

DESIGN AND CONTROL OF THE BLUEFOOT PLATFORM :
A MULTI-TERRAIN QUADRUPED ROBOT

THESIS

Submitted in Partial Fulfillment of
the Requirements for
the Degree of

MASTER OF SCIENCE (Electrical Engineering)

at the

NEW YORK UNIVERSITY
POLYTECHNIC SCHOOL OF ENGINEERING

by

Brian Cairl

May 2015

Approved:

Advisor

Date

Department Head Signature

Date

Copy No. # 3
University ID: N14463743