



Characterize the
physical properties of
any tendon-driven
system.

Good!softhiswork:

**Test whether linear models
work differently across
postures**







NO POSTURE DEPENDENCY
IN ROBOT

Goals of this work:

Characterize the
physical properties of
any tendon-driven
system. ✓

Test whether linear models
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NO POSTURE DEPENDENCY IN ROBOT



What's Next?

