tendon driven limbs == robotic limbs

Prior work:

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description may be more critical than the solution

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Implicit assumptions:

relationship is

Muscle to force

immediate and linear


joints

one another at fixed

Bones are attached to

limited joint by joint

Rotation ranges are

Joints translate

throughout movement

be limited by skin and

Rotation ranges can

passive ligaments

Delayed & sluggish

Squishy Limbs