

Learning in Games: Solution Concepts

Ben Chasnov

February 20, 2020

An optimization problem with multiple 'players.'

Single objective:

- ▶ Cost: $f : X \rightarrow \mathbb{R}$
- ▶ Variable: $x \in X$

Optimality:

$$f(x^*) \leq f(x), x \in X_{x^*} \text{ (local)}$$

$$\min_{x \in X} f(x)$$

Single objective

An optimization problem with multiple 'players.'

Single objective:

- ▶ Cost: $f : X \rightarrow \mathbb{R}$
- ▶ Variable: $x \in X$

Optimality:

$$f(x^*) \leq f(x), x \in X_{x^*} \text{ (local)}$$

$$\min_{x \in X} f(x)$$

Single objective

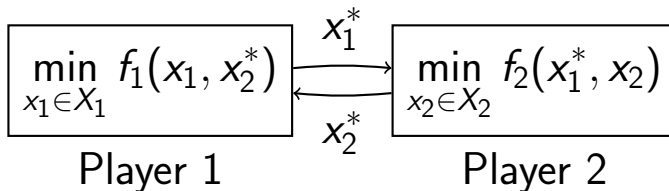
Game (two players):

- ▶ Game: $\mathcal{G} = (f_1, f_2)$.
- ▶ Costs: $f_i : X_1 \times X_2 \rightarrow \mathbb{R}, i \in [1, 2]$
- ▶ Variables: $(x_1, x_2) \in X_1 \times X_2$.

Optimality:

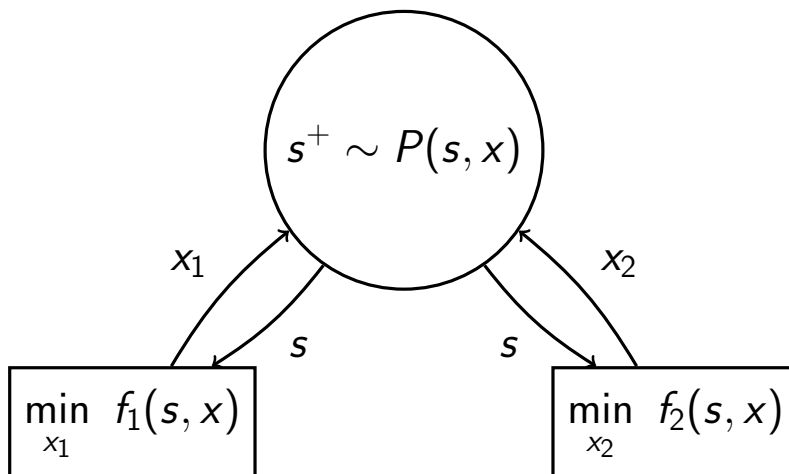
$$f_1(x_1^*, x_2^*) \leq f_1(x_1, x_2^*), x_1 \in X_1,$$

$$f_2(x_1^*, x_2^*) \leq f_2(x_1^*, x_2), x_2 \in X_2.$$



Learning in Dynamic Environments

Shared state s , individual costs and actions



where actions $x = (x_1, x_2)$ and shared state s that evolves via dynamics $\sim P$

- Dynamic Games
- Stochastic Games
- Multi-agent Reinforcement learning

Differential Notions of Equilibrium

Optimization (Unconstrained)

Twice-continuously differentiable
objective $c \in \mathcal{C}^2$.

Local optimality of u^* :

$$Dc(u^*) = 0, \quad D^2c(u^*) > 0.$$

Differential Notions of Equilibrium

Optimization (Unconstrained)

Twice-continuously differentiable
objective $c \in \mathcal{C}^2$.

Local optimality of u^* :

$$Dc(u^*) = 0, \quad D^2c(u^*) > 0.$$

Continuous Games

Local optimality of $u^* = (x_1^*, x_2^*)$:

First player's condition

$$D_1 f_1(x_1^*, x_2^*) = 0, \quad D_1^2 f_1(x_1^*, x_2^*) > 0$$

Second player's condition

$$D_2 f_2(x_1^*, x_2^*) = 0, \quad D_2^2 f_2(x_1^*, x_2^*) > 0$$

Differential Notions of Equilibrium

Optimization (Unconstrained)

Twice-continuously differentiable
objective $c \in \mathcal{C}^2$.

Local optimality of u^* :

$$Dc(u^*) = 0, \quad D^2c(u^*) > 0.$$

Continuous Games

Local optimality of $u^* = (x_1^*, x_2^*)$:

First player's condition

$$D_1 f_1(x_1^*, x_2^*) = 0, \quad D_1^2 f_1(x_1^*, x_2^*) > 0$$

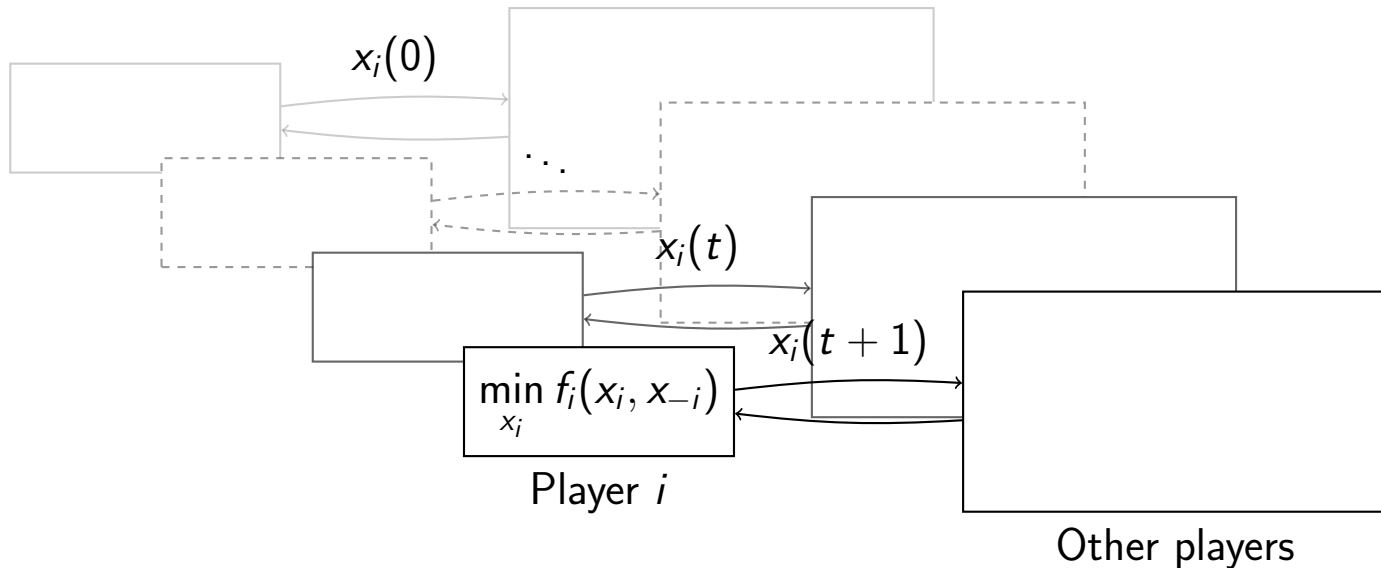
Second player's condition

$$D_2 f_2(x_1^*, x_2^*) = 0, \quad D_2^2 f_2(x_1^*, x_2^*) > 0$$

$$“D_i^2 f_i(x_i, x_{-i}) \equiv \frac{\partial}{\partial x_i^2} f_i(x) \big|_{x=(x_i, x_{-i})}”$$

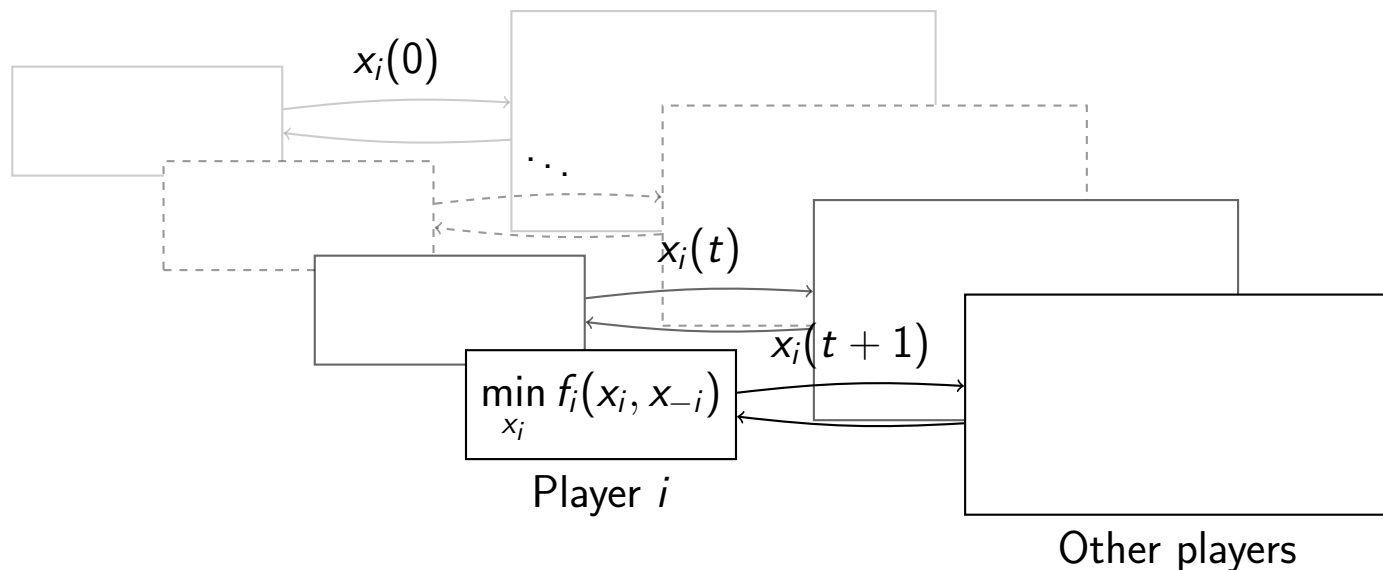
Algorithms for Learning in Games

Develop a learning rule to generate sequence $x_i(0), \dots, x_i(t)$ over time...



Algorithms for Learning in Games

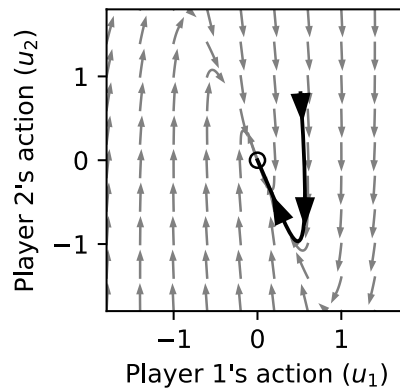
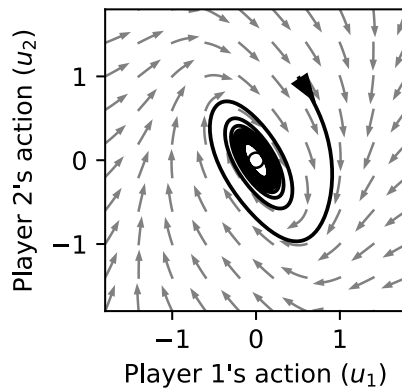
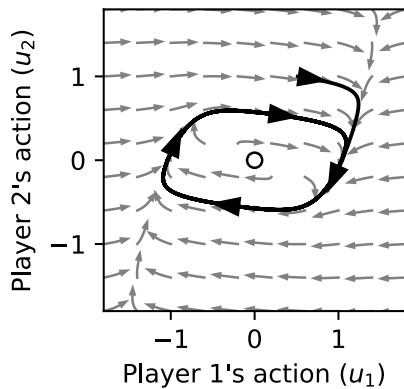
Develop a learning rule to generate sequence $x_i(0), \dots, x_i(t)$ over time...



- ▶ Asymptotic convergence: as $t \rightarrow \infty$, does $u(t) \rightarrow u^*$?
- ▶ Non-asymptotic bounds: for $t \geq T$, what is $\|u(t) - u^*\|$?
- ▶ Regret/no-regret learning: "best action *in hindsight*."

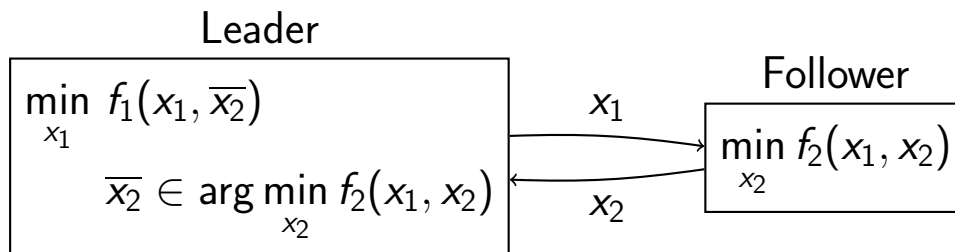
Non-uniform Learning Rates

- ▶ Vector field of $\omega \equiv (D_1 f_1, D_2 f_2)$ with costs
- ▶ $f_1(u) = \frac{1}{4}x_1^4 - \frac{1}{2}x_1^2 - x_1x_2$
- ▶ $f_2(u) = \frac{1}{2}x_2^2 + 2x_1x_2$



Extensions of the Nash equilibrium

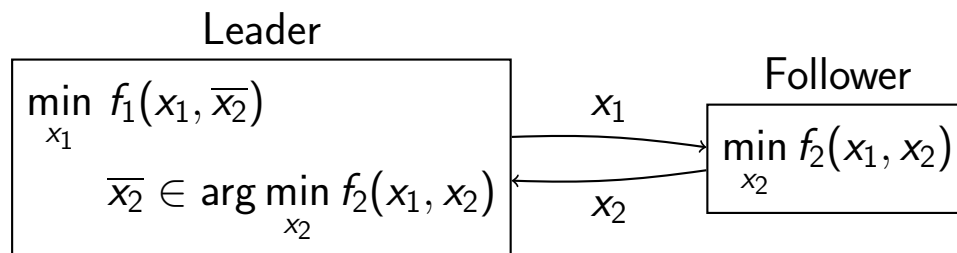
Hierarchy of play



Bilevel optimization, Stackelberg games, one-sided conjectural equilibrium.

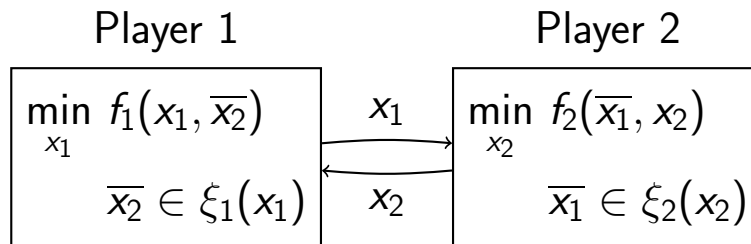
Extensions of the Nash equilibrium

Hierarchy of play



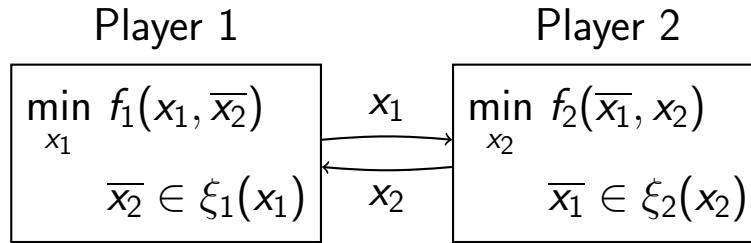
Bilevel optimization, Stackelberg games, one-sided conjectural equilibrium.

Using models of others

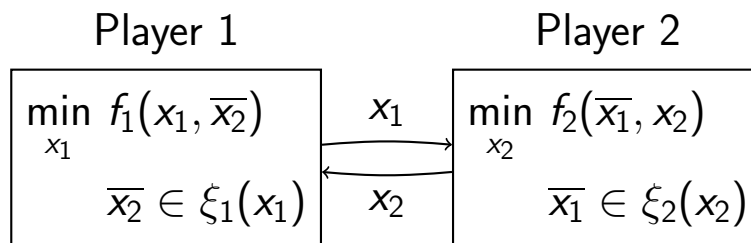


Conjectural variations equilibrium, opponent models

Conjectural Variations Equilibria



Conjectural Variations Equilibria



Differential Conjectural Variations Equilibrium

Local optimality of $u^* = (x_1^*, x_2^*)$:

First player's condition

$$Df_1(x_1^*, \xi_1(x_1^*)) = 0, \quad D^2 f_1(x_1^*, \xi_1(x_1^*)) > 0$$

Second player's condition

$$Df_2(\xi_2(x_2^*), x_2^*) = 0, \quad D^2 f_2(\xi_2(x_2^*), x_2^*) > 0$$

► Consistency: $x_2^* = \xi_1(x_1^*)$, $x_1^* = \xi_2(x_2^*)$

Conjectural learning dynamics

Ways we can construct learning dynamics to reflect this idea:

1. Descend the gradient of $Df_1(x, \xi_i(x))$ and $Df_2(\xi_2(y), y)$.

$$\begin{aligned}x_{k+1} &= x_k - \gamma(D_1 f_1(x_k, y) + D\xi_1(x_k)^\top D_2 f_1(x_k, y)) \\y_{k+1} &= y_k - \gamma(D_2 f_2(x, y_k) + D\xi_2(y_k)^\top D_1 f_2(x, y_k))\end{aligned}\tag{1}$$

where

$$D\xi_1(x) = -(D_2^2 f_2(x, y_k))^{-1} D_{21} f_2(x, y_k).$$

2. Approximate the conjecture via taylor expansion of $\xi(x) \simeq y_k$

$$\begin{aligned}x_{k+1} &= x_k - \gamma g(x_k, h(x_k)), \\y_k &= \arg \min_y f_2(x_k, y),\end{aligned}\tag{2}$$

where

$$h(x) = y_k + D\xi(x_k)(x - x_k) + (x - x_k)^\top D^2 \xi(x_k)(x - x_k) + \mathcal{O}(x^3).\tag{3}$$

Block structure of zero-sum games Approximate discrete update

$x_{k+1} = x_k - \gamma g(x)$ as $\dot{x} = -g(x)$. Linearization of g at x^* where $g(x^*) = 0$:

1. Simultaneous play games

$$Dg(x^*) = \begin{bmatrix} A & B \\ -B^\top & D \end{bmatrix}$$

2. Hierarchical (Stackelberg) game

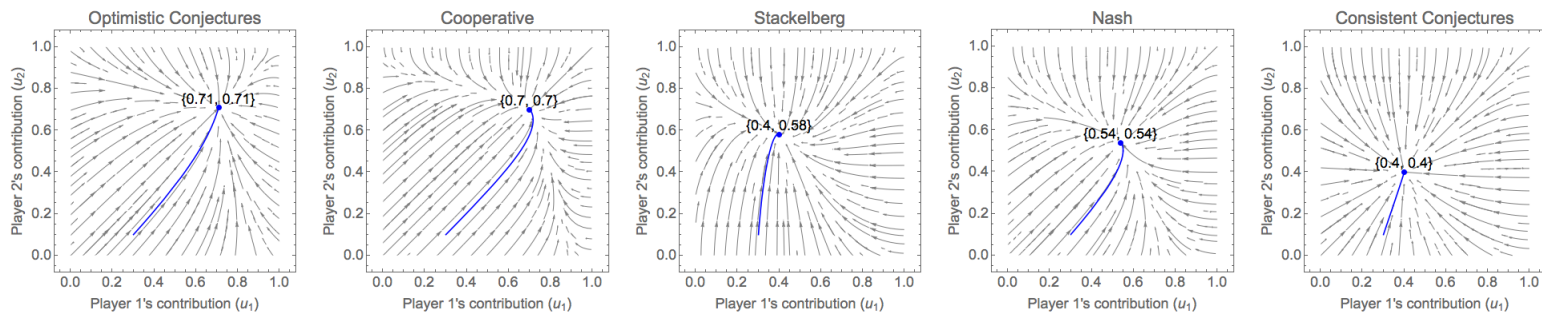
$$Dg(x^*) = \begin{bmatrix} A & 0 \\ -B^\top & D \end{bmatrix}$$

3. Conjectural (Stackelberg) game

$$Dg(x^*) = \begin{bmatrix} A & 0 \\ 0 & D \end{bmatrix}$$

Example: Individual Contribution to Public Goods

- ▶ Models the tragedy of the commons
- ▶ Utilities: $-f_i(x_i, x_{-i}) = (I_i - x_i)^{\alpha_i}(x_i + x_{-i})^{1-\alpha_i}$
- ▶ Study of hierarchy of play and effects of various agent “conjectures.”



Future Work in Learning in Games

...

- ▶ Characterize Conjectural Variations Equilibria: (stability, “performance metric”)
- ▶ Devise learning rules
- ▶ Verify agent conjecture models behaviorally
- ▶ Lots more!