Feasibility Theory

- Intuition   **All the ways that tendons create a force**
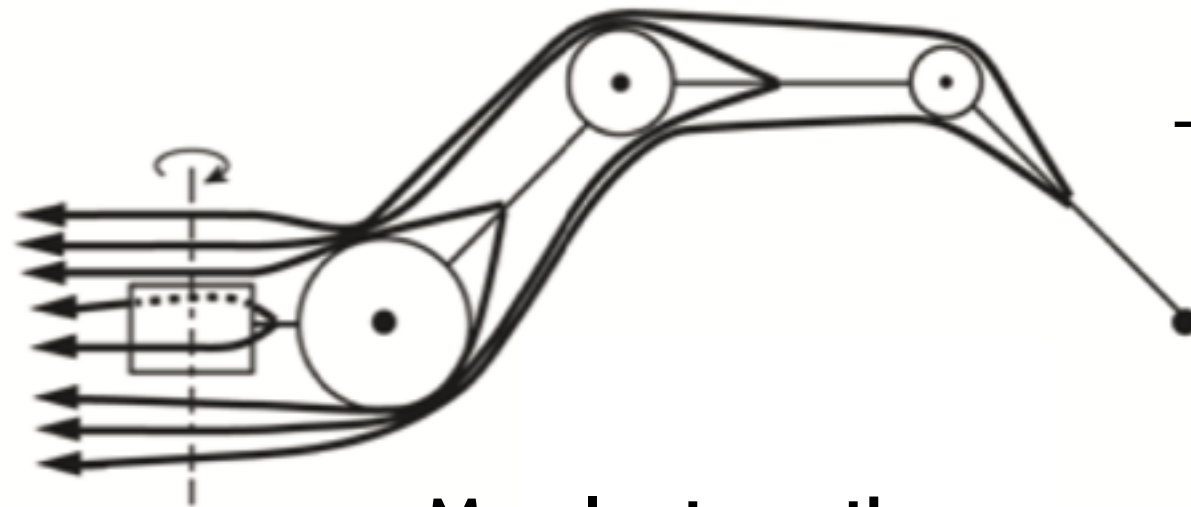
- Math   **Linear constraints to define the solution space**

- Simulation

- Experiment

Distal task force of 24N

Given:

w

**Muscle strengths
Moment arms
Joint rotations**

H Matrix

Relationships between muscles and output force directions