Project 1 - Build a thread system for kernel processes

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Contents

1	Implementation of KTread.join()					
	1.1	Overview	2			
	1.2	Correctness Constraints	2			
	1.3	Declaration	2			
	1.4	Description	3			
	1.5	Test	3			
2	Implementation of Condition2					
	2.1	Overview	5			
	2.2	Correctness Constraints	6			
	2.3	Declaration	6			
	2.4	Description	6			
	2.5	Test	6			
3	Implementation of Alarm 13					
	3.1	Overview	11			
	3.2	Correctness Constraints	11			
	3.3	Declaration	11			
	3.4	Description	11			
	3.5	Test	12			
4	Implementation of Communicator 1					
	4.1	Overview	13			
	4.2	Correctness Constraints	13			
	4.3	Declaration	13			
	4.4	Description	13			
	15		13			

5	Imp	plementation of PriorityScheduler	17		
	5.1^{-}	Overview	17		
	5.2	Correctness Constraints	17		
	5.3	Declaration	17		
	5.4	Description	18		
	5.5	Test	18		
6	Solution to Boat Problem				
	6.1	Overview	26		
	6.2	Correctness Constraints	26		
	6.3	Declaration	26		
	6.4	Description	27		
	6.5	Test	27		

1 Implementation of KTread.join()

1.1 Overview

In this task, we need to implement KThread.join(), and the method should

- if this is finished return immediately
- be called only once
- store currentThread and wake it later
- assure that the thread finish executing normally

1.2 Correctness Constraints

- Corner cases: when this equals to currentThread or this is already finished, return immediately
- Need to be atomic by disable interruption and restore interruption at last
- When this thread finish, it should wake the stored thread

1.3 Declaration

- Add new state variable waitQueue which is a ThreadQueue(true) into KThread.
- Modification of join(): Firstly, disable interruption to make the operation atomic and restore it at last; secondly, prevent joining itself and prevent a finished thread from joining others, otherwise, let the current-Thread sleep to wait this method finish.
- Modification of finish(): Assure that once this method is finished, wake the thread join it to let the joining thread normally continue executing.

1.4 Description

Shown in pseudocode.

```
procedure JOIN()
   Disable Interruption
   if currentThread == this or this.status == statusFinished then
      Restore Interruption
      return
   else
      {\it add \ current} Thread \ into \ wait Queue
      currentThread sleep
   end if
   Restore Interruption
end procedure
procedure FINISH()
   currentThread.status = statusFinished
   Ready thread in waitQueue
   sleep()
end procedure
```

1.5 Test

Using selfTest() method in KThread, the main thought is making some join example, so we have those tests below.

```
private static void test1(){
       //Test Case 1
       System.out.println("\n*** Test Case 1 for join ***");
       ToJoin toJoin = new ToJoin();
       KThread toJoinThread = new
           KThread(toJoin).setName("ToJoin Thread");
       KThread toBeJoinedThread = new KThread(new
           ToBeJoined(toJoinThread)).setName("ToBeJoined
           Thread");
       toBeJoinedThread.fork();
       toJoinThread.fork();
       ThreadedKernel.alarm.waitUntil(100000);
}
private static void test2(){
       //Test Case 2
       System.out.println("\n*** Test Case 2 for join ***");
       ToJoin toJoin = new ToJoin();
       KThread toJoinThread = new
           KThread(toJoin).setName("ToJoin Thread");
```

```
KThread toBeJoinedThread = new KThread(new
           ToBeJoined(toJoinThread)).setName("ToBeJoined
           Thread");
       toJoinThread.fork();
       toBeJoinedThread.fork();
       ThreadedKernel.alarm.waitUntil(100000);
}
private static void test3(){
       //Test Case 3
       System.out.println("\n*** Test Case 3 for join ***");
       ToJoin toJoin = new ToJoin();
       KThread toJoinThread = new
           KThread(toJoin).setName("ToJoin Thread");
       KThread toBeJoined1 = new KThread(new
           ToBeJoined(toJoinThread)).setName("ToBeJoined1
           Thread");
       KThread toBeJoined2 = new KThread(new
           ToBeJoined(toJoinThread)).setName("ToBeJoined2
           Thread");
       toBeJoined1.fork();
       toBeJoined2.fork();
       toJoinThread.fork();
       ThreadedKernel.alarm.waitUntil(100000);
private static void test4(){
       //Test Case 4
       System.out.println("\n*** Test Case 4 for join ***");
       ToJoin toJoin1 = new ToJoin();
       ToJoin toJoin2 = new ToJoin();
       KThread t1 = new KThread(toJoin1).setName("ToJoin Thread
           1");
       KThread t2 = new KThread(toJoin2).setName("ToJoin Thread
           2");
       KThread toBeJoined = new KThread(new
           ToBeJoinedCouple(t1,t2)).setName("ToBeJoined Thread");
       toBeJoined.fork();
       t1.fork();
       t2.fork();
       ThreadedKernel.alarm.waitUntil(100000);
}
```

And the results of tests are as follows.

```
*** Test Case 1 for join ***

* ToBeJoined starts running

* ToJoin joins

* ToJoin starts running

* ToJoin ends running

* ToBeJoined continues running after ToJoin Thread finishes
```

```
*** Test Case 2 for join ***
* ToJoin starts running
* ToJoin ends running
* ToBeJoined starts running
* ToJoin joins
* ToBeJoined continues running after ToJoin Thread finishes
*** Test Case 3 for join ***
* ToBeJoined starts running
* ToJoin joins
* ToBeJoined starts running
* ToJoin joins
* ToJoin starts running
* ToJoin ends running
* ToBeJoined continues running after ToJoin Thread finishes
\boldsymbol{\ast} ToBeJoined continues running after ToJoin Thread finishes
*** Test Case 4 for join ***
* ToBeJoinedCouple starts running
* ToJoin Thread 1 joins
* ToJoin starts running
* ToJoin ends running
* ToJoin starts running
* ToJoin ends running
* ToJoin Thread 2 joins
* ToBeJoinedCouple continues running after two joining threads
```

- 1. For test1, we have the thread being joined run first, and have the other thread join the former run later;
- 2. For test2, just change the running order of the threads in the first test;
- 3. For test3, we have a thread join two different threads;
- 4. For test4, we have a thread be joined by two different threads;

And all the results shows that the joining thread finished before the threads being joined continue which is the expected results.

2 Implementation of Condition2

2.1 Overview

Implement Condition2 without using semaphore and Condition2 must be equivalent implementation as Condition.

2.2 Correctness Constraints

- sleep method:
 - Atomically release the associated lock and put the current thread to sleep until be waken
 - The associated lock must be held by current thread before the method and re-required after this method.
- wake method:
 - Atomically wake up a thread which called sleep
 - The associated lock must be held by current thread before the method.
- wakeAll method:
 - Atomically wake up all thread which called sleep on this condition
 - The associated lock must be held by current thread before the method.

2.3 Declaration

- Add new state variable waitQueue which is a ThreadQueue into Condition2.
- sleep method: place currentThread into ThreadQueue and release the lock, then sleep the currentThread and then re-acquire the lock when it return from sleep
- wake method: remove the thread from the waitQueue and put it on the ready Queue
- wakeAll method: remove all threads from the waitQueue and put them on the ready Queue

2.4 Description

2.5 Test

Using selfTest() in Condition2,

In this session, the test is using Condition and Condition2 to do the same job, and compare their results, and then we finish the test. Here are the codes.

```
private static class Int {
    int value;
    Int(int _value){
        value = _value;
    }
    public void inc(){
        value++;
    }
```

```
procedure SLEEP()
   {\bf Lib.assert True\ condition Lock.is Held By Current Thread}
   Disable Interruption
   Add currentThread into waitQueue
   Release the conditionLock
   currentThread sleep
   Acquire the conditionLock
   Restore Interruption
end procedure
procedure WAKE()
   {\bf Lib.assert True\ condition Lock.is Held By Current Thread}
   Disable Interruption
   if waitQueue is not empty then
       Remove and wake the first thread in waitQueue
   end if
   Restore Interruption
end procedure
procedure WAKEALL()
   Lib. assert True\ condition Lock. is Held By Current Thread
   Disable Interruption
   \mathbf{while} \ \mathrm{waitQueue} \ \mathrm{is} \ \mathrm{not} \ \mathrm{empty} \ \mathbf{do}
       Remove and wake the first thread in waitQueue
   end while
   Restore Interruption
end procedure
```

```
public void dec(){
              value--;
       public int val(){
              return value;
       }
}
private static class Producer implements Runnable {
       private Int goods;
       private Condition2 condition;
       private Lock lock;
       private int index;
       Producer(int _index, Int _goods, Condition2 _condition,
           Lock _lock){
              index = _index;
              goods = _goods;
              condition = _condition;
              lock = _lock;
       }
       public void run() {
              lock.acquire();
              System.out.println("Producer " + index + " starts
                   running");
              goods.inc();
              System.out.println("Producer " + index + "
                  produces 1 item (" + goods.val() + " items)");
              condition.wakeAll();
              System.out.println("Producer " + index + " ends
                  running");
              lock.release();
       }
private static class Consumer implements Runnable {
       private Int goods;
       private Condition2 condition;
       private Lock lock;
       private int index;
       Consumer(int _index, Int _goods, Condition2 _condition,
           Lock _lock) {
              index = _index;
              goods = _goods;
              condition = _condition;
              lock = _lock;
       }
       public void run() {
              lock.acquire();
```

```
System.out.println("Consumer " + index + " starts
                          running");
                      while(goods.val() < 1){</pre>
                             System.out.println("Consumer " + index + "
                                 sleeps " + "(" + goods.val() + "
                                 items)");
                             condition.sleep();
                      goods.dec();
                      System.out.println("Consumer " + index + "
                          consumes " + "" + 1 + " item (" + goods.val()
                          + " items)");
                      System.out.println("Consumer " + index + " ends
                          running");
                      lock.release();
              }
       }
public static void selfTest(){
       Int goods = new Int(0);
       Lock lock = new Lock();
       Condition2 condition = new Condition2(lock);
       KThread consumer1 = new KThread(new Consumer(1, goods,
           condition, lock));
       KThread consumer2 = new KThread(new Consumer(2, goods,
           condition, lock));
       KThread producer1 = new KThread(new Producer(1, goods,
           condition, lock));
       KThread producer2 = new KThread(new Producer(2, goods,
           condition, lock));
       KThread producer3 = new KThread(new Producer(3, goods,
           condition, lock));
       KThread consumer3 = new KThread(new Consumer(3, goods,
           condition, lock));
       consumer1.fork();
       consumer2.fork();
       producer1.fork();
       producer2.fork();
       producer3.fork();
       consumer3.fork();
       ThreadedKernel.alarm.waitUntil(100000);
}
```

And for Condition, we just change the test code above. And here are the results.

```
using condition2:
Consumer 1 starts running
Consumer 1 sleeps (0 items)
Consumer 2 starts running
```

```
Consumer 2 sleeps (0 items)
Producer 1 starts running
Producer 1 produces 1 item (1 items)
Producer 1 ends running
Producer 2 starts running
Producer 2 produces 1 item (2 items)
Producer 2 ends running
Producer 3 starts running
Producer 3 produces 1 item (3 items)
Producer 3 ends running
Consumer 3 starts running
Consumer 3 consumes 1 item (2 items)
Consumer 3 ends running
Consumer 1 consumes 1 item (1 items)
Consumer 1 ends running
Consumer 2 consumes 1 item (0 items)
Consumer 2 ends running
using condition:
Consumer 1 starts running
Consumer 1 sleeps (0 items)
Consumer 2 starts running
Consumer 2 sleeps (0 items)
Producer 1 starts running
Producer 1 produces 1 item (1 items)
Producer 1 ends running
Producer 2 starts running
Producer 2 produces 1 item (2 items)
Producer 2 ends running
Producer 3 starts running
Producer 3 produces 1 item (3 items)
Producer 3 ends running
Consumer 3 starts running
Consumer 3 consumes 1 item (2 items)
Consumer 3 ends running
Consumer 1 consumes 1 item (1 items)
Consumer 1 ends running
Consumer 2 consumes 1 item (0 items)
Consumer 2 ends running
```

In this test result, Consumer waits for Producer rightly when there is no good and Consumer, Producer consumes and produces good rightly. And Condition2 works the same as Condition.

3 Implementation of Alarm

3.1 Overview

Implementation of Alarm class, such that after the thread called waitUtill(x) at time t then timerInterrupt wake the thread after time x+t.

3.2 Correctness Constraints

- waitUtill method: Move the calling thread into waitQueue and block the thread.
- timerInterrupt method: The thread should be woken when the interval on the call is over.

3.3 Declaration

- Create a new class WaitThread which contains a thread and its wake time. Add a new instance variable waitQueue of WaitThread which is a PriorityQueue with wake time as priority.
- waitUtill method: Calculate the wake time by adding x to current time and the WaitThread of the thread should be store in waitQueue which is a priority queue(hence is efficient).
- timerInterrupt method: use a while loop to wake threads whose wake time is less than current time.

3.4 Description

```
procedure WAITUNTIL(x)
Disable Interruption
Calculate the wake time(x + currentTime) and create a waitThread
Put waitThread into waitQueue
sleep this thread
Restore Interruption
end procedure
procedure TIMERINTERRUPT()
Disable Interruption
while waitQueue is not empty AND wake time of first thread in waitQueue
< currentTime do
wake first thread in waitQueue
end while
Restore Interruption
end procedure
```

3.5 Test

Call waitUtill by several threads and print the calling time and the wake time. Find out whether the threads are waken after wake time.

So the codes are as follows.

And the result is as follows.

```
Thread starts at 120
Thread calls waitUtill with delay 100
Thread starts at 130
Thread calls waitUtill with delay 200
Thread starts at 140
Thread calls waitUtill with delay 300
Thread starts at 150
Thread calls waitUtill with delay 400
Thread starts at 160
Thread calls waitUtill with delay 500
Thread starts at 170
Thread calls waitUtill with delay 600
Thread starts at 180
Thread calls waitUtill with delay 700
Thread starts at 190
Thread calls waitUtill with delay 800
Thread starts at 200
Thread calls waitUtill with delay 900
Thread starts at 210
Thread calls waitUtill with delay 1000
Thread recovers at 500 (500>=120+100)
Thread recovers at 510 (510>=130+200)
Thread recovers at 520 (520 >= 140 + 300)
Thread recovers at 1030 (1030>=150+400)
Thread recovers at 1040 (1040>=160+500)
Thread recovers at 1050 (1050>=170+600)
Thread recovers at 1060 (1060>=180+700)
Thread recovers at 1070 (1070>=190+800)
Thread recovers at 1540 (1540>=200+900)
Thread recovers at 1550 (1550>=210+1000)
```

And the test accurately meet the needs, since all threads continues after the delay time.

4 Implementation of Communicator

4.1 Overview

Implementat Communicator class. Two methods speak and listener to implement. The message is passed from exactly one speaker to exactly one listener.

4.2 Correctness Constraints

- Listeners wait when there is no speaker
- Speakers wait when there is no listener

4.3 Declaration

- Add a state variable lock which is a Lock into Communicator. Add four counters AS, WS, AL, WL initially as 0. Add three conditions for speaker, listener and return with the same lock. Add a state variable word to store words from speakers.
- Note that the first speaker or listener is what we call active speaker or listener and is exchanging message and sleep on condition utill other one wakes it up and both return.
- A speaker speaks to only one listener and a listener listens to only one speaker, so the waiting speaker(listener) will be blocked by active speaker(listener).

4.4 Description

4.5 Test

Test a senquence of speakers and listeners in different orders and check the output.

And the test code as follows.

```
procedure COMMUNICATOR()
   initialize lock
   initialize AS WS AL WL to 0
   initialize conditions with same lock
end procedure
procedure SPEAK(word)
   Acquire the lock
   while AS != 0 do
      WS++
      // sleep on condition speaker
      sleep
      WS--
   end while
   AS++
   set word
   if AL != 0 then
      Wake active listener
   else
      if WL != 0 then
         wake one listener
      // in case that the later speaker runs too fast and cover the word
      // sleep on condition return
      sleep till the wait listener to return
      AS-
      AL-
      if WS != 0 then
         wake the wait speaker
      end if
   end if
   Release the lock
   return
end procedure
```

```
procedure LISTENER()
   Acquire the lock
   while AL != 0 do
      WL++
      // sleep on condition listener
      sleep
      WL--
   end while
   AL++
   if AS != 0 then
      Wake active speaker
   else
      if WS != 0 then
         wake one speaker
      end if
      // in case that the later listener runs too fast and retreive the word
      // sleep on condition return
      sleep till the wait speaker to return
      AL-
      AS-
      if WL != 0 then
         wake the wait listener
      end if
   end if
   retreive word
   Release the lock
   return
end procedure
```

And the results is as follows.

```
case 1
Listener 1 starts listening
Listener 2 starts listening
Speaker 1 starts speaking
Speaker 1 speaks 1
Speaker 1 ends speaking
Speaker 2 starts speaking
Speaker 3 starts speaking
Listener 3 starts listening
Listener 1 hears 1 from speaker 1
Listener 1 ends listening
Speaker 2 speaks 2
Speaker 2 ends speaking
Listener 2 hears 2 from speaker 2
Listener 2 ends listening
Speaker 3 speaks 3
Speaker 3 ends speaking
Listener 3 hears 3 from speaker 3
Listener 3 ends listening
case 2
Listener 1 starts listening
Listener 2 starts listening
Listener 3 starts listening
Listener 4 starts listening
Listener 5 starts listening
Speaker 5 starts speaking
Speaker 5 speaks 5
Speaker 5 ends speaking
Speaker 4 starts speaking
Speaker 3 starts speaking
Speaker 2 starts speaking
Speaker 1 starts speaking
Listener 1 hears 5 from speaker 5
Listener 1 ends listening
Speaker 4 speaks 4
Speaker 4 ends speaking
Listener 2 hears 4 from speaker 4
Listener 2 ends listening
Listener 3 hears 3 from speaker 3
Listener 3 ends listening
```

```
Speaker 3 speaks 3
Speaker 3 ends speaking
Speaker 2 speaks 2
Speaker 2 ends speaking
Listener 4 hears 2 from speaker 2
Listener 4 ends listening
Speaker 1 speaks 1
Speaker 1 ends speaking
Listener 5 hears 1 from speaker 1
Listener 5 ends listening
```

And According the results, each Listener listens to exactly one Speaker and each Speaker speaks to exactly one Listener which meets the requirements.

5 Implementation of PriorityScheduler

5.1 Overview

Implement PriorityScheduler class so that the scheduler can properly schedule the threads by its priority and by priority donation we can avoid priority inversion.

5.2 Correctness Constraints

- Waiting thread donates its priority to the thread which is holding the resource to avoid priority inversion.
- Scheduler always retreive the thread with highest priority from the waiting Queue.

5.3 Declaration

• Here we only consider the case transferPriority is true, since when it's false, we only have to sort the threads by their o riginal priority and don't need to calculate EP.

• In PriorityQueue:

Add waitingList: a priority-queue(realized by maximal heap or red-black tree) by EP of ThreadState waiting for this resource. Add a maxEP denotes maximal EP in the waitingQueue. Add a boolean changed denotes whether maxEP should be updated. Add a ThreadState master which is occupying the resource.

• In ThreadState:

Add a list by EP of PriorityQueue occupiedResources collects the resources which is now occupied by this thread. Add a list by EP of PriorityQueue acquiredResources collects the resources which is being

acquired(but no yet) by this thread. Add a boolean changed denotes whether EP should be updated. Add a EP denotes EP of this thread.

• The EP should be recursively updated when a new waiting thread enter or when a thread quit holding resources. And updated by rules: Waiting thread donates its priority to the thread which is holding the resource to avoid priority inversion.

5.4 Description

5.5 Test

- 1. Set up serveral threads with random priorities associated with one condition. And test whether they execute in decreasing order.
- 2. Set up serveral threads with random priorities associated with mutiple conditions. And test whether they execute in decreasing order. And Test by printing that whether the waiting thread properly donate its priority and whether the quit-holding thread recover its priority.

The following are test codes.

```
private static void test1() {
              System.out.println("PriorityScheduler.test1() begins.");
              KThread thread0 = new KThread(new PSTest(0));
              KThread thread1 = new KThread(new PSTest(1));
              thread0.fork();
              thread1.fork();
              thread0.join();
              thread1.join();
              System.out.println("PriorityScheduler.test1() ends.");
       }
       private static void test2() {
              System.out.println("PriorityScheduler.test2() begins.");
              KThread thread0 = new KThread(new PSTest(0));
              KThread thread1 = new KThread(new PSTest(1));
              boolean intStatus = Machine.interrupt().disable();
              ThreadedKernel.scheduler.setPriority(thread0, 2);
              Machine.interrupt().restore(intStatus);
              thread0.fork();
              thread1.fork();
              thread0.join();
```

Algorithm 1 PriorityQueue procedure GETMAXEP() if !transferPriority then return minimum priority end if if changed then $maxEP \leftarrow minimum \ priority$ for each ThreadState ts in waitingQueue do $temp \leftarrow MAX(maxEP, ts.getEP())$ end for changed \leftarrow false end if return maxEP end procedure procedure WAITFORACCESS(KThread thread) Lib.assertTrue(Machine.interrupt.disable())) Add (ts \leftarrow getThreadState(thread)) into waitingQueue ts.waitForAccess(this) end procedure procedure ACQUIRE(KThread thread) Lib.assertTrue(Machine.interrupt.disable())) $\mathbf{if} \text{ master } != \mathbf{null} \mathbf{then}$ Remove this from master.occupiedResource end if ${\tt getThreadState(thread).acquire(this)}$ end procedure procedure NEXTTHREAD() Lib.assertTrue(Machine.interrupt.disable())) if master != null then Remove this from master.occupiedResource end if

 $thread \leftarrow null$

return thread end procedure

end if

if waitingQueue is not empty then thread ← pickNextThread() Remove thread from waitingQueue

thread.acquire(this)

```
procedure PICKNEXTTHREAD()

if waitingQueue is not empty then

threadState ← first element of waitingQueue

for each ThreadState ts in waitingQueue do

if ts has higher priority than threadState then

threadState ← ts

end if

end for

else

thread ← null

end if

return thread

end procedure
```

Algorithm 2 ThreadState

```
// once new thread enter, all the EP should change
procedure CHANGE()
   if !changed then
       changed \leftarrow true
       EP \leftarrow getEP()
       for each PriorityQueue pq in acquiredResource do
           if pq.master!= null && transferPriority then
              pq.changed \leftarrow true
              pq.master.change()
           end if
       end for
   end if
end procedure
procedure GETEP()
   if changed then
       \mathrm{EP} \leftarrow \mathrm{priority}
       {\bf for}each Priority
Queue pq in occupied
Queue<br/> {\bf do}
           EP \leftarrow MAX(EP, pq.getMaxEP)
       end for
   end if
   return EP
end procedure
```

```
procedure SETPRIORITY(int Priority)
   if priority != Priority then
       priority \leftarrow Priority
       change()
   end if
end procedure
procedure WAITFORACCESS(PriorityQueue waitQueue)
   Add waitQueue into acquiredResource
   if waitQueue is in occupiedResource then
       Remove\ wait Queue\ from\ occupied Resource
       waitQueue.master \leftarrow null
   end if
   \mathbf{if} \ \mathrm{waitQueue.master} \ != \mathrm{null} \ \mathbf{then}
       // new thread wait hence EP should change
       if transferPriority then
          waitQueue.changed \leftarrow true
          waitQueue.master.change()
       end if
   end if
end procedure
procedure ACQUIRE(PriorityQueue waitQueue)
   Add waitQueue into occupiedResource
   if waitQueue is in acquiredResource then
       Remove\ waitQueue\ from\ acquired Resource
       waitQueue.master \leftarrow this
   end if
   change()
end procedure
```

```
thread1.join();
       System.out.println("PriorityScheduler.test2() ends.");
}
private static void test3() {
       System.out.println("PriorityScheduler.test3() begins.");
       KThread thread0 = new KThread(new PSTest(0));
       KThread thread1 = new KThread(new PSTest(1));
       thread0.setName("thread0");
       thread1.setName("thread1");
       boolean intStatus = Machine.interrupt().disable();
       ThreadedKernel.scheduler.setPriority(thread0, 2);
       Machine.interrupt().restore(intStatus);
       thread0.fork();
       thread1.fork();
        * The main thread which has increased its priority is
            waiting for
        * thread1.
        */
       ThreadedKernel.scheduler.increasePriority();
       thread1.join();
       thread0.join();
       ThreadedKernel.scheduler.decreasePriority();
       System.out.println("PriorityScheduler.test3() ends.");
}
private static void test4() {
       System.out.println("PriorityScheduler.test4() begins.");
       KThread thread0 = new KThread(new PSTest(0));
       KThread thread1 = new KThread(new PSTest(1));
       thread0.setName("thread0");
       thread1.setName("thread1");
       boolean intStatus = Machine.interrupt().disable();
       ThreadedKernel.scheduler.setPriority(thread0, 2);
       Machine.interrupt().restore(intStatus);
```

```
thread0.fork();
       thread1.fork();
        * The main thread which has increased its priority is
            waiting for
        * thread1.
        */
       ThreadedKernel.scheduler.increasePriority();
       ThreadedKernel.scheduler.increasePriority();
       thread1.join();
       thread0.join();
       ThreadedKernel.scheduler.decreasePriority();
       ThreadedKernel.scheduler.decreasePriority();
       System.out.println("PriorityScheduler.test4() ends.");
}
private static void test5() {
       System.out.println("PriorityScheduler.test5() begins.");
       KThread thread0 = new KThread(new PSTest(0));
       KThread thread1 = new KThread(new PSTest(1));
       KThread thread2 = new KThread(new PSTest(2));
       thread0.setName("thread0");
       thread1.setName("thread1");
       thread2.setName("thread2");
       /* Disable interrupt for convenience. */
       boolean intStatus = Machine.interrupt().disable();
       ThreadedKernel.scheduler.setPriority(thread0, 2);
       ThreadedKernel.scheduler.setPriority(thread1, 2);
       ThreadedKernel.scheduler.setPriority(thread2, 1);
       thread0.fork();
       thread1.fork();
       thread2.fork();
       /* Priority of thread1 is changed later than thread2, but
           that thread is enqueued earlier. */
       ThreadedKernel.scheduler.setPriority(thread1, 1);
       /* Wait until all the threads ends. */
       thread0.join();
       thread1.join();
       thread2.join();
       Machine.interrupt().restore(intStatus);
```

```
System.out.println("PriorityScheduler.test5() ends.");
}
public static void selfTest() {
       test1();
       test2();
       test3();
       test4();
       test5();
}
private static class PSTest implements Runnable {
       private int index;
       PSTest(int _index) {
               index = _index;
       }
       public void run() {
               int i;
              boolean intStatus = Machine.interrupt().disable();
              System.out.println("EffectivePriority of thread" +
                   index + " is "
                                  ThreadedKernel.scheduler.getEffectivePriority());
              Machine.interrupt().restore(intStatus);
              for (i = 0; i < 5; i++) {</pre>
                      System.out.println("PSTest " + index + "
                          loop " + i);
                      KThread.yield();
              }
       }
}
```

The results go as follows:

```
PriorityScheduler.test1() begins.
EffectivePriority of thread0 is 1
PSTest 0 loop 0
EffectivePriority of thread1 is 1
PSTest 1 loop 0
PSTest 0 loop 1
PSTest 1 loop 1
PSTest 1 loop 2
PSTest 1 loop 2
PSTest 0 loop 3
PSTest 1 loop 3
PSTest 1 loop 4
PSTest 1 loop 4
```

```
PriorityScheduler.test1() ends.
PriorityScheduler.test2() begins.
EffectivePriority of thread0 is 2
PSTest 0 loop 0
PSTest 0 loop 1
PSTest 0 loop 2
PSTest 0 loop 3
PSTest 0 loop 4
EffectivePriority of thread1 is 1
PSTest 1 loop 0
PSTest 1 loop 1
PSTest 1 loop 2
PSTest 1 loop 3
PSTest 1 loop 4
PriorityScheduler.test2() ends.
PriorityScheduler.test3() begins.
EffectivePriority of thread1 is 2
PSTest 1 loop 0
EffectivePriority of thread0 is 2
PSTest 0 loop 0
PSTest 1 loop 1
PSTest 0 loop 1
PSTest 1 loop 2
PSTest 0 loop 2
PSTest 1 loop 3
PSTest 0 loop 3
PSTest 1 loop 4
PSTest 0 loop 4
PriorityScheduler.test3() ends.
PriorityScheduler.test4() begins.
EffectivePriority of thread1 is 3
PSTest 1 loop 0
PSTest 1 loop 1
PSTest 1 loop 2
PSTest 1 loop 3
PSTest 1 loop 4
EffectivePriority of thread0 is 3
PSTest 0 loop 0
PSTest 0 loop 1
PSTest 0 loop 2
PSTest 0 loop 3
PSTest 0 loop 4
PriorityScheduler.test4() ends.
PriorityScheduler.test5() begins.
EffectivePriority of thread0 is 2
PSTest 0 loop 0
PSTest 0 loop 1
PSTest 0 loop 2
PSTest 0 loop 3
PSTest 0 loop 4
```

```
EffectivePriority of thread1 is 1
EffectivePriority of thread2 is 1
PSTest 2 loop 0
PSTest 1 loop 0
PSTest 2 loop 1
PSTest 2 loop 1
PSTest 2 loop 2
PSTest 1 loop 2
PSTest 1 loop 2
PSTest 2 loop 3
PSTest 1 loop 3
PSTest 2 loop 4
PSTest 1 loop 4
PriorityScheduler.test5() ends.
```

6 Solution to Boat Problem

6.1 Overview

Implement Boat class to solve the boat problem.

6.2 Correctness Constraints

- The boat can only hold one or two children or one adult.
- Each time the location of the boat changes, the number of passengers in boat cannot be zero.
- begin method finished with both of children and adults is on Molokai.

6.3 Declaration

- In Boat class, add locationOfBoat, numOfChildOahu, numOfAdultOahu, numOfChildMolokai, numOfAdultMolokai, numOfChildBoat, boatLock, waitOnOahuCondition, waitBoardingCondition, waitOnMolokaiCondition, and message a Communicator.
- In begin, what we need to do is for each children and adults create a thread, and we also use message to see whether we have move all people to Molokai.
- In AdultItinerary, the adult can move to Molokai when the boat is at Oahu and empty with child on Molokai can't be zero. Then we move this adult to Molokai and wake waiting on Molokai.
- In ChildItinerary, add location to show the location of this child. For child move to Molokai, the condition is boat is at Oahu and empty or with one child, and also the child can't be himself. If the child is the first in

the boat, then it wait for another to board. If the location of the boat is on Molokai, then it must have one child back to Oahu.

6.4 Description

```
procedure BEGIN(int adults, int children, BoatGrader b)
   bg \leftarrow b
   for each childs, create a thread of ChildItinerary
   for each adults, create a thread of AdultItinerary
   while message.listen() is not the total of children and adults do
   end while
end procedure
procedure AdultItinerary
   numOfAdultOahu++
   boatLock.acquire()
   while locationOfBoat is not Oahu or numOfChildBoat ¿ 0 or nu-
mOfChildOahu ¿ 1 do
      if locationOfBoat is on Oahu then
         waitOnOahuCondition.wakeAll()
      end if
      waitOnOahuCondition.sleep()
   end while
   bg.AdultRowToMolokai()
   numOfAdultOahu-, numOfAdultMolokai++
   locationOfBoat is Molokai
   message.speak (numOfAdultMolokai + numOfChildMolokai) \\
   waitOnMolokaiCondition.wakeAll()
   boat.release()
end procedure
```

6.5 Test

```
public static void selfTest() {
     BoatGrader b = new BoatGrader();

     begin(4, 3, b);
}
```

We test the case start with 4 adults and 3 childs and here is the result:

```
A child has forked.
A child has forked.
A child has forked.
An adult as forked.
```

```
procedure CHILDITINERARY
   location is Oahu
   numOfChildOahu++\\
   while true do
      boat.acquire()
      if location is Oahu then
         while locationOfBoat is not Oahu or numOfChildBoat is 2 or nu-
mOfChildOahu is 1 do
            if locationOfBoat is Oahu then
                waitOnOahuCondition.wakeAll()
            end if
            waitOnOahuCondition.sleep()
         end while
         numOfChildBoat++
         if numOfChildBoat == 1 then
            waitOnOahuCondition.wakeAll()
            waitBoardingCondition.sleep()
            numOfChildOahu-
            bg.ChildRideToMolokai()
            location is Molokai
            numOfChildBoat \leftarrow 0
            numOfChildMolokai++
            message.speak(numOfAdultMolokai + numOfChildMolokai)
            waitOnMolokaiCondition.wakeAll()
            waitOnMolokaiCondition.sleep()
         else
            waitBoardingCondition.wake()
            numOfChildOahu-
            bg.ChildRowToMolokai()
            location is Molokai
            numOfChildMolokai++\\
            waitOnMolokaiCondition.sleep()
         end if
      else
         while locationOfBoat is not Molokai do
            waitOnMolokaiCondition.sleep()
         end while
         numOfChildMolokai-
         bg.ChildRowToOahu()
         location is Oahu
         locationOfBoat is Oahu
         numOfChildOahu++
         waitOnOahuCondition.wakeAll()
         waitOnOahuCondition.sleep()
      end if
      boat.release()
   end while
end procedure
                                 28
```

```
An adult as forked.
An adult as forked.
An adult as forked.
**Child rowing to Molokai.
**Child arrived on Molokai as a passenger.
**Child rowing to Oahu.
**Child\ rowing\ to\ Molokai.
**Child arrived on Molokai as a passenger.
**Child rowing to Oahu.
**Adult rowing to Molokai.
**Child rowing to Oahu.
**Child\ rowing\ to\ Molokai.
**Child arrived on Molokai as a passenger.
**Child rowing to Oahu.
**Adult rowing to Molokai.
**Child rowing to Oahu.
**Child rowing to Molokai.
**Child arrived on Molokai as a passenger.
**Child rowing to Oahu.
**Adult rowing to Molokai.
**Child rowing to Oahu.
**Child rowing to Molokai.
**Child arrived on Molokai as a passenger.
**Child rowing to Oahu.
**Adult rowing to Molokai.
**Child rowing to Oahu.
**Child rowing to Molokai.
**Child arrived on Molokai as a passenger.
```

As we can easily check, the question is solved properly.