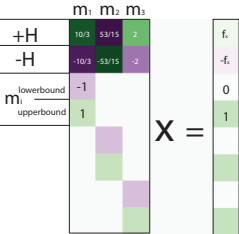


$$Ax = b$$



Unitless $a \rightarrow w$ mapping

By default, joint velocities were assumed zero output



velocity_output



redundant constraints removed

