

Overview

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- System for cataloging the properties of cadaveric and robotic limbs alike, with cadaver studies scheduled for Fall 2017.
- A 35GB dataset with 98 million tension-to-force observations on a robotic limb, with 1200 different endpoint postures in the workspace.
- Evidence that feasibility spaces approximate tendon-driven force control.
- Data to simulate afferent signals of muscle spindles and Golgi organs in future studies.



