4. Feasibility theory
(as a linear approximation)
is effective across the workspace

a — Finger endpoint position x (cm)

b — Variance Accounted For (FX), Count
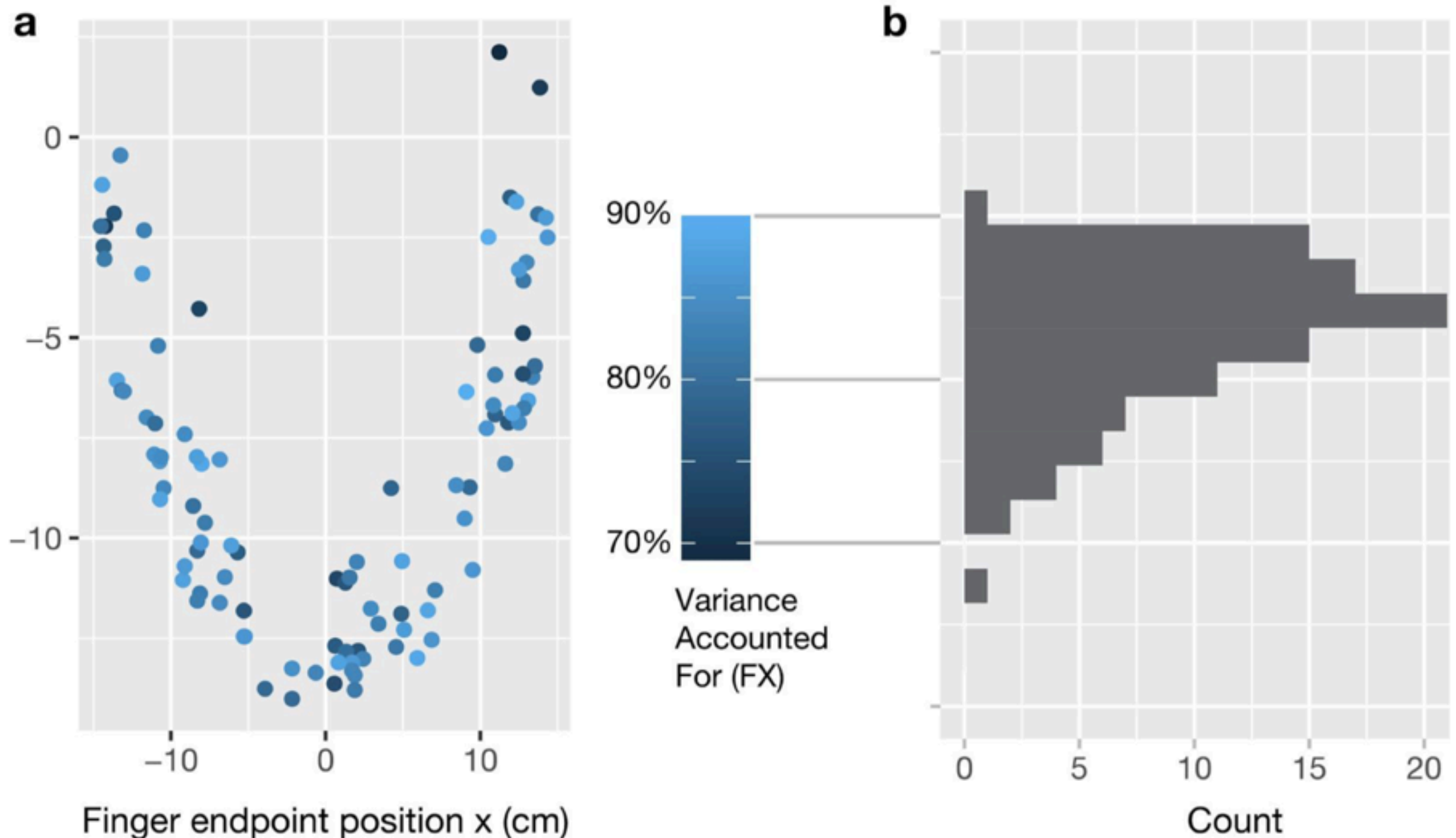
Goals of this work:

Characterize the
physical properties of
any tendon-driven
system.

Test whether linear models
work differently across
postures