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Goals of this work:

work differently across

Test whether linear models

postures



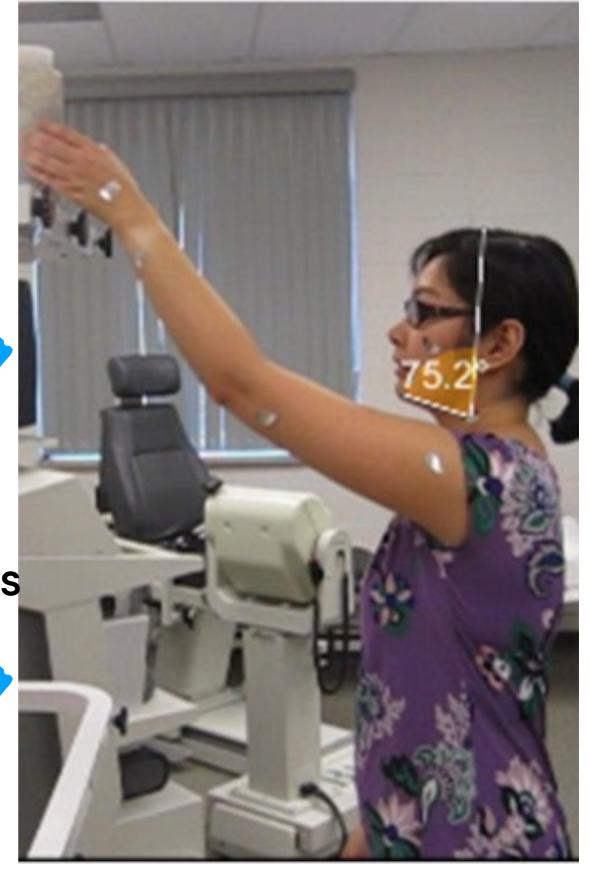


NO POSTURE DEPENDENCY IN ROBOT

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What's Next?

