

Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

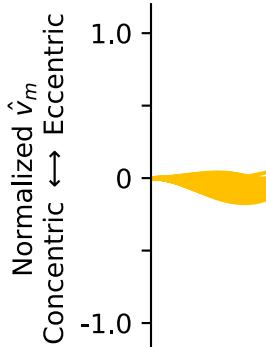
BIC

BRD

ECRB

TRI

DELTp



Start

Finish

Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \hat{v}_m
Concentric \rightarrow Eccentric

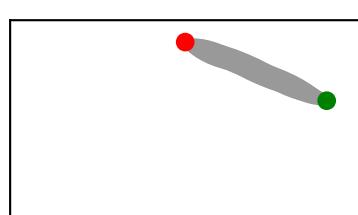
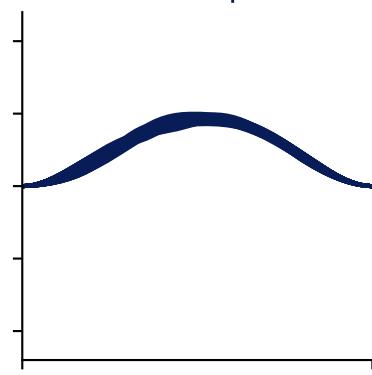
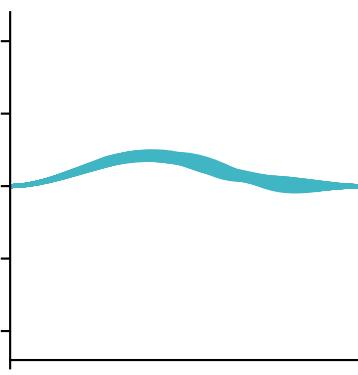
1.0

0

-1.0

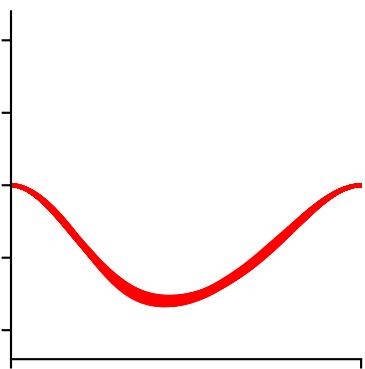
Start

Finish

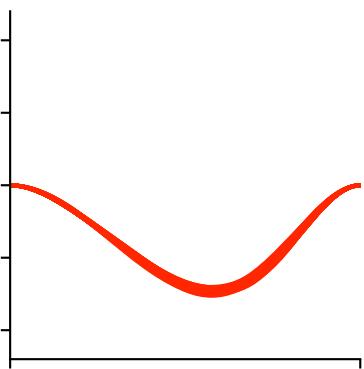


Fixed Final Position
Movement Duration : 1 sec

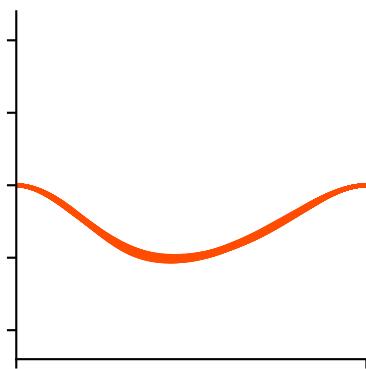
PC



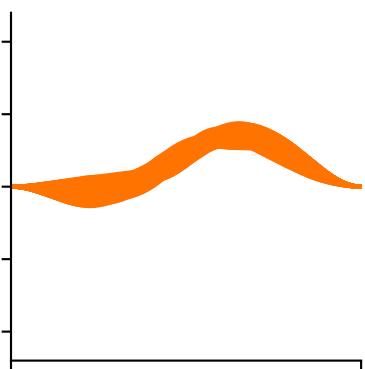
DELTa



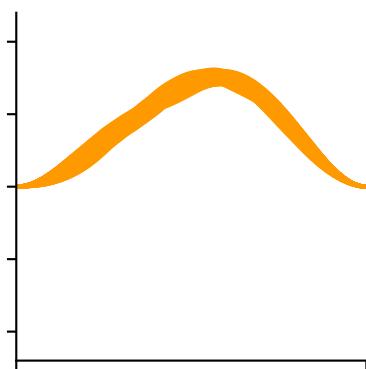
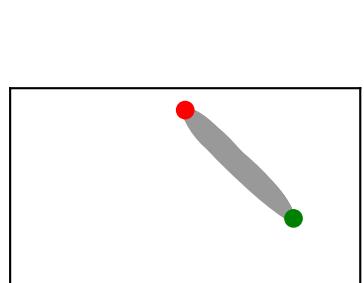
CB



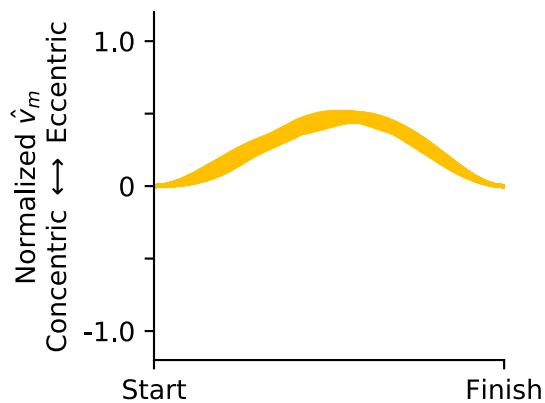
BIC



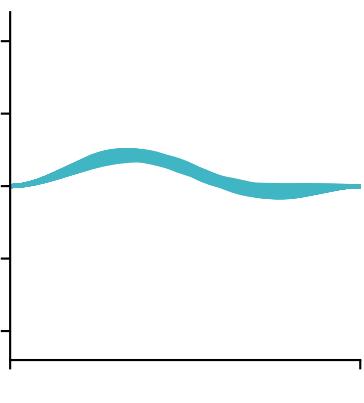
BRD



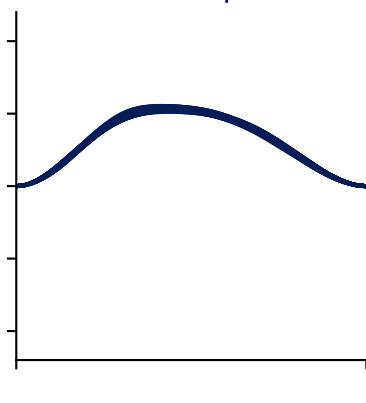
ECRB



TRI



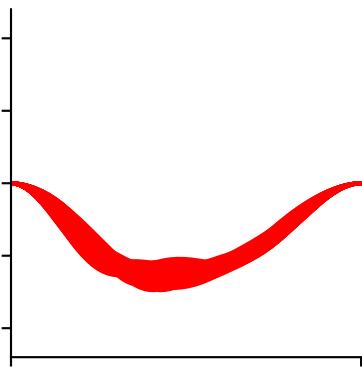
DELTp



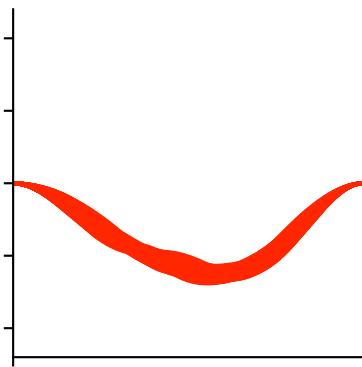
Normalized \hat{v}_m
Concentric \rightarrow Eccentric

Fixed Final Position
Movement Duration : 1 sec

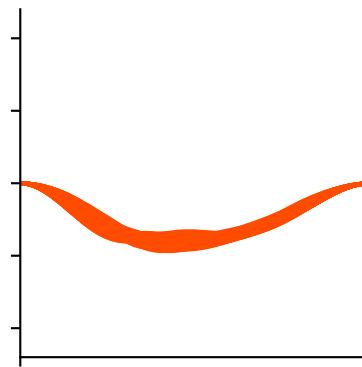
PC



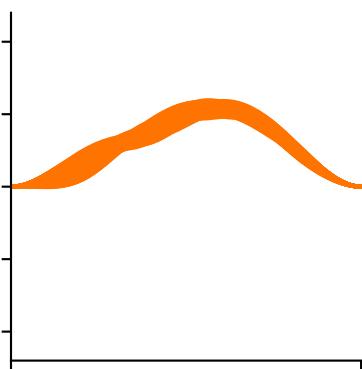
DELTa



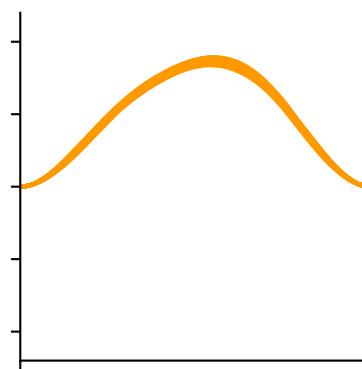
CB



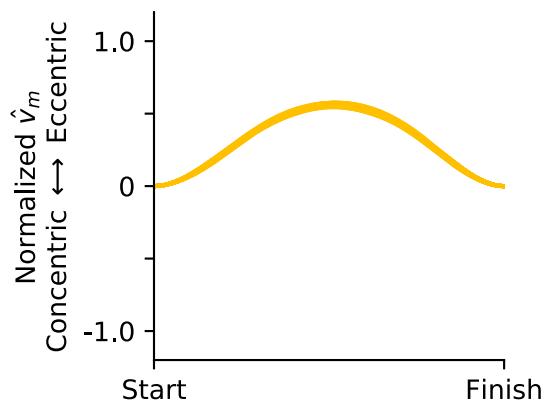
BIC



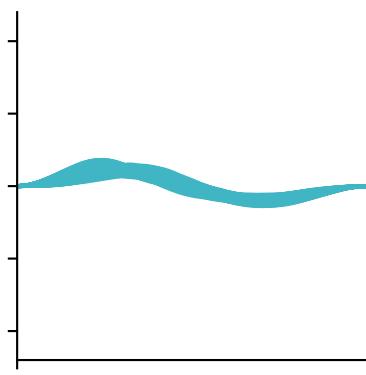
BRD



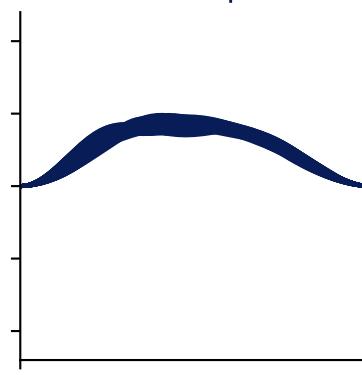
ECRB



TRI



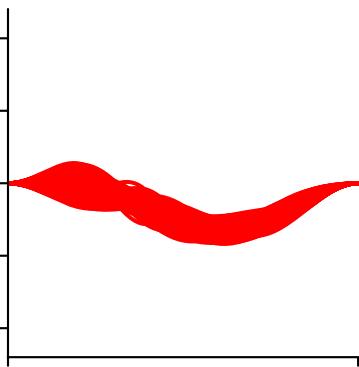
DELTp



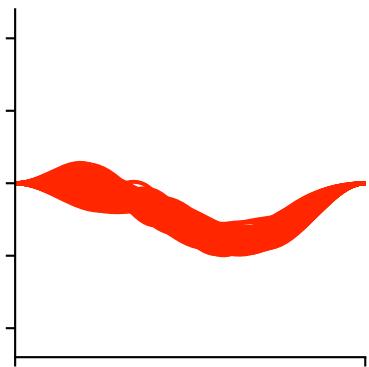
Normalized \hat{v}_m
Concentric \rightarrow Eccentric

Fixed Final Position
Movement Duration : 1 sec

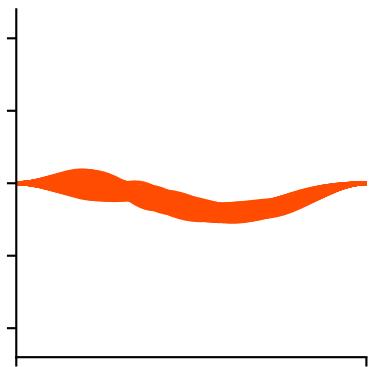
PC



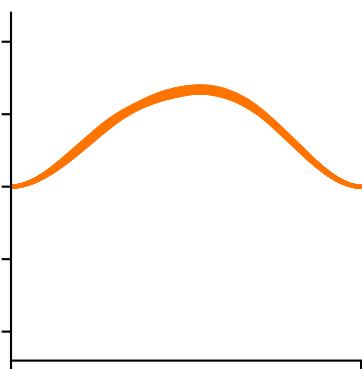
DELTa



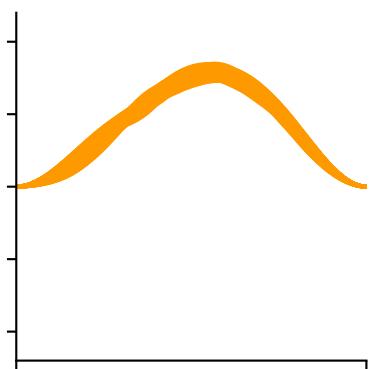
CB



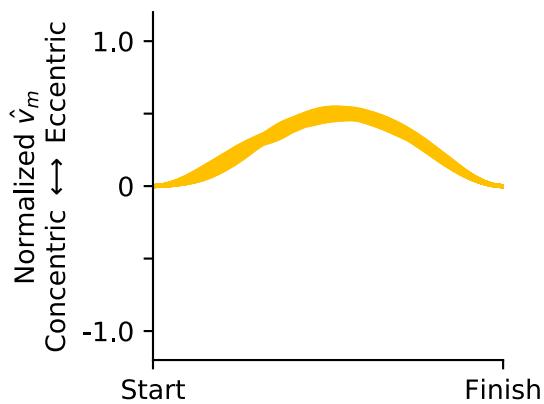
BIC



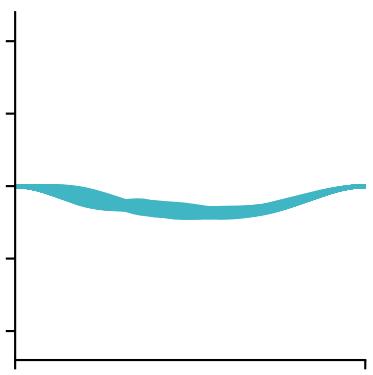
BRD



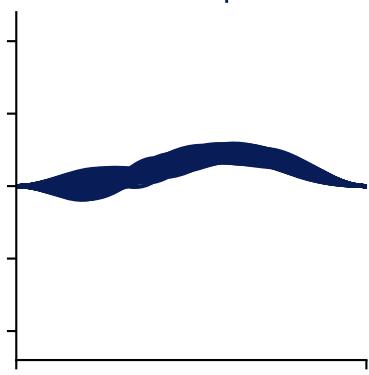
ECRB



TRI



DELTp



Normalized \hat{v}_m
Concentric \rightarrow Eccentric

1.0

0

-1.0

Start

Finish

Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

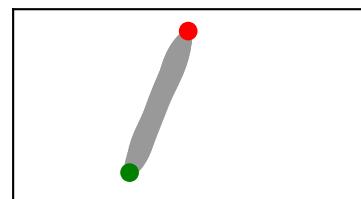
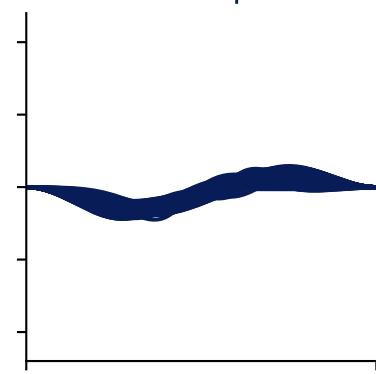
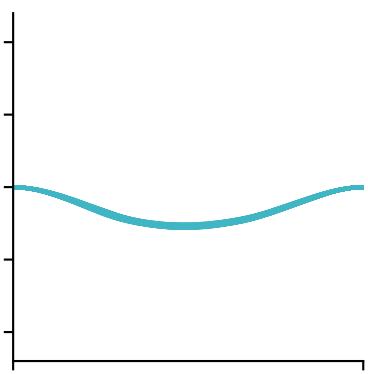
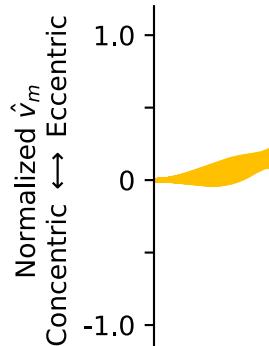
BIC

BRD

ECRB

TRI

DELTp



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Movement Duration : 1 sec

PC

DELTa

CB

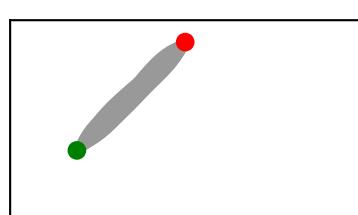
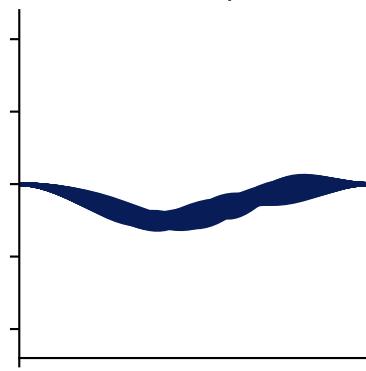
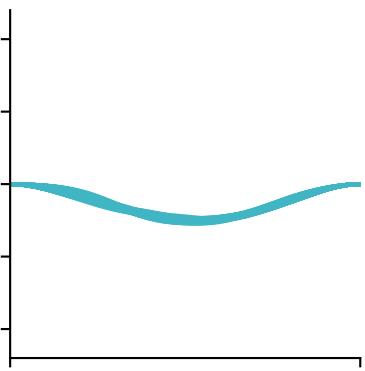
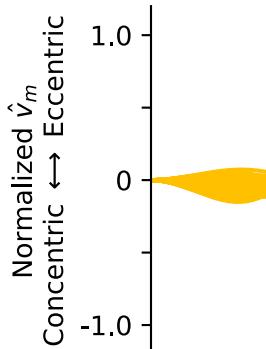
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Fixed Final Position
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DELTa

CB

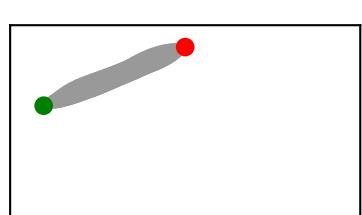
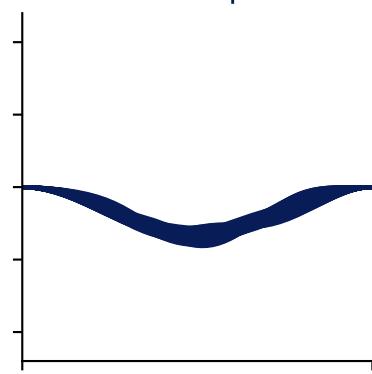
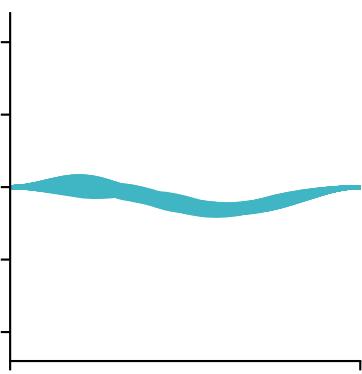
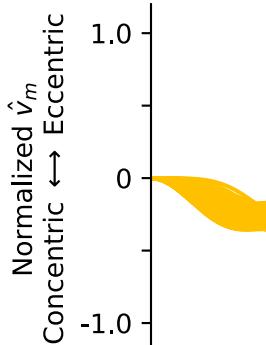
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DELTa

CB

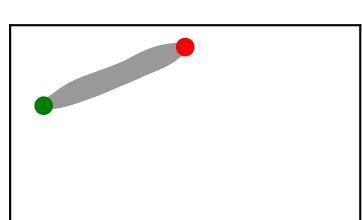
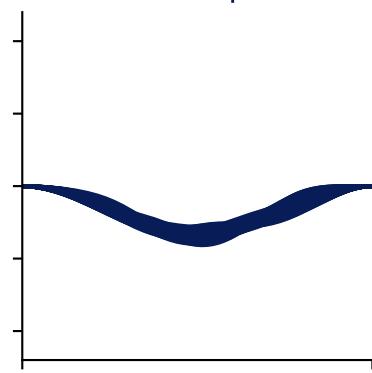
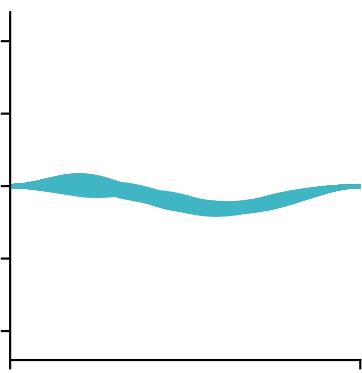
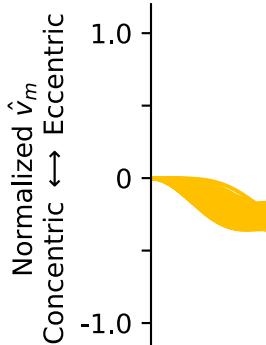
BIC

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DELTa

CB

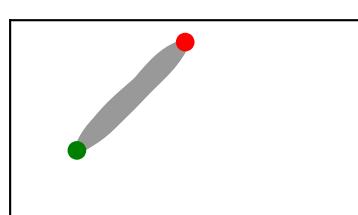
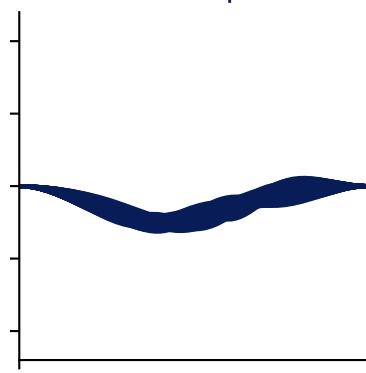
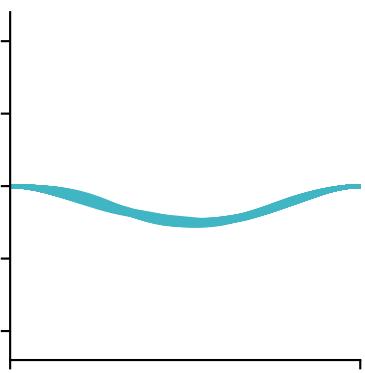
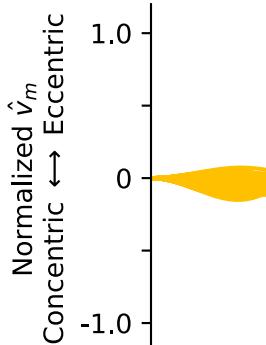
BIC

BRD

ECRB

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Movement Duration : 1 sec

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DELTa

CB

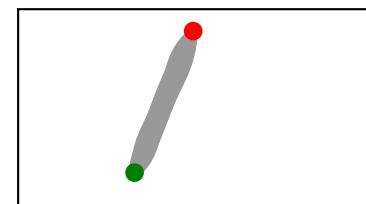
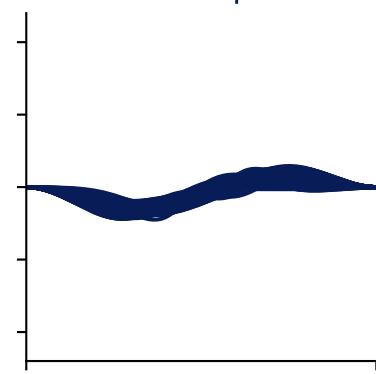
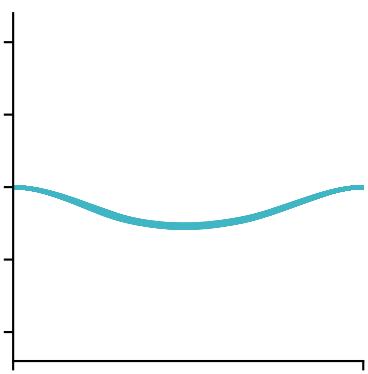
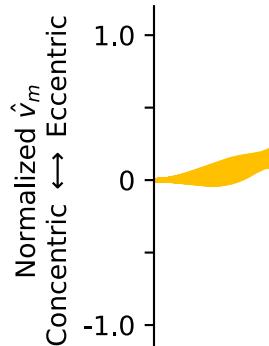
BIC

BRD

ECRB

TRI

DELTp



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

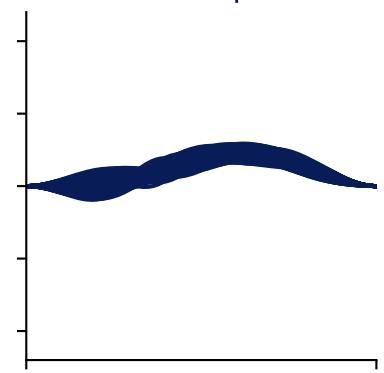
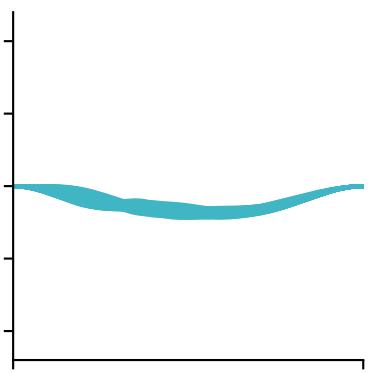
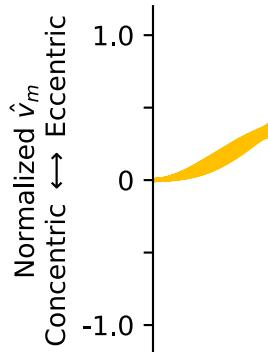
BIC

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TRI

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Fixed Final Position
Movement Duration : 1 sec

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DELTa

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BIC

BRD

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Normalized \hat{v}_m
Concentric \rightarrow Eccentric

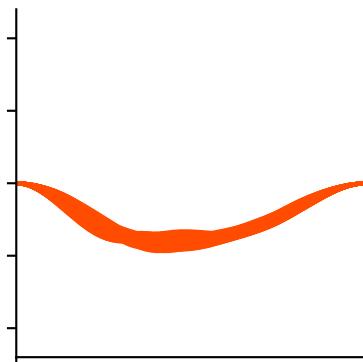
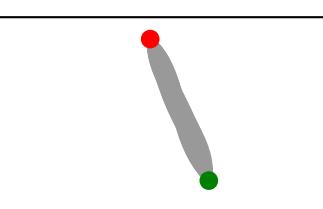
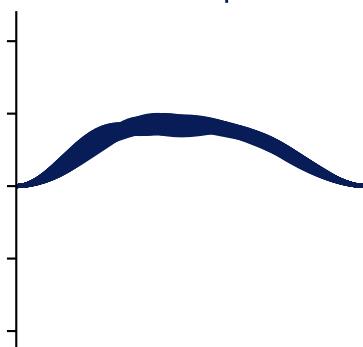
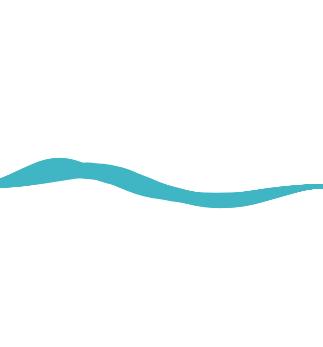
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0

-1.0

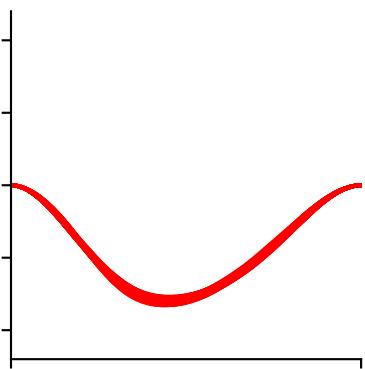
Start

Finish

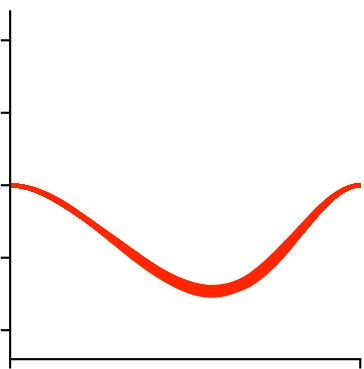


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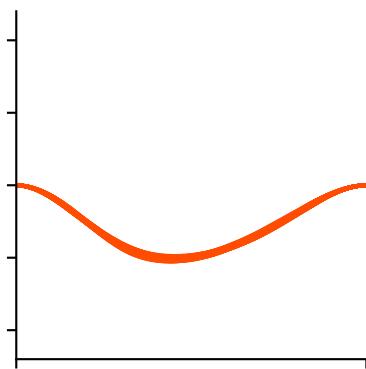
PC



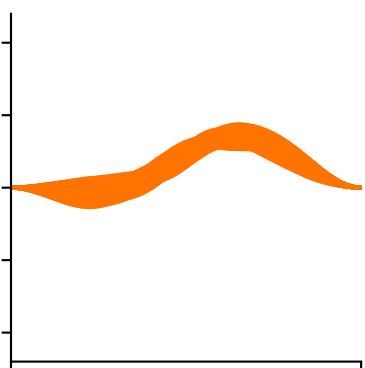
DELTa



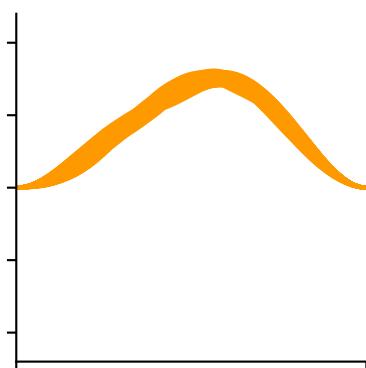
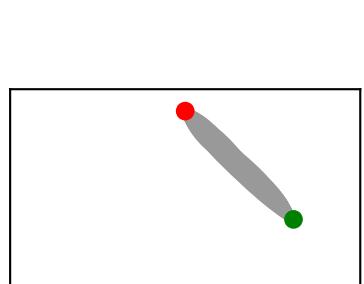
CB



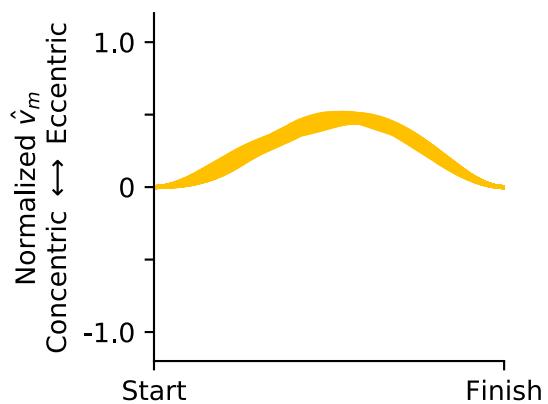
BIC



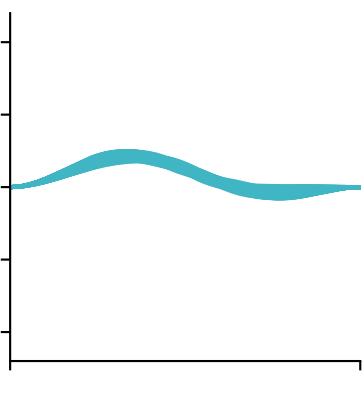
BRD



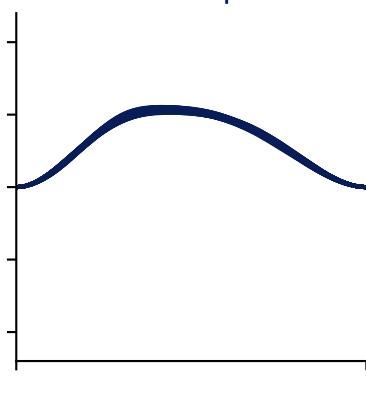
ECRB



TRI



DELTp



Fixed Final Position
Movement Duration : 1 sec

PC

DELTa

CB

BIC

BRD

ECRB

TRI

DELTp

Normalized \hat{v}_m
Concentric \rightarrow Eccentric

1.0

0

-1.0

Start

Finish