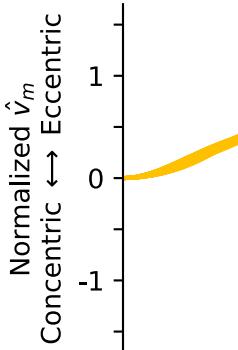
BIC

BRD

ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

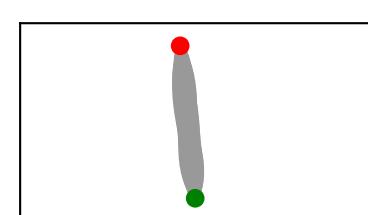
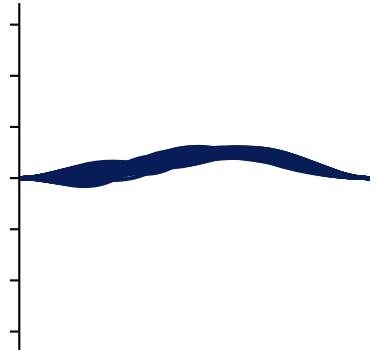
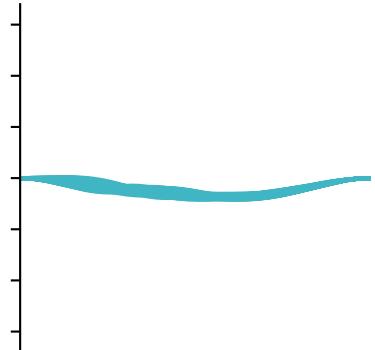
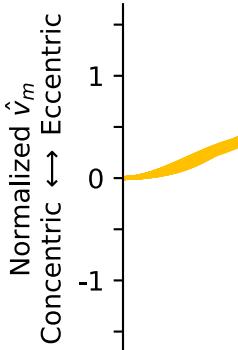
BIC

BRD

ECRB

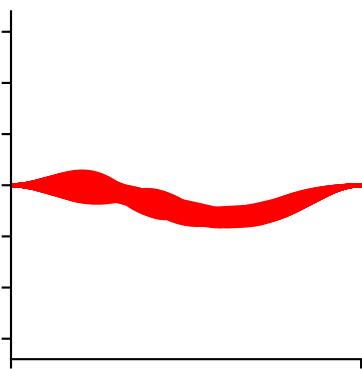
TRI

DELTp

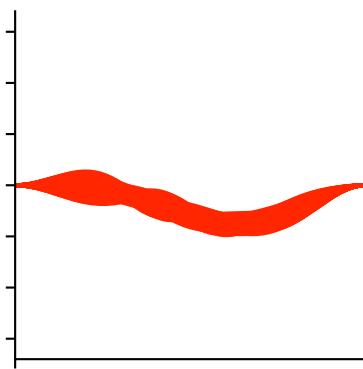


Fixed Initial Position
Movement Duration : 1 sec

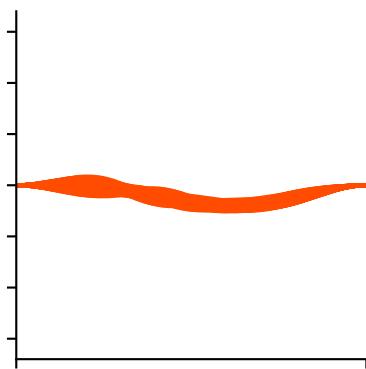
PC



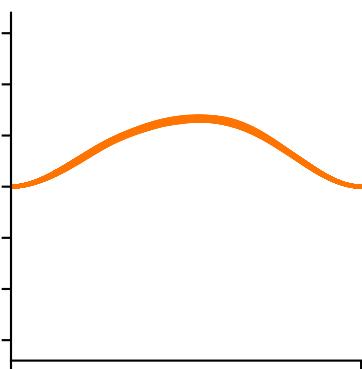
DELTa



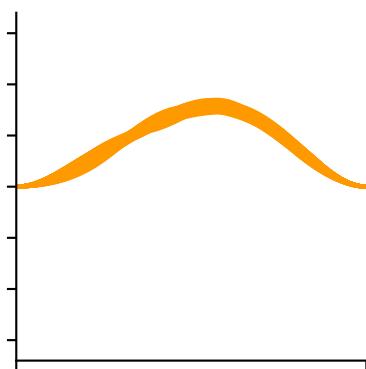
CB



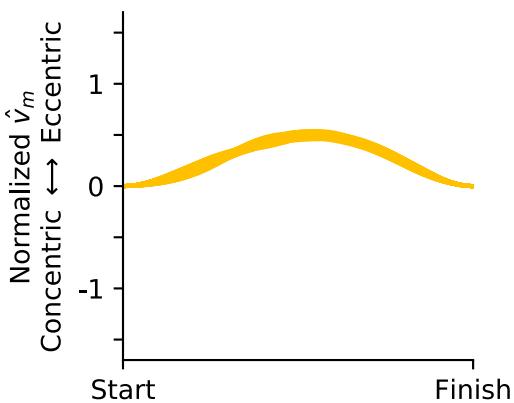
BIC



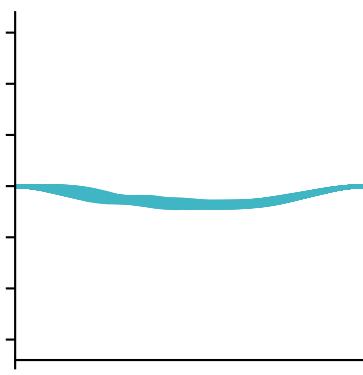
BRD



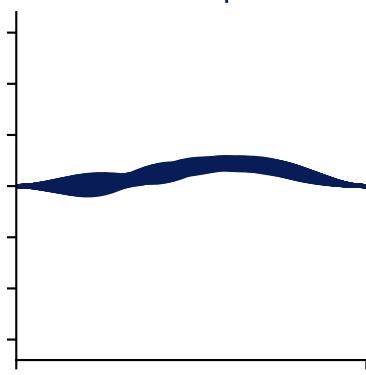
ECRB



TRI



DELTp



Normalized \dot{V}_m
Concentric \leftrightarrow Eccentric

Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

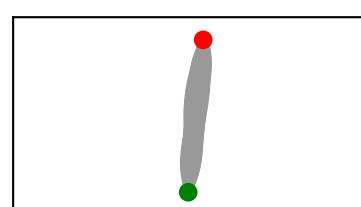
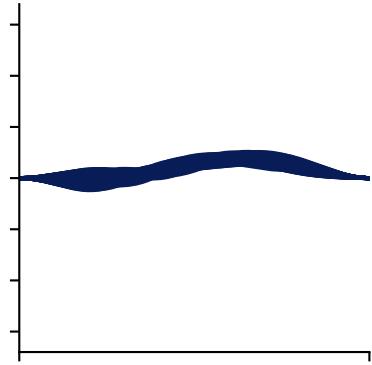
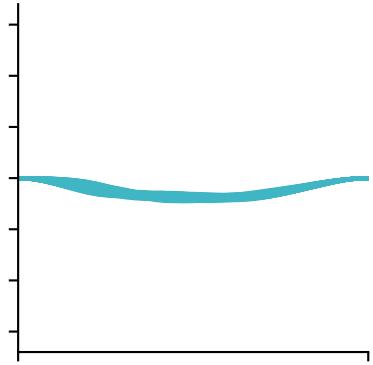
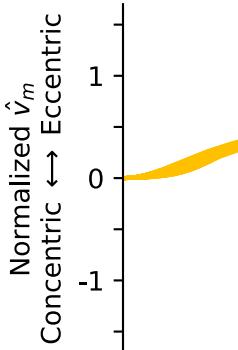
BIC

BRD

ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

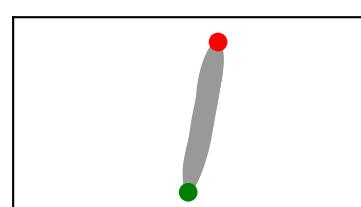
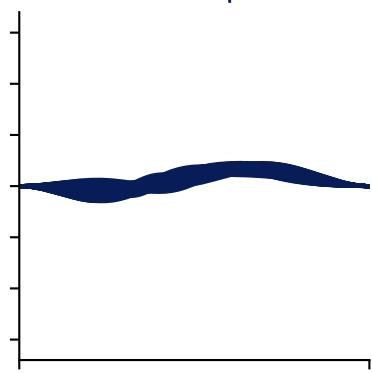
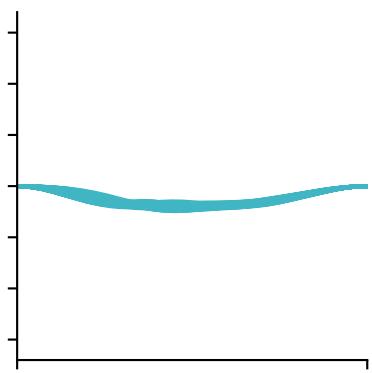
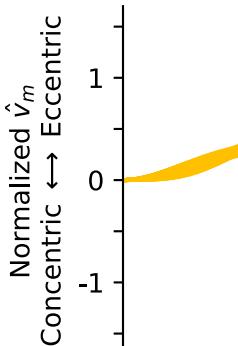
BIC

BRD

ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

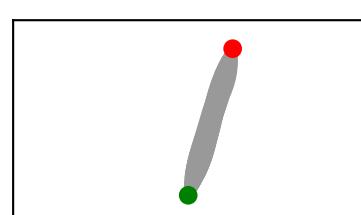
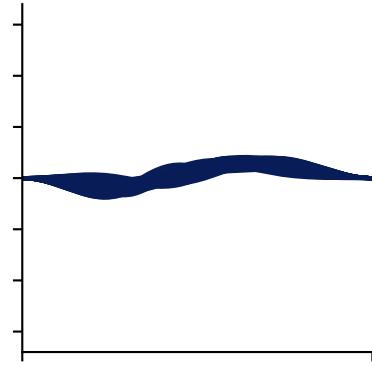
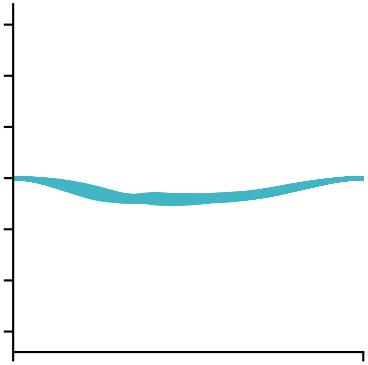
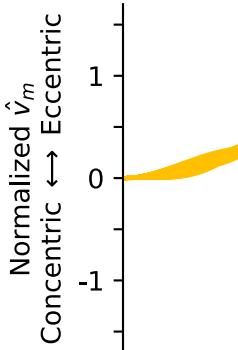
BIC

BRD

ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

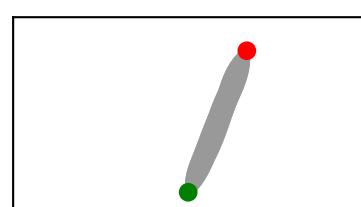
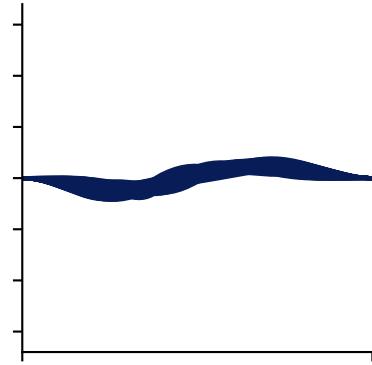
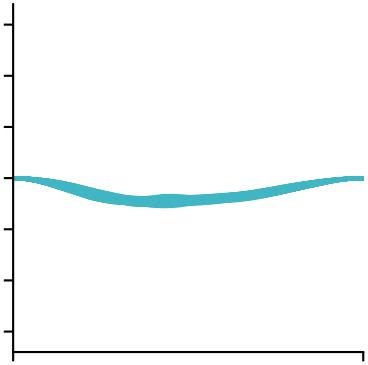
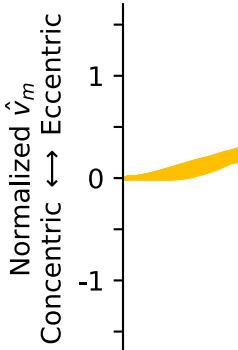
BIC

BRD

ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

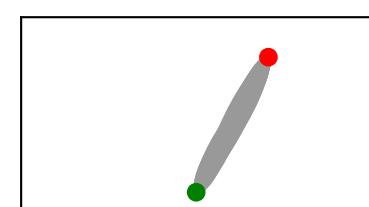
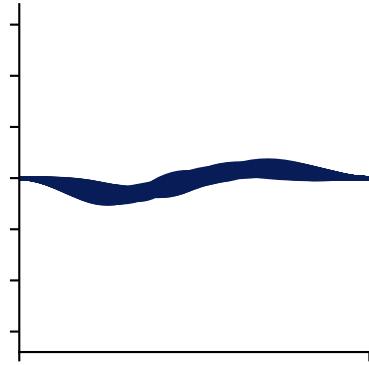
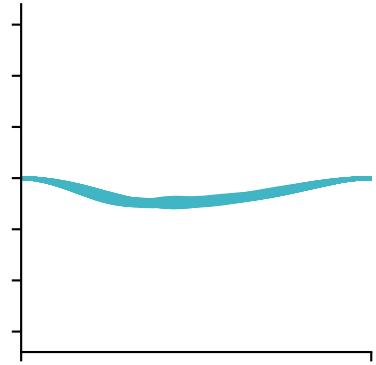
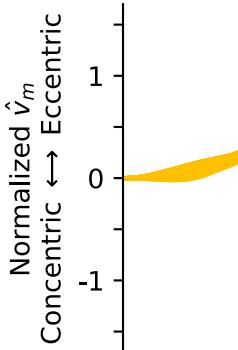
BIC

BRD

ECRB

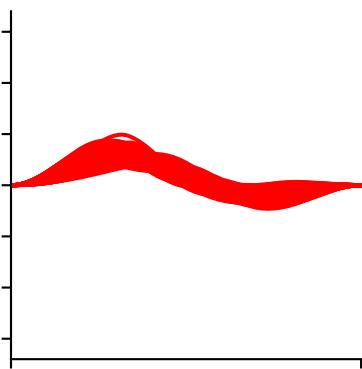
TRI

DELTp

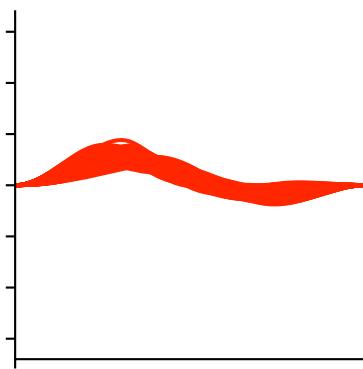


Fixed Initial Position
Movement Duration : 1 sec

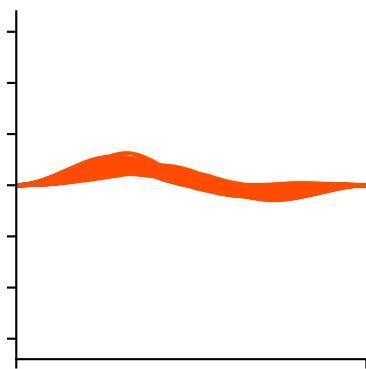
PC



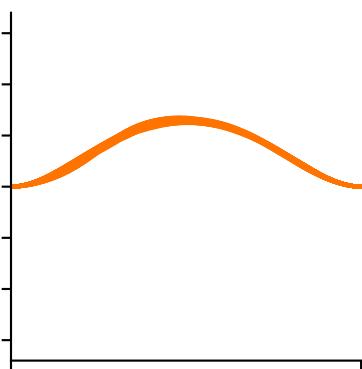
DELTa



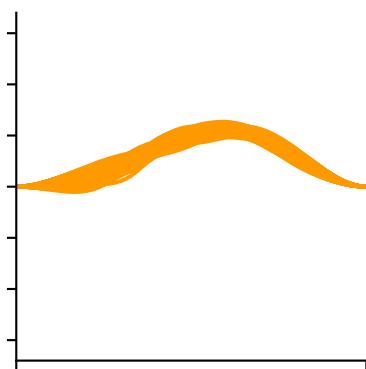
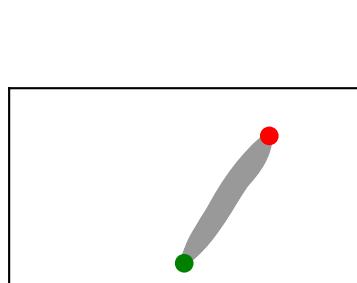
CB



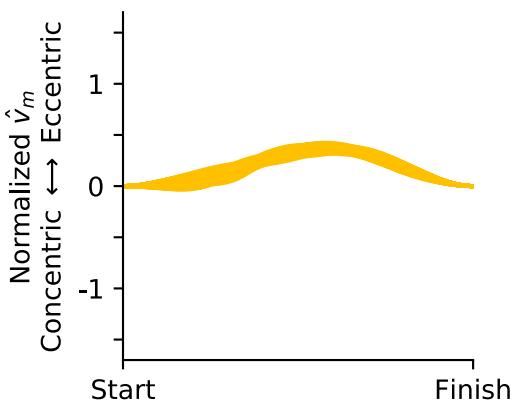
BIC



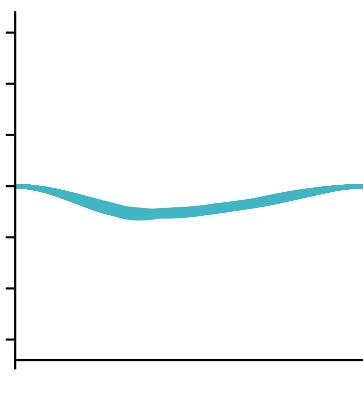
BRD



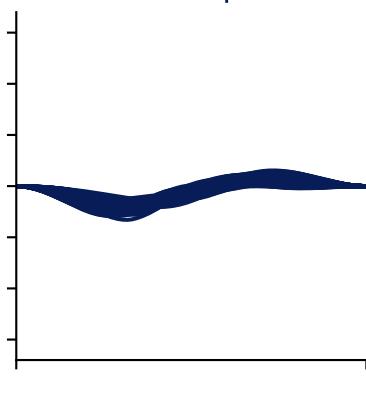
ECRB



TRI



DELTp

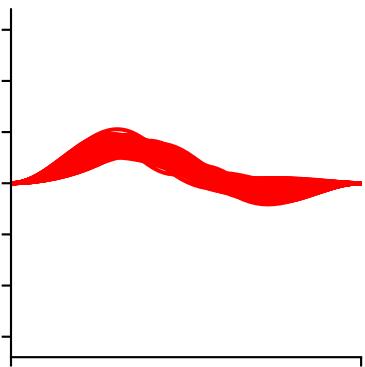


Normalized \hat{V}_m
Concentric \leftrightarrow Eccentric

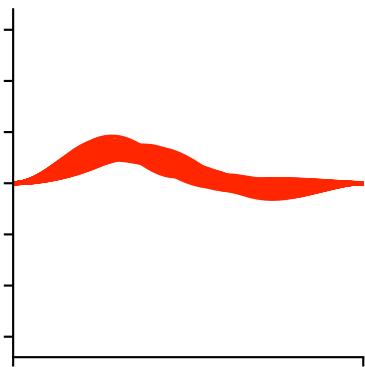
Start Finish

Fixed Initial Position
Movement Duration : 1 sec

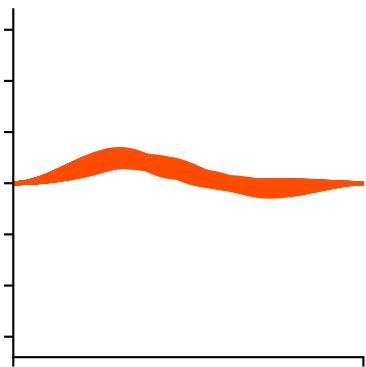
PC



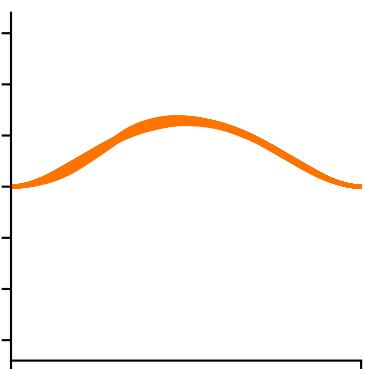
DELTa



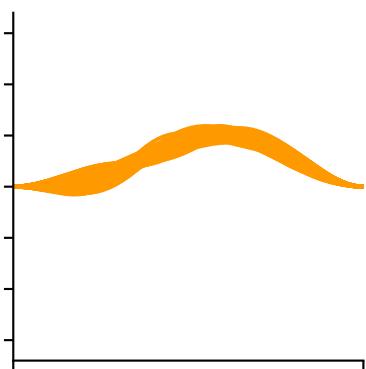
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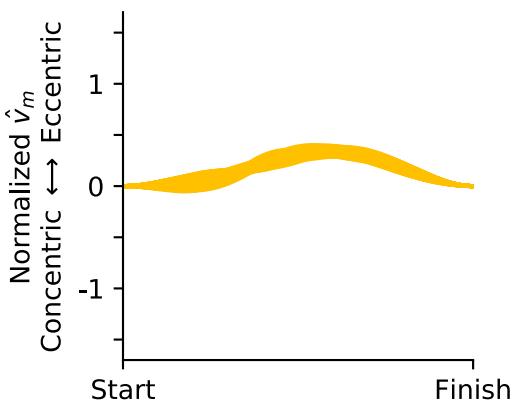
BIC



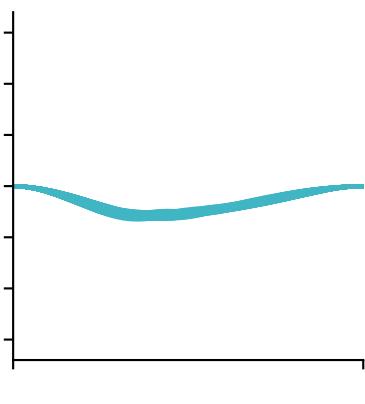
BRD



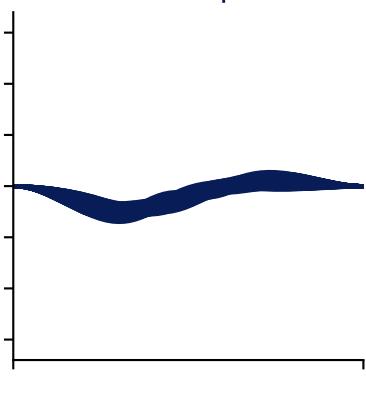
ECRB



TRI



DELTp



Normalized \hat{V}_m
Concentric \leftrightarrow Eccentric

Start Finish

Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

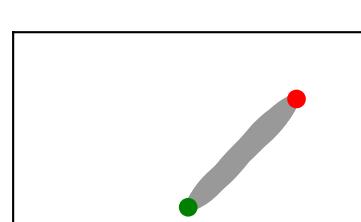
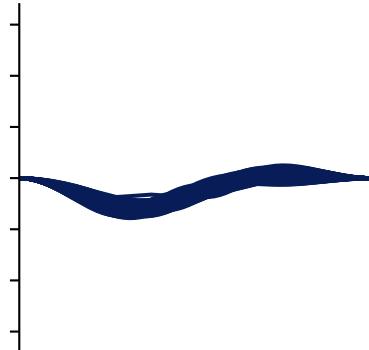
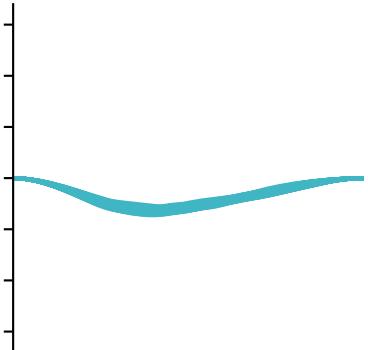
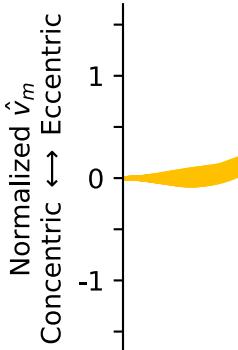
BIC

BRD

ECRB

TRI

DELTp



Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

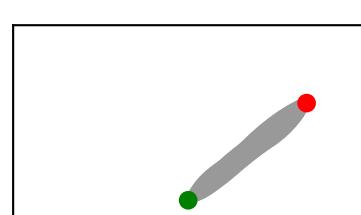
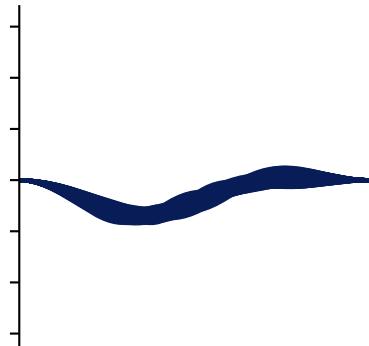
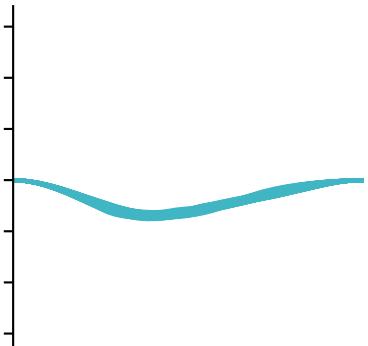
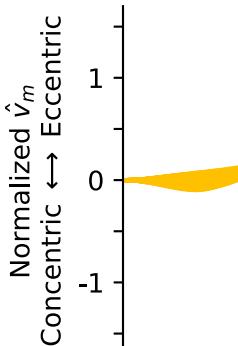
BIC

BRD

ECRB

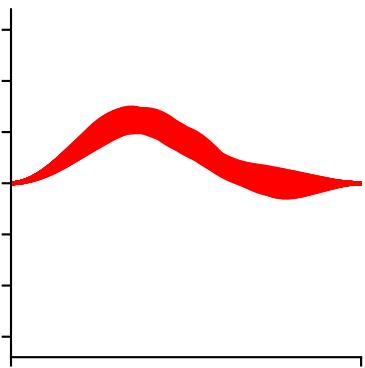
TRI

DELTp

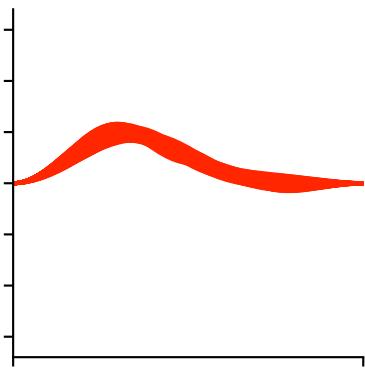


Fixed Initial Position
Movement Duration : 1 sec

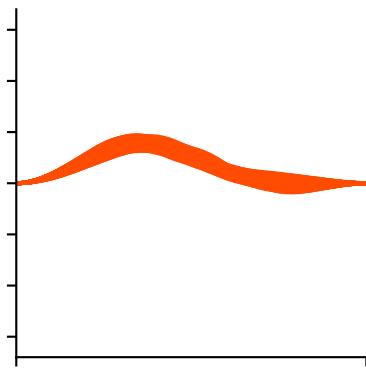
PC



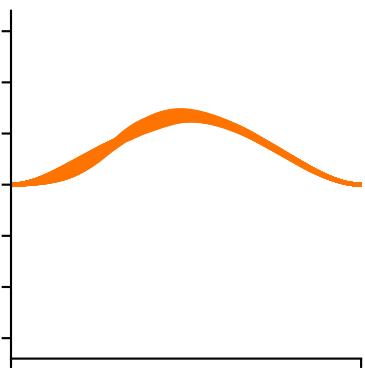
DELTa



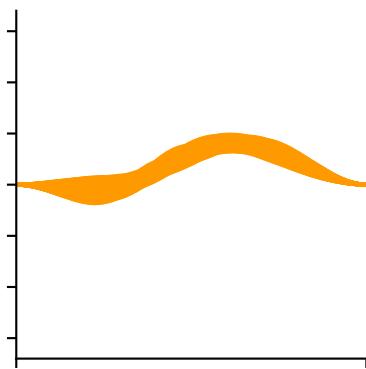
CB



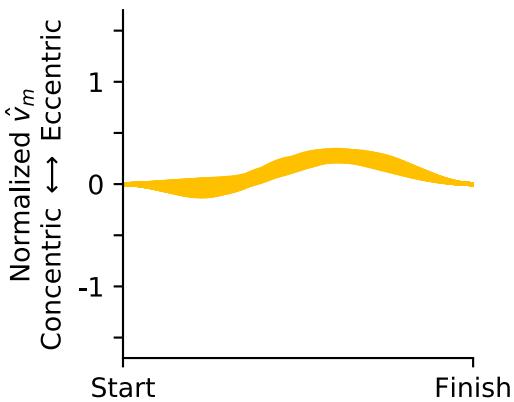
BIC



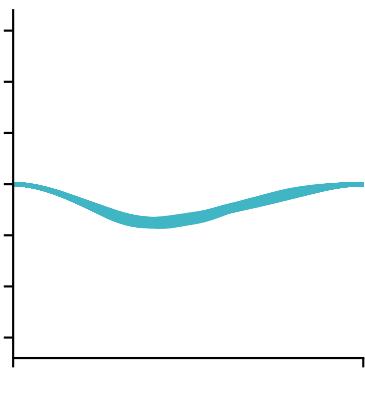
BRD



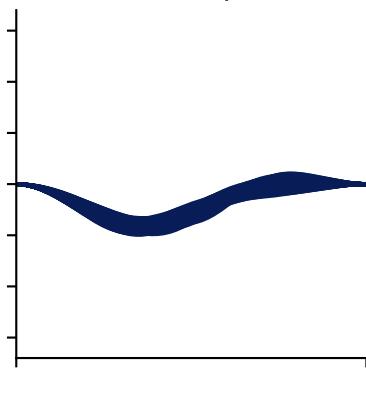
ECRB



TRI



DELTp



Normalized \hat{V}_m
Concentric \leftrightarrow Eccentric

Start Finish

Fixed Initial Position
Movement Duration : 1 sec

PC

DELTa

CB

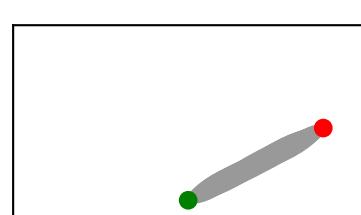
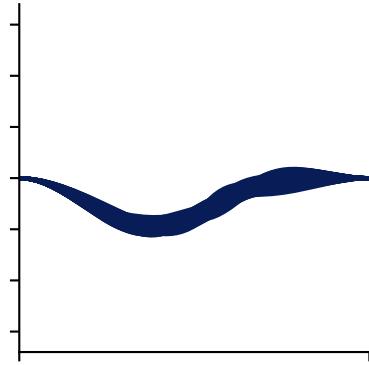
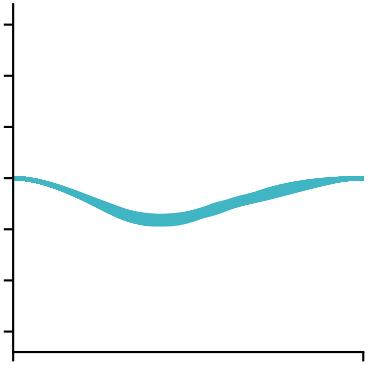
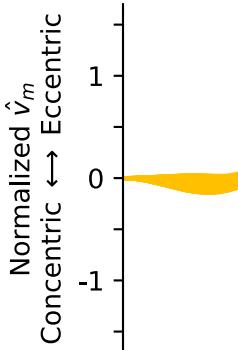
BIC

BRD

ECRB

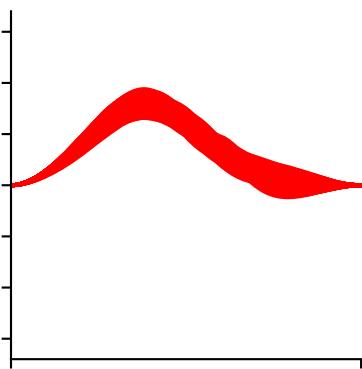
TRI

DELTp

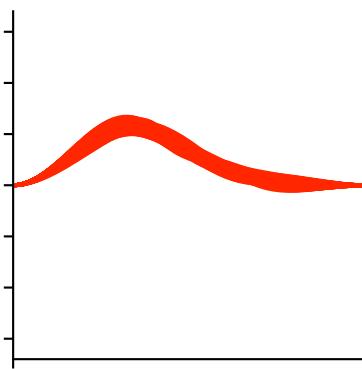


Fixed Initial Position
Movement Duration : 1 sec

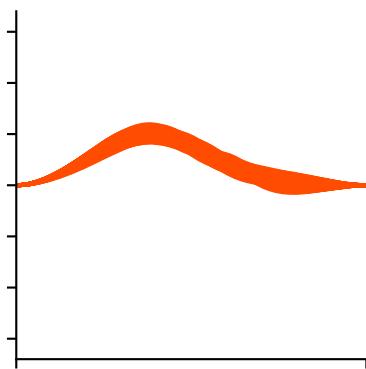
PC



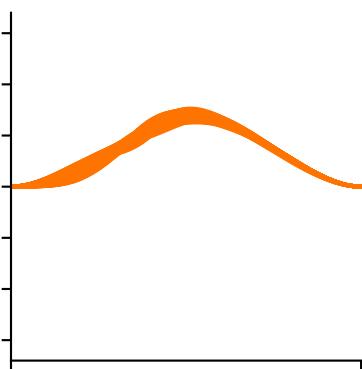
DELTa



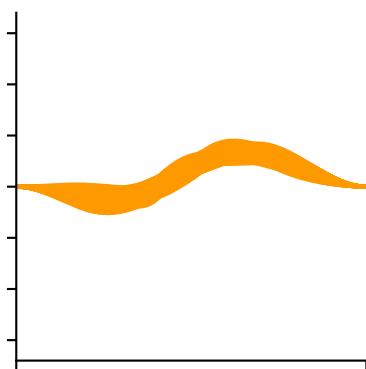
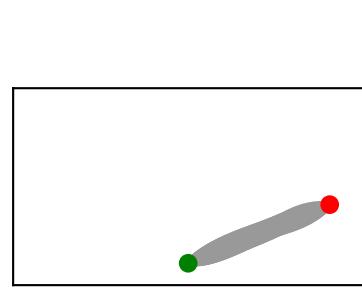
CB



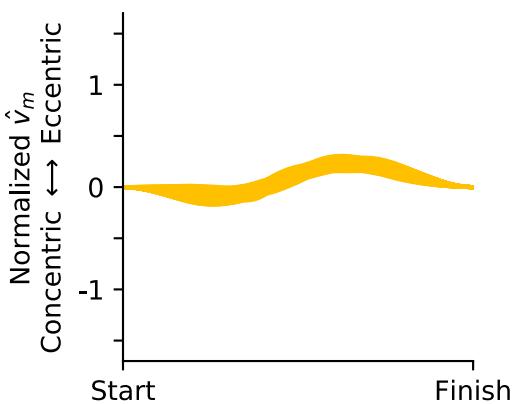
BIC



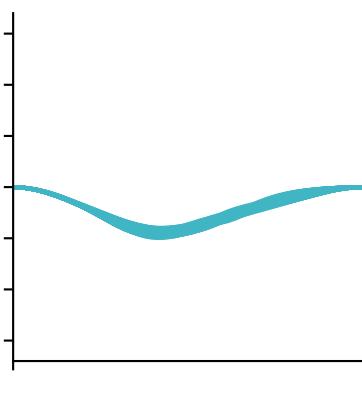
BRD



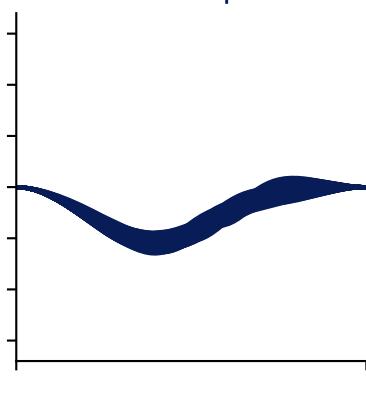
ECRB



TRI



DELTp



Normalized \hat{V}_m
Concentric \leftrightarrow Eccentric

1

0

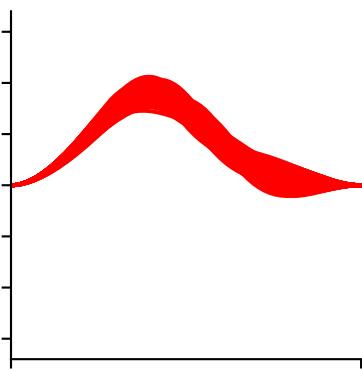
-1

Start

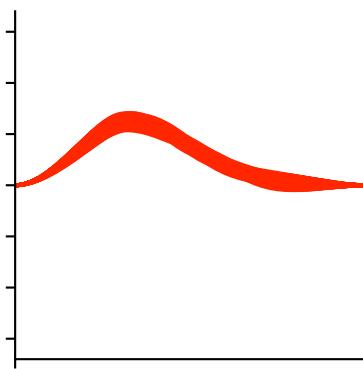
Finish

Fixed Initial Position
Movement Duration : 1 sec

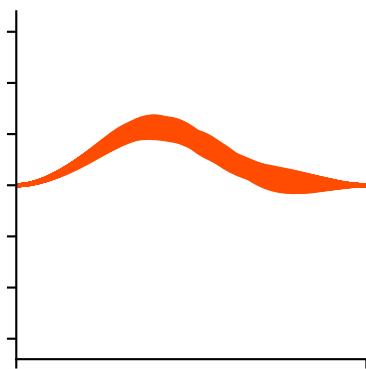
PC



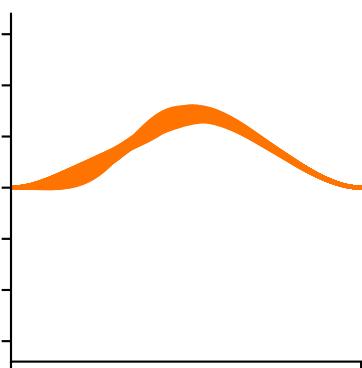
DELTa



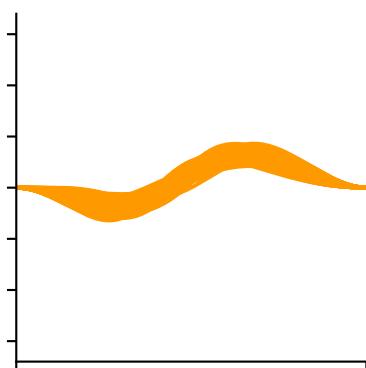
CB



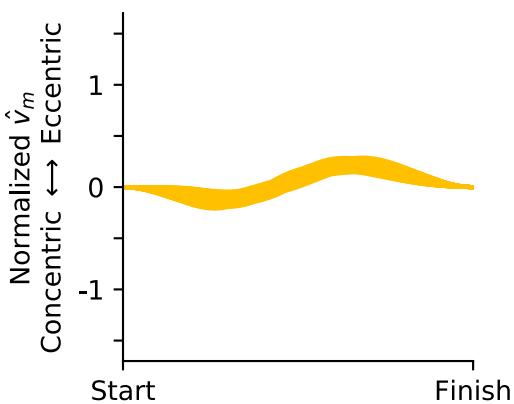
BIC



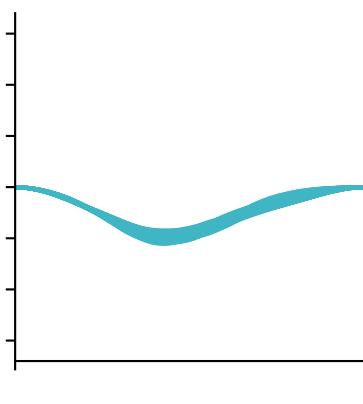
BRD



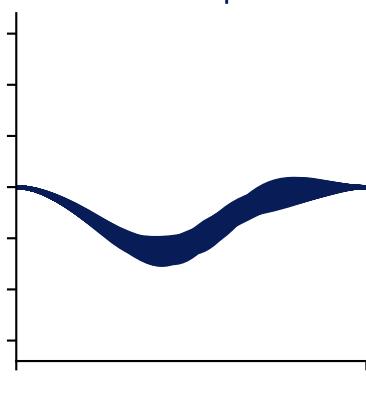
ECRB



TRI



DELTp



Normalized \hat{V}_m Eccentric
Concentric \leftrightarrow Eccentric

1

0

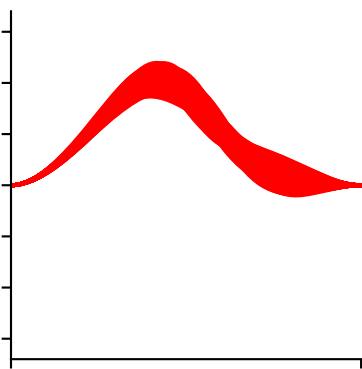
-1

Start

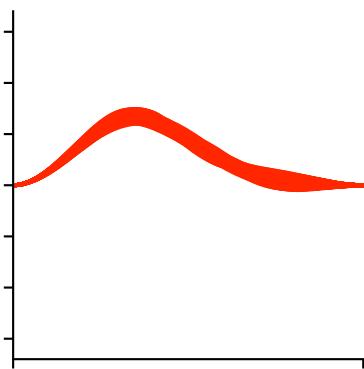
Finish

Fixed Initial Position
Movement Duration : 1 sec

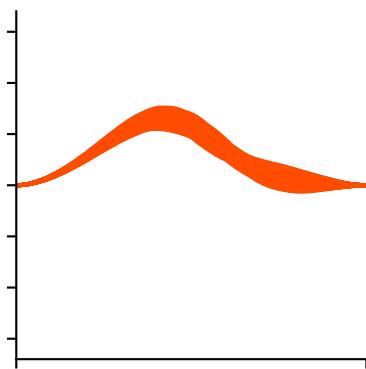
PC



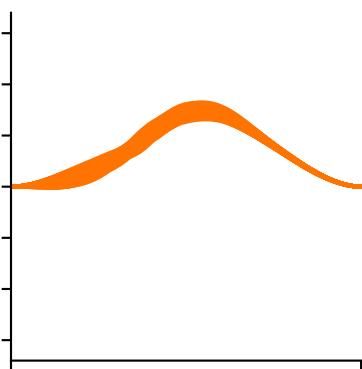
DELTa



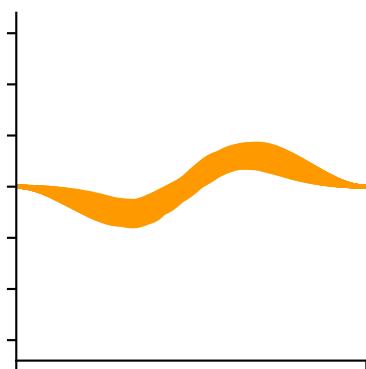
CB



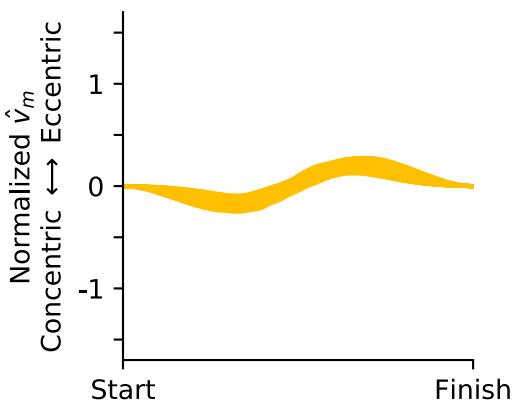
BIC



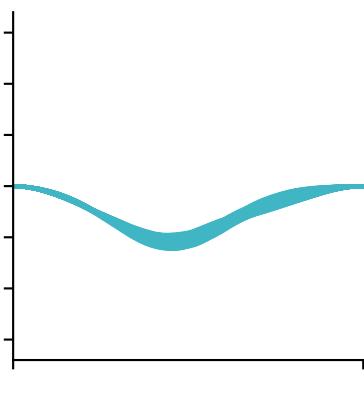
BRD



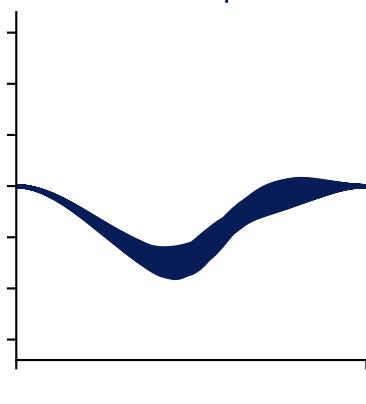
ECRB



TRI



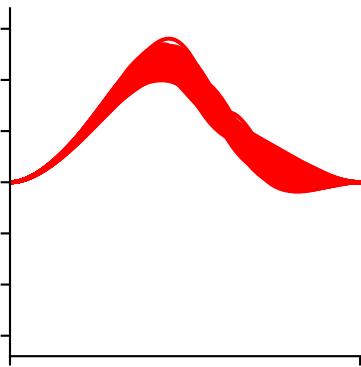
DELTp



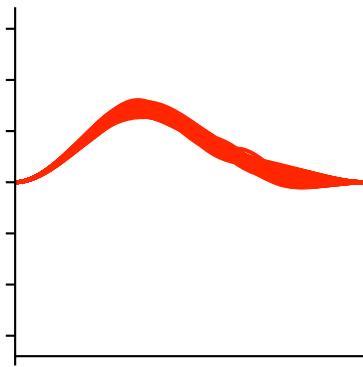
Normalized \hat{V}_m Eccentric
Concentric \leftrightarrow Eccentric

Fixed Initial Position
Movement Duration : 1 sec

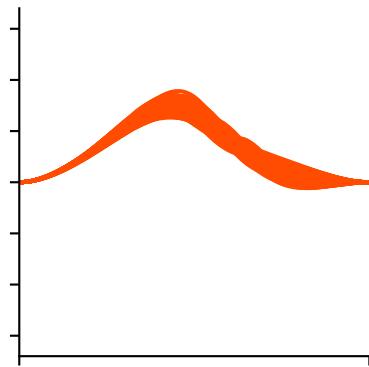
PC



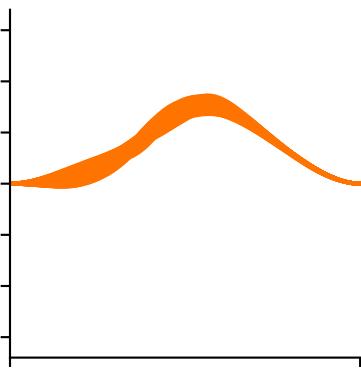
DELTa



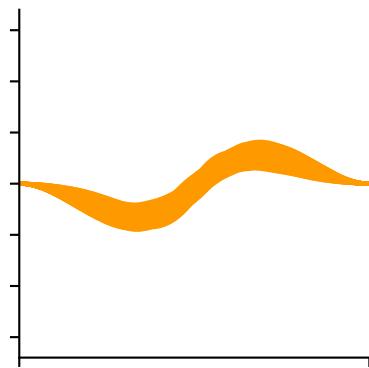
CB



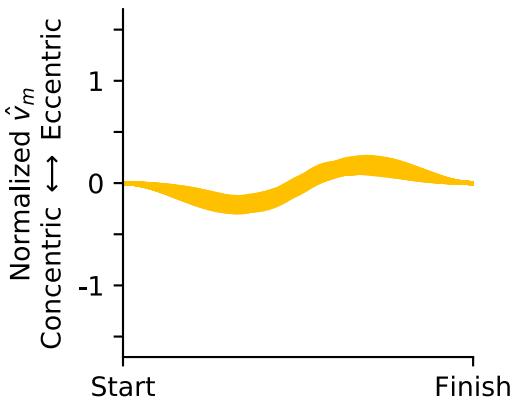
BIC



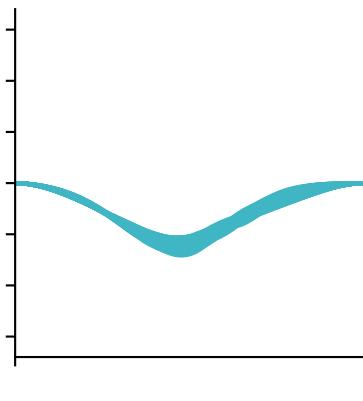
BRD



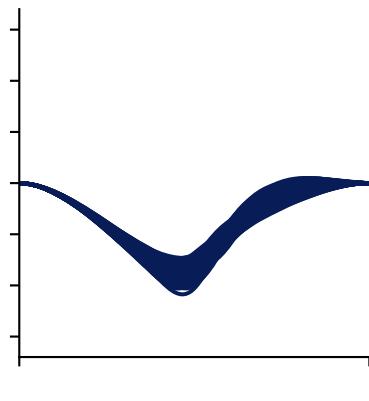
ECRB



TRI



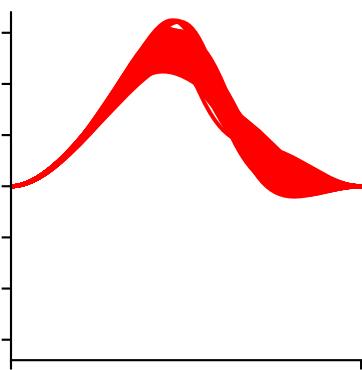
DELTp



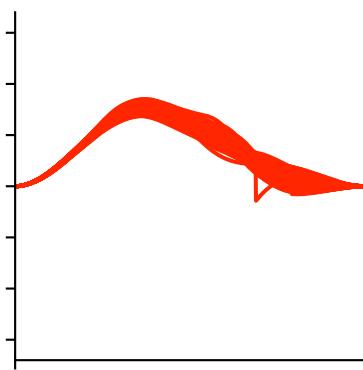
Normalized \dot{V}_m → Eccentric

Fixed Initial Position
Movement Duration : 1 sec

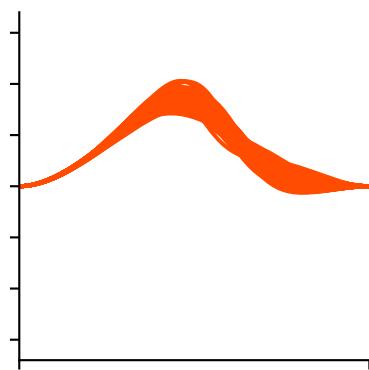
PC



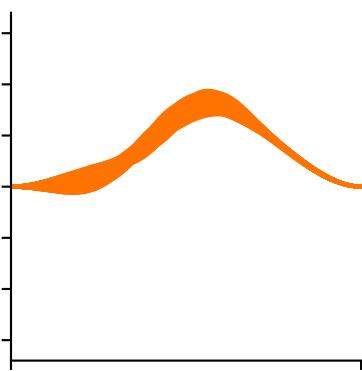
DELTa



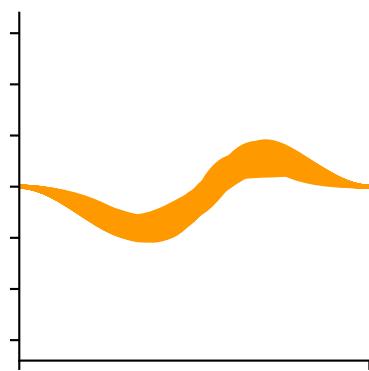
CB



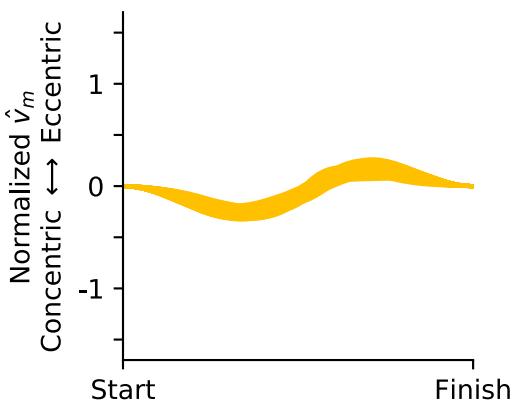
BIC



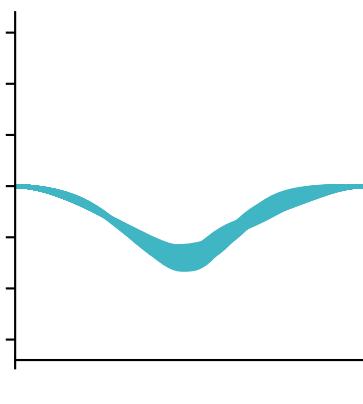
BRD



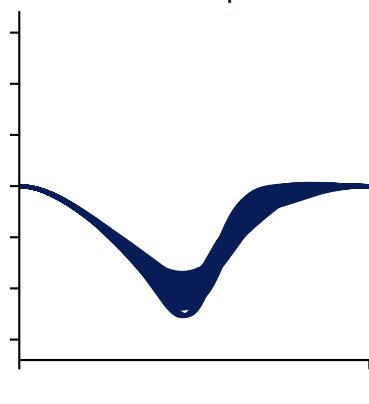
ECRB



TRI



DELTp



Normalized \dot{V}_m → Eccentric

1

0

-1

Start

Finish