

DESIGN AND CONTROL OF THE BLUEFOOT PLATFORM :  
A MULTI-TERRAIN QUADRUPED ROBOT

THESIS

Submitted in Partial Fulfillment of  
the Requirements for  
the Degree of

MASTER OF SCIENCE (Electrical Engineering)

at the

NEW YORK UNIVERSITY  
POLYTECHNIC SCHOOL OF ENGINEERING

by

Brian Cairl

May 2015

Approved:

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Advisor

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Date

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Department Head Signature

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Date

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